### **ORIGINAL PAPER**



# **Kinematic limit analysis of the slope encapsulating a laterally loaded pile**

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#### **Abstract**

This study aims to present a theoretical method for the safety factor of a slope encapsulating a laterally loaded pile. The factor can be derived by the object function concerning the external work rate and internal energy dissipation based on kinematic limit analysis, after assuming the log-spiral failure mechanism of the slope. To address the core issues (the critical point depth and lateral force provided by the pile) in the analysis, the modifed strain wedge technique and the soil wedge assumption were adopted to evaluate the soil resistance and extra earth pressure around the pile, respectively. Besides, the proposed method was verifed by published data and numerical methods, and the slope failure mechanism was revealed by observing two wedge-shaped failure regions around the pile. Furthermore, the variations of normalized safety factors with normalized lateral loads can be empirically ftted by cubic functions, and the normalized safety factor mainly depends on the lateral load and pile location but is not sensitive to the shear strength. The safety factor of the slope encapsulating a laterally loaded pile ( $FoS_1$ ) can be thus alternatively predicted by scaling the safety factor of the slope without the lateral load ( $FoS_0$ ) with the corresponding normalized safety factor *η*.

**Keywords** Laterally loaded pile · Slope stability · Kinematic limit analysis · Strain wedge · Factor of safety

# **Introduction**

Piles have been frequently employed to sustain superstructures of bridges (Zhao et al. [2017,](#page-16-0) [2019,](#page-16-1) [2020\)](#page-16-2), transmission towers, and buildings in mountainous areas (Peng et al. [2019](#page-16-3), [2020a,](#page-16-4) [b](#page-16-5)) such as western and southern hilly terrain (Ng et al. [2001](#page-16-6); Ng and Zhang [2001;](#page-16-7) Zhang et al. [2008](#page-16-8)) in

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China (Fig. [1](#page-1-0)a). The pile would inevitably carry lateral loads caused by high-speed vehicles, typhoons (Liang et al. [2012](#page-16-9)), and earthquakes (Wang et al. [2021](#page-16-10)), and the lateral load would be transferred from the pile head to the slope, leading to a degeneration of slope stability and even a slope failure (Fig. [1](#page-1-0)b). Hence, the mechanical context and behavior of the slope encapsulating a laterally loaded pile are more complicated than those of the slope reinforced with anti-slide piles, and the corresponding stability analysis has become one of the signifcant technical issues in highway bridge engineering in mountainous areas.

In the feld of slope stability analysis (Liu et al. [2021](#page-16-11)), much more effort has been devoted to the slope without a laterally loaded pile and the commonly used methods include the limit equilibrium method (Ito et al. [1979](#page-16-12); Poulos [1995](#page-16-13)), numerical simulation (Lee et al. [1991](#page-16-14); Ni et al. [2018](#page-16-15)), and limit analysis method (Ausilio et al. [2001](#page-15-0); Huang et al. [2013;](#page-15-1) Gao et al. [2014;](#page-15-2) Qin et al. [2017](#page-16-16)). The main thought of these methods is to sum the lateral reaction forces provided by anti-slide piles on the potential sliding block and then evaluate the slope safety factor by reducing the shear strength of soil or comparing the resisting moment with the overturning moment on the block. For



**Fig. 1** Slope encapsulating laterally loaded piles: **a** pile foundations in mountainous areas; **b** global instability and local instability

<span id="page-1-0"></span>the limit equilibrium method, the solutions satisfy the static equilibrium condition and Mohr–Coulomb criterion; however, certain simplifed assumptions are required and the stress–strain relationship of soil is neglected (Yu et al. [1998\)](#page-16-17). For the numerical simulation, the response of the pile-slope system could be preferably investigated; however, the method is challenged by intensive computations and excessive sensitiveness to input soil parameters and constitutive relation. As to the limit analysis method, the solutions can consider the stress–strain relationship of soil based on rigid-perfectly plastic assumptions, and the method has been broadly employed due to its simplicity and convenience. Hence, it is also an efective theoretical means to predict the stability of the slope encapsulating a laterally loaded pile based on the limit analysis method but has not been systematically reported yet. To the authors' acknowledge, the lateral load transferred from the pile head to the slope would result in diferent mechanical responses such as the soil resistance and extra earth pressure around the pile. Two cases of slope failure ascribed to by laterally loaded piles were reported by Uto et al. [\(1987\)](#page-16-18), but there was no further development on the failure mechanism. To tackle it, an assumption of the wedge-shaped local failure in front of the laterally loaded pile was presented (Nakasima et al. [1985\)](#page-16-19), and the local failure was subsequently observed in some model experiments (Muthukkumaran [2014](#page-16-20)). In addition, three-dimensional numerical analysis was carried out to quantitatively investigate the efect of the laterally loaded pile on the slope stability, and the mechanisms of lateral load transfer from the pile to the slope were revealed (Ng et al. [2001\)](#page-16-6). However, these studies failed to theoretically predict the mechanical response (Ng et al. [2001;](#page-16-6) Uto et al. [1987;](#page-16-18) Nakasima et al. [1985;](#page-16-19) Muthukkumaran [2014\)](#page-16-20) and satisfy the requirement of the recent design code (JTG [2020](#page-16-21)). In conclusion, it is necessary to estimate the soil resistance

and extra earth pressure in the theoretical analysis of slope stability with a laterally loaded pile.

On account of this, the assessments of degraded soil resistance in front of the pile and extra earth pressure behind the pile should be considered (Fig. [2](#page-1-1)). For the former, it is commonly estimated by reducing the standard *p*-*y* curves in the level ground (Reese and Welch [1975\)](#page-16-22) with reduction coefficients (Mezazigh and Levacher [1998](#page-16-23); Liyanapathirana and Poulos [2010](#page-16-24); Nimityongskul et al. [2018\)](#page-16-25), idealizing the soil as a series of nonlinear springs along piles (Reese et al. [2006;](#page-16-26) Jiang et al. [2020\)](#page-16-27). However, the estimation would rely on measured *p*-*y* curves in the feld, with a limited range of pile properties (e.g., the pile type, pile stifness, and pile top restrains) and material properties (e.g., sand and clay). To make up these limitations, the strain wedge technique (Norris [1986](#page-16-28); Ashour et al. [1998](#page-15-3), [2004;](#page-15-4) Xu et al. [2013](#page-16-29); Yang et al. [2017\)](#page-16-30) has been modifed to evaluate the degraded soil resistance in the mountainside (Peng et al. [2019](#page-16-3), [2020b\)](#page-16-5). It



<span id="page-1-1"></span>**Fig. 2** Laterally loaded pile-soil interaction in the mountainside

envisioned a relationship of the three-dimensional responses of laterally loaded piles to parameters of one-dimensional beam on elastic foundation. As to the latter, theoretical methods are more economically efficient and time-saving in preliminary designs; however, it has been mainly investigated by experiments (Peng et al. [2020a;](#page-16-4) Muthukkumaran [2014](#page-16-20); Zhao et al. [2018](#page-16-31)) and numerical simulations (Ng et al. [2001](#page-16-6); Ng and Zhang [2001;](#page-16-7) Zhang et al. [2008\)](#page-16-8). Hence, the soil wedge assumption (Paik and Salgado [2003](#page-16-32); He et al. [2015\)](#page-15-5) has been employed to evaluate the extra earth pressure behind the laterally loaded pile (Peng et al. [2020b\)](#page-16-5), the magnitude and distribution of which have been mentioned in previously published studies (Ng et al. [2001;](#page-16-6) Ng and Zhang [2001](#page-16-7)). In the assumption, the nonlinear distribution of the extra earth pressure is proposed based on experiments (Tsagareli [1965](#page-16-33); Fang and Ishibashi [1986\)](#page-15-6) and theoretical methods (Wang [2000\)](#page-16-34), difering from the traditional Coulomb and Rankine theory.

