

Quaternionic Monge–Ampère Equations

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ABSTRACT. The main result of this article is the existence and uniqueness of the solution of the Dirichlet problem for quaternionic Monge–Ampère equations in quaternionic strictly pseudoconvex bounded domains in \mathbb{H}^n . We continue the study of the theory of plurisubharmonic functions of quaternionic variables started by the author at [2].

1. Introduction

This article is a continuation of the author’s previous article [2]. In [2] we have developed the necessary algebraic technique and we have introduced and studied the class of plurisubharmonic functions of quaternionic variables (this class was independently introduced also by G. Henkin [36]). The main result of the present article is the existence of a generalized solution of the Dirichlet problem for quaternionic Monge–Ampère equations in quaternionic strictly pseudoconvex bounded domains in \mathbb{H}^n . The uniqueness of solution was established in [2].

The versions of this result for real and complex Monge–Ampère equations were established in classical articles by A.D. Aleksandrov [1] (the real case) and E. Bedford and B. Taylor [10] (the complex case). We prove also a result on the regularity of solution in the Euclidean ball. For real Monge–Ampère equations this result was proved by L. Caffarelli, L. Nirenberg, and J. Spruck [14] for arbitrary strictly convex bounded domains, and for complex Monge–Ampère equations by L. Caffarelli, J. Kohn, L. Nirenberg, and J. Spruck [15] and N. Krylov [42] for arbitrary strictly pseudoconvex bounded domains.

The real Monge–Ampère equations appear in various geometric problems such as the Minkowski problem (see A. Pogorelov [52]). The Dirichlet problem has received considerable study. The interior regularity of the solution of the Dirichlet problem was proved by A. Pogorelov, and the proof was briefly described in [49]–[51]. The complete proof was published in [52] and [16, 17]. In [17] Cheng and Yau gave a different proof of interior regularity; they also studied some related geometric problems on flat manifolds. Another motivation of studying of the real Monge–Ampère equations is the Monge–Kantorovich problem on the measure transportation (see e.g., [21] and [54]).

The complex Monge–Ampère equations were studied in particular in the connection to Kähler geometry. Good references are the books by T. Aubin [8], A. Besse [11], D. Joyce [40].

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There is a general philosophy (promoted especially by V. Arnold, see e.g., [4]) that some mathematical theories should have three versions which are analogous to each other in certain sense: real, complex, and quaternionic. However they should reflect different phenomena. In this article we present the theory of plurisubharmonic functions of quaternionic variables and the theory of quaternionic Monge–Ampère equations whose study we have started in [2]. Their real and complex analogs are well known (the real analog of the theory of plurisubharmonic functions is the theory of convex functions).

We are going to formulate our main result more precisely and recall the main notions from [2]. Let \mathbb{H} denote the (non-commutative) field of quaternions. Let \mathbb{H}^n denote the space of n -tuples of quaternions (q_1, q_2, \dots, q_n) . We consider \mathbb{H}^n as right \mathbb{H} -module (we call it right \mathbb{H} -vector space). An $n \times n$ quaternionic matrix $A = (a_{ij})$ is called *hyperhermitian* if $A^* = A$, i.e., $a_{ij} = \bar{a}_{ji}$ for all i, j .

In order to write the classical (real or complex) Monge–Ampère equations one has to use the notion of determinant of matrices. By now there is no construction of determinant of matrices with non-commuting (even quaternionic) entries which would have *all* the properties of the usual (commutative) determinant. The most general theory of non-commutative determinants is due to Gelfand and Retakh (see [27]–[28], also [29, 30]). However, it turns out that on the class of quaternionic hyperhermitian matrices there is a notion of the Moore determinant which has all the properties of the usual determinant of complex (resp. real) hermitian (resp. symmetric) matrices. Some of these properties are reviewed in Section 2, and we refer to [2] for further details and references. Here we mention only that the Moore determinant depends polynomially on the entries of a hyperhermitian matrix, and the Moore determinant of any complex hermitian matrix A considered as quaternionic hyperhermitian coincides with the usual determinant of A . We denote the Moore determinant of A by $\det A$.

The quaternionic Monge–Ampère equation is written in terms of this determinant. We have to also recall the notion of plurisubharmonic function of quaternionic variables and the definition of quaternionic strictly pseudoconvex domain following [2]. Let Ω be a domain in \mathbb{H}^n .

Definition 1.1. A real valued function $u : \Omega \rightarrow \mathbb{R}$ is called quaternionic plurisubharmonic (psh) if it is upper semi-continuous and its restriction to any right *quaternionic* line is subharmonic.

Recall that upper semi-continuity means that $f(x_0) \geq \limsup_{x \rightarrow x_0} f(x)$ for any $x_0 \in \Omega$.

Moreover, we will call a C^2 -smooth function $u : \Omega \rightarrow \mathbb{R}$ to be *strictly plurisubharmonic* if its restriction to any right quaternionic line is strictly harmonic (i.e., the Laplacian is strictly positive).

Definition 1.2. An open-bounded domain $\Omega \subset \mathbb{H}^n$ with a smooth boundary $\partial\Omega$ is called strictly pseudoconvex if for every point $z_0 \in \partial\Omega$ there exists a neighborhood \mathcal{O} and a smooth strictly psh function h on \mathcal{O} such that $\Omega \cap \mathcal{O} = \{h < 0\}$, $h(z_0) = 0$, and $\nabla h(z_0) \neq 0$.

We will write a quaternion q in the usual form

$$q = t + x \cdot i + y \cdot j + z \cdot k,$$

where t, x, y, z are real numbers, and i, j, k satisfy the usual relations

$$i^2 = j^2 = k^2 = -1, \quad ij = -ji = k, \quad jk = -kj = i, \quad ki = -ik = j.$$

The Dirac–Weyl operator $\frac{\partial}{\partial \bar{q}}$ is defined as follows. For any \mathbb{H} -valued function f

$$\frac{\partial}{\partial \bar{q}} f := \frac{\partial f}{\partial t} + i \frac{\partial f}{\partial x} + j \frac{\partial f}{\partial y} + k \frac{\partial f}{\partial z} .$$

Let us also define the operator $\frac{\partial}{\partial q}$:

$$\frac{\partial}{\partial q} f := \overline{\frac{\partial}{\partial \bar{q}} \bar{f}} = \frac{\partial f}{\partial t} - \frac{\partial f}{\partial x} i - \frac{\partial f}{\partial y} j - \frac{\partial f}{\partial z} k .$$

Remarks. (a) The operator $\frac{\partial}{\partial \bar{q}}$ is sometimes called the Cauchy–Riemann–Moisil–Fueter operator since it was introduced by Moisil in [45] and used by Fueter [22, 23] to define the notion of quaternionic analyticity. For further results on quaternionic analyticity we refer e.g., to [12, 47, 48, 58], and for applications to mathematical physics to [34]. Another name used for this operator is the Dirac–Weyl operator. But in fact it was used earlier by J.C. Maxwell in [44], Vol. II, 570–576, where he has applied the quaternions to electromagnetism.

(b) Note that

$$\frac{\partial}{\partial \bar{q}} = \frac{\partial}{\partial t} + \nabla ,$$

where $\nabla = i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z}$. The operator ∇ was first introduced by W.R. Hamilton in [35].

(c) In quaternionic analysis one considers a right version of the operators $\frac{\partial}{\partial \bar{q}}$ and $\frac{\partial}{\partial q}$ which are denoted, respectively, by $\overleftarrow{\frac{\partial}{\partial \bar{q}}}$ and $\overleftarrow{\frac{\partial}{\partial q}}$. The operator $\overleftarrow{\frac{\partial}{\partial q}}$ is related to $\overleftarrow{\frac{\partial}{\partial \bar{q}}}$ by the same formula as $\frac{\partial}{\partial \bar{q}}$ is related to $\frac{\partial}{\partial q}$, and $\overleftarrow{\frac{\partial}{\partial \bar{q}}}$ is defined as

$$\overleftarrow{\frac{\partial}{\partial \bar{q}}} f := \frac{\partial f}{\partial t} + \frac{\partial f}{\partial x} i + \frac{\partial f}{\partial y} j + \frac{\partial f}{\partial z} k .$$

Now we can write the quaternionic Monge–Ampère equation with respect to C^2 - smooth psh function u on Ω :

$$\det \left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j} \right) = f ,$$

where f is a given function. Note that the matrix $(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j})$ is quaternionic hyperhermitian (since u is real valued), \det means the Moore determinant of this matrix. Note also that since the function u is psh, the matrix $(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j})$ is non-negative definite, and hence its Moore determinant is non-negative (the notion of positive definiteness of a hyperhermitian matrix is recalled in Section 2, Definition 2.4).

One of the main results of Section 2 of [2] was the definition of non-negative measure also denoted by $\det(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j})$ for any *continuous* psh function u (which is not necessarily smooth). That construction generalizes to the quaternionic situation the well-known constructions in the real and complex cases due, respectively, to A.D. Aleksandrov [1] and Chern–Levine–Nirenberg [18]. Now we can formulate the main results of this article.

Theorem 1.3. *Let $\Omega \subset \mathbb{H}^n$ be a bounded quaternionic strictly pseudoconvex domain. Let $f \in C(\bar{\Omega})$, $f \geq 0$. Let $\phi \in C(\partial\Omega)$. Then there exists unique function $u \in C(\bar{\Omega})$ which is psh in Ω such that*

$$\det \left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j} \right) = f \text{ in } \Omega ,$$

$$u|_{\partial\Omega} = \phi .$$

Note that the uniqueness was proved in [2]. Theorem 1.3 claims existence of a solution in a generalized sense (e.g., the function u does not have to be smooth). It is of interest to prove the regularity of solution u under assumptions of regularity of the initial data f , ϕ . We can prove it when the domain Ω is the Euclidean ball B in \mathbb{H}^n . In Section 7 we prove the following result (called Theorem 7.1).

Theorem 1.4. *Let $f \in C^\infty(\bar{B})$, $f > 0$. Let $\phi \in C^\infty(\partial B)$. There exists unique psh function $u \in C^\infty(\bar{B})$ which is a solution of the Dirichlet problem*

$$\det \left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j} \right) = f ,$$

$$u|_{\partial B} = \phi .$$

The real version of this result was proved for arbitrary strictly convex bounded domains in \mathbb{R}^n by Caffarelli, Nirenberg, and Spruck [14]. The complex version of it was proved for arbitrary strictly pseudoconvex bounded domains in \mathbb{C}^n by Caffarelli, Kohn, Nirenberg, and Spruck [15] and Krylov [42]. Our method is a modification of the method of the last article [15]. Also note that in the case $n = 1$, the problem is reduced to the classical Dirichlet problem for the Laplacian in \mathbb{R}^4 (which is a linear problem); it was solved in XIX century.

Let us make a few comments why the method of [15] cannot be generalized immediately to arbitrary strictly pseudoconvex bounded domain in \mathbb{H}^n . The main difficulty is that in the complex case one uses the holomorphic transformations to make the domain to be (locally) close to the Euclidean ball. In the quaternionic situation it does not work. Indeed in the complex case the class of diffeomorphisms of a domain which are either holomorphic or anti-holomorphic can be characterized as the class of diffeomorphisms preserving the class of psh functions. In the quaternionic situation the class of diffeomorphisms preserving psh functions is very small: all of them must be affine transformations, more precisely modulo translations the corresponding group is equal to $GL_n(\mathbb{H})Sp(1)$. The last fact is proved in Section 3.2.

Let us make a few comments on the method of the proof of Theorem 1.3. It uses the solution of the Dirichlet problem in the unit ball given by Theorem 1.4. The method to deduce the general case from this one follows the lines of the article [10] by Bedford and Taylor. It was necessary to generalize to the quaternionic situation many results from the usual (complex) theory of plurisubharmonic functions (this investigation was started in [2]). Sections 5 and 6 of this article follow very closely the complex case [10].

This article is organized as follows. In Section 2 we review the necessary facts from the theory on non-commutative determinants; the exposition follows [2]. In Section 3 we review the theory of plurisubharmonic functions of quaternionic variables as it was developed in [2]. In Section 4 we construct the matrix valued measure $\left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j} \right)$ for any (finite) psh function u on Ω . This construction is a quaternionic version of the well-known analogous construction in the complex case (see [43], p. 70). This construction will be used in the proof of Theorem 1.3.

In Section 5 we construct for any finite psh function u an operator $\Phi(u)$ which is essentially $\left(\det \frac{\partial^2 u}{\partial q_i \partial \bar{q}_i}\right)^{\frac{1}{n}}$ (following Section 5 of the article [10] by Bedford and Taylor). This operator plays an important technical role in the proof of Theorem 1.3. In Section 6 we establish several facts on the envelopes of functions from the Perron–Bremermann families following closely again the technique developed in the complex case in [10]. In Section 7 we prove Theorem 1.4 on the existence of C^∞ -regular solution of the Dirichlet problem in the unit ball under appropriate assumptions on the regularity of the initial data. In Section 8 we prove Theorem 1.3; the proof uses the results of all previous sections. In Section 9 we discuss further the notion of strictly pseudoconvex domain in the quaternionic space. Thus we introduce the quaternionic analogue of the Levi form and consider some examples. In Section 9.3 we state some open questions.

