ORIGINAL ARTICLE

The quantitative evaluation of the cutting surface quality levels in abrasive water jet cutting by measurement of the representative striation mark displacement

Martin Brandstätter1 · Andreas Wöhrle1 · Michael Kaufeld2,4 · Frank Pude3,4 · Akash Nag5 · Sergej Hloch[6](http://orcid.org/0000-0003-4066-0620)

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Abstract

Non-thermally afected surfaces created by abrasive water jet, among many other advantages, are manufactured with geometric inaccuracies. These geometric inaccuracies are mainly related to waviness, especially in the lower parts of thick engineering components. Therefore, the study establishes a link between the surface quality and abrasive water jet material disintegration parameters related to striation mark displacement. The materials used for the experiments (aluminum, steel, and polyethylene plastic) are selected to cover a wide range of hardness values. These materials are often machined, which enables to draw practical reference values from the results obtained. Experiments are used for determination of the surface quality to assign a range of surface roughness profile parameters R_z and R_a , as soon as no clear striation marks are recordable on the surface for particular materials with specifc mechanical properties.

Keywords Abrasive water jet · Surface quality · Striation mark displacement · Surface roughness · Surface waviness · Design of experiment

Abbreviations

- m_a ^{α} Abrasive flow rate (g/s)
- *u* Angle defect (-)
- R_a Average roughness value (μ m)
- *h_c* Critical depth (mm)
- v_c Cutting speed (mm/s)
- *t* Cutting thickness (mm)
- *λ_c* Cutoff wavelength (mm)
- *h* Depth of cut (mm)
- ρ Density (kg/m³)
- r_k Edge radius (mm)

 \boxtimes Sergej Hloch sergej.hloch@tuke.sk

- Faculty of Mechanical Engineering and Vehicle Engineering, Ulm University of Applied Sciences, Ulm, Germany
- ² Faculty of Mechatronics and Medical Engineering, Ulm University of Applied Sciences, Ulm, Germany
- ³ Inspire AG, ETH Zurich, Zurich, Switzerland
- ⁴ Steinbeis Consulting Center High-Pressure Waterjet Technology, Horgau, Germany
- ⁵ Indian Institute of Technology, Dhanbad, India
- ⁶ Faculty of Manufacturing Technologies, TUKE With a Seat in Prešov, Prešov, Slovakia
- h_f Fine cut length (mm) *df* Focusing tube inner diameter (mm) *f* Groove width (mm) s_b Jet influenced zone (mm) *λs* Lower wavelength flter (µm) *Nm* Machinability (-) *N_m* Machinability number (-) R_z Maximum roughness (μ m)
W_z Maximum waviness (μ m) W_z Maximum waviness (μ m)
RSm Mean width of roughness Mean width of roughness profile (mm) *d* Nozzle diameter (mm) *pw* Pressure (MPa) *Q* Quality level (-) *g* Ridge (mm) h_r Remaining length (mm)
 R_h Rockwell hardness (HR) *Rb* Rockwell hardness (HRBW) z Standoff distance (mm) *n* Striation mark displacement (mm) *l_r* Single measuring distance (mm) *ln* Total measuring distance (mm) *s* Water side entry (-) m_w^{\dagger} Water flow rate (l/min) v_w Waterjet velocity (mm/s) AWJ Abrasive water jet DoE Design of experiment

