**KIDNEYS, URETERS, BLADDER, RETROPERITONEUM**



# **A methodological study of 2D shear wave elastography for noninvasive quantitative assessment of renal fbrosis in patients with chronic kidney disease**

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## **Abstract**

**Purpose** To determine the optimal measurement method of 2D shear wave elastography (2D-SWE) for noninvasive quantitative assessment of renal fbrosis in chronic kidney disease (CKD) patients.

**Methods** A total of 190 CKD patients were enrolled for 2D-SWE of right kidney. The success rates, coefficients of variation (CV), and pathological correlation of diferent measurement sites, body positions, and depths were compared.

**Results** (1) Measurement sites: Success rate in the middle part (100%) was higher than that in the lower pole (97.3%, *P*>0.05). CV in the middle part (10.2%) was lower than that in the lower pole (16.4%, *P*<0.05). Pathological correlation of the middle part  $(r = -0.452, P < 0.05)$  was higher than that of the lower pole  $(r = 0.097, P > 0.05)$ . (2) Body positions: Success rate in left lateral decubitus position (100%) was higher than that in supine (99.4%, *P*>0.05) and prone position (99.4%,  $P > 0.05$ ). CV was lowest (11.9%) and pathological correlation was highest ( $r = 0.256$ ,  $P < 0.05$ ) in prone position. (3) Measurement depths: Success rate at depth<4 cm (100%) was higher than that at depth≥4 cm (98.8%, *P*>0.05). CV at depth <4 cm (11.1%) was lower than that at depth  $\geq 4$  cm (14.4%, *P* < 0.05). Pathological correlation at depth <4 cm (*r*= −0.303, *P*<0.05) was higher than that at depth≥4 cm (*r*= −0.156, *P*>0.05).

**Conclusion** The optimal measurement method of 2D-SWE for renal fbrosis assessment was prone position, renal middle part, and measurement depth  $<$  4 cm.

**Keywords** 2D shear wave elastography · Noninvasive assessment · Renal fbrosis · Methodological study



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#### **Abbreviations**



## **Introduction**

Nowadays, the high prevalence and mortality of CKD have caused a huge social and medical burden [[1,](#page-10-0) [2\]](#page-10-1). At present, the global prevalence of CKD is about 9.1% [\[1\]](#page-10-0). In China, CKD patients in tertiary hospitals account for 4.86% of the total inpatients; the total medical expenditure of all CKD patients in China was 27.646 billion yuan, accounting for 6.50% of the total medical expenditure in 2016 [[2\]](#page-10-1). Renal fbrosis is the main pathological change in the course of CKD [[3\]](#page-10-2). The evaluation of degree of fbrosis has important

guiding signifcance for disease assessment, prognosis judgment, and treatment decisions of CKD.

Renal biopsy and histopathological examination is still the gold standard for evaluating degree of renal fbrosis in CKD patients, but it has some complications such as hemorrhage, infection, vascular fistula, etc.  $[4, 5]$  $[4, 5]$  $[4, 5]$  $[4, 5]$  $[4, 5]$ , even nephrectomy or death [\[6](#page-11-1)]. And it is also unsuitable for long-term and repeated monitoring of CKD because of invasiveness. Therefore, attention has been focused on looking for noninvasive techniques for early monitoring renal fbrosis.

The common clinical indicators for monitoring the progression of CKD mainly include estimated glomerular fltration rate (eGFR), proteinuria, etc., but these indicators have a low specifcity in evaluation of the severity of CKD [\[7](#page-11-2)[–9](#page-11-3)]. In addition, imaging examination is also a common method in CKD, such as magnetic resonance techniques [\[10](#page-11-4)–[12\]](#page-11-5); however, they are also affected by renal blood perfusion, collecting system dilation, tissue edema, etc. Furthermore, these methods indirectly refect the degree of renal fbrosis through evaluation of renal function, mechanical properties, molecular properties, etc., conducing to certain limitations in the evaluation of CKD.

