The Scalar Curvature of Minimal Hypersurfaces in Spheres

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Introduction

Let M be a closed minimally immersed hypersurface of S^{n+1} , and h its second fundamental form. We denote the square of the length of h by S. It follows from the Gauss and Codazzi equations that the apparently extrinsic quantity S is in fact intrinsic and is given by

$$S=n(n-1)-R,$$

where R is the scalar curvature of M. If $0 \le S(x) \le n$ for all $x \in M$, then either $S \equiv 0$ or $S \equiv n$ [6]. In the case that $S \equiv n$, Chern, do Carmo, Kobayashi; and Lawson independently proved that M is a Clifford torus [2, 4]. In a previous paper [5] we showed that there exists a positive real number $C(n) > 0 \left[C(3) = 3 \text{ and } C(n) \ge \frac{1}{12n} \text{ in general} \right]$ such that if S(x) is a constant bigger than n then it must be bigger than or

equal to n+C(n). We also learned that Naoya Doi has worked on the same problem [3]. His main results are for minimal hypersurface M of S^{n+1} with constant scalar curvature and whose sectional curvature is bounded above by 1, he proved that either S=0 or $S \ge 2(2n-3)$. However, under his assumptions it is easily seen that either S=0; or n=3, S=6 and M is the classical isoparametric example. To see this, let e_1, \ldots, e_n be a local orthonormal frame field of principal curvature directions of M, then the sectional curvature in the direction e_i , e_j , for $i \ne j$, is $1 + \lambda_i \lambda_i$, where λ_i 's are the principal curvatures. The conditions

$$\sum_{i=1}^{n} \lambda_{i} = 0,$$

$$\sum_{i} \lambda_{i}^{2} = S, \text{ constant},$$

$$1 + \lambda_{i} \lambda_{i} \leq 1, \text{ for } i \neq j,$$

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imply that there are at most one positive λ_i and one negative λ_i and the principal curvatures of M are constants. Hence either $\lambda_i = 0$ for all i, which gives S = 0; or by Theorem 1 of [5], n=3, S=6 and M is the classical isoparametric example.

In this paper, we prove a pinching theorem for minimal hypersurfaces in S^{n+1} for $n \leq 5$:

Theorem A. Let M be a closed minimally immersed hypersuface in S^{n+1} , $n \le 5$, and S the square of the length of the second fundamental form of M. Then there exists $\delta(n) > 0$ such that if $n \le S(x) \le n + \delta(n)$ then S(x) = n, hence M is a Clifford torus.

The proof uses the equations for Δh , $\Delta(\nabla h)$, and some integral equations naturally associated to the second fundamental form h. Since we do not assume that S is a constant function, the estimate we have in [5] can not be applied here, and the technique of using integral equations seems essential.

In the end of this paper, we give a proof of the theorem we stated in [5], namely:

Theorem B. Let M^3 be a closed minimal hypersurface with constant scalar curvature R in S^4 . If all three principal curvatures of M are distinct at every point, then R = 0.

1. Formulas Involving the Second Fundamental Form of Minimal Hypersurfaces

In this section, we will review the notation used in our previous paper [5], derive several new formulas and give a proof of Theorem A. Let M be a minimal hypersurface of S^{n+1} , and e_1, \ldots, e_n a local orthonormal frame field on M, w_1, \ldots, w_n its dual coframe. Then we have

$$I = \sum_{i} w_i^2 , \qquad (1.1)$$

$$II = h = \sum_{i,j} h_{ij} w_i w_j, \qquad h_{ij} = h_{ji},$$
(1.2)

$$\nabla h = \sum_{i,j,k} h_{ijk} w_i w_j w_k, \qquad h_{ijk} = h_{ikj}, \qquad (1.3)$$

$$\nabla^2 h = \sum_{i,j,k,l} h_{ijkl} w_i w_j w_k w_l, \qquad (1.4)$$

where

$$h_{ijkl} = h_{ijlk} + \sum_{m} h_{mj} R_{mikl} + \sum_{m} h_{im} R_{mjkl}.$$

$$V^{3}h = \sum_{\substack{i, j, k, l \\ m}} h_{ijklm} w_{i} w_{j} w_{k} w_{l} w_{m}, \qquad (1.5)$$

where

$$h_{ijklm} = h_{ijkml} + \sum_{r} h_{rjk} R_{rilm} + \sum_{r} h_{irk} R_{rjlm} + \sum_{r} h_{ijr} R_{rklm},$$
$$\Delta h_{ij} = (n-S)h_{ij}, \qquad (1.6)$$

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where

$$S = |h|^2$$
.

