

Two classes of optimal two-dimensional OOCs

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Abstract Let $\Phi(u \times v, k, \lambda_a, \lambda_c)$ denote the largest possible size among all 2-D $(u \times v, k, \lambda_a, \lambda_c)$ -OOCs. In this paper, the exact value of $\Phi(u \times v, k, \lambda_a, k - 1)$ for $\lambda_a = k - 1$ and k is determined. The case $\lambda_a = k - 1$ is a generalization of a result in Yang (Inform Process Lett 40:85–87, 1991) which deals with one dimensional OOCs namely, $u = 1$.

Keywords Optimal · Two-dimensional optical orthogonal code · Orbit · Stabilizer

Mathematics Subject Classification (2000) 05B30

1 Introduction

An optical orthogonal code is a family of $(0, 1)$ -matrices with good auto- and cross-correlation properties. Its study has been motivated by applications in an optical code-division multiple access (OCDMA) system. For more information, the interested reader may refer to [18, 21, 22, 25, 26].

Let u, v, k, λ_a and λ_c be positive integers. A *two-dimensional* $(u \times v, k, \lambda_a, \lambda_c)$ *optical orthogonal code* (briefly, 2-D $(u \times v, k, \lambda_a, \lambda_c)$ -OOC), \mathcal{C} , is a family of $u \times v$ $(0, 1)$ -matrices (called *codewords*) of Hamming weight k satisfying the following two correlation properties:

- (1) The auto-correlation property: $\sum_{i=0}^{u-1} \sum_{j=0}^{v-1} a_{ij} a_{i, j+\tau} \leq \lambda_a$ for any matrix $\mathbf{A} = (a_{ij})_{u \times v} \in \mathcal{C}$ and any integer $\tau \not\equiv 0 \pmod{v}$;
- (2) The cross-correlation property: $\sum_{i=0}^{u-1} \sum_{j=0}^{v-1} a_{ij} b_{i, j+\tau} \leq \lambda_c$ for any matrices $\mathbf{A} = (a_{ij})_{u \times v} \in \mathcal{C}$, $\mathbf{B} = (b_{ij})_{u \times v} \in \mathcal{C}$ with $\mathbf{A} \neq \mathbf{B}$, and any integer τ ,

where the integer $j + \tau$ is reduced modulo v . The number of codewords of \mathcal{C} is called the *size* of \mathcal{C} . Let $\Phi(u \times v, k, \lambda_a, \lambda_c)$ denote the largest possible size among all 2-D $(u \times v, k, \lambda_a, \lambda_c)$ -

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OOCs. A 2-D $(u \times v, k, \lambda_a, \lambda_c)$ -OOC with $\Phi(u \times v, k, \lambda_a, \lambda_c)$ codewords is said to be *optimal*. A 2-D $(1 \times v, k, \lambda_a, \lambda_c)$ -OOC is usually called one-dimensional $(v, k, \lambda_a, \lambda_c)$ -OOC (or 1-D $(v, k, \lambda_a, \lambda_c)$ -OOC). When $\lambda_a = \lambda_c = \lambda$, the notations of 2-D $(u \times v, k, \lambda)$ -OOC and $\Phi(u \times v, k, \lambda)$ are employed the abbreviated notation. From the definition of optimal OOC, it is straightforward that an optimal 2-D OOC exists for all parameter values: it is simply an OOC of the largest possible size. Determining $\Phi(u \times v, k, \lambda_a, \lambda_c)$ for the parameters u, v, k, λ_a and λ_c is apparently a difficult task.

Throughout the present paper let $\Omega(u \times v, k)$ be the set of all k -subsets of $I_u \times Z_v$, where $I_u = \{0, 1, \dots, u - 1\}$ and Z_v is the residue group of integers modulo v . The notion of 2-D OOCs can be more conveniently reformulated as follows. By identifying codewords in \mathcal{C} with k -subsets of $I_u \times Z_v$ representing the indices of the nonzero positions in a matrix, \mathcal{C} can be viewed as a family $\mathcal{F} \subseteq \Omega(u \times v, k)$ satisfying the following two properties:

- (1') The auto-correlation property: $|X \cap (X + \tau)| \leq \lambda_a$ for any $X \in \mathcal{F}$ and every $\tau \in Z_v \setminus \{0\}$;
- (2') The cross-correlation property: $|X \cap (Y + \tau)| \leq \lambda_c$ for any $X, Y \in \mathcal{F}$ with $X \neq Y$ and every $\tau \in Z_v$,

where $X + i = \{(x, y + i) : (x, y) \in X\}$ and all the additive operations are performed in Z_v .

