

# Unconditional convergence and optimal error estimates of the Euler semi-implicit scheme for a generalized nonlinear Schrödinger equation

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**Abstract** In this paper, we focus on a linearized backward Euler scheme with a Galerkin finite element approximation for the time-dependent nonlinear Schrödinger equation. By splitting an error estimate into two parts, one from the spatial discretization and the other from the temporal discretization, we obtain unconditionally optimal error estimates of the fully-discrete backward Euler method for a generalized nonlinear Schrödinger equation. Numerical results are provided to support our theoretical analysis and efficiency of this method.

**Keywords** Unconditional convergence · Optimal error estimate · Backward Euler method · Galerkin finite element method · Time-dependent Schrödinger equation

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# 1 Introduction

Nonlinear Schrödinger equation is a classical partial differential equation that has been applied in modelling the evolution of a wave packet in a nonlinear and dispersive medium. It has been derived in many fields; i.e., nonlinear optics [23, 25], plasma physics [12] and water wave [1, 12, 23, 25]. Moreover, this equation can be used in pattern formulation, where it can model many non-equilibrium pattern forming systems. For example, it can be developed for the optics field as a model for optical pulse propagation in nonlinear fibers [4].

In the past several decades, numerous effort has been devoted to mathematical study of nonlinear Schrödinger equation. There are two main branches of mathematical research for nonlinear Schrödinger equation. One is construction of exact solution, which includes the trial function method [5], Jacobi elliptic function expansion method [8, 30], and G'/G-expansion method [19]. Another important branch is numerical approximation method, including the finite element method, finite difference method and spectral method. Many authors have studied a considerable number of numerical methods for nonlinear Schrödinger equation. For example, Delfour [6], Bao et al. [3] and Reichel [26] on the finite difference method, Akrivis [2], Tourigny [28], Sanz-Serna [27], and Zouraris [31] on the finite element method and Feit [10] on the spectral method. In [6], Delfour presented a finite difference method to approximate a Schrödinger equation. The main feature of this method given by Delfour is that it satisfies a discrete analogue of an important conservation law of this equations. In [28], Tourigny obtained optimal  $H^1$  estimates for the fully-implicit backward Euler scheme and Crank-Nicolson scheme for a nonlinear Schrödinger equation by applying a nonlinear stability theory. But these optimal  $H^1$  error estimates required the time step conditions  $\Delta t = o(h^{\frac{d}{2}})$  and  $\Delta t = o(h^{\frac{d}{4}})$  for the two schemes, respectively, where *d* represents the dimension of space.

Several time-discrete methods have been widely used to time-dependent nonlinear partial differential equations (PDEs), for example, fully-implicit, semi-implicit, and explicit. The fully-implicit time-discrete Euler method for PDEs must solve nonlinear equations at every time step and needs inner iterations. Compared to the fully-implicit method, the explicit and semi-implicit time-discrete methods have been widely used because they just need to solve a linear system at each time step. However, in order to obtain error estimates of the explicit and semi-implicit methods for PDEs, one usually needs the boundedness of their fully-discrete solution in the  $L^{\infty}$  norm. For this purpose, many authors employ the mathematical induction with an inverse inequality to obtain

$$\|U_h^n - R_h u^n\|_{L^{\infty}} \le Ch^{-d/2} \|U_h^n - R_h u^n\|_{L^2} \le Ch^{-d/2} (\Delta t + h^{r+1}).$$

where  $U_h^n$  is a numerical solution,  $u^n$  is the exact solution,  $R_h$  is a projection operator, r is the degree of the fully discrete Galerkin finite element method,  $\Delta t$  is a time step, and h is a spatial step. However, the above inequality results in a restriction on  $\Delta t$  and h; see [3, 13, 16, 17, 24]. That is, optimal error estimates are obtained under a time-step condition. This condition may result in the use of small time steps. Thus the computational complexity is increased extremely in practice. Recently, a new analytic method is presented in [11, 20–22]. The main approach of these papers is to

split an error estimate into a time-discrete error estimate and a spatial-discrete error estimate. The spatial-discrete error is obtained by discretizing the temporal discrete equation, independent of time-step  $\Delta t$ .

In this paper, we apply this approach to study a generalized nonlinear Schrödinger equation by *r*-order FEMs (finite element methods,  $r \ge 1$ ) and the backward Euler time-discrete method. As the regularity of the time-discrete solution  $U^n$  of this Schrödinger equation is obtained, an error estimate of the fully-discrete solution is established without any time step restriction by using the mathematical induction and an inverse inequality:

$$\|U_h^n - R_h U^n\|_{L^{\infty}} \le Ch^{-d/2} \|U_h^n - R_h U^n\|_{L^2} \le Ch^{r+1-d/2},$$

where  $U^n$  is the numerical solution of the time-discrete Schrödinger equation and  $R_h$  is a Ritz operator. Due to the above boundedness of  $U_h^n$  in the  $L^\infty$  norm, we can obtain the  $L^2$  norm optimal error estimate without any restriction on  $\Delta t$  and h in the traditional way [28]:

$$\|u^m - U_h^m\|_{L^2} \le C^{**}(\Delta t + h^{r+1}).$$

The outline of this paper is as follows: In Section 2, a function setting of the Schrödinger equation is introduced, together with some basic assumptions. Moreover, we present a backward Euler FEM for a generalized nonlinear Schrödinger equation. In Section 3, the regularity of a time-discrete numerical solution is obtained. Meanwhile, the boundedness of the time-discrete numerical solution in the  $L^{\infty}$  norm is established. In Section 4, the unconditionally optimal  $L^2$  norm error estimate of the fully-discrete FEM is obtained. In Section 5, we give two numerical experiments to validate our theoretical analysis. Finally, conclusions are drawn in Section 6.

#### 2 Preliminaries

In this section, we focus on a nonlinear Schrödinger equation defined by

$$\begin{cases} iu_t + \Delta u + f(|u|^2)u = 0, \ x \in \Omega, \ 0 < t \le T, \\ u(x, 0) = u_0(x), & x \in \Omega, \\ u = 0, & x \in \partial\Omega, \end{cases}$$
(2.1)

where *u* is a complex-valued function defined in  $\Omega \times [0, T]$  and  $\Omega \subset R^2$  is a bounded domain with boundary  $\partial \Omega$ . Meanwhile, we assume that  $f : R \mapsto R$  is a given function belonging to  $C^2(R)$ .

Let  $\Gamma_h$  be a regular partition of  $\Omega$  into triangles  $T_j$ , j = 1, 2, ..., M, in  $\mathbb{R}^2$ , and  $h = \max_{1 \le j \le M} \{diam T_j\}$  be the mesh size. If a triangle  $T_j$  is on the boundary, we define  $\widetilde{T}_j$  as the triangle with one curved side. If  $T_j$  is an interior element, we set  $\widetilde{T}_j = T_j$ .

From the above definition, for a given division  $\Gamma_h$ , we define the finite element spaces

 $V_h = \{v_h \in C(\overline{\Omega}) : v_h|_{T_j} \text{ is a polynomial of degree } r \text{ and } v_h = 0 \text{ on } \partial\Omega\},\$  $S_h = \{v_h \in C(\overline{\Omega}) : v_h|_{\widetilde{T_j}} \text{ is a polynomial of degree } r\},\$ 

where  $\partial \Omega$  is defined by  $\widetilde{T}_j \setminus T_j$ .

From the above definitions, we can find that  $V_h$  is a subspace of  $H_0^1(\Omega_h)$  and  $S_h$  is a subspace of  $H^1(\Omega_h)$ . We define  $\pounds := \{ \pounds v : \pounds v = 0 \text{ on } \partial \Omega; \pounds v = v \text{ on } T_j \forall v \in S_h \}$ . Moreover, we set  $F : C(\overline{\Omega}) \longrightarrow S_h$  to be the Lagrangian operator and define  $\Pi_h := \pounds F$ . Obviously,  $\Pi_h$  is a projection operator from  $C(\overline{\Omega}) \longrightarrow V_h$ .