1 Introduction

One of the few tools with the specifc properties necessary for engineering material development is the abrasive water jet (AWJ) [\[1\]](#page-16-0). AWJ is considered one of the most advanced unconventional manufacturing technological procedures [[2\]](#page-16-1). In recent years, this technology has become an increasingly competitive tool due to its suitability in diverse applications $[3-7]$ $[3-7]$ $[3-7]$; that is, owing to its ability to manufacture component parts out of hard-tomachine materials in any direction, and to the absence of a heat-afected zone or heat deformation with minimum environmental impact [\[8,](#page-16-4) [9\]](#page-16-5). With the parallel improvement of the pumps [\[10\]](#page-16-6), waterjet cutting has become one of the most powerful cutting methods ever used, with an industrial standard water pressure of $p = 600$ MPa and a cutting capacity of up to 300-mm thickness for softer materials [\[11\]](#page-16-7). Nevertheless, this process has remained a rather rare phenomenon for special applications compared to conventional machining and manufacturing [[12](#page-16-8)]. The limitation of a high-speed AWJ is unevenness in the form of striations and roughness [[13](#page-16-9)] generated during the material disintegration caused by many factors [\[9](#page-16-5), [14](#page-16-10)]. The causes of surface defects limit a broader utilization of the technology of high-speed AWJs in industry [[15](#page-17-0)]. For this reason, and because of the fundamental diversity of editable materials, there is no universal model for AWJ cutting [[16\]](#page-17-1). The most common description of the surface is based on the fve quality (*Q*) levels [[17\]](#page-17-2). There are no clear defnitions that relate these *Q* levels to surface quality and striation mark displacement. In terms of practical applications, the worker should be able to produce a (clearly) required surface and verify it with simple means. The idea is to determine the most easily measurable surface characteristic, the striation mark displacement, and then be able to draw conclusions about the roughness, waviness, and *Q* level from it [[18](#page-17-3)]. Hashish frst explained the processes and interactions between the abrasive particles and the material in [[19](#page-17-4)], followed by many other authors [\[20–](#page-17-5)[24](#page-17-6)]. Kulekci [\[20\]](#page-17-5) studied the infuence of water pressure, grain size, and traverse speed on surface roughness and depth of cut. Hlavac [[21\]](#page-17-7) developed theoretical model to calculate the tilt angle of the cutting head enabling the jet to follow trajectory approximately normal to the material surface during its exit after material cutting. Hreha et al. [[22](#page-17-8)] investigated the vibration frequency emission during impact of abrasive particle with the material [[25\]](#page-17-9). It was concluded that the monitoring of the vibration signals can be used as feedback mechanism for online process control. Lemma et al. [[23](#page-17-10)] studied the interlink between the twophase cyclic material removal mechanism and striation formation. Perec et al. [\[24](#page-17-6), [26](#page-17-11)] also studied the infuence of basic cutting parameters such as traverse speed, abrasive type, and mass fow rate of abrasive on cutting depth while cutting titanium samples. In order to illustrate and better understand the processes of AWJ cutting, the author in $[19]$ $[19]$ carried out cutting experiments with acrylic glass and flmed them. Calculations were based on the energy of the abrasive particles. More specifcally, the forces and moments of a particle were determined, and the volume removal was determined by means of the resistance forces. From this preliminary work and some other considerations, the author developed a model by which the cutting depth can be determined. In summary, the following fndings can be mentioned. The illustration (Fig. [1\)](#page-1-0) of the cutting process in the acrylic glass

Fig. 1 (**a**) Cutting and deformation mechanisms of wear as designed by Hashish; (**b**) three stages in the cutting process: E1—input stage, E2 stabilized cutting, E3—output stage. (*h*—depth of cut) From [[19](#page-17-4)] (redrawn)

Table
levels

test shows that there are two essential phases of material disintegration. During the frst phase, the particles hit the surface at a small angle and grind off the material. In the second phase, larger parts are broken from the material as the abrasive particles hit at a steeper angle. According to Hashish, the disintegration process consists of three stages: the input stage, material cutting stage, and output stage. In the cutting zone, material removal is performed by abrasive particles under shallow angles, while in the deformation zone high angles are apparent (Fig. [1](#page-1-0)b). The erosive process occurs in a cyclic way, with stable material removal until critical depth h_c . Below critical depth h_c , the process of material removal is uneven, causing the formation of striae and waviness of the surface, as per Hashish. A change in the material removal mechanism below the critical depth causes waviness of the cutting material surface. The water in the AWJ serves almost exclusively as a carrier medium, which accelerates the abrasive particles. However, the infuence of particle size and properties is not apparent from this publication [[3](#page-16-2)].

Chao et al. [[27](#page-17-12)] studied the connection of striation formation and two-phase cyclic material removal similar to experiments conducted by Hashish [[19](#page-17-4)], proving the cyclic character of the cutting process. Contrary to Hashish, who determined an exact boundary and distance between two removal mechanisms, the result of which is two diferent types of surface profles, their fndings showed that the formation commenced in the proximity of the surface (Fig. [1\)](#page-1-0). This fact indicated the singularity of the material removal mechanism $[23]$ $[23]$ $[23]$. They found that the striae begin in the segment on the material surface, unlike the smooth zone considered by Hashish. Lemma et al. [[23\]](#page-17-10) investigated mechanisms such as the kinetic energy of abrasive particles and equipment vibrations as causes of unevenness and striation formation. The designed models of striation formation mechanisms in some cases do

not provide an explanation of the erosive entity of AWJ, whereas other models are fundamentally diferent. Using the model studies summarized by Hashish, Zeng and Kim [[28\]](#page-17-13) first investigated the behavior of the abrasive particles during the cutting process and determined the material removal of a single particle. Thus, a frst equation was developed, which estimates the cutting depth depending on the cutting speed v_c , the nozzle diameter *d*, and the abrasive mass flow \dot{m}_a (Eq. [1](#page-2-0)).

