

## Adaptive estimation of heavy right tails: resampling-based methods in action

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**Abstract** In this paper, we discuss an algorithm for the adaptive estimation of a positive *extreme value index*,  $\gamma$ , the primary parameter in *Statistics of Extremes*. Apart from the classical extreme value index estimators, we suggest the consideration of associated second-order corrected-bias estimators, and propose the use of resampling-based computer-intensive methods for an asymptotically consistent choice of the *thresholds* to use in the adaptive estimation of  $\gamma$ . The algorithm is described for a classical  $\gamma$ -estimator and associated corrected-bias estimator, but it can work similarly for the estimation of other parameters of extreme events, like a *high quantile*, the *probability of exceedance* or the *return period of a high level*.

**Keywords** Statistics of extremes · Semi-parametric estimation ·  
Resampling-based methodology

**AMS 2000 Subject Classifications** Primary—62G32 · 62E20; Secondary—65C05

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## 1 Introduction and outline of the paper

Heavy-tailed models appear often in practice in fields like Telecommunications, Insurance, Finance, Bibliometrics and Biostatistics. Power laws, such as the Pareto distribution and the Zipf's law, have been observed a few decades ago in some important phenomena in Economics and Biology, and have seriously attracted scientists in recent years.

We shall essentially deal with the estimation of a positive *extreme value index* (EVI), denoted  $\gamma$ , the primary parameter in *Statistics of Extremes*. Apart from the classical Hill, moment and generalized-Hill semi-parametric estimators of  $\gamma$ , we shall also consider associated classes of second-order reduced-bias (RB) estimators. RB estimation of any parameter of extreme events, such as the EVI, has recently revealed to be of primordial importance. Indeed, the classical estimators, and particularly the Hill estimator, reveal usually a high non-null (asymptotic) bias at optimal levels, i.e., levels  $k$  where the mean squared error (MSE) is minimum, where  $k$  is directly related with the number of top order statistics (o.s.'s) involved in the estimation. This non-null bias, together with a rate of convergence of the order of  $1/\sqrt{k}$ , leads to sample paths with a high variance for small  $k$ , a high bias for large  $k$ , and a very sharp MSE pattern, as a function of  $k$ . In the pioneering papers in the field of RB EVI-estimation, among which we mention Beirlant et al. (1999), Feuerverger and Hall (1999) and Gomes et al. (2000), authors have been led to a reduction of bias at expenses of a larger asymptotic variance, with a ruler never smaller than  $(\gamma(1 - \rho)/\rho)^2$ , the minimal asymptotic variance of RB EVI-estimators at Drees' class of models (Drees 1998), with  $\rho(\leq 0)$  a second-order parameter ruling the rate of convergence of the sequence of maximum values to a non-degenerate limit. For an overview of this topic, see Reiss and Thomas (2007), Chapter 6, 189–204, as well as the more recent paper by Gomes et al. (2008a). The classes of RB EVI-estimators considered in this paper are based on the adequate “external” estimation of a “scale” and a “shape” second-order parameters,  $\beta$  and  $\rho$ , respectively, as performed in Caeiro et al. (2005), among others. They are valid for a reasonably large class of heavy-tailed underlying parents and are appealing in the sense that we are able to reduce the asymptotic bias of a classical estimator without increasing its asymptotic variance. We shall call these estimators “*classical-variance reduced-bias*” (CVRB) estimators.

After the introduction, in Section 2, of a few technical details in the area of *Extreme Value Theory* (EVT), related with the EVI-estimators under consideration in this paper, we shall briefly discuss, in Section 3, the asymptotic properties of those estimators, and the kind of second-order parameters' estimation which enables the building of corrected-bias estimators with the same asymptotic variance of the associated classical estimators, i.e., the building of CVRB estimators. In Section 4, in the lines of Gomes et al. (2011), we propose an algorithm for the adaptive consistent estimation of a positive EVI, through the use of resampling computer-intensive methods. The algorithm is described for a classical EVI estimator and associated CVRB estimator, but it can work similarly for the estimation of other parameters of extreme events, like a high quantile, the probability of exceedance or the return

period of a high level. In Section 5, we present some of the results of a large-scale Monte-Carlo simulation related with the behaviour of the non-adaptive and adaptive estimators under consideration, emphasizing the low coverage probabilities of bootstrap confidence intervals. Finally, Section 6 is entirely dedicated to the application of the algorithm described in Section 4 to the analysis of an environmental data set.

## 2 The EVI-estimators under consideration

In the area of EVT, and whenever dealing with large values, a model  $F$  is usually said to be *heavy-tailed* whenever the *right-tail function*,  $\bar{F} := 1 - F$ , is a regularly varying function with a negative index of regular variation, denoted  $-1/\gamma$ , i.e., for all  $x > 0$ , there exists  $\gamma > 0$ , such that

$$\bar{F}(tx)/\bar{F}(t) \xrightarrow[t \rightarrow \infty]{} x^{-1/\gamma}. \quad (2.1)$$

If Eq. 2.1 holds, we use the notation  $\bar{F} \in RV_{-1/\gamma}$ , with  $RV$  standing for *regular variation*. For this type of models, and for independent, identically distributed or even stationary and weakly dependent sequences of random variables (r.v.'s),  $\{X_n\}_{n \geq 1}$ , the sequence of maximum values,  $X_{n:n} := \max(X_1, X_2, \dots, X_n)$ , linearly normalized, converges weakly towards a non-degenerate r.v., with an *extreme value* (EV) distribution function (d.f.),

$$EV_\gamma(x) = \exp\left(- (1 + \gamma x)^{-1/\gamma}\right), \quad x > -1/\gamma, \quad \gamma > 0. \quad (2.2)$$

If Eq. 2.1 holds, we are working in the whole domain of attraction (for maxima) of  $EV_\gamma$ , in Eq. 2.2, denoted  $\mathcal{D}_M^+ \equiv \mathcal{D}_{\mathcal{M}}(EV_\gamma)_{\gamma > 0}$ . Equivalently, with

$$U(t) := F^{\leftarrow}(1 - 1/t) = \inf\{x : F(x) \geq 1 - 1/t\}$$

denoting a reciprocal quantile function, we have the validity of the so-called *first-order condition*,

$$F \in \mathcal{D}_{\mathcal{M}}^+ \iff \bar{F} \in RV_{-1/\gamma} \iff U \in RV_\gamma. \quad (2.3)$$

For these heavy-tailed parents, given a sample  $\underline{X}_n := (X_1, X_2, \dots, X_n)$  and the associated sample of ascending o.s.'s,  $(X_{1:n} \leq X_{2:n} \leq \dots \leq X_{n:n})$ , the classical EVI estimator is the Hill (H) estimator (Hill 1975),

$$H(k) \equiv H_{k,n} := \frac{1}{k} \sum_{i=1}^k \{\ln X_{n-i+1:n} - \ln X_{n-k:n}\}, \quad (2.4)$$

the average of the  $k$  log-excesses over a high random threshold  $X_{n-k:n}$ , which needs to be an *intermediate* o.s., i.e.,  $k$  needs to be such that

$$k \equiv k_n \rightarrow \infty \quad \text{and} \quad k/n \rightarrow 0, \quad \text{as } n \rightarrow \infty. \tag{2.5}$$

But, as mentioned before, the Hill-estimator  $H(k)$ , in Eq. 2.4, reveals usually a high non-null asymptotic bias at optimal levels. Hence the importance of RB EVI-estimators and, among them, of the second-order minimum-variance reduced-bias (MVRB) EVI-estimators in Caeiro et al. (2005) and Gomes et al. (2007, 2008c), which outperform the Hill estimator for all  $k$ . For technical reasons, essentially related with the erratic estimation of the second-order parameter  $\rho$ , whenever  $\rho = 0$ , but also to get full information on the dominant component of the asymptotic bias of the RB EVI-estimators, we then need to work in a region slightly more restrict than  $\mathcal{D}_{\mathcal{M}}^+$ . In this paper, we shall consider parents such that, as  $t \rightarrow \infty$ , the *third-order condition*,

$$U(t) = Ct^\gamma (1 + A(t)/\rho + \eta A^2(t) + o(A^2(t))), \quad A(t) =: \gamma \beta t^\rho, \tag{2.6}$$

holds, with  $\gamma > 0$ ,  $\rho < 0$ , and  $\beta, \eta \neq 0$ , where  $\beta$  and  $\eta$  can more generally be slowly varying functions, i.e., elements of  $RV_0$ . Note that for models in Eq. 2.6, the slowly varying function  $L(t)$ , in  $U(t) = t^\gamma L(t)$ , behaves approximately as a constant. Consequently, no deviation that has slowly varying components going towards infinity or zero is allowed. The class in Eq. 2.6 is however a wide class of models, that contains most of the heavy-tailed parents useful in applications, like the *Fréchet*, the *generalized Pareto* and the *Student- $t_v$* , with  $v$  degrees of freedom.

The most simple class of second-order MVRB EVI-estimators is the one in Caeiro et al. (2005), used for a semi-parametric estimation of  $\ln \text{VaR}_p$  in Gomes and Pestana (2007b), with  $\text{VaR}_p$  standing for the Value-at-Risk at the level  $p$ , the size of the loss occurred with a small probability  $p$ . This class of EVI-estimators, here denoted  $\overline{H} \equiv \overline{H}(k)$ , is the CVRB-estimator associated with the Hill estimator,  $H \equiv H(k)$ , in Eq. 2.4, and depends upon the estimation of the second-order parameters  $(\beta, \rho)$ , in Eq. 2.6. Its functional form is

$$\overline{H}(k) \equiv \overline{H}_{k,n;\hat{\beta},\hat{\rho}} := H(k) (1 - \hat{\beta}(n/k)^{\hat{\rho}} / (1 - \hat{\rho})), \tag{2.7}$$

where  $(\hat{\beta}, \hat{\rho})$  is an adequate consistent estimator of  $(\beta, \rho)$ . Algorithms for the estimation of  $(\beta, \rho)$  are provided, for instance, in Gomes and Pestana (2007a, b), and one of them will be reformulated in the *Algorithm* presented in Section 4.2 of this paper.

Apart from the *Hill* estimator, in Eq. 2.4, we suggest the consideration of two other classical estimators, valid for all  $\gamma \in \mathbb{R}$ , but considered here exclusively for heavy tails, the *moment* (Dekkers et al. 1989) and the *generalized-Hill* (Beirlant et al. 1996, 2005) estimators. The *moment* estimator,  $M \equiv M(k)$ , has the functional expression

$$M(k) \equiv M_{k,n} := M_{k,n}^{(1)} + \frac{1}{2} \left\{ 1 - (M_{k,n}^{(2)} / (M_{k,n}^{(1)})^2 - 1)^{-1} \right\}, \tag{2.8}$$

with

$$M_{k,n}^{(j)} := \frac{1}{k} \sum_{i=1}^k (\ln X_{n-i+1:n} - \ln X_{n-k:n})^j, \quad j \geq 1, \tag{2.9}$$

$M_{k,n}^{(1)} \equiv H(k)$ , in Eq. 2.4. The *generalized Hill* estimator,  $GH \equiv GH(k)$ , is defined for  $k = 2, \dots, n - 1$ , and it is given by

$$GH(k) \equiv GH_{k,n} := \frac{1}{k} \sum_{j=1}^k \ln UH_{j,n} - \ln UH_{k,n},$$

$$UH_{j,n} := X_{n-j:n} H_{j,n}, \quad 1 \leq j \leq k, \tag{2.10}$$

with  $H_{k,n}$  defined in Eq. 2.4. To enhance the similarity between the moment estimator, in Eq. 2.8, and the generalized Hill estimator, in Eq. 2.10, we can also write an asymptotically equivalent expression for  $GH(k)$ , given by

$$GH^*(k) := H_{k,n} + \frac{1}{k} \sum_{i=1}^k \{ \ln H_{i,n} - \ln H_{k,n} \}. \tag{2.11}$$

This means that  $H_{k,n} \equiv M_{k,n}^{(1)}$  is estimating  $\gamma^+ := \max(0, \gamma)$ , both in Eqs. 2.8 and 2.11, whereas  $\gamma^- := \min(0, \gamma) = \gamma - \gamma^+$  is being estimated differently.