For  $u, v \in L^2(\Omega)$ , we define the  $L^2$  inner product as follows:

$$(u, v) = \int_{\Omega} u(x) \overline{v(x)} dx,$$

where  $\overline{v}$  is the conjugate of v. By an interpolation theory, we obtain

$$\|\Pi_h v - v\|_{L^2} + h \|\nabla(\Pi_h v - v)\|_{L^2} \le Ch^{r+1} \|v\|_{H^{r+1}}, \qquad (2.2)$$

where C > 0 is a constant. Subsequently, for simplicity, C (with or without a subscript) will denote a positive constant depending only on  $\Omega$ , which may stand for a different value at its different occurrence.

Assume that  $R_h: H_0^1(\Omega) \to V_h$  is a Ritz projection operator defined by

$$(\nabla(v - R_h v), \nabla w) = 0 \quad \forall w \in V_h.$$
(2.3)

By the classical finite element theory [7, 29], it holds that

$$\|v - R_h v\|_{L^2} + h \|\nabla (v - R_h v)\|_{L^2} \le Ch^s \|v\|_{H^s}, \quad 1 \le s \le r+1, \quad v \in H^1_0(\Omega)$$
(2.4)

and the inverse inequality holds:

$$\|v\|_{L^{\infty}} \le Ch^{-\frac{a}{2}} \|v\|_{L^{2}}, \quad d = 2, 3, \quad v \in V_{h}.$$
(2.5)

Let  $\Delta t > 0$  be the time step and  $t^n = n\Delta t$ , n = 0, 1, ..., N, where  $t^N = T$ . We denote  $u^n = u(x, t_n)$ . For a sequence  $\{z^n\}_{n=0}^N$ , we define

$$D_t z^n = \frac{z^n - z^{n-1}}{\Delta t}, \quad n = 1, 2..., N$$

With an explicit treatment of the nonlinear term, an Euler semi-implicit scheme is to find  $U_h^n \in V_h$  such that

$$i(D_t U_h^n, v) - (\nabla U_h^n, \nabla v) + (f(|U_h^{n-1}|^2)U_h^n, v) = 0, \quad n = 1, 2, ...N,$$
(2.6)

for any  $v \in V_h$ , where  $U_h^0 = \prod_h u_0$ .

Meanwhile, we define  $U^n$  to be the solution of the following time-discrete system:

$$iD_t U^n + \Delta U^n + f(|U^{n-1}|^2)U^n = 0, \quad n = 1, 2, ...N,$$
 (2.7)

with the boundary and initial conditions

$$\begin{cases} U^{n}(x) = 0 & \forall x \in \partial \Omega, \ n = 1, 2, ..., N, \\ U^{0}(x) = u_{0}(x) \ \forall x \in \Omega. \end{cases}$$
(2.8)

The key to our proof in this paper is the following error splitting [11, 20–22]:

$$||U_h^n - u^n|| \le ||e^n|| + ||e_h^n|| + ||U^n - R_h U^n||$$

for any norm  $\|\cdot\|$ , where

$$e^n = U^n - u^n, \quad e^n_h = R_h U^n - U^n_h.$$

Below  $e^n$  and  $e^n_h$  are always defined by the above forms.

**Lemma 2.1** (Discrete Gronwall's inequality [14, 15, 18]) Let  $\Delta t$ , B,  $a_k$ ,  $b_k$ ,  $c_k$  and  $\gamma_k$ , for integers  $k \ge 0$ , be non-negative numbers such that

$$a_n + \Delta t \sum_{k=0}^n b_k \le \Delta t \sum_{k=0}^n \gamma_k a_k + \Delta t \sum_{k=0}^n c_k + B, \quad n \ge 0.$$
 (2.9)

Suppose that  $\Delta t \gamma_k < 1$ , and set  $\sigma_k = (1 - \Delta t \gamma_k)^{-1}$ . Then

$$a_n + \Delta t \sum_{k=0}^n b_k \le \exp(\Delta t \sum_{k=0}^n \gamma_k \sigma_k) (\Delta t \sum_{k=0}^n c_k + B), \quad n \ge 0.$$
(2.10)

Throughout this paper we make the following assumption on the prescribed data for problem (2.1), which specifies the regularity of the sultion for our main results.

**Assumption** (A1): The solution to the initial/boundary value problem (2.1) exists and satisfies

$$\|u_0\|_{H^{r+1}} + \|u\|_{L^{\infty}((0,T);H^{r+1})} + \|u_t\|_{L^{\infty}((0,T);H^{r+1})} + \|u_{tt}\|_{L^2((0,T);L^2)} \le C,$$
  
where C is a positive constant, which depends only on  $\Omega$ .

#### **3** Temporal error estimates

In this section, we establish an error bound for  $||u^n - U^n||_{L^2}$  and the boundedness of the time discrete numerical solution in the  $L^{\infty}$  norm.

We assume that u is the solution of system (2.1). Then we see that

$$iD_{t}u^{n} + \Delta u^{n} + f(|u^{n-1}|^{2})u^{n} = iD_{t}u^{n} - iu_{t}^{n} + f(|u^{n-1}|^{2})u^{n} - f(|u^{n}|^{2})u^{n}.$$
 (3.1)  
Let  $P^{n} = iD_{t}u^{n} - iu_{t}^{n} + f(|u^{n-1}|^{2})u^{n} - f(|u^{n}|^{2})u^{n}$  and  $K = \max_{0 \le n \le N} ||u^{n}||_{L^{\infty}} + 1.$   
Due to the regularity assumption **Assumption(A1)**, it is easy to see that

$$\left(\sum_{n=1}^{N} \Delta t \| P^{n} \|_{L^{2}}^{2}\right)^{\frac{1}{2}} + \Delta t \| P^{n} \|_{L^{2}} \le C \Delta t \quad \forall v \in V_{h},$$
(3.2)

where we applying

$$|f(|u^{n}|^{2})| + |f'(\xi)| \le C_{L}$$
for  $|\xi| \le ||u^{n}||_{L^{\infty}}^{2} + ||u^{n-1}||_{L^{\infty}}^{2} \le 2K^{2}.$ 
(3.3)

**Theorem 3.1** Suppose that (2.1) has a unique solution u satisfying Assumption (A1). Then there exists a positive constant  $\tau$  such that when  $\Delta t < \tau_0$ , the time-discrete system defined in Eq. 2.7 has a unique solution  $U^n$ , n=1,...,N, such that

$$\left\| U^{n} \right\|_{H^{2}} \le C_{0}, \tag{3.4}$$

$$\left\|e^{n}\right\|_{L^{2}}+\left\|e^{n}\right\|_{H^{1}}+(\Delta t)^{\frac{1}{2}}\left\|e^{n}\right\|_{H^{2}}\leq C_{0}\Delta t.$$
(3.5)

*Proof* System (2.6) is a linear elliptic equation. Following the classical theory of PDEs, we can find that the solution of system (2.6) exists and is unique. From Eqs. 3.1 and 2.7, we see that

$$i\frac{e^{1}}{\Delta t} + \Delta e^{1} + f(|u_{0}|^{2})e^{1} = P^{1}.$$
(3.6)

Multiplying Eq. 3.6 by  $e^1$  and integrating the result over  $\Omega$ , we have

$$i\frac{\|e^1\|_{L^2}^2}{\Delta t} - \|\nabla e^1\|_{L^2}^2 + (f(|u_0|^2)e^1, e^1) = (P^1, e^1).$$
(3.7)

Taking the imaginary parts of the above equation and applying (3.2), we obtain

$$\left\|e^{1}\right\|_{L^{2}} \leq \Delta t \left\|P^{1}\right\|_{L^{2}} \leq C\Delta t.$$
(3.8)

