

## Existence and Multiplicity Results for the $p$ -Laplacian with a $p$ -Gradient Term

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**Abstract.** We study the existence and multiplicity of positive solutions to  $p$ -Laplace equations where the nonlinear term depends on a  $p$ -power of the gradient. For this purpose we combine Picone's identity, blow-up arguments, the strong maximum principle and Liouville-type theorems to obtain a priori estimates.

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### 1. Introduction

We study the existence and multiplicity of positive solutions of nonlinear elliptic equations of the form

$$\begin{cases} -\Delta_p u = |\nabla u|^p + \lambda f(x, u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases} \quad (P_\lambda)$$

where  $\lambda$  is a positive parameter and  $\Omega \subset \mathbb{R}^N$  is a bounded domain with  $N > p > 1$ , and  $f : \Omega \times [0, +\infty) \rightarrow [0, +\infty)$  is a continuous function.

In the semilinear elliptic case ( $p = 2$ ), the equation  $(P_\lambda)$  may be viewed as a perturbation of the stationary part of the equation

$$u_t - \Delta u = \varepsilon |\nabla u|^2.$$

Existence results for problems such as  $(P_\lambda)$  with  $p = 2$  and  $f(x, u) = f(x)$  start with the classical references [19, 20]. Later on, many authors have considered elliptic equations with first-order terms having quadratic growth with respect to the gradients (see [1, 5, 12, 14, 15, 22, 26] and references therein).

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We would like to mention that most of the works mentioned above deal with the case where the nonlinearity  $f(x)$  belongs to an appropriate Lebesgue space while in this work we deal with functions  $f(x, u)$  which lie between powers of  $u$ .

Concerning to equation  $(P_\lambda)$ , it is worth mentioning that [24] and [17] have studied related problems. For instance, [24] studies the existence of positive solutions for the problem

$$\begin{cases} \Delta_m u + \psi(x, u, \nabla u) = 0, & x \in \Omega, \\ u(x) = 0, & x \in \partial\Omega, \end{cases} \tag{1.1}$$

where  $1 < m < N$ , and  $\psi : \Omega \times \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}$  is a non-negative continuous function satisfying

$$\left[ \begin{array}{l} u^q - M|\eta|^\alpha \leq \psi(x, u, \eta) \leq au^q + M|\eta|^\alpha, \\ \forall (x, u, \eta) \in \Omega \times \mathbb{R} \times \mathbb{R}^N, \quad \text{where } a \geq 1, M > 0, \\ q \in \left(m - 1, \frac{N(m - 1)}{N - m}\right) \quad \text{and} \quad \alpha \in \left(m - 1, \frac{mq}{q + 1}\right). \end{array} \right.$$

From these results a natural question arises, namely, are there exponents  $q$  and  $\alpha$  ensuring the existence of positive solutions? We will give a partial answer to this question.

It is also interesting to mention that equations appearing in these types of problems do not have, in general, a variational structure, hence most of the classical tools to study partial differential equations fail. In our case performing an adequate change of variable we pass from the problem with a gradient term to a new one, but without a gradient term. However, for instance, the new nonlinearity does not verify the well-known Ambrosetti–Rabinowitz condition, which is a basic assumption needed to ensure compactness of the operator associated to the problem. In this work we will avoid this difficulty by using topological methods, Picone’s identity, a blow-up argument and a Liouville-type theorem.

We note that, when  $f$  is a positive constant, the change of variable mentioned above transforms the equation in Problem  $(P_\lambda)$  into the equation  $-\Delta_p v = \tilde{\lambda}(v + 1)^{p-1} = \tilde{\lambda}g(v)$  in  $\Omega$  with homogeneous Dirichlet boundary conditions, where  $\tilde{\lambda} = \lambda C$  for some positive constant  $C$ . This type of elliptic equation has been studied by several authors. For instance, when  $p = 2$ , existence of solutions was obtained in [6] when  $g$  is a  $C^1$ -convex, non-decreasing function. In [13], among other interesting results, the existence of weak non-negative solutions was obtained for  $g(t) = (1+t)^q$  with  $q > 0$  and  $N > p > 1$ . However, we emphasize that these particular cases are not considered here, because our nonlinearity  $g_\lambda$  is of mixed power-logarithmic type, and therefore the geometry associated to the problem is quite different (see Problem (2.2) below).

Throughout this work, we assume the following hypotheses:

- $(F_1)$  The nonlinearity  $f : \bar{\Omega} \times [0, +\infty) \rightarrow [0, +\infty)$  is a Carathéodory function (i.e.  $f(x, \cdot)$  is continuous for a.e.  $x \in \Omega$  and  $f(\cdot, s)$  is bounded if  $s$  belongs to bounded sets).

(F<sub>2</sub>) There exist  $q \in (0, +\infty)$  and positive constants  $c_0$  and  $c_1$  such that

$$c_0 t^q \leq f(x, t) \leq c_1 t^q$$

for all  $(x, t) \in \bar{\Omega} \times [0, +\infty)$ .

(F<sub>3</sub>) If  $q = p - 1$  we have

$$\lim_{t \rightarrow 0^+} \frac{f(x, t)}{t^{p-1}} = \inf_{t > 0} \frac{f(x, t)}{t^{p-1}} = f_0,$$

uniformly for  $x \in \bar{\Omega}$  for some positive constant  $f_0$ .

(F<sub>4</sub>) If  $0 < q < p - 1$ , there is a non-negative constant  $k$  such that the map

$$t \mapsto (t + 1)^{p-1} f(x, (p - 1) \ln(t + 1)) + kt^{p-1}$$

is strictly increasing if  $t \in [0, +\infty)$  for a.e.  $x \in \Omega$ .

