



Execution examination of chaotic S-box dependent on improved PSO algorithm

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Abstract

Achieving proper nonlinear properties and autocorrelation in the S-box structure is an open challenge in cryptography. Besides, there have been numerous articles on the optimization of S-box, using two types of fitness functions for optimization. This study investigated both types of functions and compares their performance. In addition, this study used ergodic chaotic maps. First, the performance of particle swarm optimization (PSO) was improved using these maps. Then, the new chaotic S-boxes were designed based on the ergodic maps. After that, the improved PSO was used for optimization to obtain the best S-boxes. This optimization was performed once by selecting nonlinearity as a fitness function. At the second optimization, the entropy source was selected as a fitness function for optimization by examining the *P*-value of the mono-test frequency. Finally, the related results for the introduced chaotic S-boxes were compared to the optimized chaotic S-boxes with two types of fitness functions. The introduced S-boxes were safe due to the use of ergodic maps with high keyspace length. Furthermore, the simulation performance was analyzed and compared with other relevant approaches.

Keywords Substitution boxes (S-boxes) · Chaotic maps · Particle swarm optimization · Nonlinearity · Mono-test frequency · Performance analysis

1 Introduction

Maintaining the security of information transmission is important given the significant advances in network communication technologies. A serious challenge in cryptosystems is designing of substitution boxes (S-boxes) [1]. S-box designs are proposed based on mathematical structures, a group of theoretic approach [2]. S-box, performing confusion, has been widely employed in traditional cryptographic standards such as the Data Encryption Standard (DES) [3] and the Advanced Encryption Standard (AES) [4] for encryption and decryption process. Considering that the previous designs still do not have the highest score for the good S-box criteria, it is necessary to create a new S-box structure. In order to determine how efficient the

S-box is, it has been examined in the form of a series of criteria such as nonlinearity (NL), linear approximation (LP), differential approximation (DP), strictly avalanche criteria (SAC), and bit independence criteria (BIC) [5, 6]. Therefore, if it reaches 120 in nonlinearity attacks [7], it will be one of the most ideal possible arrangements against nonlinearity attacks. The best-obtained value of SAC is 0.500 [8]. The best values so far obtained for BIC, LP, and DP are 112, 0.062, and 4, respectively [4]. Researchers have recently developed some algorithms for S-box design using the nonlinear properties of chaos. To use the chaotic space of nonlinear dynamic systems, a logistic map was used to design the S-box [9]. Subsequent studies have used maps such as three-dimensional Baker [8] or a combination of Baker and logistics [10] to develop the keyspace. Since hyper-chaotic systems have unique features, these systems were used in this article [11]. Studies on the use of chaos theory in the design of S-boxes have focused on the development of keyspace, and the use of chaotic boxes in nonlinear systems has not been considered in previous studies [12–18]. In ref. [19], the initial S-box was made with a spatiotemporal chaotic system, and then, its

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elements were randomly changed. The use of fractional derivatives as a superset of integer-order derivatives provides a more accurate description of natural phenomena [20–23]. Various applications of these derivatives have been found to solve problems such as mathematical biology [24–26], RC-electrical circuits [27], heat [28, 29], and fractal boundary value [30]. The fractional derivative of known equations such as the Fokker–Plank has better described the velocity of a particle in Brownian motion [31]. Solving nonlinear fractional models has been conducted even when the chaotic behavior has been studied [32–34]. Further, some attempts have been made to use the capabilities of fractional models combined with the chaotic properties of nonlinear systems to improve the designed S-boxes [35].

Optimization has been used to achieve stronger S-box. Optimization methods such as ant colony optimization [36], genetic algorithm optimization [37], firefly (FA) optimization [38], and teaching–learning-based optimization (TLBO) [39] have been used so far to increase the safety of designed S-boxes.

Russell Eberhart and James Kennedy (1995) devised particle swarm optimization [40]. PSO is a method based on swarm intelligence and solves optimization problems using optimized social behavior. The simplicity and simple implementation of PSO make it useful for signal processing and machine learning, neural networks, heat transfer, and so on [41–43]. In Ref. [44], one-dimensional and two-dimensional logistics and particle swarm optimization (PSO) were used to form the S-box. The random distribution capabilities of nonlinear dynamic systems can be used to reduce the required steps to achieve better results by the PSO method. Such a merger will improve the used PSO method [45].

Due to the increasing development of computational tools, it is necessary to review cryptographic methods and tools. The daily development of virtual network users has been accompanied by the need to increase key space. Considering the above-mentioned necessities, attention is paid to the forming and achieving of chaotic systems to meet these needs. Encryption algorithms with the help of S-box based on a strong chaotic system solve these problems while maintaining security. Increasing the complexity of the chaotic system used in the S-box has a significant effect on improving its criteria [46]. In order to improve the key space and the usable intervals of the map, another discrete map should be used to design the S-box.

In this study, the examples of Chebyshev polynomial of type one, two, their coupling, and hierarchy of rational-order maps were mentioned. Behavioral differences in these maps were used to improve PSO. Such differences can be seen again in the formation of the chaotic S-box. Finally, the performance of the produced chaotic S-boxes

was optimized using the best results of improved PSO with two types of fitness. This study aimed to look for the best results by reviewing the available fitness (objective) functions.

This study is organized as follows: Section 2 presents the model. Section 3 provides the improved PSO. Section 4 includes the design of the S-box. The S-box analysis is indicated in Sect. 5. The final section presents the conclusion.

2 The model

In the previous studies, the polynomial of chaotic maps is proposed [47–49]. The coupling of these maps will also increase the key space [50]. Such studies continued with the introduction of the hierarchy of rational-order chaotic maps from the same family of maps [51]. The above-mentioned maps are used in subsequent sections in the generation of improved PSO, chaotic S-box, and optimized chaotic S-box. The use of these ergodic maps increases the speed of achieving the desired model in the optimization.

2.1 One-parameter families of chaotic maps

The ratio of polynomials of degree N is considered as follows:

$$\Phi(x, \alpha) = \frac{\alpha^2 F}{1 + (\alpha^2 - 1)F},$$

where F can be substituted with the Chebyshev polynomial of type one for $\Phi_N^{(1)}$ and Chebyshev polynomial of type two for $\Phi_N^{(2)}$. It should be noted that for certain value, the formed polynomial of type two is reduced to the logistic map. Using the first and second types of Chebyshev functions will lead to different types by this polynomial. In addition, the sentences of the odd and even present distinct behaviors. The chaotic interval is for even N and the first type in $\alpha \in (0, N)$, while the second-type chaotic interval occurs in $\alpha \in (1/N, \infty)$ [47]. Besides, for odd N , the chaotic interval is observed in $\alpha \in (1/N, N)$.

The Kolmogorov–Sinai entropy and invariant measures of these maps are calculated in [47]. Three of these maps are given below:

$$\Phi_2^{(1)} = \frac{\alpha^2(2x - 1)^2}{4x(1 - x) + \alpha^2(2x - 1)^2}, \quad (1)$$

$$\Phi_2^{(2)} = \frac{4\alpha^2 x(1 - x)}{1 + 4(\alpha^2 - 1)x(1 - x)}, \quad (2)$$

$$\Phi_3^{(1,2)} = \frac{\alpha^2 x(4x - 3)^2}{\alpha^2 x(4x - 3)^2 + (1 - x)(4x - 1)^2}. \quad (3)$$

Figure 1 indicates the time series diagram of Chebyshev polynomial of type one and Chebyshev polynomial of type two. The sensitivity of the maps to the partial change of their initial values is seen in these figures. In all of three figures, the control parameter $\alpha = 0.75$ is set, and the initial condition changes. Figure 1.1 is plotted for $x_0 = 0.705$ and

$x_0 = 0.706$, indicating that despite a slight change in the initial value of x_0 , time series diagrams are obtained by a completely different way. Figure 1.2 is drawn for $x_0 = 0.307$ and $x_0 = 0.308$, and again with a slight change in the initial value of x_0 , we see two different time series charts. We plotted Fig. 1.3 for $x_0 = 0.88899$ and $x_0 = 0.88891$,

