Local and Global Well-Posedness of Strong Solutions to the 3D Primitive Equations with Vertical Eddy Diffusivity

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Abstract

In this paper, we consider the initial-boundary value problem of the viscous 3D primitive equations for oceanic and atmospheric dynamics with only vertical diffusion in the temperature equation. Local and global well-posedness of strong solutions are established for this system with H^2 initial data.

1. Introduction

The primitive equations are derived from the full incompressible Navier–Stokes equations using the Boussinesq and hydrostatic approximations. They are the fundamental models for weather prediction, see, for example, Lewandowski [14], Pedlosky [19], and Washington and Parkinson [25]. In the context of the oceans and the atmosphere dynamics the horizontal scales are much larger than the vertical one. By taking advantage of this, the scale analysis (see, for example, Pedlosky [19] and Vallis [24]) leads to the hydrostatic approximation, see also Azérad and Guillén [1] and Lions et al. [16] for the rigourous mathematical justification.

In this paper, we consider the primitive equations with only vertical diffusion. The primitive equations are given by the following system (see, for example, [15, 16, 18, 20, 23])

$$\partial_t v + (v \cdot \nabla_H)v + w\partial_z v + \nabla_H p + L_1 v + f_0 k \times v = 0, \qquad (1.1)$$

$$\partial_z p + T = 0, \qquad (1.2)$$

$$\nabla_H \cdot v + \partial_z w = 0, \qquad (1.3)$$

$$\partial_t T + (v \cdot \nabla_H)T + w\partial_z T + L_2 T = Q, \qquad (1.4)$$

where the horizontal velocity $v = (v^1, v^2)$, the vertical velocity w, the temperature T and the pressure p are the unknowns, f_0 is the Coriolis parameter, and Q is a given heat source. In the above system, the term $k \times v$ is understood as the

first two components of the vector product of $k = (0, 0, 1)$ and $(v^1, v^2, 0)$. Here, for simplicity, we assume that the heat source Q is identically zero; however, the results obtained in this paper hold true for the nonzero but appropriately regular Q. The operators L_1 and L_2 in (1.1) and (1.4) are the viscosity and the heat vertical diffusion operators, respectively, given by

$$L_1 = -\frac{1}{R_1}\Delta_H - \frac{1}{R_2}\partial_z^2, \qquad L_2 = -\frac{1}{R_3}\partial_z^2$$

with positive constants R_1, R_2 and R_3, where R_1, R_2 represent the horizontal and vertical dimensionless Reynolds numbers, respectively, while R_3 is the vertical dimensionless eddy heat diffusivity turbulence mixing coefficient (see [8,9] for example). In this paper, we use the notations $\nabla_H = (\partial_x, \partial_y)$ and $\Delta_H = \partial_x^2 + \partial_y^2$ to stand for the horizontal gradient and Laplacian, respectively.

The mathematical studies of primitive equations were initiated by Lions et al. [15–17] in 1990s, where the global existence of weak solutions were obtained. Weak solutions in 2D turn out to be unique, see Bresch et al. [2]; however, the uniqueness of weak solutions in the three-dimensional case is still unclear. Concerning the strong solutions for the 2D case, the local existence result was established by Guillén-González et al. [10], while the global existence was achieved by Bresch et al. [3] and Temam and Ziane [23]. The global existence of strong solutions for the 3D case was established by Cao and Titi [6]. In [6], the authors take advantage of the observation that the pressure is essentially a function of the two-dimensional horizontal variables; as a result, they obtain the L^6 estimates on the velocity vector field, which allows them to prove the global well-posedness of strong solutions. The global existence of strong solutions were also obtained later by Kobelkov [11], see also the subsequent articles of Kukavica and Ziane [12,13] for a different boundary condition. In all the papers [6,11–13], systems are assumed to have diffusion in all directions. However, it was recently shown by Cao and Titi [7] that these global existence results still hold true for systems with only vertical diffusion, provided the local in time strong solutions exist. Notably, it has also been shown recently in [4] that for a certain class of initial data the solutions of the invisicd 2D and 3D primitive equations develop finite-time singularity (see also [26] for a related result).

The aims of this paper are two fold on one hand, we establish the local existence of strong solutions to the primitive equations with only vertical diffusion, provided the initial data belong to H^2; on the other hand, we prove that this local strong solution can be in fact extended to be a global one by adopting the energy estimates established in [7] and some suitable t-weighted estimates, as well as our local existence result. Note that the regularity assumptions on the initial data in this paper are weaker than those in Cao and Titi [7] and consequently we improve the results of [7].

In this paper, we consider the problem in the domain $\Omega_0 = M \times (-h, 0)$ with $M = (0, 1) \times (0, 1)$. We complement system (1.1)–(1.4) with the boundary conditions

$$v, w, T \text{ are periodic in } x \text{ and } y, \tag{1.5}$$

$$(\partial_z v, w)|_{z=-h,0} = 0, \tag{1.6}$$

$$T|_{z=-h} = 1, \quad T|_{z=0} = 0, \tag{1.7}$$

and the initial data

$$(v, T)|_{t=0} = (v_0, T_0). \tag{1.8}$$

Replacing T and p by $T + \frac{z}{h}$ and $p - \frac{z^2}{2h}$, respectively, then system (1.1)–(1.4) with (1.5)–(1.8) is equivalent to the following system

$$\partial_t v + (v \cdot \nabla_H)v + w\partial_z v + \nabla_H p + L_1 v + f_0 k \times v = 0, \tag{1.9}$$

$$\partial_z p + T = 0, \tag{1.10}$$

$$\nabla_H \cdot v + \partial_z w = 0, \tag{1.11}$$

$$\partial_t T + (v \cdot \nabla_H)T + w\left(\partial_z T + \frac{1}{h}\right) + L_2 T = 0, \tag{1.12}$$

complemented with the boundary and initial conditions

$$v, w, T \text{ are periodic in } x \text{ and } y, \tag{1.13}$$

$$(\partial_z v, w)|_{z=-h,0} = 0, \quad T|_{z=-h,0} = 0, \tag{1.14}$$

$$(v, T)|_{t=0} = (v_0, T_0). \tag{1.15}$$

Here, for simplicity, we still use T_0 to denote the initial temperature in (1.15), though it is now different from that in (1.8).

Notice that the periodic subspace $\mathcal{H}$, given by

$$\mathcal{H} := \{(v, w, p, T)|v, w, p \text{ and } T \text{ are spatially periodic in all three variables}$$
$$\text{and even, odd, even and odd in } z \text{ variable, respectively}\},$$

is invariant under the dynamics system (1.1)–(1.4). That is if the initial data satisfy the properties stated in the definition of $\mathcal{H}$, then, as we will see later (see Theorem 1.1), the solutions to system (1.1)–(1.4) will obey the same symmetry as the initial data. This motivated us to consider the following system

$$\partial_t v + (v \cdot \nabla_H)v + w\partial_z v + \nabla_H p + L_1 v + f_0 k \times v = 0, \tag{1.16}$$

$$\partial_z p + T = 0, \tag{1.17}$$

$$\nabla_H \cdot v + \partial_z w = 0, \tag{1.18}$$

$$\partial_t T + (v \cdot \nabla_H)T + w\left(\partial_z T + \frac{1}{h}\right) + L_2 T = 0, \tag{1.19}$$

in $\Omega := M \times (-h, h)$, subject to the boundary and initial conditions

$$v, w, p \text{ and } T \text{ are periodic in } x, y, z, \tag{1.20}$$

$$v \text{ and } p \text{ are even in } z, \text{ and } w \text{ and } T \text{ are odd in } z, \tag{1.21}$$

$$(v, T)|_{t=0} = (v_0, T_0). \tag{1.22}$$

One can easily check that the restriction on the sub-domain Ω_0 of a solution (v, w, p, T) to system (1.16)–(1.22) is a solution to the original system (1.9)–(1.15). Because of this, throughout this paper, we are mainly concerned with the study of system (1.16)–(1.22) defined on Ω, while the well-posedness results for system (1.9)–(1.15) defined on Ω_0 follow as a corollary of those for system (1.16)–(1.22).

For any function $\phi(x, y, z)$ defined on Ω, we denote

$$\bar{\phi}(x, y) = \frac{1}{2h} \int_{-h}^{h} \phi(x, y, z) \, dz, \qquad \tilde{\phi} = \phi - \bar{\phi}.$$

System (1.16)–(1.22) is equivalent to (see, for example, [7])

$$\partial_t v + L_1 v + (v \cdot \nabla_H)v - \left(\int_{-h}^{z} \nabla_H \cdot v(x, y, \xi, t) \, d\xi \right) \partial_z v$$

$$+ f_0 k \times v + \nabla_H \left(p_s(x, y, t) - \int_{-h}^{z} T(x, y, \xi, t) \, d\xi \right) = 0, \qquad (1.23)$$

$$\nabla_H \cdot \bar{v} = 0, \qquad (1.24)$$

$$\partial_t T + L_2 T + v \cdot \nabla_H T - \left(\int_{-h}^{z} \nabla_H \cdot v(x, y, \xi, t) \, d\xi \right) \left(\partial_z T + \frac{1}{h} \right) = 0 \quad (1.25)$$

in $\Omega = M \times (-h, h)$, complemented with the following boundary and initial conditions

$$v \text{ and } T \text{ are periodic in } x, y, z, \qquad (1.26)$$

$$v \text{ and } T \text{ are even and odd in } z, \text{ respectively}, \qquad (1.27)$$

$$(v, T)|_{t=0} = (v_0, T_0). \qquad (1.28)$$

In addition, one can also check that $\bar{v}$ and $\tilde{v}$ satisfy the following system (see, for example, [7])

$$\partial_t \bar{v} - \frac{1}{R_1} \Delta_H \bar{v} + (\bar{v} \cdot \nabla_H)\bar{v} + \overline{(\tilde{v} \cdot \nabla_H)\tilde{v} + (\nabla_H \cdot \tilde{v})\tilde{v}} + f_0 k \times \bar{v}$$

$$+ \nabla_H \left(p_s(x, y, t) - \frac{1}{2h} \int_{-h}^{h} \int_{-h}^{z} T(x, y, \xi, t) \, d\xi \, dz \right) = 0, \qquad (1.29)$$

$$\nabla_H \cdot \bar{v} = 0, \qquad (1.30)$$

$$\partial_t \tilde{v} + L_1 \tilde{v} + (\tilde{v} \cdot \nabla_H)\tilde{v} - \left(\int_{-h}^{z} \nabla_H \cdot \tilde{v}(x, y, \xi, t) \, d\xi \right) \partial_z \tilde{v} + (\tilde{v} \cdot \nabla_H)\bar{v}$$

$$+ (\bar{v} \cdot \nabla_H)\tilde{v} - \overline{(\tilde{v} \cdot \nabla_H)\tilde{v} + (\nabla_H \cdot \tilde{v})\tilde{v}} + f_0 k \times \tilde{v}$$

$$- \nabla_H \left(\int_{-h}^{z} T(x, y, \xi, t) \, d\xi - \frac{1}{2h} \int_{-h}^{h} \int_{-h}^{z} T(x, y, \xi, t) \, d\xi \, dz \right) = 0. \quad (1.31)$$

Throughout this paper, we denote by $L^q(\Omega)$, $L^q(M)$ and $W^{m,q}(\Omega)$, $W^{m,q}(M)$ the standard Lebesgue and Sobolev spaces, respectively. For $q = 2$, we use H^m instead of $W^{m,2}$. We use $W_{per}^{m,q}(\Omega)$ and H_{per}^m to denote the spaces of periodic functions in $W^{m,q}(\Omega)$ and $H^m(\Omega)$, respectively. For simplicity, we use the same notations

L^p and H^m to denote the N product spaces $(L^p)^N$ and $(H^m)^N$, respectively. We always use $\|u\|_p$ to denote the L^p norm of u.

Definitions of the strong solution, maximal existence time and global strong solution are stated in the following three definitions, respectively.

Definition 1.1. Let $v_0 \in H^2(\Omega)$ and $T_0 \in H^2(\Omega)$ be two periodic functions, such that they are even and odd in z, respectively. Given a positive number t_0. A couple (v, T) is called a strong solution to system (1.23)–(1.28) (or equivalently (1.16)–(1.22)) on $\Omega \times (0, t_0)$ if

  (i) v and T are periodic in x, y, z, and they are even and odd in z, respectively;
 (ii) v and T have the regularities

$$v \in L^\infty(0, t_0; H^2(\Omega)) \cap C([0, t_0]; H^1(\Omega)) \cap L^2(0, t_0; H^3(\Omega))$$
$$T \in L^\infty(0, t_0; H^2(\Omega)) \cap C([0, t_0]; H^1(\Omega)), \quad \partial_z T \in L^2(0, t_0; H^2(\Omega)),$$
$$\partial_t v \in L^2(0, t_0; H^1(\Omega)), \quad \partial_t T \in L^2(0, t_0; H^1(\Omega));$$

(iii) v and T satisfies (1.23)–(1.25) almost everywhere in $\Omega \times (0, t_0)$ and the initial condition (1.28).

Definition 1.2. A finite positive number T^* is called the maximal existence time of a strong solution (v, T) to system (1.23)–(1.28) if (v, T) is a strong solution to system on $\Omega \times (0, t_0)$ for any $t_0 < T^*$ and $\overline{\lim}_{t \to T^*_-} (\|v\|^2_{H^2} + \|T\|^2_{H^2}) = \infty$.

Definition 1.3. A couple (v, T) is called a global strong solution to system (1.23)–(1.28) if it is a strong solution on $\Omega \times (0, t_0)$ for any $t_0 < \infty$.

The main result of this paper is the following:

Theorem 1.1. *Suppose that the periodic functions $v_0, T_0 \in H^2(\Omega)$ are even and odd in z, respectively. Then system (1.16)–(1.22) has a unique global strong solution (v, T).*

As a first step in proving Theorem 1.1, we prove the local existence of strong solutions. This is done by regularizing the original system, solving the regularized system and then taking the limit as the regularization parameter ε tends to zero. More precisely, we first prove the local existence of strong solutions to the regularized system by the contraction mapping principle, then we prove that the existence time and the corresponding a priori estimates for these solutions are independent of the regularization parameter ε, and finally, thanks to these uniform estimates, we can take the limit to obtain the local strong solutions of the original system. By adopting the energy inequalities established in [7] and doing the t-weighted estimates on the high order derivatives, we prove that the H^2 norms of the solutions keep finite for any finite time, and thus prove the global existence of strong solutions.

As a corollary of Theorem 1.1, we have the following theorem, which states the well-posedness of strong solutions to system (1.9)–(1.15). The strong solutions to system (1.9)–(1.15) are defined in the similar way as before.

Theorem 1.2. *Let v_0 and T_0 be two functions such that they are periodic in x and y. Denote by v_0^{ext} and T_0^{ext} the even and odd extensions in z of v_0 and T_0, respectively. Suppose that v_0^{ext}, $T_0^{\text{ext}} \in H_{\text{per}}^2(\Omega)$. Then system* (1.9)–(1.15) *has a unique global strong solution* (v, T).

The existence part follows directly by applying Theorem 1.1 with initial data $(v_0^{\text{per}}, T_0^{\text{ext}})$ and restricting the solution on the sub-domain Ω_0, while the uniqueness part can be proven in the same way as that for Theorem 1.1.

Remark 1.1. The condition that v_0^{ext}, $T_0^{\text{ext}} \in H_{\text{per}}^2(\Omega)$ in the above theorem is necessary for the existence of strong solutions to system (1.9)–(1.15). Using similar arguments to those stated in the appendix section of this paper, one can show that strong solutions are in fact smooth away from the initial time. It follows from equation (1.12) and the boundary condition (1.14) that $\partial_z^2 T|_{z=-h,0} = 0$ for any $t > 0$, and thus we can extend T oddly and periodically in z such that T^{ext} is odd in z and belongs to $H_{\text{per}}^2(\Omega)$ for any $t > 0$. By the definition of strong solutions, it follows that $T \in L^\infty(0, t_0; H^2(\Omega_0)) \cap C([0, t_0]; L^2(\Omega_0))$, and thus $T^{\text{ext}} \in L^\infty(0, t_0; H^2(\Omega)) \cap C([0, t_0]; L^2(\Omega))$. Combining these statements, by Banach–Alaoglu theorem, it must have $T_0^{\text{ext}} \in H_{\text{per}}^2$. Similarly, one can verify that v_0^{ext} must belong to $H_{\text{per}}^2(\Omega)$.

The rest of this paper is arranged as follows: in the next section, Section 2, we prove the local existence of strong solutions to the regularized system; in Section 3, we establish the local existence and uniqueness of strong solutions to system (1.16)–(1.22); in Section 4, we show that the local strong solution can be extended to be a global one and thus obtain a global strong solution; some necessary regularities used in Section 4 are justified in the appendix section.

Throughout this paper, the constant C denotes a general constant which may be different from line to line.

2. The Regularized System with Full Diffusion

In this section, we prove the local existence of strong solutions to the following modified system

$$\partial_t v + L_1 v + (v \cdot \nabla_H)v - \left(\int_{-h}^z \nabla_H \cdot v(x, y, \xi, t)\, \mathrm{d}\xi\right)\partial_z v$$

$$+ f_0 k \times v + \nabla_H\left(p_s(x, y, t) - \int_{-h}^z T(x, y, \xi, t)\, \mathrm{d}\xi\right) = 0, \quad (2.1)$$

$$\nabla_H \cdot \bar{v} = 0, \quad (2.2)$$

$$\partial_t T + L_2 T - \varepsilon \Delta_H T + v \cdot \nabla_H T$$

$$- \left(\int_{-h}^z \nabla_H \cdot v(x, y, \xi, t)\, \mathrm{d}\xi\right)\left(\partial_z T + \frac{1}{h}\right) = 0, \quad (2.3)$$

complemented with the boundary and initial conditions

$$v \text{ and } T \text{ are periodic in } x, y, z, \quad (2.4)$$

$$v \text{ and } T \text{ are even and odd in } z, \text{ respectively,} \qquad (2.5)$$

$$(v, T)|_{t=0} = (v_0, T_0). \qquad (2.6)$$

Strong solutions to system (2.1)–(2.6) are defined in the similar way as Definition 1.1. We have the following proposition.

Proposition 2.1. *Given $\varepsilon > 0$. Let v_0 and $T_0 \in H^2(\Omega)$ be two periodic functions, such that they are even and odd in z, respectively. Then system (2.1)–(2.6) has a strong solution (v, T) on $\Omega \times (0, t_\varepsilon)$ such that*

$$(v, T) \in L^2(0, t_\varepsilon; H^3(\Omega)), \qquad (\partial_t v, \partial_t T) \in L^2(0, t_\varepsilon; H^1(\Omega)),$$

where $t_\varepsilon > 0$ depends only on $R_1, R_2, R_3, h, \varepsilon$ and the initial data.

We will use the contractive mapping principle to prove this proposition. We first introduce the function spaces and define the mapping. For any given positive number t_0, we define the spaces

$$X_0 = \{\phi \mid \phi \in C([0, t_0]; H^2(M)) \cap L^2(0, t_0; H^3(M)), \phi \text{ is periodic}\},$$
$$X = \{v \mid v \in C([0, t_0]; H^2(\Omega)) \cap L^2(0, t_0; H^3(\Omega)), \nabla_H \cdot \bar{v} = 0,$$
$$\qquad v \text{ is periodic in } x, y, z \text{ and even in } z\},$$
$$Y = \{T \mid T \in C([0, t_0]; H^2(\Omega)) \cap L^2(0, t_0; H^3(\Omega)),$$
$$\qquad T \text{ is periodic in } x, y, z \text{ and odd in } z\},$$

and set $\mathcal{M}_{t_0} = X \times Y$. The norms of these function spaces are defined in the natural way.

