

Software defect prediction: future directions and challenges

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Abstract

Software defect prediction is one of the most popular research topics in software engineering. The objective of defect prediction is to identify defective instances prior to the occurrence of software defects, thus it aids in more effectively prioritizing software quality assurance efforts. In this article, we delve into various prospective research directions and potential challenges in the feld of defect prediction. The aim of this article is to propose a range of defect prediction techniques and methodologies for the future. These ideas are intended to enhance the practicality, explain– ability, and actionability of the predictions of defect models.

Keywords Software defect prediction · Empirical software engineering · Software analytics · Quality assurance

1 Introduction

Software defect prediction (SDP) is a vibrant research domain in software engineer‑ ing and plays an important role in ensuring quality assurance (Menzies et al. [2010;](#page-12-0) Kamei and Shihab [2016;](#page-11-0) Wan et al. [2020;](#page-13-0) Tantithamthavorn and Hassan [2018](#page-12-1)). It is

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a very crucial and essential activity. By identifying defective instances (e.g., components, fles, classes, methods, changes) before testing, SDP has the potential to reduce code inspection costs and improve software quality. This empowers software quality assurance teams to efectively allocate their limited resources for testing and maintenance, leading to enhanced efficiency (Li et al. [2018c](#page-11-1)).

In the past few decades, analytical modeling of defects has attracted a lot of attention from both the academic and industrial communities (Hall et al. [2012;](#page-11-2) Hosseini et al. [2019;](#page-11-3) Chen et al. [2021\)](#page-10-0). Various SDP methods have been introduced across different prediction settings, such as within-project defect prediction (WPDP) (Menzies et al. [2007](#page-12-2); Lessmann et al. [2008;](#page-11-4) Ghotra et al. [2015](#page-11-5)), cross-project defect prediction (CPDP) (Zimmermann et al. [2009](#page-13-1); Li et al. [2021](#page-11-6), [2023\)](#page-12-3), heterogeneous defect prediction (HDP) (Jing et al. [2015;](#page-11-7) Nam and Kim [2015](#page-12-4); Li et al. [2018a,](#page-11-8) [2017,](#page-11-9) [2018b](#page-11-10)), and just-in-time defect prediction (Kamei et al. [2013](#page-11-11); Zhao et al. [2023\)](#page-13-2). These methods have yielded promising defect prediction results. Therefore, SDP plays a pivotal role in software development organizations worldwide nowadays. Given its signifcance, we believe that the timing is opportune to write a paper on the future of software engineering focusing on the subject of software defect prediction.

This paper is presented from the perspective of academic researchers and has two primary objectives. Firstly, it provides a brief overview of SDP and highlights several key steps within this domain. Secondly, it proposes a collection of research directions for future defect prediction.

2 Defect prediction process

The common software defect prediction process involves the utilization of various machine learning techniques and methodologies (Shepperd et al. [2014;](#page-12-5) Li et al. [2018c](#page-11-1); Giray et al. [2023\)](#page-11-12), ranging from classic classifcation algorithms to advanced deep learning architectures, to proactively identify and detect potential defects in software instances. This essential process is vital for enhancing software quality and reliability. It is comprised of several key steps, each playing an important role in predicting and mitigating defects before they manifest in the fnal software prod‑ ucts. Figure [1](#page-2-0) illustrates these steps in the software defect prediction process, includ– ing data collection, preprocessing, model construction and prediction, and fnally the evaluation and interpretation of the defect prediction results. This process is not only integral for ensuring software quality but also plays a crucial role in prioritizing resource allocation and minimizing the impact of defects on users and stakeholders. The following sections provide detailed descriptions for each step.

1 *Data collection*. In software defect prediction, data collection involves gath‑ ering information about projects, specifcally related to code versions, historical changes, and associated attributes. This includes data on past defects, bug reports, source code metrics, process metrics, developer activities, and other relevant soft-ware project features (Li et al. [2018c\)](#page-11-1). Alternatively, it might involve directly extracting abstract syntax trees and various types of graphs from source codes for deep learning-based techniques (Giray et al. [2023;](#page-11-12) Zain et al. [2023\)](#page-13-3). The aim is to create a comprehensive dataset that enables the training and evaluation of machine

Fig. 1 Overview of the common software defect prediction process

learning models for predicting potential software defects. This data can be acquired from version control systems (e.g., Git, CVS, SVN), bug tracking tools (e.g, JIRA, Bugzilla, GitHub Issues), code repositories, project documentation, and other repositories where relevant information is stored. In short, efficient and accurate data col-lection is vital for building effective defect prediction models (Kim et al. [2011](#page-11-13); Wu et al. [2011;](#page-13-4) Tantithamthavorn et al. [2015\)](#page-12-6).