[[28](#page-17-13)]

$$
v_c = \left(\frac{N_m * p_w^{1.25} * m_w^{0.687} * m_a^{0.343}}{8800 * Q * h * d^{0.618}}\right)^{1.15} \text{[mm/s]}
$$
(1)

where, N_m is the machinability number, p_w is water pressure, m_w is water flow rate. Experiments with various materials and works by other authors have confrmed that the model can be used for all common materials. In order to achieve better practicality and applicability, an equation has been developed from this preparatory work in which the weighting of the individual parameters is carried out by exponents. To determine these exponents, Zeng again carried out a large number of cutting tests with various materials. The values were determined by means of a regression analysis. It was also Zeng who introduced the processing number N_m as a material-specifc quantity to classify the material specifcally for the AWJ [\[28](#page-17-13)]. The defnition of quality levels by Zeng is given in Table [1](#page-2-1), with examples of the section surfaces in Fig. [2](#page-2-2). The user-friendly formula with which the cutting speed can be determined (hereinafter called the Zeng formula) is given as Eq. ([1](#page-2-0)). The parameters nozzle distance, abrasive grain diameter, and abrasive type have no infuence on this formula. However, the abrasive type is an important aspect that may have a major infuence on the cutting depth and thus on the fnal cutting speed. This is not explained in more detail by the author [\[28\]](#page-17-13), but the infuence of the

Fig. 2 Samples of the fve quality levels [[12](#page-16-8)]

abrasive on the cutting depth is understandable. Round grains, for example, form blunt edges, whereas angular or harder grains remain sharper for longer. Zeng describes the determination of a correction factor, which must be determined individually for each abrasive material pairing.

The Swiss standard 214,001 "Berührungsloses Trennen-Wasserstrahlschneiden-Geometrische Produktspezifkation und Qualität" defnes the surface characteristics typical for AWJ such as cutting angle defects (u) , edge radius (r_k) , ridge (*g*), groove width (*f*), striation mark displacement (*n*), and dimensional and quality tolerances (Fig. [3\)](#page-3-0).

The roughness of the cutting surface is mainly infuenced by the cutting speed, material type, and thickness, and to a lesser extent by the cutting medium and process control. According to the roughness defnition used here, it can be assumed that the waviness is also partially involved in the roughness. The roughness value R_a is thus a mixed value composed of two diferent values, which cannot be exactly diferentiated. The frst size is the basic roughness (microscopic) and is infuenced exclusively by the abrasive grain size. This form of surface fnish can also be found in sand blasting, where the material removal takes place in the same way as in the AWJ. The second size is the macroscopic waviness [\[2](#page-16-1)]. Unfortunately, no classifcation takes place with regard to the type of surface view, i.e., how the roughness determination has to be carried out (periodic or aperiodic profle, determination of the profle flters). Table [2](#page-4-0) lists the fve *Q* levels according to the standard, including a sample image.

Miles and Henning [[29](#page-17-14)] took a closer look at the type of surface measurement. They used the relationship between surface quality and cutting depth created by Zeng. The Zeng formula provides a connection between otherwise constant setting parameters in that the cutting depth is an inverse function of the surface quality defned by the *Q* levels. Therefore, the present study acknowledges the problem of the subjectivity of the *Q* levels and develops a method for standard measurement of the surface with proflometers.

Until now, there has been no method developed for the completely clear determination of the surface quality for AWJ surfaces. The quality levels are partly diferent from each other and insufficiently defined. In all the sources listed above, at least quantitatively, no distinction is made between roughness and waviness. According to the standards DIN EN ISO 4287 and DIN EN ISO 4288 of the surface assessment, the measurements of roughness made in the sources, in which the waviness is incorporated or at least not clearly delimited between the sizes, are prohibited for determination of the surface quality. In addition, all publications lack information about the profle flters and the type of surface, because AWJ-typical surfaces can be viewed either periodically or aperiodically. Therefore, a discussion must take place about a new approach for the better determination of the surface quality by means of striation mark displacement (*n*), roughness (*R*), and waviness (*W*).

Fig. 3 Description of dimensions at the AWJ cutting surface in SN 214,001 [\[2\]](#page-16-1), where *g*=ridge, *hf*=fne cut length, hr =remaining length, r_k =edge radius, sb = jet-influenced zone, t =cutting thickness, u =cutting angle error, *f*=width of striation marks, *n*=striation mark displacement, *s*=water jet entry side

Table 2 Defnition of quality levels in [\[2](#page-16-1)]

The aim of this work is, therefore, frst to extend and concretize the defnition of the *Q* levels in connection with the quantitative determination of the striation mark displacement. By linking these two variables, good applicability and practicality could be achieved. The fnal goal is thus a quantitative determination of the surface quality without tactile or optical measurements, but purely with the length measurement of the striation mark displacement *n* (Fig. [3](#page-3-0)). This measurement can be carried out very quickly with a vernier caliper and is therefore particularly user-friendly during setup or quality control during ongoing operations of the AWJ system. It should be noted that the initial zone is neglected in this study for practical reasons [\[30](#page-17-15)].

2 Materials and methods

2.1 Materials

The aim of the selection of sample materials for the current study was to select three materials with diferent hardness values, which together cover the entire range of materials generally used. In addition, these represent materials that are often machined, so that it can be determine practical reference values from the results obtained. For this reason, the following three materials were used: alloyed tempered steel (50CrMo4 ISO-No: 1.7228), an aluminum alloy (EN AW-5183A), and a polyethylene plastic material (PE-LD

(Trade name Dyneema)). This preselection was helped by a list of different materials and their N_m values, which can be seen in Fig. [4](#page-6-0). This presentation enabled an initial estimation of the processing number N_m of the selected test materials. The next step was to determine the true value.

