

Free Boundary Problem for the Equation of Spherically Symmetric Motion of Viscous Gas (III)

Šárka MATUŠŮ-NEČASOVÁ*†, Mari OKADA†† and Tetu MAKINO††

†*Mathematical Institute, Academy of Sciences,
Czech Republic, Žitná 25, 115 67 Praha 1,
Czech Republic*

††*Department of Applied Science,
Faculty of Engineering, Yamaguchi University,
Ube 755, Japan*

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We study the spherically symmetric motion of viscous barotropic gas surrounding a solid ball. We are interested in the density distribution which contacts the vacuum at a finite radius. The equilibrium is asymptotically stable with respect to small perturbation, provided that $\gamma > \frac{4}{3}$ and a is sufficiently small, when the equation of state is $p = a\rho^\gamma$, p being the pressure and ρ the density.

Key words: Navier-Stokes equation, asymptotic stability of equilibria, free boundary problem, spherically symmetric motion

We are investigating the equations

$$\begin{cases} \frac{\partial \rho}{\partial t} + u \frac{\partial \rho}{\partial r} + \rho \frac{\partial u}{\partial r} + \frac{2}{r} \rho u = 0, \\ \rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial r} \right) + \frac{\partial p}{\partial r} = \nu \left(\frac{\partial^2 u}{\partial r^2} + \frac{2}{r} \frac{\partial u}{\partial r} - \frac{2}{r^2} u \right) - \frac{\rho M}{r^2}, \\ p = a\rho^\gamma, \end{cases}$$

where ν , a , γ are positive constants and $1 < \gamma \leq 2$. These equations govern the spherically symmetric motion of a viscous barotropic gas. We consider these equations in $r \geq 1$ with the boundary condition

$$u|_{r=1} = 0$$

and the initial conditions

$$\rho|_{t=0} = \rho^0(r), \quad u|_{t=0} = u^0(r).$$

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These equations admit the equilibria

$$\rho = \begin{cases} \left[\frac{(\gamma-1)M}{a\gamma} \left(\frac{1}{r} - \frac{1}{R} \right) \right]^{1/(\gamma-1)} & (r \leq R) \\ 0 & (R < r), \end{cases} \quad u = 0.$$

Here $R > 1$ is arbitrary. Since we are interested in the class of initial data which includes these equilibria, we introduce the Lagrange coordinates

$$x = 4\pi \int_1^r \rho(s, t) s^2 ds.$$

Then the equations turn out to be

$$(1) \quad \frac{\partial \rho}{\partial t} + 4\pi \rho^2 \frac{\partial}{\partial x} (r^2 u) = 0,$$

$$(2) \quad \frac{\partial u}{\partial t} + 4\pi r^2 \frac{\partial p}{\partial x} = 16\pi^2 \nu \frac{\partial}{\partial x} \left(r^4 \rho \frac{\partial u}{\partial x} \right) - 2\nu \frac{u}{r^2 \rho} - \frac{M}{r^2},$$

$$(3) \quad p = a\rho^\gamma,$$

where

$$(4) \quad r = \left[1 + \frac{3}{4\pi} \int_0^x \frac{d\xi}{\rho(\xi, t)} \right]^{1/3}.$$

Normalizing the total mass, we consider the equations (1) (2) (3) (4) in $0 \leq x \leq 1$ with the boundary conditions

$$(5) \quad u|_{x=0} = 0, \quad 4\pi r^2 p - 16\pi^2 \nu r^4 \rho \frac{\partial u}{\partial x} \Big|_{x=1} = 0$$

and the initial conditions

$$(6) \quad \rho|_{t=0} = \rho_0(x), \quad u|_{t=0} = u_0(x).$$

In this case the equilibrium is unique. We denote it by $\rho = \bar{\rho}(x)$, $p = \bar{p}(x) = a\bar{\rho}(x)^\gamma$ and $r = \bar{r}(x)$, who satisfy

$$(7) \quad 4\pi \bar{r}^2 \frac{\partial \bar{p}}{\partial x} = -\frac{M}{\bar{r}^2},$$

$$(8) \quad \frac{1}{C}(1-x) \leq \bar{p}(x) \leq C(1-x).$$

In the paper [2], we constructed global solutions under the following assumptions:

- (A.0) $\rho_0 \in C[0, 1]$, $\rho_0(x) > 0$ for $0 \leq x < 1$, $\rho_0(0) = 0$,
total variation $[\rho_0] < +\infty$;
- (A.1) There exists a monotone decreasing function $\lambda(x)$ such that
 $0 \leq \lambda(x) \leq \rho_0(x)$ and $\int_0^1 \frac{dx}{\lambda(x)} < +\infty$;
- (A.2) $u_0 \in C[0, 1]$;
- (A.3) This is a slightly complicated assumption concerning ρ_0 and u_0 .
But it is satisfied at least if $p_0 = a\rho^\gamma \in C^1[0, 1]$ and $u_0 = 0$.
See [2] for the details.