Let us comment on the hypotheses above. The conditions (F<sub>1</sub>) and (F<sub>2</sub>), and also (F<sub>3</sub>) are necessary to obtain existence and nonexistence results. But condition (F<sub>4</sub>) is only a technical assumption in order to obtain multiplicity results (see the theorems below). More precisely, our main results are the following.

**Theorem 1.1.** *Let  $q > p - 1$  and assume that (F<sub>1</sub>) and (F<sub>2</sub>) hold. Then  $(P_\lambda)$  has at least one positive solution for all  $\lambda > 0$ .*

**Theorem 1.2.** *Let  $q = p - 1$  and assume that (F<sub>1</sub>), (F<sub>2</sub>) and (F<sub>3</sub>) hold. Then  $(P_\lambda)$  has at least one positive solution for  $\lambda \in (0, \bar{\lambda})$  and no positive solutions for  $\lambda \geq \bar{\lambda}$  where  $\bar{\lambda} = \lambda_1(\Omega)/f_0$ . Here  $\lambda_1(\Omega)$  denotes the first eigenvalue of  $-\Delta_p$  in  $W_0^{1,p}(\Omega)$ .*

**Theorem 1.3.** *Let  $0 < q < p - 1$  and assume that (F<sub>1</sub>), (F<sub>2</sub>) and (F<sub>4</sub>) hold. Then there exists  $\bar{\Lambda} > 0$  such that  $(P_\lambda)$  has at least two positive solutions for  $0 < \lambda < \bar{\Lambda}$ , at least one solution for  $\lambda = \bar{\Lambda}$  and no solutions for  $\lambda > \bar{\Lambda}$ .*

The paper is organized as follows. In Section 2, we establish some basic facts that will be needed in the sequel. In particular, we will give a short proof of a Liouville-type theorem which depends only on Picone's identity. Section 3 is devoted to the proof of the Theorems stated above.

## 2. Preliminaries

Let  $u$  be a regular positive solution of  $(P_\lambda)$ . Performing the change of variable  $v = e^{\frac{u}{p-1}} - 1$  (see [18]) we get

$$\begin{cases} -\Delta_p v = g_\lambda(x, v) & \text{in } \Omega, \\ v = 0 & \text{on } \partial\Omega, \end{cases} \tag{2.2}$$

where  $g_\lambda(x, v) = \lambda \left(\frac{v+1}{p-1}\right)^{p-1} f(x, (p - 1) \ln(v + 1))$ . Note that, for all  $\lambda > 0$ , the function  $g_\lambda$  satisfies:

(G<sub>1</sub>)  $g_\lambda : \bar{\Omega} \times [0, +\infty) \rightarrow [0, +\infty)$  is a Carathéodory function.

(G<sub>2</sub>) For all  $t \geq 0$ ,

$$\lambda c_0(t + 1)^{p-1} (\ln(t + 1))^q \leq \frac{g_\lambda(x, t)}{(p - 1)^{q+1-p}} \leq \lambda c_1(t + 1)^{p-1} (\ln(t + 1))^q,$$

for all  $x \in \bar{\Omega}$ .

(G<sub>3</sub>) When  $0 < q < p - 1$ , there exists a non-negative constant  $k$  such that the map  $t \mapsto g_\lambda(x, t) + kt^{p-1}$  is strictly increasing if  $t \in [0, +\infty)$  for a.e.  $x \in \Omega$ .

Note that, under the conditions stated above, the solutions to the problem (2.2) belong to  $C^{1,\alpha}$  for some  $\alpha \in (0, 1)$  (see, for example, [16]). Therefore, if we are able to find a solution to the problem (2.2), we will obtain a regular solution to the original equation ( $P_\lambda$ ).

The following result is the well-known Picone identity for the  $p$ -Laplacian (see e.g. [2, 11, 25]). This will be fundamental in our approach.

**Theorem 2.1 (Picone’s identity).** *Let  $u, v \in W_{loc}^{1,p}(\Omega) \cap C(\Omega)$  be such that  $u \geq 0$  and  $v > 0$ .*

*Set*

$$\begin{aligned} \mathcal{L}(u, v) &= |\nabla u|^p + (p - 1) \left(\frac{u}{v}\right)^p |\nabla v|^p - p \left(\frac{u}{v}\right)^{p-1} \nabla u |\nabla v|^{p-2} \nabla v, \\ \mathcal{R}(u, v) &= |\nabla u|^p - \nabla \left(\frac{u^p}{v^{p-1}}\right) |\nabla v|^{p-2} \nabla v. \end{aligned}$$

*Then  $\mathcal{L}(u, v) = \mathcal{R}(u, v) \geq 0$  a.e. in  $\Omega$ . Moreover,  $\mathcal{L}(u, v) = \mathcal{R}(u, v) = 0$  a.e. in  $\Omega$  if and only if  $u = cv$  in  $\Omega$  for a constant  $c > 0$ .*

Using Picone’s identity we give a simple proof of the following Liouville-type result.

