The Scalar Curvature of Minimal Hypersurfaces in Spheres

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Introduction

Let M be a closed minimally immersed hypersurface of S^{n+1} , and h its second fundamental form. We denote the square of the length of h by S . It follows from the Gauss and Codazzi equations that the apparently extrinsic quantity S is in fact intrinsic and is given by

$$
S=n(n-1)-R,
$$

where R is the scalar curvature of M. If $0 \le S(x) \le n$ for all $x \in M$, then either $S = 0$ or $S \equiv n$ [6]. In the case that $S \equiv n$, Chern, do Carmo, Kobayashi; and Lawson independently proved that M is a Clifford torus $[2, 4]$. In a previous paper $[5]$ we showed that there exists a positive real number $C(n) > 0$ $C(3) = 3$ and $C(n) \ge \frac{1}{12n}$ in general such that if $S(x)$ is a constant bigger than *n* then it must be bigger than or

equal to $n+C(n)$. We also learned that Naoya Doi has worked on the same problem [3]. His main results are for minimal hypersurface M of S^{n+1} with constant scalar curvature and whose sectional curvature is bounded above by 1, he proved that either $S=0$ or $S\geq 2(2n-3)$. However, under his assumptions it is easily seen that either $S=0$; or $n=3$, $S=6$ and M is the classical isoparametric example. To see this, let $e_1, ..., e_n$ be a local orthonormal frame field of principal curvature directions of M, then the sectional curvature in the direction e_i , e_j , for $i=j$, is $1 + \lambda_i \lambda_j$, where λ_i 's are the principal curvatures. The conditions

$$
\sum_{i}^{n} \lambda_{i} = 0,
$$

$$
\sum_{i} \lambda_{i}^{2} = S, \text{ constant},
$$

$$
1 + \lambda_{i} \lambda_{j} \leq 1, \text{ for } i \neq j,
$$

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imply that there are at most one positive λ_i and one negative λ_i and the principal curvatures of M are constants. Hence either $\lambda_i = 0$ for all i, which gives $S = 0$; or by Theorem 1 of [5], $n=3$, $S=6$ and M is the classical isoparametric example.

In this paper, we prove a pinching theorem for minimal hypersurfaces in S^{n+1} for $n \leq 5$:

Theorem A. Let M be a closed minimally immersed hypersuface in S^{n+1} , $n \leq 5$, and *S the square of the length of the second fundamental form of M. Then there exists* $\delta(n)$ > 0 such that if $n \leq S(x) \leq n + \delta(n)$ then $S(x) \equiv n$, hence M is a Clifford torus.

The proof uses the equations for Δh , $\Delta(\overline{V}h)$, and some integral equations naturally associated to the second fundamental form h . Since we do not assume that S is a constant function, the estimate we have in [5] can not be applied here, and the technique of using integral equations seems essential.

In the end of this paper, we give a proof of the theorem we stated in $[5]$, namely:

Theorem B. Let M^3 be a closed minimal hypersurface with constant scalar curvature *R* in $S⁴$. If all three principal curvatures of M are distinct at every point, then $R = 0$.

1. Formulas Involving the Second Fundamental Form of Minimal Hypersurfaces

In this section, we will review the notation used in our previous paper [5], derive several new formulas and give a proof of Theorem A. Let M be a minimal hypersurface of S^{n+1} , and $e_1, ..., e_n$ a local orthonormal frame field on M, $w_1, ..., w_n$ its dual coframe. Then we have

$$
I = \sum_{i} w_i^2, \tag{1.1}
$$

$$
II = h = \sum_{i,j} h_{ij} w_i w_j, \qquad h_{ij} = h_{ji}, \tag{1.2}
$$

$$
\nabla h = \sum_{i,j,k} h_{ijk} w_i w_j w_k, \qquad h_{ijk} = h_{ikj}, \tag{1.3}
$$

$$
V^{2}h = \sum_{i,j,k,l} h_{ijkl} w_{i} w_{j} w_{k} w_{l}, \qquad (1.4)
$$

where

$$
h_{ijkl} = h_{ijlk} + \sum_{m} h_{mj} R_{mikl} + \sum_{m} h_{im} R_{mjkl}.
$$

$$
V^3 h = \sum_{\substack{i,j,k,l \ j,k \neq m}} h_{ijklm} w_i w_j w_k w_l w_m,
$$
 (1.5)

where

$$
h_{ijklm} = h_{ijkml} + \sum_{r} h_{rjk} R_{rilm} + \sum_{r} h_{irk} R_{rjlm} + \sum_{r} h_{ijr} R_{rklm},
$$