The global solution (ρ, u) constructed in [2] satisfies that, for any T ,

$$(9) \quad \rho, u \in L^\infty([0, T] \times [0, 1]) \cap C^1([0, T]; L^2(0, 1)),$$

$$(10) \quad \rho u_x \in L^\infty([0, T] \times [0, 1]) \cap C^{1/2}([0, T]; L^2(0, 1)),$$

and there exists a constant $C(T)$ such that

$$(11) \quad \frac{1}{C(T)}\rho_0(x) \leq \rho(x, t) \leq C(T)\rho_0(x) \quad \text{for } 0 \leq t \leq T, \quad 0 \leq x \leq 1.$$

In the last paper [3], we showed that such a solution is unique.

In this paper we will show that the solution tends to the equilibrium as $t \rightarrow +\infty$ under some additional assumptions.

First we prepare some preliminary estimates. Here we apply the argument of I. Straskraba [4].

PROPOSITION 1. *There exists a constant C such that*

$$(12) \quad \rho(x, t) \leq C \quad \text{for } 0 \leq x \leq 1 \quad \text{and} \quad 0 \leq t < +\infty.$$

Here and hereafter C denotes various constants depending on the parameters γ, ν, M, a and the initial conditions ρ_0 and u_0 .

Proof. We rewrite the equation (2) as

$$(2)' \quad u_t = 4\pi r^2(4\pi\nu\rho(r^2u)_x - p)_x - \frac{M}{r^2}.$$

Integrating (2)' with respect to x from x to 1 and using the boundary condition (5), we get

$$\int_x^1 \frac{u_t}{r^2} dx = -4\pi(4\pi\nu\rho(r^2u)_x - p) - \int_x^1 \frac{M}{r^4} dx.$$

But, since $4\pi\rho(r^2u)_x = -(\log\rho)_t$ from (1), this can be rewritten

$$(13) \quad \frac{\partial}{\partial t} \log\rho = \frac{1}{\nu} \left[\frac{1}{4\pi} \frac{\partial}{\partial t} \int_x^1 \frac{u}{r^2} dx - p + H \right],$$

where

$$(14) \quad H = \frac{1}{2\pi} \int_x^1 \frac{u^2}{r^3} dx + \frac{1}{4\pi} \int_x^1 \frac{M}{r^4} dx.$$

Here we use the fact that $r_t = u$.

Now we use the energy equality

$$(15) \quad \frac{d}{dt} \int_0^1 \left(\frac{1}{2} u^2 + \frac{1}{\gamma-1} \frac{p}{\rho} - \frac{M}{r} \right) dx + Y(t) = 0,$$

where

$$(16) \quad Y(t) = \int_0^1 \left(16\pi^2 \nu r^4 \rho u_x^2 + 2\nu \frac{u^2}{r^2 \rho} \right) dx.$$

Let us denote

$$(17) \quad E_0 = \int_0^1 \left(\frac{1}{2} u_0^2 + \frac{1}{\gamma-1} \frac{p_0}{\rho_0} - \frac{M}{r_0} \right) dx.$$

Since $r \geq 1$, the energy equality (15) implies the boundedness of H , say $H \leq H^*$.

Suppose $p(x_0, T) > H^*$ for some T . Then there exists $t_1 < T$ such that
i) $t_1 > 0$, $p(x_0, t) \geq H^*$ for $t \in [t_1, T]$, $p(x_0, t_1) = H^*$ or ii) $t_1 = 0$ and $p(x_0, t) \geq H^*$ for $t \in [0, T]$. Integrating (13) with respect to t from t_1 to T , we see

$$\log\rho(x_0, T) = \log\rho(x_0, t_1) + \frac{1}{\nu} \left[\frac{1}{4\pi} \int_{x_0}^1 \frac{u}{r^2} \Big|_{t_1}^T dx + \int_{t_1}^T (H - p) dt \right].$$

But, since $H - p \leq 0$ along $x = x_0$, $t_1 \leq t \leq T$, and since

$$\left| \int_{x_0}^1 \frac{u}{r^2} dx \right| \leq \left[\int_{x_0}^1 u^2 dx \right]^{1/2} \leq [2(E_0 + M)]^{1/2},$$

we get

$$\log\rho(x_0, T) \leq \max \left(\log\rho_0(x_0), \log(H^*/a)^{1/\gamma} \right) + \frac{1}{2\pi\nu} [2(E_0 + M)]^{1/2}.$$

This completes the proof, since $\rho_0 \in C[0, 1]$ is bounded.

