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ARYABHATA REMAINDER THEOREM: RELEVANCE TO PUBLIC-KEY CRYPTO-ALGORITHMS*

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Abstract. Public-key crypto-algorithms are widely employed for authentication, signatures, secret-key generation and access control. The new range of public-key sizes for *RSA* and *DSA* has gone up to 1024 bits and beyond. The elliptic-curve key range is from 162 bits to 256 bits. Many varied software and hardware algorithms are being developed for implementation for smart-card crypto-coprocessors and for public-key infrastructure. We begin with an algorithm from *Aryabhatiya* for solving the indeterminate equation $a \cdot x + c = b \cdot y$ of degree one (also known as the Diophantine equation) and its extension to solve the system of two residues $X \bmod m_i = X_i$ (for $i = 1, 2$). This contribution known as the Aryabhatiya algorithm (AA) is very profound in the sense that the problem of two congruences was solved with just one modular inverse operation and a modular reduction to a smaller modulus than the compound modulus.

We extend AA to any set of t residues, and this is stated as the Aryabhata remainder theorem (ART). An iterative algorithm is also given to solve for t moduli m_i ($i = 1, 2, \ldots, t$). The ART, which has much in common with the extended Euclidean algorithm (EEA), Chinese remainder theorem (CRT) and Garner's algorithm (GA), is shown to have a complexity comparable to or better than that of the CRT and GA.

Key words: Diophantine equation, Aryabhata, Aryabhatiya, modular arithmetic, residue number system, modular inverse.

1. Introduction

We begin with an algorithm of Aryabhata (Pearce [10] states: "we can accurately claim that Aryabhata was born in 476 A.D., ... he was 23 years old when he wrote his most significant mathematical work *Aryabhatiya* in 499 A.D ... .") found in the text *Aryabhatiya* [2], [6], [12], which solves the linear indeterminate

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equation $a \cdot x + c = b \cdot y$, for positive integers a, b, and c (sometimes called a Diophantine equation). This algorithm also solves for X, given the pair of residues $X \bmod m_i = x_i$ (for $i = 1, 2$). There is some underlying principle of simplicity in this solution, which has been found to be applicable to solving the general case of n residues in an iterative manner, requiring as few inverse operations as any we know of today and also without requiring a final modular reduction operation. This leads us to state this idea as the *Aryabhata remainder theorem* (*ART*). The *ART* algorithm presented here is comparable and in some ways more efficient than the *CRT* algorithm of Gauss [4], the original Garner algorithm [3], and the later version of *GA* given in [8], [9].

1.1. Aryabhata algorithm (AA)

In the field of pure mathematics, one of the most significant contributions of Aryabhata is his solution to the indeterminate equation $a \cdot x + c = b \cdot y$. We copy here the example and discussion given by Pearce [10] from *Aryabhatiya* [2], [12]

Example 1.

$$137 \cdot x + 10 = 60 \cdot y \tag{1}$$

```
60)137(2    (60 divides into 137 twice with remainder 17, etc)
   120
 ----------
    17)60 (3
      51
    ----------
       9)17 (1
          9
       ----------
             9 (1
           (8)8
          ----------
          [ 1 ]
```

The column of quotients known as *valli* (Vertical line) is constructed: $\begin{pmatrix} 2 \\ 3 \\ 1 \\ 1 \end{pmatrix}$

Remark. This method was called *kuttaka*, which literally means "pulverizer," on account of the process of continued division that is carried out to obtain successively smaller remainders. This is traditionally called a Euclidean algorithm. This

process in traditional textbook format of n equations is written as follows:

$$\left.\begin{aligned} a &= b \cdot q_1 + r_1 \\ b &= r_1 \cdot q_2 + r_2 \\ &\vdots \\ r_{n-2} &= r_{n-1} \cdot q_n + r_n \end{aligned}\right\} \tag{2}$$

In some books [1], this is given as a continued fraction version of Euclid's algorithm. The number of quotients, omitting the first one, is 3, which is odd. Hence, we choose a multiplier k such that on multiplication by the last residue, 1 (in the dashed rectangle), and subtracting 10 from the product the result is divisible by the penultimate remainder, 8 (in the dashed circle). If the number of quotients, after omitting the first one, is even, then adding 10 is required instead of subtracting.

We have $1 \cdot 18 - 10 = 1 \cdot 8$. Then we can form the following table:

	2	2	2	297
	3	3	130	130
	1	1	37	
	1	19		
$k = 18$	18			
	1			

This can be explained as follows.

