J. Geom. 79 (2004) 75 – 88 0047–2468/04/020075 – 14 © Birkhauser Verlag, Basel, 2004 ¨ DOI 10.1007/s00022-003-1551-z

Journal of Geometry

On conformally flat contact metric manifolds

Florence Gouli-Andreou and Niki Tsolakidou

Abstract. In the present paper we classify the conformally flat contact metric manifolds of dimension $2n + 1$ $(n > 1)$ satisfying $R(\cdot, \xi)\xi = -k\phi^2$. We prove that these manifolds are Sasakian of constant curvature 1.

Mathematics Subject Classification (2000): 53C15, 53C25. *Key words:* Contact metric manifold, conformally flat Riemannian manifold.

1. Introduction

Let M^{2n+1} be a $(2n+1)$ -dimensional contact metric manifold and (ϕ, ξ, η, g) be its contact metric structure. If the characteristic vector field ξ is Killing, then M^{2n+1} is called a K-contact Riemannian manifold. Moreover if the structure is normal, M^{2n+1} is said to be Sasakian. Every Sasakian manifold is K-contact but the opposite is true only for the dimension 3. We denote by ∇ , R and Q the Levi-Civita connection, the Riemannian curvature and the Ricci operator on M^{2n+1} respectively. J. Davidov and O. Mushkarov [5] and S.R. Deng [6] gave results which show that there exist K -contact manifolds with $Q\phi = \phi Q$ which are not Sasakian. S. Tanno [11], generalizing the corresponding result of M. Okumura [8] for Sasakian manifolds, proved that every conformally flat K-contact manifold is a space form. Z. Olszak in [9] proved that any contact metric manifold of constant sectional curvature and of dimension \geq 5 has the sectional curvature equal to 1 and is a Sasakian manifold. D.E. Blair and Th. Koufogiorgos proved in [4] that a conformally flat contact metric manifold M^{2n+1} with $Q\phi = \phi Q$ is of constant curvature 1 if $n > 1$ and 0 or 1 if $n = 1$. K. Bang in [1] proved that in dimension greater than 3, there are no conformally flat contact metric manifolds with $\ell = 0$, $(\ell := R(\cdot, \xi)\xi)$. The first author and Ph.J. Xenos proved in [7] that every 3-dimensional conformally flat contact metric manifold satisfying $\nabla_{\xi} \tau = 0$ ($\tau = L_{\xi} g$) is either flat or a Sasakian space form. This result extends Bang's result.

An open problem in Riemannian Geometry is the classification of the Riemannian manifolds (M, g) satisfying the conditions: a) M admits a non-vanishing vector field ξ b) The Jacobi operator associated to ξ is proportional to the identity on the complementary subspaces. Motivating the above mentioned problem we study a subclass of these manifolds, i.e., contact metric manifolds of dimension $2n + 1$ ($n > 1$) satisfying $\ell = -k\phi^2$, where k is a smooth function. The condition $\ell = -k\phi^2$ (which generalizes the K-contact condition)

implies the condition $\nabla_{\xi} \tau = 0$ for dimensions > 5 and is equivalent to the condition $\nabla_{\xi} \tau = 0$ for the dimension 3. We have to mention that D. Perrone in [10] gave results which show that there exist contact Riemannian manifolds with $\ell = -k\phi^2$ where k is not constant and D.E. Blair in [3] gave examples of 3-dimensional contact metric manifolds with $\ell = -k\phi^2$, where k is not constant.

The main result of the present paper is the following: Let M^{2n+1} $(n > 1)$ be a conformal1y flat contact metric manifold satisfying $\ell = -k\phi^2$ for some smooth function k on M^{2n+1} . Then M^{2n+1} is Sasakian of constant curvature 1. The above result generalizes the corresponding results of S. Tanno [11] for K-contact manifolds and of the first author and Ph. J. Xenos for the dimension 3.

2. Preliminaries

A *contact metric manifold* is a $(2n + 1)$ -dimensional differentiable manifold M^{2n+1} which carries a global differential 1-form η such that $\eta \wedge (d\eta)^n \neq 0$ everywhere on M^{2n+1} . Every contact metric manifold has an underlying *contact Riemannian structure* (ϕ, ξ, η, g) , where ξ is a global vector field (called the *characteristic vector field*), φ a global tensor field of type (1,1) and g a Riemannian metric (called *associated metric*). We note that the set of all contact Riemannian structures associated to a fixed contact form is infinite dimensional. The tensor fields ϕ , ξ , η , g satisfy:

$$
\eta(\xi) = 1, \quad \phi^2 = -I + \eta \otimes \xi, \quad \eta(X) = g(\xi, X), \nd\eta(X, Y) = g(X, \phi Y), \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y).
$$
\n(1)

From now on we assume M^{2n+1} is a contact metric manifold with contact metric structure (ϕ, ξ, η, g) .