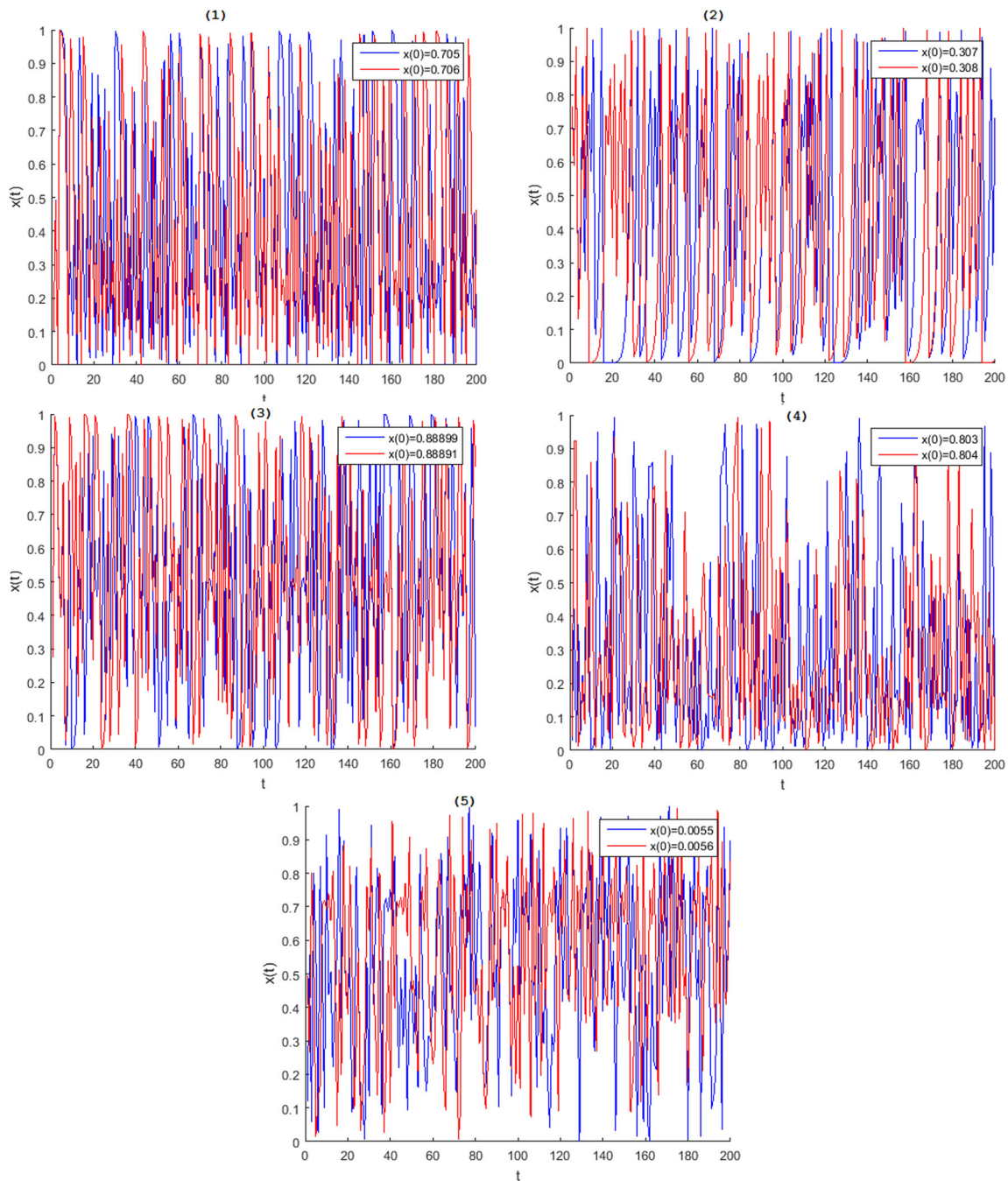


Fig. 1 The sensitivity of the chaotic map to initial conditions (1) $\Phi_2^{(1)}(x, \alpha)$ for $x_0 = 0.705$ and $x_0 = 0.706$, (2) $\Phi_2^{(2)}(x, \alpha)$ for $x_0 = 0.307$ and $x_0 = 0.308$, (3) $\Phi_3^{(1,2)}(x, \alpha)$ for $x_0 = 0.88899$ and $x_0 = 0.88891$ where the control parameter $\alpha = 0.75$, (4) the chaotic coupled map

lattices for $x_0 = 0.803$ and $x_0 = 0.804$ where the control parameter $a_1 = 1.5$, $a_2 = 2.4$, $N_1 = 6$, $N_2 = 10$, $\varepsilon = 0.4$ and $y_0 = 0.756$, (5) hierarchy of rational-order chaotic maps for $x_0 = 0.0055$ and $x_0 = 0.0056$ where the control parameter $a_1 = 2.61$ and $a_2 = 3.168$

where the difference between the time series charts for minor changes in x_0 is evident.

Dependence on control parameter is quantified by Lyapunov exponent. In other words, the Lyapunov exponent of the chaotic system shows that neighboring orbits are exponentially separated. Positive Lyapunov exponent shows the chaotic area of the parameter and the measurability of system. In addition, a possible way to describe the keyspace may be in terms of positive Lyapunov exponents [52]. Lyapunov exponent curves for the maps of Eqs. 1, 2, 3 are shown in Figs. 2(1,2,3), respectively. It was obvious that in the various maps, the chaotic domains were different.

2.2 The chaotic coupled map lattices

The chaotic coupled map lattices were introduced and used in cryptography [50]. The form of these maps is as follows:

$$\Phi_{coupled}(X_{n+1}, Y_{n+1}) = \begin{cases} X_{n+1} = (1 - \varepsilon)f_1(x_n) + \varepsilon f_2(y_n), \\ Y_{n+1} = (1 - \varepsilon)f_1(y_n) + \varepsilon f_2(x_n). \end{cases} \tag{4}$$

Here, the strength of the coupling is shown with ε . f_1 and f_2 are the chaotic trigonometric maps:

$$\begin{cases} f_1(x_n, a_1) = \frac{1}{a_1^2} \tan^2\left(N_1 \arctan\left(x_{n-1}^{\frac{1}{2}}\right)\right), \\ f_2(x_n, a_2) = \frac{1}{a_2^2} \cot^2\left(N_2 \arctan\left(x_{n-1}^{-\frac{1}{2}}\right)\right), \end{cases}$$

where a_1 and a_2 represent control parameters. Time series and Lyapunov exponent curve are shown in Figs. 1.4, 2.4, respectively. Figure 1.4 is plotted for constant parameter $a_1 = 1.5$, $a_2 = 2.4$, $N_1 = 6$, $N_2 = 10$, $\varepsilon = 0.4$ and $y_0 = 0.756$ as well as variable initial value $x_0 = 0.803$ and $x_0 = 0.804$.

2.3 Hierarchy of rational-order chaotic maps

Hierarchy of rational-order chaotic maps was introduced in [51]. Numerical results and analytical calculations for Lyapunov exponent and Kolmogorov–Sinai entropy were obtained [51]. An example of this maps is:

$$x_{n+1} = \frac{a_1}{a_2} \times \frac{1 - 3x_n^2}{3x_n - x_n^3} \pm \sqrt{1 + \left(\frac{a_1}{a_2} \times \frac{1 - 3x_n^2}{3x_n - x_n^3}\right)^2}, \tag{5}$$

where a_1 and a_2 represent control parameters. Figure 1.5 shows the corresponding time series diagram of dynamical system Eq. 5. Figure 1.5 is plotted for constant control parameter $a_1 = 2.61$ and $a_2 = 3.168$ as well as variable initial value $x_0 = 0.03$ and $x_0 = 0.030001$. Lyapunov exponent curve is shown in Fig. 2.5.

3 Improved PSO

Difficulty in well adjusting the global and local search capabilities and the possibility of being locked into stagnation are some of the problems that conventional PSO faces [53]. In order to solve this problem, the PSO algorithm was improved by chaotic behaviors. These algorithms included chaos initialization or updating step by chaotic map [45]. This section describes the PSO steps and how to use chaotic maps to determine its initial population and update its particle location and velocity. The best result of this section was used as an improved PSO for later designing of the S-box in sect. 4.

3.1 PSO algorithm

In PSO, the swarm comprises particles with position and speed, each one showing a possible solution in the optimization problems. PSO algorithms are divided into types such as the linearly decreasing inertia weight PSO (LDwPSO) [54], the nonlinearly decreasing inertia weight PSO [55], and chaotic inertia weight PSO [56], in terms of how the w parameter changes. This study used the linearly decreasing inertia weight PSO (LDwPSO). The steps of the PSO algorithm are as follows:

- Step 1 Defining the problem parameters
 Cost function, number of decision variables (for example:nVar = 10), size of decision variables matrix (for example:VarSize = [1 nVar]), lower bound of variables (for example:VarMin = -10;) and upper bound of variables (for example:VarMax = 10) is determined in this step.
- Step 2 Number the PSO Parameters
 Maximum number of iterations (for example:MaxIt = 1000), population size (for example:nPop = 100), inertia weight (for example:w = 1), inertia weight damping ratio (wdamp=0.99), personal learning coefficient (for example:c1 = 1.5), global learning coefficient (for example:c2 = 2.0) is determined.
- Step 3 Having initial population production using unifrnd function and call cost function for all primary particles and calculation of personal and global best for this population.

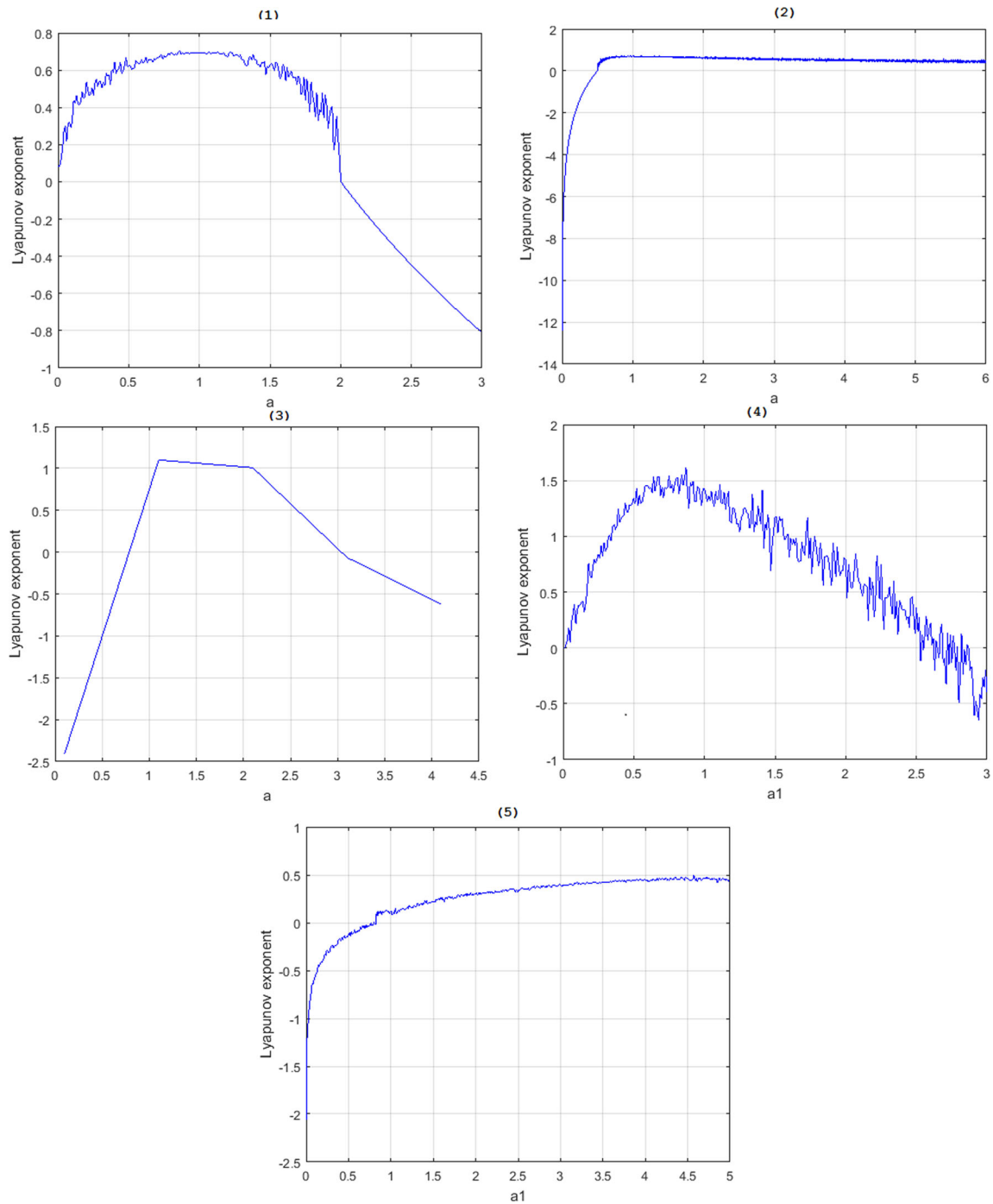


Fig. 2 The variation of the Lyapunov characteristic exponent (1) $\Phi_2^{(1)}(x, \alpha)$ in terms of parameters $a = \alpha$, (2) $\Phi_2^{(2)}(x, \alpha)$ in terms of parameters $a = \alpha$, (3) $\Phi_3^{(1,2)}(x, \alpha)$ in terms of parameters $a = \alpha$, (4) the

chaotic coupled map lattices in terms of parameters $a1$, (5) hierarchy of rational-order chaotic maps in terms of parameters $a1$

