

Observability Inequality for the Petrovsky Equation

Zhong-yu BAI^{1,†}, Shu-gen CHAI²

¹Common Required Course Department, Haikou College of Economics, Haikou 571127, China

(E-mail: 610977231@qq.com)

²School of Mathematical Science, Shanxi University, Taiyuan 030006, China (Email: sgchai@sxu.edu.cn)

Abstract The aim of this paper is to study the exact controllability of the Petrovsky equation. Under some checkable geometric assumptions, we establish the observability inequality via the multiplier method for the Dirichlet control problem.

Keywords exact controllability; compact uniqueness; multiplier method

2000 MR Subject Classification 93B07; 35L35

1 Introduction

Consider the initial/boundary value problem:

$$\begin{cases} u'' + \Delta^2 u + u = \chi_G(x)h(x, t), & (x, t) \in \Omega \times (0, T), \\ u(x, t) = \Delta u = 0, & (x, t) \in \Gamma \times (0, T), \\ u(0) = u_0, u'(0) = u_1, & x \in \Omega, \end{cases} \quad (1)$$

where Ω is a bounded domain in \mathbb{R}^n with the boundary Γ , T is a positive constant, G is a sub domain, $\chi_G(x)$ is the eigenfunction of the set G , $\chi_G(x)h(x, t)$ is the locally distributed control.

In this paper, we use the geometric assumptions and the piecewise multiplier method to establish inequality for the Petrovsky equation. For the conservative systems, How to choose the control subregion so that the system has exact controllability, this problem has been studied extensively^[3,6]. The locally distributed control for the Petrovsky equation was studied by Liu^[5]. Very recently, a novel control approach is utilized to solve the control problem^[4,7].

We study the Petrovsky equation, and the geometric conditions on Ω and G were introduced by Liu^[5]. In the system (1), due to the increase of the general term u and the initial value condition, this makes its analysis much more complicated than that of the Petrovsky system with the simply supported boundary condition^[5]. So we are faced with new difficulties: to set up appropriate geometric conditions for the observability estimates and to derive the control inequality for the solution u of (1).

Set

$$V = H_0^2(\Omega), \quad \|v\|_V = \left(\int_{\Omega} |\Delta v|^2 dx \right)^{\frac{1}{2}}, \quad H = L^2(\Omega), \quad \|v\|_H = \left(\int_{\Omega} |v|^2 dx \right)^{\frac{1}{2}},$$

Manuscript received July 1, 2014. Revised July 16, 2015.

Supported by the Natural Science Foundation of Hainan Province (No. 20161011).

[†]Corresponding author.

where

$$H_0^2(\Omega) = \{u \in H^2(\Omega), u = \partial_\nu u = 0, x \in \Gamma\},$$

$H^2(\Omega)$ is 2-order Sobolev space^[1]. Then, H and V are complex Hilbert spaces, the corresponding derived inner product denoted as \langle, \rangle_V and \langle, \rangle_H . Introduce the space $U = V \times H$, with the norm $\|(u, v)\|_U = (\|u\|_V^2 + \|v\|_H^2)^{\frac{1}{2}}$. It is obvious that U is also a complex Hilbert space with the inner product \langle, \rangle_U .

It is clear that for each $h \in L^2(\Omega \times (0, T))$ and $(u^0, u^1) \in U$, the Problem (1) has a unique solution satisfies

$$u \in C^1([0, T]; H) \cap C([0, T]; V).$$

Define the energy of the System (1) by

$$E(t) = \frac{1}{2} \int_{\Omega} (|u'|^2 + |\Delta u|^2 + |u|^2) dx. \tag{2}$$

Remark 1.1. For $S \subset \mathbb{R}^n, \varepsilon > 0$, let

$$N_\varepsilon(S) = \bigcup_{x \in S} \{y \in \mathbb{R}^n : |y - x| < \varepsilon\}. \tag{3}$$

