



Convex hypersurfaces with prescribed scalar curvature and asymptotic boundary in hyperbolic space

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Abstract

The existence of a smooth complete strictly locally convex hypersurface with prescribed scalar curvature and asymptotic boundary at infinity in \mathbb{H}^3 is proved under the assumption that there exists a strictly locally convex subsolution.

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1 Introduction

In this paper, we are concerned with the asymptotic Plateau type problem in hyperbolic space \mathbb{H}^{n+1} : to find a complete strictly locally convex hypersurface Σ with prescribed curvature and asymptotic boundary at infinity. For hyperbolic space, we will use the half-space model

$$\mathbb{H}^{n+1} = \{(x, x_{n+1}) \in \mathbb{R}^{n+1} \mid x = (x_1, \dots, x_n) \in \mathbb{R}^n, x_{n+1} > 0\}$$

equipped with the hyperbolic metric

$$ds^2 = \frac{1}{x_{n+1}^2} \sum_{i=1}^{n+1} dx_i^2.$$

The ideal boundary at infinity of \mathbb{H}^{n+1} can be identified with

$$\partial_\infty \mathbb{H}^{n+1} = \mathbb{R}^n = \mathbb{R}^n \times \{0\} \subset \mathbb{R}^{n+1}$$

and the asymptotic boundary Γ of Σ is given at $\partial_\infty \mathbb{H}^{n+1}$, which consists of a disjoint collection of smooth closed embedded $(n-1)$ dimensional submanifolds $\{\Gamma_1, \dots, \Gamma_m\}$. Given a positive function $\psi \in C^\infty(\mathbb{H}^{n+1})$, we are interested in finding a complete strictly locally convex hypersurfaces Σ in \mathbb{H}^{n+1} satisfying the curvature equation

$$f(\kappa) = \sigma_k^{1/k}(\kappa) = \psi^{1/k}(\mathbf{x}) \quad (1.1)$$

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as well as with the asymptotic boundary

$$\partial \Sigma = \Gamma, \tag{1.2}$$

where \mathbf{x} is a conformal Killing field which will be specified in Sect. 6, $\kappa = (\kappa_1, \dots, \kappa_n)$ are the hyperbolic principal curvatures of Σ at \mathbf{x} , and

$$\sigma_k(\lambda) = \sum_{1 \leq i_1 < \dots < i_k \leq n} \lambda_{i_1} \cdots \lambda_{i_k}$$

is the k -th elementary symmetric function defined on k -th Gårding’s cone

$$\Gamma_k \equiv \{\lambda \in \mathbb{R}^n \mid \sigma_j(\lambda) > 0, \quad j = 1, \dots, k\}.$$

$\sigma_k(\kappa)$ is the so called k -th Weingarten curvature of Σ . In particular, the 1st, 2nd and n -th Weingarten curvature correspond to mean curvature, scalar curvature and Gauss curvature respectively. We call a hypersurface Σ strictly locally convex (locally convex) if all principal curvatures at any point of Σ are positive (nonnegative).

In this paper, all hypersurfaces are assumed to be connected and orientable. We will see from Lemma 2.1 that a strictly locally convex hypersurface in \mathbb{H}^{n+1} with compact (asymptotic) boundary must be a vertical graph over a bounded domain in \mathbb{R}^n . We thus assume the normal vector field on Σ to be upward. Write

$$\Sigma = \{(x, u(x)) \in \mathbb{R}_+^{n+1} \mid x \in \Omega\},$$

where Ω is the bounded domain on $\partial_\infty \mathbb{H}^{n+1} = \mathbb{R}^n$ enclosed by Γ . Consequently, (1.1)–(1.2) can be expressed in terms of u ,

$$\begin{cases} f(\kappa[u]) = \psi^{\frac{1}{k}}(x, u) & \text{in } \Omega, \\ u = 0 & \text{on } \Gamma. \end{cases} \tag{1.3}$$

The essential difficulty for the Plateau type problem (1.3) is due to the singularity at $u = 0$. When ψ is a positive constant, problem (1.3) has been extensively investigated in [1–5] (see also the references therein for some previous work). Their basic idea is: first, to prove the existence of a solution u^ϵ to the approximate Dirichlet problem

$$\begin{cases} f(\kappa[u]) = \psi^{\frac{1}{k}}(x, u) & \text{in } \Omega, \\ u = \epsilon & \text{on } \Gamma, \end{cases} \tag{1.4}$$

and then, to show these u^ϵ converge to a solution of (1.3) after passing to a subsequence. For general ψ , Szapiel [6] studied the existence of strictly locally convex solutions to (1.4) for $f = \sigma_n^{1/n}$, but he also assumed a very strong assumption on f (see (1.11) in [6]) which excluded the case $f = \sigma_n^{1/n}$. As far as the author knows, there is no literature which gives an existence result for the asymptotic Plateau type problem (1.3) for general ψ .

Our first task in this paper is to improve the result of [6]. As in [7], we assume the existence of a strictly locally convex subsolution $\underline{u} \in C^4(\Omega)$, that is,

$$\begin{cases} f(\kappa[\underline{u}]) \geq \psi^{\frac{1}{k}}(x, \underline{u}) & \text{in } \Omega, \\ \underline{u} = 0 & \text{on } \Gamma. \end{cases} \tag{1.5}$$

Different from [2–6], we take a new approximate Dirichlet problem

$$\begin{cases} f(\kappa[u]) = \psi^{\frac{1}{k}}(x, u) & \text{in } \Omega_\epsilon, \\ u = \epsilon & \text{on } \Gamma_\epsilon, \end{cases} \tag{1.6}$$

where the ϵ -level set of \underline{u} and its enclosed region in \mathbb{R}^n are respectively

$$\Gamma_\epsilon = \{x \in \Omega \mid \underline{u}(x) = \epsilon\} \text{ and } \Omega_\epsilon = \{x \in \Omega \mid \underline{u}(x) > \epsilon\}.$$

We may assume the dimension of Γ_ϵ is $(n - 1)$ by Sard’s theorem, and in addition, $\Gamma_\epsilon \in C^4$.

A crucial step for proving the existence of a strictly locally convex solution to (1.6) is to establish second order a priori estimates for strictly locally convex solutions u of (1.6) satisfying $u \geq \underline{u}$ on Ω_ϵ . An essential difference from [2–5] is that we allow the C^2 bound to depend on ϵ . This looser requirement gives us more flexibility to apply techniques for general Dirichlet problem and with less technical assumptions (for example, there is no prescribed upper bound for ψ). For C^2 boundary estimates, we change the variable from u to v by $u = \sqrt{v}$ (see [8] for a similar idea for radial graphs), which is the main difference from [2,6] and fundamentally improves the result in [6].

One reason that we purely study strictly locally convex hypersurfaces is due to C^2 boundary estimates. In [3], Guan-Spruck assumed Γ to be mean convex. Then the solution u behaves nicely near Γ and therefore k -admissible solutions can be studied in their framework. However, without any geometric assumptions on Γ_ϵ , C^2 boundary estimates can only be obtained for strictly locally convex hypersurfaces.

In order to apply continuity method and degree theory to prove the existence of a strictly locally convex solution to (1.6), the strict local convexity has to be preserved during the continuity process. This is true when $k = n$ in view of the nondegeneracy of (1.6), while for $1 \leq k < n$, we have to impose certain assumptions on Ω , \underline{u} and ψ to guarantee the full rank of the second fundamental form on locally convex Σ up to the boundary. In this paper, we want to apply the constant rank theorem developed in [9–11] to Dirichlet boundary value problems when assuming a subsolution. For this, we assume

$$\left\{ \left(\frac{\underline{u}}{f(\kappa[\underline{u}])} \right)_{x_\alpha x_\beta} \right\}_{n \times n} \geq 0, \tag{1.7}$$

$$\begin{pmatrix} \frac{k+1}{k} \frac{\psi_{x_\alpha} \psi_{x_\beta}}{\psi} - \psi_{x_\alpha x_\beta} - \frac{k\psi}{u^2} \delta_{\alpha\beta} + \frac{\psi_u}{u} \delta_{\alpha\beta} & \frac{k+1}{k} \frac{\psi_{x_\alpha} \psi_u}{\psi} - \psi_{x_\alpha u} - \frac{\psi_{x_\alpha}}{u} \\ \frac{k+1}{k} \frac{\psi_{x_\alpha} \psi_u}{\psi} - \psi_{x_\alpha u} - \frac{\psi_{x_\alpha}}{u} & \frac{k+1}{k} \frac{\psi_u^2}{\psi} - \psi_{uu} - \frac{k\psi}{u^2} - \frac{\psi_u}{u} \end{pmatrix} \geq 0. \tag{1.8}$$

Besides, we also need a condition which can guarantee that locally convex solutions to the associated equations of (1.6) are strictly locally convex near the boundary Γ_ϵ . However, we did not find such a condition. Therefore, our existence results are limited to $k = n$.

Theorem 1.1 *Under the subsolution condition (1.5), for $k = n$, there exists a smooth strictly locally convex solution u^ϵ to the Dirichlet problem (1.6) with $u^\epsilon \geq \underline{u}$ in Ω_ϵ .*

Our second task in this paper is to solve (1.3). A central issue is to provide certain uniform C^2 bound for u^ϵ . Different from [2–5], where the authors derived uniform bound for certain quantities regarding solutions of (1.4) under certain assumptions, we use (1.6) as an approximate Dirichlet problem and tolerate the ϵ -dependent C^2 bound for solutions to (1.6), since we are able to use the idea of Guan-Qiu [12], who established C^2 interior estimates for convex hypersurfaces with prescribed scalar curvature in \mathbb{R}^{n+1} . We extend their estimates to \mathbb{H}^{n+1} , which, together with Evans-Krylov interior estimates (see [13,14]) and standard diagonal process, lead to the following existence result. Since the pure C^2 interior estimates can only be derived up to scalar curvature equations (see Pogorelov [15] and Urbas [16] for counterexamples when $k \geq 3$), we hope to investigate the cases $k \geq 3$ in future work by other means. Meanwhile, interior C^2 estimates are limited to hypersurfaces satisfying certain convexity property (see [12]), which also explains why we only focus on strictly locally convex hypersurfaces.

Theorem 1.2 *In \mathbb{H}^3 , for $f = \sigma_2^{1/2}$, under the subsolution condition (1.5), there exists a smooth strictly locally convex solution $u \geq \underline{u}$ to (1.3) on Ω , equivalently, there exists a smooth complete strictly locally convex vertical graph solving (1.1)–(1.2).*

This paper is organized as follows: in Sect. 2, we provide some basic formulae, properties and calculations for vertical graphs. The C^2 estimates for strictly locally convex solutions of (1.6) are presented in Sects. 3 and 4. In Sect. 5, we prove Theorem 1.1 via continuity method and degree theory. Section 6 provides the interior C^2 estimates for convex solutions to prescribed scalar curvature equations in \mathbb{H}^{n+1} , which finishes the proof of Theorem 1.2.

2 Vertical graphs

Suppose Σ is locally represented as the graph of a positive C^2 function over a domain $\Omega \subset \mathbb{R}^n$:

$$\Sigma = \{(x, u(x)) \in \mathbb{R}_+^{n+1} \mid x \in \Omega\}.$$

Since the coordinate vector fields on Σ are

$$\partial_i + u_i \partial_{n+1}, \quad i = 1, \dots, n \quad \text{where} \quad \partial_i = \frac{\partial}{\partial x_i},$$

thus the upward Euclidean unit normal vector field to Σ , the Euclidean metric, its inverse and the Euclidean second fundamental form of Σ are given respectively by

$$v = \left(\frac{-Du}{w}, \frac{1}{w} \right), \quad w = \sqrt{1 + |Du|^2},$$

$$\tilde{g}_{ij} = \delta_{ij} + u_i u_j, \quad \tilde{g}^{ij} = \delta_{ij} - \frac{u_i u_j}{w^2}, \quad \tilde{h}_{ij} = \frac{u_{ij}}{w}.$$

Consequently, the Euclidean principal curvatures $\tilde{\kappa}[\Sigma]$ are the eigenvalues of the symmetric matrix:

$$\tilde{a}_{ij} := \frac{1}{w} \gamma^{ik} u_{kl} \gamma^{lj},$$

where

$$\gamma^{ik} = \delta_{ik} - \frac{u_i u_k}{w(1+w)}$$

and its inverse

$$\gamma_{ik} = \delta_{ik} + \frac{u_i u_k}{1+w}, \quad \gamma_{ik} \gamma_{kj} = \tilde{g}_{ij}.$$

For geometric quantities in hyperbolic space, we first note that the upward hyperbolic unit normal vector field to Σ is

$$\mathbf{n} = u v = u \left(\frac{-Du}{w}, \frac{1}{w} \right)$$

and the hyperbolic metric of Σ is

$$g_{ij} = \frac{1}{u^2} (\delta_{ij} + u_i u_j). \tag{2.1}$$

To compute the hyperbolic second fundamental form h_{ij} of Σ , applying the Christoffel symbols in \mathbb{H}^{n+1} ,

$$\Gamma_{ij}^k = \frac{1}{x_{n+1}} \left(-\delta_{ik}\delta_{n+1j} - \delta_{kj}\delta_{n+1i} + \delta_{kn+1}\delta_{ij} \right), \tag{2.2}$$

we obtain

$$\mathbf{D}_{\partial_i + u_i \partial_{n+1}} (\partial_j + u_j \partial_{n+1}) = -\frac{u_j}{x_{n+1}} \partial_i - \frac{u_i}{x_{n+1}} \partial_j + \left(\frac{\delta_{ij}}{x_{n+1}} + u_{ij} - \frac{u_i u_j}{x_{n+1}} \right) \partial_{n+1},$$

where \mathbf{D} denotes the Levi-Civita connection in \mathbb{H}^{n+1} . Therefore,

$$h_{ij} = \frac{1}{u^2 w} (\delta_{ij} + u_i u_j + uu_{ij}).$$

The hyperbolic principal curvatures $\kappa[\Sigma]$ are the eigenvalues of the symmetric matrix $A[u] = \{a_{ij}\}$:

$$a_{ij} = u^2 \gamma^{ik} h_{kl} \gamma^{lj} = \frac{1}{w} \gamma^{ik} (\delta_{kl} + u_k u_l + uu_{kl}) \gamma^{lj} = \frac{1}{w} (\delta_{ij} + u \gamma^{ik} u_{kl} \gamma^{lj}).$$

Remark 2.1 The graph of u is strictly locally convex if and only if the symmetric matrix $\{a_{ij}\}$, $\{h_{ij}\}$ or $\{\delta_{ij} + u_i u_j + uu_{ij}\}$ is positive definite.

