



Regularity theory for type I Ricci flows

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Abstract

We consider Type I Ricci flows and obtain integral estimates for the curvature tensor valid up to, and including, the singular time. Our estimates partially extend to higher dimensions a curvature estimate recently shown to hold in dimension three by Kleiner and Lott (Acta Math 219(1):65–134, 2017). To do this we adapt the technique of quantitative stratification, introduced by Cheeger–Naber (Invent Math 191(2):321–339, 2013), to this setting.

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1 Introduction

In this paper we study complete Ricci flows $(M, g(t))_{t \in [0, T]}$ satisfying a curvature bound of the form

$$\sup_M |\text{Rm}(g(t))|_{g(t)} \leq \frac{B}{T-t}, \quad (1.1)$$

for all $t \in [0, T)$. If $(g(t))_{t \in [0, T)}$ becomes singular as $t \rightarrow T$, namely

$$\lim_{t \rightarrow T} \sup_M |\text{Rm}(g(t))|_{g(t)} = +\infty. \quad (1.2)$$

the singularity is classified as Type I, hence we will refer to (1.1) as a Type I curvature bound. This kind of singular behaviour for the Ricci flow is very common and it is in fact conjectured that for closed manifolds M such singularities are generic; see for instance [2, 17].

Our results provide L^p bounds for the curvature along the flow assuming Type I bounds. For instance, we obtain the following theorem.

Theorem 1.1 *Let $(M^n, g(t))_{t \in [0, T)}$, $\dim M = n$, be a compact Ricci flow satisfying (1.1). Then, for every non-negative integer j and $p \in (0, 2)$ there exist $C_{p,j}(g(0)) < +\infty$ such that for every $t \in [0, T)$*

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$$\int_M |\nabla^j \text{Rm}(g(t))|_{g(t)}^{\frac{p}{j+2}} d\mu_{g(t)} \leq C_{p,j}, \tag{1.3}$$

$$\text{and } \int_0^T \int_M |\nabla^j \text{Rm}(g(s))|_{g(s)}^{\frac{p+2}{j+2}} d\mu_{g(s)} ds \leq C_{p,j}. \tag{1.4}$$

If $(g(t))_{t \in [0, T]}$ becomes singular at T , estimate (1.3) is valid at $t = T$ on the set $\Omega = \{x \in M, \sup_{t \in [0, T]} |\text{Rm}(g)|_g(x, t) < +\infty\}$. Moreover, if $g(t)$ has positive isotropic curvature and $n = 4$, the estimates above hold for any $p \in (0, 3)$.

Notice that estimate (1.3) agrees with the recent curvature estimate obtained by Kleiner–Lott [18] in dimension three. Moreover, the results [18] hold without the Type I assumption and even after the first singularity occurs. Our results on the other hand are valid in any dimension, which may hint to a general fact about weak solutions to Ricci flow. Notions of weak solutions to Ricci flow have recently been proposed by Haslhofer–Naber [15] as well as Sturm in [29] and Kopfer–Sturm in [20].

In [18] the curvature estimate is a consequence of the study of a certain class of space-time manifolds that arise naturally as limits of Perelman’s Ricci flow with surgery, as the associated fineness parameter goes to zero. In contrast, our approach bypasses Ricci flow with surgery, and instead uses the tangent flow analysis and monotonicity formula available for Type I Ricci flows. In particular, we adapt the technique of *quantitative stratification*, recently introduced by Cheeger–Naber in [7], to this setting.

The ideas in [7] are very general and have been applied in a wide range of geometric PDE, leading to improved curvature estimates; see [3,5,6,8]. However, to adapt these ideas to the Ricci flow we need to overcome a few issues, which we describe below.

We may define the singular set Σ of a Ricci flow as the set of points with no neighbourhood where the curvature remains bounded as $t \rightarrow T$. Under assumption (1.1), Naber shows in [24] that tangent flows at the singular time, namely limits of appropriate pointed sequences of rescalings, are gradient shrinking Ricci solitons. Previously Šešum [27] had shown that this is true in the case of compact tangent flows. Then, Enders–Müller–Topping in [11] show that tangent flows are non-flat if and only if they are ‘centered’ around singular points. Mantegazza–Müller [23] also prove these facts using a different approach.

Imitating the classical regularity theory for minimal surfaces or harmonic maps, as developed for instance in [1,12,26,28,31], it is natural to consider the stratification

$$\Sigma_0 \subset \dots \subset \Sigma_{n-1} = \Sigma$$

of Σ , where

$$\Sigma_k = \{x \in \Sigma, \text{ no tangent flow at } x \text{ splits more than } k \text{ Euclidean factors}\}.$$

In fact $\Sigma = \Sigma_{n-2}$, since any shrinking soliton splitting more than $n - 2$ Euclidean factors should be the Gaussian soliton in the Euclidean space.

A more detailed study of this stratification is done in [14]. There, a key issue is that the properties of each Σ_k relevant to singularity formation, as captured by the amount of the Euclidean factors split by the tangent flows, do not interact with the geometric properties of each Σ_k as a subset of $(M, g(t))$: in the shrinking round sphere example, $\Sigma = \Sigma_0 = \mathbb{S}^n$ is an n -dimensional subset, but it converges to a 0-dimensional space towards the singular time.

This is in contrast to other situations, where the interest is in the geometry of the singular set as a subset of a given ambient space. Similar issues appear when we try to adapt the philosophy of [7] in this paper.

Below we describe the results of the paper in more detail:

In Sect. 2 we recall a monotone quantity for possibly singular Type I Ricci flows and its associated density that was introduced in [14], based on Perelman’s reduced volume, extending ideas from [4,10,24]. This leads to the notion of the *spine* of a shrinking Ricci soliton with bounded curvature: the set where the density function attains its *minimum*. It is then shown that the spine satisfies a diameter estimate, modulo the splitting of Euclidean factors; see Theorem 2.2. In particular this estimate shows that, as the flow induced by the soliton approaches its singular time, the spine collapses to a Euclidean space. This is a key fact that allows us to adapt the ideas in [7] to the setting of Type I Ricci flows.

Now, let $\mathcal{C}(n, B, \kappa_0, \kappa_1)$ be the class of complete Ricci flows $(M, g(t))_{t \in (-2,0)}$, such that $\dim M = n$ and

- (1) $|\text{Rm}(g(-\tau))|_{g(-\tau)} \leq B/\tau$ in M , for every $\tau \in (0, 2)$.
- (2) $g(t)$ is κ_0 non-collapsed below scale 1, namely

$$\text{vol}_{g(t)}(B_{g(t)}(x, r)) \geq \kappa_0 r^n,$$

for every $(x, t) \in M \times (-2, 0)$ and $r \leq 1$ for which $R(g(t)) \leq r^{-2}$ in $B_{g(t)}(x, r)$, R denoting the scalar curvature.

- (3) $g(t)$ is κ_1 non-inflated below scale 1, namely

$$\text{vol}_{g(t)}(B_{g(t)}(x, r)) \leq \kappa_1 r^n,$$

for every $(x, t) \in M \times [-1, 0)$ and $r \leq 1, t - r^2 > -2$, for which

$$R \leq \frac{c(n)B}{t - \bar{t}},$$

in $B_{g(t)}(x, r)$ for all $\bar{t} \in [t - r^2, t]$, where $c(n) < +\infty$ is a constant such that $|R(g)| \leq c(n)|\text{Rm}(g)|_g$, for any Riemannian metric g .

In Sect. 3, following [7], we define the quantitative stratification $S_{\eta, \tau}^k$, where $k \geq 0$ is an integer, $\eta > 0$ and $\tau \in (0, 1]$, for each $(M, g(t))_{t \in (-2,0)}$ in $\mathcal{C}(n, B, \kappa_0, \kappa_1)$. The intuition behind the sets $S_{\eta, \tau}^k$ is that there is no scale $\bar{t} \in [\tau, 1]$ at which the flow around $x \in S_{\eta, \tau}^k$ is η -close to a shrinking Ricci soliton that splits more than k Euclidean factors. We refer the reader to Sect. 3 for the detailed definition.

The relationship of the sets $S_{\eta, \tau}^k$ to Σ_k is given by

$$\Sigma_k = \bigcup_{\eta} \bigcap_{\tau} S_{\eta, \tau}^k.$$

We show that the quantitative stratification satisfies the following volume estimate:

Theorem 1.2 *Let $(M, g(t))_{t \in (-2,0)} \in \mathcal{C}(n, B, \kappa_0, \kappa_1)$. Then, there exist $\alpha(B), \beta(B) \in (0, 1)$ and $C_\eta = C(n, B, \kappa_0, \kappa_1, \eta) < +\infty$, such that for every $0 < \tau \leq \alpha$*

$$\text{vol}_{g(-\tau)} \left(S_{\eta, \tau}^k \cap B_{g(-\alpha)}(x, \beta) \right) \leq C_\eta \tau^{\frac{n-k-\eta}{2}}. \tag{1.5}$$

Then, in Sect. 4, we combine Theorem 1.2 with the ε -regularity Lemmata 4.1 and 4.2, to prove uniform curvature estimates for any Ricci flow $(M, g(t))_{t \in (-2,0)}$ in $\mathcal{C}(n, B, \kappa_0, \kappa_1)$.

Define the curvature radius of $(M, g(t))_{t \in (-2,0)}$ at $x \in M$ as

$$r_{\text{Rm}}(x) = \sup \left\{ r \leq 1, |\text{Rm}(g)| \leq r^{-2} \text{ in } B_{g(-r^2)}(x, r) \times [-r^2, 0] \right\}.$$

Note that if $(g(t))_{t \in (-2,0)}$ is singular at x , we define $r_{\text{Rm}}(x) = 0$.

Then, Theorem 1.1 is a consequence of the following result.

Theorem 1.3 *Let $(M, g(t))_{t \in (-2,0)} \in \mathcal{C}(n, B, \kappa_0, \kappa_1)$. Then there exist $\alpha(B), \beta(B) > 0$ such that for any integer $j \geq 0$ and any $p \in (0, 2)$ there is $C_{p,j} = C_{p,j}(n, B, \kappa_0, \kappa_1) < +\infty$ such that*

$$\int_{B_{g(-\alpha)}(x,\beta) \cap \{r_{\text{Rm}} > 0\}} |\nabla^j \text{Rm}(g(0))|_{g(0)}^{\frac{p}{j+2}} d\mu_{g(0)} \leq C_{p,j}, \tag{1.6}$$

Moreover, if $\dim M = 4$ and $g(t)$ has positive isotropic curvature, then (1.6) holds for any $p \in (0, 3)$.

Observe that $\mathbb{S}^2 \times \mathbb{R}^{n-2}$ with the standard soliton structure satisfies the estimate of Theorem 1.3 for $p = 2$, so the theorem is not sharp. Similarly for the soliton $\mathbb{S}^3 \times \mathbb{R}$, for $p = 3$. On the other hand, if (1.6) were to hold for $p = 2$ in dimension three or $p = 3$ in dimension four with positive isotropic curvature, this would imply quite strong control in the geometry of $(M, g(t))_{t \in [0,T]}$ in Theorem 1.1: by a result of Topping [30] the diameter of $(g(t))_{t \in [0,T]}$ would be uniformly bounded for all t ; see also Zhang [33].

Finally, we note that Theorem 1.3 is a consequence of stronger estimates on the curvature radius proven in Theorem 4.1; see also Theorem 4.3. Furthermore, the estimates of Theorems 1.1 and 1.3 can be strengthened to $p \in (0, n - 1)$ under appropriate bounds on the Weyl curvature; see Remarks 4.1 and 4.2.