Remark 1.2. For $x_0^j \in \mathbb{R}^n, \Omega_j \subset \Omega, 1 \leq j \leq J$, set

$$\Gamma_j = \Gamma_j(x_0^j) = \{x \in \partial\Omega_j : (x - x_0^j) \cdot \nu^j(x) > 0\}, \tag{4}$$

where $\nu^j(x)$ is the unit normal vector of $\partial\Omega_j$ at $x, x \cdot y$ denotes the inner product of $x \in \mathbb{R}^n$ and $y \in \mathbb{R}^n$. We know that when Ω_j with Lipschitz boundary, $\nu^j(x) \in L^\infty(\partial\Omega_j; \mathbb{R}^n)$ ^[2].

Remark 1.3. Geometric conditions on Ω and G ^[5]: (a) Ω is sufficiently smooth; (b) there exists $\varepsilon > 0, \Omega_j$ with Lipschitz boundary $\partial\Omega_j$ and point $x_0^j \in \mathbb{R}^n, 1 \leq j \leq J$, such that

$$\Omega_i \cap \Omega_j = \emptyset, \quad 1 \leq i < j \leq J, \tag{5}$$

$$G \supset \Omega \cap N_\varepsilon \left[\bigcup_{j=1}^J \Gamma_j(x_0^j) \cup (\Omega \setminus \bigcup_{j=1}^J \Omega_j) \right]. \tag{6}$$

First, we consider dual version

$$\begin{cases} u'' + \Delta^2 u + u = 0, & (x, t) \in \Omega \times (0, T), \\ u(x, t) = \Delta u = 0, & (x, t) \in \Gamma \times (0, T), \\ u(0) = u_0, u'(0) = u_1, & x \in \Omega. \end{cases} \tag{7}$$

Let

$$\begin{cases} D(A) = \{u \in V : \Delta^2 u \in H\}, \\ Au = \Delta^2 u, \quad \forall u \in D(A). \end{cases} \tag{8}$$

And on U by

$$\begin{cases} D(\Lambda) = D(A) \times V, \\ \Lambda = \begin{pmatrix} 0 & I \\ -A & 0 \end{pmatrix}. \end{cases} \tag{9}$$

The solution of (7) is given by

$$(u(\cdot, t), u'(\cdot, t)) = e^{At}(u_0, u_1), \quad \forall (u_0, u_1) \in U. \tag{10}$$

By (10), we readily have

$$u(u_0, u_1) \in C^2([0, T]; H) \cap C^1([0, T]; V) \cap C([0, T]; D(A)), \quad \forall (u_0, u_1) \in D(A). \tag{11}$$

From the regularity results on elliptic problems^[2], we know that the geometric Condition (a) implies

$$D(A) = H^4(\Omega) \cap H_0^2(\Omega). \tag{12}$$

In general, if the solution of (1) and (7) are real valued, then (7) is conservative, i.e.

$$E(t) = \frac{1}{2} \int_{\Omega} (|u'|^2 + |\Delta u|^2 + |u|^2) dx = E(0), \quad \forall t \geq 0. \tag{13}$$

2 The Main Results and Proofs

In this section, we give the observability inequality and its proof. First, we prove Theorem 2.1. Because of the limit of the length of the paper, some obvious derivation is omitted.

Theorem 2.1. *Let the function $u \in H_{loc}^2(\mathbb{R}; H^4(\Omega))$ satisfy*

$$u'' + \Delta^2 u + u = 0, \quad (x, t) \in \Omega \times (0, T), \tag{14}$$

$q : \bar{\Omega} \rightarrow \mathbb{R}^n$ is a vector function of class C^2 , then for any given $0 < T < \infty$, the following identity holds true

$$\begin{aligned} & \int_0^T \int_{\Gamma} t(T-t) [(q \cdot \nu) u_t^2 - 2(\partial_{\nu} \Delta u) q \cdot \nabla u - 2(q \cdot \nu) u^2] d\Gamma dt \\ &= -2 \int_0^T \int_{\Omega} (T-2t) u_t q \cdot \nabla u dx dt + \int_0^T \int_{\Omega} t(T-t) (\operatorname{div} q) [u_t^2 - (\Delta u)^2 - 2u^2] dx dt \\ &+ 2 \int_0^T \int_{\Omega} t(T-t) \left[\sum_{i=1}^n (\Delta q)_i (\partial_i u) (\Delta u) + 2 \sum_{i,k=1}^n (\partial_i q_k) (\partial_i \partial_k u) (\Delta u) \right] dx dt. \end{aligned} \tag{15}$$