\n
$$
\Delta h_{ij} = (n - S) h_{ij},
$$
\n(1.6)

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where

$$
S=|h|^2.
$$

Since we do not assume S is a constant function, the same computation as in $[5]$ will lead to a slightly different formula for $\Delta(Vh)$:

$$
\Delta h_{ijk} = (2n + 3 - S)h_{ijk} + 2 \sum_{m,i} (h_{iml}h_{mk}h_{jl} + h_{jml}h_{mi}h_{lk} + h_{kml}h_{mi}h_{lj})
$$

-
$$
\sum_{m,i} (h_{ijm}h_{ml}h_{lk} + h_{ikm}h_{ml}h_{lj} + h_{jkm}h_{ml}h_{li})
$$

-
$$
(S_ih_{jk} + S_jh_{ik} + S_kh_{ij}).
$$
 (1.7)

Then it follows easily from (1.6) , (1.7) that we have:

Theorem 1. Let M be an immersed minimal hypersurface of S^{n+1} , h its second *fundamental form. Then*

$$
\frac{1}{2}\Delta S = S(n - S) + |\nabla h|^2. \tag{1.8}
$$

$$
\frac{1}{2}\Delta(|Vh|^2) = (2n+3-S)|Vh|^2 + 3(2B-A) - \frac{3}{2}|VS|^2 + |V^2h|^2, \tag{1.9}
$$

where

$$
S = |h|^2,
$$

\n
$$
A = \sum_{\substack{i,j,k \\ j,m}} h_{ijk} h_{ijl} h_{km} h_{ml},
$$

\n
$$
B = \sum_{\substack{i,j,k \\ i,m \\ j,m}} h_{ijk} h_{klm} h_{jl} h_{im}.
$$

Near any given point $p \in M$, we can choose a local frame field $e_1, ..., e_n$ so that at p, we have

$$
h_{ij} = \lambda_i \delta_{ij}.
$$

Let f_k denote the smooth function on M given by tr(h^k), i.e., $f_k = \sum_i \lambda_i^k$. With such frame field, we have shown in $[5]$ that

$$
h_{ijij} = h_{jiji} + t_{ij},
$$
\n(1.10)

where

$$
t_{ij} = (\lambda_i - \lambda_j)(1 + \lambda_i \lambda_j);
$$

$$
|\nabla^2 h|^2 \ge \frac{3}{2S} \sum_k (S + f_3 \lambda_k - S \lambda_k^2)^2, \text{ at } p.
$$
 (1.11)

Hence we have

Proposition 2. *With the same assumption as in Theorem 1, we have*

$$
|V^2h|^2 \ge \frac{3}{2}(Sf_4 - f_3^2 - S^2 - S(S - n)).
$$
\n(1.12)

Next we obtain a pointwise estimate for $A-2B$,

$$
3(A-2B) = \sum_{i,jk} h_{ijk}^2(\lambda_i^2 + \lambda_j^2 + \lambda_k^2 - 2\lambda_i\lambda_j - 2\lambda_j\lambda_k - 2\lambda_i\lambda_k)
$$

\n
$$
= \sum_{\substack{i,jk \text{ distinct} \\ \text{distinct}}} h_{ijk}^2(2(\lambda_i^2 + \lambda_j^2 + \lambda_k^2) - (\lambda_i + \lambda_j + \lambda_k)^2)
$$

\n
$$
+ 3 \sum_{i \neq k} h_{iik}^2(\lambda_k^2 - 4\lambda_i\lambda_k) + \sum_i h_{iii}^2(-3\lambda_i^2)
$$

\n
$$
< 2S \sum_{\substack{i,jk \text{ distinct} \\ \text{distinct}}} h_{ijk}^2 + \frac{(\sqrt{17}+1)}{2} S \cdot 3 \sum_{ik} h_{iik}^2,
$$

where $\lambda_k^2 - 4\lambda_i \lambda_k < \frac{k-1}{2}$ is obtained by standard Lagrange multiplier method with respect to the constraints $\sum \lambda_i = 0$ and $\sum \lambda_i^2 = S$. Hence we obtain

Proposition 3. *With the same assumptions as in Theorem 1, we have*

$$
3(A - 2B) \le \frac{\sqrt{17 + 1}}{2} S |\nabla h|^2. \tag{1.13}
$$

Now we will derive some integral equations. Following Cheng and Yau [1], for a given symmetric two tensor $I=\sum w_iw_j$ and a smooth function u on M, we ij. consider the smooth function $\sum l_{ij}u_{ij}$. *ij*

