Z. Angew. Math. Phys. (2024) 75:160 -c 2024 The Author(s), under exclusive licence to Springer Nature Switzerland AG https://doi.org/10.1007/s00033-024-02303-x

Zeitschrift für angewandte **Mathematik und Physik ZAMP**



# **Global classical solutions to an indirect chemotaxis-consumption model with signaldependent degenerate diffusion and logistic source**

Meng Zheng and Liangchen Wang

**Abstract.** This paper deals with the following indirect chemotaxis-consumption model with signal-dependent degenerate diffusion and logistic source



under homogeneous Neumann boundary conditions in a smooth bounded domain  $\Omega \subset \mathbb{R}^n$  ( $n \geq 1$ ). Here, the parameters  $a > 0$ ,  $b > 0$ ,  $\alpha \ge 1$ ,  $\delta > 0$  and  $l \ge 2$ . For all suitably regular initial data, if one of the following cases holds:

- (i)  $l > 2$ ;
- (ii)  $l = 2, n \leq 3;$
- (iii)  $l = 2, n \geq 4$ , and b is sufficiently large, then the corresponding initial boundary value problem possesses a global classical solution.

**Mathematics Subject Classification.** 35K35, 92C17, 35A01, 35B40.

**Keywords.** Indirect chemotaxis-consumption, Degenerate diffusion, Signal-dependent motility.

# **1. Introduction**

In 1971, Keller and Segel [\[16](#page-16-0)] proposed the following well-known Keller–Segel model

<span id="page-0-0"></span>
$$
\begin{cases} u_t = \Delta u - \chi \nabla \cdot (u \nabla v) + f(u), & x \in \Omega, t > 0, \\ v_t = \Delta v - uv, & x \in \Omega, t > 0, \end{cases}
$$
\n(1.1)

where  $u = u(x, t)$  represents the density of the bacteria,  $v = v(x, t)$  denotes the oxygen concentration,  $\chi \in$ R represents the chemotactic sensitivity coefficient. When the logistic source vanishes (i.e.,  $f(u) = 0$ ), Tao [\[32](#page-17-0)] showed that [\(1.1\)](#page-0-0) has global bounded classical solution under the conditions  $||v_0||_{L^{\infty}(\Omega)} \leq \frac{1}{6(n+1)\chi}$ .<br>The end Winkley [34] preved that (1.1) educts at least are global week solution in a three dimensional Tao and Winkler [\[34\]](#page-17-1) proved that [\(1.1\)](#page-0-0) admits at least one global weak solution in a three-dimensional domain which becomes smooth after some waiting time. The large time behavior of [\(1.1\)](#page-0-0) has also been studied by Zhang and Li [\[57](#page-17-2)]. When  $f(u) = ku - \mu u^2$ ,  $k \in \mathbb{R}, \mu > 0$ , Lankeit and Wang [\[18\]](#page-16-1) found that  $(1.1)$  has global bounded classical solutions for sufficiently large  $\mu$  and weak solutions exist for any  $\mu > 0$ . Furthermore, researchers have studied a modified version of system [\(1.1\)](#page-0-0) (see [\[46](#page-17-3)[–49\]](#page-17-4)).

In view of  $(1.1)$ , it is important to note that the utilization of the chemotaxis signal by cells may be more intricate in real-world scenarios. The signal could originate from external substances, be indirectly

generated, or even consist of multiple signals generated through diverse mechanisms  $(35)$ . In particular, a chemotaxis system with indirect signal consumption has been considered in [\[4](#page-16-3)]:

<span id="page-1-0"></span>
$$
\begin{cases}\n u_t = \Delta u - \nabla \cdot (u \nabla v) + f(u), \, x \in \Omega, t > 0, \\
 v_t = \Delta v - v w, & x \in \Omega, t > 0, \\
 w_t = -\delta w + u, & x \in \Omega, t > 0,\n\end{cases} \tag{1.2}
$$

where  $\delta > 0$  is a constant. When  $f(u) = 0$ , Fuest [\[4\]](#page-16-3) proved that either  $n \leq 2$  or  $n \geq 3$  with  $||v_0||_{L^{\infty}(\Omega)} \leq$  $\frac{1}{3n}$ , [\(1.2\)](#page-1-0) possesses global bounded classical solutions which converges to a spatially constant equilibrium in the large time. When  $f(u) = \mu u(1-u)$ ,  $\mu > 0$ , if  $\mu$  is suitably large, global existence of classical solutions has been established in Li et al. [\[26\]](#page-16-4). In addition, numerous findings pertain to the qualitative analysis of indirect signal mechanisms (see  $[8,12,21]$  $[8,12,21]$  $[8,12,21]$  $[8,12,21]$ ).

It is widely recognized that chemotaxis systems with signal-dependent motility have garnered significant attention in the recent literature  $[11,27]$  $[11,27]$  $[11,27]$ . Firstly, let us introduce the following Keller–Segelproduction models with signal-dependent motility

<span id="page-1-1"></span>
$$
\begin{cases}\n u_t = \Delta(\gamma(v)u) + f(u), \, x \in \Omega, t > 0, \\
 v_t = \Delta v - v + u, \quad x \in \Omega, t > 0.\n\end{cases} \tag{1.3}
$$

In the case of the absence of the logistic source (i.e.,  $f(u) = 0$ ), under the assumption that  $\gamma(s)$  has a positive lower and upper bounds (i.e.,  $k_{\gamma} \leq \gamma(s) \leq K_{\gamma}$  for all  $s \geq 0$ , where  $k_{\gamma}, K_{\gamma} > 0$ ), Tao and Winkler [\[38](#page-17-6)] showed that [\(1.3\)](#page-1-1) possesses global bounded classical solutions in two dimensions and global weak solutions in high dimensions. In particular, such weak solution will eventually become smooth in threedimensional settings. For the particular case  $\gamma(s) = c_0/s^k(c_0, k > 0)$ , the existence of global classical solutions has been studied in [\[56\]](#page-17-7) if  $c_0$  is small enough. If the motility function  $\gamma(s) = s^{-\alpha}$  with  $\alpha > 0$ , global existence of classical solutions was shown in  $[1,6,10,14,43]$  $[1,6,10,14,43]$  $[1,6,10,14,43]$  $[1,6,10,14,43]$  $[1,6,10,14,43]$  $[1,6,10,14,43]$  $[1,6,10,14,43]$ . Moreover, global weak solutions in lower dimensions ( $n \leq 3$ ) were obtained in [\[3\]](#page-16-14). If the motility function  $\gamma(s) = e^{-s}$  for all  $s \geq 0$ , certain critical mass phenomenon of  $(1.3)$  in the two-dimensional case has been detected in  $[7,15]$  $[7,15]$ . For another results on  $(1.3)$ , we refer to  $[2,9,50]$  $[2,9,50]$  $[2,9,50]$  $[2,9,50]$ .

When  $f(u) = \mu u (1 - u)$ ,  $\mu > 0$  and  $\gamma(s)$  satisfies  $\gamma(s) > 0$ ,  $\gamma'(s) < 0$  and  $\lim_{s \to +\infty} \frac{\gamma'(s)}{\gamma(s)}$  exists, Jin et al. [\[13\]](#page-16-19) obtained the global classical solution of [\(1.3\)](#page-1-1) in two-dimensional settings. Moreover, if  $\mu > \frac{K_0}{16}$ with  $K_0 = \max_{0 \le v \le \infty}$  $\frac{|\gamma'(s)|^2}{\gamma(s)}$ , the asymptotic stability was established. The similar result was proved in the higher dimensions in [\[25](#page-16-20)[,40](#page-17-10)]. When  $f(u) = \rho u - \mu u^l$ ,  $\rho \in \mathbb{R}, \mu > 0$ , global classical solutions was showed<br>in [29,30] if  $l > \max_{\rho} l \frac{n+2}{2}$  2]. There are some other results on (1.3), see [5,31] in [\[29](#page-17-11),[30\]](#page-17-12) if  $l > \max\left\{\frac{n+2}{2}, 2\right\}$ . There are some other results on [\(1.3\)](#page-1-1), see [\[5](#page-16-21)[,31](#page-17-13)].<br>Whereas if the signal is degraded rather than produced by the cells, the

Whereas if the signal is degraded, rather than produced, by the cells, the chemotaxis-consumption with signal-dependent motility has also been considered

<span id="page-1-2"></span>
$$
\begin{cases}\n u_t = \Delta(\gamma(v)u) + f(u), \, x \in \Omega, t > 0, \\
 v_t = \Delta v - uv, \quad x \in \Omega, t > 0.\n\end{cases} \tag{1.4}
$$

In the case of vanishing logistic source (i.e.,  $f(u) = 0$ ), if  $\gamma \in C^3([0, +\infty))$  is positive on  $[0, +\infty)$ , by constructing a weighted integral function, Li and Zhao [\[20](#page-16-22)] found that [\(1.4\)](#page-1-2) has global bounded classical solutions if  $||v_0||_{L^{\infty}(\Omega)}$  is sufficiently small. Li and Winkler [\[23](#page-16-23)] showed that [\(1.4\)](#page-1-2) possesses global classical bounded solutions without the smallness assumption of  $v_0$  when  $n \leq 2$  and global weak solutions when  $n \geq 3$ , such weak solutions become eventually smooth in the three-dimensional setting. If  $\gamma \in C^0([0, +\infty))$ is positive on  $[0, +\infty)$ , [\(1.4\)](#page-1-2) admits global very weak solutions for all  $n \ge 1$  [\[24\]](#page-16-24). If the motility function  $\gamma(s) = s^{-\alpha}, \alpha > 0$ , Tao and Winkler [\[39\]](#page-17-14) obtained that there exists a very weak-strong solution; under the additional restrictions that  $2 \le n \le 5$  and  $\alpha > \frac{n-2}{6-n}$ , [\(1.4\)](#page-1-2) has global weak solutions. If the motility function  $\alpha(a) = a^{\alpha}, \alpha > 0$  for all  $a > 0$ , there are some appthent results in [52, 55] function  $\gamma(s) = s^{\alpha}, \alpha > 0$  for all  $s \geq 0$ , there are some another results in [\[52](#page-17-15)[–55](#page-17-16)].

When  $f(u) = \mu u(1-u)$ , the global classical solutions in two dimensions for any  $\mu > 0$  and in the higher dimensions for large  $\mu > 0$  were established in [\[22\]](#page-16-25). When  $f(u) = au - bu^{l}$   $(a, b > 0)$ , Wang [\[41\]](#page-17-17)

obtained that [\(1.4\)](#page-1-2) possesses global bounded classical solutions and then [\(1.4\)](#page-1-2) admits at least one global weak solution  $(n \ge 3)$ , which becomes smooth after some waiting time. If  $\gamma \in C^1([0,\infty)) \cap C^3((0,\infty))$  is positive on  $(0, +\infty)$  with  $\alpha \ge 1$ , then global classical solutions can be established in [42]. On the other positive on  $(0, +\infty)$  with  $\alpha \ge 1$ , then global classical solutions can be established in [\[42\]](#page-17-18). On the other<br>hand if  $\gamma$  has rather mild regularities, then (1.4) admits at least one global weak solution in case  $\alpha > 0$ hand, if  $\gamma$  has rather mild regularities, then [\(1.4\)](#page-1-2) admits at least one global weak solution in case  $\alpha > 0$ . In addition, then the above weak solutions become eventually smooth if  $\alpha > 1$ . Some scholars also consider addition, then the above weak solutions become eventually smooth if  $\alpha > 1$ . Some scholars also consider the system  $(1.4)$  in other situations, readers can refer to  $[19, 28]$  $[19, 28]$ .

