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**Results in Mathematics** 



# Continuity and Structure of Generalized $(\phi, \psi)$ -Derivations

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Abstract. Let  $\mathcal{X}$  be a Banach algebra, let  $\phi, \psi$  be mappings on  $\mathcal{X}$ , let  $\delta$  be a  $(\phi, \psi)$ -derivation on  $\mathcal{X}$  and let d be a generalized  $(\phi, \psi)$ -derivation related to  $\delta$ . If  $\mathcal{X}$  is simple, we determine some sufficient conditions under which every generalized  $(\phi, \psi)$ -derivation on  $\mathcal{X}$  is continuous (without continuity of  $\delta$ ). In addition, we show that if d is inner on  $\mathcal{F}_1(\mathcal{X})$  (the set of all rank one operators on  $\mathcal{X}$ ) and  $\phi, \psi : \mathcal{B}(\mathcal{X}) \longrightarrow \mathcal{B}(\mathcal{X})$  are homomorphisms and surjective on  $\mathcal{F}_1(\mathcal{X})$  then d is inner on  $\mathcal{B}(\mathcal{X})$ . Finally, we characterize the linear mappings on  $\mathcal{B}(\mathcal{X})$  which behave like generalized  $(\phi, \psi)$ -derivations when acting on zero products.

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### 1. Introduction and Preliminaries

Suppose that  $\mathcal{X}$  is a complex algebra and  $\phi, \psi : \mathcal{X} \longrightarrow \mathcal{X}$  are two mappings. A linear mapping  $\delta : \mathcal{X} \longrightarrow \mathcal{X}$  is called a  $(\phi, \psi)$ -derivation, if for each  $x, y \in \mathcal{X}$ 

$$\delta(xy) = \delta(x)\phi(y) + \psi(x)\delta(y). \tag{1.1}$$

Let  $\phi, \psi : \mathcal{X} \longrightarrow \mathcal{X}$  be two mappings and let  $\delta : \mathcal{X} \longrightarrow \mathcal{X}$  be a  $(\phi, \psi)$ -derivation. A linear mapping  $d : \mathcal{X} \longrightarrow \mathcal{X}$  is called a generalized  $(\phi, \psi)$ -derivation related to  $\delta$ , if

$$d(xy) = d(x)\phi(y) + \psi(x)\delta(y) \quad (x, y \in \mathcal{X}).$$
(1.2)

If  $\phi, \psi$  are automorphisms of algebra  $\mathcal{X}$  and there exist  $x_0, y_0 \in \mathcal{X}$  such that  $d(z) = x_0\phi(z) - \psi(z)y_0$ , for all  $z \in \mathcal{X}$  then d is a generalized  $(\phi, \psi)$ -derivation which is called inner generalized  $(\phi, \psi)$ -derivation.

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The theory of automatic continuity of derivations has a long history. Sakai [11] answered to the conjecture made by Kaplansky in [8]. He proved that every derivation on a  $C^*$ -algebra is automatically continuous. In [10], Ringrose generalized these results to derivations from a  $C^*$ -algebra  $\mathcal{A}$  into a Banach  $\mathcal{A}$ -module. Johnson and Sinclair in [6] proved the continuity of derivations on semisimple Banach algebras. In [9], it's shown that every  $(\phi, \psi)$ -derivation on a  $C^*$ -algebra is automatically continuous, if  $\phi, \psi$  are continuous \*-linear mappings and in [3] the assumption of linearity of  $\phi, \psi$  were deleted. Hou et al. [4] proved that every  $(\phi, \psi)$ -derivation on  $\mathcal{B}(\mathcal{X})$  is continuous, if  $\mathcal{X}$  is simple and  $\phi, \psi$  are surjective and continuous mappings on  $\mathcal{B}(\mathcal{X})$ . For more results concerning these subjects, we refer to [2,13].

In [7], Kadison showed that every derivation of a  $C^*$ -algebra on Hilbert space is spatial and every derivation of a von Neumann algebra is inner. Sakai [12] proved that every derivation of a  $W^*$ -algebra is inner. Innerness of derivations of a nest algebra has been proved by Christensen in [1]. Also Hou et al. [4] give some sufficient conditions on which every  $(\phi, \psi)$ -derivation of  $\mathcal{B}(\mathcal{X})$  is inner.