2 A monotonicity formula for singular Ricci flows

In this section we describe a monotonicity formula, and its associated density, in the setting of a Ricci flow $(M, g(t))_{t \in (-T,0)}$, $T \in (0, +\infty]$ subject to a Type I curvature bound, namely

$$\sup_M |\text{Rm}(g(t))|_{g(t)} \leq \frac{B}{|t|}, \tag{2.1}$$

for $t \in (-T, 0)$, as introduced in [14]. Note that we allow for the possibility that

$$\limsup_{t \rightarrow 0} \sup_M |\text{Rm}(g(t))|_{g(t)} = +\infty.$$

Let us introduce some notation we will use throughout the paper. Given a Ricci flow $(M, g(t))_{t \in (-T,0]}$, $T \in (0, +\infty]$, and $x \in M$, let \mathfrak{g} denote the triplet $(M, g(t), x)_{t \in (-T,0]}$. When we want to distinguish between different pointed Ricci flows with the same underlying flow we will also use the notation \mathfrak{g}_x to denote $(M, g(t), x)_{t \in (-T,0]}$.

Moreover, for every $s > 0$ we will denote the rescaled flow, pointed at x , by

$$(\mathfrak{g}_x)_s = (M, s^{-2}g(s^2t), x)_{t \in (-T,0]}.$$

2.1 Perelman’s reduced volume

Let $(M, g(t))_{t \in [0,T]}$ be a complete smooth Ricci flow and let $l_{(x,T)}$ denote the reduced distance function based at $(x, T) \in M \times (0, T]$, as introduced by Perelman in [25]:

$$l_{(x,T)}(y, \tau) = \inf \left\{ \frac{1}{2\sqrt{\tau}} \int_0^\tau \sqrt{\bar{\tau}} \left(R(\gamma(\bar{\tau}), T - \bar{\tau}) + \left| \frac{d}{d\bar{\tau}} \gamma(\bar{\tau}) \right|_{g(T-\bar{\tau})}^2 \right) d\bar{\tau} \right\},$$

where the infimum is taken over all curves $\gamma : [0, \tau] \rightarrow M$ with $\gamma(0) = x$ and $\gamma(\tau) = y$.

Then, as in [25], we may define the reduced volume at scale $\tau > 0$ based at (x, T) :

$$\mathcal{V}_{(x,T)}(\tau) = \int_M \frac{e^{-l(y,\tau)}}{(4\pi\tau)^{n/2}} d\mu_{g(\tau)}(y). \tag{2.2}$$

Perelman discovered the remarkable fact that $\mathcal{V}_{(x,T)}(\tau)$ is monotone decreasing in τ . Moreover, $\lim_{\tau \rightarrow 0} \mathcal{V}_{(x,T)}(\tau) = 1$ and $\mathcal{V}_{(x,T)}(\tau)$ is constant if and only if $g(t)$ is the Euclidean space for every t .

With the notation introduced above, if $\mathfrak{g} = (M, g(t), x)_{t \in (-T,0)}$ we define

$$l_{\mathfrak{g}}(y, \tau) = l_{(x,0)}(y, \tau).$$

2.2 The space of uniformly type I flows

Let $\mathcal{RF}(n, B)$ denote the collection of all complete pointed Ricci flows $(M, g(t), x)_{t \in (-T,0)}$, where M is n -dimensional, $T \in (0, +\infty]$, and $g(t)$ satisfies (2.1) for all $t \in (-T, 0)$.

Moreover, let $\mathcal{RF}_{reg}(n, B)$ be the collection of $(M, g(t), x) \in \mathcal{RF}(n, B)$ satisfying

$$\sup_{M \times (-T,0)} |\text{Rm}(g(t))|_{g(t)} < +\infty.$$

Observe that any flow in $\mathfrak{g} = (M, g(t), x)_{t \in (-T,0)} \in \mathcal{RF}_{reg}(n, B)$ can be extended to a Ricci flow $(g(t))_{t \in (-T,0]}$ by Shi’s estimates.

We endow $\mathcal{RF}(n, B)$ with the topology of smooth Cheeger–Gromov convergence of Ricci flows, uniform in compact subsets of $M \times (-\infty, 0)$.

Let $T_i \nearrow 0$. Since any $(M, g(t), x)_{t \in (-T,0)}$ is the limit of the sequence $(M, g(t + T_i), x)_{t \in (-T - T_i, 0]}$, which satisfies (2.1), it follows that $\mathcal{RF}(n, B) = \overline{\mathcal{RF}_{reg}(n, B)}$.

It is a consequence of estimates of Naber in [24], as well as the work of Enders [10], that given a sequence $\{\mathfrak{g}_i\}_i$ and \mathfrak{g} in $\mathcal{RF}(n, B)$ such that $\mathfrak{g}_i \rightarrow \mathfrak{g}$, the corresponding sequence $l_{\mathfrak{g}_i}$ converges, up to subsequence, to a limit l in $C_{loc}^{0,\alpha}$.

Thus we are led to the following definition:

Definition 2.1 (Singular reduced distance) A function $l : M \times (0, T) \rightarrow \mathbb{R}$ is a singular reduced distance on $\mathfrak{g} = (M, g(t), x)_{t \in (-T,0)} \in \mathcal{RF}(n, B)$ if there is a sequence $\mathfrak{g}_i \in \mathcal{RF}_{reg}(n, B)$ such that $\mathfrak{g}_i \rightarrow \mathfrak{g}$ and $l_{\mathfrak{g}_i} \rightarrow l$ in $C_{loc}^{0,\alpha}$.

Remark 2.1 The estimates in [24] also imply that the collection of the singular reduced distances of a fixed $\mathfrak{g} \in \mathcal{RF}(n, B)$ is compact in the $C_{loc}^{0,\alpha}$ topology.

2.3 Reduced volume in the singular setting

Following Definition 2.1 and (2.2) we may define

$$\mathcal{V}_{\mathfrak{g},l}(\tau) = \int_M \frac{e^{-l(y,\tau)}}{(4\pi\tau)^{n/2}} d\mu_{g(-\tau)}(y), \tag{2.3}$$

where $\mathfrak{g} = (M, g(t), x)_{t \in (-T,0)} \in \mathcal{RF}(n, B)$ and l is a singular reduced distance on \mathfrak{g} .

The curvature bound (2.1) and the quadratic growth of a singular reduced distance l , again due to [24], imply that the map $l \mapsto \mathcal{V}_{\mathfrak{g},l}(\tau)$ is continuous, for every τ . Hence, by Remark 2.1 we may define the singular reduced volume of $\mathfrak{g} \in \mathcal{RF}(n, B)$ at scale τ as

$$\mathcal{V}_{\mathfrak{g}}(\tau) = \min\{\mathcal{V}_{\mathfrak{g},l}(\tau), l_{\text{singular reduced distance on } \mathfrak{g}}\}. \tag{2.4}$$

Remark 2.2 Note that $\mathcal{RF}(n, B) \subset \mathcal{RF}(n, B')$ for every $B' \geq B$. Thus, the reduced volume $\mathcal{V}_{\mathfrak{g}}(\tau)$ may depend on the choice of the constant $B < +\infty$; a larger constant leads to a larger number of competitors in the minimization procedure used to define $\mathcal{V}_{\mathfrak{g}}(\tau)$. Nevertheless, we see below that this definition has all the necessary properties we need in our analysis.

Before we describe some properties of the reduced volume, recall that a gradient shrinking Ricci soliton is a triplet (N, g, f) where (N, g) is a complete Riemannian manifold and $f \in C^\infty(N)$ satisfies

$$\text{Ric}(g) + \text{Hess}_g f = \frac{g}{2}.$$

It is a standard fact about gradient shrinking Ricci solitons that there is a constant c such that

$$R + |\nabla f|^2 - f = c.$$

We call (N, g, f) a *normalized Ricci soliton* and f a *normalized soliton function* if $c = 0$.

Moreover, we will say that $(N, h(t))_{t \in (-\infty, 0)}$ is induced by a gradient shrinking Ricci soliton if there exists a normalized soliton function $f \in C^\infty(N)$ such that $(N, h(-1), f)$ is a gradient shrinking Ricci soliton, and the vector field ∇f is complete.

Lemma 2.1 (Proposition 3.1 in [14]) *Given any $\mathfrak{g} \in \mathcal{RF}(n, B)$ the reduced volume $\mathcal{V}_{\mathfrak{g}}(\tau)$ has the following properties:*

- (1) $\mathcal{V}_{\mathfrak{g}}(\tau)$ is monotonically decreasing in τ .
- (2) If $\mathcal{V}_{\mathfrak{g}}(\tau_1) = \mathcal{V}_{\mathfrak{g}}(\tau_2)$ for some $0 < \tau_1 < \tau_2$, then for every τ

$$\mathcal{V}_{\mathfrak{g}}(\tau) = \mathcal{V}_{\mathfrak{g}, l}(\tau)$$

for some singular reduced distance l of \mathfrak{g} . Moreover, \mathfrak{g} is induced from a shrinking Ricci soliton and $l(\cdot, -1)$ is a normalized soliton function.

- (3) If there is a sequence $\mathfrak{g}_i \in \mathcal{RF}(n, B)$ such that $\mathfrak{g}_i \rightarrow \mathfrak{g}$ then

$$\liminf_i \mathcal{V}_{\mathfrak{g}_i}(\tau) \geq \mathcal{V}(\tau),$$

for every τ .

2.4 The density function

Using the monotonicity assertion from Lemma 2.1 we can define the density of $\mathfrak{g} \in \mathcal{RF}(n, B)$ as

$$\Theta_{\mathfrak{g}} := \lim_{\tau \rightarrow 0} \mathcal{V}_{\mathfrak{g}}(\tau). \tag{2.5}$$

Moreover, again from Lemma 2.1, it follows that if $\mathfrak{g}_i \rightarrow \mathfrak{g}$, where $\mathfrak{g}_i, \mathfrak{g} \in \mathcal{RF}(n, B)$, then

$$\liminf_i \Theta_{\mathfrak{g}_i} \geq \Theta_{\mathfrak{g}}. \tag{2.6}$$

Given a Ricci flow $(M, g(t))_{t \in (-T, 0)}$ satisfying (2.1), we now define the *density of $g(t)$ at $x \in M$* as

$$\Theta_g(x) = \Theta_{\mathfrak{g}_x}.$$

2.5 Reduced volume and density of shrinking Ricci solitons

Although the definition of the reduced volume involves minimization over all approximating Ricci flows, which makes it hard to compute, we see below that we can still say enough in the case of shrinking Ricci solitons. This is essentially due to the lower semicontinuity and scaling properties of the reduced volume.

Lemma 2.2 (Lemma 3.1 in [14]) *Let $\mathfrak{g} = (M, g(t), x)_{t \in (-\infty, 0)} \in \mathcal{RF}(n, B)$ induced by a normalized shrinking Ricci soliton $(M, g(-1), f)$.*

- (1) $\lim_{\tau \rightarrow \infty} \mathcal{V}_{\mathfrak{g}}(\tau) = \lim_{\tau \rightarrow \infty} \mathcal{V}_{\mathfrak{g}, l}(\tau) = \int_M (4\pi)^{-\frac{n}{2}} e^{-f} d\mu_{g(-1)}$, for any singular reduced distance l of \mathfrak{g} .
- (2) *If x is a critical point of f , then*

$$\Theta_{\mathfrak{g}}(x) = \int_M (4\pi)^{-\frac{n}{2}} e^{-f} d\mu_{g(-1)} \leq \Theta_{\mathfrak{g}}(y),$$

for any $y \in M$.

