

Classification of $5d \mathcal{N} = 1$ gauge theories

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ABSTRACT: We classify $5d \mathcal{N} = 1$ gauge theories carrying a simple gauge group that can arise by mass-deforming $5d$ SCFTs and $6d$ SCFTs (compactified on a circle, possibly with a twist). For theories having a $6d$ UV completion, we determine the tensor branch data of the $6d$ SCFT and capture the twist in terms of the tensor branch data. We also determine the dualities between these $5d$ gauge theories, thus determining the sets of gauge theories having a common UV completion.

KEYWORDS: Field Theories in Higher Dimensions, M-Theory, Supersymmetric Gauge Theory

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1 Introduction

The study of five and six dimensional supersymmetric gauge theories provides an interesting window to the study of the strong coupling behavior of quantum field theory. This comes about as these theories are perturbatively non-renormalizable, yet appear to exist at low energies when interacting fixed points in these dimensions are mass-deformed. As a result, the underlying microscopic theories in these cases are intrinsically strongly coupled conformal quantum field theories, and it is hoped that a better understanding of this relation can teach us much about the strong coupling behavior of quantum field theory. Additionally, by compactifying these fixed point theories on various manifolds, many interesting theories in lower dimensions can be generated, and much of their surprising behavior elucidated, as was originally advocated in [1]. Thus, the study of higher dimensional theories also has the potential to teach us much about the behavior of lower dimensional ones.

While what was said so far may also be relevant for non-supersymmetric gauge theories, most of the study on higher dimensional gauge theories has been devoted to the supersymmetric cases, as the added supersymmetry provides us with tools that greatly facilitates this study from either the field theory or string theory directions.¹ In the case of supersymmetric five dimensional gauge theories, these were initially studied in the past from field theory [6–8], using brane systems [9–11], and from geometry using compactifications of M-theory on Calabi-Yau three folds [12]. Recently the interest in this field of study has been rekindled, and much work has been done to further the study on all fronts notably from field theory [13–22], using brane systems [23–41], and even more recently from geometry [42–65].

These recent series of works addressed many questions of interest in the study of higher dimensional theories. One notable such question is the classification of five dimensional gauge theories and five dimensional SCFTs. The latter refers to the task of enumerating all $5d$ SCFTs, while the former refers to the question of which $5d$ gauge theories can be generated by a mass deformation of a $5d$ SCFT,² that is what are all the $5d$ gauge theories that

¹For a recent attempt to study a non-supersymmetric $5d$ fixed point see [2], and [3–5] for some less recent ones.

²Some clarifications appropriate for the five dimensional case are in order. For $5d$ supersymmetric gauge theories the relation is generically that there is an underlying $5d$ SCFT that can be made to flow to the gauge theory via a mass deformation. The mass deformations used are then manifested in the low-energy gauge theory as the gauge coupling constants. The interesting aspect of this relation is that it appears that many of the states in the $5d$ SCFT that were made massive by the deformation can still be recovered in the gauge theory where they appear as instantonic states. This is most notable in the study of supersymmetric partition function of these theories, notably the superconformal index, which generically forms characters of the global symmetry of the $5d$ SCFT rather than just the global symmetry of the $5d$ gauge theory, see for instance [13, 15, 16]. It is not clear at this moment whether or not this extends also to the non-BPS spectrum. Regardless, in this paper, when talking about the relation between $5d$ gauge theories and SCFTs, we shall mean it in this context.

exist as microscopic $5d$ theories. It is convenient in this context to extend the definition slightly and also allow $5d$ gauge theories that can arise via a mass-deformation of a $6d$ SCFT compactified on a circle,³ that is to consider the full space of $5d$ gauge theories that have a UV completion as a quantum field theory. It should be noted that these two classification programs are, while related, distinct. This comes about as, first, a single $5d$ SCFT can be deformed in multiple ways so as to lead to different $5d$ gauge theories, a phenomena referred to as continuation past infinite coupling, fiber-base duality or simply as duality, see for instance [9, 15, 16, 23]. Alternatively, there are $5d$ SCFTs that cannot be mass deformed to a $5d$ gauge theory, the first known example of which is probably the so called E_0 SCFT discovered in [7]. Therefore, given a classification of $5d$ SCFTs, one would also need to understand their possible mass deformations in order to also get a classification of $5d$ gauge theories. Similarly, given a classification of $5d$ gauge theories, one would need to supplement this with the list of all $5d$ SCFTs without a gauge theory deformation, as well as understanding the various dualities between them in order to also get a classification of $5d$ SCFTs.

The purpose of this article is to begin an exploration of the classification of $5d$ supersymmetric gauge theories using the geometric approach. In any classification attempt some sort of strategy, or a set of simplifying assumptions is required. Unlike the case in $4d$ or $6d$ for gauge theories with the same amount of supersymmetries [66, 67], there is no obvious field theoretic criteria for when a $5d$ supersymmetric gauge theory possesses an SCFT UV completion. So far, the most promising criteria appear to be the ones proposed in [21], which are a set of constraints on the prepotential of the gauge theory. For the most part we will not have need of the explicit conditions in this article, and so would not review them here, rather reverting to mentioning several points of note.

Depending on how a given gauge theory meets the criteria, the theory is deemed as either ruled in, ruled out or marginal. A ruled in gauge theory should have a $5d$ SCFT UV completion, a marginal theory should have a $6d$ SCFT UV completion and a ruled out should have no SCFT UV completion. It should be noted though that these criteria are thought to be necessary, but are known to be insufficient, that is a $5d$ supersymmetric gauge theory obeying these criteria may still not have an SCFT UV completion.⁴ Here, we shall assume that these criteria are indeed necessary and try to verify which of the gauge theories obeying these criteria indeed exist. The latter is to be accomplished using geometrical methods. As there are many possible gauge theories, we shall here concentrate on the simpler cases of gauge theories containing only a single simple gauge group. We leave open the analysis of quiver theories to future works.

As the list of all such gauge theories obeying the criteria of [21] were already determined in that work, all that remains for us here is to go over the list of theories and check whether these indeed have an SCFT UV completion. To do this, we analyze a local geometric setup in M-theory constructing each marginal theory appearing in [21]. The rules for

³Here, similar clarifications as mentioned in the purely $5d$ case, also apply.

⁴More accurately, it is expected that the behavior of the theory be no better than that expected from the criteria in the following order: $5d$ SCFT UV completion, $6d$ SCFT UV completion, no UV completion. In other words, a theory not obeying the conditions has no UV completion, marginal theories should have either a $6d$ SCFT UV completion or none, and ruled in theories may behave in either one of the three ways.

translating $5d$ gauge theories into local portions of Calabi-Yau threefolds, and vice-versa, are discussed in section 2 of [61] and in section 3.2 of the present paper. Performing flops and isomorphisms on this local geometric setup, it is often possible to represent the local geometry for the marginal theory in a form from which it is manifest that it describes a $6d$ SCFT compactified on a circle with a twist.⁵ The information about the corresponding $6d$ SCFT and the twist can be read from the details of the geometry when it is represented in this form. See sections 3.3 and 3.4 for more details. Once we find that a shrinkable geometry exists for a marginal theory, we are guaranteed that the geometries for theories obtained by integrating out matter from the marginal theory will be shrinkable as well. Not only that, these geometries are guaranteed to satisfy conditions proposed in [47] which should guarantee that the corresponding geometries give rise to $5d$ SCFTs. Our results also include some $5d$ gauge theories which UV complete into $5d$ SCFTs but cannot be obtained by integrating out matter from a $5d$ KK theory. The geometries corresponding to these theories were shown to satisfy the shrinkability criteria of [47] in the recent work [63]. As discussed in [63], these $5d$ SCFTs can still be obtain from $5d$ KK theories if one allows more complicated processes as compared to simple integration out of matter. Integrating out matter can be thought as integrating out BPS particles from the extended Coulomb branch of the $5d$ KK theory. A more general process involves integrating out both BPS strings and BPS particles from the extended Coulomb branch of the $5d$ KK theory. See [63] for more details.

In this paper, we also uncover all the dualities between $5d$ gauge theories with a simple gauge group, having UV completions as $5d$ SCFTs and $5d$ KK theories.⁶ To identify these, we use the results discussed in last paragraph and collect all the $5d$ gauge theories having UV completion into the same $5d$ KK theory. These gauge theories must be dual to each other. Identifying dualities between $5d$ gauge theories UV completing into $5d$ SCFTs requires some more work but these dualities can be obtained from dualities of $5d$ gauge theories having UV completion as KK theories.⁷ A duality between two gauge theories means that geometries corresponding to the two $5d$ gauge theories should be the same upto flops and isomorphisms. Since we already know all dualities between $5d$ gauge theories having a $6d$ UV completion, we find a sequence of geometric manipulations (i.e. flops and isomorphisms) taking the geometry associated to gauge theory on one side of each such duality to the geometry associated to the gauge theory on the other side of the duality. Then we integrate out matter from both sides of the duality which corresponds to blowing down the two geometries. If the sequence of geometric manipulations implementing duality is

⁵As discussed in sections 3.3 and 3.4, this form of the geometry satisfies conditions proposed in [47] which should guarantee that this local geometric piece can be shrunk and the physics associated to it be decoupled from the rest of M-theory.

⁶We use the term “ $5d$ KK theory” to mean a $6d$ SCFT compactified on a circle possibly with some twist.

⁷This exhausts the list of all possible dualities between $5d$ gauge theories whose UV completion is a $5d$ SCFT that can be obtained by integrating out matter from a $5d$ KK theory. This is because as pointed out in [61], once a duality between two $5d$ gauge theories is found, one can add matter to both sides of the duality and the resulting gauge theories remain dual, until we reach gauge theories having a $6d$ SCFT UV completion. For $5d$ gauge theories whose UV completion is a $5d$ SCFT that cannot be obtained by integrating out matter from a $5d$ KK theory, we find the corresponding dualities by performing operations discussed in [61].

left undisturbed after the blowdown, the resulting $5d$ gauge theories are dual to each other. If the sequence of geometric manipulations is obstructed by the blowdowns, the resulting $5d$ gauge theories are not dual to each other. In this way, we find all the possible dualities between the $5d$ gauge theories having $5d$ SCFT UV completion that we consider here.

The structure of this article is as follows. In section 2, we collect all the results obtained in this paper in one place for the ease and convenience of the reader. Section 2.1 collects all the $5d$ gauge theories having a UV completion as a $5d$ KK theory, organized according to the gauge algebras. Section 2.2 collects all the $5d$ gauge theories having a UV completion as a $5d$ SCFT, organized according to the gauge algebras. Section 2.3 collects all the $5d$ gauge theories which are allowed by the criteria of [21] but which we can rule out based using our geometric analysis. Section 2.4 collects all the $5d$ gauge theories allowed by the criteria of [21] but which we cannot rule out or rule in using our geometric analysis. Section 2.5 collects all the dualities between $5d$ gauge theories having UV completion either as a $5d$ KK theory or a $5d$ SCFT. Section 2.6 discusses the connection of our work with the classification program for $5d$ SCFTs. Section 3 describes the general features of our geometric methods in detail. Section 3.1 discusses general consistency conditions that all local geometries need to satisfy. Section 3.2 discusses the structure of a geometry corresponding to a $5d$ gauge theory. Section 3.3 discusses the structure of a geometry corresponding to a twisted circle compactification of a $6d$ gauge theory. Section 3.4 discusses the structure of a geometry corresponding to a $5d$ KK theory and how to read the data of the $6d$ SCFT and twist from the geometry. Section 4 provides detailed arguments for the results presented in this paper, organized according to rank.

2 Summary of results

In this section we shall summarize our results for the theories, where there is evidence from geometry that they have a $5d$ or $6d$ UV completion. The generic structure is that these cases can be grouped into families, where at the top we have a gauge theory with a $6d$ SCFT UV completion, and the rest of the gauge theories in the family can be generated by integrating out matter, and have a $5d$ SCFT UV completion. It should be noted though that there are a few exceptions to this behavior [63]. We shall next write down our results for the cases with a $6d$ SCFT UV completion, which we refer to as $5d$ KK theories. Cases with a $5d$ SCFT UV completion are then obtained by integrating out matter from these cases, in addition to the handful of cases that don't descend from integrating matter out of a KK gauge theory. These cases will be discussed afterward. Finally, there are a handful of cases where we were not able to determine whether the theory has an SCFT UV completion or not, and these cases will be reported at the end. We also collect theories satisfying the criteria of [21] but which are ruled to be inconsistent by our methods.

Many of the theories we find from geometry were previously found using other methods, notably brane systems. The latter usually fall to one of two types. One is the type I' string theory configuration involving a system of D4-branes and D8-branes probing an $O8^-$ background. This type of systems was originally used in [6] to realize $5d$ SCFTs, and can be generalized by the addition of an orbifold singularity [68]. The second type is brane webs [9–11], which involve a type IIB configuration of D5-branes, NS5-branes and

D7-branes. These can be generalized by the addition of orientifold planes [28, 32, 33, 69]. One other method to study 5d SCFTs is using holography through a gravity dual. This method, however, is related to the previous one as all known holographic duals of 5d SCFTs are thought to be near horizon limits of one of the two types of brane systems. Notably, there is the older gravity dual of [70], and its orbifold generalization [68], that are based on the type I' brane system. More recently, gravity duals believed to describe the near horizon limit of 5-brane web systems were found [71–73]. These have since been extended to also cover brane web systems involving mutually local 7-branes [74] and orientifold 7-planes [75]. Thus, in many cases having a brane realization also implies the existence of a holographic dual, though there are still types of brane systems with no known holographic dual, like ones involving mutually non-local 7-branes or orientifold 5-planes, at least at this point in time. We shall try here to give reference to known brane constructions when they exist, though there are also many cases with no known brane construction, or other previous realizations, and so are new.

To enumerate the gauge theories, we shall mostly adopt the notation of [61]. The gauge theories contain a single gauge group of type G and a collection of n_i hypermultiplets in the representation \mathbf{R}_i , where n_i can be half-integers in representations where half-hypers are possible. To denote representations, we shall use the shorthand notations: \mathbf{F} for the fundamental representation, $\mathbf{\Lambda}^k$ for the rank k antisymmetric representation, \mathbf{S}^k for the rank k symmetric representation, and \mathbf{A} for the adjoint representation. For *Spin* groups, we shall also use \mathbf{S} for the spinor representation and also \mathbf{C} for the other spinor representation if it exists.

For KK theories, we also write down the 6d SCFT lift expected from the geometry. To write these we use the F-theory notation of [76, 77]. Additionally, some of the reductions are done with a twist in a discrete symmetry and we use the notation introduced in [60] to denote that. We turn now to a short review of this notation. The twists are denoted by how they act on the basic matter multiplets: tensors, vectors and hypsers. The twist may act on the vectors as the outer automorphism of the associated gauge symmetry. To denote that, we shall use a superscript above the gauge algebra, where (1) signifies a compactification without such a twist and (2) or (3) signify that the compactification is done with a \mathbb{Z}_2 or \mathbb{Z}_3 outer automorphism twist. The superscript (3) is only used for $\mathfrak{so}(8)$ to denote its \mathbb{Z}_3 outer automorphism, while (2) denotes its \mathbb{Z}_2 outer automorphism. Additionally, the twist may act by permuting the tensor multiplets. This permutation is captured by folding the graph associated to the 6d SCFT according to this permutation.

For instance:

$$\begin{array}{ccc}
 \mathfrak{su}(m)^{(1)} & & \mathfrak{su}(m)^{(1)} \\
 2 & \text{---} & 2 \\
 \frown & & \smile
 \end{array}$$

stands for the twisted compactification of the 6d SCFT with tensor branch description as a linear quiver of four $SU(m)$ groups, with m flavor hypermultiplet for both edge groups, where the twist acts on the quiver via a reflection. In other words, the quiver is shaped like an A_4 Dynkin diagram and the discrete symmetry act on it in the same way charge conjugation acts on the A_4 Dynkin diagram.

As another example, consider:

$$\begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \leftarrow 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}} \\ m-1 \end{array}$$

which denotes the twisted compactification of $D_{m+1}(2,0)$ theory by its outer automorphism discrete symmetry, while

$$\begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 2 \rightarrow 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}} \\ m-1 \end{array}$$

denotes the twisted compactification of $A_{2m-1}(2,0)$ by its outer automorphism discrete symmetry. Additionally, there are cases where the twist acts as a combination of quiver reflections and outer automorphism transformations on some of the gauge groups.

2.1 KK theories

Here we shall enumerate the cases of $5d$ gauge theories with a simple gauge group that have a $6d$ SCFT UV completion. It is convenient to break this to two cases. One are cases that exist for arbitrary rank, while the other are special cases that occur only for low rank. We shall first deal with the general cases and then move on to discuss the special cases.

2.1.1 General rank

We begin with the cases that exist for generic rank. These cases include the maximally supersymmetric classical groups, as well as several $\mathcal{N} = 1$ only cases. The $6d$ lifts for the maximally supersymmetric Yang-Mills cases are well known, see for instance [78], and the results from geometry are consistent with that. For the $\mathcal{N} = 1$ only cases, the $6d$ lifts for most cases is well known, see [21] and references within, and our geometric results are consistent with these. There are, however, a few cases that were undetermined, and the geometric methods allow us to determine them as well. We shall next list our findings for these cases based on the gauge group.

$\mathfrak{su}(m)$:

$$\mathfrak{su}(m)_0 + \mathbf{A} = \underbrace{\begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } \dots \text{ --- } 2 \end{array}}_{m-1} \tag{2.1}$$

$$\mathfrak{su}(m)_0 + (2m+4)\mathbf{F} = \begin{array}{c} \mathfrak{sp}(m-2)^{(1)} \\ 1 \end{array} \tag{2.2}$$

$$\mathfrak{su}(m)_0 + \Lambda^2 + (m+6)\mathbf{F} = \begin{array}{c} \mathfrak{su}(m-1)^{(1)} \\ 1 \end{array} \tag{2.3}$$

$$\mathfrak{su}(m)_{\frac{m}{2}} + \Lambda^2 + 8F = \underbrace{\begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 1 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \end{array}}_{m-2} \quad (2.4)$$

$$\mathfrak{su}(2m)_0 + 2\Lambda^2 + 8F = \underbrace{\begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \\ 1 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \end{array}}_{m-1} \quad (2.5)$$

$$\mathfrak{su}(2m+1)_0 + 2\Lambda^2 + 8F = \underbrace{\begin{array}{c} \mathfrak{sp}(1)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \\ 1 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \end{array}}_{m-1} \quad (2.6)$$

$$\mathfrak{su}(2m+1)_{\frac{3}{2}} + 2\Lambda^2 + 7F = \underbrace{\begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 1 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \text{ --- } 2 \end{array}}_{m-1} \quad (2.7)$$

$$\mathfrak{su}(2m)_{\frac{3}{2}} + 2\Lambda^2 + 7F = \underbrace{\begin{array}{c} \mathfrak{sp}(1)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 1 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \text{ --- } 2 \end{array}}_{m-2} \quad (2.8)$$

$$\mathfrak{su}(m)_0 + S^2 + (m-2)F = \underbrace{\begin{array}{c} \mathfrak{su}(m-1)^{(1)} \\ 2 \end{array}}_{\text{circle}} \quad (2.9)$$

$$\mathfrak{su}(2m)_m + S^2 = \underbrace{\begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \leftarrow 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \end{array}}_{2m-2} \quad (2.10)$$

$$\mathfrak{su}(2m+1)_{m+\frac{1}{2}} + S^2 = \underbrace{\begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \end{array}}_{2m-1} \quad (2.11)$$

$$\mathfrak{su}(2m)_0 + S^2 + \Lambda^2 = \underbrace{\begin{array}{c} \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } \dots \text{ --- } 2 \text{ --- } 2 \text{ --- } 2 \end{array}}_{m-1} \quad (2.12)$$

$$\mathfrak{su}(2m+1)_0 + S^2 + \Lambda^2 = \underbrace{\begin{array}{c} \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \end{array}}_{m-1} \quad (2.13)$$

Our results from geometry are consistent with many of the existing proposals in the literature. Specifically, case (2.1) is just the well known relation between the $6d$ $(2,0)$ theory and $5d$ maximally supersymmetric Yang-Mills theory [79, 80]. Case (2.2) matches the original proposal of [19, 26]. Likewise, case (2.3) matches the original proposal of [29, 30]. In cases (2.4) and (2.13), our results are consistent with the conjectures in [21]. Cases (2.5), (2.6), (2.7) and (2.8) match the $6d$ lifts proposed for these theories in [29]. Finally, our results for case (2.9) matches the lift proposed for this case in [33].

There are a few cases where the geometrical results improve upon the results already known in the literature. Notably, the $6d$ lift of (2.12) was to our knowledge not previously discussed. Our results for cases (2.10) and (2.11) are consistent with the results found in [21] for the case of $\mathfrak{su}(3)$. However, it was conjectured there, based on this case, that the $6d$ lift for higher m is also a twisted compactification of an A type $(2,0)$ theory, while the geometric methods reveal that this is only true for odd m , and the even m cases lift to a twisted compactification of a D type $(2,0)$ theory instead. See section 2.5.1.

$\mathfrak{sp}(m)$:

$$\mathfrak{sp}(m)_0 + A = \begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \leftarrow 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}} \\ m-1 \end{array} \tag{2.14}$$

$$\mathfrak{sp}(m)_\pi + A = \begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}} \\ m-1 \end{array} \tag{2.15}$$

$$\mathfrak{sp}(m) + (2m+6)F = \begin{array}{c} \mathfrak{sp}(m-1)^{(1)} \\ 1 \end{array} \tag{2.16}$$

$$\mathfrak{sp}(m) + \Lambda^2 + 8F = \begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 1 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}} \\ m-1 \end{array} \tag{2.17}$$

For \mathfrak{sp} groups the $6d$ lifts were all previously known in the literature, and our results are consistent with this. Specifically, cases (2.14) and (2.15) are the $5d$ maximally supersymmetric \mathfrak{sp} Yang-Mills theories [78]. Case (2.16) matches the known lift in [30]. Finally, that case (2.17) lifts to the rank m E-string theory is well known from the work of [81]. We also note that all the cases here are dual to cases in the \mathfrak{su} part.

$\mathfrak{so}(m)$:

$$\mathfrak{so}(2m+1) + A = \begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}} \\ m-1 \end{array} \tag{2.18}$$

$$\mathfrak{so}(2m) + A = \begin{array}{c} \mathfrak{su}(1)^{(1)} \\ 2 \\ | \\ \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \cdots \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } \cdots \text{ --- } 2 \\ \underbrace{\hspace{10em}} \\ m-2 \end{array} \quad (2.19)$$

$$\mathfrak{so}(m) + (m-2)F = \frac{\mathfrak{su}(m-2)^{(2)}}{2} \quad (2.20)$$

The lifts for generic \mathfrak{so} cases were, also, all previously known in the literature, and our results are consistent with this. Specifically, cases (2.18) and (2.19) are the $5d$ maximally supersymmetric \mathfrak{so} Yang-Mills theories [78], and case (2.20) matches the $6d$ lift proposed for this case in [33].

Next we are going to consider the cases that only exist for small rank.

2.1.2 Rank 2

$\mathfrak{su}(3)$:

$$\mathfrak{su}(3)_4 + 6F = \frac{\mathfrak{su}(3)^{(2)}}{1} \quad (2.21)$$

$$\mathfrak{su}(3)_{\frac{15}{2}} + F = \frac{\mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)}}{2 \text{ --- } 3 \text{ --- } 2} \quad (2.22)$$

$$\mathfrak{su}(3)_9 = \frac{\mathfrak{su}(3)^{(2)}}{3} \quad (2.23)$$

All these cases have already appeared in the literature. Specifically, cases (2.21) and (2.23) were originally discovered from geometry in [47], with brane realizations following in [38]. Case (2.22) was found more recently in [59], also from geometry.

$\mathfrak{sp}(2)$:

$$\mathfrak{sp}(2) + 2\Lambda^2 + 4F = \frac{\mathfrak{su}(3)^{(2)}}{1} \quad (2.24)$$

$$\mathfrak{sp}(2)_0 + 3\Lambda^2 = \frac{\mathfrak{su}(3)^{(2)}}{2} \quad (2.25)$$

Here as well all cases have already appeared in the literature. Specifically, case (2.24) is dual to (2.21), a result originally found in [47]. Since $\mathfrak{sp}(2) = \mathfrak{so}(5)$, case (2.25) is in fact just the $m = 5$ case of (2.20). However, we have here separated it as for this case there is also the possibility to turn on a theta angle for the $\mathfrak{sp}(2)$. The $m = 5$ case of (2.20) is then the one with $\theta = 0$, while the $\theta = \pi$ case appears to have no SCFT UV completion. This

was first noted in the geometrical work of [47], and our results further support this as they suggest that its associated geometry is dual to $\mathfrak{g}_2 + A + 2F$ which is not a UV complete theory as it has more matter than the KK theory $\mathfrak{g}_2 + A$.

\mathfrak{g}_2 :

$$\mathfrak{g}_2 + A = \begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 3 \text{ --- } 2 \end{array} \quad (2.26)$$

$$\mathfrak{g}_2 + 6F = \begin{array}{c} \mathfrak{su}(3)^{(2)} \\ 1 \end{array} \quad (2.27)$$

Case (2.26) is again one of the $5d$ maximally supersymmetric Yang-Mills theories, whose $6d$ lift was worked out previously [78]. Case (2.27) is also dual to (2.21) and (2.24), a result originally found in [47].

2.1.3 Rank 3

$\mathfrak{su}(4)$:

$$\mathfrak{su}(4)_4 + 6F = \begin{array}{c} \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \\ 3 \text{ --- } 2 \text{ --- } 1 \end{array} \quad (2.28)$$

$$\mathfrak{su}(4)_8 = \begin{array}{c} \mathfrak{so}(8)^{(3)} \\ 4 \end{array} \quad (2.29)$$

$$\mathfrak{su}(4)_6 + 2\Lambda^2 = \begin{array}{c} \mathfrak{so}(8)^{(3)} \\ 2 \end{array} \quad (2.30)$$

$$\mathfrak{su}(4)_0 + 3\Lambda^2 + 4F = \begin{array}{c} \mathfrak{su}(4)^{(2)} \\ 1 \end{array} \quad (2.31)$$

$$\mathfrak{su}(4)_1 + 3\Lambda^2 + 4F = \begin{array}{c} \mathfrak{g}_2^{(1)} \\ 1 \end{array} \quad (2.32)$$

$$\mathfrak{su}(4)_2 + 3\Lambda^2 + 4F = \begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)} \\ 1 \text{ --- } 2 \end{array} \quad (2.33)$$

$$\mathfrak{su}(4)_5 + 3\Lambda^2 = \begin{array}{c} \mathfrak{so}(8)^{(3)} \\ 1 \end{array} \quad (2.34)$$

$$\mathfrak{su}(4)_0 + 4\Lambda^2 = \begin{array}{c} \mathfrak{su}(4)^{(2)} \\ 2 \end{array} \quad (2.35)$$

$$\mathfrak{su}(4)_2 + 4\Lambda^2 = \begin{array}{c} \mathfrak{g}_2^{(1)} \\ 2 \end{array} \quad (2.36)$$

$$\mathfrak{su}(4)_4 + 4\Lambda^2 = \begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)} \\ 1 \text{ --- } 3 \end{array} \quad (2.37)$$

Most of the cases here are, to our knowledge, new. The notable exceptions are cases (2.29) and (2.35). Case (2.35) is just the $m = 6$ case of (2.20), though we have singled it out here since for this case there is also the possibility of a Chern-Simons level, and the case fitting in (2.20) is the one with Chern-Simons level zero. The lift for case (2.29) was conjectured in [82], and our results are consistent with the conjecture there. Note also that while all the reductions in this section were discussed in [59], they were not given a gauge theory interpretation there.

sp(3):

$$\mathfrak{sp}(3)_0 + 2\Lambda^2 = \frac{\mathfrak{so}(8)^{(3)}}{2} \tag{2.38}$$

$$\mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \frac{19}{2}F = \frac{\mathfrak{sp}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)}}{1 \text{ --- } 2} \tag{2.39}$$

$$\mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \Lambda^2 + \frac{5}{2}F = \frac{\mathfrak{so}(8)^{(3)}}{1} \tag{2.40}$$

$$\mathfrak{sp}(3) + \Lambda^3 + 5F = \frac{\mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)}}{3 \text{ --- } 2 \text{ --- } 1} \tag{2.41}$$

Here, cases (2.38) and (2.40) are new. In cases (2.39) and (2.41), a brane web was found in [40] from which it was suggested that these cases lift to $6d$, though the exact $6d$ SCFTs they lift to were not determined. We also note that all cases here are dual to various $\mathfrak{su}(4)$ cases. See section 2.5.1.

so(7):

$$\mathfrak{so}(7) + 6S + F = \frac{\mathfrak{su}(4)^{(2)}}{1} \tag{2.42}$$

$$\mathfrak{so}(7) + 5S + 2F = \frac{\mathfrak{g}_2^{(1)}}{1} \tag{2.43}$$

$$\mathfrak{so}(7) + 4S + 3F = \frac{\mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)}}{1 \text{ --- } 2} \tag{2.44}$$

$$\mathfrak{so}(7) + 2S + 4F = \frac{\mathfrak{su}(5)^{(2)}}{1} \tag{2.45}$$

$$\mathfrak{so}(7) + 7S = \frac{\mathfrak{g}_2^{(1)}}{1} \tag{2.46}$$

The $6d$ lifts for some of the cases here were already considered in the literature, but there are new cases as well. Notably, the $6d$ lifts for cases (2.42) and (2.44) were conjectured by [83], and our findings from geometry support these conjectures. Cases (2.43), (2.45) and (2.46) are, to our knowledge, new. We also note that the cases (2.43) and (2.46) are dual to each-other. See section 2.5.1 for other dualities.

2.1.4 Rank 4

su(5):

$$\mathfrak{su}(5)_0 + 3\Lambda^2 + 3F = \frac{\mathfrak{so}(8)^{(2)}}{1} \quad (2.47)$$

$$\mathfrak{su}(5)_{\frac{3}{2}} + 3\Lambda^2 + 2F = \frac{\mathfrak{su}(1)^{(1)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)}}{2 \text{ --- } 1 \text{ --- } 3} \quad (2.48)$$

Both cases are, to our knowledge, new.

sp(4):

$$\mathfrak{sp}(4) + \frac{1}{2}\Lambda^3 + 4F = \frac{\mathfrak{so}(8)^{(3)} \quad \mathfrak{sp}(0)^{(1)}}{4 \text{ --- } 3 \text{ --- } 1} \quad (2.49)$$

This case is, to our knowledge, new.

so(8):

$$\mathfrak{so}(8) + 4S + 4F = \frac{\mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)}}{1 \text{ --- } 3 \text{ --- } 1} \quad (2.50)$$

$$\mathfrak{so}(8) + 2S + 5F = \frac{\mathfrak{su}(\tilde{6})^{(2)}}{1} \quad (2.51)$$

$$\mathfrak{so}(8) + 3S + C + 4F = \frac{\mathfrak{g}_2^{(1)} \quad \mathfrak{sp}(0)^{(1)}}{2 \text{ --- } 1} \quad (2.52)$$

$$\mathfrak{so}(8) + S + C + 5F = \frac{\mathfrak{su}(6)^{(2)}}{1} \quad (2.53)$$

$$\mathfrak{so}(8) + 3S + 2C + 3F = \frac{\mathfrak{so}(7)^{(1)}}{1} \quad (2.54)$$

$$\mathfrak{so}(8) + 2S + 2C + 4F = \frac{\mathfrak{su}(4)^{(2)} \quad \mathfrak{sp}(0)^{(1)}}{2 \text{ --- } 1} \quad (2.55)$$

The $6d$ lifts for some of the cases here were already considered in the literature. Specifically, the $6d$ lift for case (2.55) was conjectured by [83] and for case (2.50) by [84]. In both cases our findings from geometry support these conjectures. The rest of the cases are, to our knowledge, new. The case (2.51) lifts to the outer-automorphism twisted compactification of $6d$ SCFT whose tensor branch is described by the $6d$ gauge theory $\mathfrak{su}(6) + \frac{1}{2}\Lambda^3 + 15F$. The tilde on top of $\mathfrak{su}(6)$ differentiates this $6d$ SCFT from the cousin $6d$ SCFT whose tensor branch is described by the $6d$ gauge theory $\mathfrak{su}(6) + \Lambda^2 + 14F$.

so(9):

$$\mathfrak{so}(9) + S + 6F = \frac{\mathfrak{su}(7)^{(2)}}{1} \tag{2.56}$$

$$\mathfrak{so}(9) + 2S + 5F = \frac{\mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(5)^{(2)}}{1 \text{ --- } 2} \tag{2.57}$$

$$\mathfrak{so}(9) + 3S + 3F = \frac{\mathfrak{so}(8)^{(2)}}{1} \tag{2.58}$$

$$\mathfrak{so}(9) + 4S + F = \frac{\mathfrak{su}(1)^{(1)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)}}{2 \text{ --- } 1 \text{ --- } 3} \tag{2.59}$$

The $6d$ lifts for some of the cases here were already considered in the literature, but there are new cases as well. Notably, the $6d$ lift for case (2.57) was conjectured by [83], and for case (2.59) by [84]. In both cases our findings from geometry support these conjectures. The remaining cases are, to our knowledge, new.

f₄:

$$\mathfrak{f}_4 + A = \frac{\mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)}}{2 \text{ --- } 2 \text{ --- } 2 \text{ --- } 2} \tag{2.60}$$

Here the only $6d$ lifting case is the maximally supersymmetric one, whose lift was worked out previously [78]. There appears to be no $6d$ lifting case for \mathfrak{f}_4 with fundamental matter, see [63]. There are, however, $5d$ \mathfrak{f}_4 gauge theories with fundamental matter with a $5d$ SCFT UV completion. These will be covered in the next subsection.

