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An Existence Proof for the Hartree-Fock Time-dependent Problem with Bounded Two-Body Interaction

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Abstract. Using fixed point theorems for local contractions in Banach spaces, an existence and uniqueness proof for the Hartree-Fock time-dependent problem is given in the case of a finite Fermi system interacting via a bounded two-body potential. The existence proof for the "strong" solution of the evolution problem is obtained under suitable conditions on the initial state.

1. Introduction

In general, starting from a quasi-free (or generalized-free) state ϱ of a finite or infinite Fermi system at the time $t = t_0$, the natural evolution of the system gives rise to a state ϱ_t which does not remain quasi-free for $t > t_0$, and trustworthy methods of successive approximations for solving the evolution problem except in trivial cases are not known. An approximate procedure for solving this problem is provided by the time-dependent Hartree-Fock theory, first obtained by Dirac [1] and afterwards generalized by Bogoliubov [2] and Valatin [3]. These equations can be obtained by considering the evolution of the oneparticle density matrix T and assuming that ϱ_t remains quasi-free in a given time interval. Perturbative solutions of such equations for superconducting systems have been studied by Di Castro and Young [4].

In spite of the simplicity of the approach, the equation of motion for the one-particle density matrix T is non-linear so that the existence problem is not easy even in the most simple physical cases. Written in A. Bove et al.

matrix form the equation in the gauge-invariant case is of the type (see e.g. Ref. [5]): dT

$$i\frac{dT}{dt} = [A+U,T]_{-}$$
 (1.1)

where A is the kinetic energy operator and U is the self-consistent potential which is a linear function of T. U is the difference of two terms: $U = U_D - U_{EX}$, where U_D denotes the "local" part and U_{EX} the exchange part. Neglecting the spin coordinates, which are completely unessential for our purposes, and denoting by q the space coordinate, by φ a oneparticle wave-function, by v(q, q') the two-body potential, and by T(q, q')the "matrix element" of T in the coordinate representation, we have:

$$(U_D \varphi)(q) = \left[\int v(q, q') T(q', q') d^3 q' \right] \varphi(q)$$
(1.2)

$$(U_{EX}\phi)(q) = -\int v(q,q') T(q,q') \phi(q') d^3 q'.$$
(1.3)

Of course, Eq. (1.1) has to be solved with the given initial condition $T|_{t=0} = T_0$.

We give here an existence and uniqueness proof for the solution of Eq. (1.1), assuming that the total number of particles is finite $(N = \int T(q, q) d^3 q < +\infty)$ and the two-particle potential v(q, q') is bounded: $\sup_{q,q'} |v(q, q')| < +\infty$.

2. Notations and Hypotheses

We denote by:

E a Hilbert space with inner product $\langle \cdot, \cdot \rangle$;

 $\mathscr{L}(E)$ the set of all bounded linear operators defined in *E*, equipped with the norm topology $\|\cdot\|$.

 $\mathscr{L}_1(E) \subset \mathscr{L}(E)$ the set of trace-class operators, equipped with the usual norm $\|\cdot\|_1 = Tr|\cdot|$.

 $\mathscr{L}(\mathscr{L}_1(E), \mathscr{L}(E))$ the Banach space of all linear continuous mappings $\mathscr{L}_1(E) \to \mathscr{L}(E)$, equipped with the usual norm $\|\|\cdot\|\|$ topology.

$$H(E) = \{T, T \in \mathcal{L}(E), T = T^*\}$$
$$H_1(E) = \{T, T \in \mathcal{L}_1(E), T = T^*\}$$
$$C(0, \tau; H_1(E)) = \{f; f: [0, \tau] \rightarrow H_1(E), f \text{ continuous}\}$$

where $\tau > 0$; C is a real Banach space equipped with the norm $||f|| = \sup \{||f(t)||_1, t \in [0, \tau]\}.$

Let $\tau \in \mathbb{R}_+$, $T_0 \in H_1(E)$, $A: D_A(\subseteq E) \to E$ a self-adjoint operator, $B \in \mathscr{L}(\mathscr{L}_1(E), \mathscr{L}(E))$ such that:

$$T \in H_1(E) \to B(T) \in H(E).$$
 (2.1)

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We consider the following problem: find a function $T(\cdot) \in C(0, \tau; H_1(E))$ such that:

$$\begin{cases} i \frac{dT}{dt} = [A, T]_{-} + [B(T), T]_{-} \\ T(0) = T_{0}. \end{cases}$$
(2.2)

Definition 2.1. A function $T \in C(0, \tau; H_1(E))$ is called a *mild* solution of the problem (2.2) if the following equality holds:

$$T(t)x = e^{-itA} T_0 e^{itA} x + i \int_0^t e^{-i(t-s)A} [T(s), B(T(s))]_- e^{i(t-s)A} x \, ds \ (2.3)$$

for every $x \in E$.