The associated bias-corrected moment ( $\overline{M}$ ) and generalized Hill ( $\overline{GH}$ ) estimators have similar expressions, due to the same dominant component of asymptotic bias of the estimators in Eqs. 2.8 and 2.10, whenever the EVI is positive (see Gomes and Neves 2008, among others). Denoting generally  $\overline{W}$ , either  $\overline{M}$  or  $\overline{GH}$ , and with the notation  $W$  for either  $M$  or  $GH$ , we get

$$\overline{W}(k) \equiv \overline{W}_{k,n;\hat{\beta},\hat{\rho}} := W(k) \left( 1 - \hat{\beta} (n/k)^{\hat{\rho}} / (1 - \hat{\rho}) \right) - \hat{\beta} \hat{\rho} (n/k)^{\hat{\rho}} / (1 - \hat{\rho})^2. \tag{2.12}$$

In the sequel, we generally denote  $C$  any of the classical EVI-estimators, in Eqs. 2.4, 2.8 and 2.10, and  $\overline{C}$  the associated CVRB-estimator.

*Remark 2.1* As we shall see later on, in Section 3, the most interesting feature of the CVRB estimators,  $\overline{C}(k)$ , lies on the fact that they are no longer alternatives to the classical estimators,  $C(k)$ , only at optimal levels, as often happens with other RB EVI-estimators. They overpass the associated classical estimators for all  $k$ -thresholds.

### 3 Asymptotic behaviour of the estimators

In order to obtain a non-degenerate behaviour for any EVI-estimator, under a semi-parametric framework, it is convenient to assume a second-order condition,

measuring the rate of convergence in the first-order condition, given in Eq. 2.3. Such a condition involves the above mentioned non-positive parameter  $\rho$ , and can be given by

$$\lim_{t \rightarrow \infty} \frac{U(tx)/U(t) - x^\gamma}{A(t)} = x^\gamma \left( \frac{x^\rho - 1}{\rho} \right), \tag{3.1}$$

for all  $x > 0$ , where  $A(\cdot)$  is a suitably chosen function of constant sign near infinity. Then,  $|A| \in RV_\rho$  (Geluk and de Haan 1987).

In this paper, as mentioned before and mainly because of the CVRB EVI-estimators in Eqs. 2.7 and 2.12, generally denoted  $\bar{C}(k) \equiv \bar{C}_{k,n;\hat{\beta},\hat{\rho}}$ , we shall slightly more restrictively assume that the third-order condition in Eq. 2.6 holds. Then, Eq. 3.1 holds, with  $A(t) = \gamma\beta t^\rho$ ,  $\rho < 0$ , the parametrization used in Eq. 2.6. For the classical  $H$ ,  $M$  and  $GH$  estimators, generally denoted  $C$ , we know that for any intermediate sequence  $k$ , as in Eq. 2.5, and under the validity of the second-order condition in Eq. 3.1,

$$C(k) \stackrel{d}{=} \gamma + \frac{\sigma_c Z_k^C}{\sqrt{k}} + b_{c,1} A(n/k)(1 + o_p(1)), \tag{3.2}$$

where

$$\begin{aligned} \sigma_H = \gamma, \quad b_{H,1} = \frac{1}{1 - \rho}, \quad \sigma_M = \sigma_{GH} = \sqrt{\gamma^2 + 1}, \\ b_{M,1} = b_{GH,1} = \frac{\gamma(1 - \rho) + \rho}{\gamma(1 - \rho)^2} = \frac{1}{1 - \rho} + \frac{\rho}{\gamma(1 - \rho)^2}, \end{aligned} \tag{3.3}$$

being  $Z_k^C$  asymptotically standard normal r.v.'s (de Hann and Peng 1998; Dekkers et al. 1989; Beirlant et al. 1996, 2005). See also de Haan and Ferreira (2006). Moreover, if we consistently estimate  $(\beta, \rho)$ , through  $(\hat{\beta}, \hat{\rho})$ , in such a way that  $\hat{\rho} - \rho = o_p(1/\ln n)$ ,

$$\bar{C}(k) \stackrel{d}{=} \gamma + \frac{\sigma_c Z_k^C}{\sqrt{k}} + o_p(A(n/k)), \tag{3.4}$$

again under the validity of the second-order condition, in Eq. 3.1, and with  $\sigma_c$  already mentioned in Eqs. 3.2 and 3.3.

The above mentioned properties, together with trivial adaptations of the results in Caiiro et al. (2005, 2009) and Gomes et al. (2008d), for  $\bar{H}$ , and Gomes et al. (2008b), for  $\bar{M}$ , enable us to state, the following theorem, again for models with a positive EVI. We shall include in the statement of the theorem both the classical and the associated CVRB estimators.

**Theorem 3.1** *Assume that condition (3.1) holds, and let  $k \equiv k_n$  be an intermediate sequence, i.e., Eq. 2.5 holds. Then  $C(k)$  is consistent for the estimation of  $\gamma$ . Moreover, there exist a sequence  $Z_k^C$  of asymptotically standard normal r.v.s, and real*

numbers  $\sigma_C > 0$  and  $b_{C,1}$ , given in Eq. 3.3, such that the asymptotic distributional representation in Eq. 3.2 holds.

If we further assume that Eq. 2.6 holds, there exists an extra real number  $b_{C,2}$ , such that we can write

$$C(k) \stackrel{d}{=} \gamma + \frac{\sigma_C Z_k^C}{\sqrt{k}} + b_{C,1} A(n/k) + b_{C,2} A^2(n/k)(1 + o_p(1)). \tag{3.5}$$

If under the validity of the second-order condition in Eq. 3.1, we estimate  $\beta$  and  $\rho$  consistently through  $\hat{\beta}$  and  $\hat{\rho}$ , in such a way that  $\hat{\rho} - \rho = o_p(1/\ln n)$ , the asymptotic distributional representation in Eq. 3.4 holds. Under the validity of Eq. 2.6, we can guarantee that there exists a pair of real numbers  $(b_{\bar{C},1}, b_{\bar{C},2})$ , but with  $b_{\bar{C},1} = 0, \forall C$ , such that for adequate  $k$  values of an order up to  $k$  such that  $\sqrt{k}A^2(n/k) \rightarrow \lambda_A$ , finite,

$$\begin{aligned} \bar{C}(k) &\stackrel{d}{=} \gamma + \frac{\sigma_C Z_k^C}{\sqrt{k}} + b_{\bar{C},1} A(n/k) + b_{\bar{C},2} A^2(n/k) (1 + o_p(1)) \\ &\stackrel{d}{=} \gamma + \frac{\sigma_C Z_k^C}{\sqrt{k}} + b_{\bar{C},2} A^2(n/k) (1 + o_p(1)). \end{aligned} \tag{3.6}$$

*Proof* The proof of the theorem for  $\bar{H}$ , in Eq. 2.7, follows from the above mentioned papers. For the  $\bar{W}$  estimators, in Eq. 2.12, the proof can also be performed along the same lines. If we estimate consistently  $\beta$  and  $\rho$  through the estimators  $\hat{\beta}$  and  $\hat{\rho}$  in the conditions of the theorem, we may use Cramer’s delta-method, and write,

$$\begin{aligned} \bar{W}_{k,n,\hat{\beta},\hat{\rho}} &= W_{k,n} \times \left( 1 - \frac{\beta}{1-\rho} \left(\frac{n}{k}\right)^\rho - (\hat{\beta} - \beta) \frac{1}{1-\rho} \left(\frac{n}{k}\right)^\rho (1 + o_p(1)) \right. \\ &\quad - \frac{\beta}{1-\rho} (\hat{\rho} - \rho) \left(\frac{n}{k}\right)^\rho \left( \frac{1}{1-\rho} + \ln(n/k) \right) (1 + o_p(1)) - \frac{\beta \rho}{(1-\rho)^2} \left(\frac{n}{k}\right)^\rho \\ &\quad \left. - \left\{ (\hat{\beta} - \beta) \frac{\rho}{(1-\rho)^2} \left(\frac{n}{k}\right)^\rho + \frac{\beta(\hat{\rho} - \rho)}{1-\rho} \left(\frac{n}{k}\right)^\rho \left( \frac{\rho \ln(n/k)}{1-\rho} + 3 - \rho \right) \right\} (1 + o_p(1)). \right) \end{aligned}$$

We can then guarantee the existence of real values  $u_w$  and  $v_w$  such that

$$\bar{W}_{k,n,\hat{\beta},\hat{\rho}} \stackrel{d}{=} \bar{W}_{k,n,\beta,\rho} - \frac{A(n/k)}{1-\rho} \left( u_w \left( \frac{\hat{\beta} - \beta}{\beta} \right) + v_w (\hat{\rho} - \rho) \ln(n/k) \right) (1 + o_p(1)).$$

The reasoning is then quite similar to the one used in Gomes et al. (2008d) for the  $\bar{H}$ -estimator. Since  $\hat{\beta}$  and  $\hat{\rho}$  are consistent for the estimation of  $\beta$  and  $\rho$ , respectively, and  $(\hat{\rho} - \rho) \ln(n/k) = o_p(1)$ , the last summand is obviously  $o_p(A(n/k))$ , and can even be  $o_p(A^2(n/k))$ .

*Remark 3.1* Note that the values of  $b_{H,1}, b_{M,1}$  and  $b_{GH,1}$ , in Eq. 3.3, provide an easy heuristic justification for the CVRB estimators in Eqs. 2.7 and 2.12.

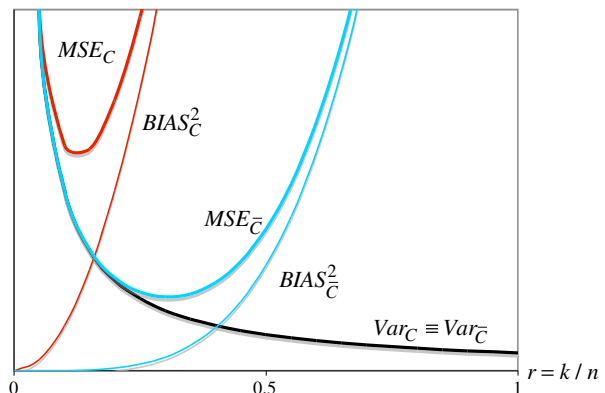
*Remark 3.2* Only the external estimation of both  $\beta$  and  $\rho$  at a level  $k_1$ , adequately chosen, and the estimation of  $\gamma$  at a level  $k = o(k_1)$ , or at a specific value  $k = O(k_1)$ , can lead to a CVRB estimator, with an asymptotic variance  $\sigma_C^2$ . Such a choice of  $k$  and  $k_1$  is theoretically possible, as shown in Gomes et al. (2008d) and in Caeiro et al. (2009), but under conditions difficult to guarantee in practice. As a compromise between theoretical and practical results, and with  $[x]$  denoting, as usual, the integer part of  $x$ , we have so far advised any choice  $k_1 = [n^{1-\epsilon}]$ , with  $\epsilon$  small (see Caeiro et al. 2005, 2009; Gomes et al. 2007, 2008b, among others). Later on, in the algorithm described in Section 4, we shall consider  $\epsilon = 0.001$ , i.e.,  $k_1 = [n^{0.999}]$ . Then we get  $\sqrt{k_1} A(n/k_1) \rightarrow \infty$  if and only if  $\rho > -499.5$ , an almost irrelevant restriction in the class defined in Eq. 2.6. We can then guarantee that  $\hat{\rho} - \rho = o_p(1/\ln n)$ , and the above mentioned behaviour, described in Theorem 3.1, for the reduced-bias EVI-estimators. Note that the above mentioned condition,  $\sqrt{k_1} A(n/k_1) \rightarrow \infty$ , is necessary for a consistent estimation of the second-order parameters  $\beta$  and  $\rho$ . The estimation of  $\gamma, \beta$  and  $\rho$  at the same value  $k$  would lead to a high increase in the asymptotic variance of the RB-estimators  $\bar{C}_{k,n;\hat{\beta},\hat{\rho}}$ , which would become  $\sigma_C^2 ((1 - \rho)/\rho)^4$  (see Feuerverger and Hall 1999; Beirlant et al. 1999; Peng and Qi 2004, also among others). The external estimation of  $\rho$  at  $k_1$ , but the estimation of  $\gamma$  and  $\beta$  at the same  $k = o(k_1)$ , enables a slight decreasing of the asymptotic variance to  $\sigma_C^2 ((1 - \rho)/\rho)^2$ , still greater than  $\sigma_C^2$  (see Gomes and Martins 2002, again among others). However, even in such cases, the results in Section 4 are still valid.