2.1.5 Rank 5

su(6):

$$\mathfrak{su}(6)_0 + \frac{1}{2}\Lambda^3 + 13F = \frac{\mathfrak{su}(5)^{(1)}}{1} \tag{2.61}$$

$$\mathfrak{su}(6)_3 + \frac{1}{2}\Lambda^3 + 9F = \frac{\mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)}}{1 \text{ --- } 2 \text{ --- } 2 \text{ --- } 2 \text{ --- } 2} \tag{2.62}$$

$$\mathfrak{su}(6)_0 + \frac{1}{2}\Lambda^3 + \Lambda^2 + 9F = \frac{\mathfrak{su}(3)^{(1)} \quad \mathfrak{su}(2)^{(1)}}{1 \text{ --- } 2} \tag{2.63}$$

$$\mathfrak{su}(6)_{\frac{3}{2}} + \frac{1}{2}\Lambda^3 + \Lambda^2 + 8F = \frac{\mathfrak{sp}(1)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)}}{1 \text{ --- } 2 \text{ --- } 2} \tag{2.64}$$

$$\mathfrak{su}(6)_{\frac{1}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 + 2F = \frac{\mathfrak{f}_4^{(1)}}{1} \tag{2.65}$$

$$\mathfrak{su}(6)_{\frac{3}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 + 2F = \frac{\mathfrak{su}(1)^{(1)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{so}(8)^{(3)}}{2 \text{ --- } 1 \text{ --- } 3} \tag{2.66}$$

$$\mathfrak{su}(6)_1 + 3\Lambda^2 = \frac{\mathfrak{f}_4^{(1)}}{2} \quad (2.67)$$

$$\mathfrak{su}(6)_3 + 3\Lambda^2 = \frac{\mathfrak{su}(1)^{(1)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{so}(8)^{(3)}}{2 \text{ --- } 1 \text{ --- } 4} \quad (2.68)$$

$$\mathfrak{su}(6)_0 + \Lambda^3 + 10F = \frac{\mathfrak{sp}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)}}{1 \text{ --- } 2} \quad (2.69)$$

$$\mathfrak{su}(6)_{\frac{3}{2}} + \Lambda^3 + 9F = \frac{\mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)}}{1 \text{ --- } 2 \text{ --- } 2 \text{ --- } 2} \quad (2.70)$$

$$\mathfrak{su}(6)_0 + \Lambda^3 + \Lambda^2 + 4F = \frac{\mathfrak{so}(8)^{(2)} \quad \mathfrak{sp}(0)^{(1)}}{3 \text{ --- } 2 \text{ --- } 1} \quad (2.71)$$

$$\mathfrak{su}(6)_{\frac{3}{2}} + \Lambda^3 + \Lambda^2 + 3F = \frac{\mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)}}{3 \text{ --- } 1 \text{ --- } 2} \quad (2.72)$$


$$\mathfrak{su}(6)_0 + \frac{3}{2}\Lambda^3 + 5F = \frac{\mathfrak{so}(10)^{(2)}}{1} \quad (2.73)$$


$$\mathfrak{su}(6)_3 + \frac{3}{2}\Lambda^3 + F = \frac{\mathfrak{e}_6^{(2)}}{1} \quad (2.74)$$

$$\mathfrak{su}(6)_{\frac{7}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 = \frac{\mathfrak{e}_6^{(2)}}{1} \quad (2.75)$$

$$\mathfrak{su}(6)_{\frac{9}{2}} + \frac{3}{2}\Lambda^3 = \frac{\mathfrak{e}_6^{(2)}}{3} \quad (2.76)$$

$$\mathfrak{su}(6)_0 + 2\Lambda^3 = \frac{\mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)}}{3 \text{ --- } 1 \text{ --- } 3} \quad (2.77)$$

$$\mathfrak{su}(6)_0 + S^2 + \frac{1}{2}\Lambda^3 + F = \frac{\mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(3)^{(1)}}{2 \text{ --- } 2} \quad (2.78)$$


$$\mathfrak{su}(6)_{\frac{3}{2}} + S^2 + \frac{1}{2}\Lambda^3 = \frac{\mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)}}{2 \text{ --- } 2 \text{ --- } 2} \quad (2.79)$$


Some of the cases appearing here have been previously studied in the literature, while some are new. Specifically, the $6d$ lifts for cases (2.61), (2.69) and (2.78) were conjectured in [40], and our results from geometry are consistent with these conjectures. Additionally, [40] also presented brane constructions for cases (2.62), (2.63), (2.64), (2.70), (2.71), (2.77), and (2.79), from which it was inferred that these are $6d$ lifting though the explicit $6d$ lift was not determined. The remaining cases are new, to our knowledge.

Finally, we note several dualities for theories in this list. Case (2.61) is dual to the $m = 6$ case of (2.3), case (2.62) is dual to the $m = 6$ case of (2.4) and to the $m = 5$ case of (2.17), case (2.64) is dual to the $m = 3$ case of (2.8), and cases (2.75) and (2.74) are dual to each other.

so(10):

$$\mathfrak{so}(10) + 4S + 2F = \frac{\mathfrak{su}(3)^{(2)}}{3} \text{ --- } \frac{\mathfrak{sp}(0)^{(1)}}{1} \text{ --- } \frac{\mathfrak{su}(2)^{(1)}}{2} \tag{2.80}$$

$$\mathfrak{so}(10) + 3S + 4F = \frac{\mathfrak{so}(9)^{(1)}}{1} \tag{2.81}$$

$$\mathfrak{so}(10) + 2S + 6F = \frac{\mathfrak{sp}(0)^{(1)}}{1} \text{ --- } \frac{\mathfrak{su}(6)^{(2)}}{2} \tag{2.82}$$

$$\mathfrak{so}(10) + S + 7F = \frac{\mathfrak{su}(8)^{(2)}}{1} \tag{2.83}$$

The $6d$ lifts for some of the cases here were already considered in the literature. Specifically, the $6d$ lift for case (2.82) was conjectured by [83] and for case (2.80) by [84]. In both cases our findings from geometry support these conjectures. The rest of the cases are, to our knowledge, new.

so(11):

$$\mathfrak{so}(11) + 2S + 3F = \frac{\mathfrak{su}(3)^{(2)}}{3} \text{ --- } \frac{\mathfrak{sp}(0)^{(1)}}{1} \text{ --- } \frac{\mathfrak{su}(3)^{(2)}}{2} \tag{2.84}$$

$$\mathfrak{so}(11) + \frac{3}{2}S + 5F = \frac{\mathfrak{so}(10)^{(2)}}{1} \tag{2.85}$$

$$\mathfrak{so}(11) + \frac{5}{2}S = \frac{\mathfrak{e}_6^{(2)}}{1} \tag{2.86}$$

$$\mathfrak{so}(11) + S + 7F = \frac{\mathfrak{sp}(0)^{(1)}}{1} \text{ --- } \frac{\mathfrak{su}(7)^{(2)}}{2} \tag{2.87}$$

$$\mathfrak{so}(11) + \frac{1}{2}S + 8F = \frac{\mathfrak{su}(9)^{(2)}}{1} \tag{2.88}$$

The $6d$ lifts for some of the cases here were already considered in the literature, but there are new cases as well. Notably, the $6d$ lift for case (2.87) was conjectured by [83], and for case (2.84) by [84]. In both cases our findings from geometry support these conjectures. The remaining cases are, to our knowledge, new. See section 2.5.1 for dualities.

2.1.6 Rank 6

su(7):

$$\mathfrak{su}(7)_0 + \Lambda^3 + 6F = \begin{array}{c} \mathfrak{so}(8)^{(2)} \quad \mathfrak{sp}(1)^{(1)} \\ 3 \text{ --- } 2 \longrightarrow 1 \end{array} \quad (2.89)$$

$$\mathfrak{su}(7)_{\frac{3}{2}} + \Lambda^3 + 5F = \begin{array}{c} \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(5)^{(2)} \\ 3 \text{ --- } 1 \text{ --- } 2 \end{array} \quad (2.90)$$

Both of these cases are new to our knowledge. The 6d SCFT corresponding to the case (2.89) is denoted as

$$\begin{array}{c} \mathfrak{sp}(1) \quad \mathfrak{so}(8) \quad \mathfrak{sp}(1) \\ 1 \text{ - - - - - } 3 \text{ --- } 1 \end{array}$$

in [60] since (upto triality) one of the $\mathfrak{sp}(1)$ gauges a hyper in F of $\mathfrak{so}(8)$ and the other $\mathfrak{sp}(1)$ gauges a hyper in S of $\mathfrak{so}(8)$, where the former gauging is denoted by a solid edge and the latter gauging is denoted by a dashed edge. While compactifying on a circle, the 6d SCFT is twisted by the \mathbb{Z}_2 outer automorphism of $\mathfrak{so}(8)$ which exchanges F and S thus folding the dashed edge onto the solid edge. Consequently, we denote the KK theory with a partially solid and partially dashed edge.

so(12):

$$\mathfrak{so}(12) + 2S + 4F = \begin{array}{c} \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \\ 3 \text{ --- } 1 \text{ --- } 3 \text{ --- } 1 \end{array} \quad (2.91)$$

$$\mathfrak{so}(12) + \frac{3}{2}S + C + F = \begin{array}{c} \mathfrak{e}_6^{(2)} \quad \mathfrak{sp}(0)^{(1)} \\ 3 \text{ --- } 2 \longrightarrow 1 \end{array} \quad (2.92)$$

$$\mathfrak{so}(12) + \frac{3}{2}S + \frac{1}{2}C + 4F = \begin{array}{c} \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{g}_2^{(1)} \\ 3 \text{ --- } 1 \text{ --- } 2 \end{array} \quad (2.93)$$

$$\mathfrak{so}(12) + S + \frac{1}{2}C + 6F = \begin{array}{c} \mathfrak{so}(11)^{(1)} \\ 1 \end{array} \quad (2.94)$$

$$\mathfrak{so}(12) + \frac{3}{2}S + 6F = \begin{array}{c} \mathfrak{so}(11)^{(1)} \\ 1 \end{array} \quad (2.95)$$

$$\mathfrak{so}(12) + S + C + 4F = \begin{array}{c} \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(4)^{(2)} \\ 3 \text{ --- } 1 \text{ --- } 2 \end{array} \quad (2.96)$$

$$\mathfrak{so}(12) + S + 8F = \begin{array}{c} \mathfrak{sp}(0)_0^{(1)} \quad \mathfrak{su}(8)^{(2)} \\ 1 \text{ --- } 2 \end{array} \quad (2.97)$$

$$\mathfrak{so}(12) + \frac{1}{2}S + \frac{1}{2}C + 8F = \begin{array}{c} \mathfrak{sp}(0)_\pi^{(1)} \quad \mathfrak{su}(8)^{(2)} \\ 1 \text{ --- } 2 \end{array} \quad (2.98)$$

$$\mathfrak{so}(12) + \frac{1}{2}S + 9F = \begin{array}{c} \mathfrak{su}(10)^{(2)} \\ 1 \end{array} \quad (2.99)$$

The $6d$ lifts for some of these cases were already considered in the literature. Specifically, the $6d$ lift for cases (2.98) and (2.97) were conjectured by [83]. As explained there, these two cases differ by the embedding of the $\mathfrak{su}(8)$ gauge symmetry on the -2 curve in the \mathfrak{e}_8 global symmetry associated with the empty -1 curve. As this difference becomes the theta angle of the $\mathfrak{sp}(n)$ gauge group if it is turned on the -1 curve [85], we differentiate the two cases by denoting this angle even though $n = 0$ here. Additionally, cases (2.91), (2.93) and (2.96) were conjectured by [84]. Our results from geometry support these conjectures in all cases.

The remaining cases are all new to our knowledge. We also note that the two cases (2.94) and (2.95) are dual to each other.

$\mathfrak{so}(13)$:

$$\mathfrak{so}(13) + S + 5F = \begin{array}{c} \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(5)^{(2)} \\ 3 \text{ --- } 1 \text{ --- } 2 \end{array} \quad (2.100)$$

$$\mathfrak{so}(13) + \frac{1}{2}S + 9F = \begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(9)^{(2)} \\ 1 \text{ --- } 2 \end{array} \quad (2.101)$$

The $6d$ lifts for both of these cases were already considered in the literature. Specifically, the $6d$ lift for case (2.101) was conjectured by [83], and for case (2.100) by [84]. In both cases our findings from geometry support these conjectures.

\mathfrak{e}_6 :

$$\mathfrak{e}_6 + A = \begin{array}{ccccccc} & & & & \mathfrak{su}(1)^{(1)} & & \\ & & & & 2 & & \\ & & & & | & & \\ \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \dots & \mathfrak{su}(1)^{(1)} & & \\ 2 \text{ --- } & 2 \text{ --- } & 2 \text{ --- } & \dots & 2 & & \\ & & & & \underbrace{\hspace{2cm}} & & \\ & & & & 3 & & \end{array} \quad (2.102)$$

Here the only $6d$ lifting case is the maximally supersymmetric one, whose lift was worked out previously [78]. There appears to be no $6d$ lifting case for \mathfrak{e}_6 with fundamental matter, see [63]. There are, however, $5d$ \mathfrak{e}_6 gauge theories with fundamental matter with a $5d$ SCFT UV completion. These will be covered in the next subsection.

2.1.7 Rank 7

$\mathfrak{so}(14)$:

$$\mathfrak{so}(14) + S + 6F = \begin{array}{c} \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(6)^{(2)} \\ 3 \text{ --- } 1 \text{ --- } 2 \end{array} \quad (2.103)$$

The $6d$ lift for this case was conjectured by [84], and our results from geometry match this conjecture.

ϵ_7 :

$$\begin{array}{ccccccc}
 & & & & \mathfrak{su}(1)^{(1)} & & \\
 & & & & 2 & & \\
 & & & & | & & \\
 \epsilon_7 + A & = & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \dots & \mathfrak{su}(1)^{(1)} \\
 & & 2 & \text{---} & 2 & \text{---} & 2 \\
 & & & & \underbrace{\hspace{2cm}} & & \\
 & & & & 4 & &
 \end{array} \tag{2.104}$$

Here the only $6d$ lifting case is the maximally supersymmetric one, whose lift was worked out previously [78]. There appears to be no $6d$ lifting case for ϵ_7 with fundamental matter, see [63]. There are, however, $5d$ ϵ_7 gauge theories with fundamental matter with a $5d$ SCFT UV completion. These will be covered in the next subsection.

2.1.8 Rank 8

ϵ_8 :

$$\begin{array}{ccccccc}
 & & & & \mathfrak{su}(1)^{(1)} & & \\
 & & & & 2 & & \\
 & & & & | & & \\
 \epsilon_8 + A & = & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \dots & \mathfrak{su}(1)^{(1)} \\
 & & 2 & \text{---} & 2 & \text{---} & 2 \\
 & & & & \underbrace{\hspace{2cm}} & & \\
 & & & & 5 & &
 \end{array} \tag{2.105}$$

Here the only $6d$ lifting case is the maximally supersymmetric one, whose lift was worked out previously [78].

2.2 SCFTs

We next turn to summarizing the cases having a $5d$ SCFT UV completion. Most of these cases can be generated by integrating out matter from the $6d$ lifting cases in the previous list, but there are a handful of cases that can not be generated by integrating out matter from a $6d$ lifting gauge theory. They still can be obtained from a $5d$ KK theory but the transition process requires a (generalized) ungauging along with integrating out matter (see [63] for more details).

2.2.1 General rank

As previously, we first start with the cases existing for generic rank, and later innumerate the finite number of special cases for low rank.

su(m):

$$\mathfrak{su}(m)_{\frac{n-p}{2}} + (2m + 4 - n - p)F, \tag{2.106}$$

$$\mathfrak{su}(m)_{\frac{n-p}{2}} + \Lambda^2 + (m + 6 - n - p)F, \tag{2.107}$$

$$\mathfrak{su}(m)_{\frac{m+n}{2}} + \Lambda^2 + (8 - n)F, \tag{2.108}$$

$$\mathfrak{su}(m)_{\frac{n-p}{2}} + 2\Lambda^2 + (8 - n - p)F, \tag{2.109}$$

$$\mathfrak{su}(m)_{\frac{3+n}{2}} + 2\Lambda^2 + (7 - n)F, \tag{2.110}$$

$$\mathfrak{su}(m)_{\frac{n-p}{2}} + S^2 + (m - 2 - n - p)F. \tag{2.111}$$

All cases here are generated by integrating matter from the cases in 2.1.1. Specifically, case (2.106) is generated by integrating n fundamentals with a positive mass and p fundamentals with a negative mass out of the $6d$ lifting case (2.2). Likewise, case (2.107) is generated by integrating n fundamentals with a positive mass and p fundamentals with a negative mass out of the $6d$ lifting case (2.3). Case (2.108) contains the cases generated by integrating matter out of case (2.4), where we have restricted only to cases not covered by the previous entry.

In the same vein, case (2.109) covers cases generated by integrating fundamental matter from cases (2.5) and (2.6), and case (2.110) covers cases generated by integrating fundamental matter from cases (2.7) and (2.8) that were not covered by the previous entry. Finally, case (2.111) covers cases generated by integrating fundamental matter from case (2.9). We can not get any additional cases by integrating non-fundamental matter or by integrating matter out of the other cases in 2.1.1.

All cases here were known to exist before, and have brane web realizations [9, 10, 21, 24, 26, 28].

sp(m):

$$\mathfrak{sp}(m)_{0/\pi} + (2m + 6 - n)F, \tag{2.112}$$

$$\mathfrak{sp}(m)_{0/\pi} + \Lambda^2 + (8 - n)F. \tag{2.113}$$

Here also all cases can be generated by integrating out fundamental matter from the $6d$ lifting cases. Specifically, case (2.112) can be generated from case (2.16), and case (2.113) from case (2.17). Here the theta angle for the \mathfrak{sp} group is only physically relevant for the pure case or the case with just a single antisymmetric hyper [7]. All the cases here are known to exist. Case (2.112) can be realized using brane webs [28, 69]. For case (2.113) there is a type I' brane construction [6], from which one can also get a brane web representation [68].

Many of these cases are dual to some of the \mathfrak{su} cases discussed previously. Specifically, case (2.112) is dual to case (2.106) with $p = 0$ and $m_{\mathfrak{su}} = m_{\mathfrak{sp}} + 1$, and case (2.113) is dual to case (2.108) with $m_{\mathfrak{su}} = m_{\mathfrak{sp}} + 1$. Both of these dualities were known previously from other works. Specifically, the duality involving case (2.112) was found in [27] (see also [30] for a brane realization), while the one involving (2.113) was found in [21]. For both cases, when there is no fundamental flavor, we have two different SCFTs associated with the different

theta angles, but only one of each case has an \mathfrak{su} dual description. Specifically, for cases where the rank is even, the theta angle with the dual is π , while for cases where the rank is odd, the theta angle with the dual is 0.

$\mathfrak{so}(m)$:

$$\mathfrak{so}(m) + (m - 2 - n)F. \tag{2.114}$$

The case here can be conveniently generated by integrating matter out of the $6d$ lifting case (2.20). This class of theories were known to exist before, notably due to a brane web realization [28, 69].

2.2.2 Rank 2

$\mathfrak{su}(3)$:

$$\mathfrak{su}(3)_{4+\frac{n}{2}} + (6 - n)F, \tag{2.115}$$

$$\mathfrak{su}(3)_6, \tag{2.116}$$

$$\mathfrak{su}(3)_8. \tag{2.117}$$

Cases (2.115) and (2.116) can be generated by integrating out fundamental matter from case (2.21), while (2.117) can be generated by integrating out fundamental matter with a positive mass from case (2.22). All three classes of theories were known before, where case (2.115) was first found from geometry in [47], case (2.116) being first noted in [29], and case (2.117) was first found, also from geometry, in [59].

$\mathfrak{sp}(2)$:

$$\mathfrak{sp}(2)_{0/\pi} + 2\Lambda^2 + (4 - n)F. \tag{2.118}$$

The case here can be generated by integrating out fundamental matter from the $6d$ lifting case in (2.24). Here the theta angle for the \mathfrak{sp} group is only physically relevant for the case with only the two antisymmetric hypermultiplets and no fundamentals (that is $n = 4$). This case is dual to (2.115), where for $n = 4$ the dual \mathfrak{sp} case is the one with theta angle π . Both this class of models and the duality were first found in [47], with the exception of the $n = 4$ case, which is just $\mathfrak{sp}(2) + 2\Lambda^2 = \mathfrak{so}(5) + 2F$ and so can also be build from the methods of [28, 32, 33, 69].⁸

\mathfrak{g}_2 :

$$\mathfrak{g}_2 + (6 - n)F. \tag{2.119}$$

The case here can be generated by integrating out fundamental matter from the $6d$ lifting case in (2.27). This case is dual to (2.115) and (2.118). Both this class of models and the duality were first found in [47]. Both were also given brane realizations in [37, 38].

⁸This seems to only give the $\theta = 0$ case.

2.2.3 Rank 3

su(4):

$$\mathfrak{su}(4)_{4+\frac{n}{2}} + (6-n)F, \tag{2.120}$$

$$\mathfrak{su}(4)_k + 3\Lambda^2 + (4-n)F; \quad 0 \leq k \leq 2 + \frac{n}{2}. \tag{2.121}$$

Case (2.120) can be generated by integrating fundamental matter with a positive mass from case (2.28), while (2.121) can be generated by integrating fundamental matter from cases (2.31), (2.32) and (2.33). Both cases appear new. Case (2.121) can also be regarded as $\mathfrak{so}(6)_k + 3F + (4-n)S$, and so one should be able to build brane webs for these cases, at least for small k , using the results of [32, 36].

sp(3):

$$\mathfrak{sp}(3) + \Lambda^3 + (5-n)F, \tag{2.122}$$

$$\mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \frac{19-2n}{2}F, \tag{2.123}$$

$$\mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \Lambda^2 + \frac{5-2n}{2}F. \tag{2.124}$$

Case (2.122) can be generated by integrating fundamental matter from case (2.41), while (2.123) and (2.124) can be generated in the same way from cases (2.39) and (2.40), respectively. Note that as the three index antisymmetric representation of $\mathfrak{sp}(3)$ contributes to the anomaly of [86], the theta angle in their presence should be physically irrelevant. For the cases (2.123) and (2.124), the geometry indicates that the theta angle is physically irrelevant.

Cases (2.122) and (2.123) have been found previously from brane constructions in [40], while (2.124) appears new. We also note that case (2.122) is dual to case (2.120), and case (2.123) is dual to the $m = 4$ case of (2.110). See section 2.5.2 for a list of dualities occurring in gauge theories having a $5d$ SCFT UV completion.

so(7):

$$\mathfrak{so}(7) + (6-n)S + F, \tag{2.125}$$

$$\mathfrak{so}(7) + (5-n)S + 2F, \tag{2.126}$$

$$\mathfrak{so}(7) + (4-n)S + 3F, \tag{2.127}$$

$$\mathfrak{so}(7) + (2-n)S + 4F, \tag{2.128}$$

$$\mathfrak{so}(7) + (7-n)S. \tag{2.129}$$

Case (2.125) can be generated by integrating fundamental matter from case (2.42). Similarly cases (2.126), (2.127), (2.128) and (2.129) can be generated in the same way from cases (2.43), (2.44), (2.45) and (2.46), respectively. A brane construction for this class of theories was given in [32], which is valid when the number of spinors is four or smaller. It should be possible to use the result of [34], and lift the class S construction for the $4d$

$\mathcal{N} = 2 \mathfrak{so}(7) + 5\text{S}$ SCFT given in [87] to $5d$ to get a brane web description also for the cases with five spinors.

The cases here are related to the previous cases and to one another by various dualities. See section 2.5.2 for a full account of these dualities.

2.2.4 Rank 4

$\mathfrak{su}(5)$:

$$\mathfrak{su}(5)_{\frac{1}{2}} + 3\Lambda^2 + 2\text{F}, \tag{2.130}$$

$$\mathfrak{su}(5)_k + 3\Lambda^2 + \text{F}; \quad k = 0, 1, 2 \tag{2.131}$$

$$\mathfrak{su}(5)_{\frac{2l+1}{2}} + 3\Lambda^2; \quad l = 0, 1, 2, 3 \tag{2.132}$$

Most of these cases can be generated by integrating fundamental flavors from cases (2.47) and (2.48), with the exception of case (2.132) for $l = 3$. This case is one of the few cases of $5d$ gauge theories that have a $5d$ SCFT UV completion, but can not be generated by integrating flavor out of $5d$ gauge theories that lift to $6d$ SCFTs. However, see the end of this subsection for a lift of this $5d$ gauge theory to a $5d$ KK theory.

$\mathfrak{sp}(4)$:

$$\mathfrak{sp}(4) + \frac{1}{2}\Lambda^3 + (4 - n)\text{F}. \tag{2.133}$$

This case can be generated by integrating out flavors from the $6d$ lifting case (2.49). We also note that from geometry it appears that the theta angle for the \mathfrak{sp} group is physically irrelevant for the $n = 4$ case.

$\mathfrak{so}(8)$:

$$\mathfrak{so}(8) + 3\text{S} + n\text{F}; \quad 3 \leq n \leq 4 \tag{2.134}$$

$$\mathfrak{so}(8) + 2\text{S} + n\text{F}; \quad 2 \leq n \leq 4 \tag{2.135}$$

$$\mathfrak{so}(8) + \text{S} + n\text{F}; \quad 1 \leq n \leq 5 \tag{2.136}$$

$$\mathfrak{so}(8) + \text{C} + 3\text{S} + 3\text{F} \tag{2.137}$$

$$\mathfrak{so}(8) + \text{C} + 2\text{S} + n\text{F}; \quad 2 \leq n \leq 4 \tag{2.138}$$

$$\mathfrak{so}(8) + \text{C} + \text{S} + n\text{F}; \quad 1 \leq n \leq 4 \tag{2.139}$$

$$\mathfrak{so}(8) + 2\text{C} + 2\text{S} + n\text{F}; \quad 2 \leq n \leq 3 \tag{2.140}$$

All cases here can be generated by integrating out flavors from the $6d$ lifting cases. To avoid over-counting, we have used the triality outer automorphism of $\mathfrak{so}(8)$ to set $n_C \leq n_S \leq n_F$, and hence the lower limitations on n . A brane construction for this class of theories was given in [32], which can be used to build brane webs for these theories with the exception of cases (2.134), (2.135) and (2.137). The results in [36] allows the extension of this method also to the case of (2.135). It should be possible to use the result of [34], and lift the class S construction for the $4d \mathcal{N} = 2 \mathfrak{so}(8)$ SCFTs with spinor matter given in [87] to $5d$ to get brane web descriptions also for cases (2.134) and (2.137).

$\mathfrak{so}(9)$:

$$\mathfrak{so}(9) + 3S + (3 - n)F, \tag{2.141}$$

$$\mathfrak{so}(9) + 4S, \tag{2.142}$$

$$\mathfrak{so}(9) + 2S + (5 - n), \tag{2.143}$$

$$\mathfrak{so}(9) + S + (6 - n)F. \tag{2.144}$$

Case (2.141) can be generated by integrating fundamental matter from case (2.58). Similarly cases (2.142), (2.143), and (2.144) can be generated in the same way from cases (2.59), (2.57), and (2.56), respectively. A brane construction for this class of theories was given in [32], which is valid when the number of spinors is two or smaller. It should be possible to use the result of [34], and lift the class S construction for the $4d \mathcal{N} = 2$ $\mathfrak{so}(9) + 3S + F$ SCFT given in [88] to $5d$ to get a brane web description also for the cases with three spinors.

The cases here are related to the previous cases and to one another by various dualities. See section 2.5.2 for a list of these dualities.

\mathfrak{f}_4 :

$$\mathfrak{f}_4 + (3 - n)F; \quad 0 \leq n \leq 3 \tag{2.145}$$

This case is one of the few cases of $5d$ gauge theories that have a $5d$ SCFT UV completion, but can not be generated by integrating flavor out of $5d$ gauge theories that lift to $6d$ SCFTs, with the exception of the $n = 3$ case which can be generated by integrating out the adjoint hyper from the maximally supersymmetric case. We also note that the $n = 0$ case is dual to the $l = 3$ case of (2.132), see [61].

Let us remark here that the $n < 3$ cases can be obtained from $5d$ KK theories by performing a generalized ungauging (along with integrating out matter). It can be seen from the geometry for $\mathfrak{f}_4 + 3F$ that the $u(1)$ instanton flavor symmetry of the theory enhances at the conformal point to an $\mathfrak{su}(2)$ subgroup of the flavor symmetry of the $5d$ SCFT.⁹ Gauging this $\mathfrak{su}(2)$ symmetry produces the $5d$ KK theory obtained by untwisted compactification of $6d$ SCFT whose tensor branch description is provide by $6d \mathfrak{f}_4 + 3F$ gauge theory. Thus, the $5d \mathfrak{f}_4 + 3F$ gauge theory can be obtained from this $5d$ KK theory by ungauging the above-mentioned $\mathfrak{su}(2)$ symmetry. The theories $f\mathfrak{f}_4 + (3 - n)F$ for $n > 0$ can then simply be obtained by integrating out matter from the $\mathfrak{f}_4 + 3F$ theory. See [63] for more details.

2.2.5 Rank 5

$\mathfrak{su}(6)$:

$$\mathfrak{su}(6)_{\frac{n-p}{2}} + \frac{1}{2}\Lambda^3 + (13 - n - p)F, \tag{2.146}$$

$$\mathfrak{su}(6)_{3+\frac{n}{2}} + \frac{1}{2}\Lambda^3 + (9 - n)F, \tag{2.147}$$

⁹This can also be seen directly from the gauge theory from instanton counting [18].

$$\mathfrak{su}(6)_{\frac{n-p}{2}} + \frac{1}{2}\Lambda^3 + \Lambda^2 + (9 - n - p)F, \tag{2.148}$$

$$\mathfrak{su}(6)_{\frac{3+n}{2}} + \frac{1}{2}\Lambda^3 + \Lambda^2 + (8 - n)F, \tag{2.149}$$

$$\mathfrak{su}(6)_{\frac{2l+n-p-1}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 + (2 - n - p)F, l = 1, 2 \tag{2.150}$$

$$\mathfrak{su}(6)_{\frac{n-p}{2}} + \Lambda^3 + (10 - n - p)F, \tag{2.151}$$

$$\mathfrak{su}(6)_{\frac{3+n}{2}} + \Lambda^3 + (9 - n)F, \tag{2.152}$$

$$\mathfrak{su}(6)_{\frac{n-p}{2}} + \Lambda^3 + \Lambda^2 + (4 - n - p)F, \tag{2.153}$$

$$\mathfrak{su}(6)_{\frac{3+n}{2}} + \Lambda^3 + \Lambda^2 + (3 - n)F, \tag{2.154}$$

$$\mathfrak{su}(6)_{\frac{n-p}{2}} + \frac{3}{2}\Lambda^3 + (5 - n - p)F, \tag{2.155}$$

$$\mathfrak{su}(6)_{\frac{7}{2}} + \frac{3}{2}\Lambda^3 \tag{2.156}$$

$$\mathfrak{su}(6)_{\frac{1}{2}} + S^2 + \frac{1}{2}\Lambda^3 \tag{2.157}$$

All cases here can be generated by integrating out fundamental flavors from $6d$ lifting cases. Specifically, case (2.146) can be generated by integrating out n fundamentals with a positive mass and p fundamentals with a negative mass from case (2.61). Case (2.147) can be generated by integrating out n fundamentals with a positive mass from case (2.62). Case (2.148) can be generated by integrating out n fundamentals with a positive mass and p fundamentals with a negative mass from case (2.63). Case (2.149) can be generated by integrating out n fundamentals with a positive mass from case (2.64). Case (2.150) can be generated by integrating out n fundamentals with a positive mass and p fundamentals with a negative mass from cases (2.65) and (2.66). Case (2.151) can be generated by integrating out n fundamentals with a positive mass and p fundamentals with a negative mass from case (2.69). Case (2.152) can be generated by integrating out n fundamentals with a positive mass from case (2.70). Case (2.153) can be generated by integrating out n fundamentals with a positive mass and p fundamentals with a negative mass from case (2.71). Case (2.154) can be generated by integrating out n fundamentals with a positive mass from case (2.72). Case (2.155) can be generated by integrating out n fundamentals with a positive mass and p fundamentals with a negative mass from case (2.73). Cases (2.156) and (2.157) can be generated by integrating out the fundamental flavor from cases (2.74) and (2.78), respectively.

Many of the cases here were found previously using brane constructions. Specifically, [40] presented brane web constructions for cases (2.146), (2.147), (2.148), (2.149), (2.151), (2.152), (2.153), (2.155), and (2.157). The remaining cases are new, to our knowledge.

We also note that case (2.146) with $p = 0$ is dual to the $m = 6, p = 0$ case of (2.107), and that case (2.147) is dual to both the $m = 6$ case of (2.108) and the $m = 5$ case of (2.113), where for $n = 8$ the \mathfrak{sp} theta angle of the dual theory is 0. Case (2.149) is dual to the $m = 6$ case of (2.110).

so(11):

$$\mathfrak{so}(11) + 2S + (3 - n)F, \quad (2.158)$$

$$\mathfrak{so}(11) + \frac{3}{2}S + (5 - n)F, \quad (2.159)$$

$$\mathfrak{so}(11) + S + (7 - n)F, \quad (2.160)$$

$$\mathfrak{so}(11) + \frac{1}{2}S + (8 - n)F. \quad (2.161)$$

All cases here can be generated by integrating fundamental matter from the $6d$ lifting cases. A brane construction for this class of theories was given in [32], which can be used to build brane webs for cases (2.161) and (2.160). It should be possible to use the result of [34], and lift the class S construction for the $4d$ $\mathcal{N} = 2$ $\mathfrak{so}(11)$ SCFTs with spinor matter given in [88] to $5d$ to get brane web descriptions also for cases (2.159) and (2.158).

We also note that case (2.158) is dual to case (2.154), while case (2.159) is dual to the $p = 0$ case of (2.155).

so(10):

$$\mathfrak{so}(10) + 4S + (2 - n)F, \quad (2.162)$$

$$\mathfrak{so}(10) + 3S + (4 - n)F, \quad (2.163)$$

$$\mathfrak{so}(10) + 2S + (6 - n)F, \quad (2.164)$$

$$\mathfrak{so}(10) + S + (7 - n)F. \quad (2.165)$$

All cases here can be generated by integrating fundamental matter from the $6d$ lifting cases. A brane construction for this class of theories was given in [32], which can be used to build brane webs for cases with two or less spinors. It should be possible to use the result of [34], and lift the class S construction for the $4d$ $\mathcal{N} = 2$ $\mathfrak{so}(10)$ SCFTs with spinor matter given in [88] to $5d$ to get brane web descriptions also for the other cases.

2.2.6 Rank 6

su(7):

$$\mathfrak{su}(7)_{\frac{n-p}{2}} + \Lambda^3 + (6 - n - p)F, \quad (2.166)$$

$$\mathfrak{su}(7)_{\frac{3+n}{2}} + \Lambda^3 + (5 - n)F \quad (2.167)$$

Case (2.166) can be generated by integrating out n fundamentals with a positive mass and p fundamentals with a negative mass from the $6d$ lifting case (2.89). Case (2.167) can be generated by integrating out n fundamentals with a positive mass from the $6d$ lifting case (2.90).

so(13):

$$\mathfrak{so}(13) + S + (5 - n)F, \quad (2.168)$$

$$\mathfrak{so}(13) + \frac{1}{2}S + (9 - n)F. \quad (2.169)$$

These cases can be generated by integrating out fundamental flavors from the $6d$ lifting cases of $\mathfrak{so}(13)$ with spinor matter. Case (2.168) is dual to case (2.167).