2 *Data preprocessing*. It is a crucial aspect in the context of defect predic‑ tion, involving preparation and manipulation of the raw data collected from software repositories to enhance the performance and accuracy of predictive models in identifying software defects. This process usually includes several key steps. (1) *Data cleaning*: Cleaning and preparing the collected data for defect analyt‑ ics. It consists of handling missing values, dealing with outliers, addressing data inconsistencies, handing noise, and removing duplicate instances (Shepperd et al. [2013\)](#page-12-7). This step ensures that the dataset used for defect prediction is consistent, accurate, and free from anomalies, setting a solid foundation for building robust and reliable predictive models. (2) *Metric selection*: Identifying and selecting the most relevant features or metrics that are likely to have a correlation with software defects. Meanwhile, eliminating correlated metrics that may not contribute signifcantly to the model's performance (Jiarpakdee et al. [2021a](#page-11-14)). This aims to reduce dimensionality and improve the efficiency of the prediction models. (3) *Normalization*: Normalizing or scaling numerical features within a specifc range or distribution. It aims to make all the software metrics in a dataset to a similar scale without distorting diferences in the ranges of values. The techniques commonly used for data normalization include log transformation (Menzies et al. 2007) and z-score standardization (Li et al. $2019a$). These methods adjust the val– ues of metrics to a standardized scale, ensuring consistency across the dataset. (4) *Handling class imbalance*: The defect dataset might have an imbalance between defective and non-defective instances. Employing class imbalance learning techniques, such as the widely used undersampling, oversampling, or synthetic data sampling algorithms, to rebalance the distribution between defective and non-defective instances in the dataset is a common strategy (Tantithamthavorn et al. [2020](#page-12-8)).

3 *Model construction*. Building a defect prediction model using machine learn‑ ing techniques on the preprocessed dataset. This step includes selecting an appropriate learning algorithm, training the model on the labeled dataset, and optimiz– ing its parameters to efectively predict the presence of defects in software projects based on various features or metrics. Common algorithms for defect prediction involve logistic regressions, decision trees, random forests, naive Bayes, support vector machines, and neural networks (Ghotra et al. [2015](#page-11-5); Tantithamthavorn et al. [2019](#page-12-9)). The goal is to build a model that generalizes well to new or unseen software instances and accurately predicts whether the given instances contain defects or not.

4 *Model prediction*. Applying the trained model that was constructed during the training phase, to predict the status of new or unseen software instances passed through the model. The model generates predictions or classifcations based on the input data, aiming to determine whether these instances are likely to be defective or not. Additionally, it might rank instances based on their predicted density (prob‑ ability/LOC) to facilitate prioritized inspection in a more cost-efective way (Kamei et al. [2010](#page-11-16); Mende and Koschke [2010\)](#page-12-10). This is a crucial step in defect prediction as it helps software developers and quality assurance teams to proactively identify potential defects in software before they cause issues or errors in production, enabling timely actions to improve software quality and reliability.

5 *Model evaluation*. Assessing the performance and efectiveness of the con‑ structed defect prediction model based on its outputs. Common non-efort-aware and effort-aware performance measures (Huang et al. [2019;](#page-11-17) Li et al. [2018c\)](#page-11-1) used for model evaluation include AUC (area under the receiver operating characteris– tic curve), MCC (Matthew's correlation coefficient), F1-score, PoB@20% (proportion of the found bugs among all bugs in the dataset when inspecting 20% LOC), PMI@20% (proportion of modules inspected when test 20% LOC), and IFA (the number of initial false alarms encountered before software testers detect the frst defect). This step is crucial for understanding how well the model performs on new or unseen data, and aids in understanding the model's strengths, weaknesses, and areas for improvement. The goal of model evaluation is to measure the model's efectiveness in making predictions.

