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Liquid and gas fows in microchannels of varying cross section: a comparative analysis of the fow dynamics and design perspectives

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Abstract

This paper presents a comparative study of the fow of liquid and gases in microchannels of converging and diverging cross sections. Towards this, the static pressure across the microchannels is measured for diferent fow rates of the two fuids. The study includes both experimental and numerical investigations, thus providing several useful insights into the local information of fow parameters as well. Three diferent microchannels of varying angles of convergence/divergence (4°, 8° and 12°) are studied to understand the efect of the angle on fow properties such as pressure drop, Poiseuille number and diodicity. A comparison of the forces involved in liquid and gas fows shows their relative signifcance and efect on the fow structure. A diodic efect corresponds to a diference in the fow resistance in a microchannel of varying cross section, when the fow is subjected alternatively to converging and diverging orientations. In the present experiments, the diodic efect is observed for both liquid and gas as working fuids. The efect of governing parameters—Reynolds number and Knudsen number, on the diodicity is analysed. Based on these results, a comparison of design perspectives that may be useful in the design of converging/diverging microchannels for liquid and gas fows is provided.

1 Introduction

Diverging and converging microchannels are an important part of microdevices. Flow in such geometries is implicit to the design of devices like converging–diverging micronozzles, valveless micropumps and micromixers (Stemme and Stemme [1993;](#page-10-0) Lauga et al. [2004;](#page-9-0) Akbari et al. [2010](#page-9-1)). They are also likely to be employed in microchannels for reducing two-phase fow instability (Agrawal et al. [2012\)](#page-9-2). MEMS devices, due to their compact nature, often have space constraints and may include sections like converging and diverging channels or sudden expansion and contraction in their design. Microchannels of gradually varying cross section have also been applied for heat transfer augmentation, accelerated particle electrophoresis and polymer processing (Akbari et al. [2011](#page-9-3)). These applications require a fundamental knowledge of fuid fow in varying cross section microchannels, and from a designer's perspective, experimental data can provide some empirical correlations acting as pointers to the design of such devices. Currently, the data available for microflow in such geometries are rather limited and the present study should be helpful in this regard by bringing out the fow physics in terms of pressure drop, velocity distribution and flow structure.

Stemme and Stemme ([1993](#page-10-0)) experimentally studied the fow in difuser and nozzle elements for their application in valveless micropumps. This idea was further investigated in detail by several other studies (Olsson et al. [1996](#page-9-4), [2000](#page-10-1); Singhal et al. [2004\)](#page-10-2). These studies explored the effect of Reynolds number on the flow rectification property of the micropumps and found that the rectifcation properties improved for high Reynolds numbers. Gerlach ([1998\)](#page-9-5) followed an empiro-theoretical approach to study the flow behaviour in microdifusers in the context of dynamic passive valves in micropumps. The flow rectification efficiency was identifed to be a function of aperture angle, relative microchannel length, throat rounding and flow velocity. Akbari et al. ([2010\)](#page-9-1) developed an analytical model to predict the frictional fow resistance in periodically converging–diverging microtubes for laminar fow conditions. They found the fow resistance to be independent of the Reynolds number but depending only on the geometrical parameters. Akbari et al. ([2011](#page-9-3)) proposed an approximate method for determining the pressure drop in laminar, single phase flow in microchannels of slowly varying cross sections of

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arbitrary shapes. They proposed a non-dimensional number that could serve to compare the relative signifcance of viscous and inertial efects under such fow conditions. Tanaka et al. [\(2013\)](#page-10-3) studied the efect of channel geometry on the pump head of a valveless micropump with difuser–nozzle elements. He et al. (2017) (2017) studied the effect of diverging angle, volume fow rate and excitation frequency on the performance of converging/diverging elements in a piezoelectric passive micropump. They found that diverging fow dominated the fow-directing capability of the micropump for a range of divergence angles ($10^{\circ} < \theta < 20^{\circ}$). Beyond these limits, the flow was seen to be independent of the diverging angle and converging mode dictated the pump performance.