Motivated by the above works, in this paper, we consider the following system

<span id="page-2-1"></span>
$$
\begin{cases}\n u_t = \Delta(uv^{\alpha}) + au - bu^l, & x \in \Omega, \quad t > 0, \\
 v_t = \Delta v - vw, & x \in \Omega, \quad t > 0, \\
 w_t = -\delta w + u, & x \in \Omega, \quad t > 0, \\
 \frac{\partial u}{\partial \nu} = \frac{\partial v}{\partial \nu} = 0, & x \in \partial\Omega, \quad t > 0, \\
 u(x, 0) = u_0(x), v(x, 0) = v_0(x), w(x, 0) = w_0(x), x \in \Omega,\n\end{cases}
$$
\n(1.5)

in a smooth bounded domain  $\Omega \subset \mathbb{R}^n$   $(n \ge 1)$ , where  $a > 0, b > 0, \delta > 0, l \ge 2, \alpha \ge 1$ . The initial data

<span id="page-2-0"></span>
$$
\begin{cases}\nu_0 \in C^0(\Omega) & \text{is nonnegative in } \Omega, \\
v_0 \in W^{1,\infty}(\Omega) & \text{is positive in } \Omega \text{ and} \\
w_0 \in W^{1,\infty}(\Omega) & \text{is nonnegative in } \Omega.\n\end{cases}
$$
\n(1.6)

<span id="page-2-3"></span>**Theorem 1.1.** *Let*  $\Omega \subset \mathbb{R}^n (n \geq 1)$  *be a bounded domain with smooth boundary. Suppose that*  $a > 0, b > 0$ *,*  $\delta > 0$  and  $\alpha > 1$ , and that the initial data  $(u_0, v_0, w_0)$  satisfy [\(1.6\)](#page-2-0). If one of the following cases holds:

- 
- *(i)*  $l > 2$ *;*<br>*(ii)*  $l = 2, n \leq 3$ *;*  $(iii)$   $l = 2, n \leq 3;$

*(iii)*  $l = 2, n \ge 4$ , and  $b > (\frac{n-2}{2})^{\frac{n+2}{n}} (n+\sqrt{n})^{\frac{4}{n}} (n-1)^{-\frac{2}{n}} \alpha^{\frac{2(n+2)}{n}} ||v_0||$  $\frac{\alpha(n+2)-2}{n}$ <br> *L*∞(Ω)
<br>  $\frac{(n+2)(n-1)^{\frac{n}{2}}\delta^{\frac{n+2}{2}}}{(n+2)(n-1)^{\frac{n}{2}}\delta^{\frac{n+2}{2}}}$  $||v_0||_{L^{\infty}(\Omega)}$ , then one can find nonnegative functions

$$
\begin{cases} u \in C^{0}(\overline{\Omega} \times [0, \infty)) \cap C^{2,1}(\overline{\Omega} \times (0, \infty)), \\ v \in \bigcap_{\theta > n} C^{0}([0, \infty); W^{1,\theta}(\Omega)) \cap C^{2,1}(\overline{\Omega} \times (0, \infty)), \\ w \in C^{0}(\overline{\Omega} \times [0, \infty)) \cap C^{0,1}(\overline{\Omega} \times (0, \infty)), \end{cases}
$$

such that  $(u, v, w)$  solves the problem  $(1.5)$  in the classical sense.

This paper is arranged as follows. In Sect. [2,](#page-2-2) we will get some preliminary inequalities and some basic lemmas. Some estimates of the solution and the proof of Theorem [1.1](#page-2-3) are shown in Sect. [3.](#page-6-0)

## <span id="page-2-2"></span>**2. Preliminaries**

<span id="page-2-4"></span>In this section, based on the well-established parabolic theory in [\[13](#page-16-19)[,33](#page-17-19)], we can obtain the local-in-time existence result of a classical solution of [\(1.5\)](#page-2-1).

**Lemma 2.1.** *Let*  $\Omega \subset \mathbb{R}^n (n \geq 1)$  *be a bounded domain with smooth boundary, and let*  $a, b, \delta, \alpha$  *be some positive constants. If the initial data fulfill* [\(1.6\)](#page-2-0)*, then there exist a triple* (u, v, w) *of nonnegative functions*

$$
\begin{cases}\nu \in C^{0}(\overline{\Omega} \times [0, T_{\max}))) \cap C^{2,1}(\overline{\Omega} \times (0, T_{\max})), \\
\nu \in \bigcap_{\theta > n} C^{0}([0, T_{\max}); W^{1, \theta}(\Omega)) \cap C^{2,1}(\overline{\Omega} \times (0, T_{\max})), \\
\omega \in C^{0}(\overline{\Omega} \times [0, T_{\max})) \cap C^{0,1}(\overline{\Omega} \times (0, T_{\max})),\n\end{cases}
$$

*which solves* [\(1.5\)](#page-2-1) *in the classical sense. Moreover, if*  $T_{\text{max}} < \infty$ *, we have* 

$$
\limsup_{t \nearrow T_{\max}} \|u(\cdot,t)\|_{L^{\infty}(\Omega)} = \infty.
$$

The following lemma can be easily obtained.

**Lemma 2.2.** *Let* [\(1.6\)](#page-2-0) *hold and*  $l > 1$ *. Then, there exists*  $C > 0$  *such that* 

<span id="page-3-0"></span>
$$
||u(\cdot,t)||_{L^{1}(\Omega)} \leq C \quad \text{for all } t \in (0,T_{\text{max}}), \tag{2.1}
$$

$$
0 \le v \le ||v_0||_{L^{\infty}(\Omega)} \quad \text{in } \Omega \times (0, T_{\text{max}}) \tag{2.2}
$$

*and*

<span id="page-3-2"></span>
$$
\int_{t}^{t+\tau} \int_{\Omega} u^{l} \le C \quad \text{for all } t \in (0, T_{\text{max}} - \tau), \tag{2.3}
$$

where  $\tau := \min\left\{1, \frac{1}{2}T_{\max}\right\}.$ 

*Proof.* Integrating the first Eq. in [\(1.5\)](#page-2-1), we have

<span id="page-3-1"></span>
$$
\frac{d}{dt} \int_{\Omega} u = a \int_{\Omega} u - b \int_{\Omega} u^{l} \le a \int_{\Omega} u - b |\Omega|^{1-l} \left( \int_{\Omega} u \right)^{l} \tag{2.4}
$$

for all  $t \in (0, T_{\text{max}})$ . Then, an ODE comparison argument implies [\(2.1\)](#page-3-0). Consequently, an integration of (2.4) shows (2.3). From the nonnegativity v, w and the maximum principle, we derive (2.2).  $(2.4)$  shows  $(2.3)$ . From the nonnegativity v, w and the maximum principle, we derive  $(2.2)$ .

In order to prove our main results later, we quote a basic property of parabolic Eq. in [\[17](#page-16-28), Lemma 1.2] (see also [\[21](#page-16-7)]).

<span id="page-3-4"></span>**Lemma 2.3.** *Let*  $T \in (0, +\infty)$ *. Suppose that*  $z_0 \in W^{1,\infty}(\Omega)$ *, and that*  $z \in C^0(\overline{\Omega} \times [0, T)) \cap C^{2,1}(\overline{\Omega} \times (0, T))$ *is the solution of*

$$
\begin{cases}\n z_t = \Delta z - zg, & x \in \Omega, t \in (0, T), \\
\frac{\partial z}{\partial \nu} = 0, & x \in \partial \Omega, t \in (0, T), \\
 z(x, 0) = z_0(x), x \in \Omega,\n\end{cases}
$$

*where*  $g \in C^0(\overline{\Omega} \times (0,T))$  *satisfies*  $g \in L^{\infty}((0,T); L^p(\Omega))$  *with*  $p > 0$ *. Then for each* 

$$
r \in \left\{ \begin{bmatrix} 1, \frac{np}{n-p} \\ 1, \infty \end{bmatrix} \text{ if } p \le n, \right.
$$

*there exists a constant* C > <sup>0</sup> *such that*

$$
||z(\cdot,t)||_{W^{1,r}(\Omega)} \leq C \quad \text{for all} \quad t \in (0,T).
$$

<span id="page-3-3"></span>The following auxiliary statement on a boundedness property will be used in the time-independent estimates (see [\[37](#page-17-20), Lemma 3.2]).

**Lemma 2.4.** *Let*  $T > 0$ *,*  $t_0 \in (0, T)$ *,*  $a > 0$ *,*  $b > 0$ *. Suppose that*  $y : [0, T) \rightarrow [0, \infty)$  *is absolutely continuous and that*

$$
y'(t) + ay(t) \le h(t) \quad \text{for a.e.} \quad t \in (0, T),
$$

*where h is a nonnegative function in*  $L_{loc}^l([0, T))$  *satisfying* 

$$
\int_{t}^{t+t_0} h(s)ds \leq b \quad t \in [0, T-t_0).
$$

*Then, we have*

$$
y(t) \le \max\left\{y(0) + b, \frac{b}{at_0} + 2b\right\}
$$
 forall  $t \in (0, T)$ .

 $\Box$ 

<span id="page-4-5"></span>Next, we shall collect two lemmas that will be frequently used later.

**Lemma 2.5.** ( [\[51,](#page-17-21) Lemma 3.4]) *Let*  $q \ge 2$  *and*  $ψ ∈ C^2(\overline{\Omega})$  *be positive fulfilling*  $\frac{\partial ψ}{\partial υ} = 0$  *on*  $\partial Ω$ *. Then, we obtain obtain*

$$
\int_{\Omega} \psi^{-q-1} |\nabla \psi|^{q+2} \le (q+\sqrt{n})^2 \int_{\Omega} \psi^{-q+3} |\nabla \psi|^{q-2} |D^2 \ln \psi|^2
$$

*and*

$$
\int_{\Omega} \psi^{-q+1} |\nabla \psi|^{q-2} |D^2 \psi|^2 \le (q+\sqrt{n}+1)^2 \int_{\Omega} \psi^{-q+3} |\nabla \psi|^{q-2} |D^2 \ln \psi|^2.
$$

<span id="page-4-6"></span>**Lemma 2.6.** ( [\[51,](#page-17-21) Lemma 3.5]) Let  $q \geq 2$  and  $\eta > 0$ . There is  $C = C(q, \eta) > 0$  such that every positive  $\psi \in C^2(\overline{\Omega})$  *with*  $\frac{\partial \psi}{\partial \nu} = 0$  *on*  $\partial \Omega$  *satisfies* 

$$
\int_{\partial\Omega} \psi^{-q+1} |\nabla \psi|^{q-2} \frac{\partial |\nabla \psi|^2}{\partial \nu} \le \eta \int_{\Omega} \psi^{-q-1} |\nabla \psi|^{q+2} + \eta \int_{\Omega} \psi^{-q+1} |\nabla \psi|^{q-2} |D^2 \psi|^2 + C \int_{\Omega} \psi.
$$

Combining [\(2.3\)](#page-3-2) and Lemma [2.4,](#page-3-3) we can derive the boundedness of  $\int_{\Omega} w^l(\cdot, t)$  with  $l > 1$ . Ω

**Lemma 2.7.** *If* [\(1.6\)](#page-2-0) *and*  $l > 1$  *hold, then there exists*  $C > 0$  *such that* 

<span id="page-4-0"></span>
$$
\int_{\Omega} w^{l}(\cdot, t) \le C \quad \text{for all} \quad t \in (0, T_{\text{max}}). \tag{2.5}
$$

*Proof.* We test the w-equation of  $(1.5)$  by  $w^{l-1}$  and integrate to obtain

$$
\frac{1}{l} \frac{d}{dt} \int_{\Omega} w^{l} = -\delta \int_{\Omega} w^{l} + \int_{\Omega} u w^{l-1}
$$
\n
$$
\leq -\delta \int_{\Omega} w^{l} + \frac{\delta}{2} \int_{\Omega} w^{l} + \frac{l-1}{l} \left(\frac{\delta l}{2}\right)^{\frac{1}{1-l}} \int_{\Omega} u^{l}
$$
\n(2.6)

for all  $t \in (0, T_{\text{max}})$ . Combining  $(2.3)$  and Lemma [2.4,](#page-3-3) we obtain  $(2.5)$ 

By a transformation  $z(x,t) = -\ln \frac{v(x,t)}{\|v_0\|_{L^\infty(\Omega)}}$ , we can construct a time-dependent pointwise lower bound for v. The ideas come from [\[42](#page-17-18),[45\]](#page-17-22).