6 *Model interpretation*. Understanding and explaining how the defect model makes predictions or decisions. Model interpretation aims to provide insights into the model's inner workings, making its output more understandable and transpar‑ ent to humans. Through thorough analysis and extraction of meaningful insights from predictions, it seeks to identify which software metrics are the most influen– tial in defect prediction. This can assist software practitioners in understanding why the defect prediction model made particular decisions and provides insights into the rationale behind predictions made by analytical models (Dam et al. [2018;](#page-11-18) Tan– tithamthavorn and Jiarpakdee (2021)). The interpretative process is indispensable for building trust in defect prediction models, emphasizing that the rationale behind a model's decisions is just as signifcant as the decisions themselves.

The overall goal of software defect prediction is to help quality assurance teams prioritize their eforts and resource allocation by identifying software instances that are more likely to contain defects. This proactive approach signifcantly contributes to enhancing software quality, reducing maintenance costs, and improving overall software development practices. Through the early identifcation of potential defects, defect prediction enables quality assurance teams to allocate their resources more efficiently, paying attention to critical areas and streamlining the quality assurance process. Ultimately, the application of defect prediction techniques brings in a more robust and reliable software development lifecycle, fostering higher-quality deliverables and minimizing the impact of defects on software products.

3 Future directions and challenges

The feld of software defect prediction has witnessed numerous achievements over the past decades (Kamei and Shihab [2016;](#page-11-0) Wan et al. [2020](#page-13-0)). Nevertheless, it is important to note that many challenges remain and are likely to emerge in the future due to shifts in data, technology, and the ever-growing signifcance of software systems. To enhance readability, we organize this section into four dimensions, including data, metrics, model construction, and model evaluation and interpretation, which is roughly similar to the defect prediction process intro-duced in Sect. [2.](#page-1-0) Fig. [2](#page-4-0) illustrates an overview of the future directions and chal– lenges in software defect prediction, with detailed descriptions for each perspec‑ tive provided below.

Fig. 2 Overview of future directions and challenges in software defect prediction

3.1 Data

Future direction and challenge 1: Data labeling quality. *Context:* Historical defect information plays a pivotal role in software maintenance such as qual– ity measurement and defect prediction. The SZZ algorithm (Śliwerski et al. [2005](#page-12-12)) stands as a primary method for identifying bug-inducing commits in software projects, which is widely used in the feld of defect prediction. *Issue:* However, current defect collection practices are based on optional bug fx keywords or bug report links in change logs, which can lead to the inclusion of noise into the collected data (Kim et al. [2011](#page-11-13); Wu et al. [2011](#page-13-4); Tantithamthavorn et al. [2015](#page-12-6)). Such biased data can signifcantly impact the performance of defect prediction models. The SZZ algorithm faces issues in achieving high precision due to the presence of noise within bugfxing commits. For instance, not all addition or deletion lines within a bug-fxing commit are directly linked to bug fxes (Tang et al. [2023](#page-12-13)). *Direction and challenge:* A potential direction is that substantial eforts are directed towards improving the precision of the SZZ algorithm in the future. Despite the advancements made by the existing studies (Kim et al. [2006](#page-11-19); Da Costa et al. [2016;](#page-10-1) Neto et al. [2018](#page-12-14); Tsantalis et al. [2018](#page-13-5)), it is challenging to incorporate all refactoring and non-essential change patterns into a tool, as this could result in the potential exclusion of relevant lines and the inclusion of irrelevant lines (Tang et al. [2023](#page-12-13)). In recent years, deep learn– ing techniques have garnered extensive application across various software engi-neering tasks (Yang et al. [2022](#page-12-15); Samoaa et al. 2022), consistently outperforming other state-of-the-art methods. The notable strength of deep learning lies in its abil‑ ity to autonomously learn highly intricate and expressive features, a capability that traditional methods cannot be done. This advantage allows deep learning models to capture complex patterns and relationships within data more effectively. Therefore, one promising avenue is the utilization of deep learning techniques for the identifcation of bug-inducing commits. By leveraging the power of deep learning, it becomes possible to automatically capture semantic relationships within commit data that contribute to more efective models, which conventional SZZ algorithms fnd challenging.