2. Background from non-commutative linear algebra

In this section we review some material on non-commutative determinants. More precisely we will recall some facts on the Dieudonné and Moore determinants of quaternionic matrices following [2].

The Dieudonné determinant of quaternionic matrices behaves exactly like the absolute value of the usual determinant of real or complex matrices from all points of view (algebraic and analytic). Let us denote by $M_n(\mathbb{H})$ the set of all quaternionic $(n \times n)$ - matrices. The Dieudonné determinant D is defined on this set and takes values in non-negative real numbers:

$$D : M_n(\mathbb{H}) \longrightarrow \mathbb{R}_{\geq 0} .$$

Then one has the following (known) results.

Theorem 2.1. (i) *For any complex $(n \times n)$ - matrix X considered as quaternionic matrix, the Dieudonné determinant $D(X)$ is equal to the absolute value of the usual determinant of X .*

(ii) *For any quaternionic matrix X*

$$D(X) = D(X^t) = D(X^*) ,$$

where X^t and X^* denote the transposed and quaternionic conjugate matrices of X , respectively.

(iii) $D(X \cdot Y) = D(X)D(Y)$.

The following result is a weak version of the decomposition of the determinant in row (column).

Theorem 2.2. *Let $A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \dots & \dots & \dots \\ a_{n1} & \dots & a_{nn} \end{bmatrix}$ be a quaternionic matrix. Then*

$$D(A) \leq \sum_{i=1}^n |a_{ii}| D(M_{li}) .$$

Similar inequalities hold for any other row or column.

(In this theorem $|a|$ denotes the absolute value of a quaternion a , and M_{pq} denotes the minor of the matrix A obtained from it by deleting the p -th row and q -th column).

In a sense, the Dieudonné determinant provides the theory of *absolute value* of determinant. However it is not always sufficient and we lose many of the algebraic properties of the usual determinant. The notion of Moore determinant provides such a theory, but only on the class of quaternionic *hyperhermitian* matrices. Remember that a square quaternionic matrix A is called hyperhermitian if its quaternionic conjugate A^* is equal to A . The Moore determinant denoted by \det is defined on the class of all hyperhermitian matrices and takes real values. For the construction of the Moore determinant we refer to [2], Section 1.1, where one can also find the references to the original articles. The important advantage of the Moore determinant with respect to the Dieudonné determinant is that it depends polynomially on the entries of a matrix; it has already all the algebraic and analytic properties of the usual determinant of real symmetric and complex hermitian matrices. Let us state some of them.

Theorem 2.3. (i) *The Moore determinant of any complex hermitian matrix considered as quaternionic hyperhermitian matrix is equal to its usual determinant.*

(ii) *For any hyperhermitian matrix A and any quaternionic matrix C*

$$\det(C^*AC) = \det A \cdot \det(C^*C) .$$

Examples.

(a) Let $A = \text{diag}(\lambda_1, \dots, \lambda_n)$ be a diagonal matrix with real λ_i 's. Then A is hyperhermitian and its Moore determinant $\det A = \prod_i \lambda_i$.

(b) A general hyperhermitian 2×2 matrix A has the form

$$A = \begin{bmatrix} a & q \\ \bar{q} & b \end{bmatrix} ,$$

where $a, b \in \mathbb{R}$, $q \in \mathbb{H}$. Then its Moore determinant is equal to $\det A = ab - q\bar{q}$.

Let us remind the definition of positive definiteness of hyperhermitian quaternionic matrix following [2].

Definition 2.4. Let $A = (a_{ij})_{i,j=1}^n$ be a hyperhermitian quaternionic matrix. A is called *non-negative definite* if for every n -column of quaternions $\xi = (\xi_i)_{i=1}^n$ one has

$$\xi^* A \xi = \sum_{i,j} \bar{\xi}_i a_{ij} \xi_j \geq 0 .$$

Similarly, A is called *positive definite* if the above expression is strictly positive once $\xi \neq 0$.

In terms of the Moore determinant one can prove the generalization of the classical Sylvester criterion of positive definiteness of hyperhermitian matrices (Theorem 1.1.13 in [2]). In terms of the Moore determinant one can introduce the notion of the mixed discriminant and to prove the analogs of Alexandrov's inequalities for mixed discriminants (Theorem 1.1.15 and Corollary 1.1.16 in [2]).

The (well-known) relation between the Dieudonné and Moore determinants is as follows: for any hyperhermitian matrix X

$$D(X) = |\det X| .$$

Note that the Dieudonné determinant was introduced originally by J. Dieudonné in [20] (see also [5] for his theory). It can be defined for arbitrary (non-commutative) field. On more

modern language this result can be formulated as a computation of the K_1 -group of a non-commutative field (see e.g., [57]). Note also that there is a more recent, very general theory of non-commutative determinants (or quasideterminants) due to I. Gelfand and V. Retakh generalizing in certain direction the theory of the Dieudonné determinant and many other known theories of non-commutative determinants. It was first introduced in [27], see also [28, 30] and references therein for further developments and applications. In a recent article [29] the connection of the Moore and Dieudonné determinants of quaternionic matrices to the theory of quasideterminants was made very explicit and well understood.

We would also like to mention a different direction of a development of the *quaternionic* linear algebra started by D. Joyce [39] and applied by himself to hypercomplex algebraic geometry. We refer also to D. Quillen’s article [53] for further investigations in that direction. Another attempt to understand the quaternionic linear algebra from the topological point of view was done by the author in [3].

3. Review of the theory of psh functions of quaternionic variables

3.1. Some results from [2]

We recall the basic facts from the theory of plurisubharmonic (psh) functions of quaternionic variables established by the author in [2] (see Definition 1.1 in this article). The operators $\frac{\partial}{\partial \bar{q}}$ and $\frac{\partial}{\partial q}$ were defined in the introduction.

First one has the following simple fact (see Proposition 2.1.6 in [2]).

Proposition 3.1. *A real-valued, twice continuously differentiable function f on the domain $\Omega \subset \mathbb{H}^n$ is quaternionic plurisubharmonic if and only if at every point $q \in \Omega$ the matrix $(\frac{\partial^2 f}{\partial q_i \partial \bar{q}_j})(q)$ is non-negative definite.*

Note that the matrix in the statement of proposition is quaternionic hyperhermitian (since the function f is real valued). The more important thing is that in analogy to the real and complex cases one can define for any continuous quaternionic plurisubharmonic function f a non-negative measure $\det(\frac{\partial^2 f}{\partial q_i \partial \bar{q}_j})$, where \det denotes the Moore determinant (this measure is obviously defined for smooth f). One has the following continuity result.

Theorem 3.2. *Let $\{f_N\}$ be a sequence of continuous quaternionic plurisubharmonic functions in a domain $\Omega \subset \mathbb{H}^n$. Assume that this sequence converges uniformly on compact subsets to a function f . Then f is continuous quaternionic plurisubharmonic function. Moreover, the sequence of measures $\det(\frac{\partial^2 f_N}{\partial q_i \partial \bar{q}_j})$ weakly converges to the measure $\det(\frac{\partial^2 f}{\partial q_i \partial \bar{q}_j})$.*

The proofs of analogous results in real and complex cases can be found in [8], where the exposition of this topic follows the approach of Chern–Levine–Nirenberg [18] and Rauch–Taylor [55]. For the complex case we refer also to the classical book by P. Lelong [43].

The next result is called the *minimum principle* (Theorem 2.2.1 in [2]).

Theorem 3.3. *Let Ω be a bounded open set in \mathbb{H}^n . Let u, v be continuous functions on $\bar{\Omega}$ which are plurisubharmonic in Ω . Assume that*

$$\det \left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j} \right) \leq \det \left(\frac{\partial^2 v}{\partial q_i \partial \bar{q}_j} \right) \text{ in } \Omega .$$

Then

$$\min \{u(z) - v(z) | z \in \bar{\Omega}\} = \min \{u(z) - v(z) | z \in \partial\Omega\} .$$

3.2. Diffeomorphisms preserving psh functions

In this section we prove the following proposition.

Proposition 3.4. *Let $\Omega \subset \mathbb{H}^n$ be a domain. Let $F : \Omega \rightarrow \Omega$ be a diffeomorphism such that for every open set $\mathcal{O} \subset \Omega$ and for any psh function f on \mathcal{O} the function $F^* f$ is psh on $F^{-1}(\mathcal{O})$. Then F is an affine transformation which can be written as a composition of a translation and a linear transformation from the group $GL_n(\mathbb{H})Sp(1)$.*

In the statement of the theorem the group $GL_n(\mathbb{H})Sp(1)$ is defined as follows. On the right quaternionic space \mathbb{H}^n there is a left action of the group of \mathbb{H} -linear invertible transformations $GL_n(\mathbb{H})$. Also the group $Sp(1)$ of norm one quaternions acts on \mathbb{H}^n from the right. Both actions commute and the group they generate is denoted by $GL_n(\mathbb{H})Sp(1)$. Note that it is isomorphic to $(GL_n(\mathbb{H}) \times Sp(1))/\{\pm Id\}$. Now let us prove the proposition. Note also that all such affine transformations preserving the domain Ω must preserve the class of psh functions (see [2], Section 2.1).

Proof. Let U be any domain in \mathbb{H}^1 and let $m : U \rightarrow \Omega$ be any \mathbb{H} -linear map. Let $p : \Omega \rightarrow \mathbb{H}^1$ be any \mathbb{H} -linear projection. Consider the composition $p \circ F \circ m : U \rightarrow \mathbb{H}^1$. It is easy to see that this map preserves the class of psh functions which is one-dimensional case means just that it preserves the class of subharmonic functions. Hence $p \circ F \circ m$ preserves the class of harmonic functions (i.e., it is so called *harmonic morphism*, see e.g., [9] for more details and references). However there is a general result of B. Fuglede [24] which says the following. Let $g : M \rightarrow N$ be a smooth map between Riemannian manifolds of the same dimension greater than 2 which preserves the class of harmonic functions (in the above sense). Then g is a conformal mapping with the constant coefficient of conformality. When M and N are linear vector spaces with Euclidean metrics this result together with the classical Liouville theorem imply that g is a composition of homothety, translation, and orthogonal transformation.

It easily follows that our original map F is an affine transformation. Also it is easy to see that F is a composition of a translation and a transformation from $GL_n(\mathbb{H})Sp(1)$. □

4. The distribution $\left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j}\right)$

In this section we will define the matrix-valued measure $\left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j}\right)$ for any (finite) psh function u on Ω . This construction is a quaternionic version of the well-known analogous construction in the complex case (see [43], p. 70).

Let us denote by \mathcal{H}_n the (real) linear space of $n \times n$ quaternionic hyperhermitian matrices. Let

$$\mathcal{C} := \{\xi \in \mathcal{H}_n | \xi \geq 0\} .$$

Thus \mathcal{C} is a closed convex cone. On the space \mathcal{H}_n one has the bilinear symmetric form $(\cdot, \cdot) : \mathcal{H}_n \times \mathcal{H}_n \rightarrow \mathbb{R}$ defined by

$$(A, B) = \text{ReTr}(A \cdot B) ,$$

where for any $n \times n$ quaternionic matrix $X = (x_{ij})$, $\text{ReTr}(X) := \sum_{i=1}^n \text{Re } x_{ii}$. Note also that for any quaternionic matrices X and C with C invertible, one has $\text{ReTr}(CXC^{-1}) = \text{ReTr } X$.

We easily have the following.

Claim 4.1. (i) (\cdot, \cdot) is a perfect pairing on \mathcal{H}_n .

(ii) For any matrices $A, B \in \mathcal{C}$ one has $(A, B) \geq 0$.

(iii) The dual cone $\mathcal{C}^o := \{\xi \in \mathcal{H}_n \mid (\xi, \eta) \geq 0 \forall \eta \in \mathcal{C}\}$ coincides with \mathcal{C} .

Definition 4.2. One says that an \mathcal{H}_n -valued distribution ψ on the domain Ω is *non-negative* ($\psi \geq 0$) if for any smooth compactly supported function f on Ω with values in the cone \mathcal{C} one has $\psi(f) \geq 0$. One can call such a ψ \mathcal{C} -valued.

As in the usual scalar valued case one has the following result. (For the scalar valued case see [25].)

Proposition 4.3. Any \mathcal{C} -valued distribution on Ω is of zero order, i.e., (non-negative) \mathcal{H}_n -valued measure.

We also have the following result (which easily follows from the scalar valued case).

Lemma 4.4. Any locally bounded sequence of \mathcal{H}_n -valued measures on Ω has a weakly convergent subsequence.

Note also that for any \mathcal{H}_n -valued distribution (resp. measure) μ on Ω one can define in the obvious way its trace $\text{Tr } \mu (= \text{ReTr } \mu)$, which is a real valued distribution (resp. measure).

Proposition 4.5. The sequence of \mathcal{C} -valued measures $\{\mu_j\}$ is (locally) bounded iff the sequence of real valued measures $\{\text{Tr } \mu_j\}$ is (locally) bounded.