For any given $(v, T) \in \mathcal{M}_{t_0}$, define a map $\mathfrak{F} : \mathcal{M}_{t_0} \to \mathcal{M}_{t_0}$ as follows

$$\mathfrak{F}(v, T) = (\mathcal{V}, \mathcal{T}), \quad \mathcal{V} = U + V, \qquad (2.7)$$

where $(U, V, \mathcal{T})$ is the unique solution to

$$\partial_t U - \frac{1}{R_1} \Delta_H U + \nabla_H p = A(v, T), \qquad \text{in } M \times (0, t_0), \qquad (2.8)$$

$$\nabla_H \cdot U = 0, \qquad \text{in } M \times (0, t_0), \qquad (2.9)$$

$$\partial_t V + L_1 V = B(v, T), \qquad \text{in } \Omega \times (0, t_0), \qquad (2.10)$$

$$\partial_t \mathcal{T} - \varepsilon \Delta_H \mathcal{T} + L_2 \mathcal{T} = E(v, T), \qquad \text{in } \Omega \times (0, t_0), \qquad (2.11)$$

with boundary and initial conditions

$$U \text{ is periodic in } x \text{ and } y, \qquad (2.12)$$

$$V \text{ and } \mathcal{T} \text{ are periodic in } x, y, z, \qquad (2.13)$$

$$V \text{ and } \mathcal{T} \text{ are even and odd in } z, \text{ respectively,} \qquad (2.14)$$

$$(U, V, \mathcal{T})|_{t=0} = (\bar{v}_0, \tilde{v}_0, T_0). \qquad (2.15)$$

Here the nonlinear operators $A(v, T)$, $B(v, T)$ and $E(v, T)$ in (2.8)–(2.11) are given by

$$A(v, T) = -(\bar{v} \cdot \nabla_H)\bar{v} - \overline{(\tilde{v} \cdot \nabla_H)\tilde{v} + (\nabla_H \cdot \tilde{v})\tilde{v}} - f_0 k \times \bar{v}$$

$$+\nabla_H \left(\frac{1}{2h} \int_{-h}^{h} \int_{-h}^{z} T(x, y, \xi, t) \, d\xi \, dz \right), \tag{2.16}$$

$$B(v, T) = -(\tilde{v} \cdot \nabla_H)\tilde{v} + \left(\int_{-h}^{z} \nabla_H \cdot \tilde{v}(x, y, \xi, t) \, d\xi \right) \partial_z \tilde{v} - (\tilde{v} \cdot \nabla_H)\bar{v}$$

$$-(\bar{v} \cdot \nabla_H)\tilde{v} + \overline{(\tilde{v} \cdot \nabla_H)\tilde{v} + (\nabla_H \cdot \tilde{v})\tilde{v}} - f_0 k \times \tilde{v}$$

$$+\nabla_H \left(\int_{-h}^{z} T(x, y, \xi, t) \, d\xi - \frac{1}{2h} \int_{-h}^{h} \int_{-h}^{z} T(x, y, \xi, t) \, d\xi \, dz \right), \tag{2.17}$$

$$E(v, T) = -v \cdot \nabla_H T + \left(\int_{-h}^{z} \nabla_H \cdot v(x, y, \xi, t) \, d\xi \right) \left(\partial_z T + \frac{1}{h} \right). \tag{2.18}$$

For any $(v, T) \in \mathcal{M}_{t_0}$, one can check that $A(v, T)$ is periodic in x, y, $B(v, T)$ is periodic in x, y, z and even in z, and $E(v, T)$ is periodic in x, y, z and odd in z. In addition, one has $\overline{B(v, T)} = 0$, and thus by Equation (2.10), $\overline{V}$ satisfies

$$\partial_t \overline{V} - \frac{1}{R_1} \Delta_H \overline{V} = 0, \quad \text{in } M \times (0, t_0).$$

This implies that $\overline{V} \equiv 0$. One can easily check that, for any given $(v, T) \in \mathcal{M}_{t_0}$

$$A(v, T) \in L^2(0, t_0; H^1(M)),$$
$$B(v, T), E(v, T) \in L^2(0, t_0; H^1(\Omega)).$$

By standard L^2 theory of linear Stokes equations and parabolic equations, there is a unique solution $(U, V, \mathcal{T}) \in X_0 \times X \times Y$ to system (2.8)–(2.15), such that

$$\partial_t U \in L^2(0, t_0; H^1(M)), \quad \partial_t V \in L^2(0, t_0; H^1(\Omega)), \quad \partial_t \mathcal{T} \in L^2(0, t_0; H^1(\Omega)).$$

Recalling that $\nabla_H \cdot U = 0$ and $\overline{V} \equiv 0$, it follows that $\nabla_H \cdot \overline{V} = \nabla_H \cdot U + \nabla_H \overline{V} = 0$. Combining these statements, the mapping $\mathfrak{F}$, given by (2.7), is well defined, and it has an extra regularity

$$\partial_t \mathfrak{F}(V, T) \in L^2(0, t_0; H^1(\Omega)). \tag{2.19}$$

One can easily check that

$$A(v, T) + B(v, T) = -(v \cdot \nabla_H)v + \left(\int_{-h}^{z} \nabla_H \cdot v(x, y, \xi, t) \, d\xi \right) \partial_z v$$

$$+\nabla_H \left(\int_{-h}^{z} T(x, y, \xi, t) \, d\xi \right) - f_0 k \times v =: D(v, T),$$

and that

$$\overline{D(v, T)} = A(v, T), \qquad B(v, T) = D(v, T) - \overline{D(v, T)}.$$

As a result, recalling (2.8)–(2.15) and $\overline{V} \equiv 0$, $(\mathcal{V}, \mathcal{T})$ satisfies

$$\partial_t \mathcal{V} + L_1 \mathcal{V} + \nabla_H p(x, y, t) = D(v, T),$$
$$\nabla_H \cdot \overline{\mathcal{V}} = 0,$$
$$\partial_t \mathcal{T} - \varepsilon \Delta_H \mathcal{T} + L_2 \mathcal{T} = E(v, T),$$

subject to the boundary and initial value conditions

> $\mathcal{V}$ and $\mathcal{T}$ are periodic in x, y, z,
> $\mathcal{V}$ and $\mathcal{T}$ are even and odd in z, respectively,
> $(\mathcal{V}, \mathcal{T})|_{t=0} = (v_0, T_0)$.

Therefore, to find a strong solution to system (2.1)–(2.6), it suffices to find a fixed point of the mapping $\mathfrak{F}$ in $\mathcal{M}_{t_0}$.

Before continuing our arguments, let's state and prove the following lemma on differentiation under the integral sign and integration by parts.

Lemma 2.1. *Let f and g be two spatial periodic functions such that*

$$f \in L^2(0, t_0; H^3(\Omega)), \quad \partial_t f \in L^2(0, t_0; H^1(\Omega)),$$
$$g \in L^2(0, t_0; H^2(\Omega)), \quad \partial_t g \in L^2(0, t_0; L^2(\Omega)).$$

Then it follows that

$$\frac{\mathrm{d}}{\mathrm{d}t} \int_\Omega |\Delta f|^2 \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z = -2 \int_\Omega \nabla \partial_t f \cdot \nabla \Delta f \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z,$$
$$\int_\Omega \nabla \partial_{x^i}^2 f \cdot \nabla \Delta f \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z = \int_\Omega |\partial_{x^i} \Delta f|^2 \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z$$

and

$$\frac{\mathrm{d}}{\mathrm{d}t} \int_\Omega |\partial_{x^i} g|^2 \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z = -2 \int_\Omega \partial_t g \partial_{x^i}^2 g \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z,$$
$$\int_\Omega \partial_{x^i}^2 g \partial_{x^j}^2 g \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z = \int_\Omega |\partial_{x^i} \partial_{x^j} g|^2 \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z$$

for almost all $t \in (0, t_0)$, where $x^i, x^j \in \{x, y, z\}$.

Proof. The idea of the proof follows lines similar to the proof of a lemma of Lions (see, for example, Lemma 1.2 in page 260 of TEMAM [22]). We only prove the identities concerning f, those for g can be done in the same way. By standard regularization, one can easily show that there is a sequence of smooth functions $\{f_n\}$, such that f_n is periodic in space variables and

$$f_n \to f \quad \text{in } L^2(0, t_0; H^3(\Omega)), \qquad \partial_t f_n \to \partial_t f \quad \text{in } L^2(0, t_0; L^2(\Omega)).$$

Take arbitrary function $\varphi(t) \in C_0^\infty((0, t_0))$. It is obvious that

$$\int_0^{t_0} \varphi'(t) \left(\int_\Omega |\Delta f|^2 \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z \right) \mathrm{d}t$$
$$= \lim_{n \to \infty} \int_0^{t_0} \varphi'(t) \left(\int_\Omega |\Delta f_n|^2 \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z \right) \mathrm{d}t$$
$$= -2 \lim_{n \to \infty} \int_0^{t_0} \varphi(t) \left(\int_\Omega \Delta f_n \Delta \partial_t f_n \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z \right) \mathrm{d}t$$

$$= 2 \lim_{n \to \infty} \int_0^{t_0} \varphi(t) \left(\int_\Omega \nabla \partial_t f_n \nabla \Delta f_n \, dx \, dy \, dz \right) dt$$

$$= 2 \int_0^{t_0} \varphi(t) \left(\int_\Omega \nabla \partial_t f \nabla \Delta f \, dx \, dy \, dz \right) dt,$$

and

$$\int_0^{t_0} \varphi(t) \left(\int_\Omega \nabla \partial_{x^i}^2 f \nabla \Delta f \, dx \, dy \, dz \right) dt$$

$$= \lim_{n \to \infty} \int_0^{t_0} \varphi(t) \left(\int_\Omega \nabla \partial_{x^i}^2 f_n \nabla \Delta f_n \, dx \, dy \, dz \right) dt$$

$$= \lim_{n \to \infty} \int_0^{t_0} \varphi(t) \left(\int_\Omega |\partial_{x^i} \Delta f_n|^2 \, dx \, dy \, dz \right) dt$$

$$= \int_0^{t_0} \varphi(t) \left(\int_\Omega |\partial_{x^i} \Delta f|^2 \, dx \, dy \, dz \right) dt.$$

These identities imply the conclusion. □

Proposition 2.2. *Given arbitrary positive number K and time t_0, such that $K \geqq 1$ and $0 < t_0 \leqq 1$, and set $\mathbb{B}_K = \{(v, T) \in \mathcal{M}_{t_0} \big| \|(v, T)\|_{\mathcal{M}_{t_0}} \leqq K\}$. Then for any $(v_1, T_1), (v_2, T_2) \in \mathbb{B}_K$, we have*

$$\|\mathfrak{F}(v_1, T_1) - \mathfrak{F}(v_2, T_2)\|_{\mathcal{M}_{t_0}} \leqq C_\varepsilon K t_0^{1/4} \|(v_1 - v_2, T_1 - T_2)\|_{\mathcal{M}_{t_0}},$$

where C_ε is a constant depending only on R_1, R_2, R_3, h and ε.

Proof. It follows from the Hölder and the Sobolev embedding inequalities that

$$\int_\Omega (|D(v_1, T_1) - D(v_2, T_2)|^2 + |\nabla(D(v_1, T_1) - D(v_2, T_2))|^2) \, dx \, dy \, dz$$

$$\leqq C \int_\Omega \bigg[|v_1|^2 |\nabla(v_1 - v_2)|^2 + |v_1 - v_2|^2 |\nabla v_2|^2 + |v_1|^2 |\nabla^2(v_1 - v_2)|^2$$

$$+ |v_1 - v_2|^2 |\nabla^2 v_2|^2 + |\nabla(v_1 - v_2)|^2 (|\nabla v_1|^2 + |\nabla v_2|^2)$$

$$+ \left(\int_{-h}^h |\nabla(T_1 - T_2)| \, d\xi \right)^2 + \left(\int_{-h}^h |\nabla^2(T_1 - T_2)| \, d\xi \right)^2$$

$$+ \left(\int_{-h}^h |\nabla v_1| \, d\xi \right)^2 |\nabla(v_1 - v_2)|^2 + \left(\int_{-h}^h |\nabla(v_1 - v_2)| \, d\xi \right)^2 |\nabla v_2|^2$$

$$+ \left(\int_{-h}^h |\nabla v_1| \, d\xi \right)^2 |\nabla^2(v_1 - v_2)|^2 + \left(\int_{-h}^h |\nabla(v_1 - v_2)| \, d\xi \right)^2 |\nabla^2 v_2|^2$$

$$+ \left(\int_{-h}^h |\nabla^2 v_1| \, d\xi \right)^2 |\nabla(v_1 - v_2)|^2 + \left(\int_{-h}^h |\nabla^2(v_1 - v_2)| \, d\xi \right)^2 |\nabla v_2|^2 \bigg] \, dx \, dy \, dz$$

$$\leqq C[\|v_1\|_\infty \|\nabla(v_1 - v_2)\|_2^2 + \|v_1 - v_2\|_\infty^2 \|\nabla v_2\|_2^2 + \|v_1\|_\infty^2 \|\nabla^2(v_1 - v_2)\|_2^2$$

$$+ \|v_1 - v_2\|_\infty^2 \|\nabla^2 v_2\|_2^2 + \|\nabla(v_1 - v_2)\|_4^2 (\|\nabla v_1\|_4 + \|\nabla v_2\|_4^2) + \|\nabla(T_1 - T_2)\|_{H^1}^2$$

$$+ \|\nabla v_1\|_6^2 \|\nabla(v_1 - v_2)\|_2 \|\nabla(v_1 - v_2)\|_6 + \|\nabla(v_1 - v_2)\|_6^2 \|\nabla v_2\|_2 \|\nabla v_2\|_6$$

$$+ \|\nabla v_1\|_6^2 \|\nabla^2(v_1 - v_2)\|_2 \|\nabla^2(v_1 - v_2)\|_6 + \|\nabla(v_1 - v_2)\|_6^2 \|\nabla^2 v_2\|_2 \|\nabla^2 v_2\|_6$$

$$+\|\nabla^2 v_1\|_2\|\nabla^2 v_1\|_6\|\nabla(v_1 - v_2)\|_6^2 + \|\nabla^2(v_1 - v_2)\|_2\|\nabla^2(v_1 - v_2)\|_6\|\nabla v_2\|_6^2$$

$$\leqq C[(\|v_1\|_{H^2}^2 + \|v_2\|_{H^2}^2)\|v_1 - v_2\|_{H^2}^2 + \|v_1\|_{H^2}^2\|v_1 - v_2\|_{H^2}\|v_1 - v_2\|_{H^3}$$

$$+\|v_2\|_{H^2}\|v_2\|_{H^3}\|v_1 - v_2\|_{H^2}^2 + \|v_1\|_{H^2}\|v_1\|_{H^3}\|v_1 - v_2\|_{H^2}^2$$

$$+\|v_2\|_{H^2}^2\|v_1 - v_2\|_{H^2}\|v_1 - v_2\|_{H^3} + \|T_1 - T_2\|_{H^2}^2]$$

$$\leqq C[(\|v_1\|_{H^2}^2 + \|v_2\|_{H^2}^2)\|v_1 - v_2\|_{H^2}\|v_1 - v_2\|_{H^3} + \|T_1 - T_2\|_{H^2}^2$$

$$+(\|v_1\|_{H^2}\|v_1\|_{H^3} + \|v_2\|_{H^2}\|v_2\|_{H^3})\|v_1 - v_2\|_{H^2}^2] \tag{2.20}$$

and

$$\int_\Omega (|C(v_1, T_1) - C(v_2, T_2)|^2 + |\nabla(C(v_1, T_1) - C(v_2, T_2))|^2)\, dx\, dy\, dz$$

$$\leqq C\int_\Omega \left[|v_1|^2|\nabla(T_1 - T_2)|^2 + |v_1 - v_2|^2|\nabla T_2|^2 + |\nabla v_1|^2|\nabla(T_1 - T_2)|^2 \right.$$

$$+|\nabla(v_1 - v_2)|^2|\nabla T_2|^2 + |v_1|^2|\nabla^2(T_1 - T_2)|^2 + |v_1 - v_2|^2|\nabla^2 T_2|^2$$

$$+\left(\int_{-h}^h |\nabla v_1|\, d\xi\right)^2 |\nabla(T_1 - T_2)|^2 + \left(\int_{-h}^h |\nabla(v_1 - v_2)|\, d\xi\right)^2 (|\nabla T_2|^2 + 1)$$

$$+\left(\int_{-h}^h |\nabla^2 v_1|\, d\xi\right)^2 |\nabla(T_1 - T_2)|^2 + \left(\int_{-h}^h |\nabla^2(v_1 - v_2)|\, d\xi\right)^2 (|\nabla T_2|^2 + 1)$$

$$+\left.\left(\int_{-h}^h |\nabla v_1|\, d\xi\right)^2 |\nabla^2(T_1 - T_2)|^2 + \left(\int_{-h}^h |\nabla(v_1 - v_2)|\, d\xi\right)^2 |\nabla^2 T_2|^2 \right] dx\, dy\, dz$$

$$\leqq C\left[\|v_1\|_\infty\|\nabla(T_1 - T_2)\|_2^2 + \|v_1 - v_2\|_\infty^2\|\nabla T_2\|_2^2 + \|\nabla v_1\|_4^2\|\nabla(T_1 - T_2)\|_4^2 \right.$$

$$+\|\nabla(v_1 - v_2)\|_4^2\|\nabla T_2\|_4^2 + \|v_1\|_\infty^2\|\nabla^2(T_1 - T_2)\|_2^2 + \|v_1 - v_2\|_\infty^2\|\nabla^2 T_2\|_2^2$$

$$+\|\nabla v_1\|_4^2\|\nabla(T_1 - T_2)\|_4^2 + \|\nabla(v_1 - v_2)\|_4^2\|\nabla T_2\|_4^2 + \|\nabla(v_1 - v_2)\|_2^2$$

$$+\|\nabla^2 v_1\|_2\|\nabla^2 v_1\|_6\|\nabla(T_1 - T_2)\|_6^2 + \|\nabla^2(v_1 - v_2)\|_2^2$$

$$+\|\nabla^2(v_1 - v_2)\|_2\|\nabla^2(v_1 - v_2)\|_6\|\nabla T_2\|_6^2 + \|\nabla(v_1 - v_2)\|_6^2\|\nabla^2 T_2\|_2\|\nabla^2 T_2\|_6$$

$$+\left.\|\nabla v_1\|_6^2\|\nabla^2(T_1 - T_2)\|_2\|\nabla^2(T_1 - T_2)\|_6\right]$$

$$\leqq C(\|v_1\|_{H^2}^2\|T_1 - T_2\|_{H^2}^2 + \|v_1 - v_2\|_{H^2}^2\|T_2\|_{H^2}^2 + \|v_1 - v_2\|_{H^2}^2$$

$$+\|v_1\|_{H^2}\|v_1\|_{H^3}\|T_1 - T_2\|_{H^2}^2 + \|v_1 - v_2\|_{H^2}\|v_1 - v_2\|_{H^3}\|T_2\|_{H^2}^2$$

$$+\|v_1 - v_2\|_{H^2}^2\|T_2\|_{H^2}\|T_2\|_{H^3} + \|v_1\|_{H^2}^2\|T_1 - T_2\|_{H^2}\|T_1 - T_2\|_{H^3})$$

$$\leqq C[(\|v_1\|_{H^2}^2 + \|T_2\|_{H^2}^2)(\|v_1 - v_2\|_{H^2}\|v_1 - v_2\|_{H^3} + \|T_1 - T_2\|_{H^2}\|T_1 - T_2\|_{H^3})$$

$$+(\|v_1\|_{H^2}\|v_1\|_{H^3} + \|T_2\|_{H^2}\|T_2\|_{H^3} + 1)(\|v_1 - v_2\|_{H^2}^2 + \|T_1 - T_2\|_{H^2}^2). \tag{2.21}$$

Setting $v = v_1 - v_2$ and $T = T_1 - T_2$, then it follows from (2.20) and (2.21) that

$$I(t) = \int_\Omega (|D(v_1, T_1) - D(v_2, T_2)|^2 + |\nabla(D(v_1, T_1) - D(v_2, T_2))|^2)\, dx\, dy\, dz$$

$$+ \int_\Omega (|C(v_1, T_1) - C(v_2, T_2)|^2 + |\nabla(C(v_1, T_1) - C(v_2, T_2))|^2)\, dx\, dy\, dz$$

$$\leqq C(\|v_1\|_{H^2}\|v_1\|_{H^3} + \|v_2\|_{H^2}\|v_2\|_{H^3} + \|T_2\|_{H^2}\|T_2\|_{H^3} + 1)(\|v\|_{H^2}^2 + \|T\|_{H^2}^2)$$

$$+C(\|v_1\|_{H^2}^2 + \|v_2\|_{H^2}^2 + \|T_2\|_{H^2}^2)(\|T\|_{H^2}\|T\|_{H^3} + \|v\|_{H^2}\|v\|_{H^3}).$$

Thus, for any $(v_1, T_1), (v_2, T_2) \in \mathbb{B}_K$, it holds that

$$
\begin{aligned}
\int_0^{t_0} I(t) \, \mathrm{d}t &\leqq CK\|(v, T)\|_{\mathcal{M}_{t_0}}^2 \int_0^{t_0} (\|v_1\|_{H^3} + \|v_2\|_{H^3} + \|T_2\|_{H^3} + 1) \, \mathrm{d}t \\
&\quad + CK^2\|(v, T)\|_{\mathcal{M}_{t_0}} \int_0^{t_0} (\|T\|_{H^3} + \|v\|_{H^3}) \, \mathrm{d}t \\
&\leqq CK\|(v, T)\|_{\mathcal{M}_{t_0}}^2 t_0^{1/2} \left[\int_0^{t_0} (\|v_1\|_{H^3}^2 + \|v_2\|_{H^3}^2 + \|T_2\|_{H^3}^2 + 1) \, \mathrm{d}t \right]^{1/2} \\
&\quad + CK^2\|(v, T)\|_{\mathcal{M}_{t_0}} t_0^{1/2} \left[\int_0^{t_0} (\|T\|_{H^3}^2 + \|v\|_{H^3}^2) \, \mathrm{d}t \right]^{1/2} \\
&\leqq CK^2 t_0^{1/2} \|(v, T)\|_{\mathcal{M}_{t_0}}^2.
\end{aligned}
\tag{2.22}
$$

