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Prescribed Gauss curvature problem on singular surfaces

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Abstract We study the existence of at least one conformal metric of prescribed Gaussian curvature on a closed surface Σ admitting conical singularities of orders α_i 's at points p_i 's. In particular, we are concerned with the case where the prescribed Gaussian curvature is sign-changing. Such a geometrical problem reduces to solving a singular Liouville equation. By employing a min–max scheme jointly with a finite dimensional reduction method, we deduce new perturbative results providing existence when the quantity $\chi(\Sigma) + \sum_i \alpha_i$ approaches a positive even integer, where $\chi(\Sigma)$ is the Euler characteristic of the surface Σ .

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1 Introduction

Let (Σ, g) be a compact orientable surface without boundary endowed with metric g and Gauss curvature κ_g . Given a Lipschitz function K defined on Σ , a classical problem in differential geometry is the question on the existence of a metric \tilde{g} on Σ conformal to g:

$$\tilde{g} = e^u g$$

(with *u* a smooth function on Σ) of prescribed Gauss curvature *K*. In particular, in the case of constant *K* the above question is referred to as classical *Uniformization problem*, whereas for general functions this is known as the *Kazdan–Warner problem* (or the *Nirenberg problem* in the case of the standard sphere). The problem of finding a conformal metric of prescribed Gauss curvature *K* amounts to solving the equation

$$-\Delta_g u + 2\kappa_g = 2Ke^u. \tag{1.1}$$

Here Δ_g is the Laplace–Beltrami operator. The solvability of this problem so far has not been completely settled, aside from the case of surfaces with zero Euler characteristic [26]. In particular, both in the case of a topological sphere and in the case when Σ has negative Euler characteristic only partial results are known [1,6,7,10–14,19].

In this paper we will focus on a singular version of the problem (1.1). Following the pioneering work of Troyanov [31], we say that (Σ, \tilde{g}) defines a punctured Riemann surface $\Sigma \setminus \{p_1, \ldots, p_m\}$ that admits a conical singularity of order $\alpha_i > -1$ at the point p_i , for any $i = 1, \ldots, m$, if in a coordinate system z = z(p) around p_i with $z(p_i) = 0$ we have

$$\tilde{g}(z) = |z|^{2\alpha_i} e^w |dz|^2$$

with w a smooth function. In other words, Σ admits a tangent cone with vertex at p_i and total angle $\theta_i = 2\pi (1 + \alpha_i)$ for any *i*. The Gauss curvature at any vertex is a Dirac mass with magnitude $-2\pi\alpha_i$. Clearly we can assume $\alpha_i \neq 0$, indeed for the *round angle* $\theta_i = 2\pi$, corresponding to $\alpha_i = 0$, we would have no singular part either.

For a given smooth function *K* defined on Σ , we address the question of finding a metric \tilde{g} conformal to g in $\Sigma \setminus \{p_1, \ldots, p_m\}$, namely

$$\tilde{g} = e^u g$$
 in $\Sigma \setminus \{p_1, \ldots, p_m\}$

(with *u* a smooth function on the punctured surface), admitting conical singularities of orders α_i 's at the points p_i 's and having *K* as the associated Gaussian curvature in $\Sigma \setminus \{p_1, \ldots, p_m\}$. Similarly to the regular case (1.1), the question reduces to solving a singular Lioville-type equation on Σ :

$$-\Delta_g u + 2\kappa_g = 2Ke^u - 4\pi \sum_{i=1}^m \alpha_i \delta_{p_i} \quad \text{in } \Sigma.$$
(1.2)

A first information is given by the Gauss–Bonnet formula: indeed, integrating (1.2) one immediately obtains

$$2\int_{\Sigma} Ke^{u}dV_{g} = 2\int_{\Sigma} \kappa_{g}dV_{g} + 4\pi \sum_{i=1}^{m} \alpha_{i} = 4\pi \left(\chi(\Sigma) + \sum_{i=1}^{m} \alpha_{i}\right), \quad (1.3)$$

where dV_g denotes the area element in (Σ, g) and $\chi(\Sigma)$ is the Euler characteristic of the surface. Analogously to what happens for the regular case, the solvability of (1.2) depends crucially on the value of the generalized Euler characteristic for singular surfaces defined as follows

$$\chi(\Sigma,\underline{\alpha}) = \chi(\Sigma) + \sum_{i=1}^{m} \alpha_i.$$
(1.4)

When $\chi(\Sigma, \underline{\alpha}) \leq 0$ Troyanov [31] obtained existence results analogous to the ones for the regular case [6,26].

Whereas if $\chi(\Sigma, \underline{\alpha}) > 0$, then (1.3) implies that the function *K* has to be positive somewhere to allow the solvability of (1.2). In [31] it is proved that if $\chi(\Sigma, \underline{\alpha}) \in (0, 2(1 + \min\{0, \alpha_1, \dots, \alpha_m\}))$, this necessary condition is also sufficient to guarantee existence of a solution.

Let us transform equation (1.2) into another one which admits a variational structure. Let G(x, p) be the Green's function of $-\Delta_g$ over Σ with singularity at p, namely G satisfies

$$\begin{cases} -\Delta_g G(x, p) = \delta_p - \frac{1}{|\Sigma|} & \text{on } \Sigma \\ \int_{\Sigma} G(x, p) dV_g = 0 \end{cases}$$

where $|\Sigma|$ is the area of Σ , that is $|\Sigma| = \int_{\Sigma} dV_g$. Next, having $\frac{4\pi\chi(\Sigma)}{|\Sigma|} - 2\kappa_g(x)$ zero mean value, we define f_g to be the (unique) solution of

$$\begin{cases} -\Delta_g f_g(x) = \frac{4\pi \chi(\Sigma)}{|\Sigma|} - 2\kappa_g(x) & \text{on } \Sigma \\ \int_{\Sigma} f_g(x) dV_g = 0. \end{cases}$$
(1.5)

By the change of variable

$$v = u + 4\pi \sum_{i=1}^{m} \alpha_i G(x, p_i) - f_g,$$
(1.6)

problem (1.2) is then equivalent to solving the following (regular) problem

$$\begin{cases} -\Delta_g v = \rho_{geo} \left(\frac{\tilde{K}(x)e^v}{\int_{\Sigma} \tilde{K}(x)e^v \, dV_g} - \frac{1}{|\Sigma|} \right) & \text{on } \Sigma \\ \rho_{geo} = 4\pi \, \chi(\Sigma, \underline{\alpha}) \end{cases}$$
(*) ρ_{geo}

where $\tilde{K}(x)$ is the function

$$\tilde{K}(x) = K(x)e^{f_g(x) - 4\pi \sum_{i=1}^{m} \alpha_i G(x, p_i)}.$$
(1.7)

Notice that, since G(x, p) can be decomposed as

$$G(x, p) = \frac{1}{2\pi} \log \frac{1}{d_g(x, p)} + h(x, p) \quad h \in C^1(\Sigma^2),$$
(1.8)

where d_g is the distance induced on Σ by g, we have

$$\tilde{K}(x) \simeq K(x) d_g(x, p_i)^{2\alpha_i} e^{\gamma_i(x)}$$
 for x close to p_i (1.9)

for some functions $\gamma_i \in C^1(\Sigma)$.

It is worth to observe that more generally one could replace the function f_g appearing in (1.6) and (1.7) by any regular function a_g having zero mean value, obtaining (with minor changes) analogous results, but for the sake of simplicity we will not comment on this issue any further.

A possible strategy to solve problem $(*)_{\rho_{peo}}$ is to study the following Liouville problem

$$-\Delta_g v = \rho \left(\frac{\tilde{K}(x)e^v}{\int_{\Sigma} \tilde{K}(x)e^v \, dV_g} - \frac{1}{|\Sigma|} \right) \quad \text{on } \Sigma \tag{(*)}_{\rho}$$

for ρ positive independent of Σ and α_i , and to deduce a posteriori the answer to the geometric question taking $\rho = \rho_{geo}$.

Since problem $(*)_{\rho}$ has a variational structure, its solutions can be found as critical points of the associated energy functional

$$J_{\rho}(v) := \frac{1}{2} \int_{\Sigma} |\nabla_g v|^2 dV_g + \frac{\rho}{|\Sigma|} \int_{\Sigma} v \, dV_g - \rho \log\left(\int_{\Sigma} \tilde{K}(x) e^v dV_g\right),$$

defined in the domain

$$X = \left\{ v \in H^1(\Sigma) \, \middle| \, \int_{\Sigma} \tilde{K}(x) e^v dV_g > 0 \right\}.$$

Problem $(*)_{\rho_{geo}}$ has been widely investigated in literature in the case $\chi(\Sigma, \underline{\alpha}) > 0$ when K is a strictly positive function and even more results are available on $(*)_{\rho}$ for $\rho > 0$ when K is positive, which is a relevant question also from the physical point of view, see for example [29] and the references therein.

In [5] (see also [4]), under the hypothesis K > 0, it is shown that a sequence u_{ρ_n} of solutions to $(*)_{\rho_n}$ may blow up only if $\rho_n \to \rho$ with ρ belonging to the following discrete set of values

$$\Gamma(\underline{\alpha}_m) = \left\{ 8\pi n + 8\pi \sum_{i \in I} (1 + \alpha_i) \, \middle| \, n \in \mathbb{N} \cup \{0\}, \ I \subset \{1, \dots, m\} \right\}.$$
(1.10)

Using this compactness result, in [2] it is proved via a Morse theoretical approach that if $\alpha_i > 0$ and $\chi(\Sigma) \le 0$ then $(*)_{\rho}$ is solvable for all $\rho \notin \Gamma(\underline{\alpha}_m)$. In the case of surfaces with positive Euler characteristic (which is the most delicate), under some extra hypotheses on the α_i 's, in [27] the solvability of $(*)_{\rho}$ for $\rho \in (8\pi, 16\pi) \setminus \Gamma(\underline{\alpha}_m)$ is established. Still for *K* strictly positive, the case when the α'_i 's are negative has been considered in [8,9].

The special case of prescribing positive constant curvature on \mathbb{S}^2 with m = 2 is considered first in [30], where it is shown that $(*)_{\rho_{geo}}$ admits a solution only if $\alpha_1 = \alpha_2$ and this implies (taking $\alpha_2 = 0$) that no solution exists for m = 1. Furthermore, necessary and sufficient conditions on the α_i 's for the solvability are determined in [22] for m = 3 and in [28] for generic $m \ge 2$.

More recently, in [15] the Leray–Schauder degree of $(*)_{\rho}$ has been computed for $\rho \notin \Gamma(\underline{\alpha}_m)$, recovering some of the previous existence results and obtaining new ones in the case $\chi(\Sigma) > 0$. Anyway on the sphere there are still different situations in which the degree vanishes and the solvability is an open problem.

All the above results are concerned with the case K > 0. Up to our knowledge the singular problem $(*)_{\rho_{geo}}$ with K sign-changing has been considered only in [20] when the surface is the standard sphere (\mathbb{S}^2 , g_0) and in [21] for a general surface under mild assumptions on the nodal set of K (see Remarks 1.3 and 1.6).

In this paper we will mainly consider the problem $(*)_{\rho_{geo}}$ with K sign-changing, obtaining new existence results via a perturbative approach already applied in [17] to deal with $(*)_{\rho}$ in the case K positive, and in [16,18] for the corresponding Liouville-type equation in a Euclidean context.

We define the set

$$\Sigma^+ := \left\{ \xi \in \Sigma \mid K(\xi) > 0 \right\},\,$$

and in order to state our results we introduce the following hypotheses on K and on the p_i 's:

- (H1) K sign-changing, namely $K(\xi)K(\eta) < 0$ for some $\xi, \eta \in \Sigma$;
- (H2) $K \in C^2(\Sigma)$;
- (H3) $\nabla K(\xi) \neq 0$ for all $\xi \in \partial \Sigma^+$;
- (H4) $p_i \in \Sigma \setminus \partial \Sigma^+$ for all $i \in \{1, \ldots, m\}$.

In virtue of (H4) we may assume, up to reordering, that

$$p_i \in \Sigma^+ \text{ for } i \in \{1, \dots, \ell\} \text{ and } p_i \in \Sigma \setminus \Sigma^+ \text{ for } i \in \{\ell + 1, \dots, m\}$$
 (1.11)

for some $0 \le \ell \le m$. We are now ready to present our main perturbative results which provide existence when the quantity $\sum_{i=1}^{m} \alpha_i + \chi(\Sigma)$ approaches an even integer from the left hand side.

Theorem 1.1 Let $N^+ \in \mathbb{N}$. Assume that Σ^+ has N^+ connected components, $N \leq N^+$, hypotheses (H1),(H2) hold and

$$\Delta_g(\log K(x)) \le -\beta < 0 \quad \forall x \in \Sigma^+$$

for some $\beta > 0$. Then for any $\alpha_{\star} > -1$ there exists $\delta \in (0, \beta |\Sigma|)$ such that if $\alpha_1, \ldots, \alpha_m > \alpha_{\star}$ satisfy

$$\alpha_i > 0 \quad \forall i = 1, \dots, \ell,$$

$$\sum_{i=1}^m \alpha_i = 2N - \chi(\Sigma) - \frac{\varepsilon}{4\pi} \quad for \ some \ \varepsilon \in (0, \delta),$$

then $(*)_{\rho_{geo}}$ admits a solution v_{ε} with $\rho_{geo} = 8\pi N - \varepsilon$, i.e., K is the Gaussian curvature of at least one metric conformal to g and having a conical singularity at p_i with order α_i . Moreover there exist distinct points $\xi_1^*, \ldots, \xi_N^* \in \Sigma^+ \setminus \{p_1, \ldots, p_\ell\}$ such that

$$\rho \frac{\tilde{K}(x)e^{v_{\varepsilon}}}{\int_{\Sigma} \tilde{K}(x)e^{v_{\varepsilon}}dV_{g}} \to 8\pi \sum_{j=1}^{N} \delta_{\xi_{j}^{*}} \quad as \ \varepsilon \to 0^{+}$$
(1.12)

in the measure sense.

Theorem 1.2 Let $N \in \mathbb{N}$. Assume that Σ^+ has a non contractible connected component, hypotheses (H1), (H2), (H3), (H4) hold and

$$\Delta_g(\log K(x)) \le -\beta < 0 \quad \forall x \in \Sigma^+$$

for some $\beta > 0$. Then for any $\alpha_{\star} > -1$ there exists $\delta \in (0, \beta |\Sigma|)$ such that if $\alpha_1, \ldots, \alpha_m > \alpha_{\star}$ satisfy

$$\alpha_i \neq 0, 1, 2, \dots, N-1 \quad \forall i = 1, \dots, \ell,$$
$$\sum_{i=1}^m \alpha_i = 2N - \chi(\Sigma) - \frac{\varepsilon}{4\pi} \quad \text{for some } \varepsilon \in (0, \delta),$$

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 8\pi N - \varepsilon$. Moreover there exist distinct points $\xi_1^*, \ldots, \xi_N^* \in \Sigma^+ \setminus \{p_1, \ldots, p_\ell\}$ such that (1.12) holds.

Remark 1.3 The previous two results are a sort of perturbative counterpart of the global existence result established in [21, Theorem 2.2] for a general surface. Indeed, in [20, Theorem 1.2] and in [21, Theorem 2.2] it has been shown that if $\rho_{geo} \notin \Gamma(\underline{\alpha}_{\ell})$ [where ℓ is defined in (1.11)] and the positive nodal region of *K* has a non contractible connected component or a sufficiently large number of connected components (precisely, a number of connected components greater than $\frac{\rho_{geo}}{8\pi}$) then $(*)_{\rho_{geo}}$ admits a solution. Nevertheless, in [21] the behaviour of the solutions as $\rho \to 8\pi N^-$ is unknown, whereas the solutions constructed in Theorems 1.1 and 1.2 exhibit a blow-up phenomena, a property that has a definite interest in its own.

When all the connected components of Σ^+ are simply connected or their number is not sufficiently large, then the solvability issue is more delicate and it is treated in the following theorem.