Proof. It immediately follows from the fact that a subset $X \subset \mathcal{C}$ is bounded iff the set $\{\text{Tr } x \mid x \in X\}$ is bounded. □

Let us now define for any quaternionic psh function u on Ω the \mathcal{C} -valued measure $(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j})$ which has the usual meaning for C^2 -smooth function u . Let u be an arbitrary (finite) quaternionic psh function on Ω . By [2], Section 2.1, u is subharmonic. But every finite subharmonic function is locally integrable (see e.g., [56], Chapter 1, Section 1.4). Hence we can define

$$u_\varepsilon := u \star \chi_\varepsilon,$$

where $\chi_\varepsilon(z) = \frac{1}{\varepsilon^{4n}} \chi(\frac{z}{\varepsilon}) \geq 0$ is the usual smoothing kernel (like as in the complex situation, see e.g., [37], p. 45). Then u_ε are C^∞ -smooth psh functions. Hence $(\frac{\partial^2 u_\varepsilon}{\partial q_i \partial \bar{q}_j}) \geq 0$ for all $\varepsilon > 0$.

Proposition-Definition 4.6. For any quaternionic psh function u on Ω the \mathcal{H}_n -valued measures $(\frac{\partial^2 u_\varepsilon}{\partial q_i \partial \bar{q}_j})$ converge weakly to a non-negative \mathcal{H}_n -valued measure as $\varepsilon \rightarrow 0$. This measure will be denoted by $(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j})$.

It is easy to see that if $u \in C^2(\Omega)$ then the limit measure has its usual meaning.

Proof. First let us show that the measures $\frac{\partial^2 u_\varepsilon}{\partial q_i \partial \bar{q}_j}$ are locally bounded. By Proposition 4.5 it is

sufficient to show that their traces are locally bounded. But $\text{Tr}(\frac{\partial^2 u_\varepsilon}{\partial q_i \partial \bar{q}_j}) = \Delta u_\varepsilon \geq 0$. Let $K \subset \Omega$ be any compact subset. Let $\gamma \geq 0$ be a smooth function with compact support on Ω which is equal to 1 on K . Then

$$\begin{aligned} \int_K \Delta u_\varepsilon d \text{ vol} &\leq \int_\Omega \Delta u_\varepsilon \cdot \gamma d \text{ vol} = \int_\Omega u_\varepsilon \cdot \Delta \gamma d \text{ vol} \\ &\leq \|\Delta \gamma\|_{C(\Omega)} \cdot \int_{\text{supp } \gamma} u_\varepsilon d \text{ vol} \leq \|\Delta \gamma\|_{C(\Omega)} \cdot \int_{\text{supp}(\gamma) + \varepsilon B} |u| d \text{ vol} \\ &= \|\Delta \gamma\|_{C(\Omega)} \cdot \|u\|_{L^1(\text{supp}(\gamma) + \varepsilon B)}, \end{aligned}$$

where B denotes the unit Euclidean ball in \mathbb{H}^n . This proves the local boundedness of the sequence of measures $(\frac{\partial^2 u_\varepsilon}{\partial q_i \partial \bar{q}_j})$. Hence by Lemma 4.4 for any sequence $\{\varepsilon_N\} \rightarrow 0$ the sequence of measures $(\frac{\partial^2 u_{\varepsilon_N}}{\partial q_i \partial \bar{q}_j})$ has a weakly convergent subsequence. It remains to show that the limit does not depend on the choice of subsequence.

Fix an arbitrary $\phi \in C^\infty(\Omega)$. We easily get for any i, j

$$\int_\Omega \phi \cdot \frac{\partial^2 u_\varepsilon}{\partial q_i \partial \bar{q}_j} d \text{ vol} = \int_\Omega u_\varepsilon \cdot \frac{\partial^2 \phi}{\partial q_i \partial \bar{q}_j} d \text{ vol} \rightarrow \int_\Omega u \cdot \frac{\partial^2 \phi}{\partial q_i \partial \bar{q}_j} d \text{ vol}.$$

Namely for smooth ϕ the limit does not depend on the choice of subsequence. This implies the statement. □

Theorem 4.7. (i) Let $\{u_N\}$ be a sequence of quaternionic psh functions on a domain $\Omega \subset \mathbb{H}^n$ which is uniformly bounded from above on every compact subset of Ω . Then either $u_N \rightarrow -\infty$ uniformly on compact subsets of Ω , or else there is a subsequence $\{u_{N_k}\}$ which converges in $L^1_{\text{loc}}(\Omega)$. If $u_N \neq -\infty$ for all N and u_N converge in the sense of distributions to a distribution U , then U is defined by a psh function u and $u_N \rightarrow u$ in $L^1_{\text{loc}}(\Omega)$.

(ii) Assume that a sequence $\{u_N\}$ of quaternionic psh functions on Ω converges in $L^1_{\text{loc}}(\Omega)$ to a quaternionic psh function u . Then one has a weak convergence of measures

$$\left(\frac{\partial^2 u_N}{\partial q_i \partial \bar{q}_j}\right) \rightarrow \left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j}\right).$$

To prove this theorem we will need a lemma which is a quaternionic analog of the corresponding complex result (see [38], Theorem 4.1.7).

Lemma 4.8. Let u be a function defined on a domain $\Omega \subset \mathbb{H}^n$. Assume that $u_A(z) := u(Az)$ is subharmonic in $\Omega_A := \{z | Az \in \Omega\}$ for every invertible linear quaternionic transformation A (i.e., $\forall A \in GL_n(\mathbb{H})$). Then u is quaternionic psh.

Assuming this lemma let us prove Theorem 4.7.

Proof of Theorem 4.7. (i) This part of the theorem is known to be true if one replaces in its statement the word ‘‘psh’’ by the word ‘‘subharmonic’’ (see [38], Theorem 3.2.12). In order to deduce part (i) of the theorem from that result it remains to show that the limit function u is psh (and not just subharmonic). But this immediately follows from Lemma 4.8.

(ii) First note that the measures $(\frac{\partial^2 u_N}{\partial q_i \partial \bar{q}_j})$, $N \geq 1$ are uniformly locally bounded in Ω . This is proved exactly as in Proposition 4.6.

Hence choosing a subsequence if necessary we may assume that this sequence of measures converges weakly to an \mathcal{H}_n -valued measure $(v_{i\bar{j}})$. We have to prove that $v_{i\bar{j}} = \frac{\partial^2 u}{\partial q_i \partial \bar{q}_j}$. To see it fix an arbitrary function $\phi \in C_0^\infty(\Omega)$. Then

$$\int_{\Omega} \frac{\partial^2 u_N}{\partial q_i \partial \bar{q}_j} \cdot \phi \, d \text{ vol} = \int_{\Omega} u_N \cdot \frac{\partial^2 \phi}{\partial q_i \partial \bar{q}_j} \, d \text{ vol} \longrightarrow \int_{\Omega} u \cdot \frac{\partial^2 \phi}{\partial q_i \partial \bar{q}_j} \, d \text{ vol} = \int_{\Omega} \frac{\partial^2 u}{\partial q_i \partial \bar{q}_j} \phi \cdot d \text{ vol} \, ,$$

where the first and the last equalities can be easily deduced from the assumptions. The result follows. □

It remains to prove Lemma 4.8.

Proof of Lemma 4.8. The proof is an easy modification of the proof of Theorem 4.1.7 in [38]. Fix $z \in \Omega$. The function $u(z_1 + w_1, z_2 + \varepsilon w_2, \dots, z_n + \varepsilon w_n)$ is subharmonic in w by hypothesis, $0 < \varepsilon < 1$. Hence

$$u(z) \leq \int_{|\zeta|=1} u(z_1 + r\zeta_1, z_2 + r\varepsilon\zeta_2, \dots, z_n + r\varepsilon\zeta_n) d\omega(\zeta) \, ,$$

where $\omega(\zeta)$ is the normalized Lebesgue measure on the unit sphere. Since u is upper semi-continuous and locally bounded above, the Fatou lemma implies as $\varepsilon \rightarrow 0$ that

$$u(z) \leq \int_{|\zeta|=1} u(z_1 + r\zeta_1, z_2, \dots, z_n) d\omega(\zeta) \, .$$

The last inequality and Theorem 3.2.3 in [38] imply that the function $z_1 \mapsto u(z_1, z_2, \dots, z_n)$ is subharmonic. The subharmonicity of the restrictions to other quaternionic lines follows from the invariance under quaternionic linear transformations. □

5. The operator $\Phi(u)$

In the rest of the paper we will denote sometimes for brevity the matrix $\left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j}\right)$ by $(\partial^2 u)$. Following Section 5 of the article [10] by Bedford and Taylor we will define for any finite psh function u an operator $\Phi(u)$ which is essentially $(\det \partial^2 u)^{\frac{1}{n}}$. It is closely related to the operator $\det(\partial^2 u)$, but it is defined for arbitrary finite psh function u .

As in the previous section we will denote by \mathcal{C} the cone of non-negative definite quaternionic hyperhermitian $n \times n$ matrices. Consider the function

$$\Psi(\xi) = (\det(\xi))^{\frac{1}{n}}, \xi \in \mathcal{C} \, .$$

Proposition 5.1. *The function Ψ is a continuous, nonnegative, concave function which is homogeneous of degree 1 on the cone \mathcal{C} .*

Proof. Concavity follows from Theorem 1.1.17 (ii) of [2]. The other properties are trivial. □

Let μ be a vector valued Borel measure on $\Omega \subset \mathbb{H}^n$ with values in the cone \mathcal{C} . Let us define a nonnegative Borel measure $\Psi(\mu)$ on Ω as follows. Choose a scalar valued nonnegative Borel measure λ on Ω so that μ is absolutely continuous with respect to λ . Then by the Radon–Nikodim theorem $d\mu = h \cdot d\lambda$ where h is a Borel measurable function on Ω with values in \mathcal{C} .

Definition 5.2. $\Psi(\mu) := \Psi(h)\lambda$.

It is easy to see that this definition is independent of the choice of the measure λ . The following proposition is trivial.

Proposition 5.3. *If μ and ν are Borel measures on Ω with values in \mathcal{C} then*

- (1) $\Psi(\alpha\mu) = \alpha\Psi(\mu)$ if $\alpha \geq 0$.
- (2) If μ, ν are mutually singular then $\Psi(\mu + \nu) = \Psi(\mu) + \Psi(\nu)$.
- (3) $\Psi(\mu)$ is absolutely continuous with respect to μ .
- (4) $\Psi(t\mu + (1-t)\nu) \geq t\Psi(\mu) + (1-t)\Psi(\nu)$, $0 < t < 1$.

Proposition 5.4. *If $\chi \geq 0$ is a continuous function with compact support then*

$$\Psi(\mu \star \chi) \geq \Psi(\mu) \star \chi$$

on any compact set Ω' with $\Omega' + \text{support}(\chi) \subset \Omega$.

Proof. The proof is exactly the same as in the complex case (see Proposition 5.4 in [10]). It is essentially based on Proposition 5.3 and general measure theoretic construction of Goffman and Serrin [32]. We do not reproduce it here. \square

Proposition 5.5. *Let μ_j be a sequence of Borel measures on Ω with values in \mathcal{C} which converges weakly to a Borel measure μ . Suppose also that Borel measures $\Psi(\mu_j)$ converge weakly. Then*

$$\Psi(\mu) \geq \lim_{j \rightarrow \infty} \Psi(\mu_j).$$

Proof. Again the proof is exactly the same as in the complex case (see Proposition 5.6 of [10]). Note that in turn this is a special case of [32], Theorem 3, p. 165 with slight modifications. \square

To define the operator $\Phi(u)$ for any psh function u note that by Proposition-Definition 4.6 the matrix of Borel measures $\left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j}\right)$ takes values in the cone \mathcal{C} .

Definition 5.6.

$$\Phi(u) := \Psi\left(\left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j}\right)\right).$$

Theorem 5.7. *Let u, v, u_j be finite psh on $\Omega \subset \mathbb{H}^n$. Then*

- (1) $\Phi(\alpha u) = \alpha\Phi(u)$, $\alpha \geq 0$,
- (2) $\Phi(tu + (1-t)v) \geq t\Phi(u) + (1-t)\Phi(v)$, $0 < t < 1$,
- (3) If $\chi \geq 0$ is a continuous function with compact support then

$$\Phi(u \star \chi) \geq \Phi(u) \star \chi$$

on any open set Ω' with $\Omega' + \text{support}(\chi) \subset \Omega$;

(4) if $u_j \rightarrow u$ as distributions on Ω and if the sequence of measures $\Phi(u_j)$ converges weakly then

$$\Phi(u) \geq \lim_{j \rightarrow \infty} \Phi(u_j).$$

(5) If $u_\varepsilon = u \star \chi_\varepsilon$ where $\chi_\varepsilon(z) = \frac{1}{\varepsilon^{4n}} \chi(\frac{z}{\varepsilon}) \geq 0$ is the usual smoothing kernel (like in the complex situation, see e.g., [37], p. 45) then

$$\lim_{\varepsilon \rightarrow 0} \Phi(u_\varepsilon) = \Phi(u) .$$

(6) $\Phi(\max\{u, v\}) \geq \min\{\Phi(u), \Phi(v)\}$.