Proof. We multiply (14) by $2t(T - t)q \cdot \nabla u$ and we integrate by parts

$$0 = \int_0^T \int_{\Omega} 2(u'' + \Delta^2 u + u)t(T - t)q \cdot \nabla u dx dt, \tag{16}$$

$$\begin{aligned} & \int_0^T \int_{\Omega} 2u_{tt}t(T - t)q \cdot \nabla u dx dt \\ &= - \int_0^T \int_{\Omega} [2(T - 2t)u_t q \cdot \nabla u + 2u_t t(T - t)q \cdot \nabla u_t] dx dt \\ &= - \int_0^T \int_{\Omega} [2(T - 2t)u_t q \cdot \nabla u + t(T - t)q \cdot \nabla u_t^2] dx dt \\ &= - \int_0^T \int_{\Omega} 2(T - 2t)u_t q \cdot \nabla u dx dt - \int_0^T \int_{\Gamma} t(T - t)(q \cdot \nu)u_t^2 d\Gamma dt \\ & \quad + \int_0^T \int_{\Omega} t(T - t)(\operatorname{div} q)u_t^2 dx dt, \end{aligned} \tag{17}$$

$$\begin{aligned} & \int_0^T \int_{\Omega} 2ut(T - t)q \cdot \nabla u dx dt \\ &= \int_0^T \int_{\Omega} 2t(T - t)q \cdot \nabla u^2 dx dt \\ &= \int_0^T \int_{\Gamma} 2t(T - t)(q \cdot \nu)u^2 d\Gamma dt - \int_0^T \int_{\Omega} 2t(T - t)(\operatorname{div} q)u^2 dx dt. \end{aligned} \tag{18}$$

Applying

$$\Delta(q \cdot \nabla u) = \sum_{i,k=1}^n \partial_i^2(q_k \partial_k u) = 2 \sum_{i,k=1}^n (\partial_i q_k)(\partial_i \partial_k u) + \sum_{i=1}^n (\Delta q_k)(\partial_k u) + \sum_{i=1}^n q_k \partial_k(\Delta u),$$

We have

$$2(\Delta u)\Delta(q \cdot \nabla u) = q \cdot \nabla(\Delta u)^2 + 2 \sum_{i=1}^n (\Delta q_i)(\partial_i u)(\Delta u) + 4 \sum_{i,k=1}^n (\partial_i q_k)(\partial_i \partial_k u)(\Delta u). \tag{19}$$

Use of (19) yields

$$\begin{aligned} & \int_0^T \int_{\Omega} 2(\Delta^2 u)t(T - t)q \cdot \nabla u dx dt \\ &= \int_0^T \int_{\Gamma} 2(\partial_{\nu} \Delta u)t(T - t)q \cdot \nabla u d\Gamma dt - \int_0^T \int_{\Omega} 2t(T - t)(\nabla \Delta u) \cdot \nabla(q \cdot \nabla u) dx dt \\ &= \int_0^T \int_{\Gamma} 2(\partial_{\nu} \Delta u)t(T - t)q \cdot \nabla u d\Gamma dt + \int_0^T \int_{\Omega} 2t(T - t)(\Delta u)\Delta(q \cdot \nabla u) dx dt \\ &= \int_0^T \int_{\Gamma} 2t(T - t)(\partial_{\nu} \Delta u)q \cdot \nabla u d\Gamma dt - \int_0^T \int_{\Omega} t(T - t)(\operatorname{div} q)(\Delta u)^2 dx dt \\ & \quad + \int_0^T \int_{\Omega} t(T - t) \left[2 \sum_{i=1}^n (\Delta q_i)(\partial_i u)(\Delta u) + 4 \sum_{i,k=1}^n (\partial_i q_k)(\partial_i \partial_k u)(\Delta u) \right] dx dt. \end{aligned} \tag{20}$$