**Lemma 2.1.** *Let  $c_0 > 0$ , and let  $p > 1$ . Then the inequality*

$$c_0 w^{p-1} \leq -\Delta_p w \tag{2.3}$$

*has no positive solution in  $W_{loc}^{1,p}(G)$ , where  $G = \mathbb{R}^N$  or  $G = \mathbb{R}_+^N$ .*

*Proof.* We argue by contradiction. Let  $w$  be a positive solution of (2.3). We may assume that  $G = \mathbb{R}_+^N$ . Take  $R > 0$  and  $x_0 \in \mathbb{R}_+^N$  such that  $\overline{B_R(x_0)} \subset \mathbb{R}_+^N$  and  $\lambda_1(B_R(x_0)) < c_0$ . Denote by  $\phi_1$  the positive eigenfunction associated with  $\lambda_1(B_R(x_0))$ . Since  $w > 0$  on  $B_R(x_0)$ , Hopf’s Lemma ([27]) implies that  $\phi_1^p/w^{p-1} \in W_0^{1,p}(B_R(x_0))$ . Then, testing (2.3) by  $\phi_1^p/w^{p-1}$  and integrating by parts, we get

$$\begin{aligned} c_0 \int_{B_R(x_0)} \phi_1^p &\leq \int_{B_R(x_0)} (-\Delta_p w) \frac{\phi_1^p}{w^{p-1}} \\ &= \int_{B_R(x_0)} p |\nabla w|^{p-2} \frac{\phi_1^{p-1}}{w^{p-1}} \nabla w \nabla \phi_1 - (p - 1) \int_{B_R(x_0)} \frac{\phi_1^p}{w^p} |\nabla w|^p. \end{aligned}$$

The preceding inequality and Picone’s identity implies that

$$c_0 \int_{B_R(x_0)} \phi_1^p - \int_{B_R(x_0)} |\nabla \phi_1|^p \leq - \int_{B_R(x_0)} \mathcal{L}(\phi_1, w) \leq 0.$$

It follows that

$$c_0 \leq \frac{\int_{B_R(x_0)} |\nabla \phi_1|^p}{\int_{B_R(x_0)} \phi_1^p} = \lambda_1(B_R(x_0))$$

and this contradiction completes the proof.  $\square$

Since we use a homotopy argument, it is necessary to prove a priori bounds for solutions of a family of problems parameterized by  $\tau \geq 0$ , namely

$$\begin{cases} -\Delta_p v = g_\lambda(x, v) + \tau & \text{in } \Omega, \\ v = 0 & \text{on } \partial\Omega, \end{cases} \quad (A_\lambda)_\tau$$

where  $\lambda > 0$  is fixed.

The following lemma allows us to control the parameter  $\tau$  in the blow-up analysis.

**Lemma 2.2.** *Let  $v$  a positive solution of  $(A_\lambda)_\tau$ , where  $\lambda \geq 0$ . Then*

$$\tau \leq \theta \left( \max_{\bar{\Omega}} v \right)^{p-1}$$

where the positive constant  $\theta$  depends only on  $\Omega$ .

*Proof.* Since  $v$  is a positive solution, the inequality holds when  $\tau = 0$ . Now, if  $\tau > 0$ , it  $(G_1)$  implies that

$$-\Delta_p v = g_\lambda(x, v) + \tau \geq \tau \quad \text{for all } x \in \Omega.$$

Let  $e$  be the positive solution of

$$\begin{cases} -\Delta_p e = 1 & \text{in } \Omega, \\ e = 0 & \text{on } \partial\Omega \end{cases} \quad (2.4)$$

and let  $w = (\tau/2)^{\frac{1}{p-1}} e$  in  $\Omega$ . Then it follows that  $-\Delta_p w = \tau/2 < -\Delta_p v$  in  $\Omega$  and  $v = w$  on  $\partial\Omega$ . Thus, using the comparison lemma (see [9]), we obtain that  $v \geq w$  in  $\Omega$ . Therefore, there is a positive constant  $\theta$  such that

$$\tau \leq \theta v^{p-1}$$

at the maximum point of  $e$ . This completes the proof.  $\square$

The next proposition establishes a bound for the  $L^\infty$ -norms of positive solutions of  $(A_\lambda)_\tau$ .

**Proposition 2.1.** *For any  $\lambda > 0$ , let  $v \in C^1(\bar{\Omega})$  be a positive solution of  $(A_\lambda)_\tau$ . Then*

$$0 \leq v(x) + \tau \leq C \quad \text{for all } x \in \bar{\Omega},$$

where  $C$  is a positive constant depending only on  $\lambda$  and  $\Omega$ , but not on  $\tau \geq 0$ .

*Proof.* Suppose that the conclusion of Proposition 2.1 is false. Then there exists a sequence  $\{(v_n, \tau_n)\}_{n \in \mathbb{N}}$  with  $v_n$  being a  $C^1$ -solution of  $(A_\lambda)_{\tau_n}$  such that  $\max_{\overline{\Omega}} v_n + \tau_n \xrightarrow{n \rightarrow \infty} \infty$ . By Lemma 2.2, we may assume that there exists  $x_n \in \Omega$  such that  $v_n(x_n) = \max_{\overline{\Omega}} v_n = S_n \xrightarrow{n \rightarrow \infty} \infty$ . Write  $\delta_n = \text{dist}(x_n, \partial\Omega)$  and define  $w_n(y) = S_n^{-1}v_n(x)$ , where  $x = A_n y + x_n$  and  $A_n = [\lambda(p-1)^{q+1-p}(\ln(S_n+1))^q]^{-\frac{1}{p}}$ . The functions  $w_n$  are well-defined for  $y$  at least in  $B(0, \delta_n A_n^{-1})$  and  $w_n(0) = \max w_n = 1$ . Straightforward computations show that

$$c_0 \Upsilon(S_n, w_n(y)) \leq -\Delta_p w_n(y) - A_n^p \frac{\tau_n}{S_n^{p-1}} \leq c_1 \Upsilon(S_n, w_n(y)),$$

where  $\Upsilon(S_n, w_n(y)) = (w_n(y) + S_n^{-1})^{p-1} [\frac{\ln(S_n w_n(y) + 1)}{\ln(S_n + 1)}]^q$ . Now, by Lemma 2.2,  $A_n^p \frac{\tau_n}{S_n^{p-1}}$  tends to zero as  $n$  tends to infinity. Then, applying regularity theorems for the  $p$ -Laplacian operator, we can obtain estimates for  $w_n$  such that (up to a subsequence)  $w_n \rightarrow w$ , locally uniformly, with  $w$  a  $C^1$ -function defined on  $\mathbb{R}^N$  or on a half space, according to whether the limit of  $\delta_n$  is positive or zero.