*Remark 3.3* Let  $k = k_n$  be intermediate and such that  $\sqrt{k} A(n/k) \rightarrow \lambda$ , finite, the type of levels  $k$  where the MSE of  $C(k)$  is minimum. Let  $\hat{\gamma}(k)$  denote either  $C(k)$  or  $\bar{C}(k)$ . Then

$$\sqrt{k}(\hat{\gamma}(k) - \gamma) \xrightarrow[n \rightarrow \infty]{d} Normal(\lambda b_{\hat{\gamma},1}, \sigma_C^2),$$

even if we work with the CVRB EVI-estimators, and we thus get asymptotically a null mean value ( $b_{\bar{C},1} = 0$ ). Since  $b_{C,1} \neq 0$  whereas  $b_{\bar{C},1} = 0$ , the  $\bar{C}$ -estimators

**Fig. 1** Typical patterns of asymptotic variances (Var), squared bias (BIAS<sup>2</sup>) and MSE of a classical EVI-estimator,  $C$ , and associated CVRB estimator,  $\bar{C}$





outperform the  $C$ -estimators for all  $k$ , as illustrated in Fig. 1, where we picture the patterns of the asymptotic variance  $\gamma^2/k$ , for  $\gamma = 1$  and  $n = 1000$ , as well as the squared bias and the mean squared error of  $C = H$  and  $\bar{C} = \bar{H}$ , for a Fréchet parent with  $\gamma = 1$  ( $\rho = -1, \eta = -1/3$ ). Then  $b_{H,1} = 0.5$  and  $b_{\bar{H},2} = 0.306$  (see Caeiro and Gomes 2011, for details on the expression of  $b_{\bar{H},2}$ , there denoted  $b_{\bar{H}}$ ). Similar results were obtained for other values of the parameters, other underlying parents, other pairs  $(C, \bar{C})$  of EVI-estimators, and we can claim that such a picture is related with a typical pattern of these estimators.

Under the conditions of Theorem 3.1, if  $\sqrt{k} A(n/k) \rightarrow \infty$ , with  $\sqrt{k} A^2(n/k) \rightarrow \lambda_A$ , finite, the type of levels  $k$  where the MSE of  $\bar{C}(k)$  is minimum, then

$$\sqrt{k} (\bar{C}(k) - \gamma) \xrightarrow[n \rightarrow \infty]{d} \text{Normal}(\lambda_A b_{\bar{C},2}, \sigma_C^2).$$

*Remark 3.4* If the second-order condition in Eq. 3.1 holds with  $\rho = 0$ , the  $\rho$ -estimators used in this paper, although consistent, do not work as nicely as for the case  $\rho < 0$ , but the Hill EVI-estimator works also very badly. Consequently, even under such conditions, any of the CVRB estimators,  $\bar{C}(k)$ , works better than the classical one,  $C(k)$ , for all  $k$ .

### 4 Adaptive classical and CVRB EVI-estimation

With AMSE standing for “asymptotic MSE”,  $\hat{\gamma}$  denoting either  $C$  or  $\bar{C}$ ,

$$k_{0|\hat{\gamma}}(n) := \arg \min_k \text{MSE}(\hat{\gamma}(k)), \tag{4.1}$$

and

$$k_{A|\hat{\gamma}}(n) := \arg \min_k \text{AMSE}(\hat{\gamma}(k)) \tag{4.2}$$

we get, on the basis of Eqs. 3.5 and 3.6,

$$\begin{aligned} k_{A|\hat{\gamma}}(n) &= \arg \min_k \begin{cases} (\sigma_{\hat{\gamma}}^2/k + b_{\hat{\gamma},1}^2 A^2(n/k)) & \text{if } \hat{\gamma} = C \\ (\sigma_{\hat{\gamma}}^2/k + b_{\hat{\gamma},2}^2 A^4(n/k)) & \text{if } \hat{\gamma} = \bar{C} \end{cases} \\ &= k_{0|\hat{\gamma}}(n)(1 + o(1)). \end{aligned}$$

The bootstrap methodology can thus enable us to consistently estimate the optimal sample fraction (OSF),  $k_{0|\hat{\gamma}}(n)/n$ , with  $k_{0|\hat{\gamma}}(n)$  defined in Eq. 4.1, on the basis of a consistent estimator of  $k_{A|\hat{\gamma}}(n)$ , in Eq. 4.2, in a way similar to the one used in Draisma et al. (1999), Danielsson et al. (2001) and Gomes and Oliveira (2001), for the classical adaptive EVI estimation, performed through the classical EVI-estimators,  $C(k)$ ,

and for second-order reduced-bias estimation in Gomes et al. (2011). We shall here use the auxiliary statistics

$$T_{k,n} \equiv T(k|\hat{\gamma}) \equiv T_{k,n|\hat{\gamma}} := \widehat{\gamma}([k/2]) - \widehat{\gamma}(k), \quad k = 2, \dots, n - 1, \tag{4.3}$$

which converge in probability to zero, for intermediate  $k$ , and have an asymptotic behaviour strongly related with the asymptotic behaviour of  $\widehat{\gamma}(k)$ . Indeed, under the above-mentioned third-order framework in Eq. 2.6, we get

$$T(k|\hat{\gamma}) \stackrel{d}{=} \frac{\sigma_{\hat{\gamma}} P_k^{\hat{\gamma}}}{\sqrt{k}} + \begin{cases} b_{\hat{\gamma},1}(2^\rho - 1) A(n/k)(1 + o_p(1)) & \text{if } \hat{\gamma} = C \\ b_{\hat{\gamma},2}(2^{2\rho} - 1) A^2(n/k)(1 + o_p(1)) & \text{if } \hat{\gamma} = \bar{C}, \end{cases}$$

with  $P_k^{\hat{\gamma}}$  asymptotically standard normal.

Consequently, denoting  $k_{0|T}(n) := \arg \min_k \text{MSE}(T_{k,n})$ , we have

$$k_{0|\hat{\gamma}}(n) = k_{0|T}(n) \times \begin{cases} (1 - 2^\rho)^{\frac{2}{1-2\rho}} (1 + o(1)) & \text{if } \hat{\gamma} = C \\ (1 - 2^{2\rho})^{\frac{2}{1-4\rho}} (1 + o(1)) & \text{if } \hat{\gamma} = \bar{C}. \end{cases} \tag{4.4}$$

### 4.1 The resampling methodology in action

How does the resampling methodology then work? Given the sample  $\underline{X}_n = (X_1, \dots, X_n)$  from an unknown model  $F$ , and the functional in Eq. 4.3,  $T_{k,n} =: \phi_k(\underline{X}_n)$ ,  $1 < k < n$ , consider for any  $n_1 = O(n^{1-\epsilon})$ ,  $0 < \epsilon < 1$ , the bootstrap sample

$$\underline{X}_{n_1}^* = (X_1^*, \dots, X_{n_1}^*),$$

from the model

$$F_n^*(x) = \frac{1}{n} \sum_{i=1}^n I_{[X_i \leq x]},$$

the empirical d.f. associated with the available sample,  $\underline{X}_n$ .

Next, associate to the bootstrap sample the corresponding bootstrap auxiliary statistic,  $T_{k_1,n_1}^* := \phi_{k_1}(\underline{X}_{n_1}^*)$ ,  $1 < k_1 < n_1$ . Then, with  $k_{0|T}^*(n_1) = \arg \min_{k_1} \text{MSE}(T_{k_1,n_1}^*)$ ,

$$\frac{k_{0|T}^*(n_1)}{k_{0|T}(n)} = \left(\frac{n_1}{n}\right)^{-\frac{c\rho}{1-c\rho}} (1 + o(1)), \quad c = \begin{cases} 2 & \text{if } \hat{\gamma} = C \\ 4 & \text{if } \hat{\gamma} = \bar{C}. \end{cases}$$

Consequently, for another sample size  $n_2$ , and for every  $\alpha > 1$ ,

$$\frac{(k_{0|T}^*(n_1))^\alpha}{k_{0|T}^*(n_2)} = \left(\frac{n_1^\alpha}{n_2^\alpha} \frac{n}{n_2}\right)^{-\frac{c\rho}{1-c\rho}} (k_{0|T}(n))^{\alpha-1} (1 + o(1)).$$

It is then enough to choose  $n_2 = [n (n_1/n)^\alpha]$ , in order to have independence of  $\rho$ . If we put  $n_2 = [n_1^2/n]$ , i.e.,  $\alpha = 2$ , we have

$$(k_{0|T}^*(n_1))^2 / k_{0|T}^*(n_2) = k_{0|T}(n)(1 + o(1)), \text{ as } n \rightarrow \infty. \tag{4.5}$$

On the basis of Eq. 4.5, we are now able to consistently estimate  $k_{0|T}$  and next  $k_{0|\hat{\gamma}}$  through Eq. 4.4, on the basis of any estimate  $\hat{\rho}$  of the second-order parameter  $\rho$ . With  $\hat{k}_{0|T}^*$  denoting the sample counterpart of  $k_{0|T}^*$ , and  $\hat{\rho}$  an adequate  $\rho$ -estimate, we thus have the  $k_0$ -estimate

$$\hat{k}_{0|\hat{\gamma}}^* \equiv \hat{k}_{0|\hat{\gamma}}(n; n_1) := \min \left( n - 1, [c_{\hat{\rho}} (\hat{k}_{0|T}^*(n_1))^2 / \hat{k}_{0|T}^*([n_1^2/n] + 1)] + 1 \right), \tag{4.6}$$

with

$$c_{\hat{\rho}} = \begin{cases} (1 - 2\hat{\rho})^{\frac{2}{1-2\hat{\rho}}} & \text{if } \hat{\gamma} = C \\ (1 - 2^2\hat{\rho})^{\frac{2}{1-4\hat{\rho}}} & \text{if } \hat{\gamma} = \bar{C}. \end{cases}$$

The adaptive estimate of  $\gamma$  is then given by

$$\hat{\gamma}^* \equiv \hat{\gamma}_{n,n_1|T}^* := \hat{\gamma}(\hat{k}_{0|\hat{\gamma}}(n; n_1)). \tag{4.7}$$

### 4.2 Algorithm for adaptive EVI-estimation through $C$ and $\bar{C}$

Again, with  $\hat{\gamma}$  denoting any of the estimators  $C$  or  $\bar{C}$ , we proceed with the description of the algorithm for the adaptive estimation of  $\gamma$ , where in **Steps 1., 2.** and **3.** we reproduce the algorithm provided in Gomes and Pestana (2007b) for the estimation of the second-order parameters  $\beta$  and  $\rho$ .