PROPOSITION 2. *We have*

$$(18) \quad \int_0^1 u(x, t)^2 dx \longrightarrow 0 \quad \text{as } t \rightarrow +\infty.$$

Proof. We start with the energy equality (15), which can be rewritten as

$$(19) \quad \frac{d}{dt} \int_0^1 \left(\frac{1}{2} u^2 dx \right) dx + Y(t) - \int_0^1 4\pi p(r^2 u)_x dx + \int \frac{Mu}{r^2} dx = 0.$$

Put

$$\epsilon(t) = \left[\int_{t-1}^t Y(s) ds \right]^{1/2}.$$

Since $\int_0^{+\infty} Y(t) dt \leq E_0 + M < +\infty$, we see $\epsilon(t) \rightarrow 0$ as $t \rightarrow +\infty$. Now we integrate (19) with respect to t from s to t , and then integrate it with respect to s from $t-1$ to t . The result is

$$\begin{aligned} & \int_0^1 \frac{1}{2} u^2(t) dx - \int_{t-1}^t \int_0^1 \frac{1}{2} u^2(s) dx ds + \int_{t-1}^t \int_s^t Y(\tau) d\tau ds \\ & = \int_{t-1}^t ds \int_s^t d\tau \left[\int_0^1 4\pi p(r^2 u)_x dx - \int_0^1 \frac{M}{r^2} dx \right] (\tau). \end{aligned}$$

We see

$$0 \leq \int_{t-1}^t \int_s^t Y(\tau) d\tau ds = \int_{t-1}^t Y(\tau) (\tau - (t-1)) d\tau \leq \int_{t-1}^t Y(\tau) d\tau = \epsilon(t)^2 \rightarrow 0.$$

On the other hand, since

$$(20) \quad u^2 = \int_0^x 2uu_x dx \leq CY,$$

we see

$$\int_{t-1}^t \int_0^1 \frac{1}{2} u^2(s) dx ds \leq C \int_{t-1}^t Y(s) ds \leq C\epsilon(t)^2 \rightarrow 0.$$

Noting

$$p(r^2 u)_x = \frac{1}{2\pi} \frac{1}{r} p u + pr^2 u_x,$$

we easily see

$$\left| \int_{t-1}^t \int_s^t \int_0^1 p(r^2 u)_x dx d\tau ds \right| \leq C \left[\int_{t-1}^t \int_0^1 \left(\frac{u^2}{r^2 \rho} + r^4 \rho u_x^2 \right) dx ds \right]^{1/2} \leq C' \epsilon(t).$$

Here we use the result of Proposition 1, say $\rho \leq C$. Similarly

$$\left| \int_{t-1}^t \int_s^t \int_0^1 \frac{Mu}{r^2} dx d\tau ds \right| \leq C \left[\int_{t-1}^t \int_0^1 \frac{u^2}{r^2 \rho} dx ds \right]^{1/2} \leq C' \epsilon(t).$$

This completes the proof.

Now we are going to estimate ρ from below to show $\rho \rightarrow \bar{\rho}$. Then we must leave the argument of I. Straskraba [4]. The reason is that [4] supposes that the external force $f(r)$ satisfies $f'(r) \leq 0$ and this plays an important role in his argument, but in our case $f(r) = -\frac{M}{r^2}$ satisfies $f'(r) = \frac{2M}{r^3} > 0$.

We assume

$$(A.4) \quad \gamma > \frac{4}{3} \quad \text{and} \quad M > 0.$$

Moreover we assume temporarily

$$(a.1) \quad p_0(x) \leq M(1-x).$$

PROPOSITION 3. *There exists a constant $B(\gamma, \nu, E^*, M^*, R^*)$ such that*

$$(21) \quad B = \sup_{\substack{0 \leq t < +\infty \\ 0 \leq x < 1}} \frac{\rho_0(x)}{\rho(x, t)} \leq B(\gamma, \nu, E^*, M^*, R^*),$$

provided that $E_0 \leq E^*$, $M \leq M^*$ and $R_0 \leq R^*$. Here

$$R_0 = r(1, 0) = \left[1 + \frac{3}{4\pi} \int_0^1 \frac{dx}{\rho_0(x)} \right]^{1/3}.$$

Proof. We write (13) (14) as

$$(22) \quad \frac{\partial}{\partial t} \log p + \frac{\gamma}{\nu} p = A(x, t),$$

where

$$(23) \quad A(x, t) = \frac{\gamma}{4\pi\nu} \frac{\partial}{\partial t} \int_x^1 \frac{u}{r^2} dx + \frac{\gamma}{2\pi\nu} \int_x^1 \frac{u^2}{r^3} dx + \frac{\gamma}{4\pi\nu} \int_x^1 \frac{M}{r^4} dx.$$

Solving (22), we get

$$(24) \quad \frac{1}{p(x, t)} = \frac{1}{p_0(x)} \left[\exp \left(- \int_0^t A ds \right) + \frac{\gamma}{\nu} p_0(x) \int_0^t \exp \left(- \int_s^t A d\tau \right) ds \right].$$