Thus,  $w$  is a solution of the problem

$$\begin{aligned} c_0 w^{p-1} &\leq -\Delta_p w \leq c_1 w^{p-1}, \\ w &> 0, \quad w(0) = \max w = 1 \end{aligned} \tag{2.5}$$

which contradicts Lemma 2.1. □

### 3. Proof of the main results

The following lemma is a variant of a result due to Rabinowitz [23] which was proved in [4].

**Lemma 3.1.** *Let  $\mathbb{R}^+ = [0, +\infty)$  and  $(E, \|\cdot\|)$  be a real Banach-space. Let  $G : \mathbb{R}^+ \times E \rightarrow E$  be a continuous map which transforms bounded subsets into relatively compact ones. Moreover, suppose that  $G$  satisfies*

- (a)  $G(0, 0) = 0$ ,
- (b) *There exists  $R > 0$  such that*
  - (i)  $u \in E, \|u\| \leq R$  and  $u = G(0, u)$  implies  $u = 0$ ,
  - (ii)  $\text{deg}(Id - G(0, \cdot), B(0, R), 0) = 1$ .

Let  $J$  denote the set of solutions of the problem

$$(\mathfrak{P})u = G(t, u)$$

in  $\mathbb{R}^+ \times E$ . Further, let  $\mathfrak{C}$  denote the component (i.e. maximal closed connected subset) of  $J$  containing  $(0, 0)$ . If

$$\mathfrak{C} \cap (\{0\} \times E) = \{(0, 0)\},$$

then  $\mathfrak{C}$  is unbounded on  $\mathbb{R}^+ \times E$ .

Now, we recall the following definition of lower and upper solutions of  $(A_\lambda)_0$  (see, for example, [3]).

**Definition 3.1.** A function  $\underline{v} \in W^{1,p}(\Omega) \cap L^\infty(\Omega)$  is said to be a lower-solution of  $(A_\lambda)_0$  if

$$\begin{cases} \int_\Omega |\nabla \underline{v}|^{p-2} \nabla \underline{v} \nabla \phi \leq \int_\Omega g_\lambda(x, \underline{v}) \phi \\ \text{for each } \phi \in W_0^{1,p}(\Omega) \text{ with } \phi \geq 0, \\ \underline{v} \leq 0 \text{ on } \partial\Omega. \end{cases}$$

(A function  $v \in W^{1,p}(\Omega)$  is said to be less than or equal to  $w \in W^{1,p}(\Omega)$  on  $\partial\Omega$  if  $\max\{0, v - w\} \in W_0^{1,p}(\Omega)$ ).

Furthermore a function  $\bar{v} \in W^{1,p}(\Omega) \cap L^\infty(\Omega)$  is said to be an upper-solution of  $(A_\lambda)_0$  if

$$\begin{cases} \int_\Omega |\nabla \bar{v}|^{p-2} \nabla \bar{v} \nabla \phi \geq \int_\Omega g_\lambda(x, \bar{v}) \phi \\ \text{for each } \phi \in W_0^{1,p}(\Omega) \text{ with } \phi \geq 0, \\ \bar{v} \geq 0 \text{ on } \partial\Omega. \end{cases}$$

(A function  $v \in W^{1,p}(\Omega)$  is said to be bigger than or equal to  $w \in W^{1,p}(\Omega)$  on  $\partial\Omega$  if  $\max\{0, w - v\} \in W_0^{1,p}(\Omega)$ ). An upper-solution which is not a solution is said to be strict.

**Proof of Theorem 1.1**

We will prove a result which is slightly more general than Theorem 1.1.

**Proposition 3.1.** *Given  $\lambda > 0$  there exists a positive constant  $\tau^* = \tau^*(\lambda)$  such that  $(A_\lambda)_\tau$  has at least one positive solution for  $0 \leq \tau < \tau^*$ .*

*Proof.* Let  $\lambda > 0$  and define  $N : C^{1,\alpha}(\bar{\Omega}) \rightarrow L^\infty(\bar{\Omega})$  by  $N(v) = g_\lambda(x, v)$ . From the continuity of  $g_\lambda$  and the compactness of the inclusion  $C^{1,\alpha}(\bar{\Omega}) \hookrightarrow L^\infty(\bar{\Omega})$  we conclude that  $N$  is compact.

Also, we consider  $T : L^\infty(\bar{\Omega}) \rightarrow C^{1,\alpha}(\bar{\Omega})$  as the unique weak solution  $T(v)$  of the problem

$$\begin{cases} -\Delta_p T(v) = v & \text{in } \Omega, \\ T(v) = 0 & \text{on } \partial\Omega. \end{cases}$$

It is well-known that the function  $T$  is continuous and maps bounded sets into bounded sets (see Lemma 1.1 in [4], for example). Then  $K = T \circ N : C^{1,\alpha}(\bar{\Omega}) \rightarrow C^{1,\alpha}(\bar{\Omega})$  is compact.

