**ORIGINAL PAPER**



# **Machine Learning Approach to Model Rock Strength: Prediction and Variable Selection with Aid of Log Data**

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## **Abstract**

Comprehensive knowledge and analysis of in situ rock strength and geo-mechanical characteristics of rocks are crucial in hydrocarbon and mineral exploration stage to maximize wellbore performance, maintain wellbore stability, and optimize hydraulic fracturing process. Due to the high cost of laboratory-based measurements of rock mechanics properties, the logbased prediction is a viable option. Nowadays, the machine learning tools are being used for estimation of the in situ rock properties using wireline log data. This paper proposes a machine learning approach for rock strength (uniaxial compressive strength) prediction. The main objectives are to investigate the performance of data-driven predictive model in determining this vital parameter and to select features of predictor log variables in the model. The backpropagation multilayer perception (MLP) artifcial neural network (ANN) with Levenberg–Marquardt training algorithm as well as the least squares support vector machine (LS-SVM) with coupled simulated annealing (CSA) optimization technique is employed to develop the dynamic data-driven models. Capturing nonlinear, high dimensional, and complex nature of real feld log data, the rock strength models' performances are evaluated using statistical criteria to ensure concerning the model reliability and accuracy. The model predictions are compared and validated against the measured values as well as the results obtained from existing log-based correlations. Both the MLP-ANN and the CSA-based LS-SVM connectionist strategies are able to predict the rock strength so that there is a very good match between the model results and corresponding measured values. The input log parameters are ranked based on their contributions in prediction performance. The acoustic travel time and gamma ray are found to have the highest relative signifcance in estimating rock strength. New correlations are also developed to obtain the in situ rock strength of the siliciclastic sedimentary rocks using the most important log parameters such as dynamic sonic slowness, formation electron density, and shalyness efect. The developed correlations can be used to obtain quick estimation of dynamic uniaxial compressive strength profle using wireline logging data, instead of static data from the surface measurements or laboratory data. It is expected that the proposed models and tools will enable oil and gas engineers to better predict rock strength and thus enhance wellbore performance.

**Keywords** Log variables · Connectionist models · Uniaxial compressive strength · Variable selection · Rock stability





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# **1 Introduction**

# **1.1 Background**

Reservoir rock mechanical properties (RMPs) play an important role in making decisions regarding exploration development, wellbore stability analysis, sanding potentiality, and safe drilling operations. The RMPs are closely related to the rock physical properties such as rock density, porosity, and pore fuid saturation. The uniaxial compressive strength (UCS) is one of the key rock strength parameters that can be used in wellbore stability assessment, in situ stress analysis, drilling optimization as well as reservoir sanding likelihood prediction (Nouri et al. [2006](#page-23-0); Crawford et al. [2011\)](#page-22-0). It is also utilized for mining and geotechnical engineering applications including the rock mass characterization, underground rock excavation, and geotechnical project design (Brown [1981](#page-22-1)). The reservoir rock strength provides the limit of axial stress in situ condition before rock failing (Fjær et al. [2008](#page-22-2)). The most common techniques for determining rock strength are in situ measurements using geophysical log-based models and laboratory measurements using core samples. The direct and indirect measurements of rock strength include UCS test, triaxial test, Brazilian test, and basic mechanical tests such as point load index, non-destructive ultrasonic test, Schmidt hammer rebound test, impact strength test, scratch test, indentation test, and Equotip hardness tester (Miller [1965](#page-23-1); Broch and Frankline [1972;](#page-22-3) Hoek and Brown [1997](#page-23-2); Fener et al. [2005](#page-22-4); Yilmaz [2013](#page-24-0); Mousavi et al. [2018](#page-23-3)). The Rock Mechanical Laboratory (RML) testing on real core samples is the most reliable method to determine the rock strength using the procedures recommended by the American Society for Testing Materials (ASTM [1986](#page-22-5)) and/or the International Society of Rock Mechanics (Brown[1981](#page-22-1)). The RML testing cannot provide continuous rock strength profle along with the in situ wellbore conditions. Also, the core sample preparation is tedious, time consuming, expensive, and very sensitive to stress unloading (Raaen et al. [1996\)](#page-24-1). Most of the times, high-quality cylindrical core specimens preparation with regular geometry is difficult due to the nature of fractured thinly bedded and clay-bearing sedimentary rocks. In addition, a large-scale core sample preparation is often challenging due to time limitation, complex variations in rock composition, and geological behavior and heterogeneity of the formation. When the formation rock sample is not attainable from the deeper depth of oil and gas and/or mining felds, the well logging data can be used to estimate the rock mechanical and physical properties. Over the past few decades, numerous studies have been performed to develop empirical models for estimation of rock strength using petrophysical logs such as the sonic and density porosity logs. The log-based existing models or correlations for rock strength were listed/summarized by diferent authors such as Chang et al. [\(2006](#page-22-6)) and Odunlami et al. ([2011](#page-23-4)). A continuous in situ UCS profle is essential to conduct rock failure analysis during a drilling operation. Nowadays, the artifcial intelligence (AI) approaches such as artifcial neural network (ANN), functional network (FN), adaptive neuro-fuzzy inference system (ANFIS), decision tree (DT), classic support vector machine (SVM), and/or least square support vector machine (LS-SVM) are extensively used to develop the data-driven models for rock mechanics related to petroleum and mining (Asoodeh and Bagheripour [2012](#page-22-7); Ocak and Seker [2012;](#page-23-5) Khandelwal and Monjezi [2013;](#page-23-6) Ashena and Thonhauser [2015;](#page-22-8) Dehghan et al. [2010](#page-22-9); Koolivand-Salooki et al. [2017;](#page-23-7) Ceryan and Can [2018;](#page-22-10) Anemangely et al. [2019;](#page-22-11) Miah et al. [2019](#page-23-8)). Recently, ANN and LSSVM are becoming more popular strategies for data-driven model development, prediction of formation elastic properties, and failure analysis to save the operational expenses and time.