Ultrasound imaging is a common examination with advantages of real-time, safe, noninvasive, cheap, and high patient acceptance. Conventional ultrasound can provide information refecting the existence of renal parenchymal injury [[13](#page-11-6), [14](#page-11-7)]. However, the correlations between ultrasound parameters and renal fbrosis were not high, so the value of conventional ultrasound in diagnosis and evaluation of CKD was limited.

Fibrosis can directly cause changes in elasticity of organs, which is reflected as increased tissue stiffness [[15\]](#page-11-8). Ultrasound elastography can be used to assess stifness noninvasively, and has been widely used in clinical evaluation of tissue stifness. Until now, there have been a certain amount of studies on renal ultrasound elastography, showing that the relationships between renal elasticity and renal fbrosis were usually diferent or even contradictory [[4,](#page-10-3) [16](#page-11-9)[–18](#page-11-10)]. There is still no uniform operation standard for renal ultrasound elastography, which may be one of the reasons for the inconsistency of results in the above studies. Therefore, we used 2D-SWE to carry out renal elastography under diferent measurement sites, body positions, and measurement depths, in an attempt to establish the methodological standards for renal elasticity measurement.

# **Materials and methods**

#### **Subjects**

A total of 190 CKD patients were prospectively recruited, who were admitted to the Department of Nephrology of our hospital from April 2019 to March 2021. This study was approved by the ethics committee of our hospital, and all the subjects signed the informed consent. Inclusion criteria for patients in this study were as follows: (1) Patients met the clinical diagnostic criteria for CKD [[19\]](#page-11-11) and (2) patients underwent a 2D-SWE examination of their right kidneys. Exclusion criteria were as follows: (1) patients were unable to undergo 2D-SWE or with inadequate or incomplete data collected; (2) the quality of ultrasound images was poor; and (3) the 2D-SWE examination was afected by renal lesions such as calculi, cysts, tumors, hydronephrosis, etc. Characteristics of patients like gender, age, height, weight, and body mass index (BMI) were recorded.

#### **Instruments and methods**

- (1) *Instruments* SWE examination was performed with a Supersonic Imagine Aixplorer ultrasound system (Aixen-Provence, France) that was equipped with an XC6-1 convex array probe with a frequency of 1–6 MHz. The size of the elastography sampling box was set as 4 cm×3 cm, and the diameter of the ROI was set as 4 mm. The elastography scale was displayed in kPa, and the range was fxed from 0 to 80 kPa.
- (2) *Shear wave elastography* All patients underwent 2D-SWE examination 1 day before renal biopsy with kidney scanning conditions predetermined by ultrasonic instrument. After micturition, patients were instructed to lie in supine, left lateral decubitus, and prone positions, respectively. All patients frst underwent a B-mode renal ultrasound scan, and then the 2D-SWE mode. Patients were required to hold their breath for 3–5 s with the sampling box placed in the middle part and lower pole of renal cortex, respectively. The color elastic images were captured and frozen. In the color imaging area, the circular ROI was placed in the cortex. Then the mean value of renal elastic modulus (unit: kPa) within the ROI (Fig. [1](#page-2-0)) and measurement depth (the distance between probe and ROI) was recorded. The detection was repeated 5 times under various conditions. A successful measurement was defned as the color-flling area was more than half of the elastic sampling box; full images were obtained within the sampling ROI; the Emin was higher than 0 (an example of successful measurements is shown in Fig. [2](#page-3-0); example of unsuccessful measurements are shown in Fig. [3\)](#page-3-1). For the 5 repeated measurements of the same patient, at least 3 successful measurements (i.e., a measurement success rate of more than 60%) were considered to be successful. If a patient's measurements were unsuccessful (i.e., the measurement success rate was less than 60%), the patient's data would be excluded. The mean value of measurements meet-



<span id="page-2-0"></span>**Fig. 1** Real-time 2D-SWE of right kidney in patients with CKD (including fan-shaped sampling box, circular ROI, and Young's modulus of Q-box)

ing the success criteria in these fve measurements was taken as the fnal stifness for statistical analysis. All patients were examined by the same sonographer with nearly 10 years of conventional ultrasound and more than 5 years of elastography experience. The operator had no knowledge of the patient's clinical data, laboratory test results, etc.