We deduce from (16)–(18) and (20) that (15). □

Theorem 2.2. For any $T > 0$, there exists a $C = C(\Omega, T, J, x_0^j, \Omega_j, G)$, $1 \leq j \leq J$ such that for every solution u of (7) with initial value $(u_0, u_1) \in U$ satisfying

$$\int_0^T \int_G |u'|^2 dxdt \geq CE(0). \tag{21}$$

Proof. First of all, using piecewise multiplier method, will justify that for any given $T > 0$, there exists a constant $M > 0$, such that the solution u of (7) satisfies

$$E(0) \leq M \int_0^T \int_{\Omega} (u^2 + |\nabla u|^2) dxdt + M \int_0^T \int_G u_t^2 dxdt. \tag{22}$$

Putting

$$\begin{aligned} x &= (x_1, \dots, x_n), & x_0^j &= (x_{01}^j, \dots, x_{0n}^j), \\ m^j &= (m_1^j, \dots, m_n^j), & m_k^j &= x_k - x_{0k}^j, & 1 \leq k \leq n, & 1 \leq j \leq J, \\ \nu^j &= (\nu_1^j, \dots, \nu_n^j), & & & 1 \leq j \leq J. \end{aligned}$$

We choose $\varepsilon_0, \varepsilon_1 > 0$ such that $0 < \varepsilon_1 < \varepsilon_0 < \varepsilon$, and set

$$\begin{cases} Q_0 = N_{\varepsilon_0} \left[\bigcup_{j=1}^J \cup \left(\Omega \setminus \bigcup_{j=1}^J \Omega_j \right) \right], \\ Q_1 = N_{\varepsilon_1} \left[\bigcup_{j=1}^J \cup \left(\Omega \setminus \bigcup_{j=1}^J \Omega_j \right) \right]. \end{cases} \tag{23}$$

Choose ϕ^j such that

$$\phi^j \in C_0^\infty(\mathbb{R}^n), \quad 0 \leq \phi^j \leq 1, \tag{24}$$

$$\phi^j = 1, \quad x \in \overline{\Omega_j} \setminus Q_0, \tag{25}$$

$$\beta\phi^j = 0, \quad x \in Q_1. \tag{26}$$

For each j , we insert $\Omega := \Omega_j$, $h(x) = \phi^j(x)m^j(x)$ into (15), we obtain

$$\begin{aligned} & \int_0^T \int_{\partial\Omega_j} t(T-t) [(\phi^j m^j \cdot \nu^j)u_t^2 - 2(\phi^j m^j \cdot \nu^j)u^2] d\Gamma dt \\ & - 2 \int_0^T \int_{\partial\Omega_j} t(T-t) (\partial_{\nu^j} \Delta u) (\phi^j m^j \cdot \nabla u) d\Gamma dt \\ & = -2 \int_0^T \int_{\Omega_j} (T-2t)u_t \phi^j m^j \cdot \nabla u dxdt \\ & + \int_0^T \int_{\Omega_j} t(T-t) [\operatorname{div}(\phi^j m^j)] [u_t^2 - (\Delta u)^2 - 2u^2] dxdt \\ & + 2 \int_0^T \int_{\Omega_j} t(T-t) \sum_{i=1}^n [\Delta(\phi^j m_i^j)] (\partial_i u) (\Delta u) \\ & + 4 \int_0^T \int_{\Omega_j} t(T-t) \sum_{i,k=1}^n [\partial_i(\phi^j m_k^j)] (\partial_i \partial_k u) (\Delta u) dxdt. \end{aligned} \tag{27}$$

