SOLVING WEIGHTED MAX-CUT PROBLEM BY GLOBAL EQUILIBRIUM SEARCH

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Abstract. *A new algorithm based on the global equilibrium search (GES) is developed to solve the weighted max-cut problem and is compared with currently the best solution algorithms. The advantages of the GES algorithm both in the performance and in the possibility of finding the best solutions are shown.*

Keywords: *maximum weighted cut of a graph, global equilibrium search, computing experiment, algorithm efficiency.*

The problem of the maximum weighted cut of a graph (weighted max-cut problem) has numerous practical applications [1]. As it is a classical discrete optimization problem, it is addressed in many publications, for example [1–6].

Recently, increasing attention has been given to the method of global equilibrium search (GES) [7, 8]. To solve the max-cut problem, special GES Tabu and GES Pr LocS algorithms were developed based on this method and specific features of the problem [9, 10]. As the analysis of experimental studies has shown, they outperform well-known algorithms. For example, in solving 44 test problems, 12 new records were found; for all the other tests (except for one), already known records were obtained. Noteworthy, the GES method is the most practically efficient among discrete optimization methods.

The present paper proposes a modification of the GES Tabu algorithm to solve the problem under study and presents the results of experimental studies on an extended set of test problems that confirm the advantages of the GES method.

Assume that an undirected graph $G = G(V, E)$ with the sets of vertices *V* and of edges *E* is specified. Each edge $(i, j) \in E$ of the graph is associated with a weight $w_{ij} > 0$. A cut of the graph *G* is a partition (V_1, V_2) of the set of its vertices *V* into two disjoint subsets V_1 and V_2 such that $i \in V_1$ and $j \in V_2$. It is obvious that each such partition generates a cut of the graph.

The problem of the maximum weighted cut (max-cut) of the undirected graph *G* is to find a cut of the maximum total weight \overline{a}

$$
w(V_1, V_2) = \sum_{i \in V_1, \ j \in V_2, \ (i, \ j) \in E} w_{ij}.
$$

The problem is *NP*-hard even if all the edges are of unit weight. The main difficulty in its solution is that computational costs exponentially grow as the problem dimension increases. Therefore, only approximate methods are efficient for the analysis of this class of high-dimensional problems.

The weighted max-cut problem can be presented as an unconstrained binary quadratic programming (UBQP) problem. We will associate each vertex of the partition (V_1, V_2) of the graph *G* with a Boolean variable x_i . If $i \in V_1$, then problem. We will associate each vertex of the partition (v_1, v_2) of $x_i = 0$; otherwise $x_i = 1$, $i \in V_2$. Then the problem becomes: find

$$
\max_{x_i \in \{0,1\}} \left\{ f(x) = \sum_{(i,j) \in E} w_{ij} (x_i - x_j)^2 \right\}.
$$
 (1)

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However, reducing the original problem to model (1) and applying the well-known algorithms to it [11, 12] would not be so effective. Therefore, as was mentioned above, special GES algorithms were developed for the max-cut problem; we will elaborate them in the present paper.

The key points of the GES method are generating the solution and searching for a local maximum near this solution. Let us consider the singularities of applying this method at the first stage.

Assume that

$$
S_j^1 = \{x \in S | x_j = 1\}, S_j^0 = \{x \in S | x_j = 0\}, j = 1, ..., n,
$$

where *S* is a subset of the set of admissible solutions of problem (1) found by the GES method. Since the "temperature" cycle is the core of the GES method, the following parameters should be set for it: the index *K* of the temperature cycle and the vector of temperature parameters $\mu = (\mu_0, ..., \mu_K)$, $\mu_0 < \mu_1 < ... < \mu_K$, whose indices of components correspond to the numbers of the temperature cycle. The vector μ allows controlling the difference between the generated initial solution and the best solution $\tilde{x} = (\tilde{x}_1, ..., \tilde{x}_n)$ from the set *S* since this solution can be obtained by a random variation of components of the vector \tilde{x} by the following rule: if $\tilde{x}_j = 0$, then this components varies with probability $p_j(\mu_k)$; otherwise, with probability $1-p_j(\mu_k)$.