- (3) *If a singular reduced distance l of \mathfrak{g} is a soliton function then*

$$\mathcal{V}_{\mathfrak{g}}(\tau) = \mathcal{V}_{\mathfrak{g}, l}(\tau),$$

for every τ .

2.6 Tangent flows and density

Let $\mathfrak{h} \in \mathcal{RF}(n, B)$ be a tangent flow of $\mathfrak{g} \in \mathcal{RF}(n, B)$, namely the limit of a sequence $(\mathfrak{g})_{s_i}$, for $s_i \searrow 0$. By [24], \mathfrak{h} is induced by a gradient shrinking Ricci soliton. The following theorem is proven in [14]:

Theorem 2.1 (Theorem 5.1 in [14]) *Let $(N, h(-1), f)$ be the shrinking Ricci soliton associated to \mathfrak{h} , with f being a normalized soliton function. Then*

$$\Theta_{\mathfrak{g}} = \Theta_{\mathfrak{h}} = \int_N (4\pi)^{-\frac{n}{2}} e^{-f} d\mu_{h(-1)}. \tag{2.7}$$

It follows that, although not unique, any tangent flow of \mathfrak{g} has the same asymptotic reduced volume $\lim_{\tau \rightarrow +\infty} \mathcal{V}_{\mathfrak{h}}(\tau)$, by Lemma 2.2.

We describe below another important implication of Theorem 2.1: although the reduced volume may depend on B , as was discussed in Remark 2.2, the density is independent of such choice. This follows from the observation that the collection of tangent flows \mathfrak{h} does not depend on B . Hence, the corresponding asymptotic reduced volume is independent of B , thus from Theorem 2.1 the density $\Theta_{\mathfrak{g}}$ also does not depend on B .

2.7 The spine of a shrinking Ricci soliton

Let $(N, h(-1), f)$ be a gradient shrinking Ricci soliton with bounded curvature, and associated Ricci flow $(N, h(t))_{t \in (-\infty, 0)}$. It is easy to see that this flow satisfies (2.1), for some $B < +\infty$.

The discussion above shows that the density function $\Theta_h : N \rightarrow (0, 1]$ is well defined and independent of the choice of the class $\mathcal{RF}(n, B)$.

We can thus define the *spine* of $(N, h(t))_{t \in (-\infty, 0)}$ as

$$S(N, h) = \{x \in N, \Theta_h \text{ attains its minimum value at } x\}.$$

We note that $S(N, h)$ is non-empty, since Θ_h attains a minimum value at any critical point of f , by Lemma 2.2. Due to the quadratic growth of f , see for instance [16], f always has a critical point.

Moreover, the lower semicontinuity of the density function (2.6) implies that $S(N, h)$ is a closed subset of N .

The notion of the spine $S(N, h)$ will be important to us because of the following theorem.

Theorem 2.2 (Theorem 4.1 in [14]) *Let $(N, h(t))_{t \in (-\infty, 0)}$ be the Ricci flow induced by a non-flat gradient shrinking Ricci soliton satisfying (2.1). Then, there exists an integer $2 \leq k \leq n$, a constant $D(n, B) < +\infty$, and a gradient shrinking Ricci soliton $(\bar{N}, \bar{h}(t))_{t \in (-\infty, 0)}$ such that*

- (1) $(N, h(t))$ splits isometrically as $(\bar{N}, \bar{h}(t)) \times (\mathbb{R}^{n-k}, g_{Eucl})$.
- (2) $S(N, h) = K \times \mathbb{R}^{n-k}$ and $\text{diam}_{\bar{h}(t)}(K) \leq D\sqrt{-t}$ for every $t \in (-\infty, 0)$.

Remark 2.3 Observe that if $k = 1$ above $(N, h(t))$ is necessarily the Euclidean space.

Remark 2.4 Note that in the regularity theory for harmonic maps/minimal currents, the spine is defined as the set where the density attains its maximum, in contrast to the definition above where the spine consists of points with minimal density. This is due to the reversal of the monotonicity and semicontinuity properties of the reduced volume.

Recall that the spine of a tangent map/cone is also the linear subspace of the available translation symmetries. Theorem 2.2 can be viewed as the analogue of this fact for shrinking Ricci solitons with bounded curvature, as it implies that the spine $(S(N, h), h(t))$ converges to \mathbb{R}^{n-k} in the pointed Gromov–Hausdorff topology, as $t \rightarrow 0$.

Remark 2.5 If $(N, h(t))_{t \in (-\infty, 0)}$ is the flow induced by a compact shrinking Ricci soliton, the tangent flow at any $x \in N$ is $(N, h(t), x)_{t \in (-\infty, 0)}$. This implies that the density function Θ_h is constant, hence $S(N, h) = N$.

The same holds if $N = \bar{N} \times \mathbb{R}^k$ for some compact shrinking Ricci soliton (\bar{N}, g, f) , as for example $\mathbb{S}^{n-k} \times \mathbb{R}^k$ with the standard soliton structure.

For the $U(n)$ -invariant shrinking Kähler Ricci solitons on line bundles over $\mathbb{C}P^{n-1}$ constructed in [13], the spine is the zero section \mathcal{Z} of the corresponding line bundle. This is because the flow is non-singular away from \mathcal{Z} and $U(n)$ acts isometrically and transitively on \mathcal{Z} .

2.8 Compactness of shrinking solitons

Below we prove a compactness theorem for Ricci solitons, under a uniform curvature bound. Moreover, Lemma 2.4 asserts that, along a convergent sequence of such solitons, points with lowest density converge to points in the spine of the limit.

We first need the following auxiliary lemma, which allows to center soliton functions ‘around’ a given point on the spine.

Lemma 2.3 (Aligning a soliton function to a point on the spine) *Let (N, g, f) be a gradient shrinking Ricci soliton satisfying*

$$\sup_N |\text{Rm}(g)|_g \leq B,$$

for some $B < +\infty$ and f is a normalized soliton function. Also, let $q \in S(N, g)$. Then, there is a normalized soliton function f' with a critical point $p \in N$ such that

$$d_g(p, q) \leq D, \tag{2.8}$$

where $D = D(n, B) < +\infty$ is the constant given by Theorem 2.2.

Proof By Theorem 2.2, (N, g) splits isometrically as $(\bar{N}^k, \bar{g}) \times \mathbb{R}^{n-k}$ and $S(N, g) = K \times \mathbb{R}^{n-k}$, where K is compact and satisfies

$$\text{diam}_{\bar{g}}(K) \leq D. \tag{2.9}$$

We may assume that $q = (\bar{q}, 0)$ for some $\bar{q} \in K$.

Now, let $p_0 = (\bar{p}, v_0) \in \bar{N} \times \mathbb{R}^k$ be a critical point for f and define f' by

$$f'(\bar{x}, v) = f(\bar{x}, v + v_0).$$

Note that f' is also a normalized soliton function and has a critical point at $(\bar{p}, 0)$.

Lemma 2.2 implies that critical points of f' are in $S(N, g)$, thus $\bar{p} \in K$. Then, (2.9) implies that

$$d_g(p, q) = d_{\bar{g}}(\bar{p}, \bar{q}) \leq D.$$

□

Lemma 2.4 Let $(N_i, h_i(t), q_i)_{t \in (-\infty, 0)}$ be a sequence of pointed complete Ricci flows induced by gradient shrinking Ricci solitons with bounded curvature. Suppose that

$$\sup_{N_i} |\text{Rm}(h_i(t))|_{h_i(t)} \leq \frac{B}{|t|} \tag{2.10}$$

for $t \in (-\infty, 0)$ and

$$\text{inj}_{h_i(-1)}(q_i) \geq i_0. \tag{2.11}$$

Then, there exists a subsequence $(N_{i_l}, h_{i_l}(t), q_{i_l})_{t \in (-\infty, 0)}$ converging in the smooth Cheeger–Gromov topology to $(N_\infty, h_\infty(t), q_\infty)_{t \in (-\infty, 0)}$, which also satisfies (2.10) and is induced by a shrinking Ricci soliton with bounded curvature.

Moreover, if $q_i \in S(N_i, h_i)$, then $q_\infty \in S(N_\infty, h_\infty)$ and

$$\Theta_{h_\infty}(q_\infty) = \lim_i \Theta_{h_i}(q_i).$$

Proof In view of bounds (2.10)–(2.11) and Hamilton’s compactness theorem for sequences of Ricci flows, passing to a subsequence if necessary, we may assume that $(N_i, h_i(t), q_i)_{t \in (-\infty, 0)}$ converges to a limit flow $(N_\infty, h_\infty, q_\infty)_{t \in (-\infty, 0)}$ that also satisfies (2.10).

Now, suppose that $q_i \in S(N_i, h_i)$ and let f_i be normalized soliton functions with critical points $p_i \in N_i$, satisfying

$$d_{h_i}(p_i, q_i) \leq D, \tag{2.12}$$

given by Lemma 2.3.

Since p_i is a critical point, (2.10) implies

$$|f_i(p_i)| = |R(h_i(-1))(p_i) + |\nabla f_i(p_i)|^2| \leq C(n, B). \tag{2.13}$$

Differentiating the soliton equation and applying Shi’s derivative estimates we obtain uniform bounds on f_i and its derivatives, within bounded distance from p_i . Thus, by Arzela–Ascoli

and passing to a subsequence if necessary, using (2.12), we may assume that f_i converges smoothly to a function f_∞ on N_∞ , uniformly locally. Moreover, f_∞ is a normalized soliton function, since it is a property that passes to smooth limits.

Since f_i grow quadratically in the distance from p_i , and the volume of $\text{vol}_{h_i(-1)}(B_{p_i}(r))$ grows at most exponentially in r , it follows that

$$\int_{N_i} e^{-f_i} d\mu_{h_i(-1)} \rightarrow \int_{N_\infty} e^{-f_\infty} d\mu_{h_\infty(-1)}. \tag{2.14}$$

Since $q_i \in S(N_i, h_i)$, recall that $\Theta_{h_i}(q_i) = \int_{N_i} e^{-f_i} d\mu_{h_i(-1)}$, due to Lemma 2.2. The lower semicontinuity of the density function under the Cheeger–Gromov convergence of Ricci flows and (2.14) imply that

$$\int_{N_\infty} e^{-f_\infty} d\mu_{h_\infty(-1)} \geq \Theta_{h_\infty}(q_\infty). \tag{2.15}$$

On the other hand, monotonicity of reduced volume and Lemma 2.2 implies that

$$\int_{N_\infty} e^{-f_\infty} d\mu_{h_\infty(-1)} = \lim_{\tau \rightarrow +\infty} \mathcal{V}_{q_\infty}(\tau) \leq \Theta_{h_\infty}(q_\infty). \tag{2.16}$$

Thus, Θ_{h_∞} attains its minimum value $\int_{N_\infty} e^{-f_\infty} d\mu_{h_\infty(-1)} = \lim_i \Theta_{h_i}(q_i)$ at q_∞ , hence $q_\infty \in S(N_\infty, h_\infty)$. This suffices to prove the Lemma. \square

3 The quantitative stratification

In this section we adapt the ideas of Cheeger–Naber from [7] to the setting of Ricci flows subject to a Type I curvature bound. In particular, we define the quantitative stratification and prove volume estimates similar to those in [7].

