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# Feedback-controlled two-wave coupling in reflection geometry: application to lithium niobate crystals subjected to extremely high external electric fields

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**ABSTRACT** An active stabilization of photorefractive two-wave coupling by means of an electronic feedback loop has been used extensively during recent years in transmission geometry. It leads to 100% diffraction efficiency  $\eta$  and also to periodic states instead of familiar steady states. We investigate the feedback operation in the case of reflection geometry, especially for iron-doped lithium niobate (LiNbO<sub>3</sub>:Fe) crystals. This includes formulation of the feedback equations, numerical analysis of the operation regimes for LiNbO<sub>3</sub> crystals, and comparison between theory and experiment, which is performed in the range of applied electric fields from 0 to 650 kV cm<sup>-1</sup>. The main findings are as follows: (i) the feedback does not lead to periodic states, (ii) it modifies the photorefractive response by introducing a frequency shift and maximizes  $\eta$ , and (iii) there is a close relation between the enhancement of  $\eta$  and the resonant excitation of space-charge waves predicted earlier in ferroelectric materials.

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## 1 Introduction

Considerable effort has been spent during recent years to understand the operation mode and potential applications of feedback-controlled photorefractive (PR) beam coupling [1–7]. Initially, it was found experimentally [1–4] that an electronic feedback loop between the output and input signal beams produces strong changes in the characteristics of two-wave coupling as well as in the diffraction properties of the recorded index grating. This feedback has allowed us to diminish the light-induced scattering, to stabilize the input light fringes, and to achieve almost 100% diffraction efficiency  $\eta$  of the refractive-index grating.

A first formulation of the feedback problem in terms of dynamic equations for beam amplitudes and boundary conditions was presented in [5] for the transmission (T) geometry. It adapted the idea of a  $\pm\pi/2$  phase shift between the diffracted and transmitted components of the signal beam [1]. Numerical simulations of the proposed equations have shown that the system reaches quickly a state with diffraction efficiency

$\eta \simeq 1$ , where the ideal ( $\pm\pi/2$ ) feedback conditions fail [5]. Thus this ideal model can be applied only to the initial stage of development.

Recently, it has been shown that inertia of the feedback loop is the key element of its permanent operation for the transmission geometry [6, 7]. As long as  $\eta$  is not very close to 1 or 0, this inertia is of no importance. The diffraction efficiency approaches 1 or 0 at this stage despite tilting and bending of the grating fringes caused by wave coupling. In the vicinity of these extreme values of  $\eta$  the phase shift between the diffracted and transmitted components of the signal beam strongly deviates from the ideal  $\pm\pi/2$  values. Instead of stationary states, familiar for feedback-free wave-mixing schemes, we have periodic states: the diffraction efficiency oscillates in the close vicinity of 1 (or 0) and the input phase of the signal beam  $\varphi_s(t)$  experiences strong periodic oscillations superimposed on a linear slope. This behavior is easily recognizable in experiments [6, 7].

Recently, holographic experiments in the reflection (R) geometry have become possible with LiNbO<sub>3</sub>:Fe crystals owing to employment of the same feedback loop [8]. Despite extreme experimental conditions ( $\approx 0.1\text{-}\mu\text{m}$  grating spacing and applied electric fields up to 650 kV cm<sup>-1</sup>) the data of the measurements were fully reproducible. Considerable improvements of the performance characteristics of this important PR material were achieved.

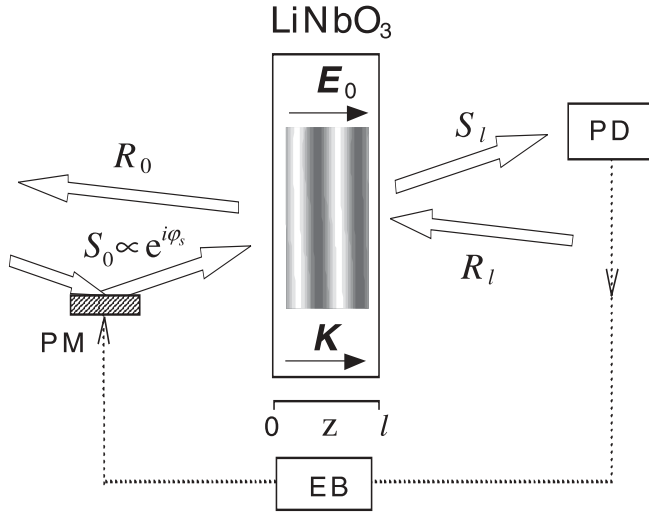
Below we investigate, both theoretically and experimentally, the impact of an active feedback loop on wave-coupling characteristics in the R-geometry. Several relevant issues have to be mentioned: (i) the results obtained earlier for the transmission geometry cannot be directly applied to the R-case. (ii) Inaccessibility of the value  $\eta = 1$  in the reflection case makes one expect that the periodic states are absent and that the feedback inertia is not important. (iii) Weakly damped low-frequency eigenmodes – space-charge waves – have been predicted in the actual range of LiNbO<sub>3</sub>:Fe parameters [9]. Therefore, the resonant enhancement and strong modification of the PR response can accompany the feedback operation.