Since we do not assume S is a constant function, the same computation as in [5] will lead to a slightly different formula for $\Delta(\nabla h)$:

$$\Delta h_{ijk} = (2n+3-S)h_{ijk} + 2\sum_{m,l} (h_{iml}h_{mk}h_{jl} + h_{jml}h_{ml}h_{lk} + h_{kml}h_{ml}h_{lj}) - \sum_{m,l} (h_{ijm}h_{ml}h_{lk} + h_{ikm}h_{ml}h_{lj} + h_{jkm}h_{ml}h_{li}) - (S_ih_{jk} + S_jh_{ik} + S_kh_{ij}).$$
(1.7)

Then it follows easily from (1.6), (1.7) that we have:

Theorem 1. Let M be an immersed minimal hypersurface of S^{n+1} , h its second fundamental form. Then

$$\frac{1}{2}\Delta S = S(n-S) + |\nabla h|^2.$$
(1.8)

$$\frac{1}{2}\Delta(|\nabla h|^2) = (2n+3-S)|\nabla h|^2 + 3(2B-A) - \frac{3}{2}|\nabla S|^2 + |\nabla^2 h|^2,$$
(1.9)

where

$$S = |h|^2,$$

$$A = \sum_{\substack{i,j,k \ l,m}} h_{ijk} h_{ijl} h_{km} h_{ml},$$

$$B = \sum_{\substack{i,j,k \ l,m}} h_{ijk} h_{klm} h_{jl} h_{im}.$$

Near any given point $p \in M$, we can choose a local frame field $e_1, ..., e_n$ so that at p, we have

$$h_{ij} = \lambda_i \delta_{ij}$$
.

Let f_k denote the smooth function on M given by $tr(h^k)$, i.e., $f_k = \sum_i \lambda_i^k$. With such frame field, we have shown in [5] that

$$h_{ijij} = h_{jiji} + t_{ij}, (1.10)$$

where

$$t_{ij} = (\lambda_i - \lambda_j)(1 + \lambda_i \lambda_j);$$

$$|\nabla^2 h|^2 \ge \frac{3}{2S} \sum_k (S + f_3 \lambda_k - S \lambda_k^2)^2, \quad \text{at } p.$$
(1.11)

Hence we have

Proposition 2. With the same assumption as in Theorem 1, we have

$$|\nabla^2 h|^2 \ge \frac{3}{2} (Sf_4 - f_3^2 - S^2 - S(S - n)).$$
(1.12)

Next we obtain a pointwise estimate for A-2B,

$$\begin{aligned} 3(A-2B) &= \sum_{ijk} h_{ijk}^2 (\lambda_i^2 + \lambda_j^2 + \lambda_k^2 - 2\lambda_i \lambda_j - 2\lambda_j \lambda_k - 2\lambda_i \lambda_k) \\ &= \sum_{\substack{ijk \\ \text{distinct}}} h_{ijk}^2 (2(\lambda_i^2 + \lambda_j^2 + \lambda_k^2) - (\lambda_i + \lambda_j + \lambda_k)^2) \\ &+ 3 \sum_{\substack{i \neq k}} h_{iik}^2 (\lambda_k^2 - 4\lambda_i \lambda_k) + \sum_i h_{iii}^2 (-3\lambda_i^2) \\ &< 2S \sum_{\substack{ijk \\ \text{distinct}}} h_{ijk}^2 + \frac{(\sqrt{17}+1)}{2} S \cdot 3 \sum_{ik} h_{iik}^2, \end{aligned}$$

where $\lambda_k^2 - 4\lambda_i\lambda_k < \frac{\sqrt{17}+1}{2}S$ is obtained by standard Lagrange multiplier method with respect to the constraints $\sum \lambda_i = 0$ and $\sum \lambda_i^2 = S$. Hence we obtain

Proposition 3. With the same assumptions as in Theorem 1, we have

$$3(A-2B) \leq \frac{|\sqrt{17+1}}{2} S |\nabla h|^2.$$
(1.13)

Now we will derive some integral equations. Following Cheng and Yau [1], for a given symmetric two tensor $l = \sum_{ij} w_i w_j$ and a smooth function u on M, we consider the smooth function $\sum_{ij} l_{ij} u_{ij}$.