We denote by L Lie differentiation and we define the tensor fields h and ℓ by

$$
h = \frac{1}{2}L_{\xi}\phi \quad and \quad \ell = R(\cdot, \xi)\xi. \tag{2}
$$

The tensor field h is symmetric and satisfies

$$
Trh\phi = Trh = 0, \quad h\xi = 0, \quad h\phi = -\phi h. \tag{3}
$$

On every contact metric manifold M^{2n+1} the following relations are valid:

$$
\nabla_X \xi = -\phi X - \phi h X \quad \text{and hence} \quad \nabla_{\xi} \xi = 0,\tag{4}
$$

$$
\nabla_{\xi}\phi = 0,\tag{5}
$$

$$
Tr\ell = g(Q\xi, \xi) = 2n - Trh^2,\tag{6}
$$

Vol. 79, 2004 On conformally flat contact metric manifolds 77

$$
\phi \ell \phi - \ell = 2(\phi^2 + h^2),\tag{7}
$$

$$
\nabla_{\xi} h = \phi - \phi \ell - \phi h^2, \qquad (8)
$$

 M^{2n+1} is said to be K-contact manifold if ξ is a Killing vector field. M^{2n+1} is K-contact iff $h = 0$ or iff $\ell = -\phi^2$ [2]. On $M^{2n+1} \times \mathcal{R}$ (\mathcal{R} is the real line) we can define an almost complex structure *J* by $J(X, f d/dt) = (\phi X - f \xi, \eta(X) d/dt)$, where f is a real valued function. If J is integrable, the contact structure on M^{2n+1} is called *normal* and M^{2n+1} is said to be *Sasakian*. A necessary and sufficient condition in order to M^{2n+1} be Sasakian is [2]:

$$
R(X,Y)\xi = \eta(Y)X - \eta(X)Y.
$$
\n(9)

A Riemannian manifold (M^n, g) is said to be conformally flat if it is conformally equivalent to a Euclidean space. A necessary and sufficient condition in order that $Mⁿ$ is conformally flat is $[4]$:

$$
R(X, Y)Z = \frac{1}{n-2}(g(Y, Z)QX - g(X, Z)QY + g(QY, Z)X - g(QX, Z)Y) - \frac{r}{(n-1)(n-2)}(g(Y, Z)X - g(X, Z)Y), \text{for } n > 3
$$
\n(10)

and

$$
(\nabla_X P)Y = (\nabla_Y P)X, \text{ for } n = 3,
$$

where $r = TrQ$ is the scalar curvature of M^n and $P = -Q + \frac{r}{4}Id$.

3. Auxiliary results

Let M^{2n+1} be a contact metric manifold satisfying

$$
\ell = -k\phi^2,\tag{11}
$$

where k is a smooth function of M^{2n+1} . We prove the following

PROPOSITION 3.1. On every contact metric manifold M^{2n+1} satisfying (11) we have $k \leq 1$ *. If* $k \leq 1$ *, then* M^{2n+1} *admits three mutually orthogonal distributions* $D(0)$ *,* $D(\lambda)$ *and* $D(-\lambda)$ *, defined by the eigenspaces of h, where* $\lambda = \sqrt{1 - k}$ *.*

Proof. The operator h is symmetric and hence diagonalizable, i.e., there exists an orthonormal frame of eigenvectors. Furthermore, $h\xi = 0$, and hence ξ is one of these eigenvectors. Now, let $X \perp \xi$ be another eigenvector with associated eigenvalue λ , i.e., $hX = \lambda X$. Then, ϕX is also an eigenvector of h with associated eigenvalue $-\lambda$. Also, on the one hand

$$
h^2 X = \lambda^2 X.
$$

On the other hand, it follows from

 $2(\phi^2 + h^2) = \phi \ell \phi - \ell = -k\phi^4 + k\phi^2 = 2k\phi^2$

that

$$
h^2 = (k-1)\phi^2,
$$

and hence

$$
h^2 X = (1 - k)X.
$$

The result follows immediately. \Box

PROPOSITION 3.2. Let M^{2n+1} be a contact metric manifold satisfying $\ell = -k\phi^2$ for *some smooth function* k *on it. Then, the distributions* D(λ) *and* D(−λ) *are parallel along* ξ *.*

Proof. Suppose X is a unit vector field belonging to $D(\lambda)$, i.e., $hX = \lambda X$. On the one hand, we see that

$$
\nabla_{\xi}(hX) = (\xi \cdot \lambda)X + \lambda \nabla_{\xi} X
$$

while, on the other hand,

$$
\nabla_{\xi}(hX) = (\nabla_{\xi}h)X + h(\nabla_{\xi}X) = \phi X - \phi \ell X - \phi h^2 X + h(\nabla_{\xi}X) = h(\nabla_{\xi}X),
$$

and hence

$$
h(\nabla_{\xi} X) = (\xi \cdot \lambda) X + \lambda \nabla_{\xi} X.
$$

Taking the inner product with X and using the fact that $g(X, \nabla_{\xi} X) = 0$, we see that $\xi \cdot \lambda = 0$
and that $\nabla_{\xi} X$ again belongs to $D(\lambda)$. and that $\nabla_{\xi} X$ again belongs to $D(\lambda)$.