Definition 2.2. A function $T \in C(0, \tau; H_1(E))$ is called a *classical* solution of problem (2.2) if the following conditions are satisfied:

- i) $T(\cdot)$ is continuously differentiable on the interval $[0, \tau]$;
- ii) $\forall x \in D_A$, $\forall t \in [0, \tau]$, we have $T(t)x \in D_A$ and

$$\begin{cases} i \frac{dT(t)}{dt} x = A T(t) x - T(t) A x + [B(T(t)), T(t)]_{-} x \\ T(0) x = T_{0} x . \end{cases}$$
(2.4)

It is easy to show that if A is a bounded operator defined on E the mild solution is also a classical solution.

3. Preliminary Results

Definition 3.1. For every $T \in H_1(E)$ we define a mapping $\varphi_T : D_A \times D_A \to \mathbb{C}$ by the following relation:

$$\varphi_T(x, y) = -i\langle Tx, Ay \rangle + i\langle Ax, Ty \rangle, \forall (x, y) \in D_A \times D_A.$$
(3.1)

If φ_T is continuous on $D_A \times D_A$ with respect to the product topology, we denote by the same symbol the unique extension to $E \times E$ of φ_T .

Definition 3.2. Let a be the linear mapping defined by

$$D_a = \{T; T \in H_1(E), \varphi_T \text{ is continuous with} \\ \text{respect to the product topology of } E \times E\}$$
(3.2)
$$\langle a(T)x, y \rangle = \varphi_T(x, y) \forall T \in D_a, \forall (x, y) \in E \times E.$$

It is easy to show that $T \in D_a$, $x \in D_A$ implies $Tx \in D_A$ and the following equality holds

$$a(T)x = -iATx + iTAx \tag{3.3}$$

(see Ref. [8]).

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Lemma 3.3. Let a have the same meaning as before; then the spectrum $\sigma(a) \in i\mathbb{R}$ and

$$(\lambda - a)^{-1} (T) x = \int_{0}^{\infty} e^{-\lambda t} e^{-itA} T e^{itA} x dt,$$

$$\forall \lambda \in \mathbb{C}, \ \operatorname{Re} \lambda > 0, \ \forall x \in E, \ T \in H_1(E).$$
(3.4)

Proof. A detailed proof of relation (3.4) can be found in Ref. [8]. The statement $\sigma(a) \subset i\mathbb{R}$ then follows easily.

Proposition 3.4. *a* is the infinitesimal generator of a contraction semigroup in $H_1(E)$ and the following relation holds:

$$e^{ia}(T) = e^{-itA} T e^{itA}, \quad \forall T \in H_1(E).$$
 (3.5)

Proof. Since e^{itA} is unitary, we have

$$\|e^{-itA} T e^{itA}\|_{1} = \|T\|_{1}.$$
(3.6)

The semigroup property can be checked in a trivial way, so that we have only to prove that:

$$\lim_{t \to 0^+} e^{-itA} T e^{itA} = T \quad \forall T \in H_1(E) .$$
(3.7)

Since the set of finite rank operators is dense in $\mathscr{L}_1(E)$ in the tracenorm topology $\|\cdot\|_1$, we can restrict ourselves to prove Eq. (3.7) for an arbitrary projection operator of rank one.

Let T be defined by

$$Tx = \langle x, y \rangle y \quad \forall x \in E, ||y|| = 1.$$

We have:

$$(e^{-itA}Te^{itA}-T)x = \langle x, e^{-itA}y \rangle e^{-itA}y - \langle x, y \rangle y.$$

The two-dimensional subspace generated by y and $e^{-itA}y$ is invariant with respect to the operator $e^{-itA}Te^{itA}-T$; so the eigenvalue problem is easily solved and one finds for the non-vanishing eigenvalues of $e^{-itA}Te^{itA}-T$:

$$\lambda = \pm (1 - |\langle e^{-itA} y, y \rangle|^2)^{\frac{1}{2}}.$$

It follows that

$$\|e^{-itA}Te^{itA} - T\|_{1} = 2|\sqrt{1 - |\langle e^{-itA}y, y \rangle|^{2}}_{t \to 0^{+}} = 0.$$

Hence the semigroup defined by (3.7) is strongly continuous. By Lemma 3.3 *a* is the infinitesimal generator of this semigroup.