The above studies pertain to liquid flow in diverging/converging microchannels. In case of gas fow in microchannels of non-uniform cross sections, Sharipov and Bertoldo [\(2005\)](#page-10-4) proposed a method to predict the mass fow rate of rarefed gas fow in a long tube of variable radius. Graur et al. [\(2014\)](#page-9-7) compared the fow of gas in varying cross section microchannels in converging and diverging orientations. They reported that the diodicity is a function of rarefaction and exists only in the slip fow and transition fow regimes. Graur et al. [\(2016](#page-9-8)) studied the diodic effect in gaseous flows in various types of microchannels. In particular, they studied the efect of having the height or width as the varying dimension along the length of the microchannel. Szalmas et al. [\(2015](#page-10-5)) showed that the diodic efect is absent for gas fows in the continuum regime and the free molecular regime and has a maximum value in the slip/transition regime.

Flow in diverging and converging microchannels has been studied for water fow under isothermal conditions by Duryodhan et al. ([2012,](#page-9-9) [2014\)](#page-9-10), respectively. They proposed an approach to determine an 'equivalent hydraulic diameter', which is the hydraulic diameter obtained at a particular location of varying cross section microchannel, which gives the same pressure drop as that of a constant cross section microchannel under otherwise same fow conditions. Varade et al. ([2015a](#page-10-6), [b](#page-10-7)) adopted a similar approach to obtain the equivalent hydraulic diameter for diverging and converging microchannels for gas fows using nitrogen as the fuid. Hemadri et al. ([2016,](#page-9-11) [2017\)](#page-9-12) extended the experiments on converging/diverging microchannels to cover the entire slip regime and early transition regime $(Kn \sim 2)$. They provided the frst experimental evidence of the existence of Knudsen minimum in microchannels of non-uniform cross sections. Study of gas fows through microchannels is diferent with respect to liquid fows due to the presence of additional efects, such as compressibility and rarefaction, that appear only in the case of gases. From the literature, it is observed that there have been independent studies relating the pumping ability of a micropump for liquid or gas fows using diffuser–nozzle elements. A comparison of flow in converging/ diverging geometries with liquid and gas as working fuid has, however, not been carried out. Such a comparison is expected to explore the possibility of utilizing a micropump that can transfer both liquid and gas. A comparative analysis is also expected to bring out the efect of Reynolds number and Knudsen number on the pumping action and the conditions for optimum pumping efficiency for both liquid and gas flows.

This article aims to present a detailed and consolidated comparison of liquid and gas fow in converging and diverging microchannels by comparing the experimental data obtained by using deionized water and nitrogen as working fuids, respectively. The other aim is to highlight the changes in the fow structure and the relative signifcance of the forces involved (inertial, pressure and viscous force) for the case of liquid and gas flows. The effect of Reynolds number and Knudsen number on the fow diodicity is studied to understand the efect of these parameters on the pumping efficiency of a diffuser–nozzle micropump.

2 Experimental set‑up and test sections

Figure [1](#page-2-0)a, b shows the schematic of the experimental arrangement to study the pressure drop in converging and diverging microchannels in the case of liquid and gas flows, respectively. In both the cases, a mass flow controller directs the fuid through the microchannel and the corresponding inlet and outlet pressure measurements are taken across the microchannel. Further details about the experimental arrangement for water and nitrogen fows can be found in Duryodhan et al. ([2012](#page-9-9)) and Varade et al. ([2015a](#page-10-6)), respectively.

The microchannels used in the experiments were fabricated in-house on a single-side polished, p-type silicon wafer of 〈100〉 orientation. The microchannels are fabricated using the conventional photolithography technique and wet etching the wafer using TMAH solution. This results in microchannels of trapezoidal cross section. The top of the microchannel is covered with an optically smooth quartz plate (Singh et al. [2008\)](#page-10-8). Three diferent microchannels of diferent convergence/divergence angles are employed in this work. The schematic of the microchannel along with the converging/ diverging orientation is shown in Fig. [2](#page-2-1). The relevant dimensions along with the uncertainties are tabulated in Table [1.](#page-2-2) Note that the same set of microchannels is utilized for both liquid and gas fow measurements allowing for the direct comparison of the two cases.

