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Experimental analysis of the extension to shear fracture transition in a rock analogue material using digital image correlation method

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Abstract This paper presents the results of axisymmetric extension tests on a Rock Analogue Material that showed a continuous transition from extension fracture to shear fracture with an increase in compressive stress. The analysis used non destructive fullfield experimental methods-digital image correlation (DIC), as well as the post-mortem specimens observation. When the mean stress was small, the fractures formed through the mode I cracking at tensile equal to the material tensile strength with smooth surfaces. These surfaces became rougher or delicate plumose patterns as the mean stress increased. Fracture angles also increased progressively from extension fractures to shear fractures. Hybrid fractures formed under mixed tensile and compressive stress states and presented plumose patterns on the rupture surface. DIC results showed the localisation of tensile deformation and the acceleration of deformation at the zone that induced the fracture. The fracture caused a reduction of deformation in the surrounding areas, which showed a release

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of elastic energy stored in the material during the propagation of fracture.

Keywords Extension test · Hybrid fracture · Plumose · Transition of extension–shear fracture · Digital image correlation

List of Symbols

$\sigma_1, \sigma_2, \sigma_3$	Principal stress
σ_m	Mean stress
$q = \sigma_1 - P_c$	Deviatoric stress
P_c	Confining pressure
Ψ	Angle between fracture/band
	and σ_1 direction
Е	Young's modulus
ν	Poisson's ratio
ρ	Density
ε_{ax}	Axial strain
$\tilde{\varepsilon}_{ax}$	Nominal axial strain
ε	Volumetric strain
σ_{ax}	Axial stress
σ_{ax}^{c}	Axial stress at central sec-
	tion of dog-bone sample
σ_{ax}^{ex}	Axial stress at extremity of
	dog-bone sample
σ_{ax}^{rup}	Axial stress at failure
σ_{ax}^{pk}	Axial peak stress
σ_t	Uniaxial tensile strength

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S_c	Area at central section of	
	dog-bone sample	
Sex	Area at extremity of dog-	
	bone sample	
Srup	Area of the fracture surface	
F_{ax}	Applied force on the sam-	
	ple	
GRAM1	Granular Rock Analogue	
	Material 1	
β	Dilatancy factor	
DIC	Digital image correlation	
С	Correlation coefficient	
$X_i, x_i = \phi_0(X_i)$	Coordinates (in pixels) of	
	homologous points in the	
	reference and deformed imag	
ϕ_0	Transformation function	

1 Introduction

Extension fractures (opening mode) and shear fractures are two basic types of brittle fractures commonly observed in rock deformation experiments. In the laboratory, a shear fracture is produced under a compressive stress state. The fracture surface forms an angle of about $20^0 - 40^0$ to the maximum principal compressive stress direction σ_1 . An extension fracture forms under a tensile stress state, presents an opening mode displacement normal to the fracture surface, which is perpendicular to the minimum principal compressive stress (Jaeger and Cook 1979; Paterson and Wong 2005). Transitional fractures known as hybrid fracture that display both opening and shear mode, are commonly formed under mixed tensile and compressive stress states (Ferrill et al. 2012; Engelder 1999; Ramsey and Chester 2004).

Within the compressive stress regime, the Mohr-Coulomb failure criterion is widely used to predict the brittle failure strength and orientation of shear fractures. As implied by Mohr's hypothesis, the orientation of the fracture surface is inclined to σ_1 at a fracture angle Ψ , equal to $\pi/4 \pm \phi/2$, where tan ϕ is the slope of the failure envelope in Mohr space (Handin 1969). The failure envelope is generally described as a continuous function from a compressive to a tensile stress state. The Griffith and modified- Griffith criteria predict parabolic failure envelope for mixed tensile and compressive stress states that includes uniaxial tensile failure. The combination of Griffith and Mohr-Coulomb criteria for compressive stress state forms composite failure envelope that shows the existence of hybrid fractures in the transition from extension to shear fracture (Brace 1960). However, little laboratory work has investigated and demonstrated clearly hybrid fracture formation.

To build up of the adequate theory of inelastic deformation and fracturing/failure of geomaterials requires large sets of good quality experimental data. The majority of the experimental tests of rock samples were performed under axisymmetric compression. There are few data from axisymmetric extension tests and mostly corresponding to the brittle faulting regime. Heard (Heard 1960) performed series of triaxial compression and extension experiments under different conditions. His data shows that the transition under extension occurs at a mean stress σ_m two times greater than under compression. However, the results by Heard do not mention in detail hybrid fractures.