Let  $G(t, v) = T(N(v)+t)$ , then  $G : \mathbb{R}^+ \times C^{1,\alpha}(\bar{\Omega}) \rightarrow C^{1,\alpha}(\bar{\Omega})$  is compact. Now, we will verify the hypotheses of Lemma 3.1. It is clear that  $G(0, 0) = 0$ . On the other hand, consider the compact homotopy  $H(\mu, v) : [0, 1] \times C^{1,\alpha}(\bar{\Omega}) \rightarrow C^{1,\alpha}(\bar{\Omega})$  given by  $H(\mu, v) = v - \mu G(0, v)$ . We will show that

$$\text{if } u \text{ is a nontrivial solution to } H(\mu, v) = 0, \text{ then } \|v\| > R > 0. \quad (*)$$

This will implies that conditions (i) and (ii) of (b) hold.

In order to prove (\*), note that  $H(\mu, v) = 0$  implies that  $v$  is a solution of the problem

$$\begin{cases} -\Delta_p v = \mu g_\lambda(x, v) & \text{in } \Omega, \\ v = 0 & \text{on } \partial\Omega, \end{cases} \tag{3.6}$$

where  $\mu \in [0, 1]$ . Now, from  $(G_2)$ , given  $\delta > 0$  small enough so that  $p + \delta$  is less than the critical exponent  $p^* = Np/(N - p)$ , and given  $\varepsilon > 0$ , there exists a constant  $c > 0$  (depending only on  $\varepsilon$  and  $\delta$ ) such that

$$g_\lambda(x, t) \leq \lambda c_1 (c |t|^\delta + \varepsilon) |t|^{p-1}. \tag{3.7}$$

Multiplying the equation in (3.6) by  $v$ , integrating over  $\Omega$ , using (3.7) and applying Hölder's and Poincare's inequalities, we have

$$\begin{aligned} \int_\Omega |\nabla v|^p &= \mu \int_\Omega g_\lambda(x, v) v \\ &\leq \lambda c_1 \left( c \int_\Omega |v|^{\delta+p} + \varepsilon \int_\Omega |v|^p \right) \\ &\leq \lambda C \left( \int_\Omega |\nabla v|^p \right)^{\frac{\delta+p}{p}} + \lambda C_1 \varepsilon \int_\Omega |\nabla v|^p. \end{aligned}$$

Choosing  $\varepsilon$  small enough we obtain that  $\|v\| > R$  for some positive constant  $R = R(\lambda)$ .

Proposition 2.1 implies that the component  $\mathfrak{C}$  which contains  $(0, 0)$  is bounded, so applying Lemma 3.1 we obtain that  $\mathfrak{C} \cap (\{0\} \times C^{1,\alpha}(\bar{\Omega})) \neq \{(0, 0)\}$ . Therefore, we have a positive solution of  $(A_\lambda)_0$ . Hence, defining  $\tau^* = \sup\{\tau > 0 : (A_\lambda)_\tau \text{ has a positive solution } v \text{ so that } (v, \tau) \in \mathfrak{C}\}$ , we see that  $\tau^*$  verifies the conclusion. This completes the proof.  $\square$

**Proof of Theorem 1.2**

First, note that  $(A_\lambda)_0$  has no positive solutions for  $\lambda > \bar{\lambda} = \frac{\lambda_1(\Omega)}{f_0}$ . Indeed, if  $v$  is a positive solution of  $(A_\lambda)_0$ , then  $v$  satisfies

$$\begin{cases} -\Delta_p v = \lambda \hat{g}(x, v) & \text{in } \Omega, \\ v = 0 & \text{on } \partial\Omega, \end{cases} \tag{*}$$

where  $\hat{g}(x, v) = \left(\frac{v+1}{p-1}\right)^{p-1} f(x, (p-1) \ln(v+1))$ .

From  $(G_2)$  and  $(F_3)$  we have

$$\begin{aligned} \hat{g}(x, v) &\geq f_0 \left(\frac{v+1}{p-1}\right)^{p-1} (p-1)^{p-1} (\ln(v+1))^{p-1} \\ &= f_0 [(v+1) \ln(v+1)]^{p-1} \geq f_0 v^{p-1}, \end{aligned}$$

then, using inequalities as in the proof of Lemma 2.1, we get

$$(\lambda f_0 - \lambda_1(\Omega)) \int_\Omega \phi_1^p \leq \int_\Omega (-\Delta_p v) \frac{\phi_1^p}{v^{p-1}} - \int_\Omega |\nabla \phi_1|^p \leq 0 \tag{3.8}$$

and this inequality implies that  $\lambda \leq \bar{\lambda}$ .



Let  $0 < \lambda < \bar{\lambda}$ . Following the lines of the proof of Proposition 3.1, we will show that any nontrivial solution of the problem

$$\begin{cases} -\Delta_p w = \rho g_\lambda(x, w) & \text{in } \Omega, \\ w = 0 & \text{on } \partial\Omega, \end{cases}$$

where  $\rho \in [0, 1]$ , satisfies condition (\*).

To this end, choose  $0 < \varepsilon < \frac{\bar{\lambda}}{\lambda} - 1$ . Then there exist positive constants  $c = c(\lambda, \varepsilon)$  and  $0 < \delta < \frac{p^2}{N-p}$  such that

$$g_\lambda(x, t) \leq \lambda f_0(1 + \varepsilon) t^{p-1} + c t^{p-1+\delta}.$$

Using the last inequality, together with the variational characterization of the first eigenvalue  $\lambda_1(\Omega)$  and Poincaré's inequality, we get

$$\begin{aligned} \|w\|^p &= \int_\Omega |\nabla w|^p = \rho \int_\Omega g_\lambda(x, w)w \\ &\leq \lambda f_0(1 + \varepsilon) \int_\Omega w^p + c \int_\Omega w^{p+\delta} \\ &\leq \lambda(1 + \varepsilon) \frac{f_0}{\lambda_1(\Omega)} \|w\|^p + C \|w\|^{p+\delta}. \end{aligned}$$

Hence  $\|w\| > \bar{c}$  for some positive constant  $\bar{c}$ .