This paper is committed to proposing a theoretical method of the safety factor of the slope encapsulating a laterally loaded pile. The safety factor is derived by the object function concerning the external work rate and internal energy dissipation based on kinematic limit analysis, with a log-spiral failure mechanism pre-assumed. The action of the laterally loaded pile on the slope is converted into equivalent resultant lateral force on the potential sliding block. To address the assessment of the critical point depth and lateral force provided by the pile, the modifed strain wedge technique and the soil wedge assumption are adopted to evaluate the soil resistance and extra earth pressure around the pile, respectively. The proposed method is frst substantiated by the cases of the slopes reinforced with anti-slide piles rather than laterally loaded piles (Poulos [1995;](#page-16-13) Cao and Zaman [1999;](#page-15-7) Cai and Ugai [2000](#page-15-8); Wei and Cheng [2009\)](#page-16-35); it is then further validated by comparing with the results of the case with a laterally loaded pile (Ng et al. [2001](#page-16-6)) by finite element limit analysis and fnite element method. In addition to verifcation, the efects of the lateral load atop the pile, pile location, and soil shear strength on slope stability are further investigated by authors. On this basis, an alternative approach for the safety factor of the slope encapsulating a laterally loaded pile can be presented by scaling the safety factor of the slope without the lateral load with the corresponding normalized safety factor.

### **Kinematic limit analysis**

In any kinematically admissible velocity feld, the load determined by the object function consisting of the rate of external work and internal energy dissipation is no less than the actual load at failure (Chen [1975](#page-15-9)), as described in Eq. [\(1](#page-2-0)).

$$
\int_{\Omega} \sigma_{ij} \dot{\epsilon}_{ij} d\Omega \ge \int_{S} T_{i} \nu_{i} dS + \int_{\Omega} X_{i} \nu_{i} d\Omega \tag{1}
$$

where  $\sigma_{ii}$  and  $\dot{\epsilon}_{ii}$  denote the stress tensor and strain rate in the potential sliding block  $Ω$ , respectively;  $T_i$  corresponds to the surcharge on boundary  $S$ ;  $v_i$  refers to the velocity along the velocity discontinuous surface; and  $X_i$  represents the body force.

#### **Failure mechanism**

In the analysis of the pile-slope system, a core step is to fnd a reasonable failure mechanism (kinematically admissible velocity feld). For simplicity, the plane stability of the pile-slope system is evaluated without considering the pile geometry and soil arching efect in this study, although the pile-slope interaction is three-dimensional. As illustrated in Fig. [3](#page-2-1), the log-spiral failure mechanism is frequently used by published studies (Ausilio et al. [2001](#page-15-0); Yang et al. [2004;](#page-16-36) Nian et al. [2008\)](#page-16-37). The failure curve is rotating about the point *O* with varied radius *r* (clockwise is denoted as positive), described by Eq. ([2](#page-2-2)), and intersects the pile at point *P* (critical point). Point *A* and point *B* are the starting point and ending point of the curve, respectively; point *C* and point *D* are the slope toe and crest respectively. Besides,  $\theta$  is the slope angle;  $\theta_A$  is the rotating angle from the horizontal to OA;  $\theta_B$  is the rotating angle from the horizontal to point OB;  $\theta'$  is the angle between DB and BC;  $\theta_1(\theta_2)$  is the rotating angle from the horizontal to the vertical projection pint of point *D* (point *C*) on the curve;  $\theta_{\rm P}$  is the rotating angle from the horizontal to the critical point;  $r_A$  ( $r_B$  and  $r_P$ ) symbolizes the corresponding radius at point *A* (*B* and *P*);  $x<sub>p</sub>$  refers to the horizontal distance between the pile and slope toe;  $H_p$  is the horizontal project of the slope; *H* denotes the slope height; *h* characterizes the total height of the pile above the potential sliding surface.

<span id="page-2-2"></span>
$$
r = r_{A} \exp\left[\left(\theta - \theta_{A}\right) \frac{\tan \varphi}{F \omega}\right]
$$
 (2)



<span id="page-2-1"></span><span id="page-2-0"></span>**Fig. 3** Pre-assumed log-spiral failure mechanism

The factor of safety (*FoS*) is generally defned concerning the shear strength of soil (internal friction angle *φ* and cohesion *c*), as shown in Eq.  $(3)$  $(3)$ .

$$
F \circ S = \frac{c}{c'} = \frac{\tan \varphi}{\tan \varphi'}
$$
 (3)

where *φ*′ and *c*′ are the mobilized friction angle and cohesion at failure.

#### **Objective function**

The objective function of the rate of external work and internal energy dissipation is constructed by kinematic limit analysis. The specifc derivations of components of the objective function are expressed below.

#### **External work rate**

The external work rate produced by the soil self-weight consists of four components, as given in Eq. ([4\)](#page-3-1).

$$
\dot{W}_{\gamma} = \gamma w r_{\rm A}^3 (f_1 - f_2 - f_3 - f_4) \tag{4}
$$

where  $\gamma$  denotes the unit weight of soil; *w* symbolizes the angular velocity of the potential sliding block; and  $f_1, f_2, f_3$ , and  $f_4$  are geometry-dependent non-dimensional functions of the block concerning sections OAB, OAD, OBD, and BCD, respectively. The specific expressions of the four components could be given below (Qin et al. [2017](#page-16-16)).

$$
f_1 = \frac{\tan \varphi'}{1 + 9 \tan^2 \varphi'} \left\{ \left( \cos \theta_B + \frac{\sin \theta_B}{3 \tan \varphi'} \right) \exp \left[ 3(\theta_B - \theta_A) \right] \right\}
$$
  

$$
\tan \varphi' \left] - \left( \cos \theta_A + \frac{\sin \theta_A}{3 \tan \varphi'} \right) \right\}
$$
(5)

$$
f_2 = \frac{1}{6} \frac{L \sin \theta_A}{r_A} \left( 2 \cos \theta_A - \frac{L}{r_A} \right)
$$
 (6)

$$
f_3 = \frac{\exp\left[(\theta_B - \theta_A)\tan\varphi'\right]}{6} \left[\sin\left(\theta_B - \theta_A\right) - \frac{L}{r_A}\sin\theta_B\right] \left[\cos\theta_A - \frac{L}{r_A} + \cos\theta_B\exp\left[(\theta_B - \theta_A)\tan\varphi'\right]\right]
$$
(7)

$$
f_4 = \left(\frac{H}{r_A}\right)^2 \frac{\sin(\theta - \theta')}{2 \sin \theta \sin \theta'}
$$
  
\n
$$
\left[\cos \theta_A - \frac{L}{r_A} - \frac{1}{3} \frac{H}{r_A} \left(\cot \theta + \cot \theta'\right)\right]
$$
 (8)

where *L* refers to the distance between point *A* and point *D*.