Hereafter for any $\alpha > -1$, the square bracket [α] stands for its integer part and

$$[\alpha]^{-} := \lim_{\varepsilon \to 0^{+}} [\alpha - \varepsilon] = \max\{n \mid n \in \mathbb{Z}, n < \alpha\}$$

Theorem 1.4 Let $N \in \mathbb{N}$. Assume that hypotheses (H1), (H2), (H3), (H4) hold and

$$\Delta_g(\log K(x)) \le -\beta < 0 \quad \forall x \in \Sigma^+$$

for some $\beta > 0$. Then for any $\alpha_{\star} > -1$ there exists $\delta \in (0, \beta |\Sigma|)$ such that if $\alpha_1, \ldots, \alpha_m > \alpha_{\star}$ satisfy

$$\alpha_i \neq 0, 1, 2, \dots, N-1 \quad \forall i = 1, \dots, \ell,$$

$$N \leq \ell + \sum_{i=1}^{\ell} [\alpha_i]^-,$$
(1.13)

$$\sum_{i=1}^{m} \alpha_i = 2N - \chi(\Sigma) - \frac{\varepsilon}{4\pi} \quad \text{for some } \varepsilon \in (0, \delta), \tag{1.14}$$

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 8\pi N - \varepsilon$. Moreover there exist distinct points $\xi_1^*, \ldots, \xi_N^* \in \Sigma^+ \setminus \{p_1, \ldots, p_\ell\}$ such that (1.12) holds.

Remark 1.5 Let us observe that the inequality (1.13) is consistent with the condition (1.14) provided that

$$\sum_{i=1}^{m} \alpha_i < 2\ell - \chi(\Sigma) + 2\sum_{i=1}^{\ell} [\alpha_i]^-.$$

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Fig. 1 (S², g_0), Σ^+ contractible, $\rho_{geo} = 16\pi - \varepsilon$

Roughly speaking, this requires that the total multiplicity $\sum_{i=1}^{m} \alpha_i$ has to be controlled by the first ℓ orders α_i .

Remark 1.6 In [20,21] also the case when Σ^+ has only contractible connected components is addressed, deriving both existence results (under extra assumptions on ρ_{geo} , on the α_i 's and on the location of the p_i 's) and non existence results: in particular the condition $\rho_{geo} < 8\pi \max_{i=1,...,\ell} (1 + \alpha_i)$ is required to get existence. By Theorem 1.4 we get new existence results for any (Σ, g) : indeed if Σ^+ is contractible and the following conditions hold:

 $\alpha_1, \dots, \alpha_\ell \in (0, 1], \quad \rho_{geo} \in (8\pi, 16\pi), \quad \rho_{geo} \ge 8\pi (1 + \alpha_i) \quad \forall i = 1, \dots, \ell,$

then the variational approach of [21] breaks down not for technical reasons but being the low sublevels of the Euler Lagrange functional contractible. On the other hand Theorem 1.4 allows to produce a wide class of examples in which $(*)_{\rho_{geo}}$ admits a solution even in such situations (see for instance Example 1.7). In particular this provides existence in a perturbative regime allowing larger values of ρ_{geo} with respect to the ones in- [21].

Example 1.7 (Existence results for $\rho_{geo} \in (16\pi - \delta, 16\pi)$) If *K* verifies (H1), (H2), (H3) and Σ^+ is contractible (consider for example on (\mathbb{S}^2 , g_0) the function $K(\phi) = \cos(\phi)$, defined in spherical coordinates, where ϕ is the polar angle), then, via Theorem 1.4 (with N = 2), we can exhibit many configurations

 $p_1, \ldots, p_m \in \Sigma \setminus \partial \Sigma^+, \quad \alpha_1, \ldots, \alpha_m \text{ (even with } \alpha_1, \ldots, \alpha_\ell \in (0, 1)), \quad m \ge \ell \ge 2$

such that

$$\rho_{geo} \geq 8\pi (1+\alpha_i) \quad \forall i=1,\ldots,\ell, \quad \rho_{geo} \in (16\pi-\delta,16\pi)$$

for a sufficiently small $\delta > 0$ and $(*)_{\rho_{geo}}$ admits a solution (see Figure 1 below). For instance, the case when $m \ge \ell \ge 2$ and $\alpha_i = \alpha$ for all i = 1, ..., m with α in a small left neighborhood of $\frac{2}{m}$ satisfies the above conditions together with (1.13) and (1.14), so solvability is assured by Theorem 1.4.

It is worth to notice that none of the situations described above was covered by the results in [20].

Example 1.8 (Existence results for $\rho_{geo} > 16\pi$) Still by Theorem 1.4, it is also possible to derive a wide class of existence results for K and p_1, \ldots, p_m satisfying (H1), (H2), (H3),

$$\chi(\Sigma) = 0$$
 $\chi(\Sigma) = -2$ $\chi(\Sigma) = 2$





 $\ell = 1, \ m \ge 2$ $\alpha_1 = N - 1 + \frac{\varepsilon}{4\pi}, \quad \alpha_i = \frac{N + 1 - \chi(\Sigma) - \frac{\varepsilon}{2\pi}}{m - 1}, \ i = 2, \dots, m$



$$\ell = N, m = N + 1$$

$$\alpha_i = 1 - \frac{\varepsilon}{4N\pi}, i = 1, \dots, N, \quad \alpha_{N+1} = N - \chi(\Sigma)$$



$$\ell = m = 2N - \chi(\Sigma)$$

$$\alpha_i = 1 - \frac{\varepsilon}{4\ell\pi}, i = 1, \dots, \ell$$

Fig. 2 Σ^+ contractible, $\rho_{geo} = 8\pi N - \varepsilon$, $N \ge 3$

(H4) with Σ^+ contractible and $\rho_{geo} > 16\pi$ and this is completely new. We just present some concrete examples in Figure 2 above (where *K* is assumed to be a fixed function satisfying the assumptions in Theorem 1.4).

At last, as a direct byproduct of the perturbative approach already applied in [23] to deal with the Liouville equation $(*)_{\rho}$, we can provide class of functions *K* (positive or sign-changing) for which $(*)_{\rho_{geo}}$ is solvable, even in cases in which general existence results are not available. In particular we can also deal with situations when the degree of the equation (computed in [15]) is zero so that solvability is not known in general, or when there are examples of *K* for which $(*)_{\rho_{geo}}$ does not admit solutions.

We recall, for instance, that on (\mathbb{S}^2 , g_0), if m = 1 and $\alpha_1 > 0$:

- it is proved in [31] that (*)_{ρgeo} is not solvable with K ≡ 1, namely the *tear drop* conical singularity on S² does not admit constant curvature (see also [3] for a more general non existence result);
- in the sign-changing case, if ℓ = 0, in [20] it is shown that for a class of axially symmetric functions K, satisfying (H1), (H2), (H3) and (H4) and such that Σ⁺ is contractible, equation (*)_{ρeep} is not solvable.

Whereas on (S², g_0), if m = 3, $\alpha_1 = \alpha_2 \in (-\frac{1}{3}, 0)$, $\alpha_3 > 2$:

• according to the degree-formula in [15], if *K* is positive, the Leray–Schauder degree of the equation $(*)_{\rho}$ vanishes for $\rho \in (16\pi, 8\pi(3 + 2\alpha_1))$.

Here considering functions *K* having *sufficiently convex* local minima or *sufficiently concave* local maxima, as a counterpart of the above three non existence statements we can prove the following three existence results Theorems 1.9, 1.10 and 1.11, see Sect. 5 for further details and further examples.

Theorem 1.9 On the standard sphere (\mathbb{S}^2, g_0) with m = 1 the following holds:

(i) for any $N \in \mathbb{N}$ there exists a class of positive functions K such that if

$$(0 <) \alpha_1 = 2(N-1) + \frac{\varepsilon}{4\pi}$$
 for $\varepsilon > 0$ small enough,

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 8\pi N + \varepsilon$;

(ii) for any $N \in \mathbb{N}$, $N \ge 2$, there exists a class of positive functions K such that if

$$(0 <) \alpha_1 = 2(N-1) - \frac{\varepsilon}{4\pi}$$
 for $\varepsilon > 0$ small enough,

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 8\pi N - \varepsilon$;

Theorem 1.10 On the standard sphere (\mathbb{S}^2 , g_0) with m = 1 and $\ell = 0$ the following holds:

(i) for any $N \in \mathbb{N}$ there exists a class of functions K, satisfying (H1), (H2), (H3), (H4) and with $(\mathbb{S}^2)^+$ contractible, such that if

$$(0 <) \alpha_1 = 2(N-1) + \frac{\varepsilon}{4\pi}$$
 for $\varepsilon > 0$ small enough,

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 8\pi N + \varepsilon$;

(ii) for any $N \in \mathbb{N}$, $N \ge 2$, there exists a class of functions K, satisfying (H1), (H2), (H3), (H4) and with $(\mathbb{S}^2)^+$ contractible, such that if

$$(0 <) \alpha_1 = 2(N-1) - \frac{\varepsilon}{4\pi}$$
 for $\varepsilon > 0$ small enough,

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 8\pi N - \varepsilon$;

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Theorem 1.11 On the standard sphere (\mathbb{S}^2 , g_0) with m = 3 there exists a class of positive functions K such that if

$$\begin{cases} \alpha_1 = \alpha_2 \in (-\frac{1}{3}, 0) \\ \alpha_3 = 2 - 2\alpha_1 + \frac{\varepsilon}{4\pi} & \text{for some } \varepsilon > 0 \text{ small enough,} \end{cases}$$

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 16\pi + \varepsilon$.

The paper is organized as follows. In Sect. 2 we recall the finite-dimensional reduction developed in [23] for the equation $(*)_{\rho}$, which is the starting point of our analysis. In particular in the reduction procedure the crucial role of stable critical points of the reduced energy arises in the existence of solutions for $(*)_{\rho}$. Then we state three general existence results for such critical points, which are contained in Propositions 2.5, 2.6 and 2.7. In Sect. 3 we employ the reduction approach in order to derive solutions for the more general equation $(*)_{\rho}$, by which we deduce Theorems 1.1, 1.2 and 1.4 as corollaries. Sect. 4 is devoted to the proof of Propositions 2.6, 2.7 (the proof of Proposition 2.5 is instead immediate), which are at the core of this paper, by carrying out a min–max scheme. At last in Sect. 5 we focus on the problem $(*)_{\rho eep}$ and we provide several examples of solvability.

2 The finite dimension problem

The starting point for the proofs of Theorems 1.1, 1.2 and 1.4 is the *finite dimension variational reduction* which has been carried out for the equation $(*)_{\rho}$ in the paper [23], and reduces the problem of finding families of solutions for $(*)_{\rho}$ to the problem of finding critical points of a functional $\Psi(\xi)$ defined on a finite dimensional domain.

For $\boldsymbol{\xi} = (\xi_1, \dots, \xi_N)$ let us introduce the functional

$$\Psi(\boldsymbol{\xi}) := \sum_{j=1}^{N} h(\xi_j, \xi_j) + \frac{1}{4\pi} \sum_{j=1}^{N} \log \tilde{K}(\xi_j) + \sum_{\substack{j,k=1\\j \neq k}}^{N} G(\xi_j, \xi_k)$$
(2.1)

where \tilde{K} is defined in (1.7), G denotes the Green function of $-\Delta_g$ over Σ and h its regular part as in (1.8). Ψ is well defined in the set

$$\mathcal{M}^{+} := \left(\Sigma^{+} \setminus \{p_{1}, \dots, p_{\ell}\}\right)^{N} \setminus \Delta, \quad \Delta := \left\{ \boldsymbol{\xi} \in \Sigma^{N} \mid \xi_{j} = \xi_{k} \text{ for some } j \neq k \right\}.$$
(2.2)

The definition of Ψ depends on the particular $\underline{\alpha} = (\alpha_1, \ldots, \alpha_m)$ owing to (1.7). To emphasize this fact sometimes we will write $\Psi_{\alpha}(\boldsymbol{\xi})$ in the place of $\Psi(\boldsymbol{\xi})$.

In order to state the relation between the critical points of Ψ and the solutions of $(*)_{\rho}$ let us recall the notion of *stable* critical point, which was introduced in [24] in the analysis of concentration phenomena in nonlinear Schrödinger equations.

Definition 2.1 A critical point $\boldsymbol{\xi} \in \mathcal{M}^+$ of Ψ is *stable* if for any neighborhood U of $\boldsymbol{\xi}$ in \mathcal{M}^+ there exists $\delta > 0$ such that if $||F - \Psi||_{\mathcal{C}^1(\overline{U})} \leq \delta$, then F has at least one critical point in U. In particular, any (possibly degenerate) local minimum or maximum point is *stable*, as well as any non degenerate critical point and any isolated critical point with non-trivial local degree.

Next, for $\boldsymbol{\xi} = (\xi_1, \dots, \xi_N) \in \mathcal{M}^+$ we introduce the function

$$\begin{aligned} \mathcal{A}(\boldsymbol{\xi}) &:= 4\pi \sum_{j=1}^{N} \tilde{K}(\xi_j) e^{8\pi h(\xi_j, \xi_j) + 8\pi \sum_{k \neq j} G(\xi_j, \xi_k)} \bigg[\Delta_g \log \tilde{K}(\xi_j) + \frac{8\pi N}{|\Sigma|} - 2\kappa_g(\xi_j) \bigg] \\ &= 4\pi \sum_{j=1}^{N} \tilde{K}(\xi_j) e^{8\pi h(\xi_j, \xi_j) + 8\pi \sum_{k \neq j} G(\xi_j, \xi_k)} \bigg[\Delta_g \log K(\xi_j) + \frac{8\pi N - 4\pi \chi(\Sigma, \underline{\alpha})}{|\Sigma|} \bigg]. \end{aligned}$$

$$(2.3)$$

Then, the variational reduction method developed in [23] gives the following result, where the role of *stable* critical points of Ψ arises in the existence of solutions of $(*)_{\rho}$. Even though in [23] only the case of positive orders is considered, one can easily check that the proof continue to hold also for $\alpha_i > -1$.

Proposition 2.2 ([23]) Let $N, m \in \mathbb{N}$. Assume that $K : \Sigma \to \mathbb{R}$ is a C^2 function and $p_i \in \Sigma$ for i = 1, ..., m. Then for any $-1 < \alpha_{\star} < \alpha^{\star}$ there exists $\delta = \delta(\alpha^{\star}, \alpha_{\star}) > 0$ such that if:

(a) $\alpha_{\star} \leq \alpha_i \leq \alpha^{\star}$ for any $i = 1, \ldots, m$,

(b) $\boldsymbol{\xi^*} \in \mathcal{M}^+$ is such that $\mathcal{A}(\boldsymbol{\xi^*}) > 0$ (resp. < 0),

(c) $\boldsymbol{\xi}^*$ is a stable critical point of Ψ_{α} ,

then for all $\rho \in (8\pi N, 8\pi N + \delta)$ [resp. $\rho \in (8\pi N - \delta, 8\pi N)$] there is a solution v_{ρ} of $(*)_{\rho}$.

Moreover

$$\rho \frac{\tilde{K}(x)e^{\nu_{\rho}}}{\int_{\Sigma} \tilde{K}(x)e^{\nu_{\rho}}dV_g} \to 8\pi \sum_{j=1}^N \delta_{\xi_j^*} \quad as \ \rho \to 8\pi N$$
(2.4)

in the measure sense.

We point out that the above proposition is stated here in a slightly more general way than in [23, Theorem 1.1]; precisely in our formulation we stress that the number δ can be chosen uniformly for bounded values of α_i away from -1.

