ORIGINAL ARTICLE

In vitro analysis of thoracic spinal motion segment fexibility during stepwise reduction of all functional structures

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Abstract

Purpose The aim of this study was to quantify the stabilizing effect of the passive structures in thoracic spinal motion segments by stepwise resections. These data can be used to calibrate fnite element models of the thoracic spine, which are needed to explore novel surgical treatments of spinal deformities, fractures, and tumours.

Method Six human thoracic spinal motion segments from three segmental levels (T2–T3, T6–T7, and T10–T11) were loaded with pure moments of 1 and 2.5 Nm in flexion/extension, lateral bending, and axial rotation. After each loading step, the ligaments, facet capsules, and the nucleus pulposus were stepwise resected from posterior to anterior direction, while the segmental relative motions were measured using an optical motion tracking system.

Results Significant increases ($p < 0.05$) in the range of motion were detected after resecting the anterior spinal structures depending on loading magnitude, motion direction, and segmental level. The highest relative increases in the range of motion were observed after nucleotomy in all motion directions. The vertebral arch mostly stabilized the thoracic spinal motion segments in fexion and extension, while the facet joint capsules mainly afected the segmental stability in axial rotation. Coupled motions were not observed.

Conclusions The anulus fbrosus defnes the motion characteristics qualitatively, while the ligaments and the presence of the nucleus pulposus restrict the mobility of a thoracic spinal motion segment solely in a quantitative manner. The posterior ligaments do not predominantly serve for primary stability but for the prevention of hyperfexion.

Graphic abstract

These slides can be retrieved under Electronic Supplementary Material.

Keywords Thoracic spine · Segmental fexibility · Stepwise reduction · In vitro study · Biomechanics

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Introduction

For a comprehensive understanding of spinal biomechanics in healthy and pathological conditions, fnite element models of the entire vertebral column are required. In the past, the lumbar spine has been extensively studied within clinical, experimental, and numerical studies because of its primary role in various pathologies. With regard to sagittal imbalances and spinal deformities, such as scoliosis or hyperkyphosis, as well as vertebral fractures and tumours, however, it is essential to include the thoracic spine in numerical models to evaluate surgical treatments including instrumentation of multiple levels.

In order to provide reliable and physiologically realistic results, fnite element models are required to be calibrated with data obtained from in vitro experiments with defned boundary conditions. Ideally, the calibration process of these models is performed by adapting the material properties of each component to those obtained experimentally to include the material properties of each anatomical structure. In a previous in silico study of Schmidt et al. [\[1](#page-6-0)], this calibration method was applied to a model of the lumbar functional spinal unit L4–L5, starting from the anulus fbrosus, stepwise adding each anatomical structure, and ftting the material properties to the biomechanical properties of lumbar motion segments using a special algorithm. For this purpose, eight human L4–L5 spinal motion segments were tested in the in vitro study of Heuer et al. [[2\]](#page-6-1) by stepwise resecting every anatomical structure in reverse order and determining the ranges of motion in all motion planes. Previous in vitro studies focused on the role of the posterior structures or specifc ligaments [[3](#page-6-2)[–6](#page-6-3)], while others evaluated the efect of the rib cage on the spinal kinematics and stability [[4](#page-6-4), [7](#page-6-5)[–9](#page-6-6)]. For the accurate calibration of fnite element models, however, ideally all structures of the functional spinal unit have to be taken into account.

The purposes of this in vitro study therefore were to perform a biomechanical stepwise reduction test of thoracic functional spinal units from three diferent segmental levels (upper, middle, and lower thoracic spine) in order to understand the biomechanical efect of each anatomical structure on spinal stability. The obtained data set can be used for the calibration of fnite element models of the thoracic spine.

Methods

Specimen selection and preparation

Six fresh-frozen human thoracic spinal motion segments of the levels T2–T3, T6–T7, and T10–T11, respectively, were harvested from nine human donor spines. The donors had an average age of 58 years, ranging from 50 to 65 years (Table [1](#page-1-0)). During preparation, all soft tissues were carefully removed. Each specimen was visually and manually checked for signs of severe intervertebral disc degeneration and ligamentous injuries. The upper and lower vertebrae were half embedded in PMMA (polymethylmethacrylate, Technovit 3040, Heraeus Kulzer, Wehrheim, Germany), ensuring horizontal alignment of the intervertebral disc as well as coaxiality and parallelism of the cylindrical embeddings. In order to improve the fxation between vertebrae and embedding, screws were drilled into the vertebral body prior to potting.

The samples were stored at -20 °C and thawed at 5 °C 12 h before preparation and testing. Before mechanical testing, fanges were fxed on the cranial and caudal surface of the PMMA embeddings. The specimens were constantly moistened with 0.9% saline solution, while the preparation and testing time was kept below 8 h in total to avoid specimen disintegration [[10,](#page-6-7) [11\]](#page-6-8).