Proof. Assertions (1), (2) follow from Proposition 5.3. Assertion (3) follows from Proposition 5.4. Let us prove (4). By Theorem 4.7 $(\partial^2 u_j) \rightarrow (\partial^2 u)$ in the weak topology on the space of \mathcal{H}_n -valued measures on Ω . This and Proposition 5.5 imply assertion (4). The assertions (5), (6) are proved exactly as in the complex case, and we refer to the proof of Theorem 5.7 in [10]. □

Theorem 5.8. Let u be a finite psh function on Ω such that the regularizations of $u, u_\varepsilon = u \star \chi_\varepsilon$, have the property that $\det(\partial^2 u_\varepsilon)$ is a bounded family of Borel measures on each compact subset of Ω . Then

(1) $\Phi(u)$ is absolutely continuous with respect to the Lebesgue measure, and if $\Phi(u) = g \cdot d \text{ vol}$ then $g \in L^n_{\text{loc}}(\Omega)$, i.e., g^n is locally integrable;

(2) if u is continuous and if $\det(\partial^2 u) = f \cdot d \text{ vol} + dv$ is the Lebesgue decomposition of the non-negative measure $\det(\partial^2 u)$ into its absolutely continuous and singular parts then $g^n \leq f$;

(3) if $\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j} = f_{i\bar{j}} + dv_{i\bar{j}}$ is the Lebesgue decomposition of the Borel measures $\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j}$ then $g = (\det(f_{i\bar{j}}))^{\frac{1}{n}}$.

Proof. The proof of this theorem is exactly as in the complex case, and we refer to the proof of Theorem 5.8 in [10]. □

Remark 5.9. The assumptions of Theorem 5.8 are satisfied when u is a continuous psh function.

6. On upper envelopes

Let $\Omega \subset \mathbb{H}^n$ be a domain. For functions $f \geq 0$ on Ω , and $\phi \in C(\partial\Omega)$ let us denote by

$$\mathcal{B}(\phi, f) := \left\{ v \text{ is finite psh on } \Omega \mid \Phi(v) \geq f \cdot \text{vol}, \overline{\lim}_{q \rightarrow \zeta} v(q) \leq \phi(\zeta) \forall \zeta \in \partial\Omega \right\} .$$

The main result of this section is the following result which is a quaternionic analog of Theorem 6.2 from [10].

Theorem 6.1. Let Ω be a strictly pseudoconvex bounded domain with smooth boundary. Let $\phi \in C(\partial\Omega)$, $f \in C(\bar{\Omega})$, $f \geq 0$. Let

$$u(z) := \sup_{v \in \mathcal{B}(\phi, f)} v(z) .$$

Then $u \in C(\bar{\Omega})$, u is psh in Ω , and $u|_{\partial\Omega} \equiv \phi$. Moreover, $u \in \mathcal{B}(\phi, f)$.

The proof of this theorem closely follows [10] and [13]; we are going to present it. As in [10], we will need two lemmas. Throughout this section Ω will denote a strictly pseudoconvex bounded domain in \mathcal{H}_n .

Lemma 6.2. Fix $\varepsilon > 0$. Then for every $\zeta \in \partial\Omega$ there exists $v_\zeta \in \mathcal{B}(\phi, f) \cap C(\bar{\Omega})$ such that

$$\phi(\zeta) - \varepsilon \leq v_\zeta(\zeta) \leq \phi(\zeta) .$$

Lemma 6.3. Fix $\varepsilon > 0$. Then for every $\zeta \in \partial\Omega$ there exists $h_\zeta \in C(\bar{\Omega})$ which is psh in Ω such that

- 1) $h_\zeta(z) \leq \phi(z)$ for all $z \in \partial\Omega$.
- 2) $h_\zeta(\zeta) \geq \phi(\zeta) - \varepsilon$.

First let us show that Lemma 6.3 implies Lemma 6.2. Choose a large constant $K \gg 0$ such that $\Phi(K|z|^2) = K\Phi(|z|^2) > f$. Let $\tilde{\phi}(z) := \phi(z) - K(|z|^2 - |\zeta|^2)$. Let h_ζ be as in Lemma 6.3 applied for the function $\tilde{\phi}$ instead of ϕ . Then the function $v_\zeta(z) := h_\zeta(z) + K(|z|^2 - |\zeta|^2)$ satisfies Lemma 6.2.

Proof of Lemma 6.3. By assumption (at least locally in a neighborhood of ζ) $\Omega = \{F < 0\}$ where F is twice continuously differentiable function on \mathbb{H}^n which is strictly psh and $\nabla F|_{\partial\Omega} \neq 0$. Let $G(z) := F(z) - \delta|z - \zeta|^2$. For small δ the function G is psh in a neighborhood \mathcal{O} of ζ . Clearly

$$G(\zeta) = 0, G|_{(\bar{\Omega} - \{\zeta\}) \cap \mathcal{O}} < 0 .$$

Take small $\lambda > 0$ and consider

$$F^*(z) := \max\{G, -\lambda\} .$$

It is clear that

- 1) F^* is psh in Ω and continuous in $\bar{\Omega}$;
- 2) $F^*(\zeta) = 0$;
- 3) $F^*|_{\bar{\Omega} - \zeta} < 0$.

For given $\varepsilon > 0$ there exists a constant $C \gg 0$ such that

$$C \cdot F^*(z) + \phi(\zeta) < \phi(z) + \varepsilon \text{ for all } z \in \partial\Omega .$$

Let $h_\zeta(z) := C \cdot F^*(z) + \phi(\zeta) - \varepsilon$. Then

$$\begin{aligned} h_\zeta(z) &< \phi(z) \text{ for all } z \in \partial\Omega , \\ h_\zeta(\zeta) &= \phi(\zeta) - \varepsilon . \end{aligned}$$

This proves Lemma 6.3. □

Proof of Theorem 6.1. Let us define the upper regularization of u in $\bar{\Omega}$ as usual:

$$u^*(z) := \limsup_{z' \rightarrow z} u(z') .$$

It is easy to see that u^* is psh in Ω (e.g., using Lemma 4.8 and the analogous classical result for subharmonic functions, see [56] Chapter 1, Section 1.5). Clearly $u \leq u^*$.

It follows from Lemma 6.2 that

$$u(z) \geq \phi(z) \forall z \in \partial\Omega .$$

In order to prove that u coincides with ϕ on $\partial\Omega$ let us prove the converse inequality (following [13]). Fix $\zeta \in \partial\Omega$. As in the proof of Lemma 6.3 construct F^* . Let $F^{**} := -F^*$. Then

1) F^{**} is super-harmonic;

2) $F^{**}(\zeta) = 0$;

3) $F^{**}(z) > 0$ for $z \in \bar{\Omega} - \zeta$.

In the classical potential theory F^{**} is called *barrier*, and hence the classical Dirichlet problem for harmonic functions is solvable on Ω . Hence there exists a harmonic in Ω function $h \in C(\bar{\Omega})$ such that $h|_{\partial\Omega} \equiv \phi$. Since every function from $\mathcal{B}(\phi, f)$ is subharmonic we obtain that $u(z) \leq h(z) \forall z \in \bar{\Omega}$. Since h is continuous we get

$$u^*(z) \leq h(z) \text{ on } \bar{\Omega},$$

$$\text{hence } u^*(z) \leq \phi(z) \text{ on } \partial\Omega.$$

Finally we deduce

$$u(z) = u^*(z) = \phi(z), \forall z \in \partial\Omega.$$

By H. Cartan’s theorem (see e.g., [56]) $u = u^*$ almost everywhere in Ω . Since $\mathcal{B}(\phi, f)$ is closed under taking finite maximums [Theorem 5.7 (6)] Choquet’s lemma (see e.g., [56]) implies that one can choose an increasing sequence of functions $u_j \in \mathcal{B}(\phi, f)$ which converges to u almost everywhere in Ω . But then $u_j \rightarrow u^*$ in $L^1_{\text{loc}}(\Omega)$. Hence by Theorem 4.7 (ii) $\partial^2 u_j \rightarrow \partial^2 u^*$ weakly. Hence by Proposition 5.5

$$\Phi(u^*) \geq \lim_{j \rightarrow \infty} \Phi(u_j) \geq \mu := f \cdot \text{vol} = \mu.$$

Hence $u^* \in \mathcal{B}(\phi, f)$. Since $u \leq u^*$ in $\bar{\Omega}$ we conclude

$$u \equiv u^*.$$

Hence u is psh and $u \in \mathcal{B}(\phi, f)$. Hence to finish the proof of Theorem 6.1 it remains to prove the continuity of u in $\bar{\Omega}$.

First we will prove the following

Claim 6.4. u is continuous at all points of the boundary $\partial\Omega$.

Proof. Fix any $\varepsilon > 0$ and any $\zeta \in \partial\Omega$. By Lemma 6.2 there exists a function $v_\zeta \in \mathcal{B}(\phi, f) \cap C(\bar{\Omega})$ such that $\phi(\zeta) - \varepsilon \leq v_\zeta(\zeta)$. Since v_ζ is continuous, in a small neighborhood U of ζ in $\bar{\Omega}$

$$v_\zeta(z) > \phi(\zeta) - 2\varepsilon.$$

But $u(z) \geq v_\zeta(z)$. Hence $u(z) > \phi(\zeta) - 2\varepsilon$ for $z \in U$. Hence $\liminf_{z \rightarrow \zeta} u(z) \geq \phi(\zeta)$. But u is upper semi-continuous in $\bar{\Omega}$ (since $u \equiv u^*$), hence $\limsup_{z \rightarrow \zeta} u(z) \leq u(\zeta) = \phi(\zeta)$. Hence u is continuous at ζ . This proves the claim. □

Now let us continue proving Theorem 6.1. Fix $\varepsilon > 0$. Let $\omega(\varepsilon) > 0$ be such that

$$\sup_{\substack{z, z' \in \bar{\Omega} \\ |z-z'| < \omega(\varepsilon)}} |f(z) - f(z')| < \frac{\varepsilon}{2} \text{ and } \sup_{\substack{z, z' \in \bar{\Omega}, \text{dist}(z, \partial\Omega) < 3\omega(\varepsilon) \\ |z-z'| < \omega(\varepsilon)}} |u(z) - u(z')| < \varepsilon,$$

where $\text{dist}(z, \partial\Omega)$ denotes the shortest distance from z to $\partial\Omega$. Existence of such $\omega(\varepsilon)$ follows from Claim 6.4 and the continuity of f . Let $\tau \in \mathbb{H}^n$ be any vector with $|\tau| < \omega(\varepsilon)$ (where $|\cdot|$ denotes the norm of the vector). Let

$$v(z) := u(z + \tau) + \varepsilon \cdot |z|^2 - (L + 1)\varepsilon,$$

where L be any constant satisfying $L > |z|^2$ for all $z \in \Omega$. Let

$$V(z, \tau) := \begin{cases} u(z), & \text{if } z \in \bar{\Omega}, z + \tau \notin \Omega \\ \max\{u(z), v(z)\}, & \text{if } z \in \bar{\Omega}, z + \tau \in \Omega. \end{cases}$$

Lemma 6.5. $V(z, \tau) \in \mathcal{B}(\phi, f)$.

Let us postpone the proof of this lemma and let us finish the proof of Theorem 6.1. Lemma 6.5 implies in particular that $V(z, \tau) \leq u(z)$ for all $z \in \Omega$. Hence for any $z, z + \tau \in \Omega$ such that $|\tau| < \omega(\varepsilon)$ we have

$$u(z + \tau) + \varepsilon|z|^2 - (L + 1)\varepsilon \leq u(z).$$

Hence for some constant C ,

$$u(z + \tau) - u(z) < C \cdot \varepsilon.$$

Replacing τ by $-\tau$ we get

$$|u(z + \tau) - u(z)| < C \cdot \varepsilon.$$

Hence u is continuous. □

Thus it remains to prove Lemma 6.5.

Proof of Lemma 6.5. Let us check all the conditions in the definition of $\mathcal{B}(\phi, f)$.

Claim 6.6. $V(z, \tau) \leq \phi(z)$ for all $z \in \partial\Omega$.

Proof. Indeed, if $z + \tau \notin \Omega$ then $V(z, \tau) = u(z) = \phi(z)$. If $z + \tau \in \Omega$ then either $V(z, \tau) = u(z) = \phi(z)$ or

$$\begin{aligned} V(z, \tau) &= u(z + \tau) + \varepsilon \cdot |z|^2 - (L + 1)\varepsilon \leq u(z + \tau) - \varepsilon \\ &= u(z) + (u(z + \tau) - u(z)) - \varepsilon \leq u(z) = \phi(z). \end{aligned} \quad \square$$

Let us define the subset $\Gamma := \{z \in \bar{\Omega} | z + \tau \in \partial\Omega\}$. Note that for any point $x \in \Gamma$, $\text{dist}(x, \partial\Omega) \leq \omega(\varepsilon)$. Let A be the $\omega(\varepsilon)$ -neighborhood of Γ . Then clearly for all $x \in A$ one has $\text{dist}(x, \partial\Omega) \leq 2\omega(\varepsilon)$.

Claim 6.7. For all $z \in A$ one has $V(z, \tau) = u(z)$. Hence $V(z, \tau)$ is upper semi-continuous in $\partial\Omega$.

