Aequat. Math. 92 (2018), 627–640 © The Author(s) 2018 0001-9054/18/040627-14 published online May 9, 2018 https://doi.org/10.1007/s00010-018-0558-3

Aequationes Mathematicae



Spherical bodies of constant width

MAREK LASSAKD AND MICHAŁ MUSIELAK

Abstract. The intersection L of two different non-opposite hemispheres G and H of the d-dimensional unit sphere S^d is called a lune. By the thickness of L we mean the distance of the centers of the (d-1)-dimensional hemispheres bounding L. For a hemisphere G supporting a convex body $C \subset S^d$ we define width_G(C) as the thickness of the narrowest lune or lunes of the form $G \cap H$ containing C. If width_G(C) = w for every hemisphere G supporting C, we say that C is a body of constant width w. We present properties of these bodies. In particular, we prove that the diameter of any spherical body C of constant width w on S^d is w, and that if $w < \frac{\pi}{2}$, then C is strictly convex. Moreover, we check when spherical bodies of constant width and constant diameter coincide.

Mathematics Subject Classification. 52A55.

Keywords. Spherical convex body, Spherical geometry, Hemisphere, Lune, Width, Constant width, Thickness, Diameter, Extreme point.

1. Introduction

Consider the unit sphere S^d in the (d + 1)-dimensional Euclidean space E^{d+1} for $d \ge 2$. The intersection of S^d with any two-dimensional subspace of E^{d+1} is called a great circle of S^d . By a (d-1)-dimensional great sphere of S^d we mean the common part of S^d with any hyper-subspace of E^{d+1} . The 1-dimensional great spheres of S^2 are called great circles. By a pair of antipodes of S^d we understand a pair of points of intersection of S^d with a straight line through the origin of E^{d+1} .

Clearly, if two different points $a, b \in S^d$ are not antipodes, there is exactly one great circle containing them. As the *arc ab* connecting *a* and *b* we define the shorter part of the great circle containing these points. The length of this arc is called the *spherical distance* |ab| of *a* and *b*, or shortly *distance*. Moreover, we agree that the distance of coinciding points is 0, and that of any pair of antipodes is π .

🕲 Birkhäuser

A spherical ball $B_{\rho}(x)$ of radius $\rho \in (0, \frac{\pi}{2}]$, or a ball for short, is the set of points of S^d at distances at most ρ from a fixed point x, which is called the *center* of this ball. An open ball (a sphere) is the set of points of S^d having distance smaller than (respectively, exactly) ρ from a fixed point. A spherical ball of radius $\frac{\pi}{2}$ is called a *hemisphere*. So it is the common part of S^d and a closed half-space of E^{d+1} . We denote by H(m) the hemisphere with center m. Two hemispheres with centers at a pair of antipodes are called opposite.

A spherical (d-1)-dimensional ball of radius $\rho \in (0, \frac{\pi}{2}]$ is the set of points of a (d-1)-dimensional great sphere of S^d which are at distances at most ρ from a fixed point. We call it the *center* of this ball. The (d-1)-dimensional balls of radius $\frac{\pi}{2}$ are called (d-1)-dimensional hemispheres, and semicircles for d = 2.

A set $C \subset S^d$ is said to be *convex* if no pair of antipodes belongs to C and if for every $a, b \in C$ we have $ab \subset C$. A closed convex set on S^d with nonempty interior is called a *convex body*. Some basic references on convex bodies and their properties are [4], [9] and [10]. A short survey of other definitions of convexity on S^d is given in Section 9.1 of [2].

Since the intersection of every family of convex sets is also convex, for every set $A \subset S^d$ contained in an open hemisphere of S^d there is the smallest convex set conv(A) containing Q. We call it the convex hull of A.

Let $C \subset S^d$ be a convex body. Let $Q \subset S^d$ be a convex body or a hemisphere. We say that C touches Q from inside if $C \subset Q$ and $bd(C) \cap bd(Q) \neq \emptyset$. We say that C touches Q from outside if $C \cap Q \neq \emptyset$ and $int(C) \cap int(Q) = \emptyset$. In both cases, points of $bd(C) \cap bd(Q)$ are called points of touching. In the first case, if Q is a hemisphere, we also say that Q supports C, or supports C at t, provided t is a point of touching. If at every boundary point of C exactly one hemisphere supports C, we say that C is smooth. We call $e \in C$ an extreme point of C if $C \setminus \{e\}$ is convex.

If hemispheres G and H of S^d are different and not opposite, then $L = G \cap H$ is called *a lune* of S^d . This notion is considered in many books and papers (for instance, see [12]). The (d-1)-dimensional hemispheres bounding L and contained in G and H, respectively, are denoted by G/H and H/G.

Observe that $(G/H) \cup (H/G)$ is the boundary of the lune $G \cap H$. Denote by $c_{G/H}$ and $c_{H/G}$ the centers of G/H and H/G, respectively. By *corners* of the lune $G \cap H$ we mean points of the set $(G/H) \cap (H/G)$. In particular, every lune on S^2 has two corners. They are antipodes.

We define the thickness $\Delta(L)$ of a lune $L = G \cap H$ on S^d as the spherical distance of the centers of the (d-1)-dimensional hemispheres G/H and H/G bounding L. Clearly, it is equal to each of the non-oriented angles $\angle c_{G/H}rc_{H/G}$, where r is any corner of L.