The number 18, and the number above it in the first column, multiplied and added to the number below it, gives the last but one number in the second column. Thus, $18 \cdot 1 + 1 = 19$. The same process is applied to the second column, giving the third column result: $19 \cdot 1 + 18 = 37$. Similarly, $37 \cdot 3 + 19 = 130$, $130 \cdot 2 + 37 = 297$. Then $x = 130$, $y = 297$ are solutions of the given equation. Noting that $297 (\text{mod}\, 137) = 23$ and $130 (\text{mod}\, 60) = 10$, we get $x = 10$ and $y = 23$ as simple solutions. Thus, we have $137 \cdot 10 + 10 = 60 \cdot 23$ as a solution for equation (1).

1.2. Improved Aryabhata algorithm (IAA)

We show how to simplify considerably the above procedure. First replace c with $d = gcd(a, b) = gcd\ (137, 60) = 1$ in equation (1) to obtain the following.

Example 2.

$$137 \cdot x + 1 = 60 \cdot y \tag{3}$$

We obtain q_i as before. Form a table with the first column as the iteration variable i, and the *valli* of q_i as the second column. The third column of S_i is obtained from the bottom up in a similar manner as in Example 1. We start with $S_5 = 1$, $S_4 = q_4$ as initial values and use the recursion formula:

$$S_i = q_i \cdot S_{i+1} + S_{i+2} \tag{4}$$

i	q_i	S_i
1	2	16
2	3	7
3	1	2
4	1	1
5	–	1

We compute the S_i's from the bottom up.

$$S_3 = q_3 \cdot S_4 + S_5 = 1 \cdot 1 + 1 = 2$$
$$S_2 = q_2 \cdot S_3 + S_4 = 3 \cdot 2 + 1 = 7$$
$$S_1 = q_1 \cdot S_2 + S_3 = 2 \cdot 7 + 2 = 16$$

We note the number of quotients $n = 4$, and $gcd\ (137, 60) = d = 1$. We give the answer to equation (3) as $137 \cdot S_2 + (-1)^n\ d\ = 60 \cdot S_1$. Thus, we have $137 \cdot 7 + 1 = 60 \cdot 16$. To solve equation (1), we multiply the solution for equation (3) by 10 to get $137 \cdot 70 + 10 = 60 \cdot 160$. By taking out $137 \cdot 60$ from both sides, we get the simple solution $137 \cdot 10 + 10 = 60 \cdot 23$.

Improved IAA for solving $a \cdot x + d = b \cdot y$

INPUT: a and b are positive integers and $d = gcd(a, b)$

1. $i \leftarrow 1, r_{-1} = a, r_0 = b$
2. while $(r_i \leftarrow r_{i-2} \bmod r_{i-1} \neq 0)$ do the following:
   $q_i \leftarrow quotient(r_{i-2}/r_{i-1})$
   $i \leftarrow i + 1$
3. $n \leftarrow i - 1$, $S_{n+1} = 1$, $S_n = q_n$
4. For i from $n - 2$ down to 1 do the following:
   $S_i = q_i \cdot S_{i+1} + S_{i+2}$

OUTPUT: $x = [(-1)^n \cdot S_2] \bmod b$, $y = [(-1)^n \cdot S_1] \bmod a$

Definition 1. We define the value for S_1 to be *optimal* if $0 < S_1 < a$, and S_2 to be *optimal* if $0 < S_2 < b$. Any solution to $a \cdot x + c = b \cdot y$ is said to be *optimal* if $0 < x < b$ or $0 < y < a$.

Remark. Lemma 1, given later, shows that the IAA obtains optimal values for S_1 and S_2.

The relevance of the solution $137 \cdot 7 + 1 = 60 \cdot 16$ for us is that $137^{-1} \bmod 60 = -7 \bmod 60 = 53$ and $60^{-1} \bmod 137 = 16$. Thus, we get both inverses, $a^{-1} \bmod b$ and $b^{-1} \bmod a$, by this method. Also, these lead us to the solution to the problem of two residues, as shown in Section 2.

The theory behind the results of the preceding two examples can be put in the form of two lemmas and a theorem as follows.