$\mathfrak{so}(12)$:

$$\mathfrak{so}(12) + 2S + (4 - n)F, \tag{2.170}$$

$$\mathfrak{so}(12) + \frac{3}{2}S + (6 - n)F, \tag{2.171}$$

$$\mathfrak{so}(12) + S + (8 - n)F, \tag{2.172}$$

$$\mathfrak{so}(12) + \frac{1}{2}S + (9 - n)F, \tag{2.173}$$

$$\mathfrak{so}(12) + \frac{3}{2}S + C \tag{2.174}$$

$$\mathfrak{so}(12) + \frac{3}{2}S + \frac{1}{2}C + (4 - n)F, \tag{2.175}$$

$$\mathfrak{so}(12) + S + C + (4 - n)F, \tag{2.176}$$

$$\mathfrak{so}(12) + S + \frac{1}{2}C + (6 - n)F, \tag{2.177}$$

$$\mathfrak{so}(12) + \frac{1}{2}S + \frac{1}{2}C + (8 - n)F. \tag{2.178}$$

All cases here can be generated by integrating fundamental matter from the $6d$ lifting cases. A brane construction for this class of theories was given in [32], which can be used to build brane webs for cases (2.173) and (2.172). The results in [36] allows the extension of this method also to the case of (2.178). It should be possible to use the result of [34], and lift the class S construction for the $4d \mathcal{N} = 2 \mathfrak{so}(12)$ SCFTs with spinor matter given in [88] to $5d$ to get brane web descriptions also for cases (2.171), (2.170), (2.177), (2.175) and (2.176).

\mathfrak{e}_6 :

$$\mathfrak{e}_6 + nF; \quad 0 \leq n \leq 4. \tag{2.179}$$

This case is one of the few cases of $5d$ gauge theories that have a $5d$ SCFT UV completion, but can not be generated by integrating flavor out of $5d$ gauge theories that lift to $6d$ SCFTs, with the exception of the $n = 0$ case which can be generated by integrating out the adjoint hyper from the maximally supersymmetric case.

The $n > 0$ cases can be obtained from $5d$ KK theories in the same fashion as discussed towards the end of subsection 2.2.4. The $5d$ gauge theory $\mathfrak{e}_6 + 4F$ admits an instantonic $\mathfrak{su}(2)$ flavor symmetry which can be gauged to produce the $5d$ KK theory obtained from an untwisted compactification of the $6d$ SCFT with tensor branch described by $6d$ gauge theory $\mathfrak{e}_6 + 4F$. See [63] for more details.

2.2.7 Rank 7

$\mathfrak{so}(14)$:

$$\mathfrak{so}(14) + S + (6 - n)F. \tag{2.180}$$

This case can be generated by integrating out flavors from the $6d$ lifting case.

\mathfrak{e}_7 :

$$\mathfrak{e}_7 + \frac{n}{2}\mathbf{F}; \quad 0 \leq n \leq 6. \quad (2.181)$$

This case is one of the few cases of $5d$ gauge theories that have a $5d$ SCFT UV completion, but can not be generated by integrating flavor out of $5d$ gauge theories that lift to $6d$ SCFTs, with the exception of the $n = 0$ case which can be generated by integrating out the adjoint hyper from the maximally supersymmetric case. We also note that as one cannot integrate out an odd number of half-hyper multiplets, the cases with even and odd n sit in distinct flow families.

The $n = 6$ and $n = 5$ cases can be obtained from $5d$ KK theories by a generalized ungauging. To construct the $n = 6$ case, we start with the $5d$ KK theory produced by untwisted compactification of the $6d$ SCFT whose tensor branch is described by the $6d$ gauge theory $\mathfrak{e}_7 + 3\mathbf{F}$. This $5d$ KK theory can be obtained by gauging an $\mathfrak{su}(2)$ instantonic flavor symmetry of $5d$ $\mathfrak{e}_7 + 3\mathbf{F}$, the ungauging of which leading to the above $n = 6$ case. The $n = 5$ case is obtained by applying a generalized ungauging on the $5d$ KK theory obtained by untwisted compactification of $6d$ SCFT with tensor branch $6d$ gauge theory $\mathfrak{e}_7 + \frac{5}{2}\mathbf{F}$. In this case, the generalized ungauging process cannot be interpreted as ungauging of an instantonic symmetry. See [63] for more details.

2.2.8 Rank 8

\mathfrak{e}_8 :

$$\mathfrak{e}_8 \quad (2.182)$$

This case can be generated by integrating the adjoint hyper out of the maximally supersymmetric case.

2.3 Inconsistent theories

In this section, we collect the $5d$ gauge theories allowed by [21], but disallowed by our analysis. These theories are as follows:

$$\mathfrak{su}(3)_{\frac{13}{2}} + 3\mathbf{F} \& := \mathfrak{sp}(2)_{\pi} + 3\Lambda^2 \quad (2.183)$$

$$\mathfrak{su}(3)_7 + 2\mathbf{F} \quad (2.184)$$

$$\mathfrak{su}(4)_3 + 8\mathbf{F} \quad (2.185)$$

$$\mathfrak{su}(4)_{\frac{7}{2}} + 7\mathbf{F} \quad (2.186)$$

$$\mathfrak{su}(4)_1 + 4\Lambda^2 \quad (2.187)$$

$$\mathfrak{su}(4)_3 + 4\Lambda^2 \quad (2.188)$$

$$\mathfrak{sp}(3)_{\pi} + 2\Lambda^2 \quad (2.189)$$

$$\mathfrak{su}(5)_{\frac{11+n}{2}} + (5-n)\mathbf{F}; \quad 0 \leq n \leq 4 \quad (2.190)$$

$$\mathfrak{su}(5)_3 + 3\Lambda^2 + \mathbf{F} \quad (2.191)$$

$$\mathfrak{su}(6)_0 + 3\Lambda^2 \quad (2.192)$$

$$\mathfrak{su}(6)_2 + 3\Lambda^2 \quad (2.193)$$

$$\mathfrak{su}(6)_2 + \frac{3}{2}\Lambda^3 + 3F \tag{2.194}$$

$$\mathfrak{su}(6)_{\frac{5}{2}} + \frac{3}{2}\Lambda^3 + 2F \tag{2.195}$$

$$\mathfrak{so}(12) + 2S + \frac{1}{2}C \tag{2.196}$$

We have taken the help of two kinds of arguments to rule these theories out:

1. In the first argument, a $5d$ gauge theory satisfying the conditions of [21] is shown to be dual to a $5d$ gauge theory which does not satisfy the conditions of [21]. Since the latter theory is not supposed to admit an SCFT UV completion, the former theory should not admit an SCFT UV completion either.
2. In the second argument, by deforming a $5d$ gauge theory we land onto another $5d$ gauge theory which is known to admit no SCFT UV completion, either by the conditions of [21] or by the first argument. Since deforming a theory with pure field-theoretic UV completion should lead to a theory with purely field-theoretic UV completion, we are lead to the conclusion that the gauge theory before the deformation should not admit an SCFT UV completion.

The detailed arguments for each of the above cases can be found in the appropriate subsections of section 4.

2.4 Undetermined theories

Finally, we collect all the theories which satisfy the criteria of [21], but we are neither able to confirm the existence of these theories nor rule them out. That is, we are neither able to put the geometry corresponding to these gauge theories in a form manifesting the structure of a $5d$ KK theory (which is discussed in section 3.4), nor are we able to apply either of the two kinds of arguments discussed at the end of section 2.3.

These theories are as follows:

$$\mathfrak{su}(4)_7 + \Lambda^2 \tag{2.197}$$

$$\mathfrak{su}(5)_8 \tag{2.198}$$

$$\mathfrak{su}(6)_9 \tag{2.199}$$

$$\mathfrak{su}(6)_4 + \Lambda^3 + \Lambda^2 \tag{2.200}$$

$$\mathfrak{su}(7)_5 + \Lambda^3 \tag{2.201}$$

$$\mathfrak{so}(12) + \frac{5}{2}S \tag{2.202}$$

According to the criteria proposed in [21], all of the above cases except for the case of (2.198) may either have a UV completion as a $6d$ SCFT or may have no UV completion at all. The case (2.198), on the other hand, may either have UV completion as a $5d$ SCFT, or as a $6d$ SCFT, or no UV completion at all. The case (2.198) descends from the marginal case $\mathfrak{su}(5)_{\frac{11}{2}} + 5F$ of [21]. We show later in this paper the following duality

$$\mathfrak{su}(5)_{\frac{11+n}{2}} + (5-n)F = \mathfrak{sp}(4) + (4-n)F + \Lambda^4$$

according to which the above marginal theory and its descendants are dual to $\mathfrak{sp}(4)$ theories containing Λ^4 , but such $\mathfrak{sp}(4)$ theories are ruled out by the criteria of [21]. This duality is not applicable to the $n = 5$ case, and thus this argument is insufficient to decide the fate of (2.198).

2.5 Dualities

In this subsection, we collect the dualities between different $5d$ gauge theories.

2.5.1 KK theories

$$\mathfrak{su}(m+2)_0 + (2m+8)\mathbf{F} = \mathfrak{sp}(m+1) + (2m+8)\mathbf{F} \quad (2.203)$$

$$\mathfrak{su}(m+2)_{\frac{m}{2}+1} + \Lambda^2 + 8\mathbf{F} = \mathfrak{sp}(m+1) + \Lambda^2 + 8\mathbf{F} \quad (2.204)$$

$$\mathfrak{su}(2m)_m + \mathbf{S}^2 = \mathfrak{sp}(2m-1)_0 + \mathbf{A} \quad (2.205)$$

$$\mathfrak{su}(2m+1)_{m+\frac{1}{2}} + \mathbf{S}^2 = \mathfrak{sp}(2m)_\pi + \mathbf{A} \quad (2.206)$$

$$\mathfrak{su}(3)_4 + 6\mathbf{F} = \mathfrak{sp}(2) + 2\Lambda^2 + 4\mathbf{F} = \mathfrak{g}_2 + 6\mathbf{F} \quad (2.207)$$

$$\mathfrak{su}(3)_{\frac{15}{2}} + \mathbf{F} = \mathfrak{g}_2 + \mathbf{A} \quad (2.208)$$

$$\mathfrak{su}(4)_4 + 6\mathbf{F} = \mathfrak{sp}(3) + \Lambda^3 + 5\mathbf{F} \quad (2.209)$$

$$\mathfrak{su}(4)_{\frac{3}{2}} + 2\Lambda^2 + 7\mathbf{F} = \mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \frac{19}{2}\mathbf{F} \quad (2.210)$$

$$\mathfrak{su}(4)_6 + 2\Lambda^2 = \mathfrak{sp}(3)_0 + 2\Lambda^2 \quad (2.211)$$

$$\mathfrak{su}(4)_0 + 3\Lambda^2 + 4\mathbf{F} = \mathfrak{so}(7) + 6\mathbf{S} + \mathbf{F} \quad (2.212)$$

$$\mathfrak{su}(4)_1 + 3\Lambda^2 + 4\mathbf{F} = \mathfrak{so}(7) + 5\mathbf{S} + 2\mathbf{F} = \mathfrak{so}(7) + 7\mathbf{S} \quad (2.213)$$

$$\mathfrak{su}(4)_2 + 3\Lambda^2 + 4\mathbf{F} = \mathfrak{so}(7) + 4\mathbf{S} + 3\mathbf{F} \quad (2.214)$$

$$\mathfrak{su}(4)_5 + 3\Lambda^2 = \mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \Lambda^2 + \frac{5}{2}\mathbf{F} \quad (2.215)$$

$$\mathfrak{su}(5)_0 + 3\Lambda^2 + 3\mathbf{F} = \mathfrak{so}(9) + 3\mathbf{S} + 3\mathbf{F} \quad (2.216)$$

$$\mathfrak{su}(5)_{\frac{3}{2}} + 3\Lambda^2 + 2\mathbf{F} = \mathfrak{so}(9) + 4\mathbf{S} + \mathbf{F} \quad (2.217)$$

$$\mathfrak{su}(6)_0 + \Lambda^2 + 12\mathbf{F} = \mathfrak{su}(6)_0 + \frac{1}{2}\Lambda^3 + 13\mathbf{F} \quad (2.218)$$

$$\mathfrak{su}(6)_3 + \Lambda^2 + 8\mathbf{F} = \mathfrak{su}(6)_3 + \frac{1}{2}\Lambda^3 + 9\mathbf{F} = \mathfrak{sp}(5) + \Lambda^2 + 8\mathbf{F} \quad (2.219)$$

$$\mathfrak{su}(6)_{\frac{3}{2}} + 2\Lambda^2 + 7\mathbf{F} = \mathfrak{su}(6)_{\frac{3}{2}} + \frac{1}{2}\Lambda^3 + \Lambda^2 + 8\mathbf{F} \quad (2.220)$$

$$\mathfrak{su}(6)_{\frac{3}{2}} + \Lambda^3 + \Lambda^2 + 3\mathbf{F} = \mathfrak{so}(11) + 2\mathbf{S} + 3\mathbf{F} \quad (2.221)$$

$$\mathfrak{su}(6)_0 + \frac{3}{2}\Lambda^3 + 5\mathbf{F} = \mathfrak{so}(11) + \frac{3}{2}\mathbf{S} + 5\mathbf{F} \quad (2.222)$$

$$\mathfrak{su}(6)_{\frac{7}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 = \mathfrak{su}(6)_3 + \frac{3}{2}\Lambda^3 + F = \mathfrak{so}(11) + \frac{5}{2}S \quad (2.223)$$

$$\mathfrak{su}(7)_{\frac{3}{2}} + \Lambda^3 + 5F = \mathfrak{so}(13) + S + 5F \quad (2.224)$$

$$\mathfrak{so}(12) + \frac{3}{2}S + 6F = \mathfrak{so}(12) + S + \frac{1}{2}C + 6F \quad (2.225)$$

2.5.2 SCFTs

$$\mathfrak{su}(m+2)_{\frac{n}{2}} + (2m+8-n)F = \mathfrak{sp}(m+1) + (2m+8-n)F; \quad n \leq 2m+7 \quad (2.226)$$

$$\mathfrak{su}(m+2)_{m+4} = \mathfrak{sp}(m+1)_{m\pi} \quad (2.227)$$

$$\mathfrak{su}(m+2)_{\frac{m+n}{2}+1} + \Lambda^2 + (8-n)F = \mathfrak{sp}(m+1) + \Lambda^2 + (8-n)F; \quad n \leq 7 \quad (2.228)$$

$$\mathfrak{su}(m+2)_{\frac{m}{2}+5} + \Lambda^2 = \mathfrak{sp}(m+1)_{m\pi} + \Lambda^2 \quad (2.229)$$

$$\mathfrak{su}(3)_{4+\frac{n}{2}} + (6-n)F = \mathfrak{sp}(2) + 2\Lambda^2 + (4-n)F = \mathfrak{g}_2 + (6-n)F; \quad n \leq 3 \quad (2.230)$$

$$\mathfrak{su}(3)_6 + 2F = \mathfrak{sp}(2)_{\pi} + 2\Lambda^2 = \mathfrak{g}_2 + 2F \quad (2.231)$$

$$\mathfrak{su}(3)_{6+\frac{n}{2}} + (2-n)F = \mathfrak{g}_2 + (2-n)F \quad (2.232)$$

$$\mathfrak{su}(4)_{4+\frac{n}{2}} + (6-n)F = \mathfrak{sp}(3) + \Lambda^3 + (5-n)F \quad (2.233)$$

$$\mathfrak{su}(4)_{\frac{3+n}{2}} + 2\Lambda^2 + (7-n)F = \mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \frac{19-2n}{2}F; \quad n \leq 7 \quad (2.234)$$

$$\mathfrak{su}(4)_{\frac{1}{2}} + 3\Lambda^2 + 3F = \mathfrak{so}(7) + 5S + F = \mathfrak{so}(7) + 6S \quad (2.235)$$

$$\mathfrak{su}(4)_{\frac{n-1}{2}} + 3\Lambda^2 + (3-n)F = \mathfrak{so}(7) + (6-n)S; \quad n \leq 3 \quad (2.236)$$

$$\mathfrak{su}(4)_{\frac{n+1}{2}} + 3\Lambda^2 + (3-n)F = \mathfrak{so}(7) + (5-n)S + F; \quad n \leq 2 \quad (2.237)$$

$$\mathfrak{su}(4)_{1+\frac{n}{2}} + 3\Lambda^2 + (4-n)F = \mathfrak{so}(7) + (5-n)S + 2F; \quad n \leq 2 \quad (2.238)$$

$$\mathfrak{su}(4)_{\frac{5}{2}} + 3\Lambda^2 + 3F = \mathfrak{so}(7) + 3S + 3F \quad (2.239)$$

$$\mathfrak{su}(5)_{\frac{n}{2}} + 3\Lambda^2 + (3-n)F = \mathfrak{so}(9) + 3S + (3-n)F \quad (2.240)$$

$$\mathfrak{su}(5)_2 + 3\Lambda^2 + F = \mathfrak{so}(9) + 4S \quad (2.241)$$

$$\mathfrak{su}(5)_{\frac{7}{2}} + 3\Lambda^2 = \mathfrak{f}_4 + 3F \quad (2.242)$$

$$\mathfrak{su}(6)_{\frac{n}{2}} + \Lambda^2 + (12-n)F = \mathfrak{su}(6)_{\frac{n}{2}} + \frac{1}{2}\Lambda^3 + (13-n)F; \quad n \leq 12 \quad (2.243)$$

$$\mathfrak{su}(6)_{3+\frac{n}{2}} + \Lambda^2 + (8-n)F = \mathfrak{su}(6)_{3+\frac{n}{2}} + \frac{1}{2}\Lambda^3 + (9-n)F = \mathfrak{sp}(5) + \Lambda^2 + (8-n)F; \quad n \leq 7 \quad (2.244)$$

$$\mathfrak{su}(6)_7 + \Lambda^2 = \mathfrak{su}(6)_7 + \frac{1}{2}\Lambda^3 + F = \mathfrak{sp}(5)_0 + \Lambda^2 \quad (2.245)$$

$$\mathfrak{su}(6)_{\frac{3+n}{2}} + 2\Lambda^2 + (7-n)F = \mathfrak{su}(6)_{\frac{3+n}{2}} + \frac{1}{2}\Lambda^3 + \Lambda^2 + (8-n)F; \quad n \leq 7 \quad (2.246)$$

$$\mathfrak{su}(6)_{\frac{3+n}{2}} + \Lambda^3 + \Lambda^2 + (3-n)F = \mathfrak{so}(11) + 2S + (3-n)F \quad (2.247)$$

$$\mathfrak{su}(6)_{\frac{n}{2}} + \frac{3}{2}\Lambda^3 + (5-n)F = \mathfrak{so}(11) + \frac{3}{2}S + (5-n)F \quad (2.248)$$

$$\mathfrak{su}(7)_{\frac{3+n}{2}} + \Lambda^3 + (5-n)F = \mathfrak{so}(13) + S + (5-n)F \quad (2.249)$$

2.6 Relationship of our work to the classification of 5d SCFTs

As we have seen, in this work, we are able to divide the theories appearing in [21] into the following four sets:

1. The theories appearing in section 2.1 which UV complete into 5d KK theories.
2. The theories appearing in section 2.2 which UV complete into 5d SCFTs. Combining the results of this paper with the results of [63], we conclude that all these 5d SCFTs descend from 5d KK theories. However, the descent is not as simple as integrating out some BPS particles. In some cases that were discussed in [63], the descent requires integrating out BPS strings as well.
3. The theories appearing in section 2.3 which do not UV complete into 5d KK theories or 5d SCFTs.
4. The theories appearing in section 2.4 for which it is not clear whether or not they admit an SCFT UV completion.

Thus, our results provide evidence for the conjectures made in [63] regarding the classification of 5d SCFTs. We have found that all the theories appearing in [21] which can be shown to admit UV completions into 5d SCFTs indeed descend from 5d KK theories. We have also identified a set of theories in section 2.4 for which it is not clear whether or not they admit an SCFT UV completion. Further analysis of these theories should provide another opportunity to test and challenge the conjectures of [63].

3 Geometric description of 5d theories

Throughout this paper, we will use a graphical notation to represent a local neighborhood of a collection of Hirzebruch surfaces intersecting each other inside a Calabi-Yau threefold. This notation and relevant background on Hirzebruch surfaces can be found in section 2 of [61], and section 5.2.1 and appendix A of [60]. A special role will be played by the automorphism \mathcal{S} exchanging e and f curves inside the Hirzebruch surface \mathbb{F}_0 , which is described in section 2.6 of [61]. Also relevant are isomorphisms \mathcal{I}_n and \mathcal{I}_n^{-1} between Hirzebruch surfaces of different degrees which are described in section 2.1 of [61].

3.1 General features

Each Calabi-Yau threefold X appearing in this paper is described as a local neighborhood of a collection of intersecting compact Kahler surfaces S_i . An intersection between the surfaces S_i and S_j is described as a “gluing” between the two surfaces, with the intersection locus being described as the identification of two curves

$$C_{ij}^{(\alpha)} \sim C_{ji}^{(\alpha)} \tag{3.1}$$

where $C_{ij}^{(\alpha)}$ is a curve in S_i and $C_{ji}^{(\alpha)}$ is a curve in S_j . α parametrizes different intersections between S_i and S_j with the corresponding *gluing curves* being $C_{ij}^{(\alpha)}$ and $C_{ji}^{(\alpha)}$. The curves

$$C_{ij} := \sum_{\alpha} C_{ij}^{(\alpha)} \tag{3.2}$$

in S_i and

$$C_{ji} := \sum_{\alpha} C_{ji}^{(\alpha)} \tag{3.3}$$

in S_j are referred to as *total gluing curves* for the intersections between S_i and S_j .

Consistency of (3.1) requires

$$C_{ij}^{(\alpha)} \cdot S_k = C_{ji}^{(\alpha)} \cdot S_k \tag{3.4}$$

for all S_k . We can compute the intersection number of a compact curve C in X with a surface S_i as follows. If C lives in a surface $S_j \neq S_i$, then

$$C \cdot S_i = C \cdot C_{ji} \tag{3.5}$$

where the right hand side is computed inside S_j . If C lives in S_i , then

$$C \cdot S_i = K'_i \cdot C \tag{3.6}$$

where

$$K'_i = K_i + \sum_{\alpha} (C_i^{(\alpha)} + D_i^{(\alpha)}) \tag{3.7}$$

where

$$C_i^{(\alpha)} \sim D_i^{(\alpha)} \tag{3.8}$$

describe different *self-gluing*s of S_i , and K_i is the canonical divisor of S_i . The genus g of a curve C in S_i is computed by using

$$2g - 2 = (K_i + C) \cdot C + 2 \sum_{\alpha} n^{(\alpha)} \tag{3.9}$$

where

$$n^{(\alpha)} := \min(n_1^{(\alpha)}, n_2^{(\alpha)}) \tag{3.10}$$

where

$$n_1^{(\alpha)} := C \cdot C_i^{(\alpha)} \tag{3.11}$$

and

$$n_2^{(\alpha)} := C \cdot D_i^{(\alpha)} \tag{3.12}$$

are the intersections of C with the curves involved in the self-gluing of S_i .

Moreover, for the gluing (3.1) to be consistent with Calabi-Yau structure of X , we must have

$$(C_{ij}^{(\alpha)})^2 + (C_{ji}^{(\alpha)})^2 = 2g - 2 \tag{3.13}$$

where g is the genus of $C_{ij}^{(\alpha)}$ which must be equal to the genus of $C_{ji}^{(\alpha)}$ for consistency. Let us emphasize that the self-intersection $(C_{ij}^{(\alpha)})^2$ of $C_{ij}^{(\alpha)}$ is computed inside surface S_i since the curve $C_{ij}^{(\alpha)}$ lives in S_i by definition. The condition (3.13) is referred to as the *Calabi-Yau condition*.

Another consistency condition on the gluing curves $C_{ij}^{(\alpha)}$ comes from equating the various ways of computing the triple intersection number $S_i \cdot S_j \cdot S_k$ for three distinct surfaces. This triple intersection number can be computed in three different ways

$$S_i \cdot S_j \cdot S_k = C_{ij} \cdot C_{ik} = C_{ji} \cdot C_{jk} = C_{ki} \cdot C_{kj} \quad (3.14)$$

There are two different ways of computing intersection numbers of the form $S_i^2 \cdot S_j$ for $S_i \neq S_j$ as well

$$S_i^2 \cdot S_j = C_{ji}^2 = K'_i \cdot C_{ij} \quad (3.15)$$

which provide another consistency condition on the gluings.

The (normalizable part of the) Kahler class is defined as

$$J := \sum_i \phi_i S_i \quad (3.16)$$

where ϕ_i are the normalizable Kahler parameters which are identified as the Coulomb branch moduli of the $5d$ theory. We are ignoring the contribution from non-normalizable Kahler parameters which are identified as the (supersymmetry preserving) mass parameters of the $5d$ theory. The contribution of the Coulomb branch moduli to the mass of a BPS particle coming from an M2 brane wrapping a compact curve C in X can be computed by

$$\text{vol}(C) := -J \cdot C \quad (3.17)$$

The contribution of the Coulomb branch moduli to the tension of a BPS string coming from an M5 brane wrapping S_i can be computed by

$$\text{vol}(S_i) := \frac{1}{2} J^2 \cdot S_i \quad (3.18)$$

The contribution of the Coulomb branch moduli to the prepotential of the $5d$ theory can be computed by

$$\mathcal{F} = \frac{1}{6} J^3 \quad (3.19)$$

3.2 Structure of $5d$ gauge theory

For a geometry X to describe a $5d$ $\mathcal{N} = 1$ gauge theory, a necessary condition is that all of the surfaces have to be presented as Hirzebruch surfaces

$$S_i = \mathbb{F}_{n_i}^{b_i} \quad (3.20)$$

where n_i is the degree of the Hirzebruch surface and b_i are the number of blowups on the Hirzebruch surface. Once such a description is chosen,¹⁰ we can associate an *intersection matrix* to the geometry, which is defined as

$$\mathcal{I}_{ij} := -f_i \cdot S_j \quad (3.21)$$

where f_i is the \mathbb{P}^1 fiber of the Hirzebruch surface S_i .

¹⁰We note that it might not always be possible to choose a description in terms of Hirzebruch surfaces. For example, one of the S_i might be equal to \mathbb{P}^2 which is not isomorphic to any Hirzebruch surface.

One of the requirements for the geometry to describe a $5d$ gauge theory with gauge algebra \mathfrak{g} is that the intersection matrix \mathcal{I}_{ij} associated to the geometry equals the Cartan matrix of \mathfrak{g} [61]. Another requirement is that if a gluing curve $C_{ij}^{(\alpha)}$ can be written as

$$C_{ij}^{(\alpha)} = \alpha_i f_i + \sum_{a=1}^{b_i} \beta_{i,a} x_{i,a} \tag{3.22}$$

with $x_{i,a}$ being the blowups on S_i and $\alpha_i, \beta_{i,a}$ being integers,¹¹ then the gluing curve $C_{ji}^{(\alpha)}$ must take a similar form

$$C_{ji}^{(\alpha)} = \alpha_j f_j + \sum_{a=1}^{b_j} \beta_{j,a} x_{j,a} \tag{3.23}$$

This is because an M2 brane wrapping a curve of the form shown on the right hand side of (3.22) describes a perturbative BPS particle in the $5d$ gauge theory, while M2 brane wrapping a curve of the more general form

$$C_{ji}^{(\alpha)} = \gamma_j e_j + \alpha_j f_j + \sum_{a=1}^{b_j} \beta_{j,a} x_{j,a} \tag{3.24}$$

with $\gamma_j > 0$ describes an instantonic BPS particle in the $5d$ gauge theory. So, the identification

$$C_{ij}^{(\alpha)} \sim C_{ji}^{(\alpha)} \tag{3.25}$$

is compatible with the structure of a $5d$ gauge theory only if γ_j is zero and $C_{ji}^{(\alpha)}$ takes the form shown on right hand side of (3.23).

The matter content for the $5d$ gauge theory is encoded in the blowups $x_{i,a}$ and their gluings. Our task now is to describe how one can read the matter content associated to a geometry X giving rise to a $5d$ gauge theory with gauge algebra \mathfrak{g} . First of all, notice that the intersection matrix of a geometry remains unchanged if we flop a -1 curve of the form¹² $x_{i,a}$ or $f_i - x_{i,a}$. That is, the geometry X' obtained after performing such a flop on X describes a $5d$ gauge theory with the same gauge algebra \mathfrak{g} . In fact, X' describes the same $5d$ gauge theory, and the flop transition corresponds to a phase transition on the mass-deformed Coulomb branch¹³ of the $5d$ gauge theory.

Thus, by performing such flops we can simplify X into a geometry from which it is straightforward to read the associated matter content. So, we associate a simple geometry $X_{\mathfrak{g},R}$ to every $5d$ gauge theory with a gauge algebra \mathfrak{g} and matter transforming in a representation R of \mathfrak{g} . If performing perturbative flops on X converts X to $X_{\mathfrak{g},R}$, then X describes a $5d$ gauge theory with gauge algebra \mathfrak{g} and matter transforming in representation R of \mathfrak{g} .

As long as R contains no half-hypermultiplets, the geometry $X_{\mathfrak{g},R}$ can be described easily in terms of the geometry $X_{\mathfrak{g}}$ associated to the pure $5d$ gauge theory with gauge

¹¹ α_i must be non-negative integer for the curve to be holomorphic.

¹²We refer to such flops as *perturbative flops* in what follows.

¹³In this paper, “mass-deformed Coulomb branch” refers to the space obtained by adjoining the space of mass parameters with Coulomb branch moduli space for each value of mass parameters. All phase transitions occur on this combined space.

algebra \mathfrak{g} described in detail in section 2.4 of [61]. Notice that, unlike the gauge theories carrying non-trivial amount of matter, there is a unique geometry describing a pure $5d$ gauge theory. This is because there is a single perturbative phase for a pure $5d$ gauge theory. Consequently, the Hirzebruch surfaces S_i inside $X_{\mathfrak{g}}$ carry no blowups.

Now, let us describe the construction of $X_{\mathfrak{g},R}$ when R contains no half-hypermultiplets. Let

$$R = \sum_{\mu=1}^m R_{\mu} \tag{3.26}$$

where each¹⁴ R_{μ} is an irreducible representation of \mathfrak{g} . We build $X_{\mathfrak{g},R}$ inductively starting from $X_{\mathfrak{g}}$ at step zero. At each step μ for $1 \leq \mu \leq m$, we construct a geometry $X_{\mathfrak{g}}^{\mu}$ out of the geometry $X_{\mathfrak{g}}^{\mu-1}$ obtained at step $(\mu - 1)$. To do this, let n_i be the Dynkin coefficients of the highest weight of R_{μ} . For each $i \in [1, r]$ where r is the rank of \mathfrak{g} , perform n_i blowups on the surface S_i . That is, we have performed a total of $n_{\mu} := \sum_{i=1}^r n_i$ blowups. Now, glue each pair of blowups in this set of n_{μ} blowups. Let $C_{ij,\mu}$ and $C_{ji,\mu}$ be the total gluing curves describing the gluing between S_i and S_j in $X_{\mathfrak{g}}^{\mu}$. Then, we have

$$C_{ij,\mu} = C_{ij,(\mu-1)} + n_j \sum_{a=1}^{n_i} x_{i,a} \tag{3.27}$$

where $x_{i,a}$ are the n_i blowups performed on S_i at step μ . Similarly, let $K'_{i,\mu}$ be the K' for S_i in $X_{\mathfrak{g}}^{\mu}$. Then, we have

$$K'_{i,\mu} = K'_{i,(\mu-1)} + n_i \sum_{a=1}^{n_i} x_{i,a} \tag{3.28}$$

Finally

$$X_{\mathfrak{g},R} := X_{\mathfrak{g}}^m \tag{3.29}$$

That is, $X_{\mathfrak{g},R}$ is defined to be the geometry obtained after completing step m .

The story applies to a general semi-simple \mathfrak{g} so far. However, to discuss the inclusion of CS levels and theta angles, it is easier to restrict to the case of a simple \mathfrak{g} . This is justified since we only need to consider the case of simple \mathfrak{g} in this paper. The more general semi-simple case was discussed in [61]. For $\mathfrak{g} = \mathfrak{su}(n)$, let k_m be the CS level associated to $X_{\mathfrak{g},R}$ and k_0 be the CS level associated to $X_{\mathfrak{g}}$. Then

$$k_m = k_0 + \frac{1}{2} \sum_{\mu=1}^m A_{\mu} \tag{3.30}$$

where A_{μ} is the cubic Dynkin index (also known as the *anomaly coefficient*) associated to the representation R_{μ} of $\mathfrak{g} = \mathfrak{su}(n)$. For $\mathfrak{g} = \mathfrak{sp}(n)$, the theta angle is relevant if none of the irreps R_{μ} are pseudo-real with an odd quadratic Dynkin index, in which case the theta angle associated to $X_{\mathfrak{g},R}$ equals the theta angle associated to $X_{\mathfrak{g}}$. If some R_{μ} contributes to the $4d$ Witten's anomaly, the choice of theta angle for $X_{\mathfrak{g}}$ is not relevant in the following sense. Let $X_{\mathfrak{g},R}^0$ be obtained by applying the above procedure to $X_{\mathfrak{g}}$ with theta angle zero

¹⁴We allow the possibility of $R_{\mu} = R_{\mu'}$ for $\mu \neq \mu'$.

and let $X_{\mathfrak{g},R}^\pi$ be obtained by applying the above procedure to $X_{\mathfrak{g}}$ with theta angle π . Then, $X_{\mathfrak{g},R}^0$ is related by perturbative flops to $X_{\mathfrak{g},R}^\pi$.

If R contains half-hypermultiplets, then we write it as

$$R = \frac{1}{2}\tilde{R} + \sum_{\mu=1}^m R_\mu \tag{3.31}$$

where \tilde{R} denotes the representation of all half-hypermultiplets and R_μ denote different irreps for full hypermultiplets. The same inductive construction for $X_{\mathfrak{g},R}$ as above applies for this case as well, but the geometry at step zero is taken instead to be $X_{\mathfrak{g},\frac{1}{2}\tilde{R}}$ which is a geometry describing the $5d$ gauge theory with gauge algebra \mathfrak{g} and half-hypers transforming in representation \tilde{R} of \mathfrak{g} . In this paper, we do not tackle the problem of describing $X_{\mathfrak{g},\frac{1}{2}\tilde{R}}$ for arbitrary \tilde{R} and \mathfrak{g} , but only for the cases that will be relevant for $5d$ gauge theories describing $5d$ SCFTs and $5d$ KK theories. These cases are¹⁵

$$\mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \frac{1}{2}\mathbf{F}, \tag{3.32}$$

$$\mathfrak{sp}(4) + \frac{1}{2}\Lambda^3, \tag{3.33}$$

$$\mathfrak{su}(6)_k + \frac{1}{2}\Lambda^3, \tag{3.34}$$

$$\mathfrak{so}(11) + \frac{1}{2}\mathbf{S}, \tag{3.35}$$

$$\mathfrak{so}(12) + \frac{1}{2}\mathbf{S}, \tag{3.36}$$

$$\mathfrak{so}(12) + \frac{1}{2}\mathbf{S} + \frac{1}{2}\mathbf{C}, \tag{3.37}$$

$$\mathfrak{so}(13) + \frac{1}{2}\mathbf{S}, \tag{3.38}$$

$$\mathfrak{e}_7 + \frac{1}{2}\mathbf{F}. \tag{3.39}$$

Below, we will assign a $X_{\mathfrak{g},\frac{1}{2}\tilde{R}}$ to each of these cases. It should be noted that, unlike the case of pure gauge theories, these theories admit multiple perturbative phases. Correspondingly, there is no unique or canonical choice for $X_{\mathfrak{g},\frac{1}{2}\tilde{R}}$. We only present one of the possible choices for each of the above cases. The other choices can be obtained by performing perturbative flops on our presented choices. For more details on understanding why the geometries displayed below describe the matter content we claim they describe, we refer the reader to the general discussion on matter content presented in [61]. We assign:

$$\mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \frac{1}{2}\mathbf{F} \quad :$$

$$\begin{array}{ccccc}
 \mathbf{1}_{11} & \xrightarrow{e} & \mathbf{2}_5 & \xrightarrow{e} & \mathbf{3}_0^{1+1} \\
 f, f & \searrow & & \nearrow & x-y, f-x-y \\
 & & & & 2
 \end{array} \tag{3.40}$$

¹⁵We will later see (geometrically) that the $\mathfrak{sp}(3)$ and $\mathfrak{sp}(4)$ cases do not admit a physically relevant theta angle.