Step 4 Updating the speed and position of its j th dimension at iteration t of each particle i using the following relationships and local and global search to achieve the best solution.

$$V_{ij}(t + 1) = wV_{ij}(t) + (c1)(r1)(BestX_{ij}(t) - X_{ij}(t)) + (c2)(r2)(GlobalBest(t) - X_{ij}(t)), \tag{6}$$

$$X_{ij}(t + 1) = X_{ij}(t) + V_{ij}(t + 1), \tag{7}$$

where $V_{ij}(t)$ represents a velocity of particle i at iteration t ; $X_{ij}(t)$ represents a position of i particle at iteration t ; $r1$ and $r2$ indicate two random number between $(0,1)$; $BestX_{ij}(t)$ indicates the local best particle i in all swarm; and $GlobalBest(t)$ indicates the leader of the swarm or global best position of all population.

Well-known benchmark function (minimization) was used to test the effectiveness of the given algorithm. Sphere function is:

$$F_{Sphere} = \sum_{i=1}^n x_i^2,$$

where $-10 \leq x_i \leq 10$. The minimum of this function was zero. In optimization, the goal was to get a minimum or maximum of a function. Applying the PSO algorithm with 1000 repetitions reached the number 10^{-270} , which was very close to zero. The result for sphere cost function is shown in Fig. 3. As can be seen, cost function approached the minimum value of the sphere function as the iteration increased. In the next subsections, this study attempted to get a better number in the same repetitions. Since the minimum of the sphere function was zero, the better the optimization result, the closer it was to this minimum. PSO works with the production of the initial population to make the S-box perform better. In other words, it improves the S-box.

3.2 PSO initial population determination with chaotic map

All of the families of chaotic maps in Sect. 2 were used separately for the initialization value of PSO. These values for each map were selected based on their chaotic domain (positive Lyapunov exponent). Due to the similarity in quasi-code, this study included only one of them in this

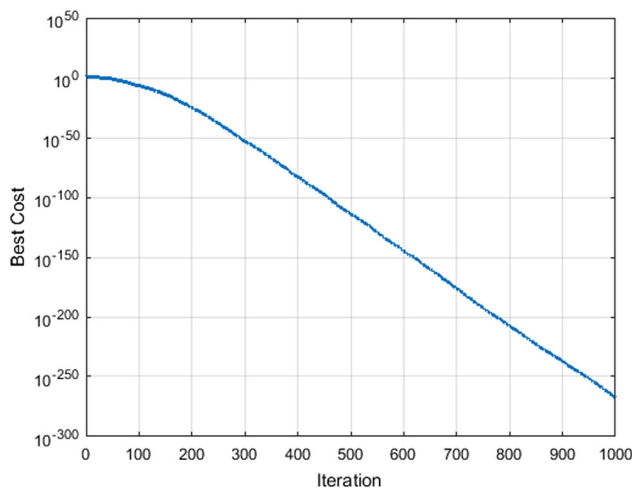


Fig. 3 The variation of the cost function (sphere) for PSO. This curve is plotted with number of decision variables ($nVar = 10$), lower bound of variables ($VarMin = -10$), upper bound of variables ($VarMax = 10$), maximum number of iterations ($MaxIt = 1000$), population size (for example: $nPop = 100$), inertia weight (for example: $w = 1$), inertia weight damping ratio ($wdamp = 0.99$), personal learning coefficient ($c1 = 1.5$), and global learning coefficient ($c2 = 2.0$)

section, while the recorded results were compared for all maps.

In this subsection, the values of X in Eqs. 1, 2, 3, 4 and 5 are normalized in the range $[0,1]$ to each decision variable in the n -dimensional space of optimization problem. By considering Lyapunov exponent curves, the parameters used here were $\alpha = 0.75$ for Eqs. 1, 2, 3, $N_1 = 6, N_2 = 10, a_1 = 1.5, a_2 = 2.4, \epsilon = 0.4$ for Eq. 4, and $a_1 = 2.61, a_2 = 3.168$ for Eq. 5. The function optimization problem with the continuous variable was defined as follows.

This study minimized $f(x)$ (cost function) by finding $X = [x_1, x_2, \dots, x_n]$. X represents the decision solution vector consisting of n variables, x_i , bounded by lower (L_i) and upper limits (U_i). PSO initial population determination procedure with chaotic map can be illustrated:

- Step 1 Entering the initial conditions chaotic map. Set $nPop = 100, x(1)$, for Eq. 1.
- Step 2 Initializing the particle swarm position X by map function by Eq. 1:

```

Input: the initial conditions and control parameters
of the chaotic map and number of random numbers required (N)
Output: vector of random numbers required
function Xn=map(x,\alpha,N)
Create random initial conditions (x0)
Xn = [];
for i = 1:10000
    Iterate chaotic map
end
for i = 1:N

    Iterate chaotic map

    Converting the generated numbers from iterating map to
    interval 0 and 1(x=mod(x,1);).

    Converting the generated numbers to interval lower bound of variables
    (for example:VarMin=-10;) and upper bound of variables
    (for example:VarMax= 10).

    Xn = [Xn x]
end
end

```

The results for all the maps are shown in Fig. 4. As can be seen in all figures, the use of a chaotic map instead of unifrnd function had no significant effect on the cost function.

Step 2 Performing chaotic search by updating of the speed and position of each particle by using a subfunction derived from Eqs. 1–5 instead of $r1$ and $r2$:

```

Input: the initial conditions and control parameters
of the chaotic map and number of random numbers required (N)
Output: vector of random numbers required
function Xn=nafis(x,\alpha,N)
Create random initial conditions (x0)
Xn = [];
for i = 1:100
    Iterate chaotic map
end
for i = 1:N

    Iterate chaotic map

    Convert the generated numbers from iterating map to
    interval 0 and 1 (x=mod(x,1);).

    Xn = [Xn x]
end
end

```

3.3 Updating velocity with chaotic maps in PSO

As mentioned in the initialization value, all of the proposed maps in Sect. 2 were used to update velocity of PSO.

Update velocity with chaotic maps in PSO is as follows:

Step 1 Entering the initial conditions chaotic map. Set $nPop = 100$, $MaxIt = 1000$, $x(1)$, for Eq. 1.

The results for all the maps are shown in Fig. 5. All curves tended to a minimum with increasing repetition. Their difference speed toward zero corresponded to the maps. Graph 5.5 reached the number 10^{-300} in the same repetitions of 1000. Hierarchy of rational-order chaotic maps reached the minimum with the least number of steps. As mentioned, Fig. 3 represents the variation in the cost function (sphere) for PSO. Compared to Fig. 5, the created

number for the cost function in the same repetitions of 1000 (graph 5) was better 10^{30} times.

4 The S-box design

Using chaos in the design of efficient S-boxes has been recently considered. This section describes the design of the S-box using the proposed chaotic maps. Then, these S-boxes are optimized by using improved PSO.