Therefore, using Lemma 3.1, we have shown the existence of a positive solution of  $(A_\lambda)_0$  for  $0 < \lambda < \bar{\lambda}$ .

Finally, we need to prove that  $(A_{\bar{\lambda}})_0$  has no positive solutions. Arguing by contradiction, we assume that there exists a positive solution  $v$  for  $\lambda = \bar{\lambda}$ . Then from (3.8) we arrive at

$$0 = (\lambda f_0 - \lambda_1(\Omega)) \int_\Omega \phi_1^p \leq \int_\Omega (-\Delta_p v) \frac{\phi_1^p}{v^{p-1}} - \int_\Omega |\nabla \phi_1|^p = - \int_\Omega \mathcal{L}(\phi_1, v) \leq 0.$$

Hence  $\mathcal{L}(\phi_1, v) = 0$  and Picone's identity implies that there exists a  $c > 0$  such that  $v = c\phi_1$ . This together with the comparison principle yields the contradiction.

**Proof of Theorem 1.3**

We define  $\varphi : (0, +\infty) \rightarrow (0, +\infty)$  by

$$\varphi(t) = \frac{(t + 1)^{p-1} (\ln(t + 1))^q}{t^{p-1}}.$$

Since  $0 < q < p - 1$ , there exists  $t_0 > 0$  such that

$$\varphi(t_0) = \inf_{t>0} \varphi(t).$$

With the same notation used in the proof of Theorem 1.2 we arrive at

$$\frac{\widehat{g}(x, t)}{t^{p-1}} \geq c_0(p - 1)^{q+1-p} \varphi(t) \quad \text{for all } t > 0.$$

Hence  $(A_\lambda)_0$  has no positive solutions if  $\lambda > \Lambda = \lambda_1(\Omega) \frac{(p-1)^{p-1-q}}{c_0 \varphi(t_0)}$ .

On the other hand, let  $\tilde{\lambda}$  such that  $\tilde{\lambda}c_1(p-1)^{q+1-p}\varphi(t_0) = \|e\|_{L^\infty}^{1-p}$ , where  $e$  is given in (2.4). Observe that, using a comparison argument, we get  $\Lambda > \tilde{\lambda}$ . Then, for any  $0 < \lambda \leq \tilde{\lambda}$ , we have that  $\bar{v}_\lambda = Me$ , is an upper-solution of  $(A_\lambda)_0$  where  $M = t_0/\|e\|_{L^\infty}$ . In effect, we have

$$\begin{aligned} \int_{\Omega} |\nabla \bar{v}_\lambda|^{p-2} \nabla \bar{v}_\lambda \nabla \phi &= M^{p-1} \int_{\Omega} |\nabla e|^{p-2} \nabla e \nabla \phi \\ &= \int_{\Omega} t_0^{p-1} \varphi(t_0) \tilde{\lambda} c_1 (p-1)^{q+1-p} \phi \\ &\geq \int_{\Omega} (Me)^{p-1} \varphi(Me) \tilde{\lambda} c_1 (p-1)^{q+1-p} \phi \\ &\geq \int_{\Omega} \lambda \hat{g}(x, Me) \phi = \int_{\Omega} g_\lambda(x, \bar{v}_\lambda) \phi. \end{aligned}$$

Thus  $\bar{v}_\lambda$  is an upper-solution of  $(A_\lambda)_0$ . Therefore, applying Theorem 1.3 of [7], we obtain a solution of  $(A_\lambda)_0$  for any  $0 < \lambda < \tilde{\lambda}$ .

Let

$$\bar{\Lambda} = \sup \{ \lambda > 0 : (A_\lambda)_0 \text{ has a positive solution} \},$$

then  $\tilde{\lambda} \leq \bar{\Lambda} \leq \Lambda$ .

**Lemma 3.2.**  $(A_{\bar{\Lambda}})_0$  has at least one positive solution.

*Proof.* As in the proof of Theorem 1.1 of [8], we consider  $\{\lambda_n\}_{n \in \mathbb{N}}$  a strictly increasing sequence with  $\lim_{n \rightarrow \infty} \lambda_n = \bar{\Lambda}$ ,  $\lambda_n \in [\bar{\Lambda}/2, \bar{\Lambda})$ , and write  $v_{\lambda_n}$  for a positive solution of  $(A_{\lambda_n})_0$  for  $n = 1, 2, \dots$ . Note that the behavior of  $\varphi$  near zero implies that, given  $\varepsilon > 0$ , there exists  $\delta > 0$  such that

$$\lambda_1(\Omega) + \varepsilon \leq \frac{\bar{\Lambda}}{2} c_0 (p-1)^{q+1-p} \varphi(s) \quad \text{for all } s \in (0, \delta). \tag{3.9}$$

Setting  $\varepsilon = 1$  we choose  $\delta_0 > 0$  so that (3.9) holds for any  $s \in (0, \delta_0)$ . Using the above we will show that

$$\|v_{\lambda_n}\|_\infty \geq \delta_0 \quad \text{for } n = 1, 2, \dots \tag{3.10}$$

Indeed, if we assume that  $0 < v_{\lambda_n} < \delta_0$  in  $\Omega$ , then Picone's identity implies that

$$\begin{aligned} \int_{\Omega} \phi_1^p &= \int_{\Omega} (\lambda_1(\Omega) + 1) \phi_1^p - \int_{\Omega} \lambda_1(\Omega) \phi_1^p \\ &\leq \frac{\bar{\Lambda}}{2} \int_{\Omega} \hat{g}_{\lambda_n}(x, v_{\lambda_n}) \frac{\phi_1^p}{v_{\lambda_n}^{p-1}} - \int_{\Omega} |\nabla \phi_1|^p \\ &\leq \lambda_n \int_{\Omega} \hat{g}_{\lambda_n}(x, v_{\lambda_n}) \frac{\phi_1^p}{v_{\lambda_n}^{p-1}} - \int_{\Omega} |\nabla \phi_1|^p \\ &= \int_{\Omega} (-\Delta_p v_{\lambda_n}) \frac{\phi_1^p}{v_{\lambda_n}^{p-1}} - \int_{\Omega} |\nabla \phi_1|^p \leq 0. \end{aligned}$$

This is a contradiction. Hence we obtain (3.10).