We put

$$\beta(T) = \sup_{\substack{0 \leq t \leq T \\ 0 \leq x < 1}} \frac{p_0(x)}{p(x, t)}.$$

This is finite by (11). Then we have

$$R(t) = r(1, t) = \left[1 + \frac{3}{4\pi} \int_0^1 \frac{dx}{\rho(x, t)} \right]^{1/3} \leq K_1 \left(1 + \beta(T)^{1/\gamma} \right)^{1/3},$$

where $K_1 = K_1(R^*)$ and

$$\begin{aligned} - \int_s^t Ad\tau &\leq -\frac{\gamma}{4\pi\nu} \int_x^1 \frac{u}{r^2} \Big|_s^t dx - \frac{\gamma}{4\pi\nu} \int_s^t d\tau \int_x^1 \frac{M}{r^4} dx \\ &\leq K_2 - \frac{\gamma M}{4\pi\nu K_1^4} (1-x) \left(1 + \beta(T)^{1/\gamma}\right)^{-4/3} (t-s) \end{aligned}$$

for $0 \leq s \leq t \leq T$, where $K_2 = \frac{\gamma}{2\pi\nu} \sqrt{2(E^* + M^*)}$. Applying this estimate to (24), we see

$$\frac{1}{p(x,t)} \leq \frac{e^{K_2}}{p_0(x)} \left(1 + \frac{4\pi\nu K_1^4}{\gamma} \left(1 + \beta(T)^{1/\gamma}\right)^{4/3}\right).$$

Here we use (a.1). Thus we get

$$\beta(T) \leq K_3 \left(1 + \left(1 + \beta(T)^{1/\gamma}\right)^{4/3}\right), \quad \text{with } K_3 = K_3(\gamma, \nu, E^*, M^*, R^*).$$

Consider the function

$$\varphi(\beta) = \frac{\beta}{K_3 \left(1 + \left(1 + \beta^{1/\gamma}\right)^{4/3}\right)}.$$

Then $\varphi(\beta) \rightarrow +\infty$ as $\beta \rightarrow +\infty$, since $\gamma > \frac{4}{3}$ by (A.4). Thus $\varphi(\beta) \leq 1$ implies $\beta \leq \beta^* = \beta^*(\gamma, \nu, E^*, M^*, R^*)$. Putting $B(\gamma, \nu, E^*, M^*, R^*) = (\beta^*)^{1/\gamma}$ we get (21). This completes the proof.

Now we write (13) (14) as

$$\frac{1}{\rho} \frac{\partial \rho}{\partial t} + \frac{1}{\nu} p = \frac{1}{4\pi\nu} \frac{\partial}{\partial t} \int_x^1 \frac{u}{r^2} dx + \frac{1}{2\pi\nu} \int_x^1 \frac{u^2}{r^3} dx + \frac{M}{4\pi\nu} \int_x^1 \frac{dx}{r^4},$$

or

$$(25) \quad \begin{aligned} \frac{\partial}{\partial t} \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) - \frac{1}{\nu} \frac{p}{\rho} &= -\frac{1}{4\pi\nu} \frac{1}{\rho} \frac{\partial}{\partial t} \int_x^1 \frac{u}{r^2} dx \\ &\quad - \frac{1}{2\pi\nu} \frac{1}{\rho} \int_x^1 \frac{u^2}{r^3} dx - \frac{M}{4\pi\nu} \frac{1}{\rho} \int_x^1 \frac{dx}{r^4}. \end{aligned}$$

The equilibrium satisfies

$$(26) \quad -\frac{1}{\nu} \frac{\bar{p}}{\bar{\rho}} = -\frac{M}{4\pi\nu} \frac{1}{\bar{\rho}} \int_x^1 \frac{dx}{r^4}.$$

Taking $\{(25) - (26)\} \times \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}}\right) \rho_0$, we get

(27)

$$\begin{aligned}
& \frac{\partial}{\partial t} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 - \frac{1}{\nu} \left(\frac{p}{\rho} - \frac{\bar{p}}{\bar{\rho}} \right) \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \rho_0 \\
&= -\frac{1}{4\pi\nu} \frac{\partial}{\partial t} \left(\frac{\rho_0}{\rho} \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \int_x^1 \frac{u}{r^2} dx \right) + \frac{1}{\nu} (r^2 u)_x \left(\rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) + \frac{\rho_0}{\rho} \right) \int_x^1 \frac{u}{r^2} dx \\
&\quad - \frac{1}{2\pi\nu} \frac{\rho_0}{\rho} \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \int_x^1 \frac{u^2}{r^3} dx - \frac{M}{4\pi\nu} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \int_x^1 \frac{dx}{r^4} \\
&\quad - \frac{M}{4\pi\nu} \frac{\rho_0}{\rho} \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \int_x^1 \left(\frac{1}{r^4} - \frac{1}{\bar{r}^4} \right) dx.
\end{aligned}$$

Now we see

$$(28) \quad -\frac{1}{\nu} \left(\frac{p}{\rho} - \frac{\bar{p}}{\bar{\rho}} \right) \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \rho_0 = \frac{\alpha(\gamma-1)}{\nu} \tilde{\rho}^\gamma \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \rho_0 \geq 0,$$

where $\tilde{\rho} = \left(\frac{1}{\bar{\rho}} + \theta \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \right)^{-1}$ with $0 < \theta < 1$.

