OPTIMAL PERIODIC L_2 -DISCREPANCY AND DIAPHONY BOUNDS FOR HIGHER ORDER DIGITAL SEQUENCES

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Abstract. We present an explicit construction of infinite sequences of points $(x_0, x_1, x_2, ...)$ in the *d*-dimensional unit-cube whose periodic L_2 -discrepancy satisfies

 $L_{2.N}^{\text{per}}(\{\boldsymbol{x}_0, \boldsymbol{x}_1, \dots, \boldsymbol{x}_{N-1}\}) \le C_d N^{-1} (\log N)^{d/2} \text{ for all } N \ge 2,$

where the factor $C_d > 0$ depends only on the dimension d. The construction is based on higher order digital sequences as introduced by J. Dick in the year 2008. The result is best possible in the order of magnitude in N according to a Rothtype lower bound shown first by P.D. Proinov. Since the periodic L_2 -discrepancy is equivalent to P. Zinterhof's diaphony the result also applies to this alternative quantitative measure for the irregularity of distribution.

1. Introduction and statement of the main result

We study distribution properties of point sequences in the *d*-dimensional unit-cube $[0, 1)^d$ by means of periodic L_2 -discrepancy and of diaphony.

Periodic L_2 -discrepancy. The periodic L_2 -discrepancy is the L_2 mean of the local discrepancy function with respect to test sets from the class of "periodic intervals". This is in contrast to the usual L_2 -discrepancy which uses as test sets exclusively subintervals of the unit-cube that are anchored in the origin, i.e., intervals of the form

$$[\mathbf{0}, \mathbf{t}) := [0, t_1) \times \cdots \times [0, t_d),$$

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where $\mathbf{t} = (t_1, \ldots, t_d)$ in $[0, 1]^d$. See [1, 7, 9, 22, 25] for general information about (standard) L_2 -discrepancy.

For $x, y \in [0, 1]$ set

$$I(x,y) = \begin{cases} [x,y) & \text{if } x \le y, \\ [0,y) \cup [x,1) & \text{if } x > y, \end{cases}$$

and for $\boldsymbol{x}, \boldsymbol{y} \in [0,1]^d$ with $\boldsymbol{x} = (x_1, \ldots, x_d)$ and $\boldsymbol{y} = (y_1, \ldots, y_d)$ we set $B(\boldsymbol{x}, \boldsymbol{y}) = I(x_1, y_1) \times \ldots \times I(x_d, y_d)$. We call $B(\boldsymbol{x}, \boldsymbol{y})$ a "periodic interval".

For a finite set $\mathcal{P}_{N,d} = \{\boldsymbol{x}_0, \boldsymbol{x}_1, \dots, \boldsymbol{x}_{N-1}\}$ of points in the *d*-dimensional unit-cube $[0, 1)^d$ the periodic L_2 -discrepancy is defined as

$$L_{2,N}^{\mathrm{per}}(\mathcal{P}) := \left(\int_{[0,1]^d} \int_{[0,1]^d} \left| \frac{A(B(\boldsymbol{x},\boldsymbol{y}),\mathcal{P}_{N,d})}{N} - \lambda_d(B(\boldsymbol{x},\boldsymbol{y})) \right|^2 \mathrm{d}\boldsymbol{x} \, \mathrm{d}\boldsymbol{y} \right)^{1/2},$$

where the counting function $A(B(\boldsymbol{x}, \boldsymbol{y}), \mathcal{P}_{N,d})$ denotes the number of indices n with $\boldsymbol{x}_n \in B(\boldsymbol{x}, \boldsymbol{y})$ and where $\lambda_d(B(\boldsymbol{x}, \boldsymbol{y}))$ denotes the volume of $B(\boldsymbol{x}, \boldsymbol{y})$. The term $A(B(\boldsymbol{x}, \boldsymbol{y}), \mathcal{P}_{N,d})/N - \lambda_d(B(\boldsymbol{x}, \boldsymbol{y}))$ is sometimes referred to as the "local discrepancy" of $\mathcal{P}_{N,d}$ for the test set $B(\boldsymbol{x}, \boldsymbol{y})$. The local discrepancy measures the difference of the relative portion of points in a periodic interval and the volume of this periodic interval. Hence it is a measure for the irregularity of distribution of a point set in $[0, 1)^d$.

For an infinite sequence $\mathcal{S}_d = (\mathbf{x}_0, \mathbf{x}_1, \mathbf{x}_2, ...)$ in $[0, 1)^d$ the periodic L_2 -discrepancy $L_{2,N}^{\text{per}}(\mathcal{S}_d)$ is the periodic L_2 discrepancy of the point set consisting of the first N elements of \mathcal{S}_d , i.e.,

$$L_{2,N}^{\mathrm{per}}(\mathcal{S}_d) := L_{2,N}^{\mathrm{per}}(\{\boldsymbol{x}_0, \boldsymbol{x}_1, \dots, \boldsymbol{x}_{N-1}\}) \quad \text{for } N \in \mathbb{N}.$$

The periodic L_2 -discrepancy has been studied recently in several papers. See, for example, [6,14,16,17,20,21,23].

Diaphony. The diaphony, as introduced by Zinterhof [37] (see also [9]), is just another quantitative measure for the irregularity of distribution of point sets and sequences in the unit-cube $[0,1)^d$. For a finite set $\mathcal{P}_{N,d} = \{\boldsymbol{x}_0, \boldsymbol{x}_1, \ldots, \boldsymbol{x}_{N-1}\}$ like above the diaphony is defined as

$$F_N(\mathcal{P}_{N,d}) := igg(\sum_{oldsymbol{h} \in \mathbb{Z}^d \setminus \{oldsymbol{0}\}} rac{1}{
ho(oldsymbol{h})^2} igg| rac{1}{N} \sum_{n=0}^{N-1} \exp(2\pi \mathtt{i}oldsymbol{h} \cdot oldsymbol{x}_n) igg|^2 igg)^{1/2},$$

where $\mathbf{i} = \sqrt{-1}$, where $\rho(\mathbf{h}) := \prod_{j=1}^d \max(1, |h_j|)$ for $\mathbf{h} = (h_1, \dots, h_d) \in \mathbb{Z}^d$ and where "·" denotes the usual Euclidean inner product. For an infinite

sequence S_d the diaphony $F_N(S_d)$ is the diaphony of the initial N elements of S_d , i.e.,

$$F_N(\mathcal{S}_d) := F_N(\{\boldsymbol{x}_0, \boldsymbol{x}_1, \dots, \boldsymbol{x}_{N-1}\}) \quad \text{for } N \in \mathbb{N}.$$

The diaphony is a popular quantitative measure for the irregularity of distribution in the sense that a sequence S_d is uniformly distributed modulo one (in the sense of Weyl [36]), if and only if $\lim_{N\to\infty} F_N(S_d) = 0$; see, for example, [9, Theorem 1.33]. Diaphony of point sets and sequences is studied in a multitude of papers, see, for example, [2,10,12,24,29,30,32,33] and the references therein. Relations between the number-theoretic concept of diaphony and crystallographic concepts are discussed in [18].