Future direction and challenge 2: Privacy-preserving data sharing. *Context:* In recent years, many researchers have utilized dataset collected from open-source software projects and have demonstrated a willingness to make their data availability and openness to facilitate reproducibility. *Issue:* Numerous commercial and pro‑ prietary software projects often lack data availability due to business sensitivity and privacy concerns. This has raised doubts about the feasibility of data sharing for research purposes. Recently, privacy preservation issue has gained attention in the feld of defect prediction (Peters et al. [2013,](#page-12-16) [2015;](#page-12-17) Li et al. [2019b\)](#page-11-20). *Direction and challenge:* The need for more privacy-preserving data sharing initiatives becomes crucial for further exploration. This can potentially facilitate the availability of more commercial and proprietary data. Benefting from this, existing methods such as cross-project defect prediction (Zhou et al. [2018](#page-13-7)) or heterogeneous defect predic‑ tion (Chen et al. [2021](#page-10-0)) could offer practical value, especially for new projects or those lacking enough historical data. However, it is very challenging for many companies or organizations are not willing to share their data due to concerns related to business sensitivity and privacy. To address this challenge, researchers need to establish strong partnerships with industrial collaborators and should actively seek collaboration with them, gaining access to their rich and diverse data repositories. Meanwhile, it is imperative to explore new methods for privacy-preserving data sharing. Lately, Yamamoto et al. ([2023\)](#page-13-8) presented a federated logistic regression model for privacy-preserving cross-project defect prediction. Inspired by this, the combination of federated deep learning and other privacy techniques emerges as a promising avenue for preserving and maintaining the security of data in defect prediction. Federated learning (Lo et al. [2021\)](#page-12-18), a decentralized training approach, allows machine learning models to be trained across multiple edge devices without the need for exchanging raw training data. This not only enhances privacy protection but also facilitates collaborative learning across diverse datasets.

3.2 Metrics

Future direction and challenge 3: Multi-feature fusion. *Context:* Defect data typically consists of multiple types of software metrics, e.g., code metrics, process metrics, ownership metrics, etc (Menzies et al. [2007;](#page-12-2) Moser et al. [2008](#page-12-19); Bird et al. [2011](#page-10-2)). Each type of metric characterizes the relevant attributes of a software product from a certain perspective, which has different physical meanings and distributions. When considering semantic features, various types of source code repre‑ sentations have been proposed (Yang et al. [2022](#page-12-15); Samoaa et al. 2022). These contain abstract syntax trees, control fow graphs, call fow graphs, data fow graphs, program dependency graphs, token-based embedding representations and so on. Indeed, these representations have found wide application in various software engineering tasks. *Issue:* For the traditional hand-crafted features, existing defect prediction studies identify software defects by concatenating and merging all the metrics into a single feature vector. For the semantic features, most defect prediction studies use each code representation individually for identifying software defects. However, these methods ignore the diversity and complementary information among different types of metrics or multiple code representations (Zhou et al. [2022](#page-13-9); Ni et al. [2022a](#page-12-20)). *Direction and challenge:* Considering that metric data are extracted from software projects from diferent perspectives, each type of metric can be recognized as a single data view. So defect data consisting of multiple types of metrics can be divided into multiple diferent data views. A promising avenue for future research involves fusing multiple types of software metrics to build robust and reliable defect prediction models. Such an approach would enable the collaborative learning of the diversity and complementarity within defect data, which will improve the model performance. However, the process of efectively fusing multiple types of software metrics could indeed pose a signifcant challenge. Regarding the semantic features, exploring the potential complementarity between tree-based and graph-based code representations in defect prediction could be benefcial for future work, particularly in the context of fusing multiple code representations. However, it also poses chal– lenges in accurately extracting various source code representations, encoding them appropriately, and effectively combining them by using existing off-the-shelf deep

learning techniques. This fusion process demands innovative strategies to harness the comprehensive potential of these diverse code representations.

Indeed, some studies (Xu et al. [2020;](#page-13-10) Wang et al. [2021](#page-13-11); Zhou et al. [2022;](#page-13-9) Ni et al. [2022a](#page-12-20)) have attempted to fuse traditional manually designed software metrics with semantic features derived from code representations to enhance the accuracy of defect prediction. The results of these studies have indicated that the combination of traditional hand-crafted metrics with semantic features contributes to improved performance in software defect prediction. However, efectively combining diverse software metrics and features presents its set of challenges. The process demands innovative approaches that address issues of feature representation, integration strategies, and the optimal balance between the information learned from various sources. Finding an efective fusion technique that maximizes the strengths of each type of feature while mitigating potential redundancies remains an ongoing chal‑ lenge in this domain.