<span id="page-4-4"></span>**Lemma 2.8.** *Let* [\(1.6\)](#page-2-0) *hold and*  $n \geq 1$ *. For some*  $p > \frac{n}{2}$ *, assume that there exists*  $C_1 > 0$  *satisfying* 

<span id="page-4-2"></span> $||w(\cdot, t)||_{L^p(\Omega)} \leq C_1$  for all  $t \in (0, T_{\text{max}}).$  (2.7)

*Then, given any*  $T \in (0, T_{\text{max}})$  *there exists*  $C_2(T) > 0$  *such that* 

<span id="page-4-3"></span>
$$
v(x,t) \ge C_2(T) \quad \text{for all} \quad t \in (0,T). \tag{2.8}
$$

*Proof.* Let  $z(x,t) = -\ln \frac{v(x,t)}{\|v_0\|_{L^{\infty}(\Omega)}}$ . Then, using the second equation of [\(1.5\)](#page-2-1), we derive

<span id="page-4-1"></span>
$$
\begin{cases}\n z_t = \Delta z - |\nabla z|^2 + w, & x \in \Omega, t \in (0, T_{\text{max}}), \\
 \frac{\partial z}{\partial \nu} = 0, & x \in \partial\Omega, t \in (0, T_{\text{max}}), \\
 z(x, 0) = z_0(x) = -\ln \frac{v_0(x)}{\|v_0\|_{L^\infty(\Omega)}}, x \in \Omega.\n\end{cases}
$$
\n(2.9)

On the basis of the variation-of-constants formula of  $(2.9)$ , using the nonnegativity of w and a comparison principle, we have

$$
z(\cdot, t) = e^{\Delta t} z_0 - \int_0^t e^{(t-s)\Delta} |\nabla z|^2 + \int_0^t e^{(t-s)\Delta} w(\cdot, s) ds
$$
  

$$
\leq e^{\Delta t} z_0 + \int_0^t e^{(t-s)\Delta} w(\cdot, s) ds
$$

for all  $t \in (0, T_{\text{max}})$ . Then by virtue of [\(2.7\)](#page-4-2) and the smoothing properties of Neumann heat semigroup  $(e^{\Delta t})_{t\geq 0}$  on  $\Omega$  ([\[44](#page-17-23), Lemma 1.3]), we infer the existences of  $c_1 > 0$  and  $c_2 > 0$  such that

<span id="page-5-0"></span>
$$
||z(\cdot,t)||_{L^{\infty}(\Omega)} \le ||e^{t\Delta}z_0||_{L^{\infty}(\Omega)} + \int_{0}^{t} ||e^{(t-s)\Delta}w(\cdot,s)||_{L^{\infty}(\Omega)} ds
$$
  

$$
\le ||z_0||_{L^{\infty}(\Omega)} + c_1 \int_{0}^{t} \left\{1 + (t-s)^{-\frac{n}{2p}}\right\} ||w(\cdot,s)||_{L^p(\Omega)} ds
$$
  

$$
\le ||z_0||_{L^{\infty}(\Omega)} + c_2 \int_{0}^{t} \left(1 + \sigma^{-\frac{n}{2p}}\right) d\sigma
$$
 (2.10)

for all  $t \in (0, T_{\text{max}})$ . Hence, thanks to  $p > \frac{n}{2}$ , for any  $T \in (0, T_{\text{max}})$ ,  $(2.10)$  in conjunction with  $(2.11)$ <br>implies that one can find some  $c_2(T, n) > 0$  fulfilling implies that one can find some  $c_3(T,p) > 0$  fulfilling

<span id="page-5-2"></span><span id="page-5-1"></span>
$$
||z(\cdot,t)||_{L^{\infty}(\Omega)} \le c_3(T,p) \quad \text{for all } t \in (0,T). \tag{2.11}
$$

Then according to the definition of  $z(\cdot, t)$ , we can readily obtain [\(2.8\)](#page-4-3).

<span id="page-5-6"></span>With the lower bound of  $v$  at hand, we can show local boundedness criterion of solutions of  $(1.5)$ .

**Lemma 2.9.** Let (1.6) hold. For all 
$$
n \ge 1
$$
, assume that there exist  $C > 0$  and  $q \ge 1$  with  $q > \frac{n}{2}$  such that  $||u(\cdot, t)||_{L^q(\Omega)} \le C$  for all  $t \in (0, T_{\text{max}}).$  (2.12)

*Then for all*  $T \in (0, T_{\text{max}})$ *, one can find*  $C(T) > 0$  *such that* 

<span id="page-5-5"></span>
$$
||u(\cdot,t)||_{L^{\infty}(\Omega)} + ||v(\cdot,t)||_{W^{1,\infty}(\Omega)} + ||w(\cdot,t)||_{L^{\infty}(\Omega)} \le C(T) \quad \text{ for all } t \in (0,T). \tag{2.13}
$$

*Proof.* We may test the third equation in [\(1.5\)](#page-2-1) by  $qw^{q-1}$  and use Young's inequality to find some  $c_1 > 0$ such that

<span id="page-5-3"></span>
$$
\frac{d}{dt} \int_{\Omega} w^q = -q \delta \int_{\Omega} w^q + q \int_{\Omega} u w^{q-1}
$$
\n
$$
\leq -\frac{q \delta}{2} \int_{\Omega} w^q + c_1 \int_{\Omega} u^q \tag{2.14}
$$

for all  $t \in (0, T_{\text{max}})$ . Using [\(2.12\)](#page-5-2) and [\(2.14\)](#page-5-3), we can show that there exists a constant  $c_2 > 0$  fulfilling

<span id="page-5-4"></span>
$$
\int_{\Omega} w^q \le c_2 \quad \text{for all } t \in (0, T_{\text{max}}). \tag{2.15}
$$

Because  $q > \frac{n}{2}$ , we have  $\frac{nq}{(n-q)+} > n$ . Thus, we can pick  $\theta > \max\left\{1, \frac{n}{2}\right\}$  such that  $\frac{nq}{(n-q)+} > 2\theta > n$ . An application of [\(2.15\)](#page-5-4) and Lemma [2.3](#page-3-4) implies that there exists  $c_3 > 0$  such that  $\|\nabla v(\cdot,t)\|_{L^{2\theta}(\Omega)} \leq c_3$  for all  $t \in (0, T_{\text{max}})$ . Moreover, [\(2.15\)](#page-5-4) in conjunction with Lemma [2.8](#page-4-4) shows that for any  $T \in (0, T_{\text{max}})$ , we can find  $c_4(T) > 0$  fulfilling  $v \geq c_4(T)$  in  $\Omega \times (0, T)$ .

For all  $p > 1$ , multiplying the first equation of [\(1.5\)](#page-2-1) by  $u^{p-1}$  and using Young's inequality, we end up with

<span id="page-6-1"></span>
$$
\frac{d}{dt} \int_{\Omega} u^p + \frac{c_4^{\alpha}(T)p(p-1)}{2} \int_{\Omega} u^{p-2} |\nabla u|^2 + \int_{\Omega} u^p \le \frac{\alpha^2 c_5(T)p(p-1)}{2} \int_{\Omega} u^p |\nabla v|^2 + (ap+1) \int_{\Omega} u^p
$$
\n(2.16)

for all  $t \in (0, T)$ , where  $c_5(T) := \max\left\{c_4^{\alpha-2}(T), \|v_0\|_{L^{\infty}(\Omega)}^{\alpha-2}\right\}$ . Regarding for  $\theta > \max\left\{1, \frac{n}{2}\right\}$ , thus  $\frac{2\theta}{\theta-1} <$  $\frac{2n}{(n-2)_+}$ , by an Ehrling-type inequality and [\(2.1\)](#page-3-0), there exists a positive constant  $c_6(p,T)$  such that

<span id="page-6-2"></span>
$$
\frac{\alpha^2 c_5(T)p(p-1)}{2} \int_{\Omega} u^p |\nabla v|^2 + (ap+1) \int_{\Omega} u^p \le \frac{\alpha^2 c_5(T)p(p-1)}{2} ||u^{\frac{p}{2}}||^2_{L^{\frac{2\theta}{\theta-1}}(\Omega)} ||\nabla v||^2_{L^{2\theta}(\Omega)}
$$
  
+ 
$$
(ap+1)||u^{\frac{p}{2}}||^2_{L^2(\Omega)} \le \frac{\alpha^2 c_3^2 c_5(T)p(p-1)}{2} ||u^{\frac{p}{2}}||^2_{L^{\frac{2\theta}{\theta-1}}(\Omega)}
$$
  
+ 
$$
(ap+1)||u^{\frac{p}{2}}||^2_{L^2(\Omega)} \le \frac{c_4^{\alpha}(T)p(p-1)}{2} \int_{\Omega} |\nabla u^{\frac{p}{2}}|^2 + c_6(p,T)
$$
 (2.17)

for all  $t \in (0, T)$ . Combining [\(2.16\)](#page-6-1) and [\(2.17\)](#page-6-2), and using an ODE argument, we infer that there exists  $c_7(p,T) > 0$  satisfying  $||u(\cdot,t)||_{L^p(\Omega)} \leq c_7(p,T)$  for all  $t \in (0,T)$ . This along with Lemma [2.3](#page-3-4) implies that one can find some  $c_8(T) > 0$  such that

<span id="page-6-4"></span>
$$
||v(\cdot,t)||_{W^{1,\infty}(\Omega)} \le c_8(T) \quad \text{for all } t \in (0,T). \tag{2.18}
$$

Thus, according to [\[36,](#page-17-24) Lemma A.1], we can find a constant  $c_9(T) > 0$  satisfying

<span id="page-6-3"></span> $||u(\cdot, t)||_{L^{\infty}(\Omega)} \leq c_9(T)$  for all  $t \in (0, T)$ . (2.19)

Applying the variation-of-constants formula for  $w$ , we have

$$
w(\cdot, t) = e^{-\delta t} w_0 + \int_0^t e^{-\delta(t-s)} u(\cdot, s) \, ds \quad \text{for all} \quad t \in (0, T),
$$

which together with  $(2.19)$  implies that there exists  $c_{10}(T) > 0$  such that

<span id="page-6-5"></span>
$$
||w(\cdot,t)||_{L^{\infty}(\Omega)} \leq c_{10}(T) \quad \text{for all} \quad t \in (0,T). \tag{2.20}
$$

Hence, collecting  $(2.18)$ – $(2.20)$ , we can derive the claimed conclusion  $(2.13)$ .  $\Box$ 

### <span id="page-6-0"></span>**3. Proof of Theorem 1.1**

In this section, our goal is to obtain global classical solutions of  $(1.5)$ . To this end, we will establish certain integral inequalities of [\(1.5\)](#page-2-1). The ideas used in this section are mainly taken from [\[18,](#page-16-1)[42](#page-17-18)[,51](#page-17-21),[52\]](#page-17-15). We start with the following integral of the type  $\int_{\Omega} u^p$ . Ω

**Lemma 3.1.** *Let* [\(1.6\)](#page-2-0) *hold. We have*

<span id="page-6-6"></span>
$$
\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} u^p + \frac{p(p-1)}{2} \int_{\Omega} u^{p-2} v^{\alpha} |\nabla u|^2 \le \frac{\alpha^2 p(p-1)}{2} \int_{\Omega} u^p v^{\alpha-2} |\nabla v|^2 + ap \int_{\Omega} u^p - bp \int_{\Omega} u^{p+l-1} \tag{3.1}
$$

*for all*  $t \in (0, T_{\text{max}})$ .