We assume temporarily

$$(a.2) \quad \rho_0(x) \leq C\bar{\rho}(x) \quad \text{for } 0 \leq x \leq 1.$$

Then we get

$$\rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \leq \frac{C}{\rho_0}, \quad \frac{\rho_0}{\rho} \leq C, \quad \rho_0 \left| \frac{1}{\rho} - \frac{1}{\bar{\rho}} \right| \leq C, \quad \frac{\rho_0}{\rho} \left| \frac{1}{\rho} - \frac{1}{\bar{\rho}} \right| \leq \frac{C}{\rho_0} \quad \text{and so on.}$$

Moreover we assume

$$(a.3) \quad \rho_0(x) \geq \frac{(1-x)^{1/\gamma}}{C}.$$

Now, for $0 < \mu$ and $0 \leq \delta \leq 1$, we put

$$(29) \quad Q_{\delta,\mu} = \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^\mu}.$$

 $Q_{\delta,\mu}$ is finite as least if $\delta > 0$.Let $\delta > 0$. Then it follows from (28) that

$$\begin{aligned}
\frac{d}{dt} Q_{\delta,\mu} &\leq \frac{d}{dt} F_{\delta,\mu} + G_{\delta,\mu} - \frac{M}{4\pi\nu} \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{1}{(1-x)^\mu} \int_x^1 \frac{d\xi}{r^4} dx \\
&\quad - \frac{M}{4\pi\nu} \int_0^{1-\delta} \frac{\rho_0}{\rho} \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \frac{1}{(1-x)^\mu} \int_x^1 \left(\frac{1}{r^4} - \frac{1}{\bar{r}^4} \right) d\xi dx,
\end{aligned}$$

where

$$\begin{aligned}
 F_{\delta,\mu} &= -\frac{1}{4\pi\nu} \int_0^{1-\delta} \frac{\rho_0}{\rho} \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \frac{1}{(1-x)^\mu} \int_x^1 \frac{u}{r^2} d\xi dx, \\
 G_{\delta,\mu} &= \frac{1}{\nu} \int_0^{1-\delta} (r^2 u)_x \left(\rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) + \frac{\rho_0}{\rho} \right) \frac{1}{(1-x)^\mu} \int_x^1 \frac{u}{r^2} d\xi dx \\
 &\quad - \frac{1}{2\pi\nu} \int_0^{1-\delta} \frac{\rho_0}{\rho} \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \frac{1}{(1-x)^\mu} \int_x^1 \frac{u^2}{r^3} d\xi dx.
 \end{aligned}$$

First we consider the case $\mu = \frac{5}{4}$. Then it is easy to see

$$|F_{\delta,5/4}| \leq C \int_0^{1-\delta} \frac{(1-x)^{1/2} dx}{(1-x)^{1/\gamma+5/4}} \sqrt{\int_x^1 u^2 d\xi} \leq C' \delta^{1/4-1/\gamma} \sqrt{\int_0^1 u^2 dx}$$

by (a.3), and

$$|G_{\delta,5/4}| \leq C\delta^{-1/4} Y \quad (\text{see (20)})$$

Here and hereafter C stands for various constants independent of δ . On the other hand

$$\begin{aligned}
 &-\frac{M}{4\pi\nu} \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{5/4}} \int_x^1 \frac{d\xi}{\bar{r}^4} \\
 &\leq -\frac{M}{4\pi\nu} \frac{1}{\bar{R}^4} \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{1/4}},
 \end{aligned}$$