In [5], Jing et al. showed that an additive mapping on operator algebra is almost a derivation, if it satisfies the formula of derivations on pairs of elements with zero product. We discuss this issue in the last section.

In this paper, we extend some of the results concerning  $(\phi, \psi)$ -derivations to generalized  $(\phi, \psi)$ -derivations. In fact, by investigating of the notion of generalized  $(\phi, \psi)$ -derivations, we deduce this results for the notion of derivations ( if  $\phi = \psi = id$  and  $\delta = d$ ), the notion of generalized derivations ( if  $\phi = \psi = id$ ), the notion of  $(\phi, \psi)$ -derivations ( if  $\delta = d$ ), and the notion of left centralizer ( if  $\phi = \psi = id$  and  $\delta = 0$ ). So it's interesting to investigate details of this general notion of derivations.

This paper consists of three sections. After introducing the notion of generalized  $(\phi, \psi)$ -derivations in the first section, we give some examples and theorems concerning continuity of generalized  $(\phi, \psi)$ -derivations on a Banach algebra, in the second. In the third section, we give some sufficient conditions on which every  $(\phi, \psi)$ -derivation on  $\mathcal{B}(\mathcal{X})$  is inner. Also we characterize the linear mappings on  $\mathcal{B}(\mathcal{X})$  which behave like derivations when acting on zero products.

For a complex Banach algebra  $\mathcal{X}$  we denote the Banach dual space of  $\mathcal{X}$ and the algebra of bounded linear operators on  $\mathcal{X}$ , by  $\mathcal{X}^*$  and  $\mathcal{B}(\mathcal{X})$ . Denote by  $\mathcal{F}_1(\mathcal{X})$ , the set of all rank one operators on  $\mathcal{X}$ . We define rank one operators on  $\mathcal{X}$  by  $(x \otimes f)(y) = f(y)x$ , for  $x, y \in \mathcal{X}$  and  $f \in \mathcal{X}^*$ . We collect some properties of  $x \otimes f$  in the following lemma;

**Lemma 1.** Let  $\mathcal{X}$  be a Banach algebra then for each  $x, y \in \mathcal{X}$ ,  $f, g \in \mathcal{X}^*$  and  $T, S \in \mathcal{B}(\mathcal{X})$  we have;

(1)  $T(x \otimes f)S = (Tx) \otimes (S'f)$ , where S' denotes the adjoint of the operator S,

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(2)  $(x \otimes f)(y \otimes g) = f(y)(x \otimes g),$ 

(3) If  $T(x \otimes f) = 0$ , for each  $x \in \mathcal{X}$  then T = 0.

Recall that if  $\mathcal{X}, \mathcal{Y}$  are normed spaces and  $T : \mathcal{X} \longrightarrow \mathcal{Y}$  is a linear mapping, the separating space  $\mathfrak{S}(T)$  of T is the set of all y such that there is a sequence  $\{x_n\}$  in  $\mathcal{X}$  that  $x_n \longrightarrow 0$  and  $Tx_n \longrightarrow y$ . Clearly,  $\mathfrak{S}(T)$  is a closed linear space. Also, if  $\mathcal{X}, \mathcal{Y}$  are Banach spaces, by closed graph theorem, T is continuous if and only if  $\mathfrak{S}(T) = \{0\}$ .

Using assertions of [4], to investigate the continuity and structure of generalized  $(\phi, \psi)$ -derivations of Banach algebras, we may assume that  $\mathcal{X}$  is unital,  $\delta(1) = 0, \phi(0) = \psi(0) = 0, \phi(1) = \psi(1) = 1$ , where 1 is the identity of  $\mathcal{X}$ .

# 2. Automatic Continuity of Generalized $(\phi, \psi)$ -Derivations of Banach Algebras

We start this section with some examples.

*Example* 1. We use idea of Example 2.4 in [3] and we assume that  $\gamma, \theta$  are two arbitrary mappings on  $\mathcal{C}[0,2]$  and take  $f_1, f_2, h_0, h_1 \in \mathcal{C}[0,2]$  such that  $f_1h_0 = 0 = f_2h_0$  and  $f_2h_1 = 0$ . Define  $\phi, \psi, d, \delta$  on  $\mathcal{C}[0,2]$  by

$$\psi(f) = \gamma(f)f_1, \quad \phi(f) = f + f_2\theta(f)$$
  
$$\delta(f) = fh_0, \quad d(f) = fh_0 + fh_1.$$

Clearly,  $\delta$  is a  $(\phi, \psi)$ -derivation and d is a generalized  $(\phi, \psi)$ -derivation related to  $\delta$ . (We see that  $\gamma$  and  $\theta$  can be nonlinear and discontinuous.)

