



Understanding the drivers of volcano deformation through geodetic model verification and validation

Josh Crozier¹ · Leif Karlstrom² · Emily Montgomery-Brown³ · Mario Angarita⁴ · Valérie Cayol⁵ · Mary Grace Bato⁶ · Taiyi A. Wang⁷ · Ronni Grapenthin⁴ · Tara Shreve^{4,8} · Kyle Anderson¹ · Ana Astort⁹ · Olivier Bodart¹⁰ · Flavio Cannavò¹¹ · Gilda Currenti¹² · Farshid Dabaghi¹³ · Brittany A. Erickson² · Deepak Garg¹⁴ · Matthew Head¹⁵ · Adriana Iozzia^{12,16} · Young Cheol Kim¹⁷ · Hélène Le Mével⁸ · Camila Novoa Lizama¹⁸ · Cody Rucker² · Francesca Silverii⁹ · Elisa Trasatti⁹ · Yan Zhan¹⁹

Received: 28 July 2023 / Accepted: 24 October 2023 / Published online: 27 November 2023
This is a U.S. Government work and not under copyright protection in the US; foreign copyright protection may apply 2023

Abstract

Volcano geodesy often involves the use of models to explain observed surface deformation. A variety of forward models are used, from analytical point sources to numerical simulations that consider complex magma system geometries, topography, and material properties. Various inversion methods can then be used to relate observed volcano data to models. Ideally, forward models should be verified through intercomparison, to check for implementation errors and quantify the error induced by any approximations used. Additionally, forward models and inversion methods should be validated through tests with synthetic and/or real data, to determine their ability to match data and estimate parameter values within uncertainty. However, to date, there have not been comprehensive verification and validation efforts in volcano geodesy. Here, we report on the first phase of the Drivers of Volcano Deformation (DVD) exercises, which were designed to build community involvement through web-based exercises involving calculations of static elastic displacement around pressurized magma reservoirs. The forward model exercises begin with a spherical reservoir in a homogeneous half space, then introduce topography, heterogeneous elastic properties, and spheroidal geometries. The inversion exercises provide synthetic noisy surface displacement data for a spherical reservoir in a homogeneous half space and assess consistency in estimates of reservoir location and volume/pressure change. There is variability in the results from both forward modeling and inversions, which highlights the strengths and limitations of different forward models, as well as the importance of inversion method choice and uncertainty quantification. This first phase of the DVD exercises serves as a community resource and will facilitate further efforts to develop standards of reproducibility.

Keywords Volcano geodesy · Volcano deformation · Validation and verification · Modeling

Introduction

Over 200 volcanoes around the world are known to be actively exhibiting ground deformation (Ebmeier et al. 2018). This number will continue to rise from expansion of ground-based monitoring networks, increases in the amount and types of satellite imagery available, and improvements in data processing and analysis methods (Poland and Zebker 2022). Ground deformation over timescales not captured in

previous data will also substantially contribute to increasing the number of known actively deforming volcanoes (Grapenthin et al. 2022).

Ground deformation in volcanic settings can arise from a variety of causes. Deformation can reflect pressurizing/depressurizing subsurface magma bodies, which could have geometries ranging from spheroid-like fluid-filled reservoirs to complex networks of dikes, sills, and crystal mush regions (Alshembari et al. 2023; Bato et al. 2021; Ebmeier et al. 2018; Grapenthin et al. 2022; Liao et al. 2021; Montgomery-Brown and Miklius 2021; Mullet and Segall 2022). Deformation can also reflect processes such as flank slip or other volcanic/tectonic faulting (Dumont et al. 2022; Poland et al. 2017) and hydrothermal activity (Fournier and Chardot 2012). Having accurate forward models of

Editorial responsibility: S. Massaro

✉ Josh Crozier
jcrozier@usgs.gov; crozierjosh1@gmail.com

Extended author information available on the last page of the article

deformation from these various processes is important for resolving magma storage geometries and understanding stress states that influence flank stability (Gonzalez-Santana and Wauthier 2021), eruption triggering (Gregg et al. 2013), dike trajectories (Karlstrom et al. 2009; Sigmundsson et al. 2015), caldera collapse onset and expected eruptive volumes (Anderson et al. 2019; Sigmundsson et al. 2020), and overall eruptive cycles (Townsend 2022). To resolve these processes and detect signs of unrest, it is important to be able to relate deformation models to monitoring data (Fernández et al. 2017).

There are a wide variety of different forward models and inversion methods in use for studying volcano deformation. Intercomparisons between particular models have been made previously (Battaglia et al. 2013; Hickey and Gottsmann 2014; Novoa et al. 2019; Segall 2010; Taylor et al. 2021), but there has not yet been a comprehensive community wide model and inversion intercomparison initiative. Model intercomparison has been conducted for other aspects of volcano science including conduit flow (Sahagian 2005), lava flows (Dietterich et al. 2017), plumes (Costa et al. 2016), and pyroclastic density currents (Esposti Ongaro et al. 2020). Particularly successful initiatives for earthquake science have been carried out over the last two decades by the Southern California Earthquake Center (SCEC), including for both the Spontaneous Rupture Code Verification and simulations of Sequences of Earthquake and Aseismic Slip (SEAS) projects (Barall and Harris 2015; Erickson et al. 2020; Harris et al. 2018, 2011, 2009; Jiang et al. 2022; Mai et al. 2016). The SCEC exercises have

developed into a multi-pronged community initiative that helps push the boundaries of earthquake modeling and have been influential for establishing standards of reproducibility.

We follow the SCEC blueprint to introduce an initial phase of volcano deformation community exercises for verification and validation. In general, verification refers to testing that a model is implemented correctly given the assumptions behind it, while validation refers to testing that a model represents reality and/or matches data (Gonnermann and Anderson 2021). Here, we verify forward models using intercomparison, which is termed benchmarking when exact analytical solutions are available for comparison. We then test inversions for noisy synthetic data; this can be considered a first step towards more comprehensive validation efforts which would involve real data and that are left for future exercises.

These exercises were initiated by a steering committee (Karlstrom, Montgomery-Brown, Crozier, Bato, Cayol) formed in fall 2021 in partnership with CONVERSE (Converging on Eruption Science with Equity), the MCS (Modelling Collaboratory for Subduction) (Gonnermann and Anderson 2021), and the IAVCEI (International Association of Volcanology and Chemistry of the Earth's Interior) Geodesy Commission (no financial support). A virtual planning workshop was advertised to the community and held in October 2021 with 32 attendees. The steering committee used community suggestions to finalize exercise design and hired a student (Angarita) to develop a website (www.driversofvolcanodeformation.org, Fig. 1) which provides complete problem specifications and the ability to

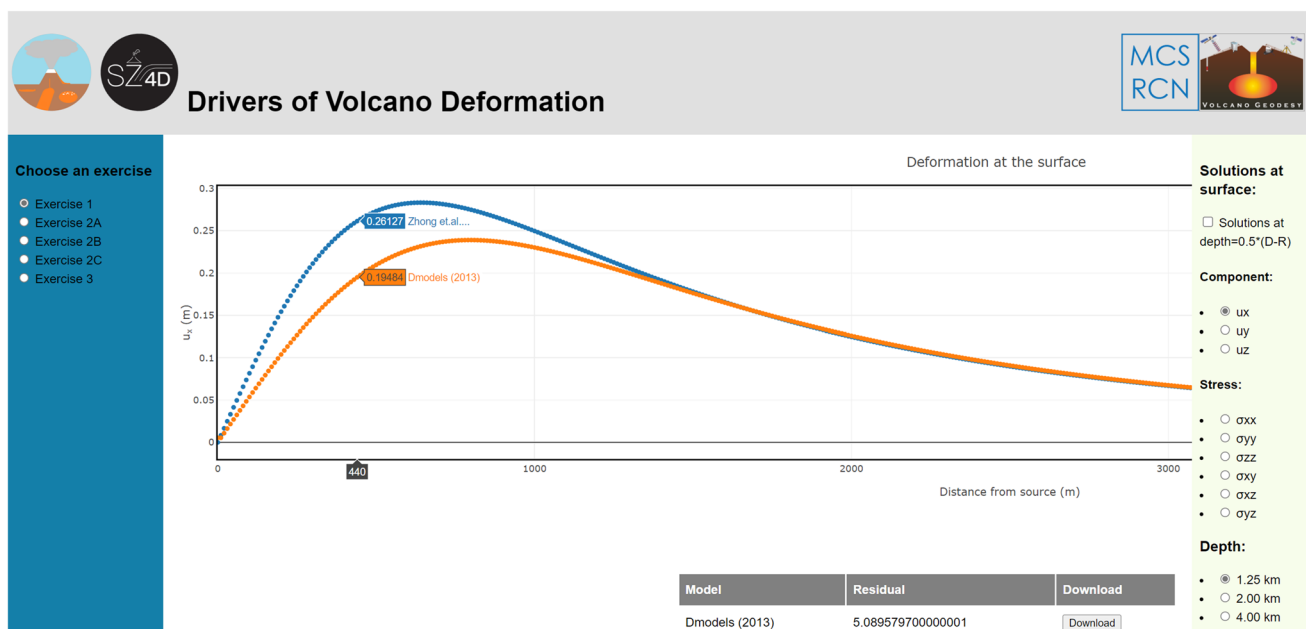


Fig. 1 Screenshot showing interactive plotting on the project website (<http://www.driversofvolcanodeformation.org>)

download or interactively plot and compare submissions. The website was published in February 2022, and was advertised through email listservs (Arizona State University Volcano Digest, IAVCEI Geodesy Commission, MCS) and presentations/meetings at multiple conferences: American Geophysical Union (Montgomery-Brown et al. 2022), European Geophysical Union, Cities on Volcanoes, and International Union of Geodesy and Geophysics (Cayol et al. 2023). Virtual office hours for participants were held in various time zones.

The exercise website is intended to remain open for continuing submissions so that it can serve as a general resource for method selection, verification, and validation. Twenty-six researchers from multiple continents and career stages participated as of summer 2023, when results were compiled and participants were asked to provide feedback. This article outlines the exercises, presents key results, and discusses future initiatives.

Forward model (verification) exercises

We kept the scope of this first phase of exercises limited by focusing on static elastic displacement, which is a necessary step for community consistency before considering more complex and time-dependent modeling (e.g., thermo-poro-viscoelasticity of host rocks or treatment of multiphase magma dynamics) and inversions (e.g., time-series data processing methods or sensor network design). We also focused on inflating/deflating spheroidal magma reservoirs, which are the most common magma system geometries used in both inversions and general magma reservoir models. Approaches that seek realistic spatial variability in material properties with constraints from geophysical images are promising (Hickey et al. 2016). However, since there are limits to how uniquely complex source geometries and rheology can be resolved (Segall 2019), linear elastic spheroidal reservoir models will remain valuable and widely used even as more sophisticated methods continue to be developed.

For forward modeling of elastic spheroidal reservoirs, a wide variety of both analytical and numerical methods are in use. Analytical models are widely used due to their simplicity and low computational cost, which is beneficial for inversions (Lisowski 2006; Taylor et al. 2021). Most analytical models assume a homogeneous elastic half space (McTigue 1987; Mogi 1958; Yang et al. 1988), and are approximations that become less accurate for small depth/radius ratios and/or eccentricities. A recently derived series expansion model for a spherical reservoir can be arbitrarily accurate but at greater computational cost (Zhong et al. 2019). Several approximate corrections for topography with varying computational cost and accuracy can be

used with analytical models (McTigue and Segall 1988; Williams and Wadge 2000). There are multiple different implementations in use for many of the analytical models and corrections, and implementation errors have previously been found in some published versions.

Numerical models can be more general than analytical models (Masterlark 2007), but also typically involve higher computational cost and have accuracy that depends upon user choices such as mesh and domain sizes. Volume discretized approaches such as finite element methods (FEMs) are robust and general, with the ability to account for various rheologies and material heterogeneity. Many different types of FEMs are commonly used in volcano geodesy, and all are sensitive to choices for domain size, boundary conditions, interpolation functions, and mesh generation (Novoa et al. 2019; Zienkiewicz 2005). Some widely used FEMs are commercial, although open source options are also available (Aagaard et al. 2013; Bodart et al. 2022; Garg et al. 2021; Lindsay et al. 2022; Longo et al. 2012; Rucker et al. 2022). Boundary integral or boundary element methods (BEMs) only discretize boundaries where stress or displacement conditions are applied, and several types are used (Cayol and Cornet 1997; Crouch and Starfield 1983). BEMs produce denser system matrices than FEMs, but typically have fewer degrees of freedom and thus are often more computationally efficient. BEMs also typically require fewer user choices than FEMs. However, BEMs are generally limited to homogeneous materials, and the commonly used constant dislocation BEM only converges within a few percent without additional treatment of dislocation edge singularities (Liu 2016). Other numerical approaches such as finite difference (Coco et al. 2014) or finite volume methods are at present less commonly used for volcano deformation, but are common in the similar problems associated with fault mechanics (Erickson et al. 2020).

We present a series of verification exercises. In each exercise, participants used models of their choice to submit predictions of displacements and stresses along two radial transects, a surface transect and a subsurface transect halfway between the top of the reservoir and the surface. The transects are 5 km long, since for most of these exercises deformation has decayed significantly by 5 km. We asked participants to provide metadata about mesh resolution, domain size, and domain boundary condition, but we did not provide guidelines on these choices or on convergence testing to gain a sense for the accuracy of models as they are used in practice. Submissions following the format specifications given on the community website could be uploaded in either “guest” mode for testing or “permanent” mode linked to a user account (these could still be updated at later times by the submitter).

All problems solve the equations of static linear elasticity without a body force (no gravity)

$$\frac{\partial \sigma_{ij}}{\partial x_j} = 0 \quad (1)$$

along with appropriate boundary and standard compatibility conditions. Cartesian coordinates (x, y, z) are indicated by x_j , and σ_{ij} is the stress tensor using “Einstein” notation in which repeated indices are summed. In an isotropic (although possibly inhomogeneous) linear elastic solid following Hooke's law

$$\sigma_{ij} = \lambda e_{kk} \delta_{ij} + 2G e_{ij} \quad (2)$$

where e_{ij} is the strain tensor (repeated indices are summed), δ_{ij} is the delta function, and λ and G are elastic constants (Lamé's first parameter and shear modulus, respectively) that may be spatially variable in inhomogeneous scenarios. Hooke's law is often written in terms of Poisson's ratio $\nu = \lambda / (2(\lambda + G))$ and Young's modulus $E = 2G / (1 + \nu)$ as $E e_{ij} = (1 + \nu) \sigma_{ij} - \sigma_{kk} \delta_{ij}$.