Numerical simulations are carried out using commercial software (ANSYS Fluent). Figure [3](#page-3-0) shows the geometry of the model employed in the simulations and the relevant boundary conditions. The computational domain is discretized by quadrilateral face elements and hexahedral volume

Fig. 1 Schematic of experimental arrangement for the case of **a** water, **b** nitrogen

Table 1 Dimensional details of the microchannels employed in the experiments

elements. The Navier–Stokes equations are solved with fnite volume discretization for the case of both liquid and gas fows. A pressure-based solver is utilized with SIMPLE algorithm for pressure–velocity coupling. The main distinction between the simulations for water and nitrogen fow is the modifcation of the wall boundary condition: from no slip used for water fow to low-pressure boundary slip module, in the case of nitrogen flow. More details of the numerical model and the results of the grid independence test for liquid and gas fows can be found in Duryodhan et al. ([2012\)](#page-9-9) and Varade et al. ([2015a](#page-10-6)), respectively.

3 Data reduction

From the measurement of mass flow rate and the corresponding pressures across the microchannel, various nondimensional parameters are obtained to facilitate comparison between liquid and gas fows. All the parameters are obtained **Fig. 3** Geometry of the simulated model along with the boundary conditions. The inlet and outlet boundary conditions are interchanged to study the flow in both converging and diverging orientations

 $\mu\sqrt{\frac{\pi RT}{2}}$ $P_{\rm m}D_{\rm h}$

using the mean hydraulic diameter (D_h) calculated at the midlength of the microchannel. The Reynolds number (*Re*) is calculated as

$$
Re = \frac{\dot{m}D_{\rm h}}{\mu A} \tag{1}
$$

where \dot{m} is the mass flow rate, μ is the dynamic viscosity, and *A* is the cross-sectional area at the mid-length of the microchannel. For liquid fows, the Darcy friction factor is obtained as

$$
f = \left(\frac{D_{\rm h}}{L}\right) \frac{\Delta P}{2\rho u^2} = \left(\frac{D_{\rm h}}{L}\right) \left(\frac{\Delta P \rho}{J^2}\right) \tag{2}
$$

where ΔP is the pressure drop across the microchannel, ρ is the density, *J* is the mass flux $(J = \frac{m}{A})$, and *L* is the length of the microchannel. For the case of gas fows, an additional pressure drop is encountered due to the acceleration of the fuid. Hence, the Darcy friction factor for gases is defned as

$$
f = \left(\frac{D_{\rm h}}{L}\right) \left[\frac{1}{J^2RT} - \frac{1}{P_{\rm i}P_{\rm o}}\right] (P_{\rm i}^2 - P_{\rm o}^2) \tag{3}
$$

where R is the specific gas constant, T is the absolute temperature, and P_i and P_o are the pressures at the inlet and outlet of the microchannel, respectively. In the above equation, the second term on the right side represents the pressure drop due to fuid acceleration. Equation [3](#page-3-1) reduces to Eq. [2](#page-3-2) for the case of incompressible fows. The Poiseuille number is defned as the product of the Darcy friction factor and the Reynolds number:

$$
Po = fRe
$$
 (4)

For the case of nitrogen fow in the microchannel, rarefaction effects also become important, specifically for lower mass flow rates. The Knudsen number (Kn) is based on mean hydraulic diameter (D_h) and mean pressure (P_m) and is defined as

where λ is the mean free path of the gas. The maximum uncertainty in Poiseuille number, Reynolds number and Knudsen number is \pm 5, \pm 4 and \pm 0.5%, respectively.

 $Kn = \frac{\lambda}{D_h} = \frac{\mu \sqrt{2}}{P_m D_h}$ (5)

4 Efect of converging/diverging angle on static pressure drop

Figure [4a](#page-4-0), b shows the comparison of static pressure drop across the converging (flled symbols) and diverging microchannels (empty symbols) for the case of water and nitrogen, respectively. For both the cases, the pressure drop in converging orientation of the microchannel is higher than that in diverging orientation. This diference is pressure drop of the microchannel when it is subjected to converging and diverging orientation is discussed later in detail in Sect. [7](#page-6-0).

In all the cases the pressure drop across the microchannels decreases with increase in diverging/converging angles. In the case of diverging microchannel, increase in the divergence angle decelerates the flow, leading to a larger pressure recovery. Hence, the total pressure drop decreases with increase in the divergence angle. It is intuitively expected that due to greater acceleration at higher convergence angles, the pressure drop should increase with increase in convergence angle. But in the case of the converging microchannels too, the pressure drop is seen to decrease with increasing angle. This is because, although the fuid acceleration is higher for larger convergence angles, the overall pressure drop is dominated by the viscous force rather than the inertial force. This effect of the angles is more clearly understood by studying the force balance in both liquid and gas flows (Sect. 6).