The principal use of the Type I hypothesis here is that it provides us with a well-defined monotone quantity for the Ricci flow *up to the singular time* exploiting the available bounds on the reduced distance from [10,24], as in Sect. 2. The existence of such monotone quantity is crucially exploited in [7], and it remains an important open problem how to obtain such quantity for the Ricci flow in general since there is no heat kernel coming from an ambient space.

Before we define the quantitative stratification in detail, a few definitions are in order. First, we need an appropriate notion of ‘closeness’ of two pointed Ricci flows:

Definition 3.1 Let $\mathfrak{g}_1 = (M_1, g_1(t), p_1)_{t \in (-2,0)}$, $\mathfrak{g}_2 = (M_2, g_2(t), p_2)_{t \in (-2,0)}$ be complete pointed Ricci flows. We say that \mathfrak{g}_2 is η -close to \mathfrak{g}_1 , $\eta > 0$, if the following holds:

- (1) There exists $U \subset M_1$ with $B_{g_1(-1)}(p_1, \eta^{-1}) \subset U$ and a smooth map $F : U \rightarrow M_2$, diffeomorphism onto its image, satisfying $F(p_1) = p_2$.
- (2) $(1 + \eta)^{-2} g_1(t) \leq F^* g_2(t) \leq (1 + \eta)^2 g_1(t)$ for every $t \in [-2 + \eta, -\eta]$.
- (3) $|(\nabla^{g_1(t)})^l F^* g_2(t)|_{g_1(t)} < \eta$ for $t \in [-2 + \eta, -\eta]$ and $1 \leq l \leq \lfloor 1/\eta \rfloor$.

Recall that from the work of Naber [24], tangent flows are selfsimilar solutions to the Ricci flow, induced by shrinking Ricci solitons. In other words, the flow looks selfsimilar in small scales. The definition below makes this precise, and also quantifies the amount of translational symmetry of a given Ricci flow, in the sense of isometric splitting of Euclidean factors.

Definition 3.2 Given $\varepsilon > 0$, $r \in (0, 1]$, $B < +\infty$ and integer $k \geq 0$, a Ricci flow $\mathfrak{g}_x = (M, g(t), x)_{t \in (-2, 0)}$ is (ε, r, k, B) -selfsimilar with respect to the k -dimensional subspace $V \subset T_x M$ if there exists a pointed shrinking Ricci soliton

$$\mathfrak{h} = (N, h(t), q)_{t \in (-\infty, 0)} = (\tilde{N}, \tilde{h}(t), \tilde{q}) \times (\mathbb{R}^k, g_{Eucl}, 0)$$

satisfying $\sup_N |\text{Rm}(h(-1))|_{h(-1)} \leq B$, such that $q \in S(N, h)$, $(\mathfrak{g}_x)_r$ is ε -close to \mathfrak{h} and $V = F_*({0} \times \mathbb{R}^k)$, where $F_* : T_{\tilde{q}} \tilde{N} \times \mathbb{R}^k \rightarrow T_p M$, F as in Definition 3.1.

Including a uniform *global* curvature bound for the soliton in the definition above is an unusual feature, compared to other instances of quantitative stratification. Here, it provides the essential control on the geometry of the spine, by Theorem 2.2.

From now on we fix a $B < +\infty$ and define the quantitative stratification as follows:

Definition 3.3 Let $(M, g(t))_{t \in (-2, 0)}$ be a complete Ricci flow, $\dim M = n$. Given an integer $0 \leq k \leq n$, $\eta > 0$ and $\tau \in (0, 1]$ define $S_{\eta, \tau}^k \subset M$ as follows:

$$S_{\eta, \tau}^k = \{x \in M, \mathfrak{g}_x \text{ is not } (\eta, s, k + 1, B)\text{-selfsimilar for any } s \in [\tau^{1/2}, 1]\}.$$

Note that the following inclusions hold when $k' \geq k$, $\eta' \leq \eta$ and $\tau' \geq \tau$:

$$S_{\eta, \tau}^k \subset S_{\eta', \tau'}^{k'}.$$

Moreover, applying Lemma 2.4 we easily see that the quantitative stratification $S_{\eta, \tau}^k$ is related to the stratification Σ_k of the singular set Σ of $(M, g(t))_{t \in (-2, 0)}$ by

$$\Sigma_k = \bigcup_{\eta} \bigcap_{\tau} S_{\eta, \tau}^k.$$

The aim of this section is to prove Theorem 1.2.

3.1 Almost self-similar scales

In this section we see that the scales and points around which a Ricci flow in $\mathcal{RF}(n, B)$ looks selfsimilar are characterized by the associated reduced volume being ‘almost’ constant. We then show, in Lemma 3.3, that as the flow evolves such points are locally ‘attracted’ towards a lower dimensional submanifold.

Lemma 3.1 (Quantitative rigidity) *For every $\varepsilon, \kappa > 0$ and $B < +\infty$, there exists $0 < \delta_1(\varepsilon, \kappa, B) \leq \varepsilon$ such that if $\mathfrak{g} = (M, g(t), x)_{t \in (-2, 0)} \in \mathcal{RF}(n, B)$ satisfies*

- (1) $g(t)$ is κ non-collapsed below scale 1 for all $t \in (-2, 0)$,
- (2) $\mathcal{V}_{\mathfrak{g}}(\delta_1 r^2) - \mathcal{V}_{\mathfrak{g}}(r^2) < \delta_1$, for some $r \in (0, 1]$

then \mathfrak{g} is $(\varepsilon, r, 0, B)$ -selfsimilar.

Proof Fix $\varepsilon, \kappa > 0$, $\gamma \in (0, 1)$ and $B < +\infty$. Suppose there is a sequence $\mathfrak{g}_i = (M_i, g_i(t), x_i)_{t \in (-2, 0)} \in \mathcal{RF}(n, B)$ that is κ non-collapsed below scale 1, and sequences $\delta_i \searrow 0$, $\delta_i < 1/2$, and $r_i \in (0, 1]$ such that

$$\mathcal{V}_{\mathfrak{g}_i}(\delta_i r_i^2) - \mathcal{V}_{\mathfrak{g}_i}(r_i^2) < \delta_i, \tag{3.1}$$

but \mathfrak{g}_i is not $(\varepsilon, r_i, 0, B)$ -selfsimilar.

The curvature bound of the class $\mathcal{RF}(n, B)$ and the κ non-collapsing assumption imply that a subsequence of $(g_i)_{r_i}$ converges to a complete pointed Ricci flow $\mathfrak{h} = (N, h(t), q)_{t \in (-2, 0)} \in \mathcal{RF}(n, B)$ in the smooth Cheeger–Gromov topology.

Let l_i be a singular reduced distance function of $(g_i)_{r_i}$ that realizes the reduced volume at scale $1/2$, namely

$$\mathcal{V}_{(g_i)_{r_i}}(1/2) = \mathcal{V}_{(g_i)_{r_i}, l_i}(1/2).$$

From the estimates of Naber [24], a subsequence of l_i converges to a singular reduced distance l_∞ of \mathfrak{h} , thus a subsequence of $\mathcal{V}_{(g_i)_{r_i}}(1/2)$ converges to $\mathcal{V}_{\mathfrak{h}, l_\infty}(1/2)$. Moreover, for the same reason a subsequence of $\mathcal{V}_{(g_i)_{r_i}, l_i}(1)$ converges to $\mathcal{V}_{\mathfrak{h}, l_\infty}(1)$.

Hence, from monotonicity and (3.1), it follows that

$$\mathcal{V}_{\mathfrak{h}, l_\infty}(1) \leq \mathcal{V}_{\mathfrak{h}, l_\infty}(1/2) \leq \mathcal{V}_{\mathfrak{h}, l_\infty}(1), \tag{3.2}$$

since by the definition of the singular reduced volume

$$\mathcal{V}_{(g_i)_{r_i}}(1) \leq \mathcal{V}_{(g_i)_{r_i}, l_i}(1).$$

Thus, l_∞ is a normalized soliton function and \mathfrak{h} is a shrinking Ricci soliton, by Lemma 2.1. Moreover, the underlying Ricci flow of \mathfrak{h} satisfies the Type I bound (2.1). This contradicts the assumption that g_i is not $(\varepsilon, r_i, 0, B)$ -selfsimilar. \square

Remark 3.1 Note that in the proof of Lemma 3.1 we do not use the full strength of assumption (2) and in fact the lemma holds under the weaker hypothesis

$$\mathcal{V}_g(\gamma r^2) - \mathcal{V}_g(r^2) < \delta_1,$$

for some $r \in (0, 1]$ and $\gamma \in (0, 1)$, and small enough δ_1 , with the same proof. However, the current proof uses the forward [9] and backward [21] uniqueness property of complete Ricci flows with bounded curvature in an essential way, namely to assert that in part (2) of Lemma 2.1 the flow g is a shrinking soliton for all time.

The weaker statement of Lemma 3.1 is more likely to hold in the incomplete setting, and it suffices for the arguments of this section.

Lemma 3.2 (Almost splitting) *For every $\varepsilon, \lambda, \mu, \kappa > 0$, $\gamma \in (0, 1]$ and $B < +\infty$, there exists $0 < \delta_2(\varepsilon, \lambda, \mu, \kappa, B, \gamma) \leq \varepsilon$ such that, if $(M, g(t), x_1)_{t \in (-2, 0)} \in \mathcal{RF}(n, B)$, $g(t)$ is κ non-collapsed below scale 1 for every $t \in (-2, 0)$ and for some $r \in (0, 1]$*

- (1) $(M, g(t), x_1)$ is (δ_2, r, k, B) -selfsimilar at x_1 with respect to $V \subset T_{x_1}M$, for some $0 \leq k \leq n$,
- (2) $(M, g(t), x_2)$ is $(\delta_2, r, 0, B)$ -selfsimilar,
- (3) $d_{g(-r^2)}(x_1, x_2) < \lambda r$,
- (4) $d_{g(-\tau)}(x_2, \exp_{g(-\gamma r^2), x_1}(V \cap B_0(2\lambda r))) \geq (D + \mu)\sqrt{\tau}$
for some $\tau \in [r^2\mu, r^2(2-\mu)]$, where $D = D(n, B)$ is the constant given by Theorem 2.2,

then $(M, g(t), x_1)_{t \in (-2, 0)}$ is $(\varepsilon, r, k + 1, B)$ -selfsimilar.

Proof Fix $\varepsilon, \lambda, \mu, \kappa > 0$, $\gamma \in (0, 1]$ and $B < +\infty$, as in the statement of the theorem. Suppose there are sequences $\delta_i \searrow 0$ and $r_i \in (0, 1]$, and a sequence of Ricci flows $(M_i, g_i(t))_{t \in (-2, 0)} \in \mathcal{RF}(n, B)$, κ non-collapsed below scale 1, satisfying:

- (1) $(M_i, g_i(t), x_1^i)$ is (δ_i, r_i, k, B) -selfsimilar with respect to $V_i \subset T_{x_1^i}M_i$,
- (2) $(M_i, g_i(t), x_2^i)$ is $(\delta_i, r_i, 0, B)$ -selfsimilar,

$$(3) \quad d_{g_i(-r_i^2)}(x_1^i, x_2^i) < \lambda r_i,$$

$$(4) \quad d_{g_i(-\tau_i)}(x_2^i, \exp_{g_i(-\gamma r_i^2), x_1^i}(V_i \cap B_0(2\lambda r_i))) \geq (D + \mu)\sqrt{\tau_i} \quad \text{for some } \tau_i \in [r_i^2\mu, r_i^2(2 - \mu)],$$

but such that $(M_i, g_i(t), x_1^i)$ is not $(\varepsilon, r_i, k + 1, B)$ -selfsimilar.