We present all forward models by showing the normalized root mean squared difference (NRMSD) of each submission component (displacement or stress) s_i from reference component s_i^{ref} :

$$NRMSD_i = \frac{\sqrt{\sum_{n=1}^N (s_i(n) - s_i^{ref}(n))^2}}{\sqrt{\sum_{n=1}^N (s_i^{ref}(n))^2}} \quad (3)$$

for N points along the radial transects. For exercises without surface topography, shear stress components of surface transects should be zero to satisfy the free surface condition. For these components we instead use:

$$NRMSD_i = \frac{\sqrt{\sum_{n=0}^N (s_i(n))^2}}{PN^{1/2}} \quad (4)$$

where the prescribed pressure P is included to nondimensionalize the error expression. For exercises where an exact analytical solution is known, we use this as the reference so that the NRMSD metric directly measures error. For exercises where an exact analytical solution is not known, we use a mean of multiple submissions as the reference so that the NRMSD metric provides information about the variation between submissions. The NRMSD metric provides a compact way to examine model accuracy or variance, but it does not reveal the spatial distribution of model error/variance. We thus also plot surface displacements for all exercises, and more detail can be seen in the full sets of displacement and stress plots in supplemental figures S1-S12 or through the exercise website.

Forward model exercise 1: sphere in a homogeneous half space

Exercise 1 considers a spherical reservoir at three different depths in a homogeneous half space (Fig. 2); this can be considered a benchmark against the Zhong series expansion model that converges to the exact solution (Zhong et al. 2019). We ask participants to solve the quasistatic linear elastic governing equations on a semi-infinite Cartesian (x, y, z) domain with coordinate origin centered on a flat, stress-free interface above a spherical magma reservoir surface Ω defined by $x^2 + y^2 + (z + D)^2 = R^2$ with reservoir radius $R = 1$ km and reservoir centroid depth below the free surface D . With the domain defined, boundary conditions for Cauchy and Hooke equations are

$$\begin{aligned} \sigma_{ij}(\Omega) n_j n_i &= -P \\ \sigma_{zz}(x, y, z = 0) &= 0 \\ \sigma_{rz}(x, y, z = 0) &= 0 \end{aligned} \quad (5)$$

with n an inward pointing normal vector, and P the reservoir pressure change (relative to lithostatic pressure). It is understood that traction goes to zero far from the reservoir in the half space. Exercises 1A, 1B, and 1C use reservoir centroid depth D of 1.25 km, 2 km, and 4 km, respectively. All three scenarios use uniform $\nu = 0.25$, $G = 10$ GPa, and $P = 10$ MPa.

We use a Zhong series expansion model calculated to 64th order (Zhong et al. 2019), which testing shows converges to near machine precision for the reservoir depth/radius ratios considered in these exercises, as the reference for comparing other submissions against (Figs. 2, 3, 4, and 5). We note that these exercises identified an error in the published implementation of the Zhong model.

Multiple other analytical approximations are available for spherical reservoirs in a homogeneous half space (Table 1). Figure 3 shows the convergence of the commonly used Mogi and McTigue models with increasing depth (i.e., depth/radius ratio), illustrating convergence of NRMSD at near-expected rates $((R/D)^3$ for Mogi and $(R/D)^6$ for McTigue). Implementation errors were also fixed in the dMODELS and VSM McTigue models as a result of these exercises (Battaglia et al. 2013; Trasatti 2022), although there is still some difference between the McTigue submissions in these exercises. However, as expected, all of the McTigue models become more accurate with increasing reservoir depth (i.e., depth/radius ratio). For the 1.25 km deep reservoir, the Mogi and McTigue models show significant surface displacement error (0.47 NRMSD for Mogi and 0.23 NRMSD for McTigue, Fig. 4), for the 2 km deep reservoir, the Mogi model still shows significant error (0.11 NRMSD) but the McTigue models are reasonably accurate (0.01 NRMSD), and for the 4 km deep reservoir, both types of models

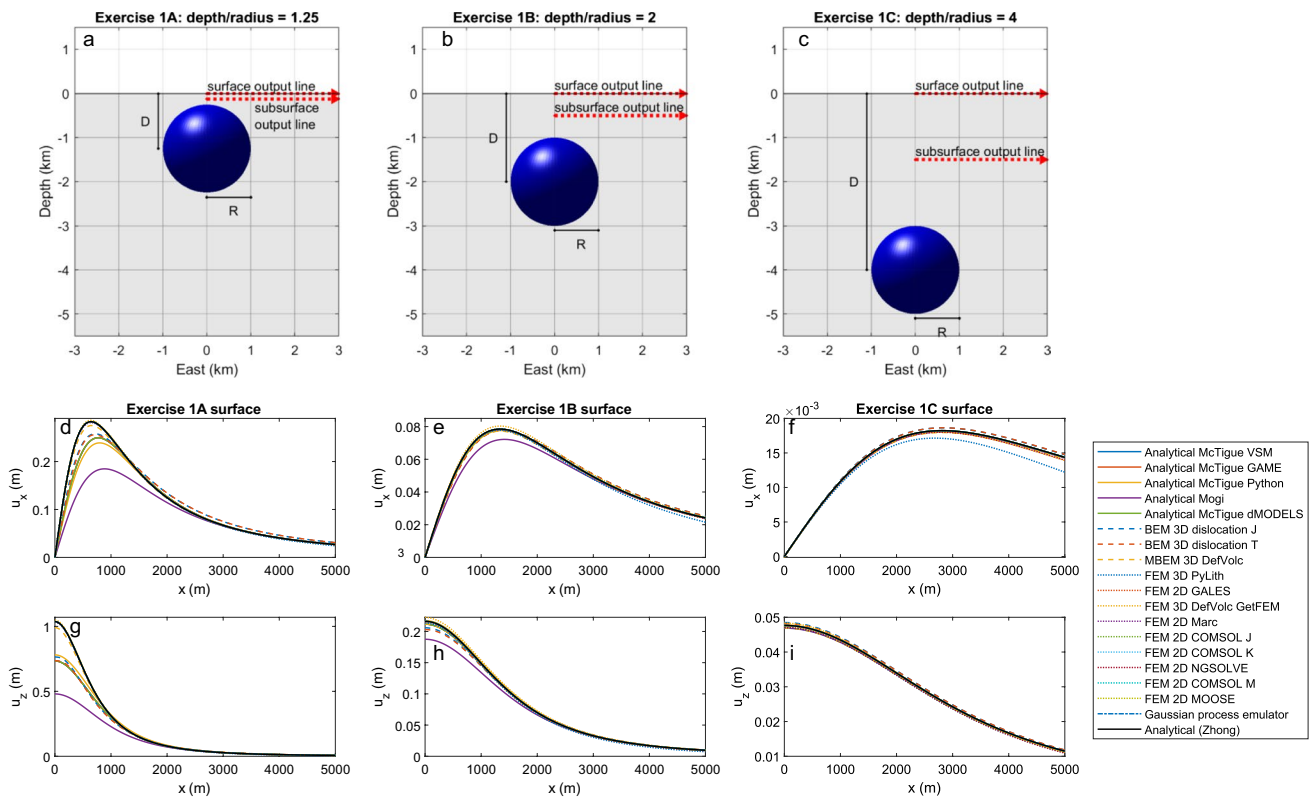


Fig. 2 Exercise 1: sphere in a homogeneous half space. **a–c** Problem geometry, with dashed output lines indicating the transects along which displacements and stresses are reported at 10 m intervals out to

5 km. **d–i** Surface displacement submissions; Table 1 provides details about each model and additional plots can be found in the supplemental material and exercise website

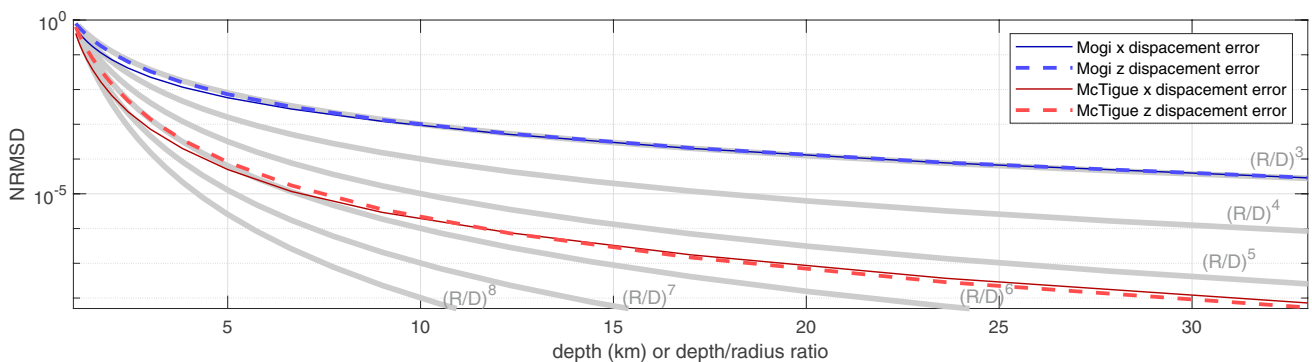


Fig. 3 Convergence of surface displacements from approximate analytical Mogi and McTigue models relative to a Zhong series expansion model for different radius/depth (R/D) ratios. Several different order polynomials are shown for comparison. Error at a single loca-

tion, rather than the aggregate normalized root mean squared difference (NRMSD) metric, would generally more closely follow the theoretical accuracy of $(R/D)^3$ for the Mogi model and $(R/D)^6$ for the McTigue model

are reasonably accurate ($NRMSD < \sim 0.01$). Stresses are generally inaccurate for these models ($NRMSD \sim 1$). All of the analytical models have computation times $\ll 1$ s, except for the Zhong model which can take multiple seconds if many terms (> 50) in the series expansion are computed.

Several 3D BEMs were submitted (Table 1). Two dislocation BEMs using triangular elements (Nikkhoo and

Walter 2015) were submitted with different numbers of reservoir mesh elements (320 and 4972). Both show similar surface displacement accuracy to the McTigue models (up to 0.21 NRMSD) for the 1.25 km deep reservoir, but their accuracy does not increase as quickly with depth. The dislocation BEMs provide generally more accurate stresses than McTigue models, but still exhibit up to 1 NRMSD for

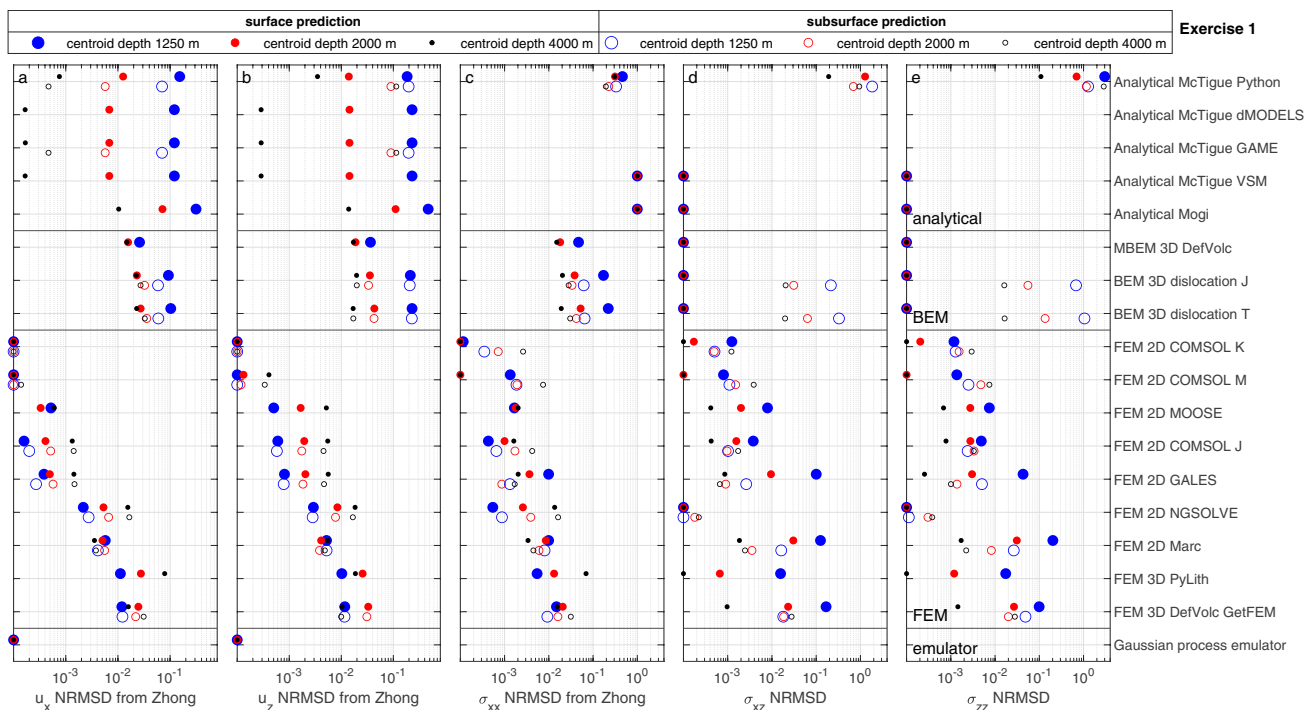


Fig. 4 Normalized root mean squared difference (NRMSD) for all exercise 1 (sphere in a homogeneous half space) submissions compared to a Zhong series expansion model. Values less than the x-axis

bounds are plotted at the bounds. The modified NRMSD metric normalized by reservoir pressure is used for σ_{zz} and σ_{xz} at the free surface (**a–e**)

subsurface σ_{zz} . Convergence testing for a constant dislocation BEM demonstrates that it does not actually converge as the mesh is refined (Fig. 5) due to element edge singularity effects. A mixed BEM (MBEM) (Cayol and Cornet 1997) was submitted with up to 5120 reservoir mesh elements; this provides reasonably accurate stresses and displacements for all depths (<0.05 NRMSD) and converges with reservoir mesh refinement (Fig. 5). The BEMs have reported computation times of tens of seconds to tens of minutes per simulation, appreciably longer than all the analytical models.

Multiple FEMs were submitted (Table 1); some with commercial software COMSOL® and Marc®, and others with open source codes or libraries: PyLith (Aagaard et al. 2013), GALES (Garg et al. 2021; Longo et al. 2012), MOOSE (Lindsay et al. 2022), NGSOLVE (Rucker et al. 2022), and DEFVOLC fictitious domain based on getFEM++ (Bodart et al. 2022, 2020). All the FEMs have <0.1 NRMSD in displacements and stresses for all reservoir depths. Some outlier FEMs are 3D, so likely used coarser meshes for computational reasons. We show convergence testing from two models: NGSOLVE using 4th order elements and COMSOL® using 2nd order elements (Fig. 5). We do not address factors such as mesh size and element order in detail but note that for quadratic elements even a fairly coarse mesh size of 270 m can yield error <0.01 NRMSD given a large enough domain size. However,

domain sizes of 20 km (or 10 times the reservoir depth) are needed to obtain error <0.01 NRMSD, whether “fixed” (zero displacement) or “roller” (zero normal displacement plus zero tangential traction) domain edge boundary conditions are used. In contrast, the “infinite element” coordinate transform approach enables high accuracy to be achieved with a domain size only slightly larger than the region of interest. Reported computation times per simulation vary from seconds-minutes for 2D models to tens of minutes for 3D models, suggesting that for 3D computations BEMs will often be faster than FEMs.

One submission used a Gaussian process emulator trained on around 500 FEM simulations (Anderson and Gu 2022; Anderson et al. 2019). The emulator has similar accuracy to the best FEMs for surface displacements for all scenarios. Computation times per emulator prediction are on the order of 0.001 s, which is comparable to most analytical models.