*Example* 2. Let  $\mathcal{X}$  be a Banach algebra, let  $\gamma, \theta$  be continuous homomorphisms of  $\mathcal{X}$ , let  $f_1, f_2$  be two functionals without linearity and continuity, and  $x_1, y_1, z_1 \in \mathcal{X}$  with  $x_1 z_1 = 0 = y_1 z_1$ . Define the mappings  $\phi, \psi, d$  on  $\mathcal{X}$  for  $u \in \mathcal{X}$  by

$$\phi(u) = \gamma(u) + f_1(u)z_1, \quad \psi(u) = \theta(u) + f_2(u)z_1$$
$$d(u) = x_1\phi(u) - \psi(u)y_1.$$

So  $\phi, \psi$  are nonlinear and discontinuous. Although,  $\phi, \psi$  are not automorphism, we see d is an inner generalized  $(\phi, \psi)$ -derivation of  $\mathcal{X}$ . Indeed, by definition of  $\phi, \psi$  and the relations of between  $x_1, z_1$  and  $y_1, z_1$  we can show that d is an inner generalized  $(\phi, \psi)$ -derivation.

Also, since we have  $d(u) = x_1 \gamma(u) - \theta(u) y_1$  for each  $u \in \mathcal{X}$ , thus d is continuous.

**Lemma 2.** Let  $\mathcal{X}$  be a complex Banach algebra, let  $\phi, \psi : \mathcal{X} \longrightarrow \mathcal{X}$  be two mappings with  $\phi$  be continuous at 0 and let d be a generalized  $(\phi, \psi)$ -derivation related to  $\delta$ . If  $x_n \to 0$  and  $d(x_n) \longrightarrow x$  then  $\delta(x_n) \longrightarrow x$ .

*Proof.* By Definition of generalized  $(\phi, \psi)$ -derivations (1.2) we have

$$x = \lim_{n \to \infty} d(1x_n) = \lim_{n \to \infty} (d(1)\phi(x_n) + \psi(1)\delta(x_n)) = \lim_{n \to \infty} \delta(x_n).$$

**Proposition 1.** Let  $\mathcal{X}$  be a Banach algebra and let  $\mathcal{M}$  be a Banach  $\mathcal{X}$ -bimodule. Let  $\phi, \psi : \mathcal{X} \longrightarrow \mathcal{M}$  be two mappings with  $\phi$  be continuous at 0. If  $d : \mathcal{X} \longrightarrow \mathcal{M}$  is a generalized  $(\phi, \psi)$ -derivation related to  $\delta : \mathcal{X} \longrightarrow \mathcal{M}$  then d is continuous if and only if  $\delta$  is continuous.

*Proof.* Put  $T := d - \delta$ . Obviously,  $T(xy) = T(x)\phi(y)$ . So  $T(y) = T(1y) = T(1)\phi(y)$ . Therefore continuity of  $\phi$  implies that T is continuous. Hence d is continuous if and only if  $\delta$  is continuous.

Now we are going to delete the assumption of the continuity of  $\delta$  and obtain continuity of d. We present the first main result.

**Theorem 1.** Let  $\mathcal{X}$  be a simple complex Banach algebra and let  $\phi, \psi : \mathcal{X} \longrightarrow \mathcal{X}$ be surjective and continuous at 0. If at least either  $\phi$  or  $\psi$  is not homomorphism, then every generalized  $(\phi, \psi)$ -derivation  $d : \mathcal{X} \longrightarrow \mathcal{X}$  related to  $\delta$  is continuous.