- (3) *Renal biopsy* Patients underwent percutaneous needle biopsy of right kidneys guiding by ultrasound with automatic biopsy gun (MG1522 Bard automatic biopsy gun, Bard Company, USA) and matching 16 G biopsy needle. The patients were instructed to lie in prone position and punctured in the lower pole of right kidneys avoiding large vessels. Biopsy specimens obtained were fxed and stained for observation.
- (4) *Evaluation of renal fbrosis* All the renal biopsy specimens were analyzed by two pathologists. The degree of renal fbrosis was evaluated based on Katafuchi semiquantitative scoring system [\[5](#page-11-0), [20](#page-11-12)]. CKD patients were then classifed according to the total scores: mildly impaired ( $\leq$ 9 points); moderately impaired (10–18 points); and severely impaired ( $\geq$  19 points). The total

score was used to evaluate the degree of renal fbrosis for correlation analysis.

## **Study design**

We studied various impact factors of 2D-SWE in 190 subjects, including measurement site, body position, and measurement depth.

- (1) *Study of diferent measurement sites* The cortical stifness values of the middle part and lower pole of kidneys were measured in the prone position (since renal needle biopsy was performed in prone position). Evaluation indicators of diferent measurement sites were compared to select the best measurement site.
- (2) *Study of diferent body positions* The cortical stifness values of the middle part of kidneys (based on the results of previous part, the best measurement site was the middle part of kidneys) were measured in the supine, left lateral decubitus, and prone positions,



<span id="page-3-0"></span>**Fig. 2** An example of successful measurements: The color-flling area was more than half of the elastic sampling box; full images were obtained within the sampling ROI; the Emin was higher than 0 (an example of successful measurements)



<span id="page-3-1"></span>**Fig. 3** An example of unsuccessful measurements: The color in the ROI of the 2D-SWE image was not full-flling

respectively. Evaluation indicators of diferent body positions were compared to select the best body position.

- (3) *Study of diferent measurement depths* The cortical stifness values of the middle part of kidneys were measured in the prone position (based on the results of previous two parts, the best measurement site and body position were the middle part and the prone position). The measurement depths were divided into two groups ( $\lt$  4 cm and  $\geq$  4 cm, the division of depth range was based on early preliminary study) according to the distance from the skin to renal cortex detected. Evaluation indicators of diferent depth ranges were compared to select the best depth range for measurement.
- (4) *Evaluation indicators* Success rate=the number of people successfully measured/the total number of people measured  $\times 100\%$ ; coefficient of variation = Standard deviation of 5 measurements of stifness values/ mean of 5 measurements of stiffness values  $\times 100\%$ , expressed in the form of median (25% percentile, 75% percentile); spearman correlation coefficient (*r* value) was used to indicate the correlation between renal stifness and the total score of renal fbrosis.

#### **Statistical analysis**

IBM SPSS Statistics (version 22.0) was used for data analysis. Numerical variables with normal distribution were expressed as mean value and standard deviation (SD), whereas variables with nonnormal distribution were expressed as median (25% percentile, 75% percentile). Nonparametric test was used for comparison between groups. Two independent samples were compared by Mann–Whitney *U* test; multiple independent samples were compared by Kruskal–Wallis one-way ANOVA, and Bonferroni correction was used for pairwise comparison. Chi square test was used for the comparison of two groups of success rates, while chi-square segmentation was used for the comparison of multiple groups of success rates. Correlation between stifness measured by 2D-SWE and the degree of renal fibrosis was analyzed by Spearman correlation coefficient. *P*<0.05 was considered statistically signifcant.

## **Results**

We performed 2D-SWE on the right kidneys in 190 patients with CKD. The characteristics of these patients are shown in Table [1](#page-4-0).

<span id="page-4-0"></span>**Table 1** The characteristics of patients



\*Data were described in the form of number of males/number of females

## **Infuence of measurement site on 2D‑SWE measurement**

The inclusion process is shown in Fig. [4.](#page-5-0) There was no signifcant diference of the success rate between the middle part and lower pole  $(P > 0.05)$  (Table [2](#page-5-1)). The coefficient of variation of each measurement site showed that the fve repeated measurements in the renal middle part had better stability  $(P < 0.05)$  (Table [3](#page-5-2)).