Remark 2.3 (Condition *b*)) If the function *K* and the orders $\alpha_1, \ldots, \alpha_m$ satisfy

$$\sup_{\xi \in \Sigma^+} \left(\Delta_g \log K(\xi) \right) < \frac{(4\pi \chi(\Sigma, \underline{\alpha}) - 8\pi N)}{|\Sigma|}, \tag{2.5}$$

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then we have $\mathcal{A}(\boldsymbol{\xi}) < 0$ for all $\boldsymbol{\xi} \in \mathcal{M}^+$, and, consequently, condition *b*) in Proposition 2.2 is satisfied. In particular (2.5) holds if there exists $\beta > 0$ such that

$$\sup_{\xi \in \Sigma^+} (\Delta_g \log K(\xi)) \le -\beta \quad \& \quad \chi(\Sigma, \underline{\alpha}) > 2N - \frac{\rho|\Sigma|}{4\pi}.$$
(2.6)

Observe that these two conditions are indeed assumed in Theorems 1.1, 1.2, and 1.4. In Sect. 5 we will also prove other existence results for $(*)_{\rho}$ without assuming (2.6) but exhibiting classes of functions *K*, sign-changing or also positive, (and values of α_i 's) for which $\mathcal{A} < \prime$ in suitable subsets of \mathcal{M}^+ where one can find a local maximum of Ψ_{α} (see Theorem 5.2).

Remark 2.4 We notice that, since K > 0 on Σ^+ and K = 0 on $\partial \Sigma^+$, one cannot have $\Delta_g K > 0$ on Σ^+ , so it is not possible to find a general reasonable explicit sufficient condition to guarantee $\mathcal{A}(\boldsymbol{\xi}) > 0$ for all $\boldsymbol{\xi} \in \mathcal{M}^+$ similar to (2.6) above. Nevertheless in Sect. 5 we will provide examples of functions K for which a stable critical point $\boldsymbol{\xi}^*$ exists for $\Psi_{\underline{\alpha}}$ and satisfies condition $\mathcal{A}(\boldsymbol{\xi}^*) > 0$, yielding solvability of problem $(*)_{\rho}$ thanks to Proposition 2.2 (see Theorem 5.1).

Proposition 2.5 Let $N^+ \in \mathbb{N}$ and $\alpha_1, \ldots, \alpha_m > -1$. Assume that Σ^+ consists of N^+ connected components, $N \leq N^+$, hypotheses (H1), (H2) hold and, in addition,

$$\alpha_i > 0 \quad \forall i = 1, \dots, \ell. \tag{2.7}$$

Then the functional Ψ admits a local maximum $\boldsymbol{\xi}^* = (\xi_1^*, \dots, \xi_N^*) \in \mathcal{M}^+$ with each point ξ_i^* belonging to a separate connected component of Σ^+ .

The proofs of the next two results are quite involved and will be postponed in Sect. 4.

Proposition 2.6 Let $N \in \mathbb{N}$ and $\alpha_1, \ldots, \alpha_m > -1$. Suppose that Σ^+ has a non contractible connected component, hypotheses (H1), (H2), (H3), (H4) hold and, in addition,

 $\alpha_i \neq 0, 1, \dots, N-1 \quad \forall i = 1, \dots, \ell.$ (2.8)

Then Ψ has a stable critical point $\boldsymbol{\xi}^* \in \mathcal{M}^+$.

Proposition 2.7 Let $N \in \mathbb{N}$ and $\alpha_1, \ldots, \alpha_m > -1$. Suppose that hypotheses (H1), (H2), (H3), (H4) hold and, in addition,

$$\alpha_i \neq 0, 1, \dots, N-1 \quad \forall i = 1, \dots, \ell,$$

$$(2.9)$$

$$N \le \ell + \sum_{i=1}^{\ell} [\alpha_i]^-.$$
(2.10)

Then Ψ has a stable critical point $\boldsymbol{\xi}^* \in \mathcal{M}^+$.

Propositions 2.5, 2.6, and 2.7 are at the core of this work, indeed by combining them with Proposition 2.2 we get all our existence results and in particular Theorems 1.1, 1.2 and 1.4, as we will see in the next section.

3 Existence results for the general Liouville problem (*)_p

In this section we provide the three main existence results for the Liouville equation $(*)_{\rho}$, from which we will deduce Theorems 1.1, 1.2 and 1.4 by choosing

$$\rho = \rho_{geo} = 4\pi \,\chi(\Sigma,\underline{\alpha}).$$

Let us begin with the first result which is a combination of Propositions 2.2 and 2.5.

Theorem 3.1 Let $N^+ \in \mathbb{N}$. Assume that Σ^+ consists of N^+ connected components, $N \leq N^+$ and hypotheses (H1), (H2) hold. Then for any $-1 < \alpha_{\star} < \alpha^{\star}$ there exists $\delta = \delta(\alpha^{\star}, \alpha_{\star}) > 0$ such that, if $\alpha_1, \ldots, \alpha_m$ verify (2.7) and

(i) $\alpha_{\star} \leq \alpha_i \leq \alpha^{\star}$ for any $i = 1, \ldots, m$,

(ii) A > 0 (resp. < 0) in the set of local maxima of Ψ ,

then for all $\rho \in (8\pi N, 8\pi N + \delta)$ [resp. $\rho \in (8\pi N - \delta, 8\pi N)$] there is a solution v_{ρ} of $(*)_{\rho}$. Moreover there exists $\xi^* \in \mathcal{M}^+$ such that (2.4) holds.

Taking into account of Remark 2.3, Theorem 3.1 can be reformulated as follows.

 N^+ , hypotheses (H1), (H2) hold and

$$\sup_{\xi \in \Sigma^+} (\Delta_g \log K(\xi)) \le -\beta$$

for some $\beta > 0$. Then for any $-1 < \alpha_{\star} < \alpha^{\star}$ there exists $\delta = \delta(\alpha^{\star}, \alpha_{\star}) > 0$ such that, if $\alpha_1, \ldots, \alpha_m$ verify (2.7) and:

- (i) $\alpha_{\star} \leq \alpha_i \leq \alpha^{\star}$ for any $i = 1, \dots, m$,
- (ii) $\chi(\Sigma, \underline{\alpha}) > 2N \frac{\beta|\Sigma|}{4\pi}$,

then for all $\rho \in (8\pi N - \delta, 8\pi N)$ there is a solution v_{ρ} of $(*)_{\rho}$. Moreover there exists $\boldsymbol{\xi}^* \in \mathcal{M}^+$ such that (2.4) holds.

Similarly, combining Propositions 2.2 and 2.6 we get the following.

Theorem 3.3 Let $N \in \mathbb{N}$. Suppose that Σ^+ has a non contractible connected component and hypotheses (H1), (H2), (H3), (H4) hold. Then for any $-1 < \alpha_* < \alpha^*$ there exists $\delta = \delta(\alpha^*, \alpha_*) > 0$ such that, if $\alpha_1, \ldots, \alpha_m$ verify (2.8) and

(i) α_{*} ≤ α_i ≤ α^{*} for any i = 1,..., m,
(ii) A > 0 (resp. < 0) in the set of critical points of Ψ,

then for all $\rho \in (8\pi N, 8\pi N + \delta)$ [resp. $\rho \in (8\pi N - \delta, 8\pi N)$] there is a solution v_{ρ} of $(*)_{\rho}$. Moreover there exists $\boldsymbol{\xi}^* \in \mathcal{M}^+$ such that (2.4) holds.

Proceeding similarly as above, using Remark 2.3 we also have:

Corollary 3.4 Let $N \in \mathbb{N}$. Suppose that Σ^+ has a non contractible connected component, hypotheses (H1), (H2), (H3), (H4) hold and

$$\sup_{\xi \in \Sigma^+} (\Delta_g \log K(\xi)) \le -\beta$$

for some $\beta > 0$. Then for any $-1 < \alpha_{\star} < \alpha^{\star}$ there exists $\delta = \delta(\alpha^{\star}, \alpha_{\star}) > 0$ such that, if $\alpha_1, \ldots, \alpha_m$ verify (2.8) and:

(i) $\alpha_{\star} \leq \alpha_i \leq \alpha^{\star}$ for any i = 1, ..., m, (ii) $\chi(\Sigma, \underline{\alpha}) > 2N - \frac{\beta|\Sigma|}{4\pi}$,

then for all $\rho \in (8\pi N - \delta, 8\pi N)$ there is a solution v_{ρ} of $(*)_{\rho}$. Moreover there exists $\boldsymbol{\xi}^* \in \mathcal{M}^+$ such that (2.4) holds.

Last, combining Propositions 2.2 and 2.7 we obtain:

Theorem 3.5 Let $N \in \mathbb{N}$. Suppose that hypotheses (H1), (H2), (H3), (H4) hold. Then for any $-1 < \alpha_{\star} < \alpha^{\star}$ there exists $\delta = \delta(\alpha^{\star}, \alpha_{\star}) > 0$ such that, if $\alpha_1, \ldots, \alpha_m$ verify (2.9), (2.10) and

(i) $\alpha_{\star} \leq \alpha_i \leq \alpha^{\star}$ for any $i = 1, \ldots, m$,

(ii) A > 0 (resp. < 0) in the set of critical points of Ψ ,

then for all $\rho \in (8\pi N, 8\pi N + \delta)$ [resp. $\rho \in (8\pi N - \delta, 8\pi N)$] there is a solution v_{ρ} of $(*)_{\rho}$. Moreover there exists $\xi^* \in \mathcal{M}^+$ such that (2.4) holds.

Once more, using Remark 2.3 we also have:

$$\sup_{\xi\in\Sigma^+} (\Delta_g \log K(\xi)) \le -\beta$$

for some $\beta > 0$. Then for any $-1 < \alpha_{\star} < \alpha^{\star}$ there exists $\delta = \delta(\alpha^{\star}, \alpha_{\star}) > 0$ such that, if $\alpha_1, \ldots, \alpha_m$ verify (2.9), (2.10) and

(i) $\alpha_{\star} \leq \alpha_i \leq \alpha^{\star}$ for any i = 1, ..., m, (ii) $\chi(\Sigma, \underline{\alpha}) > 2N - \frac{\beta|\Sigma|}{4\pi}$,

then for all $\rho \in (8\pi N - \delta, 8\pi N)$ there is a solution v_{ρ} of $(*)_{\rho}$. Moreover there exists $\boldsymbol{\xi}^* \in \mathcal{M}^+$ such that (2.4) holds.

Observe that Theorems 1.1, 1.2 and 1.4 follow immediately from Corollaries 3.2, 3.4 and 3.6, respectively, by taking $\alpha^* = 2N - \chi(\Sigma) + m$ and $\rho = \rho_{geo}$.

Thus in order to achieve the existence results for problem $(*)_{\rho_{geo}}$ such as the ones stated in Theorem 1.1, 1.2 and 1.4, it remains to prove Propositions 2.6–2.7 (the proof of Proposition 2.5 is immediate). This will be accomplished in the next section.

4 The min–max scheme

The discussion in the previous section implies that our problem reduces now to investigate the existence of stable critical points for the reduced energy Ψ in order to prove Propositions 2.6 and 2.7. In this section we will apply a max-min argument to characterize a topologically nontrivial critical value of the function Ψ in the set \mathcal{M}^+ . Since \tilde{K} is defined by (1.7), Ψ actually becomes

$$\Psi(\boldsymbol{\xi}) = \mathcal{H}(\boldsymbol{\xi}) + \frac{1}{4\pi} \sum_{j=1}^{N} \log K(\xi_j) - \sum_{i=1}^{\ell} \alpha_i \sum_{j=1}^{N} G(\xi_j, p_i) + \sum_{\substack{j,k=1\\j \neq k}}^{N} G(\xi_j, \xi_k).$$

where \mathcal{H} is a smooth term on $(\Sigma^+)^N$, precisely

$$\mathcal{H}(\boldsymbol{\xi}) := \sum_{j=1}^{N} h(\xi_j, \xi_j) - \sum_{i=\ell+1}^{m} \alpha_i \sum_{j=1}^{N} G(\xi_j, p_i) \in C^1((\Sigma^+)^N).$$

Let us briefly outline the variational argument we are going to set up, which consists of two parts.

First we will construct sets $\mathcal{B}, \mathcal{B}_0, \mathcal{D} \subset \mathcal{M}^+$ satisfying the following two properties:

(P1) \mathcal{D} is open, \mathcal{B} and \mathcal{B}_0 are compact, \mathcal{B} is connected and

$$\mathcal{B}_0 \subset \mathcal{B} \subset \mathcal{D} \subset \overline{\mathcal{D}} \subset \mathcal{M}^+;$$

(P2) let us set \mathcal{F} to be the class of all continuos maps $\gamma : \mathcal{B} \to \mathcal{D}$ with the property that there exists a continuos homotopy $\Gamma : [0, 1] \times \mathcal{B} \to \mathcal{D}$ such that:

$$\Gamma(0,\cdot) = id_{\mathcal{B}}, \quad \Gamma(1,\cdot) = \gamma, \quad \Gamma(t,\boldsymbol{\xi}) = \boldsymbol{\xi} \quad \forall t \in [0,1], \; \forall \boldsymbol{\xi} \in \mathcal{B}_0;$$

then

$$\Psi^* := \sup_{\gamma \in \mathcal{F}} \min_{\boldsymbol{\xi} \in \mathcal{B}} \Psi(\gamma(\boldsymbol{\xi})) < \min_{\boldsymbol{\xi} \in \mathcal{B}_0} \Psi(\boldsymbol{\xi});$$
(4.1)

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Secondly, we need to exclude the possibility that the critical point is placed on the boundary of our domain, and precisely we need that:

(P3) for every $\boldsymbol{\xi} \in \partial \mathcal{D}$ such that $\Psi(\boldsymbol{\xi}) = \Psi^*$, $\partial \mathcal{D}$ is smooth at $\boldsymbol{\xi}$ and there exists a vector $\tau_{\boldsymbol{\xi}}$ tangent to $\partial \mathcal{D}$ at $\boldsymbol{\xi}$ so that $\tau_{\boldsymbol{\xi}} \cdot \nabla \Psi(\boldsymbol{\xi}) \neq 0$.

Under these assumptions a critical point $\boldsymbol{\xi} \in \mathcal{D}$ of Ψ with $\Psi(\boldsymbol{\xi}) = \Psi^*$ exists, as a standard deformation argument involving the gradient flow of Ψ shows. Moreover, since properties (P2)–(P3) continue to hold also for a functional which is C^1 -close to Ψ , then such critical point will *survive* small C^1 -perturbations and, consequently, will be *stable* in the sense of Definition 2.1.

Hence, once properties (P1)–(P2)–(P3) are established, for suitable sets \mathcal{B} , \mathcal{B}_0 and \mathcal{D} , Propositions 2.6 and 2.7 would follow. We will prove (P1)–(P2)–(P3) in Sects. 4.1, 4.2 and 4.3 respectively.