Meanwhile, multiplying Eq. 3.6 by  $\Delta e^1$  and integrating it over  $\Omega$ , we get

$$-i\frac{\left\|\nabla e^{1}\right\|_{L^{2}}^{2}}{\Delta t} + \left\|\Delta e^{1}\right\|_{L^{2}}^{2} + (f(|u_{0}|^{2})e^{1}, \Delta e^{1}) = (P^{1}, \Delta e^{1}), \quad (3.9)$$

which implies

$$\frac{\left\|\nabla e^{1}\right\|_{L^{2}}^{2}}{\Delta t} \leq \frac{1}{4} \left\|\Delta e\right\|_{L^{2}}^{2} + 2\left\|P^{1}\right\|_{L^{2}}^{2} + 2\left\|f(|u_{0}|^{2})e^{1}\right\|_{L^{2}}^{2}$$
(3.10)

and

$$\left\|\Delta e^{1}\right\|_{L^{2}}^{2} \leq \frac{1}{4} \left\|\Delta e^{1}\right\|_{L^{2}}^{2} + 2\left\|P^{1}\right\|_{L^{2}}^{2} + 2\left\|f(|u_{0}|^{2})e^{1}\right\|_{L^{2}}^{2}.$$
 (3.11)

Summing Eqs. 3.10 and 3.11, we obtain

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$$\frac{\left\|\nabla e^{1}\right\|_{L^{2}}^{2}}{\Delta t} + \frac{1}{2} \left\|\Delta e^{1}\right\|_{L^{2}}^{2} \le 4 \left\|f(|u_{0}|^{2})e^{1}\right\|_{L^{2}}^{2} + 4 \left\|P^{1}\right\|_{L^{2}}^{2}.$$
(3.12)

Thus, applying Eqs. 3.2, 3.3 and 3.8, we see that

$$\left\|\nabla e^{1}\right\|_{L^{2}}^{2} + \Delta t \left\|\Delta e^{1}\right\|_{L^{2}}^{2} \le C_{1}\Delta t^{2}.$$
 (3.13)

Thanks to the Dirichlet boundary condition, we have

$$(\Delta t)^{\frac{1}{2}} \left\| e^1 \right\|_{H^2} \le C_2 \Delta t.$$
 (3.14)

Using Assumption(A1) and Eq. 3.14, we see that

$$\left\| U^{1} \right\|_{L^{\infty}} \leq \left\| u^{1} \right\|_{L^{\infty}} + \left\| u^{1} - U^{1} \right\|_{L^{\infty}} \leq \left\| u^{1} \right\|_{L^{\infty}} + C \left\| e^{1} \right\|_{H^{2}} \leq K, \quad (3.15)$$

$$\|U^1\|_{H^2} \le \|u^1\|_{H^2} + \|e^1\|_{H^2} \le C_3, \tag{3.16}$$

when  $\Delta t \le \tau_1 = \frac{1}{C^2 C_2^2}$ . Thus, Eqs. 3.4–3.5 hold for m=1.

We assume that Eqs. 3.4 and 3.5 hold for  $m \le n - 1$ . Then

$$\|U^{m}\|_{L^{\infty}} \le \|u^{m}\|_{L^{\infty}} + C \|e^{m}\|_{H^{2}} \le K,$$
(3.17)

when  $\Delta t \leq \tau_2 = \frac{1}{C^2 C_0^2}$ .

Subtracting Eq. 2.7 from Eq. 3.1 results in the error equation

$$iD_t e^n + \Delta e^n + R^n = P^n, \qquad (3.18)$$

where

$$R^{n} = [(f(|u^{n-1}|^{2}) - f(|U^{n-1}|^{2}))u^{n}] + [f(|U^{n-1}|^{2})e^{n}].$$

By the mathematical induction and Assumption (A1), we obtain

$$\begin{aligned} \left\| R^{n} \right\|_{L^{2}} &\leq \left\| f'(\xi_{1})e^{n-1}(|u^{n-1}| + |U^{n-1}|)u^{n} \right\|_{L^{2}} + \left\| f(|U^{n-1}|^{2})e^{n} \right\|_{L^{2}} \\ &\leq C(\left\| e^{n-1} \right\|_{L^{2}} + \left\| e^{n} \right\|_{L^{2}}), \end{aligned}$$
(3.19)

where we apply  $|f'(\xi_1)| + |f(|U^{n-1}|^2)| \le C_{L1}$  for  $|\xi_1| \le ||u^{n-1}||_{L^{\infty}}^2 + ||U^{n-1}||_{L^{\infty}}^2 \le 2K^2$ .

Multiplying Eq. 3.18 by  $e^n$  and integrating it over  $\Omega$  lead to

$$\frac{i}{2\Delta t} \left( \left\| e^n \right\|_{L^2}^2 - \left\| e^{n-1} \right\|_{L^2}^2 + \left\| e^n - e^{n-1} \right\|_{L^2}^2 \right) - \left\| \nabla e^n \right\|_{L^2}^2 = (P^n, e^n) - (R^n, e^n).$$
(3.20)

Taking the imaginary parts of the above equation and applying the Young inequality, we obtain

$$\frac{1}{\Delta t} \left( \left\| e^n \right\|_{L^2}^2 - \left\| e^{n-1} \right\|_{L^2}^2 \right) \le \frac{1}{2} \left\| P^n \right\|_{L^2}^2 + \frac{1}{2} \left\| R^n \right\|_{L^2}^2 + \left\| e^n \right\|_{L^2}^2.$$
(3.21)

Summing inequalities (3.21) up and using Eqs. 3.19, 3.2, and the Young inequality, there exists  $\tau_3 > 0$  such that

$$\left\|e^n\right\|_{L^2} \le C_4 \Delta t,\tag{3.22}$$

when  $\Delta t \leq \tau_3$ . Moreover, multiplying Eq. 3.18 by  $D_t e^n$  and integrating it over  $\Omega$  lead to

$$i \|D_t e^n\|_{L^2}^2 - (\nabla e^n, D_t \nabla e^n) + (R^n, D_t e^n) = (P^n, D_t e^n).$$
(3.23)

Taking the real parts, we obtain

$$\frac{1}{2\Delta t} \left( \left\| \nabla e^n \right\|_{L^2}^2 - \left\| \nabla e^{n-1} \right\|_{L^2}^2 \right) \le |Re(R^n, D_t e^n)| + |Re(P^n, D_t e^n)|.$$
(3.24)

Multiplying Eq. 3.18 by  $R^n$ , we can get

$$i(D_t e^n, R^n) - (\nabla e^n, \nabla R^n) + \left\| R^n \right\|_{L^2}^2 = (P^n, R^n).$$
(3.25)

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Thanks to the above equation, Eqs. 3.19, 3.22 and the Young inequality, we get

$$\begin{aligned} |Re(D_{t}e^{n}, R^{n})| &\leq |Im(P^{n}, R^{n})| + |Im(\nabla R^{n}, \nabla e^{n})| \\ &\leq \frac{1}{2} \|\nabla R^{n}\|_{L^{2}}^{2} + \frac{1}{2} \|\nabla e^{n}\|_{L^{2}}^{2} + \frac{1}{2} \|P^{n}\|_{L^{2}}^{2} + \frac{1}{2} \|R^{n}\|_{L^{2}}^{2} \\ &\leq C(\|\nabla e^{n}\|_{L^{2}}^{2} + \|\nabla e^{n-1}\|_{L^{2}}^{2}) + \frac{1}{2} \|P^{n}\|_{L^{2}}^{2} + C\Delta t^{2}. \end{aligned}$$
(3.26)

Meanwhile, the second term on the right-hand side of inequality (3.24) can be rewritten as

$$|Re(P^{n}, D_{t}e^{n})| = |Re(iD_{t}u^{n} - iu_{t}^{n} + f(|u^{n-1}|^{2})u^{n} - f(|u^{n}|^{2})u^{n}, D_{t}e^{n})|$$
  

$$\leq |(D_{t}u^{n} - u_{t}^{n}, D_{t}e^{n})| + |(f(|u^{n-1}|^{2})u^{n} - f(|u^{n}|^{2})u^{n}, D_{t}e^{n})|.$$
(3.27)

