

On stratified variable thermal conductivity stretched flow of Walter-B material subject to non-Fourier flux theory

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Received: 30 November 2016 / Accepted: 11 April 2017 / Published online: 3 May 2017
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Abstract The objective here is to examine the characteristics of non-Fourier flux theory in flow induced by a nonlinear stretched surface. Constitutive expression for an incompressible Walter-B liquid is taken into account. Consideration of thermal stratification and variable thermal conductivity characterizes the heat transfer process. The concept of boundary layer is adopted for the formulation purpose. Modern methodology for the computational process is implemented. Surface drag force is computed and discussed. Salient features of significant variables on the physical quantities are reported graphically. It is explored that velocity is enhanced for a larger ratio of rate constants. The increasing values of thermal relaxation factor correspond to less temperature.

Keywords Thermal stratification · Walter-B material · Non-Fourier flux theory · Stagnation point flow · Variable thermal conductivity

1 Introduction

An impressive consideration has been given to heat conduction [1–3] because of its ample applications in several fields. The traditional one-dimensional (1D) fundamental model to characterize heat conduction is analyzed through Fourier's

relation [4]. This yields an approach to analyze heat conduction and develops the foundation to investigate the thermal process of heat transfer in recent years. However, an ambiguity of Fourier's model [5–7] is that the whole structure is affected directly by the original disruption. Such behavior disprove the causality principle [8, 9] through heat conduction paradox. Cattaneo [10] recommended a generalized model which yields the relaxation factor into account. The Cattaneo basic expression only comprises partial time derivatives whereas larger spatial gradients might be needed [11] for the entire process. Hence, modifying the "time derivative" by "Oldroyds' upper-convected derivative," Christov [12] recommended the frame-indifferent modification of the Cattaneo expression:

$$\mathbf{q} + \lambda \left(\frac{\partial \mathbf{q}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{q} - \mathbf{q} \cdot \nabla \mathbf{v} + (\nabla \cdot \mathbf{v}) \mathbf{q} \right) = -k \text{grad} T.$$

Here $(\mathbf{q}, \lambda, \mathbf{v}, k, T)$ indicate heat flux, thermal relaxation parameter, velocity, thermal conductivity, and temperature, respectively. The aforementioned expression justifies objectivity principle and fascinates the attention of recent investigators [13–25].

Fluid flow and heat transport characteristics over a flat or stretched surface have turned to be the ground of great importance due to their numerous applications in plastic and rubber sheet manufacturing, filaments and polymer sheets, glass blowing, etc. Stretching flow towards a flat surface is firstly explored by Crane [26]. Moreover, plates in usage with variable thickness are utilized in marine and aeronautical configurations and mechanical and civil engineering. For reliable and effective design, it is essential to consider buckling loads for these plates. No doubt the usage of variable thickness supports to decrease the load of mechanical elements and develop the effectiveness of

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materials [27]. Few studies comprising the simultaneous characteristics of variable thickness and heat transfer can be found in the attempts [28–32].

Although required in definite utilizations, thermal stratification influences the performance of the condenser and could be destructive for structural reliability of the pool walls prepared through concrete. Analysis on rigidly stratified medium demonstrates that stationary regions are energetic at the boundary of cold and hot water, which minimizes the service lifetime of plants and several demanding components [33]. For instance, the blight heat elimination process in fast devices encounters the phenomenon of stratification at relatively high temperature producing exhaustion in nuclear mechanisms. Thus, from the structural security opinion as well, stratified coolant aspects are significant [34]. Representative studies on thermal stratification are given in [35–37]. Moreover, the ability of a substance to control heat is recognized as thermal conductivity. It is either constant or differs with temperature linearly for liquid metals from 0 to 400 °F [38]. Representative investigations regarding this topic can be mentioned through [39–42] and several studies therein.

The current investigation intends to analyze the non-Fourier flux characteristics in flow of Walter-B material over the surface with variable thickness. Stagnation velocity is considered nonlinear. Heat transfer in the presence of thermal stratification and temperature-dependent thermal conductivity is analyzed. A homotopic algorithm [43–50] is utilized to obtain convergent expressions. Graphical trends for several significant variables versus velocity and temperature fields are discussed in detail.