As in Proposition 2.1 we conclude that the functions  $v_{\lambda_n}$  are equibounded on  $C^{1,\alpha}(\bar{\Omega})$ . Thus by the Arzela–Ascoli Theorem, there exists a subsequence of  $\{v_{\lambda_n}\}$  which converges in  $C^1_0(\bar{\Omega})$  to a function  $v \in C^1_0(\bar{\Omega})$  that may be identified easily as a solution of  $(A_{\bar{\lambda}})_0$ . Moreover (3.10), shows that

$$\|v\|_\infty \geq \delta_0.$$

This proves the lemma. □

Let  $0 < \lambda < \bar{\lambda}$  be fixed. The following lemma was proved by de Figueiredo and Lions [10] in the particular case  $p = 2$  and  $g_\lambda(x, u) = g(u)$ , although slight modifications of that proof allow us to deal with the problem  $(A_\lambda)_0$ .

**Lemma 3.3.** *In addition to  $(G_1)$ ,  $(G_2)$  and  $(G_3)$ , assume that  $(A_\lambda)_0$  has a strict upper-solution  $w_\lambda$ . Then  $(A_\lambda)_0$  has two solutions  $0 < u_1 < u_2$ , and  $u_1$  is the minimal solution.*

*Proof.* Let us denote by  $X$  the Banach space of  $C^1$ -functions on  $\bar{\Omega}$  which are 0 on  $\partial\Omega$ , endowed with the usual  $C^1$ -norm. Define  $g_\lambda$  for negative  $s$  as  $g_\lambda(x, s) = g_\lambda(x, 0) = 0$  for all  $x \in \Omega$ . The solutions of  $(A_\lambda)_0$  with this extended  $g_\lambda$  are the same as the original problem  $(A_\lambda)_0$ . For in either case the solutions are all positive. Let us define the one-parameter family of functions

$$h_\mu(x, s) = \mu g_\lambda(x, s) + (1 - \mu)\xi s_+^{p-1}, \quad 0 \leq \mu \leq 1$$

where  $\xi > \lambda_1(\Omega)$  is a fixed number and  $s_+ = \max\{0, s\}$ . In view of our assumptions, there is a constant  $c_1 > 0$  such that

$$\|u\|_X \leq c_1 \tag{3.11}$$

for all possible solutions of the problems

$$\begin{cases} -\Delta_p u = h_\mu(x, u) & \text{in } \Omega, \quad 0 \leq \mu \leq 1, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \tag{Q}_\mu$$

Indeed, assume that there exist  $\{(u_n, \mu_n)\}$  such that  $\|u_n\|_X \rightarrow +\infty$  and  $\mu_n \in [0, 1]$ . If  $0 \in \overline{\{\mu_n\}_{n \in \mathbb{N}}}$ , i.e., 0 is a cluster point of the sequence  $\{\mu_n\}_{n \in \mathbb{N}}$ , then without loss of generality we may assume that  $\mu_n \rightarrow 0$ . Thus, for  $n$  large enough we have that  $\xi(1 - \mu_n) > \lambda_1(\Omega)$ . Now, using an argument similar to one used in the proof of Lemma 2.1, we get

$$(\xi(1 - \mu_n) - \lambda_1(\Omega)) \int_\Omega \phi_1^p \leq 0.$$

But this is impossible. Therefore, there exists  $0 < \mu_0 \leq 1$  such that  $\mu_0 \leq \mu_n$  for all  $n \in \mathbb{N}$ . Now, using Lieberman’s estimates [21], we may assume that  $\|u_n\|_\infty \rightarrow +\infty$ . Let  $x_n \in \Omega$  be such that  $u_n(x_n) = \|u_n\|_\infty = S_n$ ,  $d_n = \text{dist}(x_n, \partial\Omega)$  and  $A_n = [\mu_n \lambda(p-1)^{q+1-p} (\ln(S_n+1))^q]^{-\frac{1}{p}}$ . In this way, defining  $w_n(y) = S_n^{-1} u_n(A_n y + x_n)$ , we see that the functions  $w_n$  are well-defined at least on  $B(0, d_n A_n^{-1})$  and  $w_n(0) = \|w_n\|_\infty = 1$ . Now, straightforward computations show that

$$c_0 \Upsilon(S_n, w_n(y)) \leq -\Delta_p w_n(y) - (1 - \mu_n)\xi A_n^p (w_n(y))^{p-1} \leq c_1 \Upsilon(S_n, w_n(y)),$$

where  $\Upsilon(S_n, w_n(y))$  is as in the proof of Proposition 2.1. Now, applying regularity theorems for the  $p$ -Laplacian operator, we can obtain  $C^{1,\alpha}(\bar{\Omega})$  estimates for  $w_n$  such that for a subsequence  $w_n \rightarrow w$ , locally uniformly, with  $w$  a  $C^1$ -function defined on  $\mathbb{R}^N$  or on a halfspace. This implies that  $w$  is a solution of  $-\Delta_p w \geq c_0 w^{p-1}$ ,  $w \geq 0, w(0) = \max w = 1$ , which is a contradiction.