Setting $\mathcal{V} = \mathcal{V}_1 - \mathcal{V}_2$ and $\mathcal{T} = \mathcal{T}_1 - \mathcal{T}_2$, then $(\mathcal{V}, \mathcal{T})$ satisfies

$$
\begin{aligned}
\partial_t \mathcal{V} + L_1 \mathcal{V} + \nabla_H p(x, y, t) &= D(v_1, T_1) - D(v_2, T_2), \tag{2.23} \\
\nabla_H \cdot \overline{\mathcal{V}} &= 0, \tag{2.24} \\
\partial_t \mathcal{T} - \varepsilon \Delta_H \mathcal{T} + L_2 \mathcal{T} &= C(v_1, T_1) - C(v_2, T_2) \tag{2.25}
\end{aligned}
$$

and boundary and initial conditions

$$
\begin{aligned}
&\mathcal{V} \text{ and } \mathcal{T} \text{ are periodic in } x, y, z, \\
&\mathcal{V} \text{ and } \mathcal{T} \text{ are even and odd in } z, \text{ respectively,} \\
&(\mathcal{V}, \mathcal{T})|_{t=0} = (0, 0).
\end{aligned}
$$

Recalling (2.19), it is obvious that $\partial_t \mathcal{V}, \partial_t \mathcal{T} \in L^2(0, t_0; H^1(\Omega))$. Multiplying (2.23) and (2.25) by $\mathcal{V}$ and $\mathcal{T}$, respectively, and summing the resulting equations up, then it follows from integrating by parts that

$$
\begin{aligned}
&\frac{1}{2} \frac{\mathrm{d}}{\mathrm{d}t} \int_\Omega (|\mathcal{V}|^2 + |\mathcal{T}|^2) \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z \\
&\quad + \int_\Omega \left(\frac{1}{R_1} |\nabla_H \mathcal{V}|^2 + \frac{1}{R_2} |\partial_z \mathcal{V}|^2 + \varepsilon |\nabla_H \mathcal{T}|^2 + \frac{1}{R_3} |\partial_z \mathcal{T}|^2 \right) \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z \\
&\quad = \int_\Omega [(D(v_1, T_1) - D(v_2, T_2))\mathcal{V} + (C(v_1, T_1) - C(v_2, T_2))\mathcal{T}] \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z.
\end{aligned}
\tag{2.26}
$$

Applying the operator ∇ to equations (2.23), (2.25) and multiplying the resulting equations by $-\nabla \Delta \mathcal{V}$ and $-\nabla \Delta \mathcal{T}$, respectively, and summing these equations up, then it follows from Lemma 2.1 that

$$\frac{1}{2}\frac{d}{dt}\int_{\Omega}(|\Delta\mathcal{V}|^2 + |\Delta\mathcal{T}|^2)\,dx\,dy\,dz$$

$$+\int_{\Omega}\left(\frac{1}{R_1}|\nabla_H\Delta\mathcal{V}|^2 + \frac{1}{R_2}|\partial_z\Delta\mathcal{V}|^2 + \varepsilon|\nabla_H\Delta\mathcal{T}|^2 + \frac{1}{R_3}|\partial_z\Delta\mathcal{T}|^2\right)dx\,dy\,dz$$

$$=-\int_{\Omega}[\nabla(D(v_1,T_1) - D(v_2,T_2))\nabla\Delta\mathcal{V}$$

$$+\nabla(C(v_1,T_1) - C(v_2,T_2))\nabla\Delta\mathcal{T}]\,dx\,dy\,dz.$$

Summing this equation with (2.26) up, and using the Cauchy–Schwarz inequality, one obtains

$$\frac{1}{2}\frac{d}{dt}\int_{\Omega}(|\mathcal{V}|^2 + |\Delta\mathcal{V}|^2 + |\mathcal{T}|^2 + |\Delta\mathcal{T}|^2)\,dx\,du\,dz$$

$$+\int_{\Omega}\left[\frac{1}{R_1}(|\nabla_H\mathcal{V}|^2 + |\nabla_H\Delta\mathcal{V}|^2) + \frac{1}{R_2}(|\partial_z\mathcal{V}|^2 + |\partial_z\Delta\mathcal{V}|^2)\right.$$

$$\left.+\varepsilon(|\nabla_H\mathcal{T}|^2 + |\nabla_H\Delta\mathcal{T}|^2) + \frac{1}{R_3}(|\partial_z\mathcal{T}|^2 + |\partial_z\Delta\mathcal{T}|^2)\right]dx\,dy\,dz$$

$$=\int_{\Omega}\Big[(D(v_1,T_1) - D(v_2,T_2))\mathcal{V} - \nabla(D(v_1,T_1) - D(v_2,T_2))\nabla\Delta\mathcal{V}$$

$$+(C(v_1,T_1) - C(v_2,T_2))\mathcal{T} - \nabla(C(v_1,T_1) - C(v_2,T_2))\nabla\Delta\mathcal{T}\Big]\,dx\,dy\,dz$$

$$\leqq \sigma\int_{\Omega}(|\mathcal{V}|^2 + |\nabla\Delta\mathcal{V}|^2 + |\mathcal{T}|^2 + |\nabla\Delta\mathcal{T}|^2)\,dx\,dy\,dz$$

$$+C\int_{\Omega}(|D(v_1,T_1) - D(v_2,T_2)|^2 + |\nabla(D(v_1,T_1) - D(v_2,T_2))|^2)\,dx\,dy\,dz$$

$$+C\int_{\Omega}(|C(v_1,T_1) - C(v_2,T_2)|^2 + |\nabla(C(v_1,T_1) - C(v_2,T_2))|^2)\,dx\,dy\,dz$$

$$\leqq \gamma\int_{\Omega}(|\mathcal{V}|^2 + |\nabla\Delta\mathcal{V}|^2 + |\mathcal{T}|^2 + |\nabla\Delta\mathcal{T}|^2)\,dx\,dy\,dz + CI(t),$$

where $\gamma = \min\left\{\frac{1}{4R_1}, \frac{1}{4R_2}\right\}$. On account of (2.22), it follows from the above inequality that

$$\sup_{0\leqq t\leqq t_0}(\|\mathcal{V}\|_{H^2}^2 + \|\mathcal{T}\|_{H^2}^2) + \int_0^{t_0}(\|\nabla\mathcal{V}\|_{H^2}^2 + \|\nabla\mathcal{T}\|_{H^2}^2)\,dt$$

$$\leqq C\int_0^{t_0} I(t)\,dt \leqq CK^2 t_0^{1/2}\|(v,T)\|_{\mathcal{M}_{t_0}}^2,$$

which gives

$$\|\mathfrak{F}(v_1,T_1) - \mathfrak{F}(v_2,T_2)\|_{\mathcal{M}_{t_0}}^2 \leqq CK^2 t_0^{1/2}\|(v,T)\|_{\mathcal{M}_{t_0}}^2,$$

proving the conclusion. □

Proposition 2.3. *There is a positive constant K_0 depending only on R_1, R_2, R_3, h, ε and (v_0, T_0), such that*

$$\|\mathfrak{F}(v,T)\|_{\mathcal{M}_{t_\varepsilon}} \leqq 2K_0,$$

for any (v, T) with $\|(v, T)\|_{\mathcal{M}_{t_\varepsilon}} \leqq 2K_0$, where $t_\varepsilon = \min\left\{(4C_\varepsilon K_0)^{-4}, 1\right\}$ and C_ε is the same constant as in Proposition 2.2.

Proof. Recalling the definition of $\mathfrak{F}$, the L^2 theory of Stokes equations and linear parabolic equations provide that there is a constant $K_0 \geqq 1$, depending only on $R_1, R_2, R_3, h, \varepsilon$ and (v_0, T_0), such that for any $0 < t_0 \leqq 1$, one has

$$\|\mathfrak{F}(0, 0)\|_{\mathcal{M}_{t_0}} \leqq K_0.$$

By the aid of this estimate, applying Proposition 2.2, for any (v, T), with $\|(v, T)\|_{\mathcal{M}_{t_\varepsilon}}$ $\leqq 2K_0$, it holds that

$$\begin{aligned}
\|\mathfrak{F}(v, T)\|_{\mathcal{M}_{t_\varepsilon}} &\leqq \|\mathfrak{F}(0, 0)\|_{\mathcal{M}_{t_\varepsilon}} + \|\mathfrak{F}(v, T) - \mathfrak{F}(0, 0)\|_{\mathcal{M}_{t_\varepsilon}} \\
&\leqq K_0 + 2C_\varepsilon K_0 t_\varepsilon^{1/4}\|(v, T)\|_{M_{t_\varepsilon}} \\
&\leqq K_0 + 4C_\varepsilon K_0^2 t_\varepsilon^{1/4} \leqq 2K_0,
\end{aligned}$$

provided $t_\varepsilon \leqq \min\left\{(4C_\varepsilon K_0)^{-4}, 1\right\}$. This completes the proof. □

Now we are rea dy to give the proof of Proposition 2.1.

Proof of Proposition 2.1. Let K_0 be the constant stated in Proposition 2.3. By Lemma 2.2 and Proposition 2.3, the mapping defined by (2.7) satisfies

$$\mathfrak{F} : \mathbb{B}_{2K_0} \to \mathbb{B}_{2K_0},$$

$$\|\mathfrak{F}(v_1, T_1) - \mathfrak{F}(v_2, T_2)\|_{\mathcal{M}_{t_\varepsilon}} \leqq \frac{1}{2}\|(v_1 - v_2, T_1 - T_2)\|_{\mathcal{M}_{t_\varepsilon}},$$

for any $(v_1, T_1), (v_2, T_2) \in \mathbb{B}_{2K_0}$, where

$$t_\varepsilon = \min\{(4C_\varepsilon K_0)^{-4}, 1\}, \quad \mathbb{B}_{2K_0} = \{(v, T)|\|(v, T)\|_{\mathcal{M}_{t_\varepsilon}} \leqq 2K_0\}.$$

By the contraction mapping principle, there is a unique fixed point (v, T) for $\mathfrak{F}$ in $\mathbb{B}_{2K_0}$. This fixed point of $\mathfrak{F}$ is a strong solution to system (2.1)–(2.6). The regularities $\partial_t v, \partial_t T \in L^2(0, t_\varepsilon; H^1(\Omega))$ follow from (2.19), completing the proof of Proposition 2.1. □

3. The System with Only Vertical Diffusion

In this section, we prove the local existence and uniqueness of strong solutions to system (1.16)–(1.22), or equivalently system (1.23)–(1.28). The existence is obtained by taking the limit $\varepsilon \to 0$ of the solutions $(v_\varepsilon, T_\varepsilon)$ to system (2.1)–(2.6).

We first establish the uniform in ε lower bounds of the existence times and the estimates on $(v_\varepsilon, T_\varepsilon)$. In fact, we have the following:

Proposition 3.1. *There is a positive constant K_0 and a positive time t_0^*, depending only on R_1, R_2, R_3, h and (v_0, T_0), such that system (2.1)–(2.6) has a solution $(v_\varepsilon, T_\varepsilon)$ in $\Omega \times (0, t_0^*)$ with*

$$\sup_{0 \leqq t \leqq t_0^*} (\|v_\varepsilon\|_{H^2}^2 + \|T_\varepsilon\|_{H^2}^2) + \int_0^{t_0^*} (\varepsilon\|\nabla_H T_\varepsilon\|_{H^2}^2 + \|\partial_z T_\varepsilon\|_{H^2}^2 + \|\nabla v_\varepsilon\|_{H^2}^2) \, \mathrm{d}t \leqq K$$

and

$$\int_0^{t_0^*} (\|\partial_t v_\varepsilon\|_{H^1}^2 + \|\partial_t T_\varepsilon\|_{H^1}^2) \, dt \leqq K,$$

where K is a positive constant depending only on R_1, R_2, R_3, h and (v_0, T_0).

Proof. Let t_ε^* be the maximal existence time of strong solution $(v_\varepsilon, T_\varepsilon)$ to system (2.1)–(2.6). Multiplying (2.1) by v_ε and integrating over Ω yields

$$\frac{1}{2} \frac{d}{dt} \int_\Omega |v_\varepsilon|^2 \, dx \, dy \, dz + \int_\Omega \left(\frac{1}{R_1} |\nabla_H v_\varepsilon|^2 + \frac{1}{R_2} |\partial_z v_\varepsilon|^2 \right) dx \, dy \, dz$$
$$= \int_\Omega \nabla_H \left(\int_{-h}^z T_\varepsilon \, d\xi \right) v_\varepsilon \, dx \, dy \, dz.$$

Applying the operator ∇ to (2.1), multiplying the resulting equation by $-\nabla \Delta v_\varepsilon$, summing them up and integrating over Ω, then it follows from Lemma 2.1 (recall the regularities of $(v_\varepsilon, T_\varepsilon)$) that

$$\frac{1}{2} \frac{d}{dt} \int_\Omega |\Delta v_\varepsilon|^2 \, dx \, dy \, dz + \int_\Omega \left(\frac{1}{R_1} |\nabla_H \Delta v_\varepsilon|^2 + \frac{1}{R_2} |\partial_z \Delta v_\varepsilon|^2 \right) dx \, dy \, dz$$
$$= \int_\Omega \nabla \left[(v_\varepsilon \cdot \nabla_H) v_\varepsilon - \left(\int_{-h}^z \nabla_H \cdot v_\varepsilon \, d\xi \right) \partial_z v_\varepsilon - \left(\int_{-h}^z \nabla_H T_\varepsilon \, d\xi \right) \right]$$
$$\times \nabla \Delta v_\varepsilon \, dx \, dy \, dz.$$

Summing the above equation with the previous one up, and using the Hölder, Sobolev, Poincaré and Cauchy inequalities, we have

$$\frac{1}{2} \frac{d}{dt} \int_\Omega (|v_\varepsilon|^2 + |\Delta v_\varepsilon|^2) \, dx \, dy \, dz$$
$$+ \int_\Omega \left[\frac{1}{R_1} (|\nabla_H v_\varepsilon|^2 + |\nabla_H \Delta v_\varepsilon|^2) + \frac{1}{R_2} (|\partial_z v_\varepsilon|^2 + |\partial_z \Delta v_\varepsilon|^2) \right] dx \, dy \, dz$$
$$= \int_\Omega \left\{ \nabla_H \left(\int_{-h}^z T_\varepsilon \, d\xi \right) v_\varepsilon + \nabla \left[(v_\varepsilon \cdot \nabla_H) v_\varepsilon - \left(\int_{-h}^z \nabla_H \cdot v_\varepsilon \, d\xi \right) \partial_z v_\varepsilon \right. \right.$$
$$\left. \left. - \left(\int_{-h}^z \nabla_H T_\varepsilon(x, y, \xi, t) \, d\xi \right) \right] \nabla \Delta v_\varepsilon \right\} dx \, dy \, dz$$
$$\leqq C \|\nabla T_\varepsilon\|_2 \|v_\varepsilon\|_2 + C \int_\Omega \left[|v_\varepsilon| |\nabla^2 v_\varepsilon| + |\nabla v_\varepsilon|^2 + \left(\int_{-h}^h |\nabla^2 v_\varepsilon| \, d\xi \right) |\partial_z v_\varepsilon| \right.$$
$$\left. + \left(\int_{-h}^h |\nabla v_\varepsilon| \, d\xi \right) |\nabla^2 v_\varepsilon| + \left(\int_{-h}^h |\nabla^2 T_\varepsilon| \, d\xi \right) \right] |\nabla \Delta v_\varepsilon| \, dx \, dy \, dz$$
$$\leqq \sigma \int_\Omega |\nabla \Delta v_\varepsilon|^2 \, dx \, dy \, dz + C \|\nabla T_\varepsilon\|_2 \|v_\varepsilon\|_2 + C \int_\Omega \left[|v_\varepsilon|^2 |\nabla^2 v_\varepsilon|^2 + |\nabla v_\varepsilon|^4 \right.$$
$$\left. + \left(\int_{-h}^h |\nabla^2 v_\varepsilon| \, dz \right)^2 |\partial_z v_\varepsilon|^2 + \left(\int_{-h}^h |\nabla v_\varepsilon| \, dz \right)^2 |\nabla^2 v_\varepsilon|^2 + \left(\int_{-h}^h |\nabla^2 T_\varepsilon| \, dz \right)^2 \right] dx \, dy \, dz$$
$$\leqq \sigma \int_\Omega |\nabla \Delta v_\varepsilon|^2 \, dx \, dy \, dz + C \|\nabla T_\varepsilon\|_2 \|v_\varepsilon\|_2 + C(\|v_\varepsilon\|_6^2 \|\nabla^2 v_\varepsilon\|_2 \|\nabla^2 v_\varepsilon\|_6$$
$$+ \|\nabla v_\varepsilon\|_4^4 + \|\nabla^2 v_\varepsilon\|_2 \|\nabla^2 v_\varepsilon\|_6 \|\partial_z v_\varepsilon\|_6^2 + \|\nabla v_\varepsilon\|_6^2 \|\nabla^2 v_\varepsilon\|_2 \|\nabla^2 v_\varepsilon\|_6 + \|\nabla^2 T_\varepsilon\|_2^2)$$

$$\leqq \sigma \int_\Omega |\nabla \Delta v_\varepsilon|^2 \, dx \, dy \, dz + C \|\nabla T_\varepsilon\|_2 \|v_\varepsilon\|_2 + C(\|v_\varepsilon\|_{H^1}^2 \|\nabla^2 v_\varepsilon\|_2 \|\nabla \Delta v_\varepsilon\|_2$$
$$+ \|v_\varepsilon\|_{H^2}^4 + \|v_\varepsilon\|_{H^2}^3 \|\nabla \Delta v_\varepsilon\|_2 + \|\nabla^2 T_\varepsilon\|_2^2)$$
$$\leqq 2\sigma \int_\Omega |\nabla \Delta v_\varepsilon|^2 \, dx \, dy \, dz + C(1 + \|v_\varepsilon\|_{H^2}^6 + \|T_\varepsilon\|_{H^2}^6), \tag{3.1}$$

with $\sigma = \min \left\{ \frac{1}{4R_1}, \frac{1}{4R_2} \right\}$, and thus we have

$$\sup_{0 \leqq s \leqq t} \|v_\varepsilon\|_{H^2}^2 + \int_0^t \|\nabla v_\varepsilon\|_{H^2}^2 \, ds$$
$$\leqq C\|v_0\|_{H^2}^2 + C \int_0^t (1 + \|T_\varepsilon\|_{H^2}^2 + \|v_\varepsilon\|_{H^2}^2)^3 \, ds \tag{3.2}$$

for any $0 \leqq t < t_\varepsilon^*$.

