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Entanglement entropy, quantum fluctuations, and thermal entropy in topological phases

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ABSTRACT: Entanglement entropy in topologically ordered matter phases has been computed extensively using various methods. In this paper, we study the entanglement entropy of topological phases in two-spaces from a new perspective — the perspective of quasiparticle fluctuations. In this picture, the entanglement spectrum of a topologically ordered system encodes the quasiparticle fluctuations of the system, and the entanglement entropy measures the maximal quasiparticle fluctuations on the EB. As a consequence, entanglement entropy corresponds to the thermal entropy of the quasiparticles at infinite temperature on the entanglement boundary. We corroborates our results with explicit computation in the quantum double model with/without boundaries. We then systematically construct the reduced density matrices of the quantum double model on generic 2-surfaces with boundaries.

KEYWORDS: Topological States of Matter, Anyons, Topological Field Theories

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1 Introduction

Matter phases with intrinsic topological orders, or topological orders for short, are exotic, gapped phases of matter beyond the Landau-Ginzburg paradigm [1-7]. They not only have expanded our knowledge of phases of matter but also have important applications, including robust quantum memories and topological quantum computers [5, 8].

Topological orders exhibit long range entanglement [9, 10], which can be captured by the topological entanglement entropy (TEE) [7, 11] of the system. Suppose a (2 + 1)dimensional topologically ordered system is virtually divided into two regions A and B, the entanglement entropy (EE) of the system is the sum of an leading area term, proportional to the length of the boundary between the two regions, and a universal subleading term proportional to log D, where D is the total quantum dimension.¹ As such, TEE can be used to distinguish topological orders unless certain topological orders has the same total quantum dimension.

There has been extensive works computing the EE in topological orders [11-25]. In this paper, however, we propose a novel perspective of the EE in topological orders in two spatial dimensions, namely, the picture of quasiparticle fluctuations. Consider a bipartite system in a ground-state, e.g., as in figure 1(a). We show as one of our main results that the reduced density matrix ρ_A , i.e., the entanglement spectrum [26], is identified with the quasiparticle fluctuations on the entanglement boundary (EB) separating A and B, and the corresponding EE explicitly counts the allowed states describing quasiparticle fluctuations on the EB. We shall call such states EB-states. An EB-state is allowed when it ensures that no quasiparticles exist anywhere in the system except on the EB and that the total charge of the system and that of the EB are trivial. Hence, these quasiparticles cannot be seen by any global observer, say *Gabe*, of the system, as each of them is confined in a pair with its anti-quasiparticle on the other side of the EB. Such quasiparticle-antiquasiparticle pairs, which happen to be cut by the EB, comprise the quasiparticle fluctuations along the EB. We reckon that our notion of quasiparticle fluctuations complies with the usual notion of vacuum fluctuations in quantum field theory, which refers to that the vacuum consists of instantaneous particle-antiparticle pairs everywhere. Particles in vacuum fluctuations cannot be observed unless the particle-antiparticle pairs are torn apart locally by sufficient amount of energy.

Entanglement entropy counts the EB-states because of the following. To compute the EE, Gabe has to trace out region B. Tracing out region B would blind Alice from knowing the existence of region B at all. What Alice would see is a world like that in figure 1(b), complete darkness (no quasiparticles in the bulk) with a glowing physical boundary (quasiparticles residing on the boundary). Alice will detect quasiparticles at the EB, which now appears to her as a physical boundary.

Furthermore, Alice is able to measure the EB-states on the EB and find that they are all equally probable because the reduced density matrix ρ_A can be made a projector. She can then compute the thermal entropy (TE) of the boundary quasiparticle system at temperature $T = \infty$. This TE would coincide with the EE computed by Gabe. The infinite temperature can be thought as what offers the energy to tear apart the particle-antiparticle pairs at the EB.

To make the above picture of quantum fluctuations concrete and precise, we consider in particular the quantum double (QD) model of topological orders in two-spaces and

¹For a topologically ordered system with n type of anyons and d_i is the quantum dimension of the type-*i* anyons, $D = \sqrt{\sum_{i=1}^n d_i^2}$.



Figure 1. (a) is a system divided into regions A and B by a circular EB (in red). Tracing out region B in (a) is equivalent to (b), where there is only region A with a boundary decorated by quasiparticle fluctuation. The EE between A and B in (a) is equal to the TE of the quasiparticles on the boundary of A in (b).

focus on the ground-state Hilbert space of the model. The QD model [7, 27–30] is a lattice Hamiltonian extension of the Dijkgraaf-Witten gauge theory [31] with discrete gauge groups. We focus on ground-states because anyon excitations in topological orders add no more physical content to the EE.

In the QD model, we construct two useful types of bases — the holonomy bases and the fusion bases. The holonomy bases and fusion bases not only simplify the EE computation but also manifest the picture of quasiparticle fluctuations of EE. We compute the EE on a sphere in both bases, which leads to the same result, which agrees with the known result. This result corroborates our picture of quasiparticle fluctuations.

We then extend our study to topological orders with gapped physical boundaries (PBs), separating the system from the vacuum, as opposed to the EB separating two regions of the system. See figure 2. We consider the extended QD model [32, 33], dedicated to the scenario with PBs. With minor modifications, the holonomy and fusion bases work in this scenario, and hence the picture of quasiparticle fluctuations still applies. To be specific, we considered two representative cases, namely, a cylinder with region A being a meridian strip and a cylinder with region A being a longitudinal strip.² Using the holonomy and fusion bases, we offer closed-form formulae for the EE in both cases and an explicit example when the bulk gauge group is the permutation group S_3 . Such a formula in terms of the input data of the QD model has not been obtained before. We then systematically construct the reduced density matrices for topological orders on generic two-surfaces with gapped PBs.

We note that the EE on topological orders with PBs have also been computed recently on the extended QD model [22], and by using conformal field theory techniques [34–38] related to our holonomy-basis approach via boundary anyon condensation [39, 40]. It would be interesting to investigate more on the relations between these works and ours.

We reckon that the fusion bases we construct are related to the fusion bases used in a recent work studying the generalized anyon exclusion statistics [41, 42]. Hence, we expect

²The directions are defined as in the Mercator projection.



Figure 2. Physical boundary (PB) and entanglement boundary (EB).

to relate the EE in topological orders to the generalized anyon exclusion statistics. This expectation is reasonable because exclusion statistics is bound to the notion of thermal entropy. We shall leave this connection for future studies.

This paper is organized as follows. Section 2 reviews the QD model and develops the holonomy bases. Section 3 constructs the fusion bases and explains the picture of quasiparticle fluctuations. Section 4 studies the cases with PBs, with a concrete example for $G = S_3$. Section 5 discusses certain subtleties. The appendices collect certain calculations too detailed to be part of the main text.

2 Quantum double model and holonomy bases

In this section, we shall discuss the minimal and complete set of observables in a lattice topological gauge field theory. We will also discuss the relation between the gauge fields and these observables. This relation will enable us to study the entanglement from the perspective of observables.

We define a discrete gauge field theory on a 2D directed graph, with a finite gauge group G. The degrees of freedom (d.o.f.) are group elements on the edges. The Hilbert space is spanned by all possible configurations of these group elements on the edges. We identify the two states,

$$\left| + \stackrel{g}{\longrightarrow} \right\rangle \equiv \left| + \stackrel{g^{-1}}{\longrightarrow} \right\rangle, \tag{2.1}$$

where on the r.h.s. the group element is inversed and the arrow on the edge is reversed. For simplicity and illustration, we show only four-valent vertices but in general the spatial graph could contain any multivalent vertex.

Then we define a gauge transformation at a vertex v by

$$A_v^h \bigg| \underbrace{\stackrel{d}{\longrightarrow} c}_{a \ b} \bigg\rangle = \bigg| \underbrace{\stackrel{hd}{\longrightarrow} hc}_{hb} \bigg\rangle, \qquad (2.2)$$

which is a left multiplication of h on the edges coming into the vertex v.

A lattice gauge theory is defined by a Hamiltonian that commutes with any gauge transformation on the lattice. The quantum double (QD) model, also known as the Kitaev model [7], is such a lattice gauge theory, whose Hamiltonian reads

$$H = -\sum_{v} A_v - \sum_{p} B_p, \qquad (2.3)$$

where A_v is a projection operator

$$A_v = \frac{1}{|G|} \sum_{g \in G} A_v^g, \tag{2.4}$$

which projects onto states with gauge invariance at vertex v. The other operator B_p is an projection operator

$$B_p \left| \begin{array}{c} a \\ \bullet \\ \bullet \\ \bullet \\ d \end{array} \right\rangle = \delta_{abcd} \left| \begin{array}{c} a \\ \bullet \\ \bullet \\ \bullet \\ d \end{array} \right\rangle, \qquad (2.5)$$

where $\delta_{abcd} = 1$ if abcd = 1, the unit element of G, and $\delta_{abcd} = 0$ otherwise. Here abcd is the *holonomy* around the plaquette p. Hence, B_p projects onto states with trivial holonomy at p.

In particular, when $G = \mathbb{Z}_2$ (known as the toric code model), the Hilbert space is spanned by spins on the edges, and the Hamiltonian terms are

$$A_v = \prod_{e \text{ into } v} \sigma_e^x, \quad B_p = \prod_{e \text{ around } p} \sigma_e^z, \tag{2.6}$$

where *e* represent the edges. Indeed, compared to eq. (2.2), $\prod_{e \text{ into } v} \sigma_e^x$ is (the non-identity) \mathbb{Z}_2 gauge transformation with the \mathbb{Z}_2 represented by $\{1, \sigma^x\}$. The delta function in eq. (2.5) becomes $\frac{1}{2} \left(1 + \prod_{e \text{ around } p} \sigma_e^z\right)$.