Let $\{e_1,\ldots,e_n,e_{n+1}=\phi e_1,\ldots,e_{2n}=\phi e_n,\xi\}$ be an orthonormal frame, formed from the unit eigenvectors of h: $e_i \in D(\lambda)$, $\phi e_i \in D(-\lambda)$ and ξ .

A consequence of Proposition (3.2) is that

$$
\nabla_{\xi} e_i = \sum_{\substack{j=1 \ j \neq i}}^n a_{ij} e_j,\tag{12}
$$

$$
\nabla_{\xi} \phi e_i = \sum_{\substack{j=1 \ j \neq i}}^n a_{ij} \phi e_j,\tag{13}
$$

where

$$
a_{ij} = -a_{ji} \tag{14}
$$

If we differentiate the inner products $g(e_i, e_j)$, $g(e_i, \xi)$, $i, j = 1, \ldots, 2n$ with respect to e_k , $k = 1, \ldots, 2n$ we obtain

$$
\nabla_{e_i} e_i = \sum_{\substack{k=1 \ k \neq i}}^n A_{ik} e_k + \sum_{\substack{k=1 \ k \neq i}}^n \overline{A}_{ik} \phi e_k + A_i \phi e_i,
$$
\n
$$
\nabla_{\phi e_i} \phi e_i = \sum_{\substack{k=1 \ k \neq i}}^n B_{ik} e_k + \sum_{\substack{k=1 \ k \neq i}}^n \overline{B}_{ik} \phi e_k + B_i e_i,
$$
\n
$$
\nabla_{e_i} e_j = -A_{ij} e_i + \sum_{\substack{k=1 \ k \neq j}}^n C_{ij}^k e_k + \sum_{k=1}^n \overline{C}_{ij}^k \phi e_k, \quad i \neq j,
$$
\n
$$
\nabla_{\phi e_i} \phi e_j = -\overline{B}_{ij} \phi e_i + \sum_{\substack{k=1 \ k \neq j}}^n D_{ij}^k e_k + \sum_{\substack{i \neq k \neq j \ k \neq j}}^n \overline{D}_{ij}^k \phi e_k, \quad i \neq j,
$$
\n
$$
\nabla_{e_i} \phi e_j = -\overline{A}_{ij} e_i - \sum_{\substack{k=1 \ k \neq j}}^n \overline{C}_{ik}^j e_k - \overline{C}_{ij}^j e_j
$$
\n
$$
- Z_{ij} \phi e_i + \sum_{\substack{k=1 \ k \neq j}}^n N_{ij}^k \phi e_k, \quad i \neq j,
$$
\n
$$
\nabla_{\phi e_i} e_j = -E_{ij} e_i - B_{ij} \phi e_i - D_{ij}^j \phi e_j
$$
\n
$$
- \sum_{\substack{k=1 \ k \neq j}}^n D_{ik}^j \phi e_k + \sum_{\substack{k=1 \ k \neq j \ k \neq j}}^n F_{ij}^k e_k, \quad i \neq j,
$$
\n
$$
\nabla_{e_i} \phi e_i = -A_i e_i - \sum_{\substack{k=1 \ k \neq i}}^n \overline{C}_{ik}^i e_k + \sum_{\substack{k=1 \ k \neq i}}^n E_{ik} \phi e_k + (1 + \lambda) \xi,
$$
\n
$$
\nabla_{\phi e_i} e_i = -B_i \phi e_i - \sum_{\substack{k=1 \ k \neq i}}^n D_{
$$

where

$$
N_{ij}^{k} = -N_{ik}^{j}, \quad C_{ij}^{k} = -C_{ik}^{j}, \quad F_{ij}^{k} = -F_{ik}^{j}, \quad \overline{D}_{ij}^{k} = -\overline{D}_{ik}^{j},
$$

i, j, k \in {1, 2, ..., *n*}, *i* \neq *k* \neq *j*. (16)

4. Conformally flat contact metric manifolds with $\ell = -k\phi^2$

Let M^{2n+1} be a conformally flat contact metric manifold satisfying $\ell = -k\phi^2$. If $n = 1$ the manifold is either flat or a Sasakian manifold of constant curvature 1 [7]. We will investigate the case that $n > 1$.