4.1 Definition of \mathcal{B} **,** \mathcal{B} **0, and proof of (P1)**

To establish property (P1), we define

$$\mathcal{D} = \left\{ \boldsymbol{\xi} \in \mathcal{M}^+ \mid \Phi(\boldsymbol{\xi}) > -M \right\}$$
(4.2)

where M > 0 is a sufficiently large number yet to be chosen and

$$\Phi(\boldsymbol{\xi}) := \mathcal{H}(\boldsymbol{\xi}) + \frac{1}{4\pi} \sum_{j=1}^{N} \log K(\xi_j) - \sum_{i=1}^{\ell} \alpha_i \sum_{j=1}^{N} G(\xi_j, p_i) - \sum_{\substack{j,k=1\\j \neq k}}^{N} G(\xi_j, \xi_k).$$

By using the properties of the functions K, G it is easy to check that Φ satisfies

$$\Phi(\boldsymbol{\xi}) \to -\infty \text{ as } \boldsymbol{\xi} \to \partial \mathcal{M}^+, \tag{4.3}$$

and this implies that \mathcal{D} is compactly contained in \mathcal{M}^+ . In order to define \mathcal{B} , we fix

$$\sigma_1, \dots, \sigma_N \subset \Sigma^+ \setminus \{p_1, \dots, p_\ell\}$$
(4.4)

N (not necessarily distinct) simple, closed curves in Σ^+ which do not intersect any of the singular sources p_i . Next we fix

$$\boldsymbol{\xi}_0 = (\xi_1^0, \dots, \xi_N^0) \in \sigma_1 \times \dots \times \sigma_N, \quad \xi_j^0 \neq \xi_k^0 \quad \forall j \neq k$$

a *N*-tuple of *N* distinct points. The exact choice of curves σ_j and points ξ_j^0 will be specified later and will depend on the topology of Σ^+ . We introduce the set

$$\left\{ \boldsymbol{\xi} \in (\Sigma^+)^N \, \middle| \, \boldsymbol{\xi}_j \in \sigma_j \, \& \, d_g(\boldsymbol{\xi}_j, \boldsymbol{\xi}_k) > M^{-1} \, \forall j \neq k \right\}.$$

$$(4.5)$$

In principle, we do not know whether (4.5) is connected or not, so we will choose a convenient connected component W. Since $\xi_j^0 \neq \xi_k^0$ for $j \neq k$, then ξ_0 belongs to the set in (4.5) provided that M is sufficiently large. Now we are in conditions of defining B and B_0 :

$$W := \text{ the connected component of } (4.5) \text{ containing } \boldsymbol{\xi}_0,$$
$$\mathcal{B} := \overline{W}, \quad \mathcal{B}_0 = \Big\{ \boldsymbol{\xi} \in \mathcal{B} \, \Big| \, \min_{j \neq k} d_g(\xi_j, \xi_k) = M^{-1} \Big\}.$$

 \mathcal{B} is clearly connected and $\mathcal{B}_0 \subset \mathcal{B}$. Moreover, by construction, we get that the *N*-tuple of points in (4.5) are uniformly distant from the sources p_i and as well as from the boundary $\partial \Sigma^+$ thanks to (4.4), therefore

$$\sum_{j=1}^{N} \log K(\xi_j) = O(1), \quad \sum_{i=1}^{\ell} \alpha_i \sum_{j=1}^{N} G(\xi_j, p_i) = O(1) \text{ in } \mathcal{B}$$
(4.6)

with the above quantity O(1) uniformly bounded independently of M. On the other hand in the set \mathcal{B} we also have $G(\xi_j, \xi_k) \leq \log M + C$ for $j \neq k$ by (1.8). Consequently for large M we also have $\mathcal{B} \subset \mathcal{D}$. We have thus proved property (P1).

4.2 Proof of (P2)

Throughout this section we assume that assumptions (H1), (H2), (H3), (H4) hold.

We begin by providing the following crucial intersection property which is an easy consequence of a topological degree argument.

Lemma 4.1 For any j = 1, ..., N let \mathcal{P}_j be a retraction of $\Sigma^+ \setminus \{p_1, ..., p_\ell\}$ onto σ_j , i.e. $\mathcal{P}_j : \Sigma^+ \setminus \{p_1, ..., p_\ell\} \to \sigma_j$ is a continuous map so that $\mathcal{P}_j|_{\sigma_j} = id_{\sigma_j}$. Then for any $\gamma \in \mathcal{F}$ there exists $\boldsymbol{\xi}_{\gamma}^* \in \mathcal{B}$ such that

$$\mathcal{P}_j(\gamma_j(\boldsymbol{\xi}_{\gamma}^*)) = \xi_j^0 \quad \forall j = 1, \dots, N.$$

Proof Let $\gamma \in \mathcal{F}$, namely $\gamma : \mathcal{B} \to \mathcal{D}$ is a continuous map such that there exists a continuous homotopy $\Gamma : [0, 1] \times \mathcal{B} \to \mathcal{D}$ satisfying:

$$\Gamma(0,\cdot) = id_{\mathcal{B}}, \quad \Gamma(1,\cdot) = \gamma, \quad \Gamma(t,\boldsymbol{\xi}) = \boldsymbol{\xi} \quad \forall t \in [0,1], \; \forall \boldsymbol{\xi} \in \mathcal{B}_0.$$

Extend Γ continuously from \mathcal{B} to $\boldsymbol{\sigma} := \sigma_1 \times \cdots \times \sigma_N$ as $\tilde{\Gamma} : [0, 1] \times \boldsymbol{\sigma} \to \mathcal{D}$ defined simply as

$$\widetilde{\Gamma}(t,\boldsymbol{\xi}) = \Gamma(t,\boldsymbol{\xi}) \text{ if } \boldsymbol{\xi} \in \mathcal{B}, \quad \widetilde{\Gamma}(t,\boldsymbol{\xi}) = \boldsymbol{\xi} \text{ if } \boldsymbol{\xi} \in \boldsymbol{\sigma} \setminus \mathcal{B}.$$

Notice that \mathcal{B}_0 is the topological boundary of \mathcal{B} relative to $\boldsymbol{\sigma}$, then $\tilde{\Gamma}$ is a continuos map and

$$\tilde{\Gamma}(0,\cdot) = id_{\sigma}, \quad \tilde{\Gamma}(t,\cdot)\big|_{\mathcal{B}_0} = id_{\mathcal{B}_0}, \quad \tilde{\Gamma}(t,\cdot)\big|_{\sigma \setminus \mathcal{B}} = id_{\sigma \setminus \mathcal{B}} \quad \forall t \in [0,1].$$

Set $\gamma = (\gamma_1, \dots, \gamma_N)$ and $\tilde{\Gamma} = (\tilde{\Gamma}_1, \dots, \tilde{\Gamma}_N)$ with $\gamma_j : \mathcal{B} \to \Sigma^+$ and $\tilde{\Gamma}_j : [0, 1] \times \sigma \to \Sigma^+$. Then the map $\mathcal{S} : [0, 1] \times \sigma \to \sigma$ with components

$$S_j(t,\boldsymbol{\xi}) = (\mathcal{P}_j \circ \Gamma_j)(t,\boldsymbol{\xi}), \quad j = 1, \dots, N,$$

is continuous and satisfies

$$\mathcal{S}(0,\cdot) = id_{\sigma}, \quad \mathcal{S}(t,\cdot)\Big|_{\sigma \setminus \mathcal{B}} = id_{\sigma \setminus \mathcal{B}} \quad \forall t \in [0,1].$$
(4.7)

In order to apply a degree argument, we can identify each σ_j , j = 1, ..., N, with \mathbb{S}^1 through a suitable homeomorphism, and then regard S as a map $[0, 1] \times (\mathbb{S}^1)^N \to (\mathbb{S}^1)^N$ with $S(0, \cdot) = id_{(\mathbb{S}^1)^N}$. We consider the annulus in \mathbb{R}^2

$$U := \left\{ u \in \mathbb{R}^2 \, \Big| \, \frac{1}{2} < |u| < 2 \right\}.$$

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Then we extend \mathcal{S} from $(\mathbb{S}^1)^N$ to \overline{U}^N as $\tilde{\mathcal{S}}$ having components

$$\tilde{\mathcal{S}}_j(t,\boldsymbol{u}) = |u_j|\mathcal{S}_j\left(t,\frac{u_1}{|u_1|},\ldots,\frac{u_N}{|u_N|}\right), \quad \forall \boldsymbol{u} = (u_1,\ldots,u_N) \in \overline{U}^N.$$

Notice that $\frac{u_j}{|u_j|} \in \mathbb{S}^1$ for $u_j \in \overline{U}$, so \tilde{S}_j is well defined. Clearly \tilde{S} is a continuous map by construction and

$$\tilde{\mathcal{S}}(0,\,\cdot)=id_{\overline{U}^N}.$$

Moreover the definition of \tilde{S} yields

$$|\tilde{\mathcal{S}}_{j}(t,\boldsymbol{u})| = |\boldsymbol{u}_{j}| \quad \forall t \in [0,1], \forall \boldsymbol{u} \in \overline{U}^{N}$$

$$(4.8)$$

and, consequently,

$$\tilde{\mathcal{S}}(t, U^N) \subset U^N \quad \forall t \in [0, 1]$$

and

$$\tilde{\mathcal{S}}(t, \partial(U^N)) \subset \partial(U^N) \quad \forall t \in [0, 1].$$

Once we have proved the crucial property that \tilde{S} maps the boundary $\partial(U^N)$ into itself, now we are in the position to apply a topological degree argument: indeed, the homotopy invariance gives that if $\boldsymbol{u} \in U^N$ then $\deg(\tilde{S}(1, \cdot), U^N, \boldsymbol{u}) = \deg(\tilde{S}(0, \cdot), U^N, \boldsymbol{u}) = \deg(id, U^N, \boldsymbol{u}) = 1$. In particular

$$\deg(\tilde{\mathcal{S}}(1,\cdot), U^N, \boldsymbol{\xi}^0) = 1$$

where $\boldsymbol{\xi}^0 \in (\mathbb{S}^1)^N$ corresponds to the original $\boldsymbol{\xi}_0 \in \boldsymbol{\sigma}$ through the identifications of each σ_j with \mathbb{S}^1 . Then, there exists $\boldsymbol{u}^* = (u_1^*, \dots, u_N^*) \in U^N$ so that

$$\tilde{\mathcal{S}}(1,\boldsymbol{u}^*) = \boldsymbol{\xi}^0$$

Thanks to (4.8) we get $u^* \in (\mathbb{S}^1)^N$, which, in turn, implies

$$\mathcal{S}(1,\boldsymbol{u}^*) = \tilde{\mathcal{S}}(1,\boldsymbol{u}^*) = \boldsymbol{\xi}^0.$$

Getting back to σ again by the isomorphism $\sigma \approx (\mathbb{S}^1)^N$, we deduce the existence of $\boldsymbol{\xi}^* = (\xi_1^*, \dots, \xi_N^*) \in \sigma$ such that

$$\mathcal{S}(1,\boldsymbol{\xi}^*) = \boldsymbol{\xi}_0.$$

We claim that $\boldsymbol{\xi}^* \in \mathcal{B}$: otherwise, if $\boldsymbol{\xi}^* \in \boldsymbol{\sigma} \setminus \mathcal{B}$, then $\mathcal{S}(1, \boldsymbol{\xi}^*) = \boldsymbol{\xi}^*$ by (4.7), which would lead to $\boldsymbol{\xi}^* = \boldsymbol{\xi}_0$, and this provides a contradiction to $\boldsymbol{\xi}_0 \in \mathcal{B}$. So, $\boldsymbol{\xi}^* \in \mathcal{B}$ and

$$\mathcal{P}_j(\gamma_j(\boldsymbol{\xi}^*)) = \mathcal{P}_j(\Gamma_j(1,\boldsymbol{\xi}^*)) = \mathcal{S}_j(1,\boldsymbol{\xi}^*) = \boldsymbol{\xi}_j^0 \quad \forall j = 1, \dots, N.$$

Now we are going to prove (P2). The definition of the max-min value Ψ^* in (4.1) depends on the particular M > 0 chosen in (4.2). To emphasize this fact we denote this max-min value by Ψ_M^* . In the remaining part of this section we will prove that (P2) holds for Msufficiently large. To this aim we need the estimate for Ψ_M^* provided by the following two propositions which prove the uniform boundedness (with respect to M) under the assumptions of Propositions 2.6 and 2.7, respectively.

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For the sake of simplicity, in the proofs we will use the additional assumption that

$$\Sigma^+$$
 is connected.

This assumption is made without loss of generality in this framework: indeed, if Σ^+ is not connected, then it is sufficient to replace Σ^+ by one of its connected components in the definition of the set \mathcal{M}^+ in (2.2), and then confining the search of a critical point for Ψ to such a component.

Remark 4.2 Anyway let us stress that if Σ^+ is not connected, then the results of Propositions 2.6 and 2.7 may possibly be improved (allowing larger values of *N* in Proposition 2.7, for instance) by suitably gluing the construction in each connected components. Anyway the optimal results for non-connected surface would require some more technicality and we will not comment on this issue any further.

Proposition 4.3 Assume that Σ^+ is connected and non contractible. Then the quantity Ψ_M^* is bounded independently of the number M used to define D, namely there exist two constants c, C independent of M such that

$$c \le \Psi_M^* \le C. \tag{4.9}$$

Proof To prove the lower boundedness it is sufficient to take $\gamma = i d_{\mathcal{B}}$ in the definition (4.1):

$$\Psi_{M}^{*} \geq \min_{\xi \in \mathcal{B}} \Psi(\xi) \geq \min_{\xi \in \mathcal{B}} \left(\frac{1}{4\pi} \sum_{j=1}^{N} \log K(\xi_{j}) - \sum_{i=1}^{\ell} \alpha_{i} \sum_{j=1}^{N} G(\xi_{j}, p_{i}) - C \right).$$
(4.10)

As we have already observed in (4.6), the function in the bracket is uniformly bounded in the set \mathcal{B} independently of M.

To get an upper estimate for the max-min value we need that a crucial intersection property is accomplished, and this will follow from Lemma 4.1 for a suitable choice of curves σ_j and points ξ_j^0 . Since such a choice depends on the topological properties of Σ , in order to perform the geometrical construction it is convenient to distinguish the two cases

$$\mathcal{G}(\Sigma) = 0$$
 and $\mathcal{G}(\Sigma) > 0$,

where $\mathcal{G}(\Sigma)$ denotes the genus of Σ .

Before going on we observe that the conclusion of the proposition is invariant under diffeomorphism: more precisely, assume that $\omega : \overline{\Sigma^+} \to \omega(\overline{\Sigma^+})$ is a diffeomorphism and suppose that we have proved the thesis for the functional $\Psi \circ \omega^{-1}(\xi')$ defined for $\xi' \in \omega(\overline{\Sigma^+})$ with the corresponding sets $\omega(\mathcal{D}), \omega(\mathcal{B}), \omega(\mathcal{B}_0)$; then, denoting by g' the metric on $\omega(\overline{\Sigma^+})$ and setting $\xi' := \omega(\xi)$, we have

$$cd_{g'}(\xi'_i,\xi'_k) \le d_g(\xi_j,\xi_k) \le Cd_{g'}(\xi'_i,\xi'_k).$$
 (4.11)

Since the unbounded terms in the definition of Ψ just involve the logarithm of the distance function or the logarithm of *K*, then thanks to (4.11) the thesis continues to hold for our original functional Ψ .

So, in the remaining part of the proof without loss of generality we may replace Σ^+ with a topologically equivalent surface.

Case I: $\mathcal{G}(\Sigma) = 0$.

The case of genus zero corresponds to a surface Σ which is a topological sphere. Then Σ^+ turns out to be diffeomorphic to a planar domain which is non contractible. So let us assume that Σ^+ coincides with a planar domain with a spherical hole of radius 1: more precisely

$$\Sigma^+ \equiv \Omega \subset \mathbb{R}^2,$$

and

$$B_1 := \{x^2 + y^2 < 1\}$$
 is a connected component of $\mathbb{R}^2 \setminus \overline{\Omega}$.

In this case the construction we are going to set up is based on a similar argument carried out in [18] in a Euclidean context.

Let us fix a radius $\rho > 1$ sufficiently close to 1 in such a way that the circle centered at 0 with radius ρ is contained in Ω :

$$\sigma := \{x^2 + y^2 = \rho^2\} \subset \Omega,$$

and σ does not intersect any of the singular points p_i :

$$p_i \notin \sigma \quad \forall i = 1, \ldots, \ell.$$

We construct a retraction of $\Sigma^+ \equiv \Omega$ onto σ by simply projecting along rays starting from 0:

$$\mathcal{P}(\xi) = \rho \frac{\xi}{|\xi|} \quad \forall \xi \in \Omega.$$

Then we apply Lemma 4.1 by taking

$$\sigma_i = \sigma, \quad \mathcal{P}_i = \mathcal{P} \quad \forall j = 1, \dots, N,$$

and we find that for any $\gamma \in \mathcal{F}$ there exists $\boldsymbol{\xi}_{\gamma}^* \in \mathcal{B}$ such that

$$\gamma_j(\boldsymbol{\xi}^*_{\gamma}) \in \mathcal{P}^{-1}(\boldsymbol{\xi}^0_j) \quad \forall j = 1, \dots, N.$$

By construction the fibers of \mathcal{P} are half-lines emanating from zero and are well-separated thanks to the presence of the hole B_1 , then, since $\xi_j^0 \neq \xi_k^0$ for $j \neq k$, there exists $\mu > 0$ such that

$$\operatorname{dist}_{\operatorname{eucl}}(\mathcal{P}^{-1}(\xi_j^0), \mathcal{P}^{-1}(\xi_k^0)) \ge \mu \quad \forall j \neq k$$

$$(4.12)$$

which implies

$$G(\gamma_j(\boldsymbol{\xi}^*_{\gamma}), \gamma_k(\boldsymbol{\xi}^*_{\gamma})) = O(1) \quad \forall j \neq k$$

with the above quantity O(1) uniformly bounded independently of γ . So an upper bound on Ψ_M^* is obtained by evaluating on $\gamma(\boldsymbol{\xi}_{\gamma}^*)$ as follows:

$$\min_{\boldsymbol{\xi}\in\mathcal{B}}\Psi(\gamma(\boldsymbol{\xi})) \leq \Psi(\gamma(\boldsymbol{\xi}_{\gamma}^{*})) \leq \sum_{\substack{j,k=1\\j\neq k}}^{N} G(\gamma_{j}(\boldsymbol{\xi}_{\gamma}^{*}),\gamma_{k}(\boldsymbol{\xi}_{\gamma}^{*})) + C \leq C.$$

Hence, by taking the supremum for all the maps $\gamma \in \mathcal{F}$, we conclude that the max-min value Ψ_M^* is bounded above independently of M, as desired.