2.1 Observables

Since all the operators A_v and B_p commute with each other, they form commuting observables of the toric code model, and their common eigenvectors form the basis states of the Hamiltonian. As a results, there is a \mathbb{Z}_2 charge excitations at a vertex v in a state $|\psi\rangle$ if $A_v |\psi\rangle = -|\psi\rangle$, and a \mathbb{Z}_2 flux excitation at a plaquette p if $B_p |\psi\rangle = -|\psi\rangle$. The name "charge" and "flux" can be justified by the Aharonov-Bohm effect as follows.

For a given edge e, the σ_e^z serves as the hopping operator that moves the charge from one end v_1 of e to the other end v_2 because $A_{v_{1,2}}\sigma_e^z |\psi\rangle = -\sigma_e^z A_{v_{1,2}} |\psi\rangle$. Hence, being the tensor product of σ^z around the plaquette p, B_p moves a charge around p by one turn and measures the \mathbb{Z}_2 flux in the plaquette p. The names "charge" and "flux" thus follow.

On a torus, The minimal and complete set of commuting observables (also called the set of stabilizers) of the toric code model is given by

$$A_1, A_2, \dots, A_{V-1}, B_1, B_2, \dots, B_{P-1}, Z_1, Z_2,$$
(2.7)

where V is the total number of vertices, and P the total number of plaquettes. The two operators A_V and B_P are excluded from the above set because of the two global constraints

$$\prod_{v=1}^{V} A_v = 1, \quad \prod_{p=1}^{P} B_p = 1.$$
(2.8)



Figure 3. (a) is a configuration of group elements on the edges of a graph, where trivial holonomy conditions $a_4a_3 = a_2a_1$ and $a_7a_5 = a_6a_4$ are assumed. (b) shows a non local transformation. The big dot (the lower-left vertex in (a)) is chosen as the base point. A path is chosen from the base point to every other vertex v in (a). These paths are graced with the new degrees of freedom defined in eq. (2.9). The explicit transformation consists of $g_1 = a_1$, $g_2 = a_2a_1$, $g_3 = a_3, g_4 = a_5a_3$, and $g_5 = a_7a_5a_3$. Such a transformation from the a's to g's is clearly invertible.

The operators Z_1 and Z_2 are the products of σ^z along two arbitrary, non-contractible loops, one meridian and one longitudinal, of the torus. These two operators clearly measure the \mathbb{Z}_2 fluxes going through the two holes of the torus (as seen in 3D space); they are responsible for the corresponding Aharonov-Bohm phases.

We arrive at two bases of the Hilbert space. One is spanned by the spins on all the edges, while the other is given by the simultaneous eigenvectors of the operators in eq. (2.7). The latter corresponds to three types of physical quantities in a electromagnetic theory: Z_2 electric field strengths, magnetic field strengths, and Aharanov-Bohm phases due to nontrivial spatial topology. This establishes a duality between the observables and the gauge fields. We call the Aharonov-Bohm phases the topological d.o.f.

2.2 Holonomy bases: a non-local transformation

The above duality between the gauge fields and observables can be also made precise in the QD model of a generic group G. For our purposes in this paper, we focus on the states with trivial holonomy, i.e., $B_p = 1$, everywhere. That is, we restrict ourselves to the subspace $\mathcal{H}^{B_p=1}$ of the total Hilbert space of the QD model.

We define a non-local transformation as follows. First, we pick an arbitrary vertex v_0 as the base point and choose a path on the graph from v_0 to v, for any other vertex v. Second, Given a configuration of the group elements a_e on all the edges satisfying the trivial holonomy condition, we assign to each vertex $v \neq v_0$ a new group element

$$g_v := \prod_{e \in p_{vv_0}} a_e, \tag{2.9}$$

where p_{vv_0} is the path chosen from v to v_0 . If the space has a non-contractible loop C_{α} , we also assign a g_{α} — the product of the group elements along a C_{α} to C_{α} . This way, we get a non-local transformation:

$$\{a_e\} \cong \{g_v; g_\alpha\}_{v \neq v_0}.$$
 (2.10)

Such a transformation is illustrated in figure 3.



Figure 4. A basis of Hilbert space on torus, labeled by eigenvalues of A_v , (v = 1, 2, ..., V - 1), and Z_1 , Z_2 defined along the two non-contractible loops C_1 , C_2 .. There is a base vertex shown as dot in the diagram. The gauge charge at vertex each vertex v is formulated by the product of group elements along a path between the base point and v.

For the quantum double model on a torus, g_{α} are the holonomies along the two noncontractible cycles. See illustration in figure 4. In particular in toric code model case, they corresponds to the operators Z_1 and Z_2 .

The non-local transformation above defines a new basis of $\mathcal{H}^{B_p=1}$, $\{|g_v; g_\alpha\rangle\}$, which we call a *holonomy basis*, as inspired by ref. [43]. In a holonomy basis, an operator $A_{v\neq v_0}$ acts as

$$A_{v}|g_{1},\ldots,g_{v},\ldots,g_{V-1};g_{\alpha}\rangle = \frac{1}{|G|}\sum_{h}|g_{1},\ldots,hg_{v},\ldots,g_{V-1};g_{\alpha}\rangle, \qquad (2.11)$$

and A_{v_0} acts as

$$A_{v_0} |g_1, \dots, g_{V-1}; g_\alpha \rangle = \frac{1}{|G|} \sum_h \left| g_1 h^{-1}, \dots, g_{V-1} h^{-1}; h g_\alpha h^{-1} \right\rangle.$$
(2.12)

3 Fusion basis and the quasiparticle picture of entanglement

In this section, we propose a new picture of the entanglement between the two parts of a bipartite topologically-ordered system. In this picture, we can compute the entanglement entropy by counting the configurations of quasiparticles on the boundary between the two parts that divide the system. We thus christen this new picture the *quasiparticle picture*. We shall continue our study using the QD model.

Given a bipartite system, a state is entangled if it is not a tensor product of the states of the two subsystems. Entanglement entropy is a quantity that measures how much the two subsystems are entangled.

For a given state ψ in a bipartite system, the entanglement entropy is defined as

$$S_E = -\mathrm{tr}\rho_A \log \rho_A,\tag{3.1}$$

where $\rho_A = \operatorname{tr}_B |\psi\rangle \langle \psi|$ is the reduced density matrix. As such, the EE also measures one's ignorance of subsystem *B*, whose d.o.f. are traced out. One may also choose to trace out subsystem *A* but S_E is independence of such choices. In this paper, we focus on the EE in the ground states of the QD model.



Figure 5. Configuration of charge d.o.f. for the ground state of quantum double model on a sphere. There is a base point in each subsystem, with v_A in A and v_B in B respectively.

3.1 Entanglement entropy on a sphere in a holonomy basis

To motivate the quasiparticle picture and understand how the EE is computed in the new picture, let us reexamine a well-studied case, namely, the EE of the QD model with a finite group G on a sphere. In this case, the ground state is unique up to local unitary transformations, with trivial charge and zero flux everywhere on the sphere. This makes a holonomy basis handy for our computation of the EE.

We virtually cut the sphere along an EB into a bipartite system. We would like to express the ground-state condition explicitly in terms of the charge d.o.f. on the EB. Doing this will manifest the contribution of quasiparticle fluctuations near the partition boundary to the EE and enable us to write down the reduced density matrix.

As illustrated in figure 5, we choose a base point $v_A(v_B)$ in subsystem A(B). We assume that the EB consists of L vertices. Since as far as the ground-state is concerned we can restrict the system to the subspace in which $B_p = 1$ everywhere, plus the sphere has no non-contractible cycles, the non-local transformation (2.10) would trade the original d.o.f. on the lattice edges for the new d.o.f. on the paths linking the base points to the vertices on the EB. There should be two base points, one in subsystem A and one in B. Otherwise, if there is just one base point chosen, say, in A, then there must be a path between any two neighbouring vertices on the EB, rendering all paths being closed. But $B_p = 1$ everywhere, all such closed paths must be trivial, making no sense.

Consequently, for each vertex on the EB, we have a charge d.o.f. g_v in A and g'_v in B. A ground state should be gauge invariant at each v, and has zero holonomy everywhere. The latter condition reads

$$g_1'^{-1}g_1 = g_2'^{-1}g_2 = \dots = g_L'^{-1}g_L.$$
 (3.2)

In terms of the new set of variables, the Hilbert space is spanned by the basis states $|g_1, \ldots, g_L; g'_1, \ldots, g'_L\rangle$. To obtain the ground state on the sphere, we can pick any basis state and act on it by all the vertex operators $A_{v\neq v_0}$ and A_{v_0} , which will project the basis state to a ground state. That is, pick a generic $|g_1, \ldots, g_L; g'_1, \ldots, g'_L\rangle$, then by eqs. (2.11)

and (2.12), we have

$$A_{v_{A}}A_{v_{B}}\prod_{v=1}^{L}A_{v}\left|g_{1},\ldots,g_{L};g_{1}',\ldots,g_{L}'\right\rangle$$

$$=\sum_{h_{1},\ldots,h_{L}}\sum_{h_{A},h_{B}}\left|h_{1}g_{1}h_{A}^{-1},\ldots,h_{L}g_{L}h_{A}^{-1};h_{1}g_{1}'h_{B}^{-1},\ldots,h_{L}g_{L}'h_{B}^{-1}\right\rangle$$

$$=\sum_{\tilde{g}_{1},\ldots,\tilde{g}_{L},h}\left|\tilde{g}_{1}h,\ldots,\tilde{g}_{L}h;\tilde{g}_{1},\ldots,\tilde{g}_{L}\right\rangle,$$
(3.3)

where $\tilde{g}_i := h_i g'_i h_B^{-1}$ and $h := h_B g'_1^{-1} g_1 h_A^{-1}$. The second equality above is due to the trivial holonomy condition after the action of the vertex operators, namely,

$$h_i g_i h_A^{-1} = h_i g'_i h_B^{-1} (h_B g'_{i+1}^{-1} g_{i+1} h_A^{-1}) = \tilde{g}_i (h_B g'_1^{-1} g_1 h_A^{-1}) = \tilde{g}_i h,$$

where the second equality is due to the trivial holonomy condition (3.2) before acting the vertex operators. By renaming \tilde{g}_i back to g_i again, we have a ground state

$$|\Phi\rangle = \sum_{g_1,\dots,g_L,h} |g_1h,\dots,g_Lh;g_1,\dots,g_L\rangle$$
(3.4)

$$=\sum_{g_v,h} |g_v h; g_v\rangle, \qquad (3.5)$$

where the second row follows the first row by an obvious suppression of indices. One can check that $|\Phi\rangle$ is indeed a ground state.