Relations and known results. It is a known fact that the periodic L_2 -discrepancy can be expressed in terms of exponential sums. For $\mathcal{P}_{N,d} = \{x_0, x_1, \ldots, x_{N-1}\}$ in $[0, 1)^d$ we have

(1)
$$L_{2,N}^{\text{per}}(\mathcal{P}_{N,d}) = \left(\frac{1}{3^d} \sum_{\boldsymbol{h} \in \mathbb{Z}^d \setminus \{\mathbf{0}\}} \frac{1}{r(\boldsymbol{h})^2} \left| \frac{1}{N} \sum_{n=0}^{N-1} \exp(2\pi i \boldsymbol{h} \cdot \boldsymbol{x}_n) \right|^2 \right)^{1/2},$$

where for $\boldsymbol{h} = (h_1, \ldots, h_d) \in \mathbb{Z}^d$ we set

$$r(\boldsymbol{h}) = \prod_{j=1}^{d} r(h_j) \quad \text{and} \quad r(h_j) = \begin{cases} 1 & \text{if } h_j = 0, \\ \frac{2\pi |h_j|}{\sqrt{6}} & \text{if } h_j \neq 0. \end{cases}$$

For a proof of this relation see [23, Theorem 1] or [16, p. 390]. Formula (1) shows that the periodic L_2 -discrepancy is – up to a multiplicative factor depending on d – exactly the diaphony.

We briefly explain some notation: For quantities A(N,d) and B(N,d) depending on N and d we write $A(N,d) \leq_d B(N,d)$ if there is a factor $c_d > 0$ which depends only on d (and not on N) such that $A(N,d) \leq c_d B(N,d)$. If we have $A(N,d) \leq_d B(N,d)$ and $B(N,d) \leq_d A(N,d)$ simultaneously, then we write $A(N,d) \approx_d B(N,d)$.

Using this notation we can express the fact that periodic L_2 -discrepancy and diaphony are the same up to a factor depending only on d in the form

$$L_{2,N}^{\mathrm{per}}(\mathcal{P}_{N,d}) \asymp_d F_N(\mathcal{P}_{N,d}).$$

So the periodic L_2 -discrepancy can be understood as a geometrical interpretation of the diaphony, which is of analytic nature. From this point of view, the results about periodic L_2 -discrepancy presented in this paper apply directly also to the diaphony. Both measures can be also interpreted as worst-case errors of quasi-Monte Carlo integration rules in suitable function classes. For discussions in this direction we refer to [14,16,29].

In classical discrepancy theory (see [1,9,22,25]) one is interested in how small the discrepancy can be in the best case and in constructions of point sets and sequences whose discrepancy is of the optimal order of magnitude. For the periodic L_2 -discrepancy and diaphony, respectively, the following is known:

Finite point sets. For every dimension $d \in \mathbb{N}$ there exists a quantity $c_d > 0$ which only depends on d, such that for every $N \in \mathbb{N}$ and every N-element point set $\mathcal{P}_{N,d}$ in $[0,1)^d$ we have

(2)
$$L_{2,N}^{\text{per}}(\mathcal{P}_{N,d}) \ge c_d \frac{(\log N)^{(d-1)/2}}{N}$$

See, for example, [14, Corollary 2]. This is the "periodic" counterpart of Roth's famous lower bound for the usual L_2 -discrepancy from [34]. The lower bound (2) is known to be best possible in dimension d = 2, see, for example, [13,14]. For arbitrary dimension d, it follows from [15, Theorem 5.3] (see the discussion in [21, Remark 18]) that the periodic L_2 -discrepancy of order 2 digital (t, m, d)-nets over \mathbb{Z}_2 is of order of magnitude $(\log N)^{(d-1)/2}/N$, where $N = 2^m$, which matches the lower bound (2). Another "semi" construction, based on digitally shifted digital nets in prime base b is presented in [21, Section 4] (but unfortunately here the digital shifts leading to the optimal order of magnitude are unknown, which is indicated by the term "semi construction").

REMARK 1. Just to avoid misunderstandings we mention that Lev [24] studied a slightly more general notion of diaphony which involves certain weights and which he called generalized diaphony. For this kind of generalized diaphony he showed the existence of certain nets (where Lev means point sets together with suitable positive weights for every point) yielding optimal order of magnitude (see [24, Main Theorem]). However, these upper bounds are only achieved for certain weights which do not comprise the classical setting considered in the present paper.

Infinite sequences. For every dimension $d \in \mathbb{N}$ there exists a quantity $c'_d > 0$ which only depends on d, such that for every infinite sequence S_d of points in $[0, 1)^d$ we have

(3)
$$L_{2,N}^{\text{per}}(\mathcal{S}_d) \ge c'_d \frac{(\log N)^{d/2}}{N}$$
 for infinitely many $N \in \mathbb{N}$.

This has been shown first in the context of diaphony by Proĭnov [31] (this work is only available in Bulgarian language). A discussion of Proĭnov's work

can be found in [19]. Later, a direct proof in terms of periodic L_2 -discrepancy has been provided in [20]. The lower bound (3) is known to be best possible in dimension d = 1. One-dimensional infinite sequences whose periodic L_2 -discrepancy satisfies a bound of order of magnitude $\sqrt{\log N}/N$ for every $N \ge 2$ were given in, e.g., [2,12,29,32,33]. These constructions comprise the fundamental van der Corput sequence as shown by Proĭnov and Grozdanov [33] (for information about the van der Corput sequence see [11]). On the other hand, although it suggests itself to believe that the lower bound (3) is also best possible for arbitrary dimensions $d \ge 2$, so far there was no proof for this assertion.

The main result. In this paper we give for the first time an explicit construction of *infinite* sequences in $[0, 1)^d$ for arbitrary dimension d, whose periodic L_2 -discrepancy is of order of magnitude $(\log N)^{d/2}/N$ in N which is best possible according to (3). In fact, our result even gives a slightly more refined description of the whole situation. Our main result is the following:

THEOREM 2. For every $d \in \mathbb{N}$ one can explicitly construct an infinite sequence S_d of points in $[0,1)^d$ such that for all $N \geq 2$ we have

$$L_{2,N}^{\mathrm{per}}(\mathcal{S}_d) \lesssim_d \frac{(\log N)^{(d-1)/2}}{N} \sqrt{S(N)} \lesssim_d \frac{(\log N)^{d/2}}{N},$$

where S(N) is the sum-of-digits function of N in base 2 representation, i.e., if $N = 2^{n_1} + 2^{n_2} + \cdots + 2^{n_r}$ with $n_1 > n_2 > \cdots > n_r \ge 0$, then S(N) = r.

REMARK 3. Obviously, we have $S(N) \leq \log N$ for all $N \in \mathbb{N}$ and $S(N) = (\log(N+1))/\log 2$ if N is of the form $N = 2^m - 1$ with $m \in \mathbb{N}$. However, for certain N the sum-of-digits function can be much smaller. For example, if N is a power of 2, then S(N) = 1 only. Hence the main theorem describes an infinite class of integers $N \in \mathbb{N}$, for which the periodic L_2 -discrepancy of S_d is much smaller than the worse lower bound from (3) which holds for infinitely many $N \in \mathbb{N}$.

The explicit construction of infinite sequences from Theorem 2 will be presented in Section 2. Theorem 2 will then be a consequence of Theorem 9 that will be stated at the end of Section 2.

2. Explicit constructions of sequences

We now present explicit constructions of sequences whose periodic L_2 -discrepancy satisfies the bound from Theorem 2. We use the same construction like in [8] for sequences with optimal order of the standard L_2 -discrepancy. The general construction principle was introduced by Dick in [3,4] and is based on linear algebra over the finite field \mathbb{Z}_2 of order 2 (we

identify \mathbb{Z}_2 with the set $\{0, 1\}$ equipped with the arithmetic operations modulo 2). Dick's construction in turn is based on digital sequences according to Niederreiter [26,27].