where $\bar{R} = \bar{r}(1)$, and

$$\begin{aligned}
 &-\frac{M}{4\pi\nu} \int_0^{1-\delta} \frac{\rho_0}{\rho} \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \frac{dx}{(1-x)^{5/4}} \int_x^1 \left(\frac{1}{r^4} - \frac{1}{\bar{r}^4} \right) d\xi \\
 &\leq \frac{MB}{4\pi^2\nu} \int_0^{1-\delta} \left| \frac{1}{\rho} - \frac{1}{\bar{\rho}} \right| \frac{dx}{(1-x)^{1/4}} \left(\int_0^{1-\delta} \left| \frac{1}{\rho} - \frac{1}{\bar{\rho}} \right| dx + \int_{1-\delta}^1 \left| \frac{1}{\rho} - \frac{1}{\bar{\rho}} \right| dx \right) \\
 &\leq \frac{MB}{4\pi^2\nu} \left[\int_0^1 \frac{dx}{\rho_0(1-x)^{1/4}} \right]^{1/2} \left[\int_0^1 \frac{(1-x)^{1/4}}{\rho_0} dx \right]^{1/2} \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right) \frac{dx}{(1-x)^{1/4}} \\
 &\quad + C\delta^{(\gamma-1)/\gamma} \left[\int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{1/4}} \right].
 \end{aligned}$$

Here we use the estimate

$$\int_{1-\delta}^1 \left| \frac{1}{\rho} - \frac{1}{\bar{\rho}} \right| dx \leq C\delta^{(\gamma-1)/\gamma},$$

by (a.3). Let us suppose

$$(a.4) \quad B \left[\int_0^1 \frac{dx}{\rho_0(1-x)^{1/4}} \right]^{1/2} \left[\int_0^1 \frac{(1-x)^{1/4}}{\rho_0} dx \right]^{1/2} \leq \frac{\pi}{2} \frac{1}{R^4}.$$

Then

$$\begin{aligned} \frac{d}{dt} Q_{\delta,5/4} &\leq \frac{d}{dt} F_{\delta,5/4} + G_{\delta,5/4} - \alpha \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{1/4}} \\ &\quad + C\delta^{(\gamma-1)/\gamma} \left[\int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{1/4}} \right]^{1/2}, \end{aligned}$$

where

$$\alpha = \frac{M}{8\pi\nu R^4}.$$

Suppose

$$\frac{2C\delta^{(\gamma-1)/\gamma}}{\alpha} \leq \left[\int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{1/4}} \right]^{1/2} \quad \text{for } t \geq T.$$

Then

$$\frac{d}{dt} Q_{\delta,5/4} \leq \frac{d}{dt} F_{\delta,5/4} + G_{\delta,5/4} - \frac{\alpha\delta}{2} Q_{\delta,5/4} \quad \text{for } t \geq T.$$

Since $F_{\delta,5/4} \rightarrow 0$ as $t \rightarrow +\infty$ by Proposition 2 and

$$\int_0^{+\infty} |G_{\delta,5/4}(t)| dt < +\infty,$$

it follows that $Q_{\delta,5/4}(t) \rightarrow 0$ as $t \rightarrow +\infty$ from the above differential inequality. This is a contradiction, since

$$Q_{\delta,5/4} \geq \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{1/4}}.$$

Therefore there exists a sequence $t_n(\delta) \rightarrow +\infty$ ($n \rightarrow +\infty$) such that

$$(30) \quad \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{1/4}} \leq C\delta^{2(\gamma-1)/\gamma} \quad \text{at } t = t_n(\delta).$$

Next we take $\mu = \frac{3}{4}$. Then

$$|F_{\delta,3/4}| \leq C \int_0^1 \frac{(1-x)^{1/2} dx}{(1-x)^{1/\gamma+3/4}} \sqrt{\int_x^1 u^2 d\xi} \leq C' \sqrt{\int_0^1 u^2 dx},$$

since $\frac{1}{2} - \frac{1}{\gamma} - \frac{3}{4} + 1 = \frac{3}{4} - \frac{1}{\gamma} > 0$ by (A.4)

$$|G_{\delta,3/4}| \leq CY,$$

since $1 - \frac{3}{4} = \frac{1}{4} > 0$. And by a similar argument we get

$$\begin{aligned} \frac{d}{dt} Q_{\delta,3/4} &\leq \frac{d}{dt} F_{\delta,3/4} + G_{\delta,3/4} - \alpha \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 (1-x)^{1/4} dx \\ &\quad + C\delta^{(\gamma-1)/\gamma} \left[\int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 (1-x)^{1/4} dx \right]^{1/2} \end{aligned}$$

under the assumption (a.4). Then, in this case, we have

$$\begin{aligned} Q_{\delta,3/4}(t) &\leq Q_{\delta,3/4}(t_0) + F_{\delta,3/4}(t) - F_{\delta,3/4}(t_0) + \int_{t_0}^t G_{\delta,3/4}(\tau) d\tau \\ &\quad + C\delta^{(\gamma-1)/\gamma} \int_{t_0}^t \left[\int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 (1-x)^{1/4} dx \right]^{1/2} (\tau) d\tau \\ &\leq Q_{\delta,3/4}(t_0) + F_{\delta,3/4}(t) - F_{\delta,3/4}(t_0) \\ &\quad + \int_{t_0}^t G_{\delta,3/4}(\tau) d\tau + C'\delta^{(\gamma-1)/\gamma}(t-t_0), \quad \text{for } 0 \leq t_0 \leq t. \end{aligned}$$