## 2 Theoretical background

A schematic illustration of our feedback experiment is shown in Fig. 1. The signal (S) and reference (R) light beams are incident on opposite faces of the sample.

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**FIGURE 1** Schematic diagram of a holographic experiment in the reflection geometry with an active electronic feedback system;  $\varphi_s$  is the input phase governed by the feedback loop, PD is a photo-detector, EB is an electronic block, and PM is a piezo-electrically driven mirror

The propagation coordinate is  $z$  and the crystal thickness is  $l$ . The grating vector  $\mathbf{K}$  and the applied field  $\mathbf{E}_0$  are perpendicular to the input faces and parallel to the polar (optical) axis. The light interference and grating fringes are parallel to the input surfaces and the fringe spacing  $\Lambda = 2\pi/K$  is much shorter than the light wavelength  $\lambda$ . The input phase of the signal beam  $\varphi_s$  is controlled by an electronic feedback loop via a piezo-electrically driven mirror.

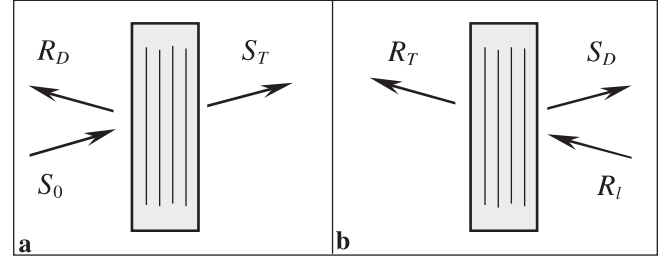
The amplitudes of the signal and reference waves,  $S$  and  $R$ , obey the coupled-wave equations

$$\partial S / \partial z = +i\kappa E_K R, \quad (1)$$

$$\partial R / \partial z = -i\kappa E_K^* S, \quad (2)$$

where  $E_K$  is the complex amplitude of the light-induced space-charge field at the spatial frequency  $K$ ,  $\kappa = \pi n_o^3 r_{13} / 2\lambda$ ,  $n_o$  is the ordinary refractive index, and  $r_{13}$  is the electro-optic constant. These equations describe Bragg diffraction from the refractive-index grating; the effect of light absorption on  $S$  and  $R$  is supposed to be negligible. The amplitude  $E_K$  is generally a function of the propagation coordinate  $z$  and time  $t$ . The intensity difference  $|S(z)|^2 - |R(z)|^2$  remains constant during propagation. The amplitudes  $S$  and  $R$  are normalized in such a way that  $|S_0|^2 + |R_l|^2 = 1$ .

The feedback conditions for  $S$  and  $R$  can be formulated regardless of the particular form of  $E_K(z, t)$ ; it is important only that this amplitude is changing slowly in the scale of the feedback response time. Imagine that we have blocked the input R-beam for a short time, i.e. set  $R_l = 0$ ; see Fig. 2a. The amplitude  $E_K(z, t)$  remains unchanged during this test. At the output we have the transmitted component of the signal beam  $S_T$  and the diffracted component of the reference beam  $R_D$ . Similarly, by a momentary blocking of the input S-beam (by setting  $S(0, t) = 0$ ) we define the diffracted component of the signal beam  $S_D$  and the transmitted component of the reference beam  $R_T$ ; see Fig. 2b. Since the diffractive properties of the grating can be time dependent, the introduced T- and D-amplitudes are generally functions of  $t$ . The diffrac-



**FIGURE 2** Diagram of thought experiments clarifying the meaning of the transmitted and diffracted components of the output amplitudes

tion efficiency of the grating is  $\eta = |R_D|^2 / |S_0|^2 \equiv |S_D|^2 / |R_l|^2$ ; furthermore  $|S_T|^2 / |S_0|^2 \equiv |R_T|^2 / |R_l|^2 = 1 - \eta$ . The reflection geometry of our problem influences strongly the values of  $S_D$  and  $S_T$  because the S- and R-beams are propagating in opposite directions.