In some of the earlier studies (Olsson et al. [1996](#page-9-4), [2000](#page-10-1)), instead of pressure drop, the comparison is presented in terms of pressure loss coefficient (ξ) given as

$$
\xi = \frac{\Delta P}{\frac{1}{2}\rho v_{\text{throat}}^2}
$$
\n(6)

where v_{throat} is the mean velocity of the fluid at the narrowest cross section. In our experiments, to study the efect of diverging/converging angle, the throat area (smallest cross section) is made the same for all the microchannels. Hence, the mean velocity at throat section is the same for all the microchannels, and the ratio of pressure loss coefficients reduces to the ratio of pressure drop across the microchannel, i.e.

$$
\frac{\xi_{\text{conv}}}{\xi_{\text{div}}} = \frac{(\Delta p)_{\text{conv}}}{(\Delta p)_{\text{div}}} \tag{7}
$$

It should be noted that the end efects are integrated in the measured experimental pressure drop. A similar analysis is carried out by Olsson et al. ([2000](#page-10-1)) and Graur et al. ([2014\)](#page-9-7) in the context of gradually diverging/converging microchannels. The end efects of the device are in the form of sudden contraction (or sudden expansion) at the end of the converging/diverging cross section into the reservoir section. These end losses are a function of the area ratio of the entry/exit of the microchannel and the reservoir. The effect of changing the area ratio on the pressure drop due to sudden expansion of the gas at the exit of the microchannel was studied numerically by Hemadri et al. ([2017](#page-9-12)). It was observed that changes in pressure drop characteristics for various reservoir sizes (corresponding to diferent area ratios) were less than 2%. As our interest is in the utilization of the converging/diverging elements as part of valveless micropumps which include reservoirs (across which the fuid is pumped), the present data provide information on the conditions under which the converging/diverging elements provide maximum pumping efficiency.

5 Comparison of Poiseuille number

Figure [5](#page-4-1)a, b shows the comparison of Poiseuille number for water and nitrogen fowing across diverging and converging microchannels for three diferent angles. In the case of incompressible, laminar fow, the Poiseuille number is a constant as can be seen from the data corresponding to liquid fow. For the case of gas fows, it is seen that, at lower Reynolds number (*Re* < 50), *Po* is a constant and about 12% higher than the liquid flow. The increase in *Po* for gases in contrast to liquids is attributed to the efect of compressibility of the gas. For *Re* > 50 there is a clear change in slope of *Po* for the case of gas fows. This change of slope corresponds to the case where the maximum Mach number in the flow increases from subsonic velocities $(Ma < 0.8)$ to transonic velocities ($Ma > 0.8$). The high Mach numbers lead to high gradients at the throat (narrowest cross section) of the varying cross section microchannel and higher pressure drop due to acceleration caused due to the density variation. The increase in *Po* is more significant in the case of converging microchannels as compared to the diverging orientation of the microchannels because in converging microchannels, apart from the density variation, additional fuid acceleration is caused by the reduction in cross-sectional area.

For very low values of $Re \, (< 1)$, the Knudsen number efect becomes signifcant for gas fows, and the *Po* starts reducing. Thus, while compressibility effects result in the increase in the *Po*, rarefaction effects act in the opposite sense by decreasing the *Po*. A detailed discussion on the efect of *Kn* on *Po* has already been presented in Hemadri et al. ([2017\)](#page-9-12). In both liquid and gas fows, the increase in convergence/divergence angles leads to an increase in the *Po*.

6 Comparison of forces for liquid and gas flows

Figure [6](#page-5-1) shows the variation of area-weighted pressure force, inertia force and viscous force along the axis of the 12° diverging and converging microchannel for $Re = 40$ for the case of water and nitrogen. A comparison of the forces in converging microchannel (Fig. [6a](#page-5-1), b) shows that the three forces vary similarly along the length of the microchannel for both liquid and rarefed gas fows. Initially, the pressure force is completely balanced by the viscous forces, and the inertial force is negligible. At the exit of the microchannel, there is a large acceleration of

Fig. 6 Streamwise variation of forces in converging microchannel of 12° angle **a** nitrogen, **b** water; and diverging microchannel, **c** nitrogen, **d** water

the fuid resulting in an increase in the inertial force. It is seen that this increase is higher in the case of gas fows which is attributed to the higher acceleration of the gas due to compressibility efects. In the diverging orientation of the microchannel (Fig. [6](#page-5-1)c, d), the forces in the rarefed gas fow behave quite diferently from that of liquid fow. In case of gas fow, there is large pressure recovery along the length of the microchannel, leading to an increase in the pressure force which is balanced by the viscous force. In all the cases, the viscous force is larger than inertial force and the diference is balanced by the pressure force. This is the reason for the increase in pressure drop across the microchannel with decreasing angle, in both converging and diverging orientations.