Then if M is a closed manifold, by Stokes' theorem we have

$$\int_{\mathbf{M}} \sum_{ij} l_{ij} u_{ij} = - \int_{\mathbf{M}} \sum_{ij} l_{ijj} u_i.$$
(1.14)

Moreover, if l satisfies the Codarzi equations, i.e., ∇l is a symmetric three tensor, and tr l is constant, then

$$\sum_{j} l_{ijj} = \sum_{j} l_{jji} = (\operatorname{tr} l)_i = 0$$

So in particular,

$$\int_{M} \sum_{ij} h_{ij}(f_3)_{ij} = 0.$$
 (1.15)

On the other hand, if we choose a local frame field $e_1, ..., e_n$ such that $h_{ij}(P) = \lambda_i \delta_{ij}$ at P, then

$$\frac{1}{3}\sum_{ij}h_{ij}(f_3)_{ij} = \frac{1}{3}\sum_k \lambda_k (f_3)_{kk}$$

$$= \sum_k \lambda_k \left(\sum_i h_{iikk} \lambda_i^2 + 2\sum_{ij} h_{ijk}^2 \lambda_i \right)$$

$$= \sum_{ik} h_{iikk} \lambda_k \lambda_i^2 + 2\sum_{ijk} h_{ijk}^2 \lambda_i \lambda_k$$

$$= \sum_{ik} (h_{kkii} + (\lambda_i - \lambda_k)(1 + \lambda_i \lambda_k)) \lambda_k \lambda_i^2 + 2B$$

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$$= \sum_{i} \left(\frac{S_{ii}}{2} - \sum_{jk} h_{ijk}^2 \right) \lambda_i^2 + \sum_{ik} \lambda_i^2 \lambda_k (\lambda_i - \lambda_k) (1 + \lambda_i \lambda_k) + 2B$$
$$= \sum_{ijk} \frac{h_{ik} h_{kj}}{2} S_{ij} + Sf_4 - f_3^2 - S^2 - (A - 2B).$$

Integrating both sides and using (1.15), we obtain

$$\begin{split} \int_{M} A - 2B &= \int_{M} Sf_4 - f_3^2 - S^2 + \sum_{ijk} \frac{h_{ik}h_{kj}}{2} S_{ij}, \\ &= \int_{M} Sf_4 - f_3^2 - S^2 - \sum_{ijk} (h_{ik}h_{kj})_j \frac{S_i}{2}, \\ &= \int_{M} Sf_4 - f_3^2 - S^2 - \sum_{ijk} h_{ikj}h_{kj} \frac{S_i}{2}, \\ &= \int_{M} Sf_4 - f_3^2 - S^2 - \frac{|\nabla S|^2}{4}. \end{split}$$

Hence we have:

Theorem 4. Let M be an immersed closed minimal hypersurface of S^{n+1} , h its second fundamental form, $S = |h|^2$ and $f_k = t_r(h^k)$. Then

$$\int_{M} A - 2B = \int_{M} Sf_4 - f_3^2 - S^2 - \frac{|\nabla S|^2}{4},$$
(1.16)

where A and B are as in Theorem 1.

We can now give a proof of Theorem A.

Proof. Integrating (1.8) and (1.9), we get

$$\int_{M} \frac{f'(S)}{2} |\nabla S|^2 = \int_{M} S(S-n)f(S) - f(S)|\nabla h|^2, \qquad (1.17)$$

$$\int_{M} |\nabla^2 h|^2 = \int_{M} (S - 2n - 3) |\nabla h|^2 + 3(A - 2B) + \frac{3}{2} |\nabla S|^2.$$
(1.18)

Using (1.12)

$$\begin{split} &\int_{M} (S-2n-3) |\nabla h|^2 + 3(A-2B) + \frac{3}{2} |\nabla S|^2 \geq \int_{M} \frac{3}{2} (Sf_4 - f_3^2 - S^2 - S(S-n)) \\ &= \int_{M} \frac{3}{2} (Sf_4 - f_3^2 - S^2) - \frac{3}{2} |\nabla h|^2 , \quad \text{using Theorem 4} \\ &= \int_{M} \frac{3}{2} (A-2B) + \frac{3}{8} |\nabla S|^2 - \frac{3}{2} |\nabla h|^2 . \end{split}$$

So

$$\int_{M} (S-2n-\frac{3}{2}) |\nabla h|^2 + \frac{3}{2} (A-2B) + \frac{9}{8} |\nabla S|^2 \ge 0.$$