*Proof.* At first, using assertions of [4], we can assume that  $\phi^{(0)} = 0$  and  $\psi(0) = 0$ . Now, we show that  $\mathfrak{S}(d)$  is two sided ideal in  $\mathcal{X}$ . For this, if  $a \in \mathfrak{S}(d)$  then there exists a sequence  $\{x_n\}$  in  $\mathcal{X}$  such that  $x_n \to 0$  and  $d(x_n) \to a$ . Since  $\phi$  and  $\psi$  are surjective, for every  $x \in \mathcal{X}$  there are  $y, z \in \mathcal{X}$  such that  $\phi(y) = x$  and  $\psi(z) = x$ . So we have

$$\lim_{n \to \infty} d(x_n y) = \lim_{n \to \infty} (d(x_n)\phi(y) + \psi(x_n)\delta(y)) = \lim_{n \to \infty} d(x_n)\phi(y) = ax$$

with  $x_n y \to 0$ . Therefore  $ax \in \mathfrak{S}(d)$ . Similarly, by Lemma 2, we have  $xa = \lim_{n \to \infty} d(zx_n)$  with  $zx_n \to 0$ , so  $xa \in \mathfrak{S}(d)$ . Hence  $\mathfrak{S}(d)$  is two sided ideal in  $\mathcal{X}$ . Since  $\mathcal{X}$  is simple, either  $\mathfrak{S}(d)=\{0\}$  or  $\mathfrak{S}(d)=\mathcal{X}$ .

If  $\mathfrak{S}(d) = \mathcal{X}$ , for arbitrary  $y, z \in \mathcal{X}$  and  $x \in \mathfrak{S}(d)$ , let  $d(x_n) \to x$  which  $x_n \to 0$ . By using idea of Lemma 3.1 in [3], we have  $d(x_n)(\phi(yz) - \phi(y)\phi(z)) = (\psi(x_ny) - \psi(x_n)\psi(y))\delta(z)$ , which obtain

$$x(\phi(yz) - \phi(y)\phi(z)) = 0.$$
 (2.1)

Similarly, we get to  $d(z)(\phi(yx_n) - \phi(y)\phi(x_n)) = (\psi(zy) - \psi(z)\psi(y))\delta(x_n)$ . So  $(\psi(yz) - \psi(y)\psi(z))x = 0.$  (2.2)

Similarly, by  $d(x_n)(\phi(\lambda y + z) - \lambda \phi(y) - \phi(z)) = 0$ , we can obtain that

$$x(\phi(\lambda y + z) - \lambda\phi(y) - \phi(z)) = 0.$$
(2.3)

And by 
$$(\psi(\lambda y + z) - \lambda \psi(y) - \psi(z))\delta(x_n) = 0$$
, we have  
 $(\psi(\lambda y + z) - \lambda \psi(y) - \psi(z))x = 0.$  (2.4)

These four equations show that  $\phi, \psi$  are homomorphisms, which is a contradiction. Hence  $\mathfrak{S}(d) = \{0\}$ . It means that d is continuous.

**Theorem 2.** Let  $\mathcal{X}$  be a simple complex Banach algebra, let  $\phi, \psi : \mathcal{X} \longrightarrow \mathcal{X}$  be surjective and continuous at 0 and let d be a generalized  $(\phi, \psi)$ -derivation related to  $\delta$ . If one of the following conditions holds:

- (1)  $\mathcal{A}nn_l(\delta(\mathcal{X})) = \{ y \in \mathcal{X} \mid y\delta(x) = 0, \forall x \in \mathcal{X} \} \neq \{ 0 \}$
- (2)  $\mathcal{A}nn_r(\delta(\mathcal{X})) = \{y \in \mathcal{X} \mid \delta(x)y = 0, \forall x \in \mathcal{X}\} \neq \{0\}$
- (3) There exists a noninvertible and nonidempotent element  $x_0 \in \mathcal{Z}(\mathcal{X})$  (the center of  $\mathcal{X}$ ) with  $0 \neq x_0^2 = x_0^3$ .

Then d is continuous.

*Proof.* If at least either  $\phi$  or  $\psi$  is not a homomorphism then by Theorem 1 we have done. Now, we suppose that  $\phi, \psi$  are homomorphisms.

If (1) holds, then for  $0 \neq x_0 \in Ann_l(\delta(\mathcal{X}))$ , we define  $\psi_0 : \mathcal{X} \longrightarrow \mathcal{X}$  with  $\psi_0(x) = \psi(x) + x_0$ . Since  $\psi$  is surjective and continuous at zero,  $\psi_0$  is surjective and continuous at zero, too. However  $\psi_0$  is not homomorphism. Clearly,  $\delta$  is a  $(\phi, \psi_0)$ -derivation and d is a generalized  $(\phi, \psi_0)$ -derivation related to  $\delta$ . Hence by Theorem 1, d is continuous.