Digital sequences. Basic module for the construction of a digital sequence in $[0, 1)^d$ are d (one for each coordinate direction) $\mathbb{N} \times \mathbb{N}$ matrices C_1 , ..., C_d with entries from \mathbb{Z}_2 . In order that the points of a digital sequence belong to $[0, 1)^d$ it is commonly assumed that for $C_j = (c_{j,k,l})_{k,l \in \mathbb{N}}$ for each $l \in \mathbb{N}$ the elements of column l become zero eventually, i.e., there exists a number $K(l) \in \mathbb{N}$, such that $c_{j,k,l} = 0$ for all k > K(l).

For $n \in \mathbb{N}_0$, where $\mathbb{N}_0 := \mathbb{N} \cup \{0\}$, the *n*-th point of the digital sequence is constructed in the following way. Consider the binary digit expansion of *n* which is of the form $n = n_0 + n_1 2 + \cdots + n_{m-1} 2^{m-1}$ with $m \in \mathbb{N}$ and $n_i \in \{0, 1\}$ for every $i \in \{0, 1, \ldots, m-1\}$, and define the binary digit vector of *n* as $\vec{n} := (n_0, n_1, \ldots, n_{m-1}, 0, 0, \ldots)^{\top} \in \mathbb{Z}_2^{\mathbb{N}}$. Then, for $j \in \{1, \ldots, d\}$, define

$$\vec{x}_{j,n} = (x_{j,n,1}, x_{j,n,2}, \ldots)^{\top} := C_j \vec{n},$$

where the matrix vector product is evaluated over \mathbb{Z}_2 , and

$$x_{j,n} := \frac{x_{j,n,1}}{2} + \frac{x_{j,n,2}}{2^2} + \frac{x_{j,n,3}}{2^3} + \cdots$$

Then the *n*-th point \boldsymbol{x}_n of the sequence S_d is given by $\boldsymbol{x}_n = (x_{1,n}, \ldots, x_{d,n})$. A sequence S_d constructed this way is called a *digital sequence* (over \mathbb{Z}_2) with generating matrices C_1, \ldots, C_d .

REMARK 4. A finite version of digital sequences are so-called *digital* nets, which consist of 2^m elements in $[0,1)^d$ and which are constructed in exactly the same way like digital sequence with the restriction that C_1 , \ldots , C_d are (finite) $p \times m$ matrices over \mathbb{Z}_2 with fixed $m, p \in \mathbb{N}, p \ge m$, and $n \in \{0, 1, \ldots, 2^m - 1\}$. For more information see [7,26,27].

Explicit constructions of suitable generating matrices C_1, \ldots, C_d for digital sequences were obtained by Sobol' [35], Niederreiter [26,27], Niederreiter– Xing [28] and others (see also [7, Chapter 8]).

A concrete construction. We briefly describe a special case of Sobol's and Niederreiter's construction of the generating matrices. Let $C_j = (c_{j,k,l})_{k,l\geq 1}$ with $c_{j,k,l} \in \mathbb{Z}_2$. Let $p_1 = x$ and $p_j \in \mathbb{Z}_2[x]$ for $j \in \{2, \ldots, d-1\}$ be the (j-1)-st primitive polynomial in a list of primitive polynomials over \mathbb{Z}_2 that is sorted in increasing order according to their degree $e_j = \deg(p_j)$, that is, $e_2 \leq e_3 \leq \cdots \leq e_{d-1}$ (the ordering of polynomials with the same degree is irrelevant). We also put $e_1 = \deg(x) = 1$.

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Let $j \in \{1, \ldots, d\}$ and $k \in \mathbb{N}$. Take i-1 and z to be respectively the main term and remainder when we divide k-1 by e_j , so that $k-1 = (i-1)e_j + z$, with $z \in \{0, 1, \ldots, e_j - 1\}$. Now consider the Laurent series expansion

$$\frac{x^{e_j-z-1}}{p_j(x)^i} = \sum_{l=1}^{\infty} \frac{a_l(i,j,z)}{x^l} \in \mathbb{Z}_2((x^{-1}))$$

and write, for $l \in \mathbb{N}$,

(4) $c_{j,k,l} = a_l(i, j, z).$

Now a digital sequence with generating matrices $C_j = (c_{j,k,l})_{k,l\geq 1}$ constructed this way is a special instance of a Sobol' sequence (which itself is a special instance of a generalized Niederreiter sequence). For more information on these constructions we refer to [7, Chapter 8]. Observe that for the presented construction of generating matrices we have $c_{j,k,l} = 0$ for all k > l.

The general construction principle. The present construction of sequences with the optimal order of periodic L_2 -discrepancy is based on higher order digital sequences as introduced by Dick in [3,4]. We state here simplified versions of their definitions that are sufficient for the present purpose.

The distribution quality of digital sequences depends on the choice of the respective generating matrices. In the following definitions we put some restrictions on C_1, \ldots, C_d with the aim to quantify the quality of equidistribution of the digital sequence.

First we give the definition for the finite case as introduced in Remark 4.

DEFINITION 5. Let $m, p, \alpha \in \mathbb{N}$ with $p \geq \alpha m$ and let t be an integer such that $0 \leq t \leq \alpha m$. Let C_1, \ldots, C_d be $p \times m$ matrices with entries from \mathbb{Z}_2 . For $j \in \{1, \ldots, d\}$ and $i \in \{1, \ldots, p\}$ let $\vec{c}_{j,i} \in \mathbb{Z}_2^m$ be the *i*-th row vector of the matrix C_j . If for all $1 \leq i_{j,\nu_i} < \cdots < i_{j,1} \leq p$ with

$$\sum_{j=1}^{d} \sum_{l=1}^{\min(\nu_j, \alpha)} i_{j,l} \le \alpha m - t$$

the vectors

$$\vec{c}_{1,i_{1,\nu_{1}}}, \ldots, \vec{c}_{1,i_{1,1}}, \ldots, \vec{c}_{d,i_{d,\nu_{d}}}, \ldots, \vec{c}_{d,i_{d,}}$$

are linearly independent over \mathbb{Z}_2 , then the digital net constructed from the generating matrices C_1, \ldots, C_d is called an *order* α *digital* (t, m, d)-*net over* \mathbb{Z}_2 . We then say that the matrices C_1, \ldots, C_d satisfy the *order* α *digital* (t, m, d)-*net property*.

DEFINITION 6. Let $\alpha \in \mathbb{N}$ and let $t \geq 0$ be an integer. Let $C_1, \ldots, C_d \in \mathbb{Z}_2^{\mathbb{N} \times \mathbb{N}}$ and let $C_{j,\alpha m \times m}$ denote the left upper $\alpha m \times m$ submatrix of C_j for $j \in \{1, \ldots, d\}$. If for all $m > t/\alpha$ the matrices $C_{1,\alpha m \times m}, \ldots, C_{d,\alpha m \times m}$ satisfy the order α digital (t, m, d)-net property, then the digital sequence with generating matrices C_1, \ldots, C_d is called an *order* α *digital* (t, d)-sequence over \mathbb{Z}_2 .