Multiplying Eq. 3.18 by  $D_t u^n - u_t^n$  and integrating it over  $\Omega$  lead to

$$i(D_t u^n - u_t^n, D_t e^n) - (\nabla e^n, \nabla (D_t u^n - u_t^n)) + (R^n, D_t u^n - u_t^n) = (P^n, D_t u^n - u_t^n).$$
(3.28)

Thanks to the above equation, Eqs. 3.19, 3.22 and the Young inequality, we can get

$$\begin{split} |(D_{t}u^{n} - u_{t}^{n}, D_{t}e^{n})| &\leq \frac{1}{2} \|\nabla e^{n}\|_{L^{2}}^{2} + \frac{1}{2} \|\nabla (D_{t}u^{n} - u_{t}^{n})\|_{L^{2}}^{2} + \frac{1}{2} \|R^{n}\|_{L^{2}}^{2} \\ &+ \frac{1}{2} \|P^{n}\|_{L^{2}}^{2} + \|(D_{t}u^{n} - u_{t}^{n})\|_{L^{2}}^{2} \\ &\leq \frac{1}{2} \|\nabla e^{n}\|_{L^{2}}^{2} + \frac{1}{2} \|\nabla (D_{t}u^{n} - u_{t}^{n})\|_{L^{2}}^{2} + \frac{1}{2} \|P^{n}\|_{L^{2}}^{2} + C\Delta t^{2}. \end{split}$$

$$(3.29)$$

Multiplying Eq. 3.18 by  $f(|u^{n-1}|^2)u^n - f(|u^n|^2)u^n$  and integrating it over  $\Omega$  lead to

$$i(D_t e^n, f(|u^{n-1}|^2)u^n - f(|u^n|^2)u^n) + (\Delta e^n, f(|u^{n-1}|^2)u^n - f(|u^n|^2)u^n) + (R^n, f(|u^{n-1}|^2)u^n - f(|u^n|^2)u^n) = (P^n, f(|u^{n-1}|^2)u^n - f(|u^n|^2)u^n).$$

Thanks to the above equation, Eqs. 3.19, 3.22, **Assumption(A1)**, Eq. 3.3, and the Young inequality, we can get the following inequality:

$$\begin{split} &|(D_{t}e^{n}, f(|u^{n-1}|^{2})u^{n} - f(|u^{n}|^{2})u^{n})| \\ &\leq \frac{1}{2} \left\| \nabla e^{n} \right\|_{L^{2}}^{2} + \frac{1}{2} \left\| f(|u^{n-1}|^{2})u^{n} - f(|u^{n}|^{2})u^{n} \right\|_{H^{1}}^{2} + \frac{1}{2} \left\| R^{n} \right\|_{L^{2}}^{2} \\ &+ \frac{1}{2} \left\| P^{n} \right\|_{L^{2}}^{2} + \left\| f(|u^{n-1}|^{2})u^{n} - f(|u^{n}|^{2})u^{n} \right\|_{L^{2}}^{2} \\ &= \frac{1}{2} \left\| \nabla e^{n} \right\|_{L^{2}}^{2} + \frac{1}{2} \left\| f'(\xi)(u^{n-1} - u^{n})(|u^{n-1}| + |u^{n}|)u^{n} \right\|_{H^{1}}^{2} + \frac{1}{2} \left\| R^{n} \right\|_{L^{2}}^{2} \\ &+ \frac{1}{2} \left\| P^{n} \right\|_{L^{2}}^{2} + \left\| f'(\xi)(u^{n-1} - u^{n})(|u^{n-1}| + |u^{n}|)u^{n} \right\|_{L^{2}}^{2} \\ &\leq \frac{1}{2} \left\| \nabla e^{n} \right\|_{L^{2}}^{2} + \frac{1}{2} \left\| P^{n} \right\|_{L^{2}}^{2} + C \Delta t^{2}. \end{split}$$
(3.30)

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From Eqs. 3.24, 3.26, 3.27, 3.29, and 3.30, we can obtain the following result:

$$\|\nabla e^n\|_{L^2}^2 - \|\nabla e^{n-1}\|_{L^2}^2 \le C\Delta t (\|\nabla e^n\|_{L^2}^2 + \|\nabla e^{n-1}\|_{L^2}^2) + 3\Delta t \|P^n\|_{L^2}^2$$
  
+  $C\Delta t^3 + \Delta t \|D_t u^n - u_t^n\|_{H^1}^2.$ 

Summing the above inequalities up and using the Gronwall inequality, Eq. 3.2, there exists  $\tau_4 > 0$  such that

$$\left\|\nabla e^n\right\|_{L^2} \le C_5 \Delta t,\tag{3.31}$$

when  $\Delta t \leq \tau_4$ . Multiplying Eq. 3.18 by  $\Delta e^n$  and integrating it over  $\Omega$  lead to

$$-i\frac{\|\nabla e^n\|_{L^2}^2}{\Delta t} + i\frac{(\nabla e^{n-1}, \nabla e^n)}{\Delta t} + \|\Delta e^n\|_{L^2}^2 + (R^n, \Delta e^n) = (P^n, \Delta e^n).$$

Taking the real parts and applying the Young inequality, we obtain

$$\left\|\Delta e^{n}\right\|_{L^{2}}^{2} \leq \frac{1}{2\Delta t} \left(\left\|\nabla e^{n-1}\right\|_{L^{2}}^{2} + \left\|\nabla e^{n}\right\|_{L^{2}}^{2}\right) + \left\|P^{n}\right\|_{L^{2}}^{2} + \left\|R^{n}\right\|_{L^{2}}^{2} + \frac{1}{2}\left\|\Delta e^{n}\right\|_{L^{2}}^{2}.$$
(3.32)

By Eqs. 3.2, 3.18, 3.21, and 3.30, we obtain

$$(\Delta t)^{\frac{1}{2}} \|e^n\|_{H^2} \le C_6 \Delta t.$$
 (3.33)

Using Eq. 3.32 and Assumption(A1), we see that

$$\|U^{n}\|_{L^{\infty}} \le \|u^{n}\|_{L^{\infty}} + C \|e^{n}\|_{H^{2}} \le K,$$
(3.34)

$$\|U^{n}\|_{H^{2}} \le \|u^{n}\|_{H^{2}} + \|e^{n}\|_{H^{2}} \le C_{7}, \tag{3.35}$$

when  $\Delta t \leq \tau_5 = \frac{1}{C^2 C_6^2}$ . With  $\tau_0 = min\{\tau_1, \tau_2, \tau_3, \tau_4, \tau_5\}$  and  $C_0 = C + \sum_{i=1}^7 C_i$  the proof of Theorem 3.1 can be completed.

## **4** The fully-discrete finite element solution

In this section, we study the error  $||U^n - U_h^n||_{L^2}$  of the Galerkin finite element for the time-discrete system (2.7)–(2.8).

**Lemma 4.1** Suppose that the time-discrete system (2.7)–(2.8) has a unique solution  $U^n$ . Then

$$\left\|R_h U^n\right\|_{L^{\infty}} \le M. \tag{4.1}$$

*Proof* Thanks to Eqs. 2.4, 2.5, 3.4, and 3.34, we can obtain the following result:

$$\begin{aligned} \|R_{h}U^{n}\|_{L^{\infty}} &= \|U^{n} - R_{h}U^{n}\|_{L^{\infty}} + \|U^{n}\|_{L^{\infty}} \\ &\leq K + Ch^{-\frac{d}{2}} \|U^{n} - R_{h}U^{n}\|_{L^{2}} \\ &\leq Ch^{-\frac{d}{2}}h^{2} \|U^{n}\|_{H^{2}} + K \\ &\leq M. \end{aligned}$$

The proof of Lemma 4.1 is complete.