Since $\delta_i \searrow 0$, assumption (1) above and Lemma 2.4 imply that we may assume, by passing to subsequence if necessary, that $(M_i, r_i^{-2}g_i(r_i^2t), x_1^i)$ converges in the smooth pointed Cheeger–Gromov topology to a shrinking Ricci soliton

$$(N, h(t), q_1)_{t \in (-\infty, 0)} = (\tilde{N}, \tilde{h}(t), \tilde{q}_1) \times (\mathbb{R}^k, g_{Eucl}, 0).$$

with $q_1 \in S(N, h)$, which satisfies $\sup_N |\text{Rm}(h(-1))|_{h(-1)} \leq B$.

Moreover, since $(M_i, g_i(t), x_1^i)$ is not $(\varepsilon, r_i, k + 1, B)$ -selfsimilar, it follows that $(\tilde{N}, \tilde{h}(t))$ does not split any Euclidean factors. Then, by Theorem 2.2, $S(N, h) = K \times \mathbb{R}^k$, where $K \subset \tilde{N}$ is compact and satisfies

$$\text{diam}_{\tilde{h}(-\tau)}(K) \leq D\sqrt{\tau}, \tag{3.3}$$

for every $\tau \in (0, +\infty)$.

Similarly, we may assume that $(M_i, r_i^{-2}g_i(r_i^2t), x_2^i)$ converges to a shrinking Ricci soliton $(\hat{N}, \hat{h}(t), \hat{q})$, with $\hat{q} \in S(\hat{N}, \hat{h})$.

Since $d_{g_i(-r_i^2)}(x_1^i, x_2^i) < \lambda r_i$, the flows $(N, h(t))$ and $(\hat{N}, \hat{h}(t))$ are isometric, by the uniqueness of smooth limits, so from now on we will identify them. In particular, we identify \hat{q} with $q_2 \in N$.

Then, since $q_1, q_2 \in S(N, h) = K \times \mathbb{R}^k$, let $q_1 = (\tilde{q}_1, 0)$ and $q_2 = (\tilde{q}_2, v)$, $v \in \mathbb{R}^k$.

Now, if $\Phi_i : B_{h(-1)}(q_1, R_i) \rightarrow M_i$, where $R_i \rightarrow +\infty$, are diffeomorphisms associated to the convergence, then

$$\Phi_i^{-1}(\exp_{g_i(-\gamma r_i^2), x_1^i}(V_i)) \rightarrow \{\tilde{q}_1\} \times \mathbb{R}^k,$$

smoothly and uniformly on compact sets. Moreover, $\Phi_i^{-1}(x_2^i) \rightarrow q_2 \in N$ and $\tau_i \rightarrow \bar{\tau}$, up to subsequence.

Since $q_2 = (\tilde{q}_2, v) \in K \times \mathbb{R}^k$, by (3.3) we conclude that

$$d_{h(-\bar{\tau})}(q_2, \{\tilde{q}_1\} \times \mathbb{R}^k) = d_{\tilde{h}(-\bar{\tau})}(\tilde{q}_1, \tilde{q}_2) \leq D\sqrt{\bar{\tau}}, \tag{3.4}$$

since the splitting $N = \tilde{N} \times \mathbb{R}^k$ is isometric.

On the other hand, $d_{g_i(-\tau_i)}(x_2^i, \exp_{g_i(-\gamma r_i^2), x_1^i}(V_i \cap B_0(2\lambda r_i))) \geq (D + \mu)\sqrt{\tau_i}$ implies that

$$d_{h(-\bar{\tau})}(q_2, \{\tilde{q}_1\} \times \mathbb{R}^k) \geq (D + \mu)\sqrt{\bar{\tau}},$$

which contradicts (3.4). □

Lemma 3.3 (Line-up lemma) *Let $\mathfrak{g}_x := (M, g(t), x)_{t \in (-2, 0)} \in \mathcal{RF}(n, B)$ such that $g(t)$ is κ non-collapsed below scale 1 for every $t \in (-2, 0)$. Then, for every $\lambda, \mu, \nu > 0$ and $\gamma \in (0, 1)$ there exists $\delta_3(B, \gamma, \kappa, \lambda, \mu, \nu) > 0$ such that if*

$$\mathcal{V}_{\mathfrak{g}_x}(\delta_3 \bar{\tau}) - \mathcal{V}_{\mathfrak{g}_x}(\bar{\tau}) < \delta_3, \tag{3.5}$$

for some $\bar{\tau} \in (0, 1]$, then there exists $0 \leq k \leq n$ and a k -dimensional subspace V of $T_x M$ such that

- (1) \mathfrak{g}_x is $(\nu, \bar{\tau}^{1/2}, k, B)$ -selfsimilar with respect to V .

(2) *The set*

$$L_{\bar{\tau}, \delta_3} = \{y \in M, \mathcal{V}_{g_y}(\delta_3 \bar{\tau}) - \mathcal{V}_{g_y}(\bar{\tau}) < \delta_3\}$$

satisfies

$$L_{\bar{\tau}, \delta_3} \cap B_{g(-\bar{\tau})}(x, \lambda \bar{\tau}^{1/2}) \subset T_{(D+\mu)\sqrt{\bar{\tau}}}^{g(-\tau)}(\exp_{g(-\gamma \bar{\tau}), x}(V \cap B_0(2\lambda \bar{\tau}^{1/2}))), \tag{3.6}$$

for every $\tau \in [\mu \bar{\tau}, (2 - \mu)\bar{\tau}]$, where D is the constant given by Theorem 2.2.

Here $T_r^g(S)$ denotes the r -tubular neighbourhood of a set S with respect to the Riemannian metric g .

Proof Let $\delta(v) = \delta_2(v, \lambda, \mu, \kappa, B, \gamma) \leq v$, where δ_2 is given by Lemma 3.2, and set $a_i(v) = \delta \circ \dots \circ \delta(v) \leq v$, where the composition is taken i -times. Then, choose $\delta_3 = \delta_1(a_n(v), \kappa, B)$, where δ_1 is given by Lemma 3.1. Thus, by (3.5), it follows that g_x is $(a_n, \bar{\tau}^{1/2}, 0, B)$ -selfsimilar.

Let k be the maximum integer such that $0 \leq k \leq n$ and g_x is $(a_{n-k}, \bar{\tau}^{1/2}, k, B)$ -selfsimilar with respect to some $V^k \subset T_x M$.

Suppose that (3.6) doesn't hold for some $\tau \in [\mu \bar{\tau}, (2 - \mu)\bar{\tau}]$. Thus, there is $y \in B_{g(-\bar{\tau})}(x, \lambda \bar{\tau}^{1/2})$ with $\mathcal{V}_{g_y}(\delta_3 \bar{\tau}) - \mathcal{V}_{g_y}(\bar{\tau}) < \delta_3$ but

$$d_{g(-\tau)}(y, \exp_{g(-\gamma \bar{\tau}), x}(V \cap B_0(2\lambda \bar{\tau}^{1/2}))) \geq (D + \mu)\sqrt{\bar{\tau}}.$$

By Lemma 3.1 it is also true that g_y is $(a_n, \bar{\tau}^{1/2}, 0, B)$ -selfsimilar. It then follows by Lemma 3.2 that g_x is $(a_{n-(k+1)}, \bar{\tau}^{1/2}, k + 1, B)$ -selfsimilar, which is a contradiction. \square

Remark 3.2 Although the arguments in Lemmata 3.2 and 3.3 are very similar to other instances of quantitative stratification [3,5–8], it is interesting to point out how Lemma 3.3 differs.

In [3,5–8] the selfsimilar points line up close to a lower dimensional subspace. Taking the analogy to the Ricci flow naively, one might expect that selfsimilar points will tend to line up around a lower dimensional submanifold. However, this is certainly not true for the Ricci flow, as the example of the standard Ricci flow on the cylinder $S^2 \times \mathbb{R}$, becoming singular at $t = 0$, shows: there, every point is selfsimilar, but the diameter of the S^2 factor is small only for times near $t = 0$. This example illustrates that a statement like that of Lemma 3.3 is more likely to hold.

3.2 Energy decomposition

Let $(M, g(t))_{t \in (-2, 0)}$ be a complete Ricci flow with bounded curvature satisfying:

- $|\text{Rm}(g(t))|_{g(t)} \leq B/|t|$ on $M \times (-2, 0)$,
- $g(t)$ is κ non-collapsed below scale 1.

For every $x \in M$ and $0 < \tau_1 < \tau_2 \leq 1$ define

$$\mathcal{W}_{\tau_1, \tau_2}(x) = \mathcal{V}_{g_x}(\tau_1) - \mathcal{V}_{g_x}(\tau_2) \geq 0.$$

Let $\alpha, \gamma \in (0, 1)$ and $\delta > 0$, and set $\tau_i = \gamma^i \alpha$. Then, for every $x \in M$ define the sequence

$$T(x) := (T_1(x), T_2(x), \dots) \in \{0, 1\}^{\mathbb{N}}$$

as

$$T_i(x) := \begin{cases} 1, & \mathcal{W}_{\delta \tau_{i-1}, \tau_{i-1}}(x) \geq \delta, \\ 0, & \mathcal{W}_{\delta \tau_{i-1}, \tau_{i-1}}(x) < \delta. \end{cases}$$

Now, given any $\mathbf{a} = (a_1, \dots, a_j) \in \{0, 1\}^j$, for some integer $j \geq 1$, define $E_{\mathbf{a}} \subset M$ as follows:

$$E_{\mathbf{a}} = \{x \in M, T_i(x) = a_i \text{ for every } 1 \leq i \leq j\}.$$

3.3 Quantitative differentiation

A priori there are 2^j sets of the form $E_{\mathbf{a}}$, for $\mathbf{a} \in \{0, 1\}^j$. We will see below that there is in fact a much smaller number of such sets, which grows polynomially in j .

Let $m \geq 1$ be the minimum integer so that the intervals $[\gamma^{m(i-1)}\alpha, \delta\gamma^{m(i-1)}\alpha]$, for all integers $i \geq 1$, are disjoint. Namely $m = \lceil \frac{\log \delta}{\log \gamma} \rceil$. Since

$$\sum_{i=1}^{\infty} \mathcal{W}_{\delta\gamma^{m(i-1)}\alpha, \gamma^{m(i-1)}\alpha}(x) \leq \Theta_g(x) - \mathcal{V}_{g_x}(\alpha) \leq 1,$$

it follows that the number of non-negative integers i for which

$$\mathcal{W}_{\delta\gamma^{m(i-1)}\alpha, \gamma^{m(i-1)}\alpha}(x) \geq \delta$$

is at most $\lfloor 1/\delta \rfloor$, hence the number of integers i for which

$$\mathcal{W}_{\delta\gamma^{i-1}\alpha, \gamma^{i-1}\alpha}(x) \geq \delta$$

is at most $m \lfloor 1/\delta \rfloor$.

Thus, for each $x \in M$, $T_i(x) = 1$ for at most $K(\delta, \gamma) = m \lfloor 1/\delta \rfloor$ values of i . This implies that for $j \geq K$ there are only

$$\binom{j}{K} \leq j^K \tag{3.7}$$

disjoint sets $E_{\mathbf{a}}$ for $\mathbf{a} \in \{0, 1\}^j$. Thus, for any $j \geq 1$ there are at most $2j^K$ disjoint such subsets.