#### Algorithm

1. Given an observed sample  $(x_1, \dots, x_n)$ , compute, for the tuning parameters  $\tau = 0$  and  $\tau = 1$ , the observed values of  $\hat{\rho}_\tau(k)$ , the most simple class of estimators in Fraga Alves et al. (2003). Such estimators depend on the statistics

$$V_{k,n}^{(\tau)} := \begin{cases} \frac{(M_{k,n}^{(1)}) - (M_{k,n}^{(2)}/2)^{1/2}}{(M_{k,n}^{(2)}/2)^{1/2} - (M_{k,n}^{(3)}/6)^{1/3}} & \text{if } \tau = 1 \\ \frac{\ln(M_{k,n}^{(1)}) - \frac{1}{2} \ln(M_{k,n}^{(2)}/2)}{\frac{1}{2} \ln(M_{k,n}^{(2)}/2) - \frac{1}{3} \ln(M_{k,n}^{(3)}/6)} & \text{if } \tau = 0, \end{cases}$$

where  $M_{k,n}^{(j)}$ ,  $j = 1, 2, 3$ , are given in Eq. 2.9, and have the functional form

$$\hat{\rho}_\tau(k) := \min \left( 0, \frac{3(V_{k,n}^{(\tau)} - 1)}{V_{k,n}^{(\tau)} - 3} \right). \tag{4.8}$$

2. Consider  $\{\hat{\rho}_\tau(k)\}_{k \in \mathcal{K}}$ , with  $\mathcal{K} = ([n^{0.995}], [n^{0.999}])$ , compute their median, denoted  $\chi_\tau$ , and compute  $I_\tau := \sum_{k \in \mathcal{K}} (\hat{\rho}_\tau(k) - \chi_\tau)^2$ ,  $\tau = 0, 1$ . Next choose the tuning parameter  $\tau^* = 0$  if  $I_0 \leq I_1$ ; otherwise, choose  $\tau^* = 1$ .
3. Work with  $\hat{\rho} \equiv \hat{\rho}_{\tau^*} = \hat{\rho}_{\tau^*}(k_1)$  and  $\hat{\beta} \equiv \hat{\beta}_{\tau^*} := \hat{\beta}_{\hat{\rho}_{\tau^*}}(k_1)$ , with  $k_1 = [n^{0.999}]$ , being  $\hat{\beta}_{\hat{\rho}}$  the estimator in Gomes and Martins (2002), given by

$$\hat{\beta}_{\hat{\rho}}(k) := \left(\frac{k}{n}\right)^{\hat{\rho}} \frac{d_k(\hat{\rho}) D_k(0) - D_k(\hat{\rho})}{d_k(\hat{\rho}) D_k(\hat{\rho}) - D_k(2\hat{\rho})}, \tag{4.9}$$

dependent on the estimator  $\hat{\rho} = \hat{\rho}_{\tau^*}(k_1)$ , and where, for any  $\alpha \leq 0$ ,

$$d_k(\alpha) := \frac{1}{k} \sum_{i=1}^k \left(\frac{i}{k}\right)^{-\alpha} \quad \text{and} \quad D_k(\alpha) := \frac{1}{k} \sum_{i=1}^k \left(\frac{i}{k}\right)^{-\alpha} U_i,$$

with

$$U_i = i \left( \ln \frac{X_{n-i+1:n}}{X_{n-i:n}} \right), \quad 1 \leq i \leq k < n,$$

the scaled log-spacings.

4. Compute  $\hat{\gamma}(k)$ ,  $k = 1, 2, \dots, n - 1$ .
5. Next, consider the sub-sample size  $n_1 = [n^{0.955}]$  and  $n_2 = [n_1^2/n] + 1$ .
6. For  $l$  from 1 till  $B$  (number of bootstrap iterations), generate independently, from the empirical d.f.  $F_n^*(x) = \frac{1}{n} \sum_{i=1}^n I_{[X_i \leq x]}$  associated with the observed sample,

$$(x_1^*, \dots, x_{n_2}^*) \quad \text{and} \quad (x_1^*, \dots, x_{n_2}^*, x_{n_2+1}^*, \dots, x_{n_1}^*),$$

bootstrap samples of sizes  $n_2$  and  $n_1$ , respectively.

7. Denoting  $T_{k,n}^*$  the bootstrap counterpart of  $T_{k,n}$ , in Eq. 4.3, obtain, for  $1 \leq l \leq B$ ,  $t_{k,n_1,l}^*$ ,  $1 < k < n_1$ ,  $t_{k,n_2,l}^*$ ,  $1 < k < n_2$ , the observed values of the statistic  $T_{k,n_i}^*$ ,  $i = 1, 2$ , and compute

$$\text{MSE}^*(n_i, k) = \frac{1}{B} \sum_{l=1}^B (t_{k,n_i,l}^*)^2, \quad k = 2, \dots, n_i - 1.$$

8. Obtain  $\hat{k}_{0|T}^*(n_i) := \arg \min_{1 < k < n_i} \text{MSE}^*(n_i, k)$ ,  $i = 1, 2$ .
9. Compute  $\hat{k}_{0|\hat{\gamma}}^* \equiv \hat{k}_{0|\hat{\gamma}}(n; n_1)$ , given in Eq. 4.6.
10. Compute  $\hat{\gamma}^* \equiv \hat{\gamma}_{n,n_1|T}^*$ , given in Eq. 4.7.

In order to obtain a final adaptive estimate of  $\gamma$  on the basis of one of the estimators under consideration, we still suggest the estimation of the MSE of any of the EVI-estimators at the bootstrap  $k_0$ -estimate, in **Step 9.**, say the estimation of  $\text{MSE}(\widehat{\gamma}(\widehat{k}_{0|\widehat{\gamma}}^*))$ , with  $\widehat{\gamma} \in \{H, \overline{H}, M, \overline{M}, GH, \overline{GH}\}$ , and the choice of the estimate  $\widehat{\gamma}$  for which  $\text{MSE}(\widehat{\gamma}(\widehat{k}_{0|\widehat{\gamma}}^*))$  is minimum, i.e., the consideration of an extra step, after **Step 7.:**

7'. For  $k = 2, \dots, n_2 - 1$ , compute  $\text{Bias}^*(n_i, k) = \frac{1}{B} \sum_{l=1}^B t_{k, n_i, l}^*$ ,  $i = 1, 2$ .

Finally, we add the extra step:

11. Compute  $\text{RMSE}_{\widehat{\gamma}}^* = \sqrt{\widehat{\text{MSE}}(\widehat{k}_{0|\widehat{\gamma}}^* | \widehat{\gamma}^*)}$ , with  $\widehat{\text{MSE}}(\widehat{k}_{0|\widehat{\gamma}}^* | \widehat{\gamma}^*)$  given by

$$\widehat{\text{MSE}}(\widehat{k}_{0|\widehat{\gamma}}^* | \widehat{\gamma}^*) := \begin{cases} \frac{(\widehat{\gamma}^*)^2}{\widehat{k}_{0|\widehat{\gamma}}^*} + \left( \frac{(\text{Bias}^*(n_1, \widehat{k}_{0|\widehat{\gamma}}^*))^2}{(2^{\widehat{\rho}} - 1)\text{Bias}^*(n_2, \widehat{k}_{0|\widehat{\gamma}}^*)} \right)^2 & \text{if } \widehat{\gamma} = H \\ \frac{(\widehat{\gamma}^*)^2}{\widehat{k}_{0|\widehat{\gamma}}^*} + \left( \frac{(\text{Bias}^*(n_1, \widehat{k}_{0|\widehat{\gamma}}^*))^2}{(2^{2\widehat{\rho}} - 1)\text{Bias}^*(n_2, \widehat{k}_{0|\widehat{\gamma}}^*)} \right)^2 & \text{if } \widehat{\gamma} = \overline{H} \\ \frac{(\widehat{\gamma}^*)^2 + 1}{\widehat{k}_{0|\widehat{\gamma}}^*} + \left( \frac{(\text{Bias}^*(n_1, \widehat{k}_{0|\widehat{\gamma}}^*))^2}{(2^{\widehat{\rho}} - 1)\text{Bias}^*(n_2, \widehat{k}_{0|\widehat{\gamma}}^*)} \right)^2 & \text{if } \widehat{\gamma} = M \text{ or } GH \\ \frac{(\widehat{\gamma}^*)^2 + 1}{\widehat{k}_{0|\widehat{\gamma}}^*} + \left( \frac{(\text{Bias}^*(n_1, \widehat{k}_{0|\widehat{\gamma}}^*))^2}{(2^{2\widehat{\rho}} - 1)\text{Bias}^*(n_2, \widehat{k}_{0|\widehat{\gamma}}^*)} \right)^2 & \text{if } \widehat{\gamma} = \overline{M} \text{ or } \overline{GH}, \end{cases}$$

and consider the final estimate,  $\widehat{\gamma}^{**} := \arg \min_{\widehat{\gamma}^*} \widehat{\text{MSE}}(\widehat{k}_{0|\widehat{\gamma}}^* | \widehat{\gamma}^*)$ .

### 4.3 Remarks on the adaptive classical or CVRB estimation

- (i) If there are negative elements in the sample, the value of  $n$ , in the **Algorithm**, must be replaced by  $n^+ := \sum_{i=1}^n I_{[X_i > 0]}$ , the number of positive elements in the sample.
- (ii) In **Step 2.** of the **Algorithm** we are led in almost all situations to the *tuning parameter*  $\tau = 0$  whenever  $-1 \leq \rho < 0$  and  $\tau = 1$ , otherwise. Due to the fact that bias reduction is really needed when  $-1 \leq \rho < 0$ , we claim again for the relevance of the choice  $\tau = 0$ . Whenever we want to refer, in the estimation of  $\gamma$  through any of the reduced-bias estimators, the use of either  $\tau = 0$  or  $\tau = 1$  in the estimation of the second-order parameter  $\rho$ , we shall use the notation  $\overline{C}_\tau$ , for  $C$  equal to  $H$  or  $M$  or  $GH$ .
- (iii) Regarding second-order parameters' estimation, attention should also be paid to the most recent classes of  $\rho$ -estimators proposed in Goegebeur et al. (2008, 2010) and in Ciuperca and Mercadier (2010), as well as to the estimators of  $\beta$  in Cairo and Gomes (2006) and in Gomes et al. (2010).
- (iv) As we shall see later on in Section 5.2, the method is only moderately dependent on the choice of the nuisance parameter  $n_1$ , in **Step 5.** of the **Algorithm**,

particularly for the MVRB estimators. This enhances the practical value of the method. Moreover, although aware of the need of  $n_1 = o(n)$ , it seems that, once again, we get good results up till  $n$ , particularly for the MVRB estimator,  $\overline{H}(k)$ , in Eq. 2.7.

- (v) The Monte-Carlo procedure in the **Steps 6.–10.** of the **Algorithm** can be replicated  $r_1$  times if we want to associate standard errors to the OSF and to the EVI-estimates. The value of  $B$  can also be adequately chosen.
- (vi) We would like to stress again that the use of the random sample of size  $n_2$ ,  $(x_1^*, \dots, x_{n_2}^*)$ , and of the extended sample of size  $n_1$ ,  $(x_1^*, \dots, x_{n_2}^*, x_{n_2+1}^*, \dots, x_{n_1}^*)$ , leads us to increase the precision of the result with a smaller  $B$ , the number of bootstrap samples generated. Indeed, if we had generated the sample of size  $n_1$  independently of the sample of size  $n_2$ , we would have got a wider confidence interval for the EVI, should we have kept the same value for  $B$ . This is quite similar to the use of the simulation technique of “*Common Random Numbers*” in comparison algorithms, when we want to decrease the variance of a final answer to  $z = y_1 - y_2$ , inducing a positive dependence between  $y_1$  and  $y_2$ .

