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Validity and reliability evidence support task‑specifc metrics for laparoscopic fundoplication

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Abstract

Background Laparoscopic hiatal hernia repair (LHHR) is a complex operation requiring advanced surgical training. Surgical simulation ofers a potential solution for learning complex operations without the need for high surgical volume. Our goal is to develop a virtual reality (VR) simulator for LHHR; however, data supporting task-specifc metrics for this procedure are lacking. The purpose of this study was to develop and assess validity and reliability evidence of task-specifc metrics for the fundoplication phase of LHHR.

Methods In phase I, structured interviews with expert foregut surgeons were conducted to develop task-specifc metrics (TSM). In phase II, participants with varying levels of surgical expertise performed a laparoscopic Nissen fundoplication procedure on a porcine stomach explant. Video recordings were independently assessed by two blinded graders using global and TSM. An intraclass correlation coefficient (ICC) was used to assess interrater reliability (IRR). Performance scores were compared using a Kruskal–Wallis test. Spearman's rank correlation was used to evaluate the association between global and TSM.

Results Phase I of the study consisted of 12 interviews with expert foregut surgeons. Phase II engaged 31 surgery residents, a fellow, and 6 attendings in the simulation. Phase II results showed high IRR for both global (ICC=0.84, *p*<0.001) and TSM (ICC=0.75, $p < 0.001$). Significant between-group differences were detected for both global ($\chi^2 = 24.01$, $p < 0.001$) and TSM $(\chi^2 = 18.4, p < 0.001)$. Post hoc analysis showed significant differences in performance between the three groups for both metrics ($p < 0.05$). There was a strong positive correlation between the global and TSM (rs = 0.86, $p < 0.001$). **Conclusion** We developed task-specifc metrics for LHHR and using a fundoplication model, we documented signifcant reliability and validity evidence. We anticipate that these LHHR task-specifc metrics will be useful in our planned VR simulator.

Keywords Task-specifc metrics · VR simulator · Nissen fundoplication · Surgical education

Achieving technical proficiency in laparoscopic surgery is critical as it remains the most frequently employed surgical technique by case volume [[1\]](#page-10-0). Recent studies in bariatric [[2\]](#page-10-1) and colorectal [\[3](#page-10-2)] surgery have shown that greater technical

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skills are associated with better outcomes and fewer complications. Due to the difficulty in acquiring laparoscopic technical skills directly in the operating room, simulation-based training has emerged as a viable alternative [\[4–](#page-10-3)[9\]](#page-10-4). Simulation training platforms provide a conducive learning environment to teach the technical and cognitive competencies necessary to master laparoscopic surgery in a safe, patientfree environment, without the cognitive load experienced in the operating room. An efective simulation-based training program is contingent upon having a robust curriculum with clearly defned and quantifable performance metrics. Such metrics can be summative to establish a high stakes pass/fail determination or formative to provide trainees with targeted feedback for improvement. The most widely used summative tool for the evaluation of surgical performance

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is the Objective Structured Assessment of Technical Skills (OSATS) [\[10](#page-10-5)], a validated global tool for assessing operative performance in 6 domains, typically through video-based review. Formative assessment usually requires the creation and validation of task-specifc metrics tailored precisely to each procedure or task.

Laparoscopic hiatal hernia repair (LHHR) is a complex procedure requiring advanced surgical training [[11\]](#page-10-6). Attaining profciency in this procedure is crucial given the high recurrence rate for such hernias, which is up to 50%, especially for paraesophageal hernias [\[12\]](#page-10-7). LHHR remains a difficult procedure to master with reported learning curves ranging from 50 to 200 cases [[13–](#page-10-8)[15\]](#page-10-9), emphasizing the need to optimize training to acquire the necessary skills. Traditional anatomic models like cadavers and live animal models have been useful for simulating many procedures but may fall short in replicating some important aspects of human HHR and can pose ethical, cost, logistical, and curricular challenges. Advances in technology have made Virtual reality (VR) simulators a potentially ideal solution, offering detailed anatomic representations that are characteristic of HHR and facilitating focused, deliberate practice [[16\]](#page-10-10). Using standardized simulation scenarios, VR trainers also enable automated objective assessment and targeted feedback to improve performance without the need for an expert surgeon reviewer. Importantly, skills acquired in VR simulators have been shown to improve operating room performance [\[17,](#page-10-11) [18](#page-10-12)]. We are developing a VR simulator for LHHR training as part of an NIH-funded project. The purpose of this study was to develop and assess task-specifc metrics for LHHR, specifcally evaluating their reliability and validity for the fundoplication portion of the procedure.