From Definition 6 it is clear that if S_d is an order α digital (t, d)-sequence, then for any $t \leq t'$, it is also an order α digital (t', d)-sequence. If $\alpha = 1$, then the concept of order 1 digital (t, d)-sequences is exactly the same like digital (t, d)-sequences as introduced by Niederreiter in [26,27]. For a geometrical interpretation of the order α digital net property we refer to [7, Chapter 15] or to [8, Section 1.4].

Note that a digital sequence can be an order α digital (t, d)-sequence over \mathbb{Z}_2 and at the same time an order α' digital (t', d)-net over \mathbb{Z}_2 for $\alpha' \neq \alpha$. This means that the quality parameter t may depend on α . If necessary we write $t(\alpha)$ instead of t for the quality parameter of an order α digital $(t(\alpha), d)$ -sequence. In particular [4, Theorem 4.10] implies that an order α digital (t, d)-sequence is an order α' digital (t', d)-sequence for all $1 \leq \alpha' \leq \alpha$ with

(5)
$$t' = \left\lceil t\alpha'/\alpha \right\rceil \le t.$$

In other words, $t(\alpha') = \lfloor t(\alpha)\alpha'/\alpha \rfloor$ for all $1 \le \alpha' \le \alpha$. More information can be found in [7, Chapter 15].

Next we present a concrete construction of an order α digital (t, d)-sequence.

A concrete construction of order α digital sequences. In order to construct order α digital sequences we need the following composition principle.

DEFINITION 7. For $\alpha \in \mathbb{N}$ the digit interlacing composition (with interlacing factor α) is defined by

$$\mathscr{D}_{\alpha} \colon [0,1)^{\alpha} \to [0,1), \quad (x_1,\ldots,x_{\alpha}) \mapsto \sum_{a=1}^{\infty} \sum_{r=1}^{\alpha} \xi_{r,a} 2^{-r-(a-1)\alpha},$$

where $x_r \in [0,1)$ has binary digit expansion of the form $x_r = \xi_{r,1}2^{-1} + \xi_{r,2}2^{-2} + \cdots$ with digits $\xi_{r,j} \in \{0,1\}$ for $j \in \mathbb{N}$ and $r \in \{1,\ldots,\alpha\}$. We also define this function for vectors by setting

$$\mathscr{D}_{\alpha}^{d} \colon [0,1)^{\alpha d} \to [0,1)^{d}$$
$$(x_{1},\ldots,x_{\alpha d}) \mapsto (\mathscr{D}_{\alpha}(x_{1},\ldots,x_{\alpha}),\ldots,\mathscr{D}_{\alpha}(x_{(d-1)\alpha+1},\ldots,x_{\alpha d}))$$

and for sequences $\mathcal{S}_{\alpha d} = (\boldsymbol{x}_0, \boldsymbol{x}_1, \ldots)$ with $\boldsymbol{x}_n \in [0, 1)^{\alpha d}$ by setting

$$\mathscr{D}^d_{\alpha}(\mathcal{S}_{\alpha d}) = \big(\mathscr{D}^d_{\alpha}(\boldsymbol{x}_0), \mathscr{D}^d_{\alpha}(\boldsymbol{x}_1), \dots \big).$$

Likewise, the interlacing can also be applied to the generating matrices $C_1, \ldots, C_{\alpha d}$ directly. This is described in [4, Section 4.4] and can be done in the following way. Let $C_1, \ldots, C_{\alpha d}$ be generating matrices of an αd dimensional digital sequence and let $\vec{c}_{j,k}$ denote the k-th row of matrix C_j . Define matrices E_1, \ldots, E_d , where the k-th row of matrix E_j is given by $\vec{e}_{j,k}$, in the following way. For all $j \in \{1, \ldots, d\}, u \in \mathbb{N}_0$ and $v \in \{1, \ldots, \alpha\}$ let

$$\vec{e}_{j,u\alpha+v} := \vec{c}_{(j-1)\alpha+v,u+1}$$

If $C_1, \ldots, C_{\alpha d}$ are the generating matrices of a digital sequence $S_{\alpha d}$ in dimension αd , then the matrices E_1, \ldots, E_d defined above, are the generating matrices of $\mathscr{D}^d_{\alpha}(S_{\alpha d})$. Thus one can also obtain generating matrices $E_1, \ldots, E_d \in \mathbb{Z}_2^{\mathbb{N} \times \mathbb{N}}$ which generate a digital sequence satisfying Theorem 2. The following result follows from [3, Theorem 4.1 and Theorem 4.2]

The following result follows from [3, Theorem 4.1 and Theorem 4.2] (where we set $\alpha = d$).

PROPOSITION 8. If $S_{\alpha d}$ is an order 1 digital $(t', \alpha d)$ -sequence over \mathbb{Z}_2 , then $\mathscr{D}^d_{\alpha}(S_{\alpha d})$ is an order α digital (t, d)-sequence over \mathbb{Z}_2 with

$$t = \alpha t' + d\binom{\alpha}{2}.$$

For the construction based on Sobol's and Niederreiter's sequence introduced above we have

$$t = \sum_{j=1}^{d} (e_j - 1)$$

(see [7, Section 8.1] for details) and therefore we obtain explicit constructions of order α digital (t, d)-sequences over \mathbb{Z}_2 with

$$t = \alpha \sum_{j=1}^{\alpha d} (e_j - 1) + d\binom{\alpha}{2}.$$

Note that for the construction introduced above we have $c_{j,k,l} = 0$ for all k > l. Using the interlacing construction we obtain generating matrices E_1 , ..., E_d with $E_j = (e_{j,k,l})_{k,l \in \mathbb{N}}$ and

(6)
$$e_{j,k,l} = 0$$
 for all $k > \alpha l$.

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Now we propose that every order α digital (t, d)-sequence over \mathbb{Z}_2 with $\alpha \geq 5$ that is constructed by interlacing of order 1 digital sequence with matrices of the form (4) has the optimal order of periodic L_2 -discrepancy. In a nutshell, we formulate the following more concrete version of our main result (Theorem 2).

THEOREM 9. Let $d \in \mathbb{N}$, $d \geq 2$. Let $S_{\alpha d}$ be a usual (i.e., order 1) digital $(t, \alpha d)$ -sequence over \mathbb{Z}_2 obtained from matrices that are constructed like in (4) with $\alpha \geq 5$. Then we have

$$L_{2,N}^{\mathrm{per}}(\mathscr{D}^d_{\alpha}(\mathcal{S}_{\alpha d})) \lesssim_d \frac{(\log N)^{(d-1)/2}}{N} \sqrt{S(N)} \quad for \ all \ N \ge 2.$$

3. Proofs

Obviously, Theorem 9 implies Theorem 2. The proof of Theorem 9 will be based on a Walsh series representation of the squared periodic L_2 -discrepancy.

Walsh functions. For $k \in \mathbb{N}_0$ the k-th Walsh function (in base 2) wal_k: $[0,1) \rightarrow \{-1,1\}$ is defined in the following way: let k have binary representation

$$k = \kappa_{a-1}2^{a-1} + \dots + \kappa_1 2 + \kappa_0,$$

with $\kappa_i \in \{0, 1\}$, and let $x \in [0, 1)$ have binary expansion

$$x = \frac{\xi_1}{2} + \frac{\xi_2}{2^2} + \cdots$$

with $\xi_i \in \{0, 1\}$ (unique in the sense that infinitely many of the ξ_i must be zero), then

$$\operatorname{wal}_k(x) := (-1)^{\xi_1 \kappa_0 + \dots + \xi_a \kappa_{a-1}}$$

For dimension $d \ge 2$, vectors $\boldsymbol{k} = (k_1, \dots, k_d) \in \mathbb{N}_0^d$ and $\boldsymbol{x} = (x_1, \dots, x_d) \in [0, 1)^d$ we write

$$\operatorname{wal}_{k}(x) := \prod_{j=1}^{d} \operatorname{wal}_{k_{j}}(x_{j})$$

A collection of useful properties of Walsh functions can be found in [7, Appendix A].