Take $t_0 = 0$. Assume

$$(a.5) \quad Q_{0,3/4}(0) = \int_0^1 \rho_0 \left(\frac{1}{\rho_0} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{3/4}} < +\infty.$$

Then, since $F_{\delta,3/4} \rightarrow F_{0,3/4}$ and $G_{\delta,3/4} \rightarrow G_{0,3/4}$, we see

$$Q_{0,3/4}(t) \leq C \quad \text{for } t \geq 0$$

and

$$(31) \quad \begin{aligned} Q_{0,3/4}(t) &\leq Q_{0,3/4}(t_0) + F_{0,3/4}(t) - F_{0,3/4}(t_0) \\ &\quad + \int_{t_0}^t G_{0,3/4}(\tau) d\tau \quad \text{for } 0 \leq t_0 \leq t. \end{aligned}$$

Here we note

$$(32) \quad Q_{\delta,3/4}(t_n(\delta)) \leq \frac{1}{\delta^{1/2}} \int_0^{1-\delta} \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{1/4}} \leq C\delta^{(3\gamma-4)/2\gamma},$$

from (30).

Finally take μ such that

$$(33) \quad \frac{3}{4} < \mu < \frac{3}{2} - \frac{1}{\gamma}.$$

Since $\frac{3}{2} - \frac{1}{\gamma} - \frac{3}{4} = \frac{3}{4} - \frac{1}{\gamma} > 0$ by (A.4), this is possible, and we see

$$|F_{\delta,\mu}| \leq C \int_0^1 \frac{(1-x)^{1/2} dx}{(1-x)^{1/\gamma+\mu}} \sqrt{\int_x^1 u^2 d\xi} \leq C' \sqrt{\int_0^1 u^2 dx},$$

since $\frac{1}{2} - \mu - \frac{1}{\gamma} + 1 = \frac{3}{2} - \frac{1}{\gamma} - \mu > 0$, and

$$|G_{\delta,\mu}| \leq CY,$$

since $1 - \mu > 1 - \frac{3}{2} + \frac{1}{\gamma} = \frac{2-\gamma}{2\gamma} \geq 0$. Then, assuming

$$(a.6) \quad B \left[\int_0^1 \frac{(1-x)^{1-\mu}}{\rho_0} dx \right]^{1/2} \left[\int_0^1 \frac{dx}{\rho_0(1-x)^{1-\mu}} \right]^{1/2} \leq \frac{\pi}{2} \frac{1}{R^4},$$

we get

$$Q_{0,\mu}(t) \leq C$$

by a similar argument to the case of $\mu = \frac{3}{4}$. Here we assume

$$(a.7) \quad Q_{0,\mu}(0) = \int_0^1 \rho_0 \left(\frac{1}{\rho_0} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^\mu} < +\infty$$

and use $1 - \mu > 1 - \left(\frac{3}{2} - \frac{1}{\gamma}\right) = \frac{2-\gamma}{\gamma} \geq 0$.

Then we get

$$\begin{aligned} Q_{0,3/4}(t_n(\delta)) &= Q_{\delta,3/4}(t_n(\delta)) + \int_{1-\delta}^1 \rho_0 \left(\frac{1}{\rho} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^{3/4}} \\ &\leq Q_{\delta,3/4}(t_n(\delta)) + \delta^{\mu-3/4} Q_{0,\mu}(t_n(\delta)) \\ &\leq C \left(\delta^{(3\gamma-4)/2\gamma} + \delta^{\mu-3/4} \right). \end{aligned}$$

It follows from (31) that

$$\limsup_{t \rightarrow +\infty} Q_{0,3/4}(t) \leq C \left(\delta^{(3\gamma-4)/2\gamma} + \delta^{\mu-3/4} \right).$$

Since $\delta > 0$ is arbitrary, we get

$$Q_{0,3/4}(t) \longrightarrow 0 \quad \text{as } t \rightarrow +\infty.$$

This is our final goal.

We are going to give a sufficient condition for (a.1) (a.2) (a.3) (a.4) (a.5) (a.6).

We put the assumption

$$(A.5) \quad \int_0^1 \rho_0 \left(\frac{1}{\rho_0} - \frac{1}{\bar{\rho}} \right)^2 \frac{dx}{(1-x)^\mu} < +\infty \quad \text{for some } \mu > \frac{3}{4}.$$

This assumption (A.5) guarantees (a.5) (a.7).