Compactness arguments show that for any hemisphere K supporting a convex body $C \subset S^d$ there is at least one hemisphere K^* supporting C such that the lune $K \cap K^*$ is of the minimum thickness. In other words, there is a "narrowest" lune of the form $K \cap K'$ over all hemispheres K' supporting C. The thickness of the lune $K \cap K^*$ is called *the width of* C *determined by* K. We denote it by width_K(C).

We define the *thickness* $\Delta(C)$ of a spherical convex body C as the smallest width of C. This definition is analogous to the classical definition of thickness (also called minimal width) of a convex body in Euclidean space.

By the relative interior of a convex set $C \subset S^d$ we mean the interior of C with respect to the smallest sphere $S^k \subset S^d$ that contains C.

2. A few lemmas on spherical convex bodies

Lemma 1. Let A be a closed set contained in an open hemisphere of S^d . Then $\operatorname{conv}(A)$ coincides with the intersection of all hemispheres containing A.

Proof. First, let us show that $\operatorname{conv}(A)$ is contained in the intersection of all hemispheres containing A. Take any hemisphere H containing A and denote by J the open hemisphere from the formulation of our lemma. Recall that $A \subset J$ and $A \subset H$. Thus since $J \cap H$ is a convex set, we obtain $\operatorname{conv}(A) \subset \operatorname{conv}(J \cap H) = J \cap H \subset H$. Thus, since $\operatorname{conv}(A)$ is contained in any hemisphere that contains A, also $\operatorname{conv}(A)$ is a subset of the intersection of all those hemispheres.

Now we intend to show that the intersection of all hemispheres containing A is contained in $\operatorname{conv}(A)$. Assume the opposite, i.e., that there is a point $x \notin \operatorname{conv}(A)$ which belongs to every hemisphere containing A. Since A is closed, by Lemma 1 of [6] the set $\operatorname{conv}(A)$ is also closed. Hence there is an $\varepsilon > 0$ such that $B_{\varepsilon}(x) \cap \operatorname{conv}(A) = \emptyset$. Since these two sets are convex, we may apply the following more general version of Lemma 2 of [6]: any two convex disjoint sets on S^d are subsets of two opposite hemispheres (which is true again by the separation theorem for convex cones in E^{d+1}). So $B_{\varepsilon}(x)$ and $\operatorname{conv}(A)$ are in some two opposite hemispheres. Hence x does not belong to the one which contains $\operatorname{conv}(A)$. Clearly, that one also contains A. This contradicts our assumption on the choice of x, and thus the proof is finished.

We omit the simple proof of the next lemma, which is analogous to the situation in E^d and needed a few times later. Here our hemisphere plays the role of a closed half-space there.

Lemma 2. Let C be a spherical convex body. Assume that a hemisphere H supports C at a point p of the relative interior of a convex set $T \subset C$. Then $T \subset bd(H)$.

Lemma 3. Let K, M be hemispheres such that the lune $K \cap M$ is of thickness smaller than $\frac{\pi}{2}$. Denote by b the center of M/K. Every point of $K \cap M$ at distance $\frac{\pi}{2}$ from b is a corner of $K \cap M$. *Proof.* Denote the center of K/M by a. Take any point $p \in K \cap M$. Let us show that there are points $x \in (K/M) \cap (M/K)$ and $y \in ab$ such that $p \in xy$.

If p = b then it is obvious. Otherwise there is a unique point $q \in K/M$ such that $p \in bq$. Moreover, there exists $x \in (K/M) \cap (M/K)$ such that $q \in ax$. The reader can easily show that points p, q belong to the triangle abx and thus observe that there exists $y \in ab$ such that $p \in xy$, which confirms the statement from the first paragraph of the proof.

We have $|by| \leq |ba| < \frac{\pi}{2}$. The inequality $|by| < \frac{\pi}{2}$ means that y is in the interior of H(b). Of course, $|bx| = \frac{\pi}{2}$, which means that $x \in bd(H(b))$. From the two preceding sentences we conclude that xy is a subset of H(b) with x being its only point on bd(H(b)). Thus, if $|pb| = \frac{\pi}{2}$, we conclude that $p \in bd(H(b))$, and consequently p = x, which implies that p is a corner of $K \cap M$. The last sentence means that the statement of our lemma holds true.

Lemma 4. Let $o \in S^d$ and $0 < \mu < \frac{\pi}{2}$. For every $x \in S^d$ at distance $\frac{\pi}{2}$ from o denote by x' the point of the arc ox at distance μ from x. Consider two points x_1, x_2 at distance $\frac{\pi}{2}$ from o such that $|x_1x_2| < \pi - \mu$. Then for every $x \in x_1x_2$ we have

$$B_{\mu}(x') \subset \operatorname{conv}(B_{\mu}(x'_1) \cup B_{\mu}(x'_2)).$$

Proof. Let o, m be points of S^d and ρ be a positive number less than $\frac{\pi}{2}$. Let us show that

$$B_{\rho}(o) \subset H(m)$$
 if and only if $|om| \leq \frac{\pi}{2} - \rho.$ (1)

First assume that $B_{\rho}(o) \subset H(m)$. Let *b* be a boundary point of $B_{\rho}(o)$ such that $o \in mb$. We have: $|om| = |bm| - |ob| = |bm| - \rho \leq \frac{\pi}{2} - \rho$, which confirms the "only if" part of (1). Assume now that $|om| \leq \frac{\pi}{2} - \rho$. Let *b* be any point of $B_{\rho}(o)$. We have: $|bm| \leq |bo| + |om| \leq \rho + (\frac{\pi}{2} - \rho) = \frac{\pi}{2}$. Therefore every point of $B_{\rho}(o)$ is at a distance at most $\frac{\pi}{2}$ from *m*. Hence $B \subset H(m)$, which confirms the "if" part of (1). So (1) is shown.

