



On Maxwell's Equations on Globally Hyperbolic Spacetimes with Timelike Boundary

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Abstract. We study Maxwell's equation as a theory for smooth k -forms on globally hyperbolic spacetimes with timelike boundary as defined by Aké et al. (Structure of globally hyperbolic spacetimes with timelike boundary. [arXiv:1808.04412](https://arxiv.org/abs/1808.04412) [gr-qc]). In particular, we start by investigating on these backgrounds the D'Alembert–de Rham wave operator \square_k and we highlight the boundary conditions which yield a Green's formula for \square_k . Subsequently, we characterize the space of solutions of the associated initial and boundary value problems under the assumption that advanced and retarded Green operators do exist. This hypothesis is proven to be verified by a large class of boundary conditions using the method of boundary triples and under the additional assumption that the underlying spacetime is ultrastatic. Subsequently we focus on the Maxwell operator. First we construct the boundary conditions which entail a Green's formula for such operator and then we highlight two distinguished cases, dubbed δd -tangential and δd -normal boundary conditions. Associated to these, we introduce two different notions of gauge equivalence and we prove that in both cases, every equivalence class admits a representative abiding to the Lorenz gauge. We use this property and the analysis of the operator \square_k to construct and to classify the space of gauge equivalence classes of solutions of the Maxwell's equations with the prescribed boundary conditions. As a last step and in the spirit of future applications in the framework of algebraic quantum field theory, we construct the associated unital $*$ -algebras of observables proving in particular that, as in the case of the Maxwell operator on globally hyperbolic spacetimes with empty boundary, they possess a non-trivial center.

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1. Introduction

Electromagnetism and the associated Maxwell's equations, written both in terms of the Faraday tensor or of the vector potential, represent one of the most studied models in mathematical physics. On the one hand, they are of indisputable practical relevance, while, on the other hand, they are the prototypical example of a gauge theory, which can be still thoroughly and explicitly investigated thanks to the Abelian nature of the underlying gauge group.

On curved backgrounds, the study of this model has attracted a lot of attention not only from the classical viewpoint but also in relation to its quantization. Starting from the early work of Dimock [18], the investigation of Maxwell's equations, generally seen as a theory for differential forms, has been thorough especially in the framework of algebraic quantum field, e.g., [20, 34]. One of the key reasons for such interest is related to the fact that electromagnetism has turned out to be one of the simplest examples where the principle of general local covariance, introduced in [11], does not hold true on account of topological obstructions—see for example [5, 7, 15, 35].

A closer look at all these references and more generally to the algebraic approach unveils that most of the analyses rest on two key data: the choice of a gauge group and of an underlying globally hyperbolic background of arbitrary dimension. While the first one is related to the interpretation of electromagnetism as a theory for the connections of a principal $U(1)$ -bundle, the second one plays a key rôle in the characterization of the space of classical solutions of Maxwell's equations and in the associated construction of a unital $*$ -algebra of observables. More precisely, every solution of Maxwell's equations identifies via the action of the gauge group an equivalence class of differential forms. Each of these classes admits a representative, namely a coclosed form which solves a normally hyperbolic partial differential equation, ruled by the D'Alembert–de Rham operator. Such representative is not unique due to a residual gauge freedom. Most notably, since the underlying spacetime is globally hyperbolic, one can rely on classical results, see for example [9], to infer that the D'Alembert–de Rham operator admits unique advanced and retarded fundamental solutions. Not only these can be used to characterize the kernel of such operator, but they also allow both to translate the requirement of considering only coclosed form as a constraint on the admissible initial data and to give an explicit representation for the space of the gauge equivalence classes of solutions of Maxwell's equations. At a quantum level, instead, the fundamental solutions represent the building block to implement the canonical commutation relations within the $*$ -algebra of observables, *cf.* [18].

Completely different is the situation when we drop the assumption of the underlying background being globally hyperbolic since especially the existence and uniqueness results for the fundamental solutions are no longer valid. In this paper, we will be working in this framework, assuming in particular that the underlying manifold (M, g) is globally hyperbolic and it possesses a time-like boundary, in the sense of [1], where this concept has been formalized. In

other words, to (M, g) one can associate $(\partial M, \iota_M^* g)$, where $\iota_M : \partial M \hookrightarrow M$, is a Lorentzian smooth submanifold. This class of spacetimes contains several notable examples, such as anti-de Sitter (AdS) or asymptotically AdS spacetimes. These play a key rôle in several models that have recently attracted a lot of attention especially for the study of the properties of Green-hyperbolic operators—like the wave, the Klein-Gordon or the Dirac operator—, see for example [2, 22, 27, 37, 38]. From a classical point of view, in order to construct the solutions for any of these equations, initial data assigned on a Cauchy surface are no longer sufficient and it is necessary to supplement them with the choice of a boundary condition. This particular feature prompts the question whether these systems still admit fundamental solutions and, if so, whether they are unique and whether they share the same structural properties of their counterparts in a globally hyperbolic spacetime with empty boundary.

For the wave operator acting on real scalar functions, a complete answer to this question has been given in [12] for static globally hyperbolic spacetimes with a timelike boundary combining spectral calculus with boundary triples, introduced by Grubb in [24].

In this work, we will be concerned instead with the study of Maxwell's equations acting on generic k -forms, with $0 \leq k < m = \dim M$, see [26] for an analysis in terms of the Faraday tensor on an anti-de Sitter spacetime. In comparison with the scalar scenario, the situation is rather different. First of all the dynamics is ruled by the operator $\delta_{k+1} d_k$ where d_k is the differential acting on $\Omega^k(M)$, the space of smooth k -forms while δ_{k+1} is the codifferential acting on $(k+1)$ -forms. To start with, one can observe that this operator is not formally self-adjoint and thus boundary conditions must be imposed. The admissible ones are established by a direct inspection of the Green's formula for the Maxwell-operator. In between the plethora of all possibilities, we highlight two distinguished choices, dubbed δd -tangential and δd -normal boundary conditions which, in the case $k=0$, reduce to the more common Dirichlet and Neumann boundary conditions.

As second step, we recognize that a notion of gauge group has to be introduced. While a more geometric approach based on interpreting Maxwell's equations in terms of connections on a principal $U(1)$ -bundle might be the most desirable approach, we decided to investigate this viewpoint in a future work. We focus instead only on Maxwell's equations as encoding the dynamics of a theory for differential k -forms. If the underlying manifold (M, g) would have no boundary, the gauge group would be chosen as $d\Omega^{k-1}(M)$. While at first glance one might wish to keep the same choice, it is immediate to realize that this is possible only for the δd -normal boundary condition which is insensitive to any shift of a form by an element of the gauge group. On the contrary, in the other cases, one needs to reduce the admissible gauge transformations so to ensure compatibility with the boundary conditions.

The next step in our analysis mimics the counterpart when the underlying globally hyperbolic spacetime (M, g) has empty boundary, namely we construct the space of gauge equivalence classes of solutions for Maxwell's equations and we prove that each class admits a non-unique representative

which is a coclosed k -form ω , such that $\square_k \omega = 0$. Using a standard nomenclature, we say that we consider a Lorenz gauge fixing. Here $\square_k = d_{k-1} \delta_k + \delta_{k+1} d_k$ is the D'Alembert–de Rham wave operator which is known to be normally hyperbolic, see e.g., [34]. On the one hand, we observe that the mentioned non-uniqueness is related to a residual gauge freedom which can be fully accounted for. On the other hand, we have reduced the characterization of the equivalence classes of solutions of Maxwell's equations to studying the D'Alembert–de Rham wave operator.

This can be analyzed similarly to the wave operator acting on scalar functions as one could imagine since the two operators coincide for $k = 0$. Therefore we study \square_k independently, first identifying via a Green's formula a collection of admissible boundary conditions. Subsequently, under the assumption that advanced and retarded Green's operators exist, we characterize completely the space of solutions of the equation $\square_k \omega = 0$, $\omega \in \Omega^k(M)$ with prescribed boundary condition. At this stage, we highlight the main technical obstruction which forces us to consider only two distinguished boundary conditions for the Maxwell operator. As a matter of facts, we show that, although at an algebraic level it holds always $\delta_k \circ \square_k = \square_{k-1} \circ \delta_k$, the counterpart at the level of fundamental solutions is verified only for specific choices of the boundary condition. This leads to an obstruction in translating the Lorenz gauge condition of working only with coclosed k -form to a constraint in the admissible initial data. This failure does not imply that the Lorenz gauge is ill-defined, but only that, for a large class of boundary conditions, one needs to envisage a strategy different from the one used on globally hyperbolic spacetimes with empty boundary in order to study the underlying problem.

It is important to mention that it is beyond our current knowledge verifying whether our assumption on the existence of fundamental solutions is always true. We expect that a rather promising avenue consists of adapting to the case in hand the techniques and the ideas discussed in [17] and in [21], but this is certainly a challenging task, which we leave for future work. On the contrary, we test our assumption in the special case of ultrastatic, globally hyperbolic spacetimes with timelike boundary. In this scenario, we adopt the techniques used in [12] proving that advanced and retarded fundamental solutions do exist for a large class of boundary conditions, including all those of interest for our analysis.

Finally, we give an application of our result inspired by the quantization of Maxwell's equations in the algebraic approach to quantum field theory. While this framework has been extremely successful on a generic globally hyperbolic spacetime with empty boundary, only recently the case with a timelike boundary has been considered, see e.g., [6, 13, 19, 32, 40]. In particular, we focus on the construction of a unital $*$ -algebra of observables for Maxwell's equations both with δd -tangential and δd -normal boundary condition and we prove that in both cases one can always find a non-trivial Abelian ideal. This is the signature that, also in presence of a timelike boundary, one cannot expect that the principle of general local covariance holds true in its original form.

To conclude, we emphasize that, from a physical viewpoint our analysis has two key goals. The first, more evident, is to discuss a rigorous quantization scheme for Maxwell equations in presence of a class of boundaries which are expected to play a rôle in many applications. A rather natural example is the Casimir effect for photons, which can be modeled as a free electromagnetic field confined between two perfectly isolating and infinitely extended parallel plates in Minkowski spacetime. The second instead consists of highlighting the necessity in presence of boundaries of revising the structure of the underlying gauge group, which changes according to the boundary conditions chosen. In the prospect of analyzing in future works interacting models, this has far-reaching consequences.

The paper is organized as follows: In Sect. 2, we introduce the notion of globally hyperbolic spacetime with timelike boundary as well as all the relevant space of differential k -forms. In addition we recall the basic definitions of differential and codifferential operator, and we introduce two distinguished maps between bulk and boundary forms. Section 3 contains the core of this paper. For clarity purposes, we start in Sect. 3.1 from the analysis of the D'Alembert–de Rham wave operator \square_k . To begin with, we study a class of boundary conditions which implement the Green's formula, hence making \square_k a formally self-adjoint operator. Subsequently, we assume that, for a given boundary condition, advanced and retarded Green's operators exist and we codify the information of the space of classical solutions of the underlying dynamics in terms of a short exact sequence, similar to the standard one when the underlying globally hyperbolic spacetime has no boundary, *cf.* [9]. In addition, we discuss the interplay between the fundamental solutions and the differential/codifferential operator. In Sect. 3.2, we focus instead on Maxwell's equations. First we investigate which boundary conditions can be imposed so that the operator ruling the dynamics is formally self-adjoint. Subsequently, we introduce the δd -tangential and the δd -normal boundary conditions together with an associated gauge group. Using these data, we prove that the equivalence classes of solutions of Maxwell's equations always admit a representative in the Lorenz gauge, which obeys an equation of motion ruled by \square_k . Such solution is non-unique in the sense that a residual gauge freedom exists. Nonetheless, using the fundamental solutions of the D'Alembert–de Rham wave operator, we are able to characterize the above equivalence classes in terms of suitable initial data. To conclude, in Sect. 3.3 we use the results from the previous parts to construct a unital $*$ -algebra of observables associated to Maxwell's equations with δd -tangential and δd -normal boundary conditions. In particular, we prove that in all cases there exists an Abelian $*$ -ideal. In “Appendix A,” we prove that our assumption on the existence of fundamental solutions is verified whenever the underlying spacetime is ultrastatic. Finally, in “Appendix B” it is proven an explicit decomposition for k -forms on globally hyperbolic spacetimes, which plays a key rôle in some proofs in the main body of the paper. In “Appendix C,” we recall the basic notion of relative cohomology for manifolds with boundaries as well as the associated Poincaré–Lefschetz duality.

2. Geometric Data

In this subsection, our goal is to fix notations and conventions, as well as to summarize the main geometric data, which play a key rôle in our analysis. Following the standard definition, see for example [30, Ch. 1], M indicates a smooth, second-countable, connected, oriented manifold of dimension $m \geq 2$, with smooth boundary ∂M , assumed for simplicity to be connected. We assume also that M admits a finite good cover. A point $p \in M$ such that there exists an open neighborhood U containing p , diffeomorphic to an open subset of \mathbb{R}^m , is called an *interior point* and the collection of these points is indicated with $\text{Int}(M) \equiv \overset{\circ}{M}$. As a consequence, $\partial M \doteq M \setminus \overset{\circ}{M}$, if non-empty, can be read as an embedded submanifold $(\partial M, \iota_{\partial M})$ of dimension $m - 1$ with $\iota_{\partial M} \in C^\infty(\partial M; M)$.

In addition we endow M with a smooth Lorentzian metric g of signature $(-, +, \dots, +)$ and consider only those cases in which $\iota_{\partial M}^* g$ identifies a Lorentzian metric on ∂M and (M, g) is time oriented. As a consequence, $(\partial M, \iota_{\partial M}^* g)$ acquires the induced time orientation and we say that (M, g) has a *timelike boundary*.

Since we will be interested particularly in the construction of advanced and retarded fundamental solutions for normally hyperbolic operators, we focus our attention on a specific class of Lorentzian manifolds with timelike boundary, namely those which are globally hyperbolic. While, in the case of $\partial M = \emptyset$ this is a standard concept, in presence of a timelike boundary it has been properly defined and studied recently in [1]. Summarizing part of their constructions and results, we say that a time-oriented, Lorentzian manifold with timelike boundary (M, g) is *causal* if it possesses no closed, causal curve, while it is *globally hyperbolic* if it is causal and, for all $p, q \in M$, $J^+(p) \cap J^-(q)$ is either empty or compact. Here J^\pm denote the causal future and past, cf. [9, Sec. 1.3]. These conditions entail the following consequences, see [1, Th. 1.1 & 3.14]:

Theorem 1. *Let (M, g) be a time-oriented Lorentzian manifold with timelike boundary of dimension $\dim M = m \geq 2$. Then the following conditions are equivalent:*

1. (M, g) is globally hyperbolic ;
2. (M, g) possesses a Cauchy surface, namely an achronal subset of M which is intersected only once by every inextendible timelike curve ;
3. (M, g) is isometric to $\mathbb{R} \times \Sigma$ endowed with the line-element

$$ds^2 = -\beta d\tau^2 + h_\tau, \tag{1}$$

where $\tau : M \rightarrow \mathbb{R}$ is a Cauchy temporal function,¹ whose gradient is tangent to ∂M , $\beta \in C^\infty(\mathbb{R} \times \Sigma; (0, \infty))$ while $\mathbb{R} \ni \tau \rightarrow (\{\tau\} \times \Sigma, h_\tau)$

¹Given a generic time oriented Lorentzian manifold (N, \tilde{g}) a Cauchy temporal function is a map $\tau : M \rightarrow \mathbb{R}$ such that its gradient is timelike and past-directed, while its level surfaces are Cauchy hypersurfaces.

identifies a one-parameter family of $(m - 1)$ -dimensional spacelike, Riemannian manifolds with boundaries. Each $\{\tau\} \times \Sigma$ is a Cauchy surface for (M, g) .

Henceforth we will be tacitly assuming that, when referring to a globally hyperbolic spacetime with timelike boundary (M, g) , we work directly with (1) and we shall refer to τ as the time coordinate. Furthermore each Cauchy surface $\Sigma_\tau \doteq \{\tau\} \times \Sigma$ acquires an orientation induced from that of M . In addition, we shall say that (M, g) is *static* if it possesses an irrotational timelike Killing vector field $\chi \in \Gamma(TM)$ whose restriction to ∂M is tangent to the boundary, i.e., $g_p(\chi, \nu) = 0$ for all $p \in \partial M$ where ν is the outward pointing, unit vector, normal to the boundary at p . With reference to (1) and for simplicity, we identify χ with ∂_τ . Thus the condition of being static translates into the constraint that both β and h_τ are independent from τ . If in addition $\beta = 1$ we call (M, g) *ultrastatic*.

On a Lorentzian spacetime (M, g) with timelike boundary, we consider $\Omega^k(M)$, $0 \leq k \leq \dim M$, the space of real valued smooth k -forms. A particular rôle will be played by the support of the forms that we consider. In the following definition, we introduce the different possibilities that we will consider, which are a generalization of the counterpart used for scalar fields which corresponds in our scenario to $k = 0$, cf. [3].

Definition 2. Let (M, g) be a Lorentzian spacetime with timelike boundary. We denote with

1. $\Omega_c^k(M)$ the space of smooth k -forms with compact support in M while we denote with $\Omega_c^k(\overset{\circ}{M}) \subset \Omega_c^k(M)$ the collection of smooth and compactly supported k -forms ω such that $\text{supp}(\omega) \cap \partial M = \emptyset$.
2. $\Omega_{\text{spc}}^k(M)$ (*resp.* $\Omega_{\text{sfc}}^k(M)$) the space of strictly past compact (*resp.* strictly future compact) k -forms, that is the collection of $\omega \in \Omega^k(M)$ such that there exists a compact set $K \subseteq M$ for which $J^+(\text{supp}(\omega)) \subseteq J^+(K)$ (*resp.* $J^-(\text{supp}(\omega)) \subseteq J^-(K)$), where J^\pm denotes the causal future and the causal past in M . Notice that $\Omega_{\text{sfc}}^k(M) \cap \Omega_{\text{spc}}^k(M) = \Omega_c^k(M)$.
3. $\Omega_{\text{pc}}^k(M)$ (*resp.* $\Omega_{\text{fc}}^k(M)$) the space of past compact (*resp.* future compact) k -forms, that is, $\omega \in \Omega^k(M)$ for which $\text{supp}(\omega) \cap J^-(K)$ (*resp.* $\text{supp}(\omega) \cap J^+(K)$) is compact for all compact $K \subset M$.
4. $\Omega_{\text{tc}}^k(M) \doteq \Omega_{\text{fc}}^k(M) \cap \Omega_{\text{pc}}^k(M)$, the space of timelike compact k -forms.
5. $\Omega_{\text{sc}}^k(M) \doteq \Omega_{\text{sfc}}^k(M) \cup \Omega_{\text{spc}}^k(M)$, the space of spacelike compact k -forms.

We indicate with $d_k: \Omega^k(M) \rightarrow \Omega^{k+1}(M)$ the exterior derivative and, being (M, g) oriented, we can identify a unique, metric-induced, Hodge operator $\star_k: \Omega^k(M) \rightarrow \Omega^{m-k}(M)$, $m = \dim M$ such that, for all $\alpha, \beta \in \Omega^k(M)$, $\alpha \wedge \star_k \beta = (\alpha, \beta)_{k,g} \mu_g$, where \wedge is the exterior product of forms, μ_g the metric induced volume form, while $(,)_{k,g}$ is the pairing between k -forms induced by the metric g . In addition one can define a pairing between k -forms as

$$(\alpha, \beta)_k \doteq \int \alpha \wedge \star_k \beta, \tag{2}$$

where $\alpha, \beta \in \Omega^k(M)$ are such that $\text{supp}(\alpha) \cap \text{supp}(\beta)$ is compact. Since M is endowed with a Lorentzian metric, it holds that, when acting on smooth k -forms, $\star_k^{-1} = (-1)^{k(m-k)-1} \star_{m-k}$. Combining these data first we define the *codifferential* operator $\delta_k : \Omega^{k+1}(M) \rightarrow \Omega^k(M)$ as $\delta_k \doteq (-1)^k \star_{k-1}^{-1} \circ d_{m-k} \circ \star_k$. Secondly we introduce the *D'Alembert-de Rham* wave operator $\square_k : \Omega^k(M) \rightarrow \Omega^k(M)$ such that $\square_k \doteq d_{k-1} \delta_k + \delta_{k+1} d_k$, as well as the *Maxwell* operator $\delta_{k+1} d_k : \Omega^k(M) \rightarrow \Omega^k(M)$. Observe, furthermore, that \square_k differs from the D'Alembert wave operator $g^{ab} \nabla_a \nabla_b$ acting on k -forms by 0-order term built out of the metric and whose explicit form depends from the value of k , see for example [34, Sec. II].