*Proof.* We test the u-equation of  $(1.5)$  by  $u^{p-1}$  and use Young's inequality to obtain

$$
\frac{d}{dt} \int_{\Omega} u^p = -p(p-1) \int_{\Omega} u^{p-2} v^{\alpha} |\nabla u|^2 - \alpha p(p-1) \int_{\Omega} u^{p-1} v^{\alpha-1} \nabla u \cdot \nabla v
$$
\n
$$
+ ap \int_{\Omega} u^p - bp \int_{\Omega} u^{p+l-1}
$$
\n
$$
\leq -\frac{p(p-1)}{2} \int_{\Omega} u^{p-2} v^{\alpha} |\nabla u|^2 + \frac{\alpha^2 p(p-1)}{2} \int_{\Omega} u^p v^{\alpha-2} |\nabla v|^2
$$
\n
$$
+ ap \int_{\Omega} u^p - bp \int_{\Omega} u^{p+l-1}
$$

for all  $t \in (0, T_{\text{max}})$ . Hence, we obtain [\(3.1\)](#page-6-6).

Next we establish a differential inequality of  $\int$  $\int_{\Omega} v^{-q+1} |\nabla v|^q$  for all  $q \ge 2$ . This idea comes from [\[42](#page-17-18),[51\]](#page-17-21), which is the key to the proof of this paper.

**Lemma 3.2.** *If* [\(1.6\)](#page-2-0) *holds, then for all*  $q \geq 2$ *, we obtain* 

<span id="page-7-0"></span>
$$
\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} v^{-q+1} |\nabla v|^q + q(q-1) \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^2 \ln v|^2 \le \frac{q}{2} \int_{\partial \Omega} v^{-q+1} |\nabla v|^{q-2} \cdot \frac{\partial |\nabla v|^2}{\partial \nu}
$$
\n
$$
+ q(q-2+\sqrt{n}) \int_{\Omega} w v^{-q+2} |\nabla v|^{q-2} |D^2 v|
$$
\n(3.2)

*for all*  $t \in (0, T_{\text{max}})$ *.* 

*Proof.* Integrating by parts in the second Eq. in [\(1.5\)](#page-2-1) and using  $2\nabla v \cdot \nabla \Delta v = \Delta |\nabla v|^2 - 2 |D^2 v|$ 2 , we can find

$$
\frac{d}{dt} \int_{\Omega} v^{-q+1} |\nabla v|^q = q \int_{\Omega} v^{-q+1} |\nabla v|^{q-2} \nabla v \cdot \nabla (\Delta v - vw) - (q-1) \int_{\Omega} v^{-q} |\nabla v|^q (\Delta v - vw)
$$
\n
$$
= \frac{q}{2} \int_{\Omega} v^{-q+1} |\nabla v|^{q-2} \Delta |\nabla v|^2 - q \int_{\Omega} v^{-q+1} |\nabla v|^{q-2} |D^2 v|^2
$$
\n
$$
- q \int_{\Omega} v^{-q+1} |\nabla v|^q \, dv \cdot \nabla (vw)
$$
\n
$$
- (q-1) \int_{\Omega} v^{-q} |\nabla v|^q \Delta v + (q-1) \int_{\Omega} w v^{-q+1} |\nabla v|^q
$$
\n
$$
= q(q-1) \int_{\Omega} v^{-q} |\nabla v|^{q-2} \nabla v \cdot \nabla |\nabla v|^2 - q \int_{\Omega} v^{-q+1} |\nabla v|^{q-2} |D^2 v|^2
$$
\n
$$
- \frac{q(q-2)}{4} \int_{\Omega} v^{-q+1} |\nabla v|^{q-4} |\nabla |\nabla v|^2|^2 - q(q-1) \int_{\Omega} v^{-q-1} |\nabla v|^{q+2}
$$
\n
$$
+ \frac{q}{2} \int_{\partial \Omega} v^{-q+1} |\nabla v|^{q-2} \cdot \frac{\partial |\nabla v|^2}{\partial \nu} + \frac{q(q-2)}{2} \int_{\Omega} w v^{-q+2} |\nabla v|^{q-4} \nabla v \cdot \nabla |\nabla v|^2
$$

<span id="page-8-2"></span><span id="page-8-1"></span> $\Box$ 

<span id="page-8-0"></span>+ 
$$
q \int_{\Omega} w v^{-q+2} |\nabla v|^{q-2} \Delta v - (q-1)^2 \int_{\Omega} w v^{-q+1} |\nabla v|^q
$$
  
(3.3)

for all  $t \in (0, T_{\text{max}})$ . For the first four terms on the right of [\(3.3\)](#page-8-0), we use the pointwise identity ( [\[51,](#page-17-21) Lemma 3.2])

$$
|D^2 \ln \varphi|^2 = -\frac{1}{\varphi^3} \nabla \varphi \cdot \nabla |\nabla \varphi|^2 + \frac{1}{\varphi^2} |D^2 \varphi|^2 + \frac{1}{\varphi^4} |\nabla \varphi|^4 \quad \text{ for all positive } \varphi \in C^2(\overline{\Omega})
$$

and  $\nabla |\nabla v|^2 = 2D^2v \cdot \nabla v$  to obtain

$$
q(q-1)\int_{\Omega} v^{-q} |\nabla v|^{q-2} \nabla v \cdot \nabla |\nabla v|^{2} - q \int_{\Omega} v^{-q+1} |\nabla v|^{q-2} |D^{2}v|^{2}
$$
  
\n
$$
-\frac{q(q-2)}{4} \int_{\Omega} v^{-q+1} |\nabla v|^{q-4} |\nabla |\nabla v|^{2}|^{2} - q(q-1) \int_{\Omega} v^{-q-1} |\nabla v|^{q+2}
$$
  
\n
$$
= -q(q-1) \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} \left( -\frac{1}{v^{3}} \nabla v \cdot \nabla |\nabla v|^{2} + \frac{1}{v^{2}} |D^{2}v|^{2} + \frac{1}{v^{4}} |\nabla v|^{4} \right)
$$
  
\n
$$
= -q(q-1) \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^{2} \ln v|^{2}
$$
\n(3.4)

for all  $t \in (0, T_{\text{max}})$ . The sixth and seventh summands on the right-hand side of  $(3.3)$  can be estimated as follows:

$$
\frac{q(q-2)}{2} \int_{\Omega} w v^{-q+2} |\nabla v|^{q-4} \nabla v \cdot \nabla |\nabla v|^2 + q \int_{\Omega} w v^{-q+2} |\nabla v|^{q-2} \Delta v
$$
  

$$
\leq q (q-2+\sqrt{n}) \int_{\Omega} w v^{-q+2} |\nabla v|^{q-2} |D^2 v|
$$
(3.5)

for all  $t \in (0, T_{\text{max}})$ , because of  $|\Delta v| \leq \sqrt{n} |D^2 v|$ . Inserting [\(3.4\)](#page-8-1) and [\(3.5\)](#page-8-2) into [\(3.3\)](#page-8-0), we obtain [\(3.2\)](#page-7-0).

In the following, we will drive a differential estimate of the type  $\int$  $\int\limits_{\Omega} w^{p+1}.$ 

**Lemma 3.3.** *Let* [\(1.6\)](#page-2-0) *hold. Then for all*  $p > 1$ *, we have* 

<span id="page-8-4"></span>
$$
\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} w^{p+1} + \frac{(p+1)\delta}{2} \int_{\Omega} w^{p+1} \le \left(\frac{2}{\delta}\right)^p \int_{\Omega} u^{p+1} \quad \text{for all} \quad t \in (0, T_{\text{max}}). \tag{3.6}
$$

*Proof.* Testing the third equation in the model  $(1.5)$  by  $(p+1)w^p$ , we obtain

<span id="page-8-3"></span>
$$
\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} w^{p+1} + (p+1)\delta \int_{\Omega} w^{p+1} \le (p+1) \int_{\Omega} w^p u \tag{3.7}
$$

for all  $t \in (0, T_{\text{max}})$ . Applying Young's inequality, we have

<span id="page-9-0"></span>
$$
(p+1)\int_{\Omega} w^{p}u \leq \frac{(p+1)\delta}{2} \int_{\Omega} w^{p+1} + \left(\frac{2p}{(p+1)\delta}\right)^{p} \int_{\Omega} u^{p+1}
$$
  

$$
\leq \frac{(p+1)\delta}{2} \int_{\Omega} w^{p+1} + \left(\frac{2}{\delta}\right)^{p} \int_{\Omega} u^{p+1}
$$
 (3.8)

for all  $t \in (0, T_{\text{max}})$ . Plugging [\(3.8\)](#page-9-0) into [\(3.7\)](#page-8-3), we obtain [\(3.6\)](#page-8-4).  $\Box$ 

<span id="page-9-3"></span>The following differential inequality of  $\int_{\Omega} u^p + \int_{\Omega} v^{-q+1} |\nabla v|^q + \frac{8\kappa_1}{(q+2)\delta} \int_{\Omega}$  $\int_{\Omega} w^{\frac{q+2}{2}}$  with some  $p > 1, q \ge 2$ ,  $\kappa_1 > 0$  and  $\delta > 0$  can be constructed.

**Lemma 3.4.** *Assume that* [\(1.6\)](#page-2-0) *is valid,*  $\alpha \geq 1$  *and*  $l > 1$ *. Then for all*  $p > 1$  *and*  $q \geq 2$ *, there exists a constant* C > <sup>0</sup> *such that*

<span id="page-9-2"></span>
$$
\frac{d}{dt} \left( \int_{\Omega} u^{p} + \int_{\Omega} v^{-q+1} |\nabla v|^{q} + \frac{8\kappa_{1}}{(q+2)\delta} \int_{\Omega} w^{\frac{q+2}{2}} \right) + \int_{\Omega} u^{p} + \int_{\Omega} v^{-q+1} |\nabla v|^{q} + \kappa_{1} \int_{\Omega} w^{\frac{q+2}{2}} \right)
$$
\n
$$
\leq \frac{p(p-1)}{2} \left( \frac{q(q-1)}{2p(p-1)(q+\sqrt{n})^{2}} \right)^{-\frac{2}{q}} \alpha^{\frac{2(q+2)}{q}} \|v_{0}\|_{L^{\infty}(\Omega)}^{\frac{\alpha(q+2)-2}{q}} \int_{\Omega} u^{\frac{p(q+2)}{q}} \left( \frac{2}{\delta} \right)^{\frac{q}{2}} \int_{\Omega} u^{\frac{q+2}{2}} - \frac{bp}{2} \int_{\Omega} u^{p+l-1} + C \tag{3.9}
$$

*for all*  $t \in (0, T_{\max})$  *with*  $\kappa_1 := \frac{8^{\frac{q}{2}} q (q + \sqrt{n} + 1)^q (q - 2 + \sqrt{n})^{\frac{q+2}{2}} ||v_0||_{L^{\infty}(\Omega)}}{(q-1)^{\frac{q}{2}}}$ .