We call $x \in [0, 1)$ a dyadic rational if it can be written in a finite binary expansion. By \oplus we denote the digit-wise addition modulo 2. In order to avoid ambiguities and since it suffices for our purpose we define \oplus just for dyadic rationals. For dyadic rationals $x = \sum_{i=1}^{\infty} \frac{\xi_i}{2^i}$ and $y = \sum_{i=1}^{\infty} \frac{\eta_i}{2^i}$ with $\xi_i, \eta_i \in \{0, 1\}$, where both digit sequences $(\xi_i)_{i \ge 1}$ and $(\eta_i)_{i \ge 1}$ become eventually zero, we put

$$x \oplus y := \sum_{i=0}^{\infty} \frac{\zeta_i}{2^i}, \text{ where } \zeta_i := \xi_i + \eta_i \pmod{2}.$$

Obviously $x \oplus y$ is then also a dyadic rational. For vectors $x, y \in [0, 1)^d$ whose components are dyadic rationals we set $x \oplus y := (x_1 \oplus y_1, \dots, x_d \oplus y_d)$.

For any $\boldsymbol{k} \in \mathbb{N}_0^d$ and $\boldsymbol{x}, \boldsymbol{y} \in [0, 1)^d$ whose components are dyadic rationals we have

(7)
$$\operatorname{wal}_{k}(x \oplus y) = \operatorname{wal}_{k}(x) \operatorname{wal}_{k}(y)$$

It can be shown (see [7, Lemma 4.72]) that any digital net $\mathcal{P}_{2^m,d}$ (see Remark 4) is a subgroup of $([0,1)^d, \oplus)$ and furthermore, all components of every point of $\mathcal{P}_{2^m,d}$ are dyadic rationals. From (7) it follows that wal_k is a character of the group $(\mathcal{P}_{2^m,d}, \oplus)$. Hence, for any digital net $\mathcal{P}_{2^m,d}$ with generating matrices $C_1, \ldots, C_d \in \mathbb{Z}_2^{m \times m}$ and any $\mathbf{k} = (k_1, \ldots, k_d) \in \mathbb{N}_0^d$ it follows that

(8)
$$\frac{1}{2^m} \sum_{h=0}^{2^m-1} \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{x}_h) = \begin{cases} 1 & \text{if } C_1^\top \vec{k_1} + \dots + C_d^\top \vec{k_d} = \vec{0}, \\ 0 & \text{otherwise.} \end{cases}$$

For a proof of this fact we refer to [7, Lemma 4.75]. This property is called the *character property of digital nets*.

Walsh series expansion of the periodic L_2 -discrepancy. The starting point is the representation of the periodic L_2 -discrepancy in terms of exponential sums. Re-writing (1) we obtain

$$(L_{2,N}^{\text{per}}(\mathcal{P}))^2 = -\frac{1}{3^d} + \frac{1}{3^d N^2} \sum_{n,p=0}^{N-1} K_d(\boldsymbol{x}_n, \boldsymbol{x}_p),$$

where

$$K_d(\boldsymbol{x}, \boldsymbol{y}) := \sum_{\boldsymbol{h} \in \mathbb{Z}^d} \frac{1}{r(\boldsymbol{h})^2} \exp(2\pi i \boldsymbol{h} \cdot (\boldsymbol{x} - \boldsymbol{y}))$$
$$= \prod_{j=1}^d \bigg(\sum_{h=-\infty}^\infty \frac{1}{r(h)^2} \exp(2\pi i h(x_j - y_j)) \bigg).$$

Now we expand $K_d(\boldsymbol{x}, \boldsymbol{y})$ into a Walsh series. We have

$$K_d(\boldsymbol{x}, \boldsymbol{y}) = \sum_{\boldsymbol{k}, \boldsymbol{l} \in \mathbb{N}_0^d}
ho(\boldsymbol{k}, \boldsymbol{l}) \mathrm{wal}_{\boldsymbol{k}}(\boldsymbol{x}) \mathrm{wal}_{\boldsymbol{l}}(\boldsymbol{y}),$$

where

$$\rho(\boldsymbol{k}, \boldsymbol{l}) = \int_{[0,1]^{2d}} K_d(\boldsymbol{x}, \boldsymbol{y}) \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{x}) \operatorname{wal}_{\boldsymbol{l}}(\boldsymbol{y}) \, \mathrm{d}\boldsymbol{x} \, \mathrm{d}\boldsymbol{y}.$$

Due to the multiplicative structure of K_d and of the multi-dimensional Walsh functions, for $\mathbf{k} = (k_1, \ldots, k_d)$ and $\mathbf{l} = (l_1, \ldots, l_d)$ in \mathbb{N}_0^d we have

$$\rho(\boldsymbol{k}, \boldsymbol{l}) = \prod_{j=1}^{d} \rho(k_j, l_j),$$

where, for d = 1 and $k, l \in \mathbb{N}_0$,

$$\rho(k,l) = \int_0^1 \int_0^1 K_1(x,y) \operatorname{wal}_{k_j}(x) \operatorname{wal}_{l_j}(y) \, \mathrm{d}x \, \mathrm{d}y$$

= $\int_0^1 \int_0^1 \sum_{h=-\infty}^\infty \frac{1}{r(h)^2} \exp(2\pi i h(x-y)) \operatorname{wal}_k(x) \operatorname{wal}_l(y) \, \mathrm{d}x \, \mathrm{d}y$
= $\sum_{h=-\infty}^\infty \frac{1}{r(h)^2} \left(\int_0^1 \exp(2\pi i hx) \operatorname{wal}_k(x) \, \mathrm{d}x \right) \left(\int_0^1 \exp(-2\pi i hy) \operatorname{wal}_l(y) \, \mathrm{d}y \right)$
= $\sum_{h=-\infty}^\infty \frac{1}{r(h)^2} \left(\int_0^1 \exp(2\pi i hx) \operatorname{wal}_k(x) \, \mathrm{d}x \right) \overline{\left(\int_0^1 \exp(2\pi i hy) \operatorname{wal}_l(y) \, \mathrm{d}y \right)}.$

Put

$$\beta_{h,k} := \int_0^1 \exp(2\pi \mathbf{i} h x) \operatorname{wal}_k(x) \, \mathrm{d} x.$$