Materials and methods

This study was approved by the UT Southwestern Institutional Review Board and was done in two phases. In phase 1, interviews were conducted with experts to create taskspecifc metrics for the assessment of performance in laparoscopic Nissen fundoplication. In phase II, a bench model study was performed to evaluate validity evidence supporting the newly created metrics.

Development of task‑specifc metrics for fundoplication

We performed a hierarchical task analysis (HTA) of the LHHR by conducting hour-long semi-structured interviews with local foregut surgeons and experts from the Society for American Gastrointestinal and Endoscopic Surgeons (SAGES) Foregut Task Force. HTA in surgery is a well-known method that breaks down any given surgical

procedure into tasks, sub-tasks, and motion end efectors, and it has been successfully used to deconstruct various minimally invasive procedures [[19](#page-10-13)[–21](#page-10-14)]. To guide our expert interviews, we formulated an initial list of procedure steps, drawing from recorded operative videos, information from textbooks, and prior task analysis of the laparoscopic fundoplication procedure [[22,](#page-10-15) [23](#page-10-16)]. Experts were then asked to describe how they perform the procedure, highlight key moments, identify variations in the procedure, and list common procedural errors in order of their severity. The recordings were then independently analyzed by two authors (SH and GS) to create task trees with variations and a list of errors. Any discrepancies were resolved by an expert author (CH) and through consultations with the interviewed experts.

Validity evidence evaluation for the fundoplication task‑specifc metrics

In phase II, we assessed the validity evidence of the newly created metrics by conducting a study at the UT Southwestern Simulation Center using a porcine explant Nissen fundoplication model. Messick's unitary framework was used to evaluate the validity of our task-specifc metrics [[24](#page-10-17)]. Specifically, data were collected to evaluate validity evidence in the following domains: content alignment, response process, internal structure, and relationship to other variables.

Fundoplication simulator design

We created a Nissen fundoplication simulator using a porcine stomach explant, which was placed inside a modifed version of a laparoscopic box trainer [[4\]](#page-10-3) (Fig. [1\)](#page-2-0). A frozen porcine stomach and esophagus specimen (Animal Technologies Inc., Tyler, Texas) was thawed and positioned in the box trainer. The esophagus was passed through a small circular incision in the lap box, about 2 inches from the base and held taut using an Allis clamp. To prevent lateral movement, the stomach was secured with two alligator clips. To create a retroesophageal window for the fundoplication, a Penrose drain was inserted through a circular incision about 4 inches from the base to lift the stomach at the gastroesophageal junction and keep the model under tension. A 0° laparoscope connected to a standard equipment tower was used for visualization. A pair of standard laparoscopic needle drivers, curved graspers, and scissors were used to perform the procedure. In addition, 2–0 silk sutures pre-cut to 15 cm in length were placed on a foam box to be used for suturing.

Fig. 1 Laparoscopic Nissen fundoplication simulator; **A** overall set-up; **B** specimen set-up

Study design and procedure

The study was performed at the UT Southwestern Simulation Center with a between-subjects design. Recruited participants were stratifed into three groups by level of expertise: novice (post-graduate year [PGY] 1–2 residents in general surgery), intermediates (PGY 3–5 residents and a minimally invasive fellow), and experts (faculty).