As a next step we express the amplitudes  $S_T$  and  $S_D$  algebraically by the input and output amplitudes of the recording waves (see Appendix A for details). The explicit relations read

$$S_T = S_0 \frac{|R_l|^2 - |S_l|^2}{R_0^* R_l - S_0 S_l^*}, \quad S_D = R_l \frac{R_0^* S_l - S_0 R_l^*}{R_0^* R_l - S_0 S_l^*}. \quad (3)$$

They differ from the relations of the T-geometry, see [5, 7]. As long as  $S_D$  and  $S_T$  are non-zero quantities, the phase difference between them,  $\Phi = \arg(S_D S_T^*)$ , can be adjusted to any desirable value by a proper choice of the input phase  $\varphi_s = \arg(S_0)$ .

With the diffracted and transmitted components introduced, one can understand easily the experimental implementation of the feedback. Let an auxiliary (small and fast) oscillating component,  $\delta\varphi_s = \psi_0 \sin(\omega t)$ , be introduced into the input phase  $\varphi_s$ . It does not affect the recording process and serves merely for initiation of the feedback loop. The output intensity  $|S(l, t)|^2 = |S_T \exp(i\delta\varphi_s) + S_D|^2$  acquires high-frequency components oscillating as  $\sin(\omega t)$  and  $\cos(2\omega t)$ . The amplitudes of these components are  $I_\omega = 2|R_l S_0| \times \sqrt{\eta(1-\eta)} \psi_0 \sin \Phi$  and  $I_{2\omega} = (1/2)|R_l S_0| \sqrt{\eta(1-\eta)} \psi_0^2 \times \cos \Phi$ , where  $\Phi = \arg(S_D) - \arg(S_T)$  is just the phase difference between diffracted and transmitted components of the signal beam. Using  $I_{2\omega}$  as an error signal in an electronic feedback loop, one can keep  $\Phi \simeq \pi/2$  (or  $-\pi/2$ ). Thus, we have proven for the R-geometry that the feedback can be implemented regardless of dynamic distortions of the grating fringes, i.e. for  $E_K(z, t) \neq \text{const}$ .

The feedback equation governing the input phase  $\varphi_s$  is similar to that employed for the T-case [6, 7],

$$\frac{d\varphi_s}{dt} = \mp \frac{1}{t_f} |S_0 R_l| \sqrt{\eta(1-\eta)} \cos \Phi, \quad (4)$$

where  $t_f$  is the feedback-loop response time; it is expected to be much shorter than the PR response time. If the product  $\eta(1-\eta)$  is not close to zero, the phase  $\Phi$  relaxes very quickly to the value  $\pi/2$  or  $-\pi/2$ ; the feedback inertia is here of no importance. If the governing feedback signal  $I_{2\omega}$  becomes very small, evolution of  $\varphi_s(t)$  is controlled by this inertia.

To model the temporal evolution of the feedback-controlled two-wave coupling, we need a material equation for the grating amplitude  $E_K$ . The conventional  $\text{Fe}^{2+} \leftrightarrow \text{Fe}^{3+}$

one-center charge-transport model leads to the following equation within the low-contrast approximation [9]:

$$\left( \frac{\partial}{\partial t} + \gamma_K + i\omega_K \right) E_K = 2SR^* F_K. \quad (5)$$