In order to make statements about as many materials and cutting parameters as possible with as few test cuts as possible, the "design of experiments" (DoE) method was used to plan the practical series of runs. The processing characteristics referred to in the following section as "free variable parameters" were combined in a full factorial design in the combination of the four factors (water pressure, machinability number (N_m) , abrasive mass fow rate, and quality level) on three levels, with $3⁴=81$ test runs. The experimental cuts were carried out with the water jet system of the University of Applied Sciences Ulm (Fig. [5](#page-7-0)). For pressure generation, a highpressure amplifer (BYPUMP 50APC), was used, with which a maximum working pressure of 400 MPa is possible at a flow rate of 5 l/min. The maximum working area was $1000 \times 1000 \times 400$ mm. An abrasive mixer from the Swiss company Allfi was installed for the feeding of the abrasive-type GMA ClassicCutTM 80 (Mesh 80) [[26\]](#page-17-11). A nozzle with inner diameter $d = 0.28$ mm was used. The diameter of the focusing tube was $d_f = 0.8$ mm. The standoff distance between the focusing tube and the workpiece was $z = 1$ mm for all cuts. This value has its background in practical applications. A larger distance would lead to a widening of the jet and thus a loss of power density. A smaller distance could cause a collision between the workpiece and nozzle in the event of unevenness of the workpiece support. A sample thickness $b = 15$ mm was kept for all test cuts and for all materials. This facilitated the production of test pieces as well as their evaluation, since the measuring distance for the evaluation of the surface quality was parallel to the workpiece outer edge.

In [[8,](#page-16-4) [32\]](#page-17-16), the infuence of the abrasive type is measured on the cutting depth and thus on the cutting speed with a correction factor. Just like N_m , this goes into the Zeng formula without any infuence. In this experimental work, the same abrasive material of type GMA ClassicCutTM 80 (Mesh 80) was used. The factor is neglected throughout the work, as under these conditions it only scales the results but has no change in efect related to the materials. The abrasive mass fow rate was adjusted at three levels: 290, 460, and 570 g/ min. These values were obtained from the results of the abrasive calibration with 60%, 70%, and 80% of the motor current, as shown in Fig. [6.](#page-7-1) This covers the usual abrasive quantities in the application.

Since the calculations of traverse speed v_c are based on Zeng's predictive model, the quality level values must be used as variable parameters in this model. The quality levels stipulated by Zeng cover the usual surface qualities for AWJ cutting. The predictive model of this work is intended to cover also the quality range as of Zeng's model, which is why quality levels 5, 3, and 1.2 were tested in the test sections. The dependent variable parameters have a formula-direct dependence on the sizes of the freely variable parameters to be selected. The cutting speed v_c is calculated according to Zeng's feed forecast and depends on the variable values inserted in Eq. [\(1](#page-2-0)). The selected nozzle diameter and water pressure determine the water mass fow after taking into account the physical bases with reference to the water density Eq. [\(2](#page-5-0)) sets out the context:

[[33\]](#page-17-17)

$$
\dot{m}_w = v_w * d^2 * \frac{\pi}{4} * \rho_n \quad [{}^{kg}/_s]
$$
 (2)

A value of 1003 kg/ $m³$ is assumed to be the normal density of the water. The velocity of the free water jet v_w is determined by the Bernoulli equation:

[[33\]](#page-17-17)

$$
v_w = \sqrt{\frac{2 \ * \ p_w}{\rho_{p_w}}} \quad [m /_{s}] \tag{3}
$$

In this case, the pressure dependence of the density must be considered because of the high working pressure. For 250–500 MPa, i.e., 2500–5000 bar, the following equation applies:

[[34](#page-17-18)]

$$
\rho_w(p_w) = -p_w^2 * 10^{-6} + 0.0364 * p_w + 1003 \left[\frac{kg}{m^3}\right] p_w inbar
$$
\n(4)

To determine the processing number N_m , one must estimate the hardness via Eq. (5) (5) (5) :

[[31](#page-17-19)]

$$
N_m = \left(\frac{1077}{R_b}\right)^{1.44} \tag{5}
$$

The correlation between the Rockwell hardness *B* and the workability number is used here. Unfortunately, Zeng does not indicate the test requirements or a standard, so for this work the standard Rockwell hardness *HRBW* with tungsten carbide ball (1.5875-mm diameter) was assumed as the push-in body [[35\]](#page-17-20). According to Zeng, this correlation applies only to metals and is based on the similarity between the materials [[12\]](#page-16-8). Experimentally, the above method of determination was also extended to the polyethylene plastic in this work. The hardness measurements were carried out on a ZwickRoell universal hardness tester ZHU250 top (ZwickRoell Pvt. Ltd. CIPET Industrial Estate, Chennai, India). At the time of the test, there was no possibility of determining the hardness in *HRBW,* so the Brinell hardness *HB* was used for the determination.