Since g_v are the d.o.f. in region B, while $g_v h$ are the d.o.f. in region A, the form of $|\Phi\rangle$ is manifestly Schmidt-decomposed. Hence, the reduced density matrix ρ_A is

$$\rho_A = \frac{1}{|G|^2} \sum_{g_v, h, h'} \left| g_v h \right\rangle \left\langle g_v h' \right|.$$
(3.6)

We check that ρ_A is a projection operator

$$\rho_A \rho_A = \frac{1}{|G|^4} \sum_{g_v,h,h'} \sum_{\bar{g}_v,\bar{h},\bar{h}'} |g_v h\rangle \langle \bar{g}_v \bar{h}'| \langle g_v h' | \bar{g}_v \bar{h} \rangle$$

$$= \frac{1}{|G|^4} \sum_c \sum_{g_v,h,\bar{h}'} |g_v h\rangle \langle g_v c^{-1} \bar{h}'| \sum_{\bar{g}_v,\bar{h},h'} \delta_{\bar{g}_v^{-1} g_v,c} \delta_{\bar{h}h'^{-1},c}$$

$$= \rho_A.$$
(3.7)

The normalization factor $\frac{1}{|G|^2}$ in eq. (3.6) is chosen such that ρ_A is exactly a projector. Note that since ρ_A must represent a mixed state, if ρ_A can be made a projector, it means that all probable pure-states are equally weighted in ρ_A . This leads to $S_E = -\text{tr}(\rho_A \log \rho_A) = \log \text{tr}\rho_A$. Now that

W := tr
$$\rho_A = \frac{1}{|G|^2} \sum_{g_v, h, h'} \delta_{h, h'} = |G|^{L-1},$$
 (3.8)

and the EE computes as

$$S_E^{\text{sphere}} = \log W = (L-1)\log|G|. \tag{3.9}$$

This result agrees with the known result (See for example ref. [22]). In the above we defined a quantity $W := \text{tr}\rho_A$. Clearly, Since all probable pure-states are equally weighted, W is simply the number of probable pure-states. The questions are, what are these pure states and how we may interpret them? To answer the questions, it would be better to Fourier transform the holonomy bases into what we call the fusion bases.

3.2 Fusion bases

We have just derived the reduced density matrix and computed the corresponding EE of the QD model on a sphere. This is done in a holonomy basis proposed in section 2.2. In the holonomy basis, the d.o.f. in either region A or B all live on the EB separating the two regions, and the d.o.f. in A and those in B group into entangled pairs, as seen in eq. (3.5). This observation complies with the common sense that the entanglement between two regions actually occurs only near the EB between the two regions. It is also often said that the entanglement entropy measures the ignorance of an observer in region A (B) about region B (A). The computation in the holonomy basis not only manifests this common sense but also infers a new picture of entanglement, in which the ignorance can be made concrete in terms of the quasiparticle fluctuations on the EB. Imagine an observer in A. Tracing out region B means that the observer in A is completely refrained from knowing the existence of B, instead, the observer senses a boundary of A, which is the EB that now appears physical to the observer in A. Tracing out B must leave certain residue on the EB. Recall that the entire system is in a ground state and that the total state (3.5), which is pure, is Schmidt decomposed in the holonomy basis as superposed entangled pairs. Since now the observer in A cannot see region B at all, he would likely see quasiparticle excitations on the EB. These excitations are paired up with those as appeared to an observer in region B blinded from seeing region A, such that the entire system remains in a ground state. In the QD model, however, (G-charge type) quasiparticle excitations are better expressed in a basis not in terms of the group elements but in terms of the representations of the gauge group. As to be seen shortly, such a basis is a Fourier transform of the holonomy basis. Hence, what the observer in A sees would not be a single type of quasiparticles but in fact a mixed state of all possible quasiparticle states on the EB. In other words, the observer sees quasiparticles fluctuating on the EB.

In the following, we will apply the non-local transformation (2.10) and rewrite the reduced density matrix in terms of quasiparticle d.o.f..

We shall Fourier transform the holonomy basis in terms of group elements to one in terms of the irreducible representations of the gauge group. We label the charges by the irreducible representations. This will result in a more transparent picture of the quasiparticle fluctuations near the EB.

Define

$$|jmn\rangle = \sqrt{\frac{d_j}{|G|}} \sum_{g \in G} \overline{\rho_{mn}^j(g)} |g\rangle , \qquad (3.10)$$

where j labels the unitary irreducible representations of G, and mn are matrix indices of the representations. The inverse transformation reads

$$|g\rangle = \sqrt{\frac{d_j}{|G|}} \sum_{jmn} \rho_{mn}^j(g) |jmn\rangle.$$
(3.11)

The above is the transformation on a state labeled by a single group element. The two transformations are unitary and inverse to each other, as can be proved by Peter-Weyl theorem in group representation theory. A state on the right hand side of the above equation can be regarded as a quasiparticle carrying the charge labeled by the irreducible representation. In the state (3.5), however, the holonomy basis consists of a chain of group elements for each of the two regions. Each such chain which would be transformed as in eq. (3.11), resulting in a tensor product of states labeled by irreducible representations. The tensor product can be interpreted as the fusion of a chain of charge quasiparticles, leading naturally to a fusion basis $|j_v m_v; \eta\rangle$ of the states, depicted as follows.

where η labels the set of d.o.f. on the internal lines. These d.o.f. are intermediate quasiparticles in fusing of L quasiparticles. See appendix A for the definition and the derivation of the fusion basis.³ In general, for a given chain of charge quasiparticles $j_v m_v$, there are multiple configurations η of the intermediate quasiparticles. The number of such configurations is the dimension of the corresponding Hilbert space.

Note that the fusion basis (3.12) shows that the quasiparticles on the EB must all fuse to be a trivial charge. That is, the total quasiparticle charge of region A including the EB is trivial. In fact, the reduced density matrix (3.6) is an identity matrix on all quasiparticle d.o.f. on the EB, combined with the projection P_G ,

$$\rho_A = P_G\left(\sum_{g_v} |g_v\rangle \langle g_v|\right) P_G = P_G \mathbb{1} P_G = P_G, \qquad (3.13)$$

where P_G is the average of right multiplication on all g_v by h. It enforces a G-symmetry. This global symmetry is a consequence of gauge invariance condition at the base point in A, which requires the total charge of all quasiparticles in A to be trivial. The global G-symmetry can be viewed as the broken gauge symmetry due to the appearance of the EB. As a result, the nonzero eigenspace of ρ_A are the space of all states of quasiparticles on EB that are invariant under this global G-symmetry. The η is nothing but a set of good quantum numbers of this global symmetry.

In the fusion basis, eq. 3.6 becomes

$$\rho_A = \sum_{j_v m_v, \eta} |j_v m_v; \eta\rangle \langle j_v m_v; \eta|, \qquad (3.14)$$

 $^{^{3}}$ We note that such a basis was adopted in understanding the entanglement entropy in lattice gauge theories by one of us in ref. [19].

where η, η' label the fusion basis with $j_v m_v$ fixed. Since the Fourier transform cannot prevent ρ_A being a projector, the EE remains

$$S_E = \log W, \tag{3.15}$$

where W is the dimension of the space spanned by the fusion basis. Directly counting the number of the basis vectors yields

$$W = \sum_{j_{v}} d_{j_{1}} \dots d_{j_{L}} \sum_{\eta_{1}, \dots, \eta_{L-1}} N_{0}^{j_{1}\eta_{1}} N_{\eta_{1}}^{j_{2}\eta_{2}} \dots N_{\eta_{L-1}}^{j_{L}0}$$

=
$$\sum_{\eta_{1}, \dots, \eta_{L-1}} d_{0} d_{\eta_{1}}^{2} \dots d_{\eta_{L-1}}^{2} d_{0}$$

= $|G|^{L-1},$ (3.16)

where use of $\sum_{j} N_{l}^{jk} d_{j} = d_{k} d_{l}$ is made in the second equality, and $j_{1} (j_{L})$ is renamed to $\eta_{1} (\eta_{L-1})$. See appendix A for more details. This result agrees with the previous result (3.8) obtained in the holonomy basis. This alternative derivation however has a deeper meaning, as we now elaborate on.

3.3 Entanglement measures quasiparticle fluctuations

The fusion-basis derivation in the previous subsection manifests a picture of entanglement in view of quasiparticle fluctuations. In this picture, we are able to answer the questions raised in the end of section 3.1.

In the language of gauge field theory, the ground state(s) of QD model satisfy two conditions — zero charge everywhere and zero flux everywhere. These two conditions determine the nonzero eigenspace of ρ_A , which can be spanned by the holonomy basis or the fusion basis developed in the previous subsections. In the following, we analyze the consequence of these two conditions on the charge d.o.f. g_v and g'_v on the EB.