As $\Omega \setminus (\bigcup_{j=1}^J \Omega_j) \supset \partial\Omega_j \setminus \Gamma$, combining with (23) and (26) we find that

$$\phi^j = 0, \quad x \in N_{\varepsilon_1}[(\partial\Omega_j \setminus \Gamma) \cup \Gamma_j]. \tag{28}$$

We deduce from the second equation of (7) that

$$\begin{aligned} & \int_0^T \int_{(\partial\Omega_j \setminus \Gamma_j) \cap \Gamma} t(T-t)(\partial_{\nu^j} \Delta u)(\phi^j m^j \cdot \nabla u) dx dt \\ &= \int_0^T \int_{(\partial\Omega_j \setminus \Gamma_j) \cap \Gamma} t(T-t)(\phi^j m^j \cdot \nu^j \cdot \nabla u) \Delta u dx dt = 0. \end{aligned} \tag{29}$$

Notice

$$\partial\Omega_j = (\partial\Omega_j \setminus \Gamma) \cup (\Gamma_j \cap \Gamma) \cup ((\partial\Omega_j \setminus \Gamma_j) \cap \Gamma),$$

Utilizing the second equation of (7) and (27)–(29), we have

$$\begin{aligned} & \int_0^T \int_{(\partial\Omega_j \setminus \Gamma_j) \cap \Gamma} t(T-t)(\phi^j m^j \cdot \nu^j) u_t^2 d\Gamma dt \\ &= -2 \int_0^T \int_{\Omega_j} (T-2t) u_t \phi^j m^j \cdot \nabla u dx dt \\ & \quad + \int_0^T \int_{\Omega_j} t(T-t) [\operatorname{div}(\phi^j m^j)] [u_t^2 - (\Delta u)^2 - 2u^2] dx dt \\ & \quad + 2 \int_0^T \int_{\Omega_j} t(T-t) \sum_{i=1}^n [\Delta(\phi^j m_i^j)] (\partial_i u) (\Delta u) dx dt \\ & \quad + 4 \int_0^T \int_{\Omega_j} t(T-t) \sum_{i,k=1}^n [\partial_i(\phi^j m_k^j)] (\partial_i \partial_k u) (\Delta u) dx dt. \end{aligned} \tag{30}$$

Using (4) and (24) we obtain that

$$\int_0^T \int_{(\partial\Omega_j \setminus \Gamma_j) \cap \Gamma} t(T-t)(\phi^j m^j \cdot \nu^j) u_t^2 dx dt \leq 0.$$

Pay attention to integral on $\Omega_j \cap Q_1$ is zero, by (30) can be introduced

$$\begin{aligned} & -2 \int_0^T \int_{\Omega_j \setminus Q_1} (T-2t) u_t \phi^j m^j \cdot \nabla u dx dt \\ & + \int_0^T \int_{\Omega_j \setminus Q_1} t(T-t) [\operatorname{div}(\phi^j m^j)] [u_t^2 - (\Delta u)^2 - 2u^2] dx dt \\ & + 2 \int_0^T \int_{\Omega_j \setminus Q_1} t(T-t) \sum_{i=1}^n [\Delta(\phi^j m_i^j)] (\partial_i u) (\Delta u) dx dt \\ & + 4 \int_0^T \int_{\Omega_j \setminus Q_1} t(T-t) \sum_{i,k=1}^n [\partial_i(\phi^j m_k^j)] (\partial_i \partial_k u) (\Delta u) dx dt \leq 0. \end{aligned} \tag{31}$$