Fig. 4 List of materials and their machinability [\[31\]](#page-17-19)

Fig. 5 Experimental setup: (**a**) a cutting head, (**b**) stainless steel 50CrMo4—308 HRBW, (**c**) aluminum alloy EN AW-5183A—77.4 HRBW, (**d**) polyethylene plastic—97.5 HRBW

A tungsten carbide ball with a diameter of 2.5 mm was used as the test specimen, and the ball calotte was evaluated after [\[36\]](#page-17-21). The measured values were revalued after [[37](#page-17-22)]. For the tempered steel, after interpolation, a value of 108 HB was determined, with a value of 34 HB for the aluminum. For aluminum, the result is critical, because the validity of the revalued table has a wide range and it could not be clarifed whether the aluminum used here fell within this range. The calculation of the machinability number results in values of $N_m = 27$ for steel and $N_m = 147$ for aluminum. No value can be determined for polyethylene plastics, since the measured shore hardness cannot be converted into a Rockwell hardness due to the diference in the materials. For this reason, the determination of N_m for polyethylene plastics is not possible and must therefore be performed diferently. The second investigation procedure, which does not require a reference material with known machinability, is based on the following idea. The Zeng formula (Eq. ([1](#page-2-0))) is converted to N_m resulting in the following connection:

$$
N_m = \frac{8800 * h * d^{0.618} * v_c^{0.866} * Q}{p_w^{1.25} * m_w^{0.687} * m_a^{0.343}} \quad [-1. \tag{6}
$$

Choosing values based on experience or appropriate tables, we frst selected a cutting speed. The quality level *Q* was set to 1.2 to obtain a safe cut (Table [1\)](#page-2-1). With this setting, a wedge-shaped workpiece was cut, which consisted of the material to be determined. The maximum penetration height in the test wedge now represented the missing size h for N_m determination and was measured. For the materials used in these tests, the results were, for steel, $N_m = 21.8$; for aluminum, $N_m = 60.5$; and for polyethylene plastic, $N_m = 100.1$. These values were then used for testing and evaluation.

2.2 Measurement

The measurement of the surface characteristics in the cutting surface was carried out with a contour- and roughnessmeasuring device (Zeiss Surfcom 1900SD). The surface roughness profile parameters R_z and R_a were determined in accordance with DIN EN ISO 4287 [[38](#page-17-23)] and DIN EN ISO 4288 [[39\]](#page-17-24). R_z is sum of maximum peak height and valley depth within the evaluation length. By measuring the *RSm* value at the cutting outlet of an exemplary sample, the boundary wavelength of λ_c was first determined to be 2.5 mm. This resulted in a single measuring distance *lr* of 2.5 mm and a measuring distance l_n of 12.5 mm, based on [\[39\]](#page-17-24). The lower wavelength was set by the filter λ_s to 8 μ m. After checking the recorded primary profle curve and the roughness curve after fltering with the above flter values, a clear representation of the ripple in the roughness profle showed that a signifcant proportion of the ripple was still included in the roughness value. For this reason, the flter *λc* was subsequently reduced to 0.25 mm for all samples until no ripple was visible. Only in this way could a clear separation be made between roughness and ripple. *W_z* was determined as the maximum depth of waviness within the evaluation length according to DIN EN ISO 4288 [[39](#page-17-24)]. The position at which the measurement is carried out on the sample cutting surface is specifed in the Swiss standard SN 214,001 [\[40](#page-17-25)]. According to this, the measurement must be carried out in the lower 10% of the cutting surface, but at least 1 mm from the lower edge. In this evaluation, due to the cutting depth of 15 mm, it was measured parallel to the lower edge, 1.3 mm away from it.

The striation mark displacement *n* was determined with two diferent microscopes. For samples that showed a strongly pronounced striation mark displacement as well as a large ripple in the cutting surface, the Mitutoyo Vision Measuring Machine QS250Z was used. If the striation mark displacement was impossible or difficult to detect with this measuring device, the Olympus SZX12 stereo microscope

was used for a better exposure capability of the sample. The striction mark displacement *n* was measured according to striation mark displacement *n* was measured according to the Swiss standard SN 214,001, as shown in the cutaway diagram A-A in Fig. [3](#page-3-0).

With the software of the respective microscopes, the beginning of a striation mark was marked with a line perpendicular to the workpiece surface. The water jet outlet was marked with a second line parallel to the frst. The distance between the two lines gave the striation mark displacement *n*. Three representative striation marks were measured on each sample, and their mean value was calculated. If no striation mark displacement was recognizable, it was rated 0.