Remark 2.2 From the above discussion, we can see that

$$h_{ij} = \frac{1}{u} \tilde{h}_{ij} + \frac{v^{n+1}}{u^2} \tilde{g}_{ij}, \tag{2.3}$$

where $v^{n+1} = v \cdot \partial_{n+1}$ and \cdot is the inner product in \mathbb{R}^{n+1} . This formula indeed holds for any local frame on any hypersurface Σ (which may not be a graph). The relation between $\kappa[\Sigma]$ and $\tilde{\kappa}[\Sigma]$ is

$$\kappa_i = u \tilde{\kappa}_i + v^{n+1}, \quad i = 1, \dots, n. \tag{2.4}$$

We observe the following phenomenon for strictly locally convex hypersurfaces in \mathbb{H}^{n+1} (see also Lemma 3.3 in [2] for a similar assertion).

Lemma 2.1 *Let Σ be a connected, orientable, strictly locally convex hypersurface in \mathbb{H}^{n+1} with a specially chosen orientation. Then Σ must be a vertical graph.*

Proof Suppose Σ is not a vertical graph. Then there exists a vertical line (of dimension 1) intersecting Σ at two distinct points p_1 and p_2 . Since Σ is orientable, we may assume that $v^{n+1}(p_1) \cdot v^{n+1}(p_2) \leq 0$. Since Σ is connected, there exists a 1-dimensional curve γ on Σ connecting p_1 and p_2 . Among the tangent hyperplanes (of dimension n) to Σ along γ , choose a vertical one which is tangent to Σ at a point p_3 . At p_3 , $v^{n+1} = 0$ and $u > 0$. By (2.4), $\tilde{\kappa}_i > 0$ for all i at p_3 . On the other hand, let P be a 2-dimensional plane passing through p_1, p_2 and p_3 . If $P \cap \Sigma$ is 1-dimensional and has nonpositive (Euclidean) curvature at p_3 with respect to v , we reach a contradiction; otherwise we take a different orientation of Σ , then Σ is either not strictly locally convex or we reach a contradiction. If $P \cap \Sigma$ is 2-dimensional, then any line on $P \cap \Sigma$ through p_3 leads to a contradiction. \square

Equation (1.1) can be written as

$$f(\kappa[u]) = f(\lambda(A[u])) = F(A[u]) = \psi^{1/k}(x, u). \tag{2.5}$$

Recall that the curvature function f satisfies the fundamental structure conditions

$$f_i(\lambda) \equiv \frac{\partial f(\lambda)}{\partial \lambda_i} > 0 \quad \text{in } \Gamma_k, \quad i = 1, \dots, n, \tag{2.6}$$

$$f \text{ is concave in } \Gamma_k, \tag{2.7}$$

$$f > 0 \quad \text{in } \Gamma_k, \quad f = 0 \quad \text{on } \partial\Gamma_k. \tag{2.8}$$

3 Second order boundary estimates

In this section and the next section, we derive a priori C^2 estimates for strictly locally convex solution u to the Dirichlet problem (1.6) with $u \geq \underline{u}$ in Ω_ϵ . By Evans-Krylov theory [13,14], classical continuity method and degree theory (see [17]) we prove the existence of a strictly locally convex solution to (1.6). Higher-order regularity then follows from classical Schauder theory.

Let $u \geq \underline{u}$ be a strictly locally convex function over Ω_ϵ with $u = \underline{u}$ on Γ_ϵ . We have the following C^0 estimate:

$$\underline{u} \leq u \leq \sqrt{\epsilon^2 + (\text{diam}\Omega)^2} \quad \text{in } \overline{\Omega_\epsilon}. \tag{3.1}$$

In fact, by Remark 2.1, for any $x_0 \in \Omega_\epsilon$, the function $u^2 + |x - x_0|^2$ is Euclidean strictly locally convex in Ω_ϵ , over which, we have

$$u^2 \leq u^2 + |x - x_0|^2 \leq \max_{\Gamma_\epsilon} (u^2 + |x - x_0|^2) \leq \epsilon^2 + (\text{diam}\Omega)^2.$$

Therefore we obtain (3.1).

For the gradient estimate, we perform a transformation $u = \sqrt{v}$. Denote

$$W = \sqrt{4v + |Dv|^2}.$$

The geometric quantities in Sect. 2 can be expressed in terms of v ,

$$\begin{aligned} \gamma^{ik} &= \delta_{ik} - \frac{v_i v_k}{W(2\sqrt{v} + W)}, & \gamma_{ik} &= \delta_{ik} + \frac{v_i v_k}{2\sqrt{v}(2\sqrt{v} + W)}, \\ h_{ij} &= \frac{2}{\sqrt{v}W} (\delta_{ij} + \frac{1}{2} v_{ij}), & a_{ij} &= \frac{2\sqrt{v}}{W} \gamma^{ik} (\delta_{kl} + \frac{1}{2} v_{kl}) \gamma^{lj}. \end{aligned}$$

Since the graph is strictly locally convex, v satisfies

$$\begin{cases} \Delta v + 2n > 0 & \text{in } \Omega_\epsilon, \\ v = \epsilon^2 & \text{on } \Gamma_\epsilon, \end{cases}$$

where Δ is the Laplace-Beltrami operator in \mathbb{R}^n . Let \bar{v} be the solution of

$$\begin{cases} \Delta \bar{v} + 2n = 0 & \text{in } \Omega_\epsilon, \\ \bar{v} = \epsilon^2 & \text{on } \Gamma_\epsilon. \end{cases}$$

By the comparison principle,

$$\underline{u}^2 = \underline{v} \leq v \leq \bar{v} \quad \text{in } \Omega_\epsilon.$$

Consequently,

$$|Dv| \leq C \quad \text{on } \Gamma_\epsilon, \tag{3.2}$$

where C is a positive constant depending on ϵ . Hereinafter in this section, C always denotes such a constant which may change from line to line. Equivalently,

$$|Du| \leq C \text{ on } \Gamma_\epsilon. \tag{3.3}$$

For global gradient estimate, consider the test function

$$W = \sqrt{4v + |Dv|^2}.$$

Assume its maximum is achieved at an interior point $x_0 \in \Omega_\epsilon$. Then at x_0 ,

$$W W_i = (v_{ki} + 2\delta_{ki}) v_k = 0, \quad i = 1, \dots, n.$$

Since the matrix $(v_{ki} + 2\delta_{ki})$ is positive definite, thus $v_k = 0$ for all k at x_0 . Along with (3.1) and (3.2), we obtain

$$\max_{\Omega_\epsilon} |Dv| \leq \max_{\Omega_\epsilon} \sqrt{4v + |Dv|^2} \leq \max \left\{ \max_{\Gamma_\epsilon} \sqrt{4\epsilon^2 + |Dv|^2}, 2 \max_{\Omega_\epsilon} \sqrt{v} \right\} \leq C. \tag{3.4}$$

Equivalently,

$$\max_{\Omega_\epsilon} |Du| \leq C. \tag{3.5}$$

For second order boundary estimate, we change Equ. (2.5) under the transformation $u = \sqrt{v}$ into

$$G(D^2v, Dv, v) = F(a_{ij}) = f(\lambda(a_{ij})) = \psi(x, v). \tag{3.6}$$

By direct calculation, we obtain the following formulae.

Lemma 3.1

$$\begin{aligned} G^{st} &= \frac{\partial G}{\partial v_{st}} = \frac{\sqrt{v}}{W} F^{ij} \gamma^{is} \gamma^{tj}, \\ G_v &= \frac{\partial G}{\partial v} = \left(\frac{1}{2v} - \frac{2}{W^2} \right) F^{ij} a_{ij} + \frac{v_i v_q}{W^2 v} F^{ij} a_{qj}, \\ G^s &= \frac{\partial G}{\partial v_s} = -\frac{v_s}{W^2} F^{ij} a_{ij} - \frac{W \gamma^{is} v_q + 2\sqrt{v} \gamma^{qs} v_i}{\sqrt{v} W (2\sqrt{v} + W)} F^{ij} a_{qj}. \end{aligned}$$

In addition,

$$|G^s| \leq C \text{ and } |G_v| \leq C.$$

Proof Since

$$G(D^2v, Dv, v) = F\left(\frac{2\sqrt{v}}{W} \gamma^{ik} (\delta_{kl} + \frac{1}{2} v_{kl}) \gamma^{lj}\right),$$

we have,

$$G^{st} = \frac{\partial F}{\partial a_{ij}} \frac{\partial a_{ij}}{\partial v_{st}} = \frac{\sqrt{v}}{W} F^{ij} \gamma^{is} \gamma^{tj}.$$

To compute G_v , note that

$$\frac{\partial W}{\partial v} = \frac{2}{W} \text{ and } \frac{\partial \gamma_{ik}}{\partial v} = -\frac{v_i v_k}{4v^{3/2} W}.$$

Consequently,

$$\frac{\partial \gamma^{ik}}{\partial v} = \gamma^{ip} \frac{v_p v_q}{4v^{3/2}W} \gamma^{qk}.$$

Hence,

$$\begin{aligned} G_v &= F^{ij} \left(\frac{\partial}{\partial v} \left(\frac{2\sqrt{v}}{W} \right) \gamma^{ik} (\delta_{kl} + \frac{1}{2} v_{kl}) \gamma^{lj} + \frac{4\sqrt{v}}{W} \frac{\partial \gamma^{ik}}{\partial v} (\delta_{kl} + \frac{1}{2} v_{kl}) \gamma^{lj} \right) \\ &= \left(\frac{1}{2v} - \frac{2}{W^2} \right) F^{ij} a_{ij} + \frac{\gamma^{ip} v_p v_q}{2v^{3/2}W} F^{ij} a_{qj}. \end{aligned}$$

We then obtain G_v in view of

$$\gamma^{ip} v_p = \frac{2\sqrt{v} v_i}{W}.$$

For G^s , note that

$$\begin{aligned} \frac{\partial W}{\partial v_s} &= \frac{v_s}{W}, \quad \frac{\partial \gamma^{ik}}{\partial v_s} = -\gamma^{ip} \frac{\partial \gamma_{pq}}{\partial v_s} \gamma^{qk}, \quad \text{and} \\ \frac{\partial \gamma_{pq}}{\partial v_s} &= \frac{\delta_{ps} v_q + \delta_{qs} v_p}{2\sqrt{v}(2\sqrt{v} + W)} - \frac{v_p v_q v_s}{2\sqrt{v}(2\sqrt{v} + W)^2 W} = \frac{\delta_{ps} v_q + v_p \gamma^{qs}}{2\sqrt{v}(2\sqrt{v} + W)}. \end{aligned}$$

It follows that

$$\begin{aligned} G^s &= F^{ij} \left(-\frac{2\sqrt{v} v_s}{W^3} \gamma^{ik} (\delta_{kl} + \frac{1}{2} v_{kl}) \gamma^{lj} + \frac{4\sqrt{v}}{W} \frac{\partial \gamma^{ik}}{\partial v_s} (\delta_{kl} + \frac{1}{2} v_{kl}) \gamma^{lj} \right) \\ &= -\frac{v_s}{W^2} F^{ij} a_{ij} - \frac{W \gamma^{is} v_q + 2\sqrt{v} \gamma^{qs} v_i}{\sqrt{v} W (2\sqrt{v} + W)} F^{ij} a_{qj}. \end{aligned}$$

□

For an arbitrary point on Γ_ϵ , we may assume it to be the origin of \mathbb{R}^n . Choose a coordinate system so that the positive x_n axis points to the interior normal of Γ_ϵ at the origin. There exists a uniform constant $r > 0$ such that $\Gamma_\epsilon \cap B_r(0)$ can be represented as a graph

$$x_n = \rho(x') = \frac{1}{2} \sum_{\alpha, \beta < n} B_{\alpha\beta} x_\alpha x_\beta + O(|x'|^3), \quad x' = (x_1, \dots, x_{n-1}).$$

Since

$$v = \epsilon^2 \quad \text{on } \Gamma_\epsilon,$$

or equivalently

$$v(x', \rho(x')) = \epsilon^2,$$

we have

$$v_\alpha + v_n \rho_\alpha = 0 \tag{3.7}$$

and

$$v_{\alpha\beta} + v_{\alpha n} \rho_\beta + (v_{n\beta} + v_{nn} \rho_\beta) \rho_\alpha + v_n \rho_{\alpha\beta} = 0.$$

Therefore,

$$v_{\alpha\beta}(0) = -v_n(0) \rho_{\alpha\beta}(0), \quad \alpha, \beta < n.$$

Consequently,

$$|v_{\alpha\beta}(0)| \leq C, \quad \alpha, \beta < n, \tag{3.8}$$

where C is a constant depending on ϵ .