2 Formulation

Here steady two-dimensional stagnation point flow of Walter-B material towards a surface moving with nonlinear velocity is modeled. A stretching surface of variable thickness generates the flow. Heat transfer via non-Fourier flux theory is investigated. Thermal stratification along with temperature-dependent thermal conductivity is retained. Viscous dissipation effects are not accounted. The governing equations are

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0, \tag{1}$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = U_e \frac{dU_e}{dx} + \frac{\mu_0}{\rho} \left(\frac{\partial^2 u}{\partial y^2} \right) - \frac{k_0}{\rho} \left(\frac{u \frac{\partial^3 u}{\partial x \partial y^2} + v \frac{\partial^3 u}{\partial y^3}}{-\frac{\partial u}{\partial y} \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial v}{\partial y} \frac{\partial^2 u}{\partial y^2}} \right), \tag{2}$$

$$\begin{aligned} u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} + \lambda \left(u \frac{\partial u}{\partial x} \frac{\partial T}{\partial x} + v \frac{\partial v}{\partial y} \frac{\partial T}{\partial y} + u \frac{\partial v}{\partial x} \frac{\partial T}{\partial y} + v \frac{\partial u}{\partial y} \frac{\partial T}{\partial x} \right) \\ + 2uv \frac{\partial^2 T}{\partial x \partial y} + u^2 \frac{\partial^2 T}{\partial x^2} + v^2 \frac{\partial^2 T}{\partial y^2} \\ = \frac{1}{\rho c_p} \frac{\partial}{\partial y} \left(k(T) \frac{\partial T}{\partial y} \right), \end{aligned} \tag{3}$$

$$\begin{aligned} u = U_w(x) = U_0(x + b)^n, v = 0, T = T_w \\ = T_0 + c(x + b) \text{ at } y = A_1(x + b)^{\frac{1-n}{2}}, \\ u \rightarrow U_e(x) = U_\infty(x + b)^n, T \rightarrow T_\infty = T_0 + d(x + b) \text{ when } y \rightarrow \infty. \end{aligned} \tag{4}$$

Here (u, v) specify the liquid velocities parallel to horizontal and vertical directions, $\nu = \left(\frac{\mu}{\rho}\right)$ the kinematic viscosity, ρ the fluid density, (k_0, μ_0) the short memory coefficient and restricting viscosity at low shear rate, $(U_w(x), U_e(x))$ the stretching and free stream velocities, (T, T_∞) the fluid and ambient fluid temperature, (U_0) the reference velocity, (b, c, d) the dimensional constants, A_1 the small variable with respect to the surface is adequately thin, and $k(T)$ the temperature-dependent thermal conductivity, which is given as [20]

$$k(T) = k_\infty \left(1 + \varepsilon \frac{T - T_\infty}{\nabla T} \right). \tag{6}$$

Here, ambient fluid thermal conductivity is denoted by k_∞ , ε is the small parameter which characterizes the behavior of temperature on thermal conductivity and $\nabla T = T - T_0$. Also, the type of motion, surface shape and characteristics of the boundary layer can be controlled through the parameter n . It is worth pointing that the present analysis reduced to a surface with growing thickness and convex outer shape, whereas the analysis converted to a surface with growing thickness and convex outer shape when $n < 1$. Also, for $n = 0$, the motion is reduced to a linear case with constant velocity. Considering [16],

$$\begin{aligned} \psi = \sqrt{\frac{2}{n+1}} \nu U_0 (x + b)^{n+1} F(\xi), \xi = \sqrt{\frac{n+1}{2}} \frac{U_0}{\nu} (x + b)^{n-1} y, u = U_0 (x + b)^n F'(\xi), \\ v = -\sqrt{\frac{n+1}{2}} \nu U_0 (x + b)^{n-1} \left(F(\xi) + \eta \frac{n-1}{n+1} F'(\xi) \right), \Theta(\xi) = \frac{T - T_\infty}{T_w - T_0}, \end{aligned} \tag{7}$$