#### **1.2 Literature survey**

Several empirical correlations exist for calculation of UCS along the wellbore using rock porosity  $(\phi)$ , sonic travel time (DT), elastic moduli, and other formation properties such as shale volume and resistivity (Fjaer et al. [1992](#page-22-12); Edimann et al. [1998;](#page-22-13) Sonmez et al. [2004](#page-24-2); Chang et al. [2006;](#page-22-6) Odunlami et al. [2011](#page-23-4); Singh et al. [2012](#page-24-3); Rabbani et al. [2012\)](#page-24-4). The rock strength can be estimated from the empirical correlations considering the lithology type (e.g., carbonate or clastic rocks) and availability of log variables. In addition, there are so-called "worldwide" models, which can be used irrespective of the rock type (Chang et al. [2006](#page-22-6)). Well-known correlations for estimating rock strength (UCS) using log data in the oil and gas industry are listed in Table [1.](#page-3-0) Onyia [\(1988](#page-24-5)) investigated the in situ rock strength and developed a correlation to estimate ultimate rock strength using drilling and logging data such as gamma-ray (GR) log, resistivity log, density log, and borehole compensated sonic logs. Fjaer et al. ([1992](#page-22-12)) developed a correlation that is most commonly used to obtain the rock strength for shaly sand reservoirs using three rock parameters, namely, Poisson's ratio  $(v)$ , sonic velocity (Vp), and shale volume (Vsh). The shale volume measurement is a costly and time-consuming approach through core analysis, while it can be found from the wireline log data including GR log. For instance, the shale volume can be obtained using the entire GR log of formation to capture the maximum and minimum magnitudes of GR if the full-length log is available. Moos et al. [\(2001](#page-23-9)) developed the UCS correlation for the clastic sandstone rocks using sonic travel time or acoustic velocity, and formation bulk density. Also, Chang et al. [\(2006\)](#page-22-6) took into account only sonic travel time to introduce the UCS correlation. Both correlations of Moos et al. [\(2001\)](#page-23-9) and Chang et al. [\(2006](#page-22-6)) did not consider the shale content efect (e.g., GR parameter) to estimate the in situ UCS parameter. A number of studies have investigated the infuences of various rock properties on rock strength; however, the ranking of variables was not discussed in their studies (Rajabzadeh et al. [2012;](#page-24-6) Haftani et al. [2015](#page-23-10); Jamshidi et al. [2016](#page-23-11), [2018](#page-23-12); Kong and Shang, [2018](#page-23-13)). The existing UCS correlations have been developed considering static formation properties from core analysis, as well as a few infuential log variables.

In situ UCS models have not been developed yet to capture the lithology indicator (GR), number of electron density, and acoustic travel time of the porous shay sand formation. Thus, it seems necessary to develop new correlation(s) for estimation of realistic continuous in situ rock strength profle using dynamic wireline logging data in the absence of drilling or laboratory-based data.

The connectionist models, for example ANN and LS-SVM, are being increasingly used to predict rock mechanical properties for wellbore failure analysis, reservoir geomechanics, underground excavation as well as rock mass characterization (Yang and Zhang [1997](#page-24-7); Yılmaz and Yuksek [2008;](#page-24-8) Ocak and Seker [2012;](#page-23-5) Asoodeh and Bagheripour [2012;](#page-22-7) Khandelwal and Monjezi [2013](#page-23-6); Barzegar et al. [2016;](#page-22-14) Negara et al. [2017;](#page-23-14) Matin et al. [2018](#page-23-15); Abdi et al. [2018](#page-22-15); Onalo et al. [2018](#page-24-9); Ceryan and Can [2018](#page-22-10); Onalo [2019](#page-24-10)). Although several research works have attempted to determine the elastic or geomechanical characteristics of rocks using experimental core and log data, only a few studies have forecasted the rock strength (UCS) using wireline logs with AI or machine learning tools. The existing literature reveals that several input variables are adopted in soft computing smart models to obtain the UCS or Young's modulus (*E*) using rock physical properties or features such as porosity, unit weight (uw), dry density (dd), compressional wave velocity  $(Vp)$ , water absorption (wa), water content (wc), Schmidt hammer rebound number or hardness number (SRn), Brazilian tensile strength (BST), point load index  $(Is_{(50)})$ , and slake durability index  $(I_d)$ . The main studies conducted for rock strength prediction are listed in Table [2](#page-4-0) with a focus on the corresponding research methods and shortcomings. Only a few studies investigated ranking of the input variables while determining the rock strength (UCS) (Majidi and Rezaci [2013;](#page-23-16) Torabi-Kaveh et al. [2015](#page-24-11); Matin et al. [2018](#page-23-15)). Also, the use of AI approaches to estimate elastic properties and rock strength parameter was found to be limited (Sharma et al. [2010](#page-24-12); Tariq et al. [2017;](#page-24-13) Onalo et al. [2018](#page-24-9)). Sharma et al. [\(2010](#page-24-12)) introduced a correlation between UCS and physical properties of weakly cemented sandstone rocks such as RB, synthetic Vp and Vs, and Vsh

<span id="page-3-0"></span>

# <span id="page-4-0"></span>**Table 2** Applications of AI-based connectionist tools for rock strength and mechanical properties prediction



# **Table 2** (continued)





(volume of shale). An extended version of the correlation was built through employing multiple regression analysis; the model is valid for the range of 0–4 MPa of UCS using synthetic velocities and multiple parameters from wireline log data. The performance of the regression-based model was also compared with that of an ANN model. Torabi-Kaveh et al. [\(2015](#page-24-11)) utilized the ANN model and regressive equation for predicting the rock strength and elasticity modulus of carbonate and limestone rocks. They claimed that higher accuracy can be obtained from the ANN predictive model, compared to the multiple regression analysis (MVRA). Tariq et al. ([2017](#page-24-13)) investigated the applicability of machine learning approaches such as ANN, ANFIS, and SVM to predict UCS. It was concluded that ANN outperforms the other techniques; an empirical correlation to predict the UCS was also proposed that gives better results, compared to a number of existing correlations. It was claimed that four geomechanical parameters such as RB, BP, Vs, and dynamic Young's modulus  $(E)$  are sufficient to forecast the rock strength; however, the relative contribution of the variables was not investigated. Onalo et al. ([2018](#page-24-9)) constructed an MLP-based ANN model using input log variables such as GR, Vsh, and RB to predict sonic acoustic velocities. In their study, they obtained the elastic moduli using correlations; the results obtained from the correlations were also compared with ANN predictions. The researchers also investigated sanding possibility as a case study of shaly sand reservoir, Niger delta basin. In their study, ranking of input variables for the predictive ANN model was not discussed. Abdi et al. ([2018\)](#page-22-15) applied the ANN and the MLR approaches to obtain the sedimentary rock strength parameters using experimental data sets. It was found that ANN results in higher accuracy than MLR. They introduced a correlation to estimate UCS using data sets for diferent rock samples of limestone, sandstone, conglomerate, and marl. In their research study, the correlation did not include the lithology type and they did not rank the input variables. Based on the literature review, further comprehensive investigations are required to identify relative contributions of the input variables in prediction of rock strength as well as mechanical properties of shaly sand formations.

#### **1.3 Research objectives**

To the best of our knowledge, data-driven predictive model and feature ranking of logging variables to study the rock strength with the aid of logging data have not been investigated systematically. The variable selection and ranking of logging parameters appear to be an important challenge for not only petroleum and mining engineers and drillers but also geologists to estimate ultimate rock strength profle using the wireline log data with acceptable accuracy. The logging data are expensive to assemble and depict the entire formation profle. The current study is planned to fll in the knowledge gap by fnding the most contributing predictor log variables, corresponding to their relative performance while predicting the ultimate rock strength. It is believed that the research strategies employed in this study can be less time consuming and cost efective for efficient rock formation evaluation. The objectives of this research work are listed as follows:

- To investigate the performance of rock strength models and compare the predictive performance of deterministic tools through statistical analysis.
- To perform comprehensive parametric sensitivity analysis and fnd the most contributing variables for predicting UCS.
- Develop new correlations to estimate in situ formation UCS, capturing most efective log parameters.