Furthermore, we have

$$\sum_{j=1}^J \int_0^T \int_{\Omega_j \setminus Q_0} t(T-t) [n u_t^2 + (4-n)(\Delta u)^2 - 2n u^2] dx dt$$

$$\begin{aligned}
 &\leq 2 \sum_{j=1}^J \int_0^T \int_{\Omega_j \setminus Q_1} (T-2t) u_t \phi^j m^j \cdot \nabla u \, dx dt \\
 &\quad - \sum_{j=1}^J \int_0^T \int_{\Omega_j \cap Q_0 \setminus Q_1} t(T-t) [\operatorname{div}(\phi^j m^j)] [u_t^2 - (\Delta u)^2 - 2u^2] \, dx dt \\
 &\quad - 2 \sum_{j=1}^J \int_0^T \int_{\Omega_j \cap Q_0 \setminus Q_1} t(T-t) \sum_{i=1}^n [\Delta(\phi^j m_i^j)] (\partial_i u) (\Delta u) \, dx dt \\
 &\quad - 4 \sum_{j=1}^J \int_0^T \int_{\Omega_j \cap Q_0 \setminus Q_1} t(T-t) \sum_{i,k=1}^n [\partial_i(\phi^j m_k^j)] (\partial_i \partial_k u) (\Delta u) \, dx dt \\
 &\leq C_1 \int_0^T \int_{\Omega} |u_t| |\nabla u| \, dx dt \\
 &\quad + C_1 \sum_{j=1}^J \int_0^T \int_{\Omega_j \cap Q_0} [u_t^2 + (\Delta u)^2 + u^2] \, dx dt, \tag{32}
 \end{aligned}$$

where $C_1 = C_1(T, n, m^j, \phi^j) > 0$ is a constant independent of u , and used here from (25)

$$\begin{aligned}
 \operatorname{div}(\phi^j m^j) &= \operatorname{div} m^j = n, & x \in \Omega_j \setminus Q_0, \\
 \frac{\partial(\phi^j m_k^j)}{\partial x_i} &= \begin{cases} 1, & k = i, \\ 0, & K \neq i, \end{cases} & x \in \Omega_j \setminus Q_0.
 \end{aligned}$$

On the other hand, multiplying the first equation of (7) by $(n-2)t(T-t)u$, and we integrate on $\Omega \times (0, T)$, then using the second equation of (7) we obtain that

$$-(n-2) \int_0^T \int_{\Omega} (T-2t) u_t u \, dx dt + (n-2) \int_0^T \int_{\Omega} t(T-t) [(\Delta u)^2 - u_t^2 + u^2] \, dx dt = 0.$$

Hence

$$\begin{aligned}
 &-(n-2) \int_0^T \int_{\Gamma} (T-2t) u_t u \, dx dt + (n-2) \int_0^T \int_{\Omega \setminus Q_0} t(T-t) [(\Delta u)^2 - u_t^2 + u^2] \, dx dt \\
 &+ (n-2) \int_0^T \int_{\Omega \cap Q_0} t(T-t) [(\Delta u)^2 - u_t^2 + u^2] \, dx dt = 0. \tag{33}
 \end{aligned}$$

Combing now (32), (33), and applying (5), (13) and $\bigcup_{j=1}^J (\Omega_j \setminus Q_0) = (\Omega \setminus Q_0)$, we discover

$$\begin{aligned}
 &2T^3 E(0) - (n-2) \int_0^T \int_{\Omega} (T-2t) u_t u \, dx dt \\
 &\leq \int_0^T \int_{\Omega \cap Q_0} t(T-t) [(4-n+C_1)(\Delta u)^2 + (n+C_1)u_t^2 + (4+C_1)u^2] \, dx dt \\
 &\quad + C_1 \int_0^T \int_{\Omega} |u_t| |\nabla u| \, dx dt. \tag{34}
 \end{aligned}$$

By $G \supset \Omega \cap Q_0$, (34) implies

$$\begin{aligned}
 T^3 E(0) \leq & M_1 \left[\int_0^T \int_{\Omega} (|u_t u| + |u_t| |\nabla u|) dx dt + \int_0^T \int_G u_t^2 dx dt \right. \\
 & \left. + \int_0^T \int_{\Omega \cap Q_0} t(T-t)(\Delta u)^2 dx dt + \int_0^T \int_{\Omega \cap Q_0} t(T-t)u^2 dx dt \right], \tag{35}
 \end{aligned}$$

where $M_1 > 0$ is a constant.