Zero-flux condition requires the charge d.o.f. on both sides of the EB to be paired up to a global symmetry, as concluded in eq. (3.2). Here, we can imagine that the EB is fattened a bit to be a narrow strip. In figure 5, this requires $g_v = g'_v h$ for some constant hat all vertices v on the EB. We shall consider the global symmetry on these charge d.o.f. later and let us ignore the constant h at this moment. Locally, charges appear in pairs (and the pair goes across the fattened EB) at each vertex on the EB. We say that the charge quasiparticles in an EB-state satisfy the:

boundary matching condition :
$$g_v = g'_v$$
, (3.17)

at all vertices v on the EB.

Zero-charge condition has two consequences. First, at each vertex v on the EB, charge pairs appear with equal weight. That is, locally, the ground state must read as $\sum_{g} |g\rangle_A \otimes$ $|g\rangle_B$ because it is the only state invariant under gauge transformations at v. Hence, at each v on the EB, the ground state locally reads as

equal-weight charge pair :
$$\sum_{g_v} |g_v\rangle_A \otimes |g_v\rangle_B$$
. (3.18)

The equal-weight charge pairs leads to a picture of quasiparticle fluctuations. A quasiparticle fluctuation is a charge pair across the EB. By the equal-weight condition (3.18), in the fusion basis these quasiparticles $j_v m_v$ (as well as their fusion multiplicity d.o.f. η) are paired across the EB. When the system is partitioned into two regions by the EB, however, local observers in a A (in a mixed state ρ_A) can detect quasiparticles with equal probability on the EB. Our picture coincides with the quantum fluctuation in a vacuum state of a quantum field theory, which refers to a particle-antiparticle pair locally excited by an amount of energy. In our case, no actual energy is injected into the system, and a global observer (in a pure state $|\Phi\rangle$) cannot detect any quasiparticles anywhere because all quasiparticles on one side of the EB are confined with their counterparts on the other side.

Second, the gauge-invariance condition at the base point of region A imposes a global symmetry, implemented by the P_G in eq. (3.13). All states $|g_v\rangle_A$ in A ought to be invariant under the global right-multiplications over G. This global symmetry can be viewed as the broken gauge symmetry in A. Since as appeared to a local observer in A the EB is a PB, this gauge symmetry breaking is understood as due to the charge condensation on the EB [44, 45].

To sum up, the ground state(s) of the QD model meet three conditions on the EB: the boundary matching condition, equal-weight local charge pairs, and a global symmetry P_G .

The advantage of the holonomy bases is that the d.o.f. are well allocated into two regions. By "well" we mean that all the three conditions on the ground state(s) are inherited by the EB states of region A(B). In the following, we reexamine the three conditions from the eyes of the observers within A.

In the sphere case, the reduced density matrix ρ_A is a projector, implying that the considered ground state $|\Phi\rangle$ admits a Schmidt decomposition:

$$|\Phi\rangle = \sum_{i=1}^{W} |\Psi_i\rangle_A \otimes |\Psi_i\rangle_B.$$
(3.19)

The states $|\Psi_i\rangle_A$ ($|\Psi_i\rangle_B$) are defined in region A (B), rendering the total state $|\Psi\rangle$ explicitly an entangled state, as if region A lies in a particular $|\Psi_i\rangle_A$, region B has to be in the state $|\Psi_i\rangle_B$ indexed by the same i. Seen from the fusion-basis expression of the reduced density matrix (3.14), $|\Psi_i\rangle_A = |j_v m_v; \eta\rangle$, where the index i is a set of labels ($j_{v=1,...,L}, m_{v=1,...,L}; \eta$) specifying a particular fusion-basis state. In a state $|\Psi_i\rangle_A$, region A has no quasiparticles everywhere except on the EB a particular configuration (e.g. (3.12)) of charge quasiparticles $j_v m_v$ with fixed internal d.o.f. labeled by η . Since the actual d.o.f. in region A are the quasiparticles residing on the EB, we may abuse our terminology to call a $|\Psi_i\rangle_A$ an EBstate of region A. The elaboration above applies to region B too.

Now let us adapt our analysis of the ground states to that of EB states $|\Psi_i\rangle_A$. The boundary matching condition (3.17), together with the equal weight condition (3.18) on chair pairs, implies that all possible charge quasiparticles will appear with equal probability on the EB in A. In the sphere case, this leads to that each of the W basis-states $|\Psi_i\rangle_A$ is equally probable.

The EB-states $|\Psi_i\rangle_A$ form a basis of all allowed states (in A) of the charge quasiparticles on EB. We summarize EB conditions on the EB states of region A (B) as follows.



Figure 6. Schmidt decomposition of the ground state $|\Phi\rangle = \sum_i |\Psi_i\rangle_A \otimes |\Psi_i\rangle_B$. The entire system is divided into regions A and B. The entangled EB-states $|\Psi_i\rangle_A (|\Psi_i\rangle_B)$ are defined for A (B). Each EB-state specifies a configuration of charge quasiparticles on the EB. The EB-states of A and those of B must match, such that the total state of the entire system is a ground state.

- 1. They ensure that region A(B) has no quasiparticles except on the EB.
- 2. Locally, charge quasiparticles appear with equal probability everywhere on the EB.
- 3. If there are non-contractible loops in region A (B), the holonomy along these loops is unit element of G.
- 4. The total quasiparticle charge of either the entire region A or B is trivial, i.e., the quasiparticles in each allowed EB-state must fuse to be a trivial charge in either A or B.

Condition 3 is due to the special choice of the ground state which has trivial holonomy along these non-contractible loops. In general, if we choose other ground states $|\Phi'\rangle$, we should modify this condition such that any observable \hat{O} along these non-contractible loops in region A(B) should evaluates to the same value in $|\Psi_i\rangle_A(|\Psi_i\rangle_B)$ and in $|\Phi'\rangle$.

Condition 4 may look somehow odd at first glance that we require a global symmetry in A and one in B at the same time. We need both since they are the broken gauge symmetries in A and in B. In the sphere case, the two global symmetries coincide with P_G but in general they may differ as the spatial topology of the system becomes more complicated. We shall see such example in the next section and will discuss about this condition in more details in section 4.3.

Eq. (3.19) reads as a boundary matching condition upon gluing regions A and B along the EB, such that the total state $|\Psi\rangle$ is a ground state that is free of quasiparticles everywhere.

Therefore, the EB-states of A and those of B are what are being entangled, as they are paired up. They are maximally entangled because all the EB-states are equally probable in the Schmidt decomposition. This physical picture is illustrated in figure 6.

In terms of quasiparticles, the entanglement entropy entropy can be interpreted as a measurement of quasiparticle fluctuations. Quasiparticles on one side of the fattened EB are paired with their counterparts on the other side, and "paired" means "entangled". In fact, such pairing is the only contribution to the entanglement entropy, as we can see in the formula $S_E = \log W$, which counts how many states of such quasiparticles are allowed on the EB. The fact that charge quasiparticles appear with equal probability on the EB is a consequence of a equilibrium state in region A with maximal quasiparticle fluctuations across the EB. We say an equilibrium state has "maximal quasiparticle fluctuations" if the energy threshold to excite any charge pairs on the EB becomes zero. (A ground state is an eigenvector of $A_v = 1$ and reads locally as a superposition of equal-weight charge pairs as in eq. (3.18). The partial trace $\operatorname{tr}_B A_v$ becomes an identity operator, implying that quasiparticles on the EB can be excited without energy penalty as seen by the observers in A.) Hence we conclude:

> Entanglement spectrum corresponds to all possible states with quasiparticle fluctuations on the EB, and Entanglement entropy measures maximal quasiparticle fluctuations on the EB.

In other words, entanglement entropy $S_E = \log W$ counts the number of entangled EB-states of regions A and B. To compute S_E amounts to the problem of state-counting W of the EB states satisfying the EB conditions.

The above statement can also be formulated purely in terms of the energy eigenstates on the sphere regardless of the bipartition. From the ground state $|\Phi\rangle$ on the sphere, we generate a subspace $\{\hat{W} | \Phi \rangle\}$, where \hat{W} represents the creation operator that creates charge pairs on any two neighboring vertices on the EB. We then conclude that the nonzero eigenspace of $\rho_A = \text{tr}_B(|\Phi\rangle \langle \Phi|)$ becomes effectively such generated subspace, whose dimension becomes the W in $S_E = \log W$. To be discussed in the next section, however, on a more generic surface with gapped boundaries and/or multiple disconnected EB components, ρ_A may no longer be a projector due to the gapped PB conditions.

The EE (3.9) consists of a leading area term $L \log |G|$ and a universal subleading term $-\log |G|$. The leading term results from the fact that there are L vertices on the EB where quasiparticle pairs are allowed, and that there are |G| types of quasiparticle pairs at each vertex (in either basis $|g\rangle$ or $|jmn\rangle$). The universal subleading term $-\log |G|$ results from the global symmetry imposed by P_G in eq. (3.13), which demands that the quasiparticle fluctuations across the EB should preserve this global symmetry. The result agrees with our previous observation that the nonzero eigenspace of $\rho_A = P_G$ is the space of all the states of quasiparticles on the EB that are invariant under the global G-symmetry.