The research on optimal 1-D OOC has concentrated on the case when $\lambda_a = \lambda_c$ in many papers, see, for example, [1–3, 6, 11, 8–10, 12–17, 19, 20, 35]; a little work has been done on the case when $\lambda_a \neq \lambda_c$, the reader refers to [5, 23, 31]. For the research on optimal 2-D OOC, the reader may refer to [4, 7, 24, 27, 29, 32, 34] and the references therein. It should be mentioned that because of the practical point of view in the definition of OOC λ_a must be less than k . Therefore $\lambda_a = k$ is an extreme case.

For any $g \in Z_v$ and $B \in \Omega(u \times v, k)$, define $B + g = \{(x, y + g) : (x, y) \in B\}$. Then Z_v acts on $\Omega(u \times v, k)$. The orbit generated by B is defined by the set of all distinct $B + g$ where g takes over Z_v . If an orbit has v elements, then the orbit is said to be *full*, otherwise *short*. The subgroup $\{g \in Z_v : B + g = B\}$ is called the *stabilizer* of B in Z_v . We know that $\Omega(u \times v, k)$ can be partitioned into some orbits.

In the present paper we consider two classes of optimal 2-D $(u \times v, k, \lambda_a, k - 1)$ -OOCs, where $\lambda_a = k - 1, k$. In this situation, let $\mathcal{F} \subseteq \Omega(u \times v, k)$ be a 2-D $(u \times v, k, \lambda_a, k - 1)$ -OOC. By (2') of the definition, X and Y belong to distinct orbits of $\Omega(u \times v, k)$ if $X, Y \in \mathcal{F}$ with $X \neq Y$. Combined with the property (1') of the definition, we have the following lemma.

Lemma 1.1 $\Phi(u \times v, k, k - 1)$ is the number of all full orbits in $\Omega(u \times v, k)$;
 $\Phi(u \times v, k, k, k - 1)$ is the number of all orbits in $\Omega(u \times v, k)$.

In the rest of this paper, we will determine the number of all full orbits (or all orbits, respectively) in $\Omega(u \times v, k)$. We then give two classes of optimal 2-D $(u \times v, k, \lambda_a, k - 1)$ -OOCs where $\lambda_a = k - 1, k$.

2 Exact value of $\Phi(u \times v, k, k - 1)$

To determine the exact value of $\Phi(u \times v, k, k - 1)$, by Lemma 1.1 we only need to find the number of all full orbits in $\Omega(u \times v, k)$. Before proceeding, we recall that the well-known Möbius function is defined as follows.

$$\mu(n) = \begin{cases} 1, & \text{if } n = 1, \\ (-1)^r, & \text{if } n \text{ is the product of } r \text{ distinct} \\ & \text{prime numbers,} \\ 0, & \text{if } n \text{ has a square factor.} \end{cases}$$

The following result on Möbius function is well-known, for example, see [30, Theorem 10.3].

Lemma 2.1

$$\sum_{d|n} \mu(d) = \begin{cases} 1 & n = 1, \\ 0 & n \neq 1, \end{cases}$$

where $d | n$ means that d runs over all positive factors of n .

Lemma 2.2 *Let $B \in \Omega(u \times v, k)$. Then the order d of the stabilizer of B in Z_v is a divisor of (k, v) . Furthermore, B can be written as $B = \cup_{i=0}^{d-1} (B_0 + \frac{vi}{d})$ for some $B_0 \in \Omega(u \times \frac{v}{d}, \frac{k}{d})$, where $B_0 + vi/d = \{(x, y + vi/d) : (x, y) \in B_0\}$.*

Proof Let $B = \{(x_1, y_1), (x_2, y_2), \dots, (x_k, y_k)\}$, where $x_i \in I_u$ and $y_i \in Z_v$ for $1 \leq i \leq k$. The stabilizer of B is $G_B = \{\delta \in Z_v : B + \delta = B\}$. Since G_B is a subgroup of order d in Z_v , we have $d|v$ and $G_B = \langle v/d \rangle$. Noting that $B + v/d = B$, we then conclude that

$$\sum_{i=1}^k y_i = \sum_{i=1}^k (y_i + \frac{v}{d}),$$

which implies that $\frac{kv}{d} \equiv 0 \pmod{v}$, i.e. $k \equiv 0 \pmod{d}$. Hence, d is a divisor of (k, v) .

