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An Existence Proof for the Hartree-Fock Time-dependent Problem with Bounded Two-Body Interaction

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Abstract. Using fixed point theorems for local contractions in Banach spaces, an existence and uniqueness proof for the Hartree-Fock time-dependent problem is given in the case of a finite Fermi system interacting via a bounded two-body potential. The existence proof for the "strong" solution of the evolution problem is obtained under suitable conditions on the initial state.

1. Introduction

In general, starting from a quasi-free (or generalized-free) state ρ of a finite or infinite Fermi system at the time $t = t_0$, the natural evolution of the system gives rise to a state ρ_t which does not remain quasi-free for $t > t_0$, and trustworthy methods of successive approximations for solving the evolution problem except in trivial cases are not known. An approximate procedure for solving this problem is provided by the time-dependent Hartree-Fock theory, first obtained by Dirac [1] and afterwards generalized by Bogoliubov [2] and Valatin [3]. These equations can be obtained by considering the evolution of the oneparticle density matrix T and assuming that ρ , remains quasi-free in a given time interval. Perturbative solutions of such equations for superconducting systems have been studied by Di Castro and Young [4].

In spite of the simplicity of the approach, the equation of motion for the one-particle density matrix T is non-linear so that the existence problem is not easy even in the most simple physical cases. Written in i84 A. Bove *et al.*

matrix form the equation in the gauge-invariant case is of the type (see e.g. Ref. $\lceil 5 \rceil$):

$$
i\frac{dT}{dt} = [A+U, T] \tag{1.1}
$$

where A is the kinetic energy operator and U is the self-consistent potential which is a linear function of T . U is the difference of two terms: $U = U_D - U_{EX}$, where U_D denotes the "local" part and U_{EX} the exchange part. Neglecting the spin coordinates, which are completely unessential for our purposes, and denoting by q the space coordinate, by φ a oneparticle wave-function, by $v(q, q')$ the two-body potential, and by $T(q, q')$ the "matrix element" of T in the coordinate representation, we have:

$$
(U_D \varphi)(q) = \iint v(q, q') T(q', q') d^3 q' \iint \varphi(q)
$$
 (1.2)

$$
(U_{EX}\varphi)(q) = -\int v(q,q') T(q,q') \varphi(q') d^3 q' . \qquad (1.3)
$$

Of course, Eq. (1.1) has to be solved with the given initial condition $T|_{t=0} = T_0$.

We give here an existence and uniqueness proof for the solution of Eq. (1.1) , assuming that the total number of particles is finite $(N = \int T(q, q) d^3 q < +\infty)$ and the two-particle potential $v(q, q')$ is bounded: $\sup_{q,q} |v(q,q')| < +\infty$.

2. Notations and Hypotheses

We denote by:

E a Hilbert space with inner product $\langle \cdot, \cdot \rangle$;

 $\mathscr{L}(E)$ the set of all bounded linear operators defined in E, equipped with the norm topology $\|\cdot\|$.

 $\mathscr{L}_1(E) \subset \mathscr{L}(E)$ the set of trace-class operators, equipped with the usual norm $\|\cdot\|_1 = Tr|\cdot|$.

 $\mathscr{L}(\mathscr{L}_1(E), \mathscr{L}(E))$ the Banach space of all linear continuous mappings $\mathscr{L}_1(E) \rightarrow \mathscr{L}(E)$, equipped with the usual norm $\|\cdot\|$ topology.

$$
H(E) = \{T, T \in \mathcal{L}(E), T = T^*\}
$$

\n
$$
H_1(E) = \{T, T \in \mathcal{L}_1(E), T = T^*\}
$$

\n
$$
C(0, \tau; H_1(E)) = \{f; f : [0, \tau] \to H_1(E), f \text{ continuous}\}
$$

where $\tau > 0$; C is a real Banach space equipped with the norm $|| f || = \sup \{ || f(t) ||_1, t \in [0, \tau] \}.$