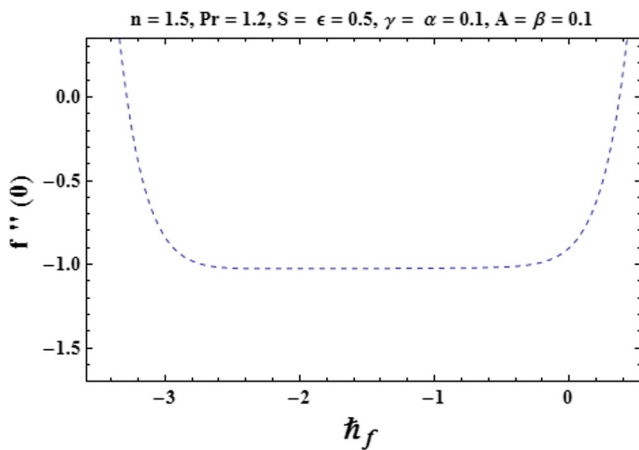


Fig. 1 h -curve for f

the continuity equation ((1)) is fulfilled automatically and the emerging nonlinear problems in F and Θ are

$$F''' - \frac{2n}{n+1} F'^2 + FF'' + \beta \left(\frac{3n-1}{2} F'^2 - (3n-1) F' F'' + \frac{n+1}{2} FF'' \right) + \frac{2n}{n+1} A^2 = 0, \tag{8}$$

$$(1 + \varepsilon\Theta) \Theta'' + \varepsilon\Theta'^2 + \text{Pr}F\Theta' + \text{Pr}\gamma \left(\frac{n-3}{2} FF'\Theta' - \frac{n+1}{2} F^2\Theta'' \right) + \text{Pr}(S + \Theta) \left(-\frac{2n}{n+1} \gamma F'^2 - \frac{2}{n+1} F' \right) = 0, \tag{9}$$

$$F(\alpha) = \alpha \frac{1-n}{1+n}, F'(\alpha) = 1, F'(\infty) = A, \tag{10}$$

$$\Theta(\alpha) = 1-S, \Theta(\infty) = 0. \tag{11}$$

Here, prime signifies differentiation with respect to ξ and $\alpha = A_1 \sqrt{\frac{n+1}{2} \frac{U_0}{\nu}}$. Letting $F(\xi) = f(\xi - \alpha) = f(\eta)$ and $\Theta(\xi) = \theta(\xi$