Multiplying Equation (2.2) by T_ε, then it follows from integrating by parts that

$$\frac{1}{2} \frac{d}{dt} \int_\Omega |T_\varepsilon|^2 \, dx \, dy \, dz + \int_\Omega \left(\varepsilon |\nabla_H T_\varepsilon|^2 + \frac{1}{R_3} |\partial_z T_\varepsilon|^2 \right) \, dx \, dy \, dz$$
$$= \frac{1}{h} \int_\Omega \left(\int_{-h}^z \nabla_H \cdot v_\varepsilon \, d\xi \right) T_\varepsilon \, dx \, dy \, dz \leqq C\|T_\varepsilon\|_2 \|\nabla v_\varepsilon\|_2. \tag{3.3}$$

Recalling the Gagliado–Nirenberg inequality of the form

$$\|f\|_\infty \leqq C \|f\|_6^{1/2} \|f\|_{H^2}^{1/2}, \qquad \forall f \in H^2(\Omega), \Omega \subseteq \mathbb{R}^3,$$

it follows from the Hölder, Sobolev and Poincaré inequalities that

$$\|\partial_z T_\varepsilon\|_\infty \leqq C \|\partial_z T_\varepsilon\|_6^{1/2} (\|\nabla^2 \partial_z T_\varepsilon\|_2^{1/2} + \|\partial_z T_\varepsilon\|_2^{1/2})$$
$$\leqq C \|\Delta T_\varepsilon\|_2^{1/2} (\|\Delta \partial_z T_\varepsilon\|_2^{1/2} + \|\partial_z T_\varepsilon\|_2^{1/2}) \tag{3.4}$$

and

$$\|\nabla v_\varepsilon\|_\infty \leqq C \|\nabla v_\varepsilon\|_6^{1/2} (\|\nabla^3 v_\varepsilon\|_2^{1/2} + \|\nabla v_\varepsilon\|_2^{1/2})$$
$$\leqq C \|\nabla^2 v_\varepsilon\|_2^{1/2} \|\nabla^3 v_\varepsilon\|_2^{1/2} = C \|\Delta v_\varepsilon\|_2^{1/2} \|\nabla \Delta v_\varepsilon\|_2^{1/2}. \tag{3.5}$$

Applying the operator ∇ to Equation (2.3) and multiplying the resulting equation by $-\nabla \Delta T_\varepsilon$ and integrating over Ω, then it follows from Lemma 2.1 (recall the regularities of $(v_\varepsilon, T_\varepsilon)$), (3.4), (3.5), the Hölder, Soblolev, Poincaré and Cauchy–Schwarz inequalities that

$$\frac{1}{2} \frac{d}{dt} \int_\Omega |\Delta T_\varepsilon|^2 \, dx \, dy \, dz + \int_\Omega \left(\varepsilon |\nabla_H \Delta T_\varepsilon|^2 + \frac{1}{R_3} |\partial_z \Delta T_\varepsilon|^2 \right) \, dx \, dy \, dz$$
$$= \int_\Omega \Delta \left[\left(\int_{-h}^z \nabla_H \cdot v_\varepsilon \, d\xi \right) \left(\partial_z T_\varepsilon + \frac{1}{h} \right) - (v_\varepsilon \cdot \nabla_H) T_\varepsilon \right] \Delta T_\varepsilon \, dx \, dy \, dz$$
$$= \int_\Omega \left[\left(\int_{-h}^z \Delta \nabla_H \cdot v_\varepsilon \, d\xi \right) \left(\partial_z T_\varepsilon + \frac{1}{h} \right) + 2 \left(\int_{-h}^z \nabla \nabla_H \cdot v_\varepsilon \, d\xi \right) \nabla \partial_z T_\varepsilon \right.$$
$$\left. - (\Delta v_\varepsilon \cdot \nabla_H) T_\varepsilon - 2 \nabla v_\varepsilon \cdot \nabla_H \nabla T_\varepsilon \right] \Delta T_\varepsilon \, dx \, dy \, dz$$

$$= \int_{\Omega} \left[\left(\int_{-h}^{z} \Delta \nabla_H \cdot v_{\varepsilon} \, d\xi \right) \left(\partial_z T_{\varepsilon} + \frac{1}{h} \right) - (\Delta v_{\varepsilon} \cdot \nabla_H) T_{\varepsilon} - 2 \nabla v_{\varepsilon} \cdot \nabla_H \nabla T_{\varepsilon} \right] \Delta T_{\varepsilon} \, dx \, dy \, dz$$

$$-2 \int_{\Omega} \left[\nabla \nabla_H \cdot v_{\varepsilon} \nabla T_{\varepsilon} \Delta T_{\varepsilon} + \left(\int_{-h}^{z} \nabla \nabla_H \cdot v_{\varepsilon} \, d\xi \right) \nabla T_{\varepsilon} \Delta \partial_z T_{\varepsilon} \right] dx \, dy \, dz$$

$$\leq C (\|\Delta \nabla v_{\varepsilon}\|_2 \|\partial_z T_{\varepsilon}\|_{\infty} \|\Delta T_{\varepsilon}\|_2 + \|\Delta \nabla v_{\varepsilon}\|_2 \|\Delta T_{\varepsilon}\|_2 + \|\Delta v_{\varepsilon}\|_3 \|\nabla_H T_{\varepsilon}\|_6 \|\Delta T_{\varepsilon}\|_2$$

$$+ \|\nabla v_{\varepsilon}\|_{\infty} \|\nabla^2 T_{\varepsilon}\|_2^2 + \|\nabla^2 v_{\varepsilon}\|_3 \|\nabla T_{\varepsilon}\|_6 \|\Delta T_{\varepsilon}\|_2 + \|\nabla^2 v_{\varepsilon}\|_3 \|\nabla T_{\varepsilon}\|_6 \|\Delta \partial_z T_{\varepsilon}\|_2)$$

$$\leq C \Big[\|\nabla \Delta v_{\varepsilon}\|_2 \|\Delta T_{\varepsilon}\|_2^{1/2} (\|\Delta \partial_z T_{\varepsilon}\|_2^{1/2} + \|\partial_z T_{\varepsilon}\|_2^{1/2}) \|\Delta T_{\varepsilon}\|_2 + \|\Delta \nabla v_{\varepsilon}\|_2 \|\Delta T_{\varepsilon}\|_2$$

$$+ \|\Delta v_{\varepsilon}\|_2^{1/2} \|\nabla \Delta v_{\varepsilon}\|_2^{1/2} \|\Delta T_{\varepsilon}\|_2^2 + \|\Delta v_{\varepsilon}\|_2^{1/2} \|\nabla \Delta v_{\varepsilon}\|_2^{1/2} \|\Delta T_{\varepsilon}\|_2 \|\Delta \partial_z T_{\varepsilon}\|_2 \Big]$$

$$\leq \sigma (\|\Delta \partial_z T_{\varepsilon}\|_2^2 + \|\nabla \Delta v_{\varepsilon}\|_2^2) + C_{\sigma} (1 + \|v_{\varepsilon}\|_{H^2}^6 + \|T_{\varepsilon}\|_{H^2}^6), \tag{3.6}$$

where σ is a sufficiently small positive constant.

Combining (3.3) with (3.6), it follows that

$$\sup_{0 \leq s \leq t} \|T_{\varepsilon}\|_{H^2}^2 + \int_0^t (\varepsilon \|\nabla_H T_{\varepsilon}\|_{H^2}^2 + \|\partial_z T_{\varepsilon}\|_{H^2}^2) \, ds$$

$$\leq C \|T_0\|_{H^2}^2 + \sigma \int_0^t \|\nabla \Delta v_{\varepsilon}\|_2^2 \, ds + C_{\sigma} \int_0^t (1 + \|T_{\varepsilon}\|_{H^2}^2 + \|v_{\varepsilon}\|_{H^2}^2)^3 \, ds,$$

with a sufficiently small positive constant σ, for any $0 \leq t < t_{\varepsilon}^*$. This, combined with (3.2), implies

$$\sup_{0 \leq s \leq t} (\|v_{\varepsilon}\|_{H^2}^2 + \|T_{\varepsilon}\|_{H^2}^2) + \int_0^t (\varepsilon \|\nabla_H T_{\varepsilon}\|_{H^2}^2 + \|\partial_z T_{\varepsilon}\|_{H^2}^2 + \|\nabla v_{\varepsilon}\|_{H^2}^2) \, ds$$

$$\leq C (\|v_0\|_{H^2}^2 + \|T_0\|_{H^2}^2) + C \int_0^t (1 + \|T_{\varepsilon}\|_{H^2}^2 + \|v_{\varepsilon}\|_{H^2}^2)^3 \, ds$$

for any $0 \leq t < t_{\varepsilon}^*$. Set

$$f(t) = \sup_{0 \leq s \leq t} (\|v_{\varepsilon}\|_{H^2}^2 + \|T_{\varepsilon}\|_{H^2}^2 + 1)$$

$$+ \int_0^t (\varepsilon \|\nabla_H T_{\varepsilon}\|_{H^2}^2 + \|\partial_z T_{\varepsilon}\|_{H^2}^2 + \|\nabla v_{\varepsilon}\|_{H^2}^2) \, ds$$

for $t \in [0, t_{\varepsilon}^*)$. Then one has

$$f(t) \leq CC_0 + C \int_0^t (f(s))^3 \, ds, \quad t \in [0, t_{\varepsilon}^*), \tag{3.7}$$

where $C_0 = \|v_0\|_{H^2}^2 + \|T_0\|_{H^2}^2$. Set $F(t) = \int_0^t (f(t)^3) \, ds + 1$, then by (3.7) one has

$$F'(t) = (f(t))^3 \leq C_1 (F(t))^3, \quad \forall t \in [0, t_{\varepsilon}^*),$$

where C_1 is a positive constant depending only on R_1, R_2, R_3, h and (v_0, T_0). This inequality implies

$$F(t) \leq \frac{1}{\sqrt{1 - 2C_1 t}}, \quad \forall t \in [0, t_{\varepsilon}^*) \cap \left[0, \frac{1}{2C_1} \right),$$

and thus

$$\sup_{0 \leq s \leq t} (\|v_\varepsilon\|_{H^2}^2 + \|T_\varepsilon\|_{H^2}^2) + \int_0^t (\varepsilon \|\nabla_H T_\varepsilon\|_{H^2}^2 + \|\partial_z T_\varepsilon\|_{H^2}^2 + \|\nabla v_\varepsilon\|_{H^2}^2) \, ds$$

$$\leq CC_0 + CF(t) \leq CC_0 + \frac{C}{\sqrt{1 - 2C_1 t}} \leq C(C_0 + \sqrt{2}),$$

for any $t \in [0, t_\varepsilon^*) \cap [0, \frac{1}{4C_1}]$. Recalling that t_ε^* is the maximal existence time, the above inequality implies $t_\varepsilon^* > \frac{1}{4C_1}$, and thus, we can choose $t_0^* = \frac{1}{4C_1}$, and

$$\sup_{0 \leq s \leq t_0^*} (\|v_\varepsilon\|_{H^2}^2 + \|T_\varepsilon\|_{H^2}^2) + \int_0^{t_0^*} (\varepsilon \|\nabla_H T_\varepsilon\|_{H^2}^2$$

$$+ \|\partial_z T_\varepsilon\|_{H^2}^2 + \|\nabla v_\varepsilon\|_{H^2}^2) \, ds \leq C(C_0 + \sqrt{2}). \tag{3.8}$$

We still need to establish estimates on $\partial_t v_\varepsilon$ and $\partial_t T_\varepsilon$. The estimates on $\partial_t T_\varepsilon$ follow from Equation (2.3), the estimates (3.8) and the Sobolev embedding inequality as follows

$$\int_0^{t_0^*} \|\partial_t T_\varepsilon\|_{H^1}^2 \, dt \leq C \int_0^{t_0^*} \left(\|\partial_z^2 T_\varepsilon\|_{H^1}^2 + \varepsilon \|\Delta_H T_\varepsilon\|_{H^1}^2 + \|v_\varepsilon \cdot \nabla_H T_\varepsilon\|_{H^1}^2 \right.$$

$$+ \left\| \int_{-h}^z \nabla_H \cdot v_\varepsilon \, d\xi \left(\partial_z T_\varepsilon + \frac{1}{h} \right) \right\|_{H^1}^2 \Bigg) \, dt$$

$$\leq C \int_0^{t_0^*} \left(\|\partial_z T_\varepsilon\|_{H^2}^2 + \varepsilon \|\nabla_H T_\varepsilon\|_{H^2}^2 + \|v_\varepsilon\|_{W^{1,\infty}}^2 (\|\nabla T_\varepsilon\|_{H^1}^2 + 1) \right.$$

$$+ \left\| \int_{-h}^z \nabla_H \nabla_H \cdot v_\varepsilon \, d\xi (|\partial_z T_\varepsilon| + 1) \right\|_2^2 \Bigg) \, dt$$

$$\leq C \int_0^{t_0^*} [\|\partial_z T_\varepsilon\|_{H^2}^2 + \varepsilon \|\nabla_H T_\varepsilon\|_{H^2}^2 + \|v_\varepsilon\|_{W^{1,\infty}}^2 (\|\nabla T_\varepsilon\|_{H^1}^2 + 1)$$

$$+ (\|\partial_z T_\varepsilon\|_\infty^2 + 1) \|\nabla^2 v_\varepsilon\|_2^2] \, dt$$

$$\leq C \int_0^{t_0^*} [\|\partial_z T_\varepsilon\|_{H^2}^2 + \varepsilon \|\nabla_H T_\varepsilon\|_{H^2}^2 + \|v_\varepsilon\|_{H^3}^2 (\|T_\varepsilon\|_{H^2}^2 + 1)$$

$$+ \|\partial_z T_\varepsilon\|_{H^2}^2 \|v_\varepsilon\|_{H^2}^2] \, dt$$

$$\leq C(C_0 + \sqrt{2})^2 (t_0^* + 1).$$

For the estimates on $\partial_t v_\varepsilon$, we split v_ε as $v_\varepsilon = \tilde{v}_\varepsilon + \bar{v}_\varepsilon$ (recall the definitions of $\tilde{\phi}$ and $\bar{\phi}$ in the Introduction). Then $\tilde{v}_\varepsilon$ and $\bar{v}_\varepsilon$ satisfy system (see, for example, CAO and TITI [6])

$$\partial_t \bar{v}_\varepsilon - \frac{1}{R_1} \Delta_H \bar{v}_\varepsilon + (\bar{v}_\varepsilon \cdot \nabla_H) \bar{v}_\varepsilon + \overline{(\tilde{v}_\varepsilon \cdot \nabla_H) \tilde{v}_\varepsilon + (\nabla_H \cdot \tilde{v}_\varepsilon) \tilde{v}_\varepsilon} + f_0 k \times \bar{v}_\varepsilon$$

$$+ \nabla_H \left(p_s(x, y, t) - \frac{1}{2h} \int_{-h}^h \int_{-h}^z T_\varepsilon(x, y, \xi, t) \, d\xi \, dz \right) = 0,$$

$$\nabla_H \cdot \bar{v}_\varepsilon = 0,$$

$$\partial_t \tilde{v}_\varepsilon + L_1 \tilde{v}_\varepsilon + (\tilde{v}_\varepsilon \cdot \nabla_H)\tilde{v}_\varepsilon - \left(\int_{-h}^{z} \nabla_H \cdot \tilde{v}_\varepsilon(x, y, \xi, t)\, d\xi\right) \partial_z \tilde{v}_\varepsilon + (\tilde{v}_\varepsilon \cdot \nabla_H)\bar{v}_\varepsilon$$

$$+ (\bar{v}_\varepsilon \cdot \nabla_H)\tilde{v}_\varepsilon - \overline{(\tilde{v}_\varepsilon \cdot \nabla_H)\tilde{v}_\varepsilon + (\nabla_H \cdot \tilde{v}_\varepsilon)\tilde{v}_\varepsilon} + f_0 k \times \tilde{v}_\varepsilon$$

$$- \nabla_H \left(\int_{-h}^{z} T_\varepsilon(x, y, \xi, t)\, d\xi - \frac{1}{2h}\int_{-h}^{h}\int_{-h}^{z} T_\varepsilon(x, y, \xi, t)\, d\xi\, dz\right) = 0. \quad (3.9)$$

Thanks to the estimates (3.8), we can apply the L^2 theory of Stokes equations and the Sobolev embedding inequality to deduce

$$\int_0^{t_0^*} \|\partial_t \bar{v}_\varepsilon\|_{H^1(M)}^2\, dt \leqq C \int_0^{t_0^*} \left(\|\Delta_H \bar{v}_\varepsilon\|_{H^1(M)}^2 + \|\bar{v}_\varepsilon \cdot \nabla_H \bar{v}_\varepsilon\|_{H^1(M)}^2 + \|\overline{\tilde{v}_\varepsilon \cdot \nabla_H \tilde{v}_\varepsilon}\|_{H^1(M)}^2\right.$$

$$\left. + \|\overline{\nabla_H \cdot \tilde{v}_\varepsilon \tilde{v}_\varepsilon}\|_{H^1(M)}^2 + \|\bar{v}_\varepsilon\|_{H^1(M)}^2 + \left\|\nabla_H \int_{-h}^{h}\int_{-h}^{z} T_\varepsilon\, d\xi\, dz\right\|_{H^1(M)}^2\right) dt$$

$$\leqq C \int_0^{t_0^*} (\|\nabla v_\varepsilon\|_{H^2}^2 + \|v_\varepsilon\|_{W^{1,\infty}}^2 \|\nabla v_\varepsilon\|_{H^1}^2 + \|v_\varepsilon\|_{H^2}^2 + \|T_\varepsilon\|_{H^2}^2)\, dt$$

$$\leqq C \int_0^{t_0^*} (\|\nabla v_\varepsilon\|_{H^2}^2 + \|v_\varepsilon\|_{H^3}^2 \|v_\varepsilon\|_{H^2}^2 + \|v_\varepsilon\|_{H^2}^2 + \|T_\varepsilon\|_{H^2}^2)\, dt \leqq C(C_0 + \sqrt{2})^2(t_0^* + 1),$$

and similarly, it follows from Equation (3.9) and the Sobolev embedding inequality that

$$\int_0^{t_0^*} \|\partial_t \tilde{v}_\varepsilon\|_{H^1}^2\, dt \leqq C(C_0 + \sqrt{2})^2(t_0^* + 1).$$

Therefore, one obtains

$$\int_0^{t_0^*} \|\partial_t v_\varepsilon\|_{H^1}^2\, dt \leq C \int_0^{t_0^*} (\|\partial_t \tilde{v}_\varepsilon\|_{H^1}^2 + \|\partial_t \bar{v}_\varepsilon\|_{H^1(M)}^2)\, dt \leqq C(C_0 + \sqrt{2})^2(t_0^* + 1).$$

This completes the proof. □

We will use the following lemma to prove the uniqueness.

Lemma 3.1. *The following inequalities hold true*

$$\left|\int_M \left(\int_{-h}^{h} f(x, y, z)\, dz\right)\left(\int_{-h}^{h} g(x, y, z)h(x, y, z)\, dz\right) dx\, dy\right|$$

$$\leqq C\|f\|_2^{1/2}(\|f\|_2^{1/2} + \|\nabla_H f\|_2^{1/2})\|g\|_2\|h\|_2^{1/2}(\|h\|_2^{1/2} + \|\nabla_H h\|_2^{1/2}),$$

and

$$\left|\int_M \left(\int_{-h}^{h} f(x, y, z)\, dz\right)\left(\int_{-h}^{h} g(x, y, z)h(x, y, z)\, dz\right) dx\, dy\right|$$

$$\leqq C\|f\|_2\|g\|_2^{1/2}(\|g\|_2^{1/2} + \|\nabla_H g\|_2^{1/2})\|h\|_2^{1/2}(\|h\|_2^{1/2} + \|\nabla_H h\|_2^{1/2}).$$

Proof. The proof can be established in the same way as in Proposition 2.2 of [5], and thus it is omitted here. □

We also need the following version of the Aubin–Lions lemma.

Lemma 3.2. (Aubin–Lions Lemma, See Simon [21] Corollary 4) *Assume that X, B and Y are three Banach spaces, with $X \hookrightarrow\hookrightarrow B \hookrightarrow Y$. Then it holds that*

(i) *If F is a bounded subset of $L^p(0, T; X)$ where $1 \leqq p < \infty$, and $\frac{\partial F}{\partial t} = \left\{ \frac{\partial f}{\partial t} | f \in F \right\}$ is bounded in $L^1(0, T; Y)$, then F is relatively compact in $L^p(0, T; B)$;*

(ii) *If F is bounded in $L^\infty(0, T; X)$ and $\frac{\partial F}{\partial t}$ is bounded in $L^r(0, T; Y)$ where $r > 1$, then F is relatively compact in $C([0, T]; B)$.*

Proposition 3.2. *Let v_0 and $T_0 \in H^2(\Omega)$ be two periodic functions, such that they are even and odd in z, respectively. Then system (1.16)–(1.22) has a unique strong solution (v, T) in $\Omega \times (0, t_0^*)$, such that*

$$(v, T) \in L^\infty(0, t_0^*; H^2(\Omega)) \cap C([0, t_0^*]; H^1(\Omega)), \quad (\nabla v, \partial_z T) \in L^2(0, t_0^*; H^2(\Omega))$$

and

$$(\partial_t v, \partial_t T) \in L^2(0, t_0^*; H^1(\Omega)),$$

where t_0^* is the same positive time stated in Proposition 3.1.

Moreover, the strong solutions are continuously dependent on the initial data, in other words, for any two strong solutions (v_1, T_1) and (v_2, T_2) to system (1.16)–(1.22) on $\Omega \times (0, t_0)$, with initial data (v_{10}, T_{10}) and (v_{20}, T_{20}), respectively, it holds that

$$\sup_{0 \leqq t \leqq t_0} (\|v\|_2^2 + \|T\|_2^2) \leqq C e^{C \int_0^{t_0} (1 + \|v_2\|_{H^2}^4 + \|T_2\|_{H^2}^4) \, dt} (\|v_0\|_2^2 + \|T_0\|_2^2),$$

with $(v_0, T_0) = (v_{10} - v_{20}, T_{10}, T_{20})$.

Proof. By Proposition 3.1, for any given $\varepsilon > 0$, system (2.1)–(2.6) has a solution $(v_\varepsilon, T_\varepsilon)$ in $\Omega \times (0, t_0^*)$ such that

$$\sup_{0 \leqq t \leqq t_0^*} (\|v_\varepsilon(t)\|_{H^2}^2 + \|T_\varepsilon(t)\|_{H^2}^2) + \int_0^{t_0^*} (\varepsilon \|\nabla_H T_\varepsilon\|_{H^2}^2 + \|\partial_z T_\varepsilon\|_{H^2}^2 + \|\nabla v_\varepsilon\|_{H^2}^2) \, dt \leqq K$$

and

$$\int_0^{t_0^*} (\|\partial_t v_\varepsilon\|_{H^1}^2 + \|\partial_t T_\varepsilon\|_{H^1}^2) \, dt \leqq K,$$

where K is a constant which is independent of ε. On account of these estimates, by Lemma 3.2, there is a subsequence of $(v_{\varepsilon_j}, T_{\varepsilon_j})$ and (v, T), such that

$$(v_{\varepsilon_j}, T_{\varepsilon_j}) \to (v, T), \quad \text{in } C([0, t_0]; H^1(\Omega)),$$

$$v_{\varepsilon_j} \to v, \quad \text{in } L^2(0, t_0; H^2(\Omega)), \qquad \partial_z T_{\varepsilon_j} \to \partial_z v, \quad \text{in } L^2(0, t_0; H^1(\Omega)),$$

$$(v_{\varepsilon_j}, T_{\varepsilon_j}) \rightharpoonup^* (v, T), \quad \text{in } L^\infty(0, t_0; H^2(\Omega)),$$

$$v_{\varepsilon_j} \rightharpoonup v, \quad \text{in } L^2(0, t_0; H^3(\Omega)), \qquad \partial_z T_{\varepsilon_j} \rightharpoonup \partial_z T, \quad \text{in } L^2(0, t_0; H^2(\Omega)),$$
$$(\partial_t v_{\varepsilon_j}, \partial_t T_{\varepsilon_j}) \rightharpoonup (\partial_t v, \partial_t T), \quad \text{in } L^2(0, t_0; H^1(\Omega)),$$

where $\rightharpoonup$ and $\rightharpoonup^*$ are the weak and weak-* convergence, respectively. Due to these convergences, one can take the limit $\varepsilon_j \to 0$ to see that (v, T) is a strong solution to the system (1.23)–(1.28), or equivalently system (1.16)–(1.22). The regularities of (v, T) follow from the uniform, in ε, estimates on $(v_{\varepsilon_j}, T_{\varepsilon_j})$ stated above and the weakly lower semi-continuity of the norms.