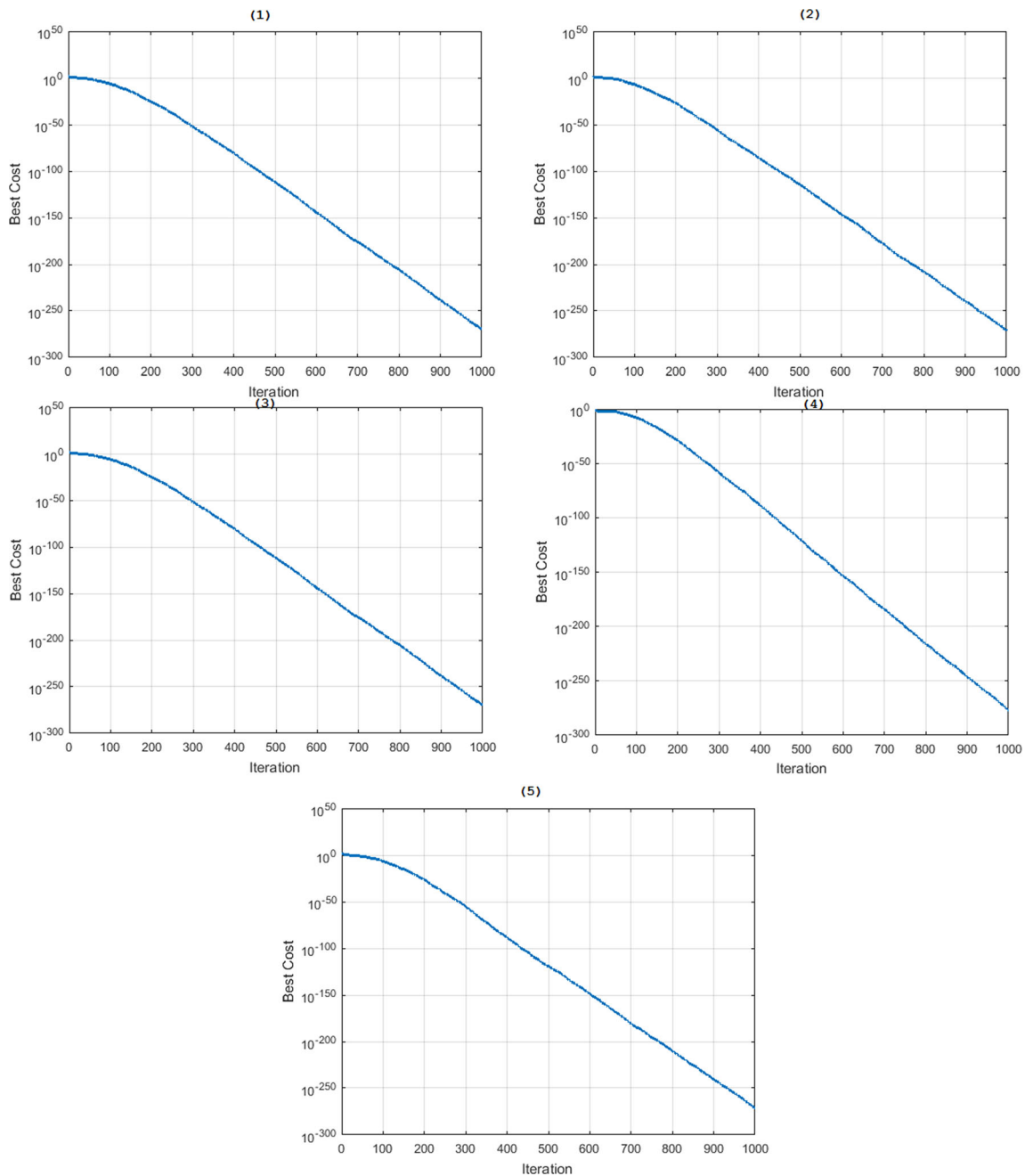


Fig. 4 The variation of the cost function (sphere) for (1) $\Phi_2^{(1)}(x, \alpha)$, (2) $\Phi_2^{(2)}(x, \alpha)$, (3) $\Phi_3^{(1,2)}(x, \alpha)$, (4) the chaotic coupled map lattices, (5) hierarchy of rational-order chaotic maps. These curves are plotted with number of decision variables($nVar = 10$), lower bound of variables($VarMin = -10$), upper bound of variables($VarMax = 10$),

Maximum number of iterations($MaxIt = 1000$), population size (for example: $nPop = 100$), inertia weight (for example: $w = 1$), inertia weight damping ratio($wdamp = 0.99$), personal learning coefficient($c1 = 1.5$) and global learning coefficient($c2 = 2.0$)

4.1 The chaotic S-box

Key is one of the fundamental pillars of any cryptography. Every algorithm is as secure as its key. For high levels of security, the key space size should not be less than 2^{100} [57, 58]. The keyspace provided by the introduced maps to produce the S-box was vast. The order of complexity for decoding in our proposed maps was calculated as follows:

- 1- for the Chebyshev polynomial

$$T(\alpha, x_0) = \theta(\alpha \times x_0),$$

- 2- for the maps of Eq. 4

$$T(N_1, N_2, a_1, a_2, \varepsilon, x_0, y_0) = \theta(N_1 \times N_2 \times a_1 \times a_2 \times \varepsilon \times x_0 \times y_0),$$

- 3- for the maps of Eq. 5

$$T(a_1, a_2, x_0) = \theta(a_1 \times a_2 \times x_0).$$

As an example in the Chebyshev polynomial of type one to determine the keyspace, the keyspace will be over than 10^{32} if the accuracy is 10^{-16} by considering the map interval (0, 1) and chaotic region of the control parameter (0,2).

This keyspace was affected by the chaotic range of control parameters and their number. This space is more than 10^{112} in the chaotic coupled map (Eq. 4) due to the increase in the number of control parameters ($x_0, y_0 \in (0, 1), \varepsilon \in (0, 1), a_1, a_2 \in (0.5, 2), N_1$ and N_2). Hierarchy of rational-order chaotic maps was examined in the same way.

These spaces could resist all types of brute-force attacks. The best keyspace was for the chaotic coupled map lattices (Eq. 4).

From the mathematical perspective, an $n * m$ S-box was a nonlinear mapping $S : V_n \rightarrow V_m$, where V_n and V_m represent the vector spaces of n, m elements from $GF(2)$. The steps for creating S-box are shown as follows:

- Step 1 Entering the initial conditions and control parameters by considering Lyapunov exponent curves (Fig. 2).
- Step 2 Repeating the map to 1000000 to pass the transition state.
- Step 3 Repeating the map to 700000 times and selecting the last number $x(f)$.
- Step 4 Getting the first S-box from the following equation.

$$S(1) = x(f) * 10^5 \text{ mod } 256$$
- Step 5 Repeating the map and selecting the last number $x(f)$.

- Step 6 The next S-box numbers were obtained from the following equation.

$$S(i) = x(f) * 10^5 \text{ mod } 256$$

- Step 7 If $S(i)$ is in the S-box, the process continues from step 5.
- Step 8 Putting the obtained $S(i)$ in the S-box table.
- Step 9 Repeating steps 5 through 8 until all 256 number S-boxes are filled.

The flowchart for creating S-box is shown in Fig. 6. Table 1 shows the best S-boxes generated from the maps of Eqs. 1, 2, 3, 4 and 5 presented in the model. This S-box is produced by the map of Eq. 3.

4.2 The chaotic S-box design with improved PSO

By considering the result of Sect. 3, this study improved PSO with the hierarchy of rational-order chaotic maps to optimize S-box. Various objective (fitness or cost) functions can be introduced in S-box optimization, including nonlinearity of the box and greater randomness of the box numbers. In this section, both cases are discussed in separate subsections.

4.2.1 The chaotic S-box design with improved PSO and nonlinearity fitness function

Many studies have considered nonlinearity as an objective function of optimization [37]. By considering this, the steps of the algorithm are as follows:

- Step 1 Entering initial conditions and control parameters related to the chaotic map of the objective function.
- Step 2 Entering improved PSO parameters.
- Step 3 Having initial population production using unifrnd function.
- Step 4 Creating of S-box with chaotic map (Sect. 4.1) and calculation of nonlinearity for all primary particles and calculation of personal and global best for this population.
- Step 5 Updating the speed and position of each particle using the hierarchy of rational-order chaotic maps and local and global search to achieve the best solution (subsection 3.3).
- Step 6 Saving the best nonlinearity and related S-box.

The flowchart for the optimized S-box design with improved PSO and nonlinearity fitness function is shown in Fig. 7. The results of all improved PSO algorithms for all

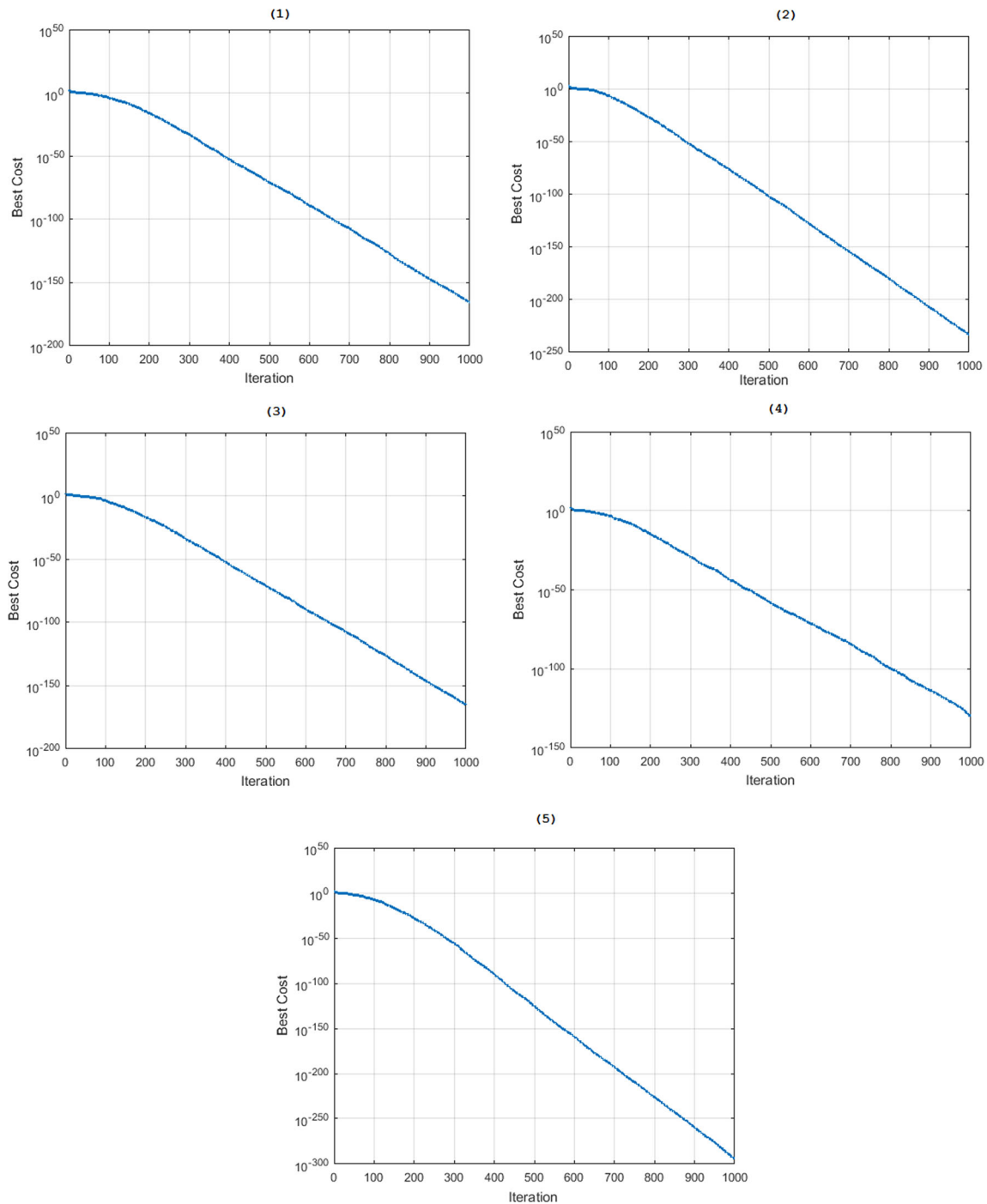


Fig. 5 The variation of the cost function (sphere) for (1) $\Phi_2^{(1)}(x, \alpha)$, (2) $\Phi_2^{(2)}(x, \alpha)$, (3) $\Phi_3^{(1,2)}(x, \alpha)$, (4) the chaotic coupled map lattices, (5) hierarchy of rational-order chaotic maps. These curves are plotted with number of decision variables($nVar = 10$), lower bound of variables($VarMin = -10$), upper bound of variables($VarMax = 10$),

maximum number of iterations($MaxIt = 1000$), population size (for example: $nPop = 100$), inertia weight (for example: $w = 1$), inertia weight damping ratio ($wdamp = 0.99$), personal learning coefficient($c1 = 1.5$), and global learning coefficient($c2 = 2.0$)

the formed S-boxes in Sect. 4.1 are given in Fig. 8. The best-created S-boxes are shown in Table 2. This S-box is produced by the map of Eq. 4.