The variational form of the time-discrete system (2.7) can be defined by

$$i(D_t U^n, v) - (\nabla U^n, \nabla v) + (f(|U^{n-1}|^2)U^n, v) = 0 \quad \forall v \in H_0^1.$$
(4.2)

Subtracting Eq. 2.6 from Eq. 4.2, we can obtain the following equation:

$$i(D_t(U^n - U_h^n), v) - (\nabla U^n - \nabla U_h^n, \nabla v) + (f(|U^{n-1}|^2)U^n - f(|U_h^{n-1}|^2)U_h^n, v) = 0$$
(4.3)

for any  $v \in V_h$ .

Thanks to Eq. 2.3, the above formulation can be rewritten as

$$i(D_t e_h^n, v) - (\nabla e_h^n, \nabla v) + (f(|U^{n-1}|^2)U^n - f(|U_h^{n-1}|^2)U_h^n, v) = -i(D_t(U^n - R_h U^n), v).$$
(4.4)

**Theorem 4.1** Assume that the unique solution u of Eq. 2.1 satisfies Assumption(A1). Then the fully discrete system (2.6) has a unique solution  $U_h^m$ , m=1,2,...,N, and there exists  $\tau' > 0$  such that, when  $\Delta t \leq \tau'$ ,  $h \leq h'$ 

$$\left\|e_{h}^{n}\right\|_{L^{2}} \le C^{*}h^{2},\tag{4.5}$$

$$\left\|e_{h}^{n}\right\|_{H^{1}} \le C^{*}h. \tag{4.6}$$

*Proof* As in [28], the existence and uniqueness of a solution to the fully-discrete system (2.6) can be shown. Next, we prove the error estimates Eqs. 4.5 and 4.6 by using the mathematical induction. Assuming  $U_h^0 = \prod_h u_0$  and using (2.2) and **Assumption** (A1), it is easy to see that

$$||u_0 - \Pi_h u_0||_{L^2} \le Ch^2 ||u_0||_{H^2} \le Ch^2.$$

With above inequality, Eq. 2.4, and Assumption(A1), we obtain

$$\left\| e_h^0 \right\|_{L^2} = \left\| R_h U^0 - U_h^0 \right\|_{L^2} = \left\| R_h u_0 - u_0 + u_0 - \Pi_h u_0 \right\|_{L^2}$$
  
 
$$\leq \left\| R_h u_0 - u_0 \right\|_{L^2} + \left\| u_0 - \Pi_h u_0 \right\|_{L^2} \leq Ch^2 \left\| u_0 \right\|_{H^2} \leq Ch^2.$$
 (4.7)

Defining  $K_1 = \max_{0 \le n \le N} ||R_h U^n||_{L^{\infty}} + 1$  and using Eqs. 4.1, 2.5 and 4.7, we have the following result:

$$\begin{split} \left\| U_{h}^{0} \right\|_{L^{\infty}} &\leq \left\| R_{h} U^{0} \right\|_{L^{\infty}} + \left\| R_{h} U^{0} - U_{h}^{0} \right\|_{L^{\infty}} \\ &\leq M + C h^{-\frac{d}{2}} \left\| R_{h} U^{0} - U_{h}^{0} \right\|_{L^{2}} \\ &\leq C^{2} h^{-\frac{d}{2}} h^{2} + M \\ &\leq K_{1}, \end{split}$$
(4.8)

when  $h \le h_1 = C^{-\frac{4}{4-d}}$ .

First, we study the error estimates at the initial time step. From Eq. 4.3, we can obtain the following formulation:

$$\frac{i}{\Delta t}(e_h^1, v) - (\nabla e_h^1, \nabla v) + (f(|U^0|^2)U^1 - f(|U_h^0|^2)U_h^1, v)$$
  
=  $\frac{i}{\Delta t}(U^0 - U_h^0, v) - \frac{i}{\Delta t}(U^1 - R_h U^1, v).$  (4.9)

Let  $v = e_h^1$  in Eq. 4.9, and then it follows that

$$\frac{i}{\Delta t} \left\| e_h^1 \right\|_{L^2}^2 - \left\| \nabla e_h^1 \right\|_{L^2}^2 + (f(|U^0|^2)U^1 - f(|U_h^0|^2)U_h^1, e_h^1) = \frac{i}{\Delta t} (U^0 - U_h^0, e_h^1) - \frac{i}{\Delta t} (U^1 - R_h U^1, e_h^1).$$
(4.10)

Taking the imaginary parts of the above equation and applying Eqs. 2.2, 2.4, 3.3 and 4.8, Assumption(A1), and the Young inequality, we can obtain

$$\begin{split} \left\| e_{h}^{1} \right\|_{L^{2}}^{2} &= -Im((f(|U^{0}|^{2}) - f(|U_{h}^{0}|^{2}))U^{1}, e_{h}^{1})\Delta t \\ &- Im(f(|U_{h}^{0}|^{2})(U^{1} - R_{h}U^{1}), e_{h}^{1})\Delta t \\ &- Im(f(|U_{h}^{0}|^{2})(R_{h}U^{1} - U_{h}^{1}), e_{h}^{1})\Delta t + Re(U^{0} - U_{h}^{0}, e_{h}^{1}) \\ &- Re(U^{1} - R_{h}U^{1}, e_{h}^{1}) \leq \frac{1}{2} \left\| (f(|U^{0}|^{2}) - f(|U_{h}^{0}|^{2}))U^{1} \right\|_{L^{2}}^{2} \\ &+ \frac{1}{2} \left\| f(|U_{h}^{0}|^{2})(U^{1} - R_{h}U^{1}) \right\|_{L^{2}}^{2} + \left\| f(|U_{h}^{0}|^{2})e_{h}^{1} \right\|_{L^{2}}^{2}\Delta t \\ &+ \left\| U^{0} - U_{h}^{0} \right\|_{L^{2}}^{2} + \left\| U^{1} - R_{h}U^{1} \right\|_{L^{2}}^{2} + (\Delta t + \frac{1}{2}) \left\| e_{h}^{1} \right\|_{L^{2}}^{2} \\ \leq \frac{1}{2} \left\| f'(\xi_{3})(U^{0} - U_{h}^{0})(|U^{0}| + |U_{h}^{0}|)U^{1} \right\|_{L^{2}}^{2} \\ &+ \frac{1}{2} \left\| f(|U_{h}^{0}|^{2})(U^{1} - R_{h}U^{1}) \right\|_{L^{2}}^{2} + \left\| U^{0} - U_{h}^{0} \right\|_{L^{2}}^{2} + \left\| U^{1} - R_{h}U^{1} \right\|_{L^{2}}^{2} \\ &+ \left(\frac{1}{2} + (1 + C_{k}^{2})\Delta t) \left\| e_{h}^{1} \right\|_{L^{2}}^{2} \leq ((1 + C_{L^{2}}^{2})\Delta t + \frac{1}{2}) \left\| e_{h}^{1} \right\|_{L^{2}}^{2} + Ch^{4}, \end{split}$$

$$\tag{4.11}$$

where we using  $f(|U_h^0|^2) + f'(\xi_2) \le C_{L2}$  for  $|\xi_2| \le ||U^0||_{L^{\infty}}^2 + ||U_h^0||_{L^{\infty}}^2 \le K^2 + K_1^2$ . So, we can get

$$\|e_h^1\|_{L^2} \le C_7 h^2, \tag{4.12}$$

when  $\Delta t \leq \tau_6 = \frac{1}{2(1+C_{L3}^2)}$ . Thus, Eq. 4.5 holds for n=1. From Eqs. 4.1, 2.5, and 4.11, we can get the following result:

$$\left\| U_{h}^{1} \right\|_{L^{\infty}} \leq \left\| R_{h} U^{1} \right\|_{L^{\infty}} + \left\| e_{h}^{1} \right\|_{L^{\infty}} \leq M + C C_{7} h^{-\frac{d}{2}} h^{2} \leq K_{1},$$
(4.13)

when  $h \le h_1 = (CC_7)^{-\frac{2}{4-d}}$ .