Here  $\gamma_K + i\omega_K \simeq (|S|^2 + |R|^2) (E_q + E_D + iE_{pv} - iE_0) / E_q t_M$ ,  $F_K \simeq -(E_0 - E_{pv} + iE_D) / t_M$ ,  $E_0$  is the applied electric field,  $E_{pv}$  is the photovoltaic field [11, 12],  $E_q \simeq eN_{Fe}^{2+} / \varepsilon \varepsilon_0 K$  is the saturation field,  $E_D = Kk_B T / e$  is the diffusion field,  $t_M$  is the Maxwell relaxation time calculated for the total input intensity,  $e$  is the elementary charge,  $N_{Fe}^{2+}$  is the concentration of  $Fe^{2+}$  centers,  $\varepsilon$  is the static dielectric constant,  $\varepsilon_0$  is the permittivity of free space,  $k_B$  is the Boltzmann constant, and  $T$  is the absolute temperature. All material parameters entering (5) are known (or controlled) in experiments with  $LiNbO_3:Fe$ . It is important that the grating spacing is very short for the R-geometry;  $\Lambda \simeq 0.1 \mu m$ . This makes the saturation field  $E_q$  relatively small. By setting  $N_{Fe}^{2+} = 10^{18} cm^{-3}$  we obtain  $E_q \approx 100 kV cm^{-1}$ . The photovoltaic field  $E_{pv}$  does not depend on  $N_{Fe}^{2+}$  if the fraction of donors is relatively small; it can roughly be estimated as  $\approx 100 kV cm^{-1}$ . The diffusion field is considerably smaller,  $E_D \simeq 16 kV cm^{-1}$ . The applied field  $E_0$  can be considerably larger than  $E_q$ ,  $E_{pv}$ , and  $E_D$  in our experiments.

The main outcome of (5) and the above estimates is as follows: suppose that  $|E_0 - E_{pv}| \gg E_q, E_D$ ; then  $|\omega_K| \gg \gamma_K$ , i.e. there is a weakly damped space-charge wave with the eigenfrequency  $\omega_K$ . With a zero frequency shift between S- and R-beams we have  $E_K \approx imE_q$  in steady state; this corresponds to  $\approx \pi/2$  phase shift between the light and index fringes and to power transfer into one of the recording beams. Let now the frequency shift between S- and R-beams,  $\Omega$ , be equal to the eigenfrequency  $\omega_K$ , which corresponds to the resonant excitation of the eigenmode. Then we have in steady state:

$$E_K \simeq (\omega_K / \gamma_K) m E_q. \quad (6)$$

The grating has become non-shifted (the power transfer suppressed) and its amplitude is enhanced by a factor of  $|\omega_K| / \gamma_K \gg 1$ .

Relation (6) possesses a remarkable feature. Being applied to the case  $m \approx 1$ , it leads to the fundamental grating amplitude  $E_K$  larger than the saturation field  $E_q$ . In reality, the low-contrast approximation fails here and the function  $E_K(m)$  saturates on the level of  $\approx E_q$ . A similar situation is known for the resonant enhancement in fast PR materials [10]. To take into consideration the saturation effect, we have replaced in (5) the damping constant  $\gamma_K$  by  $\gamma_K / (1 - |E_K / cE_q|^2)$ , where  $c \approx 1$  is a fitting parameter. Being fairly simple, this phenomenological method allows us to keep the major features of the resonant PR response [9].

Experience shows that the feedback tends to maximize the diffraction efficiency of the grating in the transmission geometry. If this assertion is applicable to the reflection case, then one can expect that the feedback will bring the system automatically to the resonant excitation of a non-shifted index grating.

Lastly, we comment on the difference between the R- and T-geometries with regard to feedback operation. In the T-case,

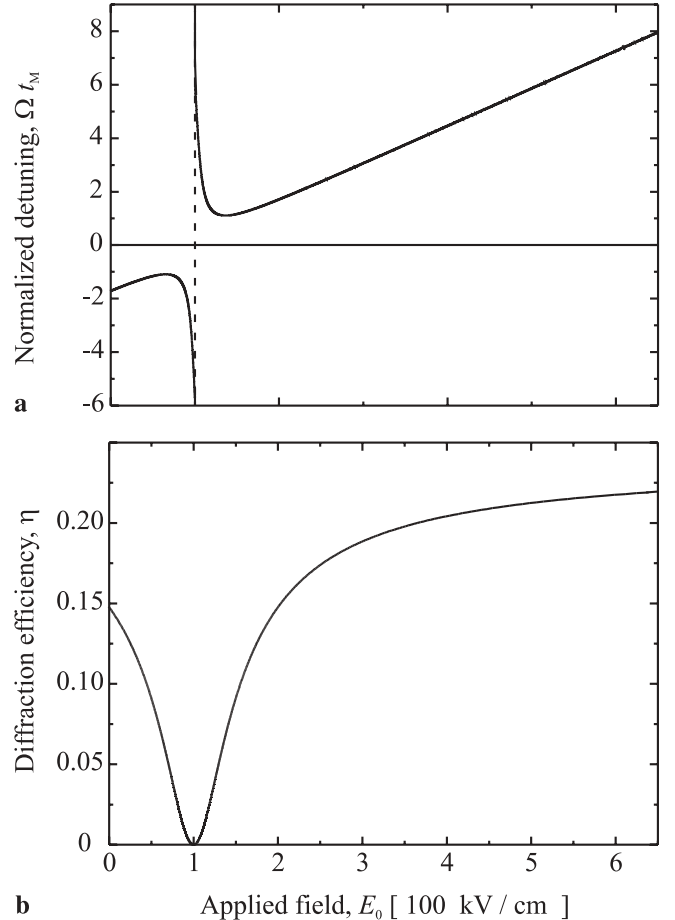
the diffraction efficiency of the index grating,  $\eta$ , can reach a unit value for finite grating amplitude and thickness. Just this feature is responsible for strong periodic oscillations of the input phase  $\varphi_s$  in addition to its linear growth or decrease [6, 7]. In the R-case, the diffraction efficiency can never reach unity. Hence, no periodic states are expected here.