Prior to starting the procedure, each participant completed a survey that captured demographic information, clinical experience, and simulator experience. After providing informed consent, participants were given general instructions explaining the study objective and the task, without any technical/operative guidance. Specifcally, we did not provide any instructions on number and type of sutures, the distance between the sutures and the placement of the wrap. Participants were then asked to complete a Nissen fundoplication on the porcine stomach model. They were given 1 h to complete up to 2 unassisted attempts. Video recordings focused on the instruments actively utilized in the laparoscopic box trainer, the training model itself, and a card displaying the participants' random identifcation number to ensure anonymity during the video review process. Additionally, we also collected and analyzed the following real-time in situ metrics for each participant: (I) number of attempts completed (1 or 2), (II) number of sutures placed for fundoplication, (III) space between sutures measured in centimeters, and (IV) whether seromuscular bites were taken through the esophagus (dichotomized as 0 or 1).

At the conclusion of the study, participants were asked to complete a post-simulation survey to assess the quality of the simulator on a 5-point Likert scale. The survey covered 5 categories that included the visual appearance of the simulation, the quality of models and textures, the realism of the

simulator interface, how closely the task mirrored the actual surgical procedure, and the simulator's overall effectiveness in teaching LHHR.

Two qualifed raters, blinded to the participants' experience levels, independently evaluated the video recordings of performances using both global and task-specifc metrics. Table [1](#page-3-0) presents the global metrics derived from the OSATS rubric, whereas Table [2](#page-4-0) displays the task-specifc metrics grounded in the HTA [[10](#page-10-5), [25–](#page-10-18)[28](#page-10-19)]. Among the OSATS domains, we excluded the scoring rubric for knowledge of instruments because all participants were provided with the same set of laparoscopic tools. Initially, the two raters assessed the performance of 5 participants, comparing their ratings to discuss the grading and to resolve discrepancies. They then evaluated another 5 videos to ensure concordance between their ratings and reviewed the intraclass correlation coefficient (ICC). Finally, each rater independently graded the remaining videos.

Data analysis

The ICC estimates and their 95% confdent intervals for establishing interrater reliability (IRR) were calculated based on mean rating $(k=2)$, absolute agreement, and 2-way mixed-efects model. An ICC value between 0.75 and 0.9 was deemed good, while a value above 0.9 was deemed excellent for IRR [[29\]](#page-10-20). A total score was calculated by frst averaging the individual metric scores from both raters and then summing them up for both global and task-specifc evaluations. The Spearman rank correlation test was used to assess the association between the total global and task-specifc scores. To determine performance diferences between the three groups, the data were frst evaluated for normality using the Shapiro–Wilk test. If the data were normally

distributed, a one-way analysis of variance (ANOVA) was conducted, followed by a pairwise *t* test with Bonferroni correction for post hoc analysis. If not normally distributed, the Kruskal–Wallis test was employed, followed by a pairwise Wilcoxon test with Benjamini–Hochberg correction. Post hoc effect size was reported when appropriate.

Sample size

A priori power analysis was conducted using the G*software [\[30\]](#page-10-21) to test the difference in performance between the three groups, with α = 0.5, a medium effect size f = 0.5 and power β = 0.8. The analysis showed that a total of 30 subjects equally distributed in three groups was needed to achieve the necessary power.

Results

Phase I results

Task analysis

A total of 12 expert foregut surgeons participated in interviews for task analysis, spanning 720 min in total. Table [3](#page-5-0) displays the HTA of LHHR, outlining 6 major tasks, 27 subtasks, and 19 major errors. Using the HTA (Table [3\)](#page-5-0) and the cataloged errors, we formulated metrics for video-based assessment of the LHHR (see Appendix 1).

Phase II results

Pre‑survey results

Demographics A total of 38 participants were recruited to complete the fundoplication simulation (Table [4](#page-6-0)). Participants were grouped into novice $(n=17, 45\%)$, intermediate (*n*=15, 39%), and expert (*n*=6, 16%). Additionally, 50% $(n=19)$ were male, 45% $(n=17)$ were under the age of 30, 87% (*n*=33) self-reported being right-handed, and 58% $(n=22)$ were wearing corrective lenses.