#### **Internal energy dissipation rate**

The internal energy dissipation rate is derived as follows.

$$
\dot{W}_{D1} = \int_{\theta_{\rm A}}^{\theta_{\rm B}} c(V \cos \varphi) \frac{r d\theta}{\cos \varphi} = c w r_{\rm A}^2 f_5 \tag{9}
$$

<span id="page-3-0"></span>
$$
f_5 = \frac{\exp\left[2(\theta_B - \theta_A)\tan\varphi'\right] - 1}{2\tan\varphi'}\tag{10}
$$

Moreover, the slope safety factor would be afected by the laterally loaded pile (Ng et al. [2001](#page-16-6)), and the pile action should be incorporated as a resultant lateral force *F* and moment exerted on a possible sliding block at the depth of the critical point. The dissipation rate of the resultant lateral force and moment can be then given as:

<span id="page-3-2"></span>
$$
\dot{W}_{D2} = Fr_A \sin \theta_P w \exp \left[ (\theta_P - \theta_A) \tan \varphi' \right] - F_X h w \tag{11}
$$

where  $\chi$  is a ratio of the distance between the critical point and action point of resultant force to the overall *h*.

Some geometric parameters in the formulas mentioned above could be obtained from the failure mechanism and the relative position of the pile and slope.

<span id="page-3-1"></span>
$$
h = r_{\rm P} \sin \theta_{\rm P} - r_{\rm B} \sin \theta_{\rm B} + x_{\rm P} \tan \theta \tag{12}
$$

$$
x_{\rm P} = r_{\rm P} \cos \theta_{\rm P} - r_{\rm B} \cos \theta_{\rm B} - d \tag{13}
$$

$$
d = \frac{\sin(\theta - \theta')}{\sin \theta \sin \theta'} H
$$
 (14)

where *d* is the length of line BC.

<span id="page-3-3"></span>As a consequence, the total energy dissipation rate is given as:

$$
\dot{W}_D = \dot{W}_{D1} + \dot{W}_{D2} \tag{15}
$$

Based on the kinematic limit analysis, the total external work rate equals the overall energy dissipation rate.

<span id="page-3-4"></span>
$$
\dot{W}_{\gamma} = \dot{W}_D \tag{16}
$$

Above all, the safety factor of the slope encapsulating a laterally loaded pile could be evaluated by Eq. [\(3\)](#page-3-0), and the signifcative parameters ( $\varphi'$  and  $c'$ ) in the equation would be determined by substituting Eqs.  $(4-11)$  $(4-11)$  and Eq.  $(15)$  $(15)$  $(15)$  into Eq.  $(16)$  $(16)$  $(16)$ .

# **Solutions for critical point depth and resultant force**

The core issue in the stability analysis of the slope encapsulating a laterally loaded pile is the assessment of the critical point depth and resultant lateral force provided by the pile. In this study, the critical point is assumed as the point where the lateral defection of piles is zero. The detailed derivation is elaborated below by employing the modifed strain wedge technique and the soil wedge assumption (Fig. [4](#page-4-0)).



<span id="page-4-0"></span>**Fig. 4** Strain wedge in front of the pile and soil wedge behind the pile

### **Governing equation**

The governing equation for the laterally loaded pile in the mountainside is given as:

$$
EI\left(\frac{d^4y}{dz^4}\right) + p(z) - q(z) = 0\tag{17}
$$

where *EI* symbolizes the fexural rigidity of the pile; *y* is the pile deflection;  $p(z)$  is the soil resistance below the critical point (evaluated by the beam on elastic foundation method) or the degraded soil resistance above the critical point (quantifed by the modifed strain wedge technique); and  $q(z)$  is the extra earth pressure (estimated by the soil wedge assumption).

<span id="page-4-1"></span>

#### **Modifed strain wedge technique**

The original strain wedge technique (Norris [1986;](#page-16-28) Ashour et al. [1998,](#page-15-3) [2004](#page-15-4)) was presented to evaluate the soil resistance in front of the laterally loaded pile in the level ground (Fig. [5](#page-4-1)a). In the technique, the strain wedge was characterized as three main parameters (base angle  $\beta_m$ , fan angle  $\varphi_m$ , and strain wedge depth *h*). Thereinto, the base angle and fan angle satisfy the assumption,  $\beta_m = \pi/4 + \varphi_m/2$ ; the fan angle depends on the mobilization of soil strength within the strain wedge, and the strain wedge depth is equal to the critical point depth. All of them are variable with the lateral load at the pile head and estimated by iterative procedures. Whereafter, the technique has been modifed to estimate the degraded soil resistance in front of the laterally loaded pile in the mountainside (Peng et al. [2019,](#page-16-3) [2020b](#page-16-5)), as illustrated in Fig. [5b](#page-4-1) where *D* denotes the width (diameter) of a square (circular) pile;  $Z_0$  represents the intersection depth of the far surface (plane  $B_0B_1C_1C_0$ ) and slope surface (plane  $B_0B_2C_2C_0$ ; and the depth of the intersection of the  $(j-1)$ th and *j*th sublayer strain wedge is marked as  $Z_j$ ,  $j = 1, 2, ..., n$ .

<span id="page-4-2"></span>Besides, the linearized defection assumption (Ashour et al. [1998](#page-15-3)) was employed in the analysis of the performance of the long fexible pile as well as that of the short rigid pile. The pile defection was considered linear above the critical point (Fig. [6\)](#page-5-0), and other details about the strain wedge technique were detailed in Ref. (Ashour et al. [1998](#page-15-3), [2004](#page-15-4)) where *δ* denotes the linearized deflection angle and  $y_0$  is the deflection at the pile head.

Furthermore, the soil above each sublayer strain wedge is abstracted as the uniformly distributed load *q*, and the stress status within the strain wedge satisfes the static equilibrium equation in the lateral direction, Eq. ([18\)](#page-5-1), as depicted in the elevation view and plan view (Fig. [7\)](#page-5-2).





<span id="page-5-0"></span>**Fig. 6** Linearized defection assumption and correlative strain wedge

$$
p(z) = \Delta \sigma_i L(z) S_1 + 2\tau D S_2 \tag{18}
$$

where  $Y_0$  denotes the horizontal distance from the intersection of the slope surface and far surface to the pile;  $\sigma_{vi}(z)$ and  $\Delta \sigma_i$  symbolize the effective vertical stress and lateral stress increment, respectively; *τ* symbolizes the side friction (Ashour et al.  $1998$ );  $L(z)$  denotes the width of far surface; and  $S_1$  and  $S_2$  are pile shape coefficients (Briaud et al. [1984](#page-15-10)).