### 3 Numerical simulations

In our theoretical studies of the feedback-controlled two-wave coupling we have solved numerically (1), (2), and (5) together with the feedback equation (4). The feedback-loop response time  $t_f$  ranged from  $10^{-3}$  to  $10^{-4}$  of the Maxwell time  $t_M$ . It was found that the signs  $+$  and  $-$  in this equation ensure stabilization for  $E_0 - E_{pv} < 0$  and  $E_0 - E_{pv} > 0$ , respectively.

Consider first the case of unit input beam ratio,  $\beta = |S_0|^2 / |R_0|^2 = 1$ . The system arrives here quickly (for  $t = (2-3)t_M$ ) at steady state where there is no noticeable energy exchange between the S- and R-beams, i.e.  $m(z) = 1$ . The input phase of the signal wave  $\varphi_s$  grows linearly in time, which means introduction of a constant frequency shift  $\Omega$  between the recording beams.

Figure 3a shows the dependence  $\Omega(E_0)$  calculated for  $E_{pv} = 100 kV cm^{-1}$  and  $N^{2+} = 0.7 \times 10^{18} cm^{-3}$ . For  $E_0 \gtrsim$



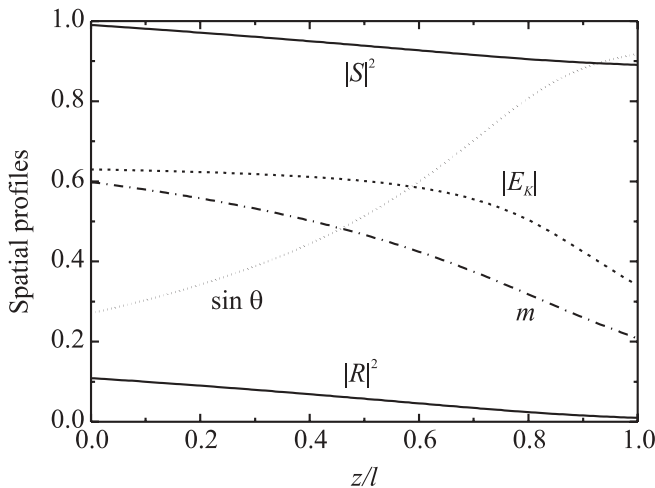
**FIGURE 3** Field dependence of frequency shift  $\Omega$  (a) and diffraction efficiency  $\eta$  (b) for the feedback-controlled steady state with  $\beta = 1$ ,  $N^{2+} = 0.7 \times 10^{18} cm^{-3}$ , and  $l = 0.22 mm$

$E_{pv}$  this dependence is practically linear and very close to the field dependence of the eigenfrequency  $\omega_K(E_0)$ . Thus, the expected linear excitation of space-charge waves takes place. The phase difference  $\Phi$  is very close to  $\pi/2$  when the applied field  $E_0$  exceeds the photovoltaic field  $E_{pv}$ ; the feedback inertia is not important in this region. With  $E_0$  approaching  $E_{pv}$  from above, the frequency detuning  $\Omega$  grows steeply, tending to infinity. The phase  $\Phi$  deflects here strongly from  $\pi/2$  and the feedback inertia is very important; the smaller  $t_f$ , the stronger is the growth of  $\Omega$ . This means that there is no steady state that meets the ideal feedback conditions at  $\beta = 1$  for the diffusion PR response.