Another important diference is the presence of a negative gradient at the entrance of the diverging microchannel for the case of water fow. This negative pressure gradient is caused due to the vena contracta efect when the water is made to pass through the throat of the microchannel. Such an adverse pressure gradient is noticeably absent in the case of gas fows, leading to a positive pressure gradient all along the microchannel. This absence of fow reversal is a characteristic of rarefed gas fows and has also been reported in Agrawal et al. [\(2005\)](#page-9-13) and Varade et al. ([2014](#page-10-9), [2015b\)](#page-10-7). The existence of slip velocity, momentum difusivity and negligible kinetic energy together contribute to the absence of fow separation. In microsystems, the kinetic energy is very small compared to the driving pressure energy of the fow. Hence, any change in the kinetic energy does not sufficiently influence the flow to give rise to negative pressure gradient. The higher momentum difusivity in the case of rarefed gas fows also contributes in the prevention of separation by allowing the gas molecules to difuse and thus closely follow the microchannel surface.

An entropy generation analysis performed on the 12° converging microchannel gave a peak in entropy generation at the narrowest cross section, which is in line with physical reasoning (the velocity is maximum at the narrowest cross section) and force balance analysis presented here.

7 Diodicity

Fluidic diodicity (D) is the asymmetric transfer in flow passages/devices, which offer a lower flow resistance in one direction and greater resistance in the opposite direction. Diodicity is defned as the ratio for diverging to converging microchannel of the mass fow rate to the diference of square of inlet and outlet pressures. It is given as

$$
D = \frac{\dot{m}^{\text{div}} / \left[\left(P_i^{\text{div}} \right)^2 - \left(P_o^{\text{div}} \right)^2 \right]}{\dot{m}^{\text{conv}} / \left[\left(P_i^{\text{conv}} \right)^2 - \left(P_o^{\text{conv}} \right)^2 \right]}
$$
(8)

In the present set of experiments, the mass fow controller is used to obtain the same flow rates in both the converging and diverging orientations. Therefore, Eq. [\(8](#page-6-1)) becomes,

$$
D = \frac{(P_{\rm i}^{\rm conv})^2 - (P_{\rm o}^{\rm conv})^2}{(P_{\rm i}^{\rm div})^2 - (P_{\rm o}^{\rm div})^2} = \frac{(P_{\rm m}\Delta P)^{\rm conv}}{(P_{\rm m}\Delta P)^{\rm div}}
$$
(9)

A diodicity value other than unity implies that there is a fow-directing ability to the microchannel, resulting in different values of pressure drop when the working mode is changed from diverging to converging by reversing the flow direction. For the same mass flow rate, $D > 1$ implies that the pressure drop in the converging mode is higher than that of diverging mode and the reverse is true for $D < 1$.

In the case of liquid fows, few authors (Stemme and Stemme [1993](#page-10-0); Olsson et al. [1996,](#page-9-4) [2000\)](#page-10-1) have studied the diodic efect in converging and diverging orientations of varying cross section microchannel in relation to valveless micropumps. In these studies, it was found that the diference in the mass fow rates across the converging and diverging orientations of the microchannel (for the same inlet and outlet pressures) was due to large pressure recovery and small separation in the diverging mode and gross separation and vena contracta efects in the converging mode of the microchannel.