#### **Geometry parameters**

The base angles  $\beta_{m,j}$  and fan angle  $\varphi_{m,j}$  of different sublayer strain wedges satisfy the assumption,  $\beta_m = \pi/4 + \varphi_m/2$ .

$$
\beta_{\mathrm{m},j} = \frac{\pi}{4} + \frac{\varphi_{\mathrm{m},j}}{2} \tag{19}
$$

The depth  $Z_0$  and  $Z_j$  could then be defined by the wedge geometry.

$$
Z_0 + \frac{Z_0}{\tan \theta} = h \tag{20}
$$

$$
Z_j + \frac{Z_j}{\tan \theta} = Z_{j-1} \tag{21}
$$

Finally, the far surface width  $L(z)$  is given as:

$$
L(z) = D + 2(h - z) \tan \beta_m \tan \varphi_m \ (z < Z_0) \tag{22}
$$

$$
L(z) = D + \frac{2z \tan \varphi_m}{\tan \theta} \left( z < Z_0 \right) \tag{23}
$$

#### **Stress state**

The effective vertical stress  $\sigma_{vi}(z)$  above different sublayer strain wedges is derived by Eqs.  $(24)$  and  $(25)$  $(25)$ .

<span id="page-5-3"></span>
$$
\sigma_{vi}(z) = \gamma \left(z - \frac{z_0}{2}\right) \left(z \ge Z_0\right) \tag{24}
$$

<span id="page-5-4"></span><span id="page-5-1"></span>
$$
\sigma_{vi}(z) = \gamma \left(z - \frac{z_j}{2}\right) \left(Z_{j-1} \ge z \ge Z_j, j \ge 1\right)
$$
\n(25)

The lateral stress increment and side friction are written as Eqs. ([26\)](#page-5-5) and ([27\)](#page-5-6).

<span id="page-5-5"></span>
$$
\Delta \sigma_i = \sigma_{vi} \left[ \tan^2 \left( \frac{\pi}{4} + \frac{\varphi_m}{2} \right) - 1 \right]
$$
 (26)

<span id="page-5-6"></span>
$$
\tau = \sigma_{\rm vi} \tan \varphi_{\rm m} \tag{27}
$$

In the strain wedge technique, the stress level (*SL*), expressed as Eq. [\(28](#page-6-0)), had been employed to characterize the relationship

<span id="page-5-2"></span>





<span id="page-6-1"></span>**Fig. 8** Mobilized efective friction angle varied with lateral stress: **a** sand; **b** *c*-*φ* soil

between the stress state of soil before yielding and the yield state. It can also defne the fan angle characterizing the geometry of strain wedge, and the fan angle equals the mobilized efective friction angle of soil (Fig. [8](#page-6-1)), varied with the lateral stress. The other details of *SL* were sketched in Appendix [1.](#page-13-0)

$$
SL = \frac{\Delta \sigma_i}{\Delta \sigma_{\text{hf}}} = \frac{\tan^2 (\pi/4 + \varphi_{\text{m}}/2) - 1}{\tan^2 (\pi/4 + \varphi/2) - 1}
$$
(28)

$$
\Delta \sigma_{\rm hf} = \sigma_{\rm v0} \left[ \tan^2 \left( \frac{\pi}{4} + \frac{\varphi}{2} \right) - 1 \right] \tag{29}
$$

where  $\Delta \sigma_{\text{hf}}$  and  $\sigma_{\text{v0}}$  represent the lateral stress increment and vertical stress in the yield status.

#### **Soil wedge assumption**

To estimate the extra earth pressure, the soil wedge assumption (Peng et al. [2020b](#page-16-5); Paik and Salgado [2003](#page-16-32); He et al. [2015](#page-15-5)) is utilized in this study. In the assumption, two points should be noted: (i) the soil wedge depth is regarded as the critical point depth; (ii) and the soil wedge width can be considered equal to the width of the laterally loaded pile.

#### **Soil wedge concept**

The slip plane of the soil wedge behind the pile is of an angle  $\theta_0$  to the horizontal (Fig. [9\)](#page-6-2). The expressions of the angle  $\theta_0$  and  $\beta_0$  (the angle between the slip plane and slope surface equals to  $\theta_0$ - $\theta$ ) could be estimated by the stress state of the diferential element of the pile and corresponding Mohr's circle, detailed in Ref. (He et al. [2015](#page-15-5)).

$$
\beta_0 = \frac{1}{2} \left( \varphi - \theta + \arccos \frac{\sin \theta}{\sin \varphi} \right) \tag{30}
$$

$$
\theta_0 = \frac{1}{2} \left( \varphi + \theta + \arccos \frac{\sin \theta}{\sin \varphi} \right)
$$
 (31)

#### **Lateral earth pressure**

<span id="page-6-0"></span>To investigate the lateral earth pressure within the soil wedge, it is sliced into many diferential elements (Fig. [10](#page-7-0)). The path line (dotted line) of minor principal stress  $\sigma_3$  is assumed as an arc with radius *R*. As to the major principal stress  $\sigma_1$ , it is perpendicular to the arc (Fig. [10](#page-7-0)a) where *S* symbolizes the differential element length,  $S = (H - z)\cos\theta_0$ sin*β*; d*V*′ represents a component of the diferential stress d*V*, and *V*′ symbolizes the resultant of d*V*′, perpendicular to line  $E_0P$ ;  $\psi$  represents the angle between the normal line OD and the horizontal;  $\omega$  is the angle between the normal line OP and the vertical,  $\omega = 0$ ;  $\theta_w$  is the angle between the normal line OJ and the horizontal,  $\theta_w = \pi/4 + \varphi/2$ ; and  $\xi$  refers



<span id="page-6-2"></span>**Fig. 9** Elevation view of the soil wedge

<span id="page-7-0"></span>**Fig. 10** Principal stress on a diferential element: **a** minor and major principal stresses; **b** vertical force



(a) Major and minor principal stress

(b) Schematic of the vertical force

to the angle between the normal line OQ and the vertical, derived as Eq.  $(32)$  $(32)$ .

$$
\xi = \frac{\pi}{4} + \frac{\varphi}{2} - \theta_0 = \frac{1}{2} \left( \frac{\pi}{2} - \theta - \cos^{-1} \frac{\sin \theta}{\sin \varphi} \right)
$$
(32)

The lateral earth pressure coefficient  $K_{an}$  and mean vertical stress  $\overline{\sigma}_v$  are given by Eqs. [\(33\)](#page-7-2) and ([34](#page-7-3)), respectively, the derivations of which are written in Appendices [2](#page-13-0) and [3.](#page-15-11)

$$
K_{\rm an} = \frac{\sigma_{\rm h}}{\tilde{\sigma}_{\rm v}} = \frac{\cos\left(\theta_{\rm w} + \xi\right)\cos\theta}{\cos\left(\theta + \xi\right)\cos\theta_{\omega}} \cdot \frac{3\left(N\cos^2\theta_{\rm w} + \sin^2\theta_{\rm w}\right)}{3N - (N-1)\cos^2\theta_{\rm w}}
$$
(33)

$$
\overline{\sigma}_{\rm v} = \frac{\gamma h \cos \theta}{1 - (K_{\rm an} \tan \varphi - K_{\rm an} \tan \theta + m_0) \frac{\sin \beta_0}{\cos \theta_0}} \times \left[ \left( 1 - \frac{z}{h} \right)^{(K_{\rm an} \tan \varphi - K_{\rm an} \tan \theta + m_0) \frac{\sin \beta_0}{\cos \theta_0}} - \left( 1 - \frac{z}{h} \right) \right] \tag{34}
$$

$$
m_0 = \frac{K_{\text{an}} \sin \xi \cos \theta}{\left(N \cos^2 \theta_w + \sin^2 \theta_w\right) \cos \left(\xi + \theta\right)}
$$
(35)

