Recent progress in dynamics and aeroelasticity

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Abstract. With the emphasis on higher performance, modern aircraft designs aim at lower structural weight, aerodynamically efficient thinner configurations, and reduced or even negative stability margins augmented by automatic flight control systems. These design considerations lead to highly flexible structural designs with associated problems of dynamic and aeroelastic interactions which need to be considered at the preliminary design stage itself. Advent of advanced composites and active control techniques have given the aircraft designer the freedom to use aeroelastic interactions in an advantageous way. This paper reviews the recent research and development efforts in the areas of aeroelastic tailoring, structural optimisation with aeroelastic constraints and aeroservoelasticity, and applications of the same in practical designs. The developments and applications in India in these areas are also highlighted.

Keywords. Aeroelasticity; aerodynamic interactions; aeroelastic tailoring; aeroservoelasticity; structural optimisation.

1. Introduction

The general developments in the aerospace industry during the last two decades have called for a fresh look at the role of dynamics and aeroelasticity in aerospace vehicle design. Higher performance and extended mission requirements demand designs with low structural weight, aerodynamically efficient configurations and reduced or even negative stability margins augmented by automatic flight control systems. These conflicting design requirements lead to highly flexible structural designs with associated problems of dynamic, aeroelastic and control interactions which need to be predicted and controlled at the preliminary design stage itself without undue weight penalty. Greater emphasis on the transonic flight regime presents its own special problems of flow unsteadiness and resulting structural response and flutter. Another important development that has a strong impact on design is the increasing use of advanced composite materials in primary structures such as wing and empennage. While composites offer attractive weight savings in view of their higher specific strength and stiffness properties, they also present the problem of anisotropy and resultant coupled deformation behaviours. Research studies in the past two decades have shown how the directional properties of composites could be put to advantageous use

through aeroelastic tailoring techniques to. obtain improved aeroelastic and even aerodynamic performance without any weight penalty. On the other hand, studies on active control technology have also demonstrated possibilities of significant benefits through control and suppression of aeroelastic instabilities. However, with all the new developments, areas of overlap between structures, aerodynamics and controls in the unsteady, dynamic regime have increased leading to possibilities of aero-servoelastic (ASE) interactions. Thus an efficient aircraft design calls for an integrated design approach involving close interaction amongst aerodynamic, structural and control engineers at all stages of design. Emergence of new tools such as powerful computers and specialised application software capable of handling a multitude of design variables and parameters have made such an approach possible.

This paper briefly discusses the progress in the last decade in the following two areas: (i) aeroelastic tailoring and structural optimisation with aeroelastic constraints and (ii) aeroservoelasticity. The discussions are restricted to fixed wing aircraft. Recent work and developments in India in the above two areas are described in some detail.

2. Aeroelastic tailoring and optimisation

Shirk *et al* (1986) give a standard definition of aeroelastic tailoring as "the embodiment of directional stiffness into an aircraft structural design to control aeroelastic deformation, static or dynamic, in such a fashion as to affect the aerodynamic and structural performance of that aircraft in a beneficial way". Two technological developments in the last two decades have contributed to the evolution of aeroelastic tailoring as a design tool with great potential. These are (i) high performance fibrous composite materials and (ii) mathematical programming methods. The first has significantly increased aircraft structural design options, and the second has permitted the resulting multitude of design variables to be considered and used efficiently. Shirk *et al* (1986) give a comprehensive survey of the status of aeroelastic tailoring, covering the historical background, theoretical foundations and associated research studies on trends, and specific applications of the technology in design exercises. Haftka (1986) also presents developments in the United States in the application of structural optimisation under aeroelastic constraints.

Research studies reported by Shirk *et al* (1986) have shown aeroelastic tailoring using advanced composites to be effective in flutter control, divergence control, particularly of forward swept wings, manoeuvre load relief, improvement of control effectiveness and aerodynamic performance improvement. Figure 1 indicates the aeroelastic deformation trends to be obtained through forward or aft orientation of the primary stiffness direction in a fibre composite laminate with respect to the elastic axis and the corresponding benefits to be expected. Aft location of the primary stiffness direction results in a bend-twist coupling leading to a wash-in (increase of streamwise angle of attack along span) type of torsional deformation under an upward bending load. A wash-out type of torsion (decrease of streamwise angle of attack) is obtained under the same load with a forward location of the primary stiffness direction. It is generally seen that a design with increased aerodynamic effectiveness or improved flutter performance is poorer in terms of manoeuvre load relief and divergence characteristics. Weisshaar & Foist (1982) developed a nondimensional stiffness cross-coupling parameter bounded between ± 1 , in terms of the bending and torsional stiffness terms and a stiffness cross-coupling term which permitted tailoring studies to be conducted without a detailed definition of the laminate geometry.