Figure [7](#page-7-0)a, b shows the variation of diodicity in the three microchannels of 4°, 8° and 12° for water and nitrogen, respectively. In the case of water, the diodicity approaches unity as the Reynolds number decreases. At higher *Re* (*Re* > 20) the diodicity increases, which corresponds to a higher resistance in the converging mode of the microchannel. As shown by Stemme and Stemme [\(1993](#page-10-0)), this greater pressure drop in the converging mode can be attributed to the loss of kinetic energy in the form of a jet at the exit of the microchannel. The rate of increase in diodicity with *Re* is dependent on the angle of convergence/divergence and is higher for higher angles. This is because of larger pressure recovery at higher angles in the case of diverging microchannels. In the case of nitrogen fow in microchannel too, the diodicity is unity for lower Reynolds numbers (*Re* < 10). Similar to the case of water flow, the diodicity increases with increase in *Re*. Here too, the converging orientation has a larger pressure drop, due to the loss of kinetic energy at the exit of the microchannel.

Comparing water and nitrogen values for diodicity shows two important similarities and diferences (Fig. [7](#page-7-0)c). For both fuids, the diodicity value approaches unity as the Reynolds number is lowered. This means that for low *Re* flows, the diodic efect cannot be employed to obtain a pumping action. At higher values of *Re*, for both water and nitrogen, the converging mode has a higher pressure drop, and in this region, **Fig. 7** Diodicity in converging/ diverging microchannel as a function of *Re* for **a** water, **b** nitrogen, **c** comparison of water (empty symbols) and nitrogen (flled symbols)

 (a) ^{1.5}

 1.4

 1.3

 1.2

 1.1

1

 0.9

 0.8

 Ω

the microchannel has a fow-directing ability which can be used to passively pump the fuid.

The main diferences between water and nitrogen are (1) the rise in the value of diodicity is higher in the case of nitrogen, compared to water; (2) unlike water, for nitrogen flow, diodicity is not a strong function of the angle of convergence/divergence. The higher value of diodicity for nitrogen is expected due to the presence of compressibility efects in the case of gas fows. Apart from the acceleration of the gas in the converging microchannel, due to a reduction in the cross-sectional area, there is also an additional acceleration of the gas due to the change in density along the length of the microchannel. In Fig. [7](#page-7-0)b the data points are divided into two sets based on the outlet Mach number of the fow for converging microchannel. It can be seen that the sudden steep rise in the value of diodicity corresponds to an exit Mach number > 0.3 , showing the presence of strong compressibility efects.

In the study performed by Graur et al. [\(2016](#page-9-8)), for the case where the varying cross section was obtained by changing the width of the microchannel and the height is kept constant (i.e. $h < w_s$ and $h \ll w_L$; similar to the microchannels

Fig. 8 Efect of Knudsen number on diodicity

employed in the present study), the diodic efect was not observed. When the microchannel height was used as the varying dimension, the diodic efect was seen to exist and to be dependent on the Knudsen number. The data for diodicity as a function of *Kn* for nitrogen are plotted in Fig. [8](#page-7-1) to investigate the efect of gas rarefaction on the diodicity. It is seen that, in the present case, the Knudsen number does not seem to afect the diodicity of the converging/diverging microchannel. If the data points corresponding to compressibility effects ($Ma > 0.3$) are ignored, the diodicity shows a constant value of unity for higher Knudsen numbers $(Kn > 0.01)$. The main reason for the absence of Knudsen number effect on diodicity for the present set of microchannels is the negligible infuence of the lateral walls on the flow. Due to the considerably higher width compared to the height of the microchannel, the microchannel flow behaves like a flow between parallel plates and the effect of varying width is not noticeable. At higher *Re* (low *Kn*), the rarefaction is negligible and compressibility efects dominate the flow leading to the observed diodicity.

8 Design considerations for converging and diverging microchannels

Flow in converging and diverging microchannels has not been studied extensively, and hence, there is lack of theoretical or empirical correlations governing such fows. However, relatively larger data exist for both liquid and gas fows in microchannels of constant cross section. In channels of varying cross sections, the length scale to be employed is not very obvious since the dimensions of the microchannels vary with length. In this regard, it would be advantageous from a designer's perspective, if some sort of a length scale can be proposed for varying cross section microchannels, such that the expressions/correlations that are readily available for constant cross section microchannels can be extended

 (a)

to converging/diverging microchannels. In the present set of experiments, this length scale is called as the 'equivalent hydraulic diameter' and is defned as the hydraulic diameter at an appropriate location along the length of the converging/ diverging microchannel $(L_{eq} = \text{distance from the narrower})$ end) that gives the same pressure drop as that of a constant cross section microchannel, under identical boundary conditions (Fig. [9](#page-8-0)).