The lateral earth pressure  $\sigma_h$  is derived by multiplying  $\overline{\sigma}_v$ by  $K_{\text{an}}$ .

$$
\sigma_{\rm h} = \frac{K_{\rm an} \gamma h \cos \theta}{1 - (K_{\rm an} \tan \varphi - K_{\rm an} \tan \theta + m_0) \frac{\sin \beta_0}{\cos \theta_0}} \times \left[ \left( 1 - \frac{z}{h} \right)^{(K_{\rm an} \tan \varphi - K_{\rm an} \tan \theta + m_0) \frac{\sin \beta_0}{\cos \theta_0}} - \left( 1 - \frac{z}{h} \right) \right]
$$
(36)

### **Iterative solution**

The critical point depth and resultant lateral force provided by the laterally loaded pile could be derived by the governing

<span id="page-7-1"></span>equation, Eq. [\(17](#page-4-2)), adopting the modifed strain wedge technique (Peng et al. [2019](#page-16-3), [2020b\)](#page-16-5) and soil wedge assumption (Ashour et al. [1998\)](#page-15-3). The iterative procedures are illustrated in Fig. [11](#page-7-4). Thereinto, the governing equation, Eq. [\(17](#page-4-2)), would be handled by substituting Eqs.  $(18)$  and  $(36)$  $(36)$  $(36)$ . The deflection at the pile top obtained from Eq.  $(17)$  $(17)$  is labeled as  $y_0$ ,

<span id="page-7-3"></span><span id="page-7-2"></span>

<span id="page-7-4"></span>**Fig. 11** Iterative procedure

<span id="page-7-5"></span>**STOP OUTPUT DATA**  $y(z)$ 



<span id="page-8-0"></span>**Fig. 12** Nonlinearized defection pattern of the pile

whereas an alternative pile head defection, evaluated by the deflection pattern  $\delta$  and soil strain  $\varepsilon$ , is labeled as  $(y_0)_{\text{sw}}$ . Likewise,  $y_j$  refers to the lateral displacement of piles at depth  $Z_j$  obtained from by Eq. ([17\)](#page-4-2), whereas  $(y_j)_{SW}$  is estimated by the strain wedge length  $Y_j$  and soil strain  $\varepsilon$ . The nonlinear defection pattern of the laterally loaded pile in the mountainside is depicted in Figs. [12](#page-8-0) and [13](#page-8-1).

# **Case studies**

To verify the proposed method, some cases of slopes without a laterally loaded pile (Poulos [1995](#page-16-13); Cao and Zaman [1999](#page-15-7); Cai and Ugai [2000](#page-15-8); Wei and Cheng [2009](#page-16-35)) and the case of the slope encapsulating a laterally loaded pile (Ng et al. [2001\)](#page-16-6) have been quoted.



The example slopes are composed of homogeneous materials, and the slope height, slope angle, and material parameters are listed in Table [1](#page-9-0). A row of stabilizing piles would be required in the slopes (the pile location,  $x_n$ , is detailed in the references) since the initial safety factors of the slope are inadequate. Employing the proposed method, the safety factors of these slopes are evaluated and listed in Table [2](#page-9-1). It indicates that the proposed method is capable of predicting the safety factor of the slope considering the pile efect.

### **Slope encapsulating a laterally loaded pile**

The slope is 15 m high with a slope angle of 32°, and the mechanical properties of the pile-soil system are illustrated in Fig. [14](#page-9-2). The diameter and length of the laterally loaded pile are 2 m and 30 m, respectively, ignoring the efect of groundwater. The ultimate shear capacity of the pile is specifed as  $V_u = 0.8 f_c^{0.5} A$  ( $f_c$  denotes the concrete compressive strength,  $f_c = 45$  MPa; *A* refers to the pile cross-section area) (British Standards Institution [1985\)](#page-15-12). To investigate the slope stability and failure mechanism, the lateral loads  $V = 0.03, 0.06, 0.12$ , and  $0.36V<sub>u</sub>$  are applied to the pile head in the analysis (the design load is  $0.12V<sub>u</sub>$ ). The predicted safety factors are compared with those from published literature, shown in Table [3.](#page-10-0)

Table [3](#page-10-0) indicates that the safety factors of the slope under diferent lateral loads evaluated by the proposed method are reasonably consistent with those obtained from the published study (Ng et al. [2001\)](#page-16-6) and the fnite element limit analysis program, OptumG2 (Optum Computational Engineering [2017](#page-16-38)) whose procedure is detailed in Appendix [4.](#page-15-11) It proves that the proposed method can well predict the stability of the slope

<span id="page-8-1"></span>

example slopes

<span id="page-9-0"></span>**Table 1** Parameters of these



<span id="page-9-1"></span>**Table 2** Comparisons between results evaluated by the proposed approach and references



<span id="page-9-2"></span>



encapsulating a laterally loaded pile as well as the fnite element limit analysis. As expected, the safety factor of the slope reinforced with anti-slide piles (lateral load is zero) is greater than that of the unreinforced condition (the factor of safety increases from 1.90 to 2.0). It can be ascribed to an extra resisting moment provided by the pile when the lateral load equals zero, and the slope stability would be improved by the pile. It should be noted that the slope is unsafe when the lateral load

<span id="page-10-0"></span>

reaches  $0.36V_{\text{u}}$ , and the exact safety factor of the slope had not been evaluated, but simply considered a value less than 1.0 (Ng et al. [2001](#page-16-6)). Furthermore, the evolution of the safety factor of the slope encapsulating a laterally loaded pile revealed in Table [3](#page-10-0) indicates that the slope would develop into instability with lateral loads atop the pile; the safety factor of the slope encapsulating the pile would signifcantly decrease with lateral loads, and it is approximately reduced by 40%, while the lateral load at the pile head increases from 0 to  $0.12V<sub>u</sub>$ .

# **Discussion**

The effect of the lateral load at the pile head on the slope failure mechanism and safety factor is investigated below. The classical failure mechanism of the slope encapsulating a laterally loaded pile is visualized by finite element limit analysis (Figs. [15](#page-10-1))

and [16](#page-10-2)). The diferent magnitudes of the plastic multiplier are characterized by diferent colors, and the variation of the color from blue to red indicates the increase of the plastic multiplier. The global potential sliding surface starts from the slope toe and extends to the slope crest, and two local failures of wedgeshaped regions occur around the laterally loaded pile; thereinto, the wedge-shaped region in front of the pile would increase with lateral loads and the distance from the slope toe, and the failure mechanism under small lateral load conditions is similar to that of the slope reinforced with anti-slide piles. These observations prove the rationality of the log-spiral failure mechanism (Fig. [3\)](#page-2-1), the strain wedge technique, and soil wedge assumption (Fig. [4\)](#page-4-0).