We now prove the continuous dependence on the initial data and the uniqueness of strong solutions. Let (v_1, T_1) and (v_2, T_2) be two strong solutions to system (1.16)–(1.22) in $\Omega \times (0, t_0)$, with initial data (v_{10}, T_{10}) and (v_{20}, T_{20}), respectively. Set $v = v_1 - v_2$ and $T = T_1 - T_2$. One can easily check that (v, T) satisfies the following system

$$\partial_t v + L_1 v + (v_1 \cdot \nabla_H)v + (v \cdot \nabla_H)v_2 - \left(\int_{-h}^{z} \nabla_H \cdot v_1 \, d\xi\right) \partial_z v - \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi\right) \partial_z v_2$$

$$+ f_0 k \times v + \nabla_H p_s(x, y, t) - \nabla_H \left(\int_{-h}^{z} T(x, y, \xi, t) \, d\xi\right) = 0, \tag{3.10}$$

$$\nabla_H \cdot \bar{v} = 0,$$

$$\partial_t T + L_2 T + v_1 \cdot \nabla_H T + v \cdot \nabla_H T_2 - \left(\int_{-h}^{z} \nabla_H \cdot v_1 \, d\xi\right) \partial_z T$$

$$- \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi\right) \left(\partial_z T_2 + \frac{1}{h}\right) = 0 \tag{3.11}$$

and the boundary and initial conditions

$$v \text{ and } T \text{ are periodic in } x, y, z,$$
$$v \text{ and } T \text{ are even and odd in } z, \text{ respectively,}$$
$$(v, T)|_{t=0} = (v_0, T_0).$$

Multiplying (3.10) by v and integrating by parts (recalling the regularities of v that we have just proved) yield

$$\frac{1}{2} \frac{d}{dt} \int_\Omega |v|^2 \, dx \, dy \, dz + \int_\Omega \left(\frac{1}{R_1}|\nabla_H v|^2 + \frac{1}{R_2}|\partial_z v|^2\right) dx \, dy \, dz$$

$$= \int_\Omega \left\{ \left[\left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi\right) \partial_z v_2 - (v \cdot \nabla_H)v_2 \right] v \right.$$

$$\left. - \left(\int_{-h}^{z} T \, d\xi\right) \nabla_H \cdot v \right\} dx \, dy \, dz. \tag{3.12}$$

By Lemma 3.1 and using Cauchy's inequality, we have the following estimates

$$\left| \int_\Omega \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi\right) \partial_z v_2 \cdot v \, dx \, dy \, dz \right| \leq \int_M \left(\int_{-h}^{h} |\nabla_H v| \, dz\right) \left(\int_{-h}^{h} |\partial_z v_2||v| \, dz\right) dx \, dy$$

$$\leq C\|\nabla_H v\|_2 \|\partial_z v_2\|_2^{1/2} (\|\partial_z v_2\|_2^{1/2} + \|\nabla_H \partial_z v_2\|_2^{1/2})\|v\|_2^{1/2}(\|v\|_2^{1/2} + \|\nabla_H v\|_2^{1/2})$$

$$\leq C\|v_2\|_{H^2}(\|v\|_2\|\nabla_H v\|_2 + \|v\|_2^{1/2}\|\nabla_H v\|_2^{3/2}) \leq \sigma\|\nabla_H v\|_2^2 + C_\sigma(1 + \|v_2\|_{H^2}^4)\|v\|_2^2,$$

with a sufficiently small positive constant σ. Noticing that $|v_2(z)| \leqq \frac{1}{2h} \int_{-h}^{h} |v_2(z)| \, dz + \int_{-h}^{h} |\partial_z v_2| \, dz$, applying Lemma 3.1 again and using the Cauchy–Schwarz inequality, we then obtain

$$
\left| \int_\Omega (v \cdot \nabla_H) v_2 \cdot v \, dx \, dy \, dz \right|
$$
$$
= - \int_\Omega [\nabla_H \cdot v v_2 \cdot v + (v \cdot \nabla_H) v \cdot v_2] \, dx \, dy \, dz \leqq \int_\Omega |\nabla_H v| |v| |v_2| \, dx \, dy \, dz
$$
$$
\leqq C \int_M \left(\int_{-h}^{h} (|v_2| + |\partial_z v_2|) \, dz \right) \left(\int_{-h}^{h} |\nabla_H v| |v| \, dz \right) dx \, dy
$$
$$
\leqq C \|\partial_z v_2\|_2^{1/2} (\|\partial_z v_2\|_2^{1/2} + \|\nabla_H \partial_z v_2\|_2^{1/2}) \|\nabla_H v\|_2 \|v\|_2^{1/2} (\|v\|_2^{1/2} + \|\nabla_H v\|_2^{1/2})
$$
$$
+ C \|v_2\|_2^{1/2} (\|v_2\|_2^{1/2} + \|\nabla_H v_2\|_2^{1/2}) \|\nabla_H v\|_2 \|v\|_2^{1/2} (\|v\|_2^{1/2} + \|\nabla_H v\|_2^{1/2})
$$
$$
\|v_2\|_{H^2} (\|v\|_2 \|\nabla_H v\|_2 + \|v\|_2^{1/2} \|\nabla_H v\|_2^{3/2}) \leqq \sigma \|\nabla_H v\|_2^2 + C_\sigma (1 + \|v_2\|_{H^2}^4) \|v\|_2^2,
$$

with a sufficiently small positive constant σ. Substituting these inequalities into (3.12) implies

$$
\frac{d}{dt} \int_\Omega |v|^2 \, dx \, dy \, dz + \int_\Omega \left(\frac{1}{R_1} |\nabla_H v|^2 + \frac{1}{R_2} |\partial_z v|^2 \right) dx \, dy \, dz
$$
$$
\leqq C(1 + \|v_2\|_{H^2}^4)(\|v\|_2^2 + \|T\|_2^2). \tag{3.13}
$$

Multiplying (3.11) by T and integrating by parts (recalling the regularities of T that have just been proved) yield

$$
\frac{1}{2} \frac{d}{dt} \int_\Omega |T|^2 \, dx \, dy \, dz + \frac{1}{R_3} \int_\Omega |\partial_z T|^2 \, dx \, dy \, dz
$$
$$
= - \int_\Omega \left[v \cdot \nabla_H T_2 - \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi \right) \left(\partial_z T_2 + \frac{1}{h} \right) \right] T \, dx \, dy \, dz. \tag{3.14}
$$

Note that $|T(z)| \leqq \frac{1}{2h} \int_{-h}^{h} |T(z)| \, dz + \int_{-h}^{h} |\partial_z T| \, dz$, we can apply Lemma 3.1 and using the Cauchy–Schwarz inequality to deduce

$$
\left| \int_\Omega v \cdot \nabla_H T_2 T \, dx \, dy \, dz \right|
$$
$$
\leqq \int_M \left(\int_{-h}^{h} (|T| + |\partial_z T|) \, dz \right) \left(\int_{-h}^{h} |v| |\nabla_H T_2| \, dz \right) dx \, dy
$$
$$
\leqq C(\|T\|_2 + \|\partial_z T\|_2) \|v\|_2^{1/2} (\|v\|_2^{1/2} + \|\nabla_H v\|_2^{1/2})
$$
$$
\times \|\nabla_H T_2\|_2^{1/2} (\|\nabla_H T_2\|_2^{1/2} + \|\nabla_H^2 T_2\|_2^{1/2})
$$
$$
\leqq C(\|T\|_2 + \|\partial_z T\|_2)(\|v\|_2 + \|v\|_2^{1/2} \|\nabla_H v\|_2^{1/2}) \|T_2\|_{H^2}
$$
$$
\leqq \sigma(\|\partial_z T\|_2^2 + \|\nabla_H v\|_2^2) + C_\sigma (1 + \|T_2\|_{H^2}^4)(\|v\|_2^2 + \|T\|_2^2),
$$

and integration by parts yields

$$
\left| \int_\Omega \left(\int_{-h}^z \nabla_H \cdot v \, d\xi \right) \partial_z T_2 T \, dx \, dy \, dz \right|
$$
$$
= \left| - \int_\Omega \left[\nabla_H \cdot v T_2 T + \left(\int_{-h}^z \nabla_H \cdot v \, d\xi \right) T_2 \partial_z T \right] dx \, dy \, dz \right|
$$
$$
\leqq \sigma \| \partial_z T \|_2^2 + C_\sigma (1 + \| T_2 \|_\infty^2)(\| T \|_2^2 + \| \nabla_H v \|_2^2)
$$
$$
\leqq \sigma \| \partial_z T \|_2^2 + C_\sigma (1 + \| T_2 \|_{H^2}^2)(\| T \|_2^2 + \| \nabla_H v \|_2^2),
$$

with a sufficiently small positive constant σ. Substituting these estimates into (3.14), one has

$$
\frac{d}{dt} \int_\Omega |T|^2 \, dx \, dy \, dz + \frac{1}{R_3} \int_\Omega |\partial_z T|^2 \, dx \, dy \, dz
$$
$$
\leqq C(1 + \| T_2 \|_{H^2}^2)\| \nabla_H v \|_2^2 + C(1 + \| T_2 \|_{H^2}^4)(\| v \|_2^2 + \| T \|_2^2). \quad (3.15)
$$

Since (v_2, T_2) is a strong solution in $\Omega \times (0, t_0)$, it satisfies

$$
\sup_{0 \leqq t \leqq t_0} (\| v_2 \|_{H^2}^2 + \| T_2 \|_{H^2}^2) < \infty.
$$

Multiplying inequality (3.13) by a sufficiently large positive number α, and summing the resulting inequality with (3.15), one reaches

$$
\frac{d}{dt} \int_\Omega (\alpha |v|^2 + |T|^2) \, dx \, dy \, dz \leqq C(1 + \| v_2 \|_{H^2}^4 + \| T_2 \|_{H^2}^4)(\| v \|_2^2 + \| T \|_2^2).
$$

By the Gronwall inequality, it follows from this inequality that

$$
\sup_{0 \leqq t \leqq t_0} (\| v \|_2^2 + \| T \|_2^2) \leqq C e^{C \int_0^{t_0} (1 + \| v_2 \|_{H^2}^4 + \| T_2 \|_{H^2}^4) \, dt} (\| v_0 \|_2^2 + \| T_0 \|_2^2).
$$

This proves the continuous dependence of the initial data. In particular, if $(v_{10}, T_{10}) = (v_{20}, T_{20})$, then $(v, T) \equiv (0, 0)$, that is $(v_1, T_1) = (v_2, T_2)$, proving the uniqueness. This completes the proof. $\quad \square$

4. Global Existence of Strong Solutions

In this section, we show that the local strong solution obtained in Section 3 can be extended to be a global one. That is, we give below the proof of Theorem 1.1.

Proof of Theorem 1.1. By Proposition 3.2, there is a unique strong solution (v, T) to system (1.16)–(1.22) on $\Omega \times (0, t_0^*)$ such that

$$
\sup_{0 \leqq t \leqq t_0^*} (\| T \|_{H^2}^2 + \| v \|_{H^2}^2) + \int_0^{t_0^*} (\| \nabla v \|_{H^2}^2 + \| \partial_z T \|_{H^2}^2) \, dt \leqq C. \quad (4.1)
$$

Set $u = \partial_z v$ and define functions η and θ

$$\eta = \nabla_H^\perp \cdot u = \partial_x u^2 - \partial_y u^1, \tag{4.2}$$

$$\theta = \nabla_H \cdot u + R_1 T = \partial_x u^1 + \partial_y u^2 + R_1 T. \tag{4.3}$$

By Proposition 5.3 (see the Appendix section below), one has

$$\sup_{0 \leqq s \leqq t} [s^2(\|\eta(s)\|_{H^2}^2 + \|\theta(s)\|_{H^2}^2)] + \int_0^t s^2(\|\eta(s)\|_{H^3}^2$$
$$+ \|\theta(s)\|_{H^3}^2 + \|\partial_t \eta(s)\|_{H^1}^2 + \|\partial_t \theta(s)\|_{H^1}^2) \, \mathrm{d}s \leqq K_3(t) \tag{4.4}$$

for all $t \in [0, t_0^*]$, where $K_3(t)$ is a bounded function on $[0, t_0^*]$.

We consider the strong solution (v, T) on the maximal interval of existence $(0, T^*)$. We are going to prove that $T^* = \infty$. Suppose that $T^* < \infty$. Thanks to the regularity properties stated in Proposition 5.3 and Proposition 5.4, below we define, for any $t \in (0, T^*)$,

$$\mathcal{X}(t) = 1 + \|\nabla_H \Delta_H \bar{v}(t)\|_2^2 + C_R \|\Delta_H T(t)\|_2^2 + C_R \|\nabla_H \partial_z T(t)\|_2^2$$
$$+ \|\Delta_H \eta(t)\|_2^2 + \|\nabla_H \partial_z \eta(t)\|_2^2 + \|\Delta_H \theta(t)\|_2^2 + \|\nabla_H \partial_z \theta(t)\|_2^2$$

$$\mathcal{Y}(t) = \|\Delta_H^2 \bar{v}(t)\|_2^2 + \|\Delta_H \partial_z T(t)\|_2^2 + \|\nabla_H \partial_z^2 T(t)\|_2^2 + \|\nabla_H \Delta_H \eta(t)\|_2^2$$
$$+ \|\Delta_H \partial_z \eta(t)\|_2^2 + \|\nabla_H \Delta_H \theta(t)\|_2^2 + \|\Delta_H \partial_z \theta(t)\|_2^2,$$

$$\mathcal{Z}(t) = \log \mathcal{X}(t),$$

where $C_R = \frac{2R_1^2(R_1 + R_2)(R_2 - R_3)^2}{R_2^2 R_3}$. Therefore, it follows (see (122) in [7])

$$\frac{d\mathcal{X}}{\mathrm{d}t} + C\mathcal{Y} \leqq C\|v\|_2(\|\nabla_H \bar{v}\|_{H^1(M)} + \|T\|_\infty + \|\eta\|_{H^1} + \|\theta\|_{H^1})\mathcal{X} \log \mathcal{X}$$
$$+ [1 + \|T\|_\infty^4 + \|\partial_z T\|_2^2 + \|\bar{v}\|_2^2(1 + \|\bar{v}\|_{H^1}^2) + (1 + \|\partial_z u\|_2^2)\|\partial_z u\|_{H^1}^2$$
$$+ (1 + \|\eta\|_2^2)\|\eta\|_{H^1}^2 + (1 + \|\theta\|_2^2)\|\theta\|_{H^1}^2]\mathcal{X} + (\|\eta\|_2^2\|\nabla_H \eta\|_2^2$$
$$+ \|\theta\|_2^2\|\nabla_H \theta\|_2^2 + \|T\|_\infty^4 + \|\partial_z u\|_2^2\|\nabla_H \partial_z u\|_2^2) \tag{4.5}$$

and

$$\frac{d\mathcal{Z}}{\mathrm{d}t} \leqq C\|v\|_2(\|\nabla_H \bar{v}\|_{H^1(M)} + \|T\|_\infty + \|\eta\|_{H^1} + \|\theta\|_{H^1})\mathcal{Z}$$
$$+ \left[1 + \|T\|_\infty^4 + \|\partial_z T\|_2^2 + \|\bar{v}\|_2^2(1 + \|\bar{v}\|_{H^1}^2) + (1 + \|\partial_z u\|_2^2)\|\partial_z u\|_{H^1}^2\right.$$
$$\left. + (1 + \|\eta\|_2^2)\|\eta\|_{H^1}^2 + (1 + \|\theta\|_2^2)\|\theta\|_{H^1}^2\right], \tag{4.6}$$

for any $t \in (0, T^*)$.

Recalling (4.1) and the definitions of η, θ in (4.2) and (4.3), it follows from (4.6) that

$$\frac{d\mathcal{Z}}{\mathrm{d}t} \leqq C(1 + \|v\|_{H^3}^2)\mathcal{Z} + C(1 + \|v\|_{H^3}^2), \quad \forall t \in (0, t_0^*),$$

and thus

$$
\begin{aligned}
\frac{\mathrm{d}}{\mathrm{d}t}(t^2 \mathcal{Z}(t)) &= t^2 \frac{d\mathcal{Z}}{\mathrm{d}t} + 2t\mathcal{Z}(t) \\
&\leqq C(1 + \|v\|_{H^3}^2)t^2 \mathcal{Z}(t) + C(1 + \|v\|_{H^3}^2)t^2 + 2t\mathcal{Z}(t)
\end{aligned}
\tag{4.7}
$$

for $t \in (0, t_0^*)$. Thanks to (4.1) and (4.4), it holds that $\int_0^{t_0^*} t\mathcal{X}(t) \, \mathrm{d}t \leqq C$, and thus, noticing that $\mathcal{X} \geq 1$, we have

$$
\int_0^{t_0^*} t\mathcal{Z}(t) \, \mathrm{d}t = \int_0^{t_0^*} t \log(\mathcal{X}(t)) \, \mathrm{d}t \leqq C \int_0^{t_0^*} t\mathcal{X}(t) \, \mathrm{d}t \leqq C.
$$

Combining the above with (4.7) gives

$$
t^2 \mathcal{Z}(t) \leqq C e^{C \int_0^t (1 + \|v\|_{H^3}^2) \, \mathrm{d}s} \int_0^t [(1 + \|v\|_{H^3}^2)s^2 + 2s\mathcal{Z}(t)] \, \mathrm{d}s \leqq C,
$$

for any $t \in (0, t_0^*)$. Recalling the definitions of $\mathcal{X}$ and $\mathcal{Z}$, the above inequality implies

$$
\sup_{\frac{t_0^*}{2} \leqq t \leqq t_0^*} \mathcal{X}(t) \leqq C.
\tag{4.8}
$$

Thanks to the estimates (59), (69), (91), (103) and (113) in [7], one has

$$
\sup_{0 \leqq t \leqq T^*} (\|v\|_2^2 + \|T\|_\infty^2 + \|\nabla_H \bar{v}\|_2^2 + \|\partial_z u\|_2^2 + \|\eta\|_2^2 + \|\theta\|_2^2)
$$
$$
+ \int_0^{T^*} (\|\nabla v\|_2^2 + \|\partial_z T\|_2^2 + \|\Delta_H \bar{v}\|_2^2 + \|\nabla \partial_z u\|_2^2 + \|\nabla \eta\|_2^2 + \|\nabla \theta\|_2^2) \, \mathrm{d}t \leqq C,
\tag{4.9}
$$

and consequently, we have

$$
\int_0^t \|v\|_2 (\|\nabla_H \bar{v}\|_{H^1(M)} + \|T\|_\infty + \|\eta\|_{H^1} + \|\theta\|_{H^1}) \, \mathrm{d}s \leqq C,
$$

and

$$
\int_0^t [\|T\|_\infty^4 + \|\partial_z T\|_2^2 + \|\bar{v}\|_2^2 (1 + \|\bar{v}\|_{H^1}^2) + (1 + \|\partial_z u\|_2^2)\|\partial_z u\|_{H^1}^2
$$
$$
+ (1 + \|\eta\|_2^2)\|\eta\|_{H^1}^2 + (1 + \|\theta\|_2^2)\|\theta\|_{H^1}^2] \, \mathrm{d}s \leqq C,
$$

for any $t \in (0, T_*)$. By the aid of these two inequalities, using (4.8), it follows from (4.6) that

$$
\sup_{t_0^*/2 \leqq t < T^*} \mathcal{Z}(t) \leqq C.
$$

Thus by (4.5) we have

$$
\sup_{t_0^*/2 \leqq t < T^*} \mathcal{X}(t) + \int_{t_0^*/2}^{T^*} \mathcal{Y}(t) \, \mathrm{d}t \leqq C.
\tag{4.10}
$$