Note that $\beta_{0,0} = 1$, $\beta_{0,k} = 0$ for $k \in \mathbb{N}$ and $\beta_{h,0} = 0$ for $h \in \mathbb{Z} \setminus \{0\}$. Then we can write

$$\rho(k,l) = \sum_{h=-\infty}^{\infty} \frac{\beta_{h,k}\overline{\beta}_{h,l}}{r(h)^2}$$

and, in particular, $\rho(0,0) = 1$ and $\rho(0,l) = \rho(k,0) = 0$ for $k, l \in \mathbb{N}$. For $k, l \in \mathbb{N}$ we have

$$\rho(k,l) = \sum_{\substack{h=-\infty\\h\neq 0}}^{\infty} \frac{\beta_{h,k}\overline{\beta}_{h,l}}{r(h)^2} = \frac{6}{4\pi^2} \sum_{\substack{h=-\infty\\h\neq 0}}^{\infty} \frac{\beta_{h,k}\overline{\beta}_{h,l}}{h^2} = 6\gamma_2(k,l),$$

where $\gamma_2(k, l)$ are defined in [7, Eq. (14.17) on p. 453] as the Walsh coefficients of the normalized and periodically extended second Bernoulli polynomial. These coefficients are computed in [7, Lemma 14.17] and from there we obtain:

LEMMA 10. We have $\rho(0,0) = 1$ and $\rho(k,0) = \rho(0,l) = 0$ for all $k, l \in \mathbb{N}$. For $k \in \mathbb{N}$ write $k = 2^{a_1-1} + 2^{a_2-1} + \dots + 2^{a_v-1}$ with $v \in \mathbb{N}$ and $a_1 > a_2 > \dots > a_v \ge 1$, and $k' = k - 2^{a_1-1}$ and $k'' = k - 2^{a_1-1} - 2^{a_2-1} = k' - 2^{a_2-1}$. Likewise, for $l \in \mathbb{N}$ write $l = 2^{b_1-1} + 2^{b_2-1} + \dots + 2^{b_w-1}$ with $w \in \mathbb{N}$ and $b_1 > b_2 > \dots > b_w \ge 1$, and $l' = l - 2^{b_1-1}$ and $l'' = l - 2^{b_1-1} - 2^{b_2-1} = l' - 2^{b_2-1}$. Then for all $k, l \in \mathbb{N}$ we have

$$\rho(k,l) = \begin{cases} 2^{-2a_1} & \text{if } k = l, \\ 2^{-a_1 - b_1 - 2} & \text{if } k' = l' > 0 \text{ and } k \neq l, \\ -2^{-a_1 - a_2 - 2} & \text{if } k'' = l, \\ -2^{-b_1 - b_2 - 2} & \text{if } k = l'', \\ 0 & \text{otherwise.} \end{cases}$$

Using the Walsh series expansion of $K_d(\cdot, \cdot)$ we can write the periodic L_2 -discrepancy in the following way:

LEMMA 11. For any point set $\mathcal{P}_{N,d} = \{x_0, x_1, \dots, x_{N-1}\}$ in $[0,1)^d$ we have

(9)
$$(L_{2,N}^{\mathrm{per}}(\mathcal{P}_{N,d}))^2 = \frac{1}{3^d N^2} \sum_{n,p=0}^{N-1} \sum_{\boldsymbol{k},\boldsymbol{l}\in\mathbb{N}_0^d\setminus\{\boldsymbol{0}\}} \rho(\boldsymbol{k},\boldsymbol{l}) \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{x}_n) \operatorname{wal}_{\boldsymbol{l}}(\boldsymbol{x}_p).$$

where $\mathbf{k} = (k_1, \ldots, k_d)$, $\mathbf{l} = (l_1, \ldots, l_d)$, $\rho(\mathbf{k}, \mathbf{l}) := \prod_{j=1}^d \rho(k_j, l_j)$, where, for $k, l \in \mathbb{N}_0$ the coefficients $\rho(k, l)$ are given in Lemma 10.

For digital nets we can simplify the above formula further. But first introduce the notion of a digitally shifted digital net. Let

$$\mathcal{P}_{2^m,d} = \{oldsymbol{x}_0,oldsymbol{x}_1,\ldots,oldsymbol{x}_{2^m-1}\}$$

in $[0,1)^d$ be a digital net over \mathbb{Z}_2 and let $\boldsymbol{\sigma} \in [0,1)^d$ (in our context we restrict to $\boldsymbol{\sigma}$ with dyadic rationals as components). Then we call the point

set $\mathcal{P}_{2^m,d}(\boldsymbol{\sigma}) = \{ \boldsymbol{x}_0 \oplus \boldsymbol{\sigma}, \boldsymbol{x}_1 \oplus \boldsymbol{\sigma}, \dots, \boldsymbol{x}_{2^m-1} \oplus \boldsymbol{\sigma} \}$ a digitally shifted digital net over \mathbb{Z}_2 .

LEMMA 12. If $\mathcal{P}_{2^m,d}$ is a digital net over \mathbb{Z}_2 , then the squared periodic L_2 -discrepancy of $\mathcal{P}_{2^m,d}$ is given by

$$(L_{2,2^m}^{\mathrm{per}}(\mathcal{P}_{2^m,d}))^2 = \frac{1}{3^d} \sum_{k,l \in \mathcal{D}^*} \rho(k,l),$$

where $\mathcal{D}^* = \mathcal{D} \setminus \{0\}$ and where \mathcal{D} is the so-called dual net given by

$$\mathcal{D} = \left\{ (k_1, \dots, k_d) \in \mathbb{N}_0^d : C_1^\top \vec{k}_1 + \dots + C_d^\top \vec{k}_d = \vec{0} \right\},\$$

where for $k \in \mathbb{N}_0$ with binary expansion $k = \kappa_0 + \kappa_1 2 + \kappa_2 2^2 + \cdots$ we put $\vec{k} = (\kappa_0, \dots, \kappa_{m-1})^\top$. Again, the coefficients $\rho(\mathbf{k}, \mathbf{l})$ are given as in Lemma 11.

If $\mathcal{P}_{2^m,d}(\boldsymbol{\sigma})$ is a digitally shifted digital net over \mathbb{Z}_2 , then we have

$$\left(L_{2,2^m}^{\mathrm{per}}(\mathcal{P}_{2^m,d}(\boldsymbol{\sigma}))\right)^2 = \frac{1}{3^d} \sum_{\boldsymbol{k},\boldsymbol{l}\in\mathcal{D}^*} \rho(\boldsymbol{k},\boldsymbol{l}) \mathrm{wal}_{\boldsymbol{k}}(\boldsymbol{\sigma}) \mathrm{wal}_{\boldsymbol{l}}(\boldsymbol{\sigma}).$$

PROOF. From Lemma 11 we obtain

$$(L_{2,2^m}^{\mathrm{per}}(\mathcal{P}_{2^m,d}))^2 = \frac{1}{3^d 2^{2m}} \sum_{n,p=0}^{2^m-1} \sum_{\boldsymbol{k},\boldsymbol{l}\in\mathbb{N}_0^d\setminus\{\boldsymbol{0}\}} \rho(\boldsymbol{k},\boldsymbol{l}) \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{x}_n) \operatorname{wal}_{\boldsymbol{l}}(\boldsymbol{x}_p)$$
$$= \frac{1}{3^d} \sum_{\boldsymbol{k},\boldsymbol{l}\in\mathbb{N}_0^d\setminus\{\boldsymbol{0}\}} \rho(\boldsymbol{k},\boldsymbol{l}) \left(\frac{1}{2^m} \sum_{n=0}^{2^m-1} \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{x}_n)\right) \left(\frac{1}{2^m} \sum_{p=0}^{2^m-1} \operatorname{wal}_{\boldsymbol{l}}(\boldsymbol{x}_p)\right).$$

Now the first result follows from (8).