Then if M is a closed manifold, by Stokes' theorem we have

$$
\int_{M} \sum_{ij} l_{ij} u_{ij} = - \int_{M} \sum_{ij} l_{ijj} u_{i}.
$$
 (1.14)

Moreover, if I satisfies the Codarzi equations, i.e., *V1* is a symmetric three tensor, and trl is constant, then

$$
\sum_j l_{ijj} = \sum_j l_{jji} = (\text{tr } l)_i = 0.
$$

So in particular,

$$
\int_{M} \sum_{ij} h_{ij} (f_3)_{ij} = 0.
$$
\n(1.15)

On the other hand, if we choose a local frame field $e_1, ..., e_n$ such that $h_{ij}(P) = \lambda_i \delta_{ij}$ at P, then

$$
\frac{1}{3} \sum_{ij} h_{ij} (f_3)_{ij} = \frac{1}{3} \sum_k \lambda_k (f_3)_{kk}
$$
\n
$$
= \sum_k \lambda_k \left(\sum_i h_{iikk} \lambda_i^2 + 2 \sum_{ij} h_{ijk}^2 \lambda_i \right)
$$
\n
$$
= \sum_{ik} h_{iikk} \lambda_k \lambda_i^2 + 2 \sum_{ijk} h_{ijk}^2 \lambda_i \lambda_k
$$
\n
$$
= \sum_{ik} (h_{kkii} + (\lambda_i - \lambda_k)(1 + \lambda_i \lambda_k)) \lambda_k \lambda_i^2 + 2B
$$

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$$
= \sum_{i} \left(\frac{S_{ii}}{2} - \sum_{jk} h_{ijk}^2 \right) \lambda_i^2 + \sum_{ik} \lambda_i^2 \lambda_k (\lambda_i - \lambda_k)(1 + \lambda_i \lambda_k) + 2B
$$

$$
= \sum_{ijk} \frac{h_{ik} h_{kj}}{2} S_{ij} + Sf_4 - f_3^2 - S^2 - (A - 2B).
$$

Integrating both sides and using (1.15), we obtain

$$
\int_{M} A - 2B = \int_{M} Sf_4 - f_3^2 - S^2 + \sum_{ijk} \frac{h_{ik}h_{kj}}{2} S_{ij},
$$

\n
$$
= \int_{M} Sf_4 - f_3^2 - S^2 - \sum_{ijk} (h_{ik}h_{kj})_j \frac{S_i}{2},
$$

\n
$$
= \int_{M} Sf_4 - f_3^2 - S^2 - \sum_{ijk} h_{ikj}h_{kj} \frac{S_i}{2},
$$

\n
$$
= \int_{M} Sf_4 - f_3^2 - S^2 - \frac{|VS|^2}{4}.
$$

Hence we have:

Theorem 4. Let M be an immersed closed minimal hypersurface of S^{n+1} , h its second *fundamental form,* $S = |h|^2$ *and* $f_k = t_r(h^k)$. Then

$$
\int_{M} A - 2B = \int_{M} Sf_4 - f_3^2 - S^2 - \frac{|FS|^2}{4},
$$
\n(1.16)

where A and B are as in Theorem 1.

We can now give a proof of Theorem A.

Proof. Integrating (1.8) and (1.9), we get

$$
\int_{M} \frac{f'(S)}{2} |FS|^{2} = \int_{M} S(S-n)f(S) - f(S)|Fh|^{2},
$$
\n(1.17)

$$
\int_{M} |V^{2}h|^{2} = \int_{M} (S - 2n - 3)|Vh|^{2} + 3(A - 2B) + \frac{3}{2}|VS|^{2}.
$$
 (1.18)

Using (1.12)

$$
\begin{aligned}\n\int_{M} (S - 2n - 3)|Fh|^{2} + 3(A - 2B) + \frac{3}{2}|FS|^{2} &\geq \int_{M} \frac{3}{2}(Sf_{4} - f_{3}^{2} - S^{2} - S(S - n)) \\
&= \int_{M} \frac{3}{2}(Sf_{4} - f_{3}^{2} - S^{2}) - \frac{3}{2}|Fh|^{2}, \quad \text{using Theorem 4} \\
&= \int_{M} \frac{3}{2}(A - 2B) + \frac{3}{8}|FS|^{2} - \frac{3}{2}|Fh|^{2}.\n\end{aligned}
$$

SO

$$
\int_{M} (S-2n-\frac{3}{2})|Fh|^{2}+\frac{3}{2}(A-2B)+\frac{9}{8}|FS|^{2} \geq 0.
$$