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We assume that Eq. 4.5 holds for  $m \le n-1$ . Similar to the derivation of the above inequality, we get

$$\left\| U_{h}^{m} \right\|_{L^{\infty}} \le \| R_{h} U^{m} \|_{L^{\infty}} + \| e_{h}^{m} \|_{L^{\infty}} \le M + C C^{*} h^{-\frac{d}{2}} h^{2} \le K_{1},$$
(4.14)

when  $h \le h_2 = (CC^*)^{-\frac{2}{4-d}}$ . Substituting  $v = e_h^n$  in Eq. 4.4, we derive at

$$\frac{i}{2\Delta t} (\|e_h^n\|_{L^2}^2 - \|e_h^{n-1}\|_{L^2}^2 + \|e_h^n - e_h^{n-1}\|_{L^2}^2) - \|\nabla e_h^n\|_{L^2}^2 + (f(|U^{n-1}|^2)U^n - f(|U_h^{n-1}|^2)U_h^n, e_h^n) = -i(D_t(U^n - R_hU^n), e_h^n).$$
(4.15)

Taking the imaginary parts of the above equation and using Eqs. 2.4, 3.4, 3.34, 3.35 and 4.14, and the Young inequality, we get

$$\frac{\left\|e_{h}^{n}\right\|_{L^{2}}^{2} - \left\|e_{h}^{n-1}\right\|_{L^{2}}^{2}}{2\Delta t} \leq \left|\left(f\left(|U^{n-1}|^{2}\right)U^{n} - f\left(|U_{h}^{n-1}|^{2}\right)U_{h}^{n}, e_{h}^{n}\right)\right| \\
+ \left|\left(D_{t}\left(U^{n} - R_{h}U^{n}\right), e_{h}^{n}\right)\right| \\
= \left|\left(f'(\xi_{4})\left(U^{n-1} - R_{h}U^{n-1} + R_{h}U^{n-1} + R_{h}U^{n-1} + R_{h}U^{n-1} - U_{h}^{n-1}\right)\left(|U^{n-1}| + |U_{h}^{n-1}|\right)U^{n} \\
+ f\left(|U_{h}^{n-1}|^{2}\right)\left(U^{n} - R_{h}U^{n} + R_{h}U^{n} - U_{h}^{n}\right), e_{h}^{n}\right)\right| \\
+ \left|\left(D_{t}\left(U^{n} - R_{h}U^{n}\right), e_{h}^{n}\right)\right| \leq C\left(\left\|e_{h}^{n}\right\|_{L^{2}}^{2} + \left\|e_{h}^{n-1}\right\|_{L^{2}}^{2}\right) \\
+ Ch^{4} + \left|\left(D_{t}\left(U^{n} - R_{h}U^{n}\right), e_{h}^{n}\right)\right|,$$
(4.16)

where we applying  $|f'(\xi_3)| + |f(|U_h^{n-1}|^2)| \leq C_{L3}$  for  $|\xi_3| \leq ||U_h^{n-1}||_{L^{\infty}}^2 +$  $\|U^{n-1}\|_{L^{\infty}}^2 \le K_1^2 + K^2.$ 

With Eq. 2.4 and the Young inequality, we see that

$$\sum_{m=1}^{n} \Delta t |(D_t(U^m - R_h U^m), e_h^m)| \le Ch^4 \sum_{m=1}^{n} \Delta t ||D_t U^m||_{H^2}^2 + \frac{1}{2} \sum_{m=1}^{n} \Delta t ||e_h^m||_{L^2}^2.$$
(4.17)

Multiplying Eq. 3.18 by  $\Delta e^n$  and integrating it over  $\Omega$  lead to

$$-\frac{i}{2\Delta t}(\|\nabla e^n\|_{L^2}^2 - \|\nabla e^{n-1}\|_{L^2}^2 + \|\nabla e^n - \nabla e^{n-1}\|_{L^2}^2) + \|\Delta e^n\|_{L^2}^2 + (R^n, \Delta e^n)$$
  
=  $(P^n, \Delta e^n)$  (4.18)

Taking real parts of above inequality and applying Gronwall inequality, we have

$$\frac{\Delta t}{2} \|\Delta e^n\|_{L^2}^2 \le \Delta t \|R^n\|_{L^2}^2 + \Delta t \|P^n\|_{L^2}^2.$$
(4.19)

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Summing inequalities (4.19) up and using Eqs. 3.19, 3.22, and 3.2 lead to

$$\sum_{m=1}^{n} \Delta t \|\Delta e^{m}\|_{L^{2}}^{2} \leq 2 \sum_{m=1}^{n} \Delta t \|R^{m}\|_{L^{2}}^{2} + 2 \sum_{m=1}^{n} \Delta t \|P^{m}\|_{L^{2}}^{2}$$
$$\leq C \Delta t^{2}.$$
(4.20)

Thus, we have

$$\sum_{m=1}^{n} \Delta t \|\Delta D_t e^m\|_{L^2}^2 \le C \Delta t^{-2} \sum_{m=1}^{n} \Delta t \|\Delta e^m\|_{L^2}^2 \le C$$
(4.21)

From above inequality and Assumption(A1), we can get

$$\sum_{m=1}^{n} \Delta t \| D_t U^m \|_{H^2} \le \sum_{m=1}^{n} \Delta t \| D_t u^m \|_{H^2}^2 + \sum_{m=1}^{n} \Delta t \| \Delta D_t e^m \|_{L^2}^2 \le C.$$
(4.22)

Summing inequalities (4.16) up and using Eqs. 4.17, 4.22, and 4.7, we can obtain

$$\begin{aligned} \left\| e_{h}^{n} \right\|_{L^{2}}^{2} &\leq \left\| e_{h}^{0} \right\|_{L^{2}}^{2} + C \Delta t \sum_{m=0}^{n} \left\| e_{h}^{m} \right\|_{L^{2}}^{2} + \sum_{m=1}^{n} \Delta t \left| (D_{t} (U^{m} - R_{h} U^{m}), e_{h}^{m}) \right| + C h^{4} \\ &\leq C \Delta t \sum_{m=0}^{n} \left\| e_{h}^{m} \right\|_{L^{2}}^{2} + C h^{4}. \end{aligned}$$

$$(4.23)$$

By Gronwall inequality, there exists  $\tau_7 > 0$  such that

 $\|e_h^n\|_{L^2} \le C_8 h^2, \tag{4.24}$ 

when  $\Delta t \leq \tau_7$ .

Due to the  $\Delta t$ -independent property of estimate (4.5), we can obtain the  $H^1$  error estimate by using an inverse inequality:

$$\left\|e_{h}^{n}\right\|_{H^{1}} \le Ch^{-1} \left\|e_{h}^{n}\right\|_{L^{2}} \le C_{9}h.$$
(4.25)

Thus, choosing  $\tau' = min(\tau_0, \tau_6, \tau_7)$ ,  $h' = min(h_1, h_2)$  and  $C^* = C + \sum_{i=7}^{9} C_i$ , we finish the proof of Eqs. 4.5–4.6.

**Theorem 4.2** Assume that the unique solution u and the initial datum  $u_0$  of system (2.1) satisfy Assumption(A1). Then the finite element system (2.6) has a unique solution  $U_h^m$ , m = 1, 2, ..., N, and there exists  $\tau'' > 0$ , h' > 0, such that, when  $\Delta t \leq \tau''$ ,  $h \leq h'$ ,

$$\left\| u^m - U^m_h \right\|_{L^2} \le C^{**} (\Delta t + h^{r+1}), \tag{4.26}$$

where  $C^{**}$  is a positive constant independent of  $\Delta t$  and h.

*Proof* First, we study the optimal estimate as r=1. Thanks to Eqs. 2.4 and 3.35, Theorem 3.1, and Theorem 4.1, we have

$$\|u^m - U_h^m\|_{L^2} \le C_{10}(\Delta t + h^2),$$

when  $\Delta t < \tau', h \leq h'$ .