Lemma 1 of [6] guarantees that $Y = \operatorname{conv}(B_{\mu}(x_1') \cup B_{\mu}(x_2'))$ is a closed set as a convex hull of a closed set. Consequently, from Lemma 1 we see that Yis the intersection of all hemispheres containing Y. Moreover, observe that an arbitrary hemisphere contains a set if and only if it contains the convex hull of it. Hence Y is the intersection of all hemispheres containing $B_{\mu}(x_1') \cup B_{\mu}(x_2')$.

As a result of the preceding paragraph, in order to prove the statement of our lemma it is sufficient to show that every hemisphere H(m) containing $B_{\mu}(x'_1) \cup B_{\mu}(x'_2)$ also contains $B_{\mu}(x')$. Thus, having (1) in mind we see that in order to verify this it is sufficient to show that for any $m \in S^d$

$$|x'_1m| \le \frac{\pi}{2} - \mu$$
 and $|x'_2m| \le \frac{\pi}{2} - \mu$ imply $|x'm| \le \frac{\pi}{2} - \mu$. (2)

Let us assume the first two of these inequalities and show the third one.

Observe that x, x'_1 and x'_2 belong to the spherical triangle x_1x_2o . Therefore the arcs xo and $x'_1x'_2$ intersect. Denote the point of intersection by g.

In this paragraph we consider the intersection of S^d with the threedimensional subspace of E^{d+1} containing x'_1, x'_2, m . Observe that this intersection is a two-dimensional sphere concentric with S^d . Denote this sphere by S^2 . Denote by \overline{o} the other unique point on S^2 such that the triangles $x'_1x'_2o$ and $x'_1x'_2\overline{o}$ are congruent. By the first two inequalities of (2) we obtain $m \in B_{\frac{\pi}{2}-\mu}(x'_1) \cap B_{\frac{\pi}{2}-\mu}(x'_2)$. Observe that $g\overline{o} \cup go$ dissects $B_{\frac{\pi}{2}-\mu}(x'_1) \cap B_{\frac{\pi}{2}-\mu}(x'_2)$ into two parts so that x'_1 belongs to one of them and x'_2 belongs to the other. Therefore at least one of the arcs x'_1m and x'_2m , say x'_1m intersects $g\overline{o}$ or go, say go. Denote this point of intersection by s. Taking the first assumption of (2) into account and using two times the triangle inequality we obtain $|og| = (|os| + |x'_1s|) - |x'_1s| + |sg| \ge |ox'_1| - |x'_1s| + |sg| = \frac{\pi}{2} - \mu - |x'_1s| + |sg| \ge |x'_1m| - |x'_1s| + |sg| \ge |gm|$.

Applying the just obtained inequality and looking now again on the whole S^d we get $|x'm| \leq |x'g| + |gm| \leq |x'g| + |og| = |x'o| = \frac{\pi}{2} - \mu$ which is the required inequality in (2). Thus by (2) also our lemma holds true.

Lemma 5. Let $C \subset S^d$ be a convex body. Every point of C belongs to the convex hull of at most d + 1 extreme points of C.

Proof. We apply induction with respect to d. For d = 1 the statement is trivial since every convex body on S^1 is a spherical arc. Let $d \ge 2$ be a fixed integer. Assume that for each $k = 1, 2, \ldots, d - 1$ every boundary point of a spherical convex body $\widehat{C} \subset S^k$ belongs to the convex hull of at most k + 1 extreme points of \widehat{C} .

Let x be a point of C. Take an extreme point e of C. If x is not a boundary point of C, take the boundary point f of C such that $x \in ef$. In the opposite case put f = x.

If f is an extreme point of C, the statement follows immediately. In the opposite case take a hemisphere K supporting C at f. Put $C' = bd(K) \cap C$. Observe that every extreme point of C' is also an extreme point of C. Let Q be the intersection of the smallest linear subspace of E^{d+1} containing C' with S^d . Clearly, Q is isomorphic to S^k for k < d. Moreover, C' has non-empty relative interior with respect to Q, because otherwise there would exist a smaller linear subspace of E^{d+1} containing C'. Thus, by the inductive hypothesis we obtain that f is in the convex hull of a set F of at most d extreme points of C. Therefore $x \in \text{conv}(\{e\} \cup F)$ which means that x belongs to the convex hull of d + 1 extreme points of C. This finishes the inductive proof.

The proof of the following *d*-dimensional lemma is analogous to that of the two-dimensional Lemma 4.1 from [8] shown there for a wider class of reduced spherical convex bodies.

Lemma 6. Let $C \subset S^d$ be a spherical convex body with $\Delta(C) > \frac{\pi}{2}$ and let $L \supset C$ be a lune such that $\Delta(L) = \Delta(C)$. Each of the centers of the (d-1)-dimensional hemispheres bounding L belongs to the boundary of C and both are smooth points of the boundary of C.