Proof. Clearly it is sufficient to prove the first statement. We have to check that for $z \in A$, $v(z) \leq u(z)$. We have

$$\begin{aligned} v(z) &= u(z + \tau) + \varepsilon \cdot |z|^2 - (L + 1)\varepsilon \leq u(z + \tau) - \varepsilon \\ &\leq u(z) + (u(z + \tau) - u(z)) - \varepsilon \leq u(z) \end{aligned}$$

where the last inequality follows from the fact that $\text{dist}(z, \partial\Omega) \leq 2\omega(\varepsilon)$, $|\tau| < \omega(\varepsilon)$ and the definition of $\omega(\varepsilon)$. □

Since the maximum of two psh functions is psh we can easily get the following from the last claim.

Claim 6.8. $V(z, \tau)$ is psh in Ω .

To finish the proof of Lemma 6.5 it remains to prove the following.

Claim 6.9. $\Phi(V(z, \tau)) \geq \mu (= f \cdot d \text{ vol})$.

Proof. Let us denote by $\Gamma_0 := \Gamma \cap \Omega$. By Claim 6.7 in a small neighborhood of Γ_0 , or if $z + \tau \notin \Omega$, we have

$$\Phi(V(z, \tau)) = \Phi(u(z)) \geq \mu .$$

Now it remains to consider domain $\{z \in \Omega \mid z + \tau \in \Omega\}$. In this domain $V(z, \tau) = \max\{u(z), v(z)\}$. Hence by Theorem 5.7 (6) we get

$$\Phi(\max\{u, v\}) \geq \min\{\Phi(u), \Phi(v)\} .$$

Since $\Phi(u) \geq \mu$ let us prove that $\Phi(v) \geq \mu$. Indeed

$$\Phi(v(z)) \geq \Phi(u(z + \tau)) + 4\varepsilon \geq f(z + \tau) + 4\varepsilon \geq f(z) . \quad \square$$

Thus Lemma 6.5 and hence Theorem 6.1 are proved.

6.1. Other Perron–Bremermann families

Let Ω be a domain in \mathbb{H}^n . For brevity we will denote by $P(\Omega)$ the class of psh functions in Ω . Given $\phi \in C(\partial\Omega)$ and a non-negative measure $\mu = f \cdot d \text{ vol}$ on Ω , we define three Perron–Bremermann families of subsolutions to the Monge–Ampère equation (the first one was defined earlier in Section 5.1):

$$\mathcal{B}(\phi, f) := \{v \in P(\Omega) \mid \Phi(v) \geq \mu \text{ and } \limsup_{z \rightarrow z_0} v(z) \leq \phi(z_0), \text{ for all } z_0 \in \partial\Omega\};$$

$$C\mathcal{B}(\phi, f) := \mathcal{B}(\phi, f) \cap C(\bar{\Omega});$$

$$\mathcal{F}(\phi, \mu) := \{v \in P(\Omega) \cap C(\bar{\Omega}) \mid \det(\partial^2 v) \geq \mu \text{ and } v(z_0) \leq \phi(z_0) \text{ for all } z_0 \in \partial\Omega\}.$$

If $\mu = f \cdot d \text{ vol}$, $f \in L^n_{\text{loc}}(\Omega)$ then let $\mu^n := f^n \cdot d \text{ vol}$. If $v \in P(\Omega) \cap C(\bar{\Omega})$ then by Theorem 5.8 (2)

$$\Phi(v)^n \leq \det(\partial^2 v) ,$$

and consequently

$$C\mathcal{B}(\phi, f) \subset \mathcal{F}(\phi, \mu^n) .$$

By Theorem 5.8 (1) and Remark 5.9 if u is continuous then $\Phi(u)$ is absolutely continuous with respect to the Lebesgue measure, $\Phi(u) = g \cdot d \text{ vol}$, and $g \in L^n_{\text{loc}}(\Omega)$.

Proposition 6.10. *Let Ω be a bounded domain in \mathbb{H}^n and suppose that $u \in P(\Omega) \cap C(\bar{\Omega})$ satisfies $\det(\partial^2 u) = (\Phi(u))^n$. If $C\mathcal{B} := C\mathcal{B}(\phi, \Phi(u))$ and $\mathcal{F} := \mathcal{F}(\phi, \det(\partial^2 u))$, where $\phi = u|_{\partial\Omega}$, then $\sup\{v \mid v \in \mathcal{F}\} = \sup\{v \mid v \in C\mathcal{B}\} = u$.*

Proof. The remarks before this proposition and the assumption imply that $C\mathcal{B} \subset \mathcal{F}$. Hence $\sup\{v \mid v \in C\mathcal{B}\} \leq \sup\{v \mid v \in \mathcal{F}\}$. On the other hand obviously $u \in C\mathcal{B}$. Hence $u \leq \sup\{v \mid v \in C\mathcal{B}\}$. Thus it remains to show that $\sup\{v \mid v \in \mathcal{F}\} \leq u$. Fix any $v \in \mathcal{F}$. By the minimum principle, Theorem 3.3, $u - v$ attains its minimum on $\partial\Omega$. But since $u \geq v$ on $\partial\Omega$ we obtain that $u \geq v$ in $\bar{\Omega}$. The proposition is proved. \square

7. The Monge–Ampère equation in the Euclidean ball

In this section we prove the existence of the solution of the Dirichlet problem for the quaternionic Monge–Ampère equation for the unit Euclidean ball assuming sufficient regularity of the initial data f, ϕ . First let us introduce some notation.

Let B denote the open unit ball in \mathbb{H}^n ,

$$B := \{|q| < 1\}.$$

Let \bar{B} be its closure. The main result of this section is as follows.

Theorem 7.1. *Let $f \in C^\infty(\bar{B})$, $f > 0$. Let $\phi \in C^\infty(\partial B)$. There exists unique psh function $u \in C^\infty(\bar{B})$ which is a solution of the Dirichlet problem*

$$\det \left(\frac{\partial^2 u}{\partial q_i \partial \bar{q}_j} \right) = f, \\ u|_{\partial B} = \phi.$$

This (smooth) case will be used in the proof of the general case (Theorem 1.3). The method of the proof of this case is a modification of that of the article by Caffarelli–Kohn–Nirenberg–Spruck [15].

In this section we will denote by $\|g\|_k$ the C^k - norm of a function g in \bar{B} .

The proof uses the continuity method. In Section 7.1 we prove the first order a priori estimates. In Section 7.2 we prove the second order a priori estimates. In Section 7.3 we obtain $C^{2,\alpha}$ a priori estimates as an easy consequence of the results from Sections 7.1 and 7.2 and a general result from [15]. Then the higher smoothness results follow from these by the standard regularity theory of elliptic equations of second order (see e.g., [31, 41]).

7.1. First-order estimates

Proposition 7.2. *Assume that a psh function $u \in C^2(\bar{B})$ satisfies the quaternionic Monge–Ampère equation with $f > 0$ in \bar{B} . Then*

$$\|u\|_1 \leq C,$$

with a constant C depending only on $\|f\|_1, \|\phi\|_2$, and $\|f^{-1}\|_0$.

Proof. Let L be the linearization of the operator $v \mapsto \log(\det(\partial^2 v))$ at u . Explicitly this operator can be written

$$Lv = n f^{-1} \cdot \det \left(\partial^2 v, \partial^2 u [n - 1] \right).$$

Clearly $Lu = n$. Since u is strictly psh we have the following.

Claim. *The operator L is elliptic.*

Let D be a first order differential operator of the form $D = \frac{\partial}{\partial x_i}$, where x_i is one of the real coordinate axes in \mathbb{H}^n . First let us prove the following lemma.

Lemma 7.3.

$$\max_{\bar{B}} |Du| \leq \max_{\partial B} |Du| + C,$$

where C is a constant depending only on $\|f\|_1$, $\|\phi\|_1$, and $\|f^{-1}\|_0$.

Proof. We have

$$L(Du) = nf^{-1} \cdot \det \left(\partial^2(Du), \partial^2u[n-1] \right) = f^{-1} D \left(\det \left(\partial^2u \right) \right) = D(\log f).$$

Consider the function $w(q) := \pm Du + \lambda|q|^2$, with $\lambda \gg 0$. Then we get

$$Lw = \pm D(\log f) + \lambda L \left(|q|^2 \right).$$

But

$$L \left(|q|^2 \right) = 8nf^{-1} \cdot \det \left(I, \underbrace{\partial^2u, \dots, \partial^2u}_{n-1 \text{ times}} \right) = 8nf^{-1} \cdot \sum_{i=1}^n \det \left(M_{ii} \left(\partial^2u \right) \right),$$

where $M_{ii}(A)$ denotes the minor of a matrix A obtained from A by deleting the i -th row and the i -th column.

Claim. Let A be an invertible hyperhermitian matrix of order n . For any i , $1 \leq i \leq n$,

$$\left(A^{-1} \right)_{ii} = \frac{1}{\det A} \det M_{ii}(A).$$

Thus using this claim we get

$$Lw = \pm D(\log f) + 8n\lambda \operatorname{Tr} \left(\partial^2u \right)^{-1}.$$

For any hyperhermitian positive definite $(n \times n)$ matrix C one has $\frac{1}{n} \operatorname{Tr}(C) \geq (\det C)^{\frac{1}{n}}$. Hence we get

$$Lw \geq \pm D(\log f) + 8n^2\lambda \cdot \left(\det \left(\partial^2u \right) \right)^{-\frac{1}{n}} = \pm D(\log f) + 8n^2\lambda f^{-\frac{1}{n}}.$$

Since $f \in C^1(\bar{B})$ and f is bounded from below by a positive constant, one can choose a large λ such that the last expression will be positive. For such a λ by the maximum principle the function w achieves its maximum on the boundary ∂B . This proves Lemma 7.3.

Thus it remains to estimate the gradient ∇u on the boundary ∂B . First let $\tilde{\phi}$ denote any C^2 -smooth extension of ϕ inside the closed ball \bar{B} such that its C^2 -norm can be estimated by the C^2 -norm of ϕ . Consider the function $\tilde{\phi} + K(|q|^2 - 1)$ for large K . Let us denote this extension again by ϕ . Note that on the boundary ∂B it coincides with our original ϕ . Note also that for large K the function ϕ is psh and moreover,

$$\det \left(\partial^2\phi \right) \geq f = \det \left(\partial^2u \right).$$

Hence by the minimum principle $\phi \leq u$ in \bar{B} . Next let h be a harmonic function in B which extends ϕ . Then $u \leq h$. Hence on the boundary $|\nabla u| \leq \max\{|\nabla h|, |\nabla\phi|\}$. Thus Proposition 7.2 is proved. \square

7.2. Second-order estimates

Let D be any real first-order differential operator with constant coefficients which are not greater than one. First we need the following result.

Lemma 7.4. For a constant C depending only on $\|f\|_2, \|f^{-1}\|_0$

$$\max_{\bar{B}} D^2 u \leq \max_{\partial B} D^2 u + C .$$

Proof. We have

$$\begin{aligned} D^2(\log f) &= D^2 \left(\log \det \left(\partial^2 u \right) \right) = D \left(\frac{D(\det \partial^2 u)}{\det \partial^2 u} \right) \\ &= f^{-2} \left\{ D^2 \left(\det \partial^2 u \right) \cdot \det \left(\partial^2 u \right) - \left(D \left(\det \partial^2 u \right) \right)^2 \right\} \\ &= f^{-2} \left\{ D \left[n \cdot \det \left(\partial^2 (Du), \partial^2 u[n-1] \right) \right] \cdot \det \left(\partial^2 u \right) - \left[n \cdot \det \left(\partial^2 (Du), \partial^2 u[n-1] \right) \right]^2 \right\} \\ &= f^{-1} n \cdot \det \left(\partial^2 \left(D^2 u \right), \partial^2 u[n-1] \right) \\ &\quad + f^{-2} \left\{ n(n-1) \det \left(\partial^2 (Du)[2], \partial^2 u[n-2] \right) \cdot \det \left(\partial^2 u \right) \right. \\ &\quad \left. - \left[n \cdot \det \left(\partial^2 (Du), \partial^2 u[n-1] \right) \right]^2 \right\} . \end{aligned}$$

We need the following.