Let

$$\gamma(T) = -i[B(T), T] \quad \forall T \in H_1(E)$$
(3.8)

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then $\gamma: H_1(E) \rightarrow H_1(E)$ is a continuous mapping and

$$\|\gamma(T)\|_{1} \leq 2 \|B\| (\|T\|_{1})^{2}.$$
(3.9)

Proposition 3.5. The following statements are true:

- i) γ is locally lipschitzian on $H_1(E)$.
- ii) γ is differentiable and

$$\gamma'(T) \cdot S = -i[B(S), T] - i[B(T), S].$$

iii) The following inequality holds

$$\|T\|_{1} \leq \|T - \alpha \gamma(T)\|_{1}, \quad \forall T \in H_{1}(E), \ \forall \alpha \in \mathbb{R}_{+}.$$
(3.10)

Proof. i) Let $||T||_1$, $||S||_1 \leq r, r > 0$; then

$$\begin{aligned} \|\gamma(T) - \gamma(S)\|_{1} &= \|[B(T), T]_{-} - [B(T), S]_{-} + [B(T), S]_{-} - [B(S), S]_{-}\|_{1} \\ &\leq \|[B(T), T - S]_{-}\|_{1} + \|[B(T - S), S]_{-}\|_{1} \\ &\leq 4 \||B\|| r \|T - S\|_{1}; \end{aligned}$$

ii) can be directly verified.

iii) Let $\alpha > 0$, $T \in H_1(E)$, and

$$T - \alpha \gamma(T) = S \,. \tag{3.11}$$

Denoting by $\{\lambda_i\}$ the set of the eigenvalues of T and by $\{u_i\}$ a corresponding set of orthonormal eigenvectors, we can write:

$$T x = \sum_{i=1}^{\infty} \lambda_i \langle x, u_i \rangle u_i.$$
(3.12)

Defining:

$$\sigma(T)x = \sum_{i=1}^{\infty} \operatorname{sign}(\lambda_i) \langle x, u_i \rangle u_i$$
(3.13)

$$|T|x = \sum_{i=1}^{\infty} |\lambda_i| \langle x, u_i \rangle u_i$$
(3.14)

since

$$Tr[\gamma(T) \sigma(T)] = Tr[\sigma(T) \gamma(T)] = 0$$
(3.15)

it follows that:

$$\|T\|_{1} = \frac{1}{2} Tr(S\sigma(T) + \sigma(T)S)$$

$$\leq \frac{1}{2} Tr(|S\sigma(T) + \sigma(T)S|) \leq \|\sigma(T)\| \|S\|_{1} = \|S\|_{1}$$
(3.16)

which proves (3.10).

4. The Existence Theorem

Let X be a real Banach space (with norm $\| \|_X$), $C(0, \tau; X)$ the Banach space of the continuous mappings $[0, \tau] \to X$ equipped with the norm $\| \cdot \| = \sup \{ \| \cdot (t) \|_X, t \in [0, \tau] \}$, M the infinitesimal generator of a contraction semigroup $t \to e^{tM}$ in X. $f: X \to X$ a locally lipschitzian mapping¹ such that:

$$\|x\|_{X} \leq \|x - \alpha f(x)\|_{X} \quad \forall \alpha \geq 0, \ x \in X.$$

$$(4.1)$$

We consider the following integral equation:

$$u(t) = e^{tM}u_0 + \int_0^t e^{(t-s)M} f[u(s)] ds$$
(4.2)

where u_0 is a given element in X and $u \in C(0, \tau; X)$.

Then the following theorem holds: (for the proof see Refs. [6, 7, 11]).

Theorem 4.1. There exists a unique solution of the problem (4.2). This solution depends continuously upon the initial condition. Furthermore, if $u_0 \in D_M$ and is differentiable in X, then u is differentiable in $[0, \tau]$, $u(t) \in D_M \forall t \in [0, \tau]$ and we have

$$\begin{cases} \frac{du(t)}{dt} = M u(t) + f[u(t)] \\ u(0) = u_0. \end{cases}$$
(4.3)

Applying Theorem 4.1 to our case, we obtain:

Theorem 4.2. $\forall T_0 \in H_1(E)$ there exists a unique mild solution $T(\cdot)$ of Eq. (2.2). Furthermore, if the mapping

$$(x, y) \rightarrow \langle T_0 x, A y \rangle + \langle A x, T_0 y \rangle \quad \forall (x, y) \in D_A \times D_A$$

is continuous with respect to the product topology of $E \times E$, then $T(\cdot)$ is a classical solution which depends continuously upon the initial condition.

Proof. It is enough to apply Theorem 4.1 with $f = \gamma$, M = a, $X = H_1(E)$ and use Propositions 3.4, 3.5.