The field dependence of the steady-state diffraction efficiency  $\eta(E_0)$  is shown in Fig. 3b. It possesses a clearly pronounced minimum at  $E_0 \approx E_{pv}$  (where  $\eta$  is very small) and shows a saturation for  $E_0 \gg E_{pv}$ . The saturated value of  $\eta(E_0)$  is not close to unity so that the feedback signal  $I_{2\omega}$  is far from zero. The minimum value of  $\eta$  is controlled by the feedback response time; the longer  $t_f$ , the larger is  $\eta_{\min}$ . The origin of such low values of  $\eta$  for  $E_0 \approx E_{pv}$  is evidently the large frequency detuning causing a running interference pattern and hence strong erasure. The charge saturation is negligible in this region since  $|E_K| \ll E_q$ . Note lastly that the feedback maximizes  $\eta$  only for  $|E_0 - E_{pv}| \gtrsim E_D$ .

Now we turn to the case of small contrast,  $m \ll 1$ . Two opposite tendencies affect here the beam coupling in the region of large fields. On the one hand, the feedback tends to exploit the resonance  $\Omega = \omega_K$  to maximize  $E_K$  and  $\eta$ ; the contrast  $m$  remains small within this scenario because of no power transfer to the weakest beam. On the other hand, the feedback can try to keep  $\Omega \approx 0$  to initiate the power transfer into the weakest beam; this allows us to increase the contrast and can also be advantageous for increasing  $\eta$ .

Lastly we present numerical data for the steady state. Figure 4 shows the spatial profiles of the beam intensities, the light contrast, the grating amplitude, and the phase shift be-



**FIGURE 4** Spatial characteristics of the feedback-controlled two-wave coupling for  $\beta = 100$ ,  $N^{2+} = 0.7 \times 10^{18} \text{ cm}^{-3}$ ,  $l = 0.22 \text{ mm}$ , and  $E_0 = 600 \text{ kV cm}^{-1}$ . The intensities of signal and reference waves are  $|S|^2$  and  $|R|^2$ ,  $|E_K|$  is the absolute value of the amplitude of the space-charge field (measured in  $10^5 \text{ V cm}^{-1}$ ),  $m$  is the modulation degree (the input contrast  $m_0 \approx 0.2$ ), and  $\sin \theta$  is the sine of the phase shift  $\theta$  between the index and light patterns

tween the index and light fringes. One can see that the spatial distributions combine the features of the two expected scenarios. In the right-hand part of the sample the recorded grating is almost  $\pi/2$  shifted; this leads to decreasing intensity ratio  $|S(z)|^2/|R(z)|^2$  and increasing contrast  $m(z)$  and amplitude  $|E_K(z)|$  when the coordinate  $z$  is changing from  $l$  to  $l/2$ . In the left-hand part of the sample the grating becomes almost non-shifted; the energy transfer is weak here and the contrast  $m(z) \approx 0.6$  is much higher than its input value. This is the region of resonant enhancement. Since the total energy  $|S(z)|^2 + |R(z)|^2$  is changing across the crystal, the resonant condition  $\Omega = \omega_K$  cannot be fulfilled simultaneously in the whole crystal; in our case  $\Omega$  is much larger than  $\omega_K$  in the right-hand half of the sample. The calculated function  $\Omega(E_0)$  is strictly linear for  $E_0 \gtrsim 1.5 E_{pv}$ ; it exceeds  $\omega_K(E_0)$  calculated for the input intensity  $|S_0|^2 + |R_l|^2$  by a factor of  $\approx 1.2$ .

#### 4 Experiment

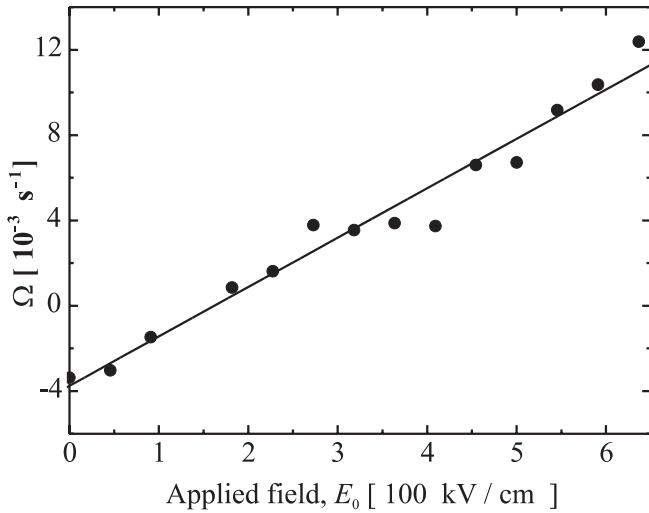
In our experiments we use a congruently melting iron-doped  $\text{LiNbO}_3$  crystal with an iron concentration of  $N_{\text{Fe}} \approx 18 \times 10^{18} \text{ cm}^{-3}$  and a thickness  $l = 0.22 \text{ mm}$ . The polar (optical) axis is perpendicular to the input faces. The absorption coefficient  $\alpha$  ranges from  $3.0$  to  $9.9 \text{ cm}^{-1}$  at  $477 \text{ nm}$  when the donor concentration  $N^{2+}$  ranges from  $\approx 0.7$  to  $\approx 2.3 \times 10^{18} \text{ cm}^{-3}$ . The fraction of  $\text{Fe}^{2+}$  ions was varied by annealing treatments [13, 14].