Ramsey and Chester (2004) carried out series of triaxial extension tests with notch-cut samples of Carrara Marble to study the extension to shear fracture transition. Their results demonstrates a continuous transition from extension fracture to shear fracture with an increase in compressive stress. The fracture angle increases with increasing confining pressure corresponding to a change in morphology. The same observation of mechanical behavior and morphological characteristics of fracture surface in extension–shear fracture transition is documented in a study of Bobich (2005) in Berea sandstone. The degree to which these results apply to granular material is uncertain because of distinct differences in rock microstructure.

The documents of hybrid fractures in field are rare. Hybrid fracture is likely an indicator of a tensile minimum effective stress and low differential stress at failure (Ferrill et al. 2012). The surface morphology of hybrid fracture is consistent with the steptread geometry that indicates fracture formation process through linkage of an array of en echelon, interacting, extension cracks (Engelder 1999; Reches and Lockner 1994). However, the correlation between the microscopic fracture mechanism, macroscopic fracture form and tension–shear strength is still not well understood.

In this study, we investigate brittle failure in a rock analogue (granular, frictional, dilatant and cohesive) material GRAM1 using triaxial extension tests of dogbone shape samples to verify the existence of hybrid fractures. Based on the previous study by Nguyen et al. (2011) conducted on the same material, we herein made modifications to the sample geometry and jacket design to improve reproducibility. New pressure cell with transparent windows allows a direct observation of the sample surface during loading. We therefore can apply the Digital image correlation technique (DIC), one of the most widespread full-field measurement techniques (Viggiani and Hall 2008; Dautriat et al. 2011; Bésuelle and Lanatà 2016; Tran et al. 2019) to obtain the displacement field and calculate the strains during the sample deformation. One of the main advantages of DIC is the non-contact optical application, which reduces the samples' interaction, preserving the best sample state at different deformation stages (Pan et al. 2009). Measuring displacements and strains in real time is carried out by comparing pairs of digital images at the first stage (or undeformed stage) and the deformed stage through a mathematical correlation analysis. Various studies have shown that the 2D DIC technique is suitable when applied to fracture case studies (Lin et al. 2019; Bertelsen 2019; Nguyen et al. 2017) and it offers high accuracy and reduced computational complexity compared with other techniques such as analytical method, and finite element method (Bermudo Gamboa et al. 2019).

For 3D objects and to avoid limiting the study to planar specimens and no-out-of plane motion, 3D DIC technique can be well applied (Chen et al. 2018; Molina-Viedma et al. 2018). The number of cameras has to be increased and positioned to take images from different angles. The 3D DIC needs a proper calibration of the axis before placing the samples and starting the tests. For a general analysis of the process, the 2D DIC analysis can be proposed instead of the 3D DIC (Bermudo Gamboa et al. 2019). For instance, Tran et al. (2019) applied the 2D DIC technique to detect the initiation and evolution of a network of deformation bands on cylindrical samples. In this case, the vertical component of displacement is of more interest. Measurement results were shown to be little affected by the curved geometry of sample. The axial strain maps obtained by DIC represented the post-mortem bands pattern faithfully (Tran et al. 2019).

On the basis of the data (the conditions of formation, fractography of fractures, and strain field), we discuss the fracturing mechanism and argue the existence of continuous transition from extension fracture to shear fracture. Hybrid fractures form under mixed tensile and compressive stress states. The surface morphology of hybrid fracture will be then described in detail. DIC results show the localisation of tensile deformation and an acceleration of deformation at the zone that induces the fracture. The fracture causes the reduction of deformation in the surrounding areas. This shows a release of the elastic energy stored in the material during the propagation of fracture.

2 Sample description

2.1 Material characterization

The experiments presented in this article were carried out on GRAM1 (Granular Rock Analogue Material 1). Its fabrication procedure and properties were described in detail in the previous studies (Nguyen et al. 2011; Mas and Chemenda 2014, 2015). GRAM1 was made from a finely ground powder of TiO₂. The average grain size is $\sim 0.3 \ \mu$ m. The powder was subjected to the hydrostatic pressure of $P_{fab} = 2MPa$, at which the grains were bonded one to another. An extensive program of GRAM1 stress-strain measurements in axisymmetric compression and extension tests at different confining pressure P_c below P_{fab} shows that material is quite relevant to the real rocks. It has frictional, cohesive, dilatant properties and mechanical behavior very similar to those of real rocks, but is about 2 orders of magnitude less strong and less rigid than rocks (Fig. 1) (Nguyen et al. 2011).