Having the next lemma in mind, we note the obvious fact that the diameter of a convex body $C \subset S^d$ is realized only for some pairs of points of bd(C).

Lemma 7. Assume that the diameter of a convex body $C \subset S^d$ is realized for points p and q. The hemisphere K orthogonal to pq at p and containing $q \in K$ supports C.

Proof. Denote the diameter of C by δ .

Assume first that $\delta > \frac{\pi}{2}$. The set of points at distance at least δ from q is the ball $B_{\pi-\delta}(q')$, where q' is the antipode of q. Clearly, K has only p in common with $B_{\pi-\delta}(q')$.

Since the diameter δ of C is realized for pq, every point of C is at distance at most δ from q. Thus C has empty intersection with the interior of $B_{\pi-\delta}(q')$.

Assume that K does not contain C. Then C contains a point $b \notin K$. Observe that the arc bp has nonempty intersection with the interior of $B_{\pi-\delta}(q')$ [the reason: K is the only hemisphere touching $B_{\pi-\delta}(q')$ from outside at p]. On the other hand, by the convexity of C we have $bp \subset C$. This contradicts the fact from the preceding paragraph that C has empty intersection with the interior of $B_{\pi-\delta}(q')$. Consequently, K contains C.

Now consider the case when $\delta \leq \frac{\pi}{2}$. For every $y \notin K$ we have |pq| < |yq| which by $|pq| = \delta$ implies $y \notin C$. Thus if $y \in C$, then $y \in K$.

Let us apply our Lemma 7 for a convex body C of diameter larger than $\frac{\pi}{2}$. Having in mind that the center k of K is in pq and thus in C, by Part III of Theorem 1 in [6] we obtain that $\Delta(K \cap K^*) > \frac{\pi}{2}$. This gives the following corollary which implies the other one. The symbol diam(C) denotes the diameter of C.

Corollary 1. Let $C \subset S^d$ be a convex body of diameter larger than $\frac{\pi}{2}$ and let diam(C) be realized for points $p, q \in C$. Take the hemisphere K orthogonal to pq at p which supports C. Then width_K $(C) > \frac{\pi}{2}$.

Corollary 2. Let $C \subset S^d$ be a convex body of diameter larger than $\frac{\pi}{2}$ and let \mathcal{K} denote the family of all hemispheres supporting C. Then $\max_{K \in \mathcal{K}} \operatorname{width}_K(C) > \frac{\pi}{2}$.

3. Spherical bodies of constant width

If for every hemisphere supporting a convex body $W \subset S^d$ the width of W determined by K is the same, we say that W is a body of constant width

(see [6] and for an application also [5]). In particular, spherical balls of radius smaller than $\frac{\pi}{2}$ are bodies of constant width. Also every spherical Reuleaux odd-gon (for the definition see [6], p. 557) is a convex body of constant width. Each of the 2^{d+1} parts of S^d dissected by d + 1 pairwise orthogonal (d-1)-dimensional spheres of S^d is a spherical body of constant width $\frac{\pi}{2}$, which easily follows from the definition of a body of constant width. The class of spherical bodies of constant width is a subclass of the class of spherical reduced bodies considered in [6] and [8], and mentioned by [3] in a larger context, (recall that a convex body $R \subset S^d$ is called *reduced* if $\Delta(Z) < \Delta(R)$ for every body $Z \subset R$ different from R, see also [7] for this notion in E^d).

By the definition of width and by Claim 2 of [6], if $W \subset S^d$ is a body of constant width, then every supporting hemisphere G of W determines a supporting hemisphere H of W for which $G \cap H$ is a lune of thickness $\Delta(W)$ such that the centers of G/H and H/G belong to the boundary of W. Hence every spherical body W of constant width is an intersection of lunes of thickness $\Delta(W)$ such that the centers of the (d-1)-dimensional hemispheres bounding these lunes belong to $\operatorname{bd}(W)$. Recall the related question from p. 563 of [6] if a convex body $W \subset S^d$ is of constant width provided every supporting hemisphere G of W determines at least one hemisphere H supporting W such that $G \cap H$ is a lune with the centers of G/H and H/G in $\operatorname{bd}(W)$.

Here is an example of a spherical body of constant width on S^3 .

Example. Take a circle $X \subset S^3$ (i.e., a set congruent to a circle in E^2) of a positive diameter $\kappa < \frac{\pi}{2}$, and a point $y \in S^3$ at distance κ from every point $x \in X$. Prolong every spherical arc yx by a distance $\sigma \leq \frac{\pi}{2} - \kappa$ up to points a and b so that a, y, x, b are on one great circle in this order. All these points a form a circle A, and all points b form a circle B. On the sphere on S^3 of radius σ whose center is y take the "smaller" part A^+ bounded by the circle A. On the sphere on S^3 of radius $\kappa + \sigma$ with center y take the "smaller" part B^+ bounded by B. For every $x \in X$ denote by x' the point on X such that $|xx'| = \kappa$. Prolong every xx' up to points d, d' so that d, x, x', d' are in this order and $|dx| = \sigma = |x'd'|$. For every x provide the shorter piece C_x of the circle with center x and radius σ connecting b and d determined by x and also the shorter piece D_x of the circle with center x of radius $\kappa + \sigma$ connecting a and d' determined by x. Denote by W the convex hull of the union of A^+ , B^+ and all the pieces C_x and D_x . It is a body of constant width $\kappa + 2\sigma$ (hint: for every hemisphere H supporting W and every H^* the centers of H/H^* and H^*/H belong to bd(W) and the arc connecting them passes through one of our points x, or through the point y).