The second part follows in the same manner using (7). \Box

With Lemma 11 and Lemma 12 we are in a comparable situation to [8]. Instead of [8, Lemma 2.2 and 2.4] for the proof of [8, Theorem 1.1] now Lemma 11 and Lemma 12 will serve as starting point of the proof of the present Theorem 9. The main difference is in the definition of the coefficients $\rho(\mathbf{k}, \mathbf{l})$ here and $r(\mathbf{k}, \mathbf{l})$ in [8]. However, we will see that $\rho(\mathbf{k}, \mathbf{l})$ can be estimated in the same way as $r(\mathbf{k}, \mathbf{l})$ in [8]. The crucial part of the proof is to estimate the periodic L_2 -discrepancy by an expression, that appears as an upper bound on the standard L_2 -discrepancy in [8, Lemma 3.1]. Then one can use exactly the same procedure like in [8] in order to finish the proof of our Theorem 9. We will show in detail how to derive the mentioned upper bound on the periodic L_2 -discrepancy.

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PROOF OF THEOREM 9. Let $S_{\alpha d}$ be a digital sequence in dimension αd based on the construction (4) and apply the digit interlacing function \mathscr{D}_{α}^{d} of order α . The resulting sequence $S_{d} := \mathscr{D}_{\alpha}^{d}(S_{\alpha d}) := (\boldsymbol{x}_{0}, \boldsymbol{x}_{1}, \boldsymbol{x}_{2}, ...)$ in $[0, 1)^{d}$ is an order α digital (t, d)-sequence with $t = \alpha \sum_{j=1}^{\alpha d} (e_{j} - 1) + d\binom{\alpha}{2}$. Using (5), S_{d} is also an order α' digital (t', d)-sequence with $t' = \lceil t\alpha'/\alpha \rceil \leq t$ for all $1 \leq \alpha' \leq \alpha$. Thus it is also an order α' digital (t, d)-sequence for all $1 \leq \alpha' \leq \alpha$.

Let C_1, \ldots, C_d denote the generating matrices of the digital sequence S_d . Let $C_{j,\mathbb{N}\times m}$ denote the first *m* columns of C_j . Due to (6) only the first αm rows of $C_{j,\mathbb{N}\times m}$ can be nonzero and hence C_j is of the form

$$C_j = \left(\begin{array}{c|c} C_{j,\alpha m \times m} & D_{j,\alpha m \times \mathbb{N}} \\ \hline 0_{\mathbb{N} \times m} & F_{j,\mathbb{N} \times \mathbb{N}} \end{array}\right) \in \mathbb{Z}_2^{\mathbb{N} \times \mathbb{N}},$$

where $0_{\mathbb{N}\times m}$ denotes the $\mathbb{N}\times m$ zero matrix. Note that the entries of each column of the matrix $F_{j,\mathbb{N}\times\mathbb{N}}$ become eventually zero.

We use Lemma 11 to obtain

$$(L_{2,N}^{\mathrm{per}}(\mathcal{S}_d))^2 = \frac{1}{3^d N^2} \sum_{\boldsymbol{k}, \boldsymbol{l} \in \mathbb{N}_0^d \setminus \{\boldsymbol{0}\}} \rho(\boldsymbol{k}, \boldsymbol{l}) \bigg(\sum_{n=0}^{N-1} \mathrm{wal}_{\boldsymbol{k}}(\boldsymbol{x}_n) \bigg) \bigg(\sum_{p=0}^{N-1} \mathrm{wal}_{\boldsymbol{l}}(\boldsymbol{x}_p) \bigg).$$

Let $N = 2^{m_1} + 2^{m_2} + \cdots + 2^{m_r}$ with $m_1 > m_2 > \cdots > m_r \ge 0$ (hence r = S(N)). We split the initial N terms of the sequence S_d into the point sets

$$\mathcal{P}_i := \left\{ x_{2^{m_1}+\dots+2^{m_{i-1}}},\dots,x_{-1+2^{m_1}+\dots+2^{m_i}}
ight\},$$

for $i \in \{1, ..., r\}$, where for i = 1 we define $2^{m_1} + \cdots + 2^{m_{i-1}} = 0$. Any $n \in \{2^{m_1} + \cdots + 2^{m_{i-1}}, \ldots, -1 + 2^{m_1} + \cdots + 2^{m_i}\}$ can be written in the form

$$n = 2^{m_1} + \dots + 2^{m_{i-1}} + a = 2^{m_{i-1}}l + a$$

with $a \in \{0, 1, ..., 2^{m_i} - 1\}$ and $l = 1 + 2^{m_i - m_{i-1}} + \cdots + 2^{m_1 - m_{i-1}}$ if i > 1and l = 0 for i = 1. Hence the binary digit vector of n is given by

$$\vec{n} = (a_0, a_1, \dots, a_{m_i-1}, l_0, l_1, l_2, \dots)^\top =: \begin{pmatrix} \vec{a} \\ \vec{l} \end{pmatrix}$$

where a_0, \ldots, a_{m_i-1} are the binary digits of a and l_0, l_1, l_2, \ldots are the binary digits of l. With this notation we have

$$C_{j}\vec{n} = \begin{pmatrix} C_{j,\alpha m_{i} \times m_{i}}\vec{a} \\ 0 \\ 0 \\ \vdots \end{pmatrix} + \begin{pmatrix} D_{j,\alpha m \times \mathbb{N}} \\ \overline{F_{j,\mathbb{N} \times \mathbb{N}}} \end{pmatrix} \vec{l}$$

For the point set \mathcal{P}_i under consideration, the vector

(10)
$$\vec{\sigma}_{i,j} := \left(\frac{D_{j,\alpha m \times \mathbb{N}}}{F_{j,\mathbb{N} \times \mathbb{N}}}\right) \vec{l}$$

is constant and its components become eventually zero (i.e., only a finite number of components is nonzero). Furthermore, $C_{j,\alpha m_i \times m_i} \vec{a}$ for $a \in \{0, 1, \ldots, 2^{m_i} - 1\}$ and $j \in \{1, \ldots, d\}$ generate an order α digital (t, m_i, d) -net over \mathbb{Z}_2 (which is also an order α' digital (t, m_i, d) -net over \mathbb{Z}_2 for $1 \leq \alpha' \leq \alpha$).

This means that the point set \mathcal{P}_i is a digitally shifted order α digital (t, m_i, d) -net over \mathbb{Z}_2 and the generating matrices

(11)
$$C_{1,\alpha m_i \times m_i}, \ldots, C_{d,\alpha m_i \times m_i}$$

of this digital net are the left upper $\alpha m_i \times m_i$ submatrices of the generating matrices C_1, \ldots, C_d of the digital sequence. We denote the digital shift, which is given by (10), by σ_i . Note that all the coordinates of the digital shift are dyadic rationals since the components of $\vec{\sigma}_{i,j}$ become eventually zero.