3.4 2D entanglement entropy = 1+1D thermal entropy

The physical picture described above also demonstrates a correspondence between the EE and thermal entropy (TE). Suppose the total system is in a ground-state $|\Phi\rangle$. A local observer restricted in A sees no existence of region B but can measure the charge quasiparticles on the EB. The observer finds that there are W equally probable quasiparticle configurations on the EB. Under the micro-canonical ensemble assumption, he computes the TE of the quasiparticle system on the EB as $\log W$. This result coincides with the EE we, as a global observer of the total system, obtained earlier. The local observer in region A certainly does not know that the TE was a consequence of a hidden region B but thought it was due to the quasiparticle fluctuation on the EB (a physical boundary as appeared to the observer). Note that the TE should be understood as one at infinite temperature because at $T = \infty$, all the quasiparticle configurations contribute to the partition function equally. We believe that the above correspondence in the sphere case can be generalized to a generic surface with non-trivial topology. If the total system is (may be in a mixed

state due to topological ground state degeneracy) at zero temperature, and we compute ρ_A , then there exists certain effective Hamiltonian on the EB such that

$$\rho_A = \lim_{T \to \infty} e^{-H_{\rm EB}/T}.$$
(3.20)

The $H_{\rm EB}$ is the effective Hamiltonian that causes the quantum fluctuations, and preserves the global symmetry broken from the gauge symmetries in A and B. The infinite temperature agrees with our conclusion that the region A is in equilibrium with maximal fluctuations on the EB. This may be related to the program of modular flows (see ref. [46] and references therein).

4 Topological orders with gapped physical boundaries

So far we have studied topological orders on closed two-spaces. Nevertheless, in reality, materials fabricated to bear topological orders usually have PBs. In particular, non-chiral topological orders, which can be studied by lattice Hamiltonian models, have gapped PBs between the system and the vacuum. It is therefore important to extend our study to the cases with physical boundaries. To this end, we consider the extended QD model with gapped boundaries [32, 33], which were developed to handle such cases. In this model, the bulk d.o.f. still take value in a finite gauge group G, while the d.o.f. on each PB take value in certain subgroup K of G. It is said that the PB is characterized by K. Our holonomy bases and fusion bases naturally extend to such cases, and the picture of quasiparticle fluctuations still applies. To be specific, in what follows, we consider two representative cases, seen in figure 7 and figure 8. The former is a cylinder with region A being a meridian strip, and the latter is a cylinder with region A being a longitudinal strip.

4.1 Cylinder case I

Consider the extended QD model on the cylinder in figure 7(a). The model is defined by a QD Hamiltonian in the bulk with gauge group G, and by a boundary Hamiltonian [33] on PBs specified by two subgroups K_1 and K_2 of G. The subgroup K_1 (K_2) dictates the gapped PB condition on the top (bottom) PB of the cylinder. Topological GSD occurs in general on a cylinder. As to be specified below, we will focus on only one particular ground state, which bears no non-contractible anyon loops.

Similar to the case on a sphere, we choose a base point $v_A(v_B)$ in A(B). Since trivial holonomy is assumed everywhere, we only need to consider the d.o.f. on the EB, which is a disjointed union of two vertical line segments, each with two end vertices respectively on the top and bottom PBs. See figure 7(b) for an illustration.

By a derivation similar to that for the ground state on a sphere, we can find one particular ground state (out of many others), which does not have any non-contractible loops, as

$$|\Phi\rangle_{\rm cyl} = \sum_{g_v, h, h' \in G, k_1, k_3 \in K_1, k_2, k_4 \in K_2} \left| k_u h, g_v h; k_u h', g_v h' \right\rangle, \tag{4.1}$$

where v labels the bulk vertices on the EB, and u = 1, 3 (u = 2, 4) label the vertices on the intersections of the upper (lower) PB and EBs. One can verify the K_1, K_2 -gauge



Figure 7. A bipartite system on a cylinder. (a) Region A is within the thick loop. (b) Configurations of group elements in the ground state chosen. The dash lines are the EBs. We take $k_1, k_3 \in K_1$ and $k_2, k_4 \in K_2$. We place the k's and g's in one region and their duplicates in the other, as a consequence of trivial holonomy condition.

invariance at the PB vertices u and G-gauge invariance at v. Hence, $|\Phi\rangle_{cyl}$ is indeed a ground state. Explicitly, the state is obtained by applying average (bulk and boundary) gauge transformations everywhere on the state with k_u, g_v set to be 1.

As in the sphere case, the ground state $|\Phi\rangle_{cyl}$ is manifestly Schmidt decomposed; hence, the reduced density matrix is readily

$$\rho_A = \sum_{g_v,h,h' \in G, k_1, k_3 \in K_1, k_2, k_4 \in K_2} \left| k_u h, g_v h \right\rangle \left\langle k_u h', g_v h' \right|, \tag{4.2}$$

Similar as in the sphere case, one can show that ρ_A is a projector multiplied by a normalization factor. Direct calculation leads to a normalized reduced density matrix

$$\bar{\rho}_A = \frac{1}{|G||K|} \rho_A,\tag{4.3}$$

where $K = K_1 \cap K_2$, satisfying

$$\bar{\rho}_A \bar{\rho}_A = \bar{\rho}_A, \quad \text{tr} \bar{\rho}_A = W = \frac{|G|^L |K_1|^2 |K_2|^2}{|K|},$$
(4.4)

where L is the total number of bulk vertices on the EB. The EE is

$$S_E = \log W = \log \frac{|G|^L |K_1|^2 |K_2|^2}{|K|}.$$
(4.5)

See appendix B for the detailed evaluation. Despite in this case the holonomy basis (4.1) has already made the EE computation simple, we would still like to write down the fusion basis as follows to manifest the picture of quasiparticle fluctuations.

4.1.1 The fusion basis

By examining eq. (4.2) and (4.4), we can extract a picture of quasiparticle fluctuations. As illustrated in figure 7, The EB intersects PB at the four vertices labeled by u. The reduced density matrix consists of two projectors. One projector is

$$P_0 = \sum_{k_u, g_v} |k_u, g_v\rangle \langle k_u, g_v|, \qquad (4.6)$$

which projects onto the subspace where we assign $k_1, k_3 \in K_1$ on the upper PB and $k_2, k_4 \in K_2$ on the lower PB. At other vertices on the EB, we assign group elements $g_v \in G$. The other projector is an average of global right-multiplications:

$$P_G = \sum_{g_u, g_v, h \in G} |g_u h, g_v h\rangle \langle g_u, g_v|$$
(4.7)

The reduced density matrix is a combination:

$$\rho_A = P_G P_0 P_G. \tag{4.8}$$

This formula is similar to that in the sphere case, where the identity matrix in eq. (3.13) is replaced by the projector P_0 . As suggested by the projector P_0 , a good fusion basis should be constructed in terms of the irreducible representations of K_1, K_2 at the four vertices uand the irreducible representations of G at the other vertices v. The projector P_G enforces a global right-multiplication symmetry, which leads to a fusion tree structure similar to eq. (3.12). To be clear, we draw the fusion basis as

$$p_{2x_{2}} p_{4x_{4}} j_{1}m_{1} j_{2}m_{2} \qquad j_{L}m_{L} \quad p_{1x_{1}} p_{3x_{3}}$$

$$(4.9)$$

where p_1, p_3 (p_2, p_4) label the irreducible representations of K_1 (K_2) , and the *j*'s are those of *G*. The *x*'s and *m*'s are the internal indices of the corresponding representations. Residing on the two big dots are the unitary transformations $U_{p,\alpha}^j$, defined in eq. (D.2), that decompose *G* representations to $K_{1,2}$ representations. On internal lines and trivalent vertices are the invariant tensor basis as defined in eq. (A.3), for K_1, K_2 , and *G* respectively.

It is more complicated to solve the eigen-problem of ρ_A in such fusion basis than in the holonomy basis. One complexity is that such fusion basis is not orthogonal with respect to the d.o.f. at the two big dots (in terms of $U_{p,\alpha}^{j}$). (These dots are $K_{1,2}$ -morphisms but not *G*-morphisms, and hence are not invariant under P_G .) We will not detail the computation of EE in such fusion basis.

The entanglement entropy in eq. (4.5) consists of two terms,

$$S_E = S_0 + S_1, (4.10)$$

with the leading area term

$$S_0 = L \log |G| + 2 \log |K_1| + 2 \log |K_2|, \tag{4.11}$$

where L is the length of the EB in the bulk, i.e., the number of bulk vertices on the EB. The latter two terms reflects the contribution of quantum fluctuations at the four vertices at the intersections of the EBs and the PBs. Each such vertex on the top (bottom) PB allows $|K_1|$ ($|K_2|$) types of quasiparticles. The subleading term is

$$S_1 = -\log|K|,\tag{4.12}$$

as a consequence of the global G-symmetry on all quasiparticles on the EB (including the four intersection points).



Figure 8. A bipartite system on a cylinder. (a) Region A is bounded by the thick line. (b) Configurations of group elements for a ground state. The dash lines are the two EBs. The group elements $k_1 \in K_1$, $k_2 \in K_2$, and $g_v, g'_v, h \in G$. We place the k's and g's in one region and their duplicates in the other, as a consequence of trivial holonomy condition.

4.2 Cylinder case II

We consider another bipartite system on a cylinder as in figure 8(a). The extended QD model is the same as in the cylinder case I, where the bulk gauge group is G, and the top and bottom PB conditions are characterized by subgroups K_1 and K_2 of G. Again we will focus on only one particular ground state to be specified below.

Since region B now has two disjoint components, we will choose the base points in a way slightly different from that in the previous case. We pick two base points in region B, with v_{B1} on the top PB and v_{B2} on the bottom PB. See figure 8(a). The d.o.f. to specify a ground state are shown in figure 8(b).