3 Results and discussion

For the determination of the results, the usual roughness characteristics R_z (average roughness depth), R_a (arithmetic center roughness), and the highest height of the roughness *Rt* were measured. The values for the ripple W _z as well as the sizes *Pz*, *Pa*, and *Pt* of the primary profle were measured. By experimentally compiling diferent diagrams, a comparison and evaluation of the surface characteristics were carried out. In the case of AWJ, larger depressions or marks were produced at irregular intervals, e.g., due to a short-term abrasive quantity maximum due to discontinuous mixing. Therefore, the maximum roughness *Rt* is not a representative quantity. The characteristic values of the primary profle without fltering seem reasonable and probably also correspond to the so-called roughness values of some of the above-mentioned sources, in which the ripple fows into the roughness. However, these variables play a minor role in practice and are therefore not efective here. The remaining surface characteristics R_z , R_a , and W_z , however, are more practical and are therefore explained in more detail below. In the case of polyethylene plastics, measurable striation mark displacement only occurred in a few cases. The majority of the samples showed a rough surface with barely visible or invisible striation marks. Therefore, there are no useful diagrams for polyethylene plastic from which conclusions can be drawn in comparison to harder materials such as steel and aluminum.

3.1 Roughness, R_z, as a surface characteristic for AWJ cutting

Figures [7](#page-9-0) and [8](#page-9-1) show the striation mark displacement *n* and the average roughness R_z for the aluminum and steel samples, respectively with a nozzle diameter of $d = 0.28$ mm. The results were divided according to quality levels and are presented with a balancing straight line for each *Q* level. It can be seen that measuring the striation mark displacement alone does not give an idea of the roughness. This is

Fig. 7 Correlation between striation mark displacement and roughness R_z for single *Q* levels. (Steel) ($N_m = 21.8$, $p_w = 200-360$ MPa, $m_a = 4.8-$ 9.5 g/s, GMA 80, $d = 0.28$ mm, $d_f = 0.8$ mm, $s = 1$ mm, $h = 15$ mm)

the case for all materials: for steel, the indistinct range of roughness is 9–12 μm. The striation mark displacement in this relatively small span of roughness varies between 0.11 and 3.11 mm. Even with knowledge of the *Q* level of the cut, the roughness cannot be clearly determined. The reason for this is the low variance of the striation mark displacement over the roughness as well as the large dispersion of the values. This observation confrms the assumption that roughness depends mainly on the abrasive grain size and material,

rather than on the cutting parameters. Figure [9](#page-10-0) confirms this observation by an evaluation of the DoE with Minitab software (Minitab LLC, state college, PA, USA). The main efect on the roughness is the material-dependent processing rate. The cutting parameter pressure and especially the abrasive quantity have only a small infuence in comparison.

Figure [10](#page-10-1) shows the relationship between roughness R_z and Q levels for the polyethylene plastic material. If the quality level is known, the roughness can be

Fig. 8 Correlation between striation mark displacement and roughness R_z for single *Q* levels. (Aluminum) ($N_m = 60.5$, $p_w = 200-360$ MPa, *m*_a=4.8–9.5 g/s, GMA 80, d =0.28 mm, d_f =0.8 mm, s =1 mm, h =15 mm)

Fig. 9 Main effects and interaction plot for R_z

reliably determined by this graph. However, the correlation between the *Q* levels and the striation mark displacement would have to be known for this. Since the striation mark displacement with measuring instruments established in the industry could not be determined at *Q* > 1.2, therefore no conclusion can be drawn.

3.2 Roughness R_a as surface characteristic for AWJ cutting

Figures [11](#page-11-0) and [12](#page-11-1) show the striation mark displacement *n* and the center roughness R_a for the aluminum and steel samples, respectively. The results were divided according

Fig. 10 Correlation between roughness R_z and *Q* level for polyethylene plastic. $(N_m = 100, p_w = 200-360 \text{ MPa}, m_a = 4.8-9.5 \text{ g/s}, \text{GMA } 80,$ $d = 0.28$ mm, $d_f = 0.8$ mm, $s = 1$ mm, $h = 15$ mm)

Fig. 11 Correlation between striation mark displacement and roughness R_a for single *Q* levels (Aluminum). (N_m =60.5, p_w =200–360 MPa, *ma*=4.8–9.5 g/s, GMA 80, *d*=0.28 mm, *df*=0.8 mm, *s*=1 mm, *h*=15 mm)

to the quality levels *Q* and are presented with a balancing straight line for each *Q* level. The surface roughness profle parameter R_a cannot be inferred from measuring the striation mark displacement alone. According to [\[38](#page-17-23)], this arithmetic mid-rough value describes the arithmetic mean of the ordinate values $Z(x)$ within a single measurement distance. It

Fig. 12 Correlation between striation mark displacement and roughness R_a for single *Q* levels (steel). $(N_m = 21.8, p_w = 200-360 \text{ MPa}, m_a = 4.8-$ 9.5 g/s, GMA 80, $d = 0.28$ mm, $d_f = 0.8$ mm, $s = 1$ mm, $h = 15$ mm)

