

Reduction of Hamiltonian Systems, Affine Lie Algebras and Lax Equations II

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The present article is the sequel to a