Forward model exercise 2A: sphere in a homogeneous half space with topography

Exercise 2A considers a spherical reservoir in a homogeneous half space overlain by surface topography consisting of a Gaussian “volcano” (Fig. 6). The setup is the same as exercise 1B, but with boundary conditions given by

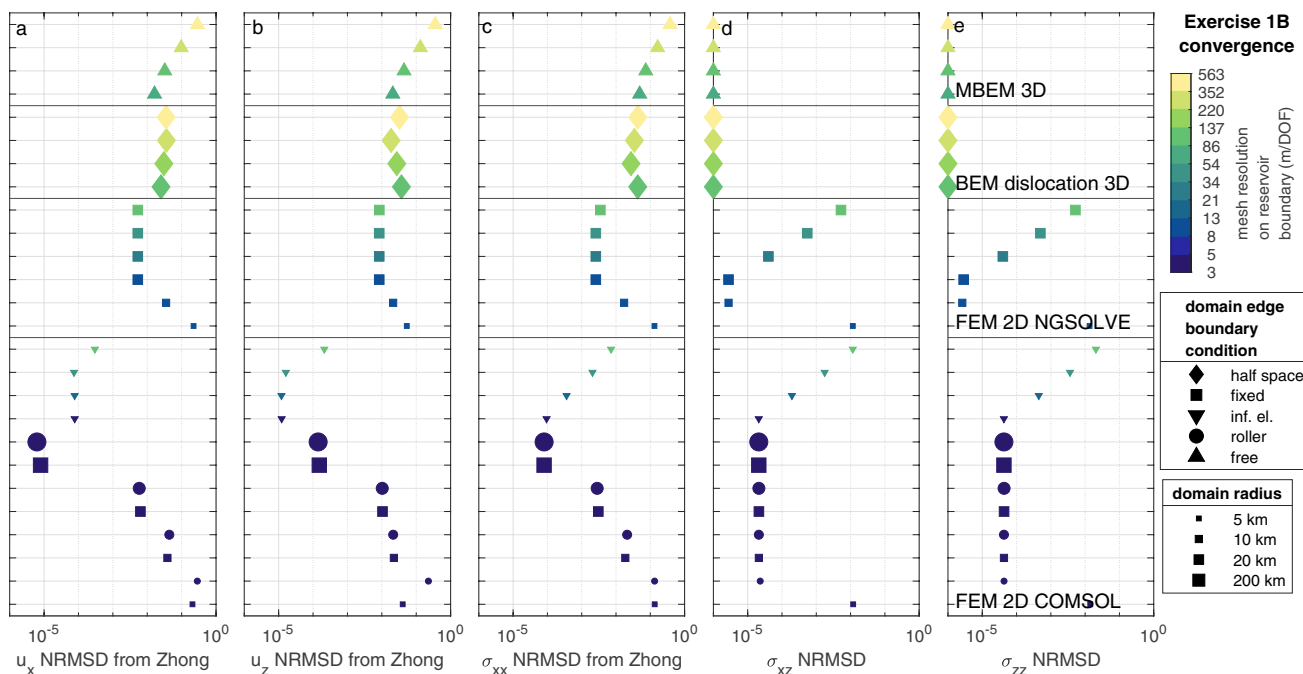


Fig. 5 Convergence of the normalized root mean square difference (NRMSD) of selected numerical methods compared to a Zhong series expansion model for different mesh/boundary treatments in exercise 1B (sphere in a homogeneous half space, centroid depth 2 km). Values $< 10^{-6}$ are plotted at 10^{-6} . The modified NRMSD metric normalized by reservoir pressure is used for σ_{zz} and σ_{xz} at the free surface (a–e). Mesh resolution is shown by the average distance per degree of freedom (m/DOF) along the reservoir boundary; this is equal to

average element size divided by element order (1 for both BEMs, 4 for NGSOLVE, and 2 for COMSOL®). Marker sizes indicate domain radius and shapes indicate outer boundary conditions (BC): diamonds for half space BEMs with no outer boundary, squares for “fixed” BC (zero displacement), circles for “roller” BC (zero normal displacement plus zero tangential traction), and triangles for “infinite element” BC (using coordinate transformations to approximate an infinite domain)

$$\begin{aligned} \sigma_{ij}(\Omega)n_j n_i &= -P \\ \sigma_{zz}(x, y, z = h(\rho)) &= 0 \\ \sigma_{rz}(x, y, z = h(\rho)) &= 0 \end{aligned} \tag{6}$$

where $\rho = x^2 + y^2$ is a 2D (cylindrical) distance and

$$h(\rho) = H \exp\left(-\frac{\rho^2}{2R_e^2}\right) \tag{7}$$

defines a Gaussian volcanic edifice overlying the magma reservoir. Parameters are $R = 1$ km, $D = 2$ km (beneath the flat surface), $R_e = 1$ km, $H = 1.5$ km, $\nu = 0.25$, $G = 10$ GPa, and $P = 10$ MPa.

In exercise 2A, exact solutions are not known so we use the average of all submitted FEMs as a reference against which to examine the variance in model results, after verifying that there are no visibly large FEM outliers (Figs. 6 and 7). Variance between all numerical models (FEM + MBEM) is < 0.03 NRMSD for displacements and 0.07 NRMSD for stress, and some of the outlier FEMs are 3D and thus likely used coarser meshes to reduce computational cost.

In this exercise, analytical models that neglect topography or only apply a varying depth (zeroth-order)

correction (Williams and Wadge 1998) produce appreciably different surface displacements (by at least 0.2 NRMSD) from numerical models, highlighting the importance of accounting for topography in this scenario. Two existing implementations of the Williams and Wadge (2000) small slope (first-order) topographic corrections produce different surface displacements from each other, and also differ from numerical models. This suggests that there is an error in at least one of the implementations, but it also highlights the limits of the correction for large topography. The first-order corrections require computation times of seconds for a McTigue model, so could be faster than numerical models and thus useful for smaller topography.

Forward model exercise 2B: spheroid in a homogeneous half space

Exercise 2B considers an oblate (vertically shortened) sill-like spheroidal reservoir in a homogeneous half space (Fig. 8). The setup is the same as exercise 1, but with the reservoir defined by

Table 1 Forward model submission information. “2D” indicates 2D axis-symmetric models. For outer domain edge boundary conditions, “fixed” is zero displacement, “roller” is zero normal displacement plus zero tangential traction, “inf. el.” (infinite element) uses coordinate transformations to approximate an infinite domain, and “free” is zero traction. Mesh and domain size values are approximate representative values;

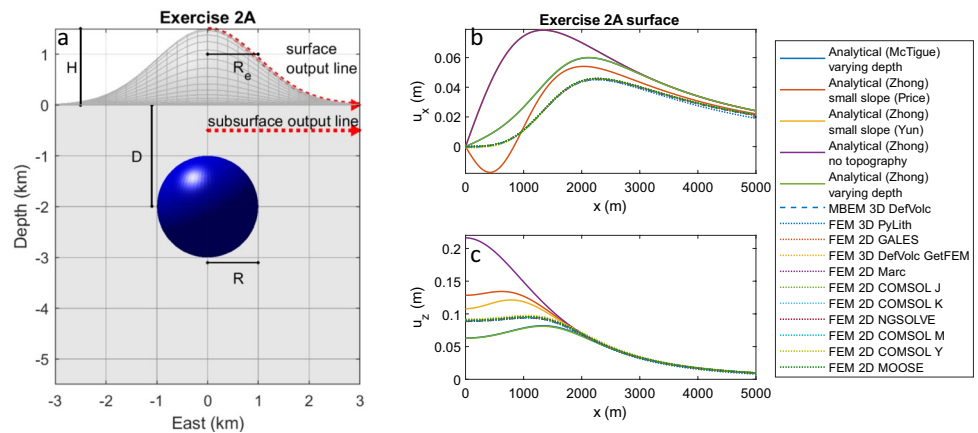
some participants used different discretization orders, used meshes with variable element sizes along the reservoir, and/or used slightly different mesh and domain sizes for different exercises. Only order of magnitude computation times are shown as participants reported computation times on different hardware

Description	Submitter	Element size on reservoir (m)	Domain radius (km)	DOMAIN edge boundary condition	Compute time order of magnitude (s)	Reference
Analytic Zhong	Crozier	none (64th order expansion)			1E2	Corrected from Zhong model (Zhong et al. 2019)
Analytic McTigue dMODELS	Kim	None				Battaglia et al. (2013)
Analytic McTigue python	Angarita	None				
Analytic McTigue varying depth	Angarita	None				
Analytic Mctigue GAME	Cannavo	None				Cannavò (2019)
Analytic McTigue VSM	Astort	None			1E−2	Trasatti (2022)
Analytic Mogi	Crozier	None			1E−2	Implemented based on Mogi (1958)
Analytic Zhong varying depth	Crozier	None (64th order expansion)			1E2	Corrected Zhong model with varying depth (Williams and Wadge 1998)
Analytic Zhong small slope (Yun)	Crozier	None (64th order expansion)			1E2	Corrected Zhong model with small slope topography (Williams and Wadge 2000) code by S. Yun
Analytic Zhong small slope (Price)	Crozier	None (64th order expansion)			1E2	Corrected Zhong model with small slope topography (Williams and Wadge 2000) code by E. Price
Analytic Cervelli	Crozier	None			1E−2	Cervelli (2013)
Analytic Nikkhoo point ECM	Crozier	None			1E−2	Nikkhoo et al. (2017)
Analytic Nikkhoo finite ECM	Crozier	None (10000 points)			1E−1	Nikkhoo and Rivalta (2022)
Analytic Fialko Crack	Crozier	None (2 integration intervals, tolerance 1E−6)			1E−1	Fialko et al. (2001)
MBEM 3D DEFVOLC	Shreve	70	20	Free	1E2	Cayol and Cornet (1997); Fukushima et al. (2005)
BEM 3D dislocation J	Crozier	140	None		1E2	Use triangular dislocations from Nikkhoo and Walter (2015)
BEM 3D dislocation T	Wang	35	None		1E3	Use triangular dislocations from Nikkhoo and Walter (2015)
FEM 2D COMSOL K	Anderson	1	120	inf. el	1E1	COMSOL Multiphysics®

Table 1 (continued)

Description	Submitter	Element size on reservoir (m)	Domain radius (km)	DOMAIN edge boundary condition	Compute time order of magnitude (s)	Reference
FEM 2D COMSOL M	Head	10	20	inf. el	1E0	COMSOL Multiphysics®
FEM 2D MOOSE	Zhan			roller	1E0	Lindsay et al. (2022)
FEM 2D COMSOL J	Crozier	100	50	fixed	1E1	COMSOL Multiphysics®
FEM 2D GALES	Garg	10	50	fixed	1E0	Garg et al. (2021); Longo et al. (2012)
FEM 2D NGSOLVE	Karlstrom & Rucker	50	20	fixed	1E1	Rucker et al. (2022)
FEM 2D Marc	Silverii	50	80	roller	1E1	MSC Software Marc®
FEM 3D PyLith	Iozzia & Currenti	50	10	fixed	1E4	Aagaard et al. (2013)
FEM 3D DefVolc GetFEM	Dabaghi		20	fixed	1E3	DefVolc fictitious domain based on getFEM++ (Bodart et al. 2022, 2020)
Gaussian process emulator	Anderson	Trained on FEMs similar to “FEM 2D COMSOL K”			1E−3	Anderson and Gu (2022); Anderson et al. (2019)

Fig. 6 Exercise 2A: sphere in a homogeneous half space with Gaussian topography. **a** Problem geometry, with dashed output lines indicating the transects along which displacements and stresses are reported at 10 m intervals out to 5 km. **b, c** Surface displacement submissions; Table 1 provides details about each model and additional plots can be found in the supplemental material and exercise website



$$\frac{\rho^2}{R_p^2} + \frac{z^2}{R_z^2} = 1 \tag{8}$$

Parameters are reservoir horizontal semi-diameter $R_p = 1$ km, reservoir vertical semi-diameter $R_z = 0.1$ km, $D = 1.1$ km, $\nu = 0.25$, $G = 10$ GPa, and $P = 10$ MPa.

In exercise 2B, exact solutions are not known so we use the average of all submitted FEMs as a reference against which to examine the variance in model results, after verifying that there are no visibly large FEM outliers (Figs. 8 and 9). Variance in all FEMs is less than 0.03 NRMSD, and some outlier FEMs are 3D and thus likely used coarser meshes for computational reasons. The dislocation BEMs and the MBEM are similar to FEMs (< 0.10 NRMSD),

and the FEM-trained emulator is also similar to FEMs (< 0.07 NRMSD).

We show several approximate analytical models for comparison. One finite ellipsoidal model (Cervelli 2013) is extended from a previous model (Yang et al. 1988) and handles prolate or oblate dipping ellipsoids with accuracy that increases with the ratio of the shallowest depth along the spheroid over the minimum semi-diameter. Another finite spheroidal model (Nikkhoo and Rivalta 2022) offers similar accuracy and can consider more general geometries, but requires more computation time (order 0.1 s compared to 0.01 s). Both models differ appreciably from FEMs (by 0.22 NRMSD) in this scenario. A point spheroid model (Nikkhoo et al. 2017) is less accurate, differing from FEMs by

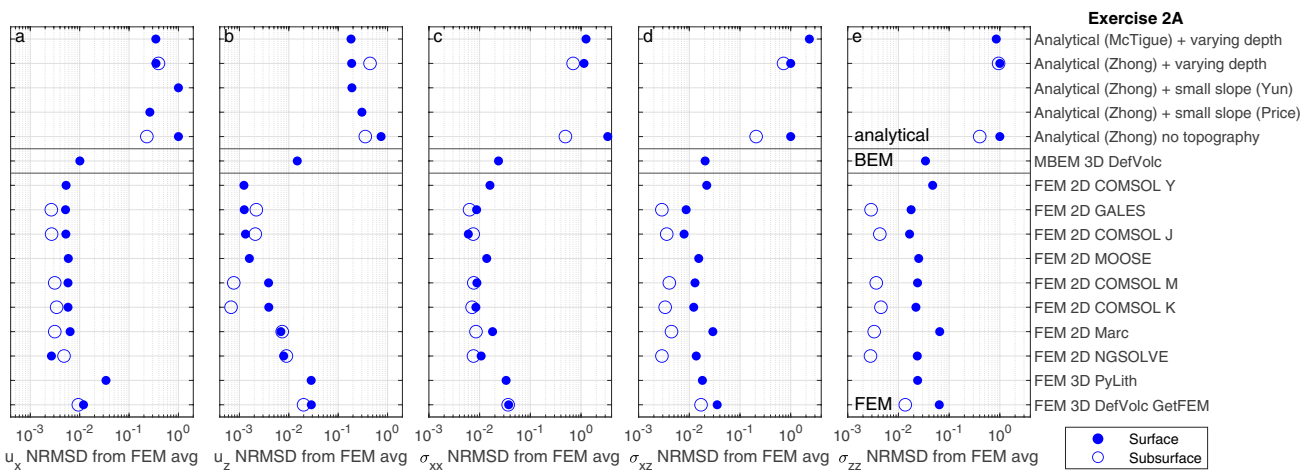
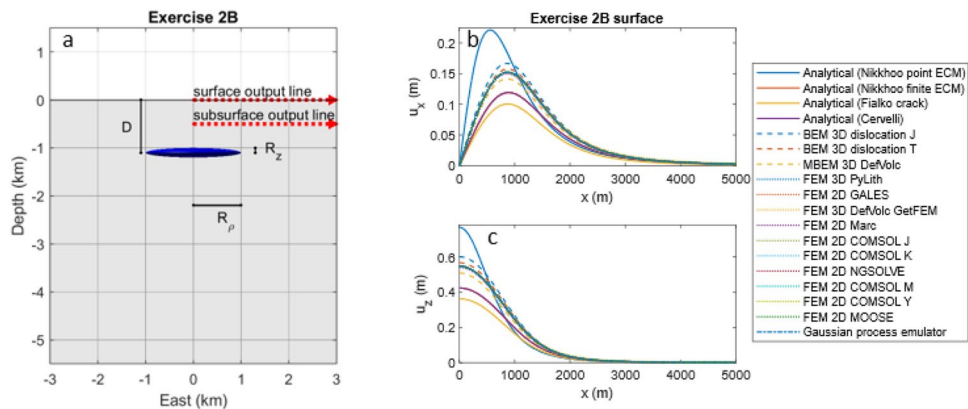