On the other hand we consider the condition

$$(a.8) \quad La(1-x) \leq p_0 \leq M(1-x),$$

where L is a suitable constant depending upon γ, ν, E^*, M^* and \bar{R} specified as follows, where $\bar{R} = \bar{R}(\gamma, \frac{a}{M})$ is the solution of

$$\frac{1}{4\pi} \left(\frac{\gamma}{\gamma-1} \frac{a}{M} \right)^{1/(\gamma-1)} = \int_1^{\bar{R}} \left(\frac{1}{r} - \frac{1}{\bar{R}} \right)^{1/(\gamma-1)} r^2 dr.$$

Under the condition (a.8), we have

$$B \leq B(\gamma, \nu, E^*, M^*, R^*)$$

provided that $E_0 \leq E^*$ and $M \leq M^*$. We see $R_0 \leq 2^{1/3}$ provided $\frac{3}{4\pi} \frac{\gamma}{\gamma-1} \left(\frac{1}{L}\right)^{1/\gamma} \leq 1$, since

$$(34) \quad \frac{1}{\rho_0} \leq \left(\frac{1}{L}\right)^{1/\gamma} \frac{1}{(1-x)^{1/\gamma}}.$$

It is easy to see (a.4) and (a.6) hold if we take L sufficiently large so that

$$B \left(\frac{1}{L}\right)^{1/\gamma} \frac{1}{\mu} \leq \frac{\pi}{2} \frac{1}{\bar{R}^4},$$

using (34). The conditions (a.1) (a.2) (a.3) are direct consequences of the condition (a.8).

We note that, for the equilibrium,

$$\frac{M}{4\pi} \bar{R}^{(-2\gamma+1)/(\gamma-1)} (1-x) \leq \bar{p} \leq \frac{M}{4\pi} \bar{R}^{(-3\gamma+4)/(\gamma-1)} (1-x) \quad \text{if } \gamma \leq \frac{3}{2}$$

or

$$\frac{M}{4\pi} \bar{R}^{-4} (1-x) \leq \bar{p} \leq \frac{M}{4\pi} \bar{R}^{-1} (1-x) \quad \text{if } \gamma \geq \frac{3}{2}.$$

Note that $\bar{R} \rightarrow 1$ as $\frac{a}{M} \rightarrow 0$. Therefore p_0 near \bar{p} satisfies (a.8) for sufficiently small a . Thus we have proved the following:

THEOREM. *Under the assumptions (A.0) (A.2) (A.3) (A.4) (A.5), suppose that a is so small that*

$$La < M, \quad \text{where } L = L(\gamma, \nu, E^*, M^*, \bar{R}),$$

provided that $E_0 \leq E^$ and $M \leq M^*$, and that the initial pressure p_0 satisfies*

$$La(1-x) \leq p_0 \leq M(1-x).$$

Then the global solution (ρ, u) satisfies

$$\int_0^1 u(x, t)^2 dx \longrightarrow 0,$$

$$\int_0^1 \rho_0(x) \left(\frac{1}{\rho(x, t)} - \frac{1}{\bar{\rho}(x)} \right)^2 \frac{dx}{(1-x)^{3/4}} \longrightarrow 0 \quad \text{as } t \rightarrow +\infty.$$

As a corollary, $\rho(x, t) \rightarrow \bar{\rho}(x)$ a.e. x as $t \rightarrow +\infty$, and moreover, since $\rho \leq C$, we know

$$\int_0^1 |\rho(x, t) - \bar{\rho}(x)|^q dx \longrightarrow 0, \quad (1 \leq q < +\infty)$$

as $t \rightarrow +\infty$, for example. On the other hand, since $\frac{1}{\rho} \leq \frac{B}{\bar{\rho}}$, we know

$$\int_0^1 \left| \frac{1}{\rho(x, t)} - \frac{1}{\bar{\rho}(x)} \right| dx \longrightarrow 0$$

and

$$R(t) = r(1, t) \longrightarrow \bar{r}$$

as $t \rightarrow +\infty$.

REMARK 1. We conjecture that the assumption $\gamma > \frac{4}{3}$ can be removed in the present case in which the effect of the self-gravitation is neglected. However if we take into account the effect of self-gravitation, namely if we replace M by

$$M + 4\pi \int_1^r \rho r^2 dr = M + x,$$

then the number of the equilibria is one when $\gamma \geq \frac{4}{3}$ and more than two when $\gamma < \frac{4}{3}$ (see W.-Ch. Kuan and S.-S. Lin, [1]). Therefore the assumption that $\gamma > \frac{4}{3}$ may be essential for the case with self-gravitation. We note that our proof can work with a slight modification for this case with self-gravitation.

REMARK 2. We have not yet been able to remove the assumption that a is sufficiently small, although this is a serious restriction of our result.

REMARK 3. It is difficult to describe our conclusion in terms of the Eulerian coordinates, since in the Eulerian coordinates the support of $\rho(\cdot, t)$, $[1, R(t)]$, which corresponds to the fixed interval $[0, 1]$ in the Lagrangean coordinates, varies with time t .

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