Theorem 1. At every boundary point p of a body $W \subset S^d$ of constant width $w > \pi/2$ we can inscribe a unique ball $B_{w-\pi/2}(p')$ touching W from inside at p. What is more, p' belongs to the arc connecting p with the center of the unique hemisphere supporting W at p, and $|pp'| = w - \frac{\pi}{2}$.

AEM

Proof. Observe that if a ball touches W at p from inside, then there exists a unique hemisphere supporting W at p such that our ball touches this hemisphere at p. So for any $\rho \in (0, \frac{\pi}{2})$ there is at most one ball of radius ρ touching W from inside at p. Our aim is to show that we can always find one.

In the first part of the proof consider the case when p is an extreme point of W. By Theorem 4 of [6] there is a lune $L = K \cap M$ of thickness w containing W such that p is the center of K/M. Denote by m the center of M and by kthe center of K. Clearly, $m \in pk$ and $|pm| = w - \frac{\pi}{2}$. Since width_M(W) = w, by the third part of Theorem 1 of [6] the ball $B_{w-\pi/2}(m)$ touches W from inside. Moreover, it touches W from inside at the center of M^*/M . Since K is one of these hemispheres M^* , our ball touches W at p.

In the second part consider the case when p is not an extreme point of W. From Lemma 5 we see that p belongs to the convex hull of a finite set E of extreme points of W. We do not lose the generality assuming that E is a minimum set of extreme points of W with this property. Hence p belongs to the relative interior of conv(E).

Take a hemisphere K supporting W at p and denote by o the center of K. Since p belongs to the relative interior of $\operatorname{conv}(E)$, by Lemma 2 we obtain $\operatorname{conv}(E) \subset \operatorname{bd}(K)$. Moreover, $\operatorname{conv}(E)$ is a subset of the boundary of W.

We intend to show that for every $x \in \operatorname{conv}(E)$ the inclusion

$$B_{w-\frac{\pi}{2}}(x') \subset W \tag{3}$$

holds true, where x' denotes the point on ox at distance $w - \frac{\pi}{2}$ from x.

By Lemma 4 for $w = \mu$, if (3) holds true for $x_1, x_2 \in \operatorname{conv}(E)$, then (3) is also true for every point of the arc x_1x_2 . Applying this lemma a finite number of times and considering the first part of this proof, we conclude that (3) is true for every point of $\operatorname{conv}(E)$, so in particular for p. Clearly, the ball $B_{w-\frac{\pi}{2}}(p')$ supports W at p from inside.

Both parts of the proof confirm the statement of our theorem.

By Lemma 6 we obtain the following proposition generalizing Proposition 4.2 from [8] for arbitrary dimension d. We omit an analogous proof.

Proposition 1. Every spherical body of constant width larger than $\frac{\pi}{2}$ (and more generally, every reduced body of thickness larger than $\frac{\pi}{2}$) of S^d is smooth.

From Corollary 2 we obtain the following corollary which implies the two other ones.

Corollary 3. If diam $(W) > \frac{\pi}{2}$ for a body $W \subset S^d$ of constant width w, then $w > \frac{\pi}{2}$.

Corollary 4. For every body $W \subset S^d$ of constant width $w \leq \frac{\pi}{2}$ we have $\operatorname{diam}(W) \leq \frac{\pi}{2}$.

Corollary 5. Let p be a point of a body $W \subset S^d$ of constant width at most $\frac{\pi}{2}$. Then $W \subset H(p)$.

The following theorem generalizes Theorem 5.2 of [8] proved there for d = 2 only.

Theorem 2. Every spherical convex body of constant width smaller than $\frac{\pi}{2}$ on S^d is strictly convex.

Proof. Take a body W of constant width $w < \frac{\pi}{2}$ and assume it is not strictly convex. Then there is a supporting hemisphere K of W that supports W at more than one point. By Claim 2 of [6] the centers a of K/K^* and b of K^*/K belong to bd(W). Since K supports W at more than one point, K/K^* contains also a boundary point $x \neq a$ of W. By the first statement of Lemma 3 of [6] we have |xb| > |ab| = w. Hence diam(W) > w.

By Corollary 4 we have diam $(W) \leq \frac{\pi}{2}$. By Theorem 3 of [6] we see that w = diam(W). This contradicts the inequality diam(W) > w from the preceding paragraph. The contradiction means that our assumption that W is not strictly convex must be false. Consequently, W is strictly convex.

On p. 566 of [6] the question is put if for every reduced spherical body $R \subset S^d$ and for every $p \in \mathrm{bd}(R)$ there exists a lune $L \supset R$ fulfilling $\Delta(L) = \Delta(R)$ with p as the center of one of the two (d-1)-dimensional hemispheres bounding this lune. The following theorem gives a positive answer in the case of spherical bodies of constant width. It is a generalization of the version for S^2 given as Theorem 5.3 in [8]. The idea of the proof of our theorem below for S^d substantially differs from the one given for S^2 .