The correlation analysis is shown in Table [4](#page-6-0), Fig. [5](#page-6-1) and [6.](#page-6-2) The correlation between renal stifness of the middle part and degree of renal fibrosis ( $r = -0.452$ ,  $P < 0.05$ ) was higher than that of the lower pole  $(r=0.097, P>0.05)$ . Therefore, the stifness of renal middle part was more correlated with the degree of fbrosis than the lower pole.

#### **Infuence of body position on 2D‑SWE measurement**

The inclusion process is shown in Fig. [7](#page-7-0). There was no statistically signifcant diference in the success rate among the three body positions  $(P > 0.05)$  (Table [5](#page-7-1)). As shown in Table [6,](#page-7-2) renal 2D-SWE had better stability between fve repeated measurements when performed in the prone position  $(P < 0.05)$ .

The correlation analysis is shown in Table [7](#page-8-0), Figs. [8](#page-8-1), [9,](#page-8-2) and [10](#page-8-3). The correlation between renal stifness and degree of fibrosis was highest in prone position ( $r = -0.256$ ,  $P < 0.05$ ), then in supine position ( $r = -0.249$ ,  $P < 0.05$ ), and lowest in left lateral decubitus position (*r*=-0.158, *P*>0.05). Therefore, prone position was an ideal body position in terms of pathological correlation.

#### **Infuence of depth on 2D‑SWE measurement**

The inclusion process is shown in Fig. [11.](#page-9-0) There was no statistically signifcant diference of the success rate between depth <4 cm and depth  $\geq$  4 cm (*P* > 0.05) (Table [8](#page-9-1)). As shown in Table [9](#page-9-2), renal 2D-SWE had better stability



<span id="page-5-0"></span>**Fig. 4** The inclusion process of study on diferent measurement sites

<span id="page-5-1"></span>**Table 2** Infuence of measurement site on the success rate of renal 2D-SWE

Measurement site Number of suc-	cessfully meas- ured patients	Total number of patients	Success rate $(\%)$
Middle part	74	74	100
Lower pole	72.	74	97.3

There was no signifcant diference of the success rate between the middle part and lower pole

<span id="page-5-2"></span>Table 3 Coefficient of variation of each measurement site in CKD patients

Measurement site	Coefficient of vari- $P_{25}$ (%) ation $(\%)$		$P_{75}$ (%)
Middle part	10.2	7.5	15.2
Lower pole	16.4	13.4	22.9

There was a significant difference of coefficient of variation between the middle part and lower pole

 $P_{25}$  was the 25% percentile,  $P_{75}$  was the 75% percentile

<span id="page-6-0"></span>**Table 4** Correlation analysis between renal stifness and total score of renal fbrosis in each measurement site

Pathological score	Middle part		Lower pole	
Total score	$-0.452*$	0.000	0.097	0.422

\**P*<0.05



<span id="page-6-1"></span>**Fig. 5** The correlation between renal stifness of the middle part and degree of renal fbrosis



<span id="page-6-2"></span>**Fig. 6** The correlation between renal stifness of the lower pole and degree of renal fbrosis

between fve repeated measurements when performed at a depth < 4 cm ( $P$  < 0.05).

The correlation analysis is shown in Table [10,](#page-10-4) Figs. [12](#page-10-5) and [13](#page-10-6). The correlation between renal stifness and fbrosis degree of depth <4 cm  $(r = -0.303, P < 0.05)$  was higher than that of depth > 4 cm  $(r = -0.156, P > 0.05)$ . Therefore, depth <4 cm was an ideal depth range in terms of pathological correlation.

## **Discussion**

In this study, we analyzed multiple methodological evaluation indicators under diferent measurement sites, body positions, and measurement depths, and got a comprehensive methodological suggestion, that is, prone position, renal middle part, measurement depth<4 cm, for 2D-SWE in CKD patients.