3.4 Covering lemma

Let $(M, g(t))_{t \in (-2, 0)}$ be a complete Ricci flow belonging to the class $\mathcal{C}(n, B, \kappa_0, \kappa_1)$.

Lemma 3.4 *Given $\alpha \leq 1$, there exists a $\kappa_2(\alpha, B, \kappa_0) > 0$ such that for every $x \in M$, and $r \leq \gamma^{1/2}$, $\tau_l = \gamma^l \alpha$ for any $l \geq 0$:*

$$\kappa_2 r^n \leq \text{vol}_{g(-\tau_l)}(B_{g(-\tau_l)}(x, r)) \leq \kappa_1 r^n. \tag{3.8}$$

Proof We will first prove the lower bound. The curvature bound of the class $\mathcal{C}(n, B, \kappa_0, \kappa_1)$ implies that for every $l \geq 0$

$$|\text{Rm}(g(-\tau_l))|_{g(-\tau_l)} \leq \frac{B}{\gamma^l \alpha},$$

hence the κ_0 non-collapsing property implies that for every scale r small enough so that $\frac{B}{\gamma^l \alpha} \leq \frac{1}{r^2}$

$$\text{vol}_{g(-\tau_l)}(B_{g(-\tau_l)}(x, r)) \geq \kappa_0 r^n. \tag{3.9}$$

Note that for every $r \leq \gamma^{1/2}$

$$\frac{B}{\gamma^l \alpha} \leq \frac{B}{r^2 \alpha} = \frac{1}{(\zeta r)^2},$$

where $\zeta = (\frac{\alpha}{B})^{1/2} \leq 1$, since we can assume without loss of generality that $B > 1$.

Thus, we may now use (3.9) to estimate, for every $r \leq \gamma^{1/2}$,

$$\text{vol}_{g(-\tau_l)}(B_{g(-\tau_l)}(x, r)) \geq \text{vol}_{g(-\tau_l)}(B_{g(-\tau_l)}(x, \zeta r)) \geq \kappa_0 \zeta^n r^n.$$

The lower bound of the claim now follows by putting $\kappa_2 = \zeta^n \kappa_0$.

The upper bound directly follows from the κ_1 non-inflating property (i.e. requirement (3) in the definition of the class $\mathcal{C}(n, B, \kappa_0, \kappa_1)$) since $\gamma^{l/2} \leq 1$. □

Lemma 3.5 (Covering lemma) *There are $\alpha(B, \gamma), \delta(B, \gamma, \kappa_0, \eta) > 0$ so that the construction of Sects. 3.2 and 3.3 satisfies the following: there exist $C_1, C_2 < +\infty$ and $\beta(B, \gamma) \in (0, 1/2)$ such that, for every $x \in M$, any $\mathbf{a} \in \{0, 1\}^j, j \geq 1$, the set $S_{\eta, \gamma^{j-1}\alpha}^k \cap E_{\mathbf{a}} \cap B_{g(-\alpha)}(x, \beta)$ is covered by at most*

$$C_1(C_2 \gamma^{-k})^j$$

$g(-\tau_{j-1})$ metric balls of radius r_{j-1} centered at $S_{\eta, \gamma^{j-1}\alpha}^k$, where $\tau_j = \gamma^j \alpha$ and $r_j = \gamma^{j/2} \beta$.

In particular, C_1 depends only on $n, \kappa_0, \kappa_1, B, \gamma$ and C_2 only on n .

Proof We prove this by induction. For $j = 1$ we only need to estimate the number P of balls $B_{g(-\tau_0)}(y_i, r_0), i = 1, \dots, P$, in a minimal covering of

$$S_{\eta, \alpha}^k \cap B_{g(-\alpha)}(x, \beta),$$

where $y_i \in S_{\eta, \alpha}^k \cap B_{g(-\alpha)}(x, \beta)$. Note that α, β will be chosen later, depending only on B and γ .

This number is bounded above by the cardinality Q of a maximal β -separated at time $t = -\alpha$, subset $\{y_1, \dots, y_Q\}$ of $S_{\eta, \alpha}^k \cap B_{g(-\alpha)}(x, \beta)$.

If $\beta \leq \frac{1}{2}$ we can apply Lemma 3.4 to estimate

$$\begin{aligned} Q \kappa_2 (\beta/2)^n &\leq \sum_{i=1}^Q \text{vol}_{g(-\alpha)}(B_{g(-\alpha)}(y_i, \beta/2)) \\ &\leq \text{vol}_{g(-\alpha)}(B_{g(-\alpha)}(x, 2r)) \leq \kappa_1 (2\beta)^n, \end{aligned}$$

hence $P \leq Q \leq c_0 := \frac{\kappa_1 4^n}{\kappa_2}$.

We proceed to the induction step. Given any $\mathbf{a} \in \{0, 1\}^{j+1}$ denote by $\tilde{\mathbf{a}} \in \{0, 1\}^j$ the vector with $\tilde{a}_l = a_l$ for every $1 \leq l \leq j$.

Now, recall that $\tau_j = \gamma^j \alpha, r_j = \gamma^{j/2} \beta$ and suppose that

$$S_{\eta, \tau_{j-1}}^k \cap E_{\tilde{\mathbf{a}}} \cap B_{g(-\alpha)}(x, \beta) \subset \bigcup_{i=1}^N B_{g(-\tau_{j-1})}(z_i, r_{j-1}),$$

where $z_i \in S_{\eta, \tau_{j-1}}^k \cap E_{\tilde{\mathbf{a}}} \cap B_{g(-\alpha)}(x, \beta)$.

First, observe that the curvature bound of the class $\mathcal{C}(n, B, \kappa_0, \kappa_1)$ implies that

$$|\text{Rm}(g(-\tau))|_{g(-\tau)} \leq \frac{B}{\gamma^j \alpha},$$

in M for $\tau \in [\tau_j, \tau_{j-1}]$. Then, standard distance distortion estimates imply that for every $y \in M$ and $r > 0$,

$$B_{g(-\tau_j)}(y, A^{-1}r) \subset B_{g(-\tau_{j-1})}(y, r) \subset B_{g(-\tau_j)}(y, Ar),$$

where $A = e^{c(n)B\gamma^{-1}}$.

Thus, each ball of the given cover satisfies

$$B_{g(-\tau_{j-1})}(z_i, r_{j-1}) \subset B_{g(-\tau_j)}(z_i, Ar_{j-1}).$$

It follows that the cardinality L of a maximal r_j -separated at time $t = -\tau_j$ set $\{w_1, \dots, w_L\}$ in

$$S_{\eta, \tau_j}^k \cap E_{\mathbf{a}} \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1}) \subset S_{\eta, \tau_j}^k \cap E_{\mathbf{a}} \cap B_{g(-\tau_j)}(z_{i_0}, Ar_{j-1})$$

can be estimated by

$$\begin{aligned} L\kappa_2(r_j/2)^n &\leq \sum_{i=1}^L \text{vol}_{g(-\tau_j)}(B_{g(-\tau_j)}(w_i, r_j/2)), \\ &\leq \text{vol}_{g(-\tau_j)}(B_{g(-\tau_j)}(z_{i_0}, Ar_{j-1} + r_{j-1})), \\ &\leq \kappa_1(A + 1)^n(r_{j-1})^n, \end{aligned}$$

where we used again Lemma 3.4, assuming that $\beta \leq (1 + A)^{-1}$. This provides us with an estimate $L \leq \frac{\kappa_1}{\kappa_2}(A + 1)^n 2^n \gamma^{-n} =: c_1$, $c_1 = c_1(n, \alpha, B, \kappa_0, \kappa_1, \gamma)$.

Thus the set

$$S_{\eta, \tau_j}^k \cap E_{\mathbf{a}} \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1})$$

can be covered by at most c_1 balls $B_{g(-\tau_j)}(w_i, r_j)$, with centers in $S_{\eta, \tau_j}^k \cap E_{\mathbf{a}} \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1})$.

At this point it is clear that for the arguments above to go through we need to choose $\beta(B, \gamma) = \min\{1/2, (1 + A)^{-1}\}$.

The rough estimate above is valid on all scales, and relies on the Type I assumption. On the other hand, if we are on a ‘good’ scale τ_{j-1} , namely a scale on which the flow looks selfsimilar, we can do much better.

To see this, suppose that $a_j = 0$ and let $B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1})$ be one of the balls in the cover of $S_{\eta, \tau_{j-1}}^k \cap E_{\bar{\mathbf{a}}} \cap B_{g(-\alpha)}(x, \beta)$.

We will show that there is a minimal cover of

$$S_{\eta, \tau_j}^k \cap E_{\mathbf{a}} \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1})$$

by at most $c_2(n)\gamma^{-k}$ balls $B_{g(-\tau_j)}(w_i, r_j)$ with centers $w_i \in S_{\eta, \tau_j}^k \cap E_{\mathbf{a}}$.

First, observe that $E_{\mathbf{a}} \subset E_{\bar{\mathbf{a}}} \subset L_{\tau_{j-1}, \delta}$, since $a_j = 0$, and recall that $z_{i_0} \in E_{\bar{\mathbf{a}}}$.

Chose $\delta = \delta_3(B, \gamma, \kappa_0, \beta/\alpha, \mu, \mu)$ as given by Lemma 3.3, where α, μ will be chosen later.

Lemma 3.3 then implies that

$$\begin{aligned} E_{\mathbf{a}} \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1}) &\subset L_{\tau_{j-1}, \delta} \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1}), \\ &\subset T_{(D+\mu)\sqrt{\tau}}^{g(-\tau)}(\exp_{g(-\tau_j), z_{i_0}}(V \cap B_0(2r_{j-1}))) \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1}), \end{aligned} \tag{3.10}$$

for every $\tau \in [\mu\tau_{j-1}, (2-\mu)\tau_{j-1}]$ and some l -dimensional subspace V^l of $T_{z_{i_0}}M$. Moreover, $\mathfrak{g}_{z_{i_0}}$ is $(\mu, \tau_{j-1}^{1/2}, l, B)$ -selfsimilar with respect to V .

Now, chose $\mu = \min\{\eta, \gamma, D\}$. On the one hand, this choice ensures that $l \leq k$, since $z_{i_0} \in S_{\eta, \tau_{j-1}}^k$. It also ensures that $\tau_j \in [\mu\tau_{j-1}, (2 - \mu)\tau_{j-1}]$, thus estimate (3.10) holds for $\tau = \tau_j$.

Finally, chose α small enough so that $2D\sqrt{\alpha} < \beta$, so that

$$(D + \mu)\sqrt{\tau_j} < r_j/10. \tag{3.11}$$

This implies that there exists $C_2(n)$ and a minimal cover of

$$S_{\eta, \tau_j}^k \cap E_{\mathbf{a}} \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1})$$

with at most $C_2\gamma^{-k}$ balls at time $t = -\tau_j$ of radius r_j centered at S_{η, τ_j}^k .

To construct such cover, first consider a maximal $r_j/4$ -separated set in $\exp_{g(-\tau_j), z_{i_0}}(V \cap B_0(r_{j-1}))$. Then, by (3.11), the $g(-\tau_j)$ -balls of radius $r_j/2$ with centers in that set cover $S_{\eta, \tau_j}^k \cap E_{\mathbf{a}} \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1})$, for μ small enough (but independent of the other parameters of the proof). Finally, we can substitute each ball in this cover, with a ball of radius r_j centered at $S_{\eta, \tau_j}^k \cap E_{\mathbf{a}} \cap B_{g(-\tau_{j-1})}(z_{i_0}, r_{j-1})$.