*Proof.* We only need to take a linear combination of  $(3.1)$  and  $(3.2)$  to get

<span id="page-9-1"></span>
$$
\frac{d}{dt} \left( \int_{\Omega} u^p + \int_{\Omega} v^{-q+1} |\nabla v|^q \right) + \int_{\Omega} u^p + \int_{\Omega} v^{-q+1} |\nabla v|^q
$$
\n
$$
+ q(q-1) \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^2 \ln v|^2
$$
\n
$$
\leq \frac{\alpha^2 p(p-1)}{2} \int_{\Omega} u^p v^{\alpha-2} |\nabla v|^2 + (ap+1) \int_{\Omega} u^p - bp \int_{\Omega} u^{p+l-1}
$$
\n
$$
+ q(q-2+\sqrt{n}) \int_{\Omega} w v^{-q+2} |\nabla v|^{q-2} |D^2 v|
$$
\n
$$
+ \frac{q}{2} \int_{\partial \Omega} v^{-q+1} |\nabla v|^{q-2} \cdot \frac{\partial |\nabla v|^2}{\partial \nu} + \int_{\Omega} v^{-q+1} |\nabla v|^q
$$
\n
$$
(3.10)
$$

for all  $t \in (0, T_{\text{max}})$ . We employ Young's inequality with any  $\mu_1 > 0$  and Lemma [2.5](#page-4-5) to estimate

<span id="page-10-0"></span>
$$
\frac{\alpha^2 p(p-1)}{2} \int_{\Omega} u^p v^{\alpha-2} |\nabla v|^2 \leq \frac{p(p-1)}{2} \mu_1^{\frac{q+2}{2}} \int_{\Omega} v^{-q-1} |\nabla v|^{q+2} \n+ \frac{p(p-1)}{2} \mu_1^{-\frac{q+2}{q}} \alpha^{\frac{2(q+2)}{q}} \int_{\Omega} u^{\frac{p(q+2)}{q}} v^{\frac{\alpha(q+2)-2}{q}} \n\leq \frac{p(p-1)(q+\sqrt{n})^2}{2} \mu_1^{\frac{q+2}{2}} \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^2 \ln v|^2 \n+ \frac{p(p-1)}{2} \mu_1^{-\frac{q+2}{q}} \alpha^{\frac{2(q+2)}{q}} ||v_0||_{L^{\infty}(\Omega)}^{\frac{\alpha(q+2)-2}{q}} \int_{\Omega} u^{\frac{p(q+2)}{q}}
$$
\n(3.11)

for all  $t \in (0, T_{\text{max}})$ . We pick  $\mu_1 = \left(\frac{q(q-1)}{2p(p-1)(q+\sqrt{n})^2}\right)$  $\int_{0}^{\frac{2}{q+2}}$  and use [\(3.11\)](#page-10-0) to see that

<span id="page-10-2"></span>
$$
\frac{\alpha^2 p(p-1)}{2} \int_{\Omega} u^p v^{\alpha-2} |\nabla v|^2 \le \frac{q(q-1)}{4} \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^2 \ln v|^2 \n+ \frac{p(p-1)}{2} \left( \frac{q(q-1)}{2p(p-1)(q+\sqrt{n})^2} \right)^{-\frac{2}{q}} \alpha^{\frac{2(q+2)}{q}} \|v_0\|_{L^{\infty}(\Omega)}^{\frac{\alpha(q+2)-2}{q}} \int_{\Omega} u^{\frac{p(q+2)}{q}} \qquad (3.12)
$$

for all  $t \in (0, T_{\text{max}})$ . Applying Young's inequality with any  $\mu_2 > 0$  and  $\mu_3 > 0$  and Lemma [2.5](#page-4-5) to the fourth term on the right hand of  $(3.10)$ , we have

<span id="page-10-1"></span>
$$
q(q - 2 + \sqrt{n}) \int_{\Omega} w v^{-q+2} |\nabla v|^{q-2} |D^2 v|
$$
  
\n
$$
\leq \mu_2 \int_{\Omega} v^{-q+1} |\nabla v|^{q-2} |D^2 v|^2 + \mu_2^{-1} q^2 (q - 2 + \sqrt{n})^2 \int_{\Omega} w^2 v^{-q+3} |\nabla v|^{q-2}
$$
  
\n
$$
\leq \mu_2 (q + \sqrt{n} + 1)^2 \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^2 \ln v|^2 + \mu_2^{-1} q^2 (q - 2 + \sqrt{n})^2 \mu_3^{\frac{q+2}{q-2}} \int_{\Omega} v^{-q-1} |\nabla v|^{q+2}
$$
  
\n
$$
+ \mu_2^{-1} q^2 (q - 2 + \sqrt{n})^2 \mu_3^{-\frac{q+2}{4}} \int_{\Omega} w^{\frac{q+2}{2}} v
$$
  
\n
$$
\leq (q + \sqrt{n} + 1)^2 \left\{ \mu_2 + \mu_2^{-1} q^2 (q - 2 + \sqrt{n})^2 \mu_3^{\frac{q+2}{4}} \right\} \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^2 \ln v|^2
$$
  
\n
$$
+ \mu_2^{-1} q^2 (q - 2 + \sqrt{n})^2 \mu_3^{-\frac{q+2}{4}} ||v_0||_{L^{\infty}(\Omega)} \int_{\Omega} w^{\frac{q+2}{2}}
$$
  
\n(3.13)

for all  $t \in (0, T_{\text{max}})$ . Letting  $\mu_2 = \frac{q(q-1)}{8(q+\sqrt{n}+1)^2}$ ,  $\mu_3 = \left(\frac{(q-1)^2}{64(q+\sqrt{n}+1)^4(q-2+\sqrt{n})^2}\right)$  $\int_{0}^{\frac{q-2}{q+2}}$  and using [\(3.13\)](#page-10-1), we know that

<span id="page-10-3"></span>
$$
q(q-2+\sqrt{n})\int_{\Omega}w v^{-q+2}|\nabla v|^{q-2}|D^2v| \leq \frac{q(q-1)}{4}\int_{\Omega}v^{-q+3}|\nabla v|^{q-2}|D^2\ln v|^2
$$

$$
+\frac{8^{\frac{q}{2}}q(q+\sqrt{n}+1)^q(q-2+\sqrt{n})^{\frac{q+2}{2}}\|v_0\|_{L^{\infty}(\Omega)}}{(q-1)^{\frac{q}{2}}}\int_{\Omega}w^{\frac{q+2}{2}}\tag{3.14}
$$

for all  $t \in (0, T_{\text{max}})$ . Inserting [\(3.12\)](#page-10-2) and [\(3.14\)](#page-10-3) into [\(3.10\)](#page-9-1), we conclude that

<span id="page-11-2"></span>
$$
\frac{d}{dt} \left( \int_{\Omega} u^{p} + \int_{\Omega} v^{-q+1} |\nabla v|^{q} \right) + \int_{\Omega} u^{p} + \int_{\Omega} v^{-q+1} |\nabla v|^{q} \n+ \frac{q(q-1)}{2} \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^{2} \ln v|^{2} \n\leq \frac{p(p-1)}{2} \left( \frac{q(q-1)}{2p(p-1)(q+\sqrt{n})^{2}} \right)^{-\frac{2}{q}} \alpha^{\frac{2(q+2)}{q}} ||v_{0}||_{L^{\infty}(\Omega)}^{\frac{\alpha(q+2)-2}{q}} \int_{\Omega} u^{\frac{p(q+2)}{q}} \n+ \frac{8^{\frac{q}{2}} q(q+\sqrt{n}+1)^{q} (q-2+\sqrt{n})^{\frac{q+2}{2}} ||v_{0}||_{L^{\infty}(\Omega)}}{(q-1)^{\frac{q}{2}}} \int_{\Omega} w^{\frac{q+2}{2}} \n+ \frac{q}{2} \int_{\partial\Omega} v^{-q+1} |\nabla v|^{q-2} \cdot \frac{\partial |\nabla v|^{2}}{\partial \nu} + \int_{\Omega} v^{-q+1} |\nabla v|^{q} + (ap+1) \int_{\Omega} u^{p} - bp \int_{\Omega} u^{p+l-1} \n+ \frac{q}{2} \int_{\partial\Omega} v^{-q+1} |\nabla v|^{q-2} \cdot \frac{\partial |\nabla v|^{2}}{\partial \nu} + \int_{\Omega} v^{-q+1} |\nabla v|^{q} + (ap+1) \int_{\Omega} u^{p} - bp \int_{\Omega} u^{p+l-1}
$$
\n(3.15)

for all  $t \in (0, T_{\text{max}})$ . An application of  $(2.2)$ , Lemmata [2.5,](#page-4-5) [2.6](#page-4-6) and Young's inequality shows that for any  $\eta > 0$ , there exists some  $c_1 > 0$  such that

<span id="page-11-0"></span>
$$
\frac{q}{2} \int_{\partial\Omega} v^{-q+1} |\nabla v|^{q-2} \cdot \frac{\partial |\nabla v|^2}{\partial \nu} \le \eta \int_{\Omega} v^{-q-1} |\nabla v|^{q+2} + \eta \int_{\Omega} v^{-q+1} |\nabla v|^{q-2} |D^2 v|^2 + c_1 \int_{\Omega} v
$$
\n
$$
\le 2(q + \sqrt{n} + 1)^2 \eta \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^2 \ln v|^2 + c_1 |\Omega| \|v_0\|_{L^\infty(\Omega)} \tag{3.16}
$$

and

$$
\int_{\Omega} v^{-q+1} |\nabla v|^{q} \leq \eta^{\frac{q+2}{q}} \int_{\Omega} v^{-q-1} |\nabla v|^{q+2} + \eta^{-\frac{q+2}{2}} \int_{\Omega} v
$$
\n
$$
\leq (q + \sqrt{n})^{2} \eta^{\frac{q+2}{q}} \int_{\Omega} v^{-q+3} |\nabla v|^{q-2} |D^{2} \ln v|^{2} + \eta^{-\frac{q+2}{2}} |\Omega| \|v_{0}\|_{L^{\infty}(\Omega)}
$$
\n(3.17)

for all  $t \in (0, T_{\text{max}})$ . Since  $l > 1$ , by Young's inequality, we can find  $c_2 > 0$  such that

<span id="page-11-1"></span>
$$
(ap+1)\int_{\Omega} u^p - bp \int_{\Omega} u^{p+l-1} \le -\frac{bp}{2} \int_{\Omega} u^{p+l-1} + c_2
$$
\n(3.18)

for all  $t \in (0, T_{\text{max}})$ . Choosing  $\eta$  appropriately small, plugging [\(3.16\)](#page-11-0)–[\(3.18\)](#page-11-1) into [\(3.15\)](#page-11-2), we obtain