Case II: $\mathcal{G}(\Sigma) > 0$.

According to the classification of compact connected orientable surfaces (see [25, Theorem 3.7, page 217]) we have that $\overline{\Sigma^+}$ is diffeomorphic to the surface obtained from an orientable closed surface by removing the interiors of k disjoints disks. So let us assume that

 $\Sigma \setminus \overline{\Sigma^+}$ is the disjoint union of *k* open disks.

Moreover, since the genus of Σ is positive, up to a new diffeomorphism we can also assume that Σ is embedded in \mathbb{R}^3 and satisfies

$$\sigma := \{x^2 + y^2 = 1, \ z = 0\} \subset \Sigma, \ \Sigma \cap \{x^2 + y^2 < 1\} = \emptyset,$$
(4.13)

$$\sigma \subset \Sigma^+, \ \sigma \cap \{p_1, \dots, p_\ell\} = \emptyset.$$
(4.14)

This is quite obvious when $\mathcal{G}(\Sigma) = 1$: indeed, in this case Σ is diffeomorphic to the torus

$$\left\{ \left(x, y, z \right) \in \mathbb{R}^3 \mid \left(\sqrt{x^2 + y^2} - 2 \right)^2 + z^2 = 1 \right\}$$
(4.15)

which satisfies (4.13); moreover, possibly slightly perturbing the diffeomorphism, we can always assume that the singular sources p_i $(i = 1, ..., \ell)$ in Σ^+ do not belong to σ and that σ does not intersect the *k* disks of $\Sigma \setminus \overline{\Sigma^+}$, so that (4.14) holds. When $\mathcal{G}(\Sigma) = m \ge 2$, Σ is diffeomorphic to the connected sum of *m* tori, obtained by gluing in a smooth way the torus (4.15) with other m - 1 torii outside the cylinder $\{x^2 + y^2 \le 2\}$. Also in this case, Σ satisfies properties (4.13)–(4.14).

In what follows we adapt some argument used in [17] for K positive. Notice that the above assumptions (4.13)–(4.14) are crucial to define a retraction of Σ^+ onto σ as

$$\mathcal{P}(x, y, z) = \left(\frac{x}{x^2 + y^2}, \frac{y}{x^2 + y^2}, 0\right).$$
(4.16)

Indeed, by (4.13)–(4.14) the map $\mathcal{P}: \Sigma^+ \to \sigma$ is well-defined and continuous with $\mathcal{P}|_{\sigma} = id_{\sigma}$. Then we apply Lemma 4.1 by taking

 $\sigma_j = \sigma, \quad \mathcal{P}_j = \mathcal{P} \quad \forall j = 1, \dots, N,$

and we find that for any $\gamma \in \mathcal{F}$ there exists $\boldsymbol{\xi}_{\gamma}^* \in \mathcal{B}$ such that

$$\gamma_j(\boldsymbol{\xi}_{\gamma}^*) \in \mathcal{P}^{-1}(\boldsymbol{\xi}_j^0) \quad \forall j = 1, \dots, N.$$

Let us investigate the structure of the fibers of \mathcal{P} in this case: the fibers of \mathcal{P} lie on vertical half-planes starting from the *z*-axis and their (euclidean) distance from the *z*-axis is greater than 1 in view of (4.13). Then they are well-separated, so (4.12) is satisfied and we conclude as in the previous case.

Proposition 4.4 Assume that Σ^+ is connected and contractible and that the inequality (2.10) is satisfied. Then the same thesis of Proposition 4.3 holds.

Proof Σ^+ turns out to be diffeomorphic to a two dimensional domain. So, since the thesis of the proposition is invariant under diffeomorphism as we have observed at the beginning of the proof of Proposition 4.3, from now on let us assume

$$\Sigma^+ \equiv \Omega \subset \mathbb{R}^2.$$

We are in position to adapt the arguments in [16] for the following geometrical construction.

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A lower bound on Ψ_M^* follows by taking $\gamma = id_B$ and reasoning exactly as in (4.10).

Let us focus on finding an upper estimate for Ψ_M^* . Hereafter we will often use the complex numbers to identify the points in \mathbb{R}^2 and we will denote by **i** the imaginary unit. First of all let us fix angles θ_i $(i = 1, ..., \ell)$ and a number $\delta \in (0, \frac{\pi}{2})$ sufficiently small such that the cones

$$\left\{p_i + \rho e^{\mathbf{i}(\theta_i + \theta)} \mid \rho \ge 0, \ \theta \in [-\delta, \delta]\right\}, \quad i = 1, \dots, \ell$$
(4.17)

are disjoint from one another. We point out that such choice of angles always exists since the set of singular sources p_1, \ldots, p_ℓ is finite. Possibly decreasing δ , we may also assume

$$S_{\delta}(p_i) \subset \Omega, \quad |p_i - p_r| > 2\delta \quad \forall i, r = 1, \dots, \ell, \ i \neq r.$$
 (4.18)

where $S_{\delta}(p_i)$ denotes the circle in \mathbb{R}^2 with center p_i and radius δ . According to assumption (2.10) we may split N as $N_1 + N_2 + \cdots + N_\ell$ with $N_i \in \mathbb{N}$ satisfying

$$0 \le N_i \le 1 + [\alpha_i]^- \quad \forall i. \tag{4.19}$$

Next we split $\{1, \ldots, N\}$ as $I_1 \cup \ldots \cup I_\ell$ where

$$I_{1} = \{1, 2, \dots, N_{1}\},$$

$$I_{2} = \{N_{1} + 1, N_{1} + 2, \dots, N_{1} + N_{2}\},$$

$$\dots$$

$$I_{i} = \{N_{1} + \dots + N_{i-1} + 1, \dots, N_{1} + \dots + N_{i}\},$$

$$\dots$$

$$I_{\ell} = \{N_{1} + \dots + N_{\ell-1} + 1, \dots, N\}.$$

Then we set

$$\sigma_j := S_{\delta}(p_i), \quad \mathcal{P}_j(\xi) = p_i + \delta \frac{\xi - p_i}{|\xi - p_i|} \quad \forall j \in I_i, \ i = 1, \dots, \ell.$$

Now we fix N-tuple

$$\boldsymbol{\xi}_0 = (\xi_1^0, \dots, \xi_N^0)$$

by

$$\xi_j^0 = p_i + \delta e^{\mathbf{i}\left(\theta_i + j\frac{\delta}{N}\right)} \in \sigma_j \quad \forall j \in I_i, \ i = 1, \dots, \ell.$$
(4.20)

Clearly $\mathcal{P}_j : \Omega \setminus \{p_i\} \to \sigma_j$ defines a retraction onto σ_j . Then Lemma 4.1 applies with this choice of $\xi_j^0, \sigma_j, \mathcal{P}_j$ and gives that for any $\gamma \in \mathcal{F}$ there exists $\boldsymbol{\xi}_{\gamma}^* \in \mathcal{B}$ such that, setting $z_j = \gamma_j(\boldsymbol{\xi}_{\gamma}^*)$,

$$\mathcal{P}_j(z_j) = \xi_j^0 \quad \forall j = 1, \dots, N,$$

which implies

$$\frac{z_j - p_i}{|z_j - p_i|} = e^{\mathbf{i}\left(\theta_i + j\frac{\delta}{N}\right)} \quad \forall j \in I_i, \ i = 1, \dots, \ell.$$

Let us observe that in this case the fibers of \mathcal{P}_j are half-lines emanating from p_i and the assumption (2.10) is required to get a control on the energy when two or more components of $z = (z_1, \ldots, z_N)$ collapse onto p_i , which represents a crucial point to establish the uniform boundedness from above of Ψ_M^* . Indeed, by construction we obtain

$$|z_j - z_k| \ge |z_j - p_i| \sin \frac{\delta}{2N} \quad \forall j, k \in I_i, \ j \neq k \quad (i = 1, \dots, \ell).$$

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Moreover, for any $j \in I_i$ we have that ξ_j belongs to the cone (4.17). This implies that

$$|z_i - z_k| \ge \mu \quad \forall j \in I_i, \ k \in I_r, \ i \ne r$$

where the value μ depends only on the choice of the angles θ_i and the number δ . Combining these facts with (1.8) we may estimate

$$\Psi(z) \leq -\sum_{i=1}^{\ell} \frac{\alpha_i}{2\pi} \sum_{j=1}^{N} \log \frac{1}{|z_j - p_i|} + \frac{1}{2\pi} \sum_{\substack{j,k=1\\j \neq k}}^{N} \log \frac{1}{|z_j - z_k|} + C$$

$$\leq -\frac{1}{2\pi} \sum_{i=1}^{\ell} \alpha_i \sum_{j=1}^{N} \log \frac{1}{|z_j - p_i|} + \frac{1}{2\pi} \sum_{\substack{i=1\\j \neq k}}^{\ell} \sum_{\substack{j,k \in I_i\\j \neq k}}^{\ell} \log \frac{1}{|z_j - z_k|} + C.$$
(4.21)

For a fixed $i \in \{1, ..., \ell\}$ and $j \in I_i$ we have

$$-\alpha_{i} \log \frac{1}{|z_{j} - p_{i}|} + \sum_{\substack{k \in I_{i} \\ k \neq j}} \log \frac{1}{|z_{j} - z_{k}|}$$

$$\leq -\alpha_{i} \log \frac{1}{|z_{j} - p_{i}|} + (N_{i} - 1) \log \frac{1}{|z_{j} - p_{i}|} - (N_{i} - 1) \log \sin \frac{\delta}{2N}.$$

Since $\alpha_i > N_i - 1$ by (4.19), the above quantity is uniformly bounded above. Combining this with (4.21) we deduce a uniform upper bound for Ψ on the range of γ :

$$\min_{\boldsymbol{\xi}\in\mathcal{B}}\Psi(\boldsymbol{\gamma}(\boldsymbol{\xi}))\leq\Psi(\boldsymbol{\gamma}(\boldsymbol{\xi}_{\boldsymbol{\gamma}}^{*}))=\Psi(\boldsymbol{z})\leq C$$

with the constant *C* independent of γ . By taking the supremum for all the maps $\gamma \in \mathcal{F}$ we obtain the thesis.

Then taking into account of Propositions 4.3 and 4.4 the max-min inequality (P2) will follow once we have proved the next result.

Proposition 4.5 The following holds:

3.7

$$\min_{\boldsymbol{\xi}\in\mathcal{B}_0}\Psi(\boldsymbol{\xi}) = \min\left\{\Psi(\boldsymbol{\xi}) \,\middle|\, \boldsymbol{\xi}\in\mathcal{B}, \, \min_{j\neq k}d_g(\xi_j,\xi_k) = M^{-1}\right\} \to +\infty \text{ as } M \to +\infty.$$
(4.22)

Proof Let $\boldsymbol{\xi}_n = (\xi_1^n, \dots, \xi_N^n) \in \mathcal{B}$ be such that $\min_{j \neq k} d_g(\xi_j^n, \xi_k^n) \to 0$ as $n \to +\infty$. Possibly passing to a subsequence, we may assume

$$d_g(\xi_{j_0}^n, \xi_{k_0}^n) \to 0 \text{ as } n \to +\infty$$

$$(4.23)$$

for some $j_0 \neq k_0$. So, by using (4.6), we may estimate

$$\Psi(\boldsymbol{\xi}_n) = \frac{1}{2\pi} \sum_{\substack{j,k=1\\j \neq k}}^N \log \frac{1}{d_g(\xi_j^n, \xi_k^n)} + O(1) \ge \frac{1}{\pi} \log \frac{1}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)} + O(1) \to +\infty.$$

Hence, the proof of property (P3) carried out in the next section allows us to conclude the proof of Propositions 2.6 and 2.7.

4.3 Proof of (P3)

We shall show that the compactness property (P3) holds provided that M is sufficiently large and assumptions (H1), (H2), (H3), (H4), (2.8)–(2.9) hold.

By Propositions 4.3 and 4.4 we get $\Psi^* = \Psi^*_M = O(1)$ as $M \to +\infty$. Then (P3) will follow once we have proved the assertion of tangential derivative being non-zero over the boundary of \mathcal{D} for uniformly bounded values of Ψ provided that M is large enough. We point out that we will follow some argument of [17], where an analogous compactness property is proved for positive K; however, unlike [17], here we have also to rule out the possibility that some critical point occurs on the boundary $\partial \Sigma^+$ and this is a delicate situation that needs to be handled carefully.

We proceed by contradiction: assume that there exist $\boldsymbol{\xi}_n = (\xi_1^n, \dots, \xi_N^n) \in \mathcal{M}^+$ and $(\beta_1^n, \beta_2^n) \neq (0, 0)$ such that

$$\Phi(\boldsymbol{\xi}_n) \to -\infty, \quad \Psi(\boldsymbol{\xi}_n) = O(1), \tag{4.24}$$

$$\beta_1^n \nabla \Psi(\boldsymbol{\xi}_n) + \beta_2^n \nabla \Phi(\boldsymbol{\xi}_n) = 0. \tag{4.25}$$

The last expression implies that $\nabla \Psi(\boldsymbol{\xi}_n)$ and $\nabla \Phi(\boldsymbol{\xi}_n)$ are linearly dependent. Observe that, according to the Lagrange multiplier Theorem, this contradicts either the smoothness of $\partial \mathcal{D}$ or the nondegeneracy of $\nabla \Phi(\boldsymbol{\xi}_n)$ on the tangent space at the level Ψ^* . Without loss of generality we may assume

$$(\beta_1^n)^2 + (\beta_2^n)^2 = 1 \text{ and } \beta_1^n + \beta_2^n \ge 0.$$
 (4.26)

Observe that by (4.24)

$$2\sum_{\substack{j,k=1\\j\neq k}}^{N} G(\xi_j^n,\xi_k^n) = \Psi(\boldsymbol{\xi}_n) - \Phi(\boldsymbol{\xi}_n) \to +\infty,$$

which implies

$$\min_{j \neq k} d_g(\xi_j^n, \xi_k^n) = o(1).$$
(4.27)

Identity (4.25) can be rewritten as

$$\frac{\beta_1^n + \beta_2^n}{4\pi} \frac{\nabla K(\xi_j)}{K(\xi_j)} - (\beta_1^n + \beta_2^n) \sum_{i=1}^{\ell} \alpha_i \nabla_{\xi_j} G(\xi_j^n, p_i) + 2(\beta_1^n - \beta_2^n) \sum_{\substack{k=1\\k \neq j}}^N \nabla_{\xi_j} G(\xi_j^n, \xi_k^n) = O(1) \quad \forall j.$$
(4.28)

The object of the remaining part of the section is to expand the left hand side of (4.25) and to prove that the leading term is not zero, so that the contradiction arises. Before going on we fix some notation. For every $\xi \in \Sigma$ we introduce normal coordinates y_{ξ} from a neighborhood of ξ onto $B_{r_0}(0)$ (the choice of r_0 is independent of ξ) which depend smoothly on $\xi \in \Sigma$. Since $y_{\xi}(\xi) = 0$ and $d_g(x, \xi) = |y_{\xi}(x)|$ for all $x \in y_{\xi}^{-1}(B_{r_0}(0))$, we have that

$$d_g(\xi_1, \xi_2) = |y_{\xi}(\xi_1) - y_{\xi}(\xi_2)|(1 + o(1))$$

and

$$\nabla_{\xi_1} \log d_g(\xi_1, \xi_2) = \frac{y_{\xi_2}(\xi_1)}{|y_{\xi_2}(\xi_1)|^2} = \frac{y_{\xi}(\xi_1) - y_{\xi}(\xi_2) + o(|y_{\xi}(\xi_1) - y_{\xi}(\xi_2)|)}{|y_{\xi}(\xi_1) - y_{\xi}(\xi_2)|^2}$$
(4.29)

as $\xi_1, \xi_2 \to \xi$.