Proposition 4.3. If $T(\cdot)$ is a mild solution of problem (2.2) then for any $t \in [0, \tau]$ there exists a self-adjoint operator K(t) such that

$$T(t) = e^{-iK(t)} T_0 e^{iK(t)} .$$
(4.4)

Proof. Let $T_0 \in D_a$ and $T(\cdot)$ be the classical solution of problem (2.2). We put $Q(t) = B(T(t)), t \in [0, \tau]; Q$ is a Lipschitz continuous mapping $[0, \tau] \rightarrow H(E)$. It is easy to see that for the linear problem

$$\begin{cases} i \frac{du}{dt} = (A + B(T(t))) u(t) \\ u(t_0) = u_0 \end{cases}$$

$$(4.5)$$

¹ By locally lipschitzian we mean that for any r > 0, $u \in X$, $v \in X$, $||u||_X \leq r$, $||v||_X \leq r$, $\exists N_r > 0$ such that $||f(u) - f(v)||_X \leq N_r ||u - v||_X$.

there exists a unitary Green function U(t, s). It follows [8] that the problem

$$\begin{cases} i \frac{dS(t)}{dt} = [A + B(T(t)), S(t)]_{-} \\ S(0) = T_{0} \end{cases}$$
(4.6)

has a unique classical solution given by

$$S(t) = U(t, 0) T_0 U(-t, 0).$$
(4.7)

Furthermore $T(\cdot)$ is obviously a solution of (4.6), so that, from the uniqueness of the solution, we have S = T.

For any $t \in [0, \tau]$ let K(t) be the self-adjoint operator such that $U(-t, 0) = e^{iK(t)}$; Eq. (4.4) then follows.

If $T_0 \in H_1(E)$ we can prove (4.7) by a straightforward argument of density, since D_a is dense in $H_1(E)$.

5. The Hartree-Fock Time-dependent Problem

We now give sufficient conditions in order that Eq. (1.1) be solvable by the methods of Section 4.

Let $E = \mathcal{L}^2(\mathbb{R}^3)$ be the one-particle Hilbert space. We assume that the two-particle potential v(q, q')

$$v: \mathbb{R}^3 \times \mathbb{R}^3 \to \mathbb{R} \tag{5.1}$$

is a real bounded measurable function verifying the conditions:

$$v(q, q') = v(q', q)$$

$$|v(q, q')| \leq V, \ \forall q, q' \in \mathbb{R}^3.$$
(5.2)

Let $\{\varphi_k\}$ be a complete orthonormal system in *E*. We write the oneparticle density matrix in the form

$$T(q,q') = \sum_{k=1}^{\infty} \lambda_k \varphi_k(q) \,\overline{\varphi_k(q')} \,.$$
(5.3)

The positivity condition for the gauge-invariant quasi-free state defined by T implies [9, 10]

$$0 \le \lambda_k \le 1 . \tag{5.4}$$

Since we consider only systems with finite total number of particles, we have

$$\sum_{k=1}^{\infty} \lambda_k < \infty . \tag{5.5}$$

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T(q, q') determines an operator $T \in H_1(E)$ such that

$$T\psi = \sum_{k=1}^{\infty} \lambda_k(\psi, \varphi_k)\varphi_k.$$
 (5.6)

Of course

$$||T||_{1} = \sum_{k=1}^{\infty} \lambda_{k} = \int_{\mathbb{R}^{3}} T(q, q) d^{3} q.$$
 (5.7)

We define

$$B_D(\cdot): H_1(E) \to H(E), \quad B_{EX}(\cdot): H_1(E) \to H(E)$$

by the equalities

$$B_D(T)\varphi = U_D\varphi, \ B_{EX}(T)\varphi = U_{EX}\varphi \quad \forall \varphi \in E$$
 (5.8)

where U_D and U_{EX} are given by (1.2), (1.3) respectively.

It is easy to see that B_p is bounded and

$$|||B_D||| \le V. \tag{5.9}$$

Since

$$\|B_{EX}(T)\| \leq \left(\int_{\mathbb{R}^{3} \times \mathbb{R}^{3}} |v(q, q') T(q, q')|^{2} d^{3} q d^{3} q'\right)^{\frac{1}{2}}$$

$$\leq V\left(\sum_{k=1}^{\infty} \lambda_{k}^{2}\right)^{\frac{1}{2}} \leq V \|T\|_{1}$$
(5.10)

also $|||B_{EX}||| \leq V$, so that $B(T) = B_D(T) + B_{EX}(T)$ satisfies the hypotheses of Section 2. Hence the existence theorem applies and Proposition 4.3 guarantees that $T(t), t \in [0, \tau]$ satisfies the positivity condition (5.4) if T_0 satisfies (5.4). Hence T(t) defines a quasi-free state. Furthermore the state remains pure if it is initially pure $(T_0^2 = T_0)$.

The existence of the strong solution is guaranteed by the following condition on the initial state

$$R_T \subseteq D_A \,. \tag{5.11}$$

This condition is physically reasonable in the greatest majority of the applications, where A is either the kinetic energy operator, or the kinetic energy plus a central field. If (5.11) holds, $A T_0$ is bounded so that Eq. (3.3) holds.

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