<span id="page-11-3"></span>
$$
\frac{d}{dt} \left( \int_{\Omega} u^p + \int_{\Omega} v^{-q+1} |\nabla v|^q \right) + \int_{\Omega} u^p + \int_{\Omega} v^{-q+1} |\nabla v|^q
$$
\n
$$
\leq \frac{p(p-1)}{2} \left( \frac{q(q-1)}{2p(p-1)(q+\sqrt{n})^2} \right)^{-\frac{2}{q}} \alpha^{\frac{2(q+2)}{q}} \|v_0\|_{L^{\infty}(\Omega)}^{\frac{\alpha(q+2)-2}{q}} \int_{\Omega} u^{\frac{p(q+2)}{q}} \left( \frac{2(1-q)}{q} + \kappa_1 \int_{\Omega} w^{\frac{q+2}{2}} - \frac{bp}{2} \int_{\Omega} u^{p+l-1} + C \right)
$$
\n
$$
(3.19)
$$

for all  $t \in (0, T_{\max})$  with  $\kappa_1 := \frac{8^{\frac{q}{2}} q (q + \sqrt{n+1})^q (q - 2 + \sqrt{n})^{\frac{q+2}{2}} ||v_0||_{L^{\infty}(\Omega)}}{(q-1)^{\frac{q}{2}}}$ . Letting  $p := \frac{q}{2}$  in [\(3.6\)](#page-8-4), and multiplying  $\frac{8\kappa_1}{(q+2)\delta}$  in the both sides of [\(3.6\)](#page-8-4), we have

<span id="page-12-0"></span>
$$
\frac{8\kappa_1}{(q+2)\delta} \frac{d}{dt} \int_{\Omega} w^{\frac{q+2}{2}} + 2\kappa_1 \int_{\Omega} w^{\frac{q+2}{2}} \le \frac{8\kappa_1}{(q+2)\delta} \left(\frac{2}{\delta}\right)^{\frac{q}{2}} \int_{\Omega} u^{\frac{q+2}{2}} \tag{3.20}
$$

for all  $t \in (0, T_{\text{max}})$ . Substituting [\(3.20\)](#page-12-0) into [\(3.19\)](#page-11-3), we obtain [\(3.9\)](#page-9-2).

Our next plan is to deal with the first two integral terms on the right-hand side of [\(3.9\)](#page-9-2).

**Lemma 3.5.** *Let*  $\alpha \geq 1$ ,  $l > 1$ ,  $p > 1$  *and*  $q \geq 2$  *be such that* 

<span id="page-12-1"></span>
$$
q > \frac{2p}{l-1}.\tag{3.21}
$$

*Then, there exists a constant* C > <sup>0</sup> *such that*

<span id="page-12-2"></span>
$$
\frac{p(p-1)}{2} \left(\frac{q(q-1)}{2p(p-1)(q+\sqrt{n})^2}\right)^{-\frac{2}{q}} \alpha^{\frac{2(q+2)}{q}} \|v_0\|_{L^{\infty}(\Omega)}^{\frac{\alpha(q+2)-2}{q}} \int_{\Omega} u^{\frac{p(q+2)}{q}} \le \frac{bp}{4} \int_{\Omega} u^{p+l-1} + C \qquad (3.22)
$$

*for all*  $t \in (0, T_{\text{max}})$ *.* 

*Proof.* It follows from  $(3.21)$  that

$$
p + l - 1 - \frac{p(q+2)}{q} = \frac{(l-1)q - 2p}{q} > 0.
$$
Thus, we utilize Young's inequality to the first summand on the right hand of (3.9) to show the existence

of  $c > 0$  such that

$$
\frac{p(p-1)}{2} \left( \frac{q(q-1)}{2p(p-1)(q+\sqrt{n})^2} \right)^{-\frac{2}{q}} \alpha^{\frac{2(q+2)}{q}} \|v_0\|_{L^{\infty}(\Omega)}^{\frac{\alpha(q+2)-2}{q}} \int_{\Omega} u^{\frac{p(q+2)}{q}} \le \frac{bp}{4} \int_{\Omega} u^{p+l-1} + c
$$
\n
$$
\equiv (0, T_{\text{max}}), \text{ which implies (3.22).} \square
$$

<span id="page-12-5"></span>for all  $t \in (0, T_{\text{max}})$ , which implies  $(3.22)$ .

**Lemma 3.6.** *Let*  $l > 1$ *,*  $p > 1$ *. Assume that*  $q \geq 2$  *satisfies* 

<span id="page-12-3"></span>
$$
q < 2(p + l - 2). \tag{3.23}
$$

*Then, one can find a constant*  $C > 0$  *such that* 

<span id="page-12-4"></span>
$$
\frac{8\kappa_1}{(q+2)\delta} \left(\frac{2}{\delta}\right)^{\frac{q}{2}} \int\limits_{\Omega} u^{\frac{q+2}{2}} \le \frac{bp}{4} \int\limits_{\Omega} u^{p+l-1} + C \tag{3.24}
$$

*for all*  $t \in (0, T_{\text{max}})$ *, where*  $\kappa_1$  *is given by* [\(3.9\)](#page-9-2)*.* 

*Proof.* Using [\(3.23\)](#page-12-3), we obtain

$$
p + l - 1 - \frac{q+2}{2} = p + l - 2 - \frac{q}{2} > 0.
$$

Applying Young's inequality to the second term on the right of  $(3.9)$ , one can find  $c > 0$  satisfying

$$
\frac{8\kappa_1}{(q+2)\delta} \left(\frac{2}{\delta}\right)^{\frac{q}{2}} \int_{\Omega} u^{\frac{q+2}{2}} \le \frac{bp}{4} \int_{\Omega} u^{p+l-1} + c
$$

for all  $t \in (0, T_{\text{max}})$ , which immediately gives  $(3.24)$ .

<span id="page-12-6"></span>In the case of  $l > 2$ , applying Lemma [3.4,](#page-9-3) we have the following result.

 $\Box$ 

**Lemma 3.7.** Let  $l > 2$ . Assume that [\(1.6\)](#page-2-0) holds with some  $\alpha \geq 1$ . Then for all  $p > 1$ , there exists a *constant* C > <sup>0</sup> *such that*

<span id="page-13-1"></span>
$$
||u(\cdot,t)||_{L^{p}(\Omega)} \leq C \quad \text{for all } t \in (0,T_{\text{max}}). \tag{3.25}
$$

*Proof.* Since  $l > 2$ , we can readily obtain

$$
2(p+l-2) - \frac{2p}{l-1} = \frac{2[(p+l-2)(l-1)-p]}{l-1} = \frac{2(l-2)(p+l-1)}{l-1} > 0.
$$

Hence, for any  $p > 1$ , we can pick some  $q \ge 2$  fulfilling

<span id="page-13-0"></span>
$$
\frac{2p}{l-1} < q < 2(p+l-2). \tag{3.26}
$$

It follows from Lemmata [3.4–](#page-9-3)[3.6](#page-12-5) and [\(3.26\)](#page-13-0) that one can find  $c_1 > 0$  such that

$$
\frac{d}{dt} \left( \int_{\Omega} u^p + \int_{\Omega} v^{-q+1} |\nabla v|^q + \frac{8\kappa_1}{(q+2)\delta} \int_{\Omega} w^{\frac{q+2}{2}} \right) + \min \left\{ 1, \frac{(q+2)\delta}{8} \right\} \left( \int_{\Omega} u^p + \int_{\Omega} v^{-q+1} |\nabla v|^q + \frac{8\kappa_1}{(q+2)\delta} \int_{\Omega} w^{\frac{q+2}{2}} \right) \leq c_1
$$
\n(3.27)

for all  $t \in (0, T_{\text{max}})$ . Thus, a standard ODE comparison argument implies [\(3.25\)](#page-13-1).

<span id="page-13-6"></span>In the case  $l = 2$  and  $n \geq 4$ , we will derive  $L^p$ -bounds on u if b is sufficiently large.

**Lemma 3.8.** Let  $l = 2$ ,  $n \geq 4$  and  $p > 1$ . Suppose that [\(1.6\)](#page-2-0) holds, and that  $b > 0$  satisfies *α*(*p*+1)−1

<span id="page-13-4"></span>
$$
b > \lambda_1(p,n)\alpha^{\frac{2(p+1)}{p}} \|v_0\|_{L^{\infty}(\Omega)}^{\frac{\alpha(p+1)-1}{p}} + \lambda_2(p,n,\delta) \|v_0\|_{L^{\infty}(\Omega)},
$$
\n(3.28)

*where*

<span id="page-13-2"></span>
$$
\lambda_1(p,n) := (p-1)^{\frac{p+1}{p}} (2p+\sqrt{n})^{\frac{2}{p}} (2p-1)^{-\frac{1}{p}}
$$
\n(3.29)

*and*

<span id="page-13-3"></span>
$$
\lambda_2(p,n,\delta) := \frac{2^{4p+4}(2p+\sqrt{n}+1)^{2p}(2p-2+\sqrt{n})^{p+1}}{(p+1)(2p-1)^p \delta^{p+1}}.
$$
\n(3.30)

*Then, we infer the existence of*  $C > 0$  *such that* 

<span id="page-13-5"></span>
$$
||u(\cdot,t)||_{L^{p}(\Omega)} \leq C \quad \text{for all } t \in (0,T_{\text{max}}). \tag{3.31}
$$

*Proof.* Since  $l = 2$ , using [\(3.29\)](#page-13-2) and [\(3.30\)](#page-13-3), we apply Lemma [3.4](#page-9-3) to  $q := 2p$  to find

$$
\frac{d}{dt} \left( \int_{\Omega} u^{p} + \int_{\Omega} v^{-2p+1} |\nabla v|^{2p} + \frac{4\kappa_{1}}{(p+1)\delta} \int_{\Omega} w^{p+1} \right) + \int_{\Omega} u^{p} + \int_{\Omega} v^{-2p+1} |\nabla v|^{2p} + \kappa_{1} \int_{\Omega} w^{p+1} \leq \frac{p(p-1)}{2} \left( \frac{(2p-1)}{(p-1)(2p+\sqrt{n})^{2}} \right)^{-\frac{1}{p}} \alpha^{\frac{2(p+1)}{p}} \|v_{0}\|_{L^{\infty}(\Omega)}^{\frac{\alpha(p+1)-1}{p}} \int_{\Omega} u^{p+1} \leq \frac{2^{4p+3}p(2p+\sqrt{n}+1)^{2p}(2p-2+\sqrt{n})^{p+1} \|v_{0}\|_{L^{\infty}(\Omega)}}{(p+1)(2p-1)^{p}\delta^{p+1}} \int_{\Omega} u^{p+1} - \frac{bp}{2} \int_{\Omega} u^{p+1} + C
$$
\n
$$
= -\frac{p}{2} \left\{ b - \lambda_{1}(p,n) \alpha^{\frac{2(p+1)}{p}} \|v_{0}\|_{L^{\infty}(\Omega)}^{\frac{\alpha(p+1)-1}{p}} - \lambda_{2}(p,n) \|v_{0}\|_{L^{\infty}(\Omega)} \right\} \int_{\Omega} u^{p+1} + C
$$
\n(3.32)

for all  $t \in (0, T_{\text{max}})$ . Using  $(3.28)$ , we have

$$
\frac{d}{dt} \left( \int_{\Omega} u^p + \int_{\Omega} v^{-2p+1} |\nabla v|^{2p} + \frac{4\kappa_1}{(p+1)\delta} \int_{\Omega} w^{p+1} \right)
$$
\n
$$
+ \min \left\{ 1, \frac{(p+1)\delta}{4} \right\} \left( \int_{\Omega} u^p + \int_{\Omega} v^{-2p+1} |\nabla v|^2 p + \frac{4\kappa_1}{(p+1)\delta} \int_{\Omega} w^{p+1} \right) \le C
$$
\n
$$
T_{\text{max}}). \text{ Therefore, by a standard ODE comparison argument, we have (3.31).} \qquad \Box
$$

for all  $t \in (0, T_{\text{max}})$ . Therefore, by a standard ODE comparison argument, we have [\(3.31\)](#page-13-5).