Lemma 7.5. Let A, B be hyperhermitian $(n \times n)$ -matrices, $A > 0$. Then

$$n(n-1) \cdot \det(B[2], A[n-2]) \cdot \det A - (n \cdot \det(B, A[n-1]))^2 \leq 0 .$$

Assuming this lemma let us finish the proof of Lemma 7.4. We get

$$D^2(\log f) \leq f^{-1} n \cdot \det \left(\partial^2 \left(D^2 u \right), \partial^2 u[n-1] \right) = L \left(D^2 u \right) .$$

Hence we have

$$L \left(D^2 u + \lambda |q|^2 \right) \geq D^2(\log f) + 8n^2 \lambda f^{-\frac{1}{n}} ,$$

where we have used the lower estimate on $L(|q|^2)$ from the previous section. For sufficiently large λ the last expression is positive. Hence by the maximum principle

$$\max_{\bar{B}} \left(D^2 u + \lambda |q|^2 \right) \leq \max_{\partial B} \left(D^2 u + \lambda |q|^2 \right) .$$

Thus Lemma 7.4 follows. □

Proof of Lemma 7.5. The function $A \mapsto \log(\det A)$ is concave on the cone of positive definite hyperhermitian matrices [see [2], Theorem 1.1.17 (i)]. Hence

$$\frac{d^2}{dt^2} (\log \det(A + tB))|_{t=0} \leq 0 .$$

Computing explicitly this derivative we obtain the lemma. □

Note now that in order to prove an estimate on the second derivatives of u it is sufficient to prove an upper estimate on it. Indeed let $q_l = t + i \cdot x + j \cdot y + k \cdot z$ be one of the quaternionic coordinates. Since u is psh we have $u_{tt} + u_{xx} + u_{yy} + u_{zz} \geq 0$. This and the upper estimates on the second derivatives of the form D^2u imply the lower estimates on them. The estimates on the mixed derivatives also can be obtained easily since

$$2u_{tx} = \left(\frac{\partial}{\partial t} + \frac{\partial}{\partial x} \right)^2 u - u_{tt} - u_{xx} .$$

Hence we have to prove an upper estimate of D^2u on ∂B . Let us introduce additional notation. Let $r(q) = |q|^2 - 1$. Then

$$B = \{r < 0\} .$$

We will denote the quaternionic units as follows:

$$e_0 = 1, e_1 = i, e_2 = j, e_3 = k .$$

Fix a coordinate system (q_1, \dots, q_n) on \mathbb{H}^n ; we will write $q_i = \sum_{\varepsilon=0}^3 e_\varepsilon x_i^\varepsilon$. Fix an arbitrary point $P \in \partial B$. We can choose such a coordinate system near this point that the inner normal to ∂B at P coincides with the axis x_n^0 . Also we will move the center of coordinates to P , i.e., we will assume that P coincides with 0. Let us denote the center of the ball B by R .

First we have the following trivial estimates:

$$\left| u_{x_i^\varepsilon x_j^\delta}(P) \right| \leq C \text{ for } (i, \varepsilon), (j, \delta) \neq (n, 0) .$$

(Note that here we also use the first order estimates of u and ϕ). Now let us prove the following estimate.

Lemma 7.6.

$$\left| u_{x_i^\varepsilon x_n^0}(P) \right| \leq C \text{ for } (i, \varepsilon) \neq (n, 0) ,$$

where C depends only on $\|f\|_2, \|\phi\|_3, \|f^{-1}\|_0$.

Proof. Clearly one can construct a vector field T on \mathbb{H}^n such that

- 1) $T(P) = \frac{\partial}{\partial x_i^\varepsilon}$;
- 2) on the points of ∂B , T is parallel to ∂B ;
- 3) T has the form

$$T = \frac{\partial}{\partial x_i^\varepsilon} + a \cdot \frac{\partial}{\partial x_n^0} ,$$

where the function a is smooth with estimates on the derivatives depending only on n , and $a(P) = 0$.

Consider the function

$$w(q) := \pm T(u - \phi) + \left(u_{x_n^1} - \phi_{x_n^1} \right)^2 + \left(u_{x_n^2} - \phi_{x_n^2} \right)^2 + \left(u_{x_n^3} - \phi_{x_n^3} \right)^2 - Ax_n^0 + B|q - R|^2 .$$

We will show that for A, B sufficiently large

- (a) $Lw > 0$;
- (b) $w|_{\partial B} \leq 0$.

If we will prove it then by the maximum principle $w \leq 0$ in \bar{B} . Hence

$$|T(u - \phi)| \leq Ax_n^0 \text{ in } \bar{B}.$$

Hence at the point P , $|\frac{\partial}{\partial x_n^0} T(u - \phi)| \leq A$. This will finish the proof of Lemma 7.6. Thus let us check the conditions (a) and (b). By a straightforward computation

$$LT(u - \phi) = T(\log f) - \left(L(\phi_{x_i^e}) + aL(\phi_{x_n^0}) \right) + (u - \phi)_{x_n^0} La + nf^{-1} \det \left((a_{\bar{j}} \cdot (u - \phi)_{x_n^0, i}) + ((u - \phi)_{x_n^0, \bar{j}} \cdot a_i), \partial^2 u[n - 1] \right),$$

where we denote for brevity $g_i := \frac{\partial g}{\partial q_i}$, $g_{\bar{i}} := \frac{\partial g}{\partial \bar{q}_i}$. However $\frac{\partial g}{\partial x_n^0} = g_{\bar{n}} - e_1 \frac{\partial g}{\partial x_n^1} - e_2 \frac{\partial g}{\partial x_n^2} - e_3 \frac{\partial g}{\partial x_n^3}$. Hence

$$LT(u - \phi) = T(\log f) - \left(L(\phi_{x_i^e}) + aL(\phi_{x_n^0}) \right) + (u - \phi)_{x_n^0} La + nf^{-1} \left(\det \left((a_{\bar{j}}(u - \phi)_{\bar{n}, i}) + (a_{\bar{j}}(u - \phi)_{\bar{n}, i})^*, \partial^2 u[n - 1] \right) \right) - nf^{-1} \sum_{l=1}^3 \det \left((a_{\bar{j}} e_l (u - \phi)_{x_n^l, i}) + (a_{\bar{j}} e_l (u - \phi)_{x_n^l, i})^*, \partial^2 u[n - 1] \right).$$

Note also that $u_{\bar{n}, i} = u_{i, \bar{n}}$. Using first- and second-order estimates on a and ϕ , and first-order estimates on f and u we get the following inequality:

$$|LT(u - \phi)| \leq C + Cnf^{-1} \det \left(I, \partial^2 u[n - 1] \right) + nf^{-1} \left(\det \left((a_{\bar{j}} u_{i, \bar{n}}) + (a_{\bar{j}} u_{i, \bar{n}})^*, \partial^2 u[n - 1] \right) \right) + nf^{-1} \sum_{l=1}^3 \det \left((a_{\bar{j}} e_l (u - \phi)_{x_n^l, i}) + (a_{\bar{j}} e_l (u - \phi)_{x_n^l, i})^*, \partial^2 u[n - 1] \right).$$

We have the following linear algebraic identity.

Claim.

$$\det \left((a_{\bar{j}} u_{i, \bar{n}}) + (a_{\bar{j}} u_{i, \bar{n}})^*, \partial^2 u[n - 1] \right) = 2 \operatorname{Re} a_{\bar{n}} \det \left(\partial^2 u[n - 1] \right).$$

It follows from Theorem 1.1.15 (i) of [2] that for a fixed $n \times n$ positive definite hyperhermitian matrix A the bilinear form $\det(XX^*, A[n - 1])$ is non-negative definite on the space of quaternionic n -columns. Hence we get

$$|\det(XY^* + YX^*, A[n - 1])| \leq \det(XX^*, A[n - 1]) + \det(YY^*, A[n - 1]). \tag{7.1}$$

Using this inequality and the last claim we obtain the following estimate:

$$|LT(u - \phi)| \leq C + Cnf^{-1} \det \left(I, \partial^2 u[n - 1] \right) + 2n |\operatorname{Re} a_{\bar{n}}| + \sum_{l=1}^3 nf^{-1} \cdot \left(\det \left(((u - \phi)_{x_n^l, \bar{i}} (u - \phi)_{x_n^l, i}), \partial^2 u[n - 1] \right) + \det \left((a_i a_{\bar{j}}), \partial^2 u[n - 1] \right) \right).$$

Using again the first-order estimates on a , we finally get

$$|LT(u - \phi)| \leq C + Cnf^{-1} \det \left(I, \partial^2 u[n - 1] \right) + nf^{-1} \sum_{l=1}^3 \det \left(\left((u - \phi)_{x_n^l, \bar{i}} (u - \phi)_{x_n^l, j} \right), \partial^2 u[n - 1] \right), \tag{7.2}$$

but now the value of the constant C might be different from the previous one.

Now let us compute $L((u_{x_n^l} - \phi_{x_n^l})^2)$. By a straightforward computation we have

$$\begin{aligned} L \left((u_{x_n^l} - \phi_{x_n^l})^2 \right) &= 2nf^{-1} \det \left(\left((u - \phi)_{x_n^l, \bar{i}} (u - \phi)_{x_n^l, j} \right) + (u - \phi)_{x_n^l} \cdot \left((u - \phi)_{x_n^l, i \bar{j}} \right), \partial^2 u[n - 1] \right) \\ &= 2nf^{-1} \det \left(\left((u - \phi)_{x_n^l, \bar{i}} (u - \phi)_{x_n^l, j} \right), \partial^2 u[n - 1] \right) \\ &\quad + 2(u - \phi)_{x_n^l} \cdot \left((\log f)_{x_n^l} - nf^{-1} \det \left(\phi_{x_n^l, i \bar{j}}, \partial^2 u[n - 1] \right) \right). \end{aligned}$$

Using this identity and (7.2) we obtain:

$$\begin{aligned} Lw &\geq -C + (8B - C)nf^{-1} \det \left(I, \partial^2 u[n - 1] \right) \\ &\quad + \sum_{l=1}^3 nf^{-1} \det \left(\left((u - \phi)_{x_n^l, \bar{i}} (u - \phi)_{x_n^l, j} \right), \partial^2 u[n - 1] \right) \\ &\quad + 2 \sum_{l=1}^3 (u - \phi)_{x_n^l} \cdot \left((\log f)_{x_n^l} - nf^{-1} \det \left(\phi_{x_n^l, i \bar{j}}, \partial^2 u[n - 1] \right) \right). \end{aligned}$$

But the third summand is non-negative. Hence we get

$$\begin{aligned} Lw &\geq -C + (8B - C)nf^{-1} \det \left(I, \partial^2 u[n - 1] \right) \\ &\quad + 2 \sum_{l=1}^3 (u - \phi)_{x_n^l} \cdot \left((\log f)_{x_n^l} - nf^{-1} \det \left(\phi_{x_n^l, i \bar{j}}, \partial^2 u[n - 1] \right) \right). \end{aligned}$$

Using the first-order estimates on u and f and third-order estimates on ϕ we finally obtain

$$Lw \geq -C' + (8B - C')nf^{-1} \det \left(I, \partial^2 u[n - 1] \right).$$

As in the proof of Lemma 7.3

$$\det \left(I, \partial^2 u[n - 1] \right) \geq nf^{\frac{n-1}{n}}.$$

Thus for large B we get

$$Lw \geq -C' + (8B - C')n^2 f^{-\frac{1}{n}} > 0.$$

Thus the inequality (a) is proved. It remains to prove the inequality (b), namely

$$(b) w|_{\partial B} \leq 0$$

for large A, B . Note that $T(u - \phi)|_{\partial B} \equiv 0$. Clearly it is sufficient to prove the inequality (b) only near the point P . Since $u \equiv \phi$ on ∂B , then using the first order estimates on u it is easy to see that for $l = 1, 2, 3$

$$\left| u_{x_n^l}(q) - \phi_{x_n^l}(q) \right| < C|q|, \quad q \in \partial B .$$

But for $q \in \partial B$ we have $|q| \leq K(x_n^0)^{\frac{1}{2}}$. Hence $|u_{x_n^l}(q) - \phi_{x_n^l}(q)|^2 < K' \cdot x_n^0$. Thus Lemma 7.6 is proved. □

Thus to obtain an estimate on all second order derivatives of u it remains to prove

$$\left| u_{x_n^0 \cdot x_n^0}(P) \right| < C .$$

We have proven that $|u_{x_i^\varepsilon \cdot x_j^\delta}(P)| < C$ for $(i, \varepsilon), (j, \delta) \neq (n, 0)$ and

$$\left| u_{x_n^l \cdot x_n^0}(P) \right| < C \text{ for } l \neq 0 . \tag{7.3}$$

It suffices to show that

$$\left| u_{n, \bar{n}}(P) \right| < C .$$

However by (7.3) it is sufficient to show that for the $(n - 1) \times (n - 1)$ - matrix

$$\left(u_{\alpha, \bar{\beta}}(P) \right)_{\alpha, \beta < n} \geq c \cdot I \tag{7.4}$$

for some positive constant c . After subtracting a linear functional we may assume that $\phi_{x_j^l}(P) = 0$ for $(j, l) \neq (n, 0)$. In order to prove (7.4) it is sufficient to prove that

$$\sum_{\alpha, \beta < n} \bar{\xi}_\beta u_{\alpha \bar{\beta}}(P) \xi_\alpha \geq c|\xi|^2 .$$

Let us prove it for $\xi = (1, 0, \dots, 0)$. Namely, $u_{1\bar{1}} \geq c$.