The sample is placed in a Plexiglas holder and the input surfaces are contacted with transparent liquid electrodes, see [8] for more detail. The applied electric field ranges from  $0$  to  $650 \text{ kV cm}^{-1}$  and is parallel to the polar axis. Application of larger fields leads to electric breakdown. Equally strong fields of the opposite direction would invert the spontaneous polarization.

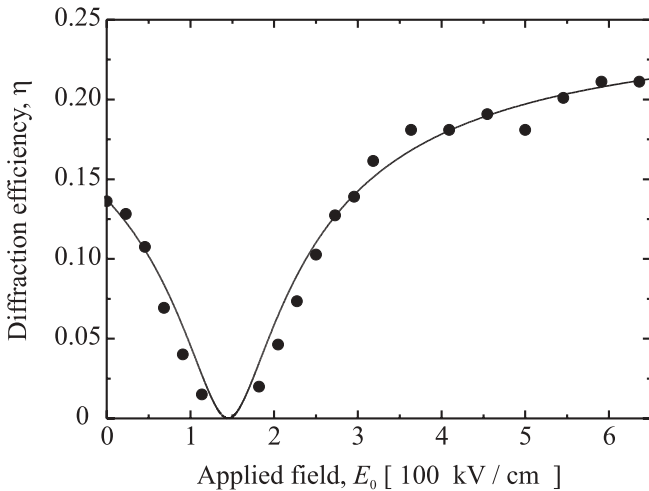
Two-wave-coupling experiments are carried out in the R-geometry using a standard interference setup supplemented by a stabilization feedback loop [2, 3]. Two pump beams from an argon-ion laser ( $\lambda = 488 \text{ nm}$ ) are incident on opposite faces of the sample at small angles with regard to the surface normal; the corresponding grating spacing  $\Lambda$  is approximately  $105 \text{ nm}$ . The total input intensity is  $\approx 0.18 \text{ W cm}^{-2}$ . The temporal evolution of the output intensities  $|R_0|^2$  and  $|S_l|^2$ , the diffraction efficiency of the recorded index grating, as well as the feedback signal driving the input phase of the signal beam,  $\varphi_s$ , are measured.

We have mentioned first that the feedback sign (the sign of the error signal  $I_{2\omega}$ ) has to be different in the regions  $E_0 - E_{pv} < 0$  and  $E_0 - E_{pv} > 0$  to ensure maximization of diffraction efficiency. This observation is in full agreement with the theoretical predictions.

By monitoring the piezo-signal driving the input phase  $\varphi_s$  we have found that it is generally linear in steady state; no periodic (or quasi-periodic) oscillations of this signal were found. The time derivative of the input phase  $\Omega = d\varphi_s/dt$  was negative for  $E_0 \lesssim 100 \text{ kV cm}^{-1}$  and positive for  $E_0 \gtrsim 200 \text{ kV cm}^{-1}$ . Our experimental data on the field dependence of the detuning  $\Omega$  are presented in Fig. 5. One sees that the experimental dots are well fitted by a linear function. Furthermore, we have estimated that the maximum value of  $\Omega$  exceeds the reciprocal Maxwell time  $t_M^{-1}$



**FIGURE 5** Frequency detuning  $\Omega$  versus applied field  $E_0$  for  $\beta = 1$  and  $N^{2+} = 0.7 \times 10^{18} \text{ cm}^{-3}$ . The filled dots are experimental data and the solid line is a linear fit



**FIGURE 6** Diffraction efficiency  $\eta$  versus applied field  $E_0$  for  $\beta = 1$  and a donor concentration  $N^{2+} \simeq 1.1 \times 10^{18} \text{ cm}^{-3}$  ( $\alpha \simeq 5 \text{ cm}^{-1}$ ). The filled squares are experimental data and the solid curve is the result of numerical simulation for  $c = 2/3$

by a factor of  $\approx 4.3$  in our experiment. This is not far from the data of Fig. 3. The main source of a spread of experimental dots are fluctuations of the input phase difference which are compensated by the feedback loop. Extreme precautions are necessary to diminish these fluctuations strongly.