Let \mathcal{D}_i denote the dual net corresponding to the digital net with generating matrices (11), i.e.,

$$\mathcal{D}_i = \left\{ \boldsymbol{k} = (k_1, \dots, k_d) \in \mathbb{N}_0^d : C_{1,\alpha m_i \times m_i}^\top \vec{k}_1 + \dots + C_{d,\alpha m_i \times m_i}^\top \vec{k}_d = \vec{0} \right\},\$$

where for $k \in \mathbb{N}_0$ with binary expansion $k = \kappa_0 + \kappa_1 2 + \kappa_2 2^2 + \cdots$ we set $\vec{k} = (\kappa_0, \kappa_1, \dots, \kappa_{\alpha m_i - 1})^\top$. Set $\mathcal{D}_i^* = \mathcal{D}_i \setminus \{\mathbf{0}\}$. Then we have

$$\sum_{n=0}^{N-1} \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{x}_n) = \sum_{i=1}^r \sum_{n=2^{m_1}+\dots+2^{m_i-1}}^{-1+2^{m_1}+\dots+2^{m_i}} \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{x}_n),$$

where again for i = 1 we set $2^{m_1} + \cdots + 2^{m_{i-1}} = 0$, and by the character property (8)

$$\sum_{n=2^{m_1}+\dots+2^{m_i}}^{-1+2^{m_1}+\dots+2^{m_i}} \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{x}_n) = \begin{cases} \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{\sigma}_i)2^{m_i} & \text{if } \boldsymbol{k} \in \mathcal{D}_i, \\ 0 & \text{if } \boldsymbol{k} \notin \mathcal{D}_i. \end{cases}$$

Therefore

$$(L_{2,N}^{\text{per}}(\mathcal{S}_d))^2 = \frac{1}{3^d N^2} \sum_{i,i'=1}^r 2^{m_i + m_{i'}} \sum_{\boldsymbol{k} \in \mathcal{D}_i^*, \boldsymbol{l} \in \mathcal{D}_{i'}^*} \rho(\boldsymbol{k}, \boldsymbol{l}) \operatorname{wal}_{\boldsymbol{k}}(\boldsymbol{\sigma}_i) \operatorname{wal}_{\boldsymbol{l}}(\boldsymbol{\sigma}_{i'})$$
$$\leq \frac{1}{3^d N^2} \sum_{i,i'=1}^r 2^{m_i + m_{i'}} \sum_{\boldsymbol{k} \in \mathcal{D}_i^*, \boldsymbol{l} \in \mathcal{D}_{i'}^*} |\rho(\boldsymbol{k}, \boldsymbol{l})|.$$

Now define

$$\mathcal{E}_{i,i'} = \left\{ (\boldsymbol{k}, \boldsymbol{l}) \in \mathcal{D}_i^* \times \mathcal{D}_{i'}^* : \rho(\boldsymbol{k}, \boldsymbol{l}) \neq 0 \right\}$$

and

$$\mathcal{E}_{i,i'}(z) = \left\{ (\boldsymbol{k}, \boldsymbol{l}) \in \mathcal{E}_{i,i'} : \mu(\boldsymbol{k}) + \mu(\boldsymbol{l}) = z \right\},\$$

where the function $\mu \colon \mathbb{N}_0 \to \mathbb{N}_0$ is defined by $\mu(0) := 0$ and for

$$k = \kappa_0 + \kappa_1 2 + \dots + \kappa_{a-2} 2^{a-2} + 2^{a-1}$$

with $\kappa_j \in \{0,1\}$ by $\mu(k) := a$ and, for $\mathbf{k} = (k_1, \ldots, k_d) \in \mathbb{N}_0^d$, we put $\mu(\mathbf{k}) := \mu(k_1) + \cdots + \mu(k_d)$.

From Lemma 10 it follows that for $(\mathbf{k}, \mathbf{l}) \in \mathcal{E}_{i,i'}$ we have

$$|
ho(oldsymbol{k},oldsymbol{l})| \leq rac{1}{2^{\mu(oldsymbol{k})+\mu(oldsymbol{l})}}$$

Thus we have

(12)
$$(L_{2,N}^{\text{per}}(\mathcal{S}_d))^2 \le \frac{1}{3^d N^2} \sum_{i,i'=1}^r 2^{m_i + m_{i'}} \sum_{(\boldsymbol{k},\boldsymbol{l})\in\mathcal{E}_{i,i'}} \frac{1}{2^{\mu(\boldsymbol{k}) + \mu(\boldsymbol{l})}}$$

Now we re-order the sum over all $(\mathbf{k}, \mathbf{l}) \in \mathcal{E}_{i,i'}$ according to the value of $\mu(\mathbf{k}) + \mu(\mathbf{l})$. Assume that $\mathbf{k} = (k_1, \ldots, k_d) \in \mathcal{D}_i^*$. Let

$$k_j = \kappa_{j,0} + \kappa_{j,1}2 + \dots + \kappa_{j,a_j-2}2^{a_j-2} + 2^{a_j-1}$$

with $a_j = \mu(k_j)$ for $j \in \{1, \ldots, d\}$. Let further $\vec{c}_{j,u}$ denote the *u*-th row vector of the matrix $C_{j,\alpha m_i \times m_i}$. Then

$$C_{1,\alpha m_i \times m_i}^{\top} \vec{k}_1 + \dots + C_{d,\alpha m_i \times m_i}^{\top} \vec{k}_d = \vec{0}$$

is equivalent to

$$\sum_{j=1}^{d} \left(\sum_{u=0}^{a_j-2} \vec{c}_{j,u+1}^{\top} \kappa_{j,u} + \vec{c}_{j,a_j-1}^{\top} \right) = \vec{0}.$$

Hence it follows from the linear independence property for the row vectors of generating matrices of digital nets in Definition 5 that

$$\mu(\mathbf{k}) = a_1 + \dots + a_d > m_i - t.$$

In the same way $\boldsymbol{l} \in \mathcal{D}_{i'}^*$ implies that $\mu(\boldsymbol{l}) > m_{i'} - t$. Hence $(\boldsymbol{k}, \boldsymbol{l}) \in \mathcal{D}_i^* \times \mathcal{D}_{i'}^*$ implies $\mu(\boldsymbol{k}) + \mu(\boldsymbol{l}) \ge m_i + m_{i'} - 2t + 2$.

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Thus for the innermost sum in (12) we have

$$\sum_{(\mathbf{k}, \mathbf{l}) \in \mathcal{E}_{i, i'}} \frac{1}{2^{\mu(\mathbf{k}) + \mu(\mathbf{l})}} = \sum_{z=m_i + m_{i'} - 2t+2}^{\infty} \frac{|\mathcal{E}_{i, i'}(z)|}{2^z}$$

and this implies

(13)
$$\left(L_{2,N}^{\text{per}}(\mathcal{S}_d)\right)^2 \leq \frac{1}{3^d} \sum_{i,i'=1}^r \frac{2^{m_i}}{N} \frac{2^{m_{i'}}}{N} \sum_{z=m_i+m_{i'}-2t+2}^\infty \frac{|\mathcal{E}_{i,i'}(z)|}{2^z}.$$

Now the right-hand side of the estimate (13) for the squared periodic L_2 -discrepancy is – up to the factor $1/3^d$ – the same as the upper bound on the standard L_2 -discrepancy in [8, Lemma 3.1, Eq. (16)]. Note that the sets $\mathcal{E}_{i,i'}(z)$ are subsets of the corresponding sets $\mathcal{J}_{i,i'}(z)$ used in [8, Lemma 3.1, Eq. (15)]. This means that from this stage on we can proceed in exactly the same way as in [8] in order to obtain the proposed upper bound in Theorem 9. \Box

REMARK 13. In [5] it is shown by a different proof method that even order $\alpha = 2$ digital sequences suffice in order to obtain the optimal order of magnitude for the standard L_2 -discrepancy. We conjecture that the same holds true for the periodic L_2 -discrepancy.

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