Fig. 6 S-box creation algorithm

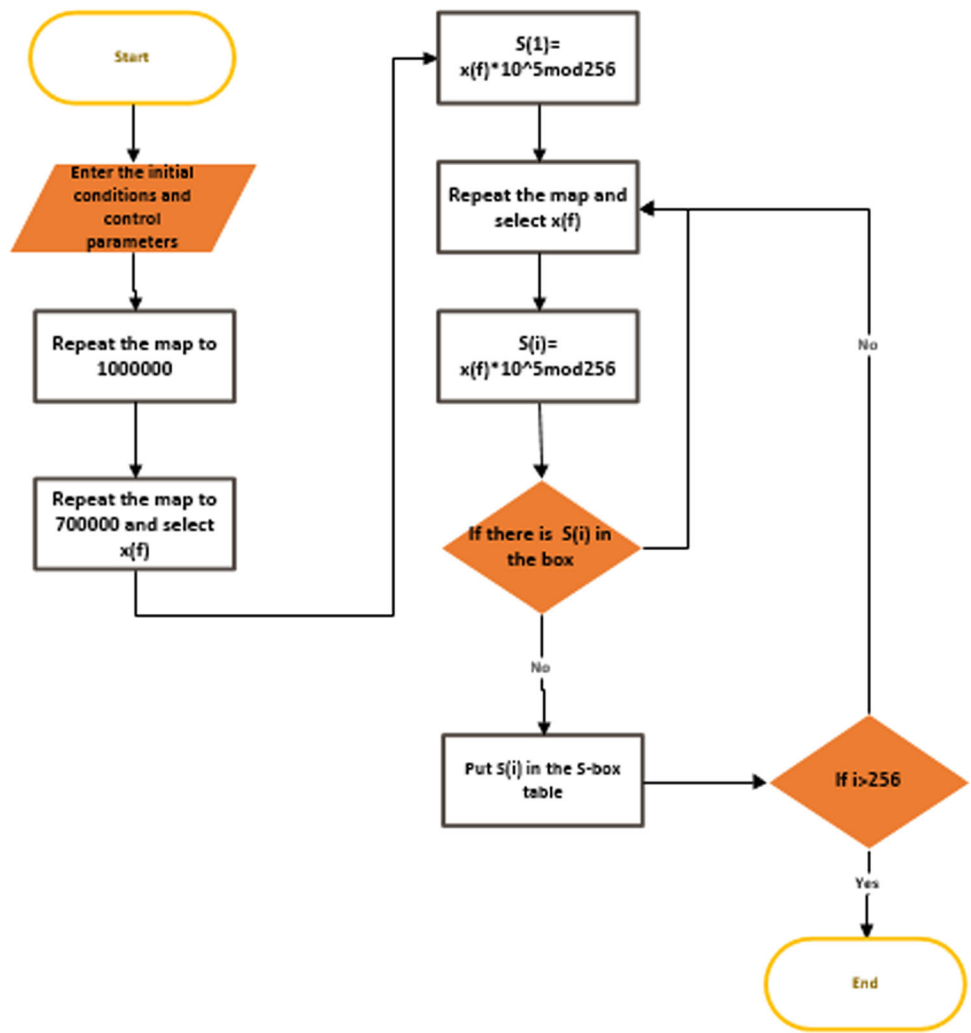


Table 1 Proposed S-box (16*16 matrix) from $\Phi_3^{(1,2)}(x, \alpha)$ in Eq. 3 for $\alpha = 0.75$,

50	18	92	216	167	118	57	64	103	235	27	86	72	197	213	232
46	204	153	14	199	246	194	130	47	44	79	24	211	196	220	20
171	137	143	222	203	248	239	243	138	125	156	17	255	174	185	132
73	100	116	84	215	12	173	210	37	177	91	74	60	198	52	139
5	66	161	96	122	111	81	136	172	170	49	42	113	146	99	48
183	95	1	151	140	227	160	195	226	157	85	71	206	148	128	182
256	230	11	39	207	9	225	158	212	97	15	168	217	114	119	62
93	205	36	34	51	188	35	228	250	251	26	56	190	134	112	75
218	124	149	117	135	223	141	200	166	101	238	90	89	120	147	76
159	55	192	25	187	245	229	63	176	202	88	152	67	6	247	244
19	186	241	32	53	221	165	191	214	13	123	3	10	115	110	129
163	133	87	219	175	107	83	208	145	164	82	7	94	142	69	68
45	240	109	254	249	155	121	16	40	54	169	2	233	224	65	231
8	150	189	80	236	98	162	179	105	58	178	181	4	180	21	30
77	234	127	43	59	22	78	29	144	104	33	41	23	70	201	193
184	108	106	31	131	126	252	154	237	38	209	242	253	61	102	28

4.2.2 The chaotic S-box design with improved PSO and mono-bit frequency test fitness function

Converting the outputs of the chaotic system to zero-one strings is one of the chaotic-based randomness production methods (entropy source) [59]. Here, six introduced maps are used to generate random numbers. The simplest and most effective ideals for statistical random measurement are the Chi-square test. The following formula was used to calculate:

$$\chi^2 = \frac{(n_0 - n_1)^2}{n},$$

where n_0 , n_1 represent the number of 0's and 1's in bit sequences, respectively [60]. This test is mono-bit frequency test. P -value was computed from the bit sequence

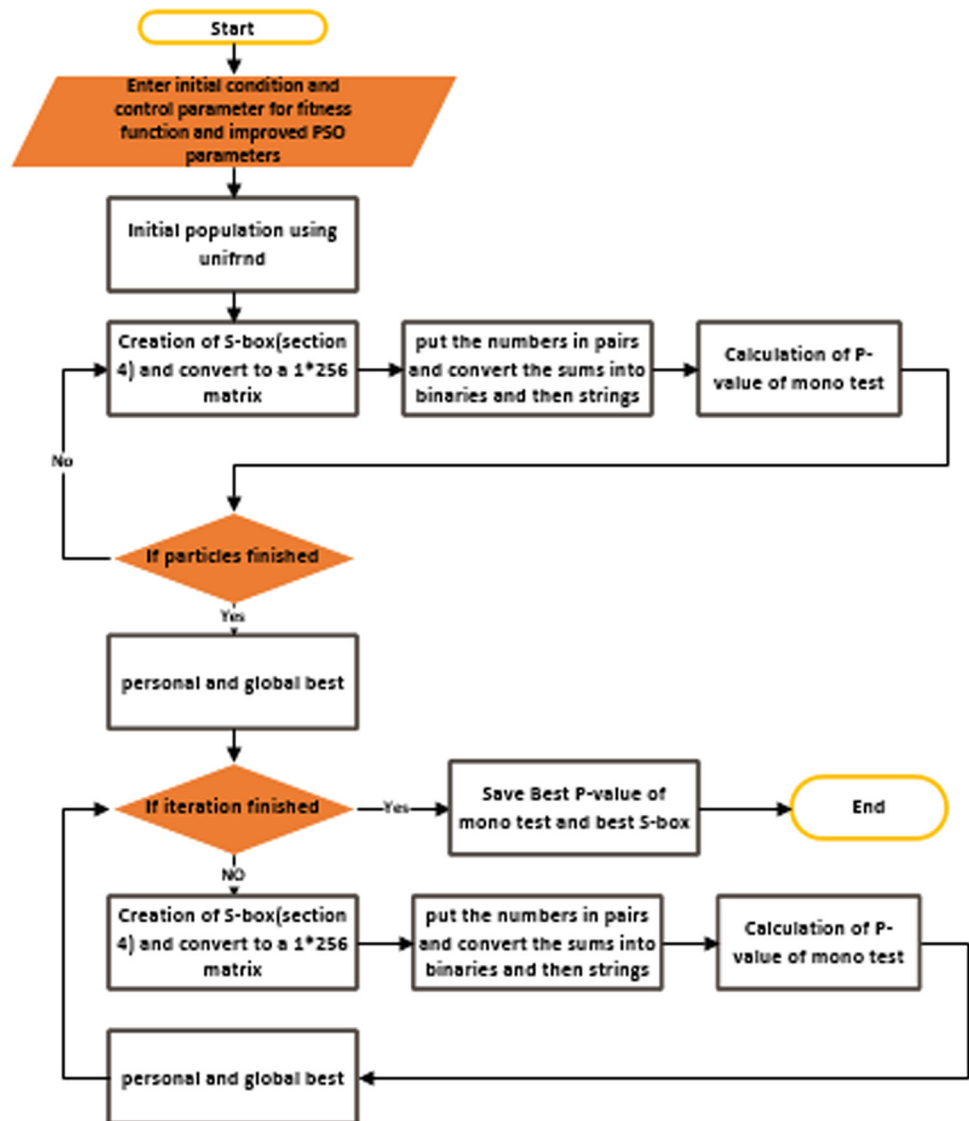
for this test. If the P -value is greater than a predefined threshold 0.01, then sequence will pass the test successfully. Here, like Reference [61], the mono-bit test was selected as the optimization objective function. The steps of the algorithm are as follows:

- Step 1 Entering initial conditions and control parameters related to the chaotic map of the objective (fitness) function.
- Step 2 Entering improved PSO parameters.
- Step 3 Having initial population production using unifrnd function.
- Step 4 Creating S-box with chaotic map (Sect. 4.1).
- Step 5 Having the generated S-box as a $16 * 16$ matrix. The rows were put together, and a $1 * 256$ matrix was obtained.