The Young's modulus E of GRAM1 is 6.5×10^8 Pa, the Poisson's ratio ν is 0.25, the internal friction coefficient α is of ~ 0.6 . Its porosity is about 50% and the density ρ is 1723 kg/m³. As for real rocks, the dilatancy factor β for GRAM1 is pressure-dependent and reduces from positive to negative values with P_c . The GRAM1 data reported in Nguyen et al. (2011) showed that the dilatancy factor β for the extension conditions varies from 0.4 (at $P_c = 0.4$ MPa) to -0.4(at $P_c = 1.5$ MPa).

2.2 Preparation of samples

In extension tests, it is necessary to apply a tensile axial stress σ_{ax} to reach the rupture in the sample. Hoek (1964) and Brace (1964) were able to make the axial stress tensile using dog-bone shaped samples in a triaxial cell, where $\sigma_1 = \sigma_2 > \sigma_3$. In practice, both σ_1 and σ_3



Fig. 1 Comparison of the curves of deviatoric stress-axial strain $q(\varepsilon_{ax})$ and volumetric strain-axial strain $\varepsilon(\varepsilon_{ax})$ for GRAM1 and rocks for extension tests. The plots for the rocks are from: Solnhofen limestone, Vosges sandstone (Nguyen et al. 2011)

are increased to confine the sample. σ_3 then applies a pressure on the curved portion of the sample and causes extension. The axial stress is, therefore, decreased to failure (Perras and Diederichs 2014). Two different dog-bone samples are usually used in the extension tests: sample shape with constant-radius segment r_{min} (Fig. 2a) (Millar and Murray 1988; Bésuelle et al. 2000) and sample shape with constant along-axis curvature of the surface R_0 (Fig. 2b) (Ramsey and Chester 2004; Bobich 2005). In the present work, we used the latter case to insure the fracture forming in the central thinned zone where the sample deformation was recorded during the test. From the images capturing, we applied the DIC technique to obtain the displacement and strain fields during the sample deformation.

The maximal tensile axial stress that can be generated in the thinned section of the dog-bone sample is defined by both confining pressure P_c and ratio r_{max}/r_{min} as in Perras and Diederichs (2014); Nguyen (2009):

$$\sigma_{ax}^c = \sigma_{ax}^{ex} S_{ex} - \frac{P_c(S_{ex} - S_c)}{S_c} \tag{1}$$

where, σ_{ax}^c and σ_{ax}^{ex} are axial stresses in central section and at the extremity, recpectively; S_c and S_{ex} are



Fig. 2 Dog-bone shape of GRAM1 samples. Samples with **a** constant-radius segment r_{min} ; **b** constant along-axis curvature of the surface R_0 (Nguyen et al. 2011)

the areas of the central section and of the extremity, respectively.

Figure 3 presents the dog-bone GRAM1 sample used in extension tests. The smallest and the biggest diameters are about 36 mm and 43 mm, respectively.



The sizes of these two diameters are chosen to ensure that the sample wrapping by latex jacket (a thin transparent latex film of about 300 μ m thickness) is convenient and does not affect the image matching procedure. Usage of latex film and specifications of DIC technique will be presented in the following sections.

3 Experimental setup and instrumentation

To perform an extension test, we followed the general methodology of previous extension tests on dog-bone shape samples (Ramsey and Chester 2004; Nguyen et al. 2011), but made modifications to the sample geometry and jacket design to improve reproducibility. The upper platen is similar to that used in Nguyen et al. (2011) for extensive tests. This helps reduce the deviation of the sample stress-state from the axial symmetry that can occur during the deformation. The sample and platens were jacketed by a transparent latex film (\sim 300 μ m of thickness) and placed into a pressure cell of 2 MPa capacity filled with clean water. The water pressure P_c was increased to the studied value by a 3 MPa capacity-pressure generator. The sample was then unloaded in the axial direction at P = const by the piston moving with a velocity of 10^{-6} m/s. During this process, stresses were measured by an internal force sensor with a frequency of five measurements per second. Due to the small thickness and rigidity, the latex

film can follow exactly the displacement of the sample surface (Tran et al. 2019). For DIC analysis, a specklelike pattern was sprayed on the transparent latex film to provide the surface with characteristic features. The droplets should be of an almost uniform size (of a few pixels, in our case about of 3-10 pixels), and sufficient density. The latter helps to increase the accuracy of DIC measurements (Dautriat et al. 2011; Tran et al. 2019).