Since there are at most K ‘bad’ scales and for the remaining $j - K$ we have the above more refined covering estimate, we obtain the result setting $C_1 = c_0c_1^K C_2^{-K} \gamma^{-K}$. \square

3.5 Proof of Theorem 1.2

Given $B < +\infty$ and γ which will be appropriately chosen later, let α, β be given by Lemma 3.5.

It suffices to prove the theorem for $\tau = \tau_{j-1}$ for all $j \geq 1$, since for any $\tau_j < \tau < \tau_{j-1}$,

$$\begin{aligned} \text{vol}_{g(-\tau)} \left(S_{\eta, \tau}^k \cap B_{g(-\alpha)}(x, \beta) \right) &\leq \text{vol}_{g(-\tau)} \left(S_{\eta, \tau_{j-1}}^k \cap B_{g(-\alpha)}(x, \beta) \right), \\ &\leq C_\eta \tau_{j-1}^{\frac{n-k-\eta}{2}}, \\ &\leq C_\eta (\gamma^{-1})^{\frac{n-k-\eta}{2}} \tau^{\frac{n-k-\eta}{2}}. \end{aligned}$$

Now, recall that $M = \bigcup_{\mathbf{a} \in \{0,1\}^j} E_{\mathbf{a}}$ and that there are at most $2j^K$ non-empty sets $E_{\mathbf{a}}$. Moreover, from Lemma 3.5, $S_{\eta, \tau_{j-1}}^k \cap E_{\mathbf{a}} \cap B_{g(-\alpha)}(x, \beta)$ is covered by at most $C_1(C_2\gamma^{-k})^j$ balls at time $t = -\tau_{j-1}$ of radius r_{j-1} . Thus, using Lemma 3.4:

$$\begin{aligned} \text{vol}_{g(-\tau_{j-1})} \left(S_{\eta, \tau_{j-1}}^k \cap B_{g(-\alpha)}(x, \beta) \right) \\ \leq 2j^K C_1 (C_2\gamma^{-k})^j \kappa_1 (2r_{j-1})^n. \end{aligned}$$

Now, we chose $\gamma = \gamma(n, \eta)$ small enough so that $C_2 \leq \gamma^{-\eta/2}$ and we can also bound $j^K \leq C(K, \eta, \gamma)(\gamma^{j-1})^{-\eta/2}$. The estimate above then becomes

$$\text{vol}_{g(-\tau_{j-1})} \left(S_{\eta, \tau_{j-1}}^k \cap B_{g(-\alpha)}(x, \beta) \right) \leq C_\eta \tau_{j-1}^{\frac{n-k-\eta}{2}},$$

which is what we want to prove. \square

Remark 3.3 Note that due to the standard lower scalar curvature bound for the Ricci flow $R(g(-\tau)) \geq -\frac{n}{2(\tau+2)}$ and the evolution of the volume under Ricci flow, for every $0 < \bar{\tau} \leq$

$$\tau \leq \alpha$$

$$\begin{aligned} \text{vol}_{g(-\bar{\tau})} \left(S_{\eta, \tau}^k \cap B_{g(-\alpha)}(x, \beta) \right) &\leq c(n) \text{vol}_{g(-\tau)} \left(S_{\eta, \tau}^k \cap B_{g(-\alpha)}(x, \beta) \right) \\ &\leq C_{\eta} \tau^{\frac{n-k-\eta}{2}}. \end{aligned}$$

Moreover, if $\Omega = \{x \in M, \sup_{t \in [0, T)} |\text{Rm}(g)|_g(x, t) < +\infty\}$, then

$$\text{vol}_{g(0)}(S_{\eta, \tau}^k \cap B_{g(-\alpha)}(x, \beta) \cap \Omega) \leq C_{\eta} \tau^{\frac{n-k-\eta}{2}}. \tag{3.12}$$

4 Curvature estimates

Let $(M, g(t))_{t \in (-2, 0)}$ be a complete Ricci flow satisfying

$$\max_M |\text{Rm}(g(t))|_{g(t)} \leq \frac{B}{|t|}. \tag{4.1}$$

for all $t \in (-2, 0)$. If $(g(t))_{t \in (-2, 0)}$ is not singular at $x \in M$, namely there is a neighbourhood U of x such that

$$\sup_{U \times (-2, 0)} |\text{Rm}(g(t))|_{g(t)} < +\infty,$$

we can define the curvature radius at x as

$$r_{\text{Rm}}(x) = \sup \{r \leq 1, |\text{Rm}(g)| \leq r^{-2} \text{ in } B_{g(-r^2)}(x, r) \times [-r^2, 0]\}.$$

If $(g(t))_{t \in (-2, 0)}$ is singular at x , we define $r_{\text{Rm}}(x) = 0$.

4.1 ε -regularity

Below we prove a few ε -regularity results for Ricci flows satisfying (4.1), which imply that high curvature regions are inside one of the sets $S_{\varepsilon, \tau}^k$.

Lemma 4.1 (ε -regularity) *For every $B < +\infty$ and $\kappa > 0$, there exists $\varepsilon(B, \kappa) > 0$ such that if a complete Ricci flow $(M, g(t))_{t \in (-2, 0)}$ satisfies (4.1) and is κ non-collapsed below scale 1, then for every $\tau \in (0, 1]$*

$$\{r_{\text{Rm}} < \sqrt{\tau}\} \subset S_{\varepsilon, \tau}^{n-2}.$$

Moreover, if $\dim M = 4$ and $g(t)$ has positive isotropic curvature, then for every $\tau \in (0, 1]$

$$\{r_{\text{Rm}} < \sqrt{\tau}\} \subset S_{\varepsilon, \tau}^1.$$

Proof To prove the first statement, take a sequence of counterexamples $(M_i, g_i(t))_{t \in (-2, 0)}$ satisfying (4.1), and $x_i \in M_i, \tau_i \in (0, 1], \varepsilon_i \searrow 0$ such that $r_{\text{Rm}}(x_i) < \sqrt{\tau_i}$ and $x_i \notin S_{\varepsilon_i, \tau_i}^{n-2}$.

Thus, the pointed flows $\mathbf{g}_i = (M_i, g_i(t), x_i)_{t \in (-2, 0)}$ are $(\varepsilon_i, s_i, n - 1, B)$ -selfsimilar, for some $s_i \in [\tau_i^{1/2}, 1]$. By Lemma 2.4, and the κ non-collapsing assumption, a subsequence of $(\mathbf{g}_i)_{s_i}$ converges to a shrinking Ricci soliton that splits at least $n - 1$ Euclidean factors. The only such soliton is the Gaussian shrinking soliton. By Perelman’s pseudolocality theorem [25] we conclude that $r_{\text{Rm}}(x_i) \geq s_i \geq \tau_i^{1/2}$ for large i , which is a contradiction.

The proof of the second statement is similar, with the difference that the limiting soliton now splits at least two Euclidean factors and has positive isotropic curvature. However, four

dimensional gradient shrinking Ricci solitons with positive isotropic curvature split at most one Euclidean factor, by [22], which is a contradiction. \square

Under an additional bound on the Weyl curvature W , we can improve Lemma 4.1 as follows.

Lemma 4.2 (ε -regularity under Weyl curvature bound) *Given $B < +\infty$ and $\kappa > 0$, there exists $\varepsilon(B, \kappa) > 0$ such that if for some $x \in M$ and $0 < r \leq 1$ a complete Ricci flow $(M, g(t))_{t \in (-2, 0)}$ satisfies (4.1), it is κ non-collapsed below scale 1, and*

- (1) $(M, g(t), x)_{t \in (-2, 0)}$ is $(\varepsilon, r, 2, B)$ -selfsimilar;
- (2) $r^2 |W(g(-r^2))|_{g(-r^2)} < \varepsilon$ in $B_{g(-r^2)}(x, \varepsilon^{-1}r)$,

then $r_{\text{Rm}}(x) \geq r$.

Proof We argue by contradiction. Let $(M_i, g_i(t))_{t \in (-2, 0)}$ be a sequence satisfying (4.1), $x_i \in M_i$ and suppose that there are sequences $r_i \in (0, 1]$ and $\varepsilon_i \searrow 0$ such that

$$r_i^2 |W(g_i(-r_i^2))|_{g_i(-r_i^2)} < \varepsilon_i \tag{4.2}$$

in $B_{g_i(-r_i^2)}(x_i, \varepsilon_i^{-1}r_i)$ and $(M_i, g_i(t), x_i)_{t \in (-2, 0)}$ is $(\varepsilon_i, r_i, 2, B)$ -selfsimilar, but $r_{\text{Rm}}(x_i) < r_i$.

By Lemma 2.4, and the κ non-collapsing assumption, there is a subsequence of $(M_i, r_i^{-2}g_i(r_i^2t), x_i)_{t \in (-2, 0)}$ converging to a shrinking Ricci soliton $(N, h(t), q)_{t \in (-2, 0)}$, which splits at least 2 Euclidean factors.

Inequality (4.2) implies that $(N, h(t))$ has vanishing Weyl curvature. Since it splits more than one Euclidean factor, it has to be the Gaussian shrinking soliton, by [34]. Perelman’s pseudolocality theorem [25] then gives that $r_{\text{Rm}}(x_i) \geq r_i$, which is a contradiction. \square

4.2 Regularity estimates

We now couple the ε -regularity results of Lemmata 4.1 and 4.2 with the volume estimate of Theorem 1.2 to prove the following.

Theorem 4.1 *Given $(M, g(t))_{t \in (-2, 0)} \in \mathcal{C}(n, B, \kappa_0, \kappa_1)$ and $\eta \in (0, 1)$ there exist $\alpha(B), \beta(B) > 0$ and $C_\eta = C(n, B, \kappa_0, \kappa_1, \eta) < +\infty$ such that for every $x \in M$ and $0 < \tau \leq \alpha$*

$$\text{vol}_{g(0)}(\{0 < r_{\text{Rm}} < \sqrt{\tau}\} \cap B_{g(-\alpha)}(x, \beta)) \leq C_\eta \tau^{1-\eta}, \tag{4.3}$$

$$\text{and } \int_{B_{g(-\alpha)}(x, \beta) \cap \{r_{\text{Rm}} > 0\}} r_{\text{Rm}}^{-2(1-\eta)} d\mu_{g(0)} \leq C_\eta. \tag{4.4}$$

If in addition $\dim M = 4$ and $g(t)$ has positive isotropic curvature then

$$\text{vol}_{g(0)}(\{0 < r_{\text{Rm}} < \sqrt{\tau}\} \cap B_{g(-\alpha)}(x, \beta)) \leq C_\eta \tau^{\frac{3}{2}-\eta}, \tag{4.5}$$

$$\text{and } \int_{B_{g(-\alpha)}(x, \beta) \cap \{r_{\text{Rm}} > 0\}} r_{\text{Rm}}^{-3(1-\eta)} d\mu_{g(0)} \leq C_\eta. \tag{4.6}$$

Proof Let $\alpha(B)$ and $\beta(B)$ be given by Theorem 1.2. Then, estimates (4.3) and (4.5) easily follow from the volume estimate of Theorem 1.2, Remark 3.3 and Lemma 4.1.