LEMMA 4.1. Let M^{2n+1} ($n > 1$) be a conformally flat contact metric manifold. A nec*essary and sufficient condition in order that the conditions* $\ell = -k\phi^2$ *and* $Q\phi = \phi Q$ *are equivalent is that* $Q\xi$ *is collinear with* ξ *. In this case* $k = 1$ *.*

Proof. We suppose that $\ell = -k\phi^2$. The relation (10) for $Y = Z = \xi$ takes the form

$$
\ell X = \frac{1}{2n-1} (QX - \eta(X)Q\xi + Tr\ell X - \eta(QX)\xi) - \frac{r}{2n(2n-1)} (X - \eta(X)\xi). \tag{17}
$$

Furthermore, from the relations (6) and (11) we have

$$
\ell X = -\frac{Tr\ell}{2n}\phi^2 X. \tag{18}
$$

Comparing the relations (17) and (18) we obtain:

$$
QX = \frac{r - Tr\ell}{2n}X + \eta(X)Q\xi + \eta(QX)\xi - \frac{(2n - 1)Tr\ell + r}{2n}\eta(X)\xi.
$$
 (19)

Suppose that $Q\xi$ is collinear to ξ . Then for every $Z \in \text{ker } \eta$ we have that $\eta(OZ)$ = $g(Z, Q\xi) = 0$. This relation and (19) yield

$$
QZ = \frac{r - Tr\ell}{2n}Z, \quad \forall Z \in \ker \eta.
$$

The above relation and $Q\xi = Tr\ell\xi$ imply $Q\phi = \phi Q$. Hence $k = 1$ [3]. On the other hand it has been proved in [4] that on every conformally flat contact metric manifold M^{2n+1} (n > 1) the relation $Q\phi = \phi Q$ implies the relations $Q\xi = Tr\ell\xi$ and $\ell = -\phi^2$. \Box

From now on we suppose that $k < 1$.

If we calculate the curvature tensors $R(e_i, \phi e_i) \xi$, $R(e_i, e_i) \xi$, $R(\phi e_i, \phi e_i) \xi$ and $R(e_i, \phi e_i) \xi$, $i \neq j$, $i, j = 1, \ldots, n$, once using (10) and (19) and secondly by direct calculation using (11), (13), (14), (15) and the relation $\lambda = \sqrt{1-k}$ we obtain:

$$
e_i \cdot \lambda = (1 + \lambda)D_{ji}^j - (1 - \lambda)B_{ji}, \qquad (20)
$$

$$
\phi e_j \cdot \lambda = (1 + \lambda) \overline{A}_{ij} - (1 - \lambda) \overline{C}_{ij}^i, \tag{21}
$$

Vol. 79, 2004 On conformally flat contact metric manifolds 81

$$
\frac{1}{2n-1}\eta(\mathcal{Q}e_i) = (1+\lambda)(\overline{B}_{ji} - E_{ji}) + 2\lambda \overline{C}_{ij}^j,
$$
\n(22)

$$
\frac{1}{2n-1}\eta(Q\phi e_j) = (1-\lambda)(Z_{ij} - A_{ij}) + 2\lambda D_{ji}^i,
$$
\n(23)

$$
(1 + \lambda)D_{ji}^{k} - (1 - \lambda)D_{jk}^{i} + (1 - \lambda)C_{ij}^{k} - (1 - \lambda)N_{ij}^{k} = 0, \quad i \neq k \neq j,
$$
 (24)

$$
(1 - \lambda)\overline{C}_{ij}^k - (1 + \lambda)\overline{C}_{ik}^j + (1 + \lambda)\overline{D}_{ji}^k - (1 + \lambda)F_{ji}^k = 0, \quad i \neq k \neq j,
$$
 (25)

$$
e_i \cdot \lambda = (1 + \lambda)(A_{ji} - Z_{ji}), \tag{26}
$$

$$
e_j \cdot \lambda = (1 + \lambda)(A_{ij} - Z_{ij}), \qquad (27)
$$

$$
\frac{1}{2n-1}\eta(Qe_j) = (1+\lambda)\overline{A}_{ij} - (1-\lambda)\overline{C}_{ij}^i - 2\lambda\overline{C}_{ji}^i,\tag{28}
$$

$$
C_{ij}^{k} - C_{ji}^{k} - N_{ij}^{k} + N_{ji}^{k} = 0, \quad i \neq k \neq j,
$$
 (29)

$$
(1+\lambda)(\overline{C}_{ik}^j - \overline{C}_{jk}^i) + (1-\lambda)(\overline{C}_{ji}^k - \overline{C}_{ij}^k) = 0, \quad i \neq k \neq j,
$$
\n(30)

$$
\phi e_i \cdot \lambda = (1 - \lambda)(E_{ji} - \overline{B}_{ji}), \qquad (31)
$$

$$
\phi e_j \cdot \lambda = (1 - \lambda)(E_{ij} - \overline{B}_{ij}), \qquad (32)
$$

$$
\frac{1}{2n-1}\eta(Q\phi e_i) = (1+\lambda)D_{ji}^j - (1-\lambda)B_{ji} - 2\lambda D_{ij}^j,
$$
\n(33)

$$
F_{ij}^k - F_{ji}^k - \overline{D}_{ij}^k + \overline{D}_{ji}^k = 0, \quad i \neq k \neq j,
$$
\n(34)