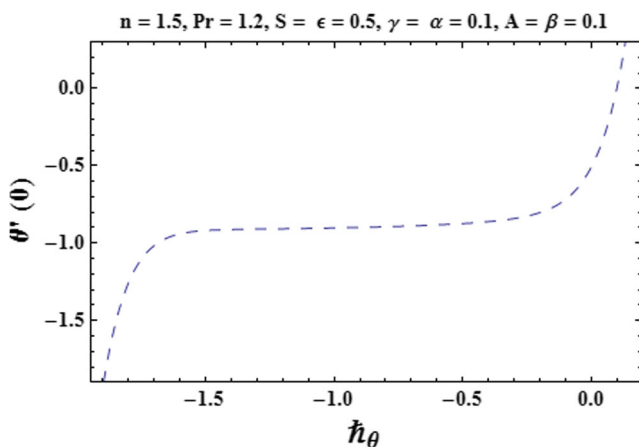


Fig. 2 h -curve for θ

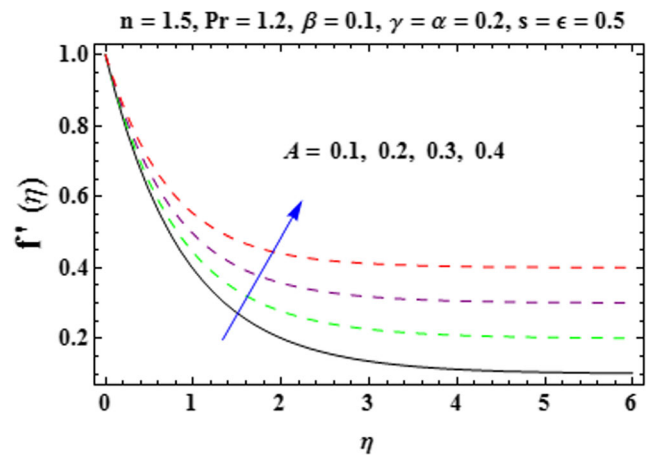


Fig. 3 A variation on f

$-\alpha) = \theta(\eta)$, Eqs. (8)–(11) yield

$$f''' - \frac{2n}{n+1} f'^2 + ff'' + \beta \left(\frac{3n-1}{2} f'^2 - (3n-1) f' f'' + \frac{n+1}{2} ff'' \right) + \frac{2n}{n+1} A^2 = 0, \tag{12}$$

$$(1 + \varepsilon\theta) \theta'' + \varepsilon\theta'^2 + \text{Pr}f\theta' + \text{Pr}\gamma \left(\frac{n-3}{2} ff'\theta' - \frac{n+1}{2} f^2\theta'' \right) + \text{Pr}(S + \theta) \left(-\frac{2n}{n+1} \gamma f'^2 - \frac{2}{n+1} f' \right) = 0, \tag{13}$$

$$f(0) = \alpha \frac{1-n}{1+n}, f'(0) = 1, f'(\infty) = A, \tag{14}$$

$$\theta(0) = 1-S, \theta(\infty) = 0, \tag{15}$$

where $A \left(= \frac{U_\infty}{U_0} \right)$ represents the ratio of velocities, $\text{Pr} \left(= \frac{\mu c_p}{k} \right)$ the Prandtl number, $\beta \left(= \frac{k_0 U_0 (x+b)^{n-1}}{\mu_0} \right)$ the local

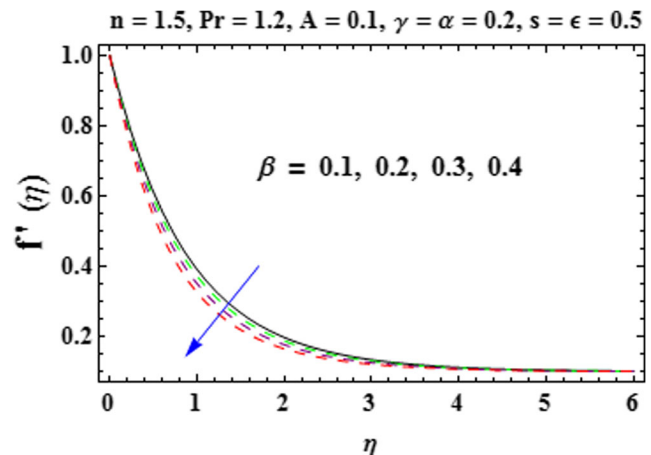


Fig. 4 β variation on f

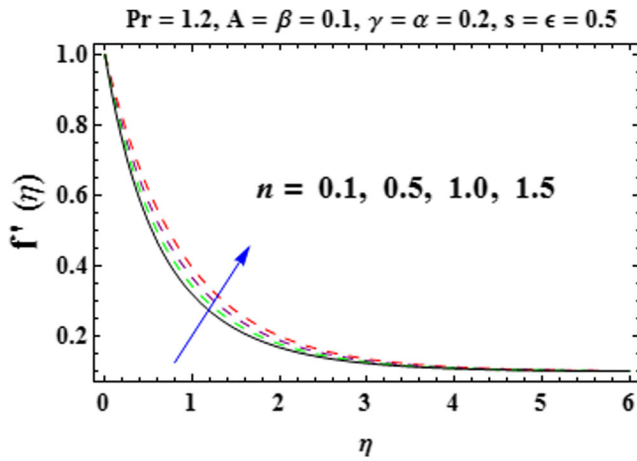


Fig. 5 n variation on f'

Weissenberg number, $S(= \frac{d}{c})$ the thermal stratification parameter, and $\gamma(= \lambda U_0(x+b)^{n-1})$ the relaxation factor.

Our analysis reduces to Fourier's situation when $\gamma=0$ in Eq. (13).