Using Proposition 3 and (1.17) we have

$$0 \leq \int_{M} (S - 2n - \frac{3}{2}) |\nabla h|^{2} + \frac{\sqrt{17} + 1}{4} S |\nabla h|^{2} + \frac{9}{4} (S^{2}(S - n) - S |\nabla h|^{2}).$$

Now suppose $n \leq S(x) < n + \varepsilon$, then

$$\int_{M} S^{2}(S-n) \leq (n+\varepsilon) \int_{M} S(S-n) = (n+\varepsilon) \int_{M} |\nabla h|^{2}$$

So we have

$$0 \leq \int_{M} \left(\frac{\sqrt{17}-4}{4} S - \frac{6-n-9\varepsilon}{4} \right) |\nabla h|^2$$

Hence, if $n \leq 5$ and $\varepsilon = \frac{6 - 1.13n}{5 + \sqrt{17}}$, then

$$(\sqrt{17}-4)S-(6-n-9\varepsilon)<0.$$

Therefore, we have $|\nabla h| = 0$, i.e., $S \equiv n$. This proves Theorem A.

3. Proof of Theorem B

Since R = 6 - S, S is a constant function. We may assume $S \ge 6$ [5]. We denote f_3 by f. If f is also a constant function, then all three principal curvatures are constants and S = 6, so we are done. If f is not a constant function, we will derive a contradiction. The derivation is rather long, so we divide it into four steps. Let $f(p) = \max_{M} f$. We may assume $f(p) \ne 0$, otherwise we use min f. We choose a local frame e_1, e_2, e_3, e_4 such that at p

$$h_{ii}(p) = \lambda_i \delta_{ii},$$

with $\lambda_1 < \lambda_2 < \lambda_3$. Then

Step 1.

- (i) $h_{ijk}(p) = 0$ for all *i*, *j*, *k*, except $h_{123}^2(p) = \frac{S(S-3)}{6}$.
- (ii) $h_{iijk}(p) = h_{iiik}(p) = h_{kiii}(p) = 0$, if i, j, k are distinct.
- (iii) $3\sum_{i=1}^{\infty} h_{iiii}^2(p) 2\sum_{i=1}^{\infty} h_{iiii}^2(p) = 3S(S-3)^2.$

To see this, we note that

$$\sum_{i} \lambda_{i} = 0, \text{ since } M \text{ is minimal.}$$

$$\sum_{i} h_{iik}(p)\lambda_{i} = \frac{S_{k}(p)}{2} = 0, S \text{ being constant.}$$

$$\sum_{i} h_{iik}(p)\lambda_{i}^{2} = \frac{f_{k}(p)}{3} = 0, f(p) \text{ being max } f.$$

By assumption, λ_1 , λ_2 , λ_3 are distinct, hence $h_{iik}(p) = 0$ for all *i*, *k*. Using (1.8) and the assumption S is a constant, we have

$$y = \sum h_{ijk}^2(p) = S(S-3) = 6h_{123}^2 + 3\sum_{i \neq k} h_{iik}^2 + \sum_i h_{iii}^2$$

Hence $h_{123}^2(p) = \frac{S(S-3)}{6}$. To obtain (ii), we take the derivative of the constant function $y = |\nabla h|^2$. We have

$$\sum_{ijk} h_{ijk}(p) h_{ijkl}(p) = 0,$$

so $h_{iiik}(p) = 0$, if i, j, k are distinct. For $j \neq k$, we also have

$$\sum_{i} h_{iijk}(p) = 0,$$

$$\sum_{i} h_{iijk}(p)\lambda_{i} = \frac{S_{jk}(p)}{2} - \sum_{il} h_{ilj}(p)h_{ilk}(p) = 0.$$

Since λ_1 , λ_2 , λ_3 are distinct, we have $h_{jjjk}(p) = h_{kkjk}(p) = 0$. Using (1.9), we have

$$\sum h_{ijkl}^2 = S(S-3)(S-9) + 3(A-2B).$$

Substitute (i) into

$$3(A-2B)(p) = \sum h_{ijk}^2(p)(\lambda_i^2 + \lambda_j^2 + \lambda_k^2 - 2\lambda_i\lambda_j - 2\lambda_i\lambda_k - 2\lambda_j\lambda_k)$$

= $6h_{123}^2(p)(\lambda_1^2 + \lambda_2^2 + \lambda_3^2 - 2\lambda_1\lambda_2 - 2\lambda_1\lambda_3 - 2\lambda_2\lambda_3)$
= $2S^2(S-3)$.