$$
(1 - \lambda)(D_{jk}^i - D_{ik}^j) + (1 + \lambda)(D_{ij}^k - D_{ji}^k) = 0, \quad i \neq k \neq j,
$$
\n(35)

$$
(1 - \lambda)\overline{A}_{ij} - (1 + \lambda)(\overline{C}_{ij}^i - \overline{B}_{ij} + E_{ij}) = 0, \qquad (36)
$$

$$
(1 + \lambda)B_{ij} - (1 - \lambda)(Z_{ij} - A_{ij} + D_{ij}^i) = 0,
$$
\n(37)

$$
\frac{1}{2n-1}\eta(Qe_i) = 2\lambda A_i - \phi e_i \cdot \lambda,\tag{38}
$$

$$
\frac{1}{2n-1}\eta(Q\phi e_i) = 2\lambda B_i - e_i \cdot \lambda.
$$
 (39)

If we calculate the curvature tensors $R(e_i, \xi) e_j$, $R(\phi e_i, \xi) \phi e_i$, $R(\phi e_i, \xi) e_i$, $R(\phi e_i, \xi) \phi e_i$ and $R(e_i, \xi)\phi e_i$, $i \neq j$, $i, j = 1, ..., n$, once using (10) and (19) and secondly by direct calculation using (11) , (13) , (14) and (15) we obtain:

$$
\xi \cdot A_{ij} = \frac{1}{2n-1} \eta(Qe_j) - e_i \cdot a_{ji} + (1 + \lambda)E_{ij} - a_{ij}A_{ji} + \sum_{\substack{k=1 \ k \neq j}}^n a_{jk}A_{ik}
$$
\n
$$
+ \sum_{\substack{k=1 \ k \neq j}}^n a_{ki}C_{kj}^k - \sum_{\substack{k=1 \ k \neq j}}^n a_{ik}C_{kj}^i,
$$
\n
$$
\xi \cdot D_{ji}^j = a_{ij}B_j + (1 - \lambda)\overline{A}_{ji} + a_{ji}B_{ij} + \sum_{\substack{k=1 \ k \neq j}}^n a_{ik}D_{jk}^j
$$
\n
$$
- \sum_{\substack{k=1 \ k \neq j}}^n a_{kj}D_{ji}^k - a_{ij}D_{ji}^i + \sum_{\substack{k=1 \ k \neq j}}^n a_{jk}D_{ki}^j,
$$
\n
$$
\xi \cdot E_{ij} = \phi e_i \cdot a_{ij} + \sum_{\substack{k=1 \ k \neq j}}^n a_{ik}F_{ik}^j - \sum_{\substack{k=1 \ k \neq j}}^n a_{kj}E_{ik} - (1 - \lambda)A_{ij}
$$
\n
$$
- a_{ij}E_{ji} + \sum_{\substack{k=1 \ k \neq j}}^n a_{ik}F_{ki}^j,
$$
\n
$$
\xi \cdot \overline{B}_{ij} = \frac{1}{2n-1} \eta(Q\phi e_j) + \phi e_i \cdot a_{ij} + \sum_{\substack{k=1 \ k \neq j}}^n a_{ik} \overline{D}_{ik}^j - \sum_{\substack{k=1 \ k \neq j}}^n a_{kj} \overline{B}_{ik}
$$
\n
$$
- (1 - \lambda)Z_{ij} - a_{ij} \overline{B}_{ji} + \sum_{\substack{k=1 \ k \neq j}}^n a_{ik} \overline{D}_{ki}^j,
$$
\n
$$
\xi \cdot Z_{ij} = e_i \cdot a_{ij} + \sum_{\substack{k=1 \ k \neq j}}^n a_{ik}N_{ik}^j - \sum_{\substack{k=1 \ k \neq j}}^n a_{kj}Z_{ik} + (1 + \lambda)\overline{B}_{ij}
$$
\n
$$
- a_{ij}Z_{ji} + \sum_{\substack{l \ k \neq j}}^n a
$$

LEMMA 4.2. *There are no conformally flat contact metric manifolds of dimension* ≥ 5 *satisfying* $\ell = -k\phi^2$ *for some constant* $k < 1$ *.*

 $k=1$
 $i \neq k \neq j$

 $a_{ik}N^j_{ki}$.