Fig. 7 Normalized root mean squared difference (NRMSD) for all exercise 2A (sphere in a homogeneous half space with Gaussian topography) submissions relative to the average FEM submission. In this case, the NRMSD metric indicates variability between models rather than error or accuracy, and the FEM average may be biased (e.g., due to overrepresenting COMSOL®). For this exercise the

NRMSD expression in Eq. 3 is used for all stresses since the topography makes σ_{zz} and σ_{xz} non-zero at the free surface. The label “varying depth” indicates a zeroth-order topographic correction (Williams and Wadge 1998), and “small slope” indicates a first-order topographic correction (Williams and Wadge 2000) (for which two different implementations were tested)

Fig. 8 Exercise 2B: oblate spheroid in a homogeneous half space. **a** Problem geometry, with dashed output lines indicating the transects along which stresses and displacements are reported at 10 m intervals out to 5 km. **b, c** Surface displacement submissions; Table 1 provides details about each model and additional plots can be found in the supplemental material and exercise website



0.46 NRMSD. Another approximate analytical model for an ellipsoidal reservoir has been derived (Amoruso and Crescentini 2013, 2011) but is not publicly available. We also show an analytical model for a penny-shaped crack (Fialko et al. 2001), which for this highly oblate reservoir provides a reasonable approximation, differing from FEMs by 0.33 NRMSD.

Forward model exercise 2C: sphere in a heterogeneous half space

Exercise 2C considers a spherical reservoir in a heterogeneous half space where elastic moduli vary with distance from the reservoir to approximate a thermal gradient (Fig. 10). The setup is the same as exercise 1B, but with spatially variable elastic coefficients. Poisson’s ratio and Young’s modulus are assumed to be temperature

dependent (Bakker et al. 2016) and vary in a radial direction away from the reservoir, with $r^2 = x^2 + y^2 + (z + D)^2$:

$$E(r) = E_0 \left[1 - \frac{1}{2} \left(\exp \left(\frac{T(r)}{T_R} \right) - 1 \right) \right] \tag{9}$$

$$\nu(r) = \left(1 - \frac{E(r)}{E_0} \right) (\nu_R - \nu_0) + \nu_0 \tag{10}$$

Temperature distribution (in degrees Celsius) is given by the infinite space conduction solution outside of $r = R$ as $T(r) = (T_R - T_0) \frac{R}{r} + T_0$. Parameters are $R = 1$ km, $D = 2$ km, far-field Poisson’s ratio $\nu_0 = 0.25$, near-reservoir Poisson’s ratio $\nu_R = 0.4$, far-field temperature $T_0 = 100$ °C, near-reservoir temperature $T_R = 1000$ °C, far-field Young’s modulus $E_0 = 10$ GPa, and $P = 10$ MPa. We note that

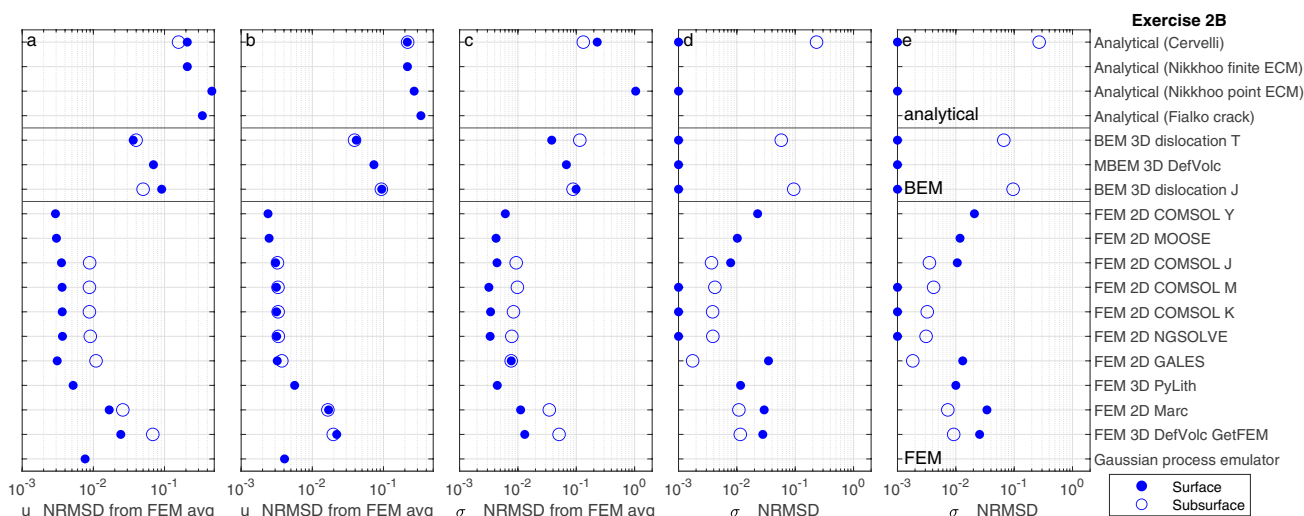


Fig. 9 Normalized root mean squared difference (NRMSD) for all exercise 2B (oblate spheroid in a homogeneous half space) submissions relative to the average FEM submission. In this exercise, the NRMSD metric indicates variability between models rather than error

or accuracy, except for σ_{zz} and σ_{xz} at the free surface where the modified NRMSD metric normalized by reservoir pressure is used **a–e**). The FEM average may be biased (e.g., due to overrepresenting COMSOL®). Values less than the x -axis bounds are plotted at the bounds

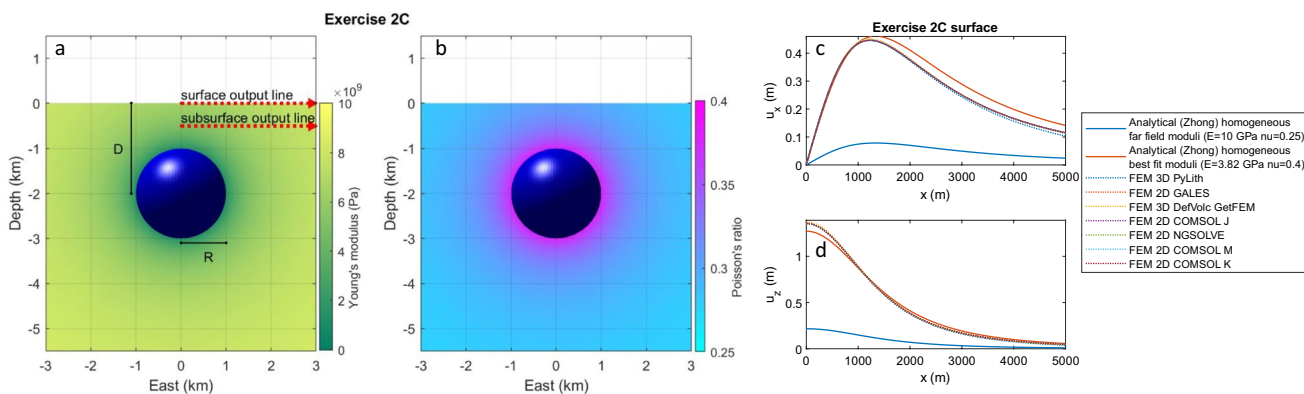


Fig. 10 Exercise 2C: sphere in a heterogeneous half space. **a, b** Problem geometry and elastic moduli, with dashed output lines indicating the transects along which displacements and stresses are reported at

10 m intervals out to 5 km. **c, d** Surface displacement submissions; Table 1 provides details about each model and additional plots can be found in the supplemental material and exercise website

elastic moduli generally also vary with depth but leave analysis of this for future exercises.

In exercise 2C, exact solutions are not known so we use the average of all submitted FEMs as a reference against which to examine the variance in model results, after verifying that there are no visibly large outliers in FEMs (Figs. 10 and 11). Of the models used in these exercises, only FEMs can directly address material heterogeneity. Variance in all FEMs is < 0.02 NRMSD, and some outlier FEMs are 3D so likely used coarser meshes for computational reasons.

We next examine how well homogeneous models can approximate the heterogeneous models. A Zhong series expansion model that uses the far-field moduli values ($\nu = 0.25$, $E = 10$ GPa) yields surface displacements that differ

from the heterogeneous FEMs by 0.9 NRMSD, showing that the heterogeneity has a large impact in this scenario. We then determine what moduli values yield the best match (i.e., minimum NRMSD) to the heterogeneous FEM “FEM 2D COMSOL J” by using a Nelder-Mead simplex inversion with bounds $0.25 < \nu < 0.4$, $0 < E < 10$ GPa, and all other parameters fixed according to the exercise specifications. A model predicting surface displacements that differ from the heterogeneous FEM by only 0.1 NRMSD can be found with $\nu = 0.4$ (the value at the reservoir boundary) and $E = 3.82$ GPa (the value ~ 200 m outside the reservoir boundary), showing that in this scenario surface deformation is most sensitive to the elastic moduli very near the reservoir. This suggests that a homogeneous model with elastic moduli

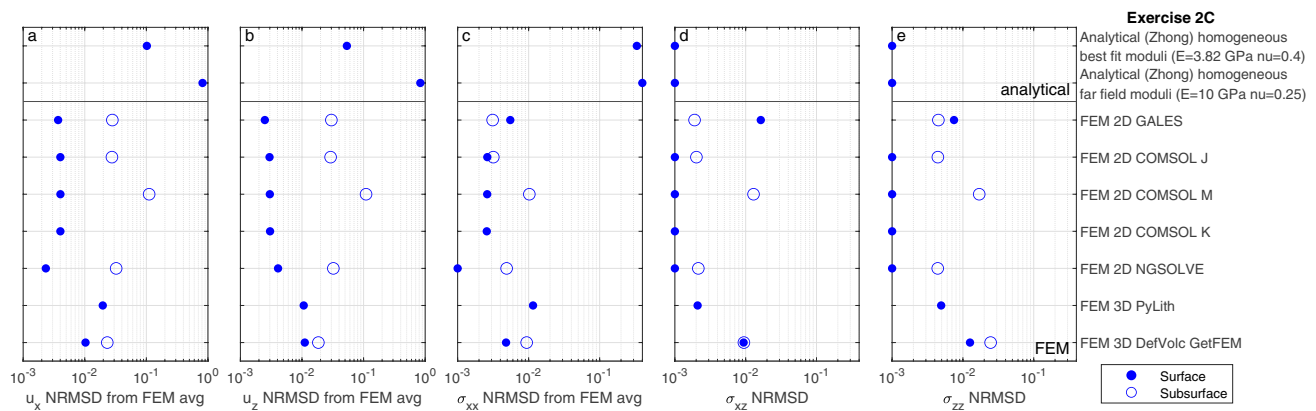


Fig. 11 Normalized root mean squared difference (NRMSD) for all exercise 2C (sphere in a heterogeneous half space) submissions relative to the average FEM submission. In this exercise, the NRMSD metric indicates variability between models rather than error or

accuracy, except for σ_{zz} and σ_{xz} at the free surface where the modified NRMSD metric normalized by reservoir pressure is used **a–e**. The FEM average may be biased (e.g., due to overrepresenting COMSOL®). Values less than the x-axis bounds are plotted at the bounds

representing those near the reservoir could provide a good enough approximation to be useful for some applications, since uncertainty in model parameters such as elastic moduli often exceeds 10% (Masterlark et al. 2016).

Inversion (validation) exercises

Reservoir parameters inverted from surface deformation data can differ due to variability in the types of data used, data processing methods (e.g., downsampling strategies), inversion methods (e.g., gradient descent or Monte Carlo sampling), forward model choice, and inherent tradeoffs between parameters (Anderson and Segall 2013; Bagnardi and Hooper 2018; Bato et al. 2018; Parks et al. 2012). Ground-based measurements include Global Navigation Satellite System (GNSS), tiltmeter, and strainmeter data. These have limited spatial coverage but high temporal resolution and accuracy (e.g., GNSS can provide mm accuracy for static positions and record 10 s of samples per second). Remote sensing products include satellite interferometric synthetic aperture radar (InSAR), SAR amplitude correlation, airborne lidar, and structure-from-motion data. These typically only have temporal resolution of days but good spatial coverage (e.g., InSAR provides up to sub-cm accuracy in time-series analysis and m-scale pixels for some sensor platforms). Each type of data has various sources of noise acting over different temporal and spatial scales. Inversions take a range of approaches for estimating solutions and/or uncertainty, for example, using methods based on linearization or methods based on various types of parameter searches (e.g., Monte Carlo sampling) (Aster et al. 2018; Bagnardi and Hooper 2018; Menke 2018; Tarantola 2004).

Inversion exercise data

For this first phase of inversion exercises (exercise 3), we focus on static elastic displacements from spherical reservoirs. We provided synthetic ground displacement data in the form of ascending and descending line-of-sight (LOS) unwrapped InSAR interferograms (Fig. 12 and Table 2). We also provided 3-component (east, north, vertical) data from 400 (20×20) regularly spaced observation points. This can be considered analogous to a GNSS survey although it is unrealistically dense; for comparison, even the best monitored volcanoes such as Kīlauea and Piton de la Fournaise have on the order of tens of measurement locations at a given time from permanent and/or temporary stations.

Participants could use either or both types of data. Spatially uncorrelated noise was added to the modeled GNSS displacements, and spatially correlated noise (Fukushima et al. 2005) was added to the InSAR data where correlation was a function of distance $C(r) = V \exp(r/\lambda)$ for variance V and correlation length λ . We provided two different datasets with different reservoir parameters and noise levels; a low noise set with better signal/noise ratio than most real data and a high noise set (Table 3). However, we emphasize that these exercises will not directly indicate how effectively reservoir parameters are estimated in real settings since we use simple forward models and noise sources, provide exact a priori information about these factors, and provide displacements rather than having participants infer these from raw data (for which processing methods can differ). We note that all displacement data and InSAR LOS direction information was given to participants at limited precision (i.e., rounded), which introduces an additional source of error.