Experimental protocol

Prior to flexibility testing, an axial compressive preload of 300 N was applied to each specimen for 15 min to simulate water content loss of the intervertebral disc in daily life [[12](#page-6-9)]. Flexibility testing started on intact motion segments (hereafter referred to as INTACT), followed by stepwise resection of anatomical structures (Fig. [1](#page-2-0)) with subsequent fexibility tests according to the study protocol of Heuer et al. [[2](#page-6-1)]. In the frst resection step, the supraspinous ligament was cut (w/o SSL) using a disposable scalpel (#11, Aesculap AG,

BMD bone mineral density, *BMI* body mass index, *SD* standard deviation

Fig. 1 Resection steps in the present in vitro study: *0* Intact condition (INTACT), *1* without supraspinous ligament (w/o SSL), *2* without interspinous ligament (w/o ISL), *3* without faval ligament (w/o FL), *4* without facet joint capsules (w/o FC), *5* without vertebral arch (w/o

Tuttlingen, Germany), followed by the resections of the interspinous ligament (w/o ISL), the faval ligament (w/o FL), and the facet joint capsules (w/o FC). In the ffth resection step, the vertebral arch (w/o VA) was removed by carefully cutting the respective bony portions without damaging the posterior longitudinal ligament using an oscillating saw (OR-SY-518.01, Synthes GmbH, Zuchwil, Switzerland). Subsequently, the posterior longitudinal ligament (w/o PLL) was resected. In the seventh step, the anterior longitudinal ligament was removed by carefully detaching it from the intervertebral disc and subsequent cutting (w/o ALL). In the last resection step, the nucleus pulposus was removed (w/o NUC) on the left side of the intervertebral disc using a scalpel and a standard rongeur (Ulrich medical GmbH, Ulm, Germany).

Flexibility testing and motion analysis

For biomechanical testing, the specimens were loaded with pure moments of ± 1 Nm and ± 2.5 Nm using a wellestablished spine tester (Fig. [2\)](#page-2-1), which consists of three independent stepper motors generating the displacement and a 6 degree-of-freedom load cell measuring the applied moment in the respective motion plane, allowing almost unconstrained movement around all three rotational axes due to balancing weights [[13](#page-6-10)]. Flexibility testing was

VA), *6* without posterior longitudinal ligament (w/o PLL), *7* without anterior longitudinal ligament (w/o ALL), *8* without nucleus pulposus (w/o NUC)

Fig. 2 Illustration of the test setup for the present in vitro study

performed quasi-statically and displacement-controlled with a constant rate of 1°/s in fexion/extension, lateral bending, and axial rotation. For each fexibility test, 3.5 loading cycles were applied, of which the last cycle was used for data evaluation, whereas the frst two loading cycles served to minimize viscoelastic efects of the specimen [[10](#page-6-7)].

Triggered by the start and stop signals of the stepper motors, contact-free motion analysis of the relative motions was performed using the optical tracking system Vicon MX13 (Vicon Motion Systems Ltd., Oxford, UK) consisting of six cameras. For this, three refective markers per vertebra were fxed to the PMMA embeddings in order to measure the in-plane and out-of-plane motions (Fig. [2](#page-2-1)). This methodology was already used in previous in vitro studies investigating thoracic spinal stability with and without the rib cage [\[9](#page-6-6), [16](#page-6-11), [18](#page-6-12)].

Data evaluation and statistics

The ranges of motion (ROM) and the neutral zones (NZ) were evaluated using a MATLAB script (MathWorks Inc., Natick, USA). Data processing was conducted using Microsoft Excel (Microsoft Corp., Redmond, USA), while statistical analysis was performed using the statistics software SPSS (IBM Corp., Armonk, USA). First, a Shapiro–Wilk test was carried out to verify the non-normal distribution of the cumulated data of the single groups, followed by a general nonparametric test for more than two conditions (Friedman test) to prove the signifcant trend. If the *p* value was below 0.05, a Wilcoxon signed-rank test was performed to identify the statistically signifcant diferences between the anatomical resection steps. In case of *p*-values below 0.05, diferences were considered to be statistically signifcant. It was hypothesized that all resection steps destabilize the thoracic spinal motion segment.

Ethics

The use of human specimens for this in vitro study was approved by the ethical committee board of the University of Ulm, Germany (No. 302/14). The specimens were acquired from an accredited and ethically approved body donation program (Anatomy Gifts Registry, Hanover, Maryland, USA).

Results

The range of motion of the three segmental levels generally increased after each resection step, while the amount of increase depended on the segmental level and the resected structure (Figs. [3,](#page-3-0) [4,](#page-4-0) [5\)](#page-4-1).