For the mixed tangential-normal derivative $v_{\alpha n}(0)$ with $\alpha < n$, note that the graph of \underline{u} is strictly locally convex on $\overline{\Omega_\epsilon}$. Hence we have

$$I + \frac{1}{2} D^2 \underline{v} \geq 3c_0 I$$

for some positive constant c_0 . Let $d(x)$ be the distance from $x \in \overline{\Omega_\epsilon}$ to Γ_ϵ in \mathbb{R}^n . Consider the barrier function

$$\Psi = A V + B |x|^2$$

with

$$V = v - \underline{v} + \tau d - N d^2,$$

where the positive constant N, τ, B and A are to be determined.

Define the linear operator $L = G^{st} D_{st} + G^s D_s$. By the concavity of G with respect to $D^2 v$,

$$\begin{aligned} LV &= G^{st} D_{st}(v - \underline{v} - N d^2) + \tau G^{st} D_{st} d + G^s D_s(v - \underline{v} + \tau d - N d^2) \\ &\leq G(D^2 v, Dv, v) - G(D^2(\underline{v} + N d^2) - 2c_0 I, Dv, v) \\ &\quad + (C\tau - 2c_0) \sum G^{ii} + C(1 + \tau + N\delta). \end{aligned}$$

Note that

$$I + \frac{1}{2} D^2(\underline{v} + N d^2) - c_0 I \geq 2c_0 I + N Dd \otimes Dd - CN\delta I := \mathcal{H}.$$

Denote $\gamma = (\gamma^{ik})$. We have

$$\begin{aligned} G(D^2(\underline{v} + N d^2) - 2c_0 I, Dv, v) &= F\left(\frac{2\sqrt{v}}{W} \gamma (I + \frac{1}{2} D^2(\underline{v} + N d^2) - c_0 I) \gamma\right) \\ &\geq F\left(\frac{2\sqrt{v}}{W} \gamma \mathcal{H} \gamma\right) = F\left(\frac{2\sqrt{v}}{W} \mathcal{H}^{1/2} \gamma \gamma \mathcal{H}^{1/2}\right) \geq F(\tilde{c} \mathcal{H}), \end{aligned}$$

where \tilde{c} is a positive constant. Hence

$$LV \leq -F(\tilde{c} \mathcal{H}) + (C\tau - 2c_0) \sum G^{ii} + C(1 + \tau + N\delta).$$

Note that $\mathcal{H} = \text{diag}(2c_0 - CN\delta, \dots, 2c_0 - CN\delta, 2c_0 - CN\delta + N)$. We can choose N sufficiently large and τ, δ sufficiently small (δ depends on N) such that

$$C\tau \leq c_0, \quad CN\delta \leq c_0, \quad -F(\tilde{c} \mathcal{H}) + C + 2c_0 \leq -1.$$

Hence the above inequality becomes

$$LV \leq -c_0 \sum G^{ii} - 1. \tag{3.9}$$

We then require $\delta \leq \frac{\tau}{N}$ so that

$$V \geq 0 \quad \text{in } \Omega_\epsilon \cap B_\delta(0).$$

By Lemma 3.1,

$$L(|x|^2) \leq C(1 + \sum G^{ii}).$$

This, together with (3.9) yields,

$$L\Psi \leq A(-c_0 \sum G^{ii} - 1) + BC(1 + \sum G^{ii}) \quad \text{in } \Omega_\epsilon \cap B_\delta(0). \tag{3.10}$$

Now, we consider the operator

$$T = \partial_\alpha + \sum_{\beta < n} B_{\alpha\beta}(x_\beta \partial_n - x_n \partial_\beta).$$

Note that for $\delta > 0$ sufficiently small,

$$|Tv| \leq C \quad \text{in } \Omega_\epsilon \cap B_\delta(0).$$

Also, in view of (3.7),

$$|Tv| \leq C|x|^2 \quad \text{on } \Gamma_\epsilon \cap B_\delta(0).$$

To compute $L(Tv)$, we need the following lemma (see [2]).

Lemma 3.2 For $1 \leq i, j \leq n$,

$$(L + G_v - \psi_v)(x_i v_j - x_j v_i) = x_i \psi_{x_j} - x_j \psi_{x_i}.$$

Proof For $\theta \in \mathbb{R}$, let

$$\begin{aligned} y_i &= x_i \cos \theta - x_j \sin \theta, \\ y_j &= x_i \sin \theta + x_j \cos \theta, \\ y_k &= x_k, \quad k \neq i, j. \end{aligned}$$

Since $G - \psi$ is invariant for the rotations of \mathbb{R}^n , we have

$$G(D^2v(y), Dv(y), v(y)) = \psi(y, v(y)).$$

Differentiate with respect to θ and change the order of differentiation,

$$(L + G_v - \psi_v)|_y \frac{\partial v}{\partial \theta} = \psi_{y_i} \frac{\partial y_i}{\partial \theta} + \psi_{y_j} \frac{\partial y_j}{\partial \theta}.$$

Set $\theta = 0$ in the above equality and notice that at $\theta = 0$,

$$y = x, \quad \frac{\partial y_i}{\partial \theta} = -x_j, \quad \frac{\partial y_j}{\partial \theta} = x_i, \quad \frac{\partial v}{\partial \theta} = x_i v_j - x_j v_i.$$

We thus proved the lemma. □

By Lemma 3.2 and 3.1, we have

$$|L(Tv)| \leq C. \tag{3.11}$$

Choose B sufficiently large such that

$$\Psi \pm Tv \geq 0 \quad \text{on } \partial(\Omega_\epsilon \cap B_\delta(0)).$$

From (3.10) and (3.11) we have

$$L(\Psi \pm Tv) \leq A(-c_0 \sum G^{ii} - 1) + BC(1 + \sum G^{ii}) + C.$$

Choose A sufficiently large such that

$$L(\Psi \pm Tv) \leq 0 \quad \text{in } \Omega_\epsilon \cap B_\delta(0).$$

By the maximum principle,

$$\Psi \pm Tv \geq 0 \quad \text{in } \Omega_\epsilon \cap B_\delta(0),$$

which implies

$$|v_{\alpha n}(0)| \leq C. \tag{3.12}$$

Up to now, we have proved that

$$|v_{\xi\eta}(x)| \leq C, \quad |v_{\xi\gamma}(x)| \leq C, \quad \forall x \in \Gamma_\epsilon,$$

where ξ and η are any unit tangential vectors and γ the unit interior normal vector to Γ_ϵ on Ω_ϵ . It suffices to give an upper bound

$$v_{\gamma\gamma} \leq C \quad \text{on } \Gamma_\epsilon. \tag{3.13}$$

Motivated by [18] (see also [19,20]), we derive (3.13).

First recall some general facts. The projection of $\Gamma_k \subset \mathbb{R}^n$ onto \mathbb{R}^{n-1} is exactly

$$\Gamma'_{k-1} = \{(\lambda_1, \dots, \lambda_{n-1}) \in \mathbb{R}^{n-1} \mid \sigma_j(\lambda_1, \dots, \lambda_{n-1}) > 0, \quad j = 1, \dots, k-1\}.$$

Let $\kappa' = (\kappa'_1, \dots, \kappa'_{n-1})$ be the roots of

$$\det(\kappa'_\zeta g_{\alpha\beta} - h_{\alpha\beta}) = 0, \tag{3.14}$$

where $(h_{\alpha\beta})$ and $(g_{\alpha\beta})$ are the first $(n-1) \times (n-1)$ principal minors of (h_{ij}) and (g_{ij}) respectively. Then $\kappa[v] \in \Gamma_k$ implies $\kappa'[v] \in \Gamma'_{k-1}$, and this is true for any local frame field. Note that $\kappa'[v]$ may not be $(\kappa_1, \dots, \kappa_{n-1})[v]$.

For $x \in \Gamma_\epsilon$, let the indices in (3.14) be given by the tangential directions to Γ_ϵ and $\kappa'[v](x)$ be the roots of (3.14). Define

$$\tilde{d}(x) = \sqrt{v} W \operatorname{dist}(\kappa'[v](x), \partial\Gamma'_{k-1}) \quad \text{and} \quad m = \min_{x \in \Gamma_\epsilon} \tilde{d}(x).$$

Choose a coordinate system in \mathbb{R}^n such that m is achieved at $0 \in \Gamma_\epsilon$ and the positive x_n axis points to the interior normal of Γ_ϵ at 0. We want to prove that m has a uniform positive lower bound.

Let $\xi_1, \dots, \xi_{n-1}, \gamma$ be a local frame field around 0 on Ω_ϵ , obtained by parallel translation of a local frame field ξ_1, \dots, ξ_{n-1} around 0 on Γ_ϵ satisfying

$$g_{\alpha\beta} = \delta_{\alpha\beta}, \quad h_{\alpha\beta}(0) = \kappa'_\alpha(0) \delta_{\alpha\beta}, \quad \kappa'_1(0) \leq \dots \leq \kappa'_{n-1}(0)$$

and the interior, unit, normal vector field γ to Γ_ϵ , along the directions perpendicular to Γ_ϵ on Ω_ϵ . We can see that this choice of frame field has nothing to do with v (or equivalently, u). In fact, if we denote

$$\xi_\alpha = \sum_{\beta=1}^{n-1} \eta_{\alpha\beta}^\beta e_\beta, \quad \alpha = 1, \dots, n-1,$$

where e_1, \dots, e_{n-1} is a fixed local orthonormal frame on Γ_ϵ , and consider a general boundary value condition, say $v = \varphi$ on Γ_ϵ , then on Γ_ϵ ,

$$\begin{aligned} g_{\alpha\beta} &= \frac{1}{u^2} \left(\xi_\alpha \cdot \xi_\beta + D_{\xi_\alpha} u D_{\xi_\beta} u \right) = \frac{1}{\varphi} \left(\xi_\alpha \cdot \xi_\beta + D_{\xi_\alpha}(\sqrt{\varphi}) D_{\xi_\beta}(\sqrt{\varphi}) \right) \\ &= \frac{1}{\varphi} \sum_{\tau, \zeta=1}^{n-1} \eta_\alpha^\tau \left(\delta_{\tau\zeta} + \frac{D_{e_\tau} \varphi D_{e_\zeta} \varphi}{4\varphi} \right) \eta_\beta^\zeta. \end{aligned}$$

Note that there exist η_α^τ for $\alpha, \tau = 1, \dots, n - 1$ such that $g_{\alpha\beta} = \delta_{\alpha\beta}$ on Γ_ϵ . By a rotation, we can further make $(h_{\alpha\beta}(0))$ to be diagonal.

By Lemma 6.1 of [21], there exists $\mu = (\mu_1, \dots, \mu_{n-1}) \in \mathbb{R}^{n-1}$ with $\mu_1 \geq \dots \geq \mu_{n-1} \geq 0$ such that

$$\sum_{\alpha=1}^{n-1} \mu_\alpha^2 = 1, \quad \Gamma'_{k-1} \subset \{\lambda' \in \mathbb{R}^{n-1} \mid \mu \cdot \lambda' > 0\} \quad \text{and}$$

$$m = \tilde{d}(0) = \sqrt{v} W \sum_{\alpha < n} \mu_\alpha \kappa'_\alpha(0) = \sum_{\alpha < n} \mu_\alpha (D_{\xi_\alpha \xi_\alpha} v + 2 \xi_\alpha \cdot \xi_\alpha)(0). \tag{3.15}$$

Since \underline{v} is strictly locally convex near Γ_ϵ and $\sum \mu_\alpha \geq 1$,

$$\sum_{\alpha < n} \mu_\alpha (D_{\xi_\alpha \xi_\alpha} \underline{v} + 2 \xi_\alpha \cdot \xi_\alpha)(0) \geq 2 c_1$$

for a uniform positive constant c_1 . Consequently,

$$\begin{aligned} (\underline{v} - v)_\gamma(0) &\sum_{\alpha < n} \mu_\alpha d_{\xi_\alpha \xi_\alpha}(0) = \sum_{\alpha < n} \mu_\alpha D_{\xi_\alpha \xi_\alpha}(\underline{v} - v)(0) \\ &= \sum_{\alpha < n} \mu_\alpha (D_{\xi_\alpha \xi_\alpha} \underline{v} + 2 \xi_\alpha \cdot \xi_\alpha)(0) - \sum_{\alpha < n} \mu_\alpha (D_{\xi_\alpha \xi_\alpha} v + 2 \xi_\alpha \cdot \xi_\alpha)(0) \geq 2 c_1 - \tilde{d}(0). \end{aligned} \tag{3.16}$$

The first line in (3.16) is true, since we can write $v - \underline{v} = \omega d$ for some function ω defined in a neighborhood of Γ_ϵ in Ω_ϵ . Differentiate this identity,

$$\begin{aligned} (v - \underline{v})_i &= \omega_i d + \omega d_i, & (v - \underline{v})_\gamma &= \omega_\gamma d + \omega d_\gamma, \\ (v - \underline{v})_{ij} &= \omega_{ij} d + \omega_i d_j + \omega_j d_i + \omega d_{ij}. \end{aligned}$$

Note that $d_{\xi_\alpha}(0) = 0$ and $d_\gamma(0) = 1$. Thus,

$$D_{\xi_\alpha \xi_\alpha} (v - \underline{v})(0) = (v - \underline{v})_\gamma(0) d_{\xi_\alpha \xi_\alpha}(0).$$