Prior experience The overwhelming majority of novice and intermediate participants (*n*=28, 88%) reported having observed 0–10 HHRs, while 3 (9%) reported observing 11–30 cases and 1 (3%) reported observing 30–50 cases. Among the attending surgeons, most had observed and/ or participated in at least 100 cases and only 1 reported observing/participating in less than 100 cases. Overall, 42% (*n*=16) of the participants self-reported a prior exposure to a robotic (Da Vinci) or laparoscopic (Fundamentals of Laparoscopic Surgery) simulation trainer, indicating that a subset of participants had previous hands-on engagement or familiarity with the technology being assessed. Additionally, 37%

Metric	Score $(0, 3, or 5$ points)	
Task-specific skills		
Wrap creation	a. Passes fundus posteriorly through retroesophageal window and performs shoeshine maneuver around the esopha- gus (5 points) b. Uses wrong part of stomach, or wrap is created with improper tension and orientation, or causes injury to esophagus, stomach, or vagus nerve (0 points)	
Wrap position	a. Wrap on esophagus (5 points) b. Wrap on stomach (0 points)	
Securing wrap	a. Three simple interrupted sutures incorporating stomach and esophagus (5 points) b. Poor knot-tying/suturing technique or injury to esophagus, stomach, or vagus nerves (0 points)	
Wrap length	a. Appropriate 2–3-cm wrap length on esophagus demonstrated with ruler/grasper (5 points) b. Improper length (too short/too long; 0 points)	
General laparoscopic skills		
Depth perception	a. Accurately directs instruments in the correct plane to target (5 points) b. Some overshooting or missing of target, but quick to correct (3 points) c. Constantly overshoots target, wide swings, slow to correct (0 points)	
Bimanual dexterity	a. Expertly uses both hands in a complimentary manner to provide optimal exposure (5 points) b. Uses both hands, but does not optimize interaction between hands (3 points) c. Uses only one hand, ignores non-dominant hand, poor coordination between hands (0 points)	
Efficiency	a. Confident, efficient, and safe conduct, maintains focus on task until it is better performed by way of an alternative approach (5 points) b. Slow, but planned movements are reasonably organized (3 points) c. Uncertain, inefficient efforts, many tentative movements, constantly changing focus or persisting without pro- gress (0 points)	
Tissue handling	a. Handles tissues well, applies appropriate traction, negligible injury to adjacent structures (5 points) b. Handles tissues reasonably well, minor trauma to adjacent tissue (occasional unnecessary bleeding or instrument slipping; 3 points) c. Rough movements, tears tissues, injures adjacent structures, poor instrument control, instruments frequently slip (0 points)	
Knowledge of procedure	a. Demonstrates familiarity of all aspects of the procedure (5 points) b. Knew important steps of procedure only (3 points) c. Insufficient knowledge of procedure and instruments (0 points)	
Flow of operation	a. Obviously planned operation with clear anticipation of next moves (5 points) b. Demonstrated some forward planning and reasonable progression of procedure (3 points) c. Frequently stopped operating and unsure of next move (0 points)	
Instrument handling	a. Fluid movements (5 points) b. Competent use of instruments but occasionally awkward (3 points) c. Tentative and awkward moves with instruments with frequent collisions (0 points)	
Bite size	a. Appropriate bite size (5 points) b. Improper bites (too small/big; 0 points)	
Knot tying	a. Appropriate technique (no air knots or suture breakage; 5 points) b. Improper technique (air knots, suture breakage; 0 points)	
Needle handling	a. Equidistant placement of sutures without tissue injury or suture breakage (5 points) b. Poor spacing of sutures with minor trauma to tissue and rare suture breakage (3 points) c. Frequent suture breakage and poor control, tearing tissue (0 points)	

Table 2 Task-specifc metrics for assessing performance of the creation and securing the wrap portion of the laparoscopic fundoplication procedure

 $(n=14)$ reported having gaming experience, with more than half of them $(n=10)$ playing at least 1–5 h a week. None of the participants included in the study reported any exposure to VR laparoscopic training.