# **2 Theory and Model Development**

#### <span id="page-6-0"></span>**2.1 Log‑Based Model to Predict Rock Strength**

The strength of rock is a function of rock mineralogy and lithology, acoustic properties, density, porosity, geometric factors, depositional environments, and compaction level. The most common logging types are the gamma-ray log, resistivity log, and porosity log. The comprehensive information on well logging principles, advantages, limitations and applications can be found in the available literature (Asquith and Krygowski [2004;](#page-22-22) Mondol [2015](#page-23-21)). The presence of clay minerals in a formation may strongly afect the rock material properties. The GR log is extensively used to identify the lithology as well as to estimate the shale volume (clay content); this corrects their presence in shaly sand rocks, yielding more accurate efective porosity  $(\phi_{\alpha})$ . Rock porosity (void space in the rock volume) can be obtained from the responses of neutron log (counts the hydrogen concentration), density log (measures the bulk electron density), and sonic log (estimates acoustic travel time) in a formation. Also, the rock porosity varies primarily with particle size distribution, grain shape, packing arrangement, compaction, cementation, and clay content (Asquith and Krygowski [2004](#page-22-22)). The conductivity (inverse of resistivity) of a rock can be obtained from the deep induction resistivity log, which converts to true resistivity  $(RT, \Omega m)$  of the virgin zone in a formation. In the present study, several well log responses are incorporated to estimate the in situ shale volume, acoustic primary velocity, and efective porosity; these rock properties are then used to estimate the rock strength.

The shale index  $(I_{GR})$  is obtained in the current study by the following equation (Schlumberger [1998](#page-24-20)):

$$
I_{\rm GR} = \frac{\rm GR_{\rm log} - GR_{\rm min}}{\rm GR_{\rm max} - GR_{\rm min}},\tag{1}
$$

where  $GR_{\text{log}}$  is the gamma-ray value of the zone of interest; and  $\text{GR}_{\text{max}}$  and  $\text{GR}_{\text{min}}$  represent the maximum and minimum magnitudes of gamma-ray log over the entire formation, respectively. The clay content or shale volume  $(V_{sh})$  is estimated from the following equation to simulate the nonlinear response of the tertiary rock formation (Larionov [1969](#page-23-22)):

$$
V_{\rm sh} = 0.083(2^{3.7I_{\rm GR}} - 1). \tag{2}
$$

The density porosity  $(\phi_D)$  is determined using the formation bulk density response  $(\rho_b)$  by the following equation:

$$
\phi_{\rm D} = \frac{\rho_{\rm ma} - \rho_{\rm b}}{\rho_{\rm ma} - \rho_{\rm fl}}.\tag{3}
$$

In Eq. ([3\)](#page-7-0),  $\rho_{\text{fl}}$  and  $\rho_{\text{ma}}$  refer to the density of the drilling mud, and the rock matrix density, respectively.

The clay corrected density porosity  $(\phi_{D,e})$  and neutron porosity ( $\phi_{N,e}$ ) are calculated as follows (Miah [2014\)](#page-23-23):

$$
\rho_{\rm b \cdot c} = \rho_{\rm b} + V_{\rm sh} \left( \rho_{\rm ma} - \rho_{\rm cl} \right),\tag{4}
$$

$$
\phi_{\rm D,e} = \frac{\rho_{\rm ma} - \rho_{\rm b.c}}{\rho_{\rm ma} - \rho_{\rm fl}},\tag{5}
$$

$$
\phi_{\rm N,e} = \phi_{\rm N} - V_{\rm sh} \phi_{\rm N,sh},\tag{6}
$$

in which,  $\rho_{b-c}$  refers to the clay corrected formation bulk density ( $g/cm<sup>3</sup>$ );  $\phi_N$  represents the neutron porosity (fraction) from the neutron log; and  $\phi_{Nsh}$  and  $\rho_{cl}$  denote the neutron porosity (fraction) and formation bulk density  $(g/cm<sup>3</sup>)$  of the shale zone, respectively.

The clay corrected effective porosity  $(\phi_0)$  is determined through the combination of clay corrected neutron and density porosities in the porous rock formation using the following equation:

$$
\phi_e = \sqrt{\frac{\phi_{\text{D,e}}^2 + \phi_{\text{N,e}}^2}{2}}.
$$
\n(7)

Although, the non-destructive testing for a rock sample is a more accurate way to predict the sonic primary velocity, it is a time consuming, expensive, and tedious method. The sonic log is employed to obtain the profle of sonic acoustic compressional wave velocity (Vp). The compressional sonic acoustic time (DT, μs/ft) is inversely proportional to the sonic primary wave velocity (Vp, km/s) of the formation, as expressed below (Gaviglio [1989;](#page-23-24) Anemangely et al. [2017\)](#page-22-23):

$$
V_{\rm p} = \frac{304.8}{DT}.
$$
 (8)

When the shear sonic slowness is not available from the wireline log data, the synthetic shear wave velocity (Vs) can be estimated from the available correlations for various rock formations (Pickett [1963;](#page-24-21) Caroll 1969; Krishna et al. [1989;](#page-23-25) Greenberg and Castagna [1992](#page-23-26); Vernik et al. [1993](#page-24-14); Brocher [2005](#page-22-24); Hossain et al. [2012](#page-23-27); Bailey and Dutton [2012](#page-22-25); Lee [2013](#page-23-28); Ojha and Sain [2014](#page-24-22); Anemangely et al. [2017](#page-22-23)). A limited number of studies have attempted to obtain the shear wave velocity for the siliciclastic or shaly sand rock formations (Castagna et al. [1985](#page-22-26); Han et al. [1986](#page-23-29); Williams [1990;](#page-24-23) Miller and Stewart [1990;](#page-23-30) Ramcharitar and Hosein [2016](#page-24-24)). Recently, Oloruntobi and Butt ([2020](#page-24-25)) have proposed an empirical correlation to estimate  $V_s$  using  $V_p$  and  $\rho_b$  for any type of sedimentary rocks such as shaly sand reservoirs, as given below:

<span id="page-7-0"></span>
$$
V_{\rm s} = A \left[ \frac{V_{\rm p}}{\sqrt{\rho_{\rm b}}} \right]^4 + B \left[ \frac{V_{\rm p}}{\sqrt{\rho_{\rm b}}} \right]^3 + C \left[ \frac{V_{\rm p}}{\sqrt{\rho_{\rm b}}} \right]^2 + D \left[ \frac{V_{\rm p}}{\sqrt{\rho_{\rm b}}} \right] + E. \tag{9}
$$

<span id="page-7-1"></span>In Eq. [\(9](#page-7-1)), *A* (0.094), *B* (−0.881), *C* (2.605), *D* (−1.415), and  $E$  (−0.435) are the coefficients of the polynomial expression.