We may assume $\tilde{d}(0) \leq c_1$, for, otherwise we are done. Then from (3.16),

$$(\underline{v} - v)_\gamma(0) \sum_{\alpha < n} \mu_\alpha d_{\xi_\alpha \xi_\alpha}(0) \geq c_1.$$

Since $0 < (v - \underline{v})_\gamma(0) \leq C$,

$$\sum_{\alpha < n} \mu_\alpha d_{\xi_\alpha \xi_\alpha}(0) \leq -2 c_2$$

for some uniform constant $c_2 > 0$. By continuity of $d_{\xi_\alpha \xi_\alpha}(x)$ at 0 and $0 \leq \mu_\alpha \leq 1$,

$$\sum_{\alpha < n} \mu_\alpha \left(d_{\xi_\alpha \xi_\alpha}(x) - d_{\xi_\alpha \xi_\alpha}(0) \right) < \sum_{\alpha < n} \mu_\alpha \frac{c_2}{n-1} \leq c_2 \quad \text{in } \Omega_\epsilon \cap B_\delta(0)$$

for some uniform constant $\delta > 0$. Thus

$$\sum_{\alpha < n} \mu_\alpha d_{\xi_\alpha \xi_\alpha}(x) < -c_2 \quad \text{in } \Omega_\epsilon \cap B_\delta(0). \tag{3.17}$$

On the other hand, by Lemma 6.2 of [21], for any $x \in \Gamma_\epsilon$ near 0,

$$\begin{aligned} \sum_{\alpha < n} \mu_\alpha \left(D_{\xi_\alpha \xi_\alpha} v + 2 \xi_\alpha \cdot \xi_\alpha \right)(x) &= \sum_{\alpha < n} \mu_\alpha \sqrt{v} W h_{\alpha\alpha}(x) \\ &\geq \sqrt{v} W \sum_{\alpha < n} \mu_\alpha \kappa'_\alpha[v](x) \geq \tilde{d}(x) \geq \tilde{d}(0). \end{aligned}$$

Thus for any $x \in \Gamma_\epsilon$ near 0,

$$\begin{aligned} (v - \varphi)_\gamma(x) \sum_{\alpha < n} \mu_\alpha d_{\xi_\alpha \xi_\alpha}(x) &= \sum_{\alpha < n} \mu_\alpha D_{\xi_\alpha \xi_\alpha}(v - \varphi)(x) \\ &= \sum_{\alpha < n} \mu_\alpha \left(D_{\xi_\alpha \xi_\alpha} v + 2 \xi_\alpha \cdot \xi_\alpha \right)(x) - \sum_{\alpha < n} \mu_\alpha \left(D_{\xi_\alpha \xi_\alpha} \varphi + 2 \xi_\alpha \cdot \xi_\alpha \right)(x) \\ &\geq \tilde{d}(0) - \sum_{\alpha < n} \mu_\alpha \left(D_{\xi_\alpha \xi_\alpha} \varphi + 2 \xi_\alpha \cdot \xi_\alpha \right)(x). \end{aligned} \tag{3.18}$$

In view of (3.17), define in $\Omega_\epsilon \cap B_\delta(0)$,

$$\Phi = \frac{1}{\sum_{\alpha < n} \mu_\alpha d_{\xi_\alpha \xi_\alpha}} \left(\tilde{d}(0) - \sum_{\alpha < n} \mu_\alpha \left(D_{\xi_\alpha \xi_\alpha} \varphi + 2 \xi_\alpha \cdot \xi_\alpha \right) \right) - (v - \varphi)_\gamma.$$

By (3.17) and (3.18), $\Phi \geq 0$ on $\Gamma_\epsilon \cap B_\delta(0)$. In addition, we have in $\Omega_\epsilon \cap B_\delta(0)$,

$$L(\Phi) \leq C(1 + \sum G^{ii}) - L(D(v - \varphi) \cdot Dd) \leq C(1 + \sum G^{ii}). \tag{3.19}$$

This is because $0 \leq \mu_\alpha \leq 1$ and

$$\begin{aligned} \left| L(D(v - \varphi) \cdot Dd) \right| &= \left| Dd \cdot L(D(v - \varphi)) + D(v - \varphi) \cdot L(Dd) + 2G^{st}(v - \varphi)_{is} d_{it} \right| \\ &\leq C(1 + \sum G^{ii}) + \left| 2G^{st} d_{it} \left(\frac{W}{\sqrt{v}} \gamma_{ki} \gamma_{sl} a_{kl} - 2\delta_{is} \right) \right| \\ &= C(1 + \sum G^{ii}) + \left| 2\gamma_{ki} d_{it} \gamma^{tj} F^{lj} a_{kl} - 4G^{st} d_{st} \right| \leq C(1 + \sum G^{ii}). \end{aligned}$$

By (3.10) and (3.19), we may choose $A \gg B \gg 1$ such that $\Psi + \Phi \geq 0$ on $\partial(\Omega_\epsilon \cap B_\delta(0))$ and $L(\Psi + \Phi) \leq 0$ in $\Omega_\epsilon \cap B_\delta(0)$. By the maximum principle, $\Psi + \Phi \geq 0$ in $\Omega_\epsilon \cap B_\delta(0)$. Since $(\Psi + \Phi)(0) = 0$ by (3.18) and (3.15), we have $(\Psi + \Phi)_n(0) \geq 0$. Therefore, $v_{nn}(0) \leq C$, which, together with (3.8) and (3.12), gives a bound $|D^2 v(0)| \leq C$, and consequently a bound for all the principal curvatures at 0. By (2.8),

$$\text{dist}(\kappa[v](0), \partial\Gamma_k) \geq c_3$$

and therefore on Γ_ϵ ,

$$\tilde{d}(x) \geq \tilde{d}(0) = \sqrt{v} W \text{dist}(\kappa'[v](0), \partial\Gamma'_{k-1}) \geq c_4,$$

where c_3 and c_4 are positive uniform constants.

By a proof similar to Lemma 1.2 of [21], we know that there exists $R > 0$ depending on the bounds (3.8) and (3.12) such that if $v_{\gamma\gamma}(x_0) \geq R$ and $x_0 \in \Gamma_\epsilon$, then the principal curvatures $(\kappa_1, \dots, \kappa_n)$ at x_0 satisfy

$$\begin{aligned} \kappa_\alpha &= \kappa'_\alpha + o(1), \quad \alpha < n, \\ \kappa_n &= \frac{h_{nn} - g_{1n}h_{n1} - \dots - g_{nn-1}h_{nn-1}}{g_{nn} - g_{1n}^2 - \dots - g_{nn-1}^2} \left(1 + \mathcal{O}\left(\frac{g_{nn} - g_{1n}^2 - \dots - g_{nn-1}^2}{h_{nn} - g_{1n}h_{n1} - \dots - g_{nn-1}h_{nn-1}} \right) \right) \end{aligned}$$

in the local frame $\xi_1, \dots, \xi_{n-1}, \gamma$ around x_0 . When R is sufficiently large, we have

$$G(D^2v, Dv, v)(x_0) > \psi(x_0, \epsilon^2),$$

contradicting with Equ. (3.6). Hence $v_{\gamma\gamma} < R$ on Γ_ϵ . (3.13) is proved.

4 Global curvature estimates

For a hypersurface $\Sigma \subset \mathbb{H}^{n+1}$, let g and ∇ be the induced hyperbolic metric and Levi-Civita connection on Σ respectively, and let \tilde{g} and $\tilde{\nabla}$ be the metric and Levi-Civita connection induced from \mathbb{R}^{n+1} when Σ is viewed as a hypersurface in \mathbb{R}^{n+1} . The Christoffel symbols associated with ∇ and $\tilde{\nabla}$ are related by the formula

$$\Gamma_{ij}^k = \tilde{\Gamma}_{ij}^k - \frac{1}{u}(u_i\delta_{kj} + u_j\delta_{ik} - \tilde{g}^{kl}u_l\tilde{g}_{ij}).$$

Consequently, for any $v \in C^2(\Sigma)$,

$$\nabla_{ij}v = (v_i)_j - \Gamma_{ij}^k v_k = \tilde{\nabla}_{ij}v + \frac{1}{u}(u_i v_j + u_j v_i - \tilde{g}^{kl}u_l v_k \tilde{g}_{ij}). \tag{4.1}$$

Note that (4.1) holds for any local frame.

Lemma 4.1 *In \mathbb{R}^{n+1} , we have the following identities.*

$$\tilde{g}^{kl}u_k u_l = |\tilde{\nabla}u|^2 = 1 - (v^{n+1})^2, \tag{4.2}$$

$$\tilde{\nabla}_{ij}u = \tilde{h}_{ij}v^{n+1} \text{ and } \tilde{\nabla}_{ij}x_k = \tilde{h}_{ij}v^k, \quad k = 1, \dots, n, \tag{4.3}$$

$$(v^{n+1})_i = -\tilde{h}_{ij}\tilde{g}^{jk}u_k, \tag{4.4}$$

$$\tilde{\nabla}_{ij}v^{n+1} = -\tilde{g}^{kl}(v^{n+1}\tilde{h}_{il}\tilde{h}_{kj} + u_l\tilde{\nabla}_k\tilde{h}_{ij}), \tag{4.5}$$

where τ_1, \dots, τ_n is any local frame on Σ .

Proof To prove (4.2), we may write

$$\partial_{n+1} = \sum_{k=1}^n a_k \tau_k + bv. \tag{4.6}$$

Taking inner product of (4.6) with v in \mathbb{R}^{n+1} , we obtain

$$v^{n+1} = \partial_{n+1} \cdot v = b.$$

Taking inner product of (4.6) with τ_j in \mathbb{R}^{n+1} , we have

$$u_j = (X \cdot \partial_{n+1})_j = \partial_{n+1} \cdot \tau_j = a_k \tau_k \cdot \tau_j = a_k \tilde{g}_{kj},$$

where X is the position vector field of Σ (note that this is different from the conformal Killing field when using half space model for \mathbb{H}^{n+1}). Thus,

$$a_k = u_j \tilde{g}^{jk}.$$

Therefore,

$$\partial_{n+1} = u_j \tilde{g}^{jk} \tau_k + v^{n+1} \nu = \tilde{\nabla} u + v^{n+1} \nu,$$

which implies (4.2).

For (4.3), note that

$$\begin{aligned} \tilde{\nabla}_{ij}(X \cdot \partial_k) &= ((X \cdot \partial_k)_j)_i - \tilde{\Gamma}^l_{ij}(X \cdot \partial_k)_l \\ &= (\tau_j \cdot \partial_k)_i - \tilde{\Gamma}^l_{ij} \tau_l \cdot \partial_k = \tilde{D}_{\tau_i} \tau_j \cdot \partial_k - \tilde{\Gamma}^l_{ij} \tau_l \cdot \partial_k \\ &= (\tilde{\nabla}_{\tau_i} \tau_j + \tilde{h}_{ij} \nu) \cdot \partial_k - \tilde{\Gamma}^l_{ij} \tau_l \cdot \partial_k = \tilde{h}_{ij} \nu \cdot \partial_k, \quad k = 1, \dots, n + 1. \end{aligned}$$

Here we have applied the Gauss formula for Σ as a hypersurface in \mathbb{R}^{n+1} .

For (4.4), by the Weingarten formula for Σ as a hypersurface in \mathbb{R}^{n+1} , we have

$$(v^{n+1})_i = (\nu \cdot \partial_{n+1})_i = \tilde{D}_{\tau_i} \nu \cdot \partial_{n+1} = -\tilde{h}_{ik} \tilde{g}^{kl} \tau_l \cdot \partial_{n+1} = -\tilde{h}_{ik} \tilde{g}^{kl} u_l.$$

Finally, (4.5) follows from (4.4), (4.3) and the Codazzi equation for Σ as a hypersurface in \mathbb{R}^{n+1} . In fact,

$$\tilde{\nabla}_{ij} v^{n+1} = -\tilde{g}^{kl} (u_l \tilde{\nabla}_i \tilde{h}_{jk} + \tilde{h}_{jk} \tilde{\nabla}_i u) = -\tilde{g}^{kl} (u_l \tilde{\nabla}_k \tilde{h}_{ij} + v^{n+1} \tilde{h}_{il} \tilde{h}_{jk}).$$

□

Lemma 4.2 *Let Σ be a strictly locally convex hypersurface in \mathbb{H}^{n+1} satisfying equation (2.5). Then in a local orthonormal frame on Σ ,*

$$\begin{aligned} F^{ij} \nabla_{ij} v^{n+1} &= -v^{n+1} F^{ij} h_{ik} h_{kj} + (1 + (v^{n+1})^2) F^{ij} h_{ij} - v^{n+1} \sum f_i \\ &\quad - \frac{2}{u^2} F^{ij} h_{jk} u_i u_k + \frac{2v^{n+1}}{u^2} F^{ij} u_i u_j - \frac{u_k}{u} \psi_k. \end{aligned} \tag{4.7}$$

Proof By (4.1), (4.5),

$$\begin{aligned} F^{ij} \nabla_{ij} v^{n+1} &= F^{ij} \left(\tilde{\nabla}_{ij} v^{n+1} + \frac{1}{u} (u_i (v^{n+1})_j + u_j (v^{n+1})_i - \tilde{g}^{kl} u_l (v^{n+1})_k \tilde{g}_{ij}) \right) \\ &= -\frac{v^{n+1}}{u^2} F^{ij} \tilde{h}_{ik} \tilde{h}_{kj} - \frac{u_k}{u^2} F^{ij} \tilde{\nabla}_k \tilde{h}_{ij} - \frac{2}{u^3} F^{ij} \tilde{h}_{jk} u_i u_k - \frac{u_k}{u} (v^{n+1})_k \sum f_i. \end{aligned} \tag{4.8}$$