Figure 1. Benefits of aeroelastic tailoring (Shirk *et al* 1986).

2.1 *Software tools*

Use of composite materials, while providing the structural designer with significant design freedom, leads to a significant increase in the complexity of the design problem because of the large number of design variables involved (ply orientations, number of plies, stacking sequence etc). As a result," advanced optimisation techniques have become essential for the efficient design of composite structures. Most of the aircraft companies have developed their own in-house optimisation software to support their design activities. Of these, the following require special mention.

Wing aeroelastic synthesis procedure (TSO)- developed by General Dynamics under an US Airforce contract (McCullers & Lynch 1974), is a preliminary design tool that employs a Ritz equivalent plate model of the wing and nonlinear programming techniques in optimisation. Minimum weight skin thickness and orientations of various plies are calculated subject to a variety of constraints including aeroelastic efficiencies, lift-curve slope and flutter and divergence speeds. The TSO program was used in several design studies for aeroelastic tailoring applications at General Dynamics (YF-16, FB-111), Boeing (KC-135, X-Wing aircraft) and MBB.

FASTOP (flutter and strength optimisation procedure) (Wilkinson *et al* 1977), developed by Grumman, is a finite-element-based two-step design procedure which uses the fully stressed design (FSD) criterion in the first step and a uniform flutter velocity derivative optimality criterion in the second step. The software provides a better structural idealisation as compared to TSO, but the objective function and the constraints are not as varied. FASTOP has been applied by Grumman in several design studies (FSW X-29, Israeli Lavi Fighter) and was also evaluated by Rockwell and Boeing.

ELFINI (Petiau 1990) is a finite-element-based general purpose software developed and extensively used by Dassault Aviation, France, in all its aircraft projects. It presents an integrated approach to aircraft structural analysis and design, incorporating airload computations, aeroelasticity and manoeuvre calculations, flutter analysis and structural optimisation for minimum weight based on a nonlinear projected conjugate gradient method. The design variables are the number of plies in each fibre direction and the constraints include aeroelastic efficiencies, natural frequencies, flutter speed and damping.

ASTROS (automated structural optimisation system) (Neill *et al* 1990) was developed under US Airforce contract. ASTROS is a multidisciplinary finite-element-based software system that can be used in the preliminary design of aerospace structures. It has primarily integrated existing methodologies into a unified package and, like ELFINI, provides basic static and dynamic structural analysis, steady and unsteady airloads, flutter analysis, sensitivity analysis, optimisation capabilities and aeroservoelastic response analysis. The optimisation procedure employs a method of modified feasible directions and optimality criteria methods. Optimisation constraints include flutter and divergence speeds, aeroelastic trim parameters and aeroelastic stability derivatives. Ply orientation in composite skin laminates is not a possible design variable as in TSO.

ADOP (aeroelastic design optimisation program) (Dodd *et al* 1990) is an interdisciplinary optimisation program for static, dynamic and aeroelastic analysis using finite element structural models. Developed by the Douglas Aircraft Company, ADOP incorporates FSD concepts, static aeroelasticity and flutter constraints in optimisation. The strategy is to perform a series of optimisation studies rather than attempt the simultaneous satisfaction of multidisciplinary constraints.

ECLIPSE (Kerr & Thomson 1986) is a finite-element-based structural optimisation program developed by the Warton Division of British Aerospace (BAe). The program is optimality criteria based and is capable of dealing with stiffness-based criteria such as aero efficiency, roll rate, divergence speed, flutter speed, natural frequency and frequency separation. The program has been used extensively by BAe in its aircraft design projects.

A finite-element-based software called ASAT (Godel & Schneider 1981) exists at MBB which is able to size cantilevered or free-free surface structures for flutter speed, deflection and strength constraints. CFC structures can also be treated efficiently.