Theorem 3. For every body $W \subset S^d$ of constant width w and every $p \in bd(W)$ there exists a lune $L \supset W$ fulfilling $\Delta(L) = w$ with p as the center of one of the two (d-1)-dimensional hemispheres bounding this lune.

Proof. Part I for $w < \frac{\pi}{2}$.

By Theorem 2 the body W is strictly convex, which means that all its boundary points are extreme. Thus the statement follows from Theorem 4 of [6].

Part II for $w = \frac{\pi}{2}$.

If p is an extreme point of W we again apply Theorem 4 of [6].

Consider the case when p is not an extreme point. Take a hemisphere G supporting W at p. Applying Corollary 5 we see that $W \subset H(p)$. Clearly, the lune $H(p) \cap G$ contains W. The point p is at distance $\frac{\pi}{2}$ from every corner of this lune and also from every point of the opposite (d-1)-dimensional hemisphere bounding the lune. Hence this is a lune that we are looking for.

Part III, for $w > \frac{\pi}{2}$.

By Lemma 5 the point p belongs to the convex hull conv(E) of a finite set E of extreme points of W. We do not lose the generality by assuming that E is a

minimum set of extreme points of W with this property. Hence p belongs to the relative interior of $\operatorname{conv}(E)$. By Proposition 1 we know that there is a unique hemisphere K supporting W at p. Since p belongs to the relative interior of $\operatorname{conv}(E)$, by Lemma 2 we have $\operatorname{conv}(E) \subset \operatorname{bd}(K)$. Moreover, $\operatorname{conv}(E)$ is a subset of the boundary of W.

By Theorem 4 of [6] for every $e \in E$ there exists a hemisphere K_e^* (it plays the part of K^* in Theorem 1 of [6]) supporting W such that the lune $K \cap K_e^*$ is of thickness $\Delta(W)$ with e as the center of K/K_e^* . By Proposition 1, for every e the hemisphere K_e^* is unique. For every $e \in E$ denote by t_e the center of K_e^*/K and by k_e the boundary point of K such that $t_e \in ok_e$, where o is the center of K. So e, k_e are antipodes. Denote the set of all these points k_e by Q.

Clearly, the ball $B = B_{\Delta(W)-\frac{\pi}{2}}(o)$ (as in Part III of Theorem 1 in [6]) touches W from inside at every point t_e . Moreover, from the proof of Theorem 1 of [6] and from the earlier established fact that every $e \in E$ is the center of K/K_e^* and every t_e is the center of K_e^*/K we obtain that o belongs to all the arcs of the form et_e .

Put $U = \operatorname{conv}(Q \cup \{o\})$. Denote by U_B the intersection of U with the boundary of B, and by U_W the intersection of U with the boundary of W. Having this construction in mind we see the following one-to-one correspondence between some pairs of points in U_B and U_W . Namely, between the pairs of points of U_B and U_W such that each pair is on the arc connecting o with a point of $\operatorname{conv}(Q)$.

Now, we will show that $U_W = U_B$. Assume the opposite. By the preceding paragraph, our opposite assumption means that there is a point x which belongs to U_W but not to U_B . Hence $|xo| > \Delta(W) - \frac{\pi}{2}$. Moreover, there is a boundary point y of the (d-1)-dimensional great sphere bounding K such that $o \in xy$ and a point $y' \in oy$ at distance $\Delta(W) - \frac{\pi}{2}$ from y.

We have $|xy'| = |xo| + |oy| - |yy'| > (\Delta(W) - \frac{\pi}{2}) + \frac{\pi}{2} - (\Delta(W) - \frac{\pi}{2}) = \frac{\pi}{2}.$

By Lemma 5 the point x belongs the convex hull of a finite set of extreme points of W. Assume for a while that all these extreme points are at distance at most $\frac{\pi}{2}$ from y'. Therefore all of them are contained in H(y'). Thus their convex hull is contained in H(y') and so $x \in H(y')$. This contradicts the fact established in the preceding paragraph that $|xy'| > \frac{\pi}{2}$. The contradiction shows that at least one of these extreme points is at distance larger than $\frac{\pi}{2}$ from y'. Take such a point z for which $|zy'| > \frac{\pi}{2}$.

Since z is an extreme point of W, by Theorem 4 of [6] it is the center of one of the (d-1)-dimensional hemispheres bounding a lune L of thickness $\Delta(W)$ which contains W. Hence by the third part of Lemma 3 of [6] every point of L different from the center of the other (d-1)-dimensional hemisphere bounding L is at distance smaller than $\Delta(W)$ from z. Taking into account that the distance of these centers is $\Delta(W)$ we see that the distance of every point of L, and in particular of W, from z is at most $\Delta(W)$.

By Theorem 1 the ball $B_{\Delta(W)-\frac{\pi}{2}}(y')$ touches W from inside at y.

For the boundary point v of this ball such that $y' \in zv$ we have $|zv| = |zy'| + |y'v| > \frac{\pi}{2} + (\Delta(W) - \frac{\pi}{2}) = \Delta(W)$, which by $v \in W$ contradicts the result of the preceding paragraph. Consequently, $U_W = U_B$.