Fig. 7 Optimized S-box creation algorithm with nonlinearity fitness function



Fig. 8 Optimized S-box creation algorithm with P -value of mono-test fitness function



- Step 6 Putting the numbers in pairs and converting the sums into binaries and then strings.
- Step 7 Calculating mono-bit frequency test for all primary particles and calculation of personal and global best for this population.
- Step 8 Updating the speed and position of each particle using the hierarchy of rational-order chaotic maps and local and global search to achieve the best solution (subsection 3.3).
- Step 9 Saving the best P -value of mono-bit frequency test and related S-box.

The flowchart for the optimized S-box design with improved PSO and P -value of mono-bit frequency test (fitness function) is shown in Fig. 9. The results of all improved PSO optimizations for all the formed S-boxes in Sect. 4.1 are given in Fig. 10. The best-created S-box is

shown in Table 3. This S-box is produced by the map of Eq. 2.

5 The S-box analysis

Subsequently, the following important tests were applied to the generated S-box in Tables 1, 2, 3:

nonlinearity (NL), strict avalanche criterion (SAC), bit independence criterion (BIC), linear approximation probability (LP), and differential approximation probability (DP).

Table 2 Offered optimized S-box (16*16 matrix) from the chaotic coupled map lattices (Eq. 4) with nonlinearity fitness for $N_1 = 6, N_2 = 10, a_1 = 1.5, a_2 = 2.4, \varepsilon = 0.4$

162	179	253	51	43	256	236	93	230	221	227	56	67	63	4	60
176	155	90	52	42	97	50	166	27	147	152	29	45	233	83	31
18	13	40	111	239	199	214	119	238	153	118	91	224	55	150	177
114	151	106	66	127	87	128	196	8	164	172	124	209	6	149	48
250	144	30	20	223	16	235	245	163	255	69	3	158	184	92	193
173	178	213	34	129	187	9	215	12	17	80	38	204	243	191	241
248	108	154	32	64	109	217	156	19	142	170	136	226	62	251	82
123	203	88	202	195	103	102	110	2	14	161	37	249	26	240	130
33	116	89	229	115	59	122	21	107	200	120	133	145	49	72	212
141	7	254	185	125	5	207	206	197	171	53	79	126	134	190	1
218	225	183	39	15	68	169	70	85	10	11	105	231	139	232	188
222	100	132	186	112	138	47	84	180	71	131	46	194	73	65	101
77	148	205	44	41	137	198	244	104	146	220	135	247	94	86	181
242	23	113	182	117	210	24	157	35	121	61	57	143	192	96	54
160	78	98	167	175	234	189	174	252	74	22	246	95	165	208	168
58	36	159	211	216	25	99	81	201	76	75	237	140	28	228	219

5.1 Nonlinearity

The degree of linearity of the S-box was given by nonlinearity test. Since the affine functions were weak in terms of cryptography, the similarity of the Boolean function variable of S-box was measured with the affine variable. The nonlinearity value was calculated using the following equation:

$$N = 2^{n-1} - \frac{1}{2} \max_{a \in B^n} \left| \sum_{x \in B^n} (-1)^{f(x)+a \cdot x} \right|,$$

where $B = \{0, 1\}$, $f : B^n \rightarrow B$, $a \in B^n$ and $a \cdot x$ represents the dot product between a and x (see [62], for example). The highest theoretical limit of nonlinearity is 120 [7]. The best received value is 112 for the AES S-box [4]. For example, the nonlinearity of eight Boolean functions of offered optimized S-box for the map of Eq. 4 with nonlinearity fitness was 108, 104, 108, 106, 104, 108, 106, and 108. Therefore, the maximum and minimum and average values were 108, 104, and 106.5, respectively. This average was better than all the averages obtained with the chaotic S-box and their optimized S-box. The maximum and minimum and average values and comparing it with the results of previous work are given in Table 4.

5.2 Strict avalanche criterion (SAC)

Webster and Tavares introduced another important measure (as strict avalanche criterion) that describing when one bit in the input of Boolean function changed, half of

the output bits should be changed [1]. The dependence matrix for all the proposed S-boxes was calculated based on the reference [1] method. Table 5 shows that the minimum, maximum, and average values of dependence matrices. Further, comparing its results with the results of previous work is presented in this table. The best-obtained average value for SAC was 0.5. All obtained values for the proposed S-boxes were appropriate and very close to 0.500. The received value for the offered optimized S-box generated by the map of Eq. 5 with the P -value fitness (0.499512) was the best-obtained value. The dependence matrix of this S-box is given in Table 6. The results were confirmed and improved compared to previous method.

5.3 Bit independence criterion (BIC)

Webster and Tavares defined a desirable feature for any encryption transformation for S-box analysis, called the output bits independence criterion (BIC)[1]. The independence of the avalanche vectors sets was measured by the BIC. If one changed the inverse of input single bits, these sets would be created [63]. BIC-nonlinearity and BIC-SAC for all the proposed S-boxes were calculated based on the reference [1] method. Table 7 indicates the average values of BIC-nonlinearity and BIC-SAC. The numerical results of this test and comparing it with the results of previous work are depicted in Table 7. The amounts of BIC-nonlinearity and BIC-SAC were 112 and 0.5 for the AES S-box [4], which were the best-achieved values. The

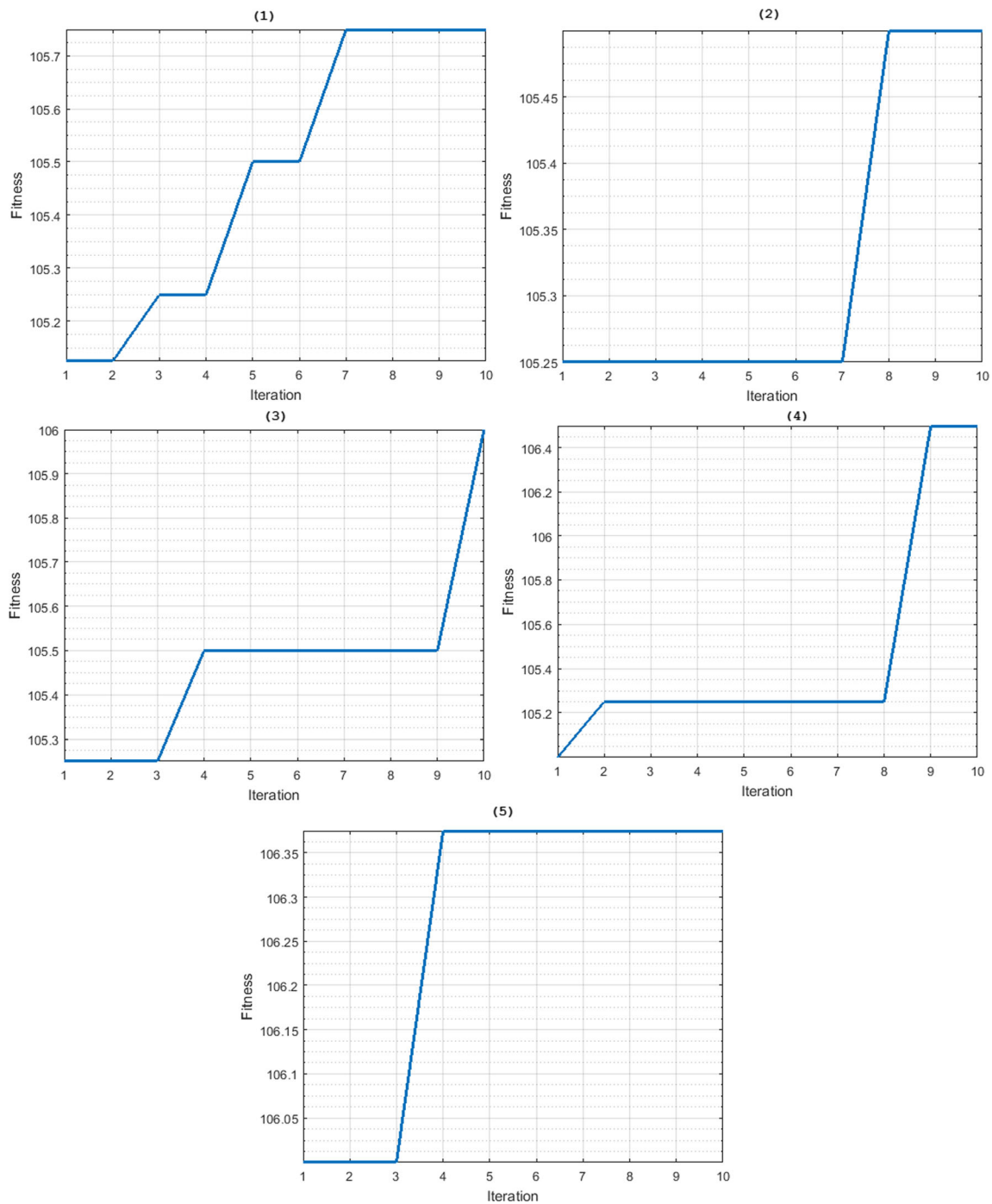


Fig. 9 Best nonlinearity of optimized S-box with nonlinearity fitness function for (1) $\Phi_2^{(1)}(x, \alpha)$ where $\alpha = 0.75$, (2) $\Phi_2^{(2)}(x, \alpha)$ for $\alpha = 0.75$, (3) $\Phi_3^{(1,2)}(x, \alpha)$ for $\alpha = 0.75$, (4) the chaotic coupled map lattices for $N_1 = 6, N_2 = 10, a_1 = 1.5, a_2 = 2.4, \varepsilon = 0.4$, (5) hierarchy of rational-order chaotic maps for $a_1 = 2.61, a_2 = 3.168$. Improved PSO based on hierarchy of rational-order chaotic maps for $a_1 = 2.61, a_2 = 3.168$ is used. Other optimization conditions are:

number of decision variables ($nVar = 9$), lower bound of variables ($VarMin = 90$), upper bound of variables ($VarMax = 120$), maximum number of iterations ($MaxIt = 10$), population size ($nPop = 9$), inertia weight ($w = 1$), inertia weight damping ratio ($wdamp = 0.99$), personal learning coefficient ($c1 = 1.5$), and global learning coefficient ($c2 = 2.0$)

obtained average values of BIC-nonlinearity for the proposed S-boxes were between 102.071 and 104.429. The best was for the chaotic coupled map lattices (Eq. 4), being

more than all of the obtained values in Table 7 references except for reference [39]. The best-obtained average value of BIC-SAC is 0.49986 for optimized S-box Chebyshev