In the literature, there are several empirical correlations to calculate the rock strength as well as elastic properties using sonic acoustic travel time and formation density. Also, elastic properties such as Young's modulus (*E*), shear modulus (*G*), bulk modulus (*K*), and Poisson's ratio (*𝜐*) can be estimated using density and sonic logs. The following equations can be utilized to obtain the four main isotropic elastic properties at dynamic conditions using bulk density  $(\rho_b)$ , sonic acoustic compressional (Vp), and shear wave velocity or  $V_s$  (Li and Fjær [2012](#page-23-31)):

$$
v = 0.5 \left( V_p^2 - 2V_s^2 \right) / \left( V_p^2 - V_s^2 \right), \tag{10}
$$

$$
E = \rho_b V_s^2 (3V_p^2 - 4V_s^2) / (V_p^2 - V_s^2),
$$
\n(11)

$$
G = \rho_{\rm b} (V_{\rm s}^2), \tag{12}
$$

$$
K = \rho_{\rm b} \left( V_{\rm p}^2 - \frac{4}{3} V_{\rm s}^2 \right) = \frac{E}{3(1 - 2\nu)}.
$$
 (13)

Any of the elastic properties (such as *E*) can be calculated using two remaining properties (e.g.,  $K$  and  $\nu$ ) (Fjær et al. [2008\)](#page-22-2). The dynamic moduli are always larger than the static ones, since the dynamic strains are always smaller than static strains of rocks (Demirdag et al. [2010](#page-22-27); Najibi et al. [2015](#page-23-32)). The conversion factor from static to dynamic moduli is dependent on the formation porosity, confning pressure, degree of loading, and other lithological factors (Rasouli et al. [2011\)](#page-24-26). In the current study, the UCS parameter is estimated using the following model for the shaly sand formations (Fjær et al. [2008;](#page-22-2) Rabbani et al. [2012](#page-24-4)):

$$
UCS = 3.3 \times 10^{-20} \rho_b^2 V_p^4 (1 - 2v) \frac{(1 + v)^2}{(1 - v)^2} (1 + 0.78 V_{sh}).
$$
\n(14)

## **2.2 Log Data Collection and Quality Assurance**

A combination of several wireline logs such as gamma ray, deep resistivity, porosity, and caliper logs is used to identify the lithology, and to estimate the formation thickness, and rock physical and mechanical properties. The gamma-ray (GR) log is a complementary log that is able to identify the formation rock type, and to measure the amount of radioactive elements (API) and clay content. The density log measures the electron density (bulk density, RB) to estimate the formation true porosity, while the neutron log counts the hydrogen concentration (NP) as well as porosity of fuidflled formation. The sonic log helps to measure the acoustic wave in the form of compressional travel time (DT) or shear slowness. On the other hand, the resistivity log measures the conductivity (inverse of resistivity, RT) in the rock formation. All of these log variables are used in this study to develop the data-driven model; feld log data are collected from a shaly sand reservoir located in the Bengal basin. The lithology of the formation studied in this investigation have been characterized in a previous study (Islam [2010](#page-23-33)). The main lithology is sandstone, and sand-shale alteration. The most common detrital grains are quartz, feldspars, and rock fragments. Quartz is the most abundant constituent. The point count data indicated that quartz, feldspars, and lithic fragments ranges (%) are 65.4–71.1, 12.3–20, and 9.2–18.9, respectively. The texture is very fne to medium grain size, and well sorted. The grain (matrix) density of the sandstone ranges from 2.66–2.78  $g/cm<sup>3</sup>$ , while the thin section porosity is about 13%. The available feld well log data (such as GR, RT, RB, and DT) and neutron-density porosity are utilized to predict the in situ rock strength profle in the shaly sand rock formations. A total of 182 data samples are used for each log variable in the study. The log data quality is also confrmed to ensure the reliability of each log dataset variable by checking the depth shift and borehole conditions. The output and input variables are classifed into training, testing, and validation phases with 75%, 15%, and 10%, respectively. All the programming tasks related to this study are carried out using Matlab (R2017b) programming environment.

## **2.3 Development of Connectionist Predictive Models**

ANN model: The ANN is composed of diferent components such as artifcial neurons (connected in each layer), weight factors, bias term, and transfer function in a connectionist process unit system. The ANN can be adopted with a single-layer perception, multilayer perception (MLP), and/or radial basis function networks (Ali [1994;](#page-22-28) Mohaghegh et al. [1996](#page-23-34); Razavi and Tolson [2011\)](#page-24-27). The MLP is one of the conceptually attractive feedforward neural network approach employed in estimation of rock formation properties, rock mechanics, stability of underground openings, wellbore failure analysis, and rock engineering (Yang and Zhang [1997](#page-24-7); Meulenkamp and Grima [1999](#page-23-35); Helle and Bhatt 2002; Yilmaz and Yuksek [2009](#page-24-17); Al-Bulushi et al. [2009](#page-22-29); Ocak and Seke [2012](#page-23-5); Khandelwal and Monjezi [2013](#page-23-6)). The deep learning MLP model consists of at least four layers with one input layer, at least two hidden layers, and an output layer for target variables. The training algorithm and activation (transfer) functions are the most important components of an ANN structure. In this study, the ANN model is processed with the Levenberg–Marquardt (LM) algorithm for training function (TRAINLM) to adjust the weight factors through simulation in the connectionist model. The LM algorithm is usually faster and more reliable in the backpropagation system for ANN model than other standard backpropagation methods



<span id="page-9-0"></span>**Fig. 1** Schematic of ANN architecture employed in the current work

(Ceryan et al. [2013\)](#page-22-19). The Tansig-type activation function is used between input and hidden layers while Purelin (linear) transfer function is employed between the last hidden layer and output layer in the model. Taheri-Garavand et al. ([2015\)](#page-24-28) claimed that a hidden layer with a lower number of neurons is desired in an ANN model because of shrinking the neural network structure as well as increasing the learning potential. In the current study, the number of hidden layers is chosen by a trial and error strategy to optimize the ANN structure such that the maximum regression coefficient and minimum mean squared error (MSE) as the selection criteria are attained to fnd the best confguration in the smart approach. The number of neurons in the hidden layer is optimized to enhance the network performance as well as to save the computational training time (Zendehboudi et al. [2014](#page-24-29)). An ANN structure is shown in Fig. [1](#page-9-0). A flowchart is also depicted in Fig. [2](#page-10-0) to present the ANN model development steps and the optimization strategy in the study. In Fig. [1](#page-9-0), N1 and N2 refer to the number of neurons in the hidden layers 1 and 2, respectively.