$\mathfrak{sp}(4) + \frac{1}{2}\Lambda^3$:

(3.41)

$\mathfrak{su}(6)_k + \frac{1}{2}\Lambda^3, k = \frac{1}{2} - l, 1 \leq l \leq 7$:

(3.42)

$\mathfrak{su}(6)_k + \frac{1}{2}\Lambda^3, k = -\frac{13}{2} - 2m, m \geq 1$:

(3.43)

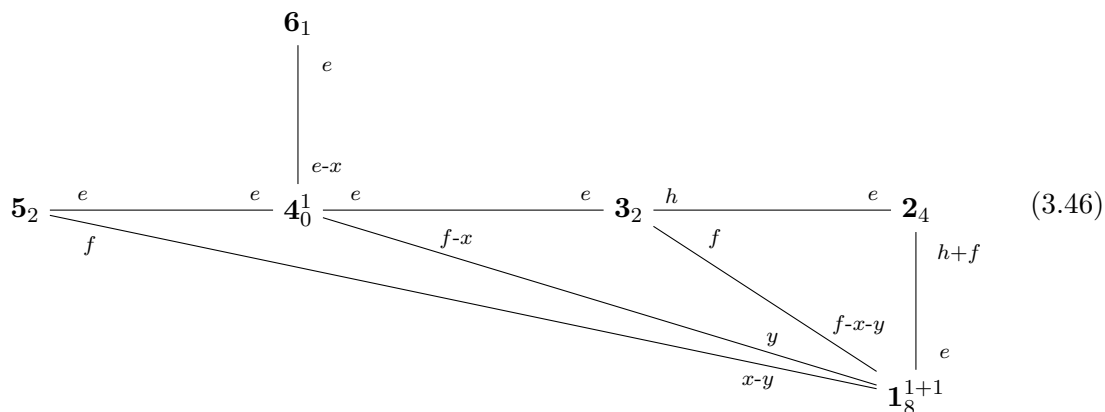
$\mathfrak{su}(6)_k + \frac{1}{2}\Lambda^3, k = -\frac{11}{2} - 2m, m \geq 1$:

(3.44)

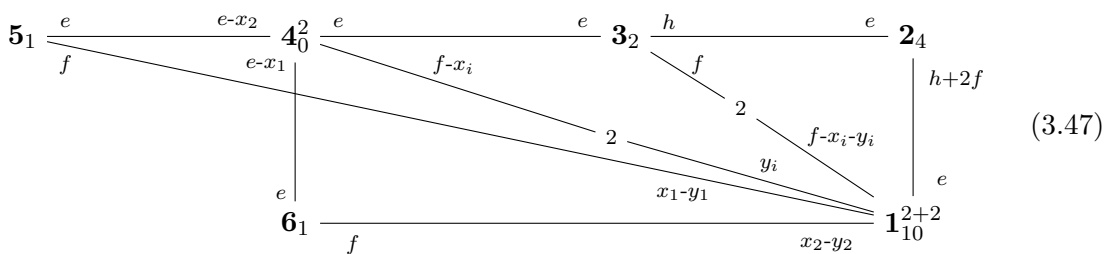
$\mathfrak{so}(11) + \frac{1}{2}\mathbf{S}$:

(3.45)

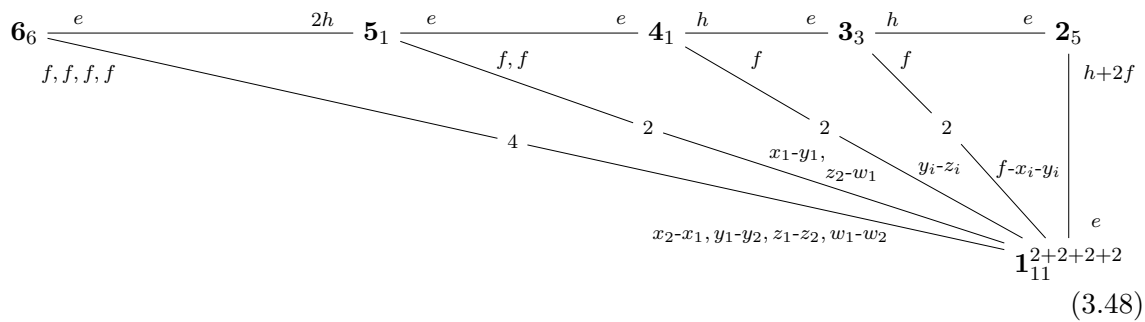
$\mathfrak{so}(12) + \frac{1}{2}\mathbf{S}$:



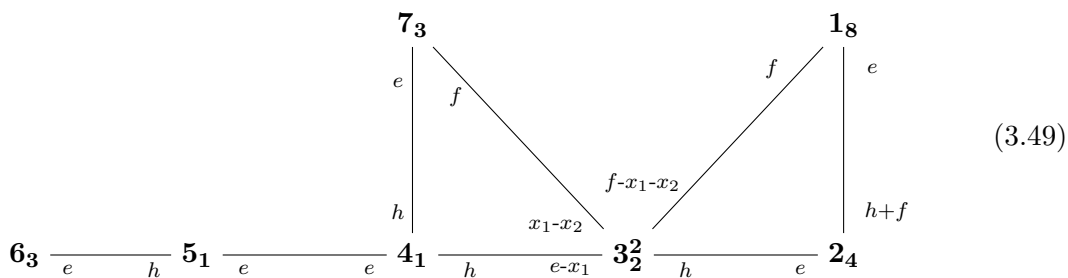
$\mathfrak{so}(12) + \frac{1}{2}\mathbf{S} + \frac{1}{2}\mathbf{C}$:



$\mathfrak{so}(13) + \frac{1}{2}\mathbf{S}$:



$\mathfrak{e}_7 + \frac{1}{2}\mathbf{F}$:



Let us now use the presented geometries (3.40) and (3.41) to argue that the theta angle is irrelevant for (3.32) and (3.33). If the theta was physically relevant for these cases, the geometries corresponding to the other theta angle would be

$$\begin{array}{ccccc}
 \mathbf{1}_{11} & \xrightarrow{e} & \mathbf{2}_5 & \xrightarrow{e} & \mathbf{3}_1^{1+1} \\
 f, f & \searrow & & \nearrow & x-y, f-x-y \\
 & & & & 2
 \end{array} \tag{3.50}$$

and

$$\begin{array}{ccccccc}
 \mathbf{1}_{14} & \xrightarrow{e} & \mathbf{2}_{12} & \xrightarrow{e} & \mathbf{3}_4 & \xrightarrow{e} & \mathbf{4}_1^{2+2} \\
 f, f, f & \searrow & f, f, f & \searrow & f-x_1-y_1, x_1-y_1, x_2-y_2 & \nearrow & f-x_1-x_2, x_1-x_2, y_1-y_2 \\
 & & & & 3 & & 3
 \end{array} \tag{3.51}$$

respectively. However, these geometries are isomorphic to (3.40) and (3.41) respectively. Applying \mathcal{I}_0 on S_3 of (3.40) using the blowup x living in S_3 converts (3.40) into (3.50). Similarly, applying \mathcal{I}_0 on S_4 of (3.41) using the blowup x_1 living in S_4 converts (3.41) into (3.51).

3.3 Structure of 6d gauge theory compactified on a circle

For a geometry X to describe a twisted circle compactification of a 6d $\mathcal{N} = (1, 0)$ gauge theory, all the S_i must be Hirzebruch surfaces with their intersection matrix \mathcal{I}_{ij} being a direct sum of Cartan matrices associated to simple (twisted and untwisted) affine Lie algebras. As for a 5d gauge theory, perturbative BPS particles must only be identified with other perturbative BPS particles.

Let us parametrize simple affine algebras as $\mathfrak{g}_\alpha^{(q_\alpha)}$, where \mathfrak{g}_α are the 6d gauge algebras and q_α capture the order of the outer-automorphism used for twisting \mathfrak{g}_α along the circle [60]. Let us correspondingly parametrize the surfaces as $S_{a,\alpha}$ with the index a (for a fixed α) parametrizing different surfaces whose intersection matrix

$$- f_{a,\alpha} \cdot S_{b,\alpha} \tag{3.52}$$

gives rise to the Cartan matrix $\mathcal{I}_{ab,\alpha}$ of $\mathfrak{g}_\alpha^{(q_\alpha)}$. We let $S_{0,\alpha}$ be the surface corresponding to the affine co-root of $\mathfrak{g}_\alpha^{(q_\alpha)}$. We let $d_{a,\alpha}$ and $d_{a,\alpha}^\vee$ be respectively the Coxeter and dual Coxeter labels¹⁶ associated to $\mathfrak{g}_\alpha^{(q_\alpha)}$. These are minimum positive integers satisfying

$$\sum_a d_{a,\alpha} \mathcal{I}_{ab,\alpha} = 0 \tag{3.53}$$

and

$$\sum_b \mathcal{I}_{ab,\alpha} d_{b,\alpha}^\vee = 0 \tag{3.54}$$

Also let $e_{a,\alpha}$ and $h_{a,\alpha}$ be the e and h curves of the Hirzebruch surface $S_{a,\alpha}$.

¹⁶These can be found in tables 14 and 15 of [60].

The gluing curves between $S_{a,\alpha}$ and $S_{b,\beta}$ for $\alpha \neq \beta$ cannot involve $e_{a,\alpha}$ or $e_{b,\beta}$ since otherwise the intersection matrix would be modified. Thus

$$f_{a,\alpha} \cdot S_{b,\beta} = 0 \tag{3.55}$$

for all a, b and $\alpha \neq \beta$. Moreover, the curve

$$f_\alpha := \sum_a d_{a,\alpha} f_{a,\alpha} \tag{3.56}$$

satisfies

$$f_\alpha \cdot S_{a,\alpha} = 0 \tag{3.57}$$

for all a . Combining this result with (3.55) we find that

$$f_\alpha \cdot S_{b,\beta} = 0 \tag{3.58}$$

for all b, β . Thus the volume of f_α defines a mass parameter of the $5d$ theory associated to X . Since f_α does not involve any blowups, and the matter content is encoded in the blowups, this mass parameter does not arise from holonomies of flavor symmetry groups around the circle. The only other possible mass parameter is given by the radius of the compactification circle, and thus f_α can be identified as the KK mode. Since there is only a single KK mode, the following curves must be equal as classes in X

$$[n_{\alpha,\beta} f_\alpha] = [n_{\beta,\alpha} f_\beta] \tag{3.59}$$

for some positive integers $n_{\alpha,\beta}$ and $n_{\beta,\alpha}$ for all α, β . This means that if there is any gluing curve between a surface $S_{a,\alpha}$ and a surface $S_{b,\beta}$ for $\alpha \neq \beta$ then the other gluing curves between the family of surfaces $\cup_a S_{a,\alpha}$ and the family of surfaces of $\cup_b S_{b,\beta}$ must be such that a particular linear combination of the gluing curves leads to the following gluing

$$n_{\alpha,\beta} f_\alpha \sim n_{\beta,\alpha} f_\beta \tag{3.60}$$

This requirement was used in [51, 60] as consistency conditions on the *gluing rules* between $\cup_a S_{a,\alpha}$ and $\cup_b S_{b,\beta}$.

The tensor branch of the $6d \mathcal{N} = (1, 0)$ theory descends to the Coulomb branch of the circle compactified theory with all mass parameters turned off, which in particular implies that the radius of compactification is set to infinity. Along this Coulomb branch, the masses and tensions of all BPS particles and strings must be non-negative. This Coulomb branch is captured by the Kahler cone $\mathcal{K}(X)$ of X (with all non-normalizable Kahler parameters turned off) along which all the holomorphic curves and surfaces in X have non-negative volume. According to (3.58), f_α must have zero volume along any direction in $\mathcal{K}(X)$. The non-negativity of volumes then implies that each $f_{a,\alpha}$ must have zero volume along any direction $\mathcal{K}(X)$. This fixes $\mathcal{K}(X)$ to be a sub-cone of the cone $\mathcal{T}(X)$ formed by

$$S_\alpha := \sum_a d_{a,\alpha}^\vee S_{a,\alpha} \tag{3.61}$$

for different values of α .

Now let us assume that there is a non-trivial $\mathcal{K}(X)$ inside $\mathcal{T}(X)$. Physically, we are assuming that the $6d$ gauge theory describes either a $6d$ SCFT or a little string theory (LST). Let us focus our attention on a fixed α . We now decompactify all $S_{b,\beta}$ for $\beta \neq \alpha$ by decompactifying the curves $e_{0,\beta}$ which forces the decompactification of other $e_{b,\beta}$. During this process, it is possible to keep all the fibers and blowups compact [63]. The compact surfaces in the resulting Calabi-Yau threefold X_α are only $S_{a,\alpha}$, while the compact curves in X_α comprise of the compact curves living inside $\cup_a S_{a,\alpha}$ along with the curves comprising solely of blowups and fibers in $S_{b,\beta}$ (which are now non-compact surfaces inside X_α) for $\beta \neq \alpha$. Physically, this decompactification process corresponds to ungauging all $6d$ gauge algebras \mathfrak{g}_β for $\beta \neq \alpha$ since the volumes of $e_{0,\beta}$ capture the masses of BPS particles arising by wrapping $6d$ instanton BPS strings on the compactification circle, and these masses are proportional to inverse gauge couplings in the $6d$ gauge theory. If our starting point was a $6d$ SCFT or a LST, we must land on a $6d$ SCFT at the end of this process. Thus X_α must have a non-trivial Kahler cone $\mathcal{K}(X_\alpha)$ inside $\mathcal{T}(X_\alpha)$. The latter cone is spanned entirely by S_α , and hence $\mathcal{K}(X_\alpha)$ is spanned by S_α . Since

$$\text{vol}(x) = -\text{vol}(f_{b,\beta} - x) \tag{3.62}$$

inside $\mathcal{K}(X_\alpha)$ for a blowup x living in $S_{b,\beta}$ (which is compact for $\beta = \alpha$ and non-compact for $\beta \neq \alpha$), we learn that

$$x \cdot S_\alpha = 0 \tag{3.63}$$

for all blowups x in X_α . But since none of the blowups were decompactified, we learn that (3.63) applies to all blowups x in X and to all α . Thus, all the perturbative BPS particles have zero mass inside $\mathcal{T}(X)$. This justifies the “shifted prepotential” proposal of [60].

Now, let us define a matrix

$$M_{\alpha\beta} = -S_\alpha \cdot e_{0,\beta} \tag{3.64}$$

which captures $\text{vol}(e_{0,\beta})$ inside $\mathcal{T}(X)$. Since the gluing curves between $S_{0,\alpha}$ and $S_{b,\beta}$ for $\beta \neq \alpha$ must correspond to perturbative BPS particles, any off-diagonal entry $M_{\alpha\beta}$ must be non-positive. If $\cup_a S_{a,\alpha}$ does not intersect $\cup_b S_{b,\beta}$, then $M_{\alpha\beta} = M_{\beta\alpha} = 0$. If $\cup_a S_{a,\alpha}$ intersects $\cup_b S_{b,\beta}$, then according to (3.60), $f_{0,\alpha}$ must participate in some gluing curve between $S_{0,\alpha}$ and $\cup_b S_{b,\beta}$, thus implying that $M_{\beta\alpha} < 0$. If that’s the case, exchanging the role of β and α , we must also have $M_{\alpha\beta} < 0$. We conclude that the matrix $[M_{\alpha\beta}]$ is a *generalized Cartan matrix*.

According to an important property of generalized Cartan matrices, if $[M_{\alpha\beta}]$ is positive definite, then there is a non-trivial sub-cone inside $\mathcal{T}(X)$ along which all $e_{0,\alpha}$ have positive volume. This sub-cone can be identified with $\mathcal{K}(X)$ as we now show. Any compact curve C inside X lives in some surface $S_{a,\alpha}$ and can be written as

$$C = m e_{a,\alpha} + n f_{a,\alpha} + \sum_i p_i x_i \tag{3.65}$$

where x_i are the blowups in $S_{a,\alpha}$ and m, n, p_i are integers with $m, n \geq 0$. Thus

$$\text{vol}(C) = m \text{vol}(e_{a,\alpha}) \tag{3.66}$$

inside $\mathcal{T}(X)$. Using the intersections between $S_{a,\alpha}$ for different a , one can further rewrite the above as

$$\text{vol}(C) = mb_{a,\alpha}\text{vol}(e_{0,\alpha}) \tag{3.67}$$

for some strictly positive integer $b_{a,\alpha}$. The quantity on the right hand side of (3.67) is manifestly non-negative inside the sub-cone under discussion. Since, inside this sub-cone, the only curve in each surface $S_{a,\alpha}$ that has non-zero volume is $e_{a,\alpha}$ while the fiber $f_{a,\alpha}$ and blowups have zero volume, each surface $S_{a,\alpha}$ has zero volume. Thus all the compact curves and surfaces have non-negative volume in this sub-cone and it can be identified with $\mathcal{K}(X)$. In this case, X corresponds to a twisted circle compactification of a $6d \mathcal{N} = (1, 0)$ gauge theory which describes the tensor branch of a $6d$ SCFT.

If $[M_{\alpha\beta}]$ is positive semi-definite, then there is a unique ray inside $\mathcal{T}(X)$ along which all $e_{0,\alpha}$ have non-negative volume. In fact, the volume of each $e_{0,\alpha}$ along this ray is exactly zero. Hence, every compact curve and surface inside X has zero volume along this ray. In this case, X corresponds to a twisted circle compactification of a $6d \mathcal{N} = (1, 0)$ gauge theory which describes the tensor branch of a $6d$ LST. The ray in the Coulomb branch descends from the non-dynamical tensor multiplet associated to the LST. The fact that the BPS particles $e_{0,\alpha}$ originating from $6d$ strings wrapped on the circle have zero mass means that the strings themselves have zero tension. This is due to the fact that we are working with all mass parameters turned off, so we have the little string mass scale M_s turned off. The size of the tensor branch of a $6d$ LST where the strings have positive tension is dictated by the M_s , and when $M_s = 0$, there is no such tensor branch, which explains our finding.

If $[M_{\alpha\beta}]$ is indefinite, then there is no non-trivial sub-cone inside $\mathcal{T}(X)$ where all $e_{0,\alpha}$ have non-negative volume. In this case, X corresponds to a twisted circle compactification of a $6d \mathcal{N} = (1, 0)$ gauge theory which describes the tensor branch of neither a $6d$ SCFT nor a $6d$ LST.

3.4 Structure of a 5d KK theory

We define a $5d$ KK theory to be a twisted circle (of finite, non-zero radius) compactification of a $6d$ SCFT. $6d$ SCFTs are built by gluing $6d \mathcal{N} = (1, 0)$ gauge theories with certain non-gauge-theoretic pieces. In this subsection, we let X be the Calabi-Yau threefold corresponding to a $5d$ KK theory. From the previous subsection, we already understand the parts of X descending from the gauge-theoretic sector of the corresponding $6d$ SCFT. So we only need to understand the geometries corresponding to non-gauge-theoretic sectors.

A non-gauge-theoretic sector of a $6d$ SCFT can be thought of as a sector with trivial gauge algebra. Thus, the corresponding piece α in the geometry X contains a single surface $S_{0,\alpha}$ which can be thought of as the affine node for trivial gauge algebra. There are three

possibilities for a non-gauge-theoretic sector, corresponding to following $S_{0,\alpha}$

$$\mathbb{F}_1^8 \tag{3.68}$$

$$\begin{array}{c} x \\ \circlearrowleft \\ \mathbb{F}_0^{1+1} \\ \circlearrowright \\ y \end{array} \tag{3.69}$$

$$\begin{array}{c} x \\ \circlearrowleft \\ \mathbb{F}_1^{1+1} \\ \circlearrowright \\ y \end{array} \tag{3.70}$$

For the first case, we define $e_{0,\alpha}$ to be one of the eight blowups instead of the e curve. For the second and third cases, we define $e_{0,\alpha}$ to be the corresponding e curve. If one of the blowups x in (3.68) is not generic and creates the curve $e - x$ in the Mori cone, we can apply \mathcal{I}_1 using this blowup to write (3.68) in the following isomorphic form

$$\mathbb{F}_2^8 \tag{3.71}$$

We will use this isomorphic geometry for this non-gauge-theoretic sector often in this paper. In this isomorphic form, we let $e_{0,\alpha}$ to still be one of the eight blowups.

The surface S_α is defined to be equal to $S_{0,\alpha}$ for non-gauge-theoretic sectors. The curve f_α for each of the three cases are defined to be $2h + f - \sum x_i$, $e + f - x - y$ and $2h + f - 2x - 2y$ respectively. In the isomorphism frame (3.71), the f_α for the first case is written as $2h - \sum x_i$ as the reader can check by applying the isomorphism between (3.68) and (3.71). The reader can also see that

$$f_\alpha \cdot S_{0,\alpha} = 0 \tag{3.72}$$

is satisfied in each of the three cases. The curve f_α for non-gauge-theoretic sectors is required to satisfy same conditions as f_α for gauge-theoretic sectors. That is, (3.58) is now viewed as a constraint on the possible ways of gluing non-gauge-theoretic sectors with the rest of the theory. Similarly, these gluings must satisfy (3.60) as well.

For a geometry X describing a general $5d$ KK theory including both gauge-theoretic and non-gauge-theoretic sectors, we define a matrix $[M_{\alpha\beta}]$ using (3.64) and the above definitions for S_α and $e_{0,\beta}$. This is again a generalized Cartan matrix, which must be positive definite for X to describe a $5d$ KK theory.

We now proceed to show how one can represent $5d$ KK theories using the data of $M_{\alpha\beta}$ and \mathfrak{g}_α for all α, β . We convert this data into a graphical form introduced in [60] to characterize $5d$ KK theories. We will use this graphical notation throughout this paper to represent $5d$ KK theories. Let us first convert the matrix $[M_{\alpha\beta}]$ into another matrix $[\Omega_{\alpha\beta}]$ via

$$\Omega_{\alpha\beta} = \frac{1}{u_\beta} M_{\alpha\beta} \tag{3.73}$$

Here, for trivial \mathfrak{g}_β , we let $u_\beta = 1$. For non-trivial \mathfrak{g}_β , we first unfold the Dynkin diagram for $\mathfrak{g}_\beta^{(q_\beta)}$ until we reach the Dynkin diagram for an untwisted affine Lie algebra \mathfrak{h}_β . The inverse

process $\mathfrak{h}_\beta \rightarrow \mathfrak{g}_\beta^{(q_\beta)}$ involves iterated foldings by identifying nodes exchanged under permutation operations. Then u_β is defined to be the product of the orders of the permutation operations corresponding to these foldings. Thus, if $q_\beta = 1$, then $u_\beta = 1$. For the algebras

$$\mathfrak{su}(2n)^{(2)}, \mathfrak{so}(2n)^{(2)}, \mathfrak{e}_6^{(2)} \tag{3.74}$$

we have $u_\beta = 2$. For the algebra

$$\mathfrak{so}(8)^{(3)} \tag{3.75}$$

we have $u_\beta = 3$. For the algebras

$$\mathfrak{su}(2n+1)^{(2)} \tag{3.76}$$

we have $u_\beta = 4$. Notice that if $[M_{\alpha\beta}]$ is positive definite, then so is $[\Omega_{\alpha\beta}]$, and vice-versa.

Now we convert the data of $[\Omega_{\alpha\beta}]$ into a graph. If α is gauge-theoretic, then we assign a node to it according to following rules:

- If $\Omega_{\alpha\alpha} > 1$, then we assign the node

$$\begin{array}{c} \mathfrak{g}_\alpha^{(q_\alpha)} \\ \Omega_{\alpha\alpha} \end{array} \tag{3.77}$$

to it.

- If $\Omega_{\alpha\alpha} = 1$ and $\mathfrak{g}_\alpha^{(q_\alpha)} \neq \mathfrak{su}(n)^{(1)}$, then we assign the node

$$\begin{array}{c} \mathfrak{g}_\alpha^{(q_\alpha)} \\ 1 \end{array} \tag{3.78}$$

to it.

- If $\Omega_{\alpha\alpha} = 1$ and $\mathfrak{g}_\alpha^{(q_\alpha)} = \mathfrak{su}(n)^{(1)}$, we consider intersections of all the compact curves composed out of fibers and blowups with surfaces $S_{a,\alpha}$ for $a \neq 0$. These intersections imply that perturbative BPS particles associated to these curves are associated to a direct sum $\oplus_\mu R_\mu$ of irreps R_μ of $\mathfrak{su}(n)$. If none of the R_μ equals 2-index symmetric irrep of $\mathfrak{su}(n)$ and $n \geq 3$, then we associate the node

$$\begin{array}{c} \mathfrak{su}(n)^{(1)} \\ 1 \end{array} \tag{3.79}$$

to it. If none of the R_μ equals 2-index symmetric irrep of $\mathfrak{su}(n)$ and $n = 2$, then we associate the node

$$\begin{array}{c} \mathfrak{sp}(1)^{(1)} \\ 1 \end{array} \tag{3.80}$$

to it. If one of R_μ equals 2-index symmetric irrep of $\mathfrak{su}(n)$, then we associate the node

$$\begin{array}{c} \mathfrak{su}(n)^{(1)} \\ 2 \\ \text{⌢} \end{array} \tag{3.81}$$

to it.

If α is non-gauge-theoretic, then we assign a node to it according to following rules:

- If $S_{0,\alpha}$ is isomorphic to (3.68), then we assign the node

$$\begin{array}{c} \mathfrak{sp}(0)^{(1)} \\ 1 \end{array} \tag{3.82}$$

to it.

- If $S_{0,\alpha}$ is isomorphic to (3.69), then we assign the node

$$\begin{array}{c} \mathfrak{su}(1)^{(1)} \\ 2 \end{array} \tag{3.83}$$

to it.

- If $S_{0,\alpha}$ is isomorphic to (3.70), then we assign the node

$$\begin{array}{c} \mathfrak{su}(1)^{(1)} \\ 2 \\ \text{---} \end{array} \tag{3.84}$$

to it.

Now we move onto the description of edges:

- If $\Omega_{\alpha\beta} = \Omega_{\beta\alpha} = -1$ for $\alpha \neq \beta$, then the nodes corresponding to α and β are joined by an edge as shown below

$$\begin{array}{cc} \mathfrak{g}_{\alpha}^{(q_{\alpha})} & \mathfrak{g}_{\beta}^{(q_{\beta})} \\ \Omega_{\alpha\alpha} & \text{---} \Omega_{\beta\beta} \end{array} \tag{3.85}$$

Here the node corresponding to α or β could carry a loop as in (3.80) and (3.83). However, we omit the loop throughout our discussion of edges, as it does not influence the discussion.

- If $\Omega_{\alpha\beta} = \Omega_{\beta\alpha} = -k < -1$ for $\alpha \neq \beta$, then the nodes corresponding to α and β are joined by an edge of the following form

$$\begin{array}{cc} \mathfrak{g}_{\alpha}^{(q_{\alpha})} & \mathfrak{g}_{\beta}^{(q_{\beta})} \\ \Omega_{\alpha\alpha} & \text{---} k \text{---} \Omega_{\beta\beta} \end{array} \tag{3.86}$$

- Now let us consider the case $\Omega_{\alpha\beta} \neq \Omega_{\beta\alpha}$ for $\beta \neq \alpha$. From the analysis of the structure of $6d$ SCFTs one can deduce that for this to happen [60], either $\Omega_{\alpha\beta} = -1$ or $\Omega_{\beta\alpha} = -1$. Let us assume without loss of generality that $\Omega_{\beta\alpha} = -1$ and $\Omega_{\alpha\beta} = -k < -1$. We denote this situation by placing the following edge

$$\begin{array}{cc} \mathfrak{g}_{\alpha}^{(q_{\alpha})} & \mathfrak{g}_{\beta}^{(q_{\beta})} \\ \Omega_{\alpha\alpha} & \text{---} k \text{---} \Omega_{\beta\beta} \end{array} \tag{3.87}$$

Sometimes different KK theories have the same associated graph. In this case, the vertices and edges are decorated to distinguish between different cases. See more details about such decorations in [60]. Finally, unfolding the graph associated to a 5d KK theory and removing the subscripts q_α give rise to the graph associated to the 6d SCFT (see [60]) whose circle compactification gives rise to the 5d KK theory. The q_α capture the outer-automorphism twist performed on \mathfrak{g}_α while going around the circle, and folding captures the permutation of tensor multiplets occurring while going around the circle.

4 Detailed analysis

4.1 General rank

Consider the following geometry describing untwisted compactification of 6d SCFT carrying $\mathfrak{sp}(m)$ on -1 curve

$$\mathbf{1}_0^{2m+8} \xrightarrow{2e+f-\sum x_i} \xrightarrow{h} \mathbf{2}_{2m+2} \xrightarrow{e} \cdots \xrightarrow{h} (\mathbf{m}-1)_8 \xrightarrow{e} \xrightarrow{h} \mathbf{m}_6 \xrightarrow{e} \xrightarrow{2e+f} (\mathbf{m}+1)_0 \quad (4.1)$$

Applying \mathcal{S} to S_1 , we obtain the geometry

$$\mathbf{1}_0^{2m+8} \xrightarrow{e+2f-\sum x_i} \xrightarrow{h} \mathbf{2}_{2m+2} \xrightarrow{e} \cdots \xrightarrow{h} (\mathbf{m}-1)_8 \xrightarrow{e} \xrightarrow{h} \mathbf{m}_6 \xrightarrow{e} \xrightarrow{2e+f} (\mathbf{m}+1)_0 \quad (4.2)$$

which can be rewritten as

$$\mathbf{1}_{2m+4}^{2m+8} \xrightarrow{e} \xrightarrow{h} \mathbf{2}_{2m+2} \xrightarrow{e} \cdots \xrightarrow{h} (\mathbf{m}-1)_8 \xrightarrow{e} \xrightarrow{h} \mathbf{m}_6 \xrightarrow{e} \xrightarrow{2e+f} (\mathbf{m}+1)_0 \quad (4.3)$$

which clearly describes the 5d gauge theory $\mathfrak{sp}(m+1) + (2m+8)\mathbf{F}$. Now, applying \mathcal{S} on S_{m+1} , we obtain the geometry

$$\mathbf{1}_{2m+4}^{2m+8} \xrightarrow{e} \xrightarrow{h} \mathbf{2}_{2m+2} \xrightarrow{e} \cdots \xrightarrow{h} (\mathbf{m}-1)_8 \xrightarrow{e} \xrightarrow{h} \mathbf{m}_6 \xrightarrow{e} \xrightarrow{e+2f} (\mathbf{m}+1)_0 \quad (4.4)$$

which describes the 5d gauge theory $\mathfrak{su}(m+2)_0 + (2m+8)\mathbf{F}$. Thus, we obtain

$$\boxed{\mathfrak{su}(m+2)_0 + (2m+8)\mathbf{F} = \mathfrak{sp}(m+1) + (2m+8)\mathbf{F} = \frac{\mathfrak{sp}(m)^{(1)}}{1}} \quad (4.5)$$

for $m \geq 1$ and

$$\boxed{\mathfrak{sp}(1) + 8\mathbf{F} = \frac{\mathfrak{sp}(0)^{(1)}}{1}} \quad (4.6)$$

for $m = 0$. Removing the blowups sitting on S_1 of (4.3) and (4.4), the two geometries remain isomorphic, thus implying that the duality between $\mathfrak{su}(m+2)$ and $\mathfrak{sp}(m+1)$ gauge

theories holds true as we integrate out fundamental matter from both sides of the duality. When all blowups are removed, we obtain that the geometry

$$\mathbf{1}_{2m+4} \xrightarrow[e]{h} \mathbf{2}_{2m+2} \xrightarrow[e]{\dots} \xrightarrow[h]{\dots} (\mathbf{m}-1)_8 \xrightarrow[e]{h} \mathbf{m}_6 \xrightarrow[e]{e+2f} (\mathbf{m}+1)_0 \quad (4.7)$$

describing pure $\mathfrak{su}(m+2)_{m+4}$ gauge theory is isomorphic to the geometry

$$\mathbf{1}_{2m+4} \xrightarrow[e]{h} \mathbf{2}_{2m+2} \xrightarrow[e]{\dots} \xrightarrow[h]{\dots} (\mathbf{m}-1)_8 \xrightarrow[e]{h} \mathbf{m}_6 \xrightarrow[e]{2e+f} (\mathbf{m}+1)_0 \quad (4.8)$$

describing pure $\mathfrak{sp}(m+1)$ gauge theory with theta angle $\theta = m\pi \pmod{2\pi}$ (See appendix B.3 of [60] for an explanation).