To obtain the displacements, we applied the 2D digital image correlation technique. As shown in the Fig. 4, two high resolution cameras (2752x2204 pixels) are mounted on fixed frame on two sides of plane windows of the pressure cell to ensure a fully stable position. It is important to align the axes of the cameras perpendicularly to these plane windows and keep a diffuse, homogeneous and unchanging illumination during the exposure time. During loading, images covering on the whole sample height were taken simultaneously at a frequency of 10 Hz. The digital correlation of the images taken by these two cameras is then performed to obtain displacement fields, strain fields and their evolution.

After the test, the sample was unloaded in a way not to cause additional inelastic deformation: the axial nominal stress was first increased to P_c , after which the complete unloading followed a hydrostatic path.





Fig. 4 Scheme of sample and the platens designed for the extension test (**a**), photo of the pressure cell with the GRAM1 sample (**b**), photo of the experimental setup (**c**) and photo of a GRAM1 sample with a wedge glued in the central part; the sample and platens were jacketed by a latex film with speckle-like pattern

4 Methods of obtaining data

4.1 Post-mortem sample observation

After removing the sample from the pressure cell, the orientation of the fractures/deformation bands was determined thanks to traces appearing on the jacket. Fracture orientation can be either measured from the trace on the latex jacket or from the photos taken perpendicularly the surface of the post-mortem sample. Fracture orientation was identified by the maximum angle between the fracture surface and the plane normal to the cylinder axis. Similar observations were made by Bésuelle et al. (2000) and Nguyen (2009). The lines described as "white, chalky zones" on the latex jacket were identified as the trace of bands or failure surfaces.

The fractures, occurring in the extension test, correspond to very thin discontinuities on the surface of the sample. The fracture surfaces after opening these discontinuities exhibit a feathery topography, known as "plumose pattern", characterized by ridges and valleys forming a divergent pattern. The observation of the

(**d**). (1) hook, (2) connector, (3) sliding piece, (4) rod with two ball joints, (5) hull, (6) lower platen, (7) dog-bone-shape sample, (8) latex film with speckle-like pattern, (9) pressure cell, (10) press cross, (11) external displacement sensor, (12) LEDs, (13) cameras

plumose patterns generated in the series of extension tests will be considered carefully and documented in the session following.

4.2 Digital image correlation technique

The DIC technique has been widely used in studying the mechanical response of different materials such as metals, ceramics, rocks and rock analogue (Viggiani and Hall 2008; Dautriat et al. 2011; Bésuelle and Lanatà 2016; Tran et al. 2019) thanks to its advantages as a measurement method without contact with the observed sample. Numerous DIC softwares have been developed. In this work, we use software "7D" which was used and described in our previous study (Tran et al. 2019).

The DIC software 7D was developed at the Applied Mechanics Laboratory in Annecy by Vacher et al. (1999). It supports most common formats of images (.tif,.jpeg,.bmp,.emf...), coded on 8 or 12 bit, black and white or colour. After determining a reference image and one or a set of images to correlate, the

user defines a grid in the analyzed area on the reference image and images at different deformation stages. Around each grid node, a square correlation window size, known as subset size, is then defined. The subset sizes are between 6 and 40 pixels. A too small subset is likely to give false correlations due to an increase in the number of local minimum on the surface of the correlation coefficients. However, larger subset also leads to the increase of computational time (Perras and Diederichs 2014). The DIC parameters used in our analyses are: the subset (correlation window) of 10×10 pixels (corresponding to an area of 0.32×0.32 mm) and the step (grid spacing) of 10 pixels. The DIC algorithm is designed to find the most similar pixel subsets corresponding to the correlation window in the reference image and images at respective different deformed stages by optimizing a correlation coefficient defined as (Tran et al. 2019; Vacher et al. 1999):

$$C = 1 - \frac{\sum_{i \in D} f((X_i) - \overline{f}) \times (g(x_i) - \overline{g})}{\sqrt{\sum_{i \in D} (f(X_i) - \overline{f})^2 \times \sum_{i \in D} (g(x_i) - \overline{g})^2}}$$
(2)

where, D is the correlation window area. X_i and $x_i = \phi_0(X_i)$ are respectively the coordinates (in pixels) of homologous points in the reference and deformed images. ϕ_0 is the transformation function. $f(X_i)$ and $g(x_i)$ are respectively the grey levels of point *i* in the reference and deformed images; \overline{f} and \overline{g} are respectively the averages of the grey levels in the correlation window in the reference and deformed images.