The activation function is Purlin for the output neuron. The generalized mathematical expression for MLP-based neural network with Tansig transfer function for the hidden neurons is given as follows:

$$
y_m = \left[\sum_{j=1}^m \omega_{jm} \text{Tansig} \times \left(\sum_{i=1}^n \omega_{ij} x_i + b_j\right) + b_m\right].\tag{15}
$$

In Eq.  $(15)$  $(15)$ ,  $y_m$  stands for the output variables;  $x_i$  introduces the vector of target variables ( $i=1, 2, 3, 4, 5...$ );  $b_m$ resembles the bias term for output layers;  $\omega_{ii}$  denotes the connection weight on the link from *i* to *j* node between input and hidden layers; *m* is the number of hidden nodes; and *n* refers to the number of input variables.

The common advantages of ANN technique are: (a) it generally provides a high prediction accuracy where it captures better the nonlinear and high dimensional relationships among data points, compared to the statistical regression models, (b) it can effectively model randomly changing variables with a non-constant variance, and (c) it offers a more convenient and user-friendly modeling approach, compared to analytical and numerical modeling strategies (Esene et al. [2020\)](#page-22-30). However, the ANN tool has some inherent limitations such as slow convergence speed, low generalization performance, reaching local optima, and overftting problem.

<span id="page-9-1"></span>LS-SVM model: The SVM is one of the powerful artifcial intelligence approaches used in data classifcation and regression analysis. The SVM uses a subset of training points in the support vectors (decision function), which was frst introduced by Vapnik ([1995](#page-24-30)). The LS-SVM is a modifed version of the classic SVM algorithm proposed by Suykens and Vandewalle [\(1999\)](#page-24-31). This modifed version is less complex than the classic SVM algorithm. It helps to reach the solution of a worsening problem (with less data points) more efficiently by setting up a linear set of equations through employing SVM instead of the quadratic

<span id="page-10-0"></span>

programming (Suykens and Vandewalle [1999](#page-24-31)). Compared to SVM, the LS-SVM learning method is less time consuming. Unlike the ANN tool, the LS-SVM can be used with a limited number of data points, while it has a higher gener-alization and training efficiency (Ghiasi et al. [2014;](#page-23-36) Kamari et al. [2014;](#page-23-37) Nejatian et al. [2014;](#page-23-38) Zendehboudi et al. [2018](#page-24-32)). However, the LS-SVM is very sensitive to outliers as well as the magnitudes of kernel and tuning parameters. Also, there is a lack of sparsity, which might limit its utilization for large-scale problems. More information regarding the theory and algorithms with diferent features of SVM or LS-SVM can be found in the literature (Smola et al. [2004](#page-24-33); Sebtosheikh et al. [2015;](#page-24-34) Esfahani et al. [2015](#page-22-31); Miah et al. [2020](#page-23-39)). The following equation is used in the LS-SVM:

$$
y(x_i) = \omega^T \varphi(x_i) + b
$$
 where  $x_i \in R^n$  and  $y_i \in R$ , (16)

where the nonlinear function  $\varphi(.)R^n \to R^{n_i}$  represents the primal space to a feature space with higher dimensions. The dimension  $n_i$  of this space is only defined in an implicit way; *b* is a bias term; and  $\omega \in \mathbb{R}^{n_i}$  introduces the weight factor. The optimization problem can be written for function estimation in the LS-SVM (Suykens et al. [2002](#page-24-35); Esfahani et al. [2015](#page-22-31)), as shown below:

<span id="page-11-0"></span>

<span id="page-11-1"></span>

Minimize 
$$
J(\omega, e_i) \approx \frac{1}{2} \omega^T \omega + \gamma \sum_{i=1}^n e_i^2
$$
. (17)

Subject to the following constraint:

$$
y_i = \omega^T \varphi(x_i) + b + e_i, i = 1, 2, 3, ..., n.
$$
 (18)

In Eq.  $(18)$  $(18)$ ,  $e_i$  represents the error variable, and γ resembles the regularization (annealing) parameter to prevent overfitting.

The kernel function is  $K(x, x_i) = \varphi(x_i)^T \varphi(x_i)$ , which needs to be satisfed with Mercer's condition. After eliminating  $\omega$  and  $e_i$ , the final expression can be formulated for the LS-SVM function estimation as follows:

$$
y(x_i) = \sum_{i}^{n} \alpha_i K(x, x_i) + b,\tag{19}
$$

where *b* and  $\alpha$  are the solutions to the linear system expressed through Eq. ([19\)](#page-12-1). The  $\alpha$  (weight factor) is a vector with the size of  $n \times 1$ ; *x* is the training sample; and  $x_i$  refers to the support vector.

The kernel function-based LS-SVM structure used in this study is illustrated in Fig. [3.](#page-11-0) A summarized methodology for development of kernel-based LS-SVM model is shown in Fig. [4.](#page-11-1)

There are many kernel functions that can be used in LS-SVM such as linear, polynomial, spinal, radial basis, and sigmoidal (Zendehboudi et al. [2018](#page-24-32)). Among all kernel functions, the Gaussian radial basis kernel function (RBF) is mostly used in the LS-SVM learning strategy to fnd the best output (Suykens et al. [2002](#page-24-35); Samui [2008](#page-24-36); Zendehboudi et al. [2018](#page-24-32)) due to its computational simplicity and other features (e.g., capable of solving nonlinear problems). The kernel function-based LS-SVM structure used in this study is shown in Fig. [3.](#page-11-0) The Gaussian RBF can be defned mathematically as follows (Samui [2008](#page-24-36)):

$$
K(x, x_i) = \exp\left(-\frac{\left(||x_i - x||\right)^2}{2\sigma^2}\right).
$$
 (20)

In the kernel function of RBF-based LS-SVM, the regularization and kernel parameters (also named as tuning parameters)  $\gamma$  and  $\sigma^2$  are adjusted through a global optimization technique, namely, the coupled simulated annealing (CSA) (Xavier-de-Souza et al. [2009](#page-24-37)). The CSA optimization process is proven to be more efective than multi-start gradient descent technique (Suykens et al. [2002;](#page-24-35) Rostami et al. [2019\)](#page-24-38). Similar to the MLP-ANN model, the databank for the log data is divided randomly into three sub-datasets to construct the LS-SVM models using diferent kernel functions. The total samples are categorized into three groups including 75% for training, 15% for testing, and 10% for validation in the LS-SVM connectionist model with the CSA optimization approach.