Consider the following geometry describing the untwisted compactification of 6d SCFT carrying $\mathfrak{su}(2n)$ on -1 curve

$$\begin{array}{ccccccc} \mathbf{2n}_0^{(2n+6)+1} & \xrightarrow[e+f-\sum x_i-y]{h-x} & (\mathbf{2n}-1)_{2n+4}^1 & \xrightarrow[e]{\dots} & \xrightarrow[h-x]{\dots} & (\mathbf{n}+2)_{n+7}^1 & \\ \begin{array}{l} \nearrow^{e-y} \\ \searrow_{e+f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^e \\ \searrow_{h+f} \end{array} \\ \mathbf{1}_0^{1+1} & & & & & & (\mathbf{n}+1)_{n+3} \\ \begin{array}{l} \nearrow^{e+f-x} \\ \searrow_e \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^e \\ \searrow_h \end{array} \\ & & \mathbf{2}_3^1 & \xrightarrow[h-x]{\dots} & \mathbf{3}_4^1 & \xrightarrow[e]{\dots} & \mathbf{n}_{n+1}^1 \end{array} \quad (4.9)$$

Applying \mathcal{S} on S_1 and S_{2n} , we obtain the geometry

$$\begin{array}{ccccccc} \mathbf{2n}_0^{(2n+6)+1} & \xrightarrow[e+f-\sum x_i-y]{h-x} & (\mathbf{2n}-1)_{2n+4}^1 & \xrightarrow[e]{\dots} & \xrightarrow[h-x]{\dots} & (\mathbf{n}+2)_{n+7}^1 & \\ \begin{array}{l} \nearrow^{f-y} \\ \searrow_{e+f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^e \\ \searrow_{h+f} \end{array} \\ \mathbf{1}_0^{1+1} & & & & & & (\mathbf{n}+1)_{n+3} \\ \begin{array}{l} \nearrow^{e+f-x} \\ \searrow_e \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^e \\ \searrow_h \end{array} \\ & & \mathbf{2}_3^1 & \xrightarrow[h-x]{\dots} & \mathbf{3}_4^1 & \xrightarrow[e]{\dots} & \mathbf{n}_{n+1}^1 \end{array} \quad (4.10)$$

which describes the 5d gauge theory $\mathfrak{su}(2n+1)_0 + \Lambda^2 + (2n+7)F$. Similarly, applying \mathcal{S} on S_1 and S_{2n+1} in

$$\begin{array}{ccccccc} (\mathbf{2n}+1)_0^{(2n+7)+1} & \xrightarrow[e+f-\sum x_i-y]{h-x} & \mathbf{2n}_{2n+5}^1 & \xrightarrow[e]{\dots} & \xrightarrow[h-x]{\dots} & (\mathbf{n}+3)_{n+8}^1 & \xrightarrow[e]{h+f-x} & (\mathbf{n}+2)_{n+5}^1 \\ \begin{array}{l} \nearrow^{e-y} \\ \searrow_{e+f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & \begin{array}{l} \nearrow^e \\ \searrow_{e-x} \end{array} \\ \mathbf{1}_0^{1+1} & & & & & & & (\mathbf{n}+1)_{n+2} \\ \begin{array}{l} \nearrow^{e+f-x} \\ \searrow_e \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & & \begin{array}{l} \nearrow^x \\ \searrow_{f-x} \end{array} & \begin{array}{l} \nearrow^e \\ \searrow_{h+f} \end{array} \\ & & \mathbf{2}_3^1 & \xrightarrow[h-x]{\dots} & \mathbf{3}_4^1 & \xrightarrow[e]{\dots} & \mathbf{n}_{n+1}^1 & \xrightarrow[h-x]{\dots} & \mathbf{n}_{n+1}^1 & \xrightarrow[e]{\dots} & (\mathbf{n}+1)_{n+2} \end{array} \quad (4.11)$$

we transition from untwisted compactification of 6d SCFT carrying $\mathfrak{su}(2n+1)$ on -1 curve to 5d gauge theory $\mathfrak{su}(2n+2)_0 + \Lambda^2 + (2n+8)F$. Thus, we obtain

$$\boxed{\mathfrak{su}(m+1)_0 + \Lambda^2 + (m+7)F = \mathfrak{su}(m)^{(1)}_1} \quad (4.12)$$

The KK theory

$$\mathfrak{sp}(0)^{(1)}_1 \text{ --- } \mathfrak{su}(1)^{(1)}_2 \text{ --- } \cdots \text{ --- } \mathfrak{su}(1)^{(1)}_2 \quad (4.13)$$

$\underbrace{\hspace{10em}}_m$

is described by the geometry

$$\begin{array}{c} (\mathbf{m}+1)_1^8 \\ \left| \begin{array}{l} 2h+f-\sum x_i \\ f \end{array} \right. \\ \mathbf{m}_0^{1+1} \xrightarrow{f-x,x} 2 \xrightarrow{f-y,y} (\mathbf{m}-1)_0^{1+1} \xrightarrow{f-x,x} \cdots \xrightarrow{f-y,y} \mathbf{2}_0^{1+1} \xrightarrow{f-x,x} 2 \xrightarrow{f-y,y} \mathbf{1}_0^{1+1} \\ \left(\begin{array}{c} e-x \\ \text{---} \\ e-y \end{array} \right) \quad \left(\begin{array}{c} e-x \\ \text{---} \\ e-y \end{array} \right) \quad \left(\begin{array}{c} e-x \\ \text{---} \\ e-y \end{array} \right) \quad \left(\begin{array}{c} e-x \\ \text{---} \\ e-y \end{array} \right) \end{array} \quad (4.14)$$

which can be rewritten as

$$\begin{array}{c} (\mathbf{m}+1)_1^8 \\ \left| \begin{array}{l} 2h+f-\sum x_i \\ e+f-x-y \end{array} \right. \\ \mathbf{m}_0^{1+1} \xrightarrow{e-y,f-x} 2 \xrightarrow{e-x,f-y} (\mathbf{m}-1)_0^{1+1} \xrightarrow{e-y,f-x} \cdots \xrightarrow{e-x,f-y} \mathbf{2}_0^{1+1} \xrightarrow{e-y,f-x} 2 \xrightarrow{e-x,f-y} \mathbf{1}_0^{1+1} \\ \left(\begin{array}{c} x \\ \text{---} \\ y \end{array} \right) \quad \left(\begin{array}{c} x \\ \text{---} \\ y \end{array} \right) \quad \left(\begin{array}{c} x \\ \text{---} \\ y \end{array} \right) \quad \left(\begin{array}{c} x \\ \text{---} \\ y \end{array} \right) \end{array} \quad (4.15)$$

which describes the 5d gauge theory $\mathfrak{sp}(m+1) + \Lambda^2 + 8F$. Another flop frame to describe the same 5d gauge theory is

$$\mathbf{1}_{2m+4}^8 \xrightarrow{e} \xrightarrow{h} \mathbf{2}_{2m+2}^1 \xrightarrow{e} \cdots \xrightarrow{h} (\mathbf{m}-1)_8 \xrightarrow{e} \xrightarrow{h} \mathbf{m}_6 \xrightarrow{e} \xrightarrow{2e+f} (\mathbf{m}+1)_0 \quad (4.16)$$

Applying \mathcal{S} on S_{m+1} of the above geometry implies that the above 5d gauge theory is dual to $\mathfrak{su}(m+2)_{\frac{m}{2}+1} + \Lambda^2 + 8F$. Thus we obtain

$$\boxed{\mathfrak{su}(m+2)_{\frac{m}{2}+1} + \Lambda^2 + 8F = \mathfrak{sp}(m+1) + \Lambda^2 + 8F = \mathfrak{sp}(0)^{(1)}_1 \text{ --- } \mathfrak{su}(1)^{(1)}_2 \text{ --- } \cdots \text{ --- } \mathfrak{su}(1)^{(1)}_2} \quad (4.17)$$

$\underbrace{\hspace{10em}}_m$

It is clear from (4.16) that the above duality between $\mathfrak{sp}(m+1)$ and $\mathfrak{su}(m+2)$ gauge theories continues to hold as we integrate out F from both sides of the duality.

The 5d KK theory

$$\begin{array}{ccccccc}
 \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(2)^{(1)} & & \mathfrak{su}(2)^{(1)} & & & \\
 1 & \text{---} & 2 & \text{---} & \cdots & \text{---} & 2 \\
 & & & & \underbrace{\hspace{10em}} & & \\
 & & & & m & &
 \end{array} \tag{4.18}$$

can be described by the geometry

$$\begin{array}{ccccccc}
 \mathbf{m}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathbf{(m-1)}_0^{1+1} & \xrightarrow{f-x} & \cdots & \xrightarrow{f-y} & \mathbf{2}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathbf{1}_0^{1+1} \\
 \begin{array}{c} f \\ e+f-\sum x_i \\ e, \\ e-x-y \\ 2 \\ e+f-\sum y_i \\ f \end{array} & \begin{array}{c} x \\ y \\ x \\ y \end{array} & & \begin{array}{c} y \\ e, \\ e-x-y \\ 2 \\ e-x-y, \\ e \end{array} & \begin{array}{c} x \\ y \\ x \\ y \end{array} & \cdots & \begin{array}{c} y \\ e, \\ e-x-y \\ 2 \\ e-x-y, \\ e \end{array} & \begin{array}{c} x \\ y \\ x \\ y \end{array} & & \begin{array}{c} y \\ e, \\ e-x-y \\ 2 \\ e-x-y, \\ e \end{array} & \begin{array}{c} x \\ y \\ x \\ y \end{array} \\
 \mathbf{(m+2)}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathbf{(m+3)}_0^{1+1} & \xrightarrow{f-x} & \cdots & \xrightarrow{f-y} & \mathbf{2m}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathbf{(2m+1)}_0^{1+1}
 \end{array} \tag{4.19}$$

Applying \mathcal{S} on all the surfaces in this geometry, we learn that

$$\boxed{
 \begin{array}{ccccccc}
 \mathfrak{su}(2m+2)_0 + 2\Lambda^2 + 8F & = & \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(2)^{(1)} & & \mathfrak{su}(2)^{(1)} & \\
 & & 1 & \text{---} & 2 & \text{---} & \cdots & \text{---} & 2 \\
 & & & & & & \underbrace{\hspace{10em}} & & \\
 & & & & & & m & &
 \end{array}
 } \tag{4.20}$$

Similarly, the KK theory

$$\begin{array}{ccccccc}
 \mathfrak{sp}(1)^{(1)} & \mathfrak{su}(2)^{(1)} & & \mathfrak{su}(2)^{(1)} & & & \\
 1 & \text{---} & 2 & \text{---} & \cdots & \text{---} & 2 \\
 & & & & \underbrace{\hspace{10em}} & & \\
 & & & & m & &
 \end{array} \tag{4.21}$$

can be described by the geometry

$$\begin{array}{ccccccc}
 \mathbf{(m+1)}_0^{1+4} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathbf{m}_0^{1+1} & \xrightarrow{f-x} & \cdots & \xrightarrow{f-y} & \mathbf{2}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathbf{1}_0^{1+1} \\
 \begin{array}{c} 2e+f-x-\sum y_i \\ x \\ 2e+f-x-\sum y_i \\ x \end{array} & \begin{array}{c} x \\ y \\ x \\ y \end{array} & & \begin{array}{c} y \\ e, \\ e-x-y \\ 2 \\ e-x-y, \\ e \end{array} & \begin{array}{c} x \\ y \\ x \\ y \end{array} & \cdots & \begin{array}{c} y \\ e, \\ e-x-y \\ 2 \\ e-x-y, \\ e \end{array} & \begin{array}{c} x \\ y \\ x \\ y \end{array} & & \begin{array}{c} y \\ e, \\ e-x-y \\ 2 \\ e-x-y, \\ e \end{array} & \begin{array}{c} x \\ y \\ x \\ y \end{array} \\
 \mathbf{(m+2)}_0^{1+4} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathbf{(m+3)}_0^{1+1} & \xrightarrow{f-x} & \cdots & \xrightarrow{f-y} & \mathbf{(2m+1)}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathbf{(2m+2)}_0^{1+1}
 \end{array} \tag{4.22}$$

Applying \mathcal{S} on all surfaces of the above geometry, we learn that

$$\boxed{\text{su}(2m+3)_0 + 2\Lambda^2 + 8F = \begin{array}{c} \mathfrak{sp}(1)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \\ 1 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}}_m \end{array}} \quad (4.23)$$

The 5d KK theory

$$\begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 1 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \text{ --- } 2 \\ \underbrace{\hspace{10em}}_m \end{array} \quad (4.24)$$

can be described by the geometry obtained by applying \mathcal{S} on all surfaces except S_{2m+2} of the following geometry

$$\begin{array}{c} \mathbf{m}_0^{1+1} \xrightarrow{e-x} \mathbf{(m-1)}_0^{1+1} \xrightarrow{e-x} \dots \xrightarrow{e-y} \mathbf{1}_0^{1+1} \\ \begin{array}{c} e \\ \nearrow \\ \mathbf{(m+1)}_0^{4+4} \\ \searrow \\ e \end{array} \begin{array}{c} f, \\ f-x-y \\ | \\ 2 \\ \end{array} \begin{array}{c} x \\ \searrow \\ \mathbf{(m+2)}_0^{1+1} \\ \nearrow \\ e \end{array} \begin{array}{c} y \\ \nearrow \\ \mathbf{(m-1)}_0^{1+1} \\ \searrow \\ y \end{array} \begin{array}{c} f, \\ f-x-y \\ | \\ 2 \\ \end{array} \begin{array}{c} x \\ \searrow \\ \mathbf{(m+3)}_0^{1+1} \\ \nearrow \\ y \end{array} \dots \begin{array}{c} y \\ \nearrow \\ \mathbf{1}_0^{1+1} \\ \searrow \\ y \end{array} \begin{array}{c} f, \\ f-x-y \\ | \\ 2 \\ \end{array} \begin{array}{c} e-x, x \\ \searrow \\ \mathbf{(2m+2)}_2^{1+1} \\ \nearrow \\ e \end{array} \begin{array}{c} f-x, f-y \\ \searrow \\ \mathbf{(2m+1)}_0^{1+1} \\ \nearrow \\ e \end{array} \\ \mathbf{(m+2)}_0^{1+1} \xrightarrow{e-x} \mathbf{(m+3)}_0^{1+1} \xrightarrow{e-x} \dots \xrightarrow{e-y} \mathbf{(2m+1)}_0^{1+1} \end{array} \quad (4.25)$$

The above geometry can be seen to be flop equivalent to

$$\begin{array}{c} \mathbf{m}_1^{1+1} \xrightarrow{h-x} \mathbf{(m-1)}_1^{1+1} \xrightarrow{h-x} \dots \xrightarrow{e-y_1} \mathbf{1}_1^{3+2} \\ \begin{array}{c} e \\ \nearrow \\ \mathbf{(m+1)}_0^{3+4} \\ \searrow \\ e \end{array} \begin{array}{c} f, \\ f-x-y \\ | \\ 2 \\ \end{array} \begin{array}{c} x \\ \searrow \\ \mathbf{(m+2)}_0^{1+1} \\ \nearrow \\ e \end{array} \begin{array}{c} y \\ \nearrow \\ \mathbf{(m-1)}_1^{1+1} \\ \searrow \\ y \end{array} \begin{array}{c} f, \\ f-x-y \\ | \\ 2 \\ \end{array} \begin{array}{c} x \\ \searrow \\ \mathbf{(m+3)}_0^{1+1} \\ \nearrow \\ y \end{array} \dots \begin{array}{c} y_1 \\ \nearrow \\ \mathbf{1}_1^{3+2} \\ \searrow \\ y \end{array} \begin{array}{c} f-y_2, \\ f-x_1-y_1 \\ | \\ 2 \\ \end{array} \begin{array}{c} h-x_1-x_2-x_3, x_1-x_2 \\ \searrow \\ \mathbf{(2m+2)}_2 \\ \nearrow \\ e \end{array} \begin{array}{c} f, f \\ \searrow \\ \mathbf{(2m+1)}_0^1 \\ \nearrow \\ e \end{array} \\ \mathbf{(m+2)}_0^{1+1} \xrightarrow{e-x} \mathbf{(m+3)}_0^{1+1} \xrightarrow{e-x} \dots \xrightarrow{e-x} \mathbf{(2m+1)}_0^1 \end{array} \quad (4.26)$$

which is isomorphic to

$$\begin{array}{ccccccc}
 & \mathfrak{m}_1^{1+1} & \xrightarrow{h-x} & \xrightarrow{e-y} & (\mathfrak{m}-1)_1^{1+1} & \xrightarrow{h-x} & \dots & \xrightarrow{e+f-x_1-x_2-\dots-y_i} & \mathfrak{l}_0^{3+2} \\
 & \nearrow e & & & \nearrow y & & & \nearrow y_1 & \nearrow f-y_2-x_3, x_2-x_1 \\
 & & \text{f,} & & \text{f,} & & & & \text{2} \\
 & & \text{f-x-y} & & \text{f-x-y} & & & & \text{f, f} \\
 (\mathfrak{m}+1)_0^{3+4} & & & & & & \dots & & (\mathfrak{2m}+2)_2 \\
 & \nwarrow e+f-\sum x_i & & & \nwarrow f-x-y & & & & \nwarrow e \\
 & & \text{f-x-y,} & & \text{f-x-y,} & & & & \\
 & & \text{f} & & \text{f} & & & & \\
 & & \text{2} & & \text{2} & & & & \\
 & \nwarrow e+f-\sum y_i & & & \nwarrow y & & & & \nwarrow x \\
 & & \text{f-x-y,} & & \text{f-x-y,} & & & & \nwarrow f-x, \\
 & & \text{f} & & \text{f} & & & & \text{f} \\
 & & \text{2} & & \text{2} & & & & \text{2} \\
 & & \text{2} & & \text{2} & & & & \text{2} \\
 (\mathfrak{m}+2)_0^{1+1} & \xrightarrow{e-x} & \xrightarrow{e-y} & (\mathfrak{m}+3)_0^{1+1} & \xrightarrow{e-x} & \dots & \xrightarrow{e-x} & (\mathfrak{2m}+1)_0^1
 \end{array}
 \tag{4.27}$$

implying that

$$\boxed{
 \mathfrak{su}(2m+3)_{\frac{3}{2}} + 2\Lambda^2 + 7F = \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \dots \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)}
 }
 \tag{4.28}$$

In a similar way, we can obtain

$$\boxed{
 \mathfrak{su}(2m+4)_{\frac{3}{2}} + 2\Lambda^2 + 7F = \mathfrak{sp}(1)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \dots \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)}
 }
 \tag{4.29}$$

Applying \mathcal{S} on S_1 and S_{2n} of

$$\begin{array}{ccccccc}
 & \mathfrak{2n}_{2n-4}^{1+(2n-2)} & \xrightarrow{e+f-x-\dots-y_i} & \xrightarrow{h-x} & (\mathfrak{2n}-1)_{2n-4}^1 & \xrightarrow{e} & \dots & \xrightarrow{h-x} & (\mathfrak{n}+2)_{n-1}^1 \\
 & \nearrow e-y & & & \nearrow x & & & \nearrow x & \nearrow e \\
 & & & & & & & & \nearrow f-x \\
 & & & & & & & & \nearrow e+(n-2)f \\
 & & & & & & & & \text{2} \\
 & & & & & & & & \text{f-x,} \\
 \mathfrak{l}_0^{1+1} & & & & & & & & \text{f-x} \\
 & \nwarrow e+f-x & & & \nwarrow f-x & & & & \nwarrow e+f-x-2y, \\
 & & & & & & & & \text{f-x} \\
 & & & & & & & & \text{2} \\
 & & & & & & & & \text{h-x, x} \\
 & & & & & & & & \text{2} \\
 & & & & & & & & \text{2} \\
 & & & & & & & & \text{2} \\
 \mathfrak{l}_3^{1+1} & \xrightarrow{e-x} & \xrightarrow{h-x} & \mathfrak{l}_3^{1+1} & \xrightarrow{e} & \dots & \xrightarrow{e} & \mathfrak{l}_{n+1}^1
 \end{array}
 \tag{4.30}$$

and applying \mathcal{S} on S_1 and S_{2n+1} of

$$\begin{array}{c}
 \begin{array}{ccccccc}
 (2n+1)_0^{1+(2n-1)} & \xrightarrow{e+f-x-\sum y_i} & 2n_{2n-3}^1 & \xrightarrow{e} \dots \xrightarrow{h-x} & (n+3)_n^1 & \xrightarrow{e+e+(n-1)f} & (n+2)_n^{1+1+1} \\
 \begin{array}{l} e-x \\ e-y \\ e+f-x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-z \\ x \\ e \end{array} \\
 \begin{array}{l} \text{arc } x \text{ over } y \\ \text{arc } e+f-x-2y-z, \\ \text{arc } z-x \end{array} & & & & & & \\
 \end{array} \\
 \begin{array}{ccccccc}
 2_3^1 & \xrightarrow{h-x} & 3_4^1 & \xrightarrow{h-x} \dots \xrightarrow{e} & n_{n+1}^1 & \xrightarrow{h-x} & (n+1)_{n+2}^1 \\
 \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} & \begin{array}{l} x \\ f-x \\ x \\ e \end{array} \\
 \begin{array}{l} \text{arc } x \\ \text{arc } h, f \end{array} & & & & & & \\
 \end{array}
 \end{array}
 \tag{4.31}$$

we find that

$$\mathfrak{su}(m+1)_0 + \mathbb{S}^2 + (m-1)\mathbb{F} = \mathfrak{su}(m)^{(1)}$$

$$\begin{array}{c}
 \mathfrak{su}(m)^{(1)} \\
 \text{arc } 2
 \end{array}
 \tag{4.32}$$

The KK theory

$$\begin{array}{ccccccc}
 \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & & \mathfrak{su}(1)^{(1)} \\
 2 \leftarrow 2 & \text{---} & 2 & \text{---} & \dots & \text{---} & 2 \\
 & & \underbrace{\hspace{10em}} & & & & \\
 & & 2m-2 & & & &
 \end{array}
 \tag{4.33}$$

can be described by the geometry

$$\begin{array}{ccccccc}
 (2m-1)_0^{1+1} & \xrightarrow{2f-x,x} & 2 & \xrightarrow{f-y,y} & (2m-2)_0^{1+1} & \xrightarrow{f-x,x} \dots \xrightarrow{f-y,y} & 2_0^{1+1} & \xrightarrow{f-x,x} & 2 & \xrightarrow{f-y,y} & 1_0^{1+1} \\
 \begin{array}{l} e-x \\ \text{arc } e-y \end{array} & & & & \begin{array}{l} e-x \\ \text{arc } e-y \end{array} & & \begin{array}{l} e-x \\ \text{arc } e-y \end{array} & & & & \begin{array}{l} e-x \\ \text{arc } e-y \end{array} \\
 \end{array}
 \tag{4.34}$$

which is isomorphic to

$$\begin{array}{ccccccc}
 (2m-1)_0^{1+1} & \xrightarrow{2e+f-x-2y,f-x} & 2 & \xrightarrow{e-x,f-y} & (2m-2)_0^{1+1} & \xrightarrow{e-y,f-x} \dots \xrightarrow{e-x,f-y} & 2_0^{1+1} & \xrightarrow{e-y,f-x} & 2 & \xrightarrow{e-x,f-y} & 1_0^{1+1} \\
 \begin{array}{l} x \\ \text{arc } y \end{array} & & & & \begin{array}{l} x \\ \text{arc } y \end{array} & & \begin{array}{l} x \\ \text{arc } y \end{array} & & & & \begin{array}{l} x \\ \text{arc } y \end{array} \\
 \end{array}
 \tag{4.35}$$

thus describing $\mathfrak{sp}(2m-1)_0 + \mathbb{A}$. Similarly, the geometry

$$\begin{array}{ccccccc}
 2m_1^{1+1} & \xrightarrow{2h-x-2y,f-x} & 2 & \xrightarrow{f-y,y} & (2m-1)_0^{1+1} & \xrightarrow{f-x,x} \dots \xrightarrow{f-y,y} & 2_0^{1+1} & \xrightarrow{f-x,x} & 2 & \xrightarrow{f-y,y} & 1_0^{1+1} \\
 \begin{array}{l} x \\ \text{arc } y \end{array} & & & & \begin{array}{l} e-x \\ \text{arc } e-y \end{array} & & \begin{array}{l} e-x \\ \text{arc } e-y \end{array} & & & & \begin{array}{l} e-x \\ \text{arc } e-y \end{array} \\
 \end{array}
 \tag{4.36}$$

describing the KK theory

$$\begin{array}{c}
 \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\
 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\
 \underbrace{\hspace{10em}}_{2m-1} \\
 \textcircled{\hspace{1em}}
 \end{array} \tag{4.37}$$

is isomorphic to the geometry

$$\begin{array}{c}
 \mathbf{2m}_0^{1+1} \xrightarrow{2h-x-2y, f-x} 2 \xrightarrow{e-x, f-y} (\mathbf{2m-1})_0^{1+1} \xrightarrow{e-y, f-x} \dots \xrightarrow{e-x, f-y} \mathbf{2}_0^{1+1} \xrightarrow{e-y, f-x} 2 \xrightarrow{e-x, f-y} \mathbf{1}_0^{1+1} \\
 x \textcircled{\hspace{1em}} y \quad x \textcircled{\hspace{1em}} y \quad x \textcircled{\hspace{1em}} y \quad x \textcircled{\hspace{1em}} y
 \end{array} \tag{4.38}$$

describing $\mathfrak{sp}(2m)_\pi + \mathbf{A}$. Moreover, applying \mathcal{S} on S_{m+1} in the following geometry

$$\begin{array}{c}
 \mathbf{1}_{2m+4}^{1+1} \xrightarrow{e} \xrightarrow{h} \mathbf{2}_{2m+2} \xrightarrow{e} \dots \xrightarrow{h} (\mathbf{m-1})_8 \xrightarrow{e} \xrightarrow{h} \mathbf{m}_6 \xrightarrow{e} \xrightarrow{2e+f} (\mathbf{m+1})_0 \\
 x \textcircled{\hspace{1em}} y
 \end{array} \tag{4.39}$$

we learn that

$$\mathfrak{sp}(m+1)_{m\pi} + \mathbf{A} = \mathfrak{su}(m+2)_{1+\frac{m}{2}} + \mathbf{S}^2 \tag{4.40}$$

Combining all these results, we obtain

$$\boxed{
 \begin{array}{c}
 \mathfrak{su}(2m)_m + \mathbf{S}^2 = \mathfrak{sp}(2m-1)_0 + \mathbf{A} = \begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}}_{2m-2} \end{array}
 \end{array}
 } \tag{4.41}$$

and

$$\boxed{
 \begin{array}{c}
 \mathfrak{su}(2m+1)_{m+\frac{1}{2}} + \mathbf{S}^2 = \mathfrak{sp}(2m)_\pi + \mathbf{A} = \begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}}_{2m-1} \end{array}
 \end{array}
 } \tag{4.42}$$

Similarly, we also obtain

$$\boxed{
 \begin{array}{c}
 \mathfrak{sp}(2m+1)_\pi + \mathbf{A} = \begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}}_{2m} \end{array}
 \end{array}
 } \tag{4.43}$$

and

$$\boxed{\mathfrak{sp}(2m)_0 + A = \begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \leftarrow 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}} \\ 2m-1 \end{array}} \quad (4.44)$$

Applying \mathcal{S} on all surfaces of

$$(4.45)$$

leads to

$$\boxed{\mathfrak{su}(2m+3)_0 + S^2 + \Lambda^2 = \begin{array}{c} \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(2)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}} \\ m \end{array}} \quad (4.46)$$

Applying \mathcal{S} on all surfaces except S_{m+1} of

$$(4.47)$$

leads to a geometry describing $\mathfrak{su}(2m+4)_0 + S^2 + \Lambda^2$. The above geometry is also isomorphic to

$$\begin{array}{ccccccc}
 & & \mathfrak{m}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & (\mathfrak{m}-1)_0^{1+1} & \xrightarrow{f-x} & \dots & \xrightarrow{f-y} & \mathfrak{2}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathfrak{1}_0^{1+1} \\
 & & \begin{array}{c} \nearrow^{f-y,y} \\ \searrow_{e-x-y} \end{array} & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} & & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} \\
 \begin{array}{c} \circlearrowleft^{e-x} \\ \circlearrowright_{e-y} \end{array} & & \begin{array}{c} \nearrow^{f+y,x} \\ \searrow_{e-x-y} \end{array} & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} & & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} \\
 & & \mathfrak{(m+1)}_0^{1+1} & & & \mathfrak{(m+2)}_0^{1+1} & & \dots & & \mathfrak{2m}_0^{1+1} & & & \mathfrak{(2m+1)}_0^{1+1} \\
 & & \begin{array}{c} \nearrow^{f-x-y} \\ \searrow_e \end{array} & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} & & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} \\
 & & \begin{array}{c} \nearrow^f \\ \searrow_e \end{array} & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} & & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} & & & \begin{array}{c} \nearrow^y \\ \searrow_{e-x-y} \end{array} \\
 & & \mathfrak{(m+2)}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathfrak{(m+3)}_0^{1+1} & \xrightarrow{f-x} & \dots & \xrightarrow{f-y} & \mathfrak{2m}_0^{1+1} & \xrightarrow{f-x} & \xrightarrow{f-y} & \mathfrak{(2m+1)}_0^{1+1}
 \end{array}$$

Thus we obtain

$$\boxed{
 \mathfrak{su}(2m+2)_0 + S^2 + \Lambda^2 = \underbrace{\mathfrak{su}(2)^{(1)} \text{ --- } \dots \text{ --- } \mathfrak{su}(2)^{(1)} \text{ --- } \mathfrak{su}(2)^{(1)} \text{ --- } \mathfrak{su}(1)^{(1)}}_m \rightarrow 2
 } \tag{4.49}$$

The fact that the geometry

$$\begin{array}{ccccccc}
 \mathfrak{m}_0^{1+1} & \xrightarrow{f-x,x} & \mathfrak{2} & \xrightarrow{f-y,y} & (\mathfrak{m}-1)_0^{1+1} & \xrightarrow{f-x,x} & \dots & \xrightarrow{f-y,y} & \mathfrak{2}_0^{1+1} & \xrightarrow{f-x,x} & \mathfrak{2} & \xrightarrow{f-y,y} & \mathfrak{1}_0^{1+1} \\
 \begin{array}{c} \circlearrowleft^{e-x} \\ \circlearrowright_{e-y} \end{array} & & & & \begin{array}{c} \circlearrowleft^{e-x} \\ \circlearrowright_{e-y} \end{array} & & & & \begin{array}{c} \circlearrowleft^{e-x} \\ \circlearrowright_{e-y} \end{array} & & & & \begin{array}{c} \circlearrowleft^{e-x} \\ \circlearrowright_{e-y} \end{array}
 \end{array}$$

is isomorphic to the geometry

$$\begin{array}{ccccccc}
 \mathfrak{m}_0^{1+1} & \xrightarrow{e-y,f-x} & \mathfrak{2} & \xrightarrow{e-x,f-y} & (\mathfrak{m}-1)_0^{1+1} & \xrightarrow{e-y,f-x} & \dots & \xrightarrow{e-x,f-y} & \mathfrak{2}_0^{1+1} & \xrightarrow{e-y,f-x} & \mathfrak{2} & \xrightarrow{e-x,f-y} & \mathfrak{1}_0^{1+1} \\
 \begin{array}{c} \circlearrowleft^x \\ \circlearrowright_y \end{array} & & & & \begin{array}{c} \circlearrowleft^x \\ \circlearrowright_y \end{array} & & & & \begin{array}{c} \circlearrowleft^x \\ \circlearrowright_y \end{array} & & & & \begin{array}{c} \circlearrowleft^x \\ \circlearrowright_y \end{array}
 \end{array}$$

implies that

$$\boxed{
 \mathfrak{su}(m+1)_0 + A = \underbrace{\mathfrak{su}(1)^{(1)} \text{ --- } \dots \text{ --- } \mathfrak{su}(1)^{(1)}}_m
 } \tag{4.52}$$

Applying \mathcal{S} on S_m of

$$\begin{array}{c}
 \mathbf{m}_0 \xrightarrow{2e+f} \xrightarrow{e} (\mathbf{m}-1)_6 \xrightarrow{h} \dots \xrightarrow{e} \mathbf{3}_{2m-2} \begin{array}{l} \xrightarrow{h} \mathbf{2}_{2m} \\ \xrightarrow{h} \mathbf{1}_{2m}^{(2m-2)+(2m-2)} \end{array} \\
 \begin{array}{l} \mathbf{2}_{2m} \\ \mathbf{1}_{2m}^{(2m-2)+(2m-2)} \end{array} \begin{array}{l} \xrightarrow{f} \\ \xrightarrow{f-x_i-y_i} \end{array} \\
 \begin{array}{l} 2m-2 \\ f-x_i-y_i \end{array}
 \end{array}
 \tag{4.53}$$

and applying \mathcal{S} on S_m of

$$\mathbf{m}_0 \xrightarrow{2e+f} \xrightarrow{e} (\mathbf{m}-1)_6 \xrightarrow{h} \dots \xrightarrow{e} \mathbf{2}_{2m} \xrightarrow{2h} \xrightarrow{e-\sum x_i - \sum y_i} \mathbf{1}_6^{(2m-1)+(2m-1)} \begin{array}{l} \xrightarrow{x_i} \\ \xrightarrow{y_i} \end{array} \mathbf{2}_{m-1}
 \tag{4.54}$$

we see that

$$\mathfrak{so}(m+2) + m\mathbf{F} = \frac{\mathfrak{su}(m)^{(2)}}{2}$$

(4.55)

The geometry

$$\begin{array}{c}
 (\mathbf{m}+1)_0^{1+1} \xrightarrow{f-x,x} \xrightarrow{2} \xrightarrow{2f-y,y} \mathbf{m}_0^{1+1} \xrightarrow{f-x,x} \dots \xrightarrow{f-y,y} \mathbf{2}_0^{1+1} \xrightarrow{f-x,x} \xrightarrow{2} \xrightarrow{f-y,y} \mathbf{1}_0^{1+1} \\
 \begin{array}{l} \xrightarrow{e-x} \\ \xrightarrow{e-y} \end{array} \quad \begin{array}{l} \xrightarrow{e-x} \\ \xrightarrow{e-y} \end{array} \quad \begin{array}{l} \xrightarrow{e-x} \\ \xrightarrow{e-y} \end{array} \quad \begin{array}{l} \xrightarrow{e-x} \\ \xrightarrow{e-y} \end{array}
 \end{array}
 \tag{4.56}$$

is isomorphic to

$$\begin{array}{c}
 (\mathbf{m}+1)_0^{1+1} \xrightarrow{e-y,f-x} \xrightarrow{2} \xrightarrow{2e+f-2x-y,f-y} \mathbf{m}_0^{1+1} \xrightarrow{e-y,f-x} \dots \xrightarrow{e-x,f-y} \mathbf{2}_0^{1+1} \xrightarrow{e-y,f-x} \xrightarrow{2} \xrightarrow{e-x,f-y} \mathbf{1}_0^{1+1} \\
 \begin{array}{l} \xrightarrow{x} \\ \xrightarrow{y} \end{array} \quad \begin{array}{l} \xrightarrow{x} \\ \xrightarrow{y} \end{array} \quad \begin{array}{l} \xrightarrow{x} \\ \xrightarrow{y} \end{array} \quad \begin{array}{l} \xrightarrow{x} \\ \xrightarrow{y} \end{array}
 \end{array}
 \tag{4.57}$$

implying that

$$\mathfrak{so}(2m+3) + \mathbf{A} = \frac{\mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)}}{2 \text{ --- } 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2}$$

(4.58)

And since the geometry

$$\begin{array}{c}
 \begin{array}{c} e-x \quad e-y \\ \frown \\ (\mathbf{m} + \mathbf{2})_0^{1+1} \\ \downarrow f-x, x \\ 2 \\ \downarrow f-y, y \\ (\mathbf{m} + \mathbf{1})_0^{1+1} \end{array} \\
 \begin{array}{c} e-x \quad e-y \\ \frown \\ (\mathbf{m} + \mathbf{1})_0^{1+1} \end{array} \xrightarrow{f-x, x} 2 \xrightarrow{f-y, y} \begin{array}{c} e-x \quad e-y \\ \frown \\ \mathbf{m}_0^{1+1} \end{array} \xrightarrow{f-x, x} \dots \xrightarrow{f-y, y} \begin{array}{c} e-x \quad e-y \\ \frown \\ \mathbf{2}_0^{1+1} \end{array} \xrightarrow{f-x, x} 2 \xrightarrow{f-y, y} \begin{array}{c} e-x \quad e-y \\ \frown \\ \mathbf{1}_0^{1+1} \end{array}
 \end{array} \tag{4.59}$$

is isomorphic to the geometry

$$\begin{array}{c}
 \begin{array}{c} x \quad y \\ \frown \\ (\mathbf{m} + \mathbf{2})_0^{1+1} \\ \downarrow e-y, f-x \\ 2 \\ \downarrow e-x, f-y \\ (\mathbf{m} + \mathbf{1})_0^{1+1} \end{array} \\
 \begin{array}{c} x \quad y \\ \frown \\ (\mathbf{m} + \mathbf{1})_0^{1+1} \end{array} \xrightarrow{e-y, f-x} 2 \xrightarrow{e-x, f-y} \begin{array}{c} x \quad y \\ \frown \\ \mathbf{m}_0^{1+1} \end{array} \xrightarrow{e-y, f-x} \dots \xrightarrow{e-x, f-y} \begin{array}{c} x \quad y \\ \frown \\ \mathbf{2}_0^{1+1} \end{array} \xrightarrow{e-y, f-x} 2 \xrightarrow{e-x, f-y} \begin{array}{c} x \quad y \\ \frown \\ \mathbf{1}_0^{1+1} \end{array}
 \end{array} \tag{4.60}$$

we obtain

$$\boxed{
 \begin{array}{c}
 \mathfrak{su}(1)^{(1)} \\
 2 \\
 | \\
 \mathfrak{so}(2m + 4) + \mathbf{A} = \begin{array}{c} \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 2 \text{ --- } 2 \text{ --- } \dots \text{ --- } 2 \\ \underbrace{\hspace{10em}}_m \end{array} \\
 \end{array}
 } \tag{4.61}$$

4.2 Rank 2

Consider the following geometry corresponding to the KK theory obtained by compactifying 6d SCFT carrying $\mathfrak{su}(3)$ on -1 curve with a charge conjugation twist

$$\mathbf{2}_0^6 \xrightarrow{4e+3f-2 \sum x_i} e \mathbf{1}_2 \tag{4.62}$$

Applying \mathcal{S} on S_2 , we obtain the geometry

$$\mathbf{2}_0^6 \frac{3e+4f-2\sum x_i}{e} \mathbf{1}_2 \tag{4.63}$$

which describes the $5d$ gauge theory $\mathfrak{g}_2 + 6F$. The above geometry is also isomorphic to the geometry

$$\mathbf{2}_0^{2+4} \frac{3e+2f-2\sum x_i - \sum y_i}{e} \mathbf{1}_2 \tag{4.64}$$

Applying \mathcal{S} on S_2 of the above geometry, we obtain the geometry

$$\mathbf{2}_0^{2+4} \frac{2e+3f-2\sum x_i - \sum y_i}{e} \mathbf{1}_2 \tag{4.65}$$

which describes the $5d$ gauge theory $\mathfrak{sp}(2) + 2\Lambda^2 + 4F$. The above geometry is also isomorphic to the geometry

$$\mathbf{2}_0^{4+2} \frac{2e+f-\sum x_i}{e} \mathbf{1}_2 \tag{4.66}$$

Applying \mathcal{S} on S_2 of the above geometry, we obtain the geometry

$$\mathbf{2}_0^{4+2} \frac{e+2f-\sum x_i}{e} \mathbf{1}_2 \tag{4.67}$$

which describes the $5d$ gauge theory $\mathfrak{su}(3)_4 + 6F$. Thus, we find that

$\mathfrak{su}(3)_4 + 6F = \mathfrak{sp}(2) + 2\Lambda^2 + 4F = \mathfrak{g}_2 + 6F = \frac{\mathfrak{su}(3)^{(2)}}{1} \tag{4.68}$
--

(4.64) and (4.65) are flop equivalent to

$$\mathbf{2}_0^2 \frac{3e+2f-2\sum x_i}{e} \mathbf{1}_6^4 \tag{4.69}$$

and

$$\mathbf{2}_0^2 \frac{2e+3f-2\sum x_i}{e} \mathbf{1}_6^4 \tag{4.70}$$

respectively. The above two geometries remain related by \mathcal{S} if we remove blowups from S_1 . In other words, the duality between $\mathfrak{sp}(2)$ and \mathfrak{g}_2 continues to hold as we integrate out F from both sides of the duality (until a total of four F have been integrated out). Similarly, (4.66) and (4.67) imply that the duality between $\mathfrak{sp}(2)$ and $\mathfrak{su}(3)$ remains as we integrate out (upto four) F from both sides of the duality in such a way that the CS level for $\mathfrak{su}(3)$ increases (in absolute value). Finally, the geometry (4.64) is also isomorphic to the geometry

$$\mathbf{2}_0^6 \frac{3e+f-\sum x_i}{e} \mathbf{1}_2 \tag{4.71}$$

Applying \mathcal{S} on S_2 of the above geometry we find the following geometry describing $\mathfrak{su}(3)_4 + 6F$

$$\mathbf{2}_0^6 \frac{e+3f-\sum x_i}{e} \mathbf{1}_2 \tag{4.72}$$

These geometries imply that the duality between $\mathfrak{su}(3)$ and \mathfrak{g}_2 remains preserved if F are integrated out from both sides of the duality in such a way that the CS level for $\mathfrak{su}(3)$ increases. Notice that we can integrate out all the six F while preserving the duality between $\mathfrak{su}(3)$ and \mathfrak{g}_2 .