It is clear that

$$v(x, y, z, t) = \bar{v}(x, y, t) + \frac{1}{2h} \int_{-h}^{h} \int_{z'}^{z} \partial_z v(x, y, \xi, t) \, d\xi \, dz',$$

and thus, it follows from elliptic estimates and Poincaré's inequality that

$$
\begin{aligned}
\|\nabla_H \nabla v\|_2^2 &= \|\nabla_H^2 v\|_2^2 + \|\nabla_H \partial_z v\|_2^2 = \|\nabla_H^2 v\|_2^2 + \|\nabla_H u\|_2^2 \\
&\leqq C\|\nabla_H^2 \bar{v}\|_2^2 + \|\nabla_H^2 u\|_2^2 + \|\nabla_H u\|_2^2) \\
&\leqq C(\|\Delta_H \bar{v}\|_2^2 + \|\nabla_H(\nabla_H^{\perp} \cdot u)\|_2^2 + \|\nabla_H(\nabla_H \cdot u)\|_2^2 + \|\nabla_H^{\perp} \cdot u\|_2^2 + \|\nabla_H \cdot u\|_2^2) \\
&\leqq C(\|\nabla_H \Delta_H \bar{v}\|_2^2 + \|\nabla_H \eta\|_2^2 + \|\nabla_H \theta\|_2^2 + \|\nabla_H T\|_2^2 + \|\eta\|_2^2 + \|\theta\|_2^2 + \|T\|_2^2) \\
&\leqq C(\|\nabla_H \Delta_H \bar{v}\|_2^2 + \|\nabla \nabla_H \eta\|_2^2 + \|\nabla \nabla_H \theta\|_2^2 + \|\nabla \nabla_H T\|_2^2 + \|\eta\|_2^2 + \|\theta\|_2^2 + \|T\|_2^2) \\
&\leqq C(\|\nabla_H \Delta_H \bar{v}\|_2^2 + \|\Delta_H \eta\|_2^2 + \|\Delta_H \theta\|_2^2 + \|\Delta_H T\|_2^2 + \|\nabla_H \partial_z \eta\|_2^2 + \|\nabla_H \partial_z \theta\|_2^2 \\
&\quad + \|\nabla_H \partial_z T\|_2^2 + \|\eta\|_2^2 + \|\theta\|_2^2 + \|T\|_2^2) \\
&\leqq C(\mathcal{X}(t) + \|\eta\|_2^2 + \|\theta\|_2^2 + \|T\|_2^2)
\end{aligned}
$$

and

$$
\begin{aligned}
\|\nabla_H^2 \nabla v\|_2^2 &= \|\nabla_H^2 \partial_z v\|_2^2 + \|\nabla_H^3 v\|_2^2 = \|\nabla_H^2 u\|_2^2 + \|\nabla_H^3 v\|_2^2 \\
&\leqq C(\|\nabla_H \nabla_H \cdot u\|_2^2 + \|\nabla_H \nabla_H^{\perp} \cdot u\|_2^2 + \|\nabla_H^3 \bar{v}\|_2^2 + \|\nabla_H^3 u\|_2^2) \\
&\leqq C(\|\nabla_H \eta\|_2^2 + \|\nabla_H \theta\|_2^2 + \|\nabla_H T\|_2^2 + \|\nabla_H \Delta \bar{v}\|_2^2 + \|\nabla_H^2 \nabla_H \cdot u\|_2^2 + \|\nabla_H^2 \nabla_H^{\perp} \cdot u\|_2^2) \\
&\leqq C(\|\nabla_H \eta\|_2^2 + \|\nabla_H \theta\|_2^2 + \|\nabla_H \nabla T\|_2^2 + \|\nabla_H \Delta \bar{v}\|_2^2 + \|\nabla_H^2 \eta\|_2^2 + \|\nabla_H^2 \theta\|_2^2 + \|\nabla_H^2 T\|_2^2) \\
&\leqq C(\|\nabla_H \eta\|_2^2 + \|\nabla_H \theta\|_2^2 + \|\nabla_H \partial_z T\|_2^2 + \|\nabla_H \Delta \bar{v}\|_2^2 + \|\Delta_H \eta\|_2^2 + \|\Delta_H \theta\|_2^2 + \|\Delta_H T\|_2^2) \\
&\leqq C(\mathcal{X}(t) + \|\nabla_H \eta\|_2^2 + \|\nabla_H \theta\|_2^2).
\end{aligned}
$$

Combining these two estimates it follows from (4.9) and (4.10) that

$$
\begin{aligned}
&\sup_{t_0^*/2 \leqq t < T^*} \|v(t)\|_{H^2}^2 + \int_{t_0^*/2}^{T^*} \|\nabla^3 v(t)\|_2^2 \, dt \\
&\leqq C \sup_{t_0^*/2 \leqq t < T^*} (\|v\|_2^2 + \|\partial_z^2 v\|_2^2 + \|\nabla_H \nabla v\|_2^2) + C \int_{t_0^*/2}^{T^*} (\|\nabla \partial_z^2 v\|_2^2 \|\nabla_H^2 \nabla v\|_2^2) \, dt \\
&= C \sup_{t_0^*/2 \leqq t < T^*} (\|v\|_2^2 + \|\partial_z u\|_2^2 + \mathcal{X}(t) + \|\eta\|_2^2 + \|\theta\|_2^2 + \|T\|_2^2) \\
&\quad + C \int_{t_0^*/2}^{T^*} (\|\nabla \partial_z u\|_2^2 + \mathcal{X}(t) + \|\nabla_H \eta\|_2^2 + \|\nabla_H \theta\|_2^2) \, dt \leqq C,
\end{aligned}
$$

and thus

$$
\sup_{t_0^*/2 \leqq t < T^*} \|v\|_{H^2}^2 + \int_{t_0^*/2}^{T^*} \|v\|_{H^3}^2 \, dt \leqq C. \tag{4.11}
$$

Thanks to (4.9), (4.10) and using the Poincaré inequality, it follows that

$$
\sup_{t_0^*/2 \leqq t < T^*} (\|T\|_2^2 + \|\nabla_H T\|_{H^1}^2) + \int_{t_0^*/2}^{T^*} (\|\partial_z T\|_2^2 + \|\partial_z \nabla_H T\|_{H^1}^2) \, dt \leqq C. \tag{4.12}
$$

Applying the operator ∂_z to (1.25) and multiplying the resulting equation by $-\partial_z^3 T$, then it follows after integrating by parts and using Lemma 2.1 that

$$
\frac{1}{2} \frac{d}{dt} \int_\Omega |\partial_z^2 T|^2 \, dx \, dy \, dz + \frac{1}{R_3} \int_\Omega |\partial_z^3 T|^2 \, dx \, dy \, dz
$$

$$
= -\int_\Omega \left((\partial_z^2 v \cdot \nabla_H) T + 2(\partial_z v \cdot \nabla_H) \partial_z T - (\partial_z \nabla_H \cdot v) \left(\partial_z T + \frac{1}{h} \right) \right.
$$

$$
\left. -2(\nabla_H \cdot v) \partial_z^2 T \right) \partial_z^2 T \, dx \, dy \, dz
$$

$$
\leqq C(\|\partial_z^2 v\|_3 \|\nabla_H T\|_6 + \|\partial_z v\|_\infty \|\nabla_H \partial_z T\|_2 + \|\partial_z \nabla_H v\|_3 \|\partial_z T\|_6
$$

$$
+ \|\partial_z \nabla_H v\|_2 + \|\nabla_H v\|_\infty \|\partial_z^2 T\|_2) \|\partial_z^2 T\|_2
$$

$$
\leqq C(\|v\|_{H^3} \|\nabla_H \nabla T\|_2 + \|v\|_{H^3} \|\nabla \partial_z T\|_2 + \|v\|_{H^2}) \|\partial_z^2 T\|_2
$$

$$
\leqq C(\|v\|_{H^3} \|\nabla_H T\|_{H^1} + \|v\|_{H^3} \|\partial_z^2 T\|_2 + \|v\|_{H^2}) \|\partial_z^2 T\|_2
$$

$$
\leqq C\|v\|_{H^3} (\|\nabla_H T\|_{H^1} + 1) + C\|v\|_{H^3} \|\partial_z^2 T\|_2^2.
$$

By the aid of (4.1), (4.11) and (4.12), it follows from the above inequality that

$$
\sup_{0 \leqq t < T^*} \|\partial_z^2 T\|_2^2 + \int_0^{T^*} \|\partial_z^3 T\|_2^2 \, dt
$$

$$
\leqq C e^{\int_0^{T^*} \|v\|_{H^3} \, dt} \left(\|\partial_z^2 T_0\|_2^2 + \int_0^t \|v\|_{H^3} (1 + \|\nabla_H T\|_{H^2}^2) \, ds \right) \leqq C. \quad (4.13)
$$

Combining (4.1) with (4.11)–(4.13), we obtain

$$
\sup_{0 \leqq t < T^*} (\|v\|_{H^2}^2 + \|T\|_{H^2}^2) + \int_0^{T^*} (\|v\|_{H^3}^2 + \|\partial_z T\|_{H^2}^2) \, dt \leqq C.
$$

As a result, we apply Proposition 3.2 to extend the strong solution (v, T) beyond T^*, contradicting to the fact that T^* is a finite maximal time of existence. This contradiction implies that $T^* = \infty$, and this completes the proof. $\quad \square$

5. Appendix: Regularities

In this appendix, we justify some necessary regularities used in the previous section, Section 4. Let (v, T) be a strong solution to system (1.23)–(1.28) in $\Omega \times (0, t_0)$ with $0 < t_0 < \infty$. For any $t \in [0, t_0)$, we set

$$
K_0(t) = \sup_{0 \leqq s \leqq t} (\|v\|_{H^2}^2 + \|T\|_{H^2}^2) + \int_0^t (\|\nabla v\|_{H^2}^2 + \|\partial_z T\|_{H^2}^2) \, ds.
$$

Recall the definition of the functions u, η, θ and ζ

$$
u = \partial_z v, \qquad \zeta = \partial_z u,
$$

$$
\eta = \nabla_H^\perp \cdot u = \partial_x u^2 - \partial_y u^1, \tag{5.1}
$$

$$
\theta = \nabla_H \cdot u + R_1 T = \partial_x u^1 + \partial_y u^2 + R_1 T. \tag{5.2}
$$

We are going to study the regularities of u, ζ, η, θ and $\bar{v}$.

For convenience, we also use the notation $\mathbf{x} = (x^1, x^2, x^3)$ to denote the spacial variables, that is using x^1, x^2 and x^3 to replace x, y and z, respectively. We will use both $\mathbf{x}$ and (x, y, z) to denote the spacial variables. Set $e_1 = (1, 0, 0)$, $e_2 = (0, 1, 0)$ and $e_3 = (0, 0, 1)$. For any spatial periodic function f and $l \neq 0$, we define the difference quotient operators δ_l^i, $i = 1, 2, 3$ as follows

$$\delta_l^i f(\mathbf{x}) = \frac{1}{l}(f(\mathbf{x} + le_i) - f(\mathbf{x})).$$

Since we will use δ_l^3 more frequently than δ_l^i, $i = 1, 2$, we will often use δ_l instead of δ_l^3.

Straightforward calculations show, for any periodic functions f and g, that

$$\delta_{l_1}\delta_{l_2} = \delta_{l_2}\delta_{l_1}, \quad \nabla\delta_l = \delta_l\nabla,$$

$$\delta_l^* = -\delta_{-l}, \quad \text{that is} \quad \int_\Omega \delta_l f g \, d\mathbf{x} = -\int_\Omega f\delta_{-l}g \, d\mathbf{x},$$

$$\delta_l(fg) = f\delta_l g + g(\cdot + le_3)\delta_l f,$$

$$\|\delta_l f\|_p \leq C\|\partial_z f\|_p, \quad \forall f \in W^{1,p}(\Omega), 1 \leq p \leq \infty,$$

where δ_l^* stands for the adjoint operator of δ_l, and C is an absolute constant. The operators δ_l^i, $i = 1, 2$ have the same properties as those of δ_l.

Lemma 5.1. *Suppose that the spatial periodic function f satisfies*

$$\sup_{0 \leq s \leq t} (s^k \|\delta_l^i f\|_2^2) + \int_0^t s^k \|\nabla\delta_l^i f\|_2^2 \, dt \leq K(t),$$

for any $t \in (0, t_0)$ and for any $0 < |l| < 1$, where $K(t)$ is a bounded increasing function on $(0, t_0)$. Then

$$\sup_{0 \leq s \leq t} (s^k \|\partial_i f\|_2^2) + \int_0^t s^k \|\nabla\partial_i f\|_2^2 \, dt \leq K(t),$$

for any $t \in (0, t_0)$.

Proof. Set $g = s^{k/2} f$, then

$$\sup_{0 \leq s \leq t} \|\delta_l^i g\|_2^2 + \int_0^t \|\nabla\delta_l^i g\|_2^2 \, dt \leq K(t),$$

for any $t \in (0, t_0)$. Given $t \in (0, t_0)$, using the sequentially weak compactness of closed balls in $L^2(\Omega)$ and $L^2(\Omega \times (0, t))$, any sequence l_n with $l_n \to 0$ as $n \to \infty$ has a subsequence, still denoted by l_n, such that

$$\delta_{l_n}^i g(\cdot, t) \rightharpoonup \Phi, \quad \text{in } L^2(\Omega),$$

and

$$\delta_{l_n}^i \nabla g \rightharpoonup \Psi, \quad \text{in } L^2(\Omega \times (0, t)).$$

Using the properties of δ_l^i stated above, for any two spatial periodic functions $\phi \in C^\infty(\mathbb{R}^3)$ and $\psi \in C^\infty(\mathbb{R}^3 \times [0, t])$, one has

$$\int_\Omega \delta_{l_n}^i g(\cdot, t)\phi \, \mathrm{d}\mathbf{x} = -\int_\Omega g(\cdot, t)\delta_{-l_n}^i \phi \, \mathrm{d}\mathbf{x} \to -\int_\Omega g(\cdot, t)\partial_i \phi \, \mathrm{d}\mathbf{x}$$

and

$$\int_0^t \int_\Omega \delta_{l_n}^i \nabla g \psi \, \mathrm{d}s = -\int_0^t \int_\Omega \nabla g \delta_{-l_n}^i \psi \, \mathrm{d}\mathbf{x} \, \mathrm{d}s \to -\int_0^t \int_\Omega \nabla g \partial_i \psi \, \mathrm{d}\mathbf{x} \, \mathrm{d}s.$$

On the other hand, the weak convergence of $\delta_{l_n}^i g(\cdot, t)$ and $\delta_{l_n}^i \nabla g$ in $L^2(\Omega)$ and $L^2(\Omega \times (0, t))$, respectively, implies

$$\int_\Omega \delta_{l_n}^i g(\cdot, t)\phi \, \mathrm{d}\mathbf{x} \to \int_\Omega \Phi \phi \, \mathrm{d}\mathbf{x},$$

and

$$\int_0^t \int_\Omega \delta_{l_n}^i \nabla g \psi \, \mathrm{d}\mathbf{x} \, \mathrm{d}s \to \int_0^t \int_\Omega \Psi \psi \, \mathrm{d}\mathbf{x} \, \mathrm{d}s.$$

Therefore, we have

$$\int_\Omega \Phi \phi \, \mathrm{d}x = -\int_\Omega g(\cdot, t)\partial_i \phi \, \mathrm{d}x, \quad \int_0^t \int_\Omega \Psi \psi \, \mathrm{d}\mathbf{x} \, \mathrm{d}s = -\int_0^t \int_\Omega \nabla g \partial_i \psi \, \mathrm{d}\mathbf{x} \, \mathrm{d}s,$$

which imply

$$\Phi = \partial_i g(\cdot, t), \qquad \Psi = \partial_i \nabla g.$$

Combining the above statements, we have proven that for any sequence l_n, with $l_n \to 0$, it has a subsequence, still denoted by l_n, such that

$$\delta_{l_n}^i g(\cdot, t) \rightharpoonup \partial_i g(\cdot, t), \quad \text{in } L^2(\Omega),$$

and

$$\delta_{l_n}^i \nabla g \rightharpoonup \partial_i \nabla g, \quad \text{in } L^2(\Omega \times (0, t)).$$

Thanks to the above two weak convergences, using the weakly lower semi-continuity of the norms and by assumption, we have

$$\|\partial_i g(\cdot, t)\|_2^2 + \int_0^t \|\partial_i \nabla g\|_2^2 \, \mathrm{d}s$$

$$\leq \varliminf_{n \to \infty} \left(\|\delta_{l_n}^i g(\cdot, t)\|_2^2 + \int_0^t \|\delta_{l_n}^i \nabla g\|_2^2 \, \mathrm{d}s \right) \leq K(t),$$

which, recalling the definition of g, gives

$$t^k \|\partial_i f(\cdot, t)\|_2^2 + \int_0^t s^k \|\partial_i \nabla f\|_2^2 \, \mathrm{d}s \leq K(t),$$

for any $t \in (0, t_0)$. The conclusion follows from taking the supremum with respect to time t. This completes the proof. $\square$

We first consider the regularities of u, that is the following proposition.

Proposition 5.1. *Let (v, T) be a strong solution to system* (1.23)–(1.28) *in $\Omega \times (0, t_0)$ and set $u = \partial_z v$. Then*

$$\sqrt{t}u \in L^\infty(0, t_0; H^2(\Omega)) \cap L^2(0, t_0; H^3(\Omega)), \quad \sqrt{t}\partial_t u \in L^2(0, t_0; H^1(\Omega))$$

and

$$\sup_{0 \leq s \leq t} (s\|u\|_{H^2}^2) + \int_0^t s(\|u\|_{H^3}^2 + \|\partial_t u\|_{H^1}^2)\, \mathrm{d}s \leq K_1(t)$$

for any $t \in (0, t_0)$, where $K_1(t)$ is a bounded increasing function on $(0, t_0)$.

Proof. Strong solution (v, T) has the following regularity properties $v \in L^2(0, t_0; H^3(\Omega))$ and $\partial_t v \in L^2(0, t_0; H^1(\Omega))$. One can differentiate Equation (1.23) with respect to z to derive

$$\partial_t u + L_1 u + (v \cdot \nabla_H)u - \left(\int_{-h}^z \nabla_H \cdot v(x, y, \xi, t)\, \mathrm{d}\xi\right)\partial_z u$$
$$+(u \cdot \nabla_H)v - (\nabla_H \cdot v)u + f_0 k \times u - \nabla_H T = 0. \tag{5.3}$$

Note that $\partial_t u \in L^2(0, t_0; L^2(\Omega))$ and $u \in L^2(0, t_0; H^2(\Omega))$. Multiplying the above equation by $-\delta_l^* \delta_l \Delta u$ and applying Lemma 2.1, it follows from the Sobolev embedding inequality and the Cauchy–Schwarz inequality that

$$\frac{1}{2}\frac{\mathrm{d}}{\mathrm{d}t}\int_\Omega |\delta_l \nabla u|^2\, \mathrm{d}\mathbf{x} + \int_\Omega \left(\frac{1}{R_1}|\delta_l \nabla_H \nabla u|^2 + \frac{1}{R_2}|\delta_l \partial_z \nabla u|^2\right)\, \mathrm{d}\mathbf{x}$$

$$= \int_\Omega [(u \cdot \nabla_H)v - (\nabla_H \cdot v)u - \nabla_H T]\delta_l^* \delta_l \Delta u\, \mathrm{d}\mathbf{x}$$

$$+ \int_\Omega \left[(v \cdot \nabla_H)u - \left(\int_{-h}^z \nabla_H \cdot v(x, y, \xi, t)\, \mathrm{d}\xi\right)\partial_z u\right]\delta_l^* \delta_l \Delta u\, \mathrm{d}\mathbf{x}$$

$$= \int_\Omega \delta_l[(u \cdot \nabla_H)v - (\nabla_H \cdot v)u - \nabla_H T]\delta_l \Delta u\, \mathrm{d}\mathbf{x}$$

$$+ \int_\Omega \left[(\delta_l v \cdot \nabla_H)u(\mathbf{x}+le_3, t) - \delta_l\left(\int_{-h}^z \nabla_H \cdot v\, \mathrm{d}\xi\right)\partial_z u(\mathbf{x}+le_3, t)\right]\delta_l \Delta u\, \mathrm{d}\mathbf{x}$$

$$+ \int_\Omega \left[(v \cdot \nabla_H)\delta_l u - \left(\int_{-h}^z \nabla_H \cdot v(x, y, \xi, t)\, \mathrm{d}\xi\right)\partial_z \delta_l u\right]\delta_l \Delta u\, \mathrm{d}\mathbf{x}$$

$$= \int_\Omega \delta_l[(u \cdot \nabla_H)v - (\nabla_H \cdot v)u - \nabla_H T]\delta_l \Delta u\, \mathrm{d}\mathbf{x}$$

$$+ \int_\Omega \left[(\delta_l v \cdot \nabla_H)u(\mathbf{x}+le_3, t) - \delta_l\left(\int_{-h}^z \nabla_H \cdot v\, \mathrm{d}\xi\right)\partial_z u(\mathbf{x}+le_3, t)\right]\delta_l \Delta u\, \mathrm{d}\mathbf{x}$$

$$- \int_\Omega \left[(\nabla v \cdot \nabla_H)\delta_l u - \left(\int_{-h}^z \nabla\nabla_H \cdot v(x, y, \xi, t)\, \mathrm{d}\xi\right)\partial_z \delta_l u\right]\delta_l \nabla u\, \mathrm{d}\mathbf{x}$$

$$- \int_\Omega \left[(v \cdot \nabla_H)\delta_l \nabla u - \left(\int_{-h}^z \nabla_H \cdot v(x, y, \xi, t)\, \mathrm{d}\xi\right)\partial_z \delta_l \nabla u\right]\delta_l \nabla u\, \mathrm{d}\mathbf{x}$$

$$= \int_\Omega \delta_l[(u \cdot \nabla_H)v - (\nabla_H \cdot v)u - \nabla_H T]\delta_l \Delta u \; d\mathbf{x}$$

$$+ \int_\Omega \left[(\delta_l v \cdot \nabla_H)u(\mathbf{x}+le_3,t) - \delta_l \left(\int_{-h}^z \nabla_H \cdot v \; d\xi \right) \partial_z u(\mathbf{x}+le_3,t) \right] \delta_l \Delta u \; d\mathbf{x}$$