Using Proposition 3 and (1.17) we have

$$
0 \leqq \int\limits_M (S-2n-\tfrac{3}{2})|\nabla h|^2 + \frac{\sqrt{17}+1}{4} S|\nabla h|^2 + \tfrac{9}{4}(S^2(S-n)-S|\nabla h|^2).
$$

Now suppose $n \leq S(x) < n + \varepsilon$, then

$$
\int_{M} S^{2}(S-n) \leq (n+\varepsilon) \int_{M} S(S-n) = (n+\varepsilon) \int_{M} |Vh|^{2}
$$

So we have

$$
0 \leq \int\limits_M \left(\frac{\sqrt{17}-4}{4} S - \frac{6-n-9\varepsilon}{4} \right) |Fh|^2.
$$

Hence, if $n \leq 5$ and $\varepsilon = \frac{6-1.13n}{\sqrt{15}}$, then $-$ 5+ $\frac{1}{7}$

$$
(\sqrt{17}-4)S-(6-n-9\varepsilon)<0.
$$

Therefore, we have $|Vh| = 0$, i.e., $S \equiv n$. This proves Theorem A.

3. Proof of Theorem B

Since $R = 6-S$, S is a constant function. We may assume $S \ge 6$ [5]. We denote f_3 by f . If f is also a constant function, then all three principal curvatures are constants and $S = 6$, so we are done. If f is not a constant function, we will derive a contradiction. The derivation is rather long, so we divide it into four steps. Let *f(p)* $=$ max *f*. We may assume $f(p)$ +0, otherwise we use min *f*. We choose a local frame M e_1, e_2, e_3, e_4 such that at p

$$
h_{ij}(p) = \lambda_i \delta_{ij},
$$

with $\lambda_1 < \lambda_2 < \lambda_3$. Then

Step 1.

- (i) $h_{ijk}(p) = 0$ for all i, j, k, except $h_{123}^2(p) = \frac{S(S-3)}{6}$.
- (ii) $h_{iijk}(p) = h_{iijk}(p) = h_{kiii}(p) = 0$, if *i, j, k* are distinct.
- (iii) 3 $\sum h_{\text{cm}}^2(p) 2 \sum h_{\text{cm}}^2(p) = 3S(S-3)^2$. *i,l i*

To see this, we note that

$$
\sum_{i} \lambda_{i} = 0, \text{ since } M \text{ is minimal.}
$$

$$
\sum_{i} h_{iik}(p)\lambda_{i} = \frac{S_{k}(p)}{2} = 0, S \text{ being constant.}
$$

$$
\sum_{i} h_{iik}(p)\lambda_{i}^{2} = \frac{f_{k}(p)}{3} = 0, f(p) \text{ being max } f.
$$

By assumption, λ_1 , λ_2 , λ_3 are distinct, hence $h_{ijk}(p) = 0$ for all i, k. Using (1.8) and the assumption S is a constant, we have

$$
y = \sum h_{ijk}^2(p) = S(S-3) = 6h_{123}^2 + 3 \sum_{i \neq k} h_{iik}^2 + \sum_i h_{iii}^2.
$$

Hence $h'_{123}(p) = \frac{1}{6}$. To obtain (ii), we take the derivative of the constant function $y = |Vh|^2$. We have

$$
\sum_{ijk} h_{ijk}(p)h_{ijkl}(p) = 0 \,,
$$

so $h_{iijk}(p)=0$, if i, j, k are distinct. For $j+k$, we also have

$$
\sum_i h_{iijk}(p) = 0 \,,
$$

$$
\sum_i h_{iijk}(p)\lambda_i = \frac{S_{jk}(p)}{2} - \sum_{ii} h_{iij}(p)h_{iik}(p) = 0.
$$

Since λ_1 , λ_2 , λ_3 are distinct, we have $h_{jijk}(p) = h_{kkjk}(p) = 0$. Using (1.9), we have

$$
\sum h_{ijkl}^2 = S(S-3)(S-9) + 3(A-2B).
$$

Substitute (i) into

$$
3(A - 2B)(p) = \sum h_{ijk}^2(p)(\lambda_i^2 + \lambda_j^2 + \lambda_k^2 - 2\lambda_i\lambda_j - 2\lambda_i\lambda_k - 2\lambda_j\lambda_k)
$$

= $6h_{123}^2(p)(\lambda_1^2 + \lambda_2^2 + \lambda_3^2 - 2\lambda_1\lambda_2 - 2\lambda_1\lambda_3 - 2\lambda_2\lambda_3)$
= $2S^2(S - 3)$.