2.2 Specific applications

Some specific applications of aeroelastic tailoring and optimisation with aeroelastic requirements in aircraft design during the past 15 to 20 years are briefly described below.

The HiMAT (highly manoeuvrable advanced technology aircraft) remotely piloted research vehicle (Lockenhauer & Layton 1976; Shirk *et al* 1986), designed and built by Rockwell for NASA, was a test-bed for application of aeroelastic tailoring concepts in the lifting surfaces of a modem aircraft. The outboard wing and the canard (figure 2) of HiMAT were aeroelastically tailored to provide optimum transonic manoeuvre performance (load factor of $8g$ at Mach 0.9 and an altitude of 20,000 ft) with minimum adverse effect on cruise performance. In the design, the aeroelastic twist distribution of the wing was maximised in order to minimise the built-in twist. The TSO program was used in the preliminary design of the vehicle. The required wing ply orientation is shown in figure 2. The HiMAT programme demonstrated the feasibility of unconventional, unbalanced, graphite-epoxy laminates in controlling aeroelastic twist.

Feasibility of designing a forward-swept wing avoiding divergence instability through use of aeroelastic tailoring was demonstrated in the fighter-class aircraft, X-29, developed by Grumman (Hertz *et al* 1982). Grumman used FASTOP in the

Figure 2. HiMAT remotely piloted research vehicle (Shirk *et al* 1986).

design and arrived at a conventional $(0^{\circ}, \pm 45^{\circ}, 90^{\circ})$ laminate, rotated such that the primary bending plies are 9° forward of the reference structural axis. This provided the necessary bend-twist coupling to minimise the inherent wash-in tendency of the forward-swept wing. A study (Ashley 1982) by Rockwell on a similar concept using TSO also led to a similar result (figure 3).

Applications of advanced optimisation techniques with composites in a combat aircraft wing & fin using ELFINI at Dassault Aviation are presented in Petiau (1990).

Figure 3. Rockwell FSW fighter wing skin studies (Ashley 1982) $(q_d$ -divergence dynamic pressure).

Figure 4. Fin-box skin optimisation using TSO (Schneider & Zimmermann 1986).

The constraints considered include static aeroelasticity, flutter and dynamic frequencies.

Schneider & Zimmerman (1986) describe the use of TSO and FASTOP at MBB in the aeroelastic design studies of the fin and wing boxes of a fighter aircraft. The fin skin optimisation results (figure 4) demonstrated significant benefits from aeroelastic tailoring. Further optimisation for flutter with FASTOP showed an 8-2% increase in flutter speed with only a 2.8% increase in the fin weight.

2.3 Developments in India

Efforts in recent years at the Aeronautical Development Agency towards incorporation of aeroelastic tailoring and optimisation concepts in the preliminary design phase of an advanced fighter aircraft are described in this section. The aeroelastic analysis is carried out using the general purpose computer software ELFINI.

The aircraft has a tailless delta-wing configuration with two elevons on each wing for longitudinal and roll control. The fin and rudder provide lateral stability and control. Both the wing and the fin are multi-spar configurations (figure 5) and are of predominantly *CF¢* construction. The skins are tailored and optimised for minimum weight subject to a variety of constraints and load cases.

The aeroelastic analysis uses a finite-element structural model of the aircraft (figure 6) with about 15,000 degrees of freedom in the half symmetric model. Several basic mass distributions are defined on the model which can later be combined to create any defined design mass case.

Basic linear aerodynamic computations based on the method of singularities provide *ACp* distributions on two-dimensional aerodynamic meshes of wing and fin.

Figure 5. Fighter aircraft wing (a) and fin (b) geometry.

These distributions are corrected (or replaced) using wind-tunnel test data and results from rigorous CFD codes. Bodies such as fuselage, stores etc. are loaded by specifying force and moment resultants on aerodynamic boxes which are subsequently distributed to finite element nodes encompassed by the boxes.

The strategy for aeroelastic analysis involves a two-stage computational procedure; extensive aerodynamic and structural computations are done independently in stage 1 and stored as tables of operators which are subsequently used in stage 2 for less extensive computations of fluid-structure interactions and related aspects for specific mass cases and flight points. This is made possible with the definition of an independent computational grid on which an aerodynamic shape basis and a reduced load basis are defined and which acts as a link between finite element and aerodynamic meshes. Upadhya *et al* (1990a, pp. 331-7) describes in detail the aeroelastic analysis procedure adopted.