Next, we derive at the optimal  $L^2$  error estimates as r > 1. By Eqs. 2.2, 2.4 and **Assumption(A1)**, we can get

$$\|R_{h}u_{0} - U_{h}^{0}\|_{L^{2}} \leq \|R_{h}u_{0} - u_{0}\|_{L^{2}} + \|u_{0} - U_{h}^{0}\|_{L^{2}}$$
  
$$\leq Ch^{r+1}\|u_{0}\|_{H^{r+1}} \leq Ch^{r+1}$$
(4.27)

Assuming that u is the solution of system (2.1), then we can get

$$i(u_t^n, v) - (\nabla u^n, \nabla v) + (f(|u^n|^2)u^n, v) = 0$$
(4.28)

for any  $v \in V_h$ . Subtracting Eq. 4.28 from Eq. 2.6 and using Eq. 2.3, we derive at

$$i(D_t(R_hu^n - U_h^n), v) - (\nabla(R_hu^n - U_h^n), \nabla v) + (f(|u^n|^2)u^n - f(|U_h^{n-1}|^2)U_h^n, v)$$
  
=  $i(D_tR_hu^n - u_t^n, v).$  (4.29)

We assume that  $\sigma_h^n = R_h u^n - U_h^n$  and  $v = \sigma_h^n$ ; by Eq. 4.29, we see that

$$\frac{i}{2\Delta t} \left( \left\| \sigma_h^n \right\|_{L^2}^2 - \left\| \sigma_h^{n-1} \right\|_{L^2}^2 + \left\| \sigma_h^n - \sigma_h^{n-1} \right\|_{L^2}^2 \right) - \left\| \nabla \sigma_h^n \right\|_{L^2}^2 + (f(|u^n|^2)u^n) - f(|U_h^{n-1}|^2)U_h^n, \sigma_h^n) = i(D_t R_h u^n - u_t^n, \sigma_h^n).$$
(4.30)

Taking the imaginary parts of the above equality and using Eqs. 4.14, 2.4, Assumption(A1), and the Young inequality, we obtain

$$\frac{\left\|\sigma_{h}^{n}\right\|_{L^{2}}^{2}-\left\|\sigma_{h}^{n-1}\right\|_{L^{2}}^{2}}{\Delta t} \leq 2\left|\left(f\left(|u^{n}|^{2}\right)u^{n}-f\left(|U_{h}^{n-1}|^{2}\right)u^{n},\sigma_{h}^{n}\right)\right|+2\left|\left(f\left(|U_{h}^{n-1}|^{2}\right)\right)\left(u^{n}-U_{h}^{n}\right),\sigma_{h}^{n}\right)\right| +2\left|\left(D_{t}R_{h}u^{n}-u_{t}^{n},\sigma_{h}^{n}\right)\right| \leq 2\left|\left(f'(\xi_{5})\left(u^{n}-U_{h}^{n-1}\right)\left(|u^{n}|+|U_{h}^{n-1}|\right)u^{n},\sigma_{h}^{n}\right)\right|+2\left|\left(f\left(|U_{h}^{n-1}|^{2}\right)\left(u^{n}-R_{h}u^{n}\right)\right)\right| +2\left|\left(f\left(|U_{h}^{n-1}|^{2}\right)\left(u^{n}-R_{h}u^{n}\right)\right)\right| +2\left|\left(f\left(|U_{h}^{n-1}|^{2}\right)\left(u^{n}-R_{h}u^{n}-U_{h}^{n}\right)\right)\right|+2\left|\left(f'(\xi_{5})\left(|u^{n-1}-R_{h}u^{n-1}|\right)\right)\right| \leq 2\left|\left(f'(\xi_{5})\left(|u_{t}(\xi_{6})|\right)\Delta t\left(|u^{n}|+|U_{h}^{n-1}|\right)u^{n},\sigma_{h}^{n}\right)\right|+2\left|\left(f'(\xi_{5})\left(|u^{n-1}-R_{h}u^{n-1}|\right)\right)u^{n},\sigma_{h}^{n}\right)\right|+2\left|\left(f\left(|U_{h}^{n-1}|^{2}\right)\left(u^{n}-R_{h}u^{n}\right),\sigma_{h}^{n}\right)\right|+2\left|\left(f\left(|U_{h}^{n-1}|^{2}\right)\left(R_{h}u^{n}-U_{h}^{n}\right),\sigma_{h}^{n}\right)\right|+2\left|\left(D_{t}R_{h}u^{n}-u_{t}^{n},\sigma_{h}^{n}\right)\right| \leq C\left(\left\|\sigma_{h}^{n}\right\|_{L^{2}}^{2}+\left\|\sigma_{h}^{n-1}\right\|_{L^{2}}^{2}\right)+Ch^{2\left(r+1\right)}+C\Delta t^{2}+\left\|D_{t}R_{h}u^{n}-u_{t}^{n}\right\|_{L^{2}}^{2}$$
(4.31)

where we applying  $|f'(\xi_4)| + |f(|U_h^{n-1}|^2)| \le C_{L4}$  for  $|\xi_4| \le ||U_h^{n-1}||_{L^{\infty}}^2 + ||u^n||_{L^{\infty}}^2 \le K^2 + K_1^2$ .

Applying Eqs. 2.4, 3.2 and Assumption(A1), we can get the following result:

$$\sum_{m=1}^{n} \Delta t \| D_{t} R_{h} u^{m} - u_{t}^{m} \|_{L^{2}}^{2} \leq \sum_{m=1}^{n} \Delta t \| D_{t} (R_{h} u^{m} - u^{m}) \|_{L^{2}}^{2} + \sum_{m=1}^{n} \Delta t \| D_{t} u^{m} - u_{t}^{m} \|_{L^{2}}^{2} \leq C \Delta t h^{2(r+1)} \sum_{m=1}^{n} \| D_{t} u^{m} \|_{H^{r+1}}^{2} + C \Delta t^{2} \leq C h^{2(r+1)} + C \Delta t^{2}.$$
(4.32)

Summing inequalities (4.31) up and using Eqs. 4.27, 4.32, and Assumption(A1), we can obtain the following result:

$$\|\sigma_{h}^{n}\|_{L^{2}}^{2} \leq \|\sigma_{h}^{0}\|_{L^{2}}^{2} + C\Delta t \sum_{m=0}^{n} \|\sigma_{h}^{m}\|_{L^{2}}^{2} + Ch^{2(r+1)} + C\Delta t^{2} + \Delta t \sum_{m=1}^{n} \|D_{t}R_{h}u^{m} - u_{t}^{m}\|_{L^{2}}^{2} \leq C\Delta t \sum_{m=0}^{n} \|\sigma_{h}^{m}\|_{L^{2}}^{2} + C\Delta t^{2} + Ch^{2(r+1)}.$$

$$(4.33)$$

Using Gronwall inequality,

$$\|\sigma_h^n\|_{L^2} \le C_{11}(\Delta t + h^{r+1}), \tag{4.34}$$

when  $\Delta t \leq \tau_8$  and  $h \leq h'$ . Thanks to Eq. 2.4 and Assumption(A1), we have

$$\begin{aligned} \left\| u^{n} - U_{h}^{n} \right\|_{L^{2}} &\leq \left\| u^{n} - R_{h} u^{n} \right\|_{L^{2}} + \left\| R_{h} u^{n} - U_{h}^{n} \right\|_{L^{2}} \\ &\leq C h^{r+1} + C_{11} (\Delta t + h^{r+1}). \end{aligned}$$
(4.35)

With  $\tau'' = min(\tau', \tau_8)$ ,  $C^{**} = max(C, C_{11})$  and  $h \le h'$ , we complete the proof of Theorem 4.2.

*Remark*. In the above proof, if r = 1, it is easy to show (4.26) (the  $L^2$ -norm optimal error estimate). However, as the Galerkin FEM order r is bigger than 1, we cannot obtain the optimal error estimates by using only Theorems 3.1 and 4.1.