Post‑simulation survey results

After the Nissen fundoplication task, we conducted a postsimulation survey in which participants rate the realism and usefulness of their experience on a scale of 1–5, with 1 being not realistic/useful and 5 being very realistic/useful. The survey questions covered 5 categories that included the realism of the anatomy of the model, the realism of the ex vivo porcine model (texture), the realism of the simulator interface (instruments, display), the overall realism of the task compared to the actual surgical task, and the overall perceived usefulness of the simulator for learning laparoscopic hiatal hernia surgical skills. Table [5](#page-6-1) shows the

Table 3 Hierarchical task analysis of the laparoscopic hiatal hernia repair showing major tasks, sub-tasks, and errors

Tasks	Sub-tasks	Errors
1. Patient positioning	1.1 Place patient in supine/split leg and then reverse Trendelenburg position	1. Patient placed in an incorrect position
2. Port placement	2.1 Establish pneumoperitoneum 2.2 Inspect site of next trocar incision, make inci- sion, and place desired ports 2.3 Expose hiatus with left lobe liver retractor	1. Air embolism 2. Injury to nearby structures
	3. Abdominal hernia sac dissection 3.1 Reduce herniated stomach/omentum/other structures if present using hand-over-hand gentle reduction of hernia and contents and the use of tension/countertension to perform dissection 3.2 Divide pars flaccida/gastrohepatic ligament until 4. Injury to crural fibers, aorta, inferior vena cava, base of the right crus 3.3 Divide short gastric until base of left crus 3.4 Perform blunt dissection of phrenoesophageal membrane/medial border of crura 3.5 Perform circumferential dissection to create retroesophageal window	1. Perforation of stomach 2. Injury to replaced vessels and vagus nerves 3. Thermal injury to stomach or retroperitoneal structures and esophagus
4. Mediastinal dissection	4.1 Identify gastroesophageal junction (GEJ) using either a bougie, endoscopy, or anatomic land- marks (fat pad) 4.2 Perform blunt proximal circumferential dissec- tion along the areolar place as high as possible up to aortic arch and up to inferior pulmonary vein 4.3 Measure intraabdominal esophageal length using either a ruler or the grasper tip 4.4 Excise hernia sac to expose angle of His	1. Esophageal perforation 2. Injury to celiac axis, esophagus, gastric wall, vagus nerve, aorta, axygos vein, lymphatics, pleura, or pericardium 3. $CO2$ pneumothorax 4. Thermal spread to esophagus if using energy device
5. Crural closure	5.1 Place posterior sutures using Ethibond/silk sutures posteriorly about 1 cm apart without angulating esophagus 5.2 Place anterior sutures if there is esophageal displacement/angulation 5.3 Check repair with bougie or endoscope 5.4 If there is tension, do right crus relaxing inci- sion	1. Esophageal perforation 2. Injury to aorta, inferior vena cava, esophagus, and phrenic nerve
6. Fundoplication	6.1 Divide additional short gastric vessels and any posterior esophageal attachments 6.2 Pass fundus posteriorly through retroesophageal window 6.3 Perform shoeshine maneuver 6.4 Retract esophagus caudad with or without a Penrose 6.5 If Nissen (360°), place three simple interrupted sutures, one stomach-stomach and two stomach- esophagus-stomach, above GEJ 6.6 If Toupet (270°) , place three simple interrupted sutures, stomach-esophagus, on each side above GEJ 6.7 Perform gastropexy if needed	1. Wrapped herniation 2. Wrapped on stomach instead of esophagus 3. Internal hernia (posterior stomach through poten- tial space by the wrap) 4. Twisted, tight/loose wrap 5. Injury to anterior vagus nerve, liver, and esophagus
7. Closure	7.1 Perform endoscopy to assess wrap and repair 7.2 Remove ports under direct visualization 7.3 Close port sites	1. Not assessing wrap and repair

survey results for the degree of realism and usefulness of the fundoplication simulation model. The vast majority of participants from all three groups rated the simulator's realism aspects highly, recognizing its usefulness and capability to capture the essential features of the task, thus establishing the content alignment.