Typical results are presented in figures 7 to 9. For an applied rigid ΔC_p distribution on the fin (figure 7) for unit values of sideslip β and rudder deflection δ , at Mach 1.2, the induced ΔC_p distribution due to flexible deformation of the fin and rudder are shown in figure 8. Aeroelastic losses occur mainly due to torsion and chordwise bending of the lifting surface and could be quite large, particularly for control aerodynamic derivatives, at supersonic Mach numbers and high dynamic pressures

Figure 7. Applied rigid ΔC_p distribution on fin $(M = 1.2)$. (a) Sideslip β , (b) rudder δ ,.

due to flexibility ($M = 1.2$, maximum dynamic pressure). (a) Sideslip β , (b) rudder $\delta_{\rm r}$.

as shown in figure 9. The.fly-by-wire FCS of the aircraft will define the minimum acceptable values of aeroelastic efficiency on critical control derivatives and the CFC skins are optimally designed to provide the necessary stiffness and aeroelastic.deformation coupling. Typical aeroelastic deformation shapes of the aircraft for angle of attack (α) and antisymmetric elevon (δ_a) effects are presented in figure 10.

The optimisation procedure requires definition of zones or patches on the skins (figure 11). The design variables are the thicknesses (or number of plies) in each of the four pre-defined fibre directions in the zones. The total number of design variables are 328 for the CFC wing skins and 154 for CFC fin skins.

Critical load cases involving combinations of normal load factor and roll rate/acceleration for the wing and sideslip and rudder deflection for the fin are defined for the optimisation study.

Static aeroelastic requirements in optimisation are defined as minimum acceptable values of eleven effectiveness in roll or rudder effectiveness in yaw. These parameters design the torsional stiffness of wing/fin box and also the bend-twist coupling which

determines the wash-in/wash-out characteristics. Other constraints considered in optimisation'are failure criteria in the skins (modified Tsai-Hill criterion for composite plies), local buckling of skin panels between spars and limited technological constraints such as maximum and minimum thickness in any given direction as a ratio of total laminate thickness in a given zone. Aeroelastic constraint is an overall constraint on the structure and is independent of load cases. Details of the optimisation procedure are presented in Upadhya *et al* (1990b, pp. 485-90).

The results of various aeroelastic tailoring/optimisation studies on the wing are summarised below.

 (1) Table 1 presents evolution of optimum weight with design constraints for a generally used value of aeroelastic efficiency parameter. These results pertain to a $0^{\circ}/+40^{\circ}/-50^{\circ}/90^{\circ}$ lay-up.

(2) Figure 12 compares optimum weights of metallic (A1-Cu and AI-Li) and CFC (T300 & T800) wing skins taking AI-Cu skin weight for roll control efficiency value C as reference. Value B corresponds to table 1 and a 5% variation on either side is considered.

It is seen that (i) for a given material, weight increase is steeper at higher values of roll efficiency as more zones come under the influence of this constraint (figure 13), (ii) the increase in weight with roll efficiency is much smaller for composites when compared to metals. This arises from the advantage of aeroelastic tailoring with composites where only the thickness in a required direction is increased to meet aeroelastic requirements.

(3) Table 2 compares relative weights of wing skins for various types of lay-ups. It is seen that unbalanced $0^{\circ}/+45^{\circ}/-45^{\circ}/90^{\circ}$ lay-up gave the minimum weight. Balanced lay-up resulted in a 31% weight penalty. Comparison of weights of lay-ups 1, la, 2 and 3 showed that orienting the 0° fibres along the inclined spars is the optimum arrangement. The results also showed that in lay-up 1, the $+45^{\circ}$ direction was the most predominant one, accounting for 43.6% of the weight, followed by -45° (28.2%), 90° (15.6%) and 0° (12.6%) layers. In the case of balanced lay-up, both \pm 45° layers shared 37.2% of the weight. It is thus clear that while both \pm 45° layers contribute towards torsional stiffness, the predominant $+45^{\circ}$ layers in lay-up 1 also provide

Figure 10. Aeroelastic deformation shapes, $\alpha(\mathbf{a})$ and $\delta_a(\mathbf{b})$ effects.