## 5 Monte-Carlo simulations

### 5.1 Non-adaptive estimation

In this section, and comparatively with the behaviour of the classical EVI-estimators  $H(k)$ ,  $M(k)$  and  $GH(k)$ , in Eqs. 2.4, 2.8 and 2.10, respectively, we are interested in the finite-sample behaviour, as functions of  $k$ , of the CVRB EVI-estimators,  $\overline{H}(k)$  and  $\overline{W}(k)$ , in Eqs. 2.7 and 2.12, respectively, with  $\overline{W}$  denoting either  $\overline{M}$ , with  $M$  the estimator in Eq. 2.8, or  $\overline{GH}$ , with  $GH$  the estimator in Eq. 2.10. We have performed a multi-sample simulation with size  $5000 \times 10$ , i.e., 10 replicates with 5000 runs each. For details on multi-sample simulation refer to Gomes and Oliveira (2001). The patterns of mean values (E) and root mean squared errors (RMSE) are based on the first replicate and are considered as a function of  $h = k/n$ . We have considered in this article the following underlying heavy-tailed parents:

- I. the Fréchet( $\gamma$ ) model, with d.f.  $F(x) = e^{-x^{-1/\gamma}}$ ,  $x > 0$ , for  $\gamma = 0.25$  ( $\rho = -1$ );
- II. the Burr( $\gamma, \rho$ ) model, with d.f.  $F(x) = 1 - (1 + x^{-\rho/\gamma})^{1/\rho}$ ,  $x > 0$ , for a few values of  $(\gamma, \rho)$ , the pairs,  $(0.25, -0.5)$ ,  $(0.25, -1)$  and  $(1, -1)$ ;
- III. the Student’s  $t_\nu$  model with  $\nu$  degrees of freedom, with a probability density function  $f_{t_\nu}(t) = \Gamma((\nu + 1)/2) (1 + t^2/\nu)^{-(\nu+1)/2} / (\sqrt{\pi\nu} \Gamma(\nu/2))$ ,  $t \in \mathbb{R}$  ( $\nu > 0$ ), for which  $\gamma = 1/\nu$  and  $\rho = -2/\nu$ . The illustration will be done for  $\nu = 4$  degrees of freedom, i.e.  $(\gamma, \rho) = (0.25, -0.5)$ ;
- IV. the *extreme value*  $EV_\gamma$  model, with d.f. in Eq. 2.2, for which  $\rho = -\gamma$ . We shall consider  $\gamma = 0.25$  ( $\rho = -0.25$ ) and  $\gamma = 1$  ( $\rho = -1$ );
- V. the *generalized Pareto*  $GP_\gamma$  model, with d.f.  $GP_\gamma(x) = 1 - (1 + \gamma x)^{-1/\gamma}$ ,  $x > 0$ , ( $\rho = -\gamma$ , as in IV.), also for  $\gamma = 0.25$  ( $\rho = -0.25$ ) and  $\gamma = 1$  ( $\rho = -1$ );

VI. the *Log-gamma<sub>n</sub>* model,  $Y = \exp(G_n)$ , where  $G_n$  is a Gamma r.v. with probability density function  $f(x) = \exp(-x) x^{n-1} / \Gamma(n), x \geq 0$ , a model out of the class in Eq. 2.6 and even out of Hall-Welsh class of models (Hall and Welsh 1985). We then have  $\gamma = 1$  and  $\rho = 0$ .

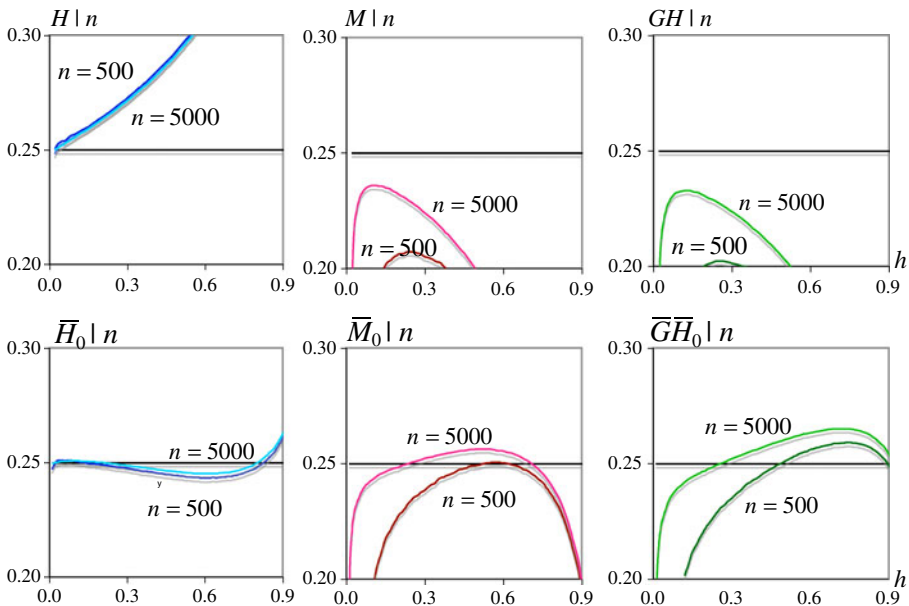
5.1.1 Mean values and root mean squared errors patterns

In Fig. 2, as an illustration of the results obtained, we show the simulated patterns of mean values for all the estimators under study, as a function of the sample fraction  $h = k/n$ , for the underlying Fréchet parent, and sample sizes  $n = 500$  and  $n = 5000$ . Figure 3 is equivalent to Fig. 2, but with the root mean squared errors (RMSE) patterns of the estimators. Similar results have been obtained for all simulated models.

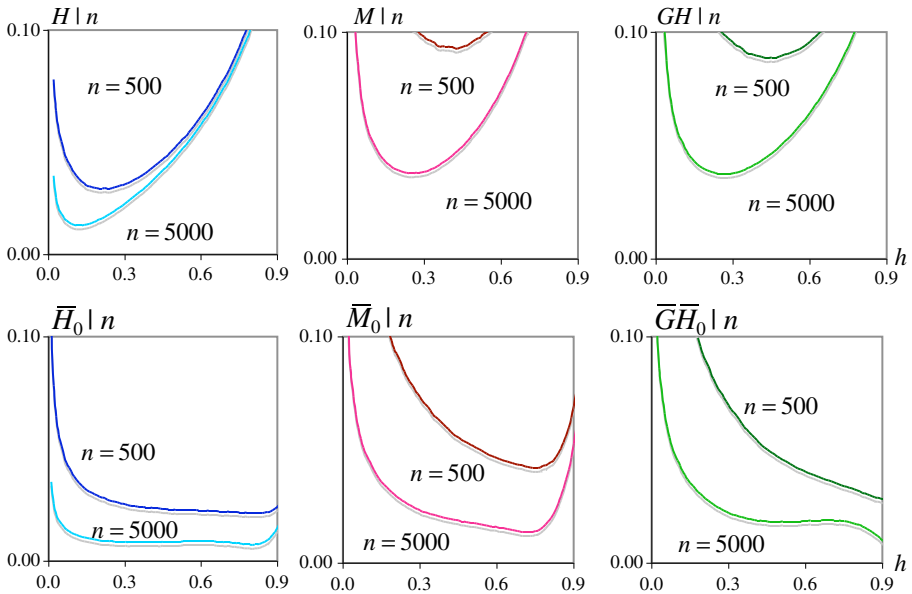
From Fig. 2 it is clear the reduction in bias achieved by any of the reduced-bias estimators. Such a bias reduction leads to much lower mean squared errors for the CVRB estimators, as can be seen from Fig. 3.

5.1.2 Relative efficiencies and mean values at optimal levels

Given a sample  $\underline{X}_n = (X_1, \dots, X_n)$ , let us denote  $S(k) = S(k; \underline{X}_n)$  any statistic or r.v. dependent on  $k$ , the number of top o.s.'s to be used in an inferential procedure related with a parameter of extreme events. Just as mentioned before for the



**Fig. 2** Patterns of mean values of the classical estimators  $H, M$  and  $GH$ , in Eqs. 2.4, 2.8 and 2.10 (top) and the associated CVRB estimators (bottom), as functions of  $k/n$ , for an underlying Fréchet parent with  $\gamma = 0.25$  ( $\rho = -1$ )



**Fig. 3** Patterns of RMSEs of the classical estimators  $H$ ,  $M$  and  $GH$ , in Eqs. 2.4, 2.8 and 2.10 (top) and the associated CVRB estimators (bottom), as functions of  $k/n$ , for an underlying Fréchet parent with  $\gamma = 0.25$  ( $\rho = -1$ )

Hill estimator  $H(k)$ , in Eq. 2.4, the OSF for  $S(k)$  is denoted  $k_{0|S}/n$ , with  $k_{0|S} := \arg \min_k \text{MSE}(S(k))$ . We have obtained, for  $n = 100, 200, 500, 1000, 2000$  and  $5000$ , and with  $\bullet$  denoting  $H$  or  $M$  or  $GH$  or  $\bar{H}_\tau$  or  $\bar{M}_\tau$  or  $\bar{GH}_\tau$ ,  $\tau = 0$  and  $1$ , the simulated OSF ( $\text{OSF}_0^\bullet = k_{0|\bullet}/n$ ), bias ( $\text{BIAS}_0^\bullet = E_0^\bullet - \gamma$ ) and relative efficiencies ( $\text{REFF}_0^\bullet$ ) of the EVI-estimators under study, at their optimal levels. The search of the minimum MSE has been performed over the region of  $k$ -values between  $1$  and  $[0.9 \times n]$ . For any EVI-estimator different from  $H$ , generally denoted  $S$ , and with the notation  $S_0 = S(k_{0|S})$ , the  $\text{REFF}_0^S$  indicator is

$$\text{REFF}_0^S := \sqrt{\frac{\text{MSE}(H_0)}{\text{MSE}(S_0)}} =: \frac{\text{RMSE}_0^H}{\text{RMSE}_0^S}.$$

As an illustration, we present in Tables 1, 2 and 3, the obtained simulated results for models with  $|\rho| < 1$  (the generalized Pareto model with  $\gamma = 0.25$ , and consequently  $\rho = -\gamma = -0.25$ ),  $|\rho| = 1$  (the Burr parent with  $\gamma = 0.25$  and  $\rho = -1$ ) and  $|\rho| > 1$  (the Student parent with  $\nu = 1$ , for which  $\gamma = 1/\nu = 1$  and  $\rho = -2/\nu = -2$ ), respectively. Among the estimators considered, and for all  $n$ , the one providing the smallest squared bias and the smallest MSE, i.e., the highest REFF is underlined and in **bold**. The second highest REFF indicators are written in *italic* and underlined. The MSE of  $H_0$ , Hill estimators at their simulated optimal level, is also provided so that it is possible to recover the MSE of any other EVI-estimator. Moreover, we present the  $\text{BIAS}_0$  and  $\text{REFF}_0$  indicators of the r.v.'s  $\bar{C}_{k,n;\beta,\rho}$  at their optimal levels, with



**Table 1** Simulated bias at optimal levels ( $\text{BIAS}_0^\bullet$ ), relative efficiency indicators ( $\text{REFF}_0^\bullet$ ) and MSE of  $H_0$ , for a *generalized Pareto*  $GP_\gamma$  parent with  $\gamma = 0.25$  ( $\rho = -0.25$ )