The skin friction coefficient is defined as

$$C_f = \frac{\tau_w}{\frac{1}{2}\rho u_w^2}, \tag{16}$$

with

$$\tau_w = \mu_0 \left(\frac{\partial u}{\partial y} \right)_{y=A_1(x+b)^{\frac{1-n}{2}}} - k_0 \left(u \frac{\partial^2 u}{\partial x \partial y} - 2 \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} \right)_{y=A_1(x+b)^{\frac{1-n}{2}}}. \tag{17}$$

Utilizing Eq. (17) in Eq. (16), the dimensionless form of the skin friction coefficient is given below:

$$\sqrt{Re_x} C_f = \sqrt{\frac{n+1}{2}} \left(\left[1 - \beta \left(\frac{7n-1}{2} f' - 2\eta \frac{n-1}{2} f'' \right) \right] f'' + \beta \eta \frac{n-1}{2} f' f''' \right)_{\eta=0}, \tag{18}$$

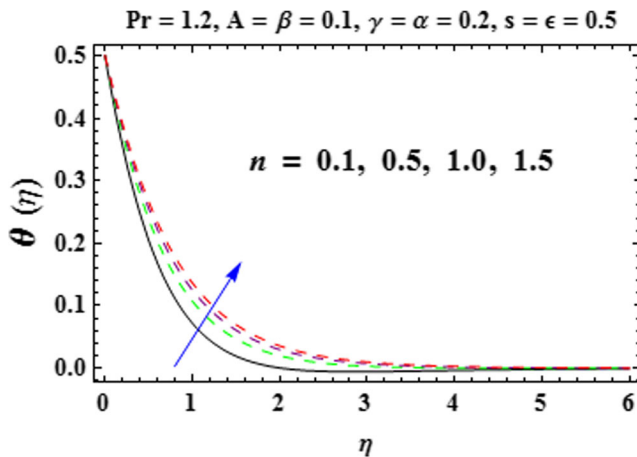


Fig. 6 n variation on θ

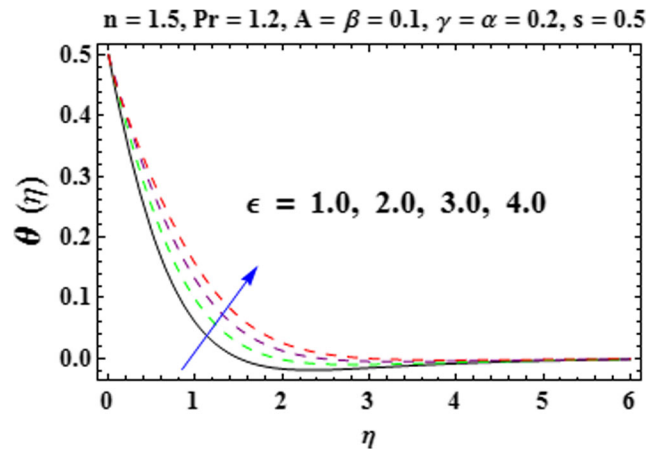


Fig. 7 ϵ variation on θ

with $Re_x = u_w(x)(x+b)/\nu$ showing the local Reynolds number.

3 Series solutions via homotopic procedure

Our intention here is to compute the convergent solution expressions for Eqs. (12) and (13) along with conditions (14) and (15). For this purpose, the initial approximations and linear operators are considered as

$$f_0(\eta) = A\eta + (1-A)(1-e^{-\eta}) + \alpha \frac{1-n}{1+n}, \theta_0(\eta) = (1-S)e^{-\eta}, \tag{19}$$

$$L_f = f''' - f', L_\theta = \theta'' - \theta, \tag{20}$$

with

$$L_f(C_1 + C_2 e^\eta + C_3 e^{-\eta}) = 0, L_\theta(C_4 e^\eta + C_5 e^{-\eta}) = 0, \tag{21}$$

in which $C_i(i=1-5)$ signify the arbitrary constants.