The coefficient C ranges from 0 to 1. C tends to zero when images have a perfect similarity, whereas C equals one corresponding to no match at all. The position of the deformed correlation window is determined as the correlation coefficient C reaches the minimum value. The software "7D" computes the difference in the positions of grid nodes in the reference and deformed images, and yields a displacement field based on two assumptions: (1) the displacement field is continuous and (2) initially square correlation windows are transformed into any quadrilateral zones during the deformation. The analysis of the displacement of four points assumes a bilinear displacement field U of the type U=ax+by+cxy+d, where a, b, c, and d are the coefficients computed at each deformation stage. The strain field is then calculated using large strain Green Lagrange formulation. The precision obtained on the displacement field can reach 0.01 pixel. This precision makes it possible to calculate the strains in a large range, from elastic strains (\pm 0.01 percent) to large strains (over 200 percent) (Vacher et al. 1999).

Axial deformation measurement. The dog-bone shaped sample causes a difficulty in ensuring a good depth of field on the entire surface of the sample, especially on the transitional areas between the central part and the extremity. This can decrease the accuracy of the strain measurement performed by the DIC technique. As mentioned in the introduction, the curved shape of the sample can lead to the computational limitations when using 2D DIC technique. The vertical component of displacement is therefore chosen to exploit. The axial deformation measurement is focused in the central zone where the fracture exists. This can reduce the impact of the curved shape on the results.

Figure 5c and d present the accumulated axial strain map at the early stage of the representative test E0.8-10T and the deformations in the central profile along the height of the sample. Those maps show that the material in the central part of about 30 mm in height is performed quasi-homogeneously. Note that, the latex film jacketed the sample deforms following the deformation of the material during loading. At the moment of rupture, it can be pressed into the space produced during the opening of the fracture and thus induces a very large value of deformation in the heart of the fractured zone (Fig. 6c) and a very thick fracture as shown by DIC (Fig. 6b). In order to better represent the differential stress-strain curve $q(\tilde{\varepsilon}_{ax})$, the nominal axial strain $\tilde{\varepsilon}_{ax}$ is thus calculated in this central zone of 30 mm in height (two red squares of 30×30 pixels) (Fig. 6).

5 Results and discussion

A total of 40 extension tests have been conducted at the confining pressure P_c from 0.25 to 0.9 MPa. This P_c range is decided from the previous study of Nguyen et al. (2011). The aim is to focus on the transition P_c from the extension to shear fracture. At the confining pressure P_c ranging from 0.7 to 0.8 MPa, two experimental cases are performed: normal tests (without using wedge) and tests with a wedge glued to the central of the sample. The usage of wedge is to study the influence of a prechosen point on the initiation anf evolution of a deformation band/fracture. The results



Fig. 5 E0.8-10T test. **a** An example of an image recorded during the test with the resolution 1 pixel $\sim 31.2 \,\mu$ m, analyzed area in yellow, analysis grid in red; **b** post-mortem sample; **c** axial strain

map (ε_{ax}) at the early deformation stage; **d** deformations at the central profile along the height of the sample





of 22 representative experiments are presented in the Table 1.

The axial stress at failure σ_{ax}^{rup} (or axial peak stress σ_{ax}^{pk}) is calculated by dividing the applied force by the rupture area (Perras and Diederichs 2014):

$$\sigma_{ax}^{rup} = \sigma_3^{rup} = P_c - \frac{F_{ax}}{S_{rup}} \tag{3}$$

where, P_c is the confining pressure; F_{ax} is the applied force on the sample; S_{rup} is the the area of the horizontal section of the sample at rupture.

As shown in Table 1, an axial tensile stress is obtained at rupture in all the tests carried out at confining pressures P_c below 0.8 MPa. At P_c less than 0.5 MPa, $\sigma_{ax} = \sigma_3$ decreases (becomes more extensive) by -0.071 (cf. Fig. 7, close to the uniaxial tensile strength of GRAM1 $\sigma_t = -0.07$ MPa (Ferrill et al. 2012) to -0.13 MPa with increasing P_c . σ_3 increases (becomes more compressive) as a function of P_c when $P_c \ge 0.5$ MPa. At $P_c = 0.8$ MPa, the axial stress at rupture $\sigma_{ax}^{pk} = \sigma_3^{pk}$ is very close to 0.