$n$	100	200	500	1000	2000	5000
<b>BIAS<sub>0</sub><sup>•</sup></b>						
$H$	0.2352	0.1219	0.0869	0.0991	0.1292	0.0448
$\overline{H}_0$	0.1979	0.1339	0.1132	0.1007	0.1046	0.0414
$\overline{H}_1$	0.2347	0.1217	0.0908	0.0991	0.1292	0.0447
$M$	0.1290	0.0700	0.0801	0.0805	0.0644	0.0239
$\overline{M}_0$	0.1470	0.0761	0.0840	<b>0.0305</b>	<b>0.0124</b>	0.0082
$\overline{M}_1$	0.1512	0.0548	0.0801	0.0753	0.0658	0.0160
$GH$	0.1210	0.0301	<b>0.0646</b>	0.0543	0.0606	0.0097
$\overline{GH}_0$	<b>0.1169</b>	0.0337	0.0650	0.0567	0.0591	<b>0.0079</b>
$\overline{GH}_1$	0.1280	<b>0.0243</b>	0.0666	0.0576	0.0557	0.0079
$\overline{H}_{\beta,\rho}$	0.0325	0.0256	0.0212	0.0175	0.0102	0.0099
$\overline{M}_{\beta,\rho}$	0.0200	0.0098	0.0224	-0.0016	-0.0076	0.0010
$\overline{GH}_{\beta,\rho}$	0.0360	0.0177	0.0284	0.0236	0.0226	0.0086
<b>REFF<sub>0</sub><sup>•</sup></b>						
$\overline{H}_0$	1.1489	1.1170	1.0880	1.0688	1.0577	1.0421
$\overline{H}_1$	1.0015	1.0007	1.0003	1.0001	1.0001	1.0000
$M$	1.0585	1.1600	1.2506	1.3032	1.3479	1.3999
$\overline{M}_0$	1.3376	1.3194	1.3055	<b>1.4244</b>	<b>1.6963</b>	<b>2.1667</b>
$\overline{M}_1$	1.0832	1.1549	1.2346	1.2880	1.3334	1.4179
$GH$	1.3591	<u>1.3605</u>	<u>1.3798</u>	1.3946	<u>1.4166</u>	<u>1.4424</u>
$\overline{GH}_0$	<b>1.5844</b>	<b>1.4981</b>	<b>1.4313</b>	<u>1.3991</u>	1.3850	1.3767
$\overline{GH}_1$	<u>1.3654</u>	1.3563	1.3693	1.3851	1.4077	1.4364
$\overline{H}_{\beta,\rho}$	4.8574	5.3039	5.8883	6.4205	6.9599	7.7053
$\overline{M}_{\beta,\rho}$	4.1515	4.8043	5.2907	5.7535	6.7673	8.6844
$\overline{GH}_{\beta,\rho}$	4.6909	4.5833	4.4753	4.4443	4.4596	4.4941
<b>MSE</b>						
$H_0$	0.0561	0.0382	0.0238	0.0172	0.0126	0.0084

$C = H, M$  and  $GH$ , denoted  $\overline{H}_{\beta,\rho}, \overline{M}_{\beta,\rho}$  and  $\overline{GH}_{\beta,\rho}$ , respectively, just to make it clear that in most situations some improvement is still possible with a better estimation of the second-order parameters. Note however, that some times the estimation of the parameters in the model (if nicely done) accommodates better the statistical fluctuations in the sample and produces better results than the use of the “true known values”. Extensive tables for all simulated models as well as 95% confidence intervals (CIs) associated with all the estimates are available from the authors.

In summary we may draw the following final conclusions:

1. For underlying parents with  $|\rho| < 1$ , the highest efficiency is generally achieved through  $\overline{GH}_0$  for  $n < 1000$  and through  $\overline{M}_0$  otherwise. The highest bias reduction pattern is not so clear-cut, as can be seen in Table 1, but the results are not a long way from the ones related with efficiency.

**Table 2** Simulated bias at optimal levels ( $\text{BIAS}_0^\bullet$ ), relative efficiency indicators ( $\text{REFF}_0^\bullet$ ) and MSE of  $H_0$ , for a Burr parent with  $(\gamma, \rho) = (0.25, -1)$

$n$	100	200	500	1000	2000	5000
$\text{BIAS}_0^\bullet$						
$H$	0.0357	0.0112	0.0293	0.0280	0.0206	0.0115
$\overline{H}_0$	<b>0.0041</b>	<b>-0.0066</b>	<b>0.0035</b>	<b>-0.0006</b>	-0.0028	-0.0018
$\overline{H}_1$	0.0289	0.0110	0.0268	0.0278	0.0201	0.0107
$M$	-0.1557	-0.1408	-0.0481	-0.0305	-0.0132	-0.0305
$\overline{M}_0$	-0.0353	-0.0731	-0.0071	0.0043	-0.0014	-0.0026
$\overline{M}_1$	-0.1173	-0.1389	-0.0399	-0.0279	-0.0137	-0.0385
$GH$	-0.1581	-0.1364	-0.0514	-0.0395	-0.0200	-0.0403
$\overline{GH}_0$	-0.0065	-0.0210	0.0038	0.0028	-0.0007	<b>-0.0007</b>
$\overline{GH}_1$	-0.0223	-0.0354	0.0066	0.0045	<b>-0.0003</b>	-0.0008
$\overline{H}_{\beta,\rho}$	0.0206	0.0055	0.0068	0.0055	0.0029	0.0047
$\overline{M}_{\beta,\rho}$	-0.0438	-0.0760	-0.0078	-0.0023	-0.0037	-0.0042
$\overline{GH}_{\beta,\rho}$	-0.0026	-0.0199	0.0060	0.0028	-0.0006	-0.0007
$\text{REFF}_0^\bullet$						
$\overline{H}_0$	<b>1.9835</b>	<b>2.1260</b>	<b>2.4273</b>	<b>2.6968</b>	<b>2.9520</b>	<b>3.3957</b>
$\overline{H}_1$	1.0432	1.0381	1.0243	1.0196	1.0159	1.0116
$M$	0.2648	0.2909	0.3148	0.3289	0.3431	0.3530
$\overline{M}_0$	0.5120	0.5659	0.6314	0.6826	0.7363	0.8146
$\overline{M}_1$	0.3168	0.3396	0.3553	0.3631	0.3710	0.3750
$GH$	0.3287	0.3330	0.3406	0.3463	0.3540	0.3593
$\overline{GH}_0$	<u>1.2003</u>	<u>1.3118</u>	<u>1.4779</u>	<u>1.6396</u>	<u>1.8180</u>	<u>2.0970</u>
$\overline{GH}_1$	0.7779	0.8633	0.9711	1.0776	1.2145	1.4126
$\overline{H}_{\beta,\rho}$	1.8925	1.9854	2.1210	2.2252	2.3388	2.4827
$\overline{M}_{\beta,\rho}$	0.4466	0.4976	0.5544	0.5957	0.6356	0.6875
$\overline{GH}_{\beta,\rho}$	1.0802	1.1947	1.3522	1.4988	1.6665	1.9248
MSE						
$H_0$	0.0044	0.0026	0.0013	0.0008	0.0005	0.0003

- Again at optimal levels, and for underlying parents with  $\rho = -1$ , the highest bias reduction as well as the highest efficiency is generally achieved through the use of  $\overline{H}_0$ , followed by  $\overline{GH}_0$ . Only for very large values of  $n$ , say  $n \geq 2000$ , did  $\overline{GH}_0$  beat  $\overline{H}_0$  regarding the bias-indicator (refer to Table 2).
- Almost generally, and for models such that  $|\rho| \leq 1$ ,  $\overline{M}_0$  ( $\overline{GH}_0$ ) works better than  $M$  ( $GH$ ). But, for models with  $|\rho| = 1$ ,  $\overline{M}_0$  never beats  $\overline{H}_0$  regarding efficiency. Regarding bias reduction,  $\overline{GH}_0$  beats  $\overline{H}_0$  for large  $n$ , almost generally.
- For the range of  $\rho$ -values close to zero ( $-1 \leq \rho \leq 0$ ), the use of  $\tau = 1$  in  $\overline{H}_\tau$  provides results only slightly better than the ones associated with the classical estimator.

**Table 3** Simulated bias at optimal levels ( $BIAS_0^\bullet$ ), relative efficiency indicators ( $REFF_0^\bullet$ ) and MSE of  $H_0$ , for a Student parent with  $\nu = 1$  degrees of freedom ( $\gamma = 1, \rho = -2$ )

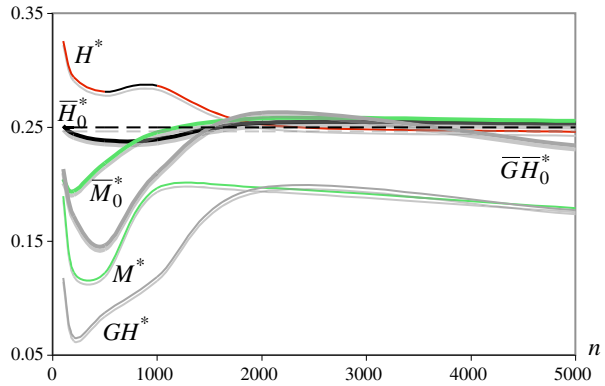
$n$	100	200	500	1000	2000	5000
$BIAS_0^\bullet$						
$H$	0.0794	0.1117	0.0936	0.0471	0.0573	0.0254
$\overline{H}_0$	-0.2632	-0.0608	0.0845	-0.0195	0.0250	<b>-0.0048</b>
$\overline{H}_1$	-0.1252	<b>0.0222</b>	0.0744	0.0116	0.0390	0.0275
$M$	<b>-0.0142</b>	0.0704	0.0915	0.0240	0.0539	0.0051
$\overline{M}_0$	-0.2392	-0.0999	<b>0.0018</b>	-0.0820	-0.0390	-0.0849
$\overline{M}_1$	-0.1865	-0.0235	0.0761	<b>0.0068</b>	0.0380	0.0073
$GH$	-0.0210	0.0503	0.0719	0.0190	0.0421	0.0334
$\overline{GH}_0$	-0.6775	-0.0997	0.0710	-0.0188	<b>0.0235</b>	0.0179
$\overline{GH}_1$	-0.6224	-0.0371	0.0667	0.0084	0.0328	0.0301
$\overline{H}_{\beta,\rho}$	0.0397	0.0488	0.0479	0.0144	0.0207	0.0152
$\overline{M}_{\beta,\rho}$	-0.0950	0.0021	0.0198	-0.0128	0.0039	-0.0073
$\overline{GH}_{\beta,\rho}$	-0.0805	0.0008	0.0413	0.0126	0.0274	0.0310
$REFF_0^\bullet$						
$\overline{H}_0$	0.2359	0.5818	0.9376	0.9826	1.1084	<b>1.3939</b>
$\overline{H}_1$	0.2073	0.7966	<b>1.1590</b>	<b>1.1583</b>	<b>1.1593</b>	1.1641
$M$	0.7932	0.8668	0.9151	0.9234	0.9232	0.9273
$\overline{M}_0$	0.2145	0.5045	0.7283	0.7116	0.6741	0.6095
$\overline{M}_1$	0.1895	0.6698	0.9660	0.9962	1.0299	1.0676
$GH$	<b>1.0459</b>	<b>1.0683</b>	1.0600	1.0469	1.0266	1.0102
$\overline{GH}_0$	0.2969	0.5618	0.9363	0.9948	1.1002	<u>1.3348</u>
$\overline{GH}_1$	0.2705	0.7593	<u>1.1151</u>	<u>1.1165</u>	<u>1.1260</u>	1.1406
$\overline{H}_{\beta,\rho}$	1.3399	1.4229	1.5261	1.6359	1.7199	1.8236
$\overline{M}_{\beta,\rho}$	0.9507	1.1146	1.2612	1.3644	1.4499	1.5628
$\overline{GH}_{\beta,\rho}$	1.1897	1.3858	1.4854	1.5209	1.5228	1.5304
MSE						
$H_0$	0.0693	0.0370	0.0166	0.0095	0.0053	0.0025

5. For underlying parents with  $\rho < -1$ , bias-reduced estimators work only for large  $n$ , say  $n \geq 500$ . Then the highest efficiency is generally achieved through the use of  $\overline{H}_1$ , followed by  $\overline{GH}_1$ . Again, and even worse than for the case  $|\rho| < 1$ , the highest bias reduction pattern is not clear-cut, as can be seen in Table 3.