Since Σ can also be viewed as a hypersurface in \mathbb{R}^{n+1} ,

$$F(g^{il} h_{lj}) = F\left(u^2 \tilde{g}^{il} \left(\frac{1}{u} \tilde{h}_{lj} + \frac{v^{n+1}}{u^2} \tilde{g}_{lj}\right)\right) = F\left(u \tilde{g}^{il} \tilde{h}_{lj} + v^{n+1} \delta_{ij}\right) = \psi.$$

Differentiate this equation with respect to $\tilde{\nabla}_k$ and then multiply by $\frac{u_k}{u}$,

$$\frac{u_k^2}{u^3} F^{ij} \tilde{h}_{ij} + \frac{u_k}{u^2} F^{ij} \tilde{\nabla}_k \tilde{h}_{ij} + \frac{u_k}{u} (v^{n+1})_k \sum f_i = \frac{u_k}{u} \psi_k.$$

Take this identity into (4.8),

$$F^{ij} \nabla_{ij} v^{n+1} = -\frac{v^{n+1}}{u^2} F^{ij} \tilde{h}_{ik} \tilde{h}_{kj} - \frac{2}{u^3} F^{ij} \tilde{h}_{jk} u_i u_k + \frac{u_k^2}{u^3} F^{ij} \tilde{h}_{ij} - \frac{u_k}{u} \psi_k.$$

In view of (2.3), we obtain (4.7). □

For global curvature estimates, we use the method in [4]. Assume

$$v^{n+1} \geq 2a > 0 \quad \text{on } \Sigma$$

for some constant a . Let $\kappa_{\max}(\mathbf{x})$ be the largest principal curvature of Σ at \mathbf{x} . Consider

$$M_0 = \sup_{\mathbf{x} \in \Sigma} \frac{\kappa_{\max}(\mathbf{x})}{v^{n+1} - a}.$$

Assume $M_0 > 0$ is attained at an interior point $\mathbf{x}_0 \in \Sigma$. Let τ_1, \dots, τ_n be a local orthonormal frame about \mathbf{x}_0 such that $h_{ij}(\mathbf{x}_0) = \kappa_i \delta_{ij}$, where $\kappa_1, \dots, \kappa_n$ are the hyperbolic principal curvatures of Σ at \mathbf{x}_0 . We may assume $\kappa_1 = \kappa_{\max}(\mathbf{x}_0)$. Thus, $\ln h_{11} - \ln(v^{n+1} - a)$ has a local maximum at \mathbf{x}_0 , at which,

$$\frac{h_{11i}}{h_{11}} - \frac{\nabla_i v^{n+1}}{v^{n+1} - a} = 0, \tag{4.9}$$

$$\frac{h_{11ii}}{h_{11}} - \frac{\nabla_{ii} v^{n+1}}{v^{n+1} - a} \leq 0. \tag{4.10}$$

Differentiate equation (2.5) twice,

$$F^{ii} h_{i11} + F^{ij,rs} h_{ij1} h_{rs1} = \psi_{11} \geq -C\kappa_1. \tag{4.11}$$

By Gauss equation, we have the following formula when changing the order of differentiation for the second fundamental form,

$$h_{iijj} = h_{jjii} + (\kappa_i \kappa_j - 1)(\kappa_i - \kappa_j). \tag{4.12}$$

Combining (4.10), (4.11), (4.12) and (4.7) yields,

$$\begin{aligned} & \left(\kappa_1^2 - \frac{1 + (v^{n+1})^2}{v^{n+1} - a} \kappa_1 + 1 \right) \sum f_i \kappa_i + \frac{a\kappa_1}{v^{n+1} - a} \left(\sum f_i + \sum f_i \kappa_i^2 \right) \\ & - F^{ij,rs} h_{ij1} h_{rs1} + \frac{2\kappa_1}{v^{n+1} - a} \sum f_i \frac{u_i^2}{u^2} (\kappa_i - v^{n+1}) - C\kappa_1 \leq 0. \end{aligned} \tag{4.13}$$

Next, take (4.4), (2.3) into (4.9),

$$h_{11i} = \frac{\kappa_1}{v^{n+1} - a} \frac{u_i}{u} (v^{n+1} - \kappa_i),$$

and recall an inequality of Andrews [22] and Gerhardt [23],

$$-F^{ij,rs} h_{ij1} h_{rs1} \geq \sum_{i \neq j} \frac{f_i - f_j}{\kappa_j - \kappa_i} h_{ij1}^2 \geq 2 \sum_{i \geq 2} \frac{f_i - f_1}{\kappa_1 - \kappa_i} h_{i11}^2.$$

Therefore, (4.13) becomes,

$$\begin{aligned}
 0 \geq & \left(\kappa_1^2 - \frac{1 + (v^{n+1})^2}{v^{n+1} - a} \kappa_1 + 1 \right) \sum f_i \kappa_i - C \kappa_1 + \frac{a \kappa_1}{v^{n+1} - a} \left(\sum f_i + \sum f_i \kappa_i^2 \right) \\
 & + \frac{2 \kappa_1^2}{(v^{n+1} - a)^2} \sum_{i \geq 2} \frac{f_i - f_1}{\kappa_1 - \kappa_i} \frac{u_i^2}{u^2} (v^{n+1} - \kappa_i)^2 + \frac{2 \kappa_1}{v^{n+1} - a} \sum f_i \frac{u_i^2}{u^2} (\kappa_i - v^{n+1}).
 \end{aligned}
 \tag{4.14}$$

For some fixed $\theta \in (0, 1)$ which will be determined later, denote

$$J = \{i : f_i \geq \theta f_i, \quad \kappa_i < v^{n+1}\}, \quad L = \{i : f_i < \theta f_i, \quad \kappa_i < v^{n+1}\}.$$

The second line of (4.14) can be estimated as follows.

$$\begin{aligned}
 & \frac{2 \kappa_1^2}{(v^{n+1} - a)^2} \sum_{i \geq 2} \frac{f_i - f_1}{\kappa_1 - \kappa_i} \frac{u_i^2}{u^2} (v^{n+1} - \kappa_i)^2 + \frac{2 \kappa_1}{v^{n+1} - a} \sum f_i \frac{u_i^2}{u^2} (\kappa_i - v^{n+1}) \\
 & \geq \frac{2 \kappa_1^2}{(v^{n+1} - a)^2} \sum_{i \in L} \frac{f_i - f_1}{\kappa_1 - \kappa_i} \frac{u_i^2}{u^2} (v^{n+1} - \kappa_i)^2 + \frac{2 \kappa_1}{v^{n+1} - a} \left(\sum_{i \in L} + \sum_{i \in J} \right) \frac{f_i u_i^2}{u^2} (\kappa_i - v^{n+1}) \\
 & \geq \frac{2(1 - \theta) \kappa_1}{(v^{n+1} - a)^2} \sum_{i \in L} \frac{f_i u_i^2}{u^2} (v^{n+1} - \kappa_i)^2 + \frac{2 \kappa_1}{v^{n+1} - a} \sum_{i \in L} \frac{f_i u_i^2}{u^2} (\kappa_i - v^{n+1}) - \frac{2}{\theta a} \sum f_i \kappa_i \\
 & = \frac{2 \kappa_1}{v^{n+1} - a} \sum_{i \in L} \frac{f_i u_i^2}{u^2} \left(\frac{(v^{n+1} - \kappa_i)^2}{v^{n+1} - a} + \kappa_i - v^{n+1} \right) \\
 & \quad - \frac{2 \theta \kappa_1}{(v^{n+1} - a)^2} \sum_{i \in L} \frac{f_i u_i^2}{u^2} (v^{n+1} - \kappa_i)^2 - \frac{2}{\theta a} \sum f_i \kappa_i \\
 & \geq - \frac{2 \kappa_1}{v^{n+1} - a} \sum_{i \in L} \frac{f_i u_i^2}{u^2} \cdot \frac{v^{n+1} + a}{v^{n+1} - a} \kappa_i - \frac{4 \theta \kappa_1}{a(v^{n+1} - a)} \sum f_i (1 + \kappa_i^2) - \frac{2}{\theta a} \sum f_i \kappa_i \\
 & \geq - \frac{4 \theta \kappa_1}{a(v^{n+1} - a)} \sum f_i (1 + \kappa_i^2) - \left(\frac{2}{\theta a} + \frac{4 \kappa_1}{a^2} \right) \sum f_i \kappa_i.
 \end{aligned}$$

Here we have applied $\tilde{g}^{kl} u_k u_l = \frac{\delta_{kl}}{u^2} u_k u_l = 1 - (v^{n+1})^2$ due to (4.2) in deriving the above inequality. Choosing $\theta = \frac{a^2}{4}$ and taking the above inequality into (4.14), we obtain an upper bound for κ_1 .

5 Existence of strictly locally convex solutions to (1.6)

The convexity of solutions is a very important prerequisite in this paper, due to the following two reasons: first, the C^2 boundary estimates derived in Sect. 3 require the condition of convexity; second, the C^2 interior estimates for prescribed scalar curvature equations in Sect. 6 need certain convexity assumption (see [12]). Therefore, the preservation of convexity of solutions is vital in order to perform the continuity process. In this section, we first give a constant rank theorem in hyperbolic space (see [9–11,24]).

Theorem 5.1 *Let Σ be a C^4 oriented connected hypersurface in \mathbb{H}^{n+1} satisfying the prescribed curvature equation*

$$\sigma_k(\kappa) = \Psi(x_1, \dots, x_n, u) > 0.
 \tag{5.1}$$

Assume that the second fundamental form $\{h_{ij}\}$ on Σ is positive semi-definite, and for any $\mathbf{x} \in \Sigma$ and a local orthonormal frame τ_1, \dots, τ_n around \mathbf{x} with $\{h_{ij}(\mathbf{x})\}$ diagonal,

$$\sum_{i \in B} \left(\Psi_{ii} - \frac{k+1}{k} \frac{\Psi_i^2}{\Psi} + k\Psi \right) (\mathbf{x}) \lesssim 0, \tag{5.2}$$

where the symbol \lesssim is defined in [10] and B is the set of bad indices of \mathbf{x} . Then the second fundamental form on Σ is of constant rank.

Let Σ be a locally convex hypersurface to equation (5.1) for $k < n$ with boundary $\partial\Sigma$. If we can find a condition (we call it **Condition I**) to guarantee that Σ is strictly locally convex in a neighbourhood of the boundary $\partial\Sigma$, then together with condition (5.2) in Theorem 5.1, we can prove that Σ is strictly locally convex up to the boundary. However, we did not find a suitable Condition I. Still, we proceed to prove the existence as if we have had Condition I in order to show how (5.2) and Condition I play the roles in the continuity process.

Now we prove the existence. We use the geometric quantities in Sect. 2 which are expressed in terms of u and write Equ. (2.5) as

$$G(D^2u, Du, u) = F(a_{ij}) = f(\lambda(a_{ij})) = \sigma_k^{1/k}(\kappa) = \psi^{1/k}(x, u). \tag{5.3}$$

For convenience, denote

$$G[u] = G(D^2u, Du, u), \quad G^{ij}[u] = G^{ij}(D^2u, Du, u), \quad \text{etc.}$$

Let δ be a small positive constant such that

$$G[u] = G(D^2u, Du, u) > \delta u \quad \text{in } \Omega_\epsilon. \tag{5.4}$$

For $t \in [0, 1]$, consider the following two auxiliary equations (see also [27]).

$$\begin{cases} G(D^2u, Du, u) = \left((1-t) \frac{u}{G[u]} + t\delta^{-1} \right)^{-1} u & \text{in } \Omega_\epsilon, \\ u = \epsilon & \text{on } \Gamma_\epsilon. \end{cases} \tag{5.5}$$

$$\begin{cases} G(D^2u, Du, u) = \left((1-t)\delta^{-1}u^{-1} + t\psi^{-1/k}(x, u) \right)^{-1} & \text{in } \Omega_\epsilon, \\ u = \epsilon & \text{on } \Gamma_\epsilon. \end{cases} \tag{5.6}$$

Lemma 5.1 *Let $\psi(x)$ be a positive function defined on $\overline{\Omega_\epsilon}$. For $x \in \overline{\Omega_\epsilon}$ and a positive C^2 function u which is strictly locally convex near x , if*

$$G[u](x) = F(a_{ij}[u])(x) = f(\kappa)(x) = \psi(x)u,$$

then

$$G_u[u](x) - \psi(x) < 0.$$

Proof By direct calculation,

$$G_u = F^{ij} \frac{1}{w} \gamma^{ik} u_{kl} \gamma^{lj} = \frac{1}{u} \left(\sum f_i \kappa_i - \frac{1}{w} \sum f_i \right).$$

Since $\sum f_i \kappa_i \leq \psi(x)u$ by the concavity of f and $f(0) = 0$,

$$G_u[u](x) - \psi(x) \leq -\frac{1}{wu} \sum f_i < 0.$$

□

Lemma 5.2 For any $t \in [0, 1]$, if \underline{U} and u are respectively any positive strictly locally convex subsolution and solution of (5.5), then $u \geq \underline{U}$. In particular, the Dirichlet problem (5.5) has at most one strictly locally convex solution.