Table 1 Results of GRAM1 triaxial extension experiments

Test	$P_c = \sigma_1$	Axial peak stress σ_{ax}^{pk}	Ψ (°)
E0.25-01T ^a	0.25	-0.071	0
E0.25-02T ^a	0.25	-0.106	0
E0.3-04T ^a	0.3	-0.101	0
E0.3-06T ^a	0.3	-0.120	0
E0.35-04T ^a	0.35	-0.130	0
E0.4-01T ^a	0.4	-0.099	0
E0.4-02T ^a	0.4	-0.129	0
E0.5-01T ^a	0.5	-0.130	0
E0.5-02T ^a	0.5	-0.112	0
E0.5-05T ^a	0.5	-0.096	0
E0.6-02T ^a	0.6	-0.114	0
E0.6-03T ^a	0.6	-0.087	0
E0.7-03T ^a	0.7	-0.047	0
E0.7-01T ^a	0.7	-0.030	1
E0.7-02T ^a	0.7	-0.020	3.8
E0.7-04T ^a	0.7	-0.059	1
E0.7-05T ^b	0.7	-0.019	1
E0.7-06T ^b	0.7	-0.020	1
E0.8-06T ^a	0.8	-0.0064	12
E0.8-08T ^a	0.8	-0.0059	13
E0.8-09T ^a	0.8	-0.0076	13
E0.8-10T ^b	0.8	-0.0066	1
E0.8-11T ^b	0.8	-0.0097	1
E0.9-02T ^a	0.9	0.024	17

 σ_{ax}^{pk} is the axial peak stress; Ψ is the angle between the fracture/band and the σ_1 direction. In the name of tests, E0.25-01T for example, E stands for extension test, 0.25 is the value of confining pressure at which the test was conducted, 01 is the test order, and T stands for the author's name

^a Normal tests (without wedge)

^b Tests with one or more wedges glued to the center of the sample



Fig.7 Axial stresses at rupture $\sigma_{ax}^{pk} = \sigma_3^{pk}$ versus the confining pressure P_c

5.1 Fracture characteristics

Figure 8 presents the photos of the post-mortem half samples in the extension tests at different P_c . The angle Ψ between the fractures and the direction of the principal stress σ_1 strongly depends on P_c or the mean stress σ_m (for extension tests, $(\sigma_1 + \sigma_2 + \sigma_3)/3 =$ $(2 \times P_c + \sigma_{ax})/3$, where $\sigma_1 = \sigma_2 = P_c$, $\sigma_3 = \sigma_{ax}$). At $P_c < 0.7$ MPa ($\sigma_m < 0.47$ MPa), the fractures are perpendicular to the direction of the axial stress. Their formation is accompanied by acoustic emission (audible noise) which proves the dynamic brittle failure of the material. At $P_c = 0.7$ MPa, the fracture is either horizontal or inclined with a low $\Psi < 4^\circ$. For $P_c > 0.8$ MPa, several oblique bands are formed in the central zone of the sample (Fig. 10a).

The evolution of the fracture angle as a function of P_c is shown on the graph (Ψ, P_c) in Fig. 9. The fracture angles Ψ formed at $P_c < 0.7MPa$ are equal to 0° and are therefore independent of the confining pressure P_c . From $P_c \ge 0.7$ MPa, Ψ increases almost linearly with P_c . However, we can see that the tests with a wedge glued to the center of the sample at $P_c = 0.8$ MPa, present a quasi-horizontal fracture ($\Psi < 1^\circ$) (the tests E0.8-10T, E0.8-11T) whereas for the tests without wedge the angle of fractures is about 13° (Table 1). In the case of $P_c = 0.7$ MPa, the wedge also has a similar influence on the angle of fracture. This can be explained by the concentration of pressure thanks to the wedge that guides the fracture to form and propagate on a plane.

Figures 10 and Fig. 11 show the fracture surfaces after separating manually the samples generated at different confining pressures P_c . The surfaces of fractures exhibit faint and delicate ridges and troughs forming a plumose topography complicated with steps appearing at relatively high pressures. At $P_c = 0.7$ MPa, the plumose tomography is complicated with steps (Fig. 11c). For $P_c \ge 0.8$ MPa, the fracture surface is characterized by sputtered plates or zones (Fig. 11e and f). The location of the plates can connect on both sides of the fracture. Furthermore, we can see clearly the influence of attaching a wedge of the testing sample. The fracture surfaces in the case with a wedge (both $P_c = 0.7$ MPa and 0.8 MPa) still present a plumose morphology, but with a greater relief in the case of 0.8 MPa confining pressure (Fig. 11d and f).