Reliability analysis

The IRR between the two blinded raters was good for both the global- (ICC = 0.84, 95% CI 0.79–0.87, *p* < 0.001) and task-specific metrics (ICC = 0.75 , 95% CI 0.7 -0.78 , p <0.001), thereby establishing internal structure validity.

Table 4 Demographics of the

Grading the videos with blinded raters mitigated potential errors due to rater bias, thus ensuring response process validity.

Analysis of metrics

The descriptive statistics of the metrics used for assessing performance are shown in Table [6](#page-6-2). Due to the unequal

Table 6 Median and interquartile range (IQR) of metrics used for the assessment of performance

sample size of the groups and data violating normality using the Shapiro–Wilk test, non-parametric tests were used and are reported here.

Global metrics

Table [6](#page-6-2) presents the median and interquartile range of the total global scores for all three groups. The Kruskal–Wallis test showed a signifcant diference in performance between the groups $(\chi^2 = 24.01, p < 0.001)$. As depicted in Fig. [2,](#page-7-0) performance improved with increasing level of expertise. Post hoc analysis revealed signifcant diferences among all three groups: novice vs. intermediate $(p=0.001)$, intermediate vs. expert ($p = 0.01$), and novice vs. expert ($p = 0.007$).

Task‑specifc metrics

The median and interquartile range of the total task-specifc scores for all three groups are shown in Table [6.](#page-6-2) The Kruskal–Wallis test revealed a significant difference in performance among the groups (χ^2 = 18.4, *p* < 0.001). As illustrated in Fig. [3](#page-7-1) and mirroring the total global score, performance improved with increasing levels of experience. Post hoc analysis showed a signifcant diference in performance among all three groups: novice vs. intermediate $(p=0.001)$, intermediate vs. expert $(p=0.03)$, and novice vs. expert $(p=0.001)$. The Spearman rank correlation indicated a strong association between the total global score and the total task-specific scores ($rs = 0.87$, $p < 0.001$), as depicted in Fig. [4](#page-7-2). In addition, Fig. [5](#page-8-0) displays photos of subjects executing various components of the task-specifc metrics.

In situ metrics

I. Number of attempts: all of the participants in the expert and intermediate groups were able to com-

Fig. 2 Total global score for the three groups

Fig. 3 Total task-specifc score for the three groups

plete the maximum of 2 attempts in the allotted time except for 1 subject each in both groups; whereas, in the novice group, only 6 out of 17 subjects were able to proceed to the second attempt. The Kruskal– Wallis test showed a signifcant diference in the number of attempts between the groups (χ^2 = 12.5, $p=0.001$). Post hoc analysis showed a significant difference between the novice and intermediate groups $(p=0.002)$. No difference was found between the novice and expert group $(p=0.07)$ and the intermediate and expert group $(p=0.54)$.

II. Number of sutures: all the subjects in the expert group placed 3 sutures to complete the fundoplication. In the intermediate group, 13 subjects placed 3

Fig. 4 Correlation between total global- and task-specifc scores

(a) Shoeshine maneuver

(b) Checking for adequate alignment before placing the suture

(c) Placement of sutures on the esophagus above the GEJ

Fig. 5 Video-based assessment of the fundoplication task

sutures and 2 placed 4 sutures. In the novice group, 3 placed only 1 suture, 2 placed 2 sutures, 8 placed 3 sutures, and 4 placed 4 sutures. Kruskal–Wallis tests showed no signifcant diference in the number of sutures placed between the three groups (χ^2 = 0.94, $p = 0.62$).