This proves (iii).

Step 2.
$$f(p) > 0$$
, $\frac{S}{6} < \lambda_1^2 < \frac{S}{2}$, $0 < \lambda_2^2 < \frac{S}{6}$, and $\lambda_1 < \lambda_2 < 0$.
Since $f(p)$ is max f , we have

$$\frac{1}{3}\Delta f(p) = (3-S)f(p) + 6\sum_{ijk} h_{ijk}^2(p)\lambda_i, \text{ using (i) of Step 1}.$$

= (3-S)f(p) \le 0.

Hence f(p) > 0.

Using Lagrange multiplier to maximizing $\sum_{i=1}^{3} x_i^3$ with respect to the constraints $\sum_{i=1}^{3} x_i = 0$ and $\sum_{i=1}^{3} x_i^2 = S$, we see that $f^2 \leq \frac{S^3}{6}$ and equality holds if and only if two of the x_i 's are equal to $\sqrt{\frac{S}{6}}$ or $-\sqrt{\frac{S}{6}}$. Hence by our assumption, $f^2 < \frac{S^3}{6}$ on M, and $\frac{S}{6} < \lambda_1^2 < \frac{S}{2}$, $0 < \lambda_2^2 < \frac{S}{6}$, $\lambda_1 < \lambda_2 < 0$.

Step 3. $h_{iill}(p) = -\frac{1}{3}(S-3)\lambda_i + g_i\lambda_l + Zg_ig_l$, where

$$g_i = \lambda_i^2 - \frac{f}{S}\lambda_i - \frac{S}{3}.$$

To obtain this, we solve the following rank 5 linear system of six equations and six unknowns h_{iiii} , $i \leq l$:

$$\sum_{i} h_{iill}(p) = 0,$$

$$\sum_{i} h_{iill}(p)\lambda_{i} = -\sum_{ij} h_{ijl}^{2}(p) + \frac{S_{ll}(p)}{2} = -\frac{S(S-3)}{3},$$
(2.1)

where

$$h_{iijj} = h_{jjii} + (1 + \lambda_i \lambda_j)(\lambda_i - \lambda_j).$$

Step 4. A Contradition

The real value Z in Step 3 is determined by substituting Step 3 into (iii) of Step 1, in fact,

$$x = Z\left(\frac{S^2}{6} - \frac{f^2(p)}{S}\right) = \left(\frac{1}{3} - \frac{1}{S}\right)f(p)$$

$$\pm \left[\frac{f^2(p)}{S^2}\left(\frac{19}{9}S^2 - \frac{8}{3}S + 1\right) + \frac{7}{9}S(S-6)\left(S - \frac{15}{7}\right)\right]^{1/2}.$$
 (2.2)

Note that $S(S-6)(S-\frac{15}{7}) \ge 0$ for $S \ge 6$ and

$$\frac{19}{9}S^2 - \frac{8}{3}S + 1 \ge (\frac{4}{3}S - 1)^2.$$

Hence we have

$$x > \left(\frac{5}{3} - \frac{2}{S}\right) f(p), \quad \text{if} \quad x \ge 0;$$
(2.3)

or

$$x < -f(p), \quad \text{if} \quad x < 0.$$
 (2.4)

On the other hand, f(p) is max f, so for each l, we have

$$\frac{1}{3}f_{il}(p) = \sum_{i} h_{iill}(p)\lambda_i^2 + 2\sum_{ij} h_{ijl}^2(p)\lambda_i \le 0.$$
(2.5)

Using the computation in Steps 1-3 and the fact that

$$f = f_3 = 3\lambda_l \left(\lambda_l^2 - \frac{S}{2}\right),$$

we have

$$-\frac{3}{S}x\left(\lambda_{l}^{2}-\frac{S}{6}\right)\left(\lambda_{l}^{2}-\frac{2S}{3}\right) \leq \lambda_{l}\left(\lambda_{l}^{2}-\frac{S}{6}\right)\left(\frac{9}{S}\lambda_{l}^{4}-\frac{15}{2}\lambda_{l}^{2}+2S-3\right)$$
(2.6)

for all l=1, 2, 3. However, if x>0, a direct computation shows that (2.6) with l=1 and (2.3) can not hold simultaneously. Similarly if x<0, then (2.6) with l=2 and (2.4) can not be true simultaneously. This contradiction proves our theorem.

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