As shown in Fig. 10, the test E0.8-08T carried out at $P_c = 0.8$ MPa causes two types of fracture



Fig. 8 Photos showing fracture angle formed in axisymmetric extension tests at different confining pressure P_c . The angle Ψ between the fracture plan and the σ_1 direction increases with P_c



Fig. 9 Evolution of the fracture angle Ψ with the confinement pressure P_c in the extension tests: (1) normal tests (without wedge); (2) tests with one or more wedges glued to the center of the sample



Fig. 10 Fracture surfaces in the test (normal test, without wedge) at $P_c = 0.8MPa$ a test E0.8-08T which includes, b the plumose surface of the weak inclined fracture and c the pulverized surface of the oblique fracture. The blue point indicates the fracture initiation point

surfaces. The first one is characterized by sputtered plates or zones as described in the above test E0.8-09T (Fig. 11e). The second one comprises two distinct parts: smooth part and the other manifesting a plumose fractography. The part of this surface with a plumose feature corresponds to the discontinuity seen at the sample surface after unloading, and the smooth part was formed during the manual extension at $P_c = 0$ due to the fracture propagation from the discontinuity front. This demonstrates a possibility of the formation of mixed horizontal-oblique fractures under a state of mixed tensile and compressive stress.

The series of triaxial extension tests was performed on identique dog-bone shape of GRAM1 samples for different confining pressures P_c . Extension tests by Nguyen (2009) were also carried out with the GRAM1 material but with two different dog-bone shape samples (Fig. 2). These different shapes may influence the value of the tensile strength as GRAM1 is a low strength analogue rock material. Our results show a continuous transition from extensive fracture to shear fracture with increasing compressive stress. The horizontal (extensive) fractures form for the tests at P_c from 0.25 to 0.7 MPa under a negative stress state. While at P_c from 0.7 to 0.9 MPa, shear fractures occur with an increase in fracture angle Ψ as a function of P_c under a negative to positive stress state. In addition, the morphology of fracture surfaces show a strong correlation to confining pressure. At P_c of 0.7 to 0.8 MPa, fractures formed under a mixed tensile and compressive stress state, display both opening and shear mode as hybrid fractures. This is in agreement with the results for the extension tests carried out on real rocks in which the same shape



Fig. 11 Surfaces of orthogonal fractures σ_3 generated at different P_c : **a** test E0.25-02T; **b** test E0.5-02T; **c** test E0.7-02T; **d** test E0.7-06T (with wedge); **e** test E0.8-09T; **f** E0.8-10T (with wedge); **g** test E0.9-02T. The blue point indicates the fracture initiation point



Fig. 12 Differential stress–strain curves $q(\tilde{\epsilon}_{ax})$ from test E0.8-10T: 1, $\tilde{\epsilon}_{ax}$ is calculated from the displacements measured by the external LVDT sensor located between the piston and the pressure cell; 2, $\tilde{\epsilon}_{ax}$ is the average of the axial DIC strains in the 30 mm height of central zone; 3, $\tilde{\epsilon}_{ax}$ is the average of the axial DIC strains in the two area of 30×30 pixels outside the fracture area. Points A1, A2, A3 are the same points at the same loading stage, points B1, B2, B3 at the moment of rupture

of the sample was used. Ramsey and Chester (2004); Bobich (2005)

5.2 Nominal stress–strain curve and deformation evolution during loading

Figure 12 presents the differential stress–strain curves $q(\tilde{\varepsilon}_{ax})$ from the representative test E0.8-10T. The $q(\tilde{\varepsilon}_{ax})$ curve (curve 3, in red) computed by DIC in the two areas of 30×30 pixels outside the fracture area as described in the section above, is obviously different from that obtained by the external LVDT sensor (curve 1, in black). The estimated Young's modulus is $E \approx 6.5 \times 10^8$ Pa. This value is also close to that determined by the same technique in the compression tests (Tran et al. 2019). However, at the time of failure, this curve shows a stress plateau. This phenomenon can be explained by the impact of the jacket which enters the fracture during its opening. The jacket deforms following the deformation of the material during loading. Upon rupture, the jacket can be pressed into the space produced during the opening of the fracture and also damage the two edges of the fracture. These, therefore, induce a very large value of deformation in the heart of the fractured zone (Fig. 6c) and a very thick fracture



Fig. 13 Test E0.8-10T: **a** sample set up before testing. The wedge is glued outside the jacket on the right; **b** post-mortem sample with the horizontal fracture; **c** stress-strain curve $\sigma_{ax}(\tilde{e}_{ax})$; **d** plumose surface of the fracture. The fracture initiation point coincides with the place of bonding of the wedge; **e**,

as shown by DIC (Fig. 6b). To avoid the existence of the plateau on the curve $q(\tilde{\varepsilon}_{ax})$, two square areas of 30×30 pixels ($\approx 9.4 \times 9.4 \text{ mm}^2$) above and below the horizontal fracture were chosen to calculate the global deformation. The curve $q(\tilde{\varepsilon}_{ax})$ obtained by this calculation method (curve 2) (Fig. 12) coincides with the curve obtained previously (curve 3). The return of the strain value at the time of fracture (point B2) shows the release of elastic energy in the material when the fracture occurs.