If (2) holds, then for  $0 \neq x_0 \in Ann_r(\delta(\mathcal{X}))$ , we define  $\phi_0 : \mathcal{X} \longrightarrow \mathcal{X}$  with  $\phi_0(x) = \phi(x) + x_0$ . Obviously,  $\phi_0$  is surjective and continuous at zero and  $\delta$  is a  $(\phi_0, \psi)$ -derivation. We can consider  $\delta$  as a generalized  $(\phi_0, \psi)$ -derivation related to  $\delta$  so by Theorem 1,  $\delta$  is continuous. Therefore by Proposition 1, d is continuous.

If (3) holds, then for  $0 \neq x_0 \in \mathcal{Z}(\mathcal{X})$  with  $x_0^2 \neq x_0$  and  $0 \neq x_0^2 = x_0^3$ , by a simple calculating we have

$$\begin{aligned} x_0^2 \delta(xy) &= x_0^2 \delta(x) \phi(y) + x_0^2 \psi(x) \delta(y) \\ &= x_0^2 \delta(x) \phi(y) + x_0^3 \psi(x) \delta(y) \\ &= x_0^2 \delta(x) \phi(y) + x_0 \psi(x) x_0^2 \delta(y) \end{aligned}$$

So  $x_0^2 \delta$  is a  $(\phi, x_0 \psi)$ -derivation and similarly,  $x_0^2 d$  is a generalized  $(\phi, x_0 \psi)$ derivation related to  $x_0^2 \delta$ . Since  $(x_0^2 - x_0)\psi(\mathcal{X}) = (x_0^2 - x_0)\mathcal{X}$  is an ideal of  $\mathcal{X}$  containing  $(x_0^2 - x_0)$  and  $\mathcal{X}$  is simple, so  $(x_0^2 - x_0)\psi(\mathcal{X}) = \mathcal{X}$ . Therefore  $(x_0\psi)(xy) - (x_0\psi)(x)(x_0\psi)(y) = (x_0\psi)(xy) - (x_0^2\psi)(xy) \neq 0$  for some  $x, y \in \mathcal{X}$ . So  $x_0\psi$  is not homomorphism. Also  $(x_0\psi)(\mathcal{X}) = x_0\mathcal{X}$  is an ideal of  $\mathcal{X}$  so  $x_0\psi(\mathcal{X}) = \mathcal{X}$ . Hence  $x_0\psi$  is surjective. By Theorem 1,  $x_0^2d$  is continuous. Since  $x_0^2\mathfrak{S}(d) \subseteq \mathfrak{S}(x_0^2d)$ , we have  $x_0^2\mathfrak{S}(d) = \{0\}$ . We know  $\mathfrak{S}(d)$  is an ideal of  $\mathcal{X}$  (by first part of Theorem 1). Since  $\mathcal{X}$  is simple, either  $\mathfrak{S}(d) = \{0\}$  or  $\mathfrak{S}(d) = \mathcal{X}$ . If  $\mathfrak{S}(d) = \mathcal{X}$  then  $x_0^2\mathcal{X} = \{0\}$ , so  $x_0^2 = x_0^3 = 0$  which is a contradiction. Therefore  $\mathfrak{S}(d) = \{0\}$  and d is continuous.

## Characterizing Structure of Generalized (φ, ψ)-Derivations on B(X)

The first theorem of this section states that innerness of generalized  $(\phi, \psi)$ derivations on  $\mathcal{F}_1(\mathcal{X})$  completely decide innerness of generalized  $(\phi, \psi)$ derivations on  $\mathcal{B}(\mathcal{X})$ . **Theorem 3.** Let  $\mathcal{X}$  be a complex Banach algebra and let two homomorphisms  $\phi, \psi : \mathcal{B}(\mathcal{X}) \longrightarrow \mathcal{B}(\mathcal{X})$  be surjective on  $\mathcal{F}_1(\mathcal{X})$ . If  $d : \mathcal{B}(\mathcal{X}) \longrightarrow \mathcal{B}(\mathcal{X})$  is a generalized  $(\phi, \psi)$ -derivation related to  $\delta$  which is inner on  $\mathcal{F}_1(\mathcal{X})$  then d is inner on  $\mathcal{B}(\mathcal{X})$ .