Lemma 1. *Let $a, b, c, q_i, r_i, S_i, d$, and n be as defined in the previous examples. For $a \cdot x + d = b \cdot y$, the IAA yields optimal values for S_1 and S_2, i.e., $0 < S_1 < a$ and $0 < S_2 < b$.*

Lemma 2. *The optimal solution to $a \cdot x + d = b \cdot y$ is given by*

$$x = [(-1)^n \cdot S_2] \bmod b,$$
$$y = [(-1)^n \cdot S_1] \bmod a.$$

Theorem 1. *An optimal solution to $a \cdot x + c = b \cdot y$ is given by*

$$x = [(-1)^n \cdot S_2(c/d)] \bmod b$$
$$y = (-1)^n \cdot S_1(c/d) + ka, \text{ where } k = \{x - [(-1)^n \cdot S_2(c/d)]/b.$$

The proofs of these lemmas and the theorem are simple and are not required to understand what follows. Therefore, we conveniently move them to the Appendix. For a clearer understanding, a few examples are also provided there.

2. The problem of two residues

Consider $X \bmod 60 = 0$ and $X \bmod 137 = 10$. Clearly, $X = 60y$ for some y and also $X = 137x + 10$ for some x. That means we solve $137 \cdot x + 10 = 60 \cdot y$, which we did in the previous section. Thus, $X = 60 \cdot 23 = 1380$. Let us now modify the problem slightly by adding a 5 to both of the residues. Then we have $X \bmod 60 = 5$ and $X \bmod 137 = 15$.

The answer here is just to add 5 to the previous solution and we get $X = 1385$.

This is the very important underlying principle in Aryabhata's solution to the problem of two residues: we solve the problem of two residues by first solving the Diophantine equation $a \cdot x + c = b \cdot y$ and then adding a constant. Solving the equation amounts to finding the modular inverse of $b \bmod a$ and then a modular multiplication with $c \bmod a$. This is a profound and significant contribution of Aryabhata, which should be recognized by the cryptology community. Its extension for the t-moduli we present here will also be of great importance due to the PCKS # 1 v2.1 of the RSA cryptographic standard [11], which discusses modulus n of 2048 bits, a composite of four primes each of 512 bits. In this context, every contribution in residue operations and number conversions will become important both now and in the future. This was called the *Aryabhata algorithm (AA)* by Kak [6]. That paper also contains a detailed historical presentation on the system of multiple residues in India and the work of Sun Tzu and others in China. Kak also discusses how the Aryabhata algorithm was used to solve problems in astronomy in India. Here we develop the solution as a formal theorem and call it the *Aryabhata reminder theorem* (*ART*) as a tribute to perhaps the greatest mathematician and astronomer of the classical period (the fifth century to the twelfth century A.D.).

2.1. Aryabhata remainder theorem (ART)

Theorem (*ART*). *Let m_1 and m_2 be relatively prime moduli and $M = m_1 m_2$. Given $X \bmod m_1 = x_1$, $X \bmod m_2 = x_2$, X has a unique solution in Z_M given by*

$$\begin{aligned} X &= ART(x_1, x_2; m_1, m_2; M) \\ &= ART(0, c; m_1, m_2; M) + x_1, \quad \textit{where } c = (x_2 - x_1) \bmod m_2 \\ &= A + x_1, \quad \textit{where } A = m_1[(c \cdot m_1^{-1}) \bmod m_2]. \end{aligned}$$

Proof. First we show that $X = A + x_1 \in Z_M$. Because $A = m_1 \cdot b$ for some $b \in Z_{m_2}$, A must be less than or equal to $m_1(m_2 - 1)$. Because $x_1 < m_1$, $A + x_1$ must be less than $M = m_1 m_2$, and therefore $X \in Z_M$. Now consider $(A + x_1) \bmod m_1$. Because A is a multiple of m_1, we have $(A + x_1) \bmod m_1 = x_1$. Because $A \bmod m_2 = c$ due to the cancellation of the terms m_1 and m_1^{-1}, we have $(A + x_1) \bmod m_2 = c + x_1 = x_2$. Thus, $A + x_1 = X$ satisfies the two congruences as required and is a solution in Z_M. It is easy to show that $A + x_1$ is a unique solution in Z_M. If $Y \in Z_M$ is another solution, then $(X - Y) \bmod m_i = 0$, for $i = 1, 2$, and $(X - Y) \bmod M = 0$. Thus, $X = Y$. □

A formal extension of ART to any number of moduli is rather straightforward and is given in Section 5. Here we illustrate by an example.

Example 3. Let $X \bmod 3 = x_1 = 1$, $X \bmod 4 = x_2 = 3$, and $X \bmod 5 = x_3 = 3$. Then $X = ART(1, 3, 3; 3, 4, 5; 60)$.