Participants were informed that the forward model used to generate data was the Zhong series expansion model for a

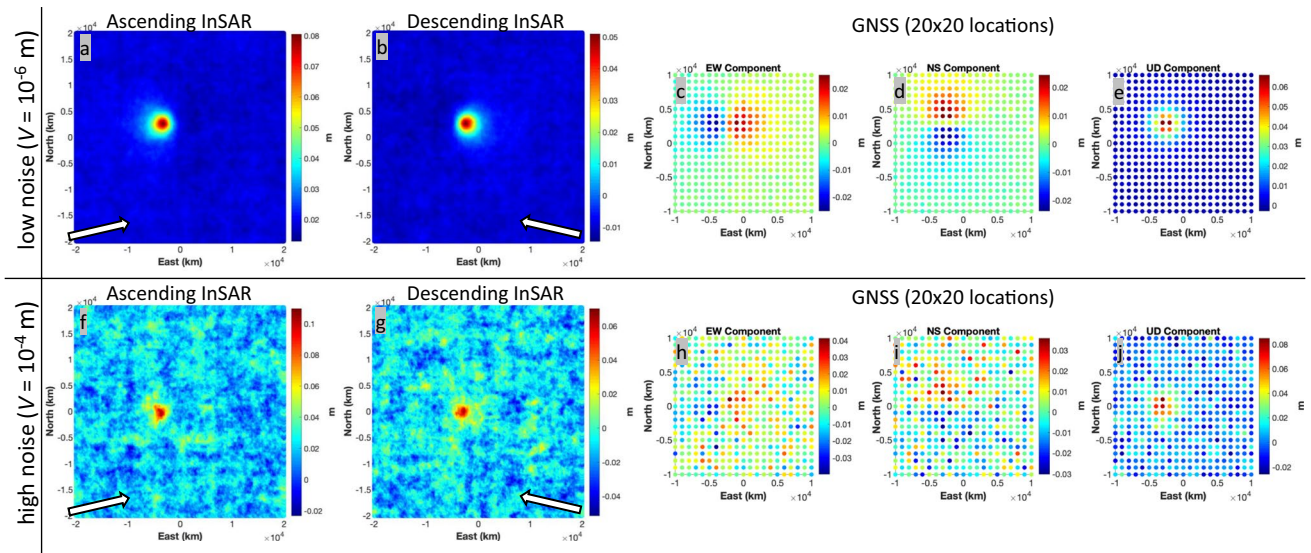


Fig. 12 Synthetic data for exercise 3 inversions. **a, b** Low noise InSAR data. **c–e** Low noise GNSS data. **f, g** High noise InSAR data. **h–j** High noise GNSS data

Table 2 Synthetic InSAR properties for both high noise and low noise datasets. The directions to satellites are given in terms of azimuth and incidence angles (from vertical) or line-of-sight (LOS) unit vectors

	Azimuth	Incidence	LOS x	LOS y	LOS z	Offset (m)
Ascending	− 11.514	33.901	− 0.54	− 0.11	0.83	0.018
Descending	− 165.960	36.870	0.56	− 0.14	0.80	− 0.010

Table 3 Synthetic data parameters for inversion exercises (exercise 3). Only the first two columns (noise parameters) were given to participants during the exercises

	GNSS + InSAR variance V (m)	InSAR correlation length λ (m)	East position (m)	North position (m)	Depth D (m)	Radius R (m)	Pressure P (Pa)	Volume change (m ³)
Low noise	1E− 6	750	− 2520	2850	2155	930	5.0E6	1.30E6
High noise	1E− 4	750	− 3010	0	2205	1500	1.19E6	1.45E6

pressurized spherical reservoir in a homogeneous elastic half space (Zhong et al. 2019), but other forward models could be used in inversions (e.g., faster approximate models). We provided the elastic moduli ($\nu = 0.25$, $G = 10$ GPa) and asked participants to estimate the reservoir position (east, north, depth), radius, volume change, and pressure change.

Inversion exercise parameter estimates

Exercise 3 results for the low and high noise datasets are shown in Figs. 13 and 14 and are grouped by the types of data and forward models used (Table 4). Parameter estimates were submitted using Mogi and McTigue models, a dislocation BEM, a MBEM, a Gaussian process emulator, and a Zhong series expansion model (Zhong et al. 2019) (i.e., the

true forward model). Participants were not given instructions on what cost functions to use or on how to report their best estimates of parameters (e.g., minimum cost or maximum likelihood or maximum a posteriori) or confidence intervals, to exemplify the variability in these measures that are used in practice.

We first consider the dependence of parameter estimates on the data types that participants chose to use. Three participants conducted otherwise identical inversions for just InSAR data, just GNSS data, and both data types. There are appreciable differences in parameter estimates depending upon the data type used, which emphasizes that care should be taken when comparing results for these exercises when different data types were used. Parameter estimates generally show the lowest accuracy and highest reported uncertainty

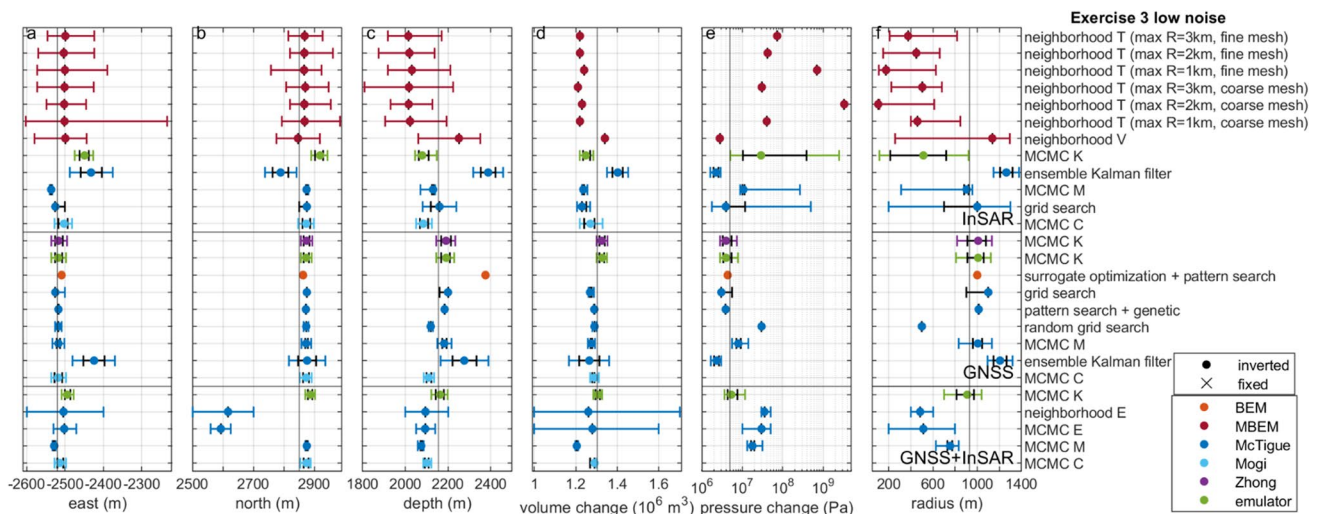


Fig. 13 Exercise 3 low noise parameter estimates. Vertical black lines are true parameters that correspond to a depth/radius ratio of ~2.3. Black and colored bars indicate 64% and 95% confidence bounds, respectively. Some participants did not report bounds or only reported

one set of bounds. For forward models except the Mogi model and Gaussian process emulator, volume change (d) is not inverted directly. Estimates of InSAR offsets are not shown

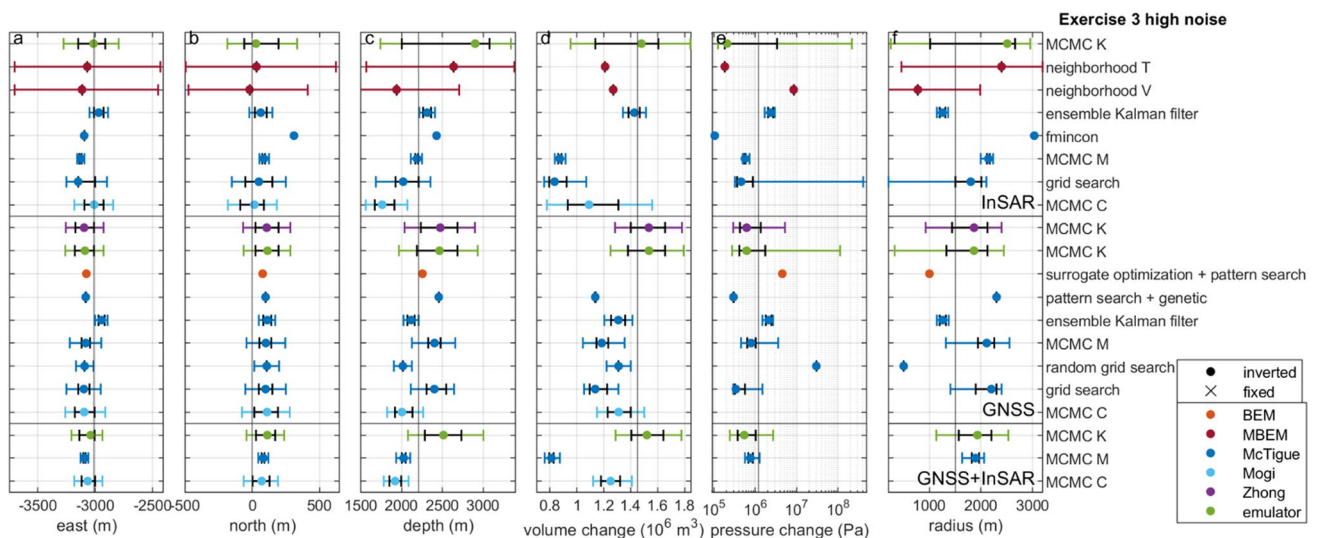


Fig. 14 Exercise 3 high noise parameter estimates. Vertical black lines are true parameters that correspond to a depth/radius ratio of ~1.5. Black and colored bars indicate 64% and 95% confidence bounds, respectively. Some participants did not report bounds or

only reported one set of bounds. For forward models except the Mogi model and Gaussian process emulator, volume change (d) is not inverted directly. Estimates of InSAR offsets are not shown

for just InSAR data; this occurs because the InSAR data only resolve line-of-sight displacements and contain spatially correlated noise.

East and north locations are generally reported to be the best constrained parameters; estimates are roughly similar across all submissions but still have a range of ~300 m for both low and high noise datasets. We expect the overestimation of north coordinates in most submissions partly reflects a bias introduced by the added noise and/or data

round-off error. Depth estimates have a range of ~400 m (or 20%) for low noise data and 800 m (or 35%) for high noise data. Volume change estimates have a range of 30% for low noise data and 50% for high noise data, pressure change estimates have a range of two orders of magnitude for both low and high noise data, and radius estimates have a range of one order of magnitude for both low and high noise data. With a Mogi model, pressure change and radius cannot be separately resolved, while for many other forward models

Table 4 Inversion submission information

Description	Submitter	Forward model	Downsampling (InSAR)	Inversion method
Neighborhood T	Shreve	MBEM, 1280 reservoir elements and 20 km domain radius with 23,940 ground surface elements (Cayol and Cornet 1997)	Quadtree (Jonsson 2002), 1836 points	Neighborhood algorithm (Fukushima et al. 2005), 34 iterations, 2016 forward models, appraisal on 10,000 points
Neighborhood V	Cayol	MBEM, 1280 reservoir elements and 20 km domain radius with 3470 ground surface elements (Cayol and Cornet 1997)	Quadtree (Jonsson 2002), 986 points	Neighborhood algorithm (Fukushima et al. 2005), 38 iterations, 1924 forward models, appraisal on 10,000 points
MCMC K (Zhong)	Anderson	Zhong series expansion (Zhong et al. 2019)	Quadtree (Jonsson 2002), 1420 points	Bayesian MCMC, uniform priors, 600,000 samples
MCMC K (emulator)	Anderson	Gaussian process FEM emulator (Anderson and Gu 2022; Anderson et al. 2019)	Quadtree (Jonsson 2002), 1420 points	Bayesian MCMC, uniform priors, 600,000 samples
Ensemble Kalman filter	Zhan	McTigue python		30 iterations
MCMC M	Angarita	McTigue python VMOD	Quadtree, controlled by variance in non-local means filter, 1942 points	Bayesian MCMC with 1,000,000 samples
Grid search	Crozier	McTigue dMODELS (Battaglia et al. 2013)	Uniform, Gaussian filter, 1681 points	Coarser resolution then finer resolution grid search, uniform priors, reduced chi-square, 2,000,000 samples
MCMC C	Novoa	Mogi GBS (Bagnardi and Hooper 2018)	Circular quadtree, 2944 points	Bayesian MCMC (Bagnardi and Hooper 2018)
Surrogate optimization + pattern search	Wang	Mogi then dislocation BEM using 5012 triangular elements (Nikkhoo and Walter 2015) with radius fixed to 1 km		MATLAB® surrogate optimization with Mogi for 1000 iterations, then MATLAB® pattern search with BEM for 10 iterations, unweighted L2 norm
Pattern search + genetic	Cannavò	McTigue GAME (Cannavò, 2019)		Pattern search with genetic algorithms
Random grid search	Le Mével	McTigue dMODELS (Battaglia et al. 2013)		Random grid search, weighted least squares
MCMC E	Trasatti	McTigue VSM (Trasatti 2022)	Personal subsampling algorithm, uniform in different areas	Bayesian MCMC (Trasatti 2022)
Neighborhood E	Trasatti	McTigue VSM (Trasatti 2022)	Personal subsampling algorithm, uniform in different areas	Neighborhood algorithm global optimization
fmincon	Kim	McTigue dMODELS (Battaglia et al. 2013)		MATLAB® fmincon, chi-square

pressure change and radius were directly inverted for and then volume changes were calculated given a formulation of reservoir elastic compressibility (often a full space approximation). However, for a spherical reservoir, strong trade-offs are generally expected between pressure change and reservoir radius, particularly for higher depth/radius ratios (McTigue 1987; Parks et al. 2012; Segall 2010). One participant tested the effect of using MBEMs with three different upper bounds on radius and found similar results for all parameters except pressure change. This highlights the need to use additional constraints in order to robustly constrain pressure changes and reservoir radius (Anderson et al. 2019).

Similar east and north location estimates were obtained with each type of forward model, suggesting that these parameters are not sensitive to forward model choice. Depth, volume change, and pressure change show more sensitivity to forward model choice, as expected (Dieterich and Decker 1975), although the relative variation between different forward models depends on the type of data and inversion methods used. For the same inversion method and type of data, FEM emulator parameter estimates nearly exactly match series expansion parameter estimates. Both parameter estimates also almost exactly match the true parameters in low noise data when InSAR and GNSS data are combined. We do not make one-to-one comparisons between other forward models given that different inversion methods were used, but in most cases McTigue and Mogi models underestimate volume change. This suggests that when inversion methods are well calibrated, forward model choice can appreciably impact results for reservoirs with moderate depth/radius ratios such as in the low noise scenario (with ratio ~ 2.3). However, there is generally more variation between parameter estimates using the same forward model than between parameter estimates using different forward models, which suggests that much of the variance between estimates is dominated by inversion methods rather than by forward model choice or even data types.