*Proof.* By the hypotheses on d, there exist  $T, S \in \mathcal{B}(\mathcal{X})$  such that  $d(x \otimes f) = S\phi(x \otimes f) - \psi(x \otimes f)T$ , for every  $x \otimes f \in \mathcal{F}_1(X)$ . We define d' on  $\mathcal{B}(\mathcal{X})$  by

$$d'(A) = d(A) - S\phi(A) + \psi(A)T \quad (A \in \mathcal{B}(\mathcal{X})).$$

We recal that  $\phi(1) = 1$  and  $\delta(1) = 0$ . Now, the result is proved by four steps;

• At first, we define  $\delta'$  on  $\mathcal{B}(\mathcal{X})$  by

$$\delta'(B) = \delta(B) + \psi(B)T - T\phi(B) \quad (B \in \mathcal{B}(\mathcal{X})).$$

We show that  $\delta'$  is a  $(\phi, \psi)$ -derivation. Indeed,

$$\begin{split} \delta'(AB) &= \delta(AB) + \psi(AB)T - T\phi(AB) \\ &= \delta(A)\phi(B) + \psi(A)\delta(B) + \psi(A)\psi(B)T - T\phi(A)\phi(B) \\ &+ (\psi(A)T\phi(B) - \psi(A)T\phi(B)) \\ &= (\delta(A) + \psi(A)T - T\phi(A))\phi(B) + \psi(A)(\delta(B) - T\phi(B) + \psi(B)T) \\ &= \delta'(A)\phi(B) + \psi(A)\delta'(B). \end{split}$$

• Also we show that d' is a generalized  $(\phi, \psi)$ -derivation related to  $\delta'$ . Since

$$\begin{aligned} d'(AB) &= d(AB) - S\phi(AB) + \psi(AB)T \\ &= d(A)\phi(B) + \psi(A)\delta(B) - S\phi(A)\phi(B) + \psi(A)\psi(B)T \\ &+ (\psi(A)T\phi(B) - \psi(A)T\phi(B)) \\ &= (d(A) - S\phi(A) + \psi(A)T)\phi(B) + \psi(A)(\delta(B) + \psi(B)T - T\phi(B)) \\ &= d'(A)\phi(B) + \psi(A)\delta'(B). \end{aligned}$$

• Obviously,  $d' \mid_{\mathcal{F}_1(X)} \equiv 0$ . At this step we show  $\delta' \mid_{\mathcal{F}_1(X)} \equiv 0$ . For  $x \otimes f, y \otimes g \in \mathcal{F}_1(X)$  we have

$$0 = d'((x \otimes f)(y \otimes g)) = d'(x \otimes f)\phi(y \otimes g) + \psi(x \otimes f)\delta'(y \otimes g).$$

Since  $d'|_{\mathcal{F}_1(X)} \equiv 0$  and  $\psi$  is surjective on  $\mathcal{F}_1(X)$  so  $\delta'(y \otimes g) = 0$ .

• Finally, we show that  $d' \equiv 0$  on  $\mathcal{B}(\mathcal{X})$ . For each  $A \in \mathcal{B}(\mathcal{X})$  and  $x \otimes f \in \mathcal{F}_1(X)$  we have

$$0 = d'(A(x \otimes f)) = d'(A)\phi(x \otimes f) + \psi(A)\delta'(x \otimes f).$$

Since  $\delta' |_{\mathcal{F}_1(X)} \equiv 0$  and  $\phi$  is surjective on  $\mathcal{F}_1(X)$ , we obtain that d'(A) = 0. Hence we conclude that  $d(A) = S\phi(A) - \psi(A)T$ , for  $A \in \mathcal{B}(\mathcal{X})$ .  $\Box$ 

In the next theorem we show that a linear mapping on  $\mathcal{B}(\mathcal{X})$  which behave like a generalized  $(\phi, \psi)$ -derivation on pairs of elements with zero product is a generalized  $(\phi, \psi)$ -derivation. Also, we recal that it can be assumed  $\phi^{(1)} = 1$ and  $\delta^{(1)} = 0$ . Vol. 72 (2017) Continuity and Structure of Generalized  $(\phi, \psi)$ -Derivations 1819

**Theorem 4.** Let  $\mathcal{X}$  be a Banach algebra and let  $\phi, \psi : \mathcal{B}(\mathcal{X}) \longrightarrow \mathcal{B}(\mathcal{X})$  be homomorphisms such that  $\phi$  be surjective on  $\mathcal{F}_1(\mathcal{X})$ . If d is a linear mapping on  $\mathcal{B}(\mathcal{X})$  such that for every  $A, B \in \mathcal{B}(\mathcal{X})$  with AB = 0,  $d(AB) = d(A)\phi(B) + \psi(A)\delta(B)$  in which  $\delta$  is a  $(\phi, \psi)$ -derivation. Then d is a generalized  $(\phi, \psi)$ derivation related to  $\delta$ .