***Step* 1.**

$$\begin{aligned} X' = X \bmod 12 &= ART(1, 3; 3, 4; 12) \\ &= ART(0, 2; 3, 4; 12) + 1 \\ &= 3[(2 \cdot 3^{-1}) \bmod 4] + 1 \\ &= 3 \cdot 2 + 1 = 7 \end{aligned}$$

***Step* 2.**

$$\begin{aligned} X &= ART(7, 3; 12, 5; 60) \\ &= ART(0, (3 - 7) \bmod 5; 12, 5; 60) + 7 \\ &= ART(0, 1; 12, 5; 60) + 7 \\ &= 12[(1 \cdot 12^{-1}) \bmod 5] + 7 \\ &= 12 \cdot 3 + 7 = 43 \end{aligned}$$

3. Multiplicative inverse

Given positive pairwise prime integers a and b, it is very often necessary to find $a^{-1} \bmod b$. That is, to find $x \in Z_b$ such that $a \cdot x \bmod b = 1$. In *RSA*, the private

key d is generated by finding the inverse of public-key $e \bmod \emptyset(n)$, where $\emptyset(n) = (p-1)(q-1)$. The *extended Euclidean algorithm* (*EEA*) [8], [9] given below obtains $a \cdot x + b \cdot y = 1$, for given a and b. Finding the multiplicative inverse is illustrated in Example (4).

3.1. Extended Euclidean algorithm (EEA)

The EEA is available in most texts [8], [9]. The simpler version of the Euclidean algorithm from [7] will illustrate the principle as well.

Example 4. Let $a = 137$ and $b = 60$.

i	r_i	q_i	x_i	y_i
-1	137		1	
0	60	–	0	1
1	17	2	1	-2
2	9	3	-3	7
3	8	1	4	-9
4	1	1	-7	16
5	0			

$$q_i \leftarrow quotient(r_{i-2}/r_{i-1}), \qquad r_i \leftarrow r_{i-2} \bmod r_{i-1}$$
$$x_i \leftarrow x_{i-2} - q_i \cdot x_{i-1}, \qquad y_i \leftarrow y_{i-2} - q_i \cdot y_{i-1}$$

From the table above we have $x = -7 \bmod 60 = 53$ and $y = 16$. Therefore $137^{-1} \bmod 60 = -7 \bmod 60 = 53$ and $60^{-1} \bmod 137 = 16$.

The EEA requires a series of successive division steps as in the *GCD* algorithm, while calculating x_i and y_i iteratively to ultimately obtain the final values. This procedure requires n divisions, $2n$ multiplications, and $2n$ subtractions, where n is the number of iterations. However the *IAA* requires n divisions and $n-2$ multiplications and $n-2$ additions to find s_2, the inverse of $a \bmod b$. Whereas the EEA derives the values x_i and y_i in a forward direction as q_i are generated, the IAA will have to generate all q_i's and then apply the iterations in a reverse manner. This requires storing q_i's and is an undesirable feature. Thus, the EEA is superior in that sense. Also if one needs only one inverse (i.e., $a^{-1} \bmod b$), the y_i column is not required and, in that case, just n multiplication and subtraction steps are needed. Knuth [8] obtains n, the average number of divisions required for *GCD* for given x and a random $y < x$ by the formula

$$n \approx 1.94 \log_{10} x.$$

For a 100-digit decimal number a and a randomly chosen $b < a$, the average number of division steps will be about 194.

3.2. Multiplicative inverse algorithm

The EEA can be improved to perform better if only one inverse is required. For instance, if $a^{-1} \bmod b$ is required for $a > b$, we may just as well begin with $a \bmod b = c$ and find $c^{-1} \bmod b$. In that case, the x_i computation will be one less step. Further, if the initial values are set appropriately, the inverse can be obtained in $n - 2$ forward steps (each step: one multiplication and one addition), the same number of steps as in the IAA (Section 1.2). We illustrate this by using the same example as before with another table.

Example 5. Find $137^{-1} \bmod 60$ ($a = 137$ and $b = 60$)

We start with $r_0 = b = 60$, $r_1 = a \bmod 60 = 17$, and $x_1 = 1$. The iterations begin from $i = 2$ with the normal division process: $q_i \leftarrow quotient(r_{i-2}/r_{i-1})$, $r_i \leftarrow r_{i-2} \bmod r_{i-1}$, and $x_2 = q_2$.

The iteration proceeds: $x_i \leftarrow x_{i-1} \cdot q_i + x_{i-2}$ (for $i > 2$).

i	r_i	q_i	x_i
0	60	–	–
1	17	–	1
2	9	3	3
3	8	1	4
4	1	1	7
5	0		

From this we observe the following:

$$a \cdot x_i(-1)^{i-1} \bmod b = r_i \text{ for } i \geq 1, \qquad 137 \cdot 7(-1)^{4-1} \bmod 60 = 1,$$
$$X = 137^{-1} \bmod 60 = 60 - 7 = 53.$$

We can now state the following lemma.