<span id="page-14-5"></span>Next, we only consider  $n \in \{2,3\}$  and  $l = 2$ , since the global bounded solution is ensured by [\(2.1\)](#page-3-0) and Lemma [2.9](#page-5-6) when  $n = 1$ .

**Lemma 3.9.** Let  $n \in \{2,3\}$  and  $l = 2$ , and suppose that [\(1.6\)](#page-2-0) holds. Then for all  $T > 0$ , one can find  $C(T) > 0$  *such that* 

<span id="page-14-4"></span>
$$
||u(\cdot,t)||_{L^{2}(\Omega)} \leq C(T) \quad \text{for all } t \in (0,T_{\text{max}}). \tag{3.34}
$$

*Proof.* Letting  $q = 2$  in  $(3.1)$ , we have

<span id="page-14-0"></span>
$$
\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} u^2 + \int_{\Omega} v^{\alpha} |\nabla u|^2 + \int_{\Omega} u^2 \leq \alpha^2 \int_{\Omega} u^2 v^{\alpha - 2} |\nabla v|^2 + (2a + 1) \int_{\Omega} u^2 \tag{3.35}
$$

for all  $t \in (0, T_{\text{max}})$ . Due to  $l = 2$ ,  $(2.5)$  in conjunction with Lemma [2.8](#page-4-4) shows that for any  $T > 0$ , we can find  $c_1(T) > 0$  fulfilling  $v \ge c_1(T)$  in  $\Omega \times (0,T)$ . Therefore, [\(3.35\)](#page-14-0) can be rewritten as

<span id="page-14-3"></span>
$$
\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} u^2 + c_1^{\alpha}(T) \int_{\Omega} |\nabla u|^2 + \int_{\Omega} u^2 \le \alpha^2 c_2(T) \int_{\Omega} u^2 |\nabla v|^2 + (2a+1) \int_{\Omega} u^2 \tag{3.36}
$$

for all  $t \in (0, T_{\text{max}})$ , where  $c_2(T) := \max\left\{c_1^{\alpha-2}(T), ||v_0||_{L^{\infty}(\Omega)}^{\alpha-2}\right\}$ . Since  $n \in \{2, 3\}, l = 2$  according to  $(2.5)$ and Lemma [2.3,](#page-3-4) we can find  $c_3 > 0$  satisfying

<span id="page-14-1"></span>
$$
\|\nabla v(\cdot, t)\|_{L^{4}(\Omega)} \leq c_3 \quad \text{for all } t \in (0, T_{\text{max}}). \tag{3.37}
$$

Using  $n \leq 3$ , [\(2.1\)](#page-3-0), [\(3.37\)](#page-14-1), Hölder's inequality and an Ehrling-type inequality, there exists a positive constant  $c_4(T)$  such that

<span id="page-14-2"></span>
$$
\alpha^{2}c_{2}(T)\int_{\Omega}u^{2}|\nabla v|^{2} + (2a+1)\int_{\Omega}u^{2} \leq \alpha^{2}c_{2}(T)\|u\|_{L^{4}(\Omega)}^{2}\|\nabla v\|_{L^{4}(\Omega)}^{2} + (2a+1)\|u\|_{L^{2}(\Omega)}^{2}
$$
\n
$$
\leq \alpha^{2}c_{2}(T)c_{3}^{2}\|u\|_{L^{4}(\Omega)}^{2} + (2a+1)\|u\|_{L^{2}(\Omega)}^{2} \leq \frac{c_{1}^{\alpha}(T)}{2}\int_{\Omega}|\nabla u|^{2} + c_{4}(T)
$$
\n(3.38)

for all  $t \in (0, T_{\text{max}})$ . Plugging  $(3.38)$  into  $(3.36)$ , we have

$$
\frac{d}{dt} \int_{\Omega} u^2 + \frac{c_1^{\alpha}(T)}{2} \int_{\Omega} |\nabla u|^2 + \int_{\Omega} u^2 \le c_4(T) \quad \text{for all} \quad t \in (0, T_{\text{max}}). \tag{3.39}
$$

Thus, using an ODE argument, we complete the proof of  $(3.34)$ .

<span id="page-14-6"></span>With the help of Lemma [2.9,](#page-5-6) the following result can be obtained.

**Lemma 3.10.** *Suppose that* [\(1.6\)](#page-2-0) and  $\alpha \geq 1$  *hold. For all*  $n \geq 1$ , *if one of the following cases holds:* (i)  $l > 2$ ;

(ii)  $l = 2, n \leq 3;$ 

(iii)  $l = 2, n \ge 4$ , and  $b > \lambda_1(\frac{n}{2}, n) \alpha^{2(n+2)} \|v_0\|$ <br>defined in (2.20) and (2.20) then for all T  $\frac{\alpha(n+2)-2}{n}\alpha(n+2)$  +  $\lambda_2(\frac{n}{2}, n, \delta)$ || $v_0$ || $L^{\infty}(\Omega)$ *, where*  $\lambda_1$  *and*  $\lambda_2$  *are as defined in* [\(3.29\)](#page-13-2) *and* [\(3.30\)](#page-13-3)*, then for all*  $T \in (0, T_{\text{max}})$ *, there exists*  $C(T) > 0$  *fulfilling* 

 $||u(\cdot,t)||_{L^{\infty}(\Omega)} + ||v(\cdot,t)||_{W^{1,\infty}(\Omega)} + ||w(\cdot,t)||_{L^{\infty}(\Omega)} \leq C(T)$  *for all*  $t \in (0,T)$ .

*Proof.* Let  $p \ge 1$  such that  $p > \frac{n}{2}$ . In the case  $l > 2$ , Lemma [3.7](#page-12-6) guarantees that  $||u(\cdot,t)||_{L^p(\Omega)}$  is bounded for all  $t \in (0, T_{\infty})$ . In the case  $l = 2$  for any  $b > 0$  in view of Lemma 3.9 and  $(2, 1)$ , we obtain th for all  $t \in (0, T_{\text{max}})$ . In the case  $l = 2$ , for any  $b > 0$ , in view of Lemma [3.9](#page-14-5) and [\(2.1\)](#page-3-0), we obtain that  $||u(\cdot,t)||_{L^2(\Omega)}$  is bounded when  $n \in \{2,3\}$  and  $||u(\cdot,t)||_{L^1(\Omega)}$  is bounded when  $n=1$ . Whereas in the case  $l = 2$  and  $n \geq 4$ , thanks to

$$
b>\lambda_1\left(\frac{n}{2},n\right)\alpha^{\frac{2(n+2)}{n}}\|v_0\|_{L^\infty\left(\Omega\right)}^{\frac{\alpha(n+2)-2}{n}}+\lambda_2\left(\frac{n}{2},n,\delta\right)\|v_0\|_{L^\infty\left(\Omega\right)}
$$

and the continuity of  $\lambda_1$  and  $\lambda_2$ , there exists  $p > \frac{n}{2}$  satisfying

$$
b>\lambda_1(p,n)\alpha^{\frac{2(p+1)}{p}}\|v_0\|_{L^\infty(\Omega)}^{\frac{\alpha(p+1)-1}{p}}+\lambda_2(p,n,\delta)\|v_0\|_{L^\infty(\Omega)}.
$$

Applying Lemma [3.8,](#page-13-6) we also see that  $||u(\cdot, t)||_{L^p(\Omega)}$  is bounded for all  $t \in (0, T_{\text{max}})$ . In conclusion, we utilize Lemma 2.9 to complete this proof. utilize Lemma [2.9](#page-5-6) to complete this proof. -

Now, we are in a position to prove Theorem [1.1.](#page-2-3)

*Proof of Theorem [1.1.](#page-2-3)* Theorem [1.1](#page-2-3) is a direct consequence of Lemmata [2.1](#page-2-4) and [3.10.](#page-14-6)  $\Box$ 

# **Acknowledgements**

The authors are very grateful to the anonymous reviewers for their carefully reading and valuable comments that lead to a substantial improvement of this manuscript.

**Author contributions** The authors claim that the research was realized in collaboration with the same responsibility. All authors read and approved the last version of the manuscript.

**Funding** This work is supported by Natural Science Foundation of Chongqing (No. cstc2021jcyj-msxmX0412), the NNSF of China (No. 12271064) and the Key Laboratory of Nonlinear Analysis and its Applications (Chongqing University), Ministry of Education.

**Data availability** Data sharing not applicable to this article as no datasets were generated or analyzed during the current study.

### **Declarations**

**Conflict of interest** The authors declare that they have no conflict of interest.

**Publisher's Note** Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Springer Nature or its licensor (e.g. a society or other partner) holds exclusive rights to this article under a publishing agreement with the author(s) or other rightsholder(s); author self-archiving of the accepted manuscript version of this article is solely governed by the terms of such publishing agreement and applicable law.