Let us estimate $\int_0^T \int_{\Omega \cap Q_0} t(T-t)(\Delta u)^2 dx dt$. Employing (6) and (23), we have $\overline{(\mathbb{R}^n \setminus G)} \cap \overline{Q_0} = \emptyset$. So take a fixed function ξ satisfies

$$\xi \in C_0^\infty(\mathbb{R}^n), \quad 0 \leq \xi \leq 1; \quad \xi = 1, \quad x \in Q_0; \quad \xi = 0, \quad x \in \mathbb{R}^n \setminus G.$$

We multiply (7) by $t(T-t)\xi u$ and integrate on $\Omega \times (0, T)$, we obtain

$$\int_0^T \int_{\Omega} (u_{tt} + \Delta^2 u + u)t(T-t)\xi u dx dt = 0.$$

Since

$$\begin{aligned}
 & \int_0^T \int_{\Omega} u_{tt} t(T-t)\xi u dx dt \\
 = & - \int_0^T \int_{\Omega} (T-2t)\xi u_t u dx dt - \int_0^T \int_{\Omega} t(T-t)\xi u_t^2 dx dt, \\
 & \int_0^T \int_{\Omega} (\Delta^2 u)t(T-t)\xi u dx dt \\
 = & - \int_0^T \int_{\Omega} t(T-t)[\xi(\nabla \Delta u) \cdot \nabla u + u(\nabla \Delta u) \cdot \nabla \xi] dx dt \\
 = & - \int_0^T \int_{\Omega} t(T-t)\nabla(\Delta u)(\nabla \xi \cdot u + \xi \cdot \nabla u) dx dt \\
 = & \int_0^T \int_{\Omega} t(T-t)[2(\Delta u)(\nabla u) \cdot \nabla \xi + \xi(\Delta u)^2 + u(\Delta u)\Delta \xi] dx dt, \\
 & \int_0^T \int_{\Omega} ut(T-t)\xi u dx dt = \int_0^T \int_{\Omega} t(T-t)\xi u^2 dx dt,
 \end{aligned}$$

hence combing three equalities above, we deduce

$$\begin{aligned}
 & \int_0^T \int_{\Omega} t(T-t)\xi(\Delta u)^2 dx dt \\
 = & \int_0^T \int_{\Omega} (T-2t)\xi u_t u dx dt \\
 & + \int_0^T \int_{\Omega} t(T-t)[\xi u_t^2 - 2(\Delta u)(\nabla u) \cdot \nabla \xi - \xi u^2 - u(\Delta u)\Delta \xi] dx dt. \tag{36}
 \end{aligned}$$

Moreover, we have

$$\begin{aligned}
 & \int_0^T \int_{\Omega \cap Q_0} t(T-t)(\Delta u)^2 dxdt \\
 & \leq \int_0^T \int_{\Omega} t(T-t)\xi(\Delta u)^2 dxdt \\
 & = \int_0^T \int_G \{ (T-2t)\xi u_t u + t(T-t)[\xi u_t^2 - 2(\Delta u)(\nabla u) \cdot \nabla \xi - \xi u^2 - u(\Delta u)\Delta \xi] \} dxdt \\
 & \leq M_2 \int_0^T \int_{\Omega} |u_t u| dxdt + \int_0^T \int_G \frac{T^2}{4} u_t^2 dxdt \\
 & \quad - \int_0^T \int_G t(T-t)[2(\Delta u)(\nabla u) \cdot \nabla \xi + u(\Delta u)\Delta \xi + \xi u^2] dxdt, \tag{37}
 \end{aligned}$$