3.3 Model construction

Future direction and challenge 4: Fine-grained line-level defect prediction. *Con*text: The current defect prediction models typically are at a relatively coarse granularity level, such as the fle level. This often makes software practitioners needing to spend significant effort in inspecting many clean lines that are actually non-defective. *Issue:* In practice, practitioners are interested in identifying the specifc lines of code that are defective (Wattanakriengkrai et al. [2022\)](#page-13-12). Hence, there is a growing need for defect prediction models to become more fne-grained and capable of pinpointing the truly lines of code that require attention. This fner granularity can signifcantly enhance the practicality and usefulness of these models in real-world software development and maintenance. However, most of the defect prediction studies did not pay attention to this domain. *Direction and challenge:* It holds promise towards code-line-level defect prediction, as it could help developers to more effectively prioritize their quality assurance efforts. Indeed, there is an increasing recognition of the potential advantages in fine-grained, code-line-level defect prediction (Pornprasit and Tantithamthavorn [2021](#page-12-21), [2023;](#page-12-22) Ni et al. [2022a;](#page-12-20) Guo et al. [2023](#page-11-21)). Meanwhile, it is important to note that substantial challenges exist in building accurate code-line-level defect prediction models effectively. In the context of tra ditional metrics, the primary challenge in constructing conventional defect models at the code line level is the design of manually crafted software features. Extracting such features at the code line level is a challenging endeavor, as it demands precise historical data for each line within the source code fles. In the context of semantic features, the collected datasets often remain highly dimensional and sparse. Consequently, building code-line-level defect prediction models using semantic features is likely unfeasible and impractical within a shorter period of time (Wattanakrieng– krai et al. [2022](#page-13-12)). Despite these challenges, the move towards a fner granularity in defect prediction can offer a more targeted and actionable approach, enabling teams to address potential issues at a more localized level within the source code, which

aligns with the industry's pursuit of higher precision and efficiency in software qual– ity assurance processes.

Future direction and challenge 5: Robust and stable defect prediction. *Context:* Ensuring robust and stable defect prediction is imperative because software projects are dynamic, and the data used to train models may change over time. Defect models lacking in robustness and stability may yield unreliable predictions, leading to decreased confdence in their efectiveness for identifying software defects. *Issue:* Recent works (Fu et al. [2016](#page-11-22); Tantithamthavorn et al. [2019](#page-12-9)) have highlighted a crucial point regarding defect prediction models in the literature. They argue that most of these models tend to rely on the default parameter settings of classification techniques, which usually have a large impact on the performance of these models and lead to suboptimal results. Thus, the hyperparameters of the defect prediction models should be carefully tuned. However, a critical observation in existing work (Tantithamthavorn et al. [2019\)](#page-12-9) is the limited quantity of hyperparameters explored for the examined classifiers. Most of these classifiers focus on tuning a single parameter, and the parameter space considered is relatively small in scale. *Direction and challenge:* There exists an opportunity for future research to delve into exploring multiple hyperparameters and broader parameter spaces, particularly in the context of deep learning-based defect prediction models. Exploring the interactions among various parameters could provide valuable insights and potentially lead to signifcant improvements in the performance and effectiveness of defect prediction models. Undoubtedly, it is important to acknowledge that dealing with multiple hyperparam– eters and expansive search spaces can pose challenges. Striking a balance between comprehensiveness and practicality will be crucial in designing experiments that are both informative and feasible. Nonetheless, the exploration of more extensive and intricate parameter confgurations holds promise in achieving robust and stable defect prediction performance.

Future direction and challenge 6: Unsupervised defect prediction. *Context:* Supervised defect prediction trains models on labeled data to predict the occurrence of defects or bugs in software. Instead, unsupervised defect prediction (Li et al. [2020](#page-11-23); Xu et al. [2021](#page-13-13)) builds models on unlabeled data through the application of unsupervised learning techniques for identifying software defects. *Issue:* Although supervised defect prediction methods have the potential to achieve better results in certain performance measures, they do have limitations. The main issue with supervised methods is that they require labeled training data to build models. The process of obtaining labeled data can be time-consuming, labor-intensive, and costly, which makes supervised methods inefficient and resource-intensive, especially in scenarios with limited historical defect data. *Direction and challenge:* Unsupervised defect prediction methods aim to identify more likely defect-prone software instances on unlabeled datasets by exploiting the intrinsic patterns and structures present in the data without the need for any labeled training data. They hold the advantage of not requiring prior knowledge of defect data to label modules. This characteristic makes unsupervised methods particularly benefcial in practice, especially for new software projects or projects with insufficient historical data. For example, Zhang et al. ([2016\)](#page-13-14) introduced a spectral clustering method that utilizes connectivity-based unsupervised classifers for predicting software defects. Their fndings demonstrated

the superiority of the proposed spectral clustering approach over some supervised classifers in both within-project and cross-project settings. Hence, unsupervised prediction techniques exhibit considerable potential in feld of software defect pre‑ diction and represent a promising avenue for future research. However, the challenge remains in devising methods that effectively uncover the intrinsic structures and patterns within the data to achieve more accurate unsupervised defect prediction.