Proof We only need to prove that $u \geq \underline{U}$ in Ω_ϵ . If not, then $\underline{U} - u$ achieves a positive maximum at $x_0 \in \Omega_\epsilon$, at which,

$$\underline{U}(x_0) > u(x_0), \quad D\underline{U}(x_0) = Du(x_0), \quad D^2\underline{U}(x_0) \leq D^2u(x_0). \tag{5.7}$$

Note that for any $s \in [0, 1]$, the deformation $u[s] := s\underline{U} + (1-s)u$ is strictly locally convex near x_0 . This is because at x_0 ,

$$\begin{aligned} \delta_{ij} + u[s] \cdot \gamma^{ik}[u[s]] \cdot (u[s])_{kl} \cdot \gamma^{lj}[u[s]] &\geq \delta_{ij} + u[s] \gamma^{ik}[\underline{U}] \cdot \underline{U}_{kl} \cdot \gamma^{lj}[\underline{U}] \\ &= (1-s) \left(1 - \frac{u}{\underline{U}}\right) \delta_{ij} + \frac{u[s]}{\underline{U}} \left(\delta_{ij} + \underline{U} \cdot \gamma^{ik}[\underline{U}] \cdot \underline{U}_{kl} \cdot \gamma^{lj}[\underline{U}]\right) > 0. \end{aligned}$$

Denote

$$\theta(x, t) = \left((1-t) \frac{u}{G[\underline{U}]} + t \delta^{-1} \right)^{-1} \tag{5.8}$$

and define a differentiable function of $s \in [0, 1]$:

$$a(s) := G[u[s]](x_0) - \theta(x_0, t) u[s](x_0).$$

Note that

$$a(0) = G[u](x_0) - \theta(x_0, t) u(x_0) = 0$$

and

$$a(1) = G[\underline{U}](x_0) - \theta(x_0, t) \underline{U}(x_0) \geq 0.$$

Thus there exists $s_0 \in [0, 1]$ such that $a(s_0) = 0$ and $a'(s_0) \geq 0$, i.e.,

$$G[u[s_0]](x_0) = \theta(x_0, t) u[s_0](x_0) \tag{5.9}$$

and

$$\begin{aligned} G^{ij}[u[s_0]](x_0) D_{ij}(\underline{U} - u)(x_0) + G^i[u[s_0]](x_0) D_i(\underline{U} - u)(x_0) \\ + \left(G_u[u[s_0]](x_0) - \theta(x_0, t) \right) (\underline{U} - u)(x_0) \geq 0. \end{aligned} \tag{5.10}$$

However, the above inequality can not hold by (5.7), (5.9) and Lemma 5.1. □

Theorem 5.2 Under assumption (1.7) and Condition I, for any $t \in [0, 1]$, the Dirichlet problem (5.5) has a unique strictly locally convex solution u , which satisfies $u \geq \underline{u}$ in Ω_ϵ .

Proof Uniqueness is proved in Lemma 5.2. For existence of a strictly locally convex solution, we first verify that $\Psi = (\theta(x, t) u)^k = \Theta(x, t) u^k$ satisfies condition (5.2) in the constant rank theorem. By direct calculation,

$$\begin{aligned} \Psi_{ii} - \frac{k+1}{k} \frac{\Psi_i^2}{\Psi} + k \Psi \\ = \sum_{\alpha, \beta=1}^n \left(\Theta_{x_\alpha x_\beta} - \frac{k+1}{k} \frac{\Theta_{x_\alpha} \Theta_{x_\beta}}{\Theta} \right) (x_\alpha)_i (x_\beta)_i u^k + \sum_{\alpha=1}^n \Theta_{x_\alpha} (x_\alpha)_{ii} u^k \\ - 2 \sum_{\alpha=1}^n \Theta_{x_\alpha} (x_\alpha)_i u^{k-1} u_i - 2k \Theta u^{k-2} u_i^2 + \Theta k u^{k-1} u_{ii} + k \Theta u^k. \end{aligned}$$

By (4.1), (4.3), (2.3) and (4.2), for $i \in B$ and $\alpha = 1, \dots, n$, we have

$$\begin{aligned} (x_\alpha)_{ii} &\sim -v^{n+1} u v^\alpha + \frac{2}{u} (x_\alpha)_i u_i - \frac{1}{u} \sum_{l=1}^n u_l (x_\alpha)_l \\ &= -u (v \cdot \partial_{n+1})(v \cdot \partial_\alpha) - u \sum_{l=1}^n \left(\frac{\tau_l}{u} \cdot \partial_{n+1}\right) \left(\frac{\tau_l}{u} \cdot \partial_\alpha\right) + \frac{2}{u} (x_\alpha)_i u_i \\ &= \frac{2}{u} (x_\alpha)_i u_i \end{aligned} \tag{5.11}$$

and

$$u_{ii} \sim \frac{2}{u} u_i^2 - u. \tag{5.12}$$

Therefore by (1.7),

$$\sum_{i \in B} \left(\Psi_{ii} - \frac{k+1}{k} \frac{\Psi_i^2}{\Psi} + k \Psi \right) \sim -k \Theta^{\frac{1}{k}+1} \sum_{i \in B} \sum_{\alpha, \beta=1}^n \left(\Theta^{-\frac{1}{k}} \right)_{x_\alpha x_\beta} (x_\alpha)_i (x_\beta)_i u^k \leq 0.$$

Next, we use the standard continuity method to prove the existence. Note that \underline{u} is a subsolution of (5.5) by (5.4). We have obtained the C^2 bound for strictly locally convex solution u (satisfying $u \geq \underline{u}$ by Lemma 5.2) of (5.5), which implies the uniform ellipticity of Equ. (5.5). By Evans-Krylov theory [13,14], we obtain the $C^{2,\alpha}$ estimate which is independent of t ,

$$\|u\|_{C^{2,\alpha}(\overline{\Omega_\epsilon})} \leq C. \tag{5.13}$$

Denote

$$\begin{aligned} C_0^{2,\alpha}(\overline{\Omega_\epsilon}) &:= \{w \in C^{2,\alpha}(\overline{\Omega_\epsilon}) \mid w = 0 \text{ on } \Gamma_\epsilon\}, \\ \mathcal{U} &:= \left\{ w \in C_0^{2,\alpha}(\overline{\Omega_\epsilon}) \mid \underline{u} + w \text{ is strictly locally convex in } \overline{\Omega_\epsilon} \right\}. \end{aligned}$$

We can see that $C_0^{2,\alpha}(\overline{\Omega_\epsilon})$ is a subspace of $C^{2,\alpha}(\overline{\Omega_\epsilon})$ and \mathcal{U} is an open subset of $C_0^{2,\alpha}(\overline{\Omega_\epsilon})$. Consider the map $\mathcal{L} : \mathcal{U} \times [0, 1] \rightarrow C^\alpha(\overline{\Omega_\epsilon})$,

$$\mathcal{L}(w, t) = G[\underline{u} + w] - \theta(x, t) (\underline{u} + w).$$

Set

$$\mathcal{S} = \{t \in [0, 1] \mid \mathcal{L}(w, t) = 0 \text{ has a solution } w \text{ in } \mathcal{U}\}.$$

Note that $\mathcal{S} \neq \emptyset$ since $\mathcal{L}(0, 0) = 0$.

We claim that \mathcal{S} is open in $[0, 1]$. In fact, for any $t_0 \in \mathcal{S}$, there exists $w_0 \in \mathcal{U}$ such that $\mathcal{L}(w_0, t_0) = 0$. The Fréchet derivative of \mathcal{L} with respect to w at (w_0, t_0) is a linear elliptic operator from $C_0^{2,\alpha}(\overline{\Omega_\epsilon})$ to $C^\alpha(\overline{\Omega_\epsilon})$,

$$\begin{aligned} \mathcal{L}_w|_{(w_0, t_0)}(h) &= G^{ij}[\underline{u} + w_0] D_{ij}h + G^i[\underline{u} + w_0] D_i h \\ &\quad + \left(G_u[\underline{u} + w_0] - \theta(x, t_0) \right) h. \end{aligned}$$

By Lemma 5.1, $\mathcal{L}_w|_{(w_0, t_0)}$ is invertible. By implicit function theorem, a neighborhood of t_0 is also contained in \mathcal{S} .

Next, we show that \mathcal{S} is closed in $[0, 1]$. Let t_i be a sequence in \mathcal{S} converging to $t_0 \in [0, 1]$ and $w_i \in \mathcal{U}$ be the unique (by Lemma 5.2) solution corresponding to t_i , i.e. $\mathcal{L}(w_i, t_i) = 0$. By Lemma 5.2, $w_i \geq 0$. By (5.13), $u_i := \underline{u} + w_i$ is a bounded sequence in $C^{2,\alpha}(\overline{\Omega_\epsilon})$, which possesses a subsequence converging to a locally convex solution u_0 of (5.5). By Condition I and Theorem 5.1, we know that u_0 is strictly locally convex in $\overline{\Omega_\epsilon}$. Since $w_0 := u_0 - \underline{u} \in \mathcal{U}$ and $\mathcal{L}(w_0, t_0) = 0$, thus $t_0 \in \mathcal{S}$. \square

From now on we may assume \underline{u} is not a solution of (1.6), since otherwise we are done.

Lemma 5.3 *If $u \geq \underline{u}$ is a strictly locally convex solution of (5.6) in Ω_ϵ , then $u > \underline{u}$ in Ω_ϵ and $(u - \underline{u})_\gamma > 0$ on Γ_ϵ .*

Proof To keep the strict local convexity of the variations in our proof, we rewrite (5.6) in terms of v ,

$$\begin{cases} G(D^2v, Dv, v) = \psi^t(x, v) & \text{in } \Omega_\epsilon, \\ v = \epsilon^2 & \text{on } \Gamma_\epsilon. \end{cases} \tag{5.14}$$

Since \underline{u} is a subsolution but not a solution of (5.6), equivalently, \underline{v} is a subsolution but not a solution of (5.14), thus,

$$G[\underline{v}] - G[v] \geq \psi^t(x, \underline{v}) - \psi^t(x, v). \tag{5.15}$$

Denote $v[s] := s \underline{v} + (1 - s)v$, which is strictly locally convex over Ω_ϵ for any $s \in [0, 1]$ since

$$\delta_{ij} + \frac{1}{2}(v[s])_{ij} = s\left(\delta_{ij} + \frac{1}{2}\underline{v}_{ij}\right) + (1 - s)\left(\delta_{ij} + \frac{1}{2}v_{ij}\right) > 0 \quad \text{in } \Omega_\epsilon.$$

From (5.15) we can deduce that

$$a_{ij}(x)D_{ij}(\underline{v} - v) + b_i(x)D_i(\underline{v} - v) + c(x)(\underline{v} - v) \geq 0 \quad \text{in } \Omega_\epsilon,$$

where

$$\begin{aligned} a_{ij}(x) &= \int_0^1 G^{ij}[v[s]](x) ds, & b_i(x) &= \int_0^1 G^i[v[s]](x) ds, \\ c(x) &= \int_0^1 G_v[v[s]](x) - \psi^t_v(x, v[s]) ds. \end{aligned}$$

Applying the Maximum Principle and Lemma H (see p. 212 of [25]) we conclude that $v > \underline{v}$ in Ω_ϵ and $(v - \underline{v})_\gamma > 0$ on Γ_ϵ . Hence the lemma is proved. \square

Theorem 5.3 *Under assumption (1.7), (1.8) and Condition I, for any $t \in [0, 1]$, the Dirichlet problem (5.6) possesses a strictly locally convex solution satisfying $u \geq \underline{u}$ in Ω_ϵ . In particular, the Dirichlet problem (1.6) has a strictly locally convex solution u^ϵ satisfying $u^\epsilon \geq \underline{u}$ in Ω_ϵ .*

Proof We first verify that

$$\Psi = \left((1 - t)\delta^{-1}u^{-1} + t\psi^{-1/k}(x, u) \right)^{-k}$$

satisfies condition (5.2) in the constant rank theorem. In fact, by assumption (1.8), (5.11) and (5.12),

$$\begin{aligned}
 &k \psi^{\frac{1}{k}+1} \sum_{i \in B} \left((\psi^{-\frac{1}{k}})_{ii} - \psi^{-\frac{1}{k}} \right) \\
 &\sim \sum_{i \in B} \tau_i^T \left(\begin{array}{cc} \frac{k+1}{k} \frac{\psi_{x_\alpha} \psi_{x_\beta}}{\psi} - \psi_{x_\alpha x_\beta} + \frac{u \psi_u - k \psi}{u^2} \delta_{\alpha\beta} & \frac{k+1}{k} \frac{\psi_{x_\alpha} \psi_u}{\psi} - \psi_{x_\alpha u} - \frac{\psi_{x_\alpha}}{u} \\ \frac{k+1}{k} \frac{\psi_{x_\alpha} \psi_u}{\psi} - \psi_{x_\alpha u} - \frac{\psi_{x_\alpha}}{u} & \frac{k+1}{k} \frac{\psi_u^2}{\psi} - \psi_{uu} - \frac{k \psi}{u^2} - \frac{\psi_u}{u} \end{array} \right) \tau_i \geq 0,
 \end{aligned}$$

and consequently,

$$\begin{aligned}
 &\sum_{i \in B} \left(\Psi_{ii} - \frac{k+1}{k} \frac{\Psi_i^2}{\Psi} + k \Psi \right) \\
 &= -k \Psi^{\frac{k+1}{k}} \sum_{i \in B} \left((1-t) \delta^{-1} \left((u^{-1})_{ii} - u^{-1} \right) + t \left((\psi^{-1/k})_{ii} - \psi^{-1/k} \right) \right) \lesssim 0.
 \end{aligned}$$