Comparing to the results of measurement site in our study, Bob et al. [[21\]](#page-11-13) obtained a similar success rate of 98.17% in the renal middle part; Wang et al. [[18\]](#page-11-10) obtained a higher CV of  $23.0 \pm 8.3\%$  when measuring renal stiffness in the middle part of 45 CKD patients, indicating that the stability of renal stifness measurement in our study was better. Hu et al. [[17](#page-11-14)] showed a similar correlation between middle cortical stifness and renal fbrosis histological score (*r* = −0.511, *P* < 0.001) in 163 CKD patients.

The higher success rate of renal middle part could be related to its perpendicular relation to ultrasonic wave, better acoustic window, and relatively fxed position. While the measurement of lower pole was often disturbed by the surrounding intestinal gas, simultaneously lower pole was relatively difficult to identify clearly because of its deep position and afection by respiratory movement. Besides, the lower pole had a greater anisotropy, resulting in a larger SWE measurement error.

Comparing to the results of the infuence of body position in our study, Bob et al. [\[21](#page-11-13)] achieved a similar success rate of 98.17% in renal stifness measurement in left lateral decubitus position, while Wang et al.  $[18]$  $[18]$  measured a higher coefficient of variation of SWE as  $23.0 \pm 8.3\%$  in 45 CKD patients under lateral decubitus position. Hu et al. [[17](#page-11-14)] measured renal stifness in 163 patients with CKD in left lateral decubitus position, and the correlation between cortical stifness and renal fibrosis histological score  $(r = -0.511, P < 0.001)$ was signifcantly higher than the pathological correlation in each body position in our study. The reasons for the lower correlation in our study need to be further explored.



<span id="page-7-0"></span>**Fig. 7** The inclusion process of study on diferent body positions

<span id="page-7-1"></span>**Table 5** Infuence of body position on the success rate of renal 2D-SWE

Body position	Number of suc- cessfully measured patients	Total number of patients	Success rate $(\%)$
Supine position 180		181	99.4
Left lateral decubitus position	181	181	100
Prone position	180	181	99.4

<span id="page-7-2"></span>Table 6 Coefficient of variation of each body position in CKD patients



 $P_{25}$  was the 25% percentile,  $P_{75}$  was the 75% percentile

 $a<sup>a</sup>$ Means  $P < 0.05$  for supine versus prone position

There was no signifcant diference in the success rate among the three body positions

<sup>b</sup>Means  $P < 0.05$  for left lateral decubitus versus prone position

The explanation for the results of best body position may be related to that the distance between kidney and body surface varies with the body positions. In supine position, the kidney is relatively far from the body surface due to the shielding of subcutaneous fat and liver. In left lateral decubitus position, the liver moves down due to gravity, so that the position of kidney is relatively shallow with improved ultrasound transmission. In the prone position, there is mainly muscle tissue between kidney and body surface, so it is easy to obtain better ultrasonic imaging. Moreover, the movement of kidney with the breath in prone position is relatively small, so the results of repeated measurements are more stable and the stifness values measured are more accurate.

<span id="page-8-0"></span>**Table 7** Correlation analysis between renal stifness and total score of renal fbrosis in each body position





\**P*<0.05

<span id="page-8-1"></span>**Fig. 8** The correlation between renal stifness in supine position and degree of renal fbrosis



<span id="page-8-2"></span>**Fig. 9** The correlation between renal stifness in left lateral decubitus position and degree of renal fbrosis

Our study on the infuence of measurement depth on renal 2D-SWE showed that depth  $<$  4 cm had a higher success rate (100%), a lower coefficient of variation (11.1%), and a higher pathological correlation ( $r = -0.303$ ,  $P < 0.05$ ). Due to the lack of similar studies on renal SWE, the results of



<span id="page-8-3"></span>**Fig. 10** The correlation between renal stifness in prone position and degree of renal fbrosis

our study cannot be compared with other studies for the time being.

The success rate was lower with measurement depth increased, which may relate to the greater ultrasound attenuation. In addition, an increased measurement depth usually means obesity; fat can cause more ultrasound energy loss [\[22](#page-11-15)], resulting in a lower success rate. Similarly, as the measurement deepens, ultrasound will have a certain degree of attenuation, showing that the shear wave becomes weaker with the increase of depth, which may be the reason for the reduction of stability and accuracy.