$$- \int_\Omega \left[(\nabla v \cdot \nabla_H)\delta_l u - \left(\int_{-h}^z \nabla \nabla_H \cdot v(x,y,\xi,t) \; d\xi \right) \partial_z \delta_l u \right] \delta_l \nabla u \; d\mathbf{x}$$

$$\leq C\|\delta_l[(u \cdot \nabla_H)v - (\nabla_H \cdot v)u]\|_2 \|\delta_l \Delta u\|_2 + C\|\delta_l \nabla_H T\|_2 \|\delta_l \Delta u\|_2$$

$$+ C \left(\|\delta_l v\|_\infty \|\nabla_H u\|_2 + \left\| \delta_l \left(\int_{-h}^z \nabla_H \cdot v \; d\xi \right) \right\|_\infty \|\partial_z u\|_2 \right) \|\delta_l \Delta u\|_2$$

$$+ C(\|\nabla v\|_\infty \|\delta_l \nabla u\|_2^2 + \|\nabla^2 v\|_3 \|\delta_l \nabla u\|_2 \|\delta_l \nabla u\|_6)$$

$$\leq C\|\partial_z[(u \cdot \nabla_H)v - (\nabla_H \cdot v)u]\|_2 \|\delta_l \Delta u\|_2 + C\|\partial_z \nabla_H T\|_2 \|\delta_l \Delta u\|_2$$

$$+ \left(\|\nabla v\|_\infty \|\nabla_H u\|_2 + \left\| \partial_z \left(\int_{-h}^z \nabla_H \cdot v \; d\xi \right) \right\|_\infty \|\partial_z u\|_2 \right) \|\delta_l \Delta u\|_2$$

$$+ C(\|\nabla v\|_\infty \|\delta_l \nabla u\|_2^2 + \|\nabla^2 v\|_3 \|\delta_l \nabla u\|_2 \|\delta_l \nabla^2 u\|_2)$$

$$\leq C \left[\int_\Omega (|\nabla u|^2 |\nabla v|^2 + |u|^2 |\nabla^2 v|^2) \; d\mathbf{x} \right]^{1/2} \|\delta_l \Delta u\|_2 + C\|\nabla^2 T\|_2 \|\delta_l \Delta u\|_2$$

$$+ C(\|v\|_{H^3} \|v\|_{H^2} \|\delta_l \Delta u\|_2 + \|v\|_{H^3} \|\delta_l \nabla u\|_2^2 + \|v\|_{H^3} \|\delta_l \nabla u\|_2 \|\delta_l \nabla^2 u\|_2)$$

$$\leq C(\|\nabla v\|_\infty \|\nabla u\|_2 + \|u\|_\infty \|\nabla^2 v\|_2 + \|\nabla^2 T\|_2) \|\delta_l \Delta u\|_2$$

$$+ C(\|v\|_{H^3} \|v\|_{H^2} \|\delta_l \Delta u\|_2 + \|v\|_{H^3} \|\delta_l \nabla u\|_2^2 + \|v\|_{H^3} \|\delta_l \nabla u\|_2 \|\delta_l \nabla^2 u\|_2)$$

$$\leq C(\|v\|_{H^2} \|v\|_{H^3} + \|T\|_{H^2}) \|\delta_l \Delta u\|_2 + C(\|v\|_{H^3} \|v\|_{H^2} \|\delta_l \Delta u\|_2$$

$$+ \|v\|_{H^3} \|\delta_l \nabla u\|_2^2 + \|v\|_{H^3} \|\delta_l \nabla u\|_2 \|\delta_l \nabla^2 u\|_2)$$

$$\leq \sigma \|\delta_l \nabla^2 u\|_2^2 + C_\sigma (1 + \|v\|_{H^3}^2)(\|\delta_l \nabla u\|_2^2 + \|v\|_{H^2}^2 + \|T\|_{H^2}^2),$$

with a sufficiently small positive constant σ, and thus

$$\frac{d}{dt} \|\delta_l \nabla u\|_2^2 + \frac{1}{R} \|\delta_l \nabla^2 u\|_2^2$$
$$\leq C(1 + \|v\|_{H^3}^2)(\|\delta_l \nabla u\|_2^2 + \|v\|_{H^2}^2 + \|T\|_{H^2}^2)$$

with $R = R_1 + R_2$, from which we obtain

$$\frac{d}{dt}(t\|\delta_l \nabla u\|_2^2) + \frac{1}{R} t\|\delta_l \nabla^2 u\|_2^2$$
$$\leq C(1 + \|v\|_{H^3}^2)t(\|\delta_l \nabla u\|_2^2 + \|v\|_{H^2}^2 + \|T\|_{H^2}^2) + \|\delta_l \nabla u\|_2^2$$
$$\leq C(1 + \|v\|_{H^3}^2)t(\|\delta_l \nabla u\|_2^2 + \|v\|_{H^2}^2 + \|T\|_{H^2}^2) + C\|\partial_z \nabla u\|_2^2$$
$$\leq C(1 + \|v\|_{H^3}^2)t\|\delta_l \nabla u\|_2^2 + C(1 + \|v\|_{H^3}^2)(\|v\|_{H^2}^2 + \|T\|_{H^2}^2)(t + 1).$$

Integrating this inequality with respect to t and applying Lemma 5.1, we obtain $\sqrt{t}\partial_z u \in L^\infty(0, t_0; H^1(\Omega)) \cap L^2(0, t_0; H^2(\Omega))$ and

$$\sup_{0 \leq s \leq t} (s \|\nabla \partial_z u\|_2^2) + \int_0^t s \|\nabla^2 \partial_z u\|_2^2 \, \mathrm{d}s$$

$$\leq C e^{C \int_0^t (1 + \|v\|_{H^3}^2) \, \mathrm{d}s} \int_0^t (1 + \|v\|_{H^3}^2)(\|v\|_{H^2}^2 + \|T\|_{H^2}^2)(s + 1) \, \mathrm{d}s$$

$$\leq C e^{C(t + K_0(t))} (K_0(t)t + K_0^2(t))(t + 1),$$

and therefore

$$\sup_{0 \leq s \leq t} (s \|\partial_z u\|_{H^1}^2) + \int_0^t s \|\partial_z u\|_{H^2}^2 \, \mathrm{d}s \leq K_1'(t) \tag{5.4}$$

for all $t \in (0, t_0)$.

Set

$$f_1(x, y, z, t) = - (v \cdot \nabla_H)u + \left(\int_{-h}^z \nabla_H \cdot v(x, y, \xi, t) \, \mathrm{d}\xi \right) \partial_z u$$
$$- (u \cdot \nabla_H)v + (\nabla_H \cdot v)u - f_0 k \times u + \nabla_H T.$$

Then it follows that

$$\|\nabla f_1\|_2^2 \leq \int_\Omega \left[|v|^2 |\nabla^2 u|^2 + |\nabla v|^2 |\nabla u|^2 + \left(\int_{-h}^h |\nabla^2 v| \, \mathrm{d}\xi \right)^2 |\partial_z u|^2 \right.$$
$$\left. + \left(\int_{-h}^h |\nabla v| \, \mathrm{d}\xi \right)^2 |\nabla \partial_z u|^2 + |u|^2 |\nabla^2 v|^2 + |\nabla u|^2 + |\nabla^2 T|^2 \right] \mathrm{d}\mathbf{x}$$
$$\leq C (\|v\|_\infty^2 \|\nabla^2 u\|_2^2 + \|\nabla v\|_\infty^2 \|\nabla u\|_2^2 + \|\nabla^2 v\|_2^2 \|\partial_z u\|_\infty^2$$
$$+ \|\nabla v\|_\infty^2 \|\nabla \partial_z u\|_2 + \|u\|_\infty^2 \|\nabla^2 v\|_2^2 + \|\nabla u\|_2^2 + \|\nabla^2 T\|_2^2)$$
$$\leq C (\|v\|_{H^2}^2 \|v\|_{H^3}^2 + \|v\|_{H^2}^2 \|\partial_z u\|_{H^2}^2 + \|v\|_{H^3}^2 \|\partial_z u\|_{H^1}^2 + \|v\|_{H^2}^2 + \|T\|_{H^2}^2),$$

and thus

$$\int_0^t s \|\nabla f_1\|_2^2 \, \mathrm{d}s \leq C \int_0^t s (\|v\|_{H^2}^2 \|v\|_{H^3}^2 + \|v\|_{H^3}^2 \|\partial_z u\|_{H^1}^2$$
$$+ \|v\|_{H^2}^2 \|\partial_z u\|_{H^2}^2 + \|v\|_{H^2}^2 + \|T\|_{H^2}^2) \, \mathrm{d}s$$
$$= C \int_0^t s (\|v\|_{H^2}^2 \|v\|_{H^3}^2 + \|v\|_{H^2}^2 + \|T\|_{H^2}^2) \, \mathrm{d}s$$
$$+ C \int_0^t s (\|v\|_{H^3}^2 \|\partial_z u\|_{H^1}^2 + \|v\|_{H^2}^2 \|\partial_z u\|_{H^2}^2) \, \mathrm{d}s$$
$$\leq C t (K_0^2(t) + K_0(t)t) + C K_0(t) K_1'(t)$$
$$= C K_0(t)(K_0(t)t + K_1'(t) + t^2) =: K_1''(t). \tag{5.5}$$

Note that u satisfies equation

$$\partial_t u + L_1 u = f_1. \tag{5.6}$$

Recalling that $u \in L^2(0, t_0; H^2(\Omega))$ and $\partial_t u \in L^2(0; t_0; L^2(\Omega))$. Multiplying the above equation by $-(\delta_l^i)^* \delta_l^i \Delta u$, $i = 1, 2$, by Lemma 2.1, we obtain

$$\frac{d}{dt} \int_\Omega |\delta_l^i \nabla u|^2 \, dx \, dy \, dz + \int_\Omega \left(\frac{1}{R_1} |\delta_l^i \nabla_H \nabla u|^2 + \frac{1}{R_2} |\delta_l^i \partial_z \nabla u|^2 \right) \, dx \, dy \, dz$$
$$= - \int_\Omega \delta_l^i f_1 \delta_l^i \Delta u \leq \eta \int_\Omega |\delta_l^i \Delta u|^2 \, dx \, dy \, dz + C \int_\Omega |\delta_l^i f_1|^2 \, dx \, dy \, dz,$$

and thus

$$\frac{d}{dt} \|\delta_l^i \nabla u\|_2^2 + \frac{1}{R} \|\delta_l^i \nabla^2 u\|_2^2 \leq C \|\delta_l^i f_1\|_2^2 \leq C \|\partial_i f_1\|_2^2$$

with $R = R_1 + R_2$, from which we obtain

$$\frac{d}{dt} (t \|\delta_l^i \nabla u\|_2^2) + \frac{1}{R} t \|\delta_l^i \nabla^2 u\|_2^2 \leq C t \|\nabla f_1\|_2^2 + \|\delta_l^i \nabla u\|_2^2.$$

Integrating this inequality in t, thanks to (5.5) and applying Lemma 5.1, we then obtain

$$\sup_{0 \leq s \leq t} (s \|\nabla_H \nabla u\|_2^2) + \int_0^t s \|\nabla_H \nabla^2 u\|_2^2 \, ds$$
$$\leq C \int_0^t s \|\nabla f_1\|_2^2 \, ds + C \int_0^t s \|\nabla_H \nabla u\|_2^2 \, ds \leq C(K_0(t) + K_1''(t)).$$

Combining this with (5.4) and using (5.5), (5.6), we obtain

$$\sup_{0 \leq s \leq t} (s \|u\|_{H^2}^2) + \int_0^t s(\|u\|_{H^3}^2 + \|\partial_t u\|_{H^1}^2) \, ds \leq K_1(t) \tag{5.7}$$

for all $t \in (0, t_0)$. This completes the proof. $\quad\square$

Next, we establish the regularity properties of ζ as stated in the following proposition.

Proposition 5.2. *Let (v, T) be a strong solution to system (1.23)–(1.28) in $\Omega \times (0, t_0)$ and set $\zeta = \partial_z^2 v$. Then*

$$t\zeta \in L^\infty(0, t_0; H^2(\Omega)) \cap L^2(0, t_0; H^3(\Omega)), \quad t\partial_t \zeta \in L^2(0, t_0; H^1(\Omega))$$

and

$$\sup_{0 \leq s \leq t} (s^2 \|\zeta\|_{H^2}^2) + \int_0^t s^2 (\|\zeta\|_{H^3}^2 + \|\partial_t \zeta\|_{H^1}^2) \, ds, \leq K_2(t)$$

for any $t \in (0, t_0)$, where $K_2(t)$ is an increasing bounded function on $(0, t_0)$.

Proof. By Proposition 5.1, one can differentiate Equation (5.3) with respect to z to deduce

$$\partial_t \zeta + L_1 \zeta + f_0 k \times \zeta = \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi \right) \partial_z \zeta + \nabla_H \cdot v \partial_z u$$
$$+ \nabla_H \partial_z T - \partial_z [(v \cdot \nabla_H) u + (u \cdot \nabla_H) v - (\nabla_H \cdot v) u]. \tag{5.8}$$

Multiplying this equation by $-\delta_l^* \delta_l \Delta \zeta$, then it follows from Lemma 2.1, the Sobolev embedding inequality and the Cauchy–Schwarz inequality that

$$\frac{1}{2} \frac{d}{dt} \int_\Omega |\delta_l \nabla \zeta|^2 \, d\mathbf{x} + \int_\Omega \left(\frac{1}{R_1} |\delta_l \nabla_H \nabla \zeta|^2 + \frac{1}{R_2} |\delta_l \partial_z \nabla \zeta|^2 \right) \, d\mathbf{x}$$

$$= \int_\Omega \delta_l \{ \partial_z [(v \cdot \nabla_H) u + (u \cdot \nabla_H) v - (\nabla_H \cdot v) u] - \nabla_H \cdot v \partial_z u - \nabla_H \partial_z T \} \delta_l \Delta \zeta \, d\mathbf{x}$$

$$- \int_\Omega \delta_l \left[\left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi \right) \partial_z \zeta \right] \delta_l \Delta \zeta \, d\mathbf{x}$$

$$\leqq C \| \delta_l \partial_z [(v \cdot \nabla_H) u + (u \cdot \nabla_H) v - (\nabla_H \cdot v) u] - \delta_l (\nabla_H \cdot v \partial_z u + \nabla_H \partial_z T) \|_2 \| \delta_l \Delta \zeta \|_2$$

$$+ \int_\Omega \left[\delta_l \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi \right) \partial_z \zeta (\mathbf{x} + l e_3, t) + \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi \right) \delta_l \partial_z \zeta \right] \delta_l \Delta \zeta \, d\mathbf{x}$$

$$\leqq C \| \partial_z^2 [(v \cdot \nabla_H) u + (u \cdot \nabla_H) v - (\nabla_H \cdot v) u] - \partial_z (\nabla_H \cdot v \partial_z u + \nabla_H \partial_z T) \|_2 \| \delta_l \Delta \zeta \|_2$$

$$+ C \left(\left\| \delta_l \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi \right) \right\|_\infty \| \partial_z \zeta \|_2 + \| \nabla v \|_\infty \| \delta_l \nabla \zeta \|_2 \right) \| \delta_l \Delta \zeta \|_2$$

$$\leqq C \left[\int_\Omega (|v|^2 |\nabla^3 u|^2 + |\nabla v|^2 |\nabla^2 u|^2 + |\nabla^2 v|^2 |\nabla u|^2 + |u|^2 |\nabla^3 v|^2) \, d\mathbf{x} \right]^{1/2} \| \delta_l \Delta \zeta \|_2$$

$$+ C \left(\| \partial_z T \|_{H^2} + \left\| \partial_z \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi \right) \right\|_\infty \| u \|_{H^2} + \| v \|_{H^3} \| \delta_l \nabla \zeta \|_2 \right) \| \delta_l \Delta \zeta \|_2$$

$$\leqq C (\| v \|_\infty \| u \|_{H^3} + \| \nabla v \|_\infty \| u \|_{H^2} + \| \nabla u \|_\infty \| v \|_{H^2} + \| u \|_\infty \| v \|_{H^3}$$

$$+ \| \partial_z T \|_{H^2} + \| \nabla v \|_\infty \| u \|_{H^2} + \| v \|_{H^3} \| \delta_l \nabla \zeta \|_2) \| \delta_l \Delta \zeta \|_2$$

$$\leqq C (\| v \|_{H^2} \| u \|_{H^3} + \| u \|_{H^2} \| v \|_{H^3} + \| \partial_z T \|_{H^2} + \| v \|_{H^3} \| \delta_l \nabla \zeta \|_2) \| \delta_l \Delta \zeta \|_2$$

$$\leqq \sigma \| \delta_l \Delta \zeta \|_2^2 + C_\sigma \| v \|_{H^3}^2 \| \delta_l \nabla \zeta \|_2^2 + C_\sigma (\| u \|_{H^3}^2 \| v \|_{H^2}^2 + \| v \|_{H^3}^2 \| u \|_{H^2}^2 + \| \partial_z T \|_{H^2}^2),$$

with a sufficiently small positive constant σ, and thus

$$\frac{d}{dt} \| \delta_l \nabla \zeta \|_2^2 + \frac{1}{R} \| \delta_l \nabla^2 \zeta \|_2^2$$
$$\leqq C \| v \|_{H^3}^2 \| \delta_l \nabla \zeta \|_2^2 + C (\| u \|_{H^3}^2 \| v \|_{H^2}^2 + \| v \|_{H^3}^2 \| u \|_{H^2}^2 + \| \partial_z T \|_{H^2}^2),$$

from which it follows that

$$\frac{d}{dt} (\| \delta_l \nabla \zeta \|_2^2 t^2) + \frac{1}{R} \| \delta_l \nabla^2 \zeta \|_2^2 t^2$$
$$\leqq C \| v \|_{H^3}^2 \| \delta_l \nabla \zeta \|_2^2 t^2 + C (\| u \|_{H^3}^2 \| v \|_{H^2}^2 + \| v \|_{H^3}^2 \| u \|_{H^2}^2$$
$$+ \| \partial_z T \|_{H^2}^2) t^2 + 2t \| \delta_l \nabla \zeta \|_2^2.$$

Combining this inequality with (5.7), it follows

$$
\sup_{0 \leq s \leq t} (\|\delta_l \nabla \zeta\|_2^2 s^2) + \int_0^t s^2 \|\delta_l \nabla^2 \zeta\|_2^2 \, ds
$$

$$
\leqq Ce^{C \int_0^t \|v\|_{H^3}^2 \, ds} \int_0^t [(\|u\|_{H^3}^2 \|v\|_{H^2}^2 + \|v\|_{H^3}^2 \|u\|_{H^2}^2 + \|\partial_z T\|_{H^2}^2)s^2 + s\|\delta_l \nabla \zeta\|_2^2] \, ds
$$

$$
\leqq Ce^{C \int_0^t \|v\|_{H^3}^2 \, ds} \int_0^t [(\|u\|_{H^3}^2 \|v\|_{H^2}^2 + \|v\|_{H^3}^2 \|u\|_{H^2}^2 + \|\partial_z T\|_{H^2}^2)s^2 + s\|\partial_z^2 \nabla u\|_2^2] \, ds
$$

$$
\leqq Ce^{CK_0(t)} (t K_0(t) K_1(t) + K_0(t)t^2 + K_1(t)),
$$

which, by Lemma 5.1, implies $t^2 \partial_z \zeta \in L^\infty(0, t_0; H^1(\Omega)) \cap L^2(0, t_0; H^2(\Omega))$ and

$$
\sup_{0 \leq s \leq t} (s^2 \|\partial_z \zeta\|_{H^1}^2) + \int_0^t s^2 \|\partial_z \zeta\|_{H^2}^2 \, ds \leqq K_2'(t) \tag{5.9}
$$

for any $t \in (0, t_0)$.