Lemma 3. *Let a, b, r_i, q_i, and x_i be defined as above. Then $a^{-1} \bmod b$ exists iff $x_n = 1$ (for some $n > 1$) and is given by*

$$a^{-1} \bmod b = x_n(-1)^{n-1}.$$

Proof. First, we need to prove that $a \cdot x_i(-1)^{i-1} \bmod b = r_i$ holds for $i \geq 1$. For $i = 1$, we have $x_1 = 1$ and $a \cdot x_1(-1)^{i-1} \bmod b = r_1$. For $i = 2$, we have the division equation $r_2 = r_0 - q_2 \cdot r_1 = r_0 - x_2 \cdot r_1$. Taking $\bmod b$ on both sides, we get $(-x_2) \cdot r_1 \bmod b = r_2$, which is the same as $(-x_2)a \bmod b = r_2$. For $i = 3$, we start with $r_3 = r_1 - q_3 \cdot r_2 = r_1 \cdot x_1 - q_3(r_0 - x_2 \cdot r_1) = r_1(x_2 \cdot q_3 + x_1) - q_3 \cdot r_0 = r_1 \cdot x_3 - q_3 \cdot r_0$. Taking mod b on both sides, we have $r_1 \cdot x_3 \bmod b = r_3$ and $a \cdot x_3 \bmod b = r_3$. Continuing this process, we obtain $a \cdot x_n(-1)^{n-1} \bmod b = r_n = 1$ and $a^{-1} \bmod b = x_n(-1)^{n-1}$. □

Algorithm for $a^{-1} \bmod b$

Step 1. $r_0 \leftarrow b$
$r_1 \leftarrow a \bmod b$
if $r_1 = 0$, then go to Step 4
else $x_1 \leftarrow 1$
$\iota \leftarrow 2$

Step 2. $q_i \leftarrow quotient(r_{i-2}/r_{i-1})$
$r_i \leftarrow r_{i-2} \bmod r_{i-1}$
If $r_i = 0$, then go to step 3
else if $i = 2$, then $x_i \leftarrow q_i$
else $x_i \leftarrow x_{i-1} \cdot q_i + x_{i-2}$
$i \leftarrow i + 1$
go to Step 2

Step 3. If $r_{i-1} = 1$, then if i is even,
then return (x_i)
else return $(b - x_i)$

Step 4. print "Inverse does not exist"

4. Chinese remainder theorem (CRT)

Let $X = CRT(v_1, v_2, \ldots, v_t; m_1, m_2, \ldots, m_t; M = \prod_{i=1}^{t} m_i)$ for $(m_i, m_j) = 1$, for all $i \neq j$. Then X is given by

$$X = \left[\sum_{i=1}^{t} v_i (M/m_i) y_i \right] \bmod M,$$

where $y_i = (M/m_i)^{-1} \bmod m_i$.

Example 6. $X = CRT(2, 1, 3, 8; 5, 7, 11, 13; 5005)$

$$y_1 = (5005/5)^{-1} \bmod 5 = (1001)^{-1} \bmod 5 = 1$$
$$y_2 = (5005/7)^{-1} \bmod 7 = (715)^{-1} \bmod 7 = 1$$
$$y_3 = (5005/11)^{-1} \bmod 11 = (455)^{-1} \bmod 11 = 3$$
$$y_4 = (5005/13)^{-1} \bmod 13 = (385)^{-1} \bmod 13 = 5$$

$$X = 2 \cdot 1001 \cdot 1 + 1 \cdot 715 \cdot 1 + 3 \cdot 455 \cdot 3 + 8 \cdot 385$$
$$= (2002 + 715 + 4095 + 15400) \bmod 5005 = 2192.$$

Remark. *CRT* requires t inverse operations and a reduction operation modulo M. As explained in [9], the number of bit operations $O(k^2 t^2) = O(n^2)$, where k is the maximum bit size of the residues and n is the combined number of bits in modular representation of $v(x)$.