Within the range  $100 \text{ kV cm}^{-1} \lesssim E_0 \lesssim 200 \text{ kV cm}^{-1}$  operation of the feedback loop was not stable enough to ensure reproducible measurements of the frequency shift. Only some qualitative indications of increasing  $|\Omega(E_0)|$  for  $E_0$  approaching  $E_{pv}$  were found.

Lastly, we present the results on the field dependence of the diffraction efficiency  $\eta$ . The experimental data for  $\beta = 1$  and the theoretical fit are shown in Fig. 6. The agreement between experiment and theory is pretty good. Note that the use of the fitting parameter  $c$ , which controls the saturation level of the amplitude  $E_K$ , is a crucial element of our simulations of the feedback operation.

## 5 Summary

The main results of this paper can be summarized as follows:

- It is shown theoretically for the reflection geometry that the  $\pm\pi/2$  feedback conditions for stabilization of two-wave coupling can be implemented regardless of dynamic distortions of the grating fringes.
- It is shown theoretically and experimentally that the feedback loop does not lead to periodic states in the reflection geometry, in contrast to the transmission configurations.
- It is proven theoretically and experimentally that the feedback operation is not reduced to stabilization of the light fringes; it introduces generally a frequency detuning between the incident light beams, i.e. a moving space-charge grating arises.
- It is shown theoretically for  $\text{LiNbO}_3:\text{Fe}$  crystals that the feedback-introduced detuning  $\Omega$  is resonant to the eigenfrequency  $\omega_K$  of the space-charge waves predicted earlier for the R-geometry and large driving field  $E_0 - E_{pv}$ .
- It is proven experimentally that the feedback-introduced frequency detuning  $\Omega$  is proportional to  $E_0 - E_{pv}$  in the region of large applied field and can be identified with the eigenfrequency  $\omega_K$ . Thus, a resonant excitation of space-charge waves and strong modification of the photorefractive response take place.

## Appendix A: calculation of $S_T$ and $S_D$

Equations (1) and (2) describe a variety of diffraction (read-out) processes for the recorded grating of the amplitude  $E_K = E_K(z)$ . These processes are distinguished by the input values of the light amplitudes. Each particular readout process can be described in a simple algebraic manner if we know the recording amplitudes  $S(z)$  and  $R(z)$ . To prove it, we point out that the general solution  $\bar{S}$  and  $\bar{R}$  of the linear set of differential equations (1) and (2) with a ‘frozen’ grating profile  $E_K(z)$  can be presented as

$$\begin{pmatrix} \bar{S} \\ \bar{R} \end{pmatrix} = c_1 \begin{pmatrix} S_1 \\ R_1 \end{pmatrix} + c_2 \begin{pmatrix} S_2 \\ R_2 \end{pmatrix}, \quad (\text{A.1})$$

where  $S_1(z)$ ,  $R_1(z)$  and  $S_2(z)$ ,  $R_2(z)$  are two independent particular solutions of the set (1) and (2) and  $c_{1,2}$  arbitrary constants. As the first solution we use the recording amplitudes,  $S_1 = S$  and  $R_1 = R$ . By taking the complex conjugate of (1) and (2), one can make sure that  $S_2 = R^*$  and  $R_2 = S^*$  can be chosen as the second independent solution.

To find the transmitted amplitude  $S_T$ , we have to consider the particular solution  $\bar{S}$  and  $\bar{R}$  meeting the boundary conditions  $\bar{S}(0) = S_0$  and  $\bar{R}(l) = 0$ . From here and (A.1) one can easily express  $c_{1,2}$  through the boundary values of the recording amplitudes  $S_0$ ,  $S_l$ ,  $R_0$ , and  $R_l$ . By calculating  $S_D = \bar{S}(l)$  from (A.1) we arrive at the necessary explicit expression, see (3). The diffracted component  $S_D = \bar{S}(l)$  can be calculated similarly; it corresponds to the boundary conditions  $\bar{S}(0) = 0$  and  $\bar{R}(l) = R_l$ .

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