Hereafter we might pass to subsequences without further notice.

Let us split $\{1, \ldots, N\}$ as $\tilde{Z} \cup Z_0 \cup Z_1 \cup \ldots \cup Z_\ell$ where

$$Z = \{j \mid d_g(\xi_j^n, \partial \Sigma^+) \ge c \& d_g(\xi_j^n, p_i) \ge c \text{ for all } i\},\$$

$$Z_0 = \{j \mid d_g(\xi_i^n, \partial \Sigma^+) \to 0\}, \quad Z_i = \{j \mid \xi_i^n \to p_i\}, \quad i = 1, \dots, \ell.$$

We begin with the following three lemmas.

Lemma 4.6 $d_g(\xi_j^n, \xi_k^n) \ge c$ for all $j, k \in Z_0, j \neq k$.

Proof Suppose by contradiction that there exists a point $\xi_0 \in \partial \Sigma^+$ which is the limit of more than one sequence ξ_i^n ; then define the subset $Y_0 \subset Z_0$ corresponding to such sequences:

 $Y_0 := \{ j \mid \xi_i^n \to \xi_0 \}, \quad d_g(\xi_j^n, \xi_0) \ge c \quad \forall j \in Z_0 \setminus Y_0.$

Let us choose two indices $j_0, k_0 \in Y_0, j_0 \neq k_0$ in such a way that we may split Y_0 as $I \cup (Y_0 \setminus I)$ with¹

$$j_0, k_0 \in I, \quad d_g(\xi_j^n, \xi_k^n) \sim d_g(\xi_{j_0}^n, \xi_{k_0}^n) \quad \forall j, k \in I, \ j \neq k.$$

and

$$d_g(\xi_{j_0}^n, \xi_{k_0}^n) = o(d_g(\xi_j, \xi_k)) \quad \forall j \in I, \forall k \in Y_0 \backslash I.$$

$$(4.30)$$

Moreover, without loss of generality we may assume

$$d_g(\xi_j^n, \partial \Sigma^+) \ge d_g(\xi_{j_0}^n, \partial \Sigma^+) \quad \forall j \in I.$$
(4.31)

By (4.30) we have

$$\nabla_{\xi_j} G(\xi_j^n, \xi_k^n) = o\left(\frac{1}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}\right) \quad \forall j \in I, \ k \in Y_0 \backslash I.$$

Recalling assumption (H2)-(H3), by (4.31) we derive

$$\frac{|\nabla K(\xi_j^n)|}{K(\xi_j^n)} \sim \frac{1}{d_g(\xi_j^n, \partial \Sigma^+)} \le C \frac{1}{d_g(\xi_{j_0}^n, \partial \Sigma^+)} \quad \forall j \in I.$$

$$(4.32)$$

Using the local chart $y_{\xi_{i_0}^n}$, and recalling (4.29), the identities (4.28) give

$$\frac{\beta_{1}^{n} + \beta_{2}^{n}}{4\pi} \frac{\nabla K(\xi_{j}^{n})}{K(\xi_{j}^{n})} + 2(\beta_{1}^{n} - \beta_{2}^{n}) \sum_{\substack{k \in I \\ k \neq j}} \frac{y_{\xi_{j_{0}}^{n}}(\xi_{j}^{n}) - y_{\xi_{j_{0}}^{n}}(\xi_{k}^{n})}{|y_{\xi_{j_{0}}^{n}}(\xi_{j}^{n}) - y_{\xi_{j_{0}}^{n}}(\xi_{k}^{n})|^{2}} = o\left(\frac{\beta_{1}^{n} - \beta_{2}^{n}}{d_{g}(\xi_{j_{0}}^{n}, \xi_{k_{0}}^{n})}\right) + O(1) \quad \forall j \in I.$$

$$(4.33)$$

¹ Here we use the notation \sim to denote sequences which in the limit $n \to +\infty$ are of the same order.

Let us multiply the above identity by $y_{\xi_{j_0}^n}(\xi_j^n)$ and next sum in $j \in I$; taking into account the following general relation

$$\sum_{\substack{j,k\in I\\j\neq k}} \frac{(z_j - z_k)(z_j - z)}{|z_j - z_k|^2} = \sum_{\substack{j,k\in I\\j< k}} 1 = \frac{\#I(\#I - 1)}{2} \quad \forall z_j, z \in \mathbb{R}^2$$
(4.34)

we obtain

$$\frac{\beta_1^n + \beta_2^n}{4\pi} \sum_{j \in I} \frac{\nabla K(\xi_j^n)}{K(\xi_j^n)} y_{\xi_{j_0}^n}(\xi_j^n) + (\beta_1^n - \beta_2^n) \# I(\# I - 1) = o(\beta_1^n - \beta_2^n) + O(d_g(\xi_{j_0}^n, \xi_{k_0}^n))$$

by which, recalling that $\#I \ge 2$ (since $j_0, k_0 \in I$) and using (4.32), we get

$$\beta_1^n - \beta_2^n = (\beta_1^n + \beta_2^n) O\left(\frac{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}{d_g(\xi_{j_0}^n, \partial \Sigma^+)}\right) + O\left(d_g\left(\xi_{j_0}^n, \xi_{k_0}^n\right)\right).$$
(4.35)

Next let us multiply (4.33) by $v_j^n := \frac{\nabla K(\xi_j^n)}{|\nabla K(\xi_j^n)|}$ and sum in $j \in I$:

$$\frac{\beta_1^n + \beta_2^n}{4\pi} \sum_{j \in I} \frac{|\nabla K(\xi_j^n)|}{K(\xi_j^n)} + 2(\beta_1^n - \beta_2^n) \sum_{\substack{j,k \in I\\k \neq j}} \frac{y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)}{|y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)|^2} \nu_j^n = o\left(\frac{\beta_1^n - \beta_2^n}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}\right) + O(1).$$
(4.36)

Since *K* is of class $C^2(\Sigma)$ according to assumption (H2), we deduce

$$\nu_j^n - \nu_k^n = O(d_g(\xi_j^n, \xi_k^n))$$

by which we can write

$$\sum_{\substack{j,k\in I\\k\neq j}} \frac{y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)}{|y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)|^2} \nu_j^n = \sum_{\substack{j,k\in I\\j< k}} \frac{y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)}{|y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)|^2} \left(\nu_j^n - \nu_k^n\right) = O(1).$$

By inserting the above estimate into (4.36) and recalling (4.32) we arrive at

$$\frac{\beta_1^n + \beta_2^n}{4\pi} \frac{1}{d_g(\xi_{j_0}^n, \partial \Sigma^+)} = o\left(\frac{\beta_1^n - \beta_2^n}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}\right) + O(1)$$

or, equivalently,

$$\beta_1^n + \beta_2^n = (\beta_1^n - \beta_2^n) o\left(\frac{d_g(\xi_{j_0}^n, \partial \Sigma^+)}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}\right) + O(d_g(\xi_{j_0}^n, \partial \Sigma^+)).$$
(4.37)

Combining (4.35) and (4.37) we get $\beta_1^n - \beta_2^n = o(1), \beta_1^n + \beta_2^n = o(1)$, in contradiction to (4.26).

Lemma 4.7 The following holds:

(a) if #Z_i = 1 for some i = 1, ..., ℓ, then β₁ⁿ + β₂ⁿ → 0;
(b) if Z₀ ≠ Ø, then β₁ⁿ + β₂ⁿ → 0;

(c) if $d_g(\xi_j^n, \xi_k^n) = o(1)$ for some $j, k \in \tilde{Z}, j \neq k$, then $\beta_1^n - \beta_2^n \to 0$;

(d) there exists $i \in \{1, ..., \ell\}$ such that $\#Z_i \ge 2$.

Proof Assume that $i = 1, ..., \ell$ is such that $\#Z_i = 1$, say $Z_i = \{j_0\}$. Then, using the local chart y_{p_i} , the identities (4.28) give

$$(\beta_1^n + \beta_2^n)\alpha_i \frac{y_{p_i}(\xi_{j_0}^n)}{|y_{p_i}(\xi_{j_0}^n)|^2} = O(1)$$

which implies $\beta_1^n + \beta_2^n = o(1)$, then *a*) follows.

Similarly, assume that $Z_0 \neq \emptyset$ and let $j_0 \in Z_0$. According to Lemma 4.6 we have $d_g(\xi_{j_0}^n, \xi_j) \ge c$ for all $j \neq j_0$. In this case the identity (4.28) with $j = j_0$ becomes

$$(\beta_1^n + \beta_2^n) \frac{\nabla K(\xi_{j_0}^n)}{K(\xi_{j_0}^n)} = O(1).$$

According to assumption (H2)–(H3) we have $\frac{|\nabla K(\xi_{j_0}^n)|}{K(\xi_{j_0}^n)} \sim \frac{1}{d_g(\xi_{j_0}^n, \partial \Sigma^+)}$, and (b) is thus established.

Next, suppose that $j_0, k_0 \in \tilde{Z}$ with $j_0 \neq k_0$ are such that $d_g(\xi_{j_0}^n, \xi_{k_0}^n) = o(1)$. We may assume

$$d_g(\xi_{j_0}^n,\xi_{k_0}^n) = \min_{j,k\in\tilde{Z},\,j\neq k} d_g(\xi_j^n,\xi_k^n) \quad \forall n\in\mathbb{N}.$$

So we can split \tilde{Z} as $I \cup J$ where

$$I = \left\{ j \in \tilde{Z} \mid d_g(\xi_j^n, \xi_{j_0}^n) \sim d_g(\xi_{j_0}^n, \xi_{k_0}^n) \right\} \cup \{j_0\}, J = \left\{ j \in \tilde{Z} \mid d_g(\xi_{j_0}^n, \xi_{k_0}^n) = o(d_g(\xi_j^n, \xi_{j_0}^n)) \right\}.$$

We observe that by construction

$$d_g(\xi_{j_0}^n,\xi_{k_0}^n) \sim d_g(\xi_j^n,\xi_k^n) \quad \forall j,k \in I, \ j \neq k$$

and $d_g(\xi_{j_0}^n, \xi_{k_0}^n) = o(d_g(\xi_j^n, \xi_k^n))$ for all $j \in I$ and $k \in J$, by which

$$\nabla_{\xi_j} G(\xi_j^n, \xi_k^n) = o\left(\frac{1}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}\right) \quad \forall j \in I, \ k \in J.$$

Then for any $j \in I$, using the local chart $y_{\xi_{i_0}^n}$ the identities (4.28) give

$$(\beta_1^n - \beta_2^n) \sum_{\substack{k \in I \\ k \neq j}} \frac{y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)}{|y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)|^2} = o\left(\frac{1}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}\right) \quad \forall j \in I.$$
(4.38)

So we multiply (4.38) by $y_{\xi_{i_0}^n}(\xi_j^n)$ and sum in $j \in I$: by using (4.34) we arrive at

$$(\beta_1^n - \beta_2^n) # I (#I - 1) = o(1).$$

Taking into account that *I* has at least two elements, since j_0 , $k_0 \in I$, we deduce $\beta_1^n - \beta_2^n = o(1)$, and c) follows.

Finally assume by contradiction that Z_i consists of at most one index for every $i = 1, ..., \ell$. Then, combining this with Lemma 4.6 and (4.27) we find that $d_g(\xi_j^n, \xi_k^n) = o(1)$ for some $j, k \in \tilde{Z}, j \neq k$. Then part (c) gives $\beta_1^n - \beta_2^n = o(1)$; consequently $\beta_1^n + \beta_2^n \ge c$

by (4.26), and part (b) implies $Z_0 = \emptyset$, that is $K(\xi_j^n) = O(1)$ for all *j*. So, thanks to (4.24) we deduce

$$2\sum_{i=1}^{\ell} \alpha_i \sum_{j=1}^{N} G(\xi_j, p_i) = -\Phi(\xi_n) - \Psi(\xi_n) + O(1) \to +\infty.$$

which implies

$$\min_{i,j} d_g(\xi_j^n, p_i) = o(1).$$

Then Z_i is nonempty for some $i = 1, ..., \ell$, so $\#Z_i = 1$ for such *i*. Then, by (a) we derive $\beta_1^n + \beta_2^n = o(1)$, and the contradiction arises.

Lemma 4.8 If $i = 1, ..., \ell$ is such that $\#Z_i \ge 2$, then $d_g(\xi_j^n, p_i) = O(d_g(\xi_j^n, \xi_k^n))$ for all $j, k \in Z_i, j \ne k$.

Proof Fix $i = 1, ..., \ell$ with $\#Z_i \ge 2$. We proceed by contradiction assuming that there exist indices $j_0, k_0 \in Z_i, j_0 \ne k_0$, such that

$$\frac{d_g(\xi_{j_0}^n,\xi_{k_0}^n)}{d_g(\xi_{j_0}^n,p_i)} = \min_{i,j\in Z_i, j\neq j} \frac{d_g(\xi_j^n,\xi_k^n)}{d_g(\xi_j^n,p_i)} \to 0.$$
(4.39)

According to (4.39) we can split Z_i as $I \cup J$ where

$$I = \left\{ j \in Z_i \mid d_g(\xi_j^n, \xi_{j_0}^n) \sim d_g(\xi_{j_0}^n, \xi_{k_0}^n) \right\} \cup \{j_0\}, J = \left\{ j \in Z_i \mid d_g(\xi_{j_0}^n, \xi_{k_0}^n) = o(d_g(\xi_j^n, \xi_{j_0}^n)) \right\}.$$

Clearly $j_0, k_0 \in I$, so $\#I \ge 2$. We observe that by construction

$$d_g(\xi_i^n, p_i) \sim d_g(\xi_{i_0}^n, p_i) \quad \forall j \in I$$

and

$$d_g(\xi_j^n, \xi_k^n) \sim d_g(\xi_{j_0}^n, \xi_{k_0}^n) \quad \forall j, k \in I, \ j \neq k.$$

Moreover $d_g(\xi_{j_0}^n, \xi_{k_0}^n) = o(d_g(\xi_j^n, \xi_k^n))$ for all $j \in I$ and $k \in J$, by which

$$\nabla_{\xi_j} G(\xi_j^n, \xi_k^n) = o\left(\frac{1}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}\right) \quad \forall j \in I, \ k \in J.$$

Using the local chart $y_{\xi_{i_0}^n}$, and recalling (4.29), the identities (4.28) give

$$\begin{aligned} (\beta_1^n + \beta_2^n) &\alpha_i \frac{y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(p_i)}{|y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(p_i)|^2} - 2(\beta_1^n - \beta_2^n) \sum_{\substack{k \in I \\ k \neq j}} \frac{y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)}{|y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(\xi_k^n)|^2} \\ &= o\Big(\frac{\beta_1^n + \beta_2^n}{d_g(\xi_{j_0}^n, p_i)}\Big) + o\Big(\frac{\beta_1^n - \beta_2^n}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}\Big) + O(1) \quad \forall j \in I. \end{aligned}$$
(4.40)

Let us multiply the above identity by $y_{\xi_{j_0}^n}(\xi_j^n)$ and next sum in $j \in I$; using (4.34) we obtain

$$(\beta_1^n - \beta_2^n) \# I(\# I - 1) = (\beta_1^n + \beta_2^n) O\left(\frac{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}{d_g(\xi_{j_0}^n, p_i)}\right) + o(\beta_1^n - \beta_2^n) + O(d_g(\xi_{j_0}^n, \xi_{k_0}^n)).$$

by which we get

$$\beta_1^n - \beta_2^n = O\left(\frac{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}{d_g(\xi_{j_0}^n, p_i)}\right) = o(1).$$
(4.41)

Next we multiply identity (4.40) by $y_{\xi_{j_0}^n}(\xi_j^n) - y_{\xi_{j_0}^n}(p_i)$ and sum in $j \in I$; by using again the relation (4.34) we get

$$\begin{aligned} (\beta_1^n + \beta_2^n) \alpha_i &\# I = (\beta_1^n - \beta_2^n) \# I (\# I - 1) \\ &+ o(\beta_1^n + \beta_2^n) + (\beta_1^n - \beta_2^n) o\left(\frac{d_g(\xi_{j_0}^n, p_i)}{d_g(\xi_{j_0}^n, \xi_{k_0}^n)}\right) + O(d_g(\xi_{j_0}^n, p_i)). \end{aligned}$$

Taking (4.41) into account we obtain that $\beta_1^n + \beta_2^n = o(1)$, in contradiction to (4.26).