Set

$$
f_2(x, y, z, t) = \left(\int_{-h}^z \nabla_H \cdot v \, d\xi \right) \partial_z \zeta + \nabla_H \cdot v \partial_z u + \nabla_H \partial_z T
$$
$$
- \partial_z[(v \cdot \nabla_H)u + (u \cdot \nabla_H)v - (\nabla_H \cdot v)u] - f_0 k \times \zeta.
$$

Then it follows that

$$
\|\nabla f_2\|_2^2 \leqq C \int_\Omega \left[\left(\int_{-h}^h |\nabla^2 v| \, d\xi \right)^2 |\partial_z \zeta|^2 + \left(\int_{-h}^h |\nabla v| \, d\xi \right)^2 |\nabla \partial_z \zeta|^2 + |\partial_z \nabla^2 T|^2 \right.
$$

$$
\left. + |v|^2 |\nabla^3 u|^2 + |\nabla v|^2 |\nabla^2 u|^2 + |\nabla^2 v|^2 |\nabla u|^2 + |u|^2 |\nabla^3 v|^2 \right] dx \, dy \, dz
$$

$$
\leqq C(\|\nabla^2 v\|_2^2 \|\partial_z \zeta\|_\infty^2 + \|\nabla v\|_\infty^2 \|\nabla \partial_z \zeta\|_2^2 + \|\partial_z T\|_{H^2}^2 + \|v\|_\infty^2 \|\nabla^3 u\|_2^2
$$

$$
+ \|\nabla v\|_\infty^2 \|\nabla^2 u\|_2^2 + \|\nabla u\|_\infty^2 \|\nabla^2 v\|_2^2 + \|u\|_\infty^2 \|\nabla^3 v\|_2^2)
$$

$$
\leqq C(\|\partial_z \zeta\|_{H^2}^2 \|v\|_{H^2}^2 + \|v\|_{H^3}^2 \|\partial_z \zeta\|_{H^2}^2 + \|\partial_z T\|_{H^2}^2
$$

$$
+ \|v\|_{H^2}^2 \|u\|_{H^3}^2 + \|v\|_{H^3}^2 \|u\|_{H^2}^2),
$$

and thus

$$
\int_0^t s^2 \|\nabla f_2\|_2^2 \, ds \leqq C \int_0^t [s^2(\|\partial_z \zeta\|_{H^2}^2 \|v\|_{H^2}^2 + \|v\|_{H^3}^2 \|\partial_z \zeta\|_{H^2}^2)
$$

$$
+ s^2(\|v\|_{H^3}^2 \|u\|_{H^2}^2 + \|u\|_{H^3}^2 \|v\|_{H^2}^2) + s^2 \|\partial_z T\|_{H^2}^2] \, ds
$$

$$
\leqq C(K_0(t) K_2'(t) + t K_0(t) K_1(t) + t^2 K_0(t))
$$

$$
= CK_0(t)(K_2'(t) + t K_1(t) + t^2) := K_2''(t). \tag{5.10}
$$

Recalling the definition of f_2, by (5.8), one can easily see that ζ satisfies

$$
\partial_t \zeta + L_1 \zeta = f_2. \tag{5.11}
$$

Multiplying Equation (5.11) by $-(\delta_l^i)^* \delta_l^i \Delta \zeta$, $i = 1, 2$, thanks to Lemma 2.1, we have

$$\frac{d}{dt} \int_\Omega |\delta_l^i \nabla \zeta|^2 \, dx \, dy \, dz + \int_\Omega \left(\frac{1}{R_1} |\delta_l^i \nabla_H \nabla \zeta|^2 + \frac{1}{R_2} |\delta_l^i \partial_z \nabla \zeta|^2 \right) dx \, dy \, dz$$

$$= -\int_\Omega \delta_l^i f_2 \delta_l^i \Delta \zeta \leqq \eta \int_\Omega |\delta_l^i \Delta \zeta|^2 \, dx \, dy \, dz + C \int_\Omega |\delta_l^i f_2|^2 \, dx \, dy \, dz,$$

and thus

$$\frac{d}{dt} \|\delta_l^i \nabla \zeta\|_2^2 + \frac{1}{R} \|\delta_l^i \nabla^2 \zeta\|_2^2 \leqq C \|\delta_l^i f_2\|_2^2 \leqq C \|\partial_i f_2\|_2^2,$$

with $R = R_1 + R_2$, from which we obtain

$$\frac{d}{dt} (t^2 \|\delta_l^i \nabla \zeta\|_2^2) + \frac{1}{R} t^2 \|\delta_l^i \nabla^2 \zeta\|_2^2 \leqq C t^2 \|\nabla f_2\|_2^2 + 2t \|\delta_l^i \nabla \zeta\|_2^2. \qquad (5.12)$$

Integrating (5.12) with respect to t, by (5.7), (5.10) and Lemma 5.1, we then obtain

$$\sup_{0 \leqq s \leqq t} (s^2 \|\nabla_H \nabla \zeta\|_2^2) + \int_0^t s^2 \|\nabla_H \nabla^2 \zeta\|_2^2 \, ds$$

$$\leqq C \int_0^t s^2 \|\nabla f_2\|_2^2 \, ds + C \int_0^t s \|\nabla^3 u\|_2^2 \, ds \leqq C(K_1(t) + K_2''(t)).$$

Combining this with (5.9) and using (5.10), (5.11), we obtain

$$\sup_{0 \leqq s \leqq t} (s^2 \|\zeta\|_{H^2}^2) + \int_0^t s^2 (\|\zeta\|_{H^3}^2 + \|\partial_t \zeta\|_{H^1}^2) \, ds \leqq K_2(t) \qquad (5.13)$$

for all $t \in (0, t_0)$. This completes the proof. □

Next we prove the regularity properties of η and θ, that is the following:

Proposition 5.3. *Let (v, T) be a strong solution to system (1.23)–(1.28) in $\Omega \times (0, t_0)$. Let η and θ be the functions given by (5.1) and (5.2), respectively. Then it holds that*

$$t\eta, t\theta \in L^\infty(0, t_0; H^2(\Omega)) \cap L^2(0, t_0; H^3(\Omega)), \quad t\partial_t \eta, t\partial_t \theta \in L^2(0, t_0; H^1(\Omega))$$

and

$$\sup_{0 \leqq s \leqq t} [s^2 (\|\eta\|_{H^2}^2 + \|\theta\|_{H^2}^2)] + \int_0^t s^2 (\|\eta\|_{H^3}^2 + \|\theta\|_{H^3}^2$$

$$+ \|\partial_t \eta\|_{H^1}^2 + \|\partial_t \theta\|_{H^1}^2) \, ds \leqq K_3(t)$$

for any $t \in (0, t_0)$, where $K_3(t)$ is a bounded increasing function on $(0, t_0)$.

Proof. One can easily check that η and θ satisfy

$$\partial_t \eta + L_1 \eta = f_3, \tag{5.14}$$
$$\partial_t \theta + L_1 \theta = f_4, \tag{5.15}$$

where

$$f_3(x, y, z, t) = -\nabla_H^{\perp} \cdot \left[(v \cdot \nabla_H) u - \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi \right) \partial_z u + (u \cdot \nabla_H) v - (\nabla_H \cdot v) u \right]$$
$$+ f_0 (R_1 T - \theta),$$

$$f_4(x, y, z, t) = -\nabla_H \cdot \left[(v \cdot \nabla_H) u - \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi y \right) \partial_z u + (u \cdot \nabla_H) v \right.$$
$$\left. - (\nabla_H \cdot v) u \right] + f_0 \eta + R_1 \left(\frac{1}{R_3} - \frac{1}{R_2} \right) \partial_z^2 T$$
$$- R_1 \left[v \cdot \nabla_H T - \left(\int_{-h}^{z} \nabla_H \cdot v \, d\xi \right) \left(\partial_z T + \frac{1}{h} \right) \right].$$

Direct calculations show

$$\|\nabla f_3\|_2^2 \leq C \int_{\Omega} \left[|v|^2 |\nabla^3 u|^2 + |\nabla v|^2 |\nabla^2 u|^2 + |\nabla^2 v|^2 |\nabla u|^2 + |u|^2 |\nabla^3 v|^2 \right.$$
$$+ \left(\int_{-h}^{h} |\nabla v| \, d\xi \right)^2 |\nabla^2 \zeta|^2 + \left(\int_{-h}^{h} |\nabla^2 v| \, d\xi \right)^2 |\nabla \zeta|^2$$
$$+ \left. \left(\int_{-h}^{h} |\nabla^3 v| \, d\xi \right)^2 |\zeta|^2 + |\nabla T|^2 + |\nabla^3 v|^2 \right] dx \, dy \, dz$$
$$\leq C (\|v\|_{\infty}^2 \|\nabla^3 u\|_2^2 + \|\nabla v\|_{\infty}^2 \|\nabla^2 u\|_2^2 + \|u\|_{\infty}^2 \|\nabla^3 v\|_2^2$$
$$+ \|\nabla v\|_{\infty} \|\nabla^2 \zeta\|_2^2 + \|\nabla^2 v\|_2^2 \|\nabla \zeta\|_{\infty}^2 + \|\nabla^3 v\|_2^2 \|\zeta\|_{\infty}^2$$
$$+ \|\nabla^2 v\|_2^2 \|\nabla u\|_{\infty}^2 + \|\nabla T\|_2^2 + \|\nabla^3 v\|_2^2)$$
$$\leq C (\|v\|_{H^2}^2 \|u\|_{H^3}^2 + \|v\|_{H^3}^2 \|u\|_{H^2}^2 + \|v\|_{H^2}^2 \|\zeta\|_{H^3}^2$$
$$+ \|v\|_{H^3}^2 \|\zeta\|_{H^2}^2 + \|T\|_{H^2}^2 + \|v\|_{H^3}^2),$$

and

$$\|\nabla f_4\|_2^2 \leq C \int_{\Omega} \left[|v|^2 |\nabla^3 u|^2 + |\nabla v|^2 |\nabla^2 u|^2 + |\nabla^2 v|^2 |\nabla u|^2 + |u|^2 |\nabla^3 v|^2 \right.$$
$$+ \left(\int_{-h}^{h} |\nabla v| \, d\xi \right)^2 |\nabla^2 \zeta|^2 + \left(\int_{-h}^{h} |\nabla^2 v| \, d\xi \right)^2 |\nabla \zeta|^2$$
$$+ \left(\int_{-h}^{h} |\nabla^3 v| \, d\xi \right)^2 |\zeta|^2 + |\nabla^3 v|^2 + |\nabla \partial_z^2 T|^2 + |\nabla v|^2 |\nabla T|^2 + |v|^2 |\nabla^2 T|^2$$
$$+ \left. \left(\int_{-h}^{h} |\nabla^2 v| \, d\xi \right)^2 (|\partial_z T|^2 + 1) + \left(\int_{-h}^{h} |\nabla v| \, d\xi \right)^2 |\nabla \partial_z T|^2 \right] dx \, dy \, dz$$

$$
\begin{aligned}
\leq & C(\|v\|_{H^2}^2 \|u\|_{H^3}^2 + \|v\|_{H^3}^2 \|u\|_{H^2}^2 + \|v\|_{H^2}^2 \|\zeta\|_{H^3}^2 + \|v\|_{H^3}^2 \|\zeta\|_{H^2}^2 \\
& + \|v\|_{H^3}^2 + \|\partial_z T\|_{H^2}^2 + \|\nabla v\|_\infty^2 \|\nabla T\|_2^2 + \|v\|_\infty^2 \|\nabla^2 T\|_2^2 \\
& + \|\partial_z T\|_\infty^2 \|\nabla^2 v\|_2^2 + \|\nabla v\|_\infty^2 \|\nabla^2 T\|_2^2) \\
\leq & C(\|v\|_{H^2}^2 \|u\|_{H^3}^2 + \|v\|_{H^3}^2 \|u\|_{H^2}^2 + \|v\|_{H^2}^2 \|\zeta\|_{H^3}^2 + \|v\|_{H^3}^2 \|\zeta\|_{H^2}^2 \\
& + \|v\|_{H^3}^2 + \|\partial_z T\|_{H^2}^2 + \|v\|_{H^3}^2 \|T\|_{H^2}^2 + \|v\|_{H^2}^2 \|\partial_z T\|_{H^2}^2) \\
\leq & C(\|v\|_{H^2}^2 \|u\|_{H^3}^2 + \|v\|_{H^3}^2 \|u\|_{H^2}^2 + \|v\|_{H^2}^2 \|\zeta\|_{H^3}^2 + \|v\|_{H^3}^2 \|\zeta\|_{H^2}^2) \\
& + C(\|\partial_z T\|_{H^2}^2 + \|v\|_{H^3}^2)(1 + \|v\|_{H^2}^2 + \|T\|_{H^2}^2).
\end{aligned}
$$

By the aid of (5.7) and (5.13), it follows from the above two inequalities that

$$
\begin{aligned}
\int_0^t s^2 \|\nabla f_3\|_2^2 \, ds \leq & C \int_0^t s^2 (\|v\|_{H^2}^2 \|u\|_{H^3}^2 + \|v\|_{H^3}^2 \|u\|_{H^2}^2 + \|v\|_{H^2}^2 \|\zeta\|_{H^3}^2 \\
& + \|v\|_{H^3}^2 \|\zeta\|_{H^2}^2 + \|T\|_{H^2}^2 + \|v\|_{H^3}^2) \, ds \\
\leq & C K_0(t)(t K_1(t) + K_2(t) + t^3 + t^2) =: K_3'(t)
\end{aligned}
$$

and

$$
\begin{aligned}
\int_0^t s^2 \|\nabla f_4\|_2^2 \, ds \leq & C \int_0^t s^2 [(\|v\|_{H^2}^2 \|u\|_{H^3}^2 + \|v\|_{H^3}^2 \|u\|_{H^2}^2 + \|v\|_{H^2}^2 \|\zeta\|_{H^3}^2 \\
& + \|v\|_{H^3}^2 \|\zeta\|_{H^2}^2) + (\|\partial_z T\|_{H^2}^2 + \|v\|_{H^3}^2)(1 + \|v\|_{H^2}^2 + \|T\|_{H^2}^2)] \, ds \\
\leq & C K_0(t)(K_2(t) + t K_1(t) + K_0(t)t^2 + t^2) =: K_3''(t).
\end{aligned}
$$

Using the above two inequalities, multiplying (5.14) and (5.15) by $-(\delta_l^i)^* \delta_l^i \Delta \eta$ and $-(\delta_l^i)^* \delta_l^i \Delta \theta$, $i = 1, 2, 3$, respectively, and summing the resulting equations up, then using a similar argument as for (5.12) leads to

$$
\begin{aligned}
\frac{d}{dt} & [t^2 (\|\delta_l^i \nabla \eta\|_2^2 + \|\delta_l^i \nabla \theta\|_2^2)] + \frac{1}{R} t^2 (\|\delta_l^i \nabla^2 \eta\|_2^2 + \|\delta_l^i \nabla^2 \theta\|_2^2) \\
& \leq C t^2 (\|\nabla f_3\|_2^2 + \|\nabla f_4\|_2^2) + 2t (\|\delta_l^i \nabla \eta\|_2^2 + \|\delta_l^i \nabla \theta\|_2^2) \\
& \leq C t^2 (\|\nabla f_3\|_2^2 + \|\nabla f_4\|_2^2) + C t (\|\nabla^2 \eta\|_2^2 + \|\nabla^2 \theta\|_2^2) \\
& \leq C t^2 (\|\nabla f_3\|_2^2 + \|\nabla f_4\|_2^2) + C t (\|u\|_{H^3}^2 + \|T\|_{H^2}^2).
\end{aligned}
$$

Integrating this inequality with respect to t and applying Lemma 5.1, then it follows from (5.7) and the estimates on f_3, f_4 that

$$
\begin{aligned}
\sup_{0 \leq s \leq t} & [s^2 (\|\nabla^2 \eta\|_2^2 + \|\nabla^2 \theta\|_2^2)] + \int_0^t s^2 (\|\nabla^3 \eta\|_2^2 + \|\nabla^3 \theta\|_2^2) \, ds \\
& \leq C(K_3'(t) + K_3''(t) + t^2 K_0(t) + K_1(t)).
\end{aligned}
$$

By the aid of this inequality and using the estimates for f_3, f_4, Equations (5.14) and (5.15), we obtain

$$\sup_{0 \leqq s \leqq t} [s^2(\|\eta\|_{H^2}^2 + \|\theta\|_{H^2}^2)] + \int_0^t s^2(\|\eta\|_{H^3}^2 + \|\theta\|_{H^3}^2 + \|\partial_t \eta\|_{H^1}^2$$

$$+ \|\partial_t \theta\|_{H^1}^2) \, ds \leqq K_3(t)$$

for any $t \in (0, t_0)$. This completes the proof. □

Finally, we consider the regularity properties of $\bar{v}$.

Proposition 5.4. *Let* (v, T) *be a strong solution to system* (1.23)–(1.28) *in* $\Omega \times (0, t_0)$. *Let* $\bar{v}$ *be the vertical average of* v *as it was defined in the Introduction. Then*

$$\sqrt{t}\bar{v} \in L^\infty(0, t_0; H^3(\Omega)) \cap L^2(0, t_0; H^4(\Omega)), \quad \sqrt{t}\partial_t \bar{v} \in L^2(0, t_0; H^2(\Omega)),$$

and

$$\sup_{0 \leqq s \leqq t} (s\|\bar{v}\|_{H^3}^2) + \int_0^t s(\|\bar{v}\|_{H^4}^2 + \|\partial_t \bar{v}\|_{H^2}^2) \, ds \leqq K_4(t),$$

for any $t \in (0, t_0)$, *where* $K_4(t)$ *is a bounded increasing function on* $(0, t_0)$.

Proof. By Equation (1.29) and (1.30), $\bar{v}$ satisfies

$$\partial_t \bar{v} - \tfrac{1}{R_1}\Delta_H \bar{v} + \nabla_H \bar{p}(x, y, t) = f_5, \tag{5.16}$$
$$\nabla_H \cdot \bar{v} = 0, \tag{5.17}$$

where

$$\bar{p}(x, y, t) = p_s(x, y, t) - \frac{1}{2h} \int_{-h}^h \int_{-h}^z T(x, y, \xi, t) \, d\xi \, dz,$$
$$f_5(x, y, t) = -(\bar{v} \cdot \nabla_H)\bar{v} - \overline{(\tilde{v} \cdot \nabla_H)\tilde{v} + (\nabla_H \cdot \tilde{v})\tilde{v}} - f_0 k \times \bar{v}.$$

It follows from the Sobolev embedding inequality that

$$\|\nabla_H^2 f_5\|_2^2 \leqq \int_M |\nabla_H^2[(\bar{v} \cdot \nabla_H)\bar{v} + \overline{(\tilde{v} \cdot \nabla_H)\tilde{v} + (\nabla_H \cdot \tilde{v})\tilde{v}} + f_0 k \times \bar{v}]|^2 \, dx \, dy$$

$$\leqq C \int_M \left[\left| \nabla_H^2 \left(\overline{(\tilde{v} \cdot \nabla_H)\tilde{v} + (\nabla_H \cdot \tilde{v})\tilde{v}} \right) \right|^2 + |\bar{v}|^2|\nabla_H^3 \bar{v}|^2 \right.$$

$$\left. + |\nabla_H \bar{v}|^2|\nabla_H^2 \bar{v}|^2 + |\nabla_H^2 \bar{v}|^2 \right] dx \, dy$$

$$\leqq \int_M \left[\left(\int_{-h}^h (|\tilde{v}||\nabla_H^3 \tilde{v}| + |\nabla_H \tilde{v}||\nabla_H^2 \tilde{v}|) \, d\xi \right)^2 \right.$$

$$\left. + |\bar{v}|^2|\nabla_H^3 \bar{v}|^2 + |\nabla_H \bar{v}|^2|\nabla_H^2 \bar{v}|^2 + |\nabla_H^2 \bar{v}|^2 \right] dx \, dy$$

$$\leqq C(\|\bar{v}\|_\infty^2\|\nabla_H^3 \bar{v}\|_2^2 + \|\nabla_H \bar{v}\|_\infty^2\|\nabla_H^2 \bar{v}\|_2^2 + \|\tilde{v}\|_\infty^2\|\nabla_H^3 \tilde{v}\|_2^2$$

$$+ \|\nabla_H \tilde{v}\|_\infty^2\|\nabla_H^2 \tilde{v}\|_2^2 + \|\nabla_H^2 \bar{v}\|_2^2)$$

$$\leqq C(\|v\|_{H^3}^2\|v\|_{H^2}^2 + \|v\|_{H^2}^2).$$

Note that $\bar{v} \in L^2(0, t_0; H^3(M))$ and $\partial_t \bar{v} \in L^2(0, t_0; H^1(M))$. Applying the operator ∇_H to Equation (5.16), multiplying the resulting equation by $-(\delta_l^i)^* \delta_l^i \nabla_H \Delta_H \bar{v}$, $i = 1, 2$ and using (5.17), then a similar argument to that for (5.12) leads to

$$\frac{\mathrm{d}}{\mathrm{d}t}(t\|\delta_l^i \Delta_H \bar{v}\|_2^2) + \frac{1}{R_1} t\|\delta_l^i \nabla_H \Delta_H \bar{v}\|_2^2$$
$$\leqq Ct\|\nabla_H^2 f_5\|_2^2 + \|\delta_l^i \Delta_H \bar{v}\|_2^2 \leqq C(t\|\nabla_H^2 f_5\|_2^2 + \|\nabla_H \Delta_H \bar{v}\|_2^2).$$

Integrating this inequality with respect to t and applying Lemma 5.1, then one has

$$\sup_{0 \leqq s \leqq t}(s\|\nabla_H \Delta_H \bar{v}\|_2^2) + \int_0^t s\|\nabla_H^2 \Delta_H \bar{v}\|_2^2 \, \mathrm{d}s$$
$$\leqq C\int_0^t (s\|\nabla_H^2 f_5\|_2^2 + \|\bar{v}\|_{H^3}^2) \, \mathrm{d}s \leqq CK_0(t)(K_0(t)t + t^2 + 1).$$

By the aid of this inequality, applying the L^2 theory of Stokes equations and using the estimate on f_5, we obtain

$$\sup_{0 \leqq s \leqq t}(s\|\bar{v}\|_{H^3}^2) + \int_0^t s(\|\bar{v}\|_{H^4}^2 + \|\partial_t \bar{v}\|_{H^2}^2) \, \mathrm{d}s \leqq K_4(t)$$

for any $t \in (0, t_0)$. This completes the proof. $\quad\square$

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