Let us write on the boundary ∂B the coordinate x_n^0 as a function of other coordinates:

$$x_n^0 = \rho \left((x_i^\varepsilon)_{(i, \varepsilon) \neq (n, 0)} \right) .$$

Let $\tilde{u} := u - \lambda x_n^0$ with λ so chosen that

$$\Delta_1 \tilde{u} \left((x_i^\varepsilon)_{(i, \varepsilon) \neq (n, 0)}, \rho \left((x_i^\varepsilon)_{(i, \varepsilon) \neq (n, 0)} \right) \right) = 0 \text{ at } P ,$$

where $\Delta_1 = \sum_{\varepsilon=0}^3 \frac{\partial^2}{(\partial x_i^\varepsilon)^2}$. Since the first derivatives of ρ vanish at P , the last equality is equivalent to

$$\tilde{u}_{1\bar{1}}(P) + \tilde{u}_{x_n^0} \rho_{1\bar{1}}(P) = 0 . \tag{7.5}$$

Consider the following Taylor decomposition:

$$\begin{aligned} \tilde{u}|_{\partial B} &= \left(\text{quadratic terms in } x_i^\varepsilon \neq x_n^0 \right) + (\text{3-order terms}) + O \left(|q|^4 \right) \\ &= E + F + O \left(\sum_{2 \leq j \leq n} |q_j|^2 \right) + O \left(|q|^4 \right) , \end{aligned}$$

where

$$E := \left(\text{quadratic terms in } x_i^\varepsilon \neq x_n^0 \right),$$

$$F := \left(\text{3-order terms in } x_1^\varepsilon \right).$$

First let us consider the term E . We can estimate all the monomials which do not contain x_1^ε by $C' \sum_{2 \leq j \leq n} |q_j|^2$. Thus

$$E = \sum_{\varepsilon, \delta=0}^3 \sum_{\substack{j \neq 1 \\ (j, \delta) \neq (n, 0)}} a_{\varepsilon, \delta, j} x_1^\varepsilon x_j^\delta + Q(x_1^\varepsilon) + o\left(\sum_{2 \leq j \leq n} |q_j|^2\right),$$

where Q is a quadratic polynomial in x_1^ε which satisfies $\Delta_1 Q = 0$.

Now let us consider the expression F . It is well-known (see e.g., [59]) that for any homogeneous polynomial F of degree 3 on a Euclidean space \mathbb{R}^N there exists a unique decomposition $F(x) = F_0(x) + l(x) \cdot |x|^2$, where F_0 is a harmonic polynomial, and l is a homogeneous polynomial of degree 1. Hence in our case ($N = 4$) we can write

$$F = F_0 + \left(\sum_{\varepsilon=0}^3 b^\varepsilon x_1^\varepsilon \right) |q_1|^2,$$

with $\Delta_1 F_0 = 0$.

On the boundary of the unit Euclidean ball ∂B we have

$$2x_n^0 = |q_1|^2 + \sum_{2 \leq j \leq n-1} |q_j|^2 + \sum_{\delta=1}^3 |x_n^\delta|^2 + o(|q|^3).$$

Thus

$$|q_1|^2 = 2x_n^0 - \left(\sum_{2 \leq j \leq n-1} |q_j|^2 + \sum_{\delta=1}^3 |x_n^\delta|^2 \right) + o(|q|^3).$$

Hence

$$F = F_0 + \left(\sum_{\varepsilon=0}^3 b^\varepsilon x_1^\varepsilon \right) \left(2x_n^0 - \left(\sum_{2 \leq j \leq n-1} |q_j|^2 + \sum_{\delta=1}^3 |x_n^\delta|^2 \right) + o(|q|^3) \right)$$

$$= F_0 + \sum_{\varepsilon=0}^3 2b^\varepsilon x_1^\varepsilon x_n^0 + o\left(\sum_{2 \leq j \leq n} |q_j|^2\right) + o(|q|^4).$$

Thus we get an estimate

$$\tilde{u}|_{\partial B} \leq \sum_{\varepsilon, \delta=0}^3 \sum_{\substack{j \neq 1 \\ (j, \delta) \neq (n, 0)}} a_{\varepsilon, \delta, j} x_1^\varepsilon x_j^\delta + Q(x_1^\varepsilon)$$

$$+ \left(F_0(x_1^\varepsilon) + \sum_{\varepsilon=0}^3 2b^\varepsilon x_1^\varepsilon x_n^0 \right) + C \sum_{2 \leq j \leq n} |q_j|^2 + o(|q|^4),$$

where $\Delta_1 F_0 = \Delta_1 Q = 0$. If we denote $G := F_0 + Q$ then the last estimate can be rewritten

$$\tilde{u}|_{\partial B} \leq \sum_{\varepsilon, \delta=0}^3 \sum_{j \neq 1} a_{\varepsilon, \delta, j} x_1^\varepsilon x_j^\delta + G + C \sum_{2 \leq j \leq n} |q_j|^2 + o(|q|^4).$$

Let us define

$$\hat{u} := \tilde{u} - G.$$

Since G depends only on q_1 and $\Delta_1 G = 0$ then

$$\hat{u}_{i\bar{j}} = \tilde{u}_{i\bar{j}} \text{ for } 1 \leq i, j \leq n.$$

We have

$$\hat{u}|_{\partial B} \leq \sum_{\varepsilon, \delta=0}^3 \sum_{j \neq 1} a_{\varepsilon, \delta, j} x_1^\varepsilon x_j^\delta + C \sum_{2 \leq j \leq n} |q_j|^2 + o(|q|^4).$$

Now let us consider the following function

$$\begin{aligned} h &:= -\alpha x_n^0 + \beta |q|^2 + \frac{1}{2D} \sum_{\varepsilon, \delta} \sum_{j \neq 1} |a_{\varepsilon, \delta, j} x_1^\varepsilon + D x_j^\delta|^2 \\ &= -\alpha x_n^0 + \beta |q|^2 + \sum_{\varepsilon, \delta} \sum_{j \neq 1} a_{\varepsilon, \delta, j} x_1^\varepsilon x_j^\delta + D \sum_{\varepsilon, \delta} \sum_{j \neq 1} |x_j^\delta|^2 + \theta, \end{aligned}$$

where α , β , and D will be chosen later, and

$$\theta := \frac{1}{2D} \sum_{\varepsilon, \delta} \sum_{j \neq 1} |a_{\varepsilon, \delta, j} x_1^\varepsilon|^2 \geq 0.$$

Hence,

$$h|_{\partial B} \geq -\alpha x_n^0 + \beta |q|^2 + \sum_{\varepsilon, \delta} \sum_{j \neq 1} a_{\varepsilon, \delta, j} x_1^\varepsilon x_j^\delta + 4D \sum_{j=2}^n |q_j|^2.$$

It is easy to see that for appropriate choices of large D and small α , β such that $-\alpha x_n^0 + \beta |q|^2 \geq 0$ one can obtain that h is psh and

$$h|_{\partial B} \geq \hat{u}|_{\partial B}.$$

Now it is easy to see that the smallest eigenvalue of the matrix $(h_{i\bar{j}})$ is equal to 4β . Clearly all the elements of this matrix are bounded independently of small β ; hence all the other eigenvalues are bounded. Thus choosing sufficiently small β we may assume that

$$\det(h_{i\bar{j}}) < f \text{ in } B.$$

Hence, by the minimum principle

$$\hat{u} \leq h \text{ in } \bar{B}.$$

Since $h(P) = \hat{u}(P) = 0$ we obtain

$$\hat{u}_{x_n^0}(P) \leq h_{x_n^0}(P) = -\alpha.$$

It is easy to see that $\tilde{u}_{x_n^0}(P) = \hat{u}_{x_n^0}(P)$. Substituting this equality and the last inequality to (7.5) we get

$$\tilde{u}_{1\bar{1}}(P) \geq \alpha \rho_{1\bar{1}}(P) = c > 0.$$

But $u_{1\bar{1}}(P) = \tilde{u}_{1\bar{1}}(P)$. Thus the second-order estimate is proved.

7.3. $C^{2,\alpha}$ - estimates

In this section we prove *a priori* $C^{2,\alpha}$ - estimates on solutions of the Dirichlet problem for the quaternionic Monge–Ampère equation. As previously we denote by u the solution of this problem. The main result of this section is the following.

Theorem 7.7. *Let Ω be strictly pseudoconvex bounded domain in \mathbb{H}^n with smooth boundary. Let u be a smooth psh solution of the Dirichlet problem for the quaternionic Monge–Ampère equation with $f > 0$, and f, ϕ be C^∞ -smooth. Then*

$$|u|_{2+\alpha} \leq K \text{ for some } 0 < \alpha < 1 ,$$

where K depends only on Ω and norms of f and ϕ .

This theorem is an immediate consequence of the following general result due to Caffarelli, Kohn, Nirenberg, and Spruck [15] and the second-order estimates obtained in the previous section.

Theorem 7.8. *Let Ω be a bounded domain in \mathbb{R}^N with the smooth boundary $\partial\Omega$. Let u be a smooth solution of the elliptic equation*

$$\begin{aligned} F(x, u, Du, D^2u) &= 0 \text{ in } \Omega , \\ u &\equiv \phi \text{ on } \partial\Omega , \end{aligned}$$

ϕ is smooth. Assume that F is concave in the second derivatives u_{ij} . Assume that u satisfies an estimate

$$|u|_2 \leq C' .$$

Then

$$|u|_{2+\alpha} \leq K \text{ for some } 0 < \alpha < 1 ,$$

where K depends only on $\Omega, F, |\phi|_4, C'$.

Note that this theorem implies Theorem 7.7 if one takes $F(x, u, Du, D^2u) = \log(\det u_{i,\bar{j}}) - \log f$.

Thus Theorem 7.1 is proved as well.

8. Proof of Theorem 1.3

In this section we will finish the proof of our main result about existence of solution of the Dirichlet problem for quaternionic Monge–Ampère equation (Theorem 1.3). But first we will need the following result.

Theorem 8.1. *Suppose $\Omega = B$ is the unit Euclidean ball in \mathbb{H}^n , $\phi \in C(\partial B), f \in C(\bar{B}), f \geq 0$. Let $d\mu = f^{\frac{1}{n}} d \text{vol}$. Then the upper envelopes of the families $\mathcal{B}(\phi, \mu), C\mathcal{B}(\phi, \mu), \mathcal{F}(\phi, \mu^n)$ coincide. If u denotes the upper envelope, then $u \in C(\bar{B})$ and satisfies*

$$\begin{aligned} \Phi(u) &= f^{\frac{1}{n}} d \text{vol} \text{ in } B , \\ \det(\partial^2 u) &= f d \text{vol} \text{ in } B , \\ u &= \phi \text{ in } \partial B . \end{aligned}$$

Proof. Remind that the Perron–Bremmermann families from the theorem were defined in Section 6.1. The argument follows very closely the proof of Theorem 8.2 of [10]. Choose a sequence of functions $f_j > 0$ with $f_j \in C^\infty(\bar{B})$ decreasing to f uniformly on \bar{B} . Choose also a sequence of functions $\phi_j \in C^\infty(\partial B)$ such that ϕ_j increases to ϕ uniformly on ∂B . By Theorem 7.1 there exist unique psh functions $u_j \in C(\bar{B})$ which are solutions of the Dirichlet problem

$$\det(\partial^2 u_j) = f_j \text{ in } B, \quad u_j = \phi_j \text{ in } \partial B.$$

By the minimum principle (Theorem 3.3) the sequence u_j is increasing. We can choose positive numbers η_j tending to zero so that $\phi_j + \eta_j \geq \phi$ on ∂B . Since

$$\det(\partial^2(u_k + \varepsilon(|z|^2 - 1))) \geq \det(\partial^2 u_k) + \varepsilon^n \det(\partial^2 |z|^2) = f_k + \varepsilon^n \det(\partial^2 |z|^2),$$

and since $f_k \rightarrow f$ uniformly we can choose positive numbers $\varepsilon_j \rightarrow 0$ such that

$$\det(\partial^2(u_k + \varepsilon_j(|z|^2 - 1))) \geq \det(\partial^2 u_j) \text{ for } k \geq j.$$

By the minimum principle (Theorem 3.3) we get

$$u_k + \varepsilon_j(|z|^2 - 1) \leq u_j(z) + \eta_j \text{ for } k \geq j, z \in \bar{B}.$$

But $u_j(z) \leq u_k(z)$. Hence $u_j \rightarrow u$ uniformly on \bar{B} . By Theorem 3.2 u is psh and $\det(\partial^2 u_j) \rightarrow \det(\partial^2 u)$ weakly. Hence $\det(\partial^2 u) = f$. Further, by Theorem 5.7 (4) $\Phi(u) \geq f^{\frac{1}{n}} d \text{ vol}$, and by Theorem 5.8 and Remark 5.9 $\Phi(u)^n \leq \det(\partial^2 u)$. Hence $\Phi(u) = f^{\frac{1}{n}} d \text{ vol}$.

It follows from Proposition 6.10 that the upper envelopes of $C\mathcal{B}(\phi, f \cdot d \text{ vol})$ and $\mathcal{F}(\phi, f^n \cdot d \text{ vol})$ coincide with u . By Theorem 6.1 the upper envelopes of $\mathcal{B}(\phi, f \cdot d \text{ vol})$ and $C\mathcal{B}(\phi, f \cdot d \text{ vol})$ coincide. \square

Theorem 8.2. Let Ω be a bounded open set in \mathbb{H}^n . Let $\phi \in C(\partial\Omega)$ and $d\mu = f^{\frac{1}{n}} \cdot d \text{ vol}$ with $f \geq 0$, $f \in C(\Omega)$. Suppose that

(i) $\mathcal{B}(\phi, \mu)$ is nonempty, and

(ii) the upper envelope $u = \sup\{v : v \in \mathcal{B}(\phi, \mu)\}$ is continuous on $\bar{\Omega}$ with $u = \phi$ on $\partial\Omega$.

Then u is psh and it is the solution to the Dirichlet problem

$$\det(\partial^2 u) = f \text{ in } \Omega, \quad u = \phi \text{ on } \partial\Omega.$$

Also $\Phi(u) = f^{\frac{1}{n}} \cdot d \text{ vol}$.