## **2.4 Model Performance Assessment**

<span id="page-12-0"></span>Four statistical indicators are used in this study to analyze the predictive model performance. The indicators are root mean square error (RMSE), coefficient of determination  $(R<sup>2</sup>)$ , average absolute percentage relative error (AAPE), and maximum average absolute percentage error (MAPE). The mathematical expressions for all performance indices are listed below (Zendehboudi et al. [2014](#page-24-29), [2018\)](#page-24-32):

<span id="page-12-1"></span>RMSE = 
$$
\sqrt{\frac{1}{n} \sum_{i=1}^{n} (Y_{\text{m},i} - Y_{\text{p},i})^2}
$$
, (21)

$$
R^{2} = 1 - \frac{\sum_{i=1}^{n} (Y_{\text{m},i} - Y_{\text{p},i})^{2}}{\sum_{i=1}^{n} (Y_{\text{m},i} - Y_{\text{m},\text{mean}})^{2}},
$$
(22)

$$
AAPE = \frac{1}{n} \sum_{i=1}^{n} \left( \frac{(Y_{m,i} - Y_{p,i})}{Y_{m,i}} \right) \times 100,
$$
 (23)

$$
MAPE = \max \left| \frac{(Y_m - Y_p)}{Y_m} \right| \times 100. \tag{24}
$$

In the preceding equations, *n* indicates the total number of samples;  $Y_m$  resembles the measured variable;  $Y_{m,\text{mean}}$  is the mean value of  $Y_m$ ; and  $Y_p$  represents the predicted output variable. The accuracies of the data-driven models are analyzed on the basis of the low or high value of statistical indices. In the study, the model is best for the high value of  $R^2$  (close to 1) and low values of RMSE, AAPE, and MAPE.

#### **2.5 Sensitivity Analysis and Variable Selection**

In this study, a systematic strategy is employed to perform the parametric sensitivity analysis as well as to fnd the relative importance of the input log variables in the AI-based predictive rock strength models (see Fig. [5\)](#page-13-0). Furthermore, the optimized AI models predict the UCS; the model performance is assessed using the statistical criteria. Based on the contribution of an input variable to the predictive models, the input parameters are ranked. The variable ranking approach is called 'single variable elimination' of the datadriven model, while it has selective multiple input variables to predict the output variable using the optimized AI structure. In the log parameter ranking through the data-driven model, if the model results in high AAPE, MAPE, and RMSE, and low  $R^2$ , it implies that the eliminated variable

#### <span id="page-13-0"></span>**Fig. 5** Flowchart to conduct parameter sensitivity analysis



<span id="page-13-1"></span>**Table 3** Summary of the statistical values of the used log data

Log parameters	Max	Min	Mean	St. Dev	Sample var
GR (API)	157.82	76.28	100.19	13.87	192.51
$RT(\Omega m)$	39.70	13.70	22.67	4.96	24.58
RB(g/cm <sup>3</sup> )	2.53	2.30	2.37	0.0425	0.0018
NPHI (v/v)	0.2039	0.1455	0.17	0.013	0.0002
$DT$ ( $\mu$ s/ft)	97.40	85.84	92.90	2.43	5.89

<span id="page-13-2"></span>**Table 4** Summary of log-based formation properties magnitudes in the study



has high impact on the model. It is worth noting that only most infuential parameters are used to develop the new correlations for obtaining continuous in situ UCS profle for the

clastic sedimentary reservoir rocks through multivariable regression analysis with real feld application.

# **3 Results and Discussions**

#### **3.1 Data Analysis**

The radioactivity properties including gamma ray, deep resistivity, formation bulk density, and sonic log responses considerably change with depth throughout a shaly sand formation. For the data set under study, the minimum and maximum values of gamma ray over the entire lithology log of the formation are 77 and 155 API, respectively, which are used to calculate the shale volume. The average shale volume extent is 11.84%, while the minimum value is 0.26% in the studied depth interval. The statistical information on the log data samples and the estimated values of rock characteristics are presented in Tables [3](#page-13-1) and [4](#page-13-2) over the entire depth of interest reservoir rock zone, respectively. Note that the formation properties in Table [4](#page-13-2) are derived from the statistical <span id="page-14-0"></span>**Fig. 6** Profle of compressional wave and Poison's ratio in the rock formation



with formation gamma ray, sonic travel time, and bulk density, depending on the number of data points

<span id="page-14-1"></span>**Fig. 7** Variation of rock strength

<span id="page-14-2"></span>**Table 5** Correlation matrix between rock strength and formation characteristics

values in Table [3](#page-13-1) by following the methodology outlined in Sect. [2.1.](#page-6-0)

The clay corrected effective porosity (PHI) is estimated using neutron and density porosity; it is then used to obtain the in situ UCS of shaly sand formation using an empirical correlation presented in Fjær et al. ([2008\)](#page-22-2). The clay corrected porosity of a siliciclastic rock changes with the heterogeneity of pore diameter, size and shape of pores, and formation density along the direction of vertical depth. Also, the primary acoustic velocity (inverse of sonic compressional travel time) and in situ Poisson's ratio vary with respect to the vertical depth (6955.95–7015.33 ft) due to the rock formation compaction, cementation, and heterogeneity, as shown in Fig. [6.](#page-14-0) The in situ rock strength, UCS, varies vertically due to the overall effect of rock heterogeneity, formation radioactive mineral depositions, compaction, pore structure, grain size, packing, and rock density, as depicted in Fig. [7](#page-14-1). The rock strength of a shaly sand formation increases with an increase in gamma ray and bulk density, while it is inversely proportional to the

<span id="page-15-0"></span>**Fig. 8** Graphical representation of **a** validation performance, and **b** training phase for optimized ANN model



acoustic travel time as well as rock resistivity and porosity. The correlation matrix between UCS and other formation properties (e.g., porosity and true resistivity) is shown in Table [5](#page-14-2).

# **3.2 Data‑Driven Model Performance**

A feedforward ANN is designed using stratifed data samples. The optimum structure is obtained with the algorithm of LM; the optimal model has one input layer with fve neurons, the frst hidden layer with four neurons, the second hidden layer with three neurons, and one output layer with one neuron. The validation performance versus the number of epochs is illustrated in Fig. [8a](#page-15-0) for the constructed MLPbased ANN model. Figure [8](#page-15-0)b also shows the performance of training phase in terms of number of epochs. In this study, the validation phase is conducted to tune the model parameters and terminate the neural network training stage before

<span id="page-16-0"></span>



overfitting;  $\mu$  (mu) is the Marquardt parameter in the training step of the network. The best validation performance is found at the epoch number of 10 with a mean square error of 0.02243. The magnitudes of the gradient and mu are 0.02034 and 0.01 at epoch 16, respectively, in the training stage. The correlation coefficient is close to one for both training and testing stages in the optimized ANN model (see Fig. [9](#page-16-0)). It follows that the predicted results are in good agreement with the actual results for all training, testing, and validation data sets. The MLP-based ANN gives less error (percentage) with an MAPE of 2.3692% and 1.1956% for the training and testing phases, respectively.