This proves (iii).

Step 2.
$$
f(p) > 0
$$
, $\frac{S}{6} < \lambda_1^2 < \frac{S}{2}$, $0 < \lambda_2^2 < \frac{S}{6}$, and $\lambda_1 < \lambda_2 < 0$.
Since $f(p)$ is max f, we have

$$
\frac{1}{3} \Delta f(p) = (3 - S) f(p) + 6 \sum_{ijk} h_{ijk}^2(p) \lambda_i, \text{ using (i) of Step 1.}
$$

$$
= (3 - S) f(p) \le 0.
$$

Hence $f(p) > 0$.

3 Using Lagrange multiplier to maximizing $\sum x_i^3$ with respect to the constraints 3 3 $i=1$ $\sum_{i=1}^{\infty} x_i = 0$ and $\sum_{i=1}^{\infty} x_i^2 = S$, we see that $f^2 \leq \frac{1}{6}$ and equality holds if and only if two of the x_i's are equal to $\left|\frac{\sqrt{S}}{6}$ or $-\left|\frac{\sqrt{S}}{6}\right|$. Hence by our assumption, $f^2 < \frac{S^3}{6}$ on *M*, and $\frac{S}{6} < \lambda_1^2 < \frac{S}{2}$, $0 < \lambda_2^2 < \frac{S}{6}$, $\lambda_1 < \lambda_2 < 0$.

Step 3. $h_{i\mu}(p) = -\frac{1}{3}(S-3)\lambda_i + g_i\lambda_i + Zg_i g_i$, where

$$
g_i = \lambda_i^2 - \frac{f}{S}\lambda_i - \frac{S}{3}.
$$

To obtain this, we solve the following rank 5 linear system of six equations and six unknowns h_{iill} , $i \leq l$:

$$
\sum_{i} h_{ii1}(p) = 0,
$$
\n
$$
\sum_{i} h_{ii1}(p)\lambda_{i} = -\sum_{ij} h_{ij1}^{2}(p) + \frac{S_{11}(p)}{2} = -\frac{S(S-3)}{3},
$$
\n(2.1)

where

$$
h_{iij}=h_{jji}+(1+\lambda_i\lambda_j)(\lambda_i-\lambda_j).
$$

Step 4. A Contradition

The real value Z in Step 3 is determined by substituting Step 3 into (iii) of Step 1, in fact,

$$
x = Z\left(\frac{S^2}{6} - \frac{f^2(p)}{S}\right) = \left(\frac{1}{3} - \frac{1}{S}\right)f(p)
$$

$$
\pm \left[\frac{f^2(p)}{S^2}\left(\frac{19}{9}S^2 - \frac{8}{3}S + 1\right) + \frac{7}{9}S(S - 6)\left(S - \frac{15}{7}\right)\right]^{1/2}.
$$
 (2.2)

Note that $S(S-6)(S-\frac{15}{7}) \ge 0$ for $S \ge 6$ and

$$
\frac{19}{9}S^2 - \frac{8}{3}S + 1 \geq (\frac{4}{3}S - 1)^2.
$$

Hence we have

$$
x > \left(\frac{5}{3} - \frac{2}{5}\right) f(p), \quad \text{if} \quad x \ge 0 \tag{2.3}
$$

or

$$
x < -f(p), \quad \text{if} \quad x < 0. \tag{2.4}
$$

On the other hand, $f(p)$ is max f, so for each l, we have

$$
\frac{1}{3}f_{il}(p) = \sum_{i} h_{iil}(p)\lambda_i^2 + 2\sum_{ij} h_{ij}^2(p)\lambda_i \le 0.
$$
 (2.5)

Using the computation in Steps 1-3 and the fact that

$$
f = f_3 = 3\lambda_l \left(\lambda_l^2 - \frac{S}{2}\right),
$$

we have

$$
-\frac{3}{S}x\left(\lambda_{i}^{2}-\frac{S}{6}\right)\left(\lambda_{i}^{2}-\frac{2S}{3}\right)\leq\lambda_{i}\left(\lambda_{i}^{2}-\frac{S}{6}\right)\left(\frac{9}{S}\lambda_{i}^{4}-\frac{15}{2}\lambda_{i}^{2}+2S-3\right)
$$
(2.6)

for all $l = 1, 2, 3$. However, if $x > 0$, a direct computation shows that (2.6) with $l = 1$ and (2.3) can not hold simultaneously. Similarly if $x < 0$, then (2.6) with $l = 2$ and (2.4) can not be true simultaneously. This contradiction proves our theorem.

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