Inversion exercise uncertainty estimates

Importantly, the difference between different parameter estimates and/or the true parameter values often exceeds reported uncertainties, and reported uncertainties estimates differ significantly between submissions which could be due to a variety of factors. Inversions require defining misfit between data (vector u^{obs}) and model predictions (vector u^{mod}); commonly using the reduced chi-square metric $\chi^2 = (u^{obs} - u^{mod})^T C^{-1} (u^{obs} - u^{mod})$ which is weighted by data covariance matrix C . In these exercises, we specified C , but in practice, C is often estimated. Misfit can then be converted to likelihood L following the general relation $L \sim \exp(-\chi^2)$, which can be multiplied by potentially non-uniform prior distributions or terms accounting for

additional sources of uncertainty (Aster et al. 2018). Next, a sampling method is used to explore the parameter space; this can range from grid searches to iterative methods such as neighborhood algorithms or MCMC (Markov Chain Monte Carlo) methods that attempt to more densely sample regions where likelihood is higher and/or varying more abruptly (Sambridge 1999). Different instances of random noise can also be added to the data, and parameters that have a linear relation to data (e.g., reservoir pressure) can either be included in the nonlinear parameter searches or solved for separately given each parameter combination. Given a set of samples, the misfit or likelihood values can provide insight into the parameter space, and probability density functions (PDFs) can be calculated by integrating either over the likelihood function or over sample density (for likelihood-based sampling).

Figure 15 shows PDFs from a subset of the low noise inversions, as well as minimum reduced chi-square χ^2 misfits from a uniform grid search with a McTigue model. The χ^2 plots show relatively pronounced global minima for east location, north location, and depth, but much broader minima for radius, volume change, and pressure change. Most submitted PDFs from MCMC methods show comparatively narrow global maxima for all parameters, which is expected given the dense data we provided (which is typical for real InSAR data but not real GNSS networks), although some MCMC PDFs are much narrower than others. Many submitted PDFs from neighborhood algorithms used a smaller number of samples than the MCMC methods and show much broader PDFs, which could indicate that some of these PDFs are under-resolved. However, some of the neighborhood algorithm parameter estimates are still relatively accurate, and so in some cases (e.g., with computationally expensive forward models) there may be advantages to such methods that can use a smaller number of samples. Overall, there is appreciable variability between different PDF submissions, even when accounting for the use of different types of data and forward models. Some of these discrepancies might arise from using different downsampling methods, different (and potentially biased or overly restrictive) prior distributions/parameter bounds, and/or from using different (or differently configured) methods for searching the parameter space.

Discussion

The results of these exercises emphasize some important considerations for volcano deformation modeling. Even points that may seem obvious to some readers are worth discussing, as these exercises highlighted the diversity of modeling practices that are used across the community. We do not attempt to provide comprehensive guidelines,

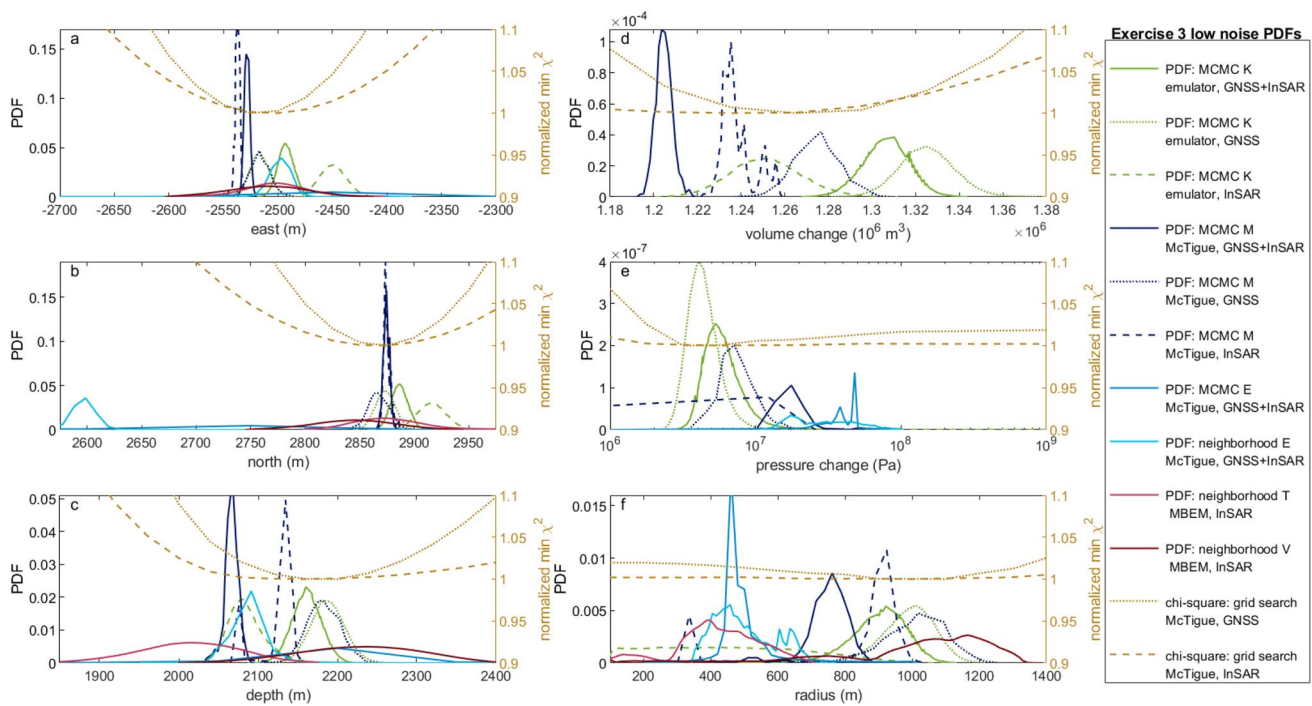


Fig. 15 Probability density functions (PDFs) from a subset of the exercise 3 low noise submissions. For forward models except the Gaussian process emulator, volume change (d) is not inverted directly. Coarser parameter resolution provided with some submissions

causes angular PDF appearances. Brown lines (right axes) show the minimum reduced chi-square χ^2 misfit (normalized so that the minimum is 1) that can be obtained with a McTigue model based on grid searches over the parameter space

given the limited scope of this first phase of exercises and the wide variety of volcano deformation scenarios. Rather, we focus on general forward and inverse modeling insights, and on identifying some promising avenues for further development.

Considerations for verifying forward models

While it is generally acknowledged that verification is an important part of using numerical models, these exercises identified several discrepancies in both analytical and numerical forward models which suggests that the volcano geodesy community could benefit from more systematic model verification practices. Analytical forward models might not always be tested thoroughly on the assumption that they were tested by previous users and/or are too simple to need extensive testing. However, the implementation errors we identified in several spherical reservoir forward models and topographic corrections show that verification is still important, with these exercises providing one way to check that a particular model implementation has been verified. For numerical forward models, convergence testing should be common practice. However, our results emphasize the importance of considering both mesh resolution and far-field boundary treatment (e.g., domain size and boundary conditions); for many submissions accuracy was

limited primarily by domain size, which often needs to be an order of magnitude or more larger than the region of interest (Figs. 4 and 5). These exercises can provide rough indications of appropriate parameter choices, but additional testing should be conducted for the conditions of each application.

Advantages of different forward models

Most analytical models have computation times that are orders of magnitude faster than all of the numerical models (Table 1). However, the accuracy of available analytical models can be limited in cases with shallow or non-spherical reservoirs, steep topography, or heterogeneous rock properties, all of which are common in volcanic settings. For spherical reservoirs in homogeneous half spaces, when depth/radius ratios are greater than ~ 2 , it is reasonable to use the approximate Mogi or McTigue models (Figs. 3, 4, 13, and 14) (Segall 2010; Taylor et al. 2021), but when depth/radius ratios are lower these models can start to yield appreciable error in estimates of volume change and depth. The Zhong model is arbitrarily accurate, but at the expense of much larger computation times. For spheroidal reservoirs with low depth/radii ratios, all available analytical models are approximations that exhibit appreciable error, as is demonstrated for the sill-like reservoir in exercise 2B (Figs. 8 and 9). When topographic

features are present that have height/width ratios greater than ~ 0.3 , approximate topography corrections are generally not accurate (Segall 2010), as is demonstrated with the Gaussian hill topography in exercise 2A (Figs. 6 and 7). Such edifices would generally lead to overestimates of source elevation and pressure change (Cayol and Cornet 1998). Crustal rock in volcanic settings can exhibit complicated heterogeneity, including vertical stratification (Currenti et al. 2007; Masterlark 2007), or radial variation around magma reservoirs due to the impact of temperature on both elastic moduli (Bakker et al. 2016) and viscoelasticity (Dragoni and Magnanensi 1989). We only consider radial heterogeneity in elastic moduli from a steady-state conduction temperature profile, but exercise 2C shows that even just this one source of heterogeneity can appreciably impact predicted deformation (Figs. 10 and 11). For this scenario, deformation can be approximated reasonably well by a model using homogeneous elastic moduli with near-reservoir moduli (i.e., high-temperature) values. This suggests that when homogeneous elastic moduli are used, if they are prescribed a priori then near-reservoir values may be most appropriate, and if they are estimated from geodetic inversions then the estimates will likely reflect near-reservoir values (Anderson and Poland 2016). More studies are needed to address how well different types of heterogeneity can be approximated with analytical models; for example, vertical stratification can amplify surface displacements and lead to source elevation and pressure being overestimated (Currenti et al. 2007; Masterlark 2007).

BEMs can be more accurate than analytical models for considering topography and non-spherical reservoirs (Figs. 6, 7, 8, and 9), but are less flexible than FEMs since most cannot include heterogeneity. Care should be taken when using constant dislocation BEMs, since element edge singularity effects limit their accuracy (Fig. 5). While BEMs will generally have faster computation times than FEMs, making quantitative comparisons from these exercises is difficult given the variable dimensionality and mesh/domain sizes of submissions (Table 1).

All the FEMs were reasonably accurate for all exercises, despite the presence of some discrepancies due to the use of different mesh and domain sizes. Reported computation times for FEMs ranged widely (Table 1); this is partly due to differences in the discretizations and computational resources used but may also reflect the efficiencies of different codes. The computational metrics that are most important (e.g., memory use, speed, parallelizability) will depend on the application, and may evolve over time as most of these models are being actively developed. Importantly, several open source codes performed well in comparison to commercial software, although participants indicated that some FEMs do require more time to learn and/or use than others.

While it is feasible to conduct probabilistic inversions with FEMs or BEMs that have computation times of seconds-minutes, doing so requires using more computational resources and/or fewer samples than could be used with faster forward models, which our exercises indicate can result in less accurate PDFs. However, several submissions represent promising approaches for producing fast and accurate forward model predictions in inversions. Fictitious domain approaches allow increased efficiency when conducting multiple simulations with different model parameters (Bodart et al. 2022, 2016), while emulators trade an initial training cost for very fast subsequent predictions. Exercises 1 and 2B demonstrated the utility of a Gaussian process emulator for spherical or spheroidal reservoirs in a homogeneous half space, but further work is needed to develop emulators that consider more complex magma system geometries, topography, and heterogeneous rheology. This will require larger training times and/or building emulators specific to particular volcanoes over particular time periods but could be valuable long term.

Discrepancies between inversions

Ultimately, we found that inversion methods contributed much more than forward model choice to differences between parameter estimates, even in the unrealistically ideal scenario of having dense, low noise datasets and a known true forward model. For spherical reservoirs, some tradeoffs between pressure change, radius, volume change, and depth are expected (Parks et al. 2012), although submissions also exhibited differences in east and north locations. Importantly, many reported confidence bounds did not overlap with other estimates or with the true parameter values. This shows that even for inversions with only a few free parameters, it is still vital to test inversion methods with synthetic data and ensure that both parameter estimations and uncertainty estimations are accurate. These exercises provide a starting point, but additional problem-specific testing is important since parameter space exploration can be more difficult for more complex forward models and sparser or noisier data. Finally, these exercises emphasize the importance of comprehensively reporting uncertainty and carefully interpreting reported uncertainties. This can be facilitated by clear specification of what uncertainty sources (e.g., model error, data variance) were considered, using approaches such as hyperparameters to account for model uncertainty, and including plots of misfits and/or PDFs.

For all inversion methods, there will be tradeoffs between accuracy, robustness, and computational cost. Neighborhood algorithms typically used far fewer samples than MCMC sampling or grid searches to produce roughly similar parameter estimates. However, neighborhood algorithms produced broader PDF peaks than MCMC sampling, suggesting that

care needs to be taken that neighborhood algorithms are not under-resolving the parameter space. There is also discrepancy between PDF peaks in different MCMC inversions, indicating that similar care needs to be taken when calibrating these methods. In some cases, combining different inversion methods and/or forward models could be optimal, as in one submission that followed broad parameter searches using an approximate analytical forward model with more focused searches using a numerical model.

Future directions

These exercises only considered static elastic displacements from spheroidal reservoirs, and only tested inversions for synthetic and already processed data with a known spherical reservoir source model. Since discrepancies between submissions were found even for these simple scenarios, this project has demonstrated the importance of community verification and validation exercises. Feedback from participants also indicates that these exercises have been a useful learning tool. Using the SCEC earthquake verification and validation exercises as a template, we anticipate benefits from expanding these exercises to more complex volcano deformation problems. Important forward modeling scenarios include time-dependent poro-viscoelastic-plastic rock response, sheet intrusions, multiple deformation sources, hydrothermal fluid circulation, and surface loading. Important inversion scenarios include providing raw time-series data to test all stages of data processing workflows, providing complicated deformation sources with minimal a priori information, and providing data from real volcanoes with additional constraints from other data types beyond deformation. Like the SCEC exercises, this will likely require multiple concurrent efforts. Such efforts will have great potential for community building, forming standards of reproducibility, advancing methods development, and gaining new science insights. We also expect that model verification and validation exercises could be expanded upon or introduced in several other aspects of volcano science with great effect. Such efforts could be extended in common, rigorous, and sustained frameworks to advance volcano science, monitoring, and hazard forecasting.

Supplementary Information The online version contains supplementary material available at <https://doi.org/10.1007/s00445-023-01687-4>.

Acknowledgements We thank Maurizio Battaglia, James Hickey, and an anonymous reviewer for providing constructive feedback.

Author contribution Original draft: J. C. Review and editing: L. K., V. C., R. G., K. A., T. S., T. W., C. N., G. C., E. T. Exercise planning and design: L. K., E. M.-B., J. C., V. C., M.-G. B., R. G. Website design: M. A. V. Exercise participation: J. C., L. K., M. A., V. C., T. A. W., T. S., K. A., A. A., O. B., F. C., G. C., F. D., B. A. E., D. G., M. H., A. I., Y.