4.1. Garner's algorithm (GA) compared with CRT

Garner [3] deduced an algorithm to convert the residue code of a number $X = (v_1, v_2, \ldots, v_t)$ with respect to pairwise relatively prime modulo $m_1, m_2, \ldots, m_t$ to a mixed radix number with weight $1, m_t, m_{t-1}m_t$, and so on up to the last one $m_2 m_3 \ldots m_t$. Then its radix equivalent can be easily computed using those weights. As an example he chose $(1, 2, 0, 4)$ for moduli set $(2, 3, 5, 7)$ and converted to the mixed radix form of $(0, 2, 3, 4)$ whose weights are $(105, 35, 7, 1)$ respectively. Then $X = (1, 2, 0, 4)$ represented $0 \cdot 105 + 2 \cdot 35 + 3 \cdot 7 + 4 = 95$. A refined version of Garner's algorithm has been given in [9] as follows.

INPUT: a positive integer $M = \prod_{i=1}^{t} m_i$, with $gcd\ (m_i, m_j) = 1$ for all $i \neq j$, and a modular representation $v(x) = (v_1, v_2, \ldots, v_t)$ of x for the m_i.

OUTPUT: the integer x in radix b representation.

1. For i from 2 to t do the following:
   $C_i \leftarrow 1$.
   For j from 1 to $(i - 1)$ do the following:
   $u \leftarrow m_j^{-1} \bmod m_i$
   $C_i \leftarrow u \cdot C_i \bmod m_i$
2. $u \leftarrow v_1, x \leftarrow u$
3. For i from 2 to t do the following: $u \leftarrow (v_i - x) \cdot C_i \bmod m_i$,
   $x \leftarrow x + u \cdot \prod_{j=1}^{i-1} m_j$
4. Return (x).

x returned by algorithm (GA) satisfies $0 \leq x < M, x \equiv v_i (\bmod m_i), 1 \leq i \leq t$.

Example 7 Garner's algorithm [9]**.** Let $m_1 = 5$, $m_2 = 7$, $m_3 = 11$, $m_4 = 13$, $M = \prod_{i=1}^{4} m_i = 5005$, and $v(x) = (2, 1, 3, 8)$. The constants $C_i =$ computed are $C_2 = 3$, $C_3 = 6$, $C_4 = 5$. The values (i, u, x) computed in Step 3 of the algorithm are $(1, 2, 2)$, $(2, 4, 22)$, $(3, 7, 267)$, and $(4, 5, 2192)$. Hence, the modular representation $v(x) = (2, 1, 3, 8)$ corresponds to the integer $X = 2192$.

Menezes et al. [9] provide a discussion on the computational efficiency of *GA* as follows:

If Garner's algorithm is used repeatedly with the same modulus M and the same factors of M, then step 1 can be considered as a precomputation, requiring the storage of $t - 1$ numbers. The classical algorithm for the CRT typically requires a modular reduction with modulus M, whereas Garner's algorithm does not. Suppose M is a kt-bit integer and each m_i is a k-bit integer. A modular reduction by M takes $O((kt)^2)$ bit operations. Whereas a modular reduction by m_i takes $O(k^2)$ bit operations. Since Garner's algorithm only does modular reduction with

m_i, $2 \le i \le t$, it takes $O(tk^2)$ bit operations in total for the reduction phase, and is thus more efficient.

However, the GA requires $t(t-1)/2$ inverse mod m_i operations. Because the inverse requires $O(k^2)$ bit operations, the complexity of inversions is $O(t^2k^2)$. The CRT requires mod M reduction, which has a complexity of $O(\log M)^2 = O(t^2k^2)$. The original algorithm of Garner [3] required only $t-1$ inversions but required a considerably larger number of modular reductions $O(k^2)$ and residue vector operations of the $O(t)$. The overall complexity of the GA can be shown to be $O(t^2k^2)$. The ART algorithm developed in the next section requires only $t-1$ inversions. Also as in the GA, it does not require mod M reduction and thus has a complexity of $O(tk^2)$ bit operations.

5. ART algorithm

The underlying principle behind Aryabhata's solution for the problem of two residues is that it requires only one modular inverse operation and any modular reduction is to the smaller moduli m_i rather than to the composite M. This simplicity is of paramount importance. This principle has been exploited in many applications and the performance, for instance, of the *RSA* signature has improved for smart-card processors by a factor greater than 3.6 [5], [11]. The ART algorithm is an extension of this principle to t moduli.

$X = ART(v_1, v_2, \ldots, v_t; m_1, m_2, \ldots, m_t; M)$

***Step* 1.** $X_1 = v_1$

***Step* 2.** $X_2 = ART(v_1, v_2; m_1, m_2; M_2)\ M_2 = m_1m_2$
$= ART(0, |v_2 - v_1|_{m_2}; m_1, m_2; M_2) + v_1$

***Step* 3.** $X_3 = ART(X_2, v_3; M_2, m_3; M_3)\ M_3 = m_1m_2m_3$
$= ART(0, |v_3 - X_2|_{m_3}; M_2, m_3; M_3) + v_2$

. . . . . .