### 5.2 Adaptive estimation

In order to better understand the performance of the adaptive bootstrap estimates as well as of bootstrap CIs, we have run Steps 6.–10. of the Algorithm in Section 4.2,  $r_1 = 100$  times, for the models considered in Section 5.1, and for  $B = 250$ . The overall estimates of  $\gamma$ , denoted  $H^*, \overline{H}_\tau^*, M^*, \overline{M}_\tau^*, GH^*$  and  $\overline{GH}_\tau^*$ ,  $\tau = 0$  or  $1$ , are the averages of the corresponding  $r_1$  partial estimates.

**Fig. 4** Bootstrap adaptive EVI-estimates as a function of the sample size  $n$ , for data simulated from a Fréchet parent with  $\gamma = 0.25$  ( $\rho = -1$ )



5.2.1 Bootstrap EVI-estimates and CIs

In Fig. 4, and as an illustration of the overall simulated behaviour of the bootstrap adaptive estimates,  $\hat{\gamma}^*$ , with  $\hat{\gamma} = H, M, GH, \bar{H}_0, \bar{M}_0$  and  $\overline{GH}_0$ , we present, for a Fréchet model with  $\gamma = 0.25$ , the bootstrap adaptive EVI-estimates, as a function of the sample size  $n$ . The method works asymptotically, as can be seen from Fig. 4. But it also works for small  $n$ , particularly if we take into account the estimate  $\bar{H}_0^*$ .

Those estimates are also given in Table 4, with associated standard errors provided between parenthesis, close to the estimates, at the first row of each entry. In the second row of each entry, we present the 99% bootstrap CIs. These bootstrap CIs are based on the quantiles of probability 0.005 and 0.995 of the  $r_1 = 100$  partial

**Table 4** Bootstrap adaptive estimates of  $\gamma$  through the classical  $C$  estimators, and the associated CVRB estimators  $\bar{C}_\tau$ , with  $\tau = 0$ , for  $C = H, M$  and  $GH$  and for an underlying Fréchet parent, with  $\gamma = 0.25$  ( $\rho = -1$ )

$H^*$	$\bar{H}_0^*$	$M^*$	$\bar{M}_0^*$	$GH^*$	$\overline{GH}_0^*$
$n = 100$					
0.326 (0.0079)	0.251 (0.0044)	0.190 (0.0248)	0.205 (0.0139)	0.118 (0.1081)	0.213 (0.0815)
(0.3003, 0.3416)	(0.2289, 0.2587)	(0.1122, 0.2452)	(0.1867, 0.2620)	(-0.0689, 0.2798)	(-0.0635, 0.2993)
$n = 200$					
0.294 (0.0136)	0.244 (0.0075)	0.123 (0.0201)	0.194 (0.0351)	0.066 (0.1083)	0.172 (0.1281)
(0.2758, 0.3181)	(0.2106, 0.2521)	(0.0804, 0.1668)	(0.1548, 0.2936)	(-0.3605, 0.1823)	(-0.3409, 0.2759)
$n = 500$					
0.281 (0.0196)	0.239 (0.0031)	0.122 (0.0127)	0.219 (0.0068)	0.087 (0.0783)	0.147 (0.1205)
(0.2404, 0.3080)	(0.2332, 0.2457)	(0.0854, 0.1561)	(0.2045, 0.2297)	(-0.1410, 0.1653)	(-0.1853, 0.2566)
$n = 1000$					
0.286 (0.0021)	0.240 (0.0008)	0.197 (0.0061)	0.246 (0.0063)	0.119 (0.1442)	0.210 (0.1210)
(0.2819, 0.2905)	(0.2382, 0.2414)	(0.1841, 0.2181)	(0.2370, 0.2626)	(-0.4448, 0.2032)	(-0.4258, 0.2627)
$n = 2000$					
0.253 (0.0092)	0.254 (0.0004)	0.197 (0.0073)	0.258 (0.0023)	0.197 (0.1327)	0.263 (0.0931)
(0.2529, 0.2548)	(0.2233, 0.2626)	(0.1885, 0.2172)	(0.2436, 0.2645)	(-0.0766, 0.6833)	(0.1698, 0.7219)
$n = 5000$					
0.254 (0.0159)	0.246 (0.0023)	0.179 (0.0041)	0.256 (0.0082)	0.177 (0.1032)	0.234 (0.0422)
(0.2501, 0.2578)	(0.2430, 0.2541)	(0.1751, 0.1938)	(0.2301, 0.2665)	(-0.0951, 0.4413)	(0.1593, 0.2788)

bootstrap estimates, and are written in *italic* whenever they do not cover the true value of  $\gamma$ , with the upper limit smaller than  $\gamma$  (underestimation). They are written in *italic* and underlined, whenever they do not cover the true value of  $\gamma$ , with the lower limit larger than  $\gamma$  (overestimation).

A few comments on the bootstrap adaptive EVI-estimates and CIs:

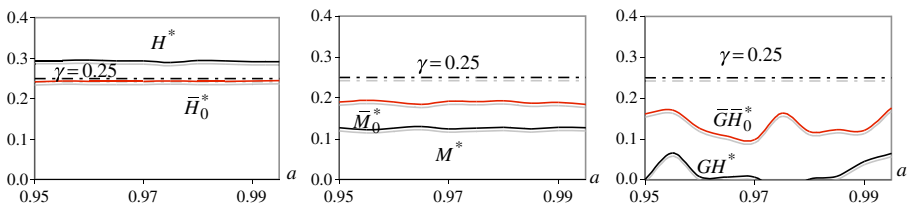
- Almost generally, the bootstrap  $M^*$  and  $GH^*$ -estimates provide a systematic under-estimation of  $\gamma$ , which is compensated by the consideration of the associated CVRB-estimates.
- On another side, and except for  $EV_\gamma$  underlying parents, the bootstrap  $H^*$ -estimates provide a systematic over-estimation of  $\gamma$ , which is again compensated by the consideration of the associated CVRB-estimates,  $\overline{H}^*$ . Moreover, for several values of  $n$ , the bootstrap 99% CIs, associated with the  $H^*$ -estimates, have lower limits above  $\gamma$ .
- The 99% bootstrap CIs associated with  $\overline{GH}^*$  do always cover the true value of  $\gamma$ , but at expenses of very large sizes. Moreover, and despite of the volatility of the simulated  $GH^*$  estimates, some of the associated 99% bootstrap CIs have upper limits below  $\gamma$ .
- In general, and despite of a slight under-estimation for a few values of  $n$  and some of the simulated parents, the results are clearly in favour of the bootstrap  $\overline{H}^*$ -estimation procedure. However, the performance of  $\overline{M}^*$  is also interesting for most of the simulated underlying parents, particularly for large sample size  $n$ .

### 5.2.2 Sensitivity of the algorithm to the subsample size $n_1$

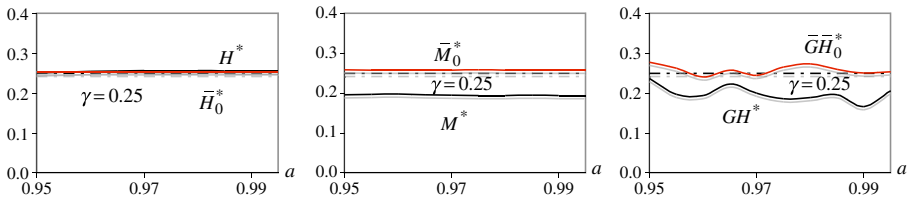
In order to detect the sensitivity of the algorithm to changes of  $n_1$ , we have run it for values of  $n_1 = [n^a]$ ,  $a = 0.950(0.005)0.995$ . In Figs. 5 and 6, and again as an illustration, we present for the same Fréchet underlying parent, the bootstrap  $\gamma$ -estimates as a function of  $a$ , for  $n = 200$  and  $n = 2000$ , respectively.

A few comments on the results:

- As expected, and due to the fact that the method works asymptotically, there is a general improvement in the estimation as the sample size,  $n$ , increases.
- The sensitivity of the *Algorithm* in Section 4.2 to the nuisance parameter  $n_1$  is weak for  $H^*$ ,  $\overline{H}^*$ ,  $M^*$  and  $\overline{M}^*$ , particularly if  $n$  is large. Such a dependency is however not so weak for both  $GH^*$  and  $\overline{GH}^*$ .



**Fig. 5** Bootstrap adaptive EVI-estimates, for samples of size  $n = 200$  from a Fréchet parent with  $\gamma = 0.25$  ( $\rho = -1$ )



**Fig. 6** Bootstrap adaptive EVI-estimates, for samples of size  $n = 2000$  from a Fréchet parent with  $\gamma = 0.25$  ( $\rho = -1$ )

5.2.3 Bootstrap CIs’ sizes and coverage probabilities

Due to the reasonably high number of bootstrap 99% CIs not covering the true value of  $\gamma$  (see Table 4), we felt the need and the curiosity of analyzing the performance of these bootstrap CIs, on the basis of a terribly time-consuming computer program. More specifically, in order to obtain information on the coverage probabilities and on the sizes of the bootstrap CIs, we have also run  $r_2 = 100$  times, the whole algorithm in Section 4.2, after the  $r_1 = 100$  replicates of **Steps 6.– 10.**, suggested in Section 5.2. This is a terrible time-consuming algorithm, and we have thus run it only for small values of  $n$ . Again as an illustration, we provide in Table 5, for a Student  $t_2$  underlying parent and for  $n = 100, 200$  and  $1000$ , the overall EVI-estimates, the sizes of the 99% bootstrap CIs and the coverage probabilities of those CIs, in the first, second and third row, respectively. The overall EVI-estimate closer to the target, the minimum size and the maximum coverage probability are written in **bold**.

**Table 5** Overall EVI-estimates (first row), sizes (second row) and percentage coverage probabilities (third row) of the 99% bootstrap CI’s for  $\gamma$ , obtained on the basis of the classical  $C$  estimators, and the associated CVRB estimators  $\overline{C}_\tau$ , with  $\tau = 0$  and  $\tau = 1$ , for  $C = H, M$  and  $GH$  and for an underlying Student  $t_\nu$  parent, with  $\nu = 2$  ( $\gamma = 1/\nu = 0.5, \rho = -2/\nu = -1$ )

	$H^*$	$\overline{H}_0^*$	$\overline{H}_1^*$	$M^*$	$\overline{M}_0^*$	$\overline{M}_1^*$	$GH$	$\overline{GH}_0^*$	$\overline{GH}_1^*$
$n = 100$	0.5751	<b>0.4882</b>	0.5885	0.4010	0.4238	0.4042	0.4753	0.4815	0.5427
	0.1880	<b>0.1427</b>	0.2443	0.2431	0.2354	0.3850	0.6440	0.4842	0.5974
	29%	31%	35%	27%	31%	36%	54%	44%	<b>55%</b>
$n = 200$	0.5648	<b>0.4898</b>	0.5881	0.4362	0.4406	0.4704	0.4800	0.4818	0.5366
	0.1573	<b>0.1154</b>	0.1899	0.17320	0.1722	0.2323	0.7195	0.5486	0.6544
	29%	34%	31%	33%	36%	46%	64%	52%	<b>67%</b>
$n = 1000$	0.5479	<b>0.4994</b>	0.5623	0.4877	0.4702	0.4965	0.5362	0.5220	0.5772
	0.1139	<b>0.0862</b>	0.1327	0.1315	0.1396	0.2705	1.2217	0.7944	1.0453
	28%	40%	27%	30%	31%	55%	82%	<b>84%</b>	81%