Fig. 13 Main effects and Interaction plot for R_a

is therefore a view of the area. From a purely hypothetical point of view, a measured distance with a single very wide and fat striation mark can therefore have the same value for R_a as an equally long measured distance with a narrow and deep striation mark and otherwise no elevations above the profle center line. This measured value is therefore no longer related to elevation and deepening so that, if the value is considered alone without knowledge of the true profle, no inference can be drawn as to the approximate depth of the surveys. For this reason, the surface characteristic R_a must be regarded as critical, especially in the case of the AWJ. It should also be noted that there is a relatively large statistical variation in the roughness. However, because this size is the most widely used in general mechanical engineering, it must not be neglected and will be discussed further below. The abovementioned effect of the arithmetic surface evaluation is amplifed in the ripple, since here the typical striation marks resulting from the AWJ for small *Q* values are included, which diminishes the effect of both. Therefore, the ripple is considered only with *Wz* and not with *Wa*. The negative slope of the balancing straight in aluminum is an illogical relationship and does not ft the general understanding of the surface fnish and the origin of it. The diferent samples of a quality level are so close together that the measurement inaccuracy is greater than the change in roughness due to the diferent cutting parameter settings. This is further proof

Fig. 14 Correlation between striation mark displacement and waviness W_z for single *Q* levels (aluminum). (N_m =60.5, p_w =200–360 MPa, *m_a*=4.8–9.5 g/s, GMA 80, *d*=0.28 mm, *d_f*=0.8 mm, *s*=1 mm, *h*=15 mm)

that the roughness value R_a is unsuitable for determining the surface quality in the AWJ.

Figure [13](#page-12-0) shows that the main effects of R_a are very similar to those of R_z .

3.3 Relationship between striation mark displacement n and ripple Wz

Figures [14](#page-12-1) and [15](#page-13-0) show the striation mark displacement *n* above the ripple W _r for aluminum and steel, broken down by the individual *Q* levels. Here, the connection between the sizes can be clearly seen. With increasing striation mark displacement, a greater striation mark depth is involved, which flows directly into the ripple. This is proof that, for small values for *Q*, a view of the ripple is more useful than that of roughness. The following evaluation of the main efects on the ripple (Fig. [16\)](#page-14-0) shows this again clearly. The smaller the *Q* level, the higher its infuence on the ripple.

3.4 Infuence of the view of the surface as a periodic or aperiodic profle

For a clear standard-compliant determination of surface characteristics, an assignment of the considered surface with respect to their periodicity is necessary. The type of viewing, as shown in Fig. [16](#page-14-0), clearly determines the flter settings and thus the boundary between ripple and roughness. In the case of the AWJ, the classifcation is ambiguous without

any further information because, depending on the set cutting parameters, very diferent surface structures are created. This problem is referred to in the statements made in the Introduction regarding the inaccurate or missing separation between roughness and ripple in the sources.

In this study, the AWJ cutting surface is basically treated as a periodic profle. The reason for this can be found in the ideal hypothesis of the AWJ. The hypothesis assumes that each abrasive grain has a specifc time interval in which the material removal takes place. If these intervals are equal in length and lined up, the feed results in regularly recurring striation marks. The distance between these striation marks then varies based on the operating parameters and is called the *RSm* value. Figure [17](#page-14-1) shows the history of the *RSm* value over *Q* for all materials. The measurement was made at the incision, as the surface was approaching the idealization described above. The curves are more qualitative, since only individual sample values have been determined. The colored horizontal boundaries show the limits at which the flter settings must be changed.

At these limits, the proportion of surface fnish to which either roughness or ripple must be assigned is changed abruptly. As a result, the requirements for a surface must also be diferent in each area, since two quantitatively identical values from diferent ranges difer qualitatively. In order to assign a surface formed by water abrasion blasting by means of the roughness characteristics R_z and R_a to one of the *Q* levels, no signifcant striation marks may be present

Fig. 15 Correlation between striation mark displacement and waviness W_z for single *Q* levels (steel). $(N_m = 21.8-100, p_w = 200-360 \text{ MPa}$, m_a = 4.8–9.5 g/s, GMA 80, d = 0.28 mm, d_f = 0.8 mm, s = 1 mm, h = 15 mm)

Fig. 16 Selection of sampling length and cutoff in accordance with ISO 4288 (04/98) [\[39\]](#page-17-24)

on the surface. These must be considered as ripple (W_z) and incorrectly influence the measurement of R_z and R_a . For the test series created here, it can be said that the roughness characteristics R_z and R_a can be applied to classify quality levels Q3–5. However, this delimitation of the categorizability of a surface is material-dependent and therefore not fully valid for other materials. There are overlaps here, so in some cases a roughness value can be assigned to all fve *Q* levels. Thus, it can be problematic to defne the *Q* levels only by a roughness value, as can be seen in Figs. [7](#page-9-0) and [12](#page-11-1). For steel, however, it can be said in this case that above 12 μm the *Q* level can be clearly determined, namely to Q1.2. If the measured striation mark is then compared to that in the chart in Fig. [7,](#page-9-0) the roughness value can be considered valid. However, the reference to the flter setting must be made here again. The samples of this work were evaluated at the beam outlet, contrary to the valid standards, all with the same flter setting described above, in order to ensure better comparability. If the surface is evaluated separately according to ripple and roughness, as in this work, then it turns out that the ripple W_{τ} is better suited for determining the surface. The classifcation into *Q* levels can be carried out safely due to the typical striation marks for the AWJ, especially in the rough range by this characteristic value. However, it can be seen in Figs. [14](#page-12-1) and [15](#page-13-0) that overlaps also occur here. This observation can be attributed to the absence of grooves at the fne *Q* levels. Therefore, the exclusive measurement of *W_z* is not a perfect method for surface determination, since only with an undulating surface can a ripple value be determined. The example images from [\[40](#page-17-25)] and [[29\]](#page-17-14) show a clear increase in the striation mark displacement with a decreasing *Q* level. Although the description of the sample images