Since $U_W = U_B$, the ball *B* touches *W* from inside at every point of U_B , in particular at the point t_p such that $o \in pt_p$. Therefore by Part III of Theorem 1 in [6] there exists a hemisphere K_p^* supporting *W* at t_p , such that t_p is the center of K_p^*/K , *p* is the center of K/K_p^* and the lune $L = K \cap K_p^*$ is of thickness $\Delta(W)$. Consequently, *L* is a lune announced in our theorem. \Box

If the body W from Theorem 3 is of constant width greater than $\frac{\pi}{2}$, then by Proposition 1 it is smooth. Thus at every $p \in bd(W)$ there is a unique supporting hemisphere of W, and so the lune L from the formulation of this theorem is unique. If the constant width of W is at most $\frac{\pi}{2}$, there are nonsmooth bodies of constant width (e.g., a Reuleaux triangle on S^2) and then for non-smooth $p \in bd(W)$ we may have more such lunes.

Our Theorem 3 and Claim 2 in [6] imply the first sentence of the following corollary. The second sentence follows from Proposition 1 and the last part of Lemma 3 in [6].

Corollary 6. For every convex body $W \subset S^d$ of constant width w and for every $p \in bd(W)$ there exists $q \in bd(W)$ such that |pq| = w. If $w > \frac{\pi}{2}$, this q is unique.

Theorem 4. If $W \subset S^d$ is a body of constant width w, then diam(W) = w.

Proof. If diam $(W) \leq \frac{\pi}{2}$, then the statement is an immediate consequence of Theorem 3 in [6].

Assume that diam $(W) > \frac{\pi}{2}$. Take an arc pq in W such that |pq| = diam(W). By Corollary 1 this hemisphere K orthogonal to pq at p which contains q, contains also W. The center of K lies strictly inside pq and thus by Part III of Theorem 1 in [6] we have $w > \frac{\pi}{2}$

Having Theorem 3 in mind, consider a lune $L \supset W$ with $\Delta(L) = \Delta(W)$ such that p is the center of a (d-1)-dimensional hemisphere bounding L. Clearly, $q \in W \subset L$. Since W is of constant width $w > \frac{\pi}{2}$, we have $\Delta(L) > \frac{\pi}{2}$.

Thus from the last part of Lemma 3 of [6] it easily follows that the center of the other (d-1)-dimensional hemisphere bounding L is a farthest point of L from p. Since it is at distance w from p, we obtain $w \ge |pq| = \text{diam}(W)$.

On the other hand, by Proposition 1 of [6] we have $w \leq \operatorname{diam}(W)$.

As a consequence, $\operatorname{diam}(W) = w$.

4. Constant width and constant diameter

We say that a convex body $W \subset S^d$ is of constant diameter w if the following two conditions hold true

(i) $\operatorname{diam}(W) = w$,

(ii) for every boundary point p of W there exists a boundary point p' of W with |pp'| = w.

This definition is analogous to the Euclidean notion (compare the beginning of Part 7.6 of [11] for the Euclidean plane, and the bottom of p. 53 of [1] also for higher dimensions). Here is a theorem similar to the planar Euclidean version from [11] (see the beginning of Part 7.6).

Theorem 5. Every spherical convex body $W \subset S^d$ of constant width w is of constant diameter w. Every spherical convex body $W \subset S^d$ of constant diameter $w \geq \frac{\pi}{2}$ is of constant width w.

Proof. For the proof of the first statement of our theorem assume that W is of constant width w. Theorem 4 implies (i) and Corollary 6 implies (ii), which means that W is of constant diameter w.

Let us prove the second statement. Let $W \subset S^d$ be a spherical body of constant diameter $w \geq \frac{\pi}{2}$. We have to show that W is a body of constant width w.

Consider an arbitrary hemisphere K supporting W. As an immediate consequence of two facts from [6], namely Theorem 3 and Proposition 1, we obtain that

$$\mathrm{width}_K(W) \le w. \tag{4}$$

Let us show that width_K(W) = w.

Make the opposite assumption (that is width_K(W) $\neq w$) in order to provide an indirect proof of this equality. By (4) this opposite assumption implies that width_K(W) < w.

Consider two cases.

At first consider the case when $w > \pi/2$.

Put $w' = \text{width}_K(W)$. There exists a hemisphere M supporting W such that $\Delta(K \cap M) = w'$. Denote the center of K/M by a and the center of M/K by b. From Corollary 2 of [6] we see that $b \in \text{bd}(W)$.

We have $\frac{\pi}{2} < w'$ since the opposite means $w' \leq \frac{\pi}{2}$ and then every point of the lune $K \cap M$ is at distance at most $\frac{\pi}{2}$ from the center *b* of M/K (for $w' = \frac{\pi}{2}$ this is clear by $K \cap M \subset H(b)$, and consequently this is also true if $w' < \frac{\pi}{2}$). Since *b* is a boundary point of our body *W* of constant diameter $w > \pi/2$, we get a contradiction to (ii).

Since b is a boundary point of the body W of constant diameter, by the assumption (ii) there exists $b' \in bd(W)$ such that |bb'| = w. By the definition of the thickness of a lune, we have |ab| = w'. Observe that the last part of Lemma 3 of [6] implies that $|uc_{H/G}| \leq |c_{G/H}c_{H/G}|$ for every point u of the lune $H \cap G$. This observation applies to our lune $K \cap M$ since $\Delta(K \cap M) > \frac{\pi}{2}$ (i.e., $w' > \frac{\pi}{2}$). Hence we obtain $|b'b| \leq |ab|$, which by the first two sentences of

638

this paragraph gives $w \leq w'$. This contradicts the inequality w' < w resulting from our opposite assumption that width_K(W) $\neq w$.