3.4 Model evaluation and interpretation

Future direction and challenge 7: Focusing on actual efort. *Context:* It is of utmost importance to evaluate defect prediction models in a realistic context, e.g. how much effort can reduce for testing and code inspection using these models. By taking into account the resources and efforts required for code inspection or test-ing, effort-aware defect prediction (Kamei et al. [2010](#page-11-16); Mende and Koschke [2010\)](#page-12-10) provides a more accurate assessment of prediction model efectiveness and aligns the evaluations with real-world scenarios. *Issue:* In recent years, there are many effort-aware defect prediction studies (Kamei et al. [2013;](#page-11-11) Yang et al. [2016;](#page-13-15) Huang et al. [2019](#page-11-17); Ni et al. [2022b](#page-12-23)) to account for the effort. Typically, these models utilize LOC (lines of code) or churn as a proxy for effort. As pointed out by Shihab et al. [\(2013](#page-12-24)), their results show that LOC is not the best measure of efort in efort-aware defect prediction. *Direction and challenge:* To progress in the feld, it is crucial for researchers to shift their focus towards the utilization of actual efort data in future effort-aware defect prediction research. Adopting this approach is expected to yield more reliable insights and enhance practical guidelines for software practitioners. One potential strategy involves leveraging effort estimation techniques (Menzies et al. [2013](#page-12-25)) to calculate actual effort. Effort estimation is the process of predicting the amount of effort required to develop or maintain a software application. Integrating this technique into defect prediction holds significant promise. However, identifying the most effective approach for accurately quantifying real effort and thereby provide robust practical guidelines remains a complex and ongoing challenge. Undoubtedly, such research endeavors can have a substantial impact on enhancing the future applicability of defect prediction techniques in real-world software development practices.

Future direction and challenge 8: Focusing on explainability and actionability. *Context:* In the feld of defect prediction, a signifcant proportion of research efforts have concentrated primarily on improving the predictive accuracy and performance of defect models to more accurately identify potential defects in software systems. The aim is to enhance software quality and minimize the occurrence of defects. *Issue:* The above research efforts have largely neglected or underemphasized comprehensive explanations and justifcations (Dam et al. [2018](#page-11-18); Tantithamthavorn and Jiarpakdee (2021)). Particularly, current defect prediction fails to explain why models make such a prediction and fails to comply with the privacy laws in terms of the requirement to explain any decision made by a method. A lack of explain– ability of the defect prediction models leads to a lack of trust in the predictions or recommendations produced by such methods, hindering their widespread adoption in software development practices (Jiarpakdee et al. [2021b\)](#page-11-24). *Direction and challenge:* The future landscape of defect prediction research should strongly emphasize explainability and actionability, particularly when focusing on deep learning-based models. A recent empirical study by Jiarpakdee et al. [\(2022](#page-11-25)) delved into evaluating model-agnostic techniques for explaining the predictions generated by defect models. Their fndings revealed the utility of generating explanations through modelagnostic techniques for each prediction. Such explanations play a crucial role in aiding developers to comprehend why a fle or commit is identifed as defective, while simultaneously providing actionable guidance to assist project managers in devising suitable quality improvement plans. In short, the overarching goal is to make defect prediction models more practical, explainable, and actionable in software engineering practices. Nevertheless, it is essential to acknowledge that ensuring the reliabil ity and trustworthiness of these predictions of defect models from the perspective of software practitioners remains an ongoing and challenging endeavor.

4 Conclusion

In this article, we present a several of future directions and potential challenges in software defect prediction. It is important to note that our work does not aim to be exhaustive; rather, it simply serves as a documentation of future directions and potential challenges. Most importantly, we would like to emphasize that we do not seek to claim the generality of our ideas. Instead, the goal of this article is that under specific circumstances, these research directions have the potential to help developers to effectively find software defects and enable managers to better develop soft– ware quality improvement plans to prevent defects in the future.

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Declarations

Competing interests The authors declare no competing interests.

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