A geometry describing the marginal theory $\mathfrak{su}(3)_{\frac{13}{2}} + 3F$ is

$$\mathbf{2}_0^3 \frac{e+2f}{} \frac{e}{} \mathbf{1}_6 \tag{4.73}$$

Applying \mathcal{S} on S_2 leads to the geometry

$$\mathbf{2}_0^3 \frac{2e+f}{} \frac{e}{} \mathbf{1}_6 \tag{4.74}$$

thus implying that the above marginal theory is dual to $\mathfrak{sp}(2)_\pi + 3\Lambda^2$ which is also a marginal theory. The geometry (4.73) is also isomorphic to the geometry

$$\mathbf{2}_0^{2+1} \frac{e+3f-\sum x_i}{} \frac{e}{} \mathbf{1}_6 \tag{4.75}$$

Applying \mathcal{S} on S_2 of the above geometry leads to the geometry

$$\mathbf{2}_0^{2+1} \frac{3e+f-\sum x_i}{} \frac{e}{} \mathbf{1}_6 \tag{4.76}$$

which implies that the above marginal theories are dual to $\mathfrak{g}_2 + A + 2F$. But $\mathfrak{g}_2 + A$ describes the circle compactification of $6d \mathcal{N} = (2, 0)$ SCFT of type D_4 twisted along the circle by the order three outer automorphism of D_4 . Thus, the theory

$$\mathfrak{su}(3)_{\frac{13}{2}} + 3F = \mathfrak{sp}(2)_\pi + 3\Lambda^2 = \mathfrak{g}_2 + A + 2F \tag{4.77}$$

is obtained by adding matter to a $6d$ SCFT (compactified on a circle), implying that it cannot be a UV complete QFT. Said another way, the geometry corresponding to (4.77) is such that it is not possible to completely shrink all the compact curves and surfaces in the geometry simultaneously to a point. Thus, it is not possible to decouple (4.77) from the rest of M-theory.

The isomorphism between (4.75) and (4.76) implies that

$$\boxed{\mathfrak{su}(3)_{\frac{15}{2}} + F = \mathfrak{g}_2 + A = \begin{matrix} \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} \\ 2 & \text{---} & 3 & \longrightarrow & 2 \end{matrix}} \tag{4.78}$$

Applying \mathcal{S} on S_2 of

$$\mathbf{2}_0 \frac{4e+f}{} \frac{e}{} \mathbf{1}_{10} \tag{4.79}$$

we find

$$\boxed{\mathfrak{su}(3)_9 = \begin{matrix} \mathfrak{su}(3)^{(2)} \\ 3 \end{matrix}} \tag{4.80}$$

Applying \mathcal{S} on S_2 of

$$\mathbf{2}_0^3 \xrightarrow{4e+2f-2\sum x_i} \xrightarrow{e} \mathbf{1}_6 \tag{4.81}$$

we find

$$\boxed{\mathfrak{sp}(2)_0 + 3\Lambda^2 = \frac{\mathfrak{su}(3)^{(2)}}{2}} \tag{4.82}$$

4.3 Rank 3

A geometry describing the marginal theory $\mathfrak{su}(4)_3 + 8F$ is

$$\mathbf{3}_0^{7+1} \xrightarrow{e+2f-\sum x_i} \xrightarrow{h} \mathbf{2}_1 \xrightarrow{e} \xrightarrow{e} \mathbf{1}_1 \tag{4.83}$$

Applying \mathcal{S} on S_3 identifies a dual description of this theory as $\mathfrak{sp}(3) + \Lambda^3 + 7F$. However,

$$\mathfrak{sp}(3) + \Lambda^3 + 5F = \mathfrak{su}(4)_4 + 6F \tag{4.84}$$

is already a $5d$ KK theory as can be seen by applying \mathcal{S} on S_2 of the following geometry

$$\mathbf{3}_1^{5+1+1+1} \xrightarrow{2h-\sum x_i-y} \xrightarrow{f} \mathbf{2}_0 \xrightarrow{4e+f} \xrightarrow{e} \mathbf{1}_{10} \tag{4.85}$$

$\underbrace{\hspace{15em}}_{4}$

 $y-w, y-w, f-y-z, f-y-z$ (under $\mathbf{3}_1$) f, f, f, f (under $\mathbf{1}_{10}$)

Thus,

$$\boxed{\mathfrak{su}(4)_4 + 6F = \mathfrak{sp}(3) + \Lambda^3 + 5F = \frac{\mathfrak{su}(3)^{(2)}}{3} \xrightarrow{2} \frac{\mathfrak{sp}(0)^{(1)}}{1}} \tag{4.86}$$

(4.83) implies that the duality between $\mathfrak{sp}(3)$ and $\mathfrak{su}(4)$ remains preserved if we integrate out F from both sides of the duality such that the CS level for $\mathfrak{su}(4)$ increases.

Applying \mathcal{S} on S_1 of

$$\mathbf{1}_0 \xrightarrow{3e+f} \xrightarrow{e} \mathbf{2}_8 \xrightarrow{h} \xrightarrow{e} \mathbf{3}_{10} \tag{4.87}$$

implies

$$\boxed{\mathfrak{su}(4)_8 = \frac{\mathfrak{so}(8)^{(3)}}{4}} \tag{4.88}$$

Consider the following geometry describing $\mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \frac{19}{2}F$

$$\mathbf{1}_9^7 \xrightarrow{e} \xrightarrow{h+2f} \mathbf{2}_3 \xrightarrow{e} \xrightarrow{2e+f-x_2-\sum y_i} \mathbf{3}_0^{2+2} \tag{4.89}$$

$\underbrace{\hspace{15em}}_{2}$

 f, f (under $\mathbf{1}_9$) $x_2-x_1, f-x_1-x_2$ (under $\mathbf{3}_0$)

This geometry is isomorphic to the following geometry

$$\begin{array}{c}
 \mathbf{1}_9 \xrightarrow[e]{h+2f} \mathbf{2}_3 \xrightarrow[e]{e+f-x_1} \mathbf{3}_0^{2+2} \\
 \underbrace{f, f \quad \quad \quad x_1-x_2, f-y_1-y_2}_{2}
 \end{array} \quad (4.90)$$

which describes $\mathfrak{su}(4)_{\frac{3}{2}} + 2\Lambda^2 + 7F$. The latter 5d KK theory is known to be a 5d KK theory from the results of section 4.1. We thus have

$$\boxed{\mathfrak{su}(4)_{\frac{3}{2}} + 2\Lambda^2 + 7F = \mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \frac{19}{2}F = \begin{array}{c} \mathfrak{sp}(1)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 1 \text{ --- } 2 \end{array}} \quad (4.91)$$

Applying \mathcal{S} on S_3 of

$$\mathbf{1}_8 \xrightarrow[e]{h} \mathbf{2}_6^2 \xrightarrow[e]{2e+f} \mathbf{3}_0 \quad (4.92)$$

yields

$$\mathfrak{sp}(3)_0 + 2\Lambda^2 = \mathfrak{su}(4)_6 + 2\Lambda^2 \quad (4.93)$$

And applying \mathcal{S} on S_3 of

$$\begin{array}{c}
 \mathbf{1}_{10} \xrightarrow[e]{h+2f} \mathbf{2}_4 \xrightarrow[e]{3e+2f-2\sum x_i - \sum y_i} \mathbf{3}_0^{2+2} \\
 \underbrace{f \quad \quad \quad x_i - y_i}_{2}
 \end{array} \quad (4.94)$$

implies

$$\boxed{\mathfrak{su}(4)_6 + 2\Lambda^2 = \mathfrak{sp}(3)_0 + 2\Lambda^2 = \begin{array}{c} \mathfrak{so}(8)^{(3)} \\ 2 \end{array}} \quad (4.95)$$

Applying \mathcal{S} on S_2 of

$$\mathbf{3}_3^3 \xrightarrow[e]{2e+f-\sum x_i} \mathbf{2}_0^3 \xrightarrow[e]{e+f-\sum x_i} \mathbf{1}_1^1 \quad (4.96)$$

implies that

$$\mathfrak{so}(7) + 6S + F = \mathfrak{su}(4)_0 + 3\Lambda^2 + 4F \quad (4.97)$$

Applying \mathcal{S} on S_2 of

$$\mathbf{3}_0 \xrightarrow[e]{2e+2f-\sum x_i - \sum y_i - 2z} \mathbf{2}_0^{3+3+1} \xrightarrow[e]{2e+f-\sum x_i - \sum y_i} \mathbf{1}_0 \quad (4.98)$$

implies that

$$\boxed{\mathfrak{su}(4)_0 + 3\Lambda^2 + 4F = \mathfrak{so}(7) + 6S + F = \begin{array}{c} \mathfrak{su}(4)^{(2)} \\ 1 \end{array}} \quad (4.99)$$

Applying \mathcal{S} on S_2 of

$$\mathbf{3}_3^4 \frac{e}{2e+f-\sum x_i} \mathbf{2}_0^3 \frac{e+f-\sum x_i}{e} \mathbf{1}_1 \tag{4.100}$$

implies that

$$\mathfrak{so}(7) + 7S = \mathfrak{su}(4)_1 + 3\Lambda^2 + 4F \tag{4.101}$$

Similarly, applying \mathcal{S} on S_2 of

$$\mathbf{3}_3^2 \frac{e}{2e+f-\sum x_i} \mathbf{2}_0^3 \frac{e+f-\sum x_i}{e} \mathbf{1}_1^2 \tag{4.102}$$

implies that

$$\mathfrak{so}(7) + 5S + 2F = \mathfrak{su}(4)_1 + 3\Lambda^2 + 4F \tag{4.103}$$

Now, applying \mathcal{S} on S_2 of

$$\mathbf{3}_1 \frac{h}{e+2f-\sum x_i} \mathbf{2}_0^7 \frac{3e+f-\sum x_i}{e} \mathbf{1}_1 \tag{4.104}$$

implies that

$$\mathfrak{su}(4)_1 + 3\Lambda^2 + 4F = \mathfrak{so}(7) + 5S + 2F = \mathfrak{so}(7) + 7S = \mathfrak{g}_2^{(1)} \tag{4.105}$$

Similarly, applying \mathcal{S} on S_2 of the following two geometries

$$\mathbf{3}_3^1 \frac{e}{2e+f-\sum x_i} \mathbf{2}_0^3 \frac{e+f-\sum x_i}{e} \mathbf{1}_1^3 \tag{4.106}$$

$$\mathbf{1}_2^{4+4} \frac{e}{f-x_i-y_i} \frac{f}{f} \mathbf{2}_0^3 \frac{4e+2f-2\sum x_i}{e} \mathbf{3}_6 \tag{4.107}$$

we find that

$$\mathfrak{su}(4)_2 + 3\Lambda^2 + 4F = \mathfrak{so}(7) + 4S + 3F = \mathfrak{sp}(0)^{(1)} \text{ --- } \mathfrak{su}(3)^{(2)} \tag{4.108}$$

A geometry describing $\mathfrak{su}(4)_5 + 3\Lambda^2$ is

$$\mathbf{3}_1^{3+3} \frac{h+f-\sum x_i}{x_i-y_i} \frac{e}{e} \mathbf{2}_2 \frac{h+3f}{e} \mathbf{1}_{10} \tag{4.109}$$

which can be rewritten as

$$\mathbf{3}_0^{3+3} \frac{2e+f-x_1-x_3-y_1-y_2}{f-x_2-y_2, y_2-x_2, x_3-y_3} \frac{e}{e} \mathbf{2}_2 \frac{h+3f}{e} \mathbf{1}_{10} \tag{4.110}$$

which implies that there is a dual description as $\mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \Lambda^2 + \frac{5}{2}\mathbf{F}$. We can further rewrite the above geometry as

$$\mathbf{3}_0^{3+3} \xrightarrow[\substack{f-x_1-y_1, x_2-y_2, x_3-y_3}]{3e+2f-x_1-2x_2-2x_3-\sum y_i} \mathbf{2}_2 \xrightarrow[\substack{f, f, f}]{h+3f} \mathbf{1}_{10} \quad (4.111)$$

which implies that

$$\boxed{\mathfrak{su}(4)_5 + 3\Lambda^2 = \mathfrak{sp}(3) + \frac{1}{2}\Lambda^3 + \Lambda^2 + \frac{5}{2}\mathbf{F} = \frac{\mathfrak{so}(8)^{(3)}}{1}} \quad (4.112)$$

Applying \mathcal{S} on S_2 of

$$\mathbf{1}_2 \xrightarrow[e]{2e+f-\sum x_i} \mathbf{2}_0^4 \xrightarrow[e]{2e+f-\sum x_i} \mathbf{3}_2 \quad (4.113)$$

leads to

$$\boxed{\mathfrak{su}(4)_0 + 4\Lambda^2 = \frac{\mathfrak{su}(4)^{(2)}}{2}} \quad (4.114)$$

Applying \mathcal{S} on S_2 of

$$\mathbf{1}_1 \xrightarrow[e]{e+f-\sum x_i} \mathbf{2}_0^{3+1} \xrightarrow[e]{2e+f-\sum x_i} \mathbf{3}_3 \quad (4.115)$$

implies that

$$\mathfrak{su}(4)_1 + 4\Lambda^2 = \mathfrak{so}(7) + \mathbf{A} + 3\mathbf{S} \quad (4.116)$$

But, since $\mathfrak{so}(7) + \mathbf{A}$ is already a $5d$ KK theory, the marginal theory $\mathfrak{su}(4)_1 + 4\Lambda^2$ cannot describe either a $5d$ SCFT or a $5d$ KK theory. Removing matter from the marginal theory leads us to the theory $\mathfrak{su}(4)_1 + 3\Lambda^2$ which is a $5d$ SCFT as it can be obtained by removing matter from $5d$ KK theories discussed above.

Applying \mathcal{S} on S_2 of

$$\mathbf{1}_0 \xrightarrow[e]{e+f-\sum x_i} \mathbf{2}_0^4 \xrightarrow[e]{3e+f-\sum x_i} \mathbf{3}_4 \quad (4.117)$$

leads to

$$\boxed{\mathfrak{su}(4)_2 + 4\Lambda^2 = \frac{\mathfrak{g}_2^{(1)}}{2}} \quad (4.118)$$

A geometry describing $\mathfrak{su}(4)_3 + 4\Lambda^2$ is obtained by applying \mathcal{S} on S_2 in the following geometry

$$\mathbf{3}_2^{3+3} \xrightarrow[\substack{f-x_i-y_i}]{3} \mathbf{2}_0^1 \xrightarrow[\substack{f}]{3e+f} \mathbf{1}_8 \quad (4.119)$$

The above geometry can be rewritten as

$$\begin{array}{c}
 \mathbf{3}_0^{3+3} \xrightarrow{x_1-x_2} \mathbf{2}_0^1 \xrightarrow{3e+f} \mathbf{1}_8^e \\
 \underbrace{f-x_1-y_1, y_1-x_1, x_2-y_2} \quad \underbrace{f, f, f} \\
 3
 \end{array} \quad (4.120)$$

which implies that this theory has a dual description as a $\mathfrak{g}_2 \oplus \mathfrak{su}(2)$ gauge theory with a half-hyper in bifundamental, a hyper in \mathbf{A} of \mathfrak{g}_2 and two full hypers in \mathbf{F} of $\mathfrak{su}(2)$. Now, turning off the gauge coupling for $\mathfrak{su}(2)$ leads to an RG flow producing $\mathfrak{g}_2 + \mathbf{A} + \mathbf{F}$ which has more matter than a KK theory. Geometrically this RG flow is implemented by decompactifying the curve e in S_3 . Thus $\mathfrak{su}(4)_3 + 4\Lambda^2$ can neither be a 5d SCFT nor a 5d KK theory, since otherwise $\mathfrak{g}_2 + \mathbf{A} + \mathbf{F}$ would have to describe a 5d SCFT or a 5d KK theory, which cannot be the case as $\mathfrak{g}_2 + \mathbf{A}$ is already a 5d KK theory.

Applying \mathcal{S} on S_2 of

$$\begin{array}{c}
 \mathbf{1}_2^{4+4} \xrightarrow{e} \mathbf{2}_0^f \xrightarrow{4e+f} \mathbf{3}_{10}^e \\
 \underbrace{f-x_i-y_i} \quad \underbrace{f} \\
 4
 \end{array} \quad (4.121)$$

we find that

$$\boxed{\mathfrak{su}(4)_4 + 4\Lambda^2 = \begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)} \\ 1 \text{ --- } 3 \end{array}} \quad (4.122)$$

A geometry describing $\mathfrak{sp}(3)_\pi + 2\Lambda^2$ is

$$\begin{array}{c}
 \mathbf{3}_1^{2+2} \xrightarrow{2h-\sum x_i} \mathbf{2}_4 \xrightarrow{h+2f} \mathbf{1}_{10}^e \\
 \underbrace{x_i-y_i} \quad \underbrace{f} \\
 2
 \end{array} \quad (4.123)$$

which can be rewritten as

$$\begin{array}{c}
 \mathbf{3}_0^{2+2} \xrightarrow{2e+f-\sum y_i} \mathbf{2}_4 \xrightarrow{h+2f} \mathbf{1}_{10}^e \\
 \underbrace{y_1-x_1, f-x_1-y_1} \quad \underbrace{f, f} \\
 2
 \end{array} \quad (4.124)$$

implying the duality

$$\mathfrak{sp}(3)_\pi + 2\Lambda^2 = \mathfrak{sp}(3) + \frac{3}{2}\Lambda^3 + \frac{3}{2}\mathbf{F} \quad (4.125)$$

but the latter theory exceeds the bounds placed on marginal theories in [21]. Hence, $\mathfrak{sp}(3)_\pi + 2\Lambda^2$ describes neither a 5d SCFT nor a 5d KK theory.

A geometry describing $\mathfrak{su}(4)_0 + S^2 + \Lambda^2$ is obtained by applying \mathcal{S} on S_1 and S_3 of

$$\begin{array}{c}
 \mathbf{1}_0^{2+2} \xrightarrow{f-x_1, x_1} \mathbf{2} \xrightarrow{h+f-x-2y, f-x} \mathbf{2}_2^{1+1} \xrightarrow{e} \mathbf{3}_0^f \\
 \underbrace{e-\sum x_i, e-\sum y_i} \quad \underbrace{e, e} \\
 2
 \end{array} \quad (4.126)$$

The above geometry can be rewritten as

$$\begin{array}{c}
 \begin{array}{ccccccc}
 & & & e-x & & e-y & \\
 & & & \frown & & \smile & \\
 \mathbf{1}_0^{2+2} & \xrightarrow{f-x_1, x_1} & \mathbf{2} & \xrightarrow{f+y, x} & \mathbf{2}_0^{1+1} & \xrightarrow{f-x-y} & \mathbf{3}_0 \\
 e-\sum x_i, e-\sum y_i & \underbrace{\hspace{15em}}_{\mathbf{2}} & & & & & e, e
 \end{array}
 \end{array}
 \quad (4.127)$$

which implies that

$$\boxed{\mathfrak{su}(4)_0 + S^2 + \Lambda^2 = \begin{array}{c} \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ \mathbf{2} \text{ --- } \mathbf{2} \longrightarrow \mathbf{2} \end{array}} \quad (4.128)$$

The geometry

$$\begin{array}{c}
 \begin{array}{ccccccc}
 \mathbf{1}_1^{2+2+4} & \xrightarrow{h-\sum z_i} & \mathbf{h} & \mathbf{2}_1 & \xrightarrow{2h} & \mathbf{e} & \mathbf{3}_6 \\
 f-x_i-y_i & \underbrace{\hspace{15em}}_{\mathbf{2}} & & & & & f
 \end{array}
 \end{array}
 \quad (4.129)$$

describing $\mathfrak{so}(7) + 2S + 4F$ can be rewritten as

$$\begin{array}{c}
 \begin{array}{ccccccc}
 \mathbf{3}_0^{2+2+4} & \xrightarrow{2e+f-x_2-\sum y_i-\sum z_i} & \mathbf{h} & \mathbf{2}_1 & \xrightarrow{2h} & \mathbf{e} & \mathbf{1}_6 \\
 y_1-x_1, f-x_1-y_1 & \underbrace{\hspace{15em}}_{\mathbf{2}} & & & & & f, f
 \end{array}
 \end{array}
 \quad (4.130)$$

which implies that

$$\boxed{\mathfrak{so}(7) + 2S + 4F = \begin{array}{c} \mathfrak{su}(5)^{(2)} \\ \mathbf{1} \end{array}} \quad (4.131)$$

4.4 Rank 4

Consider the geometry

$$\begin{array}{c}
 \begin{array}{ccccccc}
 \mathbf{1}_0 & \xrightarrow{e} & \mathbf{2}_0^{3+3+3} & \xrightarrow{e+f-\sum y_i-\sum z_i} & \mathbf{e+f} & \mathbf{3}_0 & \xrightarrow{2e+f} & \mathbf{e} & \mathbf{4}_6 \\
 & & y_i-x_i & \underbrace{\hspace{15em}}_{\mathbf{3}} & & & & & f
 \end{array}
 \end{array}
 \quad (4.132)$$

Performing \mathcal{S} on S_3 leads us to an $\mathfrak{so}(9)$ description, and performing \mathcal{S} on S_3, S_2 leads us to an $\mathfrak{su}(5)$ description. Working out the matter content, we find that

$$\boxed{\mathfrak{su}(5)_0 + 3\Lambda^2 + 3F = \mathfrak{so}(9) + 3S + 3F = \begin{array}{c} \mathfrak{so}(8)^{(2)} \\ \mathbf{1} \end{array}} \quad (4.133)$$

Applying \mathcal{S} on S_2 of the following geometry

$$\begin{array}{c}
 \begin{array}{ccccccc}
 \mathbf{1}_1 & \xrightarrow{e} & \mathbf{2}_0^3 & \xrightarrow{2e+f-\sum x_i} & \mathbf{e} & \mathbf{3}_3 & \xrightarrow{h} & \mathbf{e} & \mathbf{4}_5^1
 \end{array}
 \end{array}
 \quad (4.134)$$

leads to

$$\mathfrak{su}(5)_3 + 3\Lambda^2 + F = \mathfrak{f}_4 + 4F \tag{4.135}$$

Since $\mathfrak{f}_4 + 4F$ violates the bound for marginal theories, we conclude that $\mathfrak{su}(5)_3 + 3\Lambda^2 + F$ is not a KK theory or an SCFT.

Applying \mathcal{S} to S_1 of

$$\mathbf{1}_0^{4+1} \xrightarrow{2e+f-\sum x_i} \mathbf{2}_2 \xrightarrow{h} \mathbf{3}_4 \xrightarrow{h} \mathbf{4}_6 \tag{4.136}$$

leads to

$$\mathfrak{su}(5)_{\frac{11}{2}} + 5F = \mathfrak{sp}(4) + 4F + \Lambda^4 \tag{4.137}$$

Since the latter theory violates the bound for marginal theories, we conclude that the former theory is not a KK theory or an SCFT.

Applying \mathcal{S} to S_2 of

$$\mathbf{1}_3^{\frac{1}{3}} \xrightarrow{e} \mathbf{2}_0^3 \xrightarrow{2e+f-\sum x_i} \mathbf{3}_1 \xrightarrow{h} \mathbf{4}_3^{\frac{1}{3}} \tag{4.138}$$

implies the duality

$$\mathfrak{su}(5)_{\frac{3}{2}} + 3\Lambda^2 + 2F = \mathfrak{so}(9) + 4S + F \tag{4.139}$$

And applying \mathcal{S} to S_2 of the following geometry

$$\mathbf{1}_{10} \xrightarrow{e} \mathbf{2}_0 \xrightarrow{4e+f} \mathbf{3}_2^{4+4} \xrightarrow{2h-\sum x_i-\sum y_i} \mathbf{4}_0^{1+1} \xrightarrow{e+f-x-y} \mathbf{4}_0^{1+1} \begin{matrix} x \\ \curvearrowright \\ y \end{matrix} \tag{4.140}$$

$f \xrightarrow{\quad} \mathbf{4} \xrightarrow{\quad} f-x_i-y_i$

leads to the identification of the $\mathfrak{so}(9)$ theory as a KK theory. In full detail, we have

$\mathfrak{su}(5)_{\frac{3}{2}} + 3\Lambda^2 + 2F = \mathfrak{so}(9) + 4S + F = \begin{matrix} \mathfrak{su}(1)^{(1)} & \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(3)^{(2)} \\ 2 & \text{---} & 1 & \text{---} & 3 \end{matrix}$
--

(4.141)

Applying \mathcal{S} on S_3 of

$$\mathbf{1}_{10} \xrightarrow{e} \mathbf{2}_8 \xrightarrow{h} \mathbf{3}_0 \xrightarrow{3e+f} \mathbf{3}_0 \xrightarrow{f} \mathbf{4}_0^{2+2+4} \xrightarrow{2e+f-\sum x_i-\sum z_i} \mathbf{4}_0^{2+2+4} \tag{4.142}$$

$f, f, f \xrightarrow{\quad} \mathbf{3} \xrightarrow{\quad} f-x_1-y_1, x_1-y_1, x_2-y_2 \xrightarrow{\quad} f-x_1-x_2, x_1-x_2, y_1-y_2$

leads to

$\mathfrak{sp}(4) + \frac{1}{2}\Lambda^3 + 4F = \begin{matrix} \mathfrak{so}(8)^{(3)} & \mathfrak{sp}(0)^{(1)} \\ 4 & \text{---} & 3 & \text{---} & 1 \end{matrix}$

(4.143)

Performing \mathcal{S} on S_2 of

$$\begin{array}{c}
 \mathbf{1}_2^{2+2+2+2} \xrightarrow[e]{f} \mathbf{2}_0^{2e+f} \xrightarrow[e-\sum x_i]{f} \mathbf{3}_1^5 \xrightarrow[2h]{e} \mathbf{4}_6 \\
 \begin{array}{l}
 \text{--- } f-x_i-y_i \text{ ---} \\
 \text{--- } 2 \text{ ---} \\
 \text{--- } 4 \text{ ---}
 \end{array}
 \end{array}
 \quad (4.144)$$

we obtain

$\mathfrak{so}(9) + 2S + 5F = \begin{array}{c} \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(5)^{(2)} \\ 1 \text{ --- } 2 \end{array}$	(4.145)
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Consider the geometry

$$\begin{array}{c}
 \mathbf{1}_0^{6+2+1+1} \xrightarrow[2e+f-\sum x_i-\sum y_i-z]{h+f} \mathbf{2}_1 \xrightarrow[e]{e} \mathbf{3}_1 \xrightarrow[2h]{e} \mathbf{4}_6 \\
 \begin{array}{l}
 \text{--- } y_2-w \text{ ---} \\
 \text{--- } 2 \text{ ---}
 \end{array}
 \end{array}
 \quad (4.146)$$

which can be rewritten by performing an isomorphism on S_1 as

$$\begin{array}{c}
 \mathbf{1}_0^{6+2+1+1} \xrightarrow[e+f-\sum x_i-w]{h+f} \mathbf{2}_1 \xrightarrow[e]{e} \mathbf{3}_1 \xrightarrow[2h]{e} \mathbf{4}_6 \\
 \begin{array}{l}
 \text{--- } w-y_2 \text{ ---} \\
 \text{--- } 2 \text{ ---}
 \end{array}
 \end{array}
 \quad (4.147)$$

Equating the theories corresponding to these two isomorphic geometries, we obtain

$\mathfrak{so}(9) + S + 6F = \begin{array}{c} \mathfrak{su}(7)^{(2)} \\ 1 \end{array}$	(4.148)
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Now, consider the geometry

$$\begin{array}{c}
 \mathbf{1}_0^{2+2} \xrightarrow[2e+f-x_1-y_1-y_2]{h-\sum x_i} \mathbf{2}_2^5 \xrightarrow[e]{e} \mathbf{3}_0 \\
 \begin{array}{l}
 \text{--- } 2 \text{ ---} \\
 \text{--- } h \text{ ---} \\
 \text{--- } e \text{ ---} \\
 \text{--- } f, f \text{ ---}
 \end{array}
 \end{array}
 \quad (4.149)$$

which is isomorphic to

$$\begin{array}{c}
 \mathbf{1}_1^{2+2} \xrightarrow[h+f-\sum x_i]{h-\sum x_i} \mathbf{2}_2^5 \xrightarrow[e]{e} \mathbf{3}_0 \\
 \begin{array}{l}
 \text{--- } 2 \text{ ---} \\
 \text{--- } h \text{ ---} \\
 \text{--- } e \text{ ---} \\
 \text{--- } f \text{ ---}
 \end{array}
 \end{array}
 \quad (4.150)$$

implying

$$\boxed{\mathfrak{so}(8) + 2S + 5F = \begin{matrix} \mathfrak{su}(\tilde{6})^{(2)} \\ 1 \end{matrix}} \quad (4.151)$$

Similarly, the geometry

$$\begin{array}{ccc} & & \mathbf{3}_2 \\ & \nearrow f & | e \\ \mathbf{1}_1^{2+2} & \xrightarrow{h} & \mathbf{2}_0^5 \\ & \searrow f & | e \\ & & \mathbf{4}_2 \end{array} \quad (4.152)$$

is isomorphic to

$$\begin{array}{ccc} & & \mathbf{3}_2 \\ & \nearrow f & | e \\ \mathbf{1}_0^{2+2} & \xrightarrow{2e+f-\sum x_i-y_2} & \mathbf{2}_0^5 \\ & \searrow f & | e \\ & & \mathbf{4}_2 \end{array} \quad (4.153)$$

leading us to the conclusion that

$$\boxed{\mathfrak{so}(8) + S + C + 5F = \begin{matrix} \mathfrak{su}(6)^{(2)} \\ 1 \end{matrix}} \quad (4.154)$$

Applying \mathcal{S} on S_2 in

$$\begin{array}{ccccc} \mathbf{1}_2^{4+4} & \xrightarrow{e} & \mathbf{2}_0 & \xrightarrow{f} & \mathbf{3}_2^{4+4} \\ & \searrow f-x_i-y_i & \downarrow 4e+f & \nearrow f-x_i-y_i & \\ & & \mathbf{4}_{10} & & \end{array} \quad (4.155)$$

leads us to conclude

$$\boxed{\mathfrak{so}(8) + 4S + 4F = \begin{matrix} \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(3)^{(2)} & \mathfrak{sp}(0)^{(1)} \\ 1 & \text{---} 3 & \text{---} 1 \end{matrix}} \quad (4.156)$$