Let $\tau \in \mathbb{R}_+$, $T_0 \in H_1(E)$, $A: D_A(\subseteq E) \to E$ a self-adjoint operator, $B \in \mathcal{L}(\mathcal{L}_1(E), \mathcal{L}(E))$ such that:

$$
T \in H_1(E) \to B(T) \in H(E). \tag{2.1}
$$

We consider the following problem: find a function $T(\cdot) \in C(0, \tau; H_1(E))$ such that:

$$
\begin{cases}\ni \frac{dT}{dt} = [A, T]_{-} + [B(T), T]_{-} \\
T(0) = T_{0}.\n\end{cases}
$$
\n(2.2)

Definition 2.1. A function $T \in C(0, \tau; H_1(E))$ is called a *mild* solution of the problem (2.2) if the following equality holds:

$$
T(t)x = e^{-itA} T_0 e^{itA} x + i \int_0^t e^{-i(t-s)A} [T(s), B(T(s))]_{-} e^{i(t-s)A} x ds
$$
 (2.3)

for every $x \in E$.

Definition 2.2. A function $T \in C(0, \tau; H_1(E))$ is called a *classical* solution of problem (2.2) if the following conditions are satisfied:

- i) $T(\cdot)$ is continuously differentiable on the interval [0, τ];
- ii) $\forall x \in D_A$, $\forall t \in [0, \tau]$, we have $T(t)x \in D_A$ and

$$
\begin{cases}\ni \frac{dT(t)}{dt} x = A T(t) x - T(t) A x + [B(T(t)), T(t)]_{-} x \\
T(0) x = T_0 x.\n\end{cases}
$$
\n(2.4)

It is easy to show that if A is a bounded operator defined on E the mild solution is also a classical solution.

3. Preliminary Results

Definition 3.1. For every $T \in H_1(E)$ we define a mapping $\varphi_T : D_A$ $\times D_A \rightarrow \mathbb{C}$ by the following relation:

$$
\varphi_T(x, y) = -i \langle Tx, Ay \rangle + i \langle Ax, Ty \rangle, \forall (x, y) \in D_A \times D_A. \tag{3.1}
$$

If φ_T is continuous on $D_A \times D_A$ with respect to the product topology, we denote by the same symbol the unique extension to $E \times E$ of φ_T .

Definition 3.2. Let a be the linear mapping defined by

$$
D_a = \{T; T \in H_1(E), \varphi_T \text{ is continuous with} \text{respect to the product topology of } E \times E\}
$$
 (3.2)

$$
\langle a(T)x, y \rangle = \varphi_T(x, y) \forall T \in D_a, \forall (x, y) \in E \times E.
$$

It is easy to show that $T \in D_a$, $x \in D_A$ implies $Tx \in D_A$ and the following equality holds

$$
a(T)x = -iATx + iTAx \tag{3.3}
$$

(see Ref. [8]).

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Lemma 3.3. *Let a have the same meaning as before; then the spectrum* $\sigma(a) \in i\mathbb{R}$ and

$$
(\lambda - a)^{-1} (T) x = \int_{0}^{\infty} e^{-\lambda t} e^{-itA} T e^{itA} x dt,
$$

\n
$$
\forall \lambda \in \mathbb{C}, \text{ Re}\lambda > 0, \forall x \in E, T \in H_1(E).
$$
 (3.4)

Proof. A detailed proof of relation (3.4) can be found in Ref. [8]. The statement $\sigma(a) \subset i\mathbb{R}$ then follows easily.

Proposition 3.4. *a is the infinitesimal generator of a contraction semigroup in* $H_1(E)$ *and the following relation holds:*

$$
e^{ta}(T) = e^{-itA} T e^{itA}, \quad \forall T \in H_1(E).
$$
 (3.5)

Proof. Since e^{itA} is unitary, we have

$$
||e^{-itA}Te^{itA}||_1=||T||_1.
$$
 (3.6)

The semigroup property can be checked in a trivial way, so that we have only to prove that:

$$
\lim_{t \to 0^+} e^{-itA} T e^{itA} = T \quad \forall T \in H_1(E).
$$
 (3.7)

Since the set of finite rank operators is dense in $\mathcal{L}_1(E)$ in the tracenorm topology $\|\cdot\|_1$, we can restrict ourselves to prove Eq. (3.7) for an arbitrary projection operator of rank one.