Step t. $X_t = ART(X_{t-1}, v_t; M_{t-1}, m_t; M_t)\ M_t = M$
$= ART(0, |v_t - X_{t-1}|_{m_t}; M_{t-1}, m_t; M_t) + v_t$

The algorithmic form of this process is as follows.

INPUT: a positive integer $M = \prod_{i=1}^{t} m_i$, with $gcd\ (m_i, m_j) = 1$ for all $i \ne j$, and a modular representation $v(x) = (v_1, v_2, \ldots, v_t)$ of x for the m_i.

1. $N_1 \leftarrow 1, X_1 \leftarrow v_1$
2. For i from 2 to t do the following:
   $N_i \leftarrow N_{i-1} \cdot m_{i-1}$
   $C_i \leftarrow N_i^{-1}$ mod m_i (also denote $|N_i^{-1}|m_i$)

$U_i \leftarrow [(v_i - X_{i-1}) \cdot C_i] \bmod m_i$
$X_i \leftarrow X_{i-1} + U_i \cdot N_i$

OUTPUT: Return X_t

This is illustrated by an example.

Example 8. Find $X = ART(2, 1, 3, 8; 5, 7, 11, 13; 5005)$

i	N_i	$N_i \bmod m_i$	C_i	U_i	X_i
1	1	–	–	–	2
2	5	5	$\|5^{-1}\|_7 = 3$	$\|(1-2)\cdot 3\|_7 = 4$	$2 + 4 \cdot 5 = 22$
3	$5 \cdot 7 = 35$	$\|35\|_{11} = 2$	$\|2^{-1}\|_{11} = 6$	$\|(3-22)\cdot 6\|_{11} = 7$	$22 + 7 \cdot 35 = 267$
4	$35 \cdot 11 = 385$	$\|385\|_{13} = 8$	$\|8^{-1}\|_{13} = 5$	$\|(8-267)\cdot 5\|_{13} = 5$	$267 + 5 \cdot 385 = 2192$

Steps 2, 3, and 4 in the table are iterations of the ART, solving for 2 residues in each of these steps. The final value $X = X_4 = 2192$.

6. Conclusion

The underlying principle behind Aryabhata's solution for the problem of two residues and its simplicity are of paramount importance. Historians of mathematics have acknowledged this fact by writing about the Aryabhata algorithm ([6]), but as part of the cryptology community, we are now trying to redress this balance. This principle has been reinvented quite independently by Garner and exploited in many applications by others [5], [11]. The performance, for instance, of the *RSA* signature using this principle has improved for smart-card processors by a factor greater than 3.6. However, Aryabhata has not been recognized for this contribution when the *CRT* is mentioned. We emphasize about this fact and thus give long-overdue credit to a great mathematician. We have provided here the *Aryabhata remainder theorem* as an extension to t moduli of his original contribution. Its complexity is shown to be comparable to or better than that of the CRT and GA.

Appendix

For the following lemmas and the discussion, let $a, b, c, q_i, r_i, S_i, d$, and n be as defined in Section 1.

Lemma 1. *For $a \cdot x + d = b \cdot y$, IAA yields optimal values for S_1 and S_2, i.e., $0 < S_1 < a$, and $0 < S_2 < b$.*

Proof of Lemma 1. First, we note the ordering $a > b > r_1 > r_2 > \cdots > r_n = d \geq 1$.

Also, we have $r_{n-1} > S_{n+1} = 1$ and $r_{n-2} > q_n = S_n$ as a starter. Then using the last division equation, we have $r_{n-3} = r_{n-2} \cdot q_{n-1} + r_{n-1} > S_n \cdot q_{n-1} + S_{n+1} = S_{n-1}$, giving us $r_{n-3} > S_{n-1}$.