For the segmental level T2–T3, a signifcant efect of the resection of the vertebral arch was examined in all six motion directions (Fig. [3\)](#page-3-0). The resection of the posterior longitudinal ligament increased in fexion and extension, while the resection of the facet joint capsules significantly increased the range of motion in axial rotation. One of the six specimens (No. 4, BMD 84 mgHA/ cm^3) sustained an anterior vertebral body fracture proximal to the endplate during extension movement, resulting in an immediate failure of the sample.

The motion segment T6–T7 exhibited a signifcant efect of the posterior longitudinal ligament on the range of motion in all six motion directions (Fig. [4\)](#page-4-0). A signifcant increase in the range of motion was also found after resection of the facet joint capsules in lateral bending and axial rotation. In fexion and extension, the resections of the faval ligament and the vertebral arch each led to signifcant increases in the range of motion, while the resection of the supraspinal ligament had only a signifcant efect on the range of motion in extension. In one of the six specimens (No. 7, BMD 43 mgHA/cm³), a posterior vertebral body fracture proximal to the endplate was created during fexion movement, leading to an immediate failure.

At the segmental level T10–T11, a significant effect of the nucleotomy on the range of motion was detected in all six motion directions (Fig. [5](#page-4-1)). Resections of the vertebral arch

Fig. 3 ROM of the motion segment T2–T3 (*n*=6) in fexion, extension, right lateral bending, and left axial rotation for pure moments of 1Nm and 2.5 Nm and the different specimen conditions (p < 0.05, $\#n$ = 5)

Fig. 4 ROM of the motion segment T6–T7 (*n*=6) in fexion, extension, right lateral bending, and left axial rotation for pure moments of 1Nm and 2.5 Nm and the different specimen conditions (p < 0.05, $\#n$ = 5)

Fig. 5 ROM of the motion segment T10–T11 (*n*=6) in fexion, extension, right lateral bending, and left axial rotation for pure moments of 1Nm and 2.5 Nm and the different specimen conditions (p < 0.05)

resulted in a signifcant increase in the range of motion in axial rotation, while resections of the anterior and posterior longitudinal ligaments signifcantly increased the range of motion in fexion and extension. Additionally, the resection of the supraspinal ligament led to a signifcant increase in the range of motion in extension.

The range of motion in the intact condition was generally higher in lateral bending $(4.7^{\circ}/5.3^{\circ}/3.8^{\circ})$ and axial rotation (4.9°/5.1°/4.2°) than in fexion/extension (3.9°/3.0°/2.7°). After resecting all structures up to the anulus fbrosus, the highest relative increases in the range of motion were found in flexion/extension $(+184\%, +151\%, +150\%)$, while the relative increases in the ranges of motion in axial rotation $(+120\%, +75\%, +55\%)$ and lateral bending $(+76\%, +69\%,$ $+35\%$) were distinctly lower. In flexion/extension, the resection of the vertebral arch had the biggest effect on the increase in the range of motion $(+43\%, +25\%, +28\%)$, followed by the resection of the posterior longitudinal ligament $(+19\%, +13\%, +30\%)$. In lateral bending and axial rotation,

the nucleotomy caused the biggest increase in the range of motion $(+34\%, +20\%, +11\% \text{ and } +24\%, +17\%, +20\%).$ Coupled motions were not detected, with the exception of a small trend towards a contralateral secondary axial rotation during primary lateral bending in the motion segment T2–T3 after resection of the longitudinal ligaments and nucleotomy.

All results including range of motion and neutral zone values, coupled motions, and comparisons with the data of Heuer et al. [[2\]](#page-6-1) are available in the supplementary material fle within the electronical version of this publication.

Discussion

In the present study, the efects of stepwise, cumulative defects on the stability of three thoracic segmental levels under diferent loading magnitudes were investigated. The purposes of the study were to understand the roles of the single anatomical structures in stabilizing the thoracic spine and to provide essential data for the calibration of fnite element models of the thoracic spine. Therefore, the resection sequence of the present study was selected to be comparable to the fndings of Heuer et al. [[2\]](#page-6-1) in order to calibrate numerical models of the thoracic spine in the same way as lumbar spinal models [[1\]](#page-6-0).

The results showed that the range of motion increases after every resection step in all three primary motion directions, while there are no distinct changes in the three-dimensional motion characteristics. Since the anulus fbrosus represented the last remaining structure, it seems to defne the motion qualitatively, while the ligaments and the nucleus pulposus restrict the mobility of a motion segment solely in a quantitative manner. The highest relative increase in the range of motion was generally observed after nucleotomy in all motion directions, indicating that the presence of the nucleus pulposus is the most important factor in the stabilization of thoracic spinal motion segments by pretensioning of the anulus fbrosus fbres, leading to an increased stifness of the intervertebral disc.