In addition, the CSA optimization technique is used in the LS-SVM model as an iterative random search strategy. The optimization procedure is repeated several times to reach the optimum global point. Figure [10](#page-17-0) displays the scatter plots (target values versus predictions) of the training, testing, and validation steps for the optimized LS-SVM model. The initial values of the annealing and tuning parameters (*γ* and  $\sigma^2$ ) are 505,962.56 and 104.38, respectively. The final tuning parameters  $\gamma$  and  $\sigma^2$  of the radial kernel function (Gaussian) based log data-driven model for the UCS are  $3.62 \times 10^{11}$  and  $1.74 \times 10^3$ , after 14 iterations. The RBF-based model results in a value of MAPE (%) equal to 0.0476 for the training and

 $0.2656$  for the testing, respectively; the correlation coefficient is close to 1. The RBF-based LS-SVM predictive model has a greater performance in terms of accuracy and reliability; it leads to the lowest RMSE, AAPE and MAPE, and high  $\mathbb{R}^2$ . The statistical information for both MLP-based ANN and kernel function-based LS-SVM models is summarized in Table [6.](#page-17-1)

# **3.3 Parametric Sensitivity Analysis and Variable Selection**

The optimized ANN structure in this study has two hidden layers with the topography of (4–4–3–1). The selected ANN model is used to perform parametric sensitivity analysis. Conducting the statistical analysis, the log parameters are ranked based on their relative importance in the predictive UCS model. To further understand the effect of individual variables, one variable is excluded at each time and the remaining four variables are used in both ANN and LS-SVM models. In the model schemes A through E, the UCS predictions are obtained in the absence of one input variable. Due to the less signifcance of RT and PHI (input parameters excluded from the predictive models), models D and E show better performance (such as lower error and greater



<span id="page-17-0"></span>**Fig. 10** Performance of model A at diferent stages in the absence of DT (observer) variable

<span id="page-17-1"></span>**Table 6** Comparison of data-driven predictive models performances in the study

AI approach	Prediction phase	AAPE	<b>MAPE</b>	<b>RMSE</b>
<b>MLP-ANN</b>	Training	0.2803	2.3692	0.1735
	Testing	0.2779	1.1956	0.1314
LS-SVM	Training	0.0118	0.0476	0.0048
	Testing	0.0306	0.2656	0.0199

correlation coefficient), compared with the other models. Model A leads to a weaker performance with a low value of the correlation coefficient and high magnitudes of statistical errors due to the absence of an important log variable, DT, in the model (Fig. [10\)](#page-17-0).

Tables [7](#page-18-0) and [8](#page-18-1) present the performance metrics for the developed models. The statistical information of both connectionist techniques is presented in Fig. [11](#page-19-0).

According to the statistical analysis conducted on the LM-based ANN approach, the signifcant input variables are the sonic travel time, gamma ray, formation bulk density, porosity, and true resistivity (high to low ranked order) for prediction of UCS. Also, the same order of variable importance is attained from the RBF-based LS-SVM model. Based on the literature, the sonic porosity log (e.g., sonic travel time) is needed to estimate the rock strength using lithology-based correlations. The current study demonstrates that acoustic compressional travel time (DT) parameter has the highest contribution to the UCS value in a shaly sand formation. The rock resistivity and porosity have minor signifcance while predicting in situ UCS profle. According to the diferent testing, validation, and generalization approaches

<span id="page-18-0"></span>**Table 7** Investigating the impact of excluded variable on the performance of the MLPbased ANN msodel with four layers

Model scheme	Predictor variables	Excluded vari- Phase able		AAPE	<b>RMSE</b>	$R^2$
A	RT, GR, RB, PHI	DT	Training	3.60	1.60	0.947
			Testing	4.84	2.26	0.947
B	RT. RB. PHI. DT	<b>GR</b>	Training	1.85	0.96	0.983
			Testing	1.90	0.84	0.991
C	RT. GR. PHI. DT	<b>RB</b>	Training	0.63	0.29	0.999
			Testing	0.53	0.23	0.999
D	GR, RB, PHI, DT	RT	Training	0.18	0.10	0.999
			Testing	0.16	0.07	0.999
E	RT, GR, RB, DT	<b>PHI</b>	Training	0.005	0.003	1
			Testing	0.004	0.004	1

<span id="page-18-1"></span>**Table 8** Importance of input variables in the RBF-based LS-SVM model



used in the current study, the most signifcant predictor variables are DT, GR, and RB to estimate the rock strength of siliciclastic rock formations. Also, these variables are vital in capturing dense minerals efect, clay content, acoustic velocity, and bulk density of rocks.

## **3.4 Development of New Correlations for Rock Strength Estimation**

Several correlations have been developed to estimate rock strength (UCS) using either core or wireline log properties data. Thus, it seems that a new log-based UCS correlation is required to obtain in situ rock strength profle that can capture the mineralogical or clay efect, dynamic formation acoustic travel time, and bulk density. A set of 175 in situ data samples of a shaly sand reservoir in the Bengal basin is used in this study to figure out the influences of formation properties on the rock strength as well as to develop a new correlation. The relationships between the rock strength and formation bulk density, gamma ray, and acoustic travel time are illustrated in Figs. [12](#page-19-1),[13,](#page-19-2)[14.](#page-20-0) The bulk density is highly heterogeneous with respect to depth in the studied formation. The in situ rock strength increases with an increase in the formation bulk density due to the higher number density of electrons. The rock strength also increases with increasing gamma ray due to the radioactive minerals and clay content in the shaly sand rock. The in situ rock strength decreases with increasing acoustic travel time or decreasing compressional wave in the clastic rock formation.

To capture the lithology indicators, degree of formation density and touchstone of compaction, the formation gamma ray (GR), bulk density (RB), and sonic transit time (DT) are considered to develop the new correlations for predicting the UCS of clastic rocks such as clean or shaly sand rock formation. The following two UCS models are proposed through statistical regression analysis:

(25) Model 1∶ UCS = 68.158 + 31.347RB + 0.156GR − 1.349DT,

(26) Model 2∶ UCS = 0.149 GR0.93 + 6.67 × 1010DT<sup>−</sup><sup>5</sup> + 0.75RB3.07.

Both models are obtained through multivariate regression analysis where the feld data are used considering interrelationships between the parameters. Various forms of equations are examined and the best ones are selected based on

<span id="page-19-0"></span>**Fig. 11** Comparison of **a** R (top) and **b** statistical errors (bottom) for various model schemes in the absence of an observer variable



<span id="page-19-1"></span>**Fig. 12** Relationship between the in situ rock strength and bulk density

 $\circ$ 

**Formation bulk density, g/cm3**

 $\circ$ 

the magnitudes of statistical parameters (high  $R^2$  and low relative error).

The performance of the proposed models is compared with that of other models in Fig. [15.](#page-20-1) To develop the above

 $20 - 2.30$ 

25

**Rock strength, MPa**

Rock strength, MPa

<span id="page-19-2"></span>**Fig. 13** Relationship between the in situ rock strength and gamma ray

models, 175 feld log data samples are collected from the shaly sand clastic sedimentary reservoir rock, while it has an average UCS of 31.85 MPa, GR (API) of 98.39, *RB* of 2.36  $g/cm<sup>3</sup>$ , and *DT* of 93.12  $\mu s$ /ft in the depth interval of 6955.5–7015.34 ft. The proposed models have a lower



<span id="page-20-0"></span>**Fig. 14** In situ rock strength versus acoustic travel time



<span id="page-20-1"></span>**Fig. 15** A comparison of UCS profle obtained from diferent models

prediction error (a RMSE of 2.593 and an MAPE of 21%), compared to Moos et al. [\(2001](#page-23-9)) model (a RMSE of 8.92 and MAPE of 40.63%), while determining the UCS.