Let us sum up all the previous information contained in Lemmas 4.6, 4.7 and 4.8 in order to finally get the conclusion. According to (d) of Lemma 4.7, there exists $i = 1, ..., \ell$ be such that $\#Z_i \ge 2$. Let us split Z_i as $Y_1 \cup \cdots \cup Y_l$, $l \ge 1$, in such a way that

$$d_g(\xi_i^n, p_i) \sim d_g(\xi_k^n, p_i) \quad \forall j, k \in Y_r$$

and

$$d_g(\xi_j^n, p_i) = o(d_g(\xi_k^n, p_i)) \quad \forall j \in Y_r, \, \forall k \in Y_{r+1} \cup \dots \cup Y_l.$$

$$(4.42)$$

Notice that by construction $d_g(\xi_j^n, \xi_k^n) \sim d_g(\xi_k^n, p_i)$ for all $j \in Y_r, k \in Y_{r+1} \cup \cdots \cup Y_l$, and by Lemma 4.8 $d_g(\xi_i^n, \xi_k^n) \sim d_g(\xi_k^n, p_i)$ for all $j, k \in Y_r, j \neq k$, yielding

$$d_g(\xi_j^n, \xi_k^n) \sim d_g(\xi_k^n, p_i) \quad \forall j \in Y_r, \ \forall k \in Y_r \cup \dots \cup Y_l, \ j \neq k.$$
(4.43)

Combining (4.42)–(4.43) we get

$$\nabla_{\xi_j} G(\xi_j^n, \xi_k^n) = o\left(\frac{1}{d_g(\xi_j^n, p_i)}\right) \quad \forall j \in Y_r, \ \forall k \in Y_{r+1} \cup \dots \cup Y_l.$$

Next consider $r \in \{1, ..., l\}$ and write (4.28) for $j \in Y_r$ in the local chart y_{p_i} :

$$2(\beta_1^n - \beta_2^n) \sum_{\substack{k \in Y_1 \cup \dots \cup Y_r \\ k \neq j}} \frac{y_{p_i}(\xi_j^n) - y_{p_i}(\xi_k^n)}{|y_{p_i}(\xi_j^n) - y_{p_i}(\xi_k^n)|^2} = (\beta_1^n + \beta_2^n)\alpha_i \frac{y_{p_i}(\xi_j^n)}{|y_{p_i}(\xi_j^n)|^2} + o\left(\frac{1}{d_g(\xi_j^n, p_i)}\right)$$
(4.44)

for all $j \in Y_r$. By (4.42) and (4.43) we find $|y_{p_i}(\xi_j^n)| = o(|y_{p_i}(\xi_j^n) - y_{p_i}(\xi_k^n)|)$ for all $j \in Y_1 \cup \cdots \cup Y_{r-1}, k \in Y_r$, and we can compute

$$\frac{\langle y_{p_i}(\xi_j^n) - y_{p_i}(\xi_k^n), y_{p_i}(\xi_j^n) \rangle}{|y_{p_i}(\xi_j^n) - y_{p_i}(\xi_k^n)|^2} = 1 + \frac{\langle y_{p_i}(\xi_j^n) - y_{p_i}(\xi_k^n), y_{p_i}(\xi_k^n) \rangle}{|y_{p_i}(\xi_j^n) - y_{p_i}(\xi_k^n)|^2} = 1 + o(1)$$

for all $j \in Y_r$ and $k \in Y_1 \cup \cdots \cup Y_{r-1}$. Combining this with identity (4.34), by taking the inner product of (4.44) with $y_{p_i}(\xi_i^n)$ and summing up in $j \in Y_r$ we get that

$$2(\beta_1^n - \beta_2^n) \left(\frac{\#Y_r(\#Y_r - 1)}{2} + \#Y_r(\#Y_1 + \dots + \#Y_{r-1}) \right) = (\beta_1^n + \beta_2^n) \alpha_i \#Y_r + o(1) \quad \forall r \ge 1.$$
(4.45)

Since $\#Z_i \ge 2$, notice that the coefficient in brackets on the left hand side of (4.45) is positive when r = l, and then $\frac{1}{\alpha_i}(\beta_1^n - \beta_2^n)$ and $\beta_1^n + \beta_2^n$ are positively proportional up to higher order

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terms. So, by (4.26) and (4.45) (with r = l) we deduce that

$$\frac{\beta_1^n - \beta_2^n}{\alpha_i}, \ \beta_1^n + \beta_2^n \ge c > 0.$$
(4.46)

By (4.45) we also have

$$|\beta_2^n| \ge c > 0. \tag{4.47}$$

Indeed, if $\beta_2^n = o(1)$ we would obtain $\beta_1^n = 1 + o(1)$ and, consequently, $\#Y_1 - 1 = \alpha_i$ in view of (4.45) (with r = 1), contradicting the compactness assumption (2.8)–(2.9). Let us evaluate the different summands of the energy as follows:

$$\begin{split} &\sum_{\substack{j,k \in Z_i \\ j \neq k}} G(\xi_j^n, \xi_k^n) - \alpha_i \sum_{j \in Z_i} G(\xi_j^n, p_i) \\ &= \sum_{r=1}^l \sum_{\substack{j,k \in Y_r \\ j \neq k}} G(\xi_j^n, \xi_k^n) + 2 \sum_{r=1}^l \sum_{\substack{j \in Y_r \\ k \in Y_1 \cup \dots \cup Y_{r-1}}} G(\xi_j^n, \xi_k^n) - \alpha_i \sum_{r=1}^l \sum_{j \in Y_r} G(\xi_j^n, p_i) \\ &= -\frac{1}{2\pi} \sum_{r=1}^l \left[\sum_{\substack{j,k \in Y_r \\ j \neq k}} \log d_g(\xi_j^n, \xi_k^n) + 2 \sum_{\substack{j \in Y_r \\ k \in Y_1 \cup \dots \cup Y_{r-1}}} \log d_g(\xi_j^n, \xi_k^n) - \alpha_i \sum_{j \in Y_r} \log d_g(\xi_j^n, p_i) \right] + O(1). \end{split}$$

Since $d_g(\xi_j^n, \xi_k^n) \sim d_g(\xi_j^n, p_i)$ for all $j \in Y_r$ and $k \in Y_1 \cup \cdots \cup Y_r$ with $j \neq k$ thanks to (4.43), fixed $j_r \in Y_r$ we have that

$$\begin{split} &\sum_{\substack{j,k \in Y_r \\ j \neq k}} \log d_g(\xi_j^n, \xi_k^n) + 2 \sum_{\substack{j \in Y_r \\ k \in Y_1 \cup \dots \cup Y_{r-1}}} \log d_g(\xi_j^n, \xi_k^n) - \alpha_i \sum_{j \in Y_r} \log d_g(\xi_j^n, p_i) \\ &= \left(\sum_{\substack{j,k \in Y_r \\ j \neq k}} 1 + 2 \sum_{\substack{j \in Y_r \\ k \in Y_1 \cup \dots \cup Y_{r-1}}} 1 - \alpha_i \sum_{j \in Y_r} 1 \right) \log d_g(\xi_{j_r}^n, p_i) + O(1) \\ &= \#Y_r \Big(\#Y_r - 1 + 2(\#Y_1 + \dots + \#Y_{r-1}) - \alpha_i \Big) \log d_g(\xi_{j_r}^n, p_i) + O(1) \\ &= \frac{2\beta_2^n + o(1)}{\beta_1^n - \beta_2^n} \alpha_i \#Y_r \log d_g(\xi_{j_r}^n, p_i) + O(1) \end{split}$$

where in the last identity we have used (4.45). Recalling (4.46)–(4.47), we have thus proved that

$$\frac{1}{\beta_2^n} \left(\sum_{j,k \in \mathbb{Z}_i / / j \neq k} G(\xi_j^n, \xi_k^n) - \alpha_i \sum_{j \in \mathbb{Z}_i} G(\xi_j^n, p_i) \right) \to +\infty$$
(4.48)

for all Z_i with $\#Z_i \ge 2$. On the other hand by (4.46) and part (a) of Lemma 4.7 we have that for any $i = 1, ..., \ell$ either $Z_i = \emptyset$ or $\#Z_i \ge 2$. Moreover part (b) and (c) give $K(\xi_j^n) = O(1)$ for all j and $G(\xi_j^n, \xi_k^n) = O(1)$ for all $(j, k) \notin \bigcup_{i=1}^{\ell} (Z_i \times Z_i)$. Then we conclude

$$\begin{aligned} \frac{1}{\beta_2^n} \Psi(\boldsymbol{\xi}_n) &= \frac{1}{\beta_2^n} \bigg[\sum_{\substack{j,k=1//j \neq k}}^N G(\xi_j^n, \xi_k^n) - \sum_{i=1}^\ell \alpha_i \sum_{j=1}^N G(\xi_j^n, p_i) \bigg] + O(1) \\ &= \frac{1}{\beta_2^n} \sum_{i=1}^\ell \bigg[\sum_{\substack{j,k\in Z_i \\ j \neq k}} G(\xi_j^n, \xi_k^n) - \alpha_i \sum_{j\in Z_i} G(\xi_j^n, p_i) \bigg] + O(1) \to +\infty \end{aligned}$$

in view of (4.48), in contradiction to (4.24) and (4.47).

5 More existence results

In this section we get other existence results for solutions to $(*)_{\rho_{geo}}$, using Proposition 2.2.

In general it is hard to guarantee the validity of condition *b*) of Proposition 2.2 and in all our previous results we got it for *K* sign-changing and satisfying in particular condition (2.6) discussed in Remark 2.3, which implies $\mathcal{A}(\boldsymbol{\xi}) < 0$ for all $\boldsymbol{\xi} \in \mathcal{M}$; in such a case condition *b*) is satisfied and this led then to solutions to $(*)_{\rho_{geo}}$, for ρ_{geo} close to integer multiples of 8π from the left hand side.

As noticed in Remark 2.4 it is not possible to impose on *K* a simple condition like (2.6) and have instead $\mathcal{A}(\boldsymbol{\xi}) > 0$ for all $\boldsymbol{\xi} \in \mathcal{M}$, which would lead then to solutions to $(*)_{\rho_{geo}}$, for ρ_{geo} close to integer multiples of 8π from the right hand side. And this holds both for *K* sign-changing or positive.

Moreover observe that if we consider functions K > 0 then, since $\Delta_g \log K$ changes sign on Σ , it is not even possible to impose on it the simple condition (2.6) in Remark 2.3 and have $\mathcal{A}(\boldsymbol{\xi}) < 0$ for all $\boldsymbol{\xi} \in \mathcal{M}$. Namely for K positive it is hard to get solutions to $(*)_{\rho_{geo}}$ via Proposition 2.2 even for ρ_{geo} close to integer multiples of 8π from the left hand side.

Nevertheless in this section we exhibit classes of functions K, sign-changing or also positive, (and values of α_i 's) for which we are able to produce a stable critical point ξ^*_{α} of Ψ_{α} fulfilling conditions b) and c) of Proposition 2.2, obtaining in this way solutions to $(*)_{\rho_{geo}}$, for ρ_{geo} close to an integer multiple of 8π both from the right and from the left.

Let us first state rigorously these results on any compact orientable surface without boundary (Σ, g) . Next we will deduce from them Theorems 1.9, 1.10 and 1.11 in the introduction which are related to the case of the standard sphere and to situations for which general existence results are not available in the literature.

Let $m, N \in \mathbb{N}$, $p_1, \ldots, p_m \in \Sigma$ and $-1 < \alpha_* \le \alpha^*$ be fixed. For any $\underline{s} = (s_1, \ldots, s_m)$, $\alpha_* \le s_i \le \alpha^*$, we define the functional

$$D_{\underline{s}}(\boldsymbol{\xi}) := \sum_{j=1}^{N} h(\xi_j, \xi_j) + \frac{1}{4\pi} \sum_{j=1}^{N} f_g(\xi_j) - \sum_{i=1}^{m} s_i \sum_{j=1}^{N} G(\xi_j, p_i) + \sum_{\substack{j,k=1\\j\neq k}}^{N} G(\xi_j, \xi_k), \quad (5.1)$$

which is well defined in the set

$$\mathcal{M} := (\Sigma \setminus \{p_1, \dots, p_m\})^N \setminus \Delta, \quad \Delta := \left\{ \boldsymbol{\xi} \in \Sigma^N \, \middle| \, \xi_j = \xi_k \text{ for some } j \neq k \right\}$$
(5.2)

where G(x, p) is the Green's function of $-\Delta_g$ over Σ with singularity at p, the function h denotes its regular part as in (1.8), and f_g is defined by (1.5). Next we fix $\overline{\xi} \in \mathcal{M}$ and we consider a radius $r = r(\overline{\xi}) > 0$ such that

$$\mathcal{B}_{2r}(\bar{\boldsymbol{\xi}}) := \{ \boldsymbol{\xi} \in \Sigma^N \, | \, d_g(\bar{\boldsymbol{\xi}}, \boldsymbol{\xi}) < 2r \} \subset \mathcal{M}, \tag{5.3}$$

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where in the above brackets with a small abuse of notation we have continued to denote by d_g the distance on Σ^N . Let us set

$$M_{\bar{\xi},\alpha_*,\alpha^*}^+ := \max_{\substack{\alpha_* \le s_i \le \alpha^* \\ i=1,\dots,m}} \max_{\boldsymbol{\xi} \in \overline{B_{\frac{r}{2}}(\bar{\xi})}} D_{\underline{s}}(\boldsymbol{\xi}) \text{ and } m_{\bar{\xi},\alpha_*,\alpha^*}^+ := \min_{\substack{\alpha_* \le s_i \le \alpha^* \\ i=1,\dots,m}} \min_{\boldsymbol{\xi} \in \partial B_r(\bar{\xi})} D_{\underline{s}}(\boldsymbol{\xi}).$$

Let $K \in C^2(\Sigma)$ be either a positive function or a sign-changing function satisfying the following

$$\inf_{\boldsymbol{\xi}\in B_r(\boldsymbol{\xi})} \min_{j=1,\dots,N} K(\boldsymbol{\xi}_j) > 0, \tag{5.4}$$

$$\max_{\xi \in \overline{B_{\frac{r}{2}}(\bar{\xi})}} \left(\frac{1}{4\pi} \sum_{j=1}^{N} \log K(\xi_j) \right) < \min_{\xi \in \partial B_r(\bar{\xi})} \left(\frac{1}{4\pi} \sum_{j=1}^{N} \log K(\xi_j) \right) + m_{\bar{\xi},\alpha_*,\alpha^*}^+ - M_{\bar{\xi},\alpha_*,\alpha^*}^+$$
(5.5)

and

$$\inf_{\boldsymbol{\xi}\in B_r(\bar{\boldsymbol{\xi}})} \min_{j\in 1,\dots,N} \Delta_g \log K(\boldsymbol{\xi}_j) \ge \frac{1}{|\boldsymbol{\Sigma}|}.$$
(5.6)

Finally let us define the class of functions

$$\mathcal{K}^{+}_{\bar{\xi},\alpha_{*},\alpha^{*}} := \left\{ K \in C^{2}(\Sigma) : K \text{ satisfies (5.4), (5.5) and (5.6)} \right\}$$
(5.7)

It is clear that for any fixed $\bar{\xi}$, α_* , α^* we can exhibit plenty of functions *K*, both positive or sign-changing, belonging to the class $\mathcal{K}^+_{\bar{\xi},\alpha_*,\alpha^*}$. Roughly speaking, (5.4), (5.5) and (5.6) are satisfied if *K* has *sufficiently convex* local minima at points $\bar{\xi}_1, \ldots, \bar{\xi}_N$, where $\bar{\xi} = (\bar{\xi}_1, \ldots, \bar{\xi}_N)$.