Define

$$B_0 = \{(x, y) : (x, y) \in B, 0 \leq y \leq v/d - 1\}.$$

It is easy to see that $(B_0 + vi/d) \cap (B_0 + vj/d) = \emptyset$ for $i \neq j$ and $0 \leq i, j \leq d - 1$. Note that if $(x, y) \in B$ then $(x, y + vi/d) \in B$ for any $0 \leq i \leq d - 1$. Then $\cup_{i=0}^{d-1} (B_0 + vi/d) \subseteq B$. From the definition of B_0 , clearly $B \subseteq \cup_{i=0}^{d-1} (B_0 + vi/d)$. Hence $B = \cup_{i=0}^{d-1} (B_0 + vi/d)$ and then $|B_0| = k/d$. We know that $B_0 \in \Omega(u \times \frac{v}{d}, \frac{k}{d})$. □

Lemma 2.3 *Let $g_d(u \times v, k)$ denote the number of k -subsets $B \in \Omega(u \times v, k)$ such that the order of the stabilizer of B is d . Then*

$$|\Omega(u \times v, k)| = \sum_{d|(k,v)} g_d(u \times v, k) = \binom{uv}{k}.$$

Proof From the definition of $\Omega(u \times v, k)$, we have $|\Omega(u \times v, k)| = \binom{uv}{k}$. Let Ω_d denote the set of k -subsets $B \in \Omega(u \times v, k)$ such that the order of stabilizer of B is d . Then $g_d(u \times v, k) = |\Omega_d|$. By Lemma 2.2 it follows that $d|(k, v)$. By the definition of Ω_d , we have $\Omega(u \times v, k) = \cup_{d|(k,v)} \Omega_d$. Therefore, $|\Omega(u \times v, k)| = \sum_{d|(k,v)} |\Omega_d| = \sum_{d|(k,v)} g_d(u \times v, k) = \binom{uv}{k}$. □

Lemma 2.4 *Let $g_d(u \times v, k)$ denote the number of k -subsets $B \in \Omega(u \times v, k)$ such that the order of the stabilizer of B is d . Then the number of all k -subsets in $\Omega(u \times v, k)$ with trivial stabilizer is*

$$g_1(u \times v, k) = \sum_{d|(k,v)} \mu(d) \binom{\frac{uv}{d}}{\frac{k}{d}}.$$

Proof Let $\alpha = (k, v)$. For given $d \mid \alpha$, we consider the set $\bar{\Omega}(u \times \frac{v}{d}, \frac{k}{d})$ of all (k/d) -subsets of $I_u \times Z_{v/d}$. Denote by $\bar{g}_x(u \times \frac{v}{d}, \frac{k}{d})$ the number of (k/d) -subsets $B \in \bar{\Omega}(u \times \frac{v}{d}, \frac{k}{d})$ such that the order of stabilizer of B is x , where $x \mid \frac{\alpha}{d}$. Applying Lemma 2.3 gives the following formula,

$$\left| \bar{\Omega}\left(u \times \frac{v}{d}, \frac{k}{d}\right) \right| = \sum_{x \mid \frac{\alpha}{d}} \bar{g}_x\left(u \times \frac{v}{d}, \frac{k}{d}\right) = \binom{\frac{uv}{d}}{\frac{k}{d}}. \tag{2.1}$$