Let T be defined by

$$
Tx = \langle x, y \rangle y \quad \forall x \in E, \|y\| = 1.
$$

We have:

$$
(e^{-itA} T e^{itA} - T)x = \langle x, e^{-itA} y \rangle e^{-itA} y - \langle x, y \rangle y.
$$

The two-dimensional subspace generated by y and $e^{-itA}y$ is invariant with respect to the operator $e^{-itA} T e^{itA} - T$; so the eigenvalue problem is easily solved and one finds for the non-vanishing eigenvalues of $e^{-itA}Te^{itA}-T$:

$$
\lambda = \pm (1 - |\langle e^{-itA} y, y \rangle|^2)^{\frac{1}{2}}.
$$

It follows that

$$
||e^{-itA} T e^{itA} - T||_1 = 2\sqrt{1 - |\langle e^{-itA} y, y \rangle|^2} \xrightarrow[t \to 0]{} 0.
$$

Hence the semigroup defined by (3.7) is strongly continuous. By Lemma 3.3 a is the infinitesimal generator of this semigroup.

Let

$$
\gamma(T) = -i[B(T), T] \qquad \forall \, T \in H_1(E) \tag{3.8}
$$

then $\gamma: H_1(E) \to H_1(E)$ is a continuous mapping and

$$
\|\gamma(T)\|_1 \le 2\|B\| \left(\|T\|_1\right)^2. \tag{3.9}
$$

Proposition 3.5. *The following statements are true:*

- i) γ is locally lipschitzian on $H_1(E)$.
- ii) γ *is differentiable and*

$$
\gamma'(T)\cdot S=-i[B(S),T]-i[B(T),S].
$$

iii) *The following inequality holds*

$$
||T||_1 \le ||T - \alpha \gamma(T)||_1
$$
, $\forall T \in H_1(E)$, $\forall \alpha \in \mathbb{R}_+$. (3.10)

Proof. i) Let $||T||_1$, $||S||_1 \le r, r > 0$; then

$$
\|\gamma(T) - \gamma(S)\|_1 = \|\begin{bmatrix} B(T), T \end{bmatrix} - \begin{bmatrix} B(T), S \end{bmatrix} - \begin{bmatrix} B(T), S \end{bmatrix} - \begin{bmatrix} B(S), S \end{bmatrix} - \|_1
$$

\n
$$
\leq \|\begin{bmatrix} B(T), T - S \end{bmatrix} - \|_1 + \|\begin{bmatrix} B(T - S), S \end{bmatrix} - \|_1
$$

\n
$$
\leq 4 \|\begin{bmatrix} B\|\|_1 \|T - S\|_1 ;
$$

ii) can be directly verified.

iii) Let $\alpha > 0$, $T \in H_1(E)$, and

$$
T - \alpha \gamma(T) = S. \tag{3.11}
$$

Denoting by $\{\lambda_i\}$ the set of the eigenvalues of T and by $\{u_i\}$ a corresponding set of orthonormal eigenvectors, we can write:

$$
Tx = \sum_{i=1}^{\infty} \lambda_i \langle x, u_i \rangle u_i.
$$
 (3.12)

Defining:

$$
\sigma(T)x = \sum_{i=1}^{\infty} sign(\lambda_i) \langle x, u_i \rangle u_i
$$
 (3.13)

$$
|T|x = \sum_{i=1}^{\infty} |\lambda_i| \langle x, u_i \rangle u_i
$$
 (3.14)

since

$$
Tr[\gamma(T)\sigma(T)] = Tr[\sigma(T)\gamma(T)] = 0 \qquad (3.15)
$$

it follows that:

$$
||T||_1 = \frac{1}{2} Tr(S \sigma(T) + \sigma(T)S)
$$

\n
$$
\leq \frac{1}{2} Tr(|S \sigma(T) + \sigma(T)S|) \leq ||\sigma(T)|| ||S||_1 = ||S||_1
$$
\n(3.16)

which proves (3.10).