To further validate the robustness of the new correlations for UCS, real data taken from Volve feld in the Norwegian North Sea are also used. The detailed geological information about the feld can be found in the literature (Brekke et al. [2001](#page-22-32); Faleide et al. [2010\)](#page-22-33). Due to the availability of well log data in the open sources, Well no. 15/9- F-1-A is chosen to examine the validity of the proposed correlations. The most common lithologies of this well are carbonate rocks (limestone, 9091–10,538 ft), marlstones with the trace of limestone and sandstone (10,538–11,017 ft), claystone  $(11,017-11,250)$  ft), and predominantly sandstones with some claystone in the depth interval of 11,250–11,948 ft. The feld log data of GR, RB, and DT are employed to estimate continuous UCS profle using proposed models and other correlations, namely Chang et al. [\(2006\)](#page-22-6) and Moos et al. ([2001\)](#page-23-9) where the formation depth is in the range 11,250–11,850 ft of Volve feld (Equinor, [2018](#page-22-34)). A total of 1823 log samples are used from the selected depth of the formation with average values of 75.50  $\mu$ s/ft, 130.52 API, and 2.48 g/cm<sup>3</sup> for DT, GR, and RB, respectively. The predicted profle of UCS at 200 ft is depicted in Fig. [16](#page-20-2).

Based on the UCS profle shown in Fig. [16,](#page-20-2) Model 2 predictions are closer to the results of Moos et al. ([2001](#page-23-9))'s model; while Model 1 gives slightly lower values than the outputs obtained from Moos et al. ([2001](#page-23-9))'s model. Chang et al. [\(2006](#page-22-6))'s model underestimates the in situ rock strength. Using the North Sea felds' log data, Chang et al. ([2006](#page-22-6))'s model exhibits higher error (an AAPE of 32.52%), compared to Moos et al. [\(2001\)](#page-23-9)'s model, and Models 1 and 2 introduced in this study.



<span id="page-20-2"></span>**Fig. 16** A comparison of UCS profle obtained from diferent models in the Volve field 11400

The trial and error approach for fnding proper correlations and theoretical concepts/relevant background reveal that Model 1 in the form of a linear regressive equation offers accurate results for shaly sand formations, while Model 2 that presents a power law equation is a reliable and precise correlation to determine in situ UCS for both clean and shaly sand formations using dynamic log parameters. Chang et al. [\(2006\)](#page-22-6)'s model does not include the lithology feature (e.g., gamma-ray log) as well as formation density to capture the clay content and formation electron density efect in the model. The drilling engineers and/or geomechanists can employ Model 1 to obtain more reliable in situ UCS profle for the shaly sand rock formations, compared to the model proposed by Moos et al. [\(2001\)](#page-23-9).

Static formation properties can be obtained using surface measurements or laboratory tests. The static UCS can be measured with diferent laboratory tests, including unconfned and confned (triaxial) compressive tests. On the other hand, the dynamic rock strength can be obtained using the dynamic wireline log data. The dynamic UCS profle can be used for future wellbore failure analysis to estimate the rate of penetration for safe drilling operations. In this research, we aim to introduce new correlations for determination of the in situ rock strength (or UCS) and also to investigate the importance of log variables involved in UCS where the dynamic nature of reservoir formation is captured. It is worth noting that the relation between the feld rock strength and laboratory rock strength (particularly, intact rock strength) is a key issue in geotechnical and rock engineering. Comparison of laboratory and feld rock strength data and development of new models based on both types of data would be of high importance for future work.

In the current research investigation, a correlation matrix (Table [5](#page-14-2)) is introduced to show the relationship between UCS and other formation properties. Furthermore, we employ the machine learning strategies (ANN and LS-SVM) to find the most influential parameters while predicting in situ UCS values. According to the results, only three variables (e.g., DT, RB, and GR) are considered to develop the UCS correlations, which are valid for siliciclastic formations. It is worth noting that DT, RB, and GR represent the formation sonic slowness, electron density (related to porosity), and shale effect, respectively. The true resistivity (RT) of the formation is disregarded due to its low importance. As PHI can be obtained from the density log (RB) and neutron porosity, the PHI parameter is also eliminated to have only independent parameters as the inputs for estimation of UCS. The new models take into account the most contributing log parameters to fgure out the lithology efect, number of electron density, and acoustic travel time of the porous formation. The main advantages of the developed models over the existing correlations for siliclastic rocks are that they capture dynamic condition with key formation parameters; they are

capable of estimating continuous in situ UCS profle; and they are cost efective and can be used through a timely manner. Furthermore, the obtained UCS profle can be used to investigate the wellbore stability or rock failure criterion, and drilling performance analysis, reducing the exploration costs during the feld development phase.

# **4 Conclusions**

In this study, ANN and LS-SVM techniques are employed to predict the continuous profle of in situ rock strength (UCS) of clastic sedimentary rocks using several feld log data such as true resistivity, gamma ray, bulk density, porosity, and compressional sonic travel time. The statistical indicators such as AAPE, MAPE, RMSE, and coefficient of determination  $(R^2)$  are used to evaluate the AI-based connectionist model performance. The key fndings of this study are listed as follows:

- The connectionist models based on ANN with Levenberg–Marquardt training algorithm and the LS-SVM with CSA optimization strategy are capable of accurately estimating the reservoir rock strength (UCS) using log data.
- The compressional sonic travel time is the most influential parameter for determination of continuous in situ rock strength profle of siliciclastic rocks.
- The formation acoustic travel time, gamma ray, and the bulk density are essential to attain an accurate continuous formation UCS profle to capture lithology indicator, dense minerals, number of electron density, and acoustic travel time of the underground formation.
- Two correlations (models) are developed to estimate UCS through multivariate regression analysis by incorporating three infuential log parameters. Similar to existing correlations, the introduced models exhibit a good performance.
- It is proven that newly developed log-based correlations can be used to predict actual in situ unconfned rock strength for clastic sedimentary rocks including shaly sand rock formations.
- The deterministic tools, log variable ranking approach, and developed correlations can be useful for feld specialists, researchers, and rock engineers while dealing with rock failure analysis, geomechanics, drilling optimization as well as formation evaluation.

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**Author contributions** MIM: conceptualization, modeling/simulation, validation, and original draft; SZ: supervision, technical discussion, and writing—reviewing and editing; SA: supervision, technical discussion, and writing—reviewing and editing; SB: technical discussion and reviewing, manuscript editing.

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# **Compliance with Ethical Standards**

**Conflict of interest** The authors declare that they have no confict of interest.

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