- III. Sum of distance between sutures: experts sum of distance ranged from 2 to 3.5 cm, the intermediate group sum ranged from 1.4 to 4.4 cm, and the novice group sum ranged from 0 to 3.5 cm. The Kruskal– Wallis test showed signifcant diferences between the groups in the sum of the distances for all the sutures $(\chi^2 = 6.04, p = 0.04)$. Post hoc analysis could not find any signifcant diferences between novice and intermediate groups $(p=0.15)$, novice and expert groups $(p=0.08)$, and between intermediate and expert groups $(p=0.08)$.
- IV. Seromuscular bite: overall, 5 out of 6 subjects in the expert group, 10 out of 15 subjects in the intermediate group, and 5 out of 17 subjects in the novice group placed a seromuscular bite on the esophagus while performing fundoplication. The Kruskal–Wallis test showed a signifcant diference between the groups in seromuscular bite taken during fundoplication $(\chi^2 = 6.94, p = 0.03)$. Post hoc analysis could not fnd any diferences between novice and intermediate groups $(p=0.06)$, novice and expert groups $(p=0.06)$, and between intermediate and expert groups $(p = 0.49)$.

The results from the analysis revealed the metrics' relationship to other variables, confrming construct validity.

Discussion

Our results demonstrate that task-specifc metrics diferentiate the performance in the wrap creation step of the laparoscopic fundoplication between novice, intermediate, and expert surgeons. A strong positive correlation was also observed between the validated global OSATS score and our task-specifc scores. High IRR for both metrics established the feasibility of using our task-specifc metrics for video-based assessment of performance. Additionally, it is noteworthy that 89% of participants rated the simulator's usefulness as either 4 or 5 on a scale of 5. This rating was further supported by informal comments from several non-expert participants throughout the study expressing their desire for this practice opportunity before performing the procedure in the operating room. Many trainees also mentioned how the experience enhanced their confdence when approaching such cases involving live patients.

Expertise in laparoscopic hiatal hernia surgery requires extensive training with high case volume. Learning curve studies have shown that for individual surgeons, a total of 20–40 cases, and for individual institutions, about 50 cases, are needed for stabilization of postoperative complication rates [[13](#page-10-8), [31\]](#page-11-0). In a 10-year institutional learning curve study, it was found that 200 fundoplication cases had to be performed before operative time, conversion rates, and complications plateaued [\[14\]](#page-10-22). Given the procedure's long learning curve, obtaining adequate training is further complicated by a substantial number of cases performed in high-volume centers, indicating centralization of this procedure to a few specialty centers [[32\]](#page-11-1). This can afect the number of cases performed by residents, whose training pathways in complex foregut surgery are limited to their experience in the operating room. In our study, 88% of residents reported participating in 10 or fewer LHHRs. Simulation-based training can help bridge this gap by providing an opportunity for trainees to practice this task outside of the operating room.