Remark 3. For notational convenience, in the following we shall drop all subscripts k since the relevant value will be clear case by case from the context. Hence, unless stated otherwise, all statements of this paper apply to all k such that $0 \leq k \leq m = \dim M$.

To conclude the section, we focus on the boundary ∂M and on the interplay with k -forms lying in $\Omega^k(M)$. The first step consists of defining two notable maps. These relate k -forms defined on the whole M with suitable counterparts living on ∂M and, in the special case of $k = 1$, they boil down to the restriction to the boundary either of the tangent component of a 1-form or of its component conormal to ∂M . For later convenience, we consider in the following definition a slightly more general scenario, namely a codimension 1 smoothly embedded submanifold $N \hookrightarrow M$.

Remark 4. Since we feel that some confusion might arise, we denote the pairing between forms on ∂M with $(\ , \)_\partial$.

Definition 5. Let (M, g_M) be a smooth Lorentzian manifold and let $\iota_N : N \rightarrow M$ be a codimension 1 smoothly embedded submanifold of M with induced metric $g_N := \iota_N^* g_M$. We define the *tangential* and *normal* components relative to N as

$$t_N : \Omega^k(M) \rightarrow \Omega^k(N), \quad \omega \mapsto t_N \omega := \iota_N^* \omega, \tag{3a}$$

$$n_N : \Omega^k(M) \rightarrow \Omega^{k-1}(N), \quad \omega \mapsto n_N \omega := \star_N^{-1} t_N \star_M \omega, \tag{3b}$$

where \star_M, \star_N denote the Hodge dual over M, N respectively. In particular, for all $k \in \mathbb{N} \cup \{0\}$ we define

$$\Omega_{t_N}^k(M) \doteq \{\omega \in \Omega^k(M) \mid t_N \omega = 0\}, \quad \Omega_{n_N}^k(M) \doteq \{\omega \in \Omega^k(M) \mid n_N \omega = 0\}. \tag{4}$$

Similarly we will use the symbols $\Omega_{c, t_N}^k(M)$ and $\Omega_{c, n_N}^k(M)$ when we consider only smooth, compactly supported k -forms.

Remark 6. In this paper, the rôle of N will be played often by ∂M . In this case, we shall drop the subscript from Eq. (3), namely $t \equiv t_{\partial M}$ and $n \equiv n_{\partial M}$. Furthermore, the differential and the codifferential operators on ∂M will be denoted, respectively, as $d_\partial, \delta_\partial$.

As last step, we observe that (3) together with (4) entail the following series of identities on $\Omega^k(M)$ for all $k \in \mathbb{N} \cup \{0\}$.

$$\star \delta = (-1)^k d\star, \quad \delta\star = (-1)^{k+1} \star d, \tag{5a}$$

$$\star_{\partial} n = t\star, \quad \star_{\partial} t = (-1)^{(m-k)} n\star, \quad d_{\partial} t = td, \quad \delta_{\partial} n = -n\delta. \tag{5b}$$

A notable consequence of (5b) is that, while on globally hyperbolic spacetimes with empty boundary, the operators d and δ are formal adjoints of each other, in the case in hand, the situation is different. A direct application of Stokes' theorem yields that

$$(d\alpha, \beta) - (\alpha, \delta\beta) = (t\alpha, n\beta)_{\partial}, \tag{6}$$

where the pairing in the right-hand side is the one associated to forms living on ∂M and where $\alpha \in \Omega^k(M)$ and $\beta \in \Omega^{k+1}(M)$ are arbitrary, though such that $\text{supp}(\alpha) \cap \text{supp}(\beta)$ is compact. In connection to the operators d and δ , we shall employ the notation

$$\Omega_{\sharp}^k(M) = \{\omega \in \Omega^k(M) \mid d\omega = 0\}, \quad \Omega_{\delta}^k(M) = \{\omega \in \Omega^k(M) \mid \delta\omega = 0\}, \tag{7}$$

where $k \in \mathbb{N}$. Similarly we shall indicate with $\Omega_{\sharp, \delta}^k(M) \doteq \Omega_{\sharp}^k(M) \cap \Omega_{\delta}^k(M)$ and $\Omega_{\sharp, d}^k(M) \doteq \Omega_{\sharp}^k(M) \cap \Omega_d^k(M)$ where $\sharp \in \{c, sc, pc, fc, tc\}$.

Remark 7. With reference to Definition 5, observe that the following linear map is surjective:

$$\begin{aligned} \Omega^k(M) \ni \omega &\mapsto (n\omega, t\omega, t\delta\omega, nd\omega) \\ &\in \Omega^{k-1}(\partial M) \times \Omega^k(\partial M) \times \Omega^{k-1}(\partial M) \times \Omega^k(\partial M). \end{aligned}$$

The proof of this claim is based on a local computation similar to the one in the proof of Lemma 50. For all relatively compact open subset $U_{\partial M} \subset \partial M$, we consider a open neighborhood $U \subseteq M$ of the form $U = [0, \epsilon) \times U_{\partial M}$ built out the exponential map \exp_M . In addition, we can fine tune U in such a way, that calling x , the coordinate built via \exp_M out of the outward pointing, normal vector field at each point $p \in U$, the smooth function $N = g(\partial_x, \partial_x)$ is strictly positive. Let $U_x \doteq \{x\} \times U_{\partial M}$ for $x \in [0, \epsilon)$ and let t_{U_x}, n_{U_x} be the corresponding tangential and normal maps—cf. Definition 5. Therefore, we can split $\omega \in \Omega^k(M)$ as

$$\omega|_{U_x} = t_{U_x}\omega + n_{U_x}\omega \wedge N^{\frac{1}{2}}dx.$$

It descends from Definition 5 that

$$t\omega|_{U_{\partial M}} = t_{U_x}\omega|_{x=0}, \quad n\omega|_{U_{\partial M}} = n_{U_x}\omega|_{x=0}.$$

Applying the differential d to the local splitting of ω yields

$$nd\omega|_{U_{\partial M}} = N^{-\frac{1}{2}}\partial_x t_{U_x}\omega|_{x=0} + N^{-\frac{1}{2}}d_{\partial U}(N^{\frac{1}{2}}n_{U_x}\omega)|_{x=0}.$$

Moreover, the Hodge dual $\star_U \omega$ can be computed as

$$\star_U \omega|_{U_x} = \star_{U_x} n_{U_x}\omega + \star_{U_x} t_{U_x}\omega \wedge N^{\frac{1}{2}}dx,$$

where $\star_{U_x} : \Omega^\bullet(U_x) \rightarrow \Omega^{m-1-\bullet}(U_x)$ denotes the Hodge dual on U_x . Taking into account equations (5), we find

$$\begin{aligned} t\delta\omega|_{U_{\partial M}} &= (-1)^{(k+1)(m-k)-1} \star_{\partial U} \text{nd} \star_U \omega|_{U_{\partial M}} \\ &= (-1)^{(k+1)(m-k)-1} \star_{\partial U} \\ &\quad \left[N^{-\frac{1}{2}} \partial_x \star_{U_x} \text{n}_{U_x} \omega|_{x=0} + N^{-\frac{1}{2}} \text{d}_{\partial U} (N^{\frac{1}{2}} \star_{U_x} \text{t}_{U_x} \omega)|_{x=0} \right]. \end{aligned}$$

The claim follows from the fact that $\text{t}_{U_x} \omega|_{x=0}$, $\text{n}_{U_x} \omega|_{x=0}$, $\partial_x \text{t}_{U_x} \omega|_{x=0}$ and $\partial_x \text{n}_{U_x} \omega|_{x=0}$ are functionally independent.

Remark 8. The normal map $\text{n} : \Omega^k(M) \rightarrow \Omega^{k-1}(\partial M)$ can be equivalently read as $\nu \lrcorner \omega$, the contraction on ∂M between $\omega \in \Omega^k(M)$ and the vector field $\nu \in \Gamma(TM)|_{\partial M}$ which corresponds at each point $p \in \partial M$ to the outward pointing unit vector, normal to ∂M .

3. Maxwell’s Equations and Boundary Conditions

In this section, we analyze the space of solutions of Maxwell’s equations for arbitrary k -forms on a globally hyperbolic spacetime with timelike boundary (M, g) . We proceed in two separate steps. First we focus our attention on the D’Alembert–de Rham wave operator $\square = \delta \text{d} + \text{d} \delta$ acting on $\Omega^k(M)$. We identify a class of boundary conditions which correspond to imposing that the underlying system is closed (i.e., the symplectic flux across ∂M vanishes), and we characterize the kernel of the operator in terms of its advanced and retarded fundamental solutions. These are assumed to exist and, following the same strategy employed in [12] for the scalar wave equation, we prove that this is indeed the case whenever (M, g) is an ultrastatic spacetime, cf. “Appendix A”.

In the second part of the section, we focus instead on the Maxwell operator $\delta \text{d} : \Omega^k(M) \rightarrow \Omega^k(M)$. In order to characterize its kernel, we will need to discuss the interplay between the choice of boundary condition and that of gauge fixing. This represents the core of this part of our work.

3.1. On the D’Alembert–de Rham Wave Operator

Consider the operator $\square : \Omega^k(M) \rightarrow \Omega^k(M)$, where (M, g) is a globally hyperbolic spacetime with timelike boundary of dimension $\dim M = m \geq 2$. Then, for any pair $\alpha, \beta \in \Omega^k(M)$ such that $\text{supp}(\alpha) \cap \text{supp}(\beta)$ is compact, the following Green’s formula holds true:

$$(\square\alpha, \beta) - (\alpha, \square\beta) = (t\delta\alpha, \text{n}\beta)_\partial - (\text{n}\alpha, t\delta\beta)_\partial - (\text{nd}\alpha, \text{t}\beta)_\partial + (\text{t}\alpha, \text{nd}\beta)_\partial, \quad (8)$$

where t, n are the maps introduced in Definition 5, while $(,)$ and $(,)_\partial$ are the standard, metric induced pairing between k -forms, respectively, on M and on ∂M . In view of Definition 5, it descends that the right-hand side of (8) vanishes automatically if we restrict our attention to $\alpha \in \Omega_c^k(\overset{\circ}{M})$ or $\beta \in \Omega_c^k(\overset{\circ}{M})$, but boundary conditions must be imposed for the same property to hold true on a larger set of k -forms. From a physical viewpoint, this requirement is

tantamount to imposing that the system described by k -forms obeying the D’Alembert–de Rham wave equation is closed.

Lemma 9. *Let $f, f' \in C^\infty(\partial M)$ and let*

$$\Omega_{f,f'}^k(M) \doteq \{\omega \in \Omega^k(M) \mid n\omega = ft\omega, t\delta\omega = f'n\omega\}. \tag{9}$$

Then, $\forall \alpha, \beta \in \Omega_{f,f'}^k(M), 0 \leq k \leq m = \dim M$ such that $\text{supp}(\alpha) \cap \text{supp}(\beta)$ is compact, it holds

$$(\square\alpha, \beta) - (\alpha, \square\beta) = 0.$$

Proof. This is a direct consequence of (8) together with the property that, for every $f \in C^\infty(\partial M)$ and for every $\alpha \in \Omega^k(\partial M), \star_\partial(f\alpha) = f(\star_\partial\alpha)$. In addition observe that the assumption on the support of α and β descends also to the forms present in each of the pairing in the right hand side of (8). \square

Remark 10. In Lemma 9 two cases are quite peculiar. As a matter of fact, if $k = m = \dim M$ the first condition becomes empty since $d\omega = t\omega = 0$ for all $\omega \in \Omega^m(M)$. Similarly, if $k = 0$, the second condition does not bring any constraint since $\delta\omega = n\omega = 0$ for all $\omega \in \Omega^0(M)$. In this case, Eq. (9) reduces to Robin boundary conditions, which were studied in [12].

Remark 11. It is important to stress that the boundary conditions defined in Lemma 9 are not the largest class which makes the right hand side (8) vanish. As a matter of fact, one can think of additional possibilities similar to the so-called Wentzell boundary conditions, which were considered in the scalar scenario, see e.g., [12, 14, 40].

Lemma (9) individuates therefore a class of boundary conditions which makes the operator \square formally self-adjoint. In between all these possibilities, we highlight those which are of particular interest to our analysis—*cf.* Theorem 16.

Definition 12. Let (M, g) be a globally hyperbolic spacetime with timelike boundary and let $f \in C^\infty(\partial M)$. We call

1. space of k -forms with *Dirichlet* boundary condition

$$\Omega_D^k(M) \doteq \{\omega \in \Omega^k(M) \mid t\omega = 0, n\omega = 0\}, \tag{10}$$

2. space of k -forms with \square -*tangential* boundary condition

$$\Omega_{\parallel}^k(M) \doteq \{\omega \in \Omega^k(M) \mid t\omega = 0, t\delta\omega = 0\}, \tag{11}$$

3. space of k -forms with \square -*normal* boundary condition

$$\Omega_{\perp}^k(M) \doteq \{\omega \in \Omega^k(M) \mid n\omega = 0, n\delta\omega = 0\}. \tag{12}$$

4. space of k -forms with *Robin* \square -*tangential* boundary condition

$$\Omega_{f\parallel}^k(M) \doteq \{\omega \in \Omega^k(M) \mid t\delta\omega = fn\omega, t\omega = 0\}, \tag{13}$$

5. space of k -forms with *Robin* \square -*normal* boundary condition

$$\Omega_{f\perp}^k(M) \doteq \{\omega \in \Omega^k(M) \mid n\delta\omega = ft\omega, n\omega = 0\}, \tag{14}$$

Whenever the domain of the operator \square is restricted to one of these spaces, we shall indicate it with symbol \square_{\sharp} where $\sharp \in \{D, \parallel, \perp, f_{\parallel}, f_{\perp}\}$.

Remark 13. Since per definition $\delta\Omega^0(M) = \{0\} = n\Omega^0(M)$, we observe that $\Omega_D^0(M) = \Omega_{\parallel}^0(M)$. In particular we have

$$\begin{aligned} \Omega_D^0(M) &\doteq \{\omega \in C^\infty(M) \mid t\omega = \omega|_{\partial M} = 0\}, \\ \Omega_{\perp}^0(M) &\doteq \{\omega \in C^\infty(M) \mid n d\omega = \nu(d\omega)|_{\partial M} = 0\}, \end{aligned}$$

where, for all $p \in \partial M$, ν_p coincides with the outward pointing unit vector, normal to the boundary. These two options coincide with the standard Dirichlet and Neumann boundary conditions for scalar functions. Moreover for $f = 0$ we have $\Omega_{f_{\parallel}}^k(M) = \Omega_{\parallel}^k(M)$ as well as $\Omega_{f_{\perp}}^k(M) = \Omega_{\perp}^k(M)$.

Finally, it is worth mentioning that, for a static spacetime (M, g) , the boundary conditions 1–3, introduced in Definition 12, are themselves static, that is they do not depend explicitly on the time coordinate τ . A similar statement holds true for f_{\perp}, f_{\parallel} boundary conditions provided that $f \in C^\infty(\partial M)$ and $\partial_\tau f = 0$. This will play a key rôle when we will verify that Assumption 16 is valid on ultrastatic spacetimes—*cf.* Proposition 48 in “Appendix A”.

Remark 14. It is interesting to observe that different boundary conditions can be related via the action of the Hodge operator. In particular, using Eqs. (5) and (9), one can infer that, for any $f, f' \in C^\infty(\partial M)$ it holds that

$$\star\Omega_{f, f'}^k(M) = \Omega_{-f', -f}^{m-k}(M).$$

At the same time, with reference, to the space of k -forms in Definition 12 it holds

$$\star\Omega_D^k(M) = \Omega_D^{m-k}(M), \quad \star\Omega_{\parallel}^k(M) = \Omega_{\perp}^{m-k}(M), \quad \star\Omega_{f_{\parallel}}^k(M) = \Omega_{-f_{\perp}}^{m-k}(M). \tag{15}$$

For later convenience, we prove the following lemma.

Lemma 15. *Let $\sharp \in \{D, \parallel, \perp, f_{\parallel}, f_{\perp}\}$, with $f \in C^\infty(\partial M)$. The following statements hold true:*

1. *for all $\omega \in \Omega_{sc}^k(M) \cap \Omega_{\sharp}^k(M)$ there exists $\omega^+ \in \Omega_{spc}^k(M) \cap \Omega_{\sharp}^k(M)$ and $\omega^- \in \Omega_{sfc}^k(M) \cap \Omega_{\sharp}^k(M)$ such that $\omega = \omega^+ + \omega^-$.*
2. *for all $\omega \in \Omega_{\sharp}^k(M)$ there exists $\omega^+ \in \Omega_{pc}^k(M) \cap \Omega_{\sharp}^k(M)$ and $\omega^- \in \Omega_{fc}^k(M) \cap \Omega_{\sharp}^k(M)$ such that $\omega = \omega^+ + \omega^-$.*

Proof. We show the result in the first case, the second one can be proved in complete analogy. Let $\omega \in \Omega_{sc}^k(M) \cap \Omega_{\sharp}^k(M)$. Consider Σ_1, Σ_2 , two Cauchy surfaces on M —*cf.* [1, Def. 3.10]—such that $J^+(\Sigma_1) \subset J^+(\Sigma_2)$. Moreover, let $\varphi_+ \in \Omega_{pc}^0(M)$ be such that $\varphi_+|_{J^+(\Sigma_2)} = 1$ and $\varphi_+|_{J^-(\Sigma_1)} = 0$. We define $\varphi_- := 1 - \varphi_+ \in \Omega_{fc}^0(M)$. Notice that we can always choose φ so that, for all $x \in M$, $\varphi(x)$ depends only on the value $\tau(x)$, where τ is the global time function defined in Theorem 1. We set $\omega_{\pm} \doteq \varphi_{\pm}\omega$ so that $\omega^+ \in \Omega_{spc}^k(M) \cap \Omega_{\sharp}^k(M)$ while $\omega^- \in \Omega_{sfc}^k(M) \cap \Omega_{\sharp}^k(M)$. This is automatic for $\sharp = D$ on account of the equalities

$$t\omega^{\pm} = \varphi_{\pm}t\omega = 0, \quad n\omega^{\pm} = \varphi_{\pm}n\omega = 0.$$

We check that $\omega^\pm \in \Omega_\sharp^k(M)$ for $\sharp = \perp$. The proof for the remaining boundary conditions $\perp, f_\parallel, f_\perp$ follows from a similar computation—or by duality *cf.* Remark 14. It holds

$$n\omega_\pm = \varphi_\pm|_{\partial M}n\omega = 0, \quad nd\omega_\pm = n(d\varphi_\pm \wedge \omega) = \partial_\tau\varphi_\pm n_{\partial\Sigma_\tau}t_{\Sigma_\tau}\omega = 0.$$

In the last equality $t_{\Sigma_\tau} : \Omega^k(M) \rightarrow \Omega^k(\Sigma_\tau)$ and $n_{\partial\Sigma_\tau} : \Omega^k(\Sigma_\tau) \rightarrow \Omega^{k-1}(\partial\Sigma_\tau)$ are the maps from Definition 5 with $N \equiv \Sigma_\tau \doteq \{\tau\} \times \Sigma$, where $M = \mathbb{R} \times \Sigma$. The last identity follows because the condition $n\omega = 0$ is equivalent to $n_{\partial\Sigma_\tau}t_{\Sigma_\tau}\omega = 0$ and $n_{\partial\Sigma_\tau}n_{\Sigma_\tau}\omega = 0$ for all $\tau \in \mathbb{R}$ —*cf.* Lemma 50 in “Appendix B”. \square

In the following, we shall make a key assumption on the existence of distinguished fundamental solutions for the operator \square_\sharp for $\sharp \in \{D, \parallel, \perp, f_\parallel, f_\perp\}$. Subsequently we shall prove that such hypothesis holds true whenever the underlying globally hyperbolic spacetime with timelike boundary is ultrastatic and $f \in C^\infty(\partial\Sigma)$ has definite sign—*cf.* “Appendix A”. Recalling both Definition 2 and Definition 12 we require the following:

Assumption 16. For all $f \in C^\infty(\partial M)$ and for all k such that $0 \leq k \leq m = \dim M$, there exist advanced (−) and retarded (+) fundamental solutions for the D’Alembert–de Rham wave operator \square_\sharp where $\sharp \in \{D, \parallel, \perp, f_\parallel, f_\perp\}$. In other words, there exist continuous maps $G_\sharp^\pm : \Omega_c^k(M) \rightarrow \Omega_{sc,\sharp}^k(M) \doteq \Omega_{sc}^k(M) \cap \Omega_\sharp^k(M)$ such that

$$\square \circ G_\sharp^\pm = \text{Id}_{\Omega_c^k(M)}, \quad G_\sharp^\pm \circ \square_{c,\sharp} = \text{Id}_{\Omega_{c,\sharp}^k(M)}, \quad \text{supp}(G_\sharp^\pm\omega) \subseteq J^\pm(\text{supp}(\omega)), \tag{16}$$

for all $\omega \in \Omega_c^k(M)$ where $\square_{c,\sharp}$ indicates that the domain of \square is restricted to $\Omega_{c,\sharp}^k(M)$.