Consequently, width_K(W) = w.

Now consider the case when $w = \frac{\pi}{2}$.

From width_K(W) < w (resulting from our opposite assumption) we obtain width_K(W) < $\pi/2$. Thus $\Delta(K \cap K^*) < \frac{\pi}{2}$. Denote by b the center of K^*/K . From Corollary 2 of [6] we see that $b \in bd(W)$.

The set $D = (K/K^*) \cap (K^*/K)$ of corner points of $K \cap K^*$ is isomorphic to S^{d-2} . Moreover, S^k contains at most k + 1 points pairwise distant by $\frac{\pi}{2}$, which follows from the fact (which is easy to show) that every set of at least k+2 points pairwise equidistant on S^k must be the set of vertices of a regular simplex inscribed in S^k (still the distances of these vertices are not $\frac{\pi}{2}$). Putting k = d - 2, we see that D contains at most d - 1 points pairwise distant by $\frac{\pi}{2}$. Therefore there exists a set P_{max} of the maximum number (being at most d - 1) of points of $W \cap D$ pairwise distant by $\frac{\pi}{2}$.

Put $T = \operatorname{conv}(P_{max} \cup \{b\})$. Clearly, $T \subset W$, and since moreover $T \subset \operatorname{bd}(K^*)$ and $W \subset K^*$, we obtain $T \subset \operatorname{bd}(W)$. Take a point x from the relative interior of T. The inclusion $T \subset \operatorname{bd}(W)$ implies that $x \in \operatorname{bd}(W)$. Hence by (ii) there exists $y \in \operatorname{bd}(W)$ such that $|xy| = \frac{\pi}{2}$. By Lemma 2 we have $T \subset \operatorname{bd}(H(y))$. By this inclusion and $b \in T$ we obtain $|by| = \frac{\pi}{2}$. Thus by Lemma 3 we have $y \in D$. As a consequence, the set $P_{max} \cup \{y\}$ is a set of points of $W \cap D$ pairwise distant by $\frac{\pi}{2}$. This set has a greater number of points than the set P_{max} . This contradiction shows that our assumption width_K(W) $\neq w$ is wrong. So width_K(W) = w.

In both cases, from the arbitrariness of the hemisphere K supporting our convex body W we get that W is a body of constant width w.

Problem. Is every spherical body of constant diameter $w < \frac{\pi}{2}$ a body of constant width w?

Open Access. This article is distributed under the terms of the Creative Commons Attribution 4.0 International License (http://creativecommons.org/licenses/by/4.0/), which permits unrestricted use, distribution, and reproduction in any medium, provided you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons license, and indicate if changes were made.

References

- Chakerian, G.D., Groemer, H.: Convex bodies of constant width. In: Gruber, P.M., Wills, J.M. (eds.) Convexity and its Applications, pp. 49–96. Birkhauser, Basel (1983)
- [2] Danzer, L., Grünbaum, B., Klee, V.: Hellys theorem and its relatives. In: Proceedings of Symposia in Pure Mathematics, vol. VII, Convexity, pp. 99–180 (1963)
- [3] Gonzalez Merino, B., Jahn, T., Polyanskii, A., Wachsmuth, G.: Hunting for reduced polytopes, to appear in Discrete Comput. Geom. (see also arXiv:1701.08629v1)

- [4] Hadwiger, H.: Kleine Studie zur kombinatorischen Geometrie der Sphäre. Nagoya Math. J. 8, 45–48 (1955)
- [5] Han, H., Nishimura, T.: Self-dual shapes and spherical convex bodies of constant width $\pi/2$. J. Math. Soc. Jpn. **69**, 1475–1484 (2017)
- [6] Lassak, M.: Width of spherical convex bodies. Aequat. Math. 89, 555-567 (2015)
- [7] Lassak, M., Martini, H.: Reduced convex bodies in Euclidean space—a survey. Expos. Math. 29, 204–219 (2011)
- [8] Lassak, M., Musielak, M.: Reduced spherical convex bodies, Bull. Polish Acad. Sci. Math., to appear (see also arXiv:1607.00132v1)
- [9] Leichtweiss, K.: Curves of constant width in the Non-Euclidean geometry. Abh. Math. Sem. Univ. Hambg. 75, 257–284 (2005)
- [10] Santalo, L.A.: Note on convex spherical curves. Bull. Am. Math. Soc. 50, 528–534 (1944)
- [11] Yaglom, I.M., Boltyanskij, V.G.: Convex figures, Moscov (1951). (English translation, Holt, Rinehart and Winston, New York 1961)
- [12] Van Brummelen, G.: Heavenly Mathematics. The Forgotten Art of Spherical Trigonometry. Princeton University Press, Princeton (2013)

Marek Lassak and Michał Musielak Institute of Mathematics and Physics University of Science and Technology al. Kaliskiego 7 85-796 Bydgoszcz Poland e-mail: marek.lassak@utp.edu.pl

Michał Musielak e-mail: michal.musielak@utp.edu.pl

Received: April 13, 2017 Revised: December 17, 2017