For the frst three resection steps, generally a low efect on the range of motion was found. Therefore, it can be assumed that the posterior ligaments do not predominantly serve for primary stability but for the prevention of hyperfexion due to their distal positions and consequently their long lever arms. Furthermore, it can be derived from the results that the vertebral arch mostly stabilizes the thoracic spinal motion segment in fexion and extension movement, while the facet joint capsules mainly provide stability against axial rotation movement.

Comparing the results with the literature, the range of motion values was within the data range of previous in vitro studies on thoracic spinal motion segments applying pure moments ranging from 1.5 to 8 Nm [[14\]](#page-6-13), but distinctly lower than in the study of Wilke et al. [[15\]](#page-6-14) using pure moments of 7.5 Nm. Studies which tested the thoracic spine polysegmentally including the rib cage detected lower range of motion values, indicating additional stabilizing efects of the rib cage [[7–](#page-6-5)[9](#page-6-6), [16](#page-6-11)]. Further results of previous studies also imply that there are possible efects of the specimen length [[17](#page-6-15)], compressive follower load due to bodyweight [[18](#page-6-12)], as well as intervertebral disc degeneration and narrowing discs [[19\]](#page-6-16). In the in vitro study of Wollowick et al., anterior structure release generated more axial rotation than posterior osteotomy [[20](#page-6-17)], indicating, in accordance with the results of the present study, that the posterior structures do not primarily stabilize the thoracic spinal motion segment. In the present study, particularly the posterior ligaments were shown to have a limited efect on segmental stability, which does, however, not apply for the whole ligamentous apparatus, since it can be expected that every ligament fulfls a certain stabilizing function due to its specifc morphology, stifness, and location [\[3,](#page-6-2)

[21\]](#page-6-18). In the literature, it is assumed that the anterior longitudinal ligament especially limits extension motions due to its higher cross-sectional area compared to other ligaments, which decreases in inferior direction, whereas the posterior longitudinal ligament is considered to limit fexion motions, particularly in the midthoracic region, where it exhibits its highest strength [[21](#page-6-18)]. It is known that these two ligaments are generally thicker in the thoracic spine than in the other sections [\[3\]](#page-6-2), partially explaining their higher stabilizing effect compared with the other ligaments in the present study. Furthermore, it can be assumed that the anatomical structures of a thoracic functional spinal unit do not afect its coupled motion characteristics, since there were no distinct secondary motions observed in the present study, indicating a dominant role of the thoracic kyphosis in generating coupled motions [[18\]](#page-6-12).

The present study entails some limitations regarding study design and testing methods which should be taken into account when calibrating numerical models. First, the order of resection could have afected the relative diferences between the single resection steps. Furthermore, an efect of left-sided nucleotomy on the motion behaviour could not be detected. Another limitation of the present study is that the loading protocol could have infuenced the results of the present study. Since the spine is loaded by compressive forces in upright position, an additional axial preload would have been appropriate to simulate more physiological loading, especially with regard to load transmission by the facet joints. In the present study, however, additional preloading was not performed due to further limitations in experimental testing: frst, the results of the present study should be comparable with the study of Heuer et al., who did not use axial preloading [\[2](#page-6-1)], second, axial preloads were expected to lead to major artefacts in the resulting load–displacement curves, potentially making the results hardly comparable, and third, axial preloads were assumed to facilitate early specimen failure during the process of stepwise resection of the single structures. In spinal in vitro testing, it is recommended to load thoracic spinal motion segments with pure moments of 5 Nm. In the present in vitro study, however, the application of higher moments than 2.5 Nm was not feasible because the structures became too weak due to the resection of stabilizing structures. As a result, two specimens could not be fully included in the data evaluation because of vertebral body fractures, potentially inhibiting signifcant efects of the nucleotomy in the upper and midthoracic segmental levels. Finally, rib cage structures were not included in the experimental protocol, although showing distinct stabilizing effects $[7-9]$ $[7-9]$ $[7-9]$ $[7-9]$. However, these effects should be considered when calibrating numerical models of the thoracic spine.

Conclusions

The range of motion of thoracic spinal motion segments is lower than in the lumbar spine, while the ligamentous structures exhibit similar stabilizing properties. In the thoracic spine, the anulus fbrosus determines the qualitative motion characteristics, whereas the ligaments and the nucleus pulposus are quantitative motion limiters. Coupled motions are not caused by the anatomical structures of the thoracic functional spinal unit, but most probably by the thoracic kyphosis. The data produced in this study can be used for the calibration of numerical models of the thoracic spine. Using these models, novel surgical treatments of spinal deformities, fractures, and tumours can be developed and optimized.

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Compliance with ethical standards

Conflict of interest The authors of this study declare that they have no confict of interest to disclose.

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Afliations

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