Proof. K. Bang proved in [1] that there are no conformally flat contact metric manifolds of dimension ≥ 5 satisfying $\ell = 0$. Hence $\lambda^2 \neq 1$. Using the relations (14), (26), (29), (32), (40), (44) and $\lambda^2 \neq 1$ we obtain

$$
\xi\cdot A_{ij}-\xi\cdot Z_{ij}=\frac{1}{2n-1}\eta(Qe_j)+\frac{1+\lambda}{1-\lambda}\phi e_j\cdot\lambda-a_{ij}\frac{e_i\cdot\lambda}{1+\lambda}+\sum_{\substack{k=1\\i\neq k\neq j}}^n a_{jk}\frac{e_k\cdot\lambda}{1+\lambda}.
$$

The above relation, using (14), takes the form

$$
\xi \cdot A_{ij} - \xi \cdot Z_{ij} = \frac{1}{2n-1} \eta(Qe_j) + \frac{1+\lambda}{1-\lambda} \phi e_j \cdot \lambda + \sum_{\substack{k=1\\k \neq j}}^n a_{jk} \frac{e_k \cdot \lambda}{1+\lambda}.
$$
 (45)

If we differentiate with respect to ξ the relation (27) we obtain using the relations (4), (12) and $\xi \cdot \lambda = 0$,

$$
\xi \cdot A_{ij} - \xi \cdot Z_{ij} = \frac{\xi \cdot e_j \cdot \lambda - e_j \cdot \xi \cdot \lambda}{1 + \lambda} = \frac{[\xi, e_j] \cdot \lambda}{1 + \lambda} = \frac{(\nabla_{\xi} e_j - \nabla_{e_j} \xi) \cdot \lambda}{1 + \lambda}
$$

$$
= \frac{\sum_{\substack{k=1 \ k \neq j}}^{n} a_{jk}(e_k \cdot \lambda)}{1 + \lambda} + \phi e_j \cdot \lambda.
$$

Hence,

$$
\xi \cdot A_{ij} - \xi \cdot Z_{ij} = \frac{\sum_{k=1}^{n} a_{jk}(e_k \cdot \lambda)}{1 + \lambda} + \phi e_j \cdot \lambda. \tag{46}
$$

Comparing the relations (45) and (46) we obtain

$$
\eta(Qe_j) = -\frac{2\lambda(2n-1)}{1-\lambda}\phi e_j \cdot \lambda. \tag{47}
$$

Similarly, using the relations (4), (13), (14), (27), (31), (34), (42), (43) and $\xi \cdot \lambda = 0$, we obtain

$$
\eta(Q\phi e_j) = \frac{2\lambda(2n-1)}{1+\lambda}e_j \cdot \lambda.
$$
\n(48)

If k is a constant, then λ is constant. Hence $\eta(Qe_i) = 0$, $\eta(Q\phi e_i) = 0$, $\forall j \in \{1, 2, ..., n\}$, i.e., $Q\xi$ is collinear with ξ . Using Lemma 4.1 we obtain $Q\phi = \phi Q$, which means that M^{2n+1}
is a Sasakian space form [4]. Hence $k = 1$. A contradiction. is a Sasakian space form [4]. Hence $k = 1$. A contradiction.

LEMMA 4.3. Let M^{2n+1} $(n > 1)$ be a conformally flat contact metric manifold satisfying $\ell = -k\phi^2$ *for some smooth function* $k < 1$ *on* M^{2n+1} *. If* $\{e_1, \ldots, e_n, \phi e_1, \ldots, \phi e_n, \xi\}$ *is an orthonormal base formed from the unit eigenvectors* $e_i \in D(\lambda)$, $\phi e_i \in D(-\lambda)$ *and* ξ *, then*

$$
\nabla_{e_i} e_i = \sum_{\substack{k=1 \ k \neq i}}^n A_{ik} e_k + \frac{1 - 3\lambda}{2\lambda(1 - \lambda)} (\phi e_i \cdot \lambda) \phi e_i,
$$

$$
\nabla_{\phi e_i} \phi e_i = \sum_{\substack{k=1 \ k \neq i}}^n \overline{B}_{ik} \phi e_k + \frac{1 + 3\lambda}{2\lambda(1 + \lambda)} (e_i \cdot \lambda) e_i,
$$

$$
\nabla_{e_i} e_j = -A_{ij} e_i + \sum_{\substack{k=1 \ i \neq k \neq j}}^n C_{ij}^k e_k + \sum_{\substack{k=1 \ i \neq k \neq j}}^n \overline{C}_{ij}^k \phi e_k + \frac{1}{2\lambda} (\phi e_i \cdot \lambda) \phi e_j - \frac{1}{1 - \lambda} (\phi e_j \cdot \lambda) \phi e_i,
$$

and for the same couple $\{i, j\}$ we have:

$$
\nabla_{e_j} e_i = -A_{ji} e_j + \sum_{\substack{k=1 \ i \neq k \neq j}}^n C_{ji}^k e_k + \sum_{\substack{k=1 \ i \neq k \neq j}}^n \overline{C}_{ji}^k \phi e_k - \frac{1}{1 - \lambda} (\phi e_i \cdot \lambda) \phi e_j
$$

$$
- \frac{1 + \lambda}{2\lambda (1 - \lambda)} (\phi e_j \cdot \lambda) \phi e_i,
$$

$$
\nabla_{\phi e_j} \phi e_i = -B_{ji} \phi e_j + \sum_{\substack{k=1 \ i \neq k \neq j}}^n D_{ji}^k e_k + \frac{1}{2\lambda} (e_j \cdot \lambda) e_i + \frac{1}{1 + \lambda} (e_i \cdot \lambda) e_j
$$