Figure 11. Optimization zones on wing skins.

the required twist-bend coupling, causing a reduced nose-down twist (i.e., effective reduction in angle of attack) under an up-load on the elevon, leading to a lower weight structure for a given elevon effectiveness. In other lay-ups also, it was seen that the $+\theta$ layers were the most predominant.

(4) The wing tip displacements in a critical load case for design case B for the A1-Cu, Al-Li, T300 and T800 material designs were 179, 176, 210 and 201 mm, respectively. The higher wing tip deflections in the composite wing are again due to the tailoring effect where the bending stiffness is not increased in the same proportion as the torsional stiffness like in metal wings.

Aeroelastic analysis and optimisation studies on the fin (Kamal *et al* 1989) showed trends similar to that seen on the wing with the $+45^{\circ}$ layers being predominant. This design results in a coupled bending of the fin due to torsional load from the rudder, which induces a streamwise incidence opposed to the twist due to torsion, thus reducing the losses in the yaw moment effectiveness of the rudder due to flexibility. Another interesting observation was that rotating the entire lay-up, such that the

Design constraints	Weight (ratio)
Composite material - stress (failure criteria constraints only)	0-46
$Stress + buckling constraints$	1.0
$Stress + buckling + aeroelasticity$	1.25
$3 +$ Technological constraints	1.31
Aeroelastic constraint only	0.90
Aluminium alloy skin (comparable with 4)	2.25

Table 1. Evolution of optimum weight. Lay-up: $0^{\circ}/+40^{\circ}/-50^{\circ}/90^{\circ}$ on wing-box skin.

angle between 0° fibres and the Z-axis varied in the range 15 $^{\circ}$ to 35 $^{\circ}$, showed minimum skin weight (9% weight saving as compared to the 30° case) for the 15[°] orientation. This is most likely due to the fact that the predominant $+45^\circ$ layers provide relatively **more direct bending stiffness for this orientation, resulting in less induced spanwise incidence due to direct bending of the elastic axis due to sideload on the rudder. The most optimum fibre orientation is one which is a compromise between the coupled bending and direct bending effects which induce spanwise incidence in opposite directions.**

The study also revealed that the fin skin weight is very sensitive to the aeroelastic

Figure 13. Optimisation constraint influence zones.

Wing-box skin lay-up	Relative weight	
$0^{\circ}/+45^{\circ}/-45^{\circ}/90^{\circ}$	$1-00$	
$0/ + 45/ - 45/90$ (balanced)	$1 - 31$	
$10/+45/-45/90$	$1-20$	
$-10/ + 45/ - 45/90$	1.25	
$0/+ 40/- 40/90$	1.23	
$0/ + 40/ - 50/90$	$1 - 18$	
$0/+ 50/- 40/90$	1.29	
$0/+ 50/- 50/90$	1.25	
$0/+ 22.5/- 67.5/90$	1.65	

Table 2. Relative weight comparison.

Note: Reference axis for lay-up is inclined 20° aft of Y-axis (figure 5).

efficiency parameter. A requirement of 5% increase in supersonic yaw moment effectiveness of rudder resulted in a fin skin weight increase of nearly 36% .

3. Aeroservoelasticity

For the modern aircraft, use of an efficient flexible structure is possible with the availability of composite materials and modern design and analysis techniques, aided by large capacity, high speed computers and sophisticated structural testing methods. As the structure became more flexible, the structural frequencies have come down. At the same time advances in aircraft design have necessitated expansion of the role played by flight control systems (FCS). The aircraft is designed to be highly manoeuvrable, light, and more agile. For such an aircraft the flight control system is not just used for the control of the flight path, but also to meet the above design requirement. Thus the role of FCS has been expanded. High authority control systems, utilizing multiple blended feedbacks, are used to provide tailored aircraft response to meet mission requirements. In addition, the flight control system is used to provide artificial stability for statically unstable aircraft, reduce fatigue damage to the structure from gusts and manoeuvres, suppress flutter modes and improve ride quality. This active control technology helps to reduce structural weight of the aircraft, and provides a better aerodynamic design. With the introduction of high gain, faster response flight control systems to meet the above active control requirements, the control frequency bandwidth has increased. Further, as the frequency of operation of the control system increases, it excites the aircraft structure at higher frequencies, as a result of which the reduced frequency characterising the flow unsteadiness becomes significantly large indicating that unsteady aerodynamic effects need to be accounted for. The reduction in structural frequencies and coupled increase in the control system frequency bandwidth with the presence of unsteady aerodynamics leads to a new dynamic interaction problem which is defined as aeroservoelasticity (ASE). Thus, ASE is a multidisciplinary technology dealing with the interaction of the aircraft's flexible structure and the unsteady aerodynamic forces resulting from the motion of the aircraft with its flight control system. Detailed and complex mathematical models incorporating the effects of these technical disciplines are required to accurately predict ASE interactions and to design active control systems for flexible vehicle application.