4. The Existence Theorem

Let X be a real Banach space (with norm $|| \cdot ||_X$), $C(0, \tau; X)$ the Banach space of the continuous mappings $[0, \tau] \rightarrow \hat{X}$ equipped with the norm $\|\cdot\| = \sup{\{\|\cdot(t)\|_X, t \in [0, \tau]\}}$, *M* the infinitesimal generator of a contraction semigroup $t \rightarrow e^{tM}$ in *X.* $f: X \rightarrow X$ a locally lipschitzian mapping¹ such that:

$$
||x||_X \le ||x - \alpha f(x)||_X \quad \forall \alpha \ge 0, \ x \in X. \tag{4.1}
$$

We consider the following integral equation:

$$
u(t) = e^{tM} u_0 + \int_{0}^{t} e^{(t-s)M} f[u(s)] ds
$$
 (4.2)

where u_0 is a given element in X and $u \in C(0, \tau; X)$.

Then the following theorem holds: (for the proof see Refs. [6, 7, 11]).

Theorem 4.1. *There exists a unique solution of the problem* (4.2). *This solution depends continuously upon the initial condition. Furthermore, if* $u_0 \in D_M$ and is differentiable in X, then u is differentiable in [0, τ], $u(t) \in D_M \,\forall t \in [0, \tau]$ *and we have*

$$
\begin{cases}\n\frac{du(t)}{dt} = M u(t) + f[u(t)] \\
u(0) = u_0.\n\end{cases}
$$
\n(4.3)

Applying Theorem 4.1 to our case, we obtain:

Theorem 4.2. $\forall T_0 \in H_1(E)$ there exists a unique mild solution $T(\cdot)$ of *Eq.* (2.2). *Furthermore, if the mapping*

$$
(x, y) \rightarrow \langle T_0 x, Ay \rangle + \langle Ax, T_0 y \rangle \quad \forall (x, y) \in D_A \times D_A
$$

is continuous with respect to the product topology of $E \times E$ *, then* $T(\cdot)$ *is a classical solution which depends continuously upon the initial condition.*

Proof. It is enough to apply Theorem 4.1 with $f = \gamma$, $M = a$, $X = H_1(E)$ and use Propositions 3.4, 3.5.

Proposition 4.3. *If* $T(\cdot)$ *is a mild solution of problem* (2.2) *then for any* $t \in [0, \tau]$ *there exists a self-adjoint operator* $K(t)$ *such that*

$$
T(t) = e^{-iK(t)} T_0 e^{iK(t)}.
$$
 (4.4)

Proof. Let $T_0 \in D_a$ and $T(\cdot)$ be the classical solution of problem (2.2). We put $Q(t) = B(T(t))$, $t \in [0, \tau]$; Q is a Lipschitz continuous mapping $[0, \tau] \rightarrow H(E)$. It is easy to see that for the linear problem

$$
\begin{cases}\ni \frac{du}{dt} = (A + B(T(t)))u(t) \\
u(t_0) = u_0\n\end{cases}
$$
\n(4.5)

¹ By locally lipschitzian we mean that for any $r>0$, $u \in X$, $v \in X$, $||u||_X \leq r$, $||v||_X \leq r$, $||\exists N_r > 0$ such that $||f(u) - f(v)||_X \le N_r ||u - v||_X$.

there exists a unitary Green function $U(t, s)$. It follows [8] that the problem

$$
\begin{cases}\ni \frac{dS(t)}{dt} = [A + B(T(t)), S(t)] - \\ S(0) = T_0 \end{cases}
$$
\n(4.6)

has a unique classical solution given by

$$
S(t) = U(t, 0) T_0 U(-t, 0).
$$
 (4.7)

Furthermore $T(\cdot)$ is obviously a solution of (4.6), so that, from the uniqueness of the solution, we have $S = T$.