In our study, renal elasticity and fbrosis degree were basically negatively correlated under all measurement conditions, which was similar to the results of Asano et al. [[23](#page-11-16)], indicating that renal tissue elasticity gradually decreased with the progression of fbrosis in CKD. This result was in contrast to that found in chronic liver disease, in which the elasticity of liver tissue gradually increased with the progression of liver fbrosis [\[24\]](#page-11-17). As for the negative correlation between renal elasticity and fbrosis degree, it may be related to the following factors: (1) Renal fbrosis is not the main infuencing factor of renal tissue elasticity in ultrasound elastography [\[23](#page-11-16)]. (2) Renal



<span id="page-9-0"></span>**Fig. 11** The inclusion process of study on diferent measurement depths

<span id="page-9-1"></span>**Table 8** Infuence of measurement depth on the success rate of renal 2D-SWE

Measurement depth	Number of suc- cessfully meas- ured patients	Total number of patients	Success rate $(\%)$
Depth $<$ 4 cm	108	108	100
Depth $\geq$ 4 cm	81	82	98.8

There was no signifcant diference of the success rate between  $depth < 4$  cm and depth  $\geq 4$  cm

<span id="page-9-2"></span>Table 9 Coefficient of variation of each measurement depth range in CKD patients

Measurement depth	Coefficient of vari- $P_{25}$ (%) ation $(\%)$		$P_{75}$ (%)
Depth $<$ 4 cm	11.1	7.5	15.2
Depth $\geq$ 4 cm	14.4	9.1	18.0

There was a significant difference of coefficient of variation between  $depth < 4$  cm and depth $\geq 4$  cm

 $P_{25}$  was the 25% percentile,  $P_{75}$  was the 75% percentile

<span id="page-10-4"></span>**Table 10** Correlation analysis between renal stifness and total score of renal fbrosis in each measurement depth range

Pathological score	Depth $<$ 4 cm		Depth $\geq$ 4 cm	
Total score	$-0.303*$	0.006	$-0.156$	0.225

\**P*<0.05



<span id="page-10-5"></span>Fig. 12 The correlation between renal stiffness of depth <4 cm and degree of fbrosis



<span id="page-10-6"></span>**Fig. 13** The correlation between renal stifness of depth≥4 cm and degree of fbrosis

parenchymal elasticity is not only afected by the degree of renal fbrosis, but also afected by renal blood perfusion, vascular pressure, and urinary flow pressure [[23,](#page-11-16) [25\]](#page-11-18).

This study had the following limitations. First, the sample size of this study was relatively small, which may afect the credibility of the results and need further improvement by expanding the sample size. Second, studies had reported that renal parenchymal stifness was not only afected by the degree of renal fbrosis, but also afected by renal blood perfusion, vascular pressure, and urinary fow pressure [\[23,](#page-11-16) [25\]](#page-11-18). However, our study did not control these confounding factors, which was not conducive to the correlation analysis of renal stifness and renal pathological fbrosis degree.

## **Conclusions**

In this study, after a comprehensive evaluation of measurement success rate, coefficient of variation, and pathological correlation, the optimal measurement method of 2D-SWE for noninvasive evaluation of renal fibrosis degree was obtained: prone position, renal middle part, measurement  $depth < 4$  cm.

**Author contributions** Conceptualization: ZS, YL, YH; Methodology: JC, YH, ZS; Formal analysis and investigation: YL, JC; Writing original draft preparation: YL; Writing—review and editing: JC, YH, YL, ZS; Resources: ZS; Supervision: ZS, YL, YH.

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## **Declarations**

**Conflict of interest** The authors have no relevant fnancial or non-fnancial interests to disclose.

**Ethical approval** This is an observational study. The ethics committee at the Fifth Afliated Hospital of Sun Yat-sen University has confrmed that no ethical approval is required.

**Informed consent** Informed consent was obtained from all individual participants included in the study.

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