Consider the 1-1 mapping σ from $\bar{\Omega}(u \times \frac{v}{d}, \frac{k}{d})$ onto $\Omega(u \times v, k)$ given by

$$\sigma(B_0) = \bigcup_{i=0}^{d-1} \left(B_0 + \frac{vi}{d} \right)$$

for any $B_0 \in \bar{\Omega}(u \times \frac{v}{d}, \frac{k}{d})$. By Lemma 2.2, it is not difficult to show that the stabilizer of B_0 in $\bar{\Omega}(u \times \frac{v}{d}, \frac{k}{d})$ is x if and only if the stabilizer of $\sigma(B_0)$ in $\Omega(u \times v, k)$ is dx . We then have $\bar{g}_x(u \times \frac{v}{d}, \frac{k}{d}) = g_{dx}(u \times v, k)$. Hence, by formula (2.1), we have

$$\begin{aligned} \sum_{x \mid \frac{\alpha}{d}} \bar{g}_x\left(u \times \frac{v}{d}, \frac{k}{d}\right) &= \sum_{x \mid \frac{\alpha}{d}} g_{dx}(u \times v, k) \\ &= \sum_{d \mid x \mid \alpha} g_x(u \times v, k) = \binom{\frac{uv}{d}}{\frac{k}{d}}. \end{aligned}$$

Therefore, using Lemma 2.1, we then have

$$\begin{aligned} &\sum_{d \mid \alpha} \mu(d) \binom{\frac{uv}{d}}{\frac{k}{d}} \\ &= \sum_{d \mid \alpha} \sum_{d \mid x \mid \alpha} g_x(u \times v, k) \mu(d) = \sum_{x \mid \alpha} \sum_{d \mid x} g_x(u \times v, k) \mu(d) \\ &= \sum_{x \mid \alpha} g_x(u \times v, k) \sum_{d \mid x} \mu(d) = g_1(u \times v, k). \end{aligned}$$

□

Theorem 2.5 *Let u, v and k be positive integers. Then*

$$\Phi(u \times v, k, k - 1) = \frac{1}{v} \sum_{d \mid (k, v)} \mu(d) \binom{\frac{uv}{d}}{\frac{k}{d}}.$$

Proof From the definition of 2-D OOC, $\Phi(u \times v, k, k - 1)$ is actually the number of all full orbits of the group action $(Z_v, \Omega(u \times v, k))$. Since each full orbit contains exactly v k -subsets of $\Omega(u \times v, k)$ with trivial stabilizer, by Lemma 2.4, we obtain

$$\begin{aligned} \Phi(u \times v, k, k - 1) &= \frac{1}{v} g_1(u \times v, k) \\ &= \frac{1}{v} \sum_{d \mid (k, v)} \mu(d) \binom{\frac{uv}{d}}{\frac{k}{d}}. \end{aligned}$$

□

Taking $u = 1$ in Theorem 2.5, we have the following corollary, which was first proved by Yang [33].

Corollary 2.6 *Let v and k be positive integers. Then*

$$\Phi(v, k, k - 1) = \frac{1}{v} \sum_{d|(k,v)} \mu(d) \binom{\frac{v}{d}}{\frac{k}{d}}.$$

3 Exact value of $\Phi(u \times v, k, k, k - 1)$

To determine the exact value of $\Phi(u \times v, k, k, k - 1)$, by Lemma 1.1 we only need to find the number of all orbits in $\Omega(u \times v, k)$. Recall that Z_v acts on $\Omega(u \times v, k)$. By the well-known Cauchy-Frobenius-Burnside Lemma (refer to [28, Lemma 1.25]), we have that the number of all orbits in $\Omega(u \times v, k)$ is

$$\frac{1}{v} \sum_{g \in Z_v} |fix(g)|,$$

where $fix(g) = \{B : B + g = B, B \in \Omega(u \times v, k)\}$. We state the result as follows.

Lemma 3.1 *Let u, v and k be positive integers. Then*

$$\Phi(u \times v, k, k, k - 1) = \frac{1}{v} \sum_{g \in Z_v} |fix(g)|.$$

Theorem 3.2 *Let u, v and k be positive integers. Then*

$$\Phi(u \times v, k, k, k - 1) = \frac{1}{v} \sum_{d|(k,v)} \varphi(d) \binom{\frac{uv}{d}}{\frac{k}{d}}.$$

Proof By Lemma 3.1, we only need to compute the size of $fix(g)$ for every $g \in Z_v$.