Therefore, there exist  $c_1 > 0$  such that  $\|u\|_X \leq c_1$  for all possible positive solutions  $u$  of  $(Q)_\mu$  for  $0 \leq \mu \leq 1$ .

By  $(G_3)$  there exists  $k > 0$  such that  $g_\lambda(x, s) + ks^{p-1}$  is increasing for  $s \in [0, \|w_\lambda\|_{L^\infty}]$  for a.e.  $x \in \Omega$ . Let  $K_\mu = (-\Delta_p + k)^{-1}(h_\mu(x, \cdot) + k \cdot)$ . More precisely, let us define  $K_\mu : X \rightarrow X$  as follows:  $K_\mu v = u$ , where  $u$  is the solution of the Dirichlet problem

$$\begin{cases} -\Delta_p u + ku^{p-1} = h_\mu(x, v) + kv^{p-1} & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

The mapping  $K_\mu$  so defined is compact. From the Schauder estimates (see for instance [21]) it follows that there exists a constant  $c_2 > 0$  such that

$$\|K_\mu v\|_X \leq c_2, \quad \forall v \in X, \quad 0 \leq v \leq w_\lambda. \tag{3.12}$$

Since  $0 < q < p - 1$ , we see that there is an  $\varepsilon_\lambda > 0$  such that  $\varepsilon_\lambda \phi_1$  is a lower-solution for all problems  $(Q)_\mu$ . Also we may take  $\varepsilon_\lambda \phi_1 < w_\lambda$  on  $\Omega$ . It follows from the maximum principle that any solution  $u$  of  $(Q)_\mu$  such that  $u \geq \varepsilon_\lambda \phi_1$  on  $\Omega$  satisfies the strict inequalities  $u > \varepsilon_\lambda \phi_1$  on  $\Omega$  and  $\partial u / \partial \nu < \varepsilon_\lambda (\partial \phi_1 / \partial \nu)$  on  $\partial\Omega$ . Now consider the bounded open set

$$\mathcal{O} = \left\{ u \in X : \|u\|_X < c_1 + c_2 + 1, u > \varepsilon_\lambda \phi_1 \text{ in } \Omega, \frac{\partial u}{\partial \nu} < \varepsilon_\lambda \frac{\partial \phi_1}{\partial \nu} \text{ on } \partial\Omega \right\},$$

where  $c_1$  and  $c_2$  are the constants defined in (3.11) and (3.12), respectively, and  $\varepsilon_\lambda \phi_1$  is the lower-solution defined above. By the above remarks, it follows that  $0 \notin (I - K_\mu)(\partial\mathcal{O})$ . So the degree  $\deg(I - K_\mu, \mathcal{O}, 0)$  is independent of  $\mu \in [0, 1]$ . Clearly the degree  $\deg(I - K_0, \mathcal{O}, 0) = 0$  since  $(Q)_0$  has no solution. Hence

$$\deg(I - K_1, \mathcal{O}, 0) = 0.$$

Now let us consider the following open subset of  $\mathcal{O}$ :

$$\mathcal{O}' = \left\{ u \in \mathcal{O} : u < w_\lambda \text{ in } \Omega, \frac{\partial u}{\partial \nu} > \frac{\partial w_\lambda}{\partial \nu} \text{ on } \partial\Omega \right\},$$

and we claim that  $\deg(I - K_1, \mathcal{O}', 0) = 1$ . Once this is proved, it follows that  $\deg(I - K_\mu, \mathcal{O} \setminus \overline{\mathcal{O}'}, 0) = -1$ . So  $(Q)_1$ , which is the same as  $(A_\lambda)_0$ , has two solutions  $\tilde{u}_1 \in \mathcal{O}'$  and  $u_2 \in \mathcal{O} \setminus \overline{\mathcal{O}'}$ , which are not necessarily ordered. So we have to proceed further in order to complete the proof of the theorem. Let  $v = \min\{w_\lambda, u_2\}$ . It follows that  $v$  is in  $W_0^{1,\infty}(\Omega)$ ,  $\varepsilon_\lambda \phi_1 \leq v$  and

$$-\Delta_p v \geq g_\lambda(x, v), \quad \text{in } \mathcal{D}'(\Omega).$$

So the monotone iteration method yields the existence of a solution  $u_1$  of  $(A_\lambda)_0$ , with  $0 < u_1 < u_2$  and  $u_1$  is the minimal solution of  $(A_\lambda)_0$ . To complete the proof

we have to prove the above claim. To do so observe that  $K_1$  maps  $\mathcal{O}'$  into  $\mathcal{O}'$ . Let  $u_0 \in \mathcal{O}'$  and consider the constant mapping  $C : \mathcal{O}' \rightarrow \mathcal{O}'$  defined by  $C(u) = u_0$ . By the convexity of  $\mathcal{O}'$ , it follows that  $I - K_1$  is homotopic to  $I - C$  on  $\mathcal{O}'$  and  $\deg(I - K_1, \mathcal{O}', 0) = \deg(I - C, \mathcal{O}', 0)$ . But this last degree is trivially equal to 1. The proof is complete.  $\square$

Using Lemma 3.3 above, we only need to construct a strict upper-solution  $\bar{u}_\lambda$ . It is easy to see that, setting  $\bar{u}_\lambda = u_{\bar{\lambda}}$ , where  $u_{\bar{\lambda}}$  is a positive solution of  $(A_{\bar{\lambda}})_0$ ,  $\bar{u}_\lambda$  is a strict upper-solution to the problem  $(A_\lambda)_0$  for any  $0 < \lambda < \bar{\lambda}$ .

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