3.1 *ASE encounters*

Several instances of ASE encounters for a variety of research, development, prototype and production aircraft are documented in literature. Felt *et al* (1979) have discussed in depth ASE encounters for the following aircraft:

B-36: An ASE instability was induced by the autopilot of B-36. For this aircraft the sensor package had been located in the tail gunner's compartment and significant body bending (flexible) motion had been picked up by the sensor. The solution was to move the sensor package to a position of relatively small body bending motion.

YF-16: This aircraft experienced two separate ASE instabilities during early flight tests. Initially these instabilities were not identified by analysis, because the analysis was carried out for high Mach number, low altitude flight conditions which were the most critical for flutter. However, a critical interaction occurred at a high subsonic Mach number, which was not considered in analysis. Later ASE analysis at the proper flight condition predicted the ASE instabilities which matched with the flight test results.

YF-17: YF-17 experienced two ASE instabilities, which were predicted during the analysis stage and verified with flight test results. Parametric ASE analysis of ground test and flight test interactions were carried out to select final notch filters for the flight control system.

B-52: The ccv ride quality system tested on a B-52 encountered servoelastic oscillations on ground due to local structural vibration of bulkheads or support beams. As the local structural details were not included in the dynamic mathematical model, this interaction was not identified by the analysis. By changing accelerometer mounting, the oscillations were eliminated.

F-4: ASE instability was encountered in modified F-4 aircraft during a sideslip manoeuvre in a gear down, flap down configuration. A resonance in the pitch axis was encountered. The instability occurred at 23 Hz, which was close to both the flap rotation mode and the stabilizer rotation mode frequencies. The instability mechanism was initiated by a flap buffet which fed into a pitch rate gyro located in the left wing root just forward of the flap. The problem was solved by additional filtering in the pitch axis.

F-16 and *F-18:* These aircraft also exhibited adverse dynamic interactions between the airframe aeroelastic characteristics and their flight control systems. Flight control modifications were carried out to solve this interaction problem.

3.2 *General formulation of ASE problem*

Very few references are available in literature on ASE formulation. Noll *et al* (1989) present activities in the area of ASE at the NASA Langley Research Centre. They have discussed different modelling and analysis techniques for the prediction of ASE interactions. Suryanarayan *et al* (1992) have discussed in detail various analysis steps required to be carried out for ASE analysis. The steps are given starting from structural, aerodynamic and control system modelling up to identification of ASE interations in

the flight envelope. The steps are as below.

(i) Normal mode analysis of the aircraft structure for a given mass case (mode shapes, frequencies, modal mass and modal stiffness computation).

(ii) Calculation of modal unsteady airloads as a function of reduced frequency and Mach number for harmonic motion.

(iii) Representation of modal unsteady airloads in the time domain for arbitrary motion.

(iv) Dynamic modelling of the actuator assemblies.

(v) Development of a flexible aircraft dynamic model taking into account the effects of elastic modes and unsteady airloads along with the actuator model (state-space model of flexible aircraft).

(vi) Open loop poles and zeros computation, formation of open loop transfer function for the flexible aircraft.

(vii) Calculation of open loop frequency response at the sensor location for a sinusoidal input to the actuator from the state-space model as well as from the open loop transfer functions.

(viii) Representation of control system dynamics in terms of transfer functions.

(ix) Development of closed loop aircraft description taking all the feedback element dynamics into account.

(x) ASE stability analysis for various flight points in the flight envelope.

The flexible aircraft state-space model as given in step (v) is used for active control design applications.