Continuing this to the next division equation, we get $r_{n-4} > S_{n-2}$. This procedure leads us to $r_0 > S_2$ and $r_{-1} > S_1$. Because $b = r_0$ and $a = r_{-1}$, we have proved the lemma. □

Lemma 2. *The optimal solution to $a \cdot x + d = b \cdot y$ is given by:*

$$x = [(-1)^n \cdot S_2] \bmod b,$$
$$y = [(-1)^n \cdot S_1] \bmod a.$$

Proof of Lemma 2. We start with the nth equation of *kuttaka* (sequence of divisions):

$$d = r_n = r_{n-2} - r_{n-1} \cdot q_n.$$

Because $S_{n+1} = 1$ and $S_n = q_n$, we can write the above as

$$d = r_{n-2} \cdot S_{n+1} - r_{n-1} \cdot S_n.$$

Substituting the equation for r_{n-1} above, we get

$$\begin{aligned} d &= r_{n-2} \cdot S_{n+1} - (r_{n-3} - r_{n-2} \cdot q_{n-1}) S_n \\ &= r_{n-2}(q_{n-1} \cdot S_n + S_{n+1}) - r_{n-3} \cdot S_n \\ &= r_{n-2} \cdot S_{n-1} - r_{n-3} \cdot S_n \\ &= (r_{n-3} \cdot S_n - r_{n-2} \cdot S_{n-1})(-1). \end{aligned}$$

Continuing the substitution for $r_{n-2}, r_{n-3}, \ldots$, we get successively

$$d = (r_{n-4} \cdot S_{n-1} - r_{n-3} \cdot S_{n-2})(-1)^2 \text{ and finally}$$
$$d = (a \cdot S_2 - b \cdot S_1)(-1)^{n-1}.$$

The last equation can be rewritten as

$$a \cdot S_2(-1)^n + d = b \cdot S_1(-1)^n.$$

A solution to $ax + d = b\,y$ follows easily from the above as

$$x = S_2(-1)^n,$$
$$y = S_1(-1)^n.$$

From Lemma 1 we note that $0 < S_1 < a$ and $0 < S_2 < b$. Consider placing $\bmod b$ and $\bmod a$ to the above equations respectively. When n is even that makes no difference. When n is odd, it amounts to adding b to $-S_2$ and a to $-S_1$, which amounts to adding $a \cdot b$ to both sides of the equation, while making x and y positive optimal values. This completes the proof. □

A few examples will illustrate the application of *kuttaka* and the preceding lemmas.

Example 9. $17x + 1 = 4y$.

By using *kuttaka* and the IAA, we obtain $S_1 = 4$, $S_2 = 1$, and $n = 1$. As one solution we have $17(-1)+1 = 4(-4)$. Taking the respective moduli, we have $-1 \bmod 4 = 3$ and $-4 \bmod 17 = 13$, giving us the optimal solution $17 \cdot 3+1 = 4 \cdot 13$.

Example 10. $7x + 1 = 4y$.

By using *kuttaka* and the IAA, we obtain $S_1 = 2$, $S_2 = 1$, and $n = 2$. As one solution we have $7(1) + 1 = 4(2)$. Here both values for $x = 1$ and $y = 2$ are optimal.

For a more general case, let us make $c = 11$ in the above example.

Example 11. $7x + 11 = 4y$.

Multiplying the previous solution by 11, we get $7 \cdot 11+11 = 4 \cdot (2 \cdot 11)$. To obtain an optimal solution, we may apply the modular reduction $11 \bmod 4 = 3$ and $22 \bmod 7 = 1$. Then we get $7 \cdot 3 + 11 = 4 \cdot 1$, clearly a false solution. The correct way to get an optimal solution is to subtract (or add) a suitable multiple of $a \cdot b$ to both sides of the equation to obtain an optimal value for either x or y. If we subtract $2ab$ from both sides, then we have $7 \cdot (11 - 2 \cdot 4) + 11 = 4 \cdot (22 - 2 \cdot 7)$, yielding $7 \cdot 3 + 11 = 4 \cdot 8$, a correct solution. Here the solution is optimal, as $x = 3$ is optimal. Note that, in this case, $y = 8$ is not optimal but the solution is optimal by Definition 1.

Proof of Theorem 1. As an easy extension to the general case $a \cdot x + c = b \cdot y$ (for c, a multiple of d), we have a solution $x' = (-1)^n \cdot S_2(c/d)$ and $y' = (-1)^n \cdot S_1(c/d)$. Here x' and y' may not be optimal. To obtain an optimal solution, we consider adding kb to x' and ka to y' such that at least one of them becomes optimal. For that we first take modular reduction $x = x' \bmod b$. Then $x = x' + kb$ for some k. To balance the equation we take $y = y' + ka$. This proves Theorem 1.

Theorem 1. *An optimal solution to $a \cdot x + c = b \cdot y$ is given by:*

$$x = [(-1)^n \cdot S_2(c/d)] \bmod b,$$
$$y = (-1)^n \cdot S_1(c/d) + ka, \text{ where } k = \{x - [(-1)^n \cdot S_2(c/d)]\}/b.$$

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