The probabilities $p_j(\mu_k)$ of generating the initial solutions can be calculated based on the concepts borrowed from the annealing method [13] and depend on the current temperature μ_k and on the already found subset *S* of the set of admissible solutions. They are calculated for $j = 1,..., n$, $k = 1,..., K$ by one of the formulas:

$$
p_j(\mu_k) = \frac{1}{1 + \frac{1 - p_j(\mu_0)}{p_j(\mu_0)} \exp\left\{\frac{1}{2} \sum_{i=0}^{k-1} (\mu_{i+1} - \mu_i)(E_{ij}^0 + E_{i+1j}^0 - E_{ij}^1 - E_{i+1j}^1)\right\}},
$$

 $\overline{6}$

 $p_j(\mu_k) = \frac{1-p}{1-p}$

 $j(\mu_k) = \frac{1 - p_j}{1 - p_j}$

p

 $(\mu_k) = \frac{1 - p_i(\mu_0)}{1 - p_i(\mu_0)}$

 μ_k) = $\frac{1-p_i(\mu_k)}{1-p_i(\mu_k)}$

j

 $1+\frac{1-p_j(\mu_0)}{2}$

 μ

 $\boldsymbol{0}$

where

$$
E_{kj}^{u} = \begin{cases} 0 \text{ if } S_j^{u} = \emptyset, u \in \{0,1\}, \\ \sum_{x \in S_j^{u}} f(x) \exp\{u_k(f(x) - f(\widetilde{x}))\} \\ \frac{\sum_{x \in S_j^{u}} \exp\{u_k(f(x) - f(\widetilde{x}))\}}{\sum_{x \in S_j^{u}} \exp\{u_k(f(x) - f(\widetilde{x}))\}} \text{ if } S_j^{u} \neq \emptyset, \end{cases}
$$

or

or

$$
p_j(\mu_k) = \frac{\sum_{x \in S_j^1} \exp(-\mu_k f(x))}{\sum_{x \in S} \exp(-\mu_k f(x))},
$$

 $\hspace{1.6cm}$, (2)

where $f_j^u = \max_{y \in \mathcal{Y}} f(x)$ $=\max_{x \in S_j^u} f(x), u \in \{0, 1\}.$

In the GES algorithm modification under study, components of the probability vector can be found by formula (2).

 $=\frac{1}{1+\frac{1-p_j(\mu_0)}{\exp{\{(\mu_k-\mu_0)\}}(f^0-\mu_0)}$

 $f_i^0 - f$

₀)} $(f_j^0 - f_j^1)$

 $k - \mu_0$ $\frac{1}{2}$ $\frac{1}{j}$ $\frac{-1}{j}$

 $\frac{f^{(1)}(\mu_0)}{(\mu_0)} \exp{\{(\mu_k - \mu_0)\}(f_j^0 - f_j^1)}$

 μ_k – μ

The values of μ_k , $k = 0,..., K$, that define the annealing curve are calculated by the formulas $\mu_0 = 0$, $\mu_{k+1} = \alpha \mu_k$, *k* = 1,..., *K* -1. The values of μ_k , κ -0,..., *K*, that define the annealing curve are calculated by the formulas μ_0 -0, μ_{k+1} - $\alpha \mu_k$, k =1,..., *K* -1. The values of μ_1 and α >1 should be se temperature cycle approximately equal to the record solution from the set *S*. The annealing curve is universal and is used in solving all the problems. Only coefficients of the objective function are scaled so that to equate the value of the expected record to the given value. Noteworthy is that the tabu algorithm is taken as a search one at the second stage of the GES method and the specificity of the problem is taken into account.

To compare the developed algorithm to available ones, experimental calculations in solving test problems from [14] were carried out and their number was increased. Such problems are used for test calculations and include toroidal, planar, and random graphs. As in [6], the first 54 problems were considered.