3.3 *ASE analysis tools*

The following general purpose analysis programs are documented in the literature for carrying out ASE analysis.

STARS (Gupta *et al* 1989): Structures, aerodynamics and related aeroservoelastic system analysis is a general-purpose structural analysis program that has a complete aeroservoelastic analysis capability. In the package, Pade and least squares approximation methods are available for time domain representation of unsteady aerodynamics and it is used for open and closed loop aeroservoelastic controls analysis.

ADAM and ADAM-2"0 (Noll *et al* 1986) (Analog and digital aeroservoelasticity method): This program combines the technologies of unsteady aerodynamics, multi-input/multi output (MIMO) controls and structural dynamics into an interactive analysis package.

ISAC (Interaction of structures, aerodynamics and control) (Sallee 1990): All the active control problems at NASA Langley are analysed using ISAC. The package has 3 methods for performing aerodynamic approximation and uses optimal method for control law synthesis.

ASEPACK, Aeroservoelasticity package (Suryanarayan *et al* 1992): This program has been developed at the Aeronautical Development Agency. The program takes structural dynamics and frequency domain unsteady aerodynamics input from the general purpose finite element package ELFINI. The package has been developed on similar lines to STARS. Various in-house developed new analysis techniques, namely, modified rational function approximation (RFA) for time-domain representation of unsteady aerodynamics and low-order aircraft plant model design for the use of flight

Figure 14. ASEPACK block diagram (Suryanarayan *et al* 1992).

Table 3. Comparison of ASEPACK and STARS programs.

Capability	ASEPACK	STARS
O/L and C/L S-plane stability analysis	Yes	Yes
Loop closure with feedback elements	Yes	Yes
Bode plots of O/L and C/L frequency response	Yes	Yes
Maximum state variables	No limit	100
Aerodynamic lag terms	No limit	4
Time history analysis	Yes	Yes
Actuator representation	Fourth order	Fourth order
Sensor dynamics	Yes	Yes
Anti-aliasing filter	Second order	First order
Notch/shaping filter	Yes	Yes
Subsonic/supersonic	Yes.	Yes
O/L and C/L Z-plane stability analysis	Yes:	Yes
Time domain representation	Pure lag	Conventional
Reduced order plant representation	Yes	No

control-law design and simulation studies are implemented in this package. Figure 14 shows the ASEPACK block diagram. Table 3 shows a comparison of the capabilities of the ASEPACK and STARS programs.

3.4 *Application of ASEPACK tO a typical fighter aircraft*

The ASE analysis package is used for analysis of a typical fly-by-wire fighter aircraft configuration. Figure 15 shows the first wing bending and torsion modes, first fuselage bending mode, and also a line representation of fuselage deformation in the first five symmetric modes. Figure 16 shows the accuracy of the time-domain representation of a typical aerodynamic coefficient and figure 17 shows the open-loop normal acceleration (both amplitude and phase) response of the flexible aircraft plant at the sensor location with the rigid and flexible contributions and the total response shown separately. For the present analysis two rigid body modes (heave and pitch) and the first four symmetric elastic modes covering wing bending and twisting, and fuselage bending are considered. Both open-loop and closed-loop stability and frequency response results are generated for a typical flight condition.

Figure 15. Free vibration mode shapes (Suryanarayan *et al* 1992). (a) Fuselage symmetric mode shapes; (b) wing bending; (e) wing torsion; (d) fuselage bending.

Figure 16. Frequency domain (FD) and time domain (TD) representation of C_{1a} **(Suryanarayan** *et al* **1992).**

Figure 17. Open loop frequency response results (Suryanarayan *et al* **1992).**

4. Conclusions

In the preceding sections, recent progress in the areas of aeroelastic tailoring, structural optimisation with aeroelastic requirements and aeroservoelasticity are discussed. Developments and applications of the above technologies in India are highlighted.

So far aeroelastic tailoring and active control technology have progressed independently. However, the aeroelastic benefits to be derived from the two techniques have their own limits. Effective integration of structural stiffness tailoring and active controls through simultaneous design of a structure and control law holds great promise (Livne *et al* 1990; Dracopaulos & Oz 1992). It can be expected that they will merge into a single design tool within the next decade.

The authors are grateful to Dr Kota Harinarayana for encouragement.

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