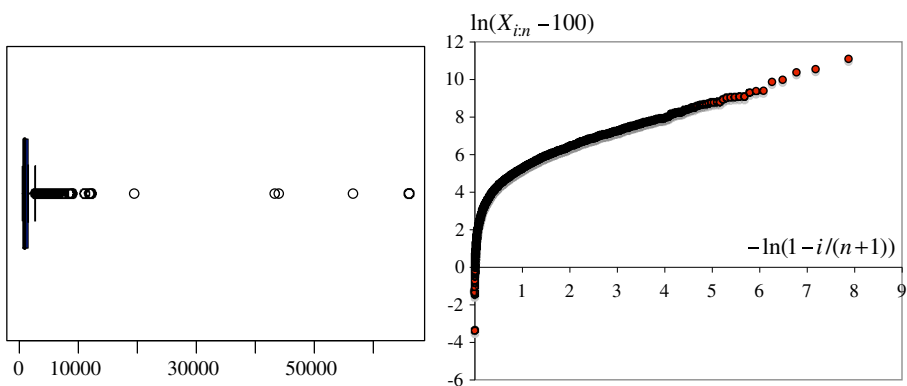
A few general comments:

- We need to be careful with the use of bootstrap CIs. We can indeed get very small coverage probabilities, comparatively with the target value, 0.99.
- Large coverage probabilities are attained only by the bootstrap  $GH^*$  and  $\overline{GH}^*$  estimates, but at expenses of a very large size.
- As expected, and in general, there is a decreasing trend in the sizes, as  $n$  increases, and a slight increasing trend in the coverage probabilities. However, in some cases, the coverage probabilities decrease with  $n$ .
- As a compromise between size and coverage probability, we are inclined to the choice of  $\overline{H}_0^*$  whenever  $|\rho| \leq 1$  and  $\overline{M}_1^*$  for models with  $|\rho| > 1$ . Indeed, these bootstrap EVI-estimates are quite close to the target  $\gamma$ .

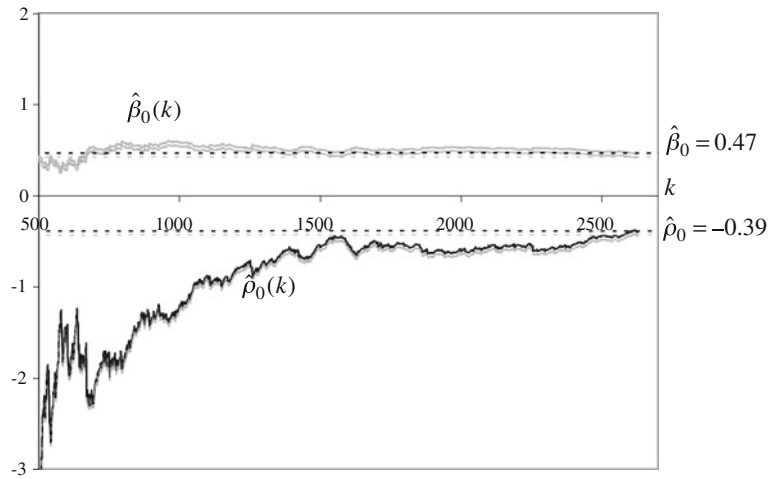
## 6 An application to burned areas data

Most of the wildfires are extinguished within a short period of time, with almost negligible effects. However, some wildfires go out of control, burning hectares of land and causing significant and negative environmental and economical impacts. The data we analyse here consists of the number of hectares, exceeding 100 ha, burnt during wildfires recorded in Portugal during 14 years (1990–2003). The data (a sample of size  $n = 2627$ ) do not seem to have a significant temporal structure, and we have used the data as a whole, although we think also sensible, to try avoiding spatial heterogeneity, the consideration of at least 3 different regions: the north, the centre and the south of Portugal (a study out of the scope of this paper). Also, it would be nice to have some kind of model diagnosis to build up the confidence that Eq. 2.6 holds for a real data set, a topic out of the scope of this paper. However, and on the basis of simulation results, we are confident on the robustness of the methodology in this paper to a possible model misspecification.

The box-plot and the Pareto quantile plot of the available data, in Fig. 7, provide evidence on the heaviness of the right tail.



**Fig. 7** Box-and-whiskers plot (*left*) and Pareto quantile plot (*right*) associated with burned areas in Portugal over 100 ha (1990–2003)

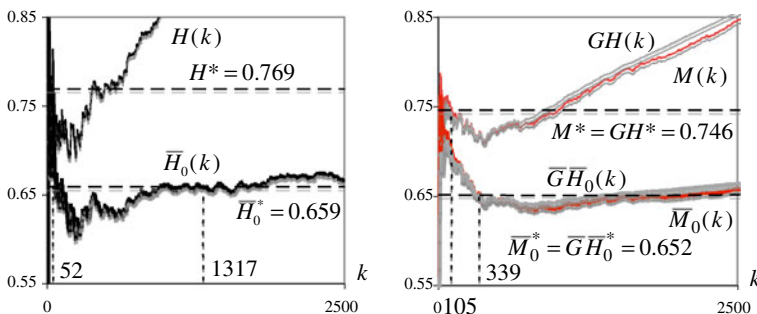


**Fig. 8** Estimates of the shape second-order parameter  $\rho$  and of the scale second-order parameter  $\beta$  for the burned areas data

In Fig. 8, we present the sample path of the  $\hat{\rho}_\tau(k)$  estimates in Eq. 4.8, as function of  $k$ , for  $\tau = 0$ , together with the sample paths of the associated  $\beta$ -estimators in Eq. 4.9, also for  $\tau = 0$ , the value obtained in the Algorithm of Section 4.2 for the tuning parameter  $\tau$ . We have been led to the  $\rho$ -estimate,  $\hat{\rho} \equiv \hat{\rho}_0 = -0.39$ , obtained at the level  $k_1 = \lceil n^{0.999} \rceil = 2606$ , and to the associated  $\beta$ -estimate,  $\hat{\beta} \equiv \hat{\beta}_0 = 0.47$ , both recorded in Fig. 8.

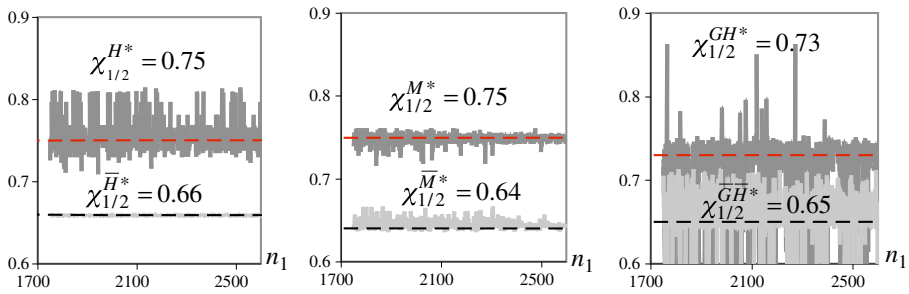
Next, in Fig. 9, we present the adaptive and non-adaptive EVI-estimates provided by  $H$  and associated MVRB estimates  $\bar{H}$  (left), as well as  $M$ ,  $GH$  and the associated CVRB estimates,  $\bar{M}$  and  $\bar{GH}$  (right).

For the Hill estimator, we have simple techniques to estimate the OSF. Indeed, we get  $\hat{k}_0^H(n) = \left[ \left( (1 - \hat{\rho})^2 n^{-2\hat{\rho}} / (-2 \hat{\rho} \hat{\beta}^2) \right)^{1/(1-2\hat{\rho})} \right] = 157$ , and an associated  $\gamma$ -estimate equal to 0.73. The algorithm in this paper helps us to adaptively estimate the OSF associated not only with the classical EVI-estimates but also with the MVRB or even CVRB estimates. For a sub-sample size  $n_1 = \lceil n^{0.955} \rceil = 1843$ , and  $B = 250$



**Fig. 9** Estimates of the EVI,  $\gamma$ , through the EVI estimators under consideration,  $H$ ,  $M$  and  $GH$  and associated CVRB estimators,  $\bar{H}$ ,  $\bar{M}$  and  $\bar{GH}$ , for the burned areas under analysis



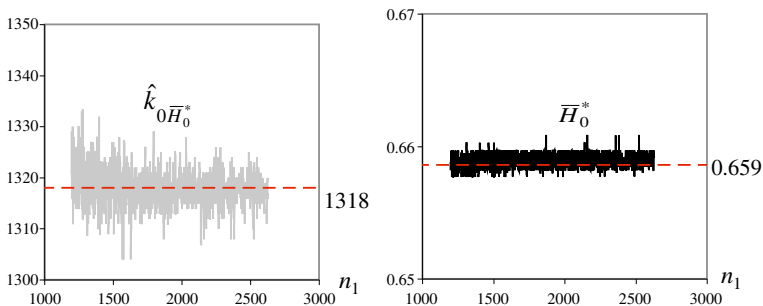


**Fig. 10** Bootstrap adaptive estimates of the EVI,  $\gamma$ , as a function of the subsample size  $n_1$ , done through  $(H^*, \bar{H}_0^*)$  (left),  $(M^*, \bar{M}_0^*)$  (center) and  $(GH^*, \bar{GH}_0^*)$  (right), for the burned areas data under analysis

bootstrap generations, we have got  $\hat{k}_{0\bar{H}}(n; n_1) = 1317$  and the MVRB-EVI-estimate  $\bar{H}^* = 0.659$ , the value pictured in Fig. 9, left, jointly with the bootstrap adaptive Hill estimate,  $H^*$ , equal to 0.769, due to the fact that we were led to  $\hat{k}_{0H}(n; n_1) = 52$ . The estimated RMSEs, in **Step 11**, of the *Algorithm*, were  $RMSE_H^* = 0.164$  and  $RMSE_{\bar{H}_0}^* = 0.049$ . Again with  $W$  denoting either  $M$  or  $GH$ , we were led to  $\hat{k}_{0W}(n; n_1) = 105$ ,  $\hat{k}_{0\bar{W}}(n; n_1) = 339$ ,  $W^* = 0.746$  and  $\bar{W}^* = 0.652$ , the values pictured at Fig. 9 (right). The estimated RMSEs were  $RMSE_W^* = 0.173$  and  $RMSE_{\bar{W}_0}^* = 0.276$ . Note the fact that the MVRB EVI-estimators look practically “unbiased” for the data under analysis and the associated adaptive estimator  $\bar{H}_0^*$ , was the one chosen, due to the smallest estimated RMSE, the value  $RMSE_{\bar{H}_0}^* = 0.049$ .

Regarding the dependency of the bootstrap methodology on the subsample size  $n_1$ , we refer to Fig. 10, where apart from the adaptive bootstrap estimates we also picture the medians of the values obtained for  $n_1 = 1750(1)2600$ .

It is clear the small sensitivity, to changes in  $n_1$ , of  $\bar{H}_0^*(n; n_1)$ , contrarily to the high sensitivity of  $GH^*(n; n_1)$ . We consider this to be another point in favour of  $\bar{H}_0^*$ . The consideration of all the above mentioned values of  $n_1$ , i.e.,  $n_1 = 1750, 1751, \dots, 2600$  led us to a minimum RMSE given by  $RMSE_{\bar{H}_0}^* = 0.018$ , attained at  $n_1 = 1320$ , with an associated EVI-estimate given by  $\bar{H}_0^* = 0.66$ , just as before. We finally exhibit, in Fig. 11, not only a zoom of the adaptive bootstrap



**Fig. 11** Bootstrap adaptive estimates of the optimal level (left) and of the EVI (right), done through the adaptive MVRB estimator,  $\bar{H}_0^*$ , for the burned areas data under analysis

estimates  $\overline{H}_0^*$  (right) but also of  $\hat{k}_{0\overline{H}_0^*}$  (left), again as a function of  $n_1$ , as well as the medians of the values obtained for  $n_1$  from 1750 until 2600, with step 1.

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