#### **5** Numerical experiments

In this section, we present two numerical examples to validate the theoretical analysis in the previous sections. All numerical results are performed by free software FreeFEM++[9].

**Table 1**  $L^2$  error estimates of the linear FEM with  $h^2 = \Delta t$  (Example 5.1)

$  u(\cdot,t_n) - U_h^n  _{L^2}$									
	t=0.5	order	t=1	order	t=1.5	order	t=2	order	
1/h = 5	1.45815E-02		3.01352E-02		7.18496E-02		1.88144E-01		
1/h = 10	4.32468E-03	1.7535	8.40798E-03	1.8416	2.00191E-02	1.8436	6.54744E-02	1.5228	
1/h = 20	1.31054E-03	1.7224	2.22639E-03	1.9171	5.14973E-03	1.9588	1.80891E-02	1.8558	
1/h = 40	3.52571E-04	1.8942	5.64739E-04	1.9791	1.30656E-03	1.9787	4.59479E-03	1.9770	

*Example 5.1* Let f(s) = s, and we can get the cubic Schrödinger equation

$$\begin{cases} iu_t + \Delta u + |u|^2 u = g, \ x \in \Omega, \ 0 < t \le T, \\ u(x, 0) = u_0(x), & x \in \Omega, \\ u = 0, & x \in \partial\Omega, \end{cases}$$
(5.1)

where  $\Omega = [0, 1] \times [0, 1]$ . Moreover, the exact solution *u* of the above system is given as follows:

$$u = 5e^{it}(1+2t^2)(1-x)(1-y)\sin(x)\sin(y)$$

and the right-hand side g is given by the exact solution u and system (5.1).

Next, we solve system (5.1) by the semi-implicit backward Euler method with a linear finite element approximation and a quadratic finite element approximation, respectively. To check the optimal convergence rate in the  $L^2$  norm, we pick  $\Delta t = h^2$  for the linear finite element approximation and  $\Delta t = h^3$  for the quadratic finite element approximation, respectively. We choose t = 0.5, 1, 1.5, and 2 to present our numerical results. From Tables 1–2, we can see that the results completely agree with the theoretical analysis above.

In [20], Tourigny showed the optimal  $L^2$  error estimate with the condition of  $\Delta t = o(h^{2/d})$ . However, in Theorem 4.2, the  $L^2$  optimal error estimate without any condition is obtained. For checking the unconditional convergence, we discuss (5.1) with different  $\Delta t$  on gradually refined meshes at t = 1.0. From Fig. 1, we can see that for a fixed  $\Delta t$ , the  $L^2$ -error of the linear FEM and quadratic FEM asymptotically converges to a small constant as 1/h increases. Obviously, it shows no restriction on  $\Delta t$  and h.

**Table 2**  $L^2$  error estimates of the quadratic FEM with  $h^3 = \Delta t$  (Example 5.1)

$\left\ u(\cdot,t_n)-U_h^n\right\ _{L^2}$									
	t=0.5	order	t=1	order	t=1.5	order	t=2	order	
1/h = 5	2.26241E-04		4.54483E-04		1.70451E-03		8.67418E-03		
1/h = 10	1.78403E-05	3.6646	2.80334E-05	4.0190	1.69899E-04	3.3266	1.03279E-03	3.0702	
1/h = 20	1.72314E-06	3.3720	1.94346E-06	3.8504	1.80592E-05	3.2339	1.21222E-04	3.0908	
1/h = 40	2.13961E-07	3.0096	2.05939E-07	3.2383	2.05455E-06	3.1358	1.50013E-05	3.0145	



**Fig. 1**  $L^2$ -norm errors of the linear and quadratic FEMs (Example 5.1)

*Example 5.2* Let  $f(s) = -s + s^2$ , and we can get the cubic-quintic Schrödinger equation

$$\begin{cases} iu_t + \Delta u - |u|^2 u + |u|^4 u = g, \ x \in \Omega, \ 0 < t \le T, \\ u(x, 0) = u_0(x), & x \in \Omega, \\ u = 0, & x \in \partial\Omega, \end{cases}$$
(5.2)

where  $\Omega = [0, 1] \times [0, 1]$ . In addition, the exact solution *u* of the above system is given as follows:

$$u = e^{it + (x+y)/2}(1+3t^2)x(1-x)y(1-y).$$

The right-hand side g is given by system (5.2) and the exact solution u. We solve system (5.2) with the Euler semi-implicit scheme by applying the linear and quadratic FEMs. Similarly, to verify our theoretical analysis, we choose  $\Delta t = h^2$  for the linear FEM and  $\Delta t = h^3$  for the quadratic FEM, respectively. From Table 3 and 4, we can see that the  $L^2$  error estimates of linear FEM are proportional to  $h^2$  and the  $L^2$  error estimates of quadratic FEM are proportional to  $h^3$ . Meanwhile, we choose different mesh scales 1/h=10,20,...,100 with different  $\Delta t = 0.2, 0.05, 0.01$  at t = 1.0. Also, from Fig. 2, we see that the errors converge to a constant as  $\frac{h}{\Delta t} \rightarrow 0$ , which shows



**Fig. 2**  $L^2$ -norm errors of the linear and quadratic FEMs (Example 5.2)

$\left\ u(\cdot,t_n)-U_h^n\right\ _{L^2}$									
	t=0.5	order	t=1	order	t=1.5	order	t=2	order	
1/h = 5	5.1901E-03		1.1201E-02		2.2399E-02		4.9182E-02		
1/h = 10	1.4603E-03	1.8124	3.0493E-03	1.8770	5.8612E-03	1.9342	1.4945E-02	1.7185	
1/h = 20	4.2169E-04	1.7920	8.1699E-04	1.9001	1.4209E-03	2.0444	4.0147E-03	1.8963	
1/h = 40	1.1064E-04	1.9303	2.0785E-04	1.9748	3.4029E-04	2.0619	1.0369E-03	1.9530	

**Table 3**  $L^2$  error estimates of the linear FEM with  $h^2 = \Delta t$  (Example 5.2)

**Table 4**  $L^2$  error estimates of the quadratic FEM with  $h^3 = \Delta t$  (Example 5.2)

$\left\ u(\cdot,t_n)-U_h^n\right\ _{L^2}$									
	t=0.5	order	t=1	order	t=1.5	order	t=2	order	
1/h = 5	1.1249E-04		2.4069E-04		4.6009E-04		1.5751E-03		
1/h = 10	9.7713E-06	3.5251	2.2870E-05	3.3956	3.4378E-05	3.7423	1.5102E-04	3.3826	
1/h = 20	1.0696E-06	3.1914	2.7265E-06	3.0684	3.1570E-06	3.4449	1.6416E-05	3.2623	
1/h = 40	1.3297E-07	3.0079	3.4950E-07	2.9636	3.6936E-07	3.0954	1.9160E-06	3.0989	

the unconditional convergence by using the Euler semi-implicit FEMs for solving the Schrödinger equation.

# 6 Conclusions

In this paper, we obtain the optimal error estimates of an Euler semi-implicit method for a generalized nonlinear Schrödinger equation without any time step restriction. This method is based on a splitting of an error into a time error and a spatial error. As the regularity of the solution  $U^n$  of the time-discrete formulation is obtained, the solution of the fully-discrete Euler method in the  $L^{\infty}$  norm can be bounded by

$$\left\|U_{h}^{n}\right\|_{L^{\infty}} \leq \left\|R_{h}U^{n}\right\|_{L^{\infty}} + \left\|U_{h}^{n} - R_{h}U^{n}\right\|_{L^{\infty}} \leq K_{1}.$$

Applying the above inequality, the optimal error estimate in the  $L^2$  norm of the fullydiscrete scheme can be obtained as follow:

$$\|u^m - U_h^m\|_{L^2} \le C^{**}(\Delta t + h^{r+1}).$$

This optimal error estimate has no restriction on the time and spatial steps. The analytic approach in this paper can be extended similarly to other PDEs.

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