For any $B \in fix(g)$, then $B + g = B$. It is clear that the spanning group $\langle g \rangle$ is a subgroup of the stabilizer G_B of B in Z_v . From Lemma 2.2 we have $|\langle g \rangle|$ is a divisor of $|G_B|$, and hence $|\langle g \rangle|$ is a divisor of (k, v) . By Lemma 2.2, B can be written as $B = \cup_{i=0}^{|\langle g \rangle|-1} (B_0 + \frac{vi}{|\langle g \rangle|})$ for some $B_0 \in \Omega(u \times \frac{v}{|\langle g \rangle|}, \frac{k}{|\langle g \rangle|})$, where $B_0 + vi/|\langle g \rangle| = \{(x, y + vi/|\langle g \rangle|) : (x, y) \in B_0\}$. Let $A = \cup_{i=0}^{x-1} (B_0 + \frac{vi}{|\langle g \rangle|})$ where $x = |G_B|/|\langle g \rangle|$. Then $A \in \Omega(u \times \frac{v}{|\langle g \rangle|}, \frac{k}{|\langle g \rangle|})$. It is readily checked that $B = \cup_{i=0}^{|\langle g \rangle|-1} (A + \frac{vi}{|\langle g \rangle|})$. Conversely, if $B = \cup_{i=0}^{|\langle g \rangle|-1} (A + \frac{vi}{|\langle g \rangle|})$ for some $A \in \Omega(u \times \frac{v}{|\langle g \rangle|}, \frac{k}{|\langle g \rangle|})$, by noting that $|\langle g \rangle| = v/(g, v)$, we then have $B + g = B$, that is $B \in fix(g)$. That means that $B \in fix(g)$ if and only if B can be written as $B = \cup_{i=0}^{|\langle g \rangle|-1} (A + \frac{vi}{|\langle g \rangle|})$ for some $A \in \Omega(u \times \frac{v}{|\langle g \rangle|}, \frac{k}{|\langle g \rangle|})$. Hence, we have $|fix(g)| = |\Omega(u \times \frac{v}{|\langle g \rangle|}, \frac{k}{|\langle g \rangle|})| = \binom{\frac{uv}{|\langle g \rangle|}}{\frac{k}{|\langle g \rangle|}}$ if $|\langle g \rangle|$ is a divisor of (k, v) ; or $fix(g) = 0$ otherwise. That is

$$|fix(g)| = \begin{cases} \binom{\frac{uv}{|\langle g \rangle|}}{\frac{k}{|\langle g \rangle|}}, & |\langle g \rangle| \mid (k, v), \\ 0, & \text{otherwise.} \end{cases} \tag{3.2}$$

Note that there are $\varphi(d)$ elements g in Z_v such that the order of the spanning group $\langle g \rangle$ is d , that is, $\varphi(d) = \sum_{\substack{g \in Z_v \\ |\langle g \rangle|=d}} 1$. Applying Lemma 3.1 and (3.2), we then have the following

$$\begin{aligned} \Phi(u \times v, k, k, k - 1) &= \frac{1}{v} \sum_{\substack{|\langle g \rangle|(k,v) \\ g \in Z_v}} \left(\frac{uv}{|\langle g \rangle|} \right) \\ &= \frac{1}{v} \sum_{d|(k,v)} \sum_{\substack{g \in Z_v \\ |\langle g \rangle|=d}} \left(\frac{uv}{d} \right) \\ &= \frac{1}{v} \sum_{d|(k,v)} \left(\frac{uv}{d} \right) \sum_{\substack{g \in Z_v \\ |\langle g \rangle|=d}} 1 \\ &= \frac{1}{v} \sum_{d|(k,v)} \varphi(d) \left(\frac{uv}{d} \right). \end{aligned}$$

This completes the proof. □

4 Concluding remarks

In the present paper, we have determined the exact value of $\Phi(u \times v, k, \lambda_a, k - 1)$ for $\lambda_a = k - 1$ and k . That means that the size of an optimal 2-D $(u \times v, k, \lambda_a, k - 1)$ -OOC with $\lambda_a = k - 1$ and k is characterized. General speaking, the determination of $\Phi(u \times v, k, \lambda_a, \lambda_c)$ is still much open for $\lambda_a < k - 1$ or $\lambda_c < k - 1$. It is worthy for further investigation.

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