To better interpret the efect of the lateral load atop the pile and the pile location on the factor of safety, the normalized safety factor  $\eta$  and normalized lateral load  $\alpha$  have been proposed. The former represents the ratio of the safety factor with the lateral load  $(FoS_1)$  to the one without the lateral load

<span id="page-10-2"></span><span id="page-10-1"></span>



<span id="page-11-0"></span>**Fig.** 17 Relationship between the normalized safety factor and normalized lateral load under different shear strengths: **a**  $x_p/H_p = 1/6$ ; **b**  $x_p/H_p =$ 1/4; **c**  $x_p/H_p = 1/3$ ; **d**  $x_p/H_p = 1/2$ ; **e**  $x_p/H_p = 3/4$ ; and **f**  $x_p/H_p = 1$ 

 $(FoS<sub>0</sub>), \eta = FoS<sub>1</sub>/FoS<sub>0</sub>$ ; the latter denotes the ratio of the lateral load (*V*) applied on the pile head to the ultimate shear capacity  $(V_{\rm u})$ ,  $\alpha = V/V_{\rm u}$ . Then, the normalized safety factor  $\eta$  decreases from 0.59 to 0.37 while the normalized lateral load *α* increases from 0.12 to 0.36 in the case (Ng et al. [2001](#page-16-6)). Furthermore, plenty of cases ( $\alpha$  = 0, 0.03, 0.06, 0.09, and 0.12;  $x_p/H_p = 1/6$ , 1/4, 1/3, 1/2, ¾, and 1; *φ* = 15°, 20°, 25°, 30°, and 35°; *c*/*γD* = 0.25, 0.5, 0.75, and 1) are supplemented for a parametric study based on the original case (Ng et al. [2001\)](#page-16-6), and the predictions of normalized safety factors *η* are illustrated in Fig. [17.](#page-11-0) The normalized safety factor, together with the safety factor of the slope, is observed to nonlinearly decrease with normalized lateral loads. It is therefore necessary to consider the efect of lateral loads on slope stability in the design of engineering practice. Furthermore, the variations of normalized safety factors with normalized lateral loads can be ftted by cubic functions (Fig. [17](#page-11-0)). The diferences between the predictions of normalized safety factors and those on ftting curves are mostly less than 0.1, except for the cases of extremely small shear strength  $\left(\frac{c}{\gamma D} = 0.25\right)$ , and the reason for the exceptions is that the slope is already unstable even without the lateral load. In addition, the normalized safety factor is positively correlated with  $x_p/H_p$ , revealing that the effect of lateral loads on the slope stability would be weakened while the pile location moves from the slope toe to the slope crest. It can be also observed that the normalized safety factor mainly depends on the lateral load and pile location but is not sensitive to the shear strength; hence, the results and corresponding ftting curves can be generalized to cases of other shear strengths.

Based on these aforementioned analyses, an alternative approach to assess the safety factor of the slope encapsulating a laterally loaded pile has been provided. It can be predicted by scaling the relatively easily obtained safety factor of the slope without the lateral load (i.e., the slope reinforced with antislide piles) with the corresponding normalized safety factor. By this means, the evaluation of the safety factor of the slope encapsulating a laterally loaded pile can be simplifed by avoiding the derivation of the critical point depth and the resultant force provided by the pile. It is noteworthy that the prediction method of normalized safety factor has been not reported yet and could be estimated by the proposed method in this work. Cases of normalized safety factors under diferent conditions (e.g., pile diameter, pile location, and slope inclination) providing more useful information for the preliminary engineering design would be further investigated in subsequent research.

# **Conclusions**

A theoretical method of the safety factor of the slope encapsulating a laterally loaded pile has been proposed by introducing the modifed strain wedge technique and soil wedge assumptions to evaluate the soil resistance and extra earth pressure around the pile, respectively. After verifying the proposed method, the efect of the lateral load atop the pile, pile location, and soil shear strength on the safety factor of the slope encapsulating a laterally loaded pile is extensively investigated under diferent conditions. Several conclusions are listed as follows:

- (i) The safety factors of some cases evaluated by the proposed theoretical method are in good agreement with those obtained from published studies and numerical simulations. It proves that the proposed method can well evaluate the safety factor of the slope encapsulating a laterally loaded pile.
- (ii) The failure mechanism under the minute lateral load is similar to that of the slope reinforced with anti-slide piles, but for cases of greater lateral load, the lateral load transferred from the pile to the slope would further result in the local failure. Local failures of two wedge-shaped regions observed around the laterally loaded pile in the numerical simulations suggest the applicability of the strain wedge technique and soil wedge assumption; thereinto, the wedge-shaped region in front of the pile would increase with lateral loads.
- (iii) The normalized safety factor, together with the safety factor of the slope, is observed to nonlinearly decrease with normalized lateral loads; the variations of normalized safety factors with normalized lateral loads can be fitted by cubic functions. In addition, the normalized safety factor, not sensitive to the shear strength, mainly depends on the lateral load and pile location, and it is positively correlated with  $x_p/H_p$ , revealing that the efect of lateral loads on the slope stability would be weakened while the pile location moves from the slope toe to the slope crest.
- (iv) The safety factor of the slope encapsulating a laterally loaded pile can be alternatively obtained by scaling the safety factor of the slope without the lateral load with the corresponding normalized safety factor. By this means, the evaluation of the safety factor of the slope encapsulating a laterally loaded pile can be simplifed by avoiding the derivation of the critical point depth and the resultant force provided by the pile, which is useful for the preliminary engineering design.

### **Appendix 1 Stress level**

The relationship between the stress level *SL* and soil strain *ε* was observed from isotropically consolidated drained and undrained triaxial tests (Ashour et al. [1998\)](#page-15-3). It can be sketched in Fig. [18](#page-13-1) and given as Eqs.  $(37)$  $(37)$  to  $(39)$  $(39)$  $(39)$ .

$$
SL_i = \frac{3.19\epsilon}{(\epsilon_{50})_i} \exp\left(-3.707SL_i\right) \text{ (Stage I } \epsilon \le \epsilon_{50}\text{)}\tag{37}
$$

$$
SL_i = \frac{\lambda_i \varepsilon}{(\varepsilon_{s0})_i} \exp\left(-3.707SL_i\right) \text{ (Stage II } \varepsilon_{50} < \varepsilon \le \varepsilon_{80}\text{)}
$$
\n
$$
\tag{38}
$$

$$
SL_i = \exp\left[\ln 0.2 + \frac{100\epsilon}{m\epsilon + q_i}\right] \text{ (Stage III } \epsilon > \epsilon_{80}) \tag{39}
$$

where  $\varepsilon_{50}$  denotes the soil strain at 50% stress level;  $\lambda_i$  varies linearly from 3.19 ( $SL = 0.5$ ) to 2.14 ( $SL = 0.8$ ); and  $m =$ 59.0 and  $q_i = 95.4 \varepsilon_{50}$ .