Similarly, applying \mathcal{S} on S_2 of

$$\begin{array}{ccccc}
 \mathbf{1}_0 & \xrightarrow[e+f-\sum x_i]{e} & \mathbf{2}_0^4 & \xrightarrow[3e+f-\sum x_i]{e} & \mathbf{3}_4 \\
 & \searrow f & \downarrow f & \nearrow 3 & \downarrow f \\
 & & \mathbf{4}_2^{3+3+1+1} & &
 \end{array}
 \tag{4.157}$$

leads us to

$\mathfrak{so}(8) + 3S + C + 4F = \mathfrak{g}_2^{(1)} \text{ --- } \mathfrak{sp}(0)^{(1)}$

$$\tag{4.158}$$

Applying \mathcal{S} on S_2 of the geometry

$$\begin{array}{ccccc}
 \mathbf{1}_2 & \xrightarrow[2e+f-\sum x_i]{e} & \mathbf{2}_0^4 & \xrightarrow[2e+f-\sum x_i]{e} & \mathbf{3}_2 \\
 & \searrow f & \downarrow f & \nearrow 2 & \downarrow f \\
 & & \mathbf{4}_2^{2+2+2+2} & &
 \end{array}
 \tag{4.159}$$

implies

$\mathfrak{so}(8) + 2S + 2C + 4F = \mathfrak{su}(4)^{(2)} \text{ --- } \mathfrak{sp}(0)^{(1)}$

$$\tag{4.160}$$

Finally, applying \mathcal{S} on S_2 of

$$\begin{array}{ccccc}
 \mathbf{1}_1 & \xrightarrow[e+f-\sum x_i-\sum y_i]{h} & \mathbf{2}_0^{3+2+3} & \xrightarrow[2e+f-\sum x_i-\sum z_i]{e} & \mathbf{3}_0 \\
 & & \downarrow e+f-\sum y_i-\sum z_i & & \\
 & & \mathbf{4}_1 & &
 \end{array}
 \tag{4.161}$$

leads to

$\mathfrak{so}(8) + 3S + 2C + 3F = \mathfrak{so}(7)^{(1)}$

$$\tag{4.162}$$

4.5 Rank 5

Applying \mathcal{S} on S_2 and S_4 of

$$\begin{array}{ccccc}
 \mathbf{2}_0 & \xrightarrow[e]{f} & \mathbf{3}_2^{4+4} & \xrightarrow[f]{h-\sum x_i} & \mathbf{4}_0 \\
 & \searrow f-x_i-y_i & \downarrow x_1-y_2, x_2-y_1, x_3-y_4, x_4-y_3 & \nearrow 4 & \downarrow 4e+f \\
 & & & & \mathbf{5}_{10} \\
 & & & & \downarrow e \\
 & & & & \mathbf{1}_{10}
 \end{array}
 \tag{4.163}$$

converts the right hand side of the following equality to the left hand side

$$\boxed{\mathfrak{su}(6)_0 + 2\Lambda^3 = \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(3)^{(2)} \quad 3 \text{ --- } 1 \text{ --- } 3} \tag{4.164}$$

Now, consider the geometry

$$\begin{array}{ccccccc} \mathbf{1}_3 & \xrightarrow[e]{2e+f-\sum x_i} & \mathbf{2}_0^{3+5} & \xrightarrow[e+f-\sum x_i-\sum y_i]{h} & \mathbf{3}_4 & \xrightarrow[e]{e+f} & \mathbf{4}_0 \\ & \searrow[f, f, f] & & \searrow[x_i] & \searrow[f] & & \searrow[2e+f] \\ & & & & & & \searrow[e] \\ & & & & & & \searrow[f-x_i-y_i] \\ & & & & & & \searrow[y_i] \\ & & & & & & \searrow[x_1-y_2, x_2-y_1, x_3-y_3] \\ & & & & & & \mathbf{5}_6^{3+3} \end{array} \tag{4.165}$$

Applying \mathcal{S} to S_2 , we obtain an $\mathfrak{so}(11)$ description, while applying \mathcal{S} to S_2 and S_4 , we obtain an $\mathfrak{su}(6)$ description

$$\boxed{\mathfrak{su}(6)_0 + \frac{3}{2}\Lambda^3 + 5F = \mathfrak{so}(11) + \frac{3}{2}S + 5F = \mathfrak{so}(10)^{(2)} \quad 1} \tag{4.166}$$

Applying \mathcal{S} on S_4 of

$$\begin{array}{ccccccc} \mathbf{1}_8^2 & \xrightarrow[e]{h} & \mathbf{2}_6^3 & \xrightarrow[e+f-\sum x_i]{h} & \mathbf{3}_4 & \xrightarrow[e]{e+f} & \mathbf{4}_0 \\ & \searrow[f, f, f] & & \searrow[f-x_i] & \searrow[f] & & \searrow[2e+f] \\ & & & & & & \searrow[e] \\ & & & & & & \searrow[f-x_i-y_i] \\ & & & & & & \searrow[y_i] \\ & & & & & & \searrow[x_1-y_2, x_2-y_1, x_3-y_3] \\ & & & & & & \mathbf{5}_6^{3+3+1} \end{array} \tag{4.167}$$

implies that

$$\mathfrak{su}(6)_2 + \frac{3}{2}\Lambda^3 + 3F = \mathfrak{so}(11) + \frac{5}{2}S + 2F \tag{4.168}$$

Since the theory on the right hand side of the above equation exceeds the bound for marginal theories, we find that the theory on the left hand side is neither a $5d$ KK theory nor a $5d$ SCFT. Integrating out matter from (4.167), we find that

$$\mathfrak{su}(6)_3 + \frac{3}{2}\Lambda^3 + F = \mathfrak{so}(11) + \frac{5}{2}S \tag{4.169}$$

where the right hand side lifts to a KK theory. See (4.196).

Applying \mathcal{S} on S_4 of

$$\begin{array}{ccccccc} \mathbf{1}_{10} & \xrightarrow[e]{h} & \mathbf{2}_8^3 & \xrightarrow[e+f-\sum x_i]{h} & \mathbf{3}_6 & \xrightarrow[e]{2e+f} & \mathbf{4}_0 \\ & \searrow[f, f, f] & & \searrow[f-x_i] & \searrow[f] & & \searrow[e+f] \\ & & & & & & \searrow[e] \\ & & & & & & \searrow[f-x_i-y_i] \\ & & & & & & \searrow[y_i] \\ & & & & & & \searrow[x_1-y_2, x_2-y_1, x_3-y_3] \\ & & & & & & \mathbf{5}_4^{3+3} \end{array} \tag{4.170}$$

leads to

$$\boxed{\mathfrak{su}(6)_{\frac{9}{2}} + \frac{3}{2}\Lambda^3 = \begin{matrix} \mathfrak{e}_6^{(2)} \\ 3 \end{matrix}} \quad (4.171)$$

Applying \mathcal{S} on S_2 and S_4 of

$$(4.172)$$

implies

$$\boxed{\mathfrak{su}(6)_0 + \Lambda^3 + \Lambda^2 + 4F = \begin{matrix} \mathfrak{so}(8)^{(2)} & \mathfrak{sp}(0)^{(1)} \\ 3 & \xrightarrow{2} & 1 \end{matrix}} \quad (4.173)$$

Applying \mathcal{S} on S_4 of

$$(4.174)$$

implies

$$\mathfrak{su}(6)_{\frac{3}{2}} + \Lambda^3 + \Lambda^2 + 3F = \mathfrak{so}(11) + 2S + 3F \quad (4.175)$$

Furthermore, applying \mathcal{S} to S_2 and S_4 of

$$(4.176)$$

leads to

$$\boxed{\mathfrak{su}(6)_{\frac{3}{2}} + \Lambda^3 + \Lambda^2 + 3F = \mathfrak{so}(11) + 2S + 3F = \begin{matrix} \mathfrak{su}(3)^{(2)} & \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(3)^{(2)} \\ 3 & \text{---} & 1 & \text{---} & 2 \end{matrix}} \quad (4.177)$$

Performing \mathcal{S} on S_1, S_2, S_4 and S_5 in

$$\begin{array}{ccccccc}
 \mathbf{1}_0 & \xrightarrow[\substack{f \\ e, e}]{f} & \mathbf{2}_0^{10+2} & \xrightarrow[\substack{2e+f-\sum x_i-\sum y_i \\ y_i}]{f-\sum y_i} & \mathbf{3}_6 & \xrightarrow[\substack{e \\ f}]{e} & \mathbf{4}_0 \\
 & & & & & & \xrightarrow[\substack{f \\ f-\sum x_i}]{2e+f} \\
 & & & & & & \mathbf{5}_0^{2+2} \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{5}_0^{2+2} \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{4}_0 \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{3}_6 \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{2}_0^{10+2} \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{1}_0
 \end{array}
 \tag{4.178}$$

leads to

$$\boxed{
 \begin{array}{ccc}
 \mathfrak{su}(6)_0 + \Lambda^3 + 10F & = & \begin{array}{cc} \mathfrak{sp}(2)^{(1)} & \mathfrak{su}(2)^{(1)} \\ 1 & \text{---} & 2 \end{array}
 \end{array}
 }
 \tag{4.179}$$

Let us consider the following geometry describing $\mathfrak{su}(6)_{\frac{3}{2}} + \Lambda^3 + 9F$

$$\begin{array}{ccccccc}
 \mathbf{1}_2 & \xrightarrow[\substack{e \\ f, f}]{e} & \mathbf{2}_0^2 & \xrightarrow[\substack{e \\ f-x_i}]{e} & \mathbf{3}_2 & \xrightarrow[\substack{h \\ f, f}]{e+2f-\sum x_i} & \mathbf{4}_0^{8+1} \\
 & & & & & & \xrightarrow[\substack{e-y \\ e-x_1}]{e+2f-\sum x_i} \\
 & & & & & & \mathbf{5}_0^{2+2} \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{4}_0^{8+1} \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{3}_2 \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{2}_0^2 \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{1}_2
 \end{array}
 \tag{4.180}$$

After the flop of $e - x_1$ in S_5 , the geometry can be written as

$$\begin{array}{ccccccc}
 \mathbf{1}_2 & \xrightarrow[\substack{e \\ f, f}]{e} & \mathbf{2}_0^2 & \xrightarrow[\substack{f \\ e-x_i}]{f} & \mathbf{3}_0^{1+1} & \xrightarrow[\substack{f \\ x, y}]{f} & \mathbf{4}_1^8 \\
 & & & & & & \xrightarrow[\substack{f-x_1, x_1 \\ e-x_i}]{2h+f-\sum x_i} \\
 & & & & & & \mathbf{5}_0^{2+1} \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{4}_1^8 \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{3}_0^{1+1} \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{2}_0^2 \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{1}_2
 \end{array}
 \tag{4.181}$$

Flopping y in S_5 leads to the geometry

$$\begin{array}{ccccccc}
 \mathbf{1}_0^{1+1} & \xrightarrow[\substack{f-x-y \\ x, y}]{f-x-y} & \mathbf{2}_0^2 & \xrightarrow[\substack{f \\ e-x_i}]{f} & \mathbf{3}_0^{1+1} & \xrightarrow[\substack{f \\ x, y}]{f} & \mathbf{4}_1^8 \\
 & & & & & & \xrightarrow[\substack{f-x_1, x_1 \\ e-x_i}]{2h+f-\sum x_i} \\
 & & & & & & \mathbf{5}_0^2 \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{4}_1^8 \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{3}_0^{1+1} \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{2}_0^2 \\
 & & & & & & \uparrow \\
 & & & & & & \mathbf{1}_0^{1+1}
 \end{array}
 \tag{4.182}$$

So, we find that

$$\boxed{\mathfrak{su}(6)_{\frac{3}{2}} + \Lambda^3 + 9F = \begin{array}{cccc} \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(2)^{(1)} & \mathfrak{su}(1)^{(1)} \\ 1 & \text{---} & 2 & \text{---} & 2 & \text{---} & 2 \end{array}} \quad (4.183)$$

The geometry

(4.184)

for $\mathfrak{su}(6)_0 + S^2 + \frac{1}{2}\Lambda^3 + F$ can be flopped to

(4.185)

Applying \mathcal{S} to S_1, S_2, S_4 and S_5 we find that

$$\boxed{\mathfrak{su}(6)_0 + S^2 + \frac{1}{2}\Lambda^3 + F = \begin{array}{cc} \mathfrak{su}(2)^{(1)} & \mathfrak{su}(3)^{(1)} \\ 2 & \text{---} & 2 \\ & & \cup \end{array}} \quad (4.186)$$

Similarly, we find that

$$\boxed{\mathfrak{su}(6)_{\frac{3}{2}} + S^2 + \frac{1}{2}\Lambda^3 = \begin{array}{ccc} \mathfrak{su}(1)^{(1)} & \mathfrak{su}(2)^{(1)} & \mathfrak{su}(2)^{(1)} \\ 2 & \text{---} & 2 & \text{---} & 2 \\ & & & & \cup \end{array}} \quad (4.187)$$

$\mathfrak{su}(6)_{\frac{3}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 + 2F$ can be described by the geometry

$$\begin{array}{ccccccc}
 \mathbf{1}_7 & \xrightarrow[e, f]{e, f} & \mathbf{2}_1 & \xrightarrow[h]{h} & \mathbf{4}_0 & \xrightarrow[e, f]{e, f} & \mathbf{5}_3 \\
 & \searrow & & \searrow & & \searrow & \\
 & & & & \mathbf{3}_0^{2+2+2+2} & & \\
 & & & & \text{Labels: } e+f-\sum x_i-z_2-\sum w_i, e+f-\sum x_i-\sum y_i, z_2-z_1, x_i-y_i, f-z_1-z_2 & &
 \end{array}$$

(4.188)

Performing isomorphisms on S_3 , we can write the above geometry as

$$\begin{array}{ccccccc}
 \mathbf{1}_7 & \xrightarrow[e, f]{e, f} & \mathbf{2}_1 & \xrightarrow[h]{h} & \mathbf{4}_0 & \xrightarrow[e, f]{e, f} & \mathbf{5}_3 \\
 & \searrow & & \searrow & & \searrow & \\
 & & & & \mathbf{3}_0^{3+3+2} & & \\
 & & & & \text{Labels: } 3e+f-\sum x_i-\sum y_i-\sum z_i, f-\sum x_i, x_i-y_i, f-z_1-z_2 & &
 \end{array}$$

(4.189)

Performing some flops associated to x_i and y_i , we obtain

$$\mathfrak{su}(6)_{\frac{3}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 + 2F = \begin{array}{ccc} \mathfrak{su}(1)^{(1)} & \mathfrak{sp}(0)^{(1)} & \mathfrak{so}(8)^{(3)} \\ 2 & \text{---} & 1 & \text{---} & 3 \end{array}$$

(4.190)

Now consider the geometry

$$\begin{array}{ccccccc}
 \mathbf{1}_6 & \xrightarrow[e, f]{e, f} & \mathbf{2}_0 & \xrightarrow[e]{e} & \mathbf{4}_1 & \xrightarrow[e, f]{h+f} & \mathbf{5}_5 \\
 & \searrow & & \searrow & & \searrow & \\
 & & & & \mathbf{3}_0^{2+2+2+2} & & \\
 & & & & \text{Labels: } e+f-x_1-z_2-\sum y_i, e+f-y_2-\sum z_i-\sum w_i, z_2-z_1, x_1-x_2, f-x_1-x_2, y_2-y_1 & &
 \end{array}$$

(4.191)

which is isomorphic to

$$\begin{array}{ccccccc}
 \mathbf{1}_6 & \xrightarrow[e, f]{e, f} & \mathbf{2}_0 & \xrightarrow[e]{e} & \mathbf{4}_1 & \xrightarrow[e, f]{h+f} & \mathbf{5}_5 \\
 & \searrow & & \searrow & & \searrow & \\
 & & & & \mathbf{3}_0^{2+2+2+2} & & \\
 & & & & \text{Labels: } 2e+f-x_2-z_2-\sum y_i-\sum w_i, e+f-y_2-\sum z_i-\sum x_i, z_2-z_1, x_2-x_1, f-w_1-w_2, y_2-y_1 & &
 \end{array}$$

(4.192)

resulting in

$$\mathfrak{su}(6)_{\frac{1}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 + 2F = \mathfrak{f}_4^{(1)}$$

(4.193)

Applying \mathcal{S} on S_4 of

$$\begin{array}{ccccccc}
 \mathbf{1}_6 & \xrightarrow[e]{f} & \mathbf{2}_4^1 & \xrightarrow[e]{h} & \mathbf{3}_2^2 & \xrightarrow[e-\sum x_i]{h} & \mathbf{4}_0 \\
 & & & \searrow[f-x] & & \searrow[f, x_i] & \\
 & & & & & & \mathbf{5}_4^{1+1+2} \\
 & & & & & \searrow[3] & \\
 & & & & & \searrow[f-x-y, z_i] & \\
 & & & & & \searrow[y] & \\
 & & & & & \searrow[x-y] & \\
 & & & & & & \mathbf{5}_4^{1+1+2}
 \end{array}
 \quad (4.194)$$

reveals that

$$\mathfrak{su}(6)_{\frac{7}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 = \mathfrak{so}(11) + \frac{5}{2}\mathbf{S} \quad (4.195)$$

And applying \mathcal{S} to S_4 of

$$\begin{array}{ccccccc}
 \mathbf{1}_{10} & \xrightarrow[e]{f} & \mathbf{2}_8^1 & \xrightarrow[e]{h} & \mathbf{3}_2 & \xrightarrow[e]{2e+f-\sum x_i-y_1-z_2} & \mathbf{4}_0^{2+2+2} \\
 & & & \searrow[f-x] & & \searrow[f] & \\
 & & & & & & \mathbf{5}_0^{1+1} \\
 & & & & & \searrow[y] & \\
 & & & & & \searrow[f-x-y] & \\
 & & & & & \searrow[x-y] & \\
 & & & & & & \mathbf{5}_0^{1+1}
 \end{array}
 \quad (4.196)$$

and recalling (4.169), we find

$$\mathfrak{su}(6)_3 + \frac{3}{2}\Lambda^3 + \mathbf{F} = \mathfrak{su}(6)_{\frac{7}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2 = \mathfrak{so}(11) + \frac{5}{2}\mathbf{S} = \mathfrak{e}_6^{(2)} \quad (4.197)$$

(4.195) is an irreducible duality, that is, it isn't possible to integrate out any matter while preserving the duality.

Performing \mathcal{S} on S_1, S_2, S_4 and S_5 of

$$\begin{array}{ccccccc}
 \mathbf{1}_0^{1+1} & \xrightarrow[e-y]{f-x-y, f} & \mathbf{2}_0^{1+8} & \xrightarrow[e+f-x-\sum y_i]{h+f} & \mathbf{3}_3 & \xrightarrow[e]{e+f-z} & \mathbf{4}_0^{1+1+1} \\
 & & & \searrow[x] & & \searrow[f] & \\
 & & & & & & \mathbf{5}_0^{1+1} \\
 & & & & & \searrow[x-y] & \\
 & & & & & \searrow[y] & \\
 & & & & & \searrow[f, f-x-y] & \\
 & & & & & & \mathbf{5}_0^{1+1}
 \end{array}
 \quad (4.198)$$

we obtain

$$\boxed{\mathfrak{su}(6)_0 + \frac{1}{2}\Lambda^3 + \Lambda^2 + 9F = \begin{array}{c} \mathfrak{su}(3)^{(1)} \quad \mathfrak{su}(2)^{(1)} \\ 1 \text{ --- } 2 \end{array}} \quad (4.199)$$

The geometry

$$\begin{array}{ccccccc} \mathbf{1}_{10}^7 & \xrightarrow[e]{h} & \mathbf{2}_{8}^1 & \xrightarrow[e]{h} & \mathbf{3}_6 & \xrightarrow[e]{h+f} & \mathbf{4}_2 \\ & \searrow[f] & & \searrow[f] & & \searrow[f] & \\ & & & & & & \mathbf{5}_0^{3+1} \\ & & & & & \nearrow[x_2-x_3] & \\ & & & & & \nearrow[x_1-x_2] & \\ & & & & & \nearrow[f-x_1-x_2] & \end{array} \begin{array}{l} e \\ e+f-x_1-y \end{array} \quad (4.200)$$

describing $\mathfrak{su}(6)_{\frac{3}{2}} + \frac{1}{2}\Lambda^3 + \Lambda^2 + 8F$ is isomorphic to

$$\begin{array}{ccccccc} \mathbf{1}_{10}^7 & \xrightarrow[e]{h} & \mathbf{2}_{8}^1 & \xrightarrow[e]{h} & \mathbf{3}_6 & \xrightarrow[e]{h+f} & \mathbf{4}_2 \\ & \searrow[f] & & \searrow[f] & & \searrow[f] & \\ & & & & & & \mathbf{5}_0^{3+1} \\ & & & & & \nearrow[x_3-x_2] & \\ & & & & & \nearrow[x_2-x_1] & \\ & & & & & \nearrow[f-x_3-y] & \end{array} \begin{array}{l} e \\ e+f-x_2-x_3 \end{array} \quad (4.201)$$

which describes $\mathfrak{su}(6)_{\frac{3}{2}} + 2\Lambda^2 + 7F$. The latter theory is known to be KK from section 4.1, and we obtain

$$\boxed{\mathfrak{su}(6)_{\frac{3}{2}} + \frac{1}{2}\Lambda^3 + \Lambda^2 + 8F = \mathfrak{su}(6)_{\frac{3}{2}} + 2\Lambda^2 + 7F = \begin{array}{c} \mathfrak{sp}(1)^{(1)} \quad \mathfrak{su}(2)^{(1)} \quad \mathfrak{su}(1)^{(1)} \\ 1 \text{ --- } 2 \text{ --- } 2 \end{array}} \quad (4.202)$$

Applying \mathcal{S} on S_1 and S_5 of

$$\begin{array}{ccccccc} \mathbf{1}_0^{13} & \xrightarrow[e]{e+f-\sum x_i} & \mathbf{2}_9^1 & \xrightarrow[e]{h} & \mathbf{3}_7 & \xrightarrow[e]{h+f} & \mathbf{4}_3 \\ & \searrow[e] & & \searrow[f-x] & & \searrow[f] & \\ & & & & & & \mathbf{5}_0^{1+1} \\ & & & & & \nearrow[y] & \\ & & & & & \nearrow[x-y] & \\ & & & & & \nearrow[e-x-y] & \end{array} \begin{array}{l} e \\ e+f-x \end{array} \quad (4.203)$$

we learn that

$$\boxed{\mathfrak{su}(6)_0 + \frac{1}{2}\Lambda^3 + 13F = \begin{array}{c} \mathfrak{su}(5)^{(1)} \\ 1 \end{array}} \quad (4.204)$$

The geometry

$$\begin{array}{ccccccc}
 \mathbf{1}_{11}^8 & \xrightarrow[e]{e} & \mathbf{2}_9 & \xrightarrow[e]{h} & \mathbf{3}_7 & \xrightarrow[e]{h+f} & \mathbf{4}_3 \\
 & \searrow[f] & & \searrow[f] & & \searrow[f] & \searrow[e] \\
 & & & & & & \mathbf{5}_0^{3+1} \\
 & & & & & \nearrow[x_2-x_3] & \nearrow[f-x_1-x_2] \\
 & & & & & \nearrow[x_1-x_2] & \nearrow[e+f-y]
 \end{array} \tag{4.205}$$

is isomorphic to

$$\begin{array}{ccccccc}
 \mathbf{1}_{11}^8 & \xrightarrow[e]{e} & \mathbf{2}_9 & \xrightarrow[e]{h} & \mathbf{3}_7 & \xrightarrow[e]{h+f} & \mathbf{4}_3 \\
 & \searrow[f] & & \searrow[f] & & \searrow[f] & \searrow[e] \\
 & & & & & & \mathbf{5}_0^{3+1} \\
 & & & & & \nearrow[x_3-x_2] & \nearrow[f-x_3-y] \\
 & & & & & \nearrow[x_2-x_1] & \nearrow[2e+f-\sum x_i]
 \end{array} \tag{4.206}$$

implying

$$\boxed{\mathfrak{su}(6)_3 + \frac{1}{2}\Lambda^3 + 9F = \mathfrak{sp}(5) + \Lambda^2 + 8F} \tag{4.207}$$

We already know from section 4.1 that the right hand side is obtained by untwisted compactification of rank-5 E-string theory.

Applying \mathcal{S} to S_2 and S_3 of the geometry

$$\begin{array}{ccccccc}
 \mathbf{1}_0 & \xrightarrow[e+f]{2e+f-\sum x_i-\sum y_i-\sum z_i} & \mathbf{2}_0^{2+3+3+1} & \xrightarrow[f]{f-\sum x_i} & \mathbf{3}_0 & \xrightarrow[e]{3e+f} & \mathbf{4}_8 & \xrightarrow[e]{h} & \mathbf{5}_{10} \\
 & & \searrow[y_i-z_i] & \searrow[e-w-y_3, x_1-y_1, x_2-y_2] & & \searrow[f] & & & \searrow[f] \\
 & & & \text{---} 3 \text{---} & & & & & \text{---} 3 \text{---}
 \end{array} \tag{4.208}$$

we see that it gives rise to the $5d$ gauge theory $\mathfrak{su}(6)_3 + 3\Lambda^2$. Flopping $f-w$ in S_2 , we obtain

$$\begin{array}{ccccccc}
 \mathbf{1}_0 & \xrightarrow[e+f-x-y]{2h+f-\sum x_i-\sum y_i-\sum z_i} & \mathbf{2}_1^{2+3+3} & \xrightarrow[f]{f-\sum x_i} & \mathbf{3}_0 & \xrightarrow[e]{3e+f} & \mathbf{4}_8 & \xrightarrow[e]{h} & \mathbf{5}_{10} \\
 & & \searrow[y_i-z_i] & \searrow[e-y_3, x_1-y_1, x_2-y_2] & & \searrow[f] & & & \searrow[f] \\
 & & & \text{---} 3 \text{---} & & & & & \text{---} 3 \text{---}
 \end{array} \tag{4.209}$$

implying that

$$\boxed{\mathfrak{su}(6)_3 + 3\Lambda^2 = \begin{array}{ccc} \mathfrak{su}(1)^{(1)} & \mathfrak{sp}(0)^{(1)} & \mathfrak{so}(8)^{(3)} \\ 2 & \text{---} 1 \text{---} & 4 \end{array}} \tag{4.210}$$

Applying \mathcal{S} on S_3 of

$$\begin{array}{ccccccc}
 \mathbf{1}_5 & \xrightarrow[e]{f} & \mathbf{2}_3 & \xrightarrow[e]{h} & \mathbf{3}_0^3 & \xrightarrow[e]{e+f-\sum x_i} & \mathbf{4}_1 \\
 & & & \searrow^f & \searrow^{e+2f-\sum x_i} & & \searrow^{h+3f} \\
 & & & & & \searrow^{x_i} & \searrow^{e-\sum x_i-\sum y_i-\sum z_i} \\
 & & & & & \searrow^3 & \searrow^{y_i-x_i} \\
 & & & & & \searrow^3 & \searrow^{z_i-y_i} \\
 & & & & & & \searrow^3 \\
 & & & & & & \mathbf{5}_0^{3+3+3}
 \end{array}
 \tag{4.211}$$

implies

$$\mathfrak{su}(6)_1 + 3\Lambda^2 = \frac{\mathfrak{f}_4^{(1)}}{2}$$

(4.212)

The theories $\mathfrak{su}(6)_k + 3\Lambda^2$ for $k = 0, 2$ can be reduced to $\mathfrak{sp}(3)_\pi + 2\Lambda^2$ by Higgsing. As the latter theory is neither $5d$ SCFT nor $5d$ KK theory, the former theories cannot be $5d$ SCFTs or $5d$ KK theories either.

Applying \mathcal{S} on S_4 of

$$\begin{array}{ccccccc}
 \mathbf{1}_6 & \xrightarrow[e]{f, f, f} & \mathbf{2}_1^{2h} & \xrightarrow[e]{e-\sum x_i} & \mathbf{3}_6^h & \xrightarrow[e]{2e+f} & \mathbf{4}_0 \\
 & & & \searrow^f & \searrow^f & & \searrow^f \\
 & & & & & \searrow^2 & \searrow^{f-x_i-y_i} \\
 & & & & & \searrow^4 & \searrow^{y_i-z_i} \\
 & & & & & & \searrow^{x_1-y_2, x_2-y_1, z_i-w_i} \\
 & & & & & & \mathbf{5}_2^{2+2+2+2}
 \end{array}
 \tag{4.213}$$

we find that

$$\mathfrak{so}(11) + \mathcal{S} + 7F = \frac{\mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(7)^{(2)}}{1 \quad 2}$$

(4.214)

The geometry

$$\begin{array}{ccccccc}
 \mathbf{1}_6 & \xrightarrow[e]{f, f} & \mathbf{2}_1^{2h} & \xrightarrow[e]{e} & \mathbf{3}_1^h & \xrightarrow[e]{e} & \mathbf{4}_3 \\
 & & & \searrow^f & \searrow^f & & \searrow^{h+f} \\
 & & & & & \searrow^2 & \searrow^{2e+f-\sum x_i-\sum y_i} \\
 & & & & & \searrow^{y_2-y_3} & \searrow^{y_3-z} \\
 & & & & & \searrow^{f-y_1-y_2, y_1-y_2} & \mathbf{5}_0^{8+3+1}
 \end{array}
 \tag{4.215}$$

is isomorphic to the geometry

$$\begin{array}{ccccccc}
 \mathbf{1}_6 & \xrightarrow[e, f, f]{e} & \mathbf{2}_1 & \xrightarrow[e, f]{e} & \mathbf{3}_1 & \xrightarrow[e, f]{h} & \mathbf{4}_3 \\
 & & & & & & \downarrow h+f \\
 & & & & & & \mathbf{5}_0^{8+3+1} \\
 & & & & & & \uparrow e+f-\sum x_i-z \\
 & & & & & & \downarrow z-y_3 \\
 & & & & & & \downarrow y_3-y_2 \\
 & & & & & & \downarrow f-y_3-z, y_2-y_1 \\
 & & & & & & \downarrow 2
 \end{array}$$

(4.216)

Thus,

$$\mathfrak{so}(11) + \frac{1}{2}S + 8F = \mathfrak{su}(9)^{(2)}_1$$

(4.217)

Applying \mathcal{S} on S_2, S_4 and S_5 of

$$\begin{array}{ccccc}
 \mathbf{2}_0 & \xrightarrow[e, f-x_i-y_i]{f} & \mathbf{3}_2^{4+4} & \xrightarrow[e, h-\sum x_i]{f} & \mathbf{4}_0^{2+2} \\
 4e+f \downarrow & & & & \downarrow e-\sum x_i, e-\sum y_i \\
 \mathbf{1}_{10} & \xrightarrow[e, f]{f} & \mathbf{4} & \xrightarrow[e, h-\sum y_i]{f} & \mathbf{5}_0 \\
 & & & & \downarrow e, e
 \end{array}$$

(4.218)

we find that

$$\mathfrak{so}(10) + 4S + 2F = \mathfrak{su}(3)^{(2)}_3 \text{ --- } \mathfrak{sp}(0)^{(1)}_1 \text{ --- } \mathfrak{su}(2)^{(1)}_2$$

(4.219)

Applying \mathcal{S} on S_2 of

$$\begin{array}{ccccc}
 \mathbf{2}_0^4 & \xrightarrow[e, e+f-\sum x_i]{e} & \mathbf{3}_0^3 & \xrightarrow[e, e-\sum x_i]{h} & \mathbf{4}_1 \\
 2e+f \downarrow & & & & \downarrow e \\
 \mathbf{1}_6 & \xrightarrow[e, f-x_i]{f-x_i} & \mathbf{3} & \xrightarrow[e, f-x_i]{e} & \mathbf{5}_2^3 \\
 & & & & \downarrow f-x_i
 \end{array}$$

(4.220)

we discover that

$$\mathfrak{so}(10) + 3S + 4F = \mathfrak{so}(9)^{(1)}_1$$

(4.221)

Applying \mathcal{S} on S_2 of

$$\begin{array}{ccccc}
 \mathbf{2}_0 & \xrightarrow[e, e-\sum x_i]{2e+f} & \mathbf{3}_0^6 & \xrightarrow[e, e-\sum x_i]{e} & \mathbf{4}_2 \\
 f \downarrow & & & & \downarrow f \\
 \mathbf{1}_2^{2+2+2+2} & \xrightarrow[e, f-x_i-y_i]{f-x_i-y_i} & \mathbf{2} & \xrightarrow[e, y_i-w_i]{2} & \mathbf{5}_2 \\
 & & & & \downarrow f
 \end{array}$$

(4.222)

leads to

$$\boxed{\mathfrak{so}(10) + 2S + 6F = \begin{array}{cc} \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(6)^{(2)} \\ 1 & \text{---} & 2 \end{array}} \quad (4.223)$$

The geometry

(4.224)

is isomorphic to the geometry

(4.225)

implying that

$$\boxed{\mathfrak{so}(10) + S + 7F = \begin{array}{c} \mathfrak{su}(8)^{(2)} \\ 1 \end{array}} \quad (4.226)$$

4.6 Rank 6

Applying S on S_2, S_3, S_4 and S_5 of

(4.227)

we find

$$\boxed{\mathfrak{su}(7)_0 + \Lambda^3 + 6F = \mathfrak{so}(8)^{(2)} \quad \mathfrak{sp}(1)^{(1)} \quad 3 \text{ --- } 2 \text{ --- } 1} \tag{4.228}$$

Applying \mathcal{S} on S_5 of

$$\begin{array}{ccccccc}
 \mathbf{1}_9^5 & \xrightarrow{e} & \mathbf{2}_7 & \xrightarrow{e} & \mathbf{3}_5 & \xrightarrow{e} & \mathbf{4}_1 \\
 & \searrow f & & \searrow f-x & & \searrow x_3, x_4 & \\
 & & & & & & \mathbf{5}_0^4 \\
 & & & & & \searrow x_3-x_2 & \\
 & & & & & \searrow x_2-x_1 & \\
 & & & & & \searrow x_4-x_3 & \\
 & & & & & & \mathbf{6}_2
 \end{array}$$

(4.229)

leads to

$$\mathfrak{su}(7)_{\frac{3}{2}} + \Lambda^3 + 5F = \mathfrak{so}(13) + S + 5F \tag{4.230}$$