We have established $C^{2,\alpha}$ estimates for strictly locally convex solutions $u \geq \underline{u}$ of (5.6), which further imply $C^{4,\alpha}$ estimates by classical Schauder theory,

$$\|u\|_{C^{4,\alpha}(\overline{\Omega_\epsilon})} < C_4. \tag{5.16}$$

In addition, we have

$$\text{dist}(\kappa[u], \partial\Gamma_k) > c_2 > 0 \quad \text{in } \overline{\Omega_\epsilon}, \tag{5.17}$$

where C_4, c_2 are independent of t . Denote

$$C_0^{4,\alpha}(\overline{\Omega_\epsilon}) := \{w \in C^{4,\alpha}(\overline{\Omega_\epsilon}) \mid w = 0 \text{ on } \Gamma_\epsilon\}$$

and

$$\mathcal{O} := \left\{ w \in C_0^{4,\alpha}(\overline{\Omega_\epsilon}) \left| \begin{array}{l} w > 0 \text{ in } \Omega_\epsilon, \quad w_\gamma > 0 \text{ on } \Gamma_\epsilon, \quad \|w\|_{C^{4,\alpha}(\overline{\Omega_\epsilon})} < C_4 + \|\underline{u}\|_{C^{4,\alpha}(\overline{\Omega_\epsilon})} \\ \{\delta_{ij} + (\underline{u} + w)_i (\underline{u} + w)_j + (\underline{u} + w)(\underline{u} + w)_{ij}\} > 0 \text{ in } \overline{\Omega_\epsilon}, \\ \text{dist}(\kappa[\underline{u} + w], \partial\Gamma_k) > c_2 \text{ in } \overline{\Omega_\epsilon} \end{array} \right. \right\},$$

which is a bounded open subset of $C_0^{4,\alpha}(\overline{\Omega_\epsilon})$. Define $\mathcal{M}_t(w) : \mathcal{O} \times [0, 1] \rightarrow C^{2,\alpha}(\overline{\Omega_\epsilon})$,

$$\mathcal{M}_t(w) = G[\underline{u} + w] - \left((1-t) \delta^{-1} \cdot (\underline{u} + w)^{-1} + t \psi^{-1/k}(x, \underline{u} + w) \right)^{-1}.$$

Let u^0 be the unique strictly locally convex solution of (5.5) at $t = 1$ (the existence and uniqueness are guaranteed by Theorem 5.2 and Lemma 5.2). Observe that u^0 is also the unique solution of (5.6) when $t = 0$. By Lemma 5.2, $w^0 := u^0 - \underline{u} \geq 0$ in Ω_ϵ . By Lemma 5.3, $w^0 > 0$ in Ω_ϵ and $w^0_\gamma > 0$ on Γ_ϵ . Also, $\underline{u} + w^0$ satisfies (5.16) and (5.17). Thus, $w^0 \in \mathcal{O}$. By Condition I, Theorem 5.1, Lemma 5.3, (5.16) and (5.17), $\mathcal{M}_t(w) = 0$ has no solution on $\partial\mathcal{O}$ for any $t \in [0, 1]$. Besides, \mathcal{M}_t is uniformly elliptic on \mathcal{O} independent of t . Therefore, we can define the t -independent degree of \mathcal{M}_t on \mathcal{O} at 0:

$$\text{deg}(\mathcal{M}_t, \mathcal{O}, 0).$$

To find this degree, we only need to compute $\text{deg}(\mathcal{M}_0, \mathcal{O}, 0)$. By the above discussion, we know that $\mathcal{M}_0(w) = 0$ has a unique solution $w^0 \in \mathcal{O}$. The Fréchet derivative of \mathcal{M}_0 with respect to w at w^0 is a linear elliptic operator from $C_0^{4,\alpha}(\overline{\Omega_\epsilon})$ to $C^{2,\alpha}(\overline{\Omega_\epsilon})$,

$$\mathcal{M}_{0,w}|_{w^0}(h) = G^{ij}[u^0] D_{ij}h + G^i[u^0] D_i h + (G_u[u^0] - \delta)h. \tag{5.18}$$

By Lemma 5.1, $G_u[u^0] - \delta < 0$ in $\overline{\Omega_\epsilon}$ and thus $\mathcal{M}_{0,w}|_{w^0}$ is invertible. By the degree theory established in [17],

$$\deg(\mathcal{M}_0, \mathcal{O}, 0) = \deg(\mathcal{M}_{0,w^0}, B_1, 0) = \pm 1 \neq 0,$$

where B_1 is the unit ball in $C_0^{4,\alpha}(\overline{\Omega_\epsilon})$. Thus $\deg(\mathcal{M}_t, \mathcal{O}, 0) \neq 0$ for all $t \in [0, 1]$, which implies that the Dirichlet problem (5.6) has at least one strictly locally convex solution $u \geq \underline{u}$ for any $t \in [0, 1]$. □

6 Interior second order estimates for prescribed scalar curvature equations in \mathbb{H}^{n+1}

Let $u^\epsilon \geq \underline{u}$ be a strictly locally convex solution over Ω_ϵ to the Dirichlet problem (1.6). For any fixed $\epsilon_0 > 0$, we want to establish the uniform C^2 estimates for u^ϵ for any $0 < \epsilon < \frac{\epsilon_0}{4}$ on $\overline{\Omega_{\epsilon_0}}$, namely,

$$\|u^\epsilon\|_{C^2(\overline{\Omega_{\epsilon_0}})} \leq C, \quad \forall 0 < \epsilon < \frac{\epsilon_0}{4}. \tag{6.1}$$

In what follows, let C be a positive constant which is independent of ϵ but depends on ϵ_0 . By (3.1), we immediately obtain the uniform C^0 estimate:

$$\epsilon_0 \leq u^\epsilon \leq C \text{ on } \overline{\Omega_{\epsilon_0}}, \quad \forall 0 < \epsilon < \epsilon_0. \tag{6.2}$$

For uniform C^1 estimate on $\overline{\Omega_{\epsilon_0}}$, we make use of the Euclidean strict local convexity of $(u^\epsilon)^2 + |x|^2$ (see [26] for a similar idea) to obtain

$$\max_{\overline{\Omega_{\epsilon_0}}} |D((u^\epsilon)^2 + |x|^2)| \leq \frac{C(n) \max_{\overline{\Omega_{\epsilon_0/2}}} ((u^\epsilon)^2 + |x|^2)}{\text{dist}(\Gamma_{\epsilon_0/2}, \overline{\Omega_{\epsilon_0}})}, \quad \forall 0 < \epsilon < \frac{\epsilon_0}{2}.$$

It follows that,

$$\|u^\epsilon\|_{C^1(\overline{\Omega_{\epsilon_0}})} \leq C, \quad \forall 0 < \epsilon < \frac{\epsilon_0}{2}. \tag{6.3}$$

We are now in a position to prove

$$|D^2 u^\epsilon| \leq C \text{ on } \overline{\Omega_{\epsilon_0}}, \quad \forall 0 < \epsilon < \frac{\epsilon_0}{4}, \tag{6.4}$$

which is equivalent to

$$\max_{\overline{\Omega_{\epsilon_0}}} |\kappa_i[u^\epsilon]| \leq C, \quad \forall 0 < \epsilon < \frac{\epsilon_0}{4}. \tag{6.5}$$

Choose $r = \text{dist}(\overline{\Omega_{\epsilon_0}}, \Gamma_{\epsilon_0/2})$, and cover $\overline{\Omega_{\epsilon_0}}$ by finitely many open balls $B_{\frac{r}{2}}$ with radius $\frac{r}{2}$ and centered in Ω_{ϵ_0} . Note that the number of such open balls depends on ϵ_0 . In addition, the corresponding balls B_r are all contained in $\Omega_{\epsilon_0/2}$, over which, we are able to apply the gradient estimate due to (6.3):

$$\|u^\epsilon\|_{C^1(\overline{\Omega_{\epsilon_0/2}})} \leq C, \quad \forall 0 < \epsilon < \frac{\epsilon_0}{4}.$$

If we are able to establish the following interior C^2 estimate on each B_r :

$$\sup_{B_{r/2}} |\kappa_i[u^\epsilon]| \leq C(\|u^\epsilon\|_{C^1(B_r)}), \quad \forall 0 < \epsilon < \frac{\epsilon_0}{4},$$

then (6.5) can be proved. Since the principal curvatures $\kappa_i[u^\epsilon], i = 1, \dots, n$ and the gradient Du^ϵ are invariant under the change of Euclidean coordinate system, we may assume the center of B_r is 0. For convenience, we also omit the superscript in u^ϵ and write as u .

In what follows, we will use Guan-Qiu’s idea [12] to derive the interior C^2 estimate

$$\sup_{B_{r/2}} |\kappa_i(x)| \leq C \tag{6.6}$$

for strictly locally convex hypersurface Σ in \mathbb{H}^{n+1} to the following equation

$$\sigma_2(\kappa) = \psi(\mathbf{x}), \tag{6.7}$$

where $B_r \subset \mathbb{R}^n$ is the open ball with radius r centered at 0 and C is a positive constant depending only on $n, r, \|\Sigma\|_{C^1(B_r)}, \|\psi\|_{C^2(B_r)}$ and $\inf_{B_r} \psi$.

For $x \in B_r$ and $\xi \in \mathbb{S}^{n-1} \cap T_{(x,u)}\Sigma$, consider the test function

$$\Theta(x, u, \xi) = 2 \ln \rho(x) + \alpha \left(\frac{u}{v^{n+1}} \right)^2 - \beta \left(\frac{\mathbf{x} \cdot v}{v^{n+1}} \right) + \ln \ln h_{\xi\xi},$$

where $\rho(x) = r^2 - |x|^2$ with $|x|^2 = \sum_{i=1}^n x_i^2$ and α, β are positive constants to be determined later. At this point, we remind the readers that \cdot means the inner product in \mathbb{R}^{n+1} while $\langle \cdot, \cdot \rangle$ represents the inner product in \mathbb{H}^{n+1} .

The maximum value of Θ can be attained in an interior point $x^0 = (x_1, \dots, x_n) \in B_r$. Let τ_1, \dots, τ_n be a normal coordinate frame around $(x^0, u(x^0))$ on Σ and assume the direction obtaining the maximum to be $\xi = \tau_1$. By rotation of τ_2, \dots, τ_n we may assume that $(h_{ij}(x^0))$ is diagonal. Thus, the function

$$2 \ln \rho(x) + \alpha \left(\frac{u}{v^{n+1}} \right)^2 - \beta \left(\frac{\mathbf{x} \cdot v}{v^{n+1}} \right) + \ln \ln h_{11}$$

also achieves its maximum at x^0 . Therefore, at x^0 ,

$$\frac{2 \rho_i}{\rho} + 2\alpha \frac{u}{v^{n+1}} \left(\frac{u}{v^{n+1}} \right)_i - \beta \left(\frac{\mathbf{x} \cdot v}{v^{n+1}} \right)_i + \frac{h_{11i}}{h_{11} \ln h_{11}} = 0, \tag{6.8}$$

$$\begin{aligned} & \frac{2\sigma_2^{ii} \rho_{ii}}{\rho} - \frac{2\sigma_2^{ii} \rho_i^2}{\rho^2} + 2\alpha \sigma_2^{ii} \left(\left(\frac{u}{v^{n+1}} \right)_i + \left(\frac{u}{v^{n+1}} \right)_{ii} \right) \\ & - \beta \sigma_2^{ii} \left(\frac{\mathbf{x} \cdot v}{v^{n+1}} \right)_{ii} + \frac{\sigma_2^{ii} h_{11ii}}{h_{11} \ln h_{11}} - (1 + \ln h_{11}) \frac{\sigma_2^{ii} h_{11i}^2}{(h_{11} \ln h_{11})^2} \leq 0. \end{aligned} \tag{6.9}$$

To compute the quantities in (6.8) and (6.9), we first convert them into quantities in \mathbb{H}^{n+1} , and apply the Gauss formula and Weingarten formula

$$\begin{aligned} \mathbf{D}_{\tau_i} \tau_j &= \nabla_{\tau_i} \tau_j + h_{ij} \mathbf{n}, \\ \mathbf{n}_i &= -h_{ij} \tau_j. \end{aligned}$$

We also note that in \mathbb{H}^{n+1} ,

$$\mathbf{D}_{\mathbf{y}} \partial_{n+1} = -\frac{1}{u} \mathbf{y},$$

where \mathbf{y} is any vector field in \mathbb{H}^{n+1} . This implies that ∂_{n+1} is a conformal Killing field in \mathbb{H}^{n+1} . By straightforward calculation, we obtain

$$\left(\frac{u}{v^{n+1}}\right)_i = \left(\frac{1}{\langle \mathbf{n}, \partial_{n+1} \rangle}\right)_i = \kappa_i \frac{\tau_i \cdot \partial_{n+1}}{(v^{n+1})^2}, \tag{6.10}$$

$$\left(\frac{u}{v^{n+1}}\right)_{ii} = h_{ij} \frac{\tau_j \cdot \partial_{n+1}}{(v^{n+1})^2} + \kappa_i^2 \frac{u}{v^{n+1}} - \frac{u}{(v^{n+1})^2} \kappa_i + 2\kappa_i^2 \frac{(\tau_i \cdot \partial_{n+1})^2}{u(v^{n+1})^3}. \tag{6.11}$$

Now we choose the conformal Killing field \mathbf{x} in \mathbb{H}^{n+1} to be

$$\mathbf{x} = x_{n+1} \sum_{i=1}^n x_i \partial_i + \frac{1}{2} (x_{n+1}^2 - |x|^2) \partial_{n+1}.$$

We can verify that

$$\mathbf{D}_y \mathbf{x} = \phi \mathbf{y}, \quad \phi = \frac{x_{n+1}^2 + |x|^2}{2x_{n+1}},$$

where \mathbf{y} is any vector field in \mathbb{H}^{n+1} .