To prove (4.4) and (4.6) we compute

$$\begin{aligned} & \int_{B_{g(-\alpha)}(x, \beta) \cap \{r_{\text{Rm}} > 0\}} r_{\text{Rm}}^{-p} d\mu_{g(0)} \\ &= \int_{B_{g(-\alpha)}(x, \beta) \cap \{r_{\text{Rm}} > 0\}} \left(\frac{1}{p} \int_{r_{\text{Rm}}}^1 s^{-(p+1)} ds + 1 \right) d\mu_{g(0)}, \\ &\leq \frac{1}{p} \int_0^1 \frac{1}{s^{p+1}} \text{vol}_{g(0)}(\{0 < r_{\text{Rm}} \leq s\} \cap B_{g(-\alpha)}(x, \beta)) ds + \text{vol}_{g(0)}(B_{g(-\alpha)}(x, \beta)), \\ &\leq C(\eta, p, n, B, \kappa_0, \kappa_1) \int_0^1 s^{-(p+1)+l-\eta} ds + \text{vol}_{g(0)}(B_{g(-\alpha)}(x, \beta)). \end{aligned}$$

For the last inequality we used either (4.3) or (4.5), substituting $l = 2$ or $l = 3$ respectively. Moreover, $\text{vol}_{g(0)}(B_{g(-\alpha)}(x, \beta))$ should be interpreted as $\text{vol}_{g(0)}(B_{g(-\alpha)}(x, \beta) \cap \{r_{\text{Rm}} > 0\})$.

Thus, for every $p = l - 2\eta$ we can bound, for some $C_p = C(p, n, B, \kappa_0, \kappa_1)$,

$$\begin{aligned} \int_{B_{g(-\alpha)}(x, \beta) \cap \{r_{\text{Rm}} > 0\}} r_{\text{Rm}}^{-p} d\mu_{g(0)} &\leq C_p + \text{vol}_{g(0)}(B_{g(-\alpha)}(x, \beta)), \\ &\leq C_p + C(n) \text{vol}_{g(-\alpha)}(B_{g(-\alpha)}(x, \beta)), \\ &\leq C_p + C(n, \kappa_1) \beta^n. \end{aligned}$$

Here, we used the volume control due to the standard scalar curvature bound $R \geq -\frac{n}{2(\tau+2)}$, as in Remark 3.3, and Lemma 3.4. This suffices to prove (4.4) and (4.6). \square

Theorem 4.2 *Given $(M, g(t))_{t \in (-2, 0)} \in \mathcal{C}(n, B, \kappa_0, \kappa_1)$ and $\eta \in (0, 1)$ there exist $\alpha(B), \beta(B) > 0, \varepsilon(B) > 0$ and $C_\eta = C(n, B, \kappa_0, \kappa_1, \eta) < +\infty$ such that if for every $t \in (-2, 0)$*

$$\sup_{B_{g(-\alpha)}(x, 2\varepsilon^{-1}\beta)} |W(g(t))|_{g(t)} < \varepsilon, \tag{4.7}$$

then for every $0 < \tau \leq \alpha$

$$\text{vol}_{g(0)}(\{0 < r_{\text{Rm}} < \sqrt{\tau}\} \cap B_{g(-\alpha)}(x, \beta)) \leq C_\eta \tau^{\frac{n-1}{2}-\eta}, \tag{4.8}$$

and
$$\int_{B_{g(-\alpha)}(x, \beta) \cap \{r_{\text{Rm}} > 0\}} r_{\text{Rm}}^{-(n-1)(1-\eta)} d\mu_{g(0)} \leq C_\eta. \tag{4.9}$$

Proof Let α, β given by Theorem 1.2 and ε by Lemma 4.2. Also, recall the following estimate from Lemma 2.6 of [24]: along any unit speed minimizing $g(t)$ -geodesic $\sigma(s), s \in [0, l]$,

$$\int_0^l \text{Ric}(\dot{\sigma}(s), \dot{\sigma}(s)) ds \leq \frac{C_1}{\sqrt{|l|}}, \tag{4.10}$$

for some constant $C_1 = C_1(n, B) < +\infty$. It follows that

$$\frac{d}{dt} d_{g(t)}(y, z) \geq -\frac{C_2(n, B)}{\sqrt{|t|}}. \tag{4.11}$$

Integrating (4.11) gives, for every $y \in B_{g(-\alpha)}(x, \beta)$ and $t \in [-\alpha, 0)$,

$$B_{g(t)}(y, \varepsilon^{-1}\beta) \subset B_{g(-\alpha)}(x, \beta(1 + \varepsilon^{-1}) + C_3\sqrt{\alpha}), \tag{4.12}$$

where $C_3 = C_3(n, B) < +\infty$.

Choosing $\varepsilon > 0$ small enough so that

$$B_{g(-\alpha)}(x, \beta(1 + \varepsilon^{-1}) + C_3\sqrt{\alpha}) \subset B_{g(-\alpha)}(x, 2\varepsilon^{-1}\beta),$$

and using Lemma 4.2, we obtain that for every $r \in (0, 2\beta)$

$$\{r_{\text{Rm}} < r\} \subset S_{\varepsilon, r^2}^1. \tag{4.13}$$

Note that $2\beta \leq 1$ by the proof of Theorem 1.2. The result then follows by arguing as in Theorem 4.1. \square

Proof of Theorem 1.3 Estimate (1.6) is an immediate consequence of estimates (4.4) and (4.6), since Shi’s local derivative estimates (see [19, Theorem D.1]) imply

$$\begin{aligned} & \int_{B_{g(-\alpha)}(x, \beta) \cap \{r_{\text{Rm}} > 0\}} |\nabla^j \text{Rm}(g(0))|_{g(0)}^p d\mu_{g(0)} \\ & \leq C(n, p, j) \int_{B_{g(-\alpha)}(x, \beta) \cap \{r_{\text{Rm}} > 0\}} r_{\text{Rm}}^{-(j+2)p} d\mu_{g(0)}. \end{aligned}$$

\square

Remark 4.1 Under the assumptions of Theorem 1.3, if in addition the Weyl curvature satisfies assumption (4.7) of Theorem 4.2, then the estimates of Theorem 1.3 hold for any $p \in (0, n - 1)$.

4.2.1 General type I Ricci flows

Given any complete Ricci flow $(M, g(t))_{t \in [0, T]}$, $T > 1$, we may define the curvature radius of $g(t)$ at a non-singular point $(x, t) \in M \times [1, T]$ as

$$r_{\text{Rm}}(x, t) = \sup \{r \leq 1, |\text{Rm}(g)| \leq r^{-2} \text{ in } B_{g(t-r^2)}(x, r) \times [t - r^2, t]\},$$

and $r_{\text{Rm}}(x, T) = 0$, if (x, T) is singular.

The following theorem holds:

Theorem 4.3 *Let $(M^n, g(t))_{t \in [0, T]}$, $\dim M = n$ and $T > 1$, be a compact Ricci flow satisfying (4.1) for some constant $B < +\infty$. Then for every $p \in (0, 2)$, there exists $C_p = C(g(0), p) < +\infty$ such that*

$$\int_{M \cap \{r_{\text{Rm}}(\cdot, t) > 0\}} r_{\text{Rm}}^{-p}(\cdot, t) d\mu_{g(t)} \leq C_p \tag{4.14}$$

for every $t \in [1, T]$.

Moreover, if $\dim M = 4$ and $g(t)$ has positive isotropic curvature, or if $\sup_{M \times [0, T]} |W(g(t))|_{g(t)} < +\infty$, the estimate above holds for $p \in (0, n - 1)$.

Proof First, observe that, due to the non-collapsing [25] and non-inflating [32] properties of the Ricci flow, there exist $\kappa_0, \kappa_1 > 0$ and $\rho > 0$, which depend on $g(0)$, T and B , such that the following holds: for every $\bar{t} \in [1, T]$ the flow $(M, \rho^{-2}g(\rho^2t + \bar{t}))_{t \in (-2, 0)}$ is in the class $\mathcal{C}(n, B, \kappa_0, \kappa_1)$.

Now, let α, β be provided by applying Theorem 1.2 to the class $\mathcal{C}(n, B, \kappa_0, \kappa_1)$. Moreover, let $N(t)$ be the minimal number of $g(t)$ -balls of radius $\rho\beta$ required to cover M .

For any $p \in (0, 2)$, applying Theorem 4.1 to $(M, \rho^{-2}g(\rho^2t + \bar{t}))_{t \in (-2,0)}$ gives

$$\begin{aligned} & \int_{M \cap \{r_{\text{Rm}}(\cdot, \bar{t}) > 0\}} r_{\text{Rm}}^{-p}(\cdot, \bar{t}) d\mu_{g(\bar{t})} \leq \\ & \leq \sum_{i=1}^{N(\bar{t} - \rho^2\alpha)} \int_{B_{g(\bar{t} - \rho^2\alpha)}(x_i, \rho\beta) \cap \{r_{\text{Rm}}(\cdot, \bar{t}) > 0\}} r_{\text{Rm}}^{-p}(\cdot, \bar{t}) d\mu_{g(\bar{t})}, \\ & \leq N(\bar{t} - \rho^2\alpha) C(n, p, B, \kappa_0, \kappa_1) \rho^{\frac{n}{2} - p}. \end{aligned}$$

To conclude the proof, note that we can estimate $N(\bar{t} - \rho^2\alpha) \leq C(g(0), B)$, since $|Rm(g(t))|_{g(t)} \leq \frac{B}{\rho^2\alpha}$ for $t \leq T - \rho^2\alpha$.

The remaining assertions of the theorem follow from a similar line of reasoning, applying Theorems 4.1 and 4.2 respectively. Note that, in order to apply Theorem 4.2 when there is a uniform bound on the Weyl curvature, we need to chose $\rho > 0$ small enough so that $\rho^2 \sup_{M \times [0, T]} |W(g(t))|_{g(t)} < \varepsilon, \varepsilon$ given by Theorem 4.2. □

Proof of Theorem 1.1 Estimate (1.3) follows from Theorem 4.3, as in the proof of Theorem 1.3. To obtain estimate (1.4) we first write $r_{\text{Rm}}^{-(j+2)p} = r_{\text{Rm}}^{-\frac{l(j+2)p}{l+2}} r_{\text{Rm}}^{-\frac{2(j+2)p}{l+2}}$, substituting $l = 2$ or 3, depending on whether we are in the general case or the case of positive isotropic curvature respectively.

Then we estimate

$$\begin{aligned} & \int_1^T \int_{M \cap \{r_{\text{Rm}}(\cdot, s) > 0\}} |\nabla^j Rm(g(s))|_{g(s)}^p d\mu_{g(s)} ds \\ & \leq C(n, p, j) \int_1^T \int_{M \cap \{r_{\text{Rm}}(\cdot, s) > 0\}} r_{\text{Rm}}^{-(j+2)p} d\mu_{g(s)} ds, \\ & = C(n, p, j) \int_1^T \int_{M \cap \{r_{\text{Rm}}(\cdot, s) > 0\}} r_{\text{Rm}}^{-\frac{l(j+2)p}{l+2}} r_{\text{Rm}}^{-\frac{2(j+2)p}{l+2}} d\mu_{g(s)} ds, \\ & \leq C(n, p, j) \int_1^T \int_{M \cap \{r_{\text{Rm}}(\cdot, s) > 0\}} r_{\text{Rm}}^{-\frac{l(j+2)p}{l+2}} (B/|s|)^{\frac{(j+2)p}{l+2}} d\mu_{g(s)} ds, \end{aligned}$$

which implies the required bound, as long as $p \in (0, \frac{l+2}{j+2})$, by Theorem 4.3. □

Remark 4.2 Under the assumptions of Theorem 4.3, if the Weyl curvature is uniformly bounded for all $t \in [0, T)$, then the estimates of Theorem 1.1 hold for any $p \in (0, n - 1)$.

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