The algorithm developed to arrive at the equivalent hydraulic diameter for converging and diverging microchannels is similar for both liquid and gas fows. It involves iteratively obtaining the Poiseuille number at diferent axial locations of the converging/diverging microchannel and comparing it with that obtained by correlations available in the literature for microchannels of constant cross section. A detailed description can be found in Duryodhan et al. ([2012,](#page-9-9) 2014) (liquid flow) and Varade et al. $(2015a, b)$ $(2015a, b)$ $(2015a, b)$ $(2015a, b)$ (gas flow). This section consolidates the results obtained in the above studies and highlights the similarities and diferences in the case of water and nitrogen fows.

The value of equivalent hydraulic diameter can be calculated by knowing the width at characteristic location. Generalized form of characteristic width can be represented by

$$
w_{\rm c} = w_{\rm s} + 2\frac{L}{n}\tan\left(\frac{\theta}{2}\right) \tag{10}
$$

where w_c is the width at the characteristic location. Further, *n* is the divisor whose value varies from 3 to 12.5 based on the mode of operation (i.e. diverging or converging), fuid (i.e. water or nitrogen) and the value of *Kn* as shown in Table [2](#page-8-1).

Table [2](#page-8-1) shows that for liquid flows, the concept of equivalent hydraulic diameter is indeed helpful, as its location is seen to be independent of the converging/diverging angle

Fig. 9 Schematic showing the location of equivalent hydraulic diameter for water fow in **a** converging microchannel, **b** diverging microchannel

for water and nitrogen

 (b)

*L*eq should be measured from the narrower end of microchannel

and the Reynolds number. It should also be noted that the L_{eq} for converging microchannel is smaller than its diverging counterpart, indicating that the pressure drop in the converging orientation is higher than the diverging orientation. This diference in the pressure drop across the microchannel when subjected to converging/diverging orientation is due to the diodic efect discussed in the previous section.

For the case of nitrogen, since the fow is rarefed, the Knudsen number comes into the picture and hence the location for equivalent hydraulic diameter is no longer unique but depends on the amount of rarefaction. Nevertheless, the concept of equivalent hydraulic diameter will facilitate to extend the use of available correlations made for uniform cross section microchannels to that of diverging/converging microchannels. Furthermore, it is useful to derive the theoretical formulae to calculate engineering numbers in terms of geometrical parameters at characteristic location.

As seen from Table [2](#page-8-1), as Knudsen number increases, L_{eq} gets smaller. With further increase in rarefaction the equivalent hydraulic diameter corresponds to the smallest crosssectional area. It is therefore appropriate to calculate the flow parameters at the smallest cross section while designing the converging/diverging microchannel to operate at higher rarefaction $(Kn > 0.1)$.

9 Conclusions

In this paper, the comparison between converging and diverging orientations of varying cross section microchannels was presented for liquid and gas fows. The efect of converging/diverging angle on the static pressure drop is studied, and it is seen that the pressure drop increases with decreasing converging/diverging angle for both liquid and gas fows. The efect of fuid on the Poiseuille number is presented. It is seen that the *Po* is a constant for the case of liquid flows, whereas in the case of gas flows, *Po* is seen to be affected by compressibility and rarefaction effects. The various forces along the microchannel for liquid and gas flows are discussed. The force comparison shows a large pressure recovery in gas flow in diverging microchannels in contrast to liquid fows. The absence of fow reversal is another important characteristic of rarefed gas fow in microchannels.

The effect of Reynolds number, Mach number and Knudsen number on the existence of diodicity is investigated. It is seen that for lower Reynolds numbers the diodic efect is absent in the case of both liquid and gas fows. Hence, the range of operation of converging/diverging elements as fow-directing valves in a micropump will be restricted by the Reynolds number. The concept of equivalent hydraulic diameter is presented which facilitates the use of correlations of constant cross section microchannels to predict the fow properties in converging/diverging microchannels. It is seen that such a diameter is more relevant to the case of liquid flows (where it is independent of flow and geometric properties) as compared to slightly rarefed gas fows (where the location of equivalent hydraulic diameter is seen to depend on Knudsen number). However, at higher rarefactions $(Kn > 0.1)$, the equivalent hydraulic diameter converges to the smallest cross-sectional area of the microchannel and hence the flow parameters obtained at this location should be utilized to design converging/diverging microchannels.

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