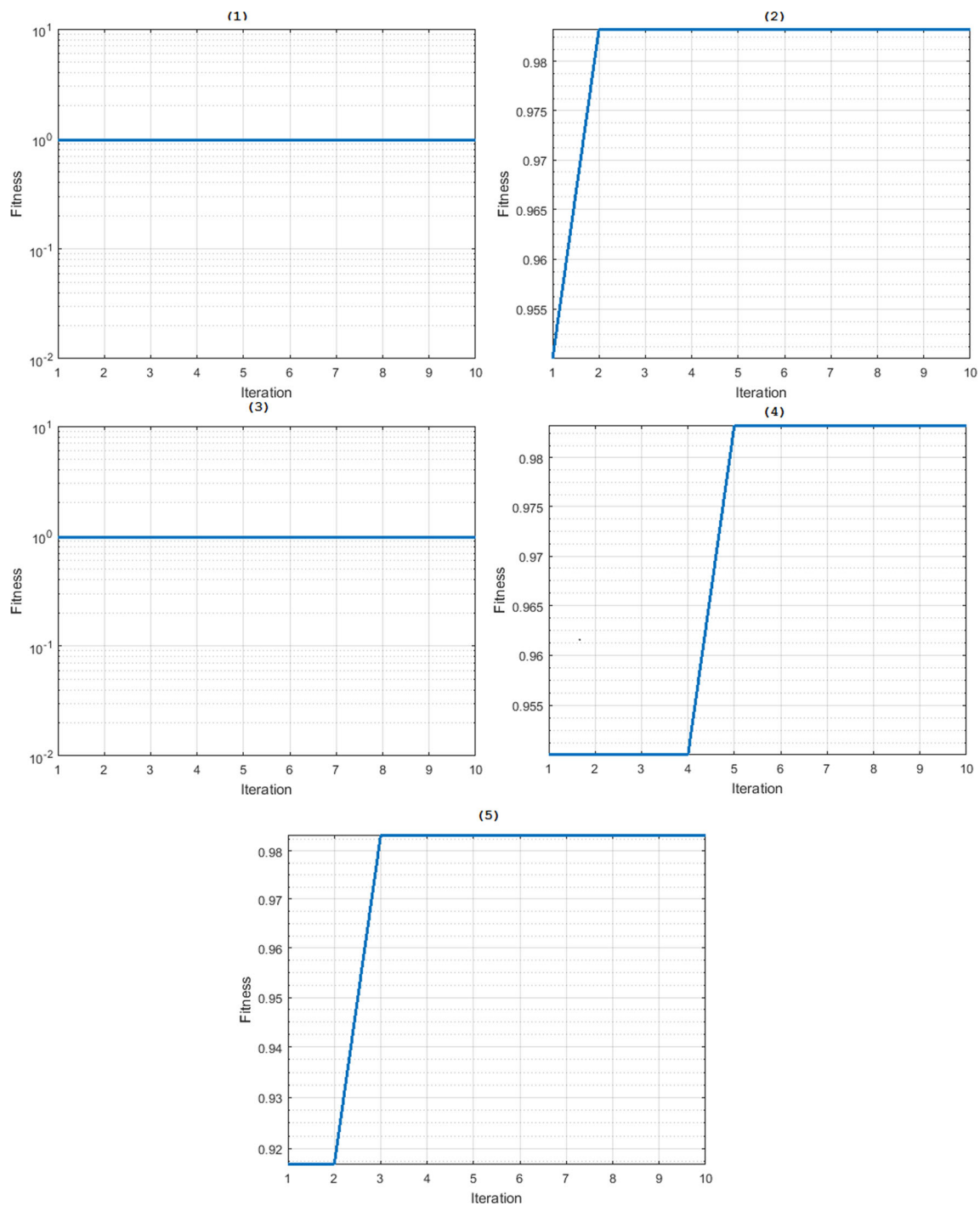


Fig. 10 Best P -value of optimized S-box with P -value of mono-test fitness function for (1) $\Phi_2^{(1)}(x, \alpha)$ where $\alpha = 0.75$, (2) $\Phi_2^{(2)}(x, \alpha)$ for $\alpha = 0.75$, (3) $\Phi_3^{(1,2)}(x, \alpha)$ for $\alpha = 0.75$, (4) the chaotic coupled map lattices for $N_1 = 6, N_2 = 10, a_1 = 1.5, a_2 = 2.4, \varepsilon = 0.4$, (5) hierarchy of rational-order chaotic maps for $a_1 = 2.61, a_2 = 3.168$. Improved PSO based on hierarchy of rational-order chaotic maps for $a_1 = 2.61, a_2 = 3.168$ is used. Other optimization conditions are:

polynomial of type odd (Eq. 3) with nonlinearity fitness. This value was more than all of the obtained values in

number of decision variables ($nVar = 9$), lower bound of variables ($VarMin = 0.01$), upper bound of variables ($VarMax = 1$), maximum number of iterations ($MaxIt = 10$), population size ($nPop = 9$), inertia weight ($w = 1$), inertia weight damping ratio ($wdamp = 0.99$), personal learning coefficient ($c1 = 1.5$), and global learning coefficient ($c2 = 2.0$)

Table 7 references. BIC-nonlinearity and BIC-SAC of best proposed S-boxes are given in Tables 8 and 9.

Table 3 Offered optimized S-box (16*16 matrix) from $\Phi_2^{(2)}(x, \alpha)$ in Eq. 2 with P -value of mono-test fitness function for $\alpha = 0.75$,

40	19	218	52	58	85	242	110	82	8	84	192	243	122	211	125
43	244	193	185	215	155	92	17	177	234	164	60	201	181	39	150
250	75	123	120	206	183	158	24	121	69	89	106	74	94	37	21
9	255	180	56	169	111	15	129	99	157	46	212	227	135	223	100
30	182	214	33	167	204	104	73	36	118	90	31	160	55	114	45
29	241	109	134	102	221	10	159	146	79	38	113	48	200	213	101
203	42	124	162	117	209	6	252	62	153	11	78	59	139	238	67
186	253	248	108	116	107	237	32	127	1	98	245	63	147	26	189
208	2	198	138	91	14	54	44	136	47	35	178	83	137	5	53
220	128	131	132	191	199	3	7	88	190	231	142	161	86	65	77
27	148	230	210	188	20	168	251	61	96	176	232	225	173	68	228
25	50	184	239	247	81	175	194	156	229	152	72	70	143	49	216
187	222	240	97	249	166	197	71	144	80	76	105	112	28	140	235
151	41	170	154	18	51	12	64	119	256	174	34	126	224	254	133
57	4	163	202	149	196	16	95	141	171	87	233	13	130	103	236
23	226	217	179	207	22	205	246	66	195	165	219	172	145	93	115

Table 4 Nonlinearity values of offered S-box. The nonlinearity of eight Boolean functions of each offered S-box is calculated, and minimum, maximum, and average of them are shown in the table

Nonlinearity	Min	Max	Avg
Offered S-box with Eq. 1	99	106	103.375
Offered S-box with Eq. 2	98	106	102.5
Offered S-box with Eq. 3	96	108	104.75
Offered S-box with Eq. 4	100	108	103.5
Offered S-box with Eq. 5	94	104	101.25
Offered optimized S-box with Eq. 1 (nonlinearity)	102	108	105.75
Offered optimized S-box with Eq. 2 (nonlinearity)	104	107	105.5
Offered optimized S-box with Eq. 3 (nonlinearity)	102	110	105.75
Offered optimized S-box with Eq. 4 (nonlinearity)	104	108	106.5
Offered optimized S-box with Eq. 5 (nonlinearity)	102	111	106.375
Offered optimized S-box with Eq. 1 (P -value)	96	108	104
Offered optimized S-box with Eq. 2 (P -value)	102	106	104.25
Offered optimized S-box with Eq. 3 (P -value)	92	109	102.625
Offered optimized S-box with Eq. 4 (P -value)	98	106	102.25
Offered optimized S-box with Eq. 5 (P -value)	100	108	103.25
In [9]	98	108	103.2
In [10]	99	106	103.4
In [8]	100	106	103
In [17]	96	106	103
In [39]	104	110	106.5
In [18]	100	109	104.2
In [66]	100	106	103.2
In [73]	102	108	105.2
In [67]	104	110	106
In [69]	104	110	106
In [70]	106	108	106.75
In [61]			106.75
In [71]			106
AES S-box ([4])	112	112	112

Table 5 SAC values of offered S-boxes. Minimum, maximum, and average values of dependence matrices are shown

SAC	Min	Max	Avg
Offered S-box with Eq. 1	0.40625	0.625	0.505859
Offered S-box with Eq. 2	0.390625	0.609375	0.49707
Offered S-box with Eq. 3	0.40625	0.609375	0.499023
Offered S-box with Eq. 4	0.40625	0.609375	0.509277
Offered S-box with Eq. 5	0.375	0.625	0.503906
Offered optimized S-box with Eq. 1 (nonlinearity)	0.4375	0.625	0.512451
Offered optimized S-box with Eq. 2 (nonlinearity)	0.414063	0.601563	0.496094
Offered optimized S-box with Eq. 3 (nonlinearity)	0.421875	0.578125	0.497559
Offered optimized S-box with Eq. 4 (nonlinearity)	0.40625	0.640625	0.503662
Offered optimized S-box with Eq. 5 (nonlinearity)	0.40625	0.601563	0.498291
Offered optimized S-box with Eq. 1 (<i>P</i> -value)	0.390625	0.578125	0.504395
Offered optimized S-box with Eq. 2 (<i>P</i> -value)	0.390625	0.578125	0.504639
Offered optimized S-box with Eq. 3 (<i>P</i> -value)	0.375	0.632813	0.49707
Offered optimized S-box with Eq. 4 (<i>P</i> -value)	0.421875	0.59375	0.497559
Offered optimized S-box with Eq. 5 (<i>P</i> -value)	0.390625	0.601563	0.499512
In [9]	0.3761	0.5975	0.5058
In [10]	0.4140	0.6015	0.4987
In [8]	0.4218	0.6093	0.5000
In [17]	0.3906	0.6250	0.5039
In [39]	0.4375	0.6406	0.5120
In [18]	0.3906	0.5703	0.4931
In [66]	0.4218	0.5938	0.5048
In [73]	0.4080	0.5894	0.5050
In [67]	0.4218	0.5937	0.5039
In [69]	0.4062	0.6093	0.5012
In [70]			0.4941
In [61]			0.5015
In [71]			0.52881
AES S-box ([4])	0.4531	0.5625	0.5048