### <span id="page-13-0"></span>**Appendix 2 Lateral earth pressure coefficient**

On the one hand, the lateral stress at point  $E_0$  (Fig. [10](#page-7-0)),  $\sigma_h$ , was obtained based on the stress equilibrium equation.

$$
\sigma_{\rm h} = \sigma_1 \cos^2 \beta_0 + \sigma_3 \sin^2 \beta_0 \tag{40}
$$

Likewise, the lateral stress at point D (Fig. [10](#page-7-0)),  $\sigma_{ab}$ , was also obtained as follows:

$$
\sigma_{\rm ah} = \sigma_1 \cos^2 \psi + \sigma_3 \sin^2 \psi \tag{41}
$$

Substituting  $\sigma_3/\sigma_1 = 1/N$  into Eq. [\(41\)](#page-13-4), the lateral stress *σ*ah could be rearranged as:

$$
\sigma_{\rm ah} = \left(\cos^2 \psi + \frac{1}{N} \sin^2 \psi\right) \sigma_1 \tag{42}
$$

where  $N = \tan^2(\pi/4 + \varphi/2)$ .

On the other hand, the vertical stress applied to the diferential element  $E_0$ JPQ was evaluated, including two components



<span id="page-13-2"></span>(Fig. [19\)](#page-13-5): (i) vertical stress applied to the quadrangle diferential element  $E_0$ J $G_0$ Q; (ii) the minor and major principal stresses on the triangular differential element  $G_0PQ$  where  $\sigma_v$  is the vertical stress applied on the diferential element, consisting of  $\sigma_f$  and  $\sigma'$ <sub>v</sub>; the former is parallel to line  $E_0G_0$ , and the latter is perpendicular to line  $E_0G_0$ , derived as:

<span id="page-13-6"></span><span id="page-13-3"></span>
$$
\frac{\sigma'_{\rm v}}{\sigma_{\rm v}} = \cos \theta \tag{43}
$$

Substituting that  $\sigma_v + \sigma_{ah} = \sigma_1 + \sigma_3$ , Eq. [\(43](#page-13-6)) could be given as Eq. [\(44](#page-13-7)):

<span id="page-13-7"></span>
$$
\frac{\sigma'_{v}}{\sigma_{1}} = \cos \theta \left( \sin^{2} \psi + \frac{1}{N} \cos^{2} \psi \right)
$$
 (44)

For simplification,  $\sigma'_{v}$  can be replaced by mean stress  $\sigma'$ (Fig. [20\)](#page-14-0) where  $h_0 = \cos\theta \, dz$ ;  $\sigma_3$  and  $\sigma_{3v}$  are the minor principal stress on the line  $G_0Q$  and its vertical component.

<span id="page-13-8"></span>
$$
\overline{\sigma'}_{\rm v} = \frac{V'}{S} \tag{45}
$$

where

<span id="page-13-4"></span>
$$
V' = \int_{\theta_{\omega}}^{\pi/2 - \omega} dV' = \int_{\theta_{\omega}}^{\pi/2 - \omega} \sigma_1 R \sin \psi \left( \sin^2 \psi + \frac{1}{N} \cos^2 \psi \right) d\psi
$$
\n(46)

<span id="page-13-10"></span>
$$
S = \frac{\cos\left(\theta_w + \xi\right)}{\cos\left(\theta + \xi\right)}R\tag{47}
$$

<span id="page-13-9"></span>Then, Eq. [\(45](#page-13-8)) could be rewritten as follows:

$$
\overline{\sigma'}_{v} = \frac{\cos(\theta + \xi)}{\cos(\theta_w + \xi)} \cos \theta_{\omega} \left( 1 - \frac{N - 1}{3N} \cos^2 \theta_{\omega} \right) \sigma_1 \tag{48}
$$

The average vertical stress  $\bar{\sigma}_v$  on the differential element could be given as Eq. ([49\)](#page-14-1).

<span id="page-13-5"></span>

<span id="page-13-1"></span>**Fig. 18** Relationship between stress level and soil strain **Fig. 19** Stress status on the quadrangle differential element E<sub>0</sub>JG<sub>0</sub>Q

<span id="page-14-4"></span>



<span id="page-14-0"></span>**Fig. 20** Stress status on the main part of the diferential element

$$
\tilde{\sigma}_{\rm v} = \frac{\overline{\sigma'}_{\rm v}}{\cos \theta} \tag{49}
$$

Substituting Eq. [\(48\)](#page-13-9) into Eq. ([49](#page-14-1)), it could be finally obtained as:

$$
\overline{\sigma}_{v} = \frac{\cos(\theta + \xi)}{\cos(\theta_{w} + \xi)\cos\theta} \cos\theta_{\omega} \left(1 - \frac{N-1}{3N}\cos^{2}\theta_{\omega}\right) \sigma_{1}
$$
\n(50)

Above all, the lateral earth pressure coefficient  $K_{an}$  is given by Eqs.  $(42)$  $(42)$  $(42)$  and  $(50)$  $(50)$  $(50)$ .

$$
K_{\rm an} = \frac{\sigma_{\rm h}}{\tilde{\sigma}_{\rm v}} = \frac{\cos\left(\theta_{\rm w} + \xi\right)\cos\theta}{\cos\left(\theta + \xi\right)\cos\theta_{\rm w}} \cdot \frac{3\left(N\cos^2\theta_{\rm w} + \sin^2\theta_{\rm w}\right)}{3N - (N - 1)\cos^2\theta_{\rm w}}
$$
(51)

# **Appendix 3 Vertical stress**

To further investigate the vertical stress within the soil wedge, the triangular element  $G_0PQ$  assumed to be in the equilibrium status can be neglected in the analysis of the diferential element E<sub>0</sub>JPQ. The minor principal stress on the line  $G_0Q \sigma_3$  and its vertical component  $\sigma_{3v}$  are derived as:

$$
\sigma_3 = \frac{K_{\text{an}}}{N \cos^2 \theta_w + \sin^2 \theta_w} \overline{\sigma}_v
$$
\n(52)

$$
\sigma_{3v} = \sigma_3 \sin \xi \frac{\cos \theta}{\cos (\xi + \theta)}
$$
(53)

The shear stress on the differential element  $E_0JG_0Q$ (Fig. [10\)](#page-7-0) can be regarded as:

 $\tau = \sigma_{h} \tan \varphi = \overline{\sigma}_{v} K_{an} \tan \varphi$  (54)

<span id="page-14-1"></span>The equilibrium equation of the differential element  $E_0$ JMQ in the vertical can be derived as Eq. [\(55\)](#page-14-3), ignoring the vertical stress on the line  $MG_0$ .

$$
DSd\overline{\sigma}_{v} + DK_{an}\overline{\sigma}_{v} \tan \varphi dz - DK_{an}\overline{\sigma}_{v} \tan \theta dz
$$
  
+ 
$$
D\sigma_{3} \frac{\sin \xi \cos \theta}{\cos (\xi + \theta)} dz = DSh_{0}\gamma
$$
 (55)

<span id="page-14-3"></span>Substituting Eq. ([52\)](#page-14-4) into Eq. [\(55](#page-14-3)),  $\overline{\sigma}_v$  is obtained as:

<span id="page-14-2"></span>
$$
\overline{\sigma}_{\rm v} = \frac{\gamma h \cos \theta}{1 - (K_{\rm an} \tan \varphi - K_{\rm an} \tan \theta + m_0) \frac{\sin \theta_0}{\cos \theta_0}} \times \left[ \left( 1 - \frac{z}{h} \right)^{(K_{\rm an} \tan \varphi - K_{\rm an} \tan \theta + m_0) \frac{\sin \theta_0}{\cos \theta_0}} - \left( 1 - \frac{z}{h} \right) \right] \tag{56}
$$



<span id="page-14-5"></span>**Fig. 21** Finite element limit analysis: (**a**) boundary condition and load condition; (**b**) adaptive remeshing technique

### <span id="page-15-11"></span>**Appendix 4 Procedure of the fnite element limit analysis**

The common procedures of fnite element limit analysis are elaborated below (Fig. [21](#page-14-5)):

- i) Establish the numerical model according to the geometric confguration of the pile-slope system, considering the boundary efect, while the slope and the pile (freehead and fxed-end) are modeled as the Mohr–Coulomb material (associated fow rule) and the linear elastic material, respectively.
- ii) The boundary condition is selected as the standard boundary condition, that is, the lateral displacement is constrained at the left and right boundaries of the model, and the bottom of the model is fxed; the lateral load atop the pile could be applied as the distributed load (Fig. [21a](#page-14-5)).
- iii) The total element number and initial element number are 10,000 and 1000, respectively; and the adaptive remeshing technique is adopted in the analysis (Fig. [21](#page-14-5)b).

**Notations**  $σ_{ij}$ : Stress tensor;  $ε$ : Soil strain;  $\dot{ε}_{ij}$ : Strain rate; Ω: Volume of the potential sliding block;  $T_i$ : Surcharge on the boundary S; *vi*: Velocity along the velocity discontinuous surface; *Xi*: Body force; *r*: Varied radius of the log-spiral curve;  $r_A$ ,  $r_B$ ,  $r_P$ : Corresponding radius at points  $A$ ,  $B$ , and  $P$ ;  $\theta$ : Slope angle;  $\theta'$ : Angle between DB and BC; *θ*A, *θ*B: Rotating angle from the horizontal to OA and OB; *θ*<sub>P</sub>: Rotating angle from the horizontal to the critical point P;  $\theta_0$ : Angle between the slip plane and the horizontal;  $\theta_1$ ,  $\theta_2$ : Rotating angle from the horizontal to the vertical projection point of points *D* and *C* on the curve;  $\beta_0$ : Angle between the slip plane and slope surface; *x*<sub>P</sub>: Horizontal distance between the pile and slope toe;  $H_p$ : Horizontal project of the slope; *H*: Slope height; *h*: Strain wedge depth (total height of the pile above the potential sliding surface); Δ*h*: Thickness of diferential soil sublayers;  $h_0$ : Vertical height of the differential element; *FoS*: Factor of safety; *FoS*1: Factor of safety for the slope with the lateral load; *FoS*0: Factor of safety for the slope without the lateral load; *φ*: Internal friction angle; *c*: Cohesion; *φ*′: Mobilized friction angle at failure; *<sup>c</sup>*′: Mobilized cohesion at failure; *Ẇ* : External work rate; *Ẇ D* : Total energy dissipation rate;  $\ddot{W}_{D1}$ : Internal energy dissipation rate generated by internal forces;  $\ddot{W}_{D2}$ : Dissipation rate of the force and moment provided by the laterally loaded pile;  $f_1$ ,  $f_2$ ,  $f_3$ ,  $f_4$ : Geometry-dependent non-dimensional function of the block;  $f_5$ : Non-dimensional function of internal energy dissipation rate *Ẇ <sup>D</sup>*1; *γ*: Unit weight; *w*: Angular velocity; *L*: Distance between point *A* and point *D*; *F*: Resultant force generated by piles;  $\chi$ : A ratio defined as the distance between the action point of the resultant force and the critical point to the overall *h*; *d*: Length of line BC; *EI*: Flexural rigidity of the pile; *p*(*z*): Soil resistance in front of the pile;  $q(z)$ : Extra earth pressure behind the pile; *τ*: Side friction; *β*m: Base angle; *φ*m: Fan angle; *β*m*,j*: Base angles of diferent sublayer strain wedges; *φ*m*,j*: Fan angle of diferent sublayer strain wedges; *D*: Width or diameter; *δ*: Linearized defection angle; *y*: Pile deflection;  $Y_0$ : Horizontal distance from the pile to the intersection of the far surface and slope surface;  $y_0$ : Deflection atop the pile; *y<sub>j</sub>*: Pile deflection atop each sublayer strain wedge; (*y*<sub>0</sub>)<sub>SW</sub>: Pile head displacement estimated by the strain wedge technique;  $(y_j)_{SW}$ : Pile defection atop each sublayer strain wedges estimated by the strain wedge technique;  $Z_0$ : Intersection depth of the far surface and slope surface; *Zj* : Depth of the intersection of the (*j*-1)th and *j*th sublayer

strain wedge ( $j = 1, 2, ..., n$ );  $q$ : Uniformly distributed load;  $\sigma_{vi}$ : Effective vertical stress;  $\Delta \sigma_i$ : Lateral stress increment;  $\Delta \sigma_{hf}$ : Lateral stress increment in the yield state; *L*(*z*): Far surface width; *SL*: Stress level;  $\varepsilon_{50}$ : Soil strain at 50% stress level; *S*<sub>1</sub>, *S*<sub>2</sub>: Pile shape coefficient; *λ<sub>i</sub>*, *m*,  $q_i$ : Coefficients of stress level;  $\sigma_1$ : Major principal stress;  $\sigma_3$ : Minor principal stress;  $\sigma_{3v}$ : Vertical component of minor principal stress;  $\sigma'_{y}$ ,  $\sigma_f$ : Two components of vertical stress on the differential element;  $\sigma'$ <sub>v</sub> : Mean value of the vertical component of stress  $\sigma'$ <sub>v</sub>; *N*: A function of friction angle; *R*: Radius of the trajectory of minor principal stress; *S*: Length of the diferential element; d*V*′: A component of the differential stress at the arbitrary point  $F_0$ ; *V*′: Resultant force of  $dV'$ ; *ψ*: Angle between the horizontal and normal OD; *ω*: Angle between the vertical and normal OP;  $\theta_w$ : Angle between the horizontal and normal OJ; *ξ*: Angle between the vertical and normal OQ; *K*an: Lateral earth pressure coefficient;  $\overline{\sigma}_v$ : Mean vertical stress;  $m_0$ : A coefficient of *𝜎*v; *σ*h: Lateral earth pressure; *σ*ah: Lateral stress at an arbitrary point D; *s*: A relatively small amount; *V*<sub>u</sub>: Ultimate shear strength of piles; *V*: Lateral load atop the pile;  $f_c$ : Concrete compressive strength; *A*: Pile cross-section area; *α*: The ratio of the lateral load atop the pile to the ultimate shear strength; *η*: Normalized safety factor

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**Data availability** Some or all data, models, or codes that support the fndings of this study are available from the corresponding author upon reasonable request (the data in the graph and the code of calculation, etc.).

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