$$
+ \sum_{\substack{k=1 \ i \neq k \neq j}}^n \overline{D}_{ij}^k \phi e_k,
$$

where $i \neq j$ and $\overline{C}_{ij}^k = -\overline{C}_{ik}^j$, $D_{ik}^j = -D_{ij}^k$, $D_{ij}^k = D_{ji}^k$, $\overline{C}_{ij}^k = \overline{C}_{ji}^k$, $i \neq k \neq j$. *Proof.* Since $k < 1$ we have that $\lambda \neq 0$. Hence, from the relation (38) we obtain

$$
A_i = \frac{1}{2\lambda(2n-1)}\eta(Qe_i) + \frac{1}{2\lambda}\phi e_i \cdot \lambda.
$$

The above equation and (47) yield

$$
A_i = \frac{1 - 3\lambda}{2\lambda(1 - \lambda)} \phi e_i \cdot \lambda.
$$
 (49)

Similarly we obtain from the equations (39) and (48)

$$
B_i = \frac{1+3\lambda}{2\lambda(1+\lambda)} e_i \cdot \lambda.
$$
 (50)

The relations (32), (36) and $\lambda^2 \neq 1$ imply

$$
(1 - \lambda)\overline{A}_{ij} - (1 + \lambda)\overline{C}_{ij}^{i} - \frac{1 + \lambda}{1 - \lambda}\phi e_j \cdot \lambda = 0.
$$
 (51)

Vol. 79, 2004 On conformally flat contact metric manifolds 85

Comparing the last relation with (21) we obtain

$$
A_{ij} = 0, \ i, j = 1, 2, \dots, n, \ i \neq j. \tag{52}
$$

The relations (51) and (52) yield

$$
\overline{C}_{ij}^{i} = -\frac{1}{1 - \lambda} \phi e_j \cdot \lambda.
$$
 (53)

From the last relation and (28), (47) and (52) we obtain

$$
\overline{C}_{ji}^{i} = -\frac{1+\lambda}{2\lambda(1-\lambda)}\phi e_j \cdot \lambda.
$$
 (54)

Using the relations (22), (31) and (47) for the same couple $\{i, j\}$ we have

$$
\overline{C}_{ij}^j = \frac{1}{2\lambda} \phi e_i \cdot \lambda. \tag{55}
$$

The relation (37) can be written in the form:

$$
(1 + \lambda)B_{ji} - (1 - \lambda)(Z_{ji} - A_{ji} + D_{ji}^j) = 0.
$$

Comparing the last relation with (26) we obtain

$$
(1+\lambda)B_{ji} - (1-\lambda)D_{ji}^j + \frac{1-\lambda}{1+\lambda}e_i \cdot \lambda = 0.
$$
 (56)

The above relation and (20) give

$$
B_{ji} = 0, \ \ j, i = 1, \dots, n, \ \ i \neq j. \tag{57}
$$

If we compare the last two relations we have

$$
D_{ji}^j = \frac{1}{1+\lambda} e_i \cdot \lambda. \tag{58}
$$

Using the relations (23), (27) and (48) we obtain

$$
D_{ji}^i = \frac{1}{2\lambda} e_j \cdot \lambda. \tag{59}
$$

At the end we will prove that $D^i_{jk} = -D^k_{ji}$, $\overline{C}^i_{jk} = -\overline{C}^k_{ji}$ and $D^k_{ij} = D^k_{ji}$, $\overline{C}^k_{ij} = \overline{C}^k_{ji}$, $i \neq k \neq j$. The relations (24) and (35) yield

$$
(1 + \lambda)D_{ij}^{k} - (1 - \lambda)D_{ik}^{j} = (1 - \lambda)(N_{ij}^{k} - C_{ij}^{k}).
$$
\n(60)

Using the relations (16) we obtain from (60)

$$
(1 + \lambda)D_{ij}^{k} - (1 - \lambda)D_{ik}^{j} = -(1 - \lambda)(N_{ik}^{j} - C_{ik}^{j}).
$$
\n(61)

The relation (24) yields

$$
(1 - \lambda)(N_{ik}^j - C_{ik}^j) = (1 + \lambda)D_{ik}^j - (1 - \lambda)D_{ij}^k.
$$
 (62)

Comparing the relations (61) and (62) we obtain

$$
D_{ik}^j = -D_{ij}^k. \tag{63}
$$

Similarly, using the relations (16), (25) and (30), we obtain

$$
\overline{C}_{jk}^{i} = -\overline{C}_{ji}^{k}.
$$
\n(64)

Using the relations (35) and (63) we have

$$
D_{ij}^k = D_{ji}^k. \tag{65}
$$

Similarly using the relations (30) and (64) we have

$$
\overline{C}_{ij}^k = \overline{C}_{ji}^k. \tag{66}
$$

 \Box

THEOREM 4.1. Let M^{2n+1} be a conformally flat contact metric manifold satisfying $\ell = -k\phi^2$ *for a smooth function* k *defined on it. Then* M^{2n+1} *is a Sasakian space form if* $n > 1$ *and flat or Sasakian space form if* $n = 1$.