Fig. 17 Correlation between *RSm* and *Q* level for all materials. $(N_m = 21.8-100, p_w = 200-360$ MPa, $m_a = 4.8$ g/s, GMA 80, $d = 0.28$ mm, $d_f = 0.8$ mm, $s = 1$ mm, $h = 15$ mm)

Table 3 Concrete values of striation marks for single *Q* levels (steel) with roughness limits

Table 5 Concrete values of striation marks for single *Q* levels (polyethylene plastic) with roughness limits

Fig. 18 Correlation between *RSm* and *Q* level for all materials (exemplary) with areas. $(N_m = 21.8 - 100, p_w = 200 - 360 \text{ MPa}, m_a = 4.8 \text{ g/s},$ GMA 80, $d=0.28$ mm, $d_f=0.8$ mm, $s=1$ mm, $h=15$ mm). Area 1 (left) has three values for *λc*, area 2 (middle) only 0.8 and 2.5 mm, and area 3 (right) only 0.8 mm, if the relationship from Fig. [15](#page-13-0) applies to *RSm* and *λc*. The proposal is therefore as follows. In area 1, i.e., for required surfaces of poor Q2, measuring the striation mark displacement is sufficient to be able to assign the surface without any doubt. In addition, roughness is not important for these poor surfaces, as further processing usually follows. In area 2, i.e., from Q2 to Q4, the roughness becomes functionally important and must therefore be checked in addition to the striation mark displacement. The striation mark displacement must not exceed a certain level, and the roughness should not fall below a limit value, so as not to be unnecessarily

expensive. If one of the highest quality levels, Q4 or Q5, is required, then a roughness measurement and a controlling ripple measurement, which must not exceed a certain value, are sufficient, since no or very few striation marks occur. In addition, it must be said that the above tables apply only in one direction because of an R_a value; no inference from the table to the striation mark displacement or the *Q* level is possible. In this work, tables were created for three representative materials. This publication therefore demonstrates an improved method to categorize the quality of the fnished surfaces. According to this procedure, such tables can also be created for other materials or groups of materials with similar physical properties to check the quality. These must also be provided with statistical security. The approach proposed here could make it safer and faster to determine the surface without misunderstandings

refers only to the striation marks and not to *n*, a clear correlation can be assumed qualitatively, independent of the cutting parameters. This assumption is confrmed by the clear relationship between the striation mark displacement and the *Q* levels (Fig. [7\)](#page-9-0). Thus, the striation mark displacement is an easy value to measure when it comes to the unique assignment of a cutting surface to one of the fve *Q* levels. However, there is also a problem here. With the fner *Q* levels, no striation mark displacement is measurable or it is equal to 0. In addition, the material used also plays a major role, so softer materials are produced; here, it was polyethylene plastic, often even with coarser *Q* levels and a rather rough surface on which no striation mark displacement occurred. Therefore, in practice, several parameters are always necessary for a clear defnition and determination. The following describes how this can be implemented for practical applicability (Tables [3](#page-15-0), [4](#page-15-1), and [5](#page-15-2)).

4 Conclusions

The following recommendations for the categorization of AWJ surfaces should help to objectively check the manufactured surface for the required *Q* level in practical applications. Furthermore, it is possible to assign the surface to a range of surface roughness profle parameters *Rz* and *Ra* as soon as no clear striation marks are recognizable on the surface, or these can be assigned to the roughness profle.

With the help of these tables, it is possible for the operators of a AWJ system to immediately check that the manufactured surface meets the required quality level by means of a simple measuring device such as a mess slider. Since the roughness characteristics R_z and R_a are frequently required parameters in production drawings, it is possible to assign them to a quality level and a range of striation mark displacement and thus to carry out a frst quick check on the set cutting parameters. It is also apparent that the areas used for the categorization of roughness ratios overlap greatly. Therefore, it must be reiterated that the *Q* level cannot be clearly determined by measuring roughness characteristics alone. Figure [18](#page-15-3) again shows the course of the *RSm* value along with diferent *Q* for all materials.

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Declarations

Ethics approval The research does not involve human participants or animals, and the authors warrant that the paper fulfls the ethical standards of the journal.

Consent to participate It is confrmed that all the authors are aware and satisfed of the authorship order and correspondence of the paper.

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