The ground state of our concern takes the form

$$|\Phi\rangle = \sum_{k_1 \in K_1, k_2 \in K_2, g_v, g'_v, h \in G} |g_v h, g'_v h; g_v k_1, g'_v k_2\rangle.$$
(4.13)

The reduced density matrix is

$$\rho_{A} = \operatorname{tr}_{B} |\Phi\rangle \langle\Phi|
= \sum_{g_{v},g'_{v},h,\bar{h}} \sum_{c_{1}\in K_{1},c_{2}\in K_{2}} |g_{v}h,g'_{v}h\rangle \langle g_{v}c_{1}h',g'_{v}c_{2}\bar{h}|
\times \sum_{\bar{g}_{v},\bar{g}'_{v},k_{1}k_{2}\bar{k}_{1}\bar{k}_{2}} \delta_{g_{v}^{-1}\bar{g}_{v},c_{1}} \delta_{k_{1}\bar{k}_{1}^{-1},c_{1}} \delta_{g'_{v}^{-1}\bar{g}'_{v},c_{2}} \delta_{k_{2}\bar{k}_{2}^{-1},c_{2}}.$$
(4.14)

which evaluates as (up to a normalization factor)

$$\rho_A = \sum_{k_1 \in K_1, k_2 \in K_2, g_v, g'_v, h, h' \in G} \left| g_v h, g'_v h \right\rangle \left\langle g_v k_1 h', g'_v k_2 h' \right|$$
(4.15)

In particular when G is Abelian, ρ_A can be normalized to be a projector

$$\bar{\rho}_A = \frac{1}{|G|^2 |K_1| |K_2|} \rho_A, \quad \bar{\rho}_A \bar{\rho}_A = \bar{\rho}_A, \tag{4.16}$$

with trace being

$$W := \operatorname{tr}\bar{\rho}_A = \frac{|G|^{L-1}|K|}{|K_1||K_2|},\tag{4.17}$$

where $K = K_1 \cap K_2$. See appendix C for the detailed computation. The EE in the Abelian case is thus

$$S_E = \log W = \log \frac{|G|^{L-1}|K|}{|K_1||K_2|},$$
(4.18)

which agrees with the result in ref. [22].

In the non-Abelian case, we need some more tricks to obtain a closed-form formula of the EE. We leave the analytic computation in the fusion basis to the next subsection.

4.2.1 The fusion basis

We see that ρ_A is a projector. We also see that ρ_A is gauge invariant at all of the base points chosen, in kets and bras respectively. These facts imply all four conditions on the EB-states are fulfilled. In this subsection, we analyze the entanglement in the picture of quasiparticle fluctuations using the fusion basis.

Let

$$R_{g_1,g_2} = \sum_{g_v,g'_v} \left| g_v g_1, g'_v g_2 \right\rangle \left\langle g_v, g'_v \right|$$
(4.19)

be the right-multiplication acting on g_v and g'_v by g_1 and g_2 . Define two projectors

$$P_G = \frac{1}{|G|} \sum_{g \in G} R_{g,g} \tag{4.20}$$

$$P_{K_1} = \frac{1}{|K_1|} \sum_{k_1 \in K_1} R_{k_1,1}, P_{K_2} = \frac{1}{|K_2|} \sum_{k_2 \in K_2} R_{1,k_2}.$$
 (4.21)

Then the reduced density matrix can be written as

$$\rho_A = P_G P_{K_1 K_2} P_G, \tag{4.22}$$

where $P_{K_1K_2} = P_{K_1}P_{K_2}$. If we traced out region A, we would get

$$\rho_B = P_{K_1 K_2} P_G P_{K_1 K_2}. \tag{4.23}$$

The projectors impose the global constraints in the bulk and on the PB respectively. The P_G projects onto the states with zero charge in bulk, while P_{K_1} and P_{K_2} projects onto the states with zero boundary $k_{1,2}$ charge at each boundary component.

We now try to find the eigenvectors of ρ_A . First consider the effect of P_G . Let us take a fusion basis, as obtained in eq. (3.12):

where we divide the labels j_1m_1, \ldots, j_Lm_L into two sets, with the d.o.f. on the upper (lower) EB all on the left (right) hand side of η_0 . Between these two parts there is one

internal line labeled by η_0 , an irreducible representation of G. The combined projector $P_{K_1K_2}$ is a projection on η_0 and contribute a factor

$$N_{\eta_0} = \frac{1}{|K_1||K_2|} \frac{1}{\dim_{\eta_0}} \sum_{k_1k_2} \chi_{\eta_0}(k_1k_2), \qquad (4.25)$$

Which satisfies

$$\sum_{\eta_0} d_{\eta_0}^2 N_{\eta_0} = |G| / |K_1 K_2|.$$
(4.26)

The eigenvalues are N_{η_0} , whose degeneracies are calculated in a way similar to that in eq. (3.16),

$$W_{\eta_0} = \sum_{j_v} d_{j_1} \dots d_{j_L} \sum_{\substack{\eta_1, \dots, \hat{\eta_0}, \dots, \eta_{L-1} \\ \eta_1, \dots, \hat{\eta_0}, \dots, \eta_{L-1}}} N_0^{j_1 \eta_1} N_{\eta_1}^{j_2 \eta_2} \dots N_{\eta_{L-1}}^{j_L 0}$$

$$= \sum_{\substack{\eta_1, \dots, \hat{\eta_0}, \dots, \eta_{L-1} \\ = |G|^{L-2} d_{\eta_0}^2} d_0$$
(4.27)

where $\hat{\eta}_0$ in the sum means that η_0 is a fixed label and is not summed.

The trace evaluates as

$$W = \operatorname{tr}(\rho_A) = \sum_{\eta_0} W_{\eta_0} N \eta_0 = \frac{|G|^{L-1}}{|K_1 K_2|}.$$
(4.28)

The normalized eigenvalues are then $\lambda_{\eta_0} = N_{\eta_0}/W$ with degeneracy W_{η_0} , and hence the EE computes as

$$S_{E} = -\sum_{\eta_{0}} W_{\eta_{0}} \lambda_{\eta_{0}} \log \lambda_{\eta_{0}}$$

= $-\sum_{\eta_{0}} W_{\eta_{0}} \frac{N_{\eta_{0}}}{W} \log \frac{N_{\eta_{0}}}{W}$
= $\log W - \sum_{\eta_{0}} \frac{d_{\eta_{0}}^{2} |K_{1}K_{2}|}{|G|} N_{\eta_{0}} \log N_{\eta_{0}}.$ (4.29)

The EE again contains two terms, $S_E = S_0 + S_1$, with the leading area term $S_0 = L \log |G|$ and a subleading term

$$S_1 = -\log|G| - \log|K_1K_2| - \sum_{\eta_0} \frac{d_{\eta_0}^2 |K_1K_2|}{|G|} N_{\eta_0} \log N_{\eta_0}, \qquad (4.30)$$

as a consequence of three mutually un-commuting symmetries: P_G acting on all quasiparticles and $P_{K_1}(P_{K_2})$ acting on the quasiparticles on the upper (lower) EB.

This closed-form formula is a novel result, which has not been obtained in other works on the EE of the QD model. In a recent work [22], a numeric result of the EE in this case for $G = S_3$, $K_1 = \{1, 4\}$, and $K_2 = \{1\}$ was given. Let us now verify as an example that our formula (4.1) yields the same numeric result. In this example, we have

$$N_1 = 1, N_2 = 0, N_3 = 1/2.$$
 (4.31)



Figure 9. (a) An open surface with boundaries. The thick lines are the EBs that separate the system into two regions A and B. The five PBs are specified by the subgroups K_1, K_2, K_3, K_4 , and K_5 of G. (b) The subspaces with group elements $k_1, k_2 \in K_1$, $k_3, k_4 \in K_2$, and $k_5, k_6 \in K_3$, and G elements g_v and g'_v assigned to the EBs.

See appendix E for S_3 and its representations. Eq. (4.1) quickly leads to

$$S_E = \log |G|^{L-1} - \frac{1}{3}\log 2, \qquad (4.32)$$

which is precisely the result in ref. [22].

When G is Abelian, N_{η} is either 0 or 1 (as can be directly verified from the definition in eq. (4.25)). Hence the last term in eq. (4.30) vanishes, recovering the result (4.18).

4.3 Generic cases

We have discussed the picture of quasiparticle fluctuations in two representative cases on a cylinder; however, this picture is valid on more generic surfaces. We will summarize some typical features of the previous analysis and then extend them to a generic surface. For example, consider an open surface with PBs as illustrated in figure 4.3. We do not consider any genus in the bulk because we always choose a particular ground state such that the global (topological) d.o.f. will not affect our computation. Specifically, we choose a ground state in which the holonomy along all non-contractible loops are the unit element of G, which makes any genus invisible in the holonomy bases.

Let us try to construct the reduced density matrices on generic surfaces. We can see that the reduced density matrices (3.13), (4.8), and (4.22) all are a combination of three types of projectors. The first type includes projectors due to the boundary conditions on the PBs, such as the P_0 in eq. (4.6), projecting all group elements at the intersection of PBs and EBs into the characterizing subgroups for PBs. (This type of projectors also depends on the choice of the ground state but we have already restricted to ground states without anyon loops throughout the paper.) The other two types are due to the gauge symmetries in regions A and B respectively, such as the P_G and $P_{K_1K_2}$ in eq. (4.22), where G is the gauge group in A, and K_1 (K_2) is the gauge group of the top (bottom) PBs in B.

These observations comply with the four conditions on the EB in section 3.3. Now we may formulate these conditions mathematically by writing down a generic form of the reduced density matrix. Keep figure 9 in mind as an example, we itemize the rules to write down the reduced density matrix:

1. The first projector projects onto a subspace with only K_1 , K_2 and K_3 d.o.f. at all intersections between EBs and PBs, and assigns *G*-elements elsewhere. In this example, it is written as

$$P_{0} = \sum_{k_{1}k_{2} \in K_{1}, k_{3}k_{4} \in K_{2}, k_{5}k_{6} \in K_{3}} \left| k_{u}, g_{v}, g_{v}' \right\rangle \left\langle k_{u}, g_{v}, g_{v}' \right|, \qquad (4.33)$$

where u = 1, 2, ..., 6.