C. K., H. L. M., C. N. L., C. R., F. S., E. T., Y. Z. Additional analysis: J. C., L. K., T. W., T. S., V. C., K. A.

Funding Support was provided by the U.S. National Science Foundation (NSF) Research Coordination Network (RCN): Community Network for Volcanic Eruption Response (CONVERSE) under award NSF-EAR1830873 and Modeling Collaboratory for Subduction under award NSF-EAR1824343. Support was also provided by the International Association of Volcanology and Chemistry of the Earth's Interior (IAVCEI) Commission on Volcano Geodesy. CNL acknowledges support from the European Research Council (ERC) through the EU Horizon 2020 project DEEPVOLC (Grant 866085) and the UK Natural Environment Research Council (NERC) through the Centre for the Observation and Modelling of Earthquakes, Volcanoes and Tectonics (COMET, <http://comet.nerc.ac.uk>). AA and ET acknowledge funding by the LOVE-CF project 2020–2023 (INGV, Internal Register no. 1865 17/07/2020). FS acknowledges support by the EU Horizon 2020 project RELIANCE (Grant 101017501). LK acknowledges support from NSF grant 1848554. RG acknowledges support from NSF grant 2019232. MA acknowledges partial support through NSF grant 1855126. The exercise website can be found at www.driversofvolcanodeformation.org. Any use of trade, firm, or product names is for descriptive purposes only and does not imply endorsement by the U.S. Government. This is contribution no. 624 of the ClerVolc program of the International Research Center for Disaster Sciences and Sustainable Development of the University of Clermont Auvergne.

Declarations

Conflict of interest The authors declare no competing interests.

References

- Aagaard BT, Knepley MG, Williams CA (2013) A domain decomposition approach to implementing fault slip in finite-element models of quasi-static and dynamic crustal deformation. *J Geophys Res Solid Earth* 118:3059–3079. <https://doi.org/10.1002/jgrb.50217>
- Alshembari R, Hickey J, Williamson BJ, Cashman K (2023) Unveiling the rheological control of magmatic systems on volcano deformation: the interplay of poroviscoelastic magma-mush and thermoviscoelastic crust. *J Geophys Res Solid Earth* 128. <https://doi.org/10.1029/2023JB026625>
- Amoruso A, Crescentini L (2013) Analytical models of volcanic ellipsoidal expansion sources. *Ann Geophys* 56. <https://doi.org/10.4401/ag-6441>
- Amoruso A, Crescentini L (2011) Modelling deformation due to a pressurized ellipsoidal cavity, with reference to the Campi Flegrei caldera, Italy. *Geophys Res Lett* 38. <https://doi.org/10.1029/2010GL046030>
- Anderson K, Segall P (2013) Bayesian inversion of data from effusive volcanic eruptions using physics-based models: application to Mount St. Helens 2004–2008. *J Geophys Res Solid Earth* 118:2017–2037. <https://doi.org/10.1002/jgrb.50169>
- Anderson KR, Gu M (2022) Emulation of volcano deformation sources using machine learning models: a Gaussian process-based approach. AGU Fall Meeting Abstract #V52B-01, San Francisco, CA, 16 December 2022. 2022AGUFM.V52B..01A
- Anderson KR, Johanson IA, Patrick MR, Gu M, Segall P, Poland MP, Montgomery-Brown EK, Miklius A (2019) Magma reservoir failure and the onset of caldera collapse at Kilauea Volcano in 2018. *Science* 366. <https://doi.org/10.1126/science.aaz1822>
- Anderson KR, Poland MP (2016) Bayesian estimation of magma supply, storage, and eruption rates using a multiphysical volcano

- model: Kīlauea Volcano, 2000–2012. *Earth Planet Sci Lett* 447:161–171. <https://doi.org/10.1016/j.epsl.2016.04.029>
- Aster RC, Borchers B, Thurber CH (2018) Parameter estimation and inverse problems. Elsevier
- Bagnardi M, Hooper A (2018) Inversion of surface deformation data for rapid estimates of source parameters and uncertainties: a bayesian approach. *Geochem Geophys Geosyst* 19:2194–2211. <https://doi.org/10.1029/2018GC007585>
- Bakker RR, Frehner M, Lupi M (2016) How temperature-dependent elasticity alters host rock/magmatic reservoir models: a case study on the effects of ice-cap unloading on shallow volcanic systems. *Earth Planet Sci Lett* 456:16–25. <https://doi.org/10.1016/j.epsl.2016.09.039>
- Barall M, Harris RA (2015) Metrics for comparing dynamic earthquake rupture simulations. *Seismol Res Lett* 86:223–235. <https://doi.org/10.1785/0220140122>
- Bato MG, Lundgren P, Pinel V, Solidum R, Daag A, Cahulogan M (2021) The 2020 eruption and large lateral dike emplacement at Taal volcano, Philippines: insights from satellite radar data. *Geophys Res Lett* 48. <https://doi.org/10.1029/2021GL092803>
- Bato MG, Pinel V, Yan Y, Jouanne F, Vandemeulebrouck J (2018) Possible deep connection between volcanic systems evidenced by sequential assimilation of geodetic data. *Sci Rep* 8:11702. <https://doi.org/10.1038/s41598-018-29811-x>
- Battaglia M, Cervelli PF, Murray JR (2013) dMODELS: a MATLAB software package for modeling crustal deformation near active faults and volcanic centers. *J Volcanol Geoth Res* 254:1–4. <https://doi.org/10.1016/j.jvolgeores.2012.12.018>
- Bodart O, Cayol V, Court S, Koko J (2016) XFEM-based fictitious domain method for linear elasticity model with crack. *SIAM J Sci Comput* 38:B219–B246. <https://doi.org/10.1137/15M1008385>
- Bodart O, Cayol V, Dabaghi F, Koko J (2022) An inverse problem in an elastic domain with a crack : a fictitious domain approach. *Comput Geosci* 26:423–435. <https://doi.org/10.1007/s10596-021-10121-7>
- Bodart O, Cayol V, Dabaghi F, Koko J (2020) Fictitious domain method for an inverse problem in volcanoes, in: Haynes R, MacLachlan S, Cai X-C, Halpern L, Kim HH, Klawonn A, Widlund O (Eds.), *Domain decomposition methods in science and engineering XXV, Lecture Notes in Computational Science and Engineering*. Springer International Publishing, Cham, pp. 409–416. https://doi.org/10.1007/978-3-030-56750-7_47
- Cannavò F (2019) A new user-friendly tool for rapid modelling of ground deformation. *Comput Geosci* 128:60–69. <https://doi.org/10.1016/j.cageo.2019.04.002>
- Cayol V, Cornet FH (1998) Effects of topography on the interpretation of the deformation field of prominent volcanoes—application to Etna. *Geophys Res Lett* 25:1979–1982. <https://doi.org/10.1029/98GL51512>
- Cayol V, Cornet FH (1997) 3D mixed boundary elements for elastostatic deformation field analysis. *Int J Rock Mech Min Sci* 34:275–287. [https://doi.org/10.1016/S0148-9062\(96\)00035-6](https://doi.org/10.1016/S0148-9062(96)00035-6)
- Cayol V, Karlstrom L, Montgomery-Brown E, Bato MG, Angarita-Vargas M, Grapenthin R, Anderson K, Astort A, Bodart O, Cannavò F, Currenti G, Dabaghi F, Garg D, Head M, Iozzia A, Le Mevel H, McCluskey O, Novoa C, Silverii F, Trasatti E, Zhan Y (2023) Drivers of Volcano Deformation (DVD) validation and verification exercises: phase 1. IUGG General Assembly, Berlin, 17 July 2023
- Cervelli P (2013) Analytical expressions for deformation from an arbitrarily oriented spheroid in a half-space. <http://volcanoes.usgs.gov/software/spheroid>. Accessed Jan 2022
- Coco A, Currenti G, Negro CD, Russo G (2014) A second order finite-difference ghost-point method for elasticity problems on unbounded domains with applications to volcanology. *Commun Comput Phys* 16:983–1009. <https://doi.org/10.4208/cicp.210713.010414a>
- Costa A, Suzuki YJ, Cerminara M, Devenish BJ, Ongaro TE, Herzog M, Van Eaton AR, Denby LC, Bursik M, de' Michieli Vitturi M, Engwell S, Neri A, Barsotti S, Folch A, Macedonio G, Girault F, Carazzo G, Tait S, Kaminski E, Mastin LG, Bonadonna C (2016) Results of the eruptive column model inter-comparison study. *J Volcanol Geotherm Res* 326:2–25. <https://doi.org/10.1016/j.jvolgeores.2016.01.017>
- Crouch SL, Starfield AM (1983) *Boundary element methods in solid mechanics: with applications in rock mechanics and geological engineering*. George Allen & Unwin, London
- Currenti G, Del Negro C, Ganci G (2007) Modelling of ground deformation and gravity fields using finite element method: an application to Etna volcano. *Geophys J Int* 169:775–786. <https://doi.org/10.1111/j.1365-246X.2007.03380.x>
- Dieterich JH, Decker RW (1975) Finite element modeling of surface deformation associated with volcanism. *J Geophys Res* 80:4094–4102. <https://doi.org/10.1029/JB080i029p04094>
- Dieterich HR, Lev E, Chen J, Richardson JA, Cashman KV (2017) Benchmarking computational fluid dynamics models of lava flow simulation for hazard assessment, forecasting, and risk management. *J Appl Volcan* 6:9. <https://doi.org/10.1186/s13617-017-0061-x>
- Dragoni M, Magnanensi C (1989) Displacement and stress produced by a pressurized, spherical magma chamber, surrounded by a viscoelastic shell. *Phys Earth Planet Inter* 56:316–328. [https://doi.org/10.1016/0031-9201\(89\)90166-0](https://doi.org/10.1016/0031-9201(89)90166-0)
- Dumont Q, Cayol V, Froger J-L, Peltier A (2022) 22 years of satellite imagery reveal a major destabilization structure at Piton de la Fournaise. *Nat Commun* 13:2649. <https://doi.org/10.1038/s41467-022-30109-w>
- Ebmeier SK, Andrews BJ, Araya MC, Arnold DWD, Biggs J, Cooper C, Cottrell E, Furtney M, Hickey J, Jay J, Lloyd R, Parker AL, Pritchard ME, Robertson E, Venzke E, Williamson JL (2018) Synthesis of global satellite observations of magmatic and volcanic deformation: implications for volcano monitoring & the lateral extent of magmatic domains. *J Appl Volcan* 7:2. <https://doi.org/10.1186/s13617-018-0071-3>
- Erickson BA, Jiang J, Barall M, Lapusta N, Dunham EM, Harris R, Abrahams LS, Allison KL, Ampuero J-P, Barbot S, Cattania C, Elbanna A, Fialko Y, Idini B, Kozdon JE, Lambert V, Liu Y, Luo Y, Ma X, Best McKay M, Wei M (2020) The community code verification exercise for simulating sequences of earthquakes and aseismic slip (SEAS). *Seismol Res Lett* 91:874–890. <https://doi.org/10.1785/0220190248>
- Esposti Ongaro T, Cerminara M, Charbonnier SJ, Lube G, Valentine GA (2020) A framework for validation and benchmarking of pyroclastic current models. *Bull Volcanol* 82:51. <https://doi.org/10.1007/s00445-020-01388-2>
- Fernández J, Pepe A, Poland MP, Sigmundsson F (2017) Volcano Geodesy: recent developments and future challenges. *J Volcanol Geoth Res* 344:1–12. <https://doi.org/10.1016/j.jvolgeores.2017.08.006>
- Fialko Y, Khazan Y, Simons M (2001) Deformation due to a pressurized horizontal circular crack in an elastic half-space, with applications to volcano geodesy. *Geophys J Int* 146:181–190. <https://doi.org/10.1046/j.1365-246X.2001.00452.x>
- Fournier N, Chardot L (2012) Understanding volcano hydrothermal unrest from geodetic observations: insights from numerical modeling and application to White Island volcano, New Zealand. *J Geophys Res Solid Earth* 117. <https://doi.org/10.1029/2012JB009469>
- Fukushima Y, Cayol V, Durand P (2005) Finding realistic dike models from interferometric synthetic aperture radar data: the February 2000 eruption at Piton de la Fournaise. *J Geophys Res* 110. <https://doi.org/10.1029/2004JB003268>