where $M_2 > 0$ is a positive constant. By (35) and (37), we have

$$\begin{aligned}
 T^3 E(0) & \leq M_3 \int_0^T \int_{\Omega} (|u_t u| + |u_t| |\nabla u|) dxdt + M_3 \int_0^T \int_G u_t^2 dxdt \\
 & \quad - M_1 \int_0^T \int_G t(T-t)[2(\Delta u)(\nabla u) \cdot \nabla \xi + \xi u^2 + u(\Delta u)\Delta \xi] dxdt \\
 & = M_3 \int_0^T \int_{\Omega} (|u_t u| + |u_t| |\nabla u|) dxdt + M_3 \int_0^T \int_G u_t^2 dxdt \\
 & \quad + M_1 \int_0^T \int_{\Omega} t(T-t)\xi(\Delta u)^2 dxdt \\
 & \quad - M_1 \int_0^T \int_{\Omega} (T-2t)\xi u_t u dxdt - M_1 \int_0^T \int_{\Omega} t(T-t)\xi u_t^2 dxdt \\
 & \leq M_3 \int_0^T \int_{\Omega} (|u_t u| + |u_t| |\nabla u|) dxdt + M_3 \int_0^T \int_G u_t^2 dxdt \\
 & \quad + M_1 \int_0^T \int_{\Omega} t(T-t)\xi(\Delta u)^2 dxdt + M_1 \int_0^T \int_{\Omega} |T-2t|\xi|u_t u| dxdt \\
 & \leq \int_0^T \int_{\Omega} \left[M_3 \left(u_t^2 + \frac{u^2 + (\nabla u)^2}{2} \right) + \frac{M_1 T^2}{4} (\Delta u)^2 + M_1 \cdot 2T \cdot \frac{u^2 + u_t^2}{2} \right] dxdt \\
 & \quad + M_3 \int_0^T \int_G u_t^2 dxdt \\
 & = \int_0^T \int_{\Omega} \left[(M_3 + M_1 T) u_t^2 + \frac{M_1 T^2}{4} (\Delta u)^2 \right] + \left[(M_1 T + \frac{M_3}{2}) u^2 \right. \\
 & \quad \left. + \frac{M_3}{2} (\nabla u)^2 \right] dxdt + M_3 \int_0^T \int_G u_t^2 dxdt \\
 & \leq 2T\delta E(0) + M_4 \int_0^T \int_{\Omega} (u^2 + |\nabla u|^2) dxdt + M_3 \int_0^T \int_G u_t^2 dxdt. \tag{38}
 \end{aligned}$$

For any $\delta > 0$, where $M_3 > 0$ and $M_4 > 0$ are constants independent of u . By (38), we have (22).

Secondly, combing with (22) and using the compact uniqueness theorem, we shall obtain the inequality of Theorem 2.2. This completes the proof of Theorem 2.2. \square

Acknowledgements. The authors would like to thank the referees for their helpful comments and suggestions.

References

- [1] Adams, R.A. Sobolev Spaces . Academic Press, New York, 1975
- [2] Grisvard, P. Elliptic problems in nonsmooth domains. Monographs and Studies in Math., Vol.24, Pitman, Boston, MA, 1985
- [3] Lagnese, J. Control of wave process with distributed controls supported on a subregion. *SIAM J. Cont. Optim.*, 21: 68–85 (1983)
- [4] Li, J., Zhang, W., Chen, M. Synchronization of delayed reaction-diffusion neural networks via an adaptive learning control approach. *Computers and Mathematics with Applications*, 65(1): 1775–1785 (2013)
- [5] Liu, K. Locally distributed control and damping for the conservative systems. *SIAM J. Control Optim.*, 35(5): 1574–1590 (1997)
- [6] Rauch, J., Taylor, M.E. Exponential decay of solutions to hyperbolic equations in bounded domains. *Indiana Univ. Math. J.*, 24(1): 79–86 (1974)
- [7] Zhang W., Xing K., Li J., Chen M. Adaptive synchronization of delayed reaction-diffusion FCNNs via learning control approach. *Journal of Intelligent & Fuzzy Systems*, 28(1): 141–150 (2015)