Now, consider the geometry

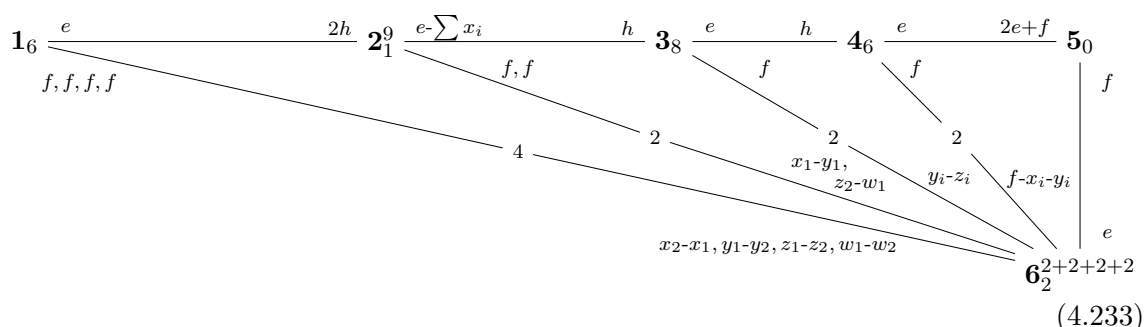
$$\begin{array}{ccccc}
 \mathbf{2}_0 & \xrightarrow{f} & \mathbf{3}_2^{2+2+2+2} & \xrightarrow{e} & \mathbf{4}_0 \\
 & \searrow f-x_i-y_i, f-z_i-w_i & & \searrow x_1-y_2, x_2-y_1 & \\
 & & & & \mathbf{5}_1^5 \\
 & & & & \mathbf{6}_6
 \end{array}$$

(4.231)

Applying \mathcal{S} on S_2 and S_4 of the above geometry, we find that

$$\boxed{\mathfrak{su}(7)_{\frac{3}{2}} + \Lambda^3 + 5F = \mathfrak{so}(13) + S + 5F = \mathfrak{su}(3)^{(2)} \quad \mathfrak{sp}(0)^{(1)} \quad \mathfrak{su}(5)^{(2)} \quad 3 \text{ --- } 1 \text{ --- } 2} \tag{4.232}$$

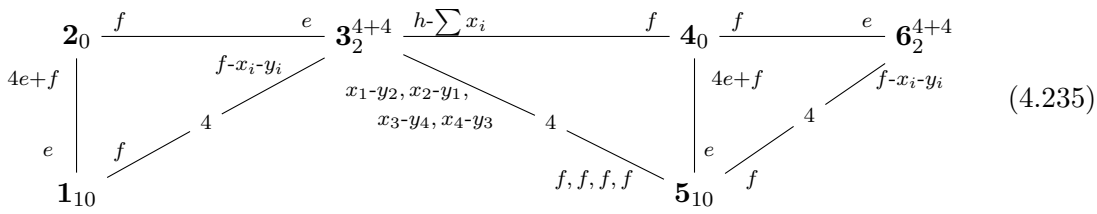
Applying \mathcal{S} on S_5 of



we obtain

$$\boxed{\mathfrak{so}(13) + \frac{1}{2}S + 9F = \begin{array}{ccc} \mathfrak{sp}(0)^{(1)} & & \mathfrak{su}(9)^{(2)} \\ 1 & \text{---} & 2 \end{array}} \quad (4.234)$$

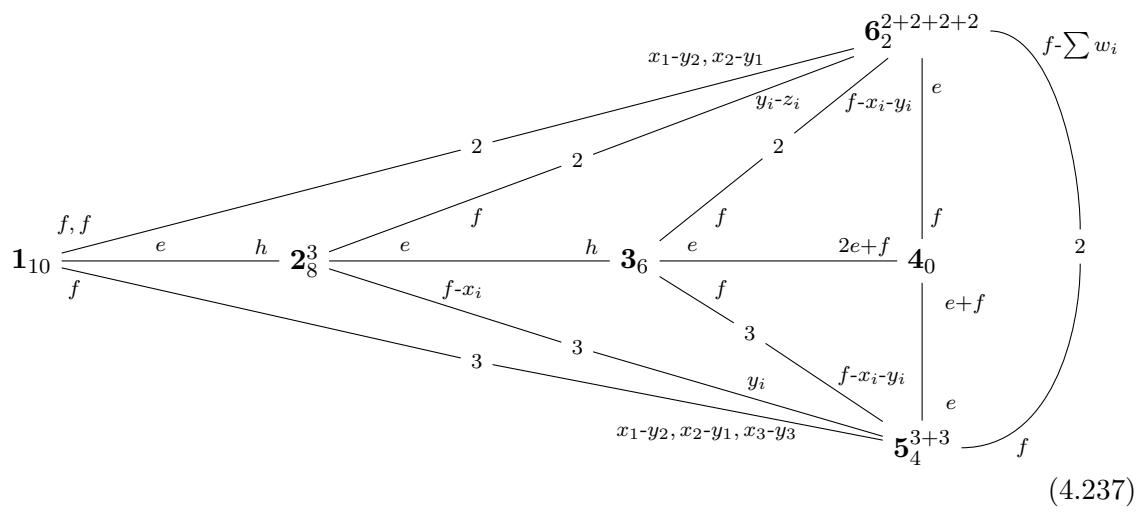
Applying \mathcal{S} on S_2 and S_4 of



we see that

$$\boxed{\mathfrak{so}(12) + 2S + 4F = \begin{array}{cccc} \mathfrak{su}(3)^{(2)} & \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(3)^{(2)} & \mathfrak{sp}(0)^{(1)} \\ 3 & \text{---} & 1 & \text{---} & 3 & \text{---} & 1 \end{array}} \quad (4.236)$$

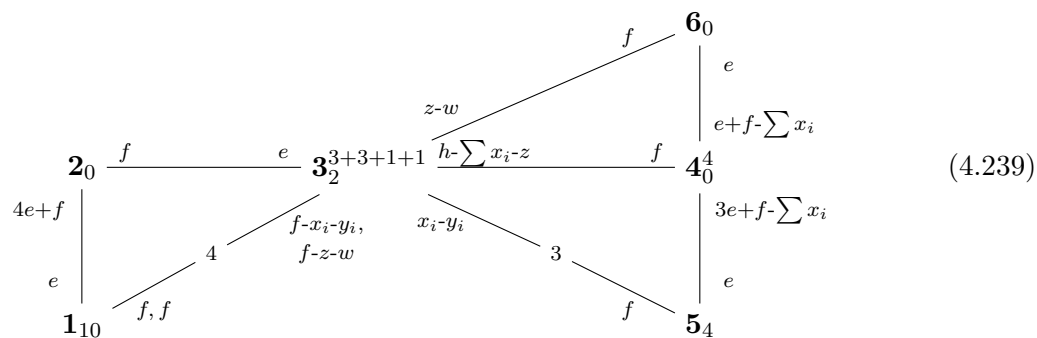
Applying \mathcal{S} on S_4 of



we obtain

$$\boxed{\mathfrak{so}(12) + \frac{3}{2}S + C + F = \begin{matrix} \mathfrak{e}_6^{(2)} & \mathfrak{sp}(0)^{(1)} \\ 3 & \text{---} 2 \text{---} 1 \end{matrix}} \quad (4.238)$$

Applying S on S_2 and S_4 in



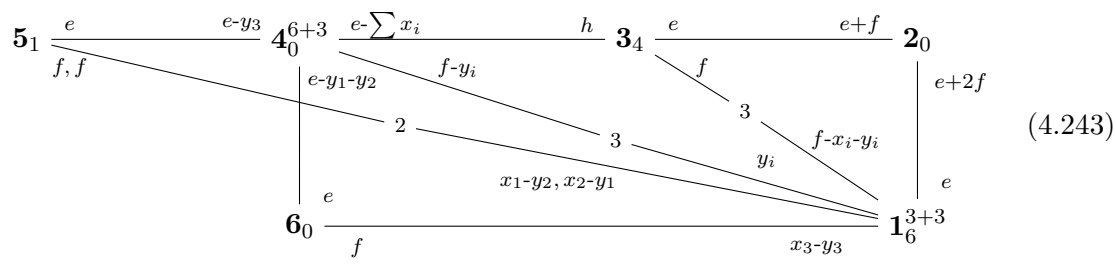
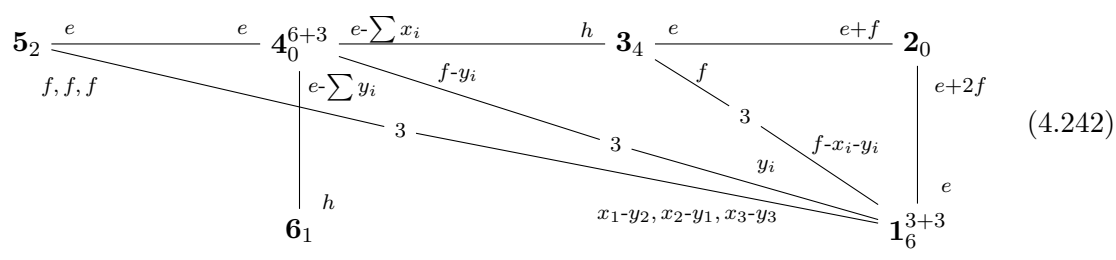
we obtain

$$\boxed{\mathfrak{so}(12) + \frac{3}{2}S + \frac{1}{2}C + 4F = \begin{matrix} \mathfrak{su}(3)^{(2)} & \mathfrak{sp}(0)^{(1)} & \mathfrak{g}_2^{(1)} \\ 3 & \text{---} 1 & \text{---} 2 \end{matrix}} \quad (4.240)$$

We claim that

$$\mathfrak{so}(12) + \frac{3}{2}S + 6F = \mathfrak{so}(12) + S + \frac{1}{2}C + 6F \quad (4.241)$$

The proof is slightly involved. Let us start with the following two geometries



describing $\mathfrak{so}(12) + \frac{3}{2}S + 6F$ and $\mathfrak{so}(12) + S + \frac{1}{2}C + 6F$ respectively. (4.242) and (4.243) can be flopped to obtain the following geometries respectively

(4.244)

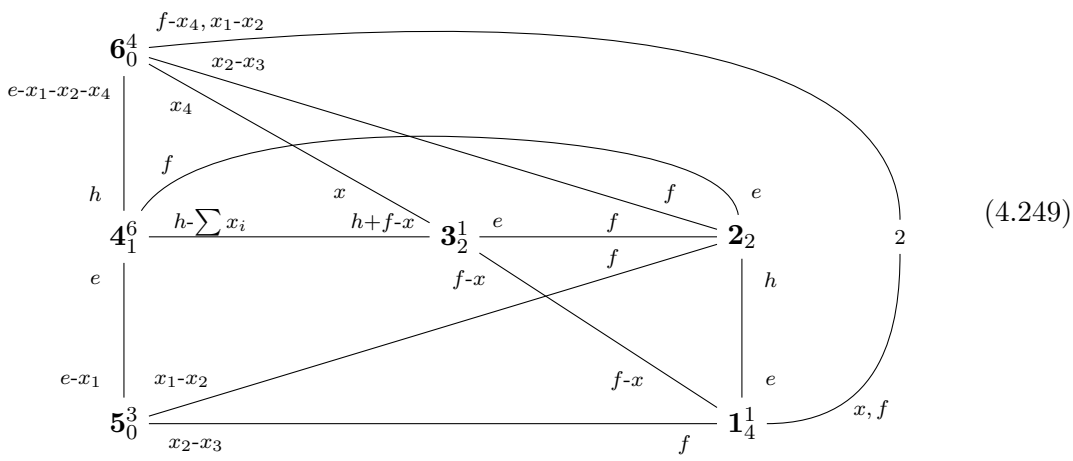
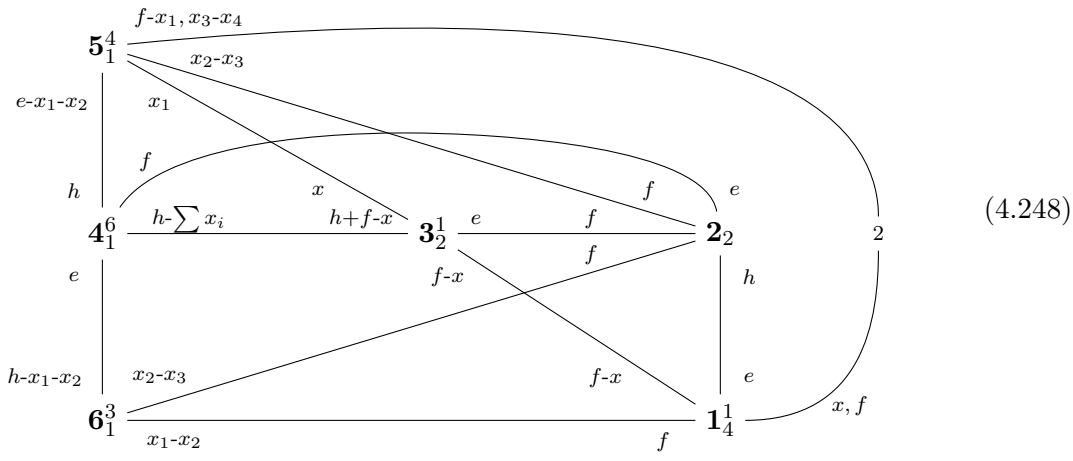
(4.245)

Applying S on S_2 of both the above geometries, we obtain the geometries

(4.246)

(4.247)

Performing a few more flops we obtain the following two geometries from (4.246) and (4.247) respectively



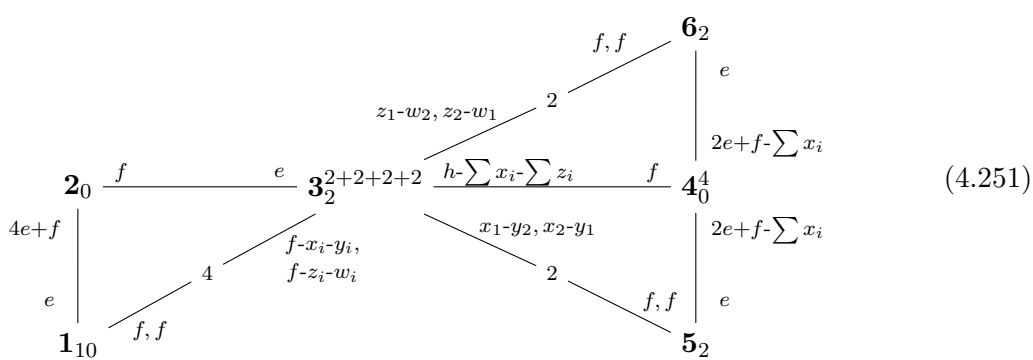
Relabeling S_5 and S_6 in (4.249) we can see that it becomes isomorphic to (4.248).

Now, applying \mathcal{S} on S_2 in (4.242), we see that

$\mathfrak{so}(12) + \frac{3}{2}S + 6F = \mathfrak{so}(12) + S + \frac{1}{2}C + 6F = \begin{matrix} \mathfrak{so}(11)^{(1)} \\ 1 \end{matrix}$	(4.250)
--	---------

The duality (4.241) is an irreducible duality. That is, the duality does not hold if we integrate out matter from both sides of (4.241).

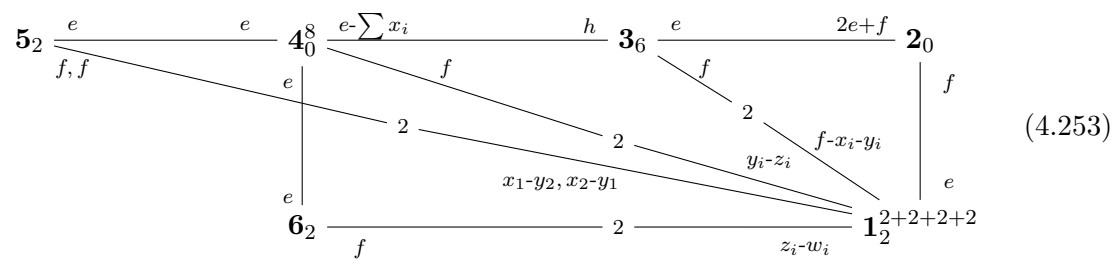
Applying \mathcal{S} on S_2 and S_4 of the geometry



we learn that

$$\mathfrak{so}(12) + S + C + 4F = \begin{matrix} \mathfrak{su}(3)^{(2)} & \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(4)^{(2)} \\ 3 & \text{---} 1 & \text{---} 2 \end{matrix} \quad (4.252)$$

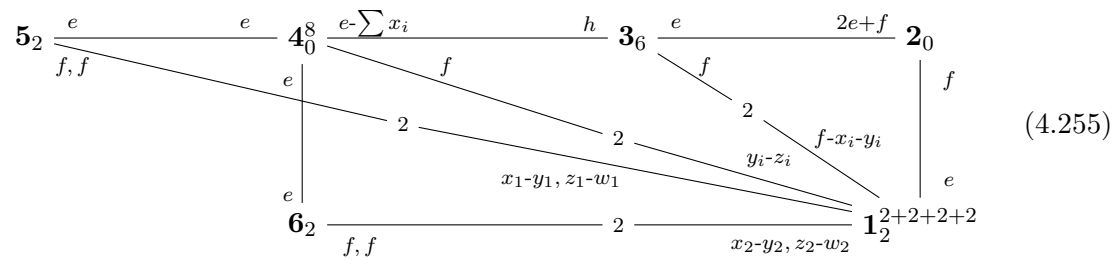
Applying \mathcal{S} on S_2 of



we obtain

$$\mathfrak{so}(12) + S + 8F = \begin{matrix} \mathfrak{sp}(0)_0^{(1)} & \mathfrak{su}(8)^{(2)} \\ 1 & \text{---} 2 \end{matrix} \quad (4.254)$$

where the theta angle $\theta = 0$ for $\mathfrak{sp}(0)$ means that the $\mathfrak{su}(8)$ is embedded into \mathfrak{e}_8 with $\mathfrak{su}(2)$ commutant. Similarly, applying \mathcal{S} on S_2 of

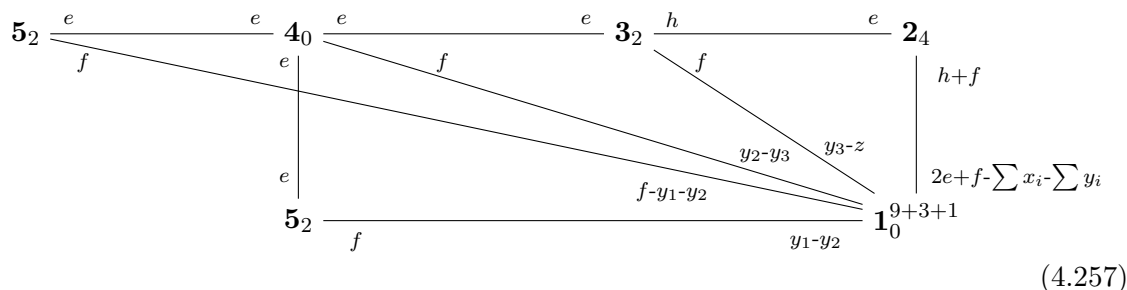


we obtain

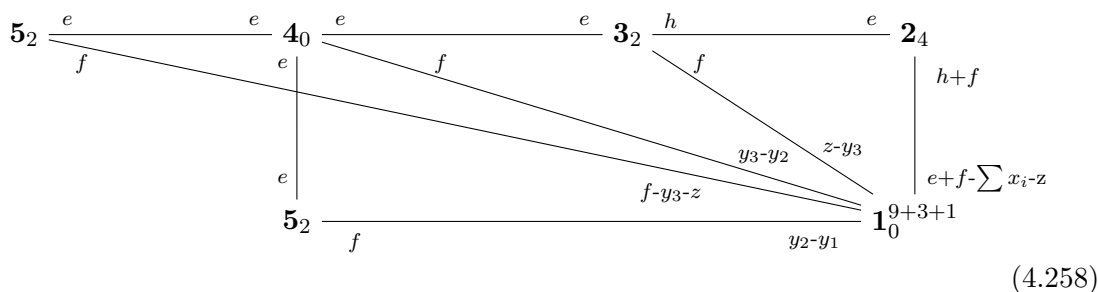
$$\mathfrak{so}(12) + \frac{1}{2}S + \frac{1}{2}C + 8F = \begin{matrix} \mathfrak{sp}(0)_\pi^{(1)} & \mathfrak{su}(8)^{(2)} \\ 1 & \text{---} 2 \end{matrix} \quad (4.256)$$

where the theta angle $\theta = \pi$ for $\mathfrak{sp}(0)$ means that the $\mathfrak{su}(8)$ is embedded into \mathfrak{e}_8 with $\mathfrak{u}(1)$ commutant.

The geometry



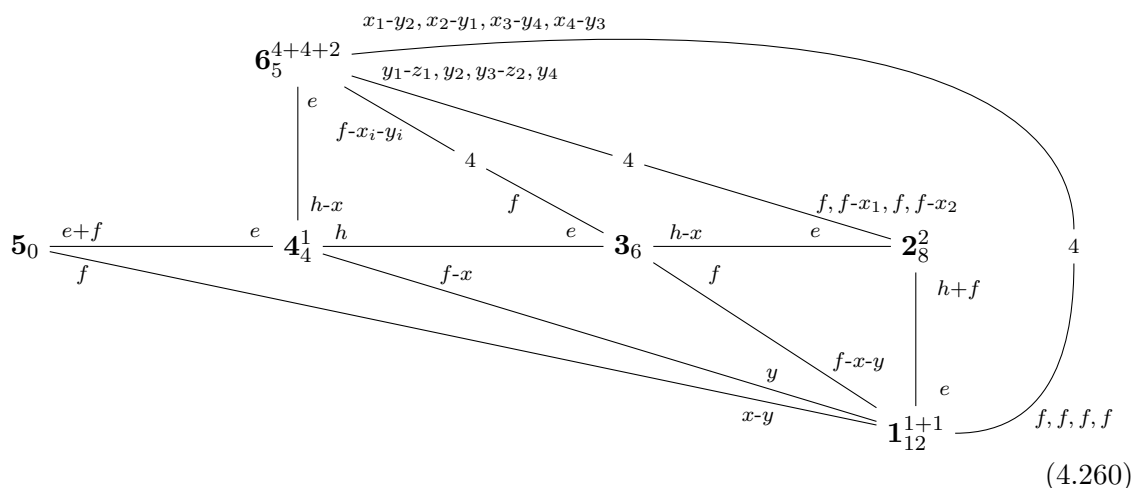
is isomorphic to the geometry



Thus,

$$\boxed{\mathfrak{so}(12) + \frac{1}{2}\mathbf{S} + 9\mathbf{F} = \frac{\mathfrak{su}(10)^{(2)}}{1}} \tag{4.259}$$

Now consider the following geometry



describing $\mathfrak{so}(12) + 2\mathbf{S} + \frac{1}{2}\mathbf{C}$. It is possible to decouple S_6 [63] by decompactifying the curves $f - x_1, f - y_2, f - x_3, f - y_4, x_2, y_1, x_4, y_3$ while keeping the curves $x_1, y_2, x_3, y_4, f - x_2, f -$

$y_1, f - x_4, f - y_3, e$ compact. After the decompactification, we obtain the geometry

$$\begin{array}{ccccccc}
 \mathbf{5}_0 & \xrightarrow[e+f]{e} & \mathbf{4}_4^1 & \xrightarrow[h]{e} & \mathbf{3}_6 & \xrightarrow[h-x]{e} & \mathbf{2}_8^2 \\
 & \searrow^f & & \searrow^{f-x} & & \searrow^f & \\
 & & & & & & \mathbf{1}_{12}^{1+1} \\
 & & & & & \nearrow^y & \\
 & & & & & \nearrow^{f-x-y} & \\
 & & & & & \nearrow^{x-y} &
 \end{array}
 \quad (4.261)$$

which describes $\mathfrak{su}(6)_{\frac{9}{2}} + \frac{1}{2}\Lambda^3 + 2\Lambda^2$ which is neither a $5d$ SCFT nor a $5d$ KK theory. We are thus led to the conclusion that $\mathfrak{so}(12) + 2S + \frac{1}{2}C$ is neither a $5d$ SCFT nor a $5d$ KK theory.

The isomorphism between

$$\begin{array}{ccc}
 \begin{array}{c} e-x \quad e-y \\ \frown \\ \mathbf{1}_0^{1+1} \\ \downarrow^{f-x, x} \\ 2 \\ \downarrow^{f-y, y} \\ \mathbf{2}_0^{1+1} \\ e-x \quad e-y \\ \smile \end{array} & \begin{array}{c} e-x \quad e-y \\ \frown \\ \mathbf{6}_0^{1+1} \\ \downarrow^{f-x, x} \\ 2 \\ \downarrow^{f-y, y} \\ \mathbf{3}_0^{1+1} \\ e-x \quad e-y \\ \smile \end{array} & \begin{array}{c} e-x \quad e-y \\ \frown \\ \mathbf{5}_0^{1+1} \\ \downarrow^{f-y, y} \\ 2 \\ \downarrow^{f-x, x} \\ \mathbf{4}_0^{1+1} \\ e-x \quad e-y \\ \smile \end{array} \\
 \downarrow^{f-x, x} & \downarrow^{f-y, y} & \downarrow^{f-x, x} \\
 \mathbf{2}_0^{1+1} & \mathbf{3}_0^{1+1} & \mathbf{4}_0^{1+1}
 \end{array}
 \quad (4.262)$$

and

$$\begin{array}{ccc}
 \begin{array}{c} x \quad y \\ \frown \\ \mathbf{1}_0^{1+1} \\ \downarrow^{e-y, f-x} \\ 2 \\ \downarrow^{e-x, f-y} \\ \mathbf{2}_0^{1+1} \\ x \quad y \\ \smile \end{array} & \begin{array}{c} x \quad y \\ \frown \\ \mathbf{6}_0^{1+1} \\ \downarrow^{e-y, f-x} \\ 2 \\ \downarrow^{e-x, f-y} \\ \mathbf{3}_0^{1+1} \\ x \quad y \\ \smile \end{array} & \begin{array}{c} x \quad y \\ \frown \\ \mathbf{5}_0^{1+1} \\ \downarrow^{e-x, f-y} \\ 2 \\ \downarrow^{e-y, f-x} \\ \mathbf{4}_0^{1+1} \\ x \quad y \\ \smile \end{array} \\
 \downarrow^{e-y, f-x} & \downarrow^{e-x, f-y} & \downarrow^{e-x, f-y} \\
 \mathbf{2}_0^{1+1} & \mathbf{3}_0^{1+1} & \mathbf{4}_0^{1+1}
 \end{array}
 \quad (4.263)$$

implies that

$$\mathfrak{e}_6 + A = \begin{array}{ccccccc}
 & & & & \mathfrak{su}(1)^{(1)} & & \\
 & & & & 2 & & \\
 & & & & | & & \\
 & & & & \mathfrak{su}(1)^{(1)} & & \\
 \mathfrak{e}_6 + A & = & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \dots & \mathfrak{su}(1)^{(1)} \\
 & & 2 & \text{---} & 2 & \text{---} & 2 \\
 & & & & \underbrace{\hspace{2cm}} & & \\
 & & & & 3 & &
 \end{array}
 \quad (4.264)$$

4.7 Rank 7

Applying \mathcal{S} on S_4 of

$$\begin{array}{ccccc}
 \mathbf{2}_0 & \xrightarrow{f} & \mathbf{3}_2^{2+2+2+2} & \xrightarrow{e} & \mathbf{4}_0 \\
 \begin{array}{c} 4e+f \\ | \\ e \end{array} & \begin{array}{c} f-x_i-y_i, f-z_i-w_i \\ | \\ f, f \end{array} & \begin{array}{c} y_i-w_i \\ | \\ 2 \\ | \\ f \end{array} & \begin{array}{c} h-\sum x_i-\sum z_i \\ | \\ x_1-y_2, x_2-y_1 \\ | \\ 2 \\ | \\ 2 \\ | \\ e \end{array} & \begin{array}{c} 2e+f \\ | \\ e-\sum x_i \\ | \\ e \end{array} \\
 \mathbf{1}_{10} & \xrightarrow{4} & & \xrightarrow{f, f} & \mathbf{5}_0^6 \\
 & & & & \begin{array}{c} | \\ e \\ | \\ e \end{array} \\
 & & & & \mathbf{6}_2 \\
 & & & & \begin{array}{c} | \\ e \end{array}
 \end{array} \tag{4.265}$$

leads to

$$\boxed{\mathfrak{so}(14) + \mathbf{S} + 6\mathbf{F} = \begin{array}{ccc} \mathfrak{su}(3)^{(2)} & \mathfrak{sp}(0)^{(1)} & \mathfrak{su}(6)^{(2)} \\ 3 & \text{---} 1 & \text{---} 2 \end{array}} \tag{4.266}$$

The isomorphism between

$$\begin{array}{ccccccc}
 \begin{array}{c} e-x \text{---} e-y \\ \cup \\ \mathbf{1}_0^{1+1} \\ | \\ f-x, x \\ | \\ 2 \\ | \\ f-y, y \\ | \\ \mathbf{2}_0^{1+1} \\ \cup \\ e-x \text{---} e-y \end{array} & & \begin{array}{c} e-x \text{---} e-y \\ \cup \\ \mathbf{7}_0^{1+1} \\ | \\ f-x, x \\ | \\ 2 \\ | \\ f-y, y \\ | \\ \mathbf{3}_0^{1+1} \\ \cup \\ e-x \text{---} e-y \end{array} & & \begin{array}{c} e-x \text{---} e-y \\ \cup \\ \mathbf{6}_0^{1+1} \\ | \\ f-y, y \\ | \\ 2 \\ | \\ f-x, x \\ | \\ \mathbf{5}_0^{1+1} \\ \cup \\ e-x \text{---} e-y \end{array} \\
 & \xrightarrow{2} & & \xrightarrow{2} & & \xrightarrow{2} & \\
 & \xrightarrow{f-x, x} & \xrightarrow{f-y, y} & \xrightarrow{f-x, x} & \xrightarrow{f-y, y} & \xrightarrow{f-x, x} & \xrightarrow{f-y, y}
 \end{array} \tag{4.267}$$

and

$$\begin{array}{ccccccc}
 \begin{array}{c} x \text{---} y \\ \cup \\ \mathbf{1}_0^{1+1} \\ | \\ e-y, f-x \\ | \\ 2 \\ | \\ e-x, f-y \\ | \\ \mathbf{2}_0^{1+1} \\ \cup \\ x \text{---} y \end{array} & & \begin{array}{c} x \text{---} y \\ \cup \\ \mathbf{7}_0^{1+1} \\ | \\ e-y, f-x \\ | \\ 2 \\ | \\ e-x, f-y \\ | \\ \mathbf{3}_0^{1+1} \\ \cup \\ x \text{---} y \end{array} & & \begin{array}{c} x \text{---} y \\ \cup \\ \mathbf{6}_0^{1+1} \\ | \\ e-x, f-y \\ | \\ 2 \\ | \\ e-y, f-x \\ | \\ \mathbf{5}_0^{1+1} \\ \cup \\ x \text{---} y \end{array} \\
 & \xrightarrow{2} & & \xrightarrow{2} & & \xrightarrow{2} & \\
 & \xrightarrow{e-y, f-x} & \xrightarrow{e-x, f-y} & \xrightarrow{e-y, f-x} & \xrightarrow{e-x, f-y} & \xrightarrow{e-y, f-x} & \xrightarrow{e-x, f-y}
 \end{array} \tag{4.268}$$

implies that

$$\begin{array}{c}
 \begin{array}{c}
 \text{su}(1)^{(1)} \\
 | \\
 2 \\
 | \\
 \text{su}(1)^{(1)} \quad \text{su}(1)^{(1)} \quad \text{su}(1)^{(1)} \quad \text{su}(1)^{(1)} \\
 | \quad | \quad | \quad | \\
 2 \quad \text{---} \quad 2 \quad \text{---} \quad 2 \quad \text{---} \quad \dots \quad \text{---} \quad 2 \\
 \underbrace{\hspace{10em}} \\
 4
 \end{array} \\
 \text{e}_7 + \text{A} =
 \end{array} \tag{4.269}$$

4.8 Rank 8

The isomorphism between

$$\begin{array}{c}
 \begin{array}{c}
 e-x \quad e-y \\
 \frown \\
 \mathbf{1}_0^{1+1} \\
 | \\
 f-x, x \\
 | \\
 2 \\
 | \\
 f-y, y \\
 | \\
 \mathbf{2}_0^{1+1} \\
 e-x \quad e-y \\
 \smile
 \end{array}
 \quad
 \begin{array}{c}
 e-x \quad e-y \\
 \frown \\
 \mathbf{8}_0^{1+1} \\
 | \\
 f-x, x \\
 | \\
 2 \\
 | \\
 f-y, y \\
 | \\
 \mathbf{3}_0^{1+1} \\
 e-x \quad e-y \\
 \smile
 \end{array}
 \quad
 \begin{array}{c}
 e-x \quad e-y \\
 \frown \\
 \mathbf{7}_0^{1+1} \\
 \xrightarrow{f-y, y} 2 \xrightarrow{f-x, x} \mathbf{6}_0^{1+1} \\
 | \\
 2 \\
 | \\
 f-y, y \\
 | \\
 \mathbf{4}_0^{1+1} \\
 e-x \quad e-y \\
 \smile
 \end{array}
 \quad
 \begin{array}{c}
 e-x \quad e-y \\
 \frown \\
 \mathbf{6}_0^{1+1} \\
 | \\
 f-y, y \\
 | \\
 2 \\
 | \\
 f-x, x \\
 | \\
 \mathbf{5}_0^{1+1} \\
 e-x \quad e-y \\
 \smile
 \end{array}
 \end{array}
 \tag{4.270}$$

and

$$\begin{array}{c}
 \begin{array}{c}
 x \quad y \\
 \frown \\
 \mathbf{1}_0^{1+1} \\
 | \\
 e-y, f-x \\
 | \\
 2 \\
 | \\
 e-x, f-y \\
 | \\
 \mathbf{2}_0^{1+1} \\
 x \quad y \\
 \smile
 \end{array}
 \quad
 \begin{array}{c}
 x \quad y \\
 \frown \\
 \mathbf{8}_0^{1+1} \\
 | \\
 e-y, f-x \\
 | \\
 2 \\
 | \\
 e-x, f-y \\
 | \\
 \mathbf{3}_0^{1+1} \\
 x \quad y \\
 \smile
 \end{array}
 \quad
 \begin{array}{c}
 x \quad y \\
 \frown \\
 \mathbf{7}_0^{1+1} \\
 \xrightarrow{e-x, f-y} 2 \xrightarrow{e-y, f-x} \mathbf{6}_0^{1+1} \\
 | \\
 2 \\
 | \\
 e-y, f-x \\
 | \\
 \mathbf{4}_0^{1+1} \\
 x \quad y \\
 \smile
 \end{array}
 \quad
 \begin{array}{c}
 x \quad y \\
 \frown \\
 \mathbf{6}_0^{1+1} \\
 | \\
 e-x, f-y \\
 | \\
 2 \\
 | \\
 e-y, f-x \\
 | \\
 \mathbf{5}_0^{1+1} \\
 x \quad y \\
 \smile
 \end{array}
 \end{array}
 \tag{4.271}$$

implies that

$$\begin{array}{c}
 \varepsilon_8 + A = \begin{array}{ccccccc}
 & & & & \mathfrak{su}(1)^{(1)} & & \\
 & & & & 2 & & \\
 & & & & | & & \\
 \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \mathfrak{su}(1)^{(1)} & \dots & \mathfrak{su}(1)^{(1)} & \\
 2 & \text{---} & 2 & \text{---} & 2 & \text{---} & 2 \\
 & & & & \underbrace{\hspace{1.5cm}} & & \\
 & & & & 5 & &
 \end{array}
 \end{array} \tag{4.272}$$

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