As the exposure of surgical trainees to LHHR varies based on whether or not they are at a high-volume center, a simulator for training in this procedure is essential. Such a simulator should not only be capable of training the important cognitive and technical aspects of this procedure but should also be capable of both high-stakes summative and low-stakes formative assessment of skills. Several tools exist for video-based assessment of performance in LHHR with limited validity evidence [[33\]](#page-11-2). A majority of training programs use a global tool for assessment of laparoscopic performance, such as the OSATS and the Global Operative Assessment of Laparoscopic Surgery (GOALS) [[34](#page-11-3)[–37\]](#page-11-4) or a combination of global scales and procedure-specifc assessment tools in the form of checklists [[38,](#page-11-5) [39\]](#page-11-6). In a study by Peyre et al. [[40\]](#page-11-7), investigators focused on a detailed 65-step procedural checklist previously developed based on task analysis for the evaluation of technical performance in laparoscopic Nissen fundoplication [[41](#page-11-8)]. Sixty-four of the 65 steps showed high degree of reliability (>0.8) when expert operative performance of Nissen fundoplication was graded by fve surgeons using the checklist. More recently, as part of its master's program, SAGES developed a videobased assessment tool for laparoscopic fundoplication and demonstrated its content validity [\[22\]](#page-10-15). In our work, we independently developed metrics for assessment using the well-established HTA method. Overall, major tasks and subtasks aligned with prior HTA fndings for this procedure [\[20,](#page-10-23) [22,](#page-10-15) [41\]](#page-11-8). Using HTA, we identifed 19 major errors and developed task-specifc metrics to evaluate performance for LHHR. Such task-specifc metrics developed using HTA and expert consensus have been validated for the assessment of performance in endotracheal intubation and colorectal anastomosis procedures [[27,](#page-10-24) [28,](#page-10-19) [42\]](#page-11-9). Though only the task-specifc metrics for the creation and securing the wrap portion of the procedure were tested in our work, we were able to clearly establish validity evidence in the following domains defned by Messick's unitary framework, namely, content alignment, response process, internal structure, and relationship to other variables.

One unique aspect of this study was the incorporation of in situ metrics in addition to our task-specifc metrics for assessment. Both the number of attempts and placement of seromuscular bite were found to be useful metrics, which could be easily incorporated in the VR simulator for assessment. Though the goal of the work was to develop assessment metrics to incorporate in our VR simulator, the developed metrics with their validity evidence can also be used for video-based assessment of performance in laparoscopic fundoplication procedures. We showed the relationship of our metrics to other variables by comparing our task-specifc metrics to OSATS but due to constraints in time in performing video-based assessment, it is not yet known how our task-specifc metrics correlate with other instruments developed for this procedure, which will be part of our future work.

The transferability of skills from simulation to live OR must be a priority when creating a simulator. Transferability would both encourage usage and result in an actual improvement in live operative technical skills and patient outcomes. Although we did not test the initial dissection and reduction of the hernia sac with its contents and the assessment of intraabdominal esophageal length due to constraints in creating a physical model, we plan to test those aspects later in a VR model. We have created a model of the crura with an enlarged esophageal hiatus and are performing studies to establish validity of the metrics for the crural repair portion of the procedure, which will be reported separately. Our fundoplication simulation closely mimics a portion of the actual LHHR operation with a few diferences, namely the simulation's lack of a diaphragm; hence, it does not replicate the exact constraints experienced in the real surgery. The realism of our simulation is evident from the feedback of the participants, 79% of whom graded it 4 or 5 on a 5-point scale of realism.

Limitations of this study include a relatively small sample size and varying participant numbers across the groups. While we were able to maintain sufficient representation from each level of surgical expertise, the intermediate and expert groups had comparatively fewer participants. This could be attributed to the escalating operative and clinical responsibilities associated with each PGY level, leaving less availability for participating in research studies. The smaller and unequal sample size also resulted in small or moderate efect size with no clear post hoc comparison results for our in situ metrics. Furthermore, despite blinding of the identities of participants in the videos, there might still be some reluctance and apprehension regarding skill evaluation among participants. Finally, due to resource constraints, we could not use the fexible endoscopy in our study to assess quality and securement of the wrap, such as tightness and potential full-thickness bites.

Using an ex vivo fundoplication model, this study established the validity and reliability of task-specifc metrics developed for assessment of performance in the creation and securing the wrap portion of the LHHR. The developed simulator and the video-based assessment metrics can be used for training and assessment in this procedure. Our next step is to incorporate the validated task-specifc metrics in our VR simulator for automated assessment.

Supplementary Information The online version contains supplementary material available at<https://doi.org/10.1007/s00464-024-10675-4>.

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Declarations

Disclosures Alexis Desir, Carolina Marques, Emile Farah, Shruti Hegde, Carla Holcomb, Daniel J. Scott, and Ganesh Sankaranarayanan have nothing to disclose.

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