2. Suppose region B has a number of disconnected components. For any disconnected component that contains a PB characterized by K, we write down a projector as the average over K of the right-multiplications acting on the EBs that are a part of the boundary of this disconnected component. For a disconnected component that does not contain any PB, we write down the projector P_G . (For simplicity, we do not consider the case with multiple PBs contained within each component of B) In the current example, B has two disconnected components, and the projectors are

$$P_{K_4} = \sum_{l \in K_4} \left| lg_u, lg_v, g'_v \right\rangle \left\langle g_u, g_v, g'_v \right|, \qquad (4.34)$$

and

$$P_{K_{5}} = \sum_{l \in K_{5}} \left| g_{u}, g_{v}, lg'_{v} \right\rangle \left\langle g_{u}, g_{v}, g'_{v} \right|.$$
(4.35)

Since these projectors are due to the global symmetry in region B, we combine them as the projector

$$P_B = P_{K_4} P_{K_5}. (4.36)$$

3. Repeat the second step also for all disconnected components of A. In the current example, we have

$$P_A = P_G = \sum_{h \in G} \left| hg_u, hg_v, hg'_v \right\rangle \left\langle g_u, g_v, g'_v \right|.$$

$$(4.37)$$

4. We finally combine all the projectors and obtain

$$\rho_A = P_A P_B P_0 P_B P_A. \tag{4.38}$$

This form of ρ_A is a consequence of the four conditions on EB-states. Conditions 1, 2, and 3 allow equal-probable configurations of charge quasiparticles on the EB. Hence, we arrive at the P_0 in eq. (4.3). Under condition 4, the two global symmetry constraints in A and B implies two projection operators P_A in eq. (4.37) and P_B in eq. (4.36). Combining all four conditions we arrive at the formula for ρ_A in eq. (4.38).

Before explaining how we combine the projectors P_0 , P_A and P_B in such a way to get ρ_A , let us figure out how the observers in A would view their world when B is traced out.



Figure 10. Observers in region A (B is traced out) think all PBs and EBs are physical boundaries.

They cannot distinguish a PB from an EB but think all the PBs and EBs are physical boundaries of their world. See figure 10. By Condition 4 on EB-states, we have a global symmetry acting on the EB d.o.f. due the broken gauge symmetry in B. The resulting global symmetry is implemented by P_B . Observers in A cannot understand why they can observe such a global symmetry on a boundary that was an EB because they are blinded from B. In this way, the projector P_B encodes how the topology and PBs of B may affect the EB-states observed in A.

There is another global symmetry acting on the EBs. Combining the already existing PB conditions (characterized by K_1 , K_2 , and K_3) and the effective boundary conditions (expressed as P_B) on the EBs, the gauge symmetry in A also breaks into a global symmetry, now imposed by P_A . The above interpretation of P_A and P_B enables us to write down the combination of the projections in the order in eq. (4.38).

We may choose to trace out region A instead and get

$$\rho_B = P_B P_A P_0 P_A P_B, \tag{4.39}$$

in which the order of projectors accords with the above interpretation of the projectors.

Since P_A and P_B do not commute, $\rho_A \neq \rho_B$. The nonzero eigenspaces of ρ_A and ρ_B are not identical. This is reasonable because the regions A and B have different spatial topologies and different PB conditions. The local observers in A and B can distinguish such differences in the EB-states. For example, local observers will find the constraint (4.25) on the fusion basis (4.24) in Cylinder case II, and find the constraint on the dotted part in fusion basis (4.9). Nevertheless, the EE computed from ρ_A and that from ρ_B out to be equal.

4.3.1 The disk case

As a simple example, we apply our generic formula (4.38) to the disk case. We consider the extended QD model a disk as in figure 11(a). The bulk gauge group is G, and the PB is specified by a subgroup K of G. The system is bipartite by an EB (solid circle in the figure). The ground state on the disk is unique, as to be specified below.

The d.o.f. would be g_v for all v on the EB. The global symmetries would be $P_A = P_G$ being the average of right-multiplications over G on g_v for all v, and $P_B = P_K$ over K. Hence the reduced density matrix ρ_A is

$$\rho_A = P_G P_K \mathbf{1} P_K P_G = P_G. \tag{4.40}$$



Figure 11. A bipartite system on a disk. Region A is bounded by the thick line. The PB condition is characterized by a subgroup K of G.

In the second equality we have used $P_G P_K = P_K P_G = P_G$. Hence the entanglement spectrum and entropy are the same as those in the sphere case.

5 Discussions

In this paper, we always choose a ground state in which there are no non-contractible anyon loops. In the sphere case, certainly there are no such loops anyway but on a cylinder, there may be because a topological order on a cylinder may have ground state degeneracy [33, 47, 48]. In general, we can choose an arbitrary ground state, with or without non-contractible anyon loops. In such cases, while the analysis and the main result will remain unaffected, we would need to slightly extends the four conditions on the entangled EB-states. Moreover, one may also consider topological orders with excited anyons, i.e., not in ground states. This would not affect the physics of EE, although special cares may be needed for defining the entangled EB-states. We shall leave such cases for future work.

In this paper, each EB accommodates only the quasiparticles that are pure charges. The reason is that each EB is composed of consecutive edges of the lattice; hence, the boundary condition is specified by G itself. This boundary condition corresponds to the smooth boundary condition on the PBs in the extended QD model [19, 32, 33]. Under the smooth boundary condition, the gapped boundary is a consequence of condensing all the flux quasiparticles on the PB, such that the gapped quasiparticle excitations on the PB are charges only. The correspondence between our EB and flux condensation on the PB of the extended QD model is more transparent to Alice, the local observer in region A, to whom the EB is effectively a PB. There are other choices of EBs, on which the quasiparticles are either pure fluxes, dyons, or of mixed types. According to ref. [19], the TEE of topological orders is independent of the choice of EB. We thus do not consider other choices of EBs here. Moreover, in ref. [39], the authors computed the EE between two different topological orders separating by a gapped domain wall by treating the domain as the EB. Since the gapped domain wall is a result of anyon condensation on the wall, the correspondence between our EBs and anyon condensation is natural.

Although our study was done for the (extended) QD model only, we believe our results can be extended to other models of topological phases, such as the twisted quantum double model [29, 33], the Levin-Wen model [6, 48–51] in two dimensions, and the twisted gauge theory model in three dimensions [52, 53]. In such extensions, however, the dimension of group representations should be extended to the quantum dimensions of the anyons. The latter is more general measure in the modular tensor category theories — the general algebraic theory of quasiparticles. We shall leave the generalization for future work.

It is an open question that can we, and to what extent, generalize our result to more systems, including gapped and gapless systems. Recently there are already efforts [54–57] trying to link particle number fluctuations to the entanglement entropy, mostly in gapless systems.

A Fusion basis in the sphere case

We have used the fusion bases to represent the EB-states. Here we provide a concrete definition of the fusion bases. We define a fusion basis by

$$|j_1 m_1, j_2 m_2, \dots, j_L m_L; \eta\rangle := \sum_{n_1, n_2, \dots, n_L} T^{\eta}_{j_1 n_1, j_2 n_2, \dots, j_L n_L} |j_1 m_1 n_1, j_2 m_2 n_2, \dots, j_L m_L n_L\rangle,$$
(A.1)

where $T^{\eta}_{j_1m_1,j_2m_2,...,j_Ln_L}$ is a tensor transforming under irreducible representations of G:

$$\sum_{n'_i} \rho^{j_i}_{n_i n'_i} T^{\eta}_{j_1 n_1, j_2 n_2, \dots, j_i n'_i, \dots, j_L n_L} = T^{\eta}_{j_1 n_1, j_2 n_2, \dots, j_i n_i, \dots, j_L n_L}.$$
(A.2)

This generalizes the Wigner-Eckart tensors with arbitrary number of pairs jn. The index η labels a normal basis of such tensors such that the contraction of tensors satisfy

$$T^{\eta} \cdot \overline{T^{\eta'}} = \delta_{\eta\eta'}, \tag{A.3}$$

and

$$\sum_{\eta} T^{\eta}_{j_1 m_1, j_2 m_2, \dots, j_L m_L} \overline{T^{\eta}_{j_1 n_1, j_2 n_2, \dots, j_L n_L}} = \delta_{m_1 n_1} \delta_{m_2 n_2} \dots \delta_{m_L n_L}.$$
(A.4)

From the group representation theory, such T^{η} can be constructed as contractions of L-3 3*j*-symbols (for L > 3)

$$T_{j_1m_1,\dots,j_Lm_L}^{\eta_1,\dots,\eta_{L-3}} = \sum_{x_1,\dots,x_{L-3}} C_{m_1m_2x_1}^{j_1j_2\eta_1} C_{x_1m_3x_2}^{\eta_1^*j_3\eta_2} \dots C_{x_{L-3}m_{L-1}m_L}^{\eta_{L-3}^*j_{L-1}j_L},$$
(A.5)

where we label η by a set of irreducible representations $\eta_1, \ldots, \eta_{L-3}$ of G.