*Proof.* Let  $p \in \mathcal{B}(\mathcal{X})$  be an idempotent. For every  $A \in \mathcal{B}(\mathcal{X})$  we have Ap(I - p) = 0 = A(I - p)p. Since

$$d(Ap(I-p)) = d(Ap)\phi(I-p) + \psi(Ap)\delta(I-p)$$
  
=  $d(Ap) - d(Ap)\phi(p) - \psi(Ap)\delta(p)$ 

and

$$d(A(I-p)p) = d(A - Ap)\phi(p) + \psi(A - Ap)\delta(p)$$
  
=  $d(A)\phi(p) - d(Ap)\phi(p) + \psi(A)\delta(p) - \psi(Ap)\delta(p).$ 

By comparing these equalities we obtain that  $d(Ap) = d(A)\phi(p) + \psi(A)\delta(p)$  for  $A \in \mathcal{B}(\mathcal{X})$ . For  $x_0 \in \mathcal{X}$  and  $f \in \mathcal{X}^*$ , if  $f(x_0) = 1$  then  $x_0 \otimes f$  is an idempotent. Now we substitude p by  $x_0 \otimes f$ . So we have for all  $A \in \mathcal{B}(\mathcal{X})$ 

$$d(A(x_0 \otimes f)) = d(A)\phi(x_0 \otimes f) + \psi(A)\delta(x_0 \otimes f).$$
(3.1)

For each  $x \in \mathcal{X}$  and  $f \in \mathcal{X}^*$ , we choose  $\lambda \in \mathbb{C}$  such that  $\mu = f(\lambda x + x_0) \neq 0$ . Put  $y := \lambda x + x_0$ , so

$$\mu^{-1}\lambda d(A(x\otimes f)) + \mu^{-1}d(A(x_0\otimes f)) = d(A(\mu^{-1}y\otimes f))$$
  
=  $d(A)\phi(\mu^{-1}y\otimes f) + \psi(A)\delta(\mu^{-1}y\otimes f)$   
=  $d(A)\phi(\mu^{-1}\lambda x\otimes f) + d(A)\phi(\mu^{-1}x_0\otimes f)$   
+  $\psi(A)\delta(\mu^{-1}\lambda x\otimes f) + \psi(A)\delta(\mu^{-1}x_0\otimes f).$ 

These equalities together with 3.1 implies

$$d(A(x \otimes f)) = d(A)\phi(x \otimes f) + \psi(A)\delta(x \otimes f)$$

for all  $A \in \mathcal{B}(\mathcal{X})$ ,  $x \in \mathcal{X}$  and  $f \in \mathcal{X}^*$ . Replacing A by AB for  $A, B \in \mathcal{B}(\mathcal{X})$ , we get

$$d(AB(x \otimes f)) = d(AB)\phi(x \otimes f) + \psi(AB)\delta(x \otimes f).$$
(3.2)

On the other hand

$$d(A(Bx \otimes f)) = d(A)\phi(Bx \otimes f) + \psi(A)\delta(Bx \otimes f)$$
  
=  $d(A)\phi(B)\phi(x \otimes f) + \psi(A)\delta(B)\phi(x \otimes f) + \psi(A)\psi(B)\delta(x \otimes f).$ 

Comparing Eq. 3.2 and the last equation, we conclude

$$(d(AB) - d(A)\phi(B) - \psi(A)\delta(B))\phi(x \otimes f) = 0.$$

Hence by surjectivity of  $\phi$  on  $\mathcal{F}_1(\mathcal{X})$ , for each  $y \in \mathcal{X}$  we have

$$(d(AB) - d(A)\phi(B) - \psi(A)\delta(B))y \otimes g$$
  
=  $(d(AB) - d(A)\phi(B) - \psi(A)\delta(B))\phi(x \otimes f) = 0.$ 

Therefore d is a generalized  $(\phi, \psi)$ -derivation related to  $\delta$ .

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