Proof. If
$$
n = 1
$$
 then M^3 is either flat or a Sasakian space form [7].

Let $n > 1$. If $k = 1$, M^{2n+1} is K-contact. S. Tanno proved in [11] that every conformally flat K -contact manifold is of constant sectional curvature and J. Olzak proved in [9] that any contact metric manifold of constant sectional curvature and of dimension \geq 5 is Sasakian of constant curvature 1. Hence in the case that $k = 1$, M^{2n+1} is Sasakian space form.

We suppose now that $k < 1$.

Using the relations (41) , (52) , (57) , (63) and (65) we obtain

$$
\sum_{\substack{k=1\\i\neq k\neq j}}^n a_{ik} D_{jk}^j + a_{ij} B_j - \xi \cdot D_{ji}^j + a_{ji} D_{ji}^i = 0.
$$

The above relation and (14), (50), (58), (59), $\xi \cdot \lambda = 0$ yield

$$
\frac{1}{1+\lambda} \sum_{\substack{k=1 \ i \neq k \neq j}}^{n} a_{ik}(e_k \cdot \lambda) + \frac{1+3\lambda}{2\lambda(1+\lambda)} a_{ij}(e_j \cdot \lambda) - \frac{1}{1+\lambda} [\xi, e_i] \cdot \lambda - \frac{1}{2\lambda} a_{ij}(e_j \cdot \lambda) = 0,
$$

or because of (4) and (12)

$$
\frac{1}{1+\lambda} \sum_{\substack{k=1 \ i \neq k \neq j}}^{n} a_{ik}(e_k \cdot \lambda) + \frac{1+3\lambda}{2\lambda(1+\lambda)} a_{ij}(e_j \cdot \lambda)
$$

$$
-\frac{1}{1+\lambda} \sum_{\substack{k=1 \ k \neq i}}^{n} a_{ik}(e_k \cdot \lambda) - \phi e_i \cdot \lambda - \frac{1}{2\lambda} a_{ij}(e_j \cdot \lambda) = 0.
$$

From the last relation we obtain

or because of (4) , (13) and (67)

$$
\phi e_i \cdot \lambda = 0. \tag{67}
$$

The above relation and $\xi \cdot \lambda = 0$ imply:

$$
\xi \cdot \phi e_i \cdot \lambda - \phi e_i \cdot \xi \cdot \lambda = 0.
$$

Hence,

$$
[\xi, \phi e_i] \cdot \lambda = 0,
$$

$$
e_i \cdot \lambda = 0. \tag{68}
$$

Hence λ is a constant which means that k is a constant. This is a contradiction because of the Lemma 4.2.

References

- [1] K. Bang, Riemannian Geometry of vector Bundles, Thesis, Michigan State University, 1994.
- [2] D.E. Blair, Contact manifolds in Riemannian Geometry, Lectures Notes in Mathematics **509**, Springer-Verlag, Berlin, 1976.
- [3] D.E. Blair, Special Directions on Contact Metric Manifolds of Negative ξ -sectional Curvature, to appear.
- [4] D.E. Blair and Th. Koufogiorgos, When is the tangent sphere bundle conformally flat?, J. Geom. **49** (1994) 55–66.
- [5] J. Davidov and O. Mushkarov, Twistor spaces with Hermitian Ricci tensor, Proc. Amer. Math. Soc. **109** (1990) 1115–1120.
- [6] S.R. Deng, Variational problems on contact manifolds, Thesis, Michigan State University, 1991.
- [7] F. Gouli-Andreou and Ph.J. Xenos, Two classes of conformally flat contact metric manifolds, to appear.
- [8] M. Okumura, Some remarks on spaces with a certain contact structure, Tôhoku Math. J. 14 (1962) 135–145.
- [9] Z. Olszak, On contact metric manifolds, Tôhoku Math. J. 31 (1979) 247–253.

88 Florence Gouli-Andreou and Niki Tsolakidou J. Geom.

- [10] D. Perrone, Contact Riemannian manifolds satisfying $R(X, \xi) \cdot R = 0$, Yokohama Mathematical J. 39 (1992) 141–149.
- [11] S. Tanno, Locally symmetric K-contact Riemannian manifolds, Proc. Japan Acad. **43** (1967) 581–583.
- [12] S. Tanno, Ricci curvatures on contact Riemannian manifolds, Tôhoku Math. J. 40 (1988) 441-448.

Florence Gouli-Andreou and Niki Tsolakidou Aristotle University of Thessaloniki Department of Mathematics GR-Thessaloniki - 540 06 Greece e-mail: fgouli@mailhost.ccf.auth.gr

Received 31 July 2000.

To access this journal online: http://www.birkhauser.ch