For any $t \in [0, \tau]$ let $K(t)$ be the self-adjoint operator such that $U(-t, 0) = e^{iR(t)}$; Eq. (4.4) then follows.

If $T_0 \in H_1(E)$ we can prove (4.7) by a straightforward argument of density, since D_a is dense in $H₁(E)$.

5. The Hartree-Fock Time-dependent Problem

We now give sufficient conditions in order that Eq. (1.1) be solvable by the methods of Section 4.

Let $E = \mathcal{L}^2(R^3)$ be the one-particle Hilbert space. We assume that the two-particle potential $v(q, q')$

$$
v: \mathbb{R}^3 \times \mathbb{R}^3 \to \mathbb{R}
$$
 (5.1)

is a real bounded measurable function verifying the conditions:

$$
v(q, q') = v(q', q)
$$

$$
|v(q, q')| \leq V, \ \forall q, q' \in \mathbb{R}^3.
$$
 (5.2)

Let $\{\varphi_k\}$ be a complete orthonormal system in E. We write the oneparticle density matrix in the form

$$
T(q, q') = \sum_{k=1}^{\infty} \lambda_k \varphi_k(q) \overline{\varphi_k(q')}.
$$
 (5.3)

The positivity condition for the gauge-invariant quasi-free state defined by T implies [9, 10]

$$
0 \leq \lambda_k \leq 1 \tag{5.4}
$$

Since we consider only systems with finite total number of particles, we have

$$
\sum_{k=1}^{\infty} \lambda_k < \infty \ . \tag{5.5}
$$

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 $T(q, q')$ determines an operator $T \in H_1(E)$ such that

$$
T\psi = \sum_{k=1}^{\infty} \lambda_k(\psi, \varphi_k) \varphi_k.
$$
 (5.6)

Of course

$$
||T||_1 = \sum_{k=1}^{\infty} \lambda_k = \int_{\mathbb{R}^3} T(q, q) d^3 q.
$$
 (5.7)

We define

$$
B_D(\cdot): H_1(E) \to H(E), \qquad B_{EX}(\cdot): H_1(E) \to H(E)
$$

by the equalities

$$
B_{\mathcal{D}}(T)\varphi = U_{\mathcal{D}}\varphi, \ B_{\mathcal{E}X}(T)\varphi = U_{\mathcal{E}X}\varphi \qquad \forall \varphi \in E \tag{5.8}
$$

where U_p and U_{EX} are given by (1.2), (1.3) respectively.

It is easy to see that B_n is bounded and

$$
\|B_D\| \le V. \tag{5.9}
$$

Since

$$
||B_{EX}(T)|| \leq \left(\int_{\mathbb{R}^3 \times \mathbb{R}^3} |v(q, q')|^{2} (q, q')|^{2} d^{3} q d^{3} q'\right)^{\frac{1}{2}}
$$

\n
$$
\leq V \left(\sum_{k=1}^{\infty} \lambda_{k}^{2}\right)^{\frac{1}{2}} \leq V ||T||_{1}
$$
\n(5.10)

also $||B_{EX}|| \leq V$, so that $B(T) = B_D(T) + B_{EX}(T)$ satisfies the hypotheses of Section 2. Hence the existence theorem applies and Proposition 4.3 guarantees that $T(t)$, $t \in [0, \tau]$ satisfies the positivity condition (5.4) if T_0 satisfies (5.4). Hence $T(t)$ defines a quasi-free state. Furthermore the state remains pure if it is initially pure $(T_0^2 = T_0)$.

The existence of the strong solution is guaranteed by the following condition on the initial state

$$
R_T \subseteq D_A. \tag{5.11}
$$

This condition is physically reasonable in the greatest majority of the applications, where A is either the kinetic energy operator, or the kinetic energy plus a central field. If (5.11) holds, AT_0 is bounded so that Eq. (3.3) holds.

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