Proof. Let us check that $\det(\partial^2 u) = f \cdot d \text{ vol}$ in Ω . First let us show that $\det(\partial^2 u) \geq f \cdot d \text{ vol}$ in Ω . By Choquet's lemma there exists an increasing sequence $u_j \in \mathcal{B}(\phi, \mu)$ which converges to u almost everywhere, and hence in $L^1_{\text{loc}}(\Omega)$. Then by Theorem 5.7 (4) $\Phi(u) \geq f^{\frac{1}{n}}$. Let us write the Lebesgue decomposition

$$\det(\partial^2 u) = \tilde{f} \cdot d \text{ vol} + d\nu.$$

By Theorem 5.8 (2)

$$f = \left(f^{\frac{1}{n}}\right)^n \leq \tilde{f}.$$

Hence $\det(\partial^2 u) \geq f \cdot d \text{ vol}$.

To prove the opposite inequality let us fix $z_0 \in \Omega$, and choose $\varepsilon > 0$ so small that the closure of the ball $B(z_0, \varepsilon) = \{|z - z_0| < \varepsilon\}$ is contained in Ω . By the previous theorem there is a psh function $v(z) \in C(B(z_0, \varepsilon))$ such that

$$\begin{aligned} v(z) &= u(z) \text{ on } \partial B(z_0, \varepsilon) ; \\ \Phi(v) &= f^{\frac{1}{n}} \cdot d \text{ vol on } B(z_0, \varepsilon) ; \\ \det(\partial^2 v) &= f \cdot d \text{ vol on } B(z_0, \varepsilon) . \end{aligned}$$

Since $f = \det(\partial^2 v) \leq \det(\partial^2 u)$ on $B(z_0, \varepsilon)$, by the minimum principle we have $v \geq u$ in $\overline{B(z_0, \varepsilon)}$. Set $U(z) = v(z)$ if $z \in B(z_0, \varepsilon)$, and $U(z) = u(z)$ if $z \in \Omega - B(z_0, \varepsilon)$. Then clearly U is continuous and psh, and $U = \phi$ on $\partial\Omega$. We also have $\Phi(U) \geq f^{\frac{1}{n}} \cdot d \text{ vol}$. Therefore $U \in \mathcal{B}(\phi, f^{\frac{1}{n}} \cdot d \text{ vol})$. Hence $U \leq u$. Hence $U \equiv u$. In particular in $B(z_0, \varepsilon)$ we have $\det(\partial^2 u) = f$ and $\Phi(u) = f^{\frac{1}{n}} \cdot d \text{ vol}$. □

Finally let us prove Theorem 1.3.

Proof. By Theorem 8.2 we have to verify that $\mathcal{B}(\phi, \mu)$ is not empty and its upper envelope $u \in C(\overline{\Omega})$, and $u = \phi$ on $\partial\Omega$. When Ω is strictly pseudoconvex this is consequence of Theorem 6.1. Thus $u = \sup\{v : v \in \mathcal{B}(\phi, \mu)\}$ is the solution of the Dirichlet problem. □

9. Quaternionic Levi form

In this section we discuss some additional properties of quaternionic strictly pseudoconvex domains. In Section 9.1 we introduce a quaternionic version of the Levi form of a domain with smooth boundary and prove that such a domain is strictly pseudoconvex if and only if its Levi form is positive definite. In Section 9.2 we consider some examples and some other analogies with the real and complex cases. In Section 9.3 we state some open questions.

9.1. The quaternionic Levi form

In this section we introduce the quaternionic version of the Levi form. For the classical complex case we refer to [38] and [19]. The main result of this section is Proposition 9.2.

Let Ω be a domain in \mathbb{H}^n with C^2 -smooth boundary $\partial\Omega$. For any $z \in \partial\Omega$ let $T_{\partial\Omega, z}$ denote the tangent space at z to the boundary $\partial\Omega$. The *quaternionic tangent space* to $\partial\Omega$ at z is by definition the maximal quaternionic subspace contained in $T_{\partial\Omega, z}$:

$${}^h T_{\partial\Omega, z} := T_{\partial\Omega, z} \cap T_{\partial\Omega, z} I \cap T_{\partial\Omega, z} J \cap T_{\partial\Omega, z} K .$$

Let $\rho \in C^2$ be a defining function of Ω , i.e.,

$$\rho < 0 \text{ on } \Omega, \rho = 0 \text{ and } d\rho \neq 0 \text{ on } \partial\Omega .$$

The *Levi form* $L_{\partial\Omega, z}$ on ${}^h T_{\partial\Omega, z}$ is defined as the restriction of the hyperhermitian quadratic form $(\frac{\partial^2 \rho(z)}{\partial q_i \partial \bar{q}_j})$ to ${}^h T_{\partial\Omega, z}$ divided by $|\nabla \rho(z)|$.

Claim 9.1. *The Levi form does not depend on the choice of ρ .*

Proof. Let ρ' be another defining function of Ω . Then in a small neighborhood of z there exists a smooth function α , $\alpha(z) > 0$, such that $\rho' = \alpha\rho$. But

$$\frac{\partial^2(\alpha\rho)}{\partial q_i \partial \bar{q}_j} = \alpha \frac{\partial^2 \rho}{\partial q_i \partial \bar{q}_j} + \frac{\partial \alpha}{\partial \bar{q}_j} \cdot \frac{\partial \rho}{\partial q_i} + \frac{\partial \rho}{\partial \bar{q}_j} \cdot \frac{\partial \alpha}{\partial q_i} + \rho \frac{\partial^2 \alpha}{\partial q_i \partial \bar{q}_j}. \tag{*}$$

Now let us choose the coordinate system such that z is at the origin, and ${}^h T_{\partial\Omega, z}$ is spanned by the first $n - 1$ coordinates q_1, \dots, q_{n-1} . If we evaluate this expression at z we obtain for $i, j \leq n - 1$:

$$\frac{\partial^2 \rho'(z)}{\partial q_i \partial \bar{q}_j} = \alpha \frac{\partial^2 \rho(z)}{\partial q_i \partial \bar{q}_j}. \quad \square$$

Proposition 9.2. *A C^2 -smooth domain Ω is strictly pseudoconvex iff the Levi form is positive definite at each point $z \in \partial\Omega$.*

Proof. If Ω is strictly pseudoconvex then there is nothing to prove. Let us prove the opposite statement. Let us fix a point $z \in \partial\Omega$ and let us assume that $L_{\partial\Omega, z}$ is positive definite. Let us fix any defining function ρ of Ω in a neighborhood of z . Let us also fix a coordinate system on \mathbb{H}^n so that again z is at the origin and ${}^h T_{\partial\Omega, z}$ is spanned by the first $n - 1$ coordinates q_1, \dots, q_{n-1} . From (*) we obtain for any real valued smooth function α :

$$\frac{\partial^2(\alpha\rho)}{\partial q_i \partial \bar{q}_j}(z) = \alpha(z) \frac{\partial^2 \rho(z)}{\partial q_i \partial \bar{q}_j} + \frac{\partial \alpha(z)}{\partial \bar{q}_j} \cdot \frac{\partial \rho(z)}{\partial q_i} + \frac{\partial \rho(z)}{\partial \bar{q}_j} \cdot \frac{\partial \alpha(z)}{\partial q_i}.$$

Now let us choose α such that $\alpha(z) = 1 + l(q_n)$, where l is \mathbb{R} -linear real valued functional depending only on q_n . Then if either $i < n$ or $j < n$ we get

$$\frac{\partial^2(\alpha\rho)(z)}{\partial q_i \partial \bar{q}_j} = \frac{\partial^2 \rho(z)}{\partial q_i \partial \bar{q}_j}.$$

For $i = j = n$ we get

$$\begin{aligned} \frac{\partial^2(\alpha\rho)(z)}{\partial q_n \partial \bar{q}_n} &= \frac{\partial^2 \rho(z)}{\partial q_n \partial \bar{q}_n} + \frac{\partial l(z)}{\partial \bar{q}_n} \cdot \frac{\partial \rho(z)}{\partial q_n} + \frac{\partial \rho(z)}{\partial \bar{q}_n} \cdot \frac{\partial l(z)}{\partial q_n} \\ &= \Delta_n(\rho) + 2 \operatorname{Re} \left(\frac{\partial l(z)}{\partial \bar{q}_n} \cdot \frac{\partial \rho(z)}{\partial q_n} \right). \end{aligned}$$

If we choose l appropriately we can make the last expression arbitrarily large, and then the matrix $(\frac{\partial^2(\alpha\rho)}{\partial q_i \partial \bar{q}_j})$ will be positive definite at z , and hence in some neighborhood of z , and hence the function $\alpha\rho$ will be strictly psh. But $\alpha\rho$ is also a defining functional of Ω near z . □

9.2. Some examples

In this section we present a general construction of quaternionic strictly pseudoconvex domains. It was suggested by M. Gromov [33] in an analogy to the complex case. Then we discuss some differences of the quaternionic situation with the real and complex cases. This part depends very much on discussions with M. Sodin.

Definition 9.3. Let S be a real $3n$ -dimensional linear subspace of \mathbb{H}^n . Then S is called *totally real* if

$$S \cap (S \cdot I) \cap (S \cdot J) \cap (S \cdot K) = \{0\}.$$

Note that a generic real $3n$ -dimensional linear subspace is totally real. Note also that S is totally real if and only if its orthogonal complement $S^\perp \subset (\mathbb{H}^n)^*$ satisfies

$$S^\perp + I \cdot S^\perp + J \cdot S^\perp + K \cdot S^\perp = (\mathbb{H}^n)^* .$$

Definition 9.4. A smooth $3n$ -dimensional submanifold of \mathbb{H}^n is called totally real if the tangent space at every point of it is totally real.

Claim 9.5. Let M be a $3n$ -dimensional totally real compact submanifold of \mathbb{H}^n . Let $\Omega := M_\varepsilon$ be the ε -neighborhood of M . Then for small $\varepsilon > 0$ the domain Ω is strictly pseudoconvex.

Now let us remind the following characterizations of convex (resp. pseudoconvex) domains in \mathbb{R}^n (resp. \mathbb{C}^n) (see e.g., [38]).

Claim 9.6. Let Ω be a bounded domain in \mathbb{R}^n (resp. \mathbb{C}^n). Then Ω is convex (resp. pseudoconvex) if and only if the function $x \mapsto -\log \text{dist}(x, \partial\Omega)$ is convex (resp. plurisubharmonic).

Unfortunately this criterion is *not* true in the quaternionic situation already in \mathbb{H}^1 . Indeed by Proposition 9.2 any bounded domain with smooth boundary is strictly pseudoconvex in the quaternionic sense. It is not difficult to construct a domain $\Omega \subset \mathbb{H}^1$ such that the function $x \mapsto -\log \text{dist}(x, \partial\Omega)$ will be not subharmonic (in the usual sense).

9.3. Questions and comments

We would like to state few questions closely related to the material of this article.

Question 1. Find a geometric (or any other) interpretation of the quaternionic Monge–Ampère equation (or of an appropriate modification of it).

Remind that the (modified) real Monge–Ampère equations appear in construction of convex hypersurfaces in \mathbb{R}^n with the prescribed conditions on curvature. For this material we refer to [8, 52]. One of the main applications of (modified) complex Monge–Ampère equations is the construction of Kähler metrics on complex manifolds. After the proof of the Calabi–Yau theorem [60, 61] and the Aubin–Yau theorem [7, 61] they became the key tool in complex differential geometry, see e.g., [8, 11, 40] for further discussion.

Question 2. (due to L. Polterovich.) Find a geometric characterization of quaternionic strictly pseudoconvex domains. (Note that we have not defined the notion of quaternionic pseudoconvex domain in the non-strict sense.)

Question 3. (due to G. Henkin.) This question is closely related to the previous one. Let $\Omega \subset \mathbb{H}^n$ be a domain which admits an exhaustion by level sets of a plurisubharmonic function; in other words there exists a plurisubharmonic function $h : \Omega \rightarrow \mathbb{R}$ such that for any number c the set $\{h \leq c\}$ is compact. (Note that in the classical complex situation this property is one of the equivalent definitions of a pseudoconvex domain.) It was observed by G. Henkin [36] that if h is strictly plurisubharmonic Morse function then Ω admits a homotopy retraction onto a compact subset of dimension at most $\frac{3}{4} \dim_{\mathbb{R}} \Omega = 3n$ (indeed the Morse index of every critical point of such a function is bounded from above by $3n$). This implies that the boundary $\partial\Omega$ is connected provided $n > 1$. These properties are analogous to the corresponding properties of pseudoconvex domains in the complex spaces (where the constant $\frac{3}{4}$ is replaced by $\frac{1}{2}$). It would be of interest to

understand the relation between the class of domains with this property and the class of strictly pseudoconvex domains in the sense of this article.

Question 4. Generalize Theorem 7.1 on the existence of the *regular* solution (under suitable assumptions on regularity of the initial data) to arbitrary strictly pseudoconvex bounded domains with smooth boundary (and not only for the Euclidean ball).

Note that the real analog of this result was proved by Caffarelli, Nirenberg, Spruck in [14], and the complex analog was proved by Caffarelli, Kohn, Nirenberg, and Spruck in [15] and Krylov in [42].

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