TABLE 1

TABLE 1, continued

	$\mathcal{D}_{\mathcal{L}}$	3	$\overline{4}$	5	6	7	8	9
sg3dl101000	1000	896	896	896(20)	896.00	2.15	8.09	8.09
sg3dl102000	1000	900	900	900(20)	900.00	1.2	2.13	2.13
sg3dl103000	1000	892	892	892(20)	892.00	1.58	6.33	6.33
sg3dl104000	1000	898	898	898(20)	898.00	1.59	7.96	7.96
sg3dl105000	1000	886	886	886(20)	886.00	2.17	27.99	27.99
sg3dl106000	1000	888	888	888(20)	888.00	1.34	2.04	2.04
sg3d1107000	1000	900	900	900(20)	900.00	1.92	68.04	68.04
sg3dl108000	1000	882	882	882(20)	882.00	2.04	15.10	15.10
sg3dl109000	1000	902	902	902(20)	902.00	1.72	7.84	7.84
sg3dl1010000	1000	894	894	894(20)	894.00	1.25	3.07	3.07
sg3d1141000	2744	2446	2446	2446(19)	2445.90	16.74	577.25	573.96
sg3dl142000	2744	2458	2458	2458(20)	2458.00	9.95	93.52	93.52
sg3d1143000	2744	2442	2442	2442(20)	2442.00	149.01	1125.69	1125.69
sg3d1144000	2744	2450	2450	2450(15)	2449.50	43.58	1135.02	998.35
sg3dl145000	2744	2446	2446	2446(20)	2446.00	8.94	104.75	104.75
sg3dl146000	2744	2450	2450	2452(15)	2451.50	54.98	1372.25	1069.78
sg3dl147000	2744	2444	2444	2444(20)	2444.00	14.54	354.47	354.47
sg3dl148000	2744	2446	2448	2448(15)	2447.50	15.51	1186.50	986.67
sg3dl149000	2744	2424	2426	2426(20)	2426.00	9.66	208.53	208.53
sg3dl1410000	2744	2458	2458	2458(19)	2457.90	12.56	1109.46	1060.13

The GES algorithm is implemented in C++, all the computing experiments involved a PC with Intel® Core QUAD CPU Q9550 2.83GHz and 8.0GB RAM. Each problem was solved 20 times with one-hour time limit. The parameters of the GES algorithm were defined as follows. At the beginning of each temperature cycle, $p_j(\mu_0) = 1/2$, $j = 1,...,n$. The following values were used for the temperature schedule: $\mu_0 = 0$, $\mu_1 = 7 * 10^{-7}$ / coef, and $\mu_k = \mu_{k-1} \frac{\log(10/\cos f) - \log \mu_k}{48}$ $p_j(\mu_0) = 1/2, j = 1,..., n.$ The
 $k = \mu_{k-1} \frac{\log(10/\cos f) - \log \mu_1}{48}$ 48 $log(10 / cos f) - log$

for $k = 2, ..., K$, $K = 50$, coef $= 18 * 10^8 / f(x^{BKS})$, and x^{BKS} being a known record solution of the problem.

Some results of these studies are summarized in Table 1. As each problem was solved 20 times for 20 different initial approximations, the average values concerning the objective function and the problem solution time should be considered. The following notation is used in the table: BKS is a record for the problem known from the literature, Best GES and BFS are the best results obtained by the GES algorithms [9,10] and the algorithm under study, respectively (the number of the revealed records for 20 solution attempts is specified in brackets), Value is the mean value of the objective function; t_{min} and t_{av} are, respectively, the minimum and average time (in sec) of finding a record, and \tilde{t}_{av} is the average solution time (in sec) for one problem. The record known from the literature and enhanced by the GES algorithm is bolded and italicized.

An analysis of the results of experimental calculations allows concluding that the GES method is highly efficient and competitive in solving this class of problems. With the use of this method, records were enhanced for 37 problems and the known records were found for the remaining ones. The performance of the GES method also exceeds that of the well-known ones. Currently, it is undoubtedly the best method to solve max-cut problems.

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