In extension tests, a horizontal fracture (fracture in opening mode) generally forms under an extensive stress state at low confining pressure P_c . At higher P_c , oblique fractures (shear mode) form under a compressive stress state (Ramsey and Chester 2004; Bobich 2005). The extension tests carried out at different confinement pressures from 0.25 to 0.9 MPa show that the type of horizontal fracture can also occur under

f Accumulated axial strain maps and strains in the central profile along the height of the sample obtained from DIC between point 0 (at the beginning of test) and points n, where n = 1, 2... 6. The numbers on the color palettes are the strain values multiplied by 10^{-3}

the mixed tensile and compressive stress state at P_c between 0.7 and 0.8 MPa. Therefore, a test at $P_c = 0.8$ MPa is chosen to present the evolution of the deformation during loading by applying the image correlation technique. A wedge is glued outside the jacket to guide the initiation location and the propagation direction of the fracture.

Figure 13 presents the accumulated axial strain maps for the representative test E0.8-10T. A dotted line indicates the position of the fracture. Significant noise can be seen at the ends of the sample. This can be explained by a shallow depth of field and the dog-bone shape, which gives a blurred effect at the edge of the sample. Therefore, we only analyze the evolution of the deformation in the central zone of about 30 mm height on the ε_{ax} maps and the associated $\varepsilon_{ax}(h)$ graphs. In Fig. 13d, we can see that the sample deforms homogeneously at stage 1, then heterogeneously from stage 2. The ε_{ax} maps at stages 3, 4, 5 show uniform deformation in both parts of the sample. Higher strain always concentrates in the middle of the sample where the fracture occurs later. At the stage (0–4), we can see that the deformation is located in the center of the strain map ε_{ax} on the right hand where a wedge is glued outside the jacket. This location is clearer on the ε_{ax} map at the stage (0–5). A horizontal fracture forms completely at stage (0–6). The fracture causes the reduction of the deformation in the surrounding areas, which shows that there was release of the elastic energy stored in the material during the fracture. The fracture presents a surface with plumoses which indicates that the fracture starts on the right and then propagates to the left. This initiation point coincides with the position of the wedge.

The axial stress at rupture $\sigma_{ax}^{pk} = \sigma_3^{pk}$ is almost similar in both experimental cases: with or without wedge (Table 1). The wedge therefore does not affect the breaking strength of the material. However, it does create a horizontal fracture and guide the fracture initiation point. Applying the DIC technique allows to track the evolution of the deformation in the material. A concentration of strain prior to fracture formation can be detected.

6 Conclusions

The reported results on GRAM1 show a continuous transition from extensive fracture to shear fracture with increasing confining pressure. The horizontal fractures (opening mode) form at low confining pressure. While at high pressure, shear fractures occur with an increase in fracture angle Ψ as a function of P_c under a negative to positive stress state. In addition, the morphology of fracture surfaces shows a strong correlation to confining pressure. The results herein provide the laboratory evidence for the existence of hybrid fractures which forms under the mixed tensile-compression stress. The surface morphology of the hybrid fracture is compatible with the experimental results obtained by Ramsey and Chester testing on Carra marbles (Ramsey and Chester 2004), Bobich testing on Berea sandstone (Bobich 2005) as well as in the natural fractures classified as hybrids (Ferrill et al. 2012; Engelder 1999; Reches and Lockner 1994).

The evolution of the deformation in the material during loading can be observed thanks to the DIC technique. A concentration of the deformation before the formation of the fracture can be detected. A release of the elastic energy is also observed as soon as the fracture forms. However, the detection of the initiation and propagation of the dilatancy band is not possible in our study due to the limitation in resolution and sampling frequency of our camera. The 2D DIC technique also remains the limitations in studying 3D objects. The data approach at the level of experiments provide the evidence for the existence of hybrid fractures. Further study and 3D DIC analysis application are needed to clearly understand the specific processes that govern the hybrid fracture formation.

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