Theorem 5.1 For any $K \in \mathcal{K}^+_{\xi,\alpha_*,\alpha^*}$ there exists $\delta = \delta(\alpha_*, \alpha^*, K) > 0$ such that if

$$\sum_{i=1}^{m} \alpha_i = 2N - \chi(\Sigma) + \frac{\varepsilon}{4\pi} \quad \text{for } \varepsilon \in (0, \delta)$$
(5.8)

and

$$\alpha_* \le \alpha_i \le \alpha^* \quad for \ all \ i = 1, \dots, m \tag{5.9}$$

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 8\pi N + \varepsilon$.

Proof By (5.3) and (5.4) we deduce

$$B_r(\bar{\boldsymbol{\xi}}) \subset \mathcal{M}^+ = (\Sigma^+ \setminus \{p_1, \ldots, p_m\})^N \setminus \Delta$$

and hence the functional $\Psi_{\underline{\alpha}}$, introduced in (2.1), is well defined in $\overline{B_r(\bar{\xi})}$.

We rewrite Ψ_{α} as

$$\Psi_{\underline{\alpha}}(\boldsymbol{\xi}) = D_{\underline{\alpha}}(\boldsymbol{\xi}) + \frac{1}{4\pi} \sum_{j=1}^{N} \log K(\xi_j), \qquad (5.10)$$

where $D_{\underline{\alpha}}$ is defined in (5.1) with $\underline{s} = \underline{\alpha} = (\alpha_1, \dots, \alpha_m)$. For the sake of clarity we split the remaining part of the proof into three steps.

STEP 1. We show that assumptions (5.5) and (5.9) imply the existence of a local minimum point (and so a stable critical point) $\xi_{\underline{\alpha}}^* \in B_r(\overline{\xi})$ of $\Psi_{\underline{\alpha}}$.

In order to prove this step it is enough to show that

$$\max_{\boldsymbol{\xi}\in B_{\frac{r}{2}}(\overline{\boldsymbol{\xi}})}\Psi_{\underline{\alpha}}(\boldsymbol{\xi}) < \min_{\boldsymbol{\xi}\in\partial B_{r}(\overline{\boldsymbol{\xi}})}\Psi_{\underline{\alpha}}(\boldsymbol{\xi}).$$

Indeed, by virtue of (5.5) and assumption (5.9) on the α_i 's we compute

$$\max_{\boldsymbol{\xi}\in\overline{B_{\frac{r}{2}}(\boldsymbol{\xi})}} \Psi_{\underline{\alpha}}(\boldsymbol{\xi}) \stackrel{(5.10)}{\leq} \max_{\boldsymbol{\xi}\in\overline{B_{\frac{r}{2}}(\boldsymbol{\xi})}} D_{\underline{\alpha}}(\boldsymbol{\xi}) + \frac{1}{4\pi} \max_{\boldsymbol{\xi}\in\overline{B_{\frac{r}{2}}(\boldsymbol{\xi})}} \left(\sum_{j=1}^{N} \log K(\boldsymbol{\xi}_{j})\right) \\
\stackrel{(5.9)}{\leq} M_{\boldsymbol{\tilde{\xi}},\alpha_{*},\alpha^{*}}^{+} + \frac{1}{4\pi} \max_{\boldsymbol{\xi}\in\overline{B_{\frac{r}{2}}(\boldsymbol{\xi})}} \left(\sum_{j=1}^{N} \log K(\boldsymbol{\xi}_{j})\right) \\
\stackrel{(5.5)}{\leq} m_{\boldsymbol{\tilde{\xi}},\alpha_{*},\alpha^{*}}^{+} + \frac{1}{4\pi} \min_{\boldsymbol{\xi}\in\partial B_{r}(\boldsymbol{\tilde{\xi}})} \left(\sum_{j=1}^{N} \log K(\boldsymbol{\xi}_{j})\right) \\
\stackrel{(5.9)}{\leq} \min_{\boldsymbol{\xi}\in\partial B_{r}(\boldsymbol{\tilde{\xi}})} D_{\underline{\alpha}}(\boldsymbol{\xi}) + \frac{1}{4\pi} \min_{\boldsymbol{\xi}\in\partial B_{r}(\boldsymbol{\tilde{\xi}})} \left(\sum_{j=1}^{N} \log K(\boldsymbol{\xi}_{j})\right) \\
\stackrel{(5.10)}{\leq} \min_{\boldsymbol{\xi}\in\partial B_{r}(\boldsymbol{\tilde{\xi}})} \Psi_{\underline{\alpha}}(\boldsymbol{\xi}).$$

STEP 2. We show that if

$$0 < \sum_{i=1}^{m} \alpha_i - 2N + \chi(\Sigma) < \frac{1}{4\pi}$$
(5.11)

then $\mathcal{A}(\boldsymbol{\xi}_{\alpha}^{*}) > 0$, where \mathcal{A} is the function defined in (2.3).

By definition of A it will be enough to prove that for any j = 1, ..., N

$$\Delta_g \log K(\xi_j^*) + \frac{8\pi N - 4\pi \chi(\Sigma, \underline{\alpha})}{|\Sigma|} > 0$$

where $\boldsymbol{\xi}_{\alpha}^* = (\xi_1^*, \dots, \xi_N^*)$. This holds true by (5.11) and the condition (5.6), since

$$\Delta_g \log K(\xi_j^*) + \frac{8\pi N - 4\pi \chi(\Sigma, \underline{\alpha})}{|\Sigma|} = \Delta_g \log K(\xi_j^*) + \frac{8\pi N - 4\pi \left(\chi(\Sigma) + \sum_{i=1}^m \alpha_i\right)}{|\Sigma|}$$

$$\stackrel{(5.11)}{>} \Delta_g \log K(\xi_j^*) - \frac{1}{|\Sigma|} \stackrel{(5.6)}{\geq} 0.$$

STEP 3. Conclusion.

By (5.9), Step 2 and Step 1 we get that the assumptions (a), (b) and (c) respectively of Proposition 2.2 are all satisfied if (5.11) holds. As a consequence $(*)_{\rho}$ admits a solution for all $\rho \in (8\pi N, 8\pi N + \delta)$ under the assumption (5.11), where $\delta = \delta(\alpha_*, \alpha^*, K) \in (0, 1)$ is provided in Proposition 2.2. The conclusion follows observing that (5.8) implies (5.11) and

$$\rho_{geo} = 4\pi \left(\chi(\Sigma) + \sum_{i=1}^{m} \alpha_i \right) \in (8\pi N, 8\pi N + \delta).$$

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Similarly one can define the class of functions

$$\mathcal{K}^{-}_{\bar{\xi},\alpha_{*},\alpha^{*}} := \left\{ K \in C^{2}(\Sigma) : K \text{ satisfies (5.4), (5.13) and (5.14)} \right\}$$
(5.12)

where

$$\max_{\xi \in \partial B_{r}(\bar{\xi})} \left(\frac{1}{4\pi} \sum_{j=1}^{N} \log K(\xi_{j}) \right) < \min_{\xi \in \overline{B_{\frac{r}{2}}(\bar{\xi})}} \left(\frac{1}{4\pi} \sum_{j=1}^{N} \log K(\xi_{j}) \right) + m_{\bar{\xi},\alpha_{*},\alpha^{*}}^{-} - M_{\bar{\xi},\alpha_{*},\alpha^{*}}^{-}$$
(5.13)

for

$$M^{-}_{\bar{\xi},\alpha_{*},\alpha^{*}} := \max_{\substack{\alpha_{*} \leq s_{i} \leq \alpha^{*} \\ i = 1, \dots, m}} \max_{\xi \in \partial B_{r}(\bar{\xi})} D_{\underline{s}}(\xi) \text{ and } m^{-}_{\bar{\xi},\alpha_{*},\alpha^{*}} := \min_{\substack{\alpha_{*} \leq s_{i} \leq \alpha^{*} \\ i = 1, \dots, m}} \min_{\xi \in \overline{B_{r}(\bar{\xi})}} D_{\underline{s}}(\xi),$$

and

$$\sup_{\boldsymbol{\xi}\in B_r(\bar{\boldsymbol{\xi}})} \max_{j=1,\dots,N} \Delta_g \log K(\boldsymbol{\xi}_j) \le -\frac{1}{|\boldsymbol{\Sigma}|},\tag{5.14}$$

1

and prove the following result.

Theorem 5.2 For any $K \in \mathcal{K}^{-}_{\bar{\xi},\alpha_*,\alpha^*}$ there exists $\delta = \delta(\alpha_*,\alpha^*,K) > 0$ such that if

$$\sum_{i=1}^{m} \alpha_i = 2N - \chi(\Sigma) - \frac{\varepsilon}{4\pi} \quad \text{for } \varepsilon \in (0, \delta)$$
(5.15)

and

$$\alpha_* \le \alpha_i \le \alpha^* \quad for \ all \ i = 1, \dots, m \tag{5.16}$$

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 8\pi N - \varepsilon$.

Proof The proof can be obtained following the same strategy of the proof of Theorem 5.1.

Indeed first we show that the assumptions (5.13) and (5.16) imply the existence of a local maximum point ξ_{α}^{*} for $\Psi_{\underline{\alpha}}$ (instead of a local minimum point).

Then we prove that $\mathcal{A}(\boldsymbol{\xi}_{\alpha}^*) < 0$ (instead of $\mathcal{A}(\boldsymbol{\xi}_{\alpha}^*) > 0$) if

$$0 < 2N - \chi(\Sigma) - \sum_{i=1}^m \alpha_i < \frac{1}{4\pi},$$

using the assumption (5.14).

Last we apply again Proposition 2.2 to deduce that $(*)_{\rho}$ admits a solution for all $\rho \in (8\pi N - \delta, 8\pi N)$, where $\delta = \delta(\alpha_*, \alpha^*, K) \in (0, 1)$ is as in Proposition 2.2. The conclusion follows observing that

$$\rho_{geo} = 4\pi \left(\chi(\Sigma) + \sum_{i=1}^{m} \alpha_i \right) \in (8\pi N - \delta, 8\pi N)$$

thanks to assumption (5.15).

We point out that also in this case for any fixed $\bar{\xi}$, α_* , α^* , considering functions K having *sufficiently concave* local maxima at points $\bar{\xi}_1, \ldots, \bar{\xi}_N$, where $\bar{\xi} = (\bar{\xi}_1, \ldots, \bar{\xi}_N)$, we can find plenty of functions K, both positive or sign-changing, in the class $\mathcal{K}_{\bar{\xi},\alpha_*,\alpha^*}^-$.

5.1 Examples in the case of the standard sphere

Now we will easily deduce Theorems 1.9, 1.10 and 1.11 in the introduction by the above Theorems 5.1 and 5.2 if $(\Sigma, g) = (\mathbb{S}^2, g_0)$. Indeed when $(\Sigma, g) = (\mathbb{S}^2, g_0)$ and m = 1, by Theorems 5.1 and 5.2 we immediately get the following.

Corollary 5.3 Let $N \in \mathbb{N}$, $p_1 \in \mathbb{S}^2$ and $\overline{\xi} \in (\mathbb{S}^2 \setminus \{p_1\})^N \setminus \Delta$. Then for any $K \in \mathcal{K}_{\overline{\xi}, -\frac{1}{2}, 2N}^{\pm}$ there exists $\delta = \delta(K) > 0$ such that if

$$\alpha_1 = 2(N-1) \pm \frac{\varepsilon}{4\pi} \quad \text{for } \varepsilon \in (0,\delta) \tag{5.17}$$

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 8\pi N \pm \varepsilon$.

Proof of Theorem 1.9 Theorem 1.9 follows by Corollary 5.3 by taking *K* in the subset of $\mathcal{K}^+_{\xi,-\frac{1}{2},2N}$ made of positive functions.

Remark 5.4 We emphasize that Theorem 1.9 provides existence of a solution for $(*)_{\rho_{geo}}$ for special classes of functions *K*, whereas according to the result in [31] if $K \equiv 1$ then $(*)_{\rho_{geo}}$ does not admit solutions on the standard sphere.

Proof of Theorem 1.10 Theorem 1.10 follows by Corollary 5.3 by taking $\ell = 0$ and considering functions *K* in the class $\mathcal{K}^+_{\xi, -\frac{1}{2}, 2N}$ satisfying (H1), (H2), (H3), (H4) with $(\mathbb{S}^2)^+$ contractible. It is easy to see that such functions exist (see Remark 5.5 below).

Remark 5.5 Observe that it is possible to find examples of functions *K* in the class considered in Theorem 1.10 which are also axially symmetric. For instance, if m = 1, $\ell = 0$, N = 1, such an example is described by the first picture in Figure 3: by locating p_1 in the south pole and $\overline{\xi}$ in the north pole we can construct an axially symmetric function *K* with $(\mathbb{S}^2)^+$ coinciding with the upper hemisphere and having in $\overline{\xi}$ a sufficiently convex local minimum such that $(*)_{Pero}$ admits a solution if $\alpha_1 > 0$ is sufficiently small.

This is particularly interesting because in [20] the authors exhibit a class of axially symmetric functions *K* satisfying (H1), (H2), (H3), (H4) and with $(\mathbb{S}^2)^+$ contractible for which $(*)_{\rho_{geo}}$ does not admit solutions if m = 1, $\ell = 0$ and $\alpha_1 > 0$ (see the second picture in Figure 3). Of course this class of functions is different from the one considered in Theorem 1.10.

Again for $(\Sigma, g) = (\mathbb{S}^2, g_0)$, when m = 3 and N = 2 we obtain the following special case from Theorem 5.1.

Corollary 5.6 Let $p_1, p_2, p_3 \in \mathbb{S}^2$, $\overline{\xi} \in (\mathbb{S}^2 \setminus \{p_1, p_2, p_3\})^2 \setminus \Delta$ and $-1 < \alpha_{\star} \leq \alpha^{\star}$. Then for any $K \in \mathcal{K}^+_{\overline{k}, \alpha_{\star}, \alpha^*}$ there exists $\delta = \delta(\alpha_{\star}, \alpha^*, K) > 0$ such that if

$$\sum_{i=1}^{3} \alpha_i = 2 + \frac{\varepsilon}{4\pi} \quad \text{for } \varepsilon \in (0, \delta)$$
(5.18)

and moreover

$$\alpha_* \le \alpha_i \le \alpha^* \quad for \ all \ i = 1, 2, 3 \tag{5.19}$$

then $(*)_{\rho_{geo}}$ admits a solution with $\rho_{geo} = 16\pi + \varepsilon$.

Proof of Theorem 1.11 We just apply Corollary 5.6 for $\alpha_* = -\frac{1}{2}$, $\alpha^* = 3$ and fixing $\alpha_1 = \alpha_2 \in (-\frac{1}{3}, 0)$, so that $\alpha_3 = 2 - 2\alpha_1 + \frac{\varepsilon}{4\pi}$.



existence (Theorem 1.10) non-existence ([20])

 $\begin{array}{ll} m=1, \quad \ell=0\\ \alpha_1=\frac{\varepsilon}{4\pi}>0\\ N=1, \quad \bar{\pmb{\xi}}=-p_1, \quad K \text{ axially symmetric} \end{array}$

Fig. 3 (\mathbb{S}^2 , g_0), Σ^+ contractible, $\rho_{geo} = 8\pi + \varepsilon$

Remark 5.7 We emphasize that Theorem 1.11 assures the existence of a solution for $(*)_{\rho_{geo}}$ in a case when, if K is also positive, the Leray-Schauder degree of the equation $(*)_{\rho_{geo}}$ vanishes according to the formula in [15].

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