- Garg D, Papale P, Longo A (2021) A partitioned solver for compressible/incompressible fluid flow and light structure. *Comput Math Appl* 100:182–195. <https://doi.org/10.1016/j.camwa.2021.09.005>
- Gonnermann HM, Anderson K (2021) Modeling volcano-magmatic systems: workshop report for the modeling collaboratory for subduction research coordination network. <https://doi.org/10.31223/X55G96>
- Gonzalez-Santana J, Wauthier C (2021) Unraveling long-term volcano flank instability at Pacaya Volcano, Guatemala, using satellite geodesy. *J Volcanol Geoth Res* 410:107147. <https://doi.org/10.1016/j.jvolgeoes.2020.107147>
- Grapenthin R, Cheng Y, Angarita M, Tan D, Meyer FJ, Fee D, Wech A (2022) Return from dormancy: rapid inflation and seismic unrest driven by transcrustal magma transfer at mt. edgcombe (l'úx shaa) volcano, alaska. *Geophys Res Lett* 49. <https://doi.org/10.1029/2022GL099464>
- Gregg PM, de Silva SL, Grosfils EB (2013) Thermomechanics of shallow magma chamber pressurization: implications for the assessment of ground deformation data at active volcanoes. *Earth Planet Sci Lett* 384:100–108. <https://doi.org/10.1016/j.epsl.2013.09.040>
- Harris RA, Barall M, Aagaard B, Ma S, Roten D, Olsen K, Duan B, Liu D, Luo B, Bai K, Ampuero J, Kaneko Y, Gabriel A, Duru K, Ulrich T, Wollherr S, Shi Z, Dunham E, Bydlon S, Zhang Z, Dalguer L (2018) A suite of exercises for verifying dynamic earthquake rupture codes. *Seismol Res Lett* 89:1146–1162. <https://doi.org/10.1785/0220170222>
- Harris RA, Barall M, Andrews DJ, Duan B, Ma S, Dunham EM, Gabriel AA, Kaneko Y, Kase Y, Aagaard BT, Oglesby DD, Ampuero JP, Hanks TC, Abrahamson N (2011) Verifying a computational method for predicting extreme ground motion. *Seismol Res Lett* 82:638–644. <https://doi.org/10.1785/gssrl.82.5.638>
- Harris RA, Barall M, Archuleta R, Dunham E, Aagaard B, Ampuero JP, Bhat H, Cruz-Atienza V, Dalguer L, Dawson P, Day S, Duan B, Ely G, Kaneko Y, Kase Y, Lapusta N, Liu Y, Ma S, Oglesby D, Olsen K, Templeton E (2009) The SCEC/USGS dynamic earthquake rupture code verification exercise. *Seismol Res Lett* 80:119–126. <https://doi.org/10.1785/gssrl.80.1.119>
- Hickey J, Gottsmann J, Nakamichi H, Iguchi M (2016) Thermomechanical controls on magma supply and volcanic deformation: application to Aira caldera, Japan. *Sci Rep* 6:32691. <https://doi.org/10.1038/srep32691>
- Hickey J, Gottsmann J (2014) Benchmarking and developing numerical Finite Element models of volcanic deformation. *J Volcanol Geoth Res* 280:126–130. <https://doi.org/10.1016/j.jvolgeoes.2014.05.011>
- Jiang J, Erickson BA, Lambert VR, Ampuero J, Ando R, Barbot SD, Cattania C, Zilio LD, Duan B, Dunham EM, Gabriel A, Lapusta N, Li D, Li M, Liu D, Liu Y, Ozawa S, Pranger C, van Dinther Y (2022) Community-driven code comparisons for three-dimensional dynamic modeling of sequences of earthquakes and aseismic slip. *J Geophys Res Solid Earth* 127. <https://doi.org/10.1029/2021JB023519>
- Jonsson S (2002) Fault slip distribution of the 1999 Mw 7.1 hector mine, California, earthquake, estimated from satellite radar and GPS measurements. *Bull Seismol Soc Am* 92:1377–1389. <https://doi.org/10.1785/0120000922>
- Karlstrom L, Dufek J, Manga M (2009) Organization of volcanic plumbing through magmatic lensing by magma chambers and volcanic loads. *J Geophys Res Solid Earth* 114. <https://doi.org/10.1029/2009JB006339>
- Liao Y, Soule SA, Jones M, Le Mével H (2021) The mechanical response of a magma chamber with poroviscoelastic crystal mush. *J Geophys Res Solid Earth* 126. <https://doi.org/10.1029/2020JB019395>
- Lindsay AD, Gaston DR, Permann CJ, Miller JM, Andrš D, Slaughter AE, Kong F, Hansel J, Carlsen RW, Icenhour C, Harbour L, Giudicelli GL, Stogner RH, German P, Badger J, Biswas S, Chapuis L, Green C, Hales J, Hu T, Wong C (2022) 2.0 - MOOSE: enabling massively parallel multiphysics simulation. *SoftwareX* 20:101202. <https://doi.org/10.1016/j.softx.2022.101202>
- Lisowski M (2006) Analytical volcano deformation source models, in: *Volcano deformation*. Springer Berlin Heidelberg, Berlin, Heidelberg, pp. 279–304. https://doi.org/10.1007/978-3-540-49302-0_8
- Liu Y (2016) On the displacement discontinuity method and the boundary element method for solving 3-D crack problems. *Eng Fract Mech* 164:35–45. <https://doi.org/10.1016/j.engfracmech.2016.07.009>
- Longo A, Papale P, Vassalli M, Saccorotti G, Montagna CP, Cassioli A, Giudice S, Boschi E (2012) Magma convection and mixing dynamics as a source of Ultra-Long-Period oscillations. *Bull Volcanol* 74:873–880. <https://doi.org/10.1007/s00445-011-0570-0>
- Mai PM, Schorlemmer D, Page M, Ampuero J, Asano K, Causse M, Custodio S, Fan W, Festa G, Galis M, Gallovic F, Imperatori W, Käser M, Malyskyy D, Okuwaki R, Pollitz F, Passone L, Razafindrakoto HNT, Sekiguchi H, Song SG, Zielke O (2016) The earthquake-source inversion validation (SIV) project. *Seismol Res Lett* 87:690–708. <https://doi.org/10.1785/0220150231>
- Masterlark T, Donovan T, Feigl KL, Haney M, Thurber CH, Tung S (2016) Volcano deformation source parameters estimated from InSAR: sensitivities to uncertainties in seismic tomography. *J Geophys Res Solid Earth* 121:3002–3016. <https://doi.org/10.1002/2015JB012656>
- Masterlark T (2007) Magma intrusion and deformation predictions: sensitivities to the Mogi assumptions. *J Geophys Res* 112. <https://doi.org/10.1029/2006JB004860>
- McTigue DF, Segall P (1988) Displacements and tilts from dip-slip faults and magma chambers beneath irregular surface topography. *Geophys Res Lett* 15:601–604. <https://doi.org/10.1029/GL015i006p00601>
- McTigue DF (1987) Elastic stress and deformation near a finite spherical magma body: resolution of the point source paradox. *J Geophys Res* 92:12931. <https://doi.org/10.1029/JB092iB12p12931>
- Menke W (2018) *Geophysical data analysis: discrete inverse theory*, 4th edn. Academic Press
- Mogi K (1958) Relation between the eruptions of various volcanoes and deformations of the ground surfaces around them. *Bull Earthq Res Inst* 36:99–134
- Montgomery-Brown EK, Karlstrom L, Crozier JA, Bato MG, Cayol V, Angarita M, Grapenthin R, Astort A, Cannavo F, Silverii F, Others (2022) Drivers of volcano deformation (DVD) verification and validation exercises: phase 1. AGU Fall Meeting Abstract# V52D-0021, Chicago IL, 16 December 2022. 2022AGUFM.V52D0021M
- Montgomery-Brown EK, Miklius A (2021) Periodic dike intrusions at Kilauea volcano, Hawaii. *Geology* 49:397–401. <https://doi.org/10.1130/G47970.1>
- Mullet B, Segall P (2022) The surface deformation signature of a transcrustal, crystal mush-dominant magma system. *J Geophys Res Solid Earth* 127. <https://doi.org/10.1029/2022JB024178>
- Nikkhoo M, Rivalta E (2022) Surface deformations and gravity changes caused by pressurized finite ellipsoidal cavities. *Geophys J Int* 232:643–655. <https://doi.org/10.1093/gji/ggac351>
- Nikkhoo M, Walter TR, Lundgren PR, Prats-Iraola P (2017) Compound dislocation models (CDMs) for volcano deformation analyses. *Geophys J Int* 208:877–894. <https://doi.org/10.1093/gji/ggw427>
- Nikkhoo M, Walter TR (2015) Triangular dislocation: an analytical, artefact-free solution. *Geophys J Int* 201:1119–1141. <https://doi.org/10.1093/gji/ggv035>
- Nova C, Remy D, Gerbault M, Baez JC, Tassara A, Cordova L, Cardona C, Granger M, Bonvalot S, Delgado F (2019) Viscoelastic relaxation: a mechanism to explain the decennial large surface displacements at the Laguna del Maule silicic volcanic complex.

- Earth Planet Sci Lett 521:46–59. <https://doi.org/10.1016/j.epsl.2019.06.005>
- Parks MM, Biggs J, England P, Mather TA, Nomikou P, Palamartchouk K, Papanikolaou X, Paradissis D, Parsons B, Pyle DM, Raptakis C, Zacharis V (2012) Evolution of Santorini Volcano dominated by episodic and rapid fluxes of melt from depth. *Nature Geosci* 5:749–754. <https://doi.org/10.1038/ngeo1562>
- Poland MP, Peltier A, Bonforte A, Puglisi G (2017) The spectrum of persistent volcanic flank instability: a review and proposed framework based on Kīlauea, Piton de la Fournaise, and Etna. *J Volcanol Geoth Res* 339:63–80. <https://doi.org/10.1016/j.jvolgeores.2017.05.004>
- Poland MP, Zebker HA (2022) Volcano geodesy using InSAR in 2020: the past and next decades. *Bull Volcanol* 84:27. <https://doi.org/10.1007/s00445-022-01531-1>
- Rucker C, Erickson BA, Karlstrom L, Lee B, Gopalakrishnan J (2022) A computational framework for time-dependent deformation in viscoelastic magmatic systems. *J Geophys Res Solid Earth* 127. <https://doi.org/10.1029/2022JB024506>
- Sahagian D (2005) Volcanic eruption mechanisms: insights from inter-comparison of models of conduit processes. *J Volcanol Geoth Res* 143:1–15. <https://doi.org/10.1016/j.jvolgeores.2004.12.006>
- Sambridge M (1999) Geophysical inversion with a neighbourhood algorithm—I. Searching a parameter space. *Geophys J Int* 138:479–494. <https://doi.org/10.1046/j.1365-246X.1999.00876.x>
- Segall P (2019) Magma chambers: what we can, and cannot, learn from volcano geodesy. *Philos Transact A Math Phys Eng Sci* 377:20180158. <https://doi.org/10.1098/rsta.2018.0158>
- Segall P (2010) Earthquake and volcano deformation. Princeton University Press, Princeton. <https://doi.org/10.1515/9781400833856>
- Sigmundsson F, Hooper A, Hreinsdóttir S, Vogfjörð KS, Ófeigsson BG, Heimisson ER, Dumont S, Parks M, Spaans K, Gudmundsson GB, Drouin V, Árnadóttir T, Jónsdóttir K, Gudmundsson MT, Högnadóttir T, Fridriksdóttir HM, Hensch M, Einarsson P, Magnússon E, Samsonov S, Eibl EPS (2015) Segmented lateral dyke growth in a rifting event at Bárðarbunga volcanic system, Iceland. *Nature* 517:191–195. <https://doi.org/10.1038/nature14111>
- Sigmundsson F, Pinel V, Grapenthin R, Hooper A, Halldórsson SA, Einarsson P, Ófeigsson BG, Heimisson ER, Jónsdóttir K, Gudmundsson MT, Vogfjörð K, Parks M, Li S, Drouin V, Geirsson H, Dumont S, Fridriksdóttir HM, Gudmundsson GB, Wright TJ, Yamasaki T (2020) Unexpected large eruptions from buoyant magma bodies within viscoelastic crust. *Nat Commun* 11:2403. <https://doi.org/10.1038/s41467-020-16054-6>
- Tarantola A (2004) Inverse problem theory and methods for model parameter estimation, 1st edn. Society for Industrial and Applied Mathematics, Philadelphia, PA, SIAM
- Taylor NC, Johnson JH, Herd RA (2021) Making the most of the Mogi model: size matters. *J Volcanol Geoth Res* 419:107380. <https://doi.org/10.1016/j.jvolgeores.2021.107380>
- Townsend M (2022) Linking surface deformation to thermal and mechanical magma chamber processes. *Earth Planet Sci Lett* 577:117272. <https://doi.org/10.1016/j.epsl.2021.117272>
- Trasatti E (2022) Volcanic and seismic source modeling: an open tool for geodetic data modeling. *Front Earth Sci* 10. <https://doi.org/10.3389/feart.2022.917222>
- Williams CA, Wadge G (2000) An accurate and efficient method for including the effects of topography in three-dimensional elastic models of ground deformation with applications to radar interferometry. *J Geophys Res* 105:8103–8120. <https://doi.org/10.1029/1999JB900307>
- Williams CA, Wadge G (1998) The effects of topography on magma chamber deformation models: application to Mt. Etna and radar interferometry. *Geophys Res Lett* 25:1549–1552. <https://doi.org/10.1029/98GL01136>
- Yang X-M, Davis PM, Dieterich JH (1988) Deformation from inflation of a dipping finite prolate spheroid in an elastic half-space as a model for volcanic stressing. *J Geophys Res* 93:4249–4257. <https://doi.org/10.1029/JB093iB05p04249>
- Zhong X, Dabrowski M, Jamtveit B (2019) Analytical solution for the stress field in elastic half-space with a spherical pressurized cavity or inclusion containing eigenstrain. *Geophys J Int* 216:1100–1115. <https://doi.org/10.1093/gji/ggy447>
- Zienkiewicz OC (2005) The finite element method: its basis and fundamentals, 6th edn. Butterworth-Heinemann
- Springer Nature or its licensor (e.g. a society or other partner) holds exclusive rights to this article under a publishing agreement with the author(s) or other rightsholder(s); author self-archiving of the accepted manuscript version of this article is solely governed by the terms of such publishing agreement and applicable law.

Authors and Affiliations

Josh Crozier¹  · Leif Karlstrom²  · Emily Montgomery-Brown³  · Mario Angarita⁴  · Valérie Cayol⁵  · Mary Grace Bato⁶  · Taiyi A. Wang⁷  · Ronni Grapenthin⁴  · Tara Shreve^{4,8}  · Kyle Anderson¹  · Ana Astort⁹  · Olivier Bodart¹⁰  · Flavio Cannavò¹¹  · Gilda Currenti¹²  · Farshid Dabaghi¹³  · Brittany A. Erickson²  · Deepak Garg¹⁴  · Matthew Head¹⁵  · Adriana Iozzia^{12,16}  · Young Cheol Kim¹⁷  · Hélène Le Mével⁸  · Camila Novoa Lizama¹⁸ · Cody Rucker²  · Francesca Silverii⁹  · Elisa Trasatti⁹  · Yan Zhan¹⁹ 

Leif Karlstrom
leif@uoregon.edu

Emily Montgomery-Brown
emontgomery-brown@usgs.gov

Mario Angarita
mfangaritasr@alaska.edu

Valérie Cayol
valerie.cayol@uca.fr

Mary Grace Bato
bato@jpl.nasa.gov

Taiyi A. Wang
taiyi@stanford.edu

Ronni Grapenthin
rgrapenthin@alaska.edu

Tara Shreve
tshreve@carnegiescience.edu

Kyle Anderson
kranderson@usgs.gov

Ana Astort
ana.astort@ingv.it

Olivier Bodart
olivier.bodart@univ-st-etienne.fr

Flavio Cannavò
flavio.cannavo@ingv.it

Gilda Currenti
gilda.currenti@ingv.it

Farshid Dabaghi
farshid.dabaghi@univ-st-etienne.fr

Brittany A. Erickson
bae@uoregon.edu

Deepak Garg
deepak.garg@ingv.it

Matthew Head
mshead@illinois.edu

Adriana Iozzia
adriana.iozzia@phd.unict.it; adriana.iozzia@ingv.it

Young Cheol Kim
yvk5286@psu.edu

Hélène Le Mével
hlemevel@carnegiescience.edu

Camila Novoa Lizama
c.p.novoalizama@leeds.ac.uk

Cody Rucker
crucker@uoregon.edu

Francesca Silverii
francesca.silverii@ingv.it

Elisa Trasatti
elisa.trasatti@ingv.it

Yan Zhan
yanzhan@cuhk.edu.hk

- 1 U.S. Geological Survey Volcano Science Center, California Volcano Observatory, Moffett Field, CA, USA
- 2 University of Oregon, Eugene, OR, USA
- 3 U.S. Geological Survey Volcano Science Center, Cascades Volcano Observatory, Vancouver, WA, USA
- 4 University of Alaska Fairbanks, Fairbanks, AK, USA
- 5 Université Clermont Auvergne, Clermont-Ferrand, France
- 6 NASA JPL, Pasadena, CA, USA
- 7 Stanford University, Stanford, CA, USA
- 8 Carnegie Institution for Science, Washington, DC, USA
- 9 Istituto Nazionale Di Geofisica E Vulcanologia, Rome, Italy
- 10 Université Jean Monnet Saint-Etienne: Saint-Etienne, Rhône-Alpes, France
- 11 Istituto Nazionale Di Geofisica E Vulcanologia, Catania, Italy
- 12 Istituto Nazionale Di Geofisica E Vulcanologia, Sezione Di Catania, Italy
- 13 Institut Camille Jordan, Université Jean Monnet, Saint-Etienne, France
- 14 Istituto Nazionale Di Geofisica E Vulcanologia, Pisa, Italy
- 15 University of Illinois at Urbana-Champaign, Urbana, IL, USA
- 16 Università Degli Studi Di Catania, Catania, Italy
- 17 Pennsylvania State University, State College, PA, USA
- 18 COMET School of Earth and Environment, University of Leeds, Leeds, UK
- 19 The Chinese University of Hong Kong, Hong Kong, Hong Kong