Table 6 Dependence matrix of the offered optimized S-box for hierarchy of rational-order chaotic maps (Eq. 5) with the *P*-value fitness

0.484375	0.468750	0.546875	0.546875	0.578125	0.421875	0.546875	0.468750
0.453125	0.515625	0.437500	0.500000	0.484375	0.468750	0.515625	0.468750
0.453125	0.515625	0.562500	0.500000	0.484375	0.593750	0.390625	0.468750
0.562500	0.515625	0.562500	0.421875	0.500000	0.453125	0.484375	0.500000
0.453125	0.578125	0.500000	0.484375	0.515625	0.484375	0.515625	0.562500
0.500000	0.484375	0.546875	0.546875	0.500000	0.484375	0.531250	0.453125
0.468750	0.453125	0.453125	0.593750	0.515625	0.546875	0.500000	0.562500
0.453125	0.515625	0.500000	0.531250	0.562500	0.437500	0.437500	0.421875

5.4 Linear approximation probability (LP)

The maximum value of imbalance in the event between input and output bits is called the linear approximation probability (LP). Mathematical definition of LP [64] is:

$$LP = \max_{a,b \neq 0} \left| \frac{\#\{x|x.a = f(x).b\}}{2^n} - 0.5 \right|,$$

where *a*, *b* represent the input and output masks, and the set *x* contains all the possible inputs, and 2^n represents the number of its elements. If the S-box has low LP, it can resist linear attacks. The best LP results were from the AES S-box [4]. The LP obtained values were suitable for all suggested S-boxes. The most suitable value was for Chebyshev polynomial of type two (Eq. 2) and the hierarchy of rational-order chaotic maps (Eq. 5) (in optimized with *P*-value fitness). In addition, compared to previous works, it

Table 7 BIC values of offered S-boxes. These values are average

BIC	BIC-SAC	BIC-nonlinearity
Offered S-box with Eq. 1	0.503767	103.679
Offered S-box with Eq. 2	0.500767	103.5
Offered S-box with Eq. 3	0.498326	103.286
Offered S-box with Eq. 4	0.508022	104.429
Offered S-box with Eq. 5	0.501186	102.714
Offered optimized S-box with Eq. 1 (nonlinearity)	0.502651	102.857
Offered optimized S-box with Eq. 2 (nonlinearity)	0.504674	103.5
Offered optimized S-box with Eq. 3 (nonlinearity)	0.49986	103.214
Offered optimized S-box with Eq. 4 (nonlinearity)	0.499512	102.857
Offered optimized S-box with Eq. 5 (nonlinearity)	0.499721	103.893
Offered optimized S-box with Eq. 1 (P-value)	0.498954	103.857
Offered optimized S-box with Eq. 2 (P-value)	0.501046	102.071
Offered optimized S-box with Eq. 3 (P-value)	0.495466	102.964
Offered optimized S-box with Eq. 4 (P-value)	0.506766	103.643
Offered optimized S-box with Eq. 5 (P-value)	0.503976	103.786
In [9]	0.5031	104.2
In [10]	0.4995	103.3
In [8]	0.5024	103.1
In [17]	0.5010	100.3
In [39]	0.4983	104.57
In [18]	0.4988	103.3
In [66]	0.5009	103.7
In [73]	0.5053	104.2
In [67]	0.5058	103.4
In [69]	0.5003	103.5
In [70]	0.4957	103.5
In [61]	0.5029	104.07
In [71]		100
AES S-box ([4])		112

Table 8 BIC-nonlinearity criterion for the offered S-box for the chaotic coupled map lattices (Eq. 4)

–	106	104	106	108	108	104	104
106	–	96	108	102	102	104	98
104	96	–	108	106	108	106	106
106	108	108	–	102	100	104	104
108	102	106	102	–	102	106	106
108	102	108	100	102	–	106	106
104	104	106	104	106	106	–	104
104	98	106	104	106	106	104	–

was less than references [8, 10, 18, 39, 65, 66], and [67] and similar to reference [17]. Table 10 shows the numerical results and compares the results of previous work.

5.5 Differential approximation probability (DP)

Biham and Shamir introduced a differential cryptanalysis method [68]. This method calculated XOR distribution between input and output bits of S-box was called DP. If this distribution is close between the input and output bits, S-box will be resistant to differential attacks. DP is defined as follows:

$$DP = \max_{\Delta_x \neq 0, \Delta_y} (\#x \in X, f_x \oplus f(x + \Delta_x) = \Delta_y / 2^n),$$

where X shows the set of all possible input values, and 2^n represents the number of its elements. The DP value for a strong S-box should be close to zero. The best result (DP = 4) was for AES S-box [4]. All of the obtained values were suitable for the introduced S-boxes. The best DP (10) was for the chaotic coupled map lattices (Eq. 4) (in all recommended S-boxes) and Chebyshev polynomial of type two and hierarchy of rational-order chaotic maps (Eq. 5) (in both optimized modes) and Chebyshev

Table 9 BIC-SAC criteria for the offered optimized S-box for $\phi_3^{(1,2)}(x, \alpha)$ in Eq. 3 with nonlinearity fitness

–	0.488281	0.511719	0.500000	0.507813	0.500000	0.482422	0.498047
0.488281	–	0.507813	0.519531	0.484375	0.498047	0.488281	0.513672
0.511719	0.507813	–	0.515625	0.521484	0.478516	0.507813	0.482422
0.500000	0.519531	0.515625	–	0.470703	0.521484	0.517578	0.511719
0.507813	0.484375	0.521484	0.470703	–	0.507813	0.490234	0.478516
0.500000	0.498047	0.478516	0.521484	0.507813	–	0.492188	0.498047
0.482422	0.488281	0.507813	0.517578	0.490234	0.492188	–	0.501953
0.498047	0.513672	0.482422	0.511719	0.478516	0.498047	0.501953	–

Table 10 LP values of offered S-boxes

LP	Max
Offered S-box with Eq. 1	0.128906
Offered S-box with Eq. 2	0.140625
Offered S-box with Eq. 3	0.15625
Offered S-box with Eq. 4	0.132813
Offered S-box with Eq. 5	0.132813
Offered optimized S-box with Eq. 1 (nonlinearity)	0.15625
Offered optimized S-box with Eq. 2 (nonlinearity)	0.132813
Offered optimized S-box with Eq. 3 (nonlinearity)	0.132813
Offered optimized S-box with Eq. 4 (nonlinearity)	0.140625
Offered optimized S-box with Eq. 5 (nonlinearity)	0.140625
Offered optimized S-box with Eq. 1 (P-value)	0.140625
Offered optimized S-box with Eq. 2 (P-value)	0.125
Offered optimized S-box with Eq. 3 (P-value)	0.140625
Offered optimized S-box with Eq. 4 (P-value)	0.140625
Offered optimized S-box with Eq. 5 (P-value)	0.125
In [65]	0.1328
In [10]	0.1328
In [39]	0.132813
In [66]	0.1289
In [17]	0.1250
In [18]	0.1563
In [8]	0.1289
In [73]	0.1172
In [67]	0.1406
In [70]	0.1172
AES S-box ([4])	0.062

Table 11 DP values of offered S-boxes

	DP
Offered S-box with Eq. 1	12
Offered S-box with Eq. 2	12
Offered S-box with Eq. 3	12
Offered S-box with Eq. 4	10
Offered S-box with Eq. 5	14
Offered optimized S-box with Eq. 1 (nonlinearity)	12
Offered optimized S-box with Eq. 2 (nonlinearity)	10
Offered optimized S-box with Eq. 3 (nonlinearity)	12
Offered optimized S-box with Eq. 4 (nonlinearity)	10
Offered optimized S-box with Eq. 5 (nonlinearity)	10
Offered optimized S-box with Eq. 1 (P-value)	10
Offered optimized S-box with Eq. 2 (P-value)	10
Offered optimized S-box with Eq. 3 (P-value)	12
Offered optimized S-box with Eq. 4 (P-value)	10
Offered optimized S-box with Eq. 5 (P-value)	10
In [9]	12
In [10]	10
In [8]	14
In [17]	12
In [39]	10
In [18]	12
In [66]	10
In [73]	12
In [67]	10
In [69]	10
In [70]	10
In [61]	10
In [71]	10
AES S-box ([4])	4

polynomial of type one (Eq. 1) (in optimized with P-value fitness). Compared to the previous work, this result was similar to references [10, 39, 61, 66, 67, 69, 70] and [71]. Table 11 represents DP results for proposed S-boxes and compares the results of previous work.

6 Concluding remarks

S-boxes aim to provide the necessary confusion that Shannon is declared as the foundations of any cipher system. This study proposed a new methodology for designing S-box by introducing strong chaotic maps. In addition, it improved PSO with this map. Improved PSO results have

been used to optimize chaotic S-boxes. This optimization was conducted with two fitness functions (nonlinearity and P -value of mono-test). This study considered the hierarchy of trigonometric maps with their composition. This family of chaotic maps has ergodic properties. Ergodicity is equivalent to the confusion property. The study incorporated in this study is enabled to open new ways in the construction S-boxes based on strong chaotic maps and improved PSO. The best chaotic S-box (Table 1) was obtained using Eq. 3 maps. Considering the results of Tables 4, 5, 6, 7, 8 for the S-boxes of Tables 2 and 3, it is better to use nonlinearity fitness function optimization. Testing the P -value was related to the randomness of the box, perhaps with considering reference [72], it needed to reexamine the chaotic property of the S-box. As future work, multi-objective particle swarm optimization (MOPSO) can be used instead of PSO for improved optimization, so that in addition to nonlinearity, all S-box analysis criteria can be optimized. Future studies can even use other optimizations, such as harmony search (HS) algorithm. Furthermore, the use of a series of Julia sets based on generalized Chebyshev polynomial of type two or quantum maps from well-known quantum systems such as the Dicke model leads to the production of S-boxes with various performances.

In future, we intend to examine the effect of this dynamic behavior on the generation of the S-box and will compare it with classical maps. Failure to meet the S-boxes ideal criteria indicates the need to create new S-boxes.

Compliance with ethical standards

Conflict of interest The authors declare that they have no conflict of interest.

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