By the above construction, we simply present the fusion basis (A.1) graphically as

B Reduced density matrix in cylinder case I

We show that the ρ_A (4.2) is a projector up to a normalization factor. We have

$$\rho_{A}\rho_{A} = \sum_{\substack{g_{v},h,h'\in G, \\ k_{1},k_{3}\in K_{1}, \\ k_{2},k_{4}\in K_{2}}} \sum_{\substack{\bar{g}_{v},\bar{h},\bar{h}'\in G, \\ \bar{k}_{1},\bar{k}_{3}\in K_{1}, \\ \bar{k}_{2},\bar{k}_{4}\in K_{2}}} |k_{u}h,g_{v}h\rangle\langle\bar{k}_{u}h',g_{v}h'| \langle k_{u}\bar{h},g_{v}\bar{h}|\bar{k}_{u}\bar{h}',\bar{g}_{v}\bar{h}'\rangle \\
= \beta \sum_{\substack{g_{v},h,h'\in G, \\ k_{1},k_{3}\in K_{1}, \\ k_{2},k_{4}\in K_{2}}} |k_{u}h,g_{v}h\rangle\langle k_{u}h',g_{v}h'| \\
= \beta\rho_{A}.$$
(B.1)

Here, the constant factor β is

$$\beta = \sum_{\substack{\bar{g}_v, \bar{k}_1, \bar{k}_3, \\ \bar{k}_2, \bar{k}_4, \bar{h}, \bar{h}'}} \sum_{c \in K} \delta_{c, \bar{h}\bar{h}'}{}^{-1} \delta_{c, \bar{g}_v g_v^{-1}} \delta_{c, \bar{k}_u k_u^{-1}} \\ = \sum_{\bar{h} \in G} \sum_{c \in K} 1 \\ = |G||K|,$$
(B.2)

where c runs over $K = K_1 \cap K_2$. To see the second equality above, we note that for example,

$$\begin{split} \sum_{c \in G} \sum_{\bar{k}_{u}} \delta_{c, \bar{k}_{u} k_{u}^{-1}} &= \sum_{c \in G} \sum_{\bar{k}_{1}, \bar{k}_{2} \in K_{1}, \bar{k}_{3}, \bar{k}_{4} \in K_{2}} \delta_{c, \bar{k}_{1} k_{1}^{-1}} \delta_{c, \bar{k}_{2} k_{2}^{-1}} \delta_{c, \bar{k}_{3} k_{3}^{-1}} \delta_{c, \bar{k}_{4} k_{4}^{-1}} \\ &= \sum_{c \in K} \sum_{\bar{k}_{1}, \bar{k}_{2} \in K_{1}, \bar{k}_{3}, \bar{k}_{4} \in K_{2}} \delta_{c, \bar{k}_{1} k_{1}^{-1}} \delta_{\bar{k}_{1} k_{1}^{-1}, \bar{k}_{3} k_{3}^{-1}} \delta_{\bar{k}_{2} k_{2}^{-1}, \bar{k}_{3} k_{3}^{-1}} \delta_{\bar{k}_{2} k_{2}^{-1}, \bar{k}_{3} k_{4}^{-1}} \\ &= \sum_{c \in K} \sum_{\bar{k}_{1}, \bar{k}_{2} \in K_{1}, \bar{k}_{3}, \bar{k}_{4} \in K_{2}} \delta_{\bar{k}_{1}, ck_{1}} \delta_{\bar{k}_{2}, ck_{2}} \delta_{\bar{k}_{3}, ck_{3}} \delta_{\bar{k}_{4}, ck_{4}} \\ &= \sum_{c \in K} 1, \end{split}$$

which also constrains $c \in K$. We can evaluate the trace of the projection operator $\beta^{-1}\rho_A$:

$$W := \operatorname{tr}(\beta^{-1}\rho_A) = \frac{|G|^L |K_1|^2 |K_2|^2}{|K|},$$
(B.3)

where L is the total number of bulk vertices (those not on PB) of the EB. Hence the EE:

$$S_E = \log W = \log \frac{|G|^L |K_1|^2 |K_2|^2}{|K|}.$$
(B.4)

C Reduced density matrix in cylinder case II

We show that the ρ_A (4.2) is a projector up to a normalization factor when the gauge group G is Abelian. We have

$$\rho_{A}\rho_{A} = \sum_{k_{1}k_{2}g_{v},g'_{v},h,h'} \sum_{\bar{k}_{1}\bar{k}_{2}\bar{g}_{v},\bar{g}'_{v},\bar{h},\bar{h}'} |g_{v}h,g'_{v}h\rangle\langle\bar{g}_{v}\bar{k}_{1}\bar{h}',\bar{g}'_{v}\bar{k}_{2}\bar{h}'|\langle g_{v}k_{1}h',g'_{v}k_{2}h'|\bar{g}_{v}\bar{h},\bar{g}'_{v}\bar{h}\rangle$$

$$= \sum_{\substack{k_{1}k_{2}g_{v},\\g'_{v},h,h'}} \sum_{\bar{k}_{1}\bar{k}_{2}} \sum_{c\in G} |g_{v}h,g'_{v}h\rangle\langle\bar{g}_{v}\bar{k}_{1}\bar{h}',\bar{g}'_{v}\bar{k}_{2}\bar{h}'|\delta_{\bar{h}h'^{-1},c}\delta_{\bar{g}_{v}^{-1}g_{v},ck_{1}^{-1}}\delta_{\bar{g}'_{v}^{-1}g'_{v},ck_{2}^{-1}}$$

$$= \sum_{g_{v},g'_{v},h,k_{1}k_{2},h',\bar{k}_{1}\bar{k}_{2},\bar{h}'} |g_{v}h,g'_{v}h\rangle\langle g_{v}k_{1}h'\bar{k}_{1}\bar{h}',g'_{v}k_{2}h'\bar{k}_{2}\bar{h}'|.$$
(C.1)

When G is Abelian, we can define a projector

$$\bar{\rho}_A = \beta^{-1} \rho_A, \tag{C.2}$$

with the constant factor

$$\beta = \sum_{\bar{k}_1, \bar{k}_2, \bar{h}'} 1 = |G|^2 |K_1| |K_2|.$$
(C.3)

We can evaluate the trace of the projector $\beta^{-1}\rho_A$:

$$W = \operatorname{tr}(\bar{\rho}_A) = \frac{1}{|G|^2 |K_1| |K_2|} \sum_{k_1, k_2, g_v, g'_v, h, h'} \delta_{h, k_1 h'} \delta_{h, k_2 h'} = \frac{|G|^{L-1} |K|}{|K_1| |K_2|}, \quad (C.4)$$

where L is the total number of vertices on the EB. The EE in the Abelian case then is

$$S_E = \log W = \log \frac{|G|^{L-1}|K|}{|K_1||K_2|}.$$
(C.5)

D Some useful identities

Let G be a finite group and K a subgroup of G. Denote by $\{j\}$ all unitary irreducible representations of G, and by $\{p\}$ those of K respectively. Denote the representation matrices by $\rho^{j}(g)$ and $R^{p}(k)$ for $g \in G$ and $k \in K$ respectively.

Obviously any representation j of G is automatically a (not necessarily irreducible) representation of K and can be decomposed into a direct sum of certain irreducible representations of K, namely,

$$j = \oplus_p N_p^j p. \tag{D.1}$$

More precisely, the decomposition means that there exists a unitary transformation U^j rendering $U^j \rho^j(k) U^{j\dagger}$ a direct sum of $R^p(k)$ for certain p's. The multiplicities N_p^j count the numbers $R^p(k)$ appearing in the direct sum. We write $U^j \rho^j(k) U^{j\dagger} = \bigoplus_p N_p^j R^p(k)$. It may be useful to write down U^j more explicitly:

$$\rho^{j}(k) = \sum_{p} \sum_{\alpha \in N_{p}^{j}} U_{p,\alpha}^{j} R^{p}(k) U_{p,\alpha}^{j}$$
(D.2)

and

$$U_{p,\alpha}^{j}U_{p',\alpha'}^{j} \stackrel{\dagger}{=} \delta_{j,j'}\delta_{\alpha,\alpha'}\mathrm{id}_{p}.$$
 (D.3)

Equation (D.2) is presented graphically as

The multiplicities N_p^j compute as

$$N_p^j = \frac{1}{|K|} \sum_{k \in K} \operatorname{tr} \rho^j(k) \overline{\operatorname{tr} R^p(k)}.$$
 (D.5)

Equation (D.2) leads to a useful identity:

$$\frac{1}{|K|} \sum_{k \in K} \rho_{mn}^{j}(k) \overline{\rho_{m'n'}^{j'}(k)} = \sum_{p} \frac{1}{d_p} \sum_{\alpha\beta} (U_{p\alpha}^{j} {}^{\dagger}U_{p\beta}^{j'})_{m'm} (U_{p\beta}^{j'} {}^{\dagger}U_{p\alpha}^{j})_{nn'}.$$
(D.6)

E Examples

In section 4.2.1, we computed as an example the EE in cylinder case II when $G = S_3$. Here, we explain some basic setup for S_3 and its representations.

Denote the group elements of S_3 by $g = 1, \ldots, 6$, with the generators 2, 4 satisfying $2 \cdot 2 \cdot 2 = 1, 4 \cdot 4 = 1$, and $4 \cdot 2 \cdot 4 = 2 \cdot 2$. Denote the rest by $3 = 2 \cdot 2, 5 = 2 \cdot 4$, and $6 = 2 \cdot 5$.

The group S_3 has three irreducible representations. A representative set of the irreducible representations is

$$g = 1 \qquad g = 2 \qquad g = 4$$

$$\rho^{1}(g) \quad \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\rho^{2}(g) \quad \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \begin{pmatrix} -1 \\ 2 \\ -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} \\ -\frac{1}{2} \end{pmatrix} \quad \begin{pmatrix} \frac{1}{2} \\ \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} \\ -\frac{1}{2} \end{pmatrix}$$
(E.1)
$$(E.1)$$

The representation matrices for other group elements can be obtained by the group multiplications. In this setting, eq. (4.31) was obtained by direct computation.

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