Convergence of secured obtained solutions is verified through the homotopy analysis method (HAM). Auxiliary variables (\hbar_f, \hbar_θ) involved in formulated series solutions are

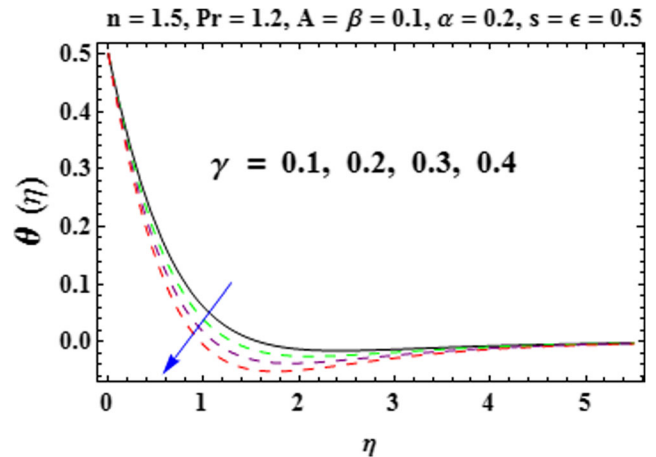


Fig. 8 γ variation on θ

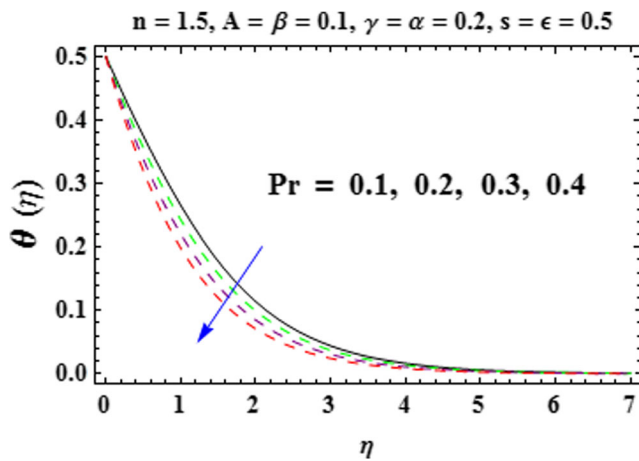


Fig. 9 Pr variation on θ

significant for such motivation. Thus, Figs. 1 and 2 highlight the plots for 12th order of approximations. The values verifying the convergence are in the ranges $-1.40 \leq h_f \leq -0.20$ and $-1.65 \leq h_\theta \leq -0.90$.

4 Discussion

This section highlights the salient characteristics of the ratio of velocities (A), Prandtl number (Pr), local Weissenberg number (β), thermal stratification parameter (S), thermal relaxation factor (γ), and power index (n) on velocity $f'(\eta)$ and temperature $\theta(\eta)$ through Figs. 3, 4, 5, 6, 7, 8, 9, and 10.

Figure 3 communicates the behavior of A on $f'(\eta)$. It is remarked that $f'(\eta)$ boosts via larger A . Impact of β on $f'(\eta)$ is reported through Fig. 4. Larger β reduces $f'(\eta)$, which relates to a thinner momentum layer. Physically, viscoelasticity yields tensile stress which diminishes the boundary layer and thus $f'(\eta)$ reduces. Figure 5 characterizes the features of n on $f'(\eta)$. Clearly $f'(\eta)$ shows increasing behavior for larger n . Actually, stretching velocity rises for larger n and consequently more deformation in the fluid is generated. Thus, $f'(\eta)$ rises.

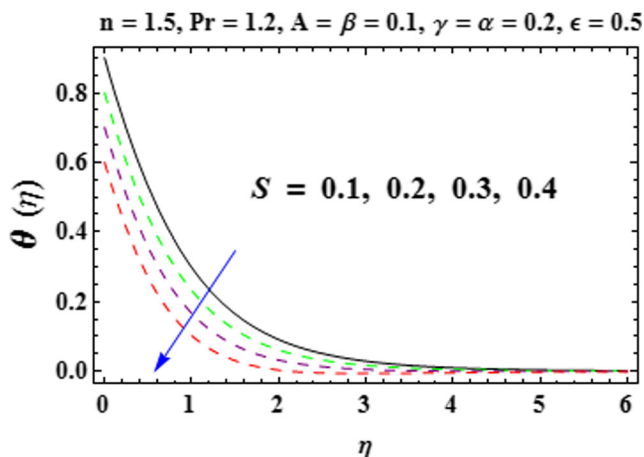


Fig. 10 S variation on θ

Table 1 Convergence of HAM expression for various orders of deformations when $n = 1.5, A = \gamma = K_2 = 0.2, K_1 = 0.1, S = 0.3, \alpha = \epsilon = 0.5, Pr = 1.2,$ and $h_f = h_\theta = -0.9$