#### <span id="page-16-2"></span>**References**

- <span id="page-16-10"></span>[1] Ahn, J., Yoon, C.: Global well-posedness and stability of constant equilibria in parabolic–elliptic chemotaxis systems without gradient sensing. Nonlinearity **32**, 1327–1351 (2019)
- <span id="page-16-17"></span>[2] Burger, M., Laurençot, P., Trescases, A.: Delayed blow-up for chemotaxis models with local sensing. J. Lond. Math. Soc. **103**, 1596–1617 (2021)
- <span id="page-16-14"></span>[3] Desvillettes, L., Kim, Y.J., Trescases, A., Yoon, C.: A logarithmic chemotaxis model featuring global existence and aggregation. Nonlinear Anal. Real World Appl. **50**, 562–582 (2019)
- <span id="page-16-3"></span>[4] Fuest, M.: Analysis of a chemotaxis model with indirect signal absorption. J. Differ. Equ. **267**, 4778–4806 (2019)
- <span id="page-16-21"></span>[5] Fujie, K., Jiang, J.: Global existence for a kinetic model of pattern formation with density-suppressed motilities. J. Differ. Equ. **269**, 5338–5378 (2020)
- <span id="page-16-11"></span>[6] Fujie, K., Jiang, J.: Boundedness of classical solutions to a degenerate Keller–Segel type model with signal-dependent motilities. Acta Appl. Math. **176**, 3 (2021)
- <span id="page-16-15"></span>[7] Fujie, K., Jiang, J.: Comparison methods for a Keller–Segel-type model of pattern formations with density-suppressed motilities. Calc. Var. Partial Differ. Equ. **60**, 92 (2021)
- <span id="page-16-5"></span>[8] Fujie, K., Senba, T.: Application of an Adams type inequality to a two-chemical substances chemotaxis system. J. Differ. Equ. **263**, 88–148 (2017)
- <span id="page-16-18"></span>[9] Fujie, K., Senba, T.: Global existence and infinite time blow-up of classical solutions to chemotaxis systems of local sensing in higher dimensions. Nonlinear Anal. **222**, 112987 (2022)
- <span id="page-16-12"></span>[10] Fujie, K., Senba, T.: Global boundedness of solutions to a parabolic–parabolic chemotaxis system with local sensing in higher dimensions. Nonlinear Anal. **35**, 3777–3811 (2022)
- <span id="page-16-8"></span>[11] Fu, X., Tang, L., Liu, C., Huang, J., Hwa, T., Lenz, P.: Stripe formation in bacterial systems with density-suppressed motility. Phys. Rev. Lett. **108**, 198102 (2012)
- <span id="page-16-6"></span>[12] Hu, B., Tao, Y.: To the exclusion of blow-up in a three-dimensional chemotaxis-growth model with indirect attractant production. Math. Models Methods Appl. Sci. **26**, 2111–2128 (2016)
- <span id="page-16-19"></span>[13] Jin, H.Y., Kim, Y.J., Wang, Z.A.: Boundedness, stabilization, and pattern formation driven by density-suppressed motility. SIAM J. Appl. Math. **78**, 1632–1657 (2018)
- <span id="page-16-13"></span>[14] Jiang, J., Laurençot, P.: Global existence and uniform boundedness in a chemotaxis model with signal-dependent motility. J. Differ. Equ. **299**, 513–541 (2021)
- <span id="page-16-16"></span>[15] Jin, H.Y., Wang, Z.A.: Critical mass on the Keller–Segel system with signal-dependent motility. Proc. Am. Math. Soc. **148**, 4855–4873 (2020)
- <span id="page-16-0"></span>[16] Kelle, E.F., Segel, L.A.: Traveling bands of chemotactic bacteria: a theoretical analysis. J. Theor. Biol. **30**, 377–380 (1971)
- <span id="page-16-28"></span>[17] Kowalczyk, R., Szyma' nska, Z.: On the global existence of solutions to an aggregation model. J. Math. Anal. Appl. **343**, 379–398 (2008)
- <span id="page-16-1"></span>[18] Lankeit, J., Wang, Y.: Global existence, boundedness and stabilization in a high-dimensional chemotaxis system with consumption. Discrete Contin. Dyn. Syst. **37**, 6099–6121 (2017)
- <span id="page-16-26"></span>[19] Lee, J., Yoon, C.: Existence and asymptotic properties of aerotaxis model with the Fokker–Planck type diffusion. Nonlinear Anal. Real World Appl. **71**, 103758 (2023)
- <span id="page-16-22"></span>[20] Li, D., Zhao, J.: Global boundedness and large time behavior of solutions to a chemotaxis-consumption system with signal-dependent motility. Z. Angew. Math. Phys. **72**, 1–20 (2021)
- <span id="page-16-7"></span>[21] Li, D., Li, Z., Zhao, J.: Boundedness and large time behavior for a chemotaxis system with signal-dependent motility and indirect signal consumption. Nonlinear Anal. Real World Appl. **64**, 103447 (2022)
- <span id="page-16-25"></span>[22] Li, X., Wang, L., Pan, X.: Boundedness and stabilization in the chemotaxis consumption model with signal-dependent motility. Z. Angew. Math. Phys. **72**, 1–18 (2021)
- <span id="page-16-23"></span>[23] Li, G., Winkler, M.: Refined regularity analysis for a Keller-Segel-consumption system involving signal-dependent motilities. Appl. Anal. **103**, 45–64 (2024)
- <span id="page-16-24"></span>[24] Li, G., Winkler, M.: Relaxation in a Keller-Segel-consumption system involving signal-dependent motilities. Commun. Math. Sci. **21**, 299–322 (2023)
- <span id="page-16-20"></span>[25] Liu, Z., Xu, J.: Large time behavior of solutions for density-suppressed motility system in higher dimensions. J. Math. Anal. Appl. **475**, 1596–1613 (2019)
- <span id="page-16-4"></span>[26] Liu, Y., Li, Z., Huang, J.: Global boundedness and large time behavior of a chemotaxis system with indirect signal absorption. J. Differ. Equ. **269**, 6365–6399 (2020)
- <span id="page-16-9"></span>[27] Liu, C., Fu, X., et al.: Sequential establishment of stripe patterns in an expanding cell population. Science **334**, 238–241 (2011)
- <span id="page-16-27"></span>[28] Lv, W.: Global existence for a class of chemotaxis-consumption systems with signal-dependent motility and generalized logistic source. Nonlinear Anal. Real World Appl. **56**, 103–160 (2020)
- <span id="page-17-11"></span>[29] Lv, W., Wang, Q.: An n-dimensional chemotaxis system with signal-dependent motility and generalized logistic source: global existence and asymptotic stabilization. Proc. R. Soc. Edinb. A **151**, 821–841 (2021)
- <span id="page-17-12"></span>[30] Lv, W., Wang, Q.: Global existence for a class of Keller-Segel models with signal-dependent motility and general logistic term. Evol. Equ. Control Theory **10**, 25–36 (2021)
- <span id="page-17-13"></span>[31] Lyu, W., Wang, Z.: Logistic damping effect in chemotaxis models with density-suppressed motility. Adv. Nonlinear Anal. **12**, 336–355 (2023)
- <span id="page-17-0"></span>[32] Tao, Y.: Boundedness in a chemotaxis model with oxygen consumption by bacteria. J. Math. Anal. Appl. **381**, 521–529 (2011)
- <span id="page-17-19"></span>[33] Tao, Y., Winkler, M.: A chemotaxis-haptotaxis model: the roles of nonlinear diffusion and logistic source. SIAM J. Math. Anal. **43**, 685–704 (2011)
- <span id="page-17-1"></span>[34] Tao, Y., Winkler, M.: Eventual smoothness and stabilization of large-data solutions in a three-dimensional chemotaxis system with consumption of chemoattractant. J. Differ. Equ. **252**, 2520–2543 (2012)
- <span id="page-17-5"></span>[35] Tao, Y., Winkler, M.: Critical mass for infinite-time aggregation in a chemotaxis model with indirect signal production. J. Eur. Math. Soc. **19**, 3641–3678 (2017)
- <span id="page-17-24"></span>[36] Tao, Y., Winkler, M.: Boundedness in a quasilinear parabolic–parabolic Keller–Segel system with subcritical sensitivity. J. Differ. Equ. **252**, 692–715 (2012)
- <span id="page-17-20"></span>[37] Tao, Y., Winkler, M.: Blow-up prevention by quadratic degradation in a two-dimensional Keller–Segel–Navier–Stokes system. Z. Angew. Math. Phys. **67**, 1–23 (2016)
- <span id="page-17-6"></span>[38] Tao, Y., Winkler, M.: Effects of signal-dependent motilities in a Keller–Segel-type reaction-diffusion system. Math. Models Methods Appl. Sci. **27**, 1645–1683 (2017)
- <span id="page-17-14"></span>[39] Tao, Y., Winkler, M.: Global solutions to a Keller-Segel-consumption system involving singularly signal-dependent motilities in domains of arbitrary dimension. J. Differ. Equ. **343**, 390–418 (2023)
- <span id="page-17-10"></span>[40] Wang, J., Wang, M.: Boundedness in the higher-dimensional Keller-Segel model with signal-dependent motility and logistic growth. J. Math. Phys. **60**, 011507 (2019)
- <span id="page-17-17"></span>[41] Wang, L.: Global dynamics for a chemotaxis consumption system with signal-dependent motility and logistic source. J. Differ. Equ. **348**, 191–222 (2023)
- <span id="page-17-18"></span>[42] Wang, L.: Global solutions to a chemotaxis consumption model involving signal-dependent degenerate diffusion and logistic-type dampening. Preprint at [arXiv:2304.02915](http://arxiv.org/abs/2304.02915)
- <span id="page-17-8"></span>[43] Wang, Z.: On the parabolic-elliptic Keller–Segel system with signal-dependent motilities: a paradigm for global boundedness and steady states. Math. Methods Appl. Sci. **44**, 10881–10898 (2021)
- <span id="page-17-23"></span>[44] Winkler, M.: Aggregation vs. global diffusive behavior in the higher-dimensional Keller–Segel model. J. Differ. Equ. **248**, 2889–2905 (2010)
- <span id="page-17-22"></span>[45] Winkler, M.: The two-dimensional Keller–Segel system with singular sensitivity and signal absorption: global large-data solutions and their relaxation properties. Math. Models Methods Appl. Sci. **26**, 987–1024 (2016)
- <span id="page-17-3"></span>[46] Winkler, M.: Asymptotic homogenization in a three-dimensional nutrient taxis system involving food-supported proliferation. J. Differ. Equ. **263**, 4826–4869 (2017)
- [47] Winkler, M.: Renormalized radial large-data solutions to the higher-dimensional Keller–Segel system with singular sensitivity and signal absorption. J. Differ. Equ. **264**, 2310–2350 (2018)
- [48] Winkler, M.: Global existence and stabilization in a degenerate chemotaxis-Stokes system with mildly strong diffusion enhancement. J. Differ. Equ. **264**, 6109–6151 (2018)
- <span id="page-17-4"></span>[49] Winkler, M.: A three-dimensional Keller–Sege–Navier–Stokes system with logistic source: global weak solutions and asymptotic stabilization. J. Differ. Equ. **276**, 1339–1401 (2019)
- <span id="page-17-9"></span>[50] Winkler, M.: Can simultaneous density-determined enhancement of diffusion and cross-diffusion foster boundedness in Keller–Segel type systems involving signal-dependent motilities? Nonlinearity **33**, 6590–6623 (2020)
- <span id="page-17-21"></span>[51] Winkler, M.: Approaching logarithmic singularitie in quasilinear chemotaxis-consumption systems with signaldependent sensitivities. Discret. Contin. Dyn. Syst. Ser. B **27**, 6565–6587 (2022)
- <span id="page-17-15"></span>[52] Winkler, M.: Application of the Moser–Trudinger inequality in the construction of global solutions to a strongly degenerate migration model. B. Math. Sci. **13**, 2250012 (2023)
- [53] Winkler, M.: A quantitative strong parabolic maximum principle and application to a taxis-type migration-consumption model involving signal-dependent degenerate diffusion. Ann. Inst. H. Poincar´e-ANL **41**, 95–127 (2024)
- [54] Winkler, M.: A degenerate migration-consumption model in domains of arbitrary dimension. Adv. Nonlinear Stud. **24**, 592–615 (2024)
- <span id="page-17-16"></span>[55] Winkler, M.: Global generalized solvability in a strongly degenerate taxis-type parabolic system modeling migrationconsumption interaction. Z. Angew. Math. Phys. **74**, 32 (2023)
- <span id="page-17-7"></span>[56] Yoon, C., Kim, Y.J.: Global existence and aggregation in a Keller–Segel model with Fokker–Planck diffusion. Acta App. Math. **149**, 101–123 (2017)
- <span id="page-17-2"></span>[57] Zhang, Q., Li, Y.: Stabilization and convergence rate in a chemotaxis system with consumption of chemoattractant. J. Math. Phys. **56**, 081509 (2015)

Meng Zheng and Liangchen Wang School of Science Chongqing University of Posts and Telecommunications Chongqing 400065 People's Republic of China e-mail: wanglc@cqupt.edu.cn

Meng Zheng e-mail: zhengmeng150573@163.com

(Received: April 12, 2024; revised: July 20, 2024; accepted: July 23, 2024)