Again, by straightforward calculation, we find that

$$\left(\frac{\mathbf{x} \cdot v}{v^{n+1}}\right)_i = \frac{\kappa_i}{u v^{n+1}} \left(\frac{(\mathbf{x} \cdot v)(\tau_i \cdot \partial_{n+1})}{v^{n+1}} - \mathbf{x} \cdot \tau_i\right), \tag{6.12}$$

$$\begin{aligned} \left(\frac{\mathbf{x} \cdot v}{v^{n+1}}\right)_{ii} &= -\left(\frac{\phi u}{v^{n+1}} + \frac{\mathbf{x} \cdot v}{(v^{n+1})^2}\right) \kappa_i + \frac{2\kappa_i(\tau_i \cdot \partial_{n+1})}{u v^{n+1}} \left(\frac{\mathbf{x} \cdot v}{v^{n+1}}\right)_i \\ &\quad + \frac{1}{u(v^{n+1})^2} \left((\mathbf{x} \cdot v)(\tau_j \cdot \partial_{n+1}) - (\mathbf{x} \cdot \tau_j)v^{n+1}\right) h_{ij}. \end{aligned} \tag{6.13}$$

Also, since

$$|x|^2 = \frac{1 - 2\langle \mathbf{x}, \partial_{n+1} \rangle}{\langle \partial_{n+1}, \partial_{n+1} \rangle},$$

by direct calculation we obtain

$$\begin{aligned} \rho_i &= 2u^3 \langle \tau_i, \partial_{n+1} \rangle \langle \mathbf{x}, \partial_{n+1} \rangle - 2u \langle \mathbf{x}, \tau_i \rangle \\ &= \frac{2}{u} \left((\tau_i \cdot \partial_{n+1})(\mathbf{x} \cdot \partial_{n+1}) - \mathbf{x} \cdot \tau_i \right), \end{aligned} \tag{6.14}$$

$$\begin{aligned} \rho_{ii} &= \kappa_i \left((u^2 - |x|^2)v^{n+1} - 2\mathbf{x} \cdot v \right) \\ &\quad + \frac{4u^2 - 2|x|^2}{u^2} (\tau_i \cdot \partial_{n+1})^2 - \frac{4}{u^2} (\tau_i \cdot \mathbf{x})(\tau_i \cdot \partial_{n+1}) - 2u^2. \end{aligned} \tag{6.15}$$

Differentiate (6.7) twice,

$$\sigma_2^{ii} h_{iik} = \psi_k, \tag{6.16}$$

$$\sum_{i \neq j} h_{ii} h_{jj} - \sum_{i \neq j} h_{ij}^2 + \sigma_2^{ii} h_{ii1} = \psi_{11} \geq -C\kappa_1. \tag{6.17}$$

Now taking (6.15), (6.10), (6.11), (6.13), (6.8), (6.16), (4.12), (6.17) into (6.9), we obtain

$$\begin{aligned}
 & -\frac{C}{\rho} \sigma_1 - C\alpha - C\beta - \frac{2\sigma_2^{ii} \rho_i^2}{\rho^2} + 2\alpha \frac{u^2}{(\nu^{n+1})^2} \sigma_2^{ii} \kappa_i^2 - \frac{2\sigma_2^{ii} \kappa_i (\tau_i \cdot \partial_{n+1}) h_{11i}}{u \nu^{n+1} \kappa_1 \ln \kappa_1} \\
 & + \frac{\sum_{i \neq j} h_{ij1}^2 - \sum_{i \neq j} h_{ii1} h_{jj1}}{\kappa_1 \ln \kappa_1} - \frac{C\sigma_1}{\ln \kappa_1} - \frac{\sigma_2^{ii} \kappa_i^2}{\ln \kappa_1} - (1 + \ln \kappa_1) \frac{\sigma_2^{ii} h_{11i}^2}{(\kappa_1 \ln \kappa_1)^2} \leq 0.
 \end{aligned} \tag{6.18}$$

By Theorem 1.2 of [28] (see also Lemma 2 of [12]), we have

$$-\sum_{i \neq j} h_{ii1} h_{jj1} \geq \frac{1}{2\sigma_2} \frac{(n-1)(2\sigma_2 h_{111} - \kappa_1 \psi_1)^2}{(n-1)\kappa_1^2 + 2(n-2)\sigma_2} - \frac{\psi_1^2}{2\sigma_2}.$$

Also,

$$-\frac{2\sigma_2^{ii} \kappa_i (\tau_i \cdot \partial_{n+1}) h_{11i}}{u \nu^{n+1} \kappa_1 \ln \kappa_1} \geq -\frac{u^2}{(\nu^{n+1})^2} \sigma_2^{ii} \kappa_i^2 - \frac{(\tau_i \cdot \partial_{n+1})^2}{u^4} \frac{\sigma_2^{ii} h_{11i}^2}{(\kappa_1 \ln \kappa_1)^2}.$$

Thus, when κ_1 is sufficiently large, (6.18) reduces to

$$-\frac{C}{\rho} \sigma_1 - \frac{2\sigma_2^{ii} \rho_i^2}{\rho^2} + (2\alpha - 2) \frac{u^2}{(\nu^{n+1})^2} \sigma_2^{ii} \kappa_i^2 + \frac{\sigma_2^{ii} h_{11i}^2}{20 \kappa_1^2 \ln \kappa_1} \leq 0. \tag{6.19}$$

As in [12], we divide our discussion into three cases. We show all the details to indicate the tiny differences due to the outer space \mathbb{H}^{n+1} .

Case (i): when $|x|^2 \leq \frac{r^2}{2}$, we have $\frac{1}{\rho} \leq \frac{2}{r^2}$. Then (6.19) reduces to

$$-C\sigma_1 + (2\alpha - 2) \frac{u^2}{(\nu^{n+1})^2} (\sigma_2\sigma_1 - 3\sigma_3) \leq 0.$$

Choosing α sufficiently large we obtain an upper bound for κ_1 .

Next, we consider the cases when $|x|^2 \geq \frac{r^2}{2}$, which implies $\rho \leq \frac{r^2}{2}$. We observe that

$$\rho_i = -\frac{2}{u} (\mathbf{x} - (\mathbf{x} \cdot \partial_{n+1}) \partial_{n+1}) \cdot \tau_i = -\frac{2}{u} \sum_{j=1}^n (\mathbf{x} \cdot \partial_j) (\partial_j \cdot \tau_i). \tag{6.20}$$

Therefore,

$$\begin{aligned}
 \sum_i \rho_i^2 &= \frac{4}{u^2} \sum_{jk} (\mathbf{x} \cdot \partial_j) (\mathbf{x} \cdot \partial_k) \sum_i (\partial_j \cdot \tau_i) (\partial_k \cdot \tau_i) \\
 &= 4 \sum_{jk} (\mathbf{x} \cdot \partial_j) (\mathbf{x} \cdot \partial_k) \left(\sum_i (\partial_j \cdot \frac{\tau_i}{u}) \frac{\tau_i}{u} \right) \cdot \partial_k \\
 &= 4 \sum_{jk} (\mathbf{x} \cdot \partial_j) (\mathbf{x} \cdot \partial_k) \left(\partial_j - (\partial_j \cdot \nu) \nu \right) \cdot \partial_k \\
 &\geq 4 \left(\sum_j (\mathbf{x} \cdot \partial_j)^2 - \sum_j (\mathbf{x} \cdot \partial_j)^2 \sum_j (\partial_j \cdot \nu)^2 \right) \\
 &= 4 \sum_j (\mathbf{x} \cdot \partial_j)^2 (\nu^{n+1})^2 = 4u^2 |x|^2 (\nu^{n+1})^2 \geq 2r^2 u^2 (\nu^{n+1})^2.
 \end{aligned} \tag{6.21}$$

Case (ii): if for some $2 \leq j \leq n$, we have $|\rho_j| > d$, where d is a small positive constant to be determined later.

By (6.8), (6.10) and (6.12), we have

$$\frac{h_{11j}}{\kappa_1 \ln \kappa_1} = -\frac{2\rho_j}{\rho} + \left(\beta \frac{(\mathbf{x} \cdot \nu)(\tau_j \cdot \partial_{n+1}) - (\mathbf{x} \cdot \tau_j) \nu^{n+1}}{u(\nu^{n+1})^2} - 2\alpha \frac{u(\tau_j \cdot \partial_{n+1})}{(\nu^{n+1})^3} \right) \kappa_j.$$

It follows that

$$\frac{h_{11j}^2}{\kappa_1^2 (\ln \kappa_1)^2} \geq \frac{2\rho_j^2}{\rho^2} - C(\alpha + \beta)^2 \kappa_j^2 \geq \frac{d^2}{\rho^2} + \frac{4d^2}{r^4} - \frac{C(\alpha + \beta)^2}{\kappa_1^2} \geq \frac{d^2}{\rho^2}$$

when κ_1 is sufficiently large. Consequently, (6.19) reduces to

$$-\frac{C\sigma_1}{\rho^2} + \frac{d^2}{20\rho^2} \sigma_2^{jj} \ln \kappa_1 \leq 0.$$

Since $\sigma_2^{jj} \geq \frac{9}{10} \sigma_1$ when κ_1 is sufficiently large, we obtain an upper bound for κ_1 .

Case (iii): if $|\rho_j| \leq d$ for all $2 \leq j \leq n$, from (6.21) we can deduce that $|\rho_1| \geq c_0 > 0$. By (6.8), (6.10) and (6.12), we have

$$\frac{h_{111}}{\kappa_1 \ln \kappa_1} = \frac{\beta \kappa_1 b_1}{(\nu^{n+1})^2} - \frac{2\rho_1}{\rho} - \frac{2\alpha u \kappa_1 (\tau_1 \cdot \partial_{n+1})}{(\nu^{n+1})^3}, \tag{6.22}$$

where

$$\begin{aligned} b_1 &= (\mathbf{x} \cdot \nu) \left(\frac{\tau_1}{u} \cdot \partial_{n+1} \right) - \left(\mathbf{x} \cdot \frac{\tau_1}{u} \right) \nu^{n+1} \\ &= \frac{\nu^{n+1}}{2} \rho_1 + \left(\frac{\tau_1}{u} \cdot \partial_{n+1} \right) \left(\mathbf{x} \cdot (\nu - (\nu \cdot \partial_{n+1}) \partial_{n+1}) \right) \\ &= \frac{\nu^{n+1}}{2} \rho_1 + \frac{1}{\nu^{n+1}} \left(\frac{\tau_1}{u} \cdot \partial_{n+1} \right) (\nu \cdot \partial_{n+1}) \sum_i (\nu \cdot \partial_i) (\mathbf{x} \cdot \partial_i) \\ &= \frac{\nu^{n+1}}{2} \rho_1 + \frac{1}{\nu^{n+1}} \sum_i \left(\left(\frac{\tau_1}{u} \cdot \partial_{n+1} \right) \partial_{n+1} \right) \cdot \left((\partial_i \cdot \nu) \nu \right) (\mathbf{x} \cdot \partial_i) \\ &= \frac{\nu^{n+1}}{2} \rho_1 + \frac{1}{\nu^{n+1}} \sum_i \left(\frac{\tau_1}{u} - \sum_j \left(\frac{\tau_1}{u} \cdot \partial_j \right) \partial_j \right) \cdot \left(\partial_i - \sum_k \left(\partial_i \cdot \frac{\tau_k}{u} \right) \frac{\tau_k}{u} \right) (\mathbf{x} \cdot \partial_i) \\ &= \frac{\nu^{n+1}}{2} \rho_1 + \frac{1}{\nu^{n+1}} \sum_i \left(-\frac{\tau_1}{u} \cdot \partial_i + \sum_{jk} \left(\frac{\tau_1}{u} \cdot \partial_j \right) (\partial_i \cdot \frac{\tau_k}{u}) (\partial_j \cdot \frac{\tau_k}{u}) \right) (\mathbf{x} \cdot \partial_i) \\ &= \frac{\nu^{n+1}}{2} \rho_1 + \frac{\rho_1}{2\nu^{n+1}} - \frac{1}{2\nu^{n+1}} \sum_{jk} \left(\frac{\tau_1}{u} \cdot \partial_j \right) (\partial_j \cdot \frac{\tau_k}{u}) \rho_k. \end{aligned}$$

Note that in the last equality we have applied (6.20). Hence

$$|b_1| \geq \frac{\nu^{n+1}}{2} |\rho_1| - \frac{1}{2\nu^{n+1}} \sum_{k \neq 1} |\rho_k| \geq c_1 > 0$$

and (6.22) can be estimated as

$$\left| \frac{h_{111}}{\kappa_1 \ln \kappa_1} \right| \geq \frac{\beta c_1 \kappa_1}{2(\nu^{n+1})^2} - \frac{C}{\rho} \geq \frac{\beta c_1 \kappa_1}{4(\nu^{n+1})^2}$$

when $\beta \gg \alpha$ and $\kappa_1 \rho$ is sufficiently large. Taking this into (6.19) and observing that

$$\sigma_2^{11} \kappa_1^2 \geq \frac{9}{10n} \sigma_2 \sigma_1$$

as κ_1 is sufficiently large, we then obtain an upper bound for $\rho^2 \ln \kappa_1$.

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