Order of approximations	$-f''(0)$	$-\theta'(0)$
1	1.0110	0.9447
5	1.0213	0.9185
10	1.0243	0.9038
15	1.0254	0.9214
20	1.0259	0.9236
25	1.0262	0.9275
30	1.0262	0.9275
35	1.0262	0.9275
40	1.0262	0.9275

Characteristics of n on $\theta(\eta)$ are disclosed through Fig. 6. It is explored that both $\theta(\eta)$ and thermal layer thickness boost for larger n . Effect of ϵ on $\theta(\eta)$ is portrayed via Fig. 7. Here, $\theta(\eta)$ augments when ϵ is increased. In fact, thermal conductivity rises through larger ϵ , due to which a considerable amount of heat moves from the sheet to the material. Therefore, $\theta(\eta)$ augments. Figure 8 highlights the influence of γ on $\theta(\eta)$. Here, $\theta(\eta)$ decays for higher γ . From the physical point of view, elements of the material need more time to transport heat to its adjacent elements, due to which $\theta(\eta)$ decays. Salient features of S on $\theta(\eta)$ is depicted in Fig. 9. It is noticed that $\theta(\eta)$ and the associated layer thickness decay for higher S . Physically, temperature difference reduces between the surface of the sheet and liquid, which generates the reduction in $\theta(\eta)$. Figure 10 explores the impact of Pr on $\theta(\eta)$. As expected, $\theta(\eta)$ and the corresponding layer thickness reduce when Pr is enhanced. An enhancement in Pr corresponds to a slow rate of thermal diffusion.

Convergence of series solution is verified numerically through Table 1. It is noticed that the 25th order of deformations are acceptable regarding convergent expressions of velocity and temperature. Characteristics of β and A on surface drag force ($C_f Re_x^{1/2}$) is disclosed through Table 2. Here, $C_f Re_x^{1/2}$ decays via larger β and A . Table 3 delivers the comparative analysis of skin friction coefficient (i.e., when $\beta = 0$ and

Table 2 Skin friction ($C_f Re_x^{1/2}$) for distinct values of parameters β and A when $n = 1.5, \gamma = 0.2, S = 0.3, \epsilon = 0.5, \alpha = 0.2,$ and $Pr = 1.2$

β	A	$C_f Re_x^{1/2}$
0.0	0.1	-0.9668
0.2		-0.4372
0.4		-0.2561
0.1	0.0	-0.7376
	0.2	-0.6843
	0.4	-0.5806

Table 3 Comparative analysis of obtained results of $f''(0)$ with [51] when $n = 1$ and $\beta = 0$

A	Ref. [51]	Present
0.1	-0.9694	-0.96939
0.2	-0.9181	-0.91811
0.5	-0.6673	-0.66726
0.7		-0.43346
0.8		-0.29929
0.9		-0.15458
1.0		0.00000

$n = 1$) with the work of Mahapatra and Gupta [51]. Reasonable agreement is observed.

5 Final remarks

Here non-Fourier heat flux in stagnation point flow towards nonlinear stretching flow of Walter's B material is addressed. The main findings are summarized below.

- There is reverse behavior of A and β on $f''(\eta)$ qualitatively.
- Temperature ($\theta(\eta)$) via γ and Pr is less when compared with ε .
- Fourier's expression has high temperature in comparison to non-Fourier expression.
- Surface drag force decays for larger A and β .
- Viscous material results can be achieved by putting $\beta = 0$.

Compliance with ethical standards

Conflict of interest The authors declare that they have no conflict of interest.

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