Remark 17. Notice that domain of G_\sharp^\pm is not restricted to $\Omega_{c,\sharp}^k(M)$. Furthermore the second identity in (16) cannot be extended to $G_\sharp^\pm \circ \square = \text{Id}_{\Omega_c^k(M)}$ since it would entail $G_\sharp^\pm \square\omega = \omega$ for all $\omega \in \Omega_c^k(M)$. Yet the left hand side also entails that $\omega \in \Omega_{c,\sharp}^k$, which is manifestly a contradiction.

Corollary 18. *Under the same hypotheses of Assumption 16, if the fundamental solutions G_\sharp^\pm exist, they are unique.*

Proof. Suppose that, beside G_\sharp^- , there exists a second map $\tilde{G}_\sharp^- : \Omega_c^k(M) \rightarrow \Omega_{sc,\sharp}^k(M)$ enjoying the properties of Eq. (16). Then, for any but fixed $\alpha \in \Omega_c^k(M)$ it holds

$$(\alpha, G_\sharp^+\beta) = (\square G_\sharp^-\alpha, G_\sharp^+\beta) = (G_\sharp^-\alpha, \square G_\sharp^+\beta) = (G_\sharp^-\alpha, \beta), \quad \forall \beta \in \Omega_c^k(M),$$

where we used both the support properties of the fundamental solutions and Lemma 9 which guarantees that \square is formally self-adjoint on $\Omega_\sharp^k(M)$. Similarly, replacing G_\sharp^- with \tilde{G}_\sharp^- , it holds $(\alpha, G_\sharp^+\beta) = (\tilde{G}_\sharp^-\alpha, \beta)$. It descends that $((\tilde{G}_\sharp^- - G_\sharp^-)\alpha, \beta) = 0$, which entails $\tilde{G}_\sharp^-\alpha = G_\sharp^-\alpha$ being the pairing between $\Omega_c^k(M)$ and $\Omega_c^k(M)$ separating. A similar result holds for the retarded fundamental solution. \square

This corollary can be also read as a consequence of the property that, for all $\omega \in \Omega_c^k(M)$, $G_{\sharp}^{\pm}\omega \in \Omega_{sc,\sharp}^k(M)$ can be characterized as the unique solution to the Cauchy problem

$$\square\psi = \omega, \quad \text{supp}(\psi) \cap M \setminus J^{\pm}(\text{supp}(\omega)) = \emptyset, \quad \psi \in \Omega_{\sharp}^k(M). \tag{17}$$

Remark 19. The fundamental solution G_{\sharp}^{+} (resp. G_{\sharp}^{-}) can be extended to $G_{\sharp}^{+} : \Omega_{pc}^k(M) \rightarrow \Omega_{pc}^k(M) \cap \Omega_{\sharp}^k(M)$ (resp. $G_{\sharp}^{-} : \Omega_{fc}^k(M) \rightarrow \Omega_{fc}^k(M) \cap \Omega_{\sharp}^k(M)$)—cf. [3, Thm. 3.8]. As a consequence, the problem $\square\psi = \omega$ with $\omega \in \Omega^k(M)$ always admits a solution lying in $\Omega_{\sharp}^k(M)$. As a matter of facts, consider any smooth function $\eta \equiv \eta(\tau)$, where $\tau \in \mathbb{R}$, cf. Eq. (1), such that $\eta(\tau) = 1$ for all $\tau > \tau_1$ and $\eta(\tau) = 0$ for all $\tau < \tau_0$. Then calling $\omega^{+} \doteq \eta\omega$ and $\omega^{-} = (1-\eta)\omega$, it holds $\omega^{+} \in \Omega_{pc}^k(M)$ while $\omega^{-} \in \Omega_{fc}^k(M)$. Hence $\psi = G_{\sharp}^{+}\omega^{+} + G_{\sharp}^{-}\omega^{-} \in \Omega_{\sharp}^k(M)$ is a solution.

We prove the main result of this section, which characterizes the kernel of \square_{\sharp} on the space of smooth k -forms with prescribed boundary condition $\sharp \in \{D, \parallel, \perp, f_{\parallel}, f_{\perp}\}$.

Proposition 20. *Whenever Assumption 16 is fulfilled, then, for all $\sharp \in \{D, \parallel, \perp, f_{\parallel}, f_{\perp}\}$, setting $G_{\sharp} \doteq G_{\sharp}^{+} - G_{\sharp}^{-} : \Omega_c^k(M) \rightarrow \Omega_{sc,\sharp}^k(M)$, the following statements hold true:*

1. for all $f \in C^{\infty}(\partial M)$ the following duality relations hold true:

$$\star G_D^{\pm} = G_D^{\pm}\star, \quad \star G_{\parallel}^{\pm} = G_{\perp}^{\pm}\star, \quad \star G_{f_{\parallel}}^{\pm} = G_{f_{\perp}}^{\pm}\star. \tag{18}$$

2. for all $\alpha, \beta \in \Omega_c^k(M)$ it holds

$$(\alpha, G_{\sharp}^{\pm}\beta) = (G_{\sharp}^{\mp}\alpha, \beta). \tag{19}$$

3. the interplay between G_{\sharp} and \square_{\sharp} is encoded in the exact sequence:

$$0 \rightarrow \Omega_{c,\sharp}^k(M) \xrightarrow{\square_{\sharp}} \Omega_c^k(M) \xrightarrow{G_{\sharp}} \Omega_{sc,\sharp}^k(M) \xrightarrow{\square_{\sharp}} \Omega_{sc}^k(M) \rightarrow 0, \tag{20}$$

where $\Omega_{c,\sharp}^k(M) \doteq \Omega_c^k(M) \cap \Omega_{\sharp}^k(M)$.

Proof. We prove the different items separately. Starting from 1., we observe that $\star\square = \square\star$. This entails that, for all $\alpha \in \Omega_c^k(M)$,

$$\square\star^{-1}G_{\sharp}^{\pm}\star\alpha = \star^{-1}\square G_{\sharp}^{\pm}\star\alpha = \alpha.$$

Remark 14 entails that $\star^{-1}G_{\sharp}^{\pm}\star\alpha$ satisfies the necessary boundary conditions, so to apply Corollary 18. This yields that $\star^{-1}G_{\sharp}^{\pm}\star = G_{\star\sharp}^{\pm}$, where $G_{\star\sharp}^{\pm}$ indicates the advanced/retarded propagator for $\star\sharp$ -boundary conditions being $\sharp \in \{D, \parallel, \perp, f_{\parallel}, f_{\perp}\}$. As a consequence Eq. (18) descends.

2. Equation (19) is a consequence of the following chain of identities valid for all $\alpha, \beta \in \Omega_c^k(M)$

$$(\alpha, G_{\sharp}^{\pm}\beta) = (\square_{\sharp}G_{\sharp}^{\mp}\alpha, G_{\sharp}^{\pm}\beta) = (G_{\sharp}^{\mp}\alpha, \square_{\sharp}G_{\sharp}^{\pm}\beta) = (G_{\sharp}^{\mp}\alpha, \beta),$$

where we used both the support properties of the fundamental solutions and Lemma 9.

3. The exactness of the series is proven using the properties already established for the fundamental solutions G_{\sharp}^{\pm} . The left exactness of the sequence is a consequence of the second identity in equation (16) which ensures that $\square_{\sharp}\alpha = 0$, $\alpha \in \Omega_{c,\sharp}^k(M)$, entails $\alpha = G_{\sharp}^+\square_{\sharp}\alpha = 0$. In order to prove that $\ker G_{\sharp} = \square_{\sharp}\Omega_{c,\sharp}^k$, we first observe that $G_{\sharp}\square_{\sharp}\Omega_{c,\sharp}^k(M) = \{0\}$ on account of equation (16). Moreover, if $\beta \in \Omega_c^k(M)$ is such that $G_{\sharp}\beta = 0$, then $G_{\sharp}^+\beta = G_{\sharp}^-\beta$. Hence, in view of the support properties of the fundamental solutions $G_{\sharp}^+\beta \in \Omega_{c,\sharp}^k(M)$ and $\beta = \square_{\sharp}G_{\sharp}^+\beta$. Subsequently, we need to verify that $\ker \square_{\sharp} = G_{\sharp}\Omega_c^k(M)$. Once more $\square_{\sharp}G_{\sharp}\Omega_c^k(M) = \{0\}$ follows from Eq. (16). Conversely, let $\omega \in \Omega_{sc,\sharp}^k(M)$ be such that $\square_{\sharp}\omega = 0$. On account of Lemma 15, we can split $\omega = \omega^+ + \omega^-$ where $\omega^+ \in \Omega_{spc,\sharp}^k(M)$. Then $\square_{\sharp}\omega^+ = -\square_{\sharp}\omega^- \in \Omega_c^k(M)$ and

$$G_{\sharp}\square_{\sharp}\omega^+ = G_{\sharp}^+\square_{\sharp}\omega^+ + G_{\sharp}^-\square_{\sharp}\omega^- = \omega.$$

To conclude we need to establish the right exactness of the sequence. Consider any $\alpha \in \Omega_{sc}^k(M)$ and the equation $\square_{\sharp}\omega = \alpha$. Consider the function $\eta(\tau)$ as in Remark 19 and let $\omega \doteq G_{\sharp}^+(\eta\alpha) + G_{\sharp}^-((1 - \eta)\alpha)$. In view of Remark 19 and of the support properties of the fundamental solutions, $\omega \in \Omega_{sc,\sharp}^k(M)$ and $\square_{\sharp}\omega = \alpha$. □

Remark 21. Following the same reasoning as in [3] together with minor adaptations of the proofs of [12], one may extend G_{\sharp} to an operator $G_{\sharp}: \Omega_{tc}^k(M) \rightarrow \Omega_{\sharp}^k(M)$ for all $\sharp \in \{\mathbb{D}, \parallel, \perp, f_{\parallel}, f_{\perp}\}$. As a consequence, the exact sequence of Proposition 20 generalizes as

$$0 \rightarrow \Omega_{tc,\sharp}^k(M) \xrightarrow{\square_{\sharp}} \Omega_{tc}^k(M) \xrightarrow{G_{\sharp}} \Omega_{\sharp}^k(M) \xrightarrow{\square_{\sharp}} \Omega^k(M) \rightarrow 0. \tag{21}$$

Remark 22. Proposition 20 and Remark 21 ensure that $\ker_c \square_{\sharp} \subseteq \ker_{tc} \square_{\sharp} = \{0\}$. In other words, there are no timelike compact solutions to the equation $\square\omega = 0$ with \sharp -boundary conditions. More generally, it can be shown that $\ker_c \square \subseteq \ker_{tc} \square = \{0\}$, namely there are no timelike compact solutions regardless of the boundary condition. This follows by standard arguments using a suitable energy functional defined on the solution space—cf. [12, Thm. 30] for the proof for $k = 0$.

In view of the applications to the Maxwell operator, it is worth focusing specifically on the boundary conditions \perp, \parallel individuated in Definition 12 since it is possible to prove a useful relation between the associated propagators and the operators d, δ .

Lemma 23. *Under the hypotheses of Assumption 16 it holds that*

$$\begin{aligned} G_{\parallel}^{\pm} \circ d &= d \circ G_{\parallel}^{\pm} && \text{on } \Omega_t^k(M) \cap \Omega_{pc/fc}^k(M), \\ G_{\parallel}^{\pm} \circ \delta &= \delta \circ G_{\parallel}^{\pm} && \text{on } \Omega_{pc/fc}^k(M), \end{aligned} \tag{22}$$

$$\begin{aligned} G_{\perp}^{\pm} \circ \delta &= \delta \circ G_{\perp}^{\pm} && \text{on } \Omega_n^k(M) \cap \Omega_{pc/fc}^k(M), \\ G_{\perp}^{\pm} \circ d &= d \circ G_{\perp}^{\pm} && \text{on } \Omega_{pc/fc}^k(M). \end{aligned} \tag{23}$$

Proof. From Eq. (18), it follows that Eqs. (22, 23) are dual to each other via the Hodge operator. Hence we shall only focus on Eq. (22).

For every $\alpha \in \Omega_{\text{tc}}^k(M) \cap \Omega_{\text{t}}^k(M)$, $G_{\parallel}^{\pm}d\alpha$ and $dG_{\parallel}^{\pm}\alpha$ lie both in $\Omega_{\parallel}^k(M)$. In particular, using Eq. (5b), $t\delta dG_{\parallel}^{\pm}\alpha = t(\square_{\parallel} - d\delta)G_{\parallel}^{\pm}(\alpha) = t\alpha = 0$ while the second boundary condition is automatically satisfied since $\text{td}G_{\parallel}^{\pm} = \text{dt}G_{\parallel}^{\pm} = 0$. Hence, considering $\beta = G_{\parallel}^{\pm}d\alpha - dG_{\parallel}^{\pm}\alpha$, it holds that $\square\beta = 0$ and $\beta \in \Omega_{\parallel}^k \cap \Omega_{\text{pc}/\text{fc}}^k(M)$. In view of Remark 19, this entails $\beta = 0$. \square

We conclude this section with a corollary to Lemma 23 which shows that, when considering the difference between the advanced and the retarded fundamental solutions, the support restrictions present in Eqs. (22, 23) disappear.

Corollary 24. *Under the hypotheses of Assumption 16 it holds that:*

(i) *for all $\alpha \in \Omega_{\text{tc}}^k(M)$ there exists $\beta_{\parallel} \in \Omega_{\text{tc}}^{k+1}(M)$ such that $t\beta_{\parallel} = 0$, $t\delta\beta_{\parallel} = t\alpha$ and*

$$\delta G_{\parallel}\alpha = G_{\parallel}\delta\alpha, \quad dG_{\parallel}\alpha = G_{\parallel}(d\alpha - \square\beta_{\parallel}). \tag{24}$$

(ii) *for all $\alpha \in \Omega_{\text{tc}}^k(M)$ there exists $\beta_{\perp} \in \Omega_{\text{tc}}^{k-1}(M)$ such that $n\beta_{\perp} = 0$, $nd\beta_{\perp} = n\alpha$ and*

$$\delta G_{\perp}\alpha = G_{\perp}(\delta\alpha - \square\beta_{\perp}), \quad dG_{\perp}\alpha = G_{\perp}d\alpha. \tag{25}$$

Proof. As starting point, we observe that the existence of $\beta_{\parallel}, \beta_{\perp}$ is guaranteed by Remark 7.

Proof for \parallel boundary conditions. On account of Lemma 23, it holds

$$\delta G_{\parallel} = G_{\parallel}\delta \quad \text{on } \Omega_{\text{tc}}^k(M), \quad dG_{\parallel} = G_{\parallel}d \quad \text{on } \Omega_{\text{tc},t}^k(M). \tag{26}$$

In addition

$$dG_{\parallel}\alpha = dG_{\parallel}(\alpha - \delta\beta_{\parallel}) + dG_{\parallel}\delta\beta_{\parallel} = G_{\parallel}d\alpha - G_{\parallel}d\delta\beta_{\parallel} + dG_{\parallel}\delta\beta_{\parallel},$$

where in the second equality we used Eq. (26) together with the boundary condition $t\delta\beta_{\parallel} = t\alpha$. Due to both Eq. (26) and the condition $t\beta_{\parallel} = 0$ it holds

$$dG_{\parallel}\delta\beta_{\parallel} = d\delta G_{\parallel}\beta_{\parallel} = \square G_{\parallel}\beta_{\parallel} - \delta dG_{\parallel}\beta_{\parallel} = -G_{\parallel}\delta d\beta_{\parallel} = -G_{\parallel}\square\beta_{\parallel} + G_{\parallel}d\delta\beta_{\parallel}.$$

Putting together these data, we find

$$dG_{\parallel}\alpha = G_{\parallel}d\alpha - G_{\parallel}d\delta\beta_{\parallel} + dG_{\parallel}\delta\beta_{\parallel} = G_{\parallel}d\alpha - G_{\parallel}\square\beta_{\parallel},$$

as claimed.

Proof for \perp boundary conditions. The proof is similar to the previous one mutatis mutandis. In particular Lemma 23 entails

$$\delta G_{\perp} = G_{\perp}\delta \quad \text{on } \Omega_{\text{tc},n}^k(M), \quad dG_{\perp} = G_{\perp}d \quad \text{on } \Omega_{\text{tc}}^k(M), \tag{27}$$

At the same time

$$\begin{aligned} \delta G_{\perp}\alpha &= \delta G_{\perp}(\alpha - d\beta_{\perp}) + \delta G_{\perp}d\beta_{\perp} = G_{\perp}\delta\alpha - G_{\perp}\delta d\beta_{\perp} + \delta G_{\perp}d\beta_{\perp} \\ &= G_{\perp}(\delta\alpha - \square\beta_{\perp}), \end{aligned}$$

where we have used the boundary conditions of β_\perp together with

$$\begin{aligned} \delta G_\perp d\beta_\perp &= \delta dG_\perp \beta_\perp = \square G_\perp \beta_\perp - d\delta G_\perp \beta_\perp = -G_\perp d\delta \beta_\perp \\ &= -G_\perp \square \beta_\perp + G_\perp \delta d\beta_\perp. \end{aligned}$$

□

Remark 25. Notice that Eqs. (24), (25) do not depend on the particular choice of $\beta_\parallel, \beta_\perp$. In particular, let assume $\hat{\beta}_\perp \in \Omega_{tc}^{k-1}(M)$ is another $(k-1)$ -form such that $n\hat{\beta}_\perp = 0$ while $nd\hat{\beta}_\perp = n\alpha$. It follows that $(\beta_\perp - \hat{\beta}_\perp) \in \Omega_{tc,\perp}^{k-1}(M)$ and therefore $G_\perp \square(\beta_\perp - \hat{\beta}_\perp) = 0$ on account of Proposition 20.

3.2. On the Maxwell Operator

In this section, we focus our attention on the Maxwell operator $\delta d : \Omega^k(M) \rightarrow \Omega^k(M)$ studying its kernel in connection both to the D’Alembert–de Rham wave operator \square and to the identification of suitable boundary conditions. We shall keep the assumption that (M, g) is a globally hyperbolic spacetime with timelike boundary of dimension $\dim M = m \geq 2$ —cf. Theorem 1. Notice that, if $k = m$, then the Maxwell operator becomes trivial, while, if $k = 0$, it coincides with the D’Alembert–de Rham operator \square . Hence this case falls in the one studied in the preceding section and in [12]. Therefore, unless stated otherwise; henceforth, we shall consider only $0 < k < m = \dim M$.

In complete analogy to the analysis of \square , we observe that, for any pair $\alpha, \beta \in \Omega^k(M)$ such that $\text{supp}(\alpha) \cap \text{supp}(\beta)$ is compact, the following Green’s formula holds true:

$$(\delta d\alpha, \beta) - (\alpha, \delta d\beta) = (t\alpha, nd\beta)_\partial - (nd\alpha, t\beta)_\partial. \tag{28}$$

In the same spirit of Lemma 9, the operator δd becomes formally self-adjoint if we restrict its domain to

$$\Omega_f^k(M) \doteq \{\omega \in \Omega^k(M) \mid nd\omega = f t\omega\}, \tag{29}$$

where $f \in C^\infty(\partial M)$ is arbitrary but fixed. In what follows we will consider two particular boundary conditions which are directly related to the \square -tangential and to the \square -normal boundary conditions for the D’Alembert–de Rham operator—cf. Definition 12.

The discussion of the general case is related to the Robin \square -tangential/Robin \square -normal boundary conditions. However, in these cases, it is not clear whether a generalization of Lemma 23 holds true. This is an important obstruction to adapt our analysis to these cases.

Definition 26. Let (M, g) be a globally hyperbolic spacetime with timelike boundary and let $0 < k < \dim M$. We call

1. space of k -forms with δd -tangential boundary condition, $\Omega_t^k(M)$ as in Eq. (4) with $N = \partial M$.
2. space of k -forms with δd -normal boundary condition

$$\Omega_{nd}^k(M) \doteq \{\omega \in \Omega^k(M) \mid nd\omega = 0\}. \tag{30}$$

Remark 27. It is worth observing that the the δd -normal boundary condition appears to play a distinguished rôle in relation to standard electromagnetism, seen as a theory for 1-forms. More precisely, if we consider a globally hyperbolic spacetime (M, g) with timelike boundary, the underlying action reads

$$S[A] = \frac{1}{2}(dA, dA).$$

By considering an arbitrary variation with respect to $\alpha \in \Omega_c^1(M)$, it descends that

$$\frac{d}{d\lambda} S[A + \lambda\alpha] \Big|_{\lambda=0} = (\alpha, \delta dA) + (t\alpha, ndA)_\partial.$$

The arbitrariness of α leads to the equation of motion $\delta dA = 0$, together with the boundary condition $ndA = 0$. This indication of the preferred rôle of the δd -normal boundary condition will be strengthened by the following discussion—*cf.* Remark 29.

In the following, our first goal is to characterize the kernel of the Maxwell operator with a prescribed boundary condition, *cf.* Eq. (29). To this end we need to focus on the *gauge invariance* of the underlying theory. In the case in hand, this translates in the following characterization.

Definition 28. Let (M, g) be a globally hyperbolic spacetime with timelike boundary and let δd be the Maxwell operator acting on $\Omega^k(M)$, $0 < k < \dim M$. We say that

1. $A \in \Omega_t^k(M)$, is *gauge equivalent* to $A' \in \Omega_t^k(M)$ if $A - A' \in d\Omega_t^{k-1}(M)$, namely if there exists $\chi \in \Omega_t^{k-1}(M)$ such that $A' = A + d\chi$. The space of solutions with δd -tangential boundary conditions is denoted by

$$\text{Sol}_t(M) \doteq \frac{\{A \in \Omega^k(M) \mid \delta dA = 0, tA = 0\}}{d\Omega_t^{k-1}(M)}. \tag{31}$$

2. $A \in \Omega_{nd}^k(M)$, is *gauge equivalent* to $A' \in \Omega_{nd}^k(M)$ if there exists $\chi \in \Omega^{k-1}(M)$ such that $A' = A + d\chi$. The space of solutions with δd -normal boundary conditions is denoted by

$$\text{Sol}_{nd}(M) \doteq \frac{\{A \in \Omega^k(M) \mid \delta dA = 0, ndA = 0\}}{d\Omega^{k-1}(M)}. \tag{32}$$

Similarly the space of spacelike supported solutions with δd -tangential (resp. δd -normal) boundary conditions are

$$\begin{aligned} \text{Sol}_t^{\text{sc}}(M) &\doteq \frac{\{A \in \Omega_{\text{sc}}^k(M) \mid \delta dA = 0, tA = 0\}}{d\Omega_{t,\text{sc}}^{k-1}(M)}, \\ \text{Sol}_{nd}^{\text{sc}}(M) &\doteq \frac{\{A \in \Omega_{\text{sc}}^k(M) \mid \delta dA = 0, ndA = 0\}}{d\Omega_{\text{sc}}^{k-1}(M)}. \end{aligned} \tag{33}$$

Remark 29. Notice that in Definition 28 we have employed two different notions of gauge equivalence in the construction of $\text{Sol}_t(M)$ and of $\text{Sol}_{nd}(M)$, which are related to the different choices of boundary conditions. It is worth observing that, at the level of solution space, the boundary condition $nd\omega = 0$

involves a constraint on a quantity, e.g., the Faraday tensor when working with $k = 1$, which is gauge invariant with respect to the standard gauge group of Maxwell theory on a globally hyperbolic spacetime without boundary. Therefore, this reverberates in the lack of any necessity to restrict the underlying gauge group in the case in hand. For this reason, such scenario is certainly distinguished. As a matter of fact, when working with $\text{Sol}_t(M)$, the boundary condition does not involve a quantity which is gauge invariant under the action of the standard gauge group of Maxwell theory on a globally hyperbolic spacetime without boundary. Hence, in this case, one must introduce a reduced gauge group. The latter can be chosen in different ways and, to avoid such quandary, one should resort to a more geometrical formulation of Maxwell's equations, namely as originating from a theory for the connections of a principal $U(1)$ -bundle over the underlying globally hyperbolic spacetime with timelike boundary, cf. [5, 7] for the case with empty boundary. Since this analysis would require a whole paper on its own, we postpone it to future work.

The following propositions discuss the existence of a representative fulfilling the Lorenz gauge condition of an equivalence classes $[A] \in \text{Sol}_t(M)$ (resp. $[A] \in \text{Sol}_{\text{nd}}(M)$)—cf. [8, Lem. 7.2]. In addition we provide a connection between δd -tangential (resp. δd -normal) boundary conditions with \square -tangential (resp. \square -normal) boundary conditions. Recalling Definition 12 of the \square -tangential boundary condition, the following holds true.

Proposition 30. *Let (M, g) be a globally hyperbolic spacetime with timelike boundary. Then for all $[A] \in \text{Sol}_t(M)$ there exists a representative $A' \in [A]$ such that*

$$\square_{\parallel} A' = 0, \quad \delta A' = 0. \tag{34}$$

Moreover, up to gauge transformation we have $A' = G_{\parallel} \alpha$ with $\alpha \in \Omega_{\text{tc}, \delta}^k(M)$. Finally, the same result holds true for $[A] \in \text{Sol}_t^{\text{sc}}(M)$ —in particular in this case $A' = G_{\perp} \alpha$ for $\alpha \in \Omega_{\text{c}, \delta}^k(M)$.

Proof. We focus only on the first statement, the proof of the second one being similar. Let $A \in [A] \in \text{Sol}_t(M)$, that is, $A \in \Omega^k(M)$, $\delta dA = 0$ and $tA = 0$. Consider any $\chi \in \Omega_t^{k-1}(M)$ such that

$$\square \chi = -\delta A, \quad \delta \chi = 0, \quad t\chi = 0. \tag{35}$$

In view of Assumption 16 and of Remark 19, we can fix $\chi = -\sum_{\pm} G_{\parallel}^{\pm} \delta A^{\pm}$, where A^{\pm} is defined as in Remark 19. Per definition of G_{\parallel}^{\pm} , $t\chi = 0$ while, on account of Lemma 23, $\delta \chi = -\sum_{\pm} \delta G_{\parallel}^{\pm} \delta A^{\pm} = 0$. Hence A' is gauge equivalent to A as per Definition 28.

Proposition 20 and Remark 21 entail that there exists $\alpha \in \Omega_{\text{tc}}^k(M)$ such that $A' = G_{\parallel} \alpha$. Equation (26) implies that

$$0 = \delta A' = \delta G_{\parallel} \alpha = G_{\parallel} \delta \alpha,$$

that is, $\delta\alpha \in \ker G_{\parallel}$. This implies that there exists $\beta \in \Omega_{\text{tc},\parallel}^{k-1}(M)$ such that $\delta\alpha = \square_{\parallel}\beta$. It follows that

$$0 = \delta^2\alpha = \delta\square_{\parallel}\beta = \square\delta\beta,$$

which entails, on account of Remark 22, $\delta\beta = 0$. It follows that $\delta\alpha = \square_{\parallel}\beta = \delta d\beta$ and therefore

$$[A'] = [G_{\parallel}\alpha - dG_{\parallel}\beta] = [G_{\parallel}(\alpha - d\beta)],$$

where we used Eq. (26). Since $\alpha - d\beta \in \Omega_{\text{tc},\delta}^k(M)$ we have obtained the sought result. \square

The proof of the analogous result for $\Omega_{\text{nd}}^k(M)$ is slightly different and, thus, we discuss it separately. Recalling Definition 12 of the \square -normal boundary conditions, the following statement holds true.

Proposition 31. *Let (M, g) be a globally hyperbolic spacetime with timelike boundary. Then for all $[A] \in \text{Sol}_{\text{nd}}(M)$ there exists a representative $A' \in [A]$ such that*

$$\square_{\perp}A' = 0, \quad \delta A' = 0. \tag{36}$$

Moreover, up to gauge transformation we have $A' = G_{\perp}\alpha$ with $\alpha \in \Omega_{\text{tc},\text{n},\delta}^k(M)$. Finally, the same result holds true for $[A] \in \text{Sol}_{\text{nd}}^{\text{sc}}(M)$ —in particular in this case $A' = G_{\perp}\alpha$ for $\alpha \in \Omega_{\text{c},\text{n},\delta}^k(M)$.

Proof. As in the previous proposition, we can focus only on the first point, the second following suit. Let A be a representative of $[A] \in \text{Sol}_{\text{nd}}(M)$. Hence $A \in \Omega^k(M)$ so that $\delta dA = 0$ and $\text{nd}A = 0$. Consider first $\chi_0 \in \Omega^{k-1}(M)$ such that $\text{nd}\chi_0 = -nA$. The existence is guaranteed since the map nd is surjective—cf. Remark 7. As a consequence, we can exploit the residual gauge freedom to select $\chi_1 \in \Omega^{k-1}(M)$ such that

$$\square\chi_1 = -\delta\tilde{A}, \quad \delta\chi_1 = 0, \quad \text{nd}\chi_1 = 0 \quad n\chi_1 = 0, \tag{37}$$

where $\tilde{A} = A + d\chi_0$. Let $\eta \equiv \eta(\tau)$ be a smooth function such that $\eta = 0$ if $\tau < \tau_0$ while $\eta = 1$ if $\tau > \tau_1$, cf. Remark 19. Since $n\tilde{A} = 0$, we can fine tune η in such a way that both $\tilde{A}^{\pm} \doteq \eta\tilde{A}$ and $\tilde{A}^{-} \doteq (1 - \eta)\tilde{A}$ satisfy $n\tilde{A}^{\pm} = 0$. Equation (5b) entails that $\text{nd}\tilde{A}^{\pm} = -\delta n\tilde{A}^{\pm} = 0$. Hence we can apply Lemma 23 setting $\chi_1 = -\sum_{\pm} G_{\perp}^{\pm}\delta\tilde{A}^{\pm}$. Calling $A' = A + d(\chi_0 + \chi_1)$, we obtained the desired result.

Proposition 20 and Remark 21 imply that there exists $\alpha \in \Omega_{\text{tc}}^k(M)$ such that $A' = G_{\perp}\alpha$. On account of Corollary 24 there exists $\beta_{\perp} \in \Omega_{\text{tc}}^{k-1}(M)$ such that

$$0 = \delta A' = \delta G_{\perp}\alpha = G_{\perp}(\delta\alpha - \square\beta_{\perp}),$$

together with $\text{nd}\beta_{\perp} = n\alpha$ and $n\beta_{\perp} = 0$. It follows that $\delta\alpha - \square\beta_{\perp} = \square_{\perp}\eta$ for $\eta \in \Omega_{\text{tc},\perp}^{k-1}(M)$. Application of δ to the above identity leads to

$$0 = \delta(\delta\alpha - \square\beta_{\perp} - \square_{\perp}\eta) = -\square(\delta\beta_{\perp} + \delta\eta).$$

Remark 22 entails that $\delta\beta_\perp + \delta\eta = 0$, that is,

$$\delta\alpha = \square_\perp\eta + \square\beta_\perp = \delta d(\eta + \beta_\perp).$$

It follows that

$$[A'] = [G_\perp\alpha - dG_\perp(\eta + \beta_\perp)] = [G_\perp(\alpha - d(\eta + \beta_\perp))].$$

where we used Eq. (27). Since $\alpha - d(\eta + \beta_\perp) \in \Omega_{\text{tc},n,\delta}^k(M)$ the proof is complete. \square

Remark 32. A direct inspection of (35) and of (36) unveils that choosing a solution to these equations does not fix completely the gauge and a residual freedom is left. This amount either to

$$\mathcal{G}_t(M) \doteq \{\chi \in \Omega^{k-1}(M) \mid \delta d\chi = 0, \text{t}\chi = 0\},$$

or, in the case of a δd -normal boundary condition, to

$$\mathcal{G}_{\text{nd}}(M) \doteq \{\chi \in \Omega^{k-1}(M) \mid \delta d\chi = 0, \text{n}\chi = 0, \text{nd}\chi = 0\}.$$

Observe that, in the definition of $\mathcal{G}_{\text{nd}}(M)$, we require χ to be in the kernel of δd . Nonetheless, since the actual reduced gauge group is $d\mathcal{G}_{\text{nd}}(M)$ we can work with $\chi_0 \in \Omega^{k-1}(M)$ such that $\square\chi_0 = 0$. As a matter of fact for all $\chi \in \mathcal{G}_{\text{nd}}$ we can set $\chi_0 \doteq \chi + d\lambda$ where $\lambda \in \Omega^{k-2}(M)$ is such that $\square\lambda = -\delta\chi$ and $\text{n}\lambda = \text{nd}\lambda = 0$ —cf. Proposition 31. In addition $d\chi = d\chi_0$.

To better codify the results of the preceding discussion, it is also convenient to introduce the following linear spaces:

$$\mathcal{S}_t^\square(M) \doteq \{A \in \Omega^k(M) \mid \square A = 0, \delta A = 0, \text{t}A = 0\}, \tag{38}$$

$$\mathcal{S}_{\text{nd}}^\square(M) \doteq \{A \in \Omega^k(M) \mid \square A = 0, \delta A = 0, \text{n}A = 0, \text{nd}A = 0\}. \tag{39}$$

where $f \in C^\infty(\partial M)$. Hence Propositions 30, 31 can be summarized as stating the existence of the following isomorphisms:

$$\begin{aligned} \mathcal{S}_{\mathcal{G}_t,k}(M) &\doteq \frac{\mathcal{S}_t^\square(M)}{d\mathcal{G}_t(M)} \simeq \text{Sol}_t(M), \\ \mathcal{S}_{\mathcal{G}_{\text{nd}},k}(M) &\doteq \frac{\mathcal{S}_{\text{nd}}^\square(M)}{d\mathcal{G}_{\text{nd}}(M)} \simeq \text{Sol}_{\text{nd}}(M). \end{aligned} \tag{40}$$

It is noteworthy that both $\text{Sol}_t^{\text{sc}}(M), \text{Sol}_{\text{nd}}^{\text{sc}}(M)$ can be endowed with a presymplectic form—cf. [25, Prop. 5.1].

Proposition 33. *Let (M, g) be a globally hyperbolic spacetime with timelike boundary. Let $[A_1], [A_2] \in \text{Sol}_t^{\text{sc}}(M)$ and, for $A_1 \in [A_1]$, let $A_1 = A_1^+ + A_1^-$ be any decomposition such that $A^+ \in \Omega_{\text{spc},t}^k(M)$ while $A^- \in \Omega_{\text{sic},t}^k(M)$ —cf. Lemma 15. Then the following map $\sigma_t: \text{Sol}_t^{\text{sc}}(M)^{\times 2} \rightarrow \mathbb{R}$ is a presymplectic form:*

$$\sigma_t([A_1], [A_2]) = (\delta dA_1^+, A_2), \quad \forall [A_1], [A_2] \in \text{Sol}_t^{\text{sc}}(M). \tag{41}$$

A similar result holds for $\text{Sol}_{\text{nd}}^{\text{sc}}(M)$, and we denote the associated presymplectic form σ_{nd} . In particular for all $[A_1], [A_2] \in \text{Sol}_{\text{nd}}^{\text{sc}}(M)$ we have $\sigma_{\text{nd}}([A_1], [A_2]) \doteq (\delta dA_1^+, A_2)$ where $A_1 \in [A_1]$ is such that $A \in \Omega_{\text{sc},\perp}^k(M)$.

Proof. We shall prove the result for σ_{nd} , the proof for σ_t being the same mutatis mutandis.

First of all notice that for all $[A] \in \text{Sol}_{\text{nd}}^{\text{sc}}(M)$ there exists $A' \in [A]$ such that $A' \in \Omega_{\perp}^k(M)$. This is realized by picking an arbitrary $A \in [A]$ and defining $A' \doteq A + d\chi$ where $\chi \in \Omega_{\text{sc}}^{k-1}(M)$ is such that $\text{nd}\chi = -nA - cf$. Remark 7. We can thus apply Lemma 15 in order to split $A' = A'_+ + A'_-$ where $A'_+ \in \Omega_{\text{spc,nd}}^k(M)$ and $A'_- \in \Omega_{\text{sfc,nd}}^k(M)$. Notice that this procedure is not necessary for δd -tangential boundary condition since we can always split $A \in \Omega_{\text{sc,t}}^k(M)$ as $A = A^+ + A^-$ with $A_+ \in \Omega_{\text{spc,t}}^k(M)$ and $A_- \in \Omega_{\text{sfc,t}}^k(M)$ without invoking Lemma 15.

After these preliminary observations, consider the map

$$\sigma_{\text{nd}} : (\ker \delta d \cap \Omega_{\text{sc},\perp}^k(M))^{\times 2} \ni (A_1, A_2) \mapsto (\delta d A_1^+, A_2),$$

where we used Lemma 15 and we split $A_1 = A_1^+ + A_1^-$, with $A_1^+ \in \Omega_{\text{spc},\perp}^k(M)$ while $A_1^- \in \Omega_{\text{sfc},\perp}^k(M)$. The pairing $(\delta d A_1^+, A_2)$ is finite because A_2 is a space-like compact k -form while $\delta d A_1^+$ is compactly supported on account of A_1 being on-shell. Moreover, $(\delta d A_1^+, A_2)$ is independent from the splitting $A_1 = A_1^+ + A_1^-$ and thus σ_{nd} is well-defined. Indeed, let $A_1 = \tilde{A}_1^+ + \tilde{A}_1^-$ be another splitting: it follows that $A_1^+ - \tilde{A}_1^+ = -(A_1^- - \tilde{A}_1^-) \in \Omega_{\text{c,nd}}^k(M)$. Therefore

$$(\delta d \tilde{A}_1^+, A_2) = (\delta d A_1^+, A_2) + (\delta d (\tilde{A}_1^+ - A_1^+), A_2) = (\delta d A_1^+, A_2),$$

where in the last equality we used the self-adjointness of δd on $\Omega_{\text{nd}}^k(M)$.

We show that $\sigma_{\text{nd}}(A_1, A_2) = -\sigma_{\text{nd}}(A_2, A_1)$ for all $A_1, A_2 \in \ker \delta d \cap \Omega_{\text{sc},\perp}^k(M)$. For that we have

$$\begin{aligned} \sigma_{\text{nd}}(A_1, A_2) &= (\delta d A_1^+, A_2) = (\delta d A_1^+, A_2^+) + (\delta d A_1^+, A_2^-) \\ &= -(\delta d A_1^-, A_2^+) + (\delta d A_1^+, A_2^-) \\ &= -(A_1^-, \delta d A_2^+) + (A_1^+, \delta d A_2^-) \\ &= -(A_1^-, \delta d A_2^+) - (A_1^+, \delta d A_2^+) \\ &= -(A_1, \delta d A_2^+) = -\sigma_{\text{nd}}(A_1, A_2), \end{aligned}$$

where we exploited Lemma 15 and $A_1^\pm, A_2^\pm \in \Omega_{\text{sc,nd}}^k(M)$.

Finally we prove that $\sigma_{\text{nd}}(A_1, d\chi) = 0$ for all $\chi \in \Omega_{\text{sc}}^k(M)$. Together with the antisymmetry shown before, this entails that σ_{nd} descends to a well-defined map $\sigma_{\text{nd}} : \text{Sol}_{\text{nd}}^{\text{sc}}(M)^{\times 2} \rightarrow \mathbb{R}$ which is bilinear and antisymmetric. Therefore it is a presymplectic form. To this end let $\chi \in \Omega_{\text{sc}}^{k-1}(M)$: we have

$$\sigma_{\text{nd}}(A, d\chi) = (\delta d A_1^+, d\chi) = (\delta^2 d A_1^+, \chi) + (n\delta d A^+, t\chi) = 0,$$

where we used Eq. (6) as well as $n\delta d A^+ = -\delta n d A^+ = 0$. □

Working either with $\text{Sol}_t^{(\text{sc})}(M)$ or $\text{Sol}_{\text{nd}}^{(\text{sc})}(M)$ leads to the natural question whether it is possible to give an equivalent representation of these spaces in terms of compactly supported k -forms. Using Assumption 16, the following proposition holds true:

Proposition 34. *Let (M, g) be a globally hyperbolic spacetime with timelike boundary. Then the following linear maps are isomorphisms of vector spaces*

$$G_{\parallel} : \frac{\Omega_{tc,\delta}^k(M)}{\delta d\Omega_{tc,t}^k(M)} \rightarrow \text{Sol}_t(M), \quad G_{\parallel} : \frac{\Omega_{c,\delta}^k(M)}{\delta d\Omega_{c,t}^k(M)} \rightarrow \text{Sol}_t^{\text{sc}}(M), \quad (42)$$

$$G_{\perp} : \frac{\Omega_{tc,n,\delta}^k(M)}{\delta d\Omega_{tc,nd}^k(M)} \rightarrow \text{Sol}_{nd}(M), \quad G_{\perp} : \frac{\Omega_{c,n,\delta}^k(M)}{\delta d\Omega_{c,nd}^k(M)} \rightarrow \text{Sol}_{nd}^{\text{sc}}(M), \quad (43)$$

Proof. Mutatis mutandis, the proof of the four isomorphisms is the same. Hence we focus only on the case of timelike supported k -forms discussing separately the statement for \parallel - and \perp - boundary conditions.

Proof for δd -tangential boundary conditions. A direct computation shows that $G_{\parallel} [\Omega_{tc,\delta}^k(M)] \subseteq \mathcal{S}_{t,k}^{\square}(M)$. The condition $\delta G_{\parallel}\omega = 0$ follows from Corollary 24—*cf.* Eq. (26). Moreover, G_{\parallel} descends to the quotient since for all $\eta \in \Omega_{tc,t}^k(M)$ we have

$$G_{\parallel} \delta d\eta = -G_{\parallel} \delta d\eta = -\delta dG_{\parallel}\eta = -d\delta G_{\parallel}\eta \in d\Omega_t^{k-1}(M),$$

where we used Eq. (26) and Proposition 20.

Proposition 30 entails that G_{\parallel} is surjective. We show that G_{\parallel} is injective: let $[\alpha] \in \frac{\Omega_{tc,\delta}^k(M)}{\delta d\Omega_{tc,t}^k(M)}$ be such that $[G_{\parallel}\alpha] = [0]$. This entails that there exists $\chi \in \Omega_{tc,t}^{k-1}(M)$ such that $G_{\parallel}\alpha = d\chi$. Corollary 24 and $\alpha \in \Omega_{tc,\delta}^k(M)$ ensures that $\delta d\chi = 0$, therefore $\chi \in \text{Sol}_t(M)$.

Proposition 30 ensures that $d\chi = dG_{\parallel}\beta$ with $\beta \in \Omega_{tc,\delta}^{k-1}(M)$ while Corollary 24 implies that there exists $\eta_{\parallel} \in \Omega_{tc}^k(M)$ such that

$$G_{\parallel}\alpha = d\chi = dG_{\parallel}\beta = G_{\parallel}(d\beta - \square\eta_{\parallel}).$$

In addition it holds $t\eta_{\parallel} = 0$ and $t\delta\eta_{\parallel} = t\chi$.

It follows that $\alpha - d\beta + \square\eta_{\parallel} \in \ker G_{\parallel}$ and therefore $\alpha - d\beta + \square\eta_{\parallel} = \square_{\parallel}\zeta$ for $\zeta \in \Omega_{tc,\parallel}^k(M)$ —*cf.* Remark 21. Applying δ to the last equality we find

$$0 = \delta\alpha - \delta d\beta + \square\delta\eta_{\parallel} - \square\delta\zeta = \square(\delta\eta_{\parallel} - \delta\zeta - \beta),$$

where we used that $\delta\beta = 0$. Remark 22 entails that $\delta\eta_{\parallel} - \delta\zeta - \beta = 0$, therefore,

$$\alpha = \square_{\parallel}\zeta + d\beta - \square\eta_{\parallel} = \delta d(\zeta - \eta_{\parallel}) \in \delta d\Omega_{c,t}^k(M),$$

that is, $[\alpha] = [0]$.

Proof for δd -normal boundary conditions. By direct inspection we have that $G_{\perp}\alpha \in \mathcal{S}_{nd,k}^{\square}(M)$ for all $\alpha \in \Omega_{tc,n,\delta}^k(M)$. Furthermore, Eq. (26) entails that $\delta G_{\perp}\alpha = G_{\perp}\delta\alpha = 0$. The map G_{\perp} also descends to the quotients since for all $\eta \in \Omega_{c,nd}^k(M)$ it holds

$$G_{\perp} \delta d\eta = \delta dG_{\perp}\eta = -\delta dG_{\perp}\eta \in d\Omega_{tc}^{k-1}(M),$$

where in the second equality we used Corollary 24.

Surjectivity of G_{\perp} is guaranteed by Proposition 31. We show injectivity of G_{\perp} : let $[\alpha] \in \frac{\Omega_{tc,n,\delta}^k(M)}{\delta d\Omega_{tc,nd}^k(M)}$ be such that $[G_{\perp}\alpha] = [0]$. By definition there exists

$\chi \in \Omega_{tc}^{k-1}(M)$ such that $G_{\perp}\alpha = d\chi$. Since $n\alpha = 0$, Corollary 24 entails that $\delta d\chi = 0$. In addition it holds $nd\chi = nG_{\perp}\alpha = 0$. It follows that $[\chi] \in \text{Sol}_{nd}(M)$.

Proposition 31 implies that there exists $\beta \in \Omega_{tc,n,\delta}^{k-1}(M)$ such that

$$G_{\perp}\alpha = d\chi = dG_{\perp}\beta = G_{\perp}d\beta,$$

where we used equation (27). It follows that $\alpha - d\beta \in \ker G_{\perp}$, therefore $\alpha - d\beta = \square_{\perp}\eta$ for $\eta \in \Omega_{tc,\perp}^k(M)$ —cf. Proposition 20 and Remark 21. Application of δ entails

$$0 = \delta(\alpha - d\beta - \square_{\perp}\eta) = -\square(\beta + \delta\eta),$$

where we also used that $\delta\beta = 0$. Remark 22 implies that $\beta + \delta\eta = 0$, hence

$$\alpha = \square_{\perp}\eta + d\beta = \delta d\eta \in \delta d\Omega_{tc,nd}^k(M),$$

which entails $[\alpha] = [0]$. □

The following proposition shows that the isomorphisms introduced in Proposition 34 for $\text{Sol}_t^{\text{sc}}(M)$ and $\text{Sol}_{nd}^{\text{sc}}(M)$ lift to isomorphisms of presymplectic spaces.

Proposition 35. *Let (M, g) be a globally hyperbolic spacetime with timelike boundary. The following statements hold true:*

1. $\frac{\Omega_{c,\delta}^k(M)}{\delta d\Omega_{c,t}^k(M)}$ is a pre-symplectic space if endowed with the bilinear map $\tilde{G}_{\parallel}([\alpha], [\beta]) \doteq (\alpha, G_{\parallel}\beta)$.

Moreover $\left(\frac{\Omega_{c,\delta}^k(M)}{\delta d\Omega_{c,t}^k(M)}, \tilde{G}_{\parallel}\right)$ is pre-symplectomorphic to $(\text{Sol}_t^{\text{sc}}(M), \sigma_t)$.

2. $\frac{\Omega_{c,n,\delta}^k(M)}{\delta d\Omega_{c,nd}^k(M)}$ is a pre-symplectic space if endowed with the bilinear map $\tilde{G}_{\perp}([\alpha], [\beta]) \doteq (\alpha, G_{\perp}\beta)$.

Moreover $\left(\frac{\Omega_{c,n,\delta}^k(M)}{\delta d\Omega_{c,nd}^k(M)}, \tilde{G}_{\perp}\right)$ is pre-symplectomorphic to $(\text{Sol}_{nd}^{\text{sc}}(M), \sigma_{nd})$.

Proof. We discuss the two cases separately.

Proof for δd -tangential boundary conditions. We observe that \tilde{G}_{\parallel} is well-defined. As a matter of fact, let $\alpha, \beta \in \Omega_{c,\delta}^k(M)$, then $G_{\parallel}\beta \in \Omega_{sc}^k(M)$. Therefore the pairing $(\alpha, G_{\parallel}\beta)$ is finite. Furthermore, if $\eta \in \Omega_{c,t}^k(M)$, it holds

$$\begin{aligned} (\delta d\eta, G_{\parallel}\beta) &= (\eta, \delta dG_{\parallel}\beta) = -(\eta, d\delta G_{\parallel}\beta) = -(\eta, dG_{\parallel}\delta\beta) = 0, \\ (\alpha, G_{\parallel}\delta d\eta) &= (\alpha, \delta dG_{\parallel}\eta) = -(\alpha, d\delta G_{\parallel}\eta) = -(\alpha, dG_{\parallel}\delta\eta) = 0, \end{aligned}$$

where we used that $G_{\parallel}\beta, \eta \in \Omega_{c,t}^k(M)$ —cf. Eq. (28)—as well as Eq. (26). Therefore \tilde{G}_{\parallel} is well-defined: Moreover, it is per construction bilinear and antisymmetric; therefore, it induces a pre-symplectic structure.

We prove that the isomorphism $G_{\parallel}: \frac{\Omega_{c,\delta}^k(M)}{\delta d\Omega_{c,\parallel}^k(M)} \rightarrow \text{Sol}_t(M)$ introduced in Proposition 34 is a pre-symplectomorphism. Let $[\alpha], [\beta] \in \frac{\Omega_{c,\delta}^k(M)}{\delta d\Omega_{c,\parallel}^k(M)}$. As a

direct consequence of the properties of $G_{\parallel} = G_{\parallel}^+ - G_{\parallel}^-$, calling $A_1 = G_{\parallel}\alpha$ and $A_2 = G_{\parallel}\beta$, we can consider $A_{\pm} = G_{\parallel}^{\pm}\alpha$ in Eq. (41). This yields

$$\begin{aligned} \sigma_t([G_{\parallel}\alpha], [G_{\parallel}\beta]) &= (\delta dG_{\parallel}^+\alpha, G_{\parallel}\beta) = (\square G_{\parallel}^+\alpha - d\delta G_{\parallel}^+\alpha, G_{\parallel}\beta) \\ &= (\alpha, G_{\parallel}\beta) = \tilde{G}_{\parallel}([\alpha], [\beta]), \end{aligned}$$

where we used Lemma 23 so that $d\delta G_{\parallel}^+\alpha = dG_{\parallel}^+\delta\alpha = 0$.

Proof for δd -normal boundary conditions. We observe that \tilde{G}_{\perp} is well-defined: indeed for all $\alpha \in \Omega_{c,n,\delta}^k(M)$ and $\eta \in \Omega_{c,nd}^k(M)$ we have

$$\begin{aligned} (\alpha, G_{\perp}\delta d\eta) &= (\alpha, \delta dG_{\perp}\eta) = -(\alpha, d\delta G_{\perp}\eta) = -(\delta\alpha, \delta G_{\perp}\eta) - (n\alpha, t\delta G_{\perp}\eta) = 0 \\ (\delta d\eta, G_{\perp}\alpha) &= (\eta, \delta dG_{\perp}\alpha) = -(\eta, d\delta G_{\perp}\alpha) = -(\eta, dG_{\perp}\delta\alpha) = 0, \end{aligned}$$

where in the former chain of equalities we used Eq. (27) as well as Eq. (6), while in the latter we used Eqs. (28) and (27).

Proposition 20 shows that \tilde{G}_{\perp} induces a pre-symplectic structure. We now prove that the isomorphism $G_{\perp} : \frac{\Omega_{c,n,\delta}^k(M)}{\delta d\Omega_{c,nd}^k(M)} \rightarrow \text{Sol}_{nd}^{sc}(M)$ introduced in Proposition 34 is in fact a symplectomorphism. Let $[\alpha], [\beta] \in \frac{\Omega_{c,n,\delta}^k(M)}{\delta d\Omega_{c,nd}^k(M)}$ and let $[A_{\alpha}] := [G_{\perp}\alpha], [A_{\beta}] := [G_{\perp}\beta] \in \text{Sol}_{nd}^{sc}(M)$. Following 33 we can choose $A_{\alpha}^{\pm} = G_{\perp}^{\pm}\alpha$ so that

$$\begin{aligned} \sigma_{nd}([A_{\alpha}], [A_{\beta}]) &= (\delta dG_{\perp}^+\alpha, G_{\perp}\beta) = (\square G_{\perp}^+\alpha, G_{\perp}\beta) - (d\delta G_{\perp}^+\alpha, G_{\perp}\beta) \\ &= (\alpha, G_{\perp}\beta) = \tilde{G}_{\perp}([\alpha], [\beta]), \end{aligned}$$

where proposition 23 ensures that $d\delta G_{\perp}^+\alpha = dG_{\perp}^+\delta\alpha = 0$. □

Remark 36. Following [25, Cor. 5.3], σ_t (resp. σ_{nd}) do not define in general a symplectic form on the space of spacelike compact solutions $\text{Sol}_t(M)$ (resp. $\text{Sol}_{nd}(M)$). A direct characterization of this deficiency is best understood by introducing the following quotients:

$$\begin{aligned} \widehat{\text{Sol}}_t^{sc} &:= \frac{\{A \in \Omega_{sc}^k(M) \mid \delta dA = 0, tA = 0\}}{d\Omega_t^{k-1}(M) \cap \Omega_{sc}^k(M)}, \\ \widehat{\text{Sol}}_{nd}^{sc} &:= \frac{\{A \in \Omega_{sc}^k(M) \mid \delta dA = 0, ndA = 0\}}{d\Omega^{k-1}(M) \cap \Omega_{sc}^k(M)}, \end{aligned} \tag{44}$$

Focusing on δd -normal boundary conditions, it follows that there is a natural surjective linear map $\text{Sol}_{nd}^{sc} \rightarrow \widehat{\text{Sol}}_{nd}^{sc}$. Moreover, $\widehat{\text{Sol}}_{nd}^{sc}$ is symplectic with respect to the form $\sigma_{nd}([A_1], [A_2]) = (\delta dA_1^+, A_2)$. This can be shown as follows: if $\sigma_{nd}([A_1], [A_2]) = 0$ for all $[A_1] \in \widehat{\text{Sol}}_{nd}^{sc}$ then, choosing $A_1 = G_{\perp}\alpha$ with $\alpha \in \Omega_{c,n,\delta}^k(M)$ leads to $0 = \sigma_{\perp}([G_{\perp}\alpha], [A_2]) = (\alpha, A_2)$ —cf. Proposition 35. This entails $dA_2 = 0$ as well as $A_2 = 0 \in H_{k,c,n}(M)^* \simeq H^k(M)$ —cf. “Appendix C”. Therefore $A_2 = d\chi$ where $\chi \in \Omega^{k-1}(M)$ that is $[A_2] = [0]$ in $\widehat{\text{Sol}}_{nd}^{sc}(M)$. A similar result holds, mutatis mutandis, for \parallel .

The net result is that $(\text{Sol}_{nd}^{sc}(M), \sigma_{nd})$ (resp. $(\text{Sol}_t^{sc}(M), \sigma_t)$) is symplectic if and only if $d\Omega_{sc}^{k-1}(M) = \Omega_{sc}^k(M) \cap d\Omega^{k-1}(M)$ (resp. $d\Omega_{sc,t}^{k-1}(M) = \Omega_{sc}^k(M) \cap$

$d\Omega_t^{k-1}(M)$). This is in agreement with the analysis in [7] for the case of globally hyperbolic spacetimes (M, g) with $\partial M = \emptyset$.

Example 37. We construct an example of a globally hyperbolic spacetime with timelike boundary (M, g) such that $d\Omega_{sc}^{k-1}(M)$ is properly included in $\Omega_{sc}^k(M) \cap d\Omega^{k-1}(M)$ —cf. [25, Ex. 5.7] for the case with empty boundary. Consider half-Minkowski spacetime $\mathbb{R}_+^m := \mathbb{R}^{m-1} \times \mathbb{R}_+$ with flat metric and let $p \in \mathring{\mathbb{R}}_+^m$. Let $M \doteq \mathbb{R}_+^m \setminus J(p)$ be endowed with the restriction to M of the Minkowski metric. This spacetime is globally hyperbolic with timelike boundary. Let B_1, B_2 be open balls in \mathbb{R}_+^m centered at p with $B_1 \subset B_2$.

We consider $\psi \in \Omega^0(M)$ such that $\psi|_{J(B_1 \cap M)} = 1$ and $\psi|_{M \setminus J(B_2 \cap M)} = 0$. In addition we introduce $\varphi \in \Omega^0(M)$ such that: (a) $\varphi = \hat{\varphi}|_M$ is the restriction to M of an element $\hat{\varphi} \in \Omega_{tc}^0(\mathbb{R}_+^m)$ such that for all $x \in \mathbb{R}_+^m$, $\hat{\varphi}(x)$ depends only on $\tau_{\mathbb{R}_+^m}(x)$ —cf. Theorem 1—and $\hat{\varphi}(p) = 1$; (b) $\chi := \varphi\psi \in \Omega^0(M)$ is such that $t\chi = \chi|_{\partial M} = 0$;

The existence of such function $\hat{\varphi}$ is guaranteed by the fact that $p \in \mathring{\mathbb{R}}_+^m$. Hence there exists a non-empty interval $I \subseteq \mathbb{R}$ such that $\tau_{\mathbb{R}_+^m}(p) \in I$ and $x \notin \partial M$ for all $x \in \text{supp}(\psi)$ with $\tau_{\mathbb{R}_+^m}(x) \in I$.

It follows that $d\chi \in \Omega_{sc}^1(M)$, though $\chi \in \Omega^0(M)$ is not spacelike compact. In addition there does not exist $\zeta \in \Omega_{sc}^0(M)$ such that $d\zeta = d\chi$. Indeed, let us consider the spacelike curve γ in M

$$\gamma(s) = (\tau(p), x_1(p), \dots, x_{m-2}(p), z(p) + s), \quad s > 0,$$

where $\tau = \tau_{\mathbb{R}_+^m}, x_1, \dots, x_{m-2}, z$ are Cartesian coordinates on \mathbb{R}_+^m . Assuming the existence of ζ with the properties described above, integration along γ would lead to the following contradiction

$$0 = \int_{\gamma} \iota_{\gamma}^* d\zeta = \int_{\gamma} \iota_{\gamma}^* d\chi = -1.$$

3.3. The Algebra of Observables for $\text{Sol}_t(M)$ and for $\text{Sol}_{nd}(M)$

In this section, we discuss an application of the previous results that we obtained. Motivated by the algebraic approach to quantum field theory, we associate a unital $*$ -algebra both to $\text{Sol}_t(M)$ and to $\text{Sol}_{nd}(M)$, whose elements are interpreted as the observables of the underlying quantum system. Furthermore we study its key structural properties and we comment on their significance. We recall that the corresponding question, when the underlying background (M, g) is globally hyperbolic manifold with $\partial M = \emptyset$ has been thoroughly discussed in the literature—cf. [8, 16, 25, 35].

We now introduce the algebra of observables associated to the solution space $\text{Sol}_t(M)$ and $\text{Sol}_{nd}(M)$ and we discuss its main properties. Our analysis follows closely that of [8, 16, 25, 35] for globally hyperbolic spacetimes with empty boundary.

Following [8] we will identify a unital $*$ -algebra $\mathcal{A}_t(M)$ (resp. $\mathcal{A}_{nd}(M)$) built out of suitable linear functionals over $\text{Sol}_t(M)$ (resp. $\text{Sol}_{nd}(M)$), whose collection is fixed so to contain enough elements to distinguish all configurations in $\text{Sol}_t(M)$ (resp. $\text{Sol}_{nd}(M)$)—cf. Proposition 40.

Taking into account the discussion in the preceding sections, particularly Eq. (5b) and Definition 5 we introduce the following structures.

Definition 38. Let (M, g) be a globally hyperbolic spacetime with timelike boundary. We call *algebra of observables* associated to $\text{Sol}_t(M)$, the associative, unital $*$ -algebra

$$\mathcal{A}_t(M) \doteq \frac{\mathcal{T}[\mathcal{O}_t(M)]}{\mathcal{I}[\mathcal{O}_t(M)]}, \quad \mathcal{O}_t(M) \doteq \frac{\Omega_{c,\delta}^k(M)}{\delta d\Omega_{c,t}^k(M)}. \tag{45}$$

Here $\mathcal{T}[\mathcal{O}_t(M)] \doteq \bigoplus_{n=0}^\infty \mathcal{O}_t(M)^{\otimes n}$ is the universal tensor algebra with $\mathcal{O}_t(M)^{\otimes 0} \equiv \mathbb{C}$, while the $*$ -operation is defined by $(\alpha_1 \otimes \dots \otimes \alpha_n)^* = (\bar{\alpha}_n \otimes \dots \otimes \bar{\alpha}_1)$ for $\alpha_1 \otimes \dots \otimes \alpha_n \in \mathcal{O}_t(M)^{\otimes n}$ and then extended by linearity—here $\bar{\alpha}$ indicates complex conjugation. In addition $\mathcal{I}[\mathcal{O}_t(M)]$ is the $*$ -ideal generated by elements of the form $[\alpha] \otimes [\beta] - [\beta] \otimes [\alpha] - i\tilde{G}_\parallel([\alpha], [\beta])\mathbb{I}$, where $[\alpha], [\beta] \in \mathcal{O}_t(M)$ while \tilde{G}_\parallel is defined in Proposition 35 and \mathbb{I} is the identity of $\mathcal{T}[\mathcal{O}_t(M)]$.

Similarly, we call *algebra of observables* associated to $\text{Sol}_{\text{nd}}(M)$, the associative, unital $*$ -algebra

$$\mathcal{A}_{\text{nd}}(M) \doteq \frac{\mathcal{T}[\mathcal{O}_{\text{nd}}(M)]}{\mathcal{I}[\mathcal{O}_{\text{nd}}(M)]}, \quad \mathcal{O}_{\text{nd}}(M) \doteq \frac{\Omega_{c,n,\delta}^k(M)}{\delta d\Omega_{c,\text{nd}}^k(M)}. \tag{46}$$

where $\mathcal{T}[\mathcal{O}_{\text{nd}}(M)] \doteq \bigoplus_{n=0}^\infty \mathcal{O}_{\text{nd}}(M)^{\otimes n}$ is the universal tensor algebra with $\mathcal{O}_{\text{nd}}(M)^{\otimes 0} \equiv \mathbb{C}$, while the $*$ -operation is defined by $(\alpha_1 \otimes \dots \otimes \alpha_n)^* = (\bar{\alpha}_n \otimes \dots \otimes \bar{\alpha}_1)$ for $\alpha_1 \otimes \dots \otimes \alpha_n \in \mathcal{O}_{\text{nd}}(M)^{\otimes n}$ and then extended by linearity—here $\bar{\alpha}$ indicates complex conjugation. In addition $\mathcal{I}[\mathcal{O}_{\text{nd}}(M)]$ is the $*$ -ideal generated by elements of the form $[\alpha] \otimes [\beta] - [\beta] \otimes [\alpha] - i\tilde{G}_\perp([\alpha], [\beta])\mathbb{I}$, where $[\alpha], [\beta] \in \mathcal{O}_{\text{nd}}(M)$ while \tilde{G}_\perp is defined in Proposition 35 and \mathbb{I} is the identity of $\mathcal{T}[\mathcal{O}_{\text{nd}}(M)]$.

Remark 39. Notice that, with respect to the definition of $\mathcal{O}_t(M)$, the vector space $\mathcal{O}_{\text{nd}}(M)$ introduced in Definition 38 contains equivalence classes built out of forms $\alpha \in \Omega_c^k(M)$ such that $\delta\alpha = 0$ as well as $n\alpha = 0$. The last condition is sufficient and necessary to have a well-defined pairing among $\mathcal{O}_{\text{nd}}(M)$ and $\text{Sol}_{\text{nd}}(M)$. Indeed for all $A \in [A] \in \text{Sol}_{\text{nd}}(M)$ and for all $\alpha \in [\alpha] \in \mathcal{O}_{\text{nd}}(M)$, we have that (α, A) is well-defined being α compactly supported. Moreover, for all $\chi \in \Omega^{k-1}(M)$ and $\eta \in \Omega_{\text{nd}}^k(M)$ it holds

$$\begin{aligned} (\alpha, d\chi) &= (\delta\alpha, \chi) + (n\alpha, t\chi)_\partial = 0, \\ (\delta d\eta, A) &= (\eta, \delta dA) + (nd\eta, tA)_\partial - (t\eta, ndA)_\partial = 0. \end{aligned}$$

Notice that in the first equation we used the condition $n\alpha = 0$ since χ has no assigned boundary condition. This is opposite to the case of δd -tangential boundary conditions, where χ is required to satisfy $t\chi = 0$ —cf. Definition 28—and therefore α is not forced to satisfy any boundary condition. Actually, the constraints $\delta\alpha = 0$ and $n\alpha = 0$ are necessary to ensure gauge-invariance, namely $(\alpha, d\chi) = 0$ for all $\chi \in \Omega^k(M)$.

We study the structural properties of the algebra of observables. On account of its definition, it suffices to focus mainly on the properties of the generators $\mathcal{O}_t(M)$ and $\mathcal{O}_{nd}(M)$. In particular, in the next proposition we follow the rationale advocated in [8] proving that $\mathcal{O}_t(M)$ and $\mathcal{O}_{nd}(M)$ are *optimal*:

Proposition 40. *Let $\mathcal{O}_t(M), \mathcal{O}_{nd}(M)$ be as per Definition 38.*

Then the pairing (\cdot, \cdot) among k -forms—cf. Eq. (2)—descends to a well-defined pairing

$$\begin{aligned} \mathcal{O}_t(M) \times \text{Sol}_t(M) &\rightarrow \mathbb{C}, & [\alpha], [A] &\mapsto (\alpha, A) \\ \mathcal{O}_{nd}(M) \times \text{Sol}_{nd}(M) &\rightarrow \mathbb{C}, & [\alpha], [A] &\mapsto (\alpha, A). \end{aligned}$$

Moreover $\mathcal{O}_t(M)$ (resp. $\mathcal{O}_{nd}(M)$) is **optimal** with respect to $\text{Sol}_t(M)$ (resp. $\text{Sol}_{nd}(M)$), namely:

1. $\mathcal{O}_t(M)$ (resp. $\mathcal{O}_{nd}(M)$) is separating with respect to $\text{Sol}_t(M)$ (resp. $\text{Sol}_{nd}(M)$), that is

$$\forall [A \in \text{Sol}_t(M)]: ([\alpha], [A]) = 0 \quad \forall [\alpha] \in \mathcal{O}_t(M) \implies [A] = [0] \in \text{Sol}_t(M), \tag{47}$$

$$\forall [A] \in \text{Sol}_{nd}(M): ([\alpha], [A]) = 0 \quad \forall [\alpha] \in \mathcal{O}_{nd}(M) \implies [A] = [0] \in \text{Sol}_{nd}(M). \tag{48}$$

2. $\mathcal{O}_t(M)$ (resp. $\mathcal{O}_{nd}(M)$) is non-redundant with respect to $\text{Sol}_t(M)$ (resp. $\text{Sol}_{nd}(M)$), that is

$$\forall [\alpha] \in \mathcal{O}_t(M): ([\alpha], [A]) = 0 \quad \forall [A] \in \text{Sol}_t(M) \implies [\alpha] = [0] \in \mathcal{O}_t(M), \tag{49}$$

$$\forall [\alpha] \in \mathcal{O}_{nd}(M): ([\alpha], [A]) = 0 \quad \forall [A] \in \text{Sol}_{nd}(M) \implies [\alpha] = [0] \in \mathcal{O}_{nd}(M), \tag{50}$$

Proof. Mutatis mutandis, the proof is similar both for the δd -tangential and the δd -normal boundary conditions.

Proof for δd -tangential boundary conditions. As starting point observe that the pairing $([\alpha], [A]) := (\alpha, A)$ is well-defined. Indeed let us consider two representatives $A \in [A] \in \text{Sol}_t(M)$ and $\alpha \in [\alpha] \in \mathcal{O}_t(M)$. The pairing (α, A) is finite being $\text{supp}(\alpha)$ compact and there is no dependence on the choice of representative. As a matter of facts, if $d\chi \in d\Omega_t^{k-1}(M)$ and $\eta \in \Omega_{c,t}^k(M)$, it holds

$$\begin{aligned} (\alpha, d\chi) &= (\delta\alpha, \chi) + (n\alpha, t\chi)_\partial = 0, \\ (\delta d\eta, A) &= (\eta, \delta dA) + (t\eta, ndA)_\partial - (nd\eta, tA)_\partial = 0, \end{aligned}$$

where in the first equation we used that $t\chi = 0$ as well as $\delta\alpha = 0$, while in the second equation we used $\delta dA = 0$ as well as $tA = t\eta = 0$.

Having established that the pairing between the equivalence classes is well-defined we prove Eqs. (47)–(49) separately.

Proof of Equation (47). Assume $\exists [A] \in \text{Sol}_t(M)$ such that $([\alpha], [A]) = 0, \forall [\alpha] \in \mathcal{O}_t(M)$. Working at the level of representative, since $\alpha \in \Omega_{c,\delta}^k(M)$ we can choose $\alpha = \delta\beta$ with $\beta \in \Omega_c^{k+1}(M)$. As a consequence $0 = (\delta\beta, A) = (\beta, dA)$ where we used implicitly (6) and $tA = 0$. The arbitrariness of β and the

non-degeneracy of (\cdot, \cdot) entails $dA = 0$. Hence A individuates a de Rham cohomology class in $H_t^k(M)$, cf. “Appendix C”. Furthermore, $([\alpha], [A]) = 0$ entails $\langle [\alpha], [A] \rangle = 0$ where $\langle \cdot, \cdot \rangle$ denotes the pairing between $H_{k,c}(M)$ and $H_t^k(M)$ —cf. “Appendix C”. On account of Remark 54, it holds that $\langle \cdot, \cdot \rangle$ is non-degenerate and therefore $[A] = 0$.

Proof of Equation (49). Assume $\exists[\alpha] \in \mathcal{O}_t(M)$ such that $([\alpha], [A]) = 0 \forall [A] \in \text{Sol}_t(M)$. Working at the level of representatives, we can consider $A = G_{\parallel}\omega$ with $\omega \in \Omega_{c,\delta}^k(M)$, while $\alpha \in \Omega_{c,\delta}^k(M)$. Hence, in view of Proposition 20, $0 = (\alpha, A) = (\alpha, G_{\parallel}\omega) = -(G_{\parallel}\alpha, \omega)$. Choosing $\omega = \delta\beta$, $\beta \in \Omega_c^{k+1}(M)$ and using (6), it descends $(dG_{\parallel}\alpha, \beta) = 0$. Since β is arbitrary and the pairing is non-degenerate $dG_{\parallel}\alpha = 0$. Since $tG_{\parallel}\alpha = 0$, it turns out that $G_{\parallel}\alpha$ individuates an equivalence class $[G_{\parallel}\alpha] \in H_t^k(M)$. Using the same argument of the previous item, $(G_{\parallel}\alpha, \beta) = 0$ for all $\beta \in \Omega_{c,\delta}^k(M)$ entails that $G_{\parallel}\alpha = d\chi$ where $\chi \in \Omega_t^{k-1}(M)$. Therefore $[G_{\parallel}\alpha] = [0] \in \text{Sol}_t(M)$: Proposition 34 entails that $[\alpha] = [0]$.

Proof for δd -normal boundary conditions. The fact that the pairing $([\alpha], [A])$ is well-defined for $[\alpha] \in \mathcal{O}_{\text{nd}}(M)$ and $[A] \in \text{Sol}_{\text{nd}}(M)$ has already been discussed in Remark 39. It remains to discuss the proof of equations (48)–(50).

Proof of Equation (48). Let $[A] \in \text{Sol}_{\text{nd}}(M)$ be such that $([\alpha], [A]) = 0$ for all $[\alpha] \in \mathcal{O}_{\text{nd}}(M)$. This implies that $(\alpha, A) = 0$ for all $A \in [A]$ and for all $\alpha \in \Omega_{c,n,\delta}^k(M)$. Taking in particular $\alpha = \delta\beta$ with $\beta \in \Omega_{c,n}^k(M)$ it follows $(dA, \beta) = 0$. The non-degeneracy of (\cdot, \cdot) implies $dA = 0$, that is A defines an element in $H^k(M)$. The hypotheses on A implies that $\langle A, [\eta] \rangle = 0$ for all $[\eta] \in H_{k,c,n}(M)$. The results in “Appendix C”—cf. Remark 54—ensure that $A = d\chi$, therefore $[A] = [0] \in \text{Sol}_{\text{nd}}(M)$.

Proof of Equation (50). Let $[\alpha] \in \mathcal{O}_{\text{nd}}(M)$ be such that $([\alpha], [A]) = 0$ for all $[A] \in \text{Sol}_{\text{nd}}(M)$. This implies in particular that, choosing $\alpha \in [\alpha]$ and $A = G_{\perp}\beta$ with $\beta \in \Omega_{c,n,\delta}^k(M)$, $0 = (\alpha, G_{\perp}\beta) = -(G_{\perp}\alpha, \beta)$. With the same argument of the first statement it follows that $G_{\perp}\alpha = d\chi$ where $\chi \in \Omega^{k-1}(M)$ is such that $\text{nd}\chi = 0$. Therefore we found that $[G_{\perp}\alpha] = [0] \in \text{Sol}_{\text{nd}}(M)$: Proposition 34 implies that $[\alpha] = [0] \in \mathcal{O}_{\text{nd}}(M)$. □

The following corollary translates at the level of algebra of observables the degeneracy of the presymplectic spaces discussed in Proposition 35—cf. Remark 36. As a matter of facts, since \tilde{G}_{\parallel} (resp. \tilde{G}_{\perp}) can be degenerate, the algebra of observables $\mathcal{A}_t(M)$ (resp. $\mathcal{A}_{\text{nd}}(M)$) will possess a non-trivial center. In other words

Corollary 41. *If $d\Omega_{\text{sc},t}^{k-1}(M) \subset \Omega_{\text{sc}}^k(M) \cap d\Omega_t^{k-1}(M)$ is a strict inclusion, then the algebra $\mathcal{A}_t(M)$ is not semi-simple. Similarly, if $d\Omega_{\text{sc}}^{k-1}(M) \subset \Omega_{\text{sc}}^k(M) \cap d\Omega^{k-1}(M)$ is a strict inclusion, then the algebra $\mathcal{A}_{\text{nd}}(M)$ is not semi-simple.*

Proof. Since the proof is the same for either δd -tangential and δd -normal boundary conditions, we shall consider only the first case.

With reference to Remark 36, if $d\Omega_{\text{sc},t}^{k-1}(M) \subset \Omega_{\text{sc}}^k(M) \cap d\Omega_t^{k-1}(M)$ is a strict inclusion then there exists an element $[A] \in \text{Sol}_t^{\text{sc}}(M)$ such that $\sigma_t([A], [B]) = 0$ for all $[B] \in \text{Sol}_t^{\text{sc}}(M)$. On account of Proposition 34 there exists $[\alpha] \in \mathcal{O}_t(M)$ such that $[G_{\parallel}\alpha] = [A]$. Moreover, Proposition 35 ensures that $\widetilde{G}_{\parallel}([\alpha], [\beta]) = 0$ for all $[\beta] \in \mathcal{O}_t(M)$. It follows from Definition 38 that $[\alpha]$ belongs to the center of $\mathcal{A}_t(M)$, that is, $\mathcal{A}_t(M)$ is not semi-simple. \square

Remark 42. Corollary 41 has established that the algebra of observables possesses a non-trivial center. While from a mathematical viewpoint this feature might not appear of particular significance, it has far-reaching consequences from the physical viewpoint. Most notably, the existence of Abelian ideals was first observed in the study of gauge theories in [15] leading to an obstruction in the interpretation of these models in the language of locally covariant quantum field theories as introduced in [11]. This issue has been thoroughly studied in [5, 7, 35, 39] turning out to be an intrinsic feature of Abelian gauge theories on globally hyperbolic spacetimes with empty boundary. Corollary 41 shows that the same conclusions can be drawn when the underlying manifold possesses a timelike boundary.

Remark 43. To conclude this section, we observe that all algebras of observables that we have constructed obey to the so-called principle of *F-locality*. This concept was introduced for the first time in [29] and it asserts that, given any globally hyperbolic region $\mathcal{O} \subset \overset{\circ}{M}$ the restriction to \mathcal{O} of the algebra of observables built on M is $*$ -isomorphic to the one which one would construct intrinsically on $(\mathcal{O}, g|_{\mathcal{O}})$. In our approach, this property is implemented per construction and its proof is a direct generalization of the same argument given in [13]. For this reason, we omit the details.

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A. Existence of Fundamental Solutions on Ultrastatic Spacetimes

In this section, we prove that Assumption 16 is verified in a large class of globally hyperbolic spacetimes (M, g) with timelike boundary. These can be characterized by the following two additional hypotheses:

1. (M, g) is ultrastatic, that is, with reference to Eq. (1), we impose $\beta = 1$ and $h_\tau = h_0$ for all $\tau \in \mathbb{R}$. Hence ∂_τ is a timelike Killing vector field.
2. The Cauchy surface (Σ, h_0) with $\partial\Sigma \neq \emptyset$ is of *bounded geometry*, that is there exists an $(m - 1)$ -dimensional Riemannian manifold $(\widehat{\Sigma}, \widehat{h})$ of bounded geometry² such that $\Sigma \subset \widehat{\Sigma}$ and $\widehat{h}|_\Sigma = h_0$. In addition, $\partial\Sigma$ is a smooth submanifold of bounded geometry in $\widehat{\Sigma}$.

It is worth recalling that, whenever one considers a complex vector bundle E over (Σ, h_0) endowed with both a fiberwise Hermitian product $\langle \cdot, \cdot \rangle_E$ and a product preserving connection ∇^E , one can define a suitable notion of Sobolev spaces. Most notably, let $\Gamma_{\text{me}}(E)$ denote the equivalence classes of measurable sections of E . Then, for all $\ell \in \mathbb{N} \cup \{0\}$, we define

$$H^\ell(\Sigma; E) \equiv H^\ell(E) \doteq \{u \in \Gamma_{\text{me}}(E) \mid \nabla^j u \in L^2(\Sigma; E \otimes T^*\Sigma^{\otimes j}), j \leq \ell\}, \tag{51}$$

where we omitted the subscript E on ∇ for notational simplicity. The theory of these space has been thoroughly studied in the literature and for the case in hand we refer mainly to [23].

In the following, we study the existence of advanced and retarded fundamental solutions for the D’Alembert–de Rham wave operator $\square = d\delta + \delta d$ acting on k -forms. We use a method, first employed in [12] for the special case $k = 0$, based on a functional analytic tool known as boundary triples, see for example [4]. In order to be self-consistent, we will recall the necessary definitions and results from this paper, to which we refer for further details. The main ingredient is the following:

Definition 44. Let H be a separable Hilbert space over \mathbb{C} and let $S : D(S) \subset \mathsf{H} \rightarrow \mathsf{H}$ be a closed, symmetric, linear operator. A **boundary triple** for the adjoint operator S^* is a triple $(\mathfrak{h}, \gamma_0, \gamma_1)$ consisting of a separable Hilbert space \mathfrak{h} over \mathbb{C} and of two linear maps $\gamma_i : D(S^*) \rightarrow \mathfrak{h}$, $i = 0, 1$ such that

$$(S^* f | f')_{\mathsf{H}} - (f | S^* f')_{\mathsf{H}} = (\gamma_1 f | \gamma_0 f')_{\mathfrak{h}} - (\gamma_0 f | \gamma_1 f')_{\mathfrak{h}}, \quad \forall f, f' \in D(S^*),$$

In addition the map $\gamma : D(S^*) \rightarrow \mathfrak{h} \times \mathfrak{h}$ such that $f \mapsto (\gamma_0(f), \gamma_1(f))$ is surjective.

Boundary triples are a convenient tool to characterize the self-adjoint extensions of a large class of linear operators. Before discussing a few notable result, we need to define the following additional structures [4].

²Recall that a Riemannian manifold (N, h) with $\partial N = \emptyset$ is called of *bounded geometry* if the injectivity radius $r_{\text{inj}}(N) > 0$ and $\|\nabla^k R\|_{L^\infty(N)} < \infty$ for all $k \in \mathbb{N} \cup \{0\}$ where R is the scalar curvature while ∇ is the Levi-Civita connection associated to h .

Definition 45. Let H be a Hilbert space over \mathbb{C} . We call **(linear) relation** over H , a subspace $\Theta \subseteq H \times H$. The domain of a linear relation Θ is $\text{dom}(\Theta) \subseteq H$ defined by

$$\text{dom}(\Theta) := \{f \in H \mid \exists f' \in H, (f, f') \in \Theta\}.$$

We indicate respectively with adjoint Θ^* and inverse Θ^{-1} of Θ as the sets

$$\Theta^* \doteq \{(f, f') \in H \times H \mid (f', g) = (f, g') \forall (g, g') \in \Theta\}, \tag{52}$$

and

$$\Theta^{-1} \doteq \{(f, f') \in H \times H \mid (f', f) \in \Theta\}.$$

Consequently we say that Θ is self-adjoint if $\Theta = \Theta^*$

The proof of the following proposition can be found in [31].

Proposition 46. *Let $S : D(S) \subseteq H \rightarrow H$ be a closed, symmetric operator. Then S admits a boundary triple (h, γ_0, γ_1) if and only if it admits self-adjoint extensions. If Θ is a closed, densely defined linear relation on h , then $S_\Theta \doteq S^*|_{\ker(\gamma_1 - \Theta\gamma_0)}$ is a closed extension of S where $\ker(\gamma_1 - \Theta\gamma_0) \doteq \{\psi \in H \mid (\gamma_0\psi, \gamma_1\psi) \in \Theta\}$. In addition the map $\Theta \rightarrow S_\Theta$ is one-to-one and $S_\Theta^* = S_{\Theta^*}$. Hence there is a one-to-one correspondence between self-adjoint relations Θ and self-adjoint extensions of S .*

In order to apply these tools to the case in hand, first of all we need to recall that our goal is that of constructing advanced and retarded fundamental solutions for the D'Alembert–de Rham wave operator \square acting on k -forms. In other words, calling as $\Lambda^k T^* \mathring{M}$ the k -th exterior power of the cotangent bundle over \mathring{M} , $k \geq 1$, and with \boxtimes the external tensor product, we look for $G^\pm \in \Gamma_c(\Lambda^k T^* \mathring{M} \boxtimes \Lambda^k T^* \mathring{M})'$ such that

$$\square \circ G^\pm = G^\pm \circ \square = \text{Id} |_{\Gamma_c(\Lambda^k T^* \mathring{M} \boxtimes \Lambda^k T^* \mathring{M})},$$

while $\text{supp}(G^\pm(\omega)) \subseteq J^\pm(\text{supp}(\omega))$ for all $\omega \in \Gamma_c(\Lambda^k T^* \mathring{M})$ —cf. Assumption 16. Working at the level of integral kernels and setting $G^\pm(\tau - \tau', x, x') = \theta[\pm(\tau - \tau')]G(\tau - \tau', x, x')$, this amounts to solving the following distributional, initial value problem

$$(\square \otimes \mathbb{I})G = (\mathbb{I} \otimes \square)G = 0, \quad G|_{\tau=\tau'} = 0, \quad \partial_\tau G|_{\tau=\tau'} = \delta_{\text{diag}(\mathring{M})}. \tag{53}$$

where $\delta_{\text{diag}(\mathring{M})}$ stands for the bi-distribution yielding $\delta_{\text{diag}(\mathring{M})}(\omega_1 \boxtimes \omega_2) = (\omega_1, \omega_2)$ for all $\omega_1, \omega_2 \in \Gamma_c(\Lambda^k T^* \mathring{M})$. Since we have assumed that the underlying spacetime (M, g) is ultrastatic, Eq. (1) entails that, up to a global irrelevant sign depending on the convention used for the metric signature, [34]

$$\square = \partial_\tau^2 + S,$$

where S is a uniformly elliptic operator whose local form can be found in [34]. This entails that, in order to construct solutions of (53), we can follow the rationale outlined in [12].

To this end, we start by focusing our attention on S analyzing it within the framework of boundary triples. Our first observation consists of noticing, that being (M, g) globally hyperbolic, Theorem 1 ensures that M is diffeomorphic to $\mathbb{R} \times \Sigma$. Leaving implicit the identification $M \simeq \mathbb{R} \times \Sigma$ and recalling Theorem 1, let us indicate with $\iota_\tau : \Sigma \rightarrow M$ the (smooth one-parameter group of) embedding maps which realizes Σ at time τ as $\iota_\tau \Sigma = \{\tau\} \times \Sigma \doteq \Sigma_\tau$. It holds $\Sigma_\tau \simeq \Sigma_{\tau'}$ for all $\tau, \tau' \in \mathbb{R}$. It follows that, on account of Theorem 1, for all $\omega \in \Omega^k(M)$ and $\tau \in \mathbb{R}$, $\omega|_{\Sigma_\tau} \in \Gamma(\iota_\tau^* \Lambda^k T^* M)$. Here $\iota_\tau^*(\Lambda^k T^* M)$ denotes the pull-back bundle over $\Sigma_\tau \simeq \Sigma$ built out of $\Lambda^k T^* M$ via ι_τ —*cf.* [28]. Moreover, recalling Definition 5, it holds that $\omega|_{\Sigma_\tau}$ can be further decomposed as

$$\omega|_{\Sigma_\tau} := (\star_{\Sigma_\tau}^{-1} \iota_\tau^* \star_M) \omega \wedge d\tau + \iota_\tau^* \omega = n_{\Sigma_\tau} \omega \wedge d\tau + t_{\Sigma_\tau} \omega.$$

where $t_{\Sigma_\tau} \omega \in \Omega^k(\Sigma_\tau)$ while $n_{\Sigma_\tau} \omega \in \Omega^{k-1}(\Sigma_\tau)$ —*cf.* Definition 5. Barring the identification between Σ_τ and $\Sigma_{\tau'}$ the latter decomposition induces the isomorphisms

$$\Gamma(\iota_\tau^* \Lambda^k T^* M) \simeq \Omega^{k-1}(\Sigma) \oplus \Omega^k(\Sigma), \quad \omega \rightarrow (\omega_0 \oplus \omega_1) \tag{54}$$

$$\begin{aligned} \Omega^k(M) &\rightarrow C^\infty(\mathbb{R}, \Omega^{k-1}(\Sigma)) \oplus C^\infty(\mathbb{R}, \Omega^k(\Sigma)), \\ \omega &\rightarrow (\tau \mapsto t_{\Sigma_\tau} \omega) \oplus (\tau \mapsto n_{\Sigma_\tau} \omega). \end{aligned} \tag{55}$$

Furthermore a direct computation shows that, for all $\omega \in \Omega^k(M)$, it holds that

$$S\omega|_{\Sigma_\tau} = (-\Delta_{k-1} t_{\Sigma_\tau} \omega) \wedge d\tau - \Delta_k n_{\Sigma_\tau} \omega,$$

where Δ_k is the Laplace-Beltrami operator acting on k -forms, built out of h_0 .

Putting together all these data and working in the language of Definition 44, we can consider the following building blocks:

1. As Hilbert space we set

$$\mathbb{H} \equiv L^2(\Omega^{k-1}(\Sigma)) \oplus L^2(\Omega^k(\Sigma)),$$

where $L^2(\Omega^k(\Sigma))$ is the closure of $\Omega_c^k(\Sigma)$ with respect to the pairing $(\cdot, \cdot)_\Sigma$ between k -forms, i.e., $(\alpha, \beta)_\Sigma = \int_\Sigma \alpha \wedge \star_\Sigma \beta$ for all $\alpha, \beta \in \Omega_c^k(\Sigma)$.

2. We identify with a slight abuse of notation S with $(-\Delta_{k-1}) \oplus (-\Delta_k)$ where Δ_k is the Laplace-Beltrami operator built out of h_0 acting on k -forms.

Observe that S can be regarded as an Hermitian and densely defined operator on $H_0^2(\Lambda^{k-1} T^* \Sigma) \oplus H_0^2(\Lambda^k T^* \Sigma)$ where $H_0^2(\Lambda^k T^* \Sigma)$ is the closure of $\Omega_c^k(\Sigma)$ with respect to the $H^2(\Lambda^k T^* \Sigma)$ -norm—*cf.* Eq. (51) with $E \equiv \Lambda^k T^* \Sigma$. In this case, both the inner product and the connection are those induced from the underlying metric h_0 . Standard arguments entail that S is a closed symmetric operator on \mathbb{H} whose adjoint S^* is defined on the maximal domain $D(S^*) \doteq \{(\omega_0 \oplus \omega_1) \in \mathbb{H} \mid S(\omega_0 \oplus \omega_1) \in \mathbb{H}\}$, with $S^*(\omega_0 \oplus \omega_1) = S(\omega_0 \oplus \omega_1)$ for all $\omega_0 \oplus \omega_1 \in D(S^*)$. In addition the deficiency indices of S^* coincide. Therefore S admits self-adjoint extensions, which can be described as per Proposition 46. In order to realize explicitly a boundary triple for S^* , we start by observing that, since $\partial\Sigma \neq \emptyset$, we can introduce the standard trace map between Sobolev spaces, i.e., for every $\ell \geq \frac{1}{2}$ there exists a continuous surjective map $\text{res}_\ell :$

$H^\ell(\Lambda^k T^* \Sigma) \rightarrow H^{\ell-\frac{1}{2}}(\iota_{\partial\Sigma}^* \Lambda^k T^* \Sigma)$ whose action on $\Omega_c^k(\Sigma)$ coincides with the restriction to $\partial\Sigma$ for every ℓ —here $\iota_{\partial\Sigma}^* \Lambda^k T^* \Sigma$ denotes the pull-back bundle with respect to the inclusion $\iota_{\partial\Sigma}: \partial\Sigma \rightarrow \Sigma$. This last property allows us to better characterize the action of the restriction map, since, for every $\alpha \in \Omega_c^k(\Sigma)$ a straightforward computations shows that, for all $\ell \geq \frac{1}{2}$

$$\alpha|_{\partial\Sigma} = \text{res}_\ell \alpha = \alpha_0 + \alpha_1 \wedge dx,$$

where, up to an irrelevant isomorphism, we can identify $\alpha_0 \equiv t_{\partial\Sigma} \alpha$ and $\alpha_1 \equiv n_{\partial\Sigma} \alpha$ —cf. Definition 5. Here, for every $p \in \partial\Sigma$, dx is the basis element of $T_p^* M$ such that $dx(\nu_p) = 1$ while $dx(X)|_p = 0$ for all smooth vector fields $X \in \Gamma(T\Sigma)$ tangent to $\partial\Sigma$ —here ν_p is the outward pointing, unit vector normal to $\partial\Sigma$ at p . With this observation in mind and following mutatis mutandis, the same analysis of [12] for the scalar case, we can construct the following boundary triple for S^*

- $\mathfrak{h} = \mathfrak{h}_0 \oplus \mathfrak{h}_1$ where $\mathfrak{h}_0 \doteq L^2(\Omega^{k-2}(\partial\Sigma)) \oplus L^2(\Omega^{k-1}(\partial\Sigma))$ while $\mathfrak{h}_1 = L^2(\Omega^{k-1}(\partial\Sigma)) \oplus L^2(\Omega^k(\partial\Sigma))$;
- the map $\gamma_0 : D(S^*) \rightarrow \mathfrak{h}$ such that, for all $\omega_0 \oplus \omega_1 \in D(S^*)$,

$$\gamma_0(\omega_0 \oplus \omega_1) = (n_{\partial\Sigma} \omega_0 \oplus t_{\partial\Sigma} \omega_0) \oplus (n_{\partial\Sigma} \omega_1 \oplus t_{\partial\Sigma} \omega_1). \tag{56}$$

- the map $\gamma_1 : D(S^*) \rightarrow \mathfrak{h}$ such that, for all $\omega_0 \oplus \omega_1 \in D(S^*)$,

$$\gamma_1(\omega_0 \oplus \omega_1) = (t_{\partial\Sigma} \delta_\Sigma \omega_0 \oplus n_{\partial\Sigma} d_\Sigma \omega_0) \oplus (t_{\partial\Sigma} \delta_\Sigma \omega_1 \oplus n_{\partial\Sigma} d_\Sigma \omega_1), \tag{57}$$

where with a slight abuse of notation we denote still with d_Σ and δ_Σ the extension to the space of square-integrable k -forms of the action of the differential and of the codifferential on $\Omega_c^k(\Sigma)$.

In view of Proposition 46, we can follow slavishly the proof of [12, Th. 30] to infer the following statement:

Theorem 47. *Let (M, g) be an ultrastatic and globally hyperbolic spacetime with timelike boundary and of bounded geometry. Let $(\mathfrak{h}, \gamma_0, \gamma_1)$ be the boundary triple built as per Eqs. (56) and (57) associated to the operator S^* . Let Θ be a self-adjoint relation on \mathfrak{h} as per Definition 45 and let $S_\Theta \doteq S^*|_{D(S_\Theta)}$ where $D(S_\Theta) = \ker(\gamma_1 - \Theta\gamma_0)$, cf. Proposition 46. If the spectrum of S_Θ is bounded from below, then there exists unique advanced and retarded Green’s operator G_Θ^\pm associated to $\partial_\tau^2 + S_\Theta$. They are completely determined in terms of the bidistributions $G_\Theta^\pm = \theta[\pm(\tau - \tau')]G_\Theta$ where $G_\Theta \in \Gamma_c(\Lambda^k T^* \overset{\circ}{M} \boxtimes \Lambda^k T^* \overset{\circ}{M})'$ is such that for $\omega_1, \omega_2 \in \Gamma_c(\Lambda^k T^* \overset{\circ}{M})$,*

$$G_\Theta(\omega_1, \omega_2) = \int_{\mathbb{R}^2} \left(\omega_1|_\Sigma, S_{k,\Theta}^{-\frac{1}{2}} \sin \left(S_{k,\Theta}^{\frac{1}{2}}(\tau - \tau') \right) \omega_2|_\Sigma \right)_\Sigma d\tau d\tau',$$

where $(\cdot, \cdot)_\Sigma$ stands for the pairing between k -forms and where ω_2 identifies an element in $D(S_\Theta)$ via the identifications (55). Moreover it holds that

$$G_\Theta^\pm \omega \in \ker(\gamma_1 - \Theta\gamma_0), \quad \forall \omega \in \Gamma_c(\Lambda^k T^* \overset{\circ}{M}). \tag{58}$$

The last step consists of proving that the boundary conditions introduced in Definition 12 fall within the class considered in Theorem 47. In the following

proposition, we adopt for simplicity the notation $t = t_{\partial\Sigma}$, $n = n_{\partial\Sigma}$, $nd = n_{\partial\Sigma}d_{\partial\Sigma}$, $t\delta = t_{\partial\Sigma}\delta_{\Sigma}$.

Proposition 48. *The following relations on \mathfrak{h} are self-adjoint:*

$$\Theta_{\parallel} \doteq \{(n\omega_0 \oplus 0 \oplus n\omega_1 \oplus 0; 0 \oplus nd\omega_0 \oplus 0 \oplus nd\omega_1) \mid \omega_0 \oplus \omega_1 \in D(S^*)\} \tag{59}$$

$$\Theta_{\perp} \doteq \{(0 \oplus t\omega_0 \oplus 0 \oplus t\omega_1; t\delta\omega_0 \oplus 0 \oplus t\delta\omega_1 \oplus 0) \mid \omega_0 \oplus \omega_1 \in D(S^*)\} \tag{60}$$

$$\Theta_{f_{\parallel}} \doteq \{(n\omega_0 \oplus 0 \oplus n\omega_1 \oplus 0; fn\omega_0 \oplus nd\omega_0 \oplus fn\omega_1 \oplus nd\omega_1) \mid \omega_0 \oplus \omega_1 \in D(S^*)\},$$

$$f \in C^{\infty}(\partial\Sigma), f \geq 0. \tag{61}$$

$$\Theta_{f_{\perp}} \doteq \{(0 \oplus t\omega_0 \oplus 0 \oplus t\omega_1; t\delta\omega_0 \oplus ft\omega_0 \oplus t\delta\omega_1 \oplus ft\omega_1) \mid \omega_0 \oplus \omega_1 \in D(S^*)\},$$

$$f \in C^{\infty}(\partial\Sigma), f \leq 0. \tag{62}$$

Moreover the self-adjoint extension $S_{\Theta_{\sharp}}$ for $\sharp \in \{\parallel, \perp, f_{\parallel}, f_{\perp}\}$ abides to the hypotheses of Theorem 47. The associated propagators G_{\sharp} , $\sharp \in \{\parallel, \perp, f_{\parallel}, f_{\perp}\}$, obey the boundary conditions as per Definition 12.

Proof. We show that $\Theta_{\parallel}, \Theta_{\perp}, \Theta_{f_{\parallel}}, \Theta_{f_{\perp}}$ are self-adjoint relations as per Definition 45. Since the proofs for the different cases are very similar we shall consider only Θ_{\parallel} . A short computation shows that $\Theta_{\parallel} \subseteq \Theta_{\parallel}^*$. We prove the converse inclusion. Let $\underline{\alpha} := (\alpha_1 \oplus \dots \alpha_4; \alpha_5 \oplus \dots \alpha_8) \in \Theta_{\parallel}^*$. Considering Eq. (52) we find

$$(n\omega_0, \alpha_5) + (n\omega_1, \alpha_7) = (nd\omega_0, \alpha_2) + (\alpha_4, nd\omega_1, \alpha_4), \quad \forall \omega_0 \oplus \omega_1 \in D(S^*). \tag{63}$$

Choosing ω_1 and $n\omega_0 = 0$ —this does not affect the value $nd\omega_0$ on account of Remark 7—it follows that $(\alpha_2, nd\omega_0) = 0$ for all $\omega_0 \in \Omega_{C,n}^{k-1}(\Sigma)$. Since nd is surjective it follows that $\alpha_2 = 0$. With a similar argument $\alpha_5 = 0$ as well as $\alpha_2 = 0, \alpha_4 = 0$. Finally, on account of Remark 7 there exists $\omega_0 \oplus \omega_1 \in D(S^*)$ such that

$$n\omega_0 = \alpha_1, \quad n\omega_1 = \alpha_3, \quad nd\omega_0 = \alpha_6, \quad nd\omega_1 = \alpha_8.$$

It follows that $\alpha \in \Theta_{\parallel}$, that is, $\Theta_{\parallel} = \Theta_{\parallel}^*$.

In addition $S_{\Theta_{\sharp}}$ is positive definite for $\sharp \in \{\parallel, \perp, f_{\parallel}, f_{\perp}\}$. It descends from the following equality, which holds for all $\omega_0 \otimes \omega_1 \in D(S^*)$:

$$(\omega_0 \oplus \omega_1, S_{\Theta_{\sharp}}(\omega_0 \oplus \omega_1))_{\mathfrak{H}} = \sum_{j=1}^2 [\|d\omega_j\|^2 + \|\delta\omega_j\|^2 + (n\omega_j, t\delta\omega_j) - (t\omega_j, nd\omega_j)],$$

where the last two terms are nonnegative because of the boundary conditions and of the hypothesis on the sign of f . Therefore we can apply Theorem 47.

Finally we should prove that the propagators $G_{\Theta_{\sharp}}^{\pm}$ associated with the relations Θ_{\sharp} coincide with the propagators G_{\sharp}^{\pm} introduced in Theorem 16. The fulfilment of the appropriate boundary conditions is a consequence of Lemma 50. \square

Remark 49. It is worth mentioning that, although we have only considered test sections of compact support in \hat{M} , such assumption can be relaxed allowing the support to intersect ∂M . In order to prove that this operation is legitimate,

a rather natural strategy consists of realizing that the boundary conditions here considered fall in the (generalization of) those of Robin type. These were considered in [21] for the case of a real scalar field on an asymptotically anti de Sitter spacetime where, in between many results, it was proven the explicit form of the wavefront set of the advanced and retarded fundamental solutions. In particular, it was shown that two points lie in the wave front set either if they are connected directly by a light geodesic or by one which is reflected at the boundary. A direct inspection of their approach suggests that the same result holds true if one considers also static globally hyperbolic spacetimes with timelike boundary and vector valued fields. A detailed proof of this statement would require a lengthy paper on its own, and thus, this question will be addressed explicitly in a future work.

B. An Explicit Decomposition

Lemma 50. *Let $M = \mathbb{R} \times \Sigma$ be a globally hyperbolic spacetime—cf. Theorem 1. Moreover, for all $\tau \in \mathbb{R}$, let $t_{\Sigma_\tau} : \Omega^k(M) \rightarrow \Omega^k(\Sigma_\tau)$, $n_{\Sigma_\tau} : \Omega^k(\Sigma_\tau) \rightarrow \Omega^{k-1}(\Sigma)$ be the tangential and normal maps on $\Sigma_\tau \doteq \{\tau\} \times \Sigma$, where $M = \mathbb{R} \times \Sigma$ —cf. Definition 5. Moreover, let $t_{\partial\Sigma_\tau} : \Omega^k(\Sigma_\tau) \rightarrow \Omega^k(\partial\Sigma_\tau)$ and let $n_{\partial\Sigma_\tau} : \Omega^k(\Sigma_\tau) \rightarrow \Omega^{k-1}(\partial\Sigma_\tau)$ be the tangential and normal maps on $\partial\Sigma_\tau \doteq \{\tau\} \times \partial\Sigma$. Let $f \in C^\infty(\partial\Sigma)$ and set $f_\tau \doteq f|_{\partial\Sigma_\tau}$. Then for $\sharp \in \{D, \parallel, \perp, f_\parallel, f_\perp\}$ it holds*

$$\omega \in \Omega_\sharp^k(M) \iff t_{\Sigma_\tau} \omega \in \Omega_\sharp^k(\Sigma_\tau), n_{\Sigma_\tau} \omega \in \Omega_\sharp^{k-1}(\Sigma_\tau), \quad \forall \tau \in \mathbb{R}. \quad (64)$$

More precisely this entails that

$$\begin{aligned} \omega \in \ker t_{\partial M} \cap \ker n_{\partial M} &\iff \\ t_{\Sigma_\tau} \omega, n_{\Sigma_\tau} \omega &\in \ker t_{\partial\Sigma_\tau} \cap \ker n_{\partial\Sigma_\tau}, \forall \tau \in \mathbb{R}; \\ \omega \in \ker n_{\partial M} \cap \ker n_{\partial M} d &\iff \\ t_{\Sigma_\tau} \omega, n_{\Sigma_\tau} \omega &\in \ker n_{\partial\Sigma_\tau} \cap \ker n_{\partial\Sigma_\tau} d_{\Sigma_\tau}, \forall \tau \in \mathbb{R}; \\ \omega \in \ker t_{\partial M} \cap \ker t_{\partial M} \delta &\iff \\ t_{\Sigma_\tau} \omega, n_{\Sigma_\tau} \omega &\in \ker t_{\partial\Sigma_\tau} \cap \ker t_{\partial\Sigma_\tau} \delta_{\Sigma_\tau}, \forall \tau \in \mathbb{R}; \\ \omega \in \ker n_{\partial M} \cap \ker(n_{\partial M} d - f t_{\partial M}) &\iff \\ t_{\Sigma_\tau} \omega, n_{\Sigma_\tau} \omega &\in \ker n_{\partial\Sigma_\tau} \cap \ker(n_{\partial\Sigma_\tau} d_{\Sigma_\tau} - f_t t_{\partial\Sigma_\tau}), \forall \tau \in \mathbb{R}; \\ \omega \in \ker t_{\partial M} \cap \ker(t_{\partial M} \delta - f n_{\partial M}) &\iff \\ t_{\Sigma_\tau} \omega, n_{\Sigma_\tau} \omega &\in \ker t_{\partial\Sigma_\tau} \cap \ker(t_{\partial\Sigma_\tau} \delta_{\Sigma_\tau} - f_t n_{\partial\Sigma_\tau}), \forall \tau \in \mathbb{R}. \end{aligned}$$

Proof. The equivalence (64) is shown for \perp -boundary condition. The proof for \parallel -boundary conditions follows per duality—cf. (13)—while the one for D -, f_\parallel -, f_\perp -boundary conditions can be carried out in a similar way.

On account of Theorem 1 it holds that, for all $\tau \in \mathbb{R}$, we can decompose any $\omega \in \Omega^k(M)$ as follows:

$$\omega|_{\Sigma_\tau} = t_{\Sigma_\tau} \omega + n_{\Sigma_\tau} \omega \wedge \beta^{\frac{1}{2}} d\tau.$$

Notice that, being M isometric to $\mathbb{R} \times \Sigma$, it holds that $\tau \rightarrow t_{\Sigma_\tau} \omega \in C^\infty(\mathbb{R}, \Omega^k(\Sigma))$ while $\tau \rightarrow n_{\Sigma_\tau} \omega \in C^\infty(\mathbb{R}, \Omega^{k-1}(\Sigma))$. Here we have implicitly identified $\Sigma \simeq \Sigma_\tau$.

A similar decomposition holds near the boundary of Σ_τ . Indeed for all relatively compact open neighborhood $U_{\partial\Sigma} \subseteq \partial\Sigma$ of $\partial\Sigma$, we consider a neighborhood $U \subseteq \Sigma$ of the form $U = [0, \epsilon_\tau) \times U_{\partial\Sigma}$ built out of the exponential map of M . Let $U_x \doteq \{x\} \times U_{\partial\Sigma}$ for $x \in [0, \epsilon_\tau)$ and let t_{U_x}, n_{U_x} be the corresponding tangential and normal maps—*cf.* Definition 5. With this definition we can always split $t_{\Sigma_\tau} \omega$ and $n_{\Sigma_\tau} \omega$ as follows:

$$\begin{aligned} \omega|_{\{\tau\} \times U_x} &= t_{U_x} t_{\Sigma_\tau} \omega + n_{U_x} t_{\Sigma_\tau} \omega \wedge N^{\frac{1}{2}} dx + t_{U_x} n_{\Sigma_\tau} \omega \wedge \beta^{\frac{1}{2}} d\tau \\ &\quad + n_{U_x} n_{\Sigma_\tau} \omega \wedge N^{\frac{1}{2}} dx \wedge \beta^{\frac{1}{2}} d\tau, \end{aligned} \tag{65}$$

where $N = g(\partial_x, \partial_x)$. Since $U_{\partial\Sigma}$ is relatively compact it follows that $(\tau, x) \rightarrow t_{U_x} t_{\Sigma_\tau} \omega \in C^\infty(\mathbb{R} \times [0, \epsilon), \Omega^k(\partial\Sigma))$ and similarly $t_{U_x} n_{\Sigma_\tau} \omega, n_{U_x} t_{\Sigma_\tau} \omega$ and $n_{U_x} n_{\Sigma_\tau} \omega$. Once again we have implicitly identified $U_{\partial\Sigma} \simeq \{x\} \times U_{\partial\Sigma} = U_x$. According to this splitting it holds

$$\begin{aligned} t_{\partial M} \omega|_{\{\tau\} \times U_{\partial\Sigma}} &= t_{U_x} t_{\Sigma_\tau} \omega|_{x=0} + t_{U_x} n_{\Sigma_\tau} \omega|_{x=0} \wedge \beta^{\frac{1}{2}}|_{\partial M} d\tau \\ &= t_{\partial\Sigma_\tau} t_{\Sigma_\tau} \omega + t_{\partial\Sigma_\tau} n_{\Sigma_\tau} \omega \wedge \beta^{\frac{1}{2}}|_{\partial M} d\tau, \\ n_{\partial M} \omega|_{\{\tau\} \times U_{\partial\Sigma}} &= n_{U_x} t_{\Sigma_\tau} \omega|_{x=0} + n_{U_x} n_{\Sigma_\tau} \omega|_{x=0} \wedge \beta^{\frac{1}{2}}|_{\partial M} d\tau \\ &= n_{\partial\Sigma_\tau} t_{\Sigma_\tau} \omega + n_{\partial\Sigma_\tau} n_{\Sigma_\tau} \omega \wedge \beta^{\frac{1}{2}}|_{\partial M} d\tau. \end{aligned}$$

It follows that

$$\begin{aligned} n_{\partial M} \omega = 0 &\iff n_{\partial\Sigma_\tau} n_{\Sigma_\tau} \omega = 0, \quad n_{\partial\Sigma_\tau} t_{\Sigma_\tau} \omega = 0, \\ t_{\partial M} \omega = 0 &\iff t_{\partial\Sigma_\tau} n_{\Sigma_\tau} \omega = 0, \quad t_{\partial\Sigma_\tau} t_{\Sigma_\tau} \omega = 0. \end{aligned} \tag{66}$$

This proves the statement for Dirichlet boundary conditions. Assuming now $n_{\partial M} \omega = 0$, a similar computation yields

$$\begin{aligned} nd_{\omega}|_{\{\tau\} \times U_{\partial\Sigma}} &= N^{-\frac{1}{2}} \partial_x t_{U_x} t_{\Sigma_\tau} \omega|_{x=0} + N^{-\frac{1}{2}} d_{\partial\Sigma} \left(N^{\frac{1}{2}} n_{U_x} t_{\Sigma_\tau} \omega \right)|_{x=0} \\ &\quad + N^{-\frac{1}{2}} \partial_x \left(\beta^{\frac{1}{2}} t_{U_x} n_{\Sigma_\tau} \omega \right)|_{x=0} \wedge d\tau \\ &\quad + N^{-\frac{1}{2}} d_{\partial\Sigma} \left(N^{\frac{1}{2}} \beta^{\frac{1}{2}} n_{U_x} n_{\Sigma_\tau} \omega \right)|_{x=0} \wedge d\tau \\ &= N^{-\frac{1}{2}} \partial_x t_{U_x} t_{\Sigma_\tau} \omega|_{x=0} + N^{-\frac{1}{2}} \partial_x (t_{U_x} n_{\Sigma_\tau} \omega)|_{x=0} \wedge \beta^{\frac{1}{2}} d\tau, \end{aligned}$$

where in the second equality we used the assumption $n_{\partial\Sigma_\tau} n_{\Sigma_\tau} \omega = 0, n_{\partial\Sigma_\tau} t_{\Sigma_\tau} \omega = 0$. Notice that the terms where either N or β are differentiated do not appear for the same reason.

On account of the hypotheses $n_{\partial\Sigma_\tau} n_{\Sigma_\tau} \omega = 0, n_{\partial\Sigma_\tau} t_{\Sigma_\tau} \omega = 0$ it follows that

$$\begin{aligned} nd_{\partial\Sigma_\tau} n_{\Sigma_\tau} \omega|_{\{\tau\} \times U_{\partial\Sigma}} &= N^{-\frac{1}{2}} \partial_x (t_{U_x} n_{\Sigma_\tau} \omega)|_{x=0} \wedge \beta^{\frac{1}{2}} d\tau, \\ nd_{\partial\Sigma_\tau} t_{\Sigma_\tau} \omega|_{\{\tau\} \times U_{\partial\Sigma}} &= N^{-\frac{1}{2}} \partial_x t_{U_x} t_{\Sigma_\tau} \omega|_{x=0}. \end{aligned}$$

It descends that $n_{\partial M}d\omega = 0$ if and only if $nd_{\partial\Sigma_\tau}n_{\Sigma_t}\omega = 0$ and $nd_{\partial\Sigma_\tau}t_{\Sigma_t}\omega|_{\{\tau\}\times U_{\partial\Sigma}} = 0$. Together with Eq. (66) this shows the thesis for \perp boundary conditions. \square

C. Relative de Rham Cohomology

In this appendix we summarize a few definitions and results concerning de Rham cohomology and Poincaré duality, especially when the underlying manifold has a non-empty boundary. A reader interested in more details can refer to [10, 36].

For the purpose of this section M refers to a smooth, oriented manifold of dimension $\dim M = m$ with a smooth boundary ∂M , together with an embedding map $\iota_{\partial M} : M \rightarrow \partial M$. In addition ∂M comes endowed with orientation induced from M via $\iota_{\partial M}$. We recall that $\Omega^\bullet(M)$ stands for the de Rham cochain complex which in degree $k \in \mathbb{N} \cup \{0\}$ corresponds to $\Omega^k(M)$, the space of smooth k -forms. Observe that we shall need to work also with compactly supported forms and all definitions can be adapted accordingly. To indicate this specific choice, we shall use a subscript c , e.g., $\Omega_c^\bullet(M)$. We denote instead the k -th de Rham cohomology group of M as

$$H^k(M) \doteq \frac{\ker(d_k : \Omega^k(M) \rightarrow \Omega^{k+1}(M))}{\text{Im}(d_{k-1} : \Omega^{k-1}(M) \rightarrow \Omega^k(M))},$$

where we introduce the subscript k to highlight that the differential operator d acts on k -forms. Equations (4) and (5b) entail that we can define $\Omega_t^\bullet(M)$, the subcomplex of $\Omega^\bullet(M)$, whose degree k corresponds to $\Omega_t^k(M) \subset \Omega^k(M)$. The associated de Rham cohomology groups will be denoted as $H_t^k(M)$, $k \in \mathbb{N} \cup \{0\}$.

Similarly we can work with the codifferential δ in place of d , hence identifying a chain complex $\Omega^\bullet(M)$ which in degree $k \in \mathbb{N} \cup \{0\}$ corresponds to $\Omega^k(M)$, the space of smooth k -forms. The associated k -th homology groups will be denoted with

$$H_k(M) \doteq \frac{\ker(\delta_k : \Omega^k(M) \rightarrow \Omega^{k-1}(M))}{\text{Im}(\delta_{k+1} : \Omega^{k+1}(M) \rightarrow \Omega^k(M))}.$$

Equations (4) and (5b) entail that we can define the $\Omega_n^\bullet(M)$ (*resp.* $\Omega_c^\bullet(M)$, $\Omega_{c,n}^\bullet(M)$), the subcomplex of $\Omega^\bullet(M)$, whose degree k corresponds to $\Omega_n^k(M) \subset \Omega^k(M)$ (*resp.* $\Omega_c^k(M)$, $\Omega_{c,n}^k(M) \subseteq \Omega^k(M)$). The associated homology groups will be denoted as $H_{k,n}(M)$ (*resp.* $H_{k,c}(M)$, $H_{k,c,n}(M)$), $k \in \mathbb{N} \cup \{0\}$. Observe that, in view of its definition and on account of Eq. (5), the Hodge operator induces an isomorphism $H^k(M) \simeq H_{m-k}(M)$ which is realized as $H^k(M) \ni [\alpha] \mapsto [\star\alpha] \in H_{m-k}(M)$. Similarly, on account of Eq. (5b), it holds $H_t^k(M) \simeq H_{m-k,n}(M)$ and $H_{c,t}^k(M) \simeq H_{m-k,c,n}(M)$.

As last ingredient, we introduce the notion of relative cohomology, *cf.* [10]. We start by defining the relative de Rham cochain complex $\Omega^\bullet(M; \partial M)$ which in degree $k \in \mathbb{N} \cup \{0\}$ corresponds to

$$\Omega^k(M; \partial M) \doteq \Omega^k(M) \oplus \Omega^{k-1}(\partial M),$$

endowed with the differential operator $\underline{d}_k : \Omega^k(M; \partial M) \rightarrow \Omega^{k+1}(M; \partial M)$ such that for any $(\omega, \theta) \in \Omega^k(M; \partial M)$

$$\underline{d}_k(\omega, \theta) = (d_k\omega, t\omega - d_{k-1}\theta). \tag{67}$$

Per construction, each $\Omega^k(M; \partial M)$ comes endowed naturally with the projections on each of the defining components, namely $\pi_1 : \Omega^k(M; \partial M) \rightarrow \Omega^k(M)$ and $\pi_2 : \Omega^k(M; \partial M) \rightarrow \Omega^k(\partial M)$. With a slight abuse of notation we make no explicit reference to k in the symbol of these maps, since the domain of definition will always be clear from the context. The relative cohomology groups associated to \underline{d}_k will be denoted instead as $H^k(M; \partial M)$ and the following proposition characterizes the relation with the standard de Rham cohomology groups built on M and on ∂M , cf. [10, Prop. 6.49]:

Proposition 51. *Under the geometric assumptions specified at the beginning of the section, there exists an exact sequence*

$$\dots \rightarrow H^k(M; \partial M) \xrightarrow{\pi_{1,*}} H^k(M) \xrightarrow{t_*} H^k(\partial M) \xrightarrow{\pi_{2,*}} H^{k+1}(M; \partial M) \rightarrow \dots, \tag{68}$$

where $\pi_{1,*}$, $\pi_{2,*}$ and t_* indicate the natural counterpart of the maps π_1 , π_2 and t at the level of cohomology groups.

The relevance of the relative cohomology groups in our analysis is highlighted by the following statement, of which we give a concise proof:

Proposition 52. *Under the geometric assumptions specified at the beginning of the section, there exists an isomorphism between $H_t^k(M)$ and $H^k(M; \partial M)$ for all $k \in \mathbb{N} \cup \{0\}$.*

Proof. Consider $\omega \in \Omega_t^k(M) \cap \ker d$ and let $(\omega, 0) \in \Omega^k(M; \partial M)$, $k \in \mathbb{N} \cup \{0\}$. Equation (67) entails

$$\underline{d}_k(\omega, 0) = (d_k\omega, t\omega) = (0, 0).$$

At the same time, if $\omega = d_{k-1}\beta$ with $\beta \in \Omega_t^{k-1}(M)$, then $(d_{k-1}\beta, 0) = \underline{d}_{k-1}(\beta, 0)$. Hence the embedding $\omega \mapsto (\omega, 0)$ identifies a map $\rho : H_t^k(M) \rightarrow H^k(M; \partial M)$ such that $\rho([\omega]) \doteq [(\omega, 0)]$.

To conclude, we need to prove that ρ is surjective and injective. Let thus $[(\omega', \theta)] \in H^k(M; \partial M)$. It holds that $d_k\omega' = 0$ and $t\omega' - d_{k-1}\theta = 0$. Recalling that $t : \Omega^k(M) \rightarrow \Omega^k(\partial M)$ is surjective—cf. Remark 7—for all values of $k \in \mathbb{N} \cup \{0\}$, there must exist $\eta \in \Omega^{k-1}(M)$ such that $t\eta = \theta$. Let $\omega \doteq \omega' - d_{k-1}\eta$. On account of (5b) $\omega \in \Omega_t^k(M) \cap \ker d_k$ and $(\omega, 0)$ is a representative of $[(\omega', \theta)]$ which entails that ρ is surjective.

Let $[\omega] \in H^k(M)$ be such that $\rho[\omega] = [0] \in H^k(M; \partial M)$. This implies that there exists $\beta \in \Omega^{k-1}(M)$, $\theta \in \Omega^{k-2}(\partial M)$ such that

$$(\omega, 0) = \underline{d}_{k-1}(\beta, \theta) = (d_{k-1}\beta, t\beta - d_{k-2}\theta).$$

Let $\eta \in \Omega^{k-2}(M)$ be such that $t\eta + \theta = 0$. It follows that

$$(\omega, 0) = \underline{d}_{k-1}((\beta, \theta) + \underline{d}_{k-2}(\eta, 0)) = \underline{d}_{k-1}(\beta + d_{k-2}\eta, 0).$$

This entails that $\omega = d_{k-1}(\beta + d_{k-2}\eta)$ where $t(\beta + d_{k-2}\eta) = 0$. It follows that $[\omega] = 0$ that is ρ is injective. \square

To conclude, we recall a notable result concerning the relative cohomology, which is a specialization to the case in hand of the Poincaré–Lefschetz duality, an account of which can be found in [33]:

Proposition 53. *Under the geometric assumptions specified at the beginning of the section and assuming in addition that M admits a finite good cover, it holds that, for all $k \in \mathbb{N} \cup \{0\}$*

$$H^{m-k}(M; \partial M) \simeq H_c^k(M)^*, \quad [\alpha] \rightarrow \left(H_c^k(M) \ni [\eta] \mapsto \int_M \bar{\alpha} \wedge \eta \in \mathbb{C} \right). \quad (69)$$

where $m = \dim M$ and where on the right hand side we consider the dual of the $(m - k)$ -th cohomology group built out compactly supported forms.

Remark 54. On account of Propositions 52, 53 and of the isomorphisms $H_{(c)}^k(M) \simeq H_{(c)}^{m-k}(M)$ the following are isomorphisms:

$$H_t^k(M) \simeq H_c^{m-k}(M)^* \simeq H_{k,c}(M)^*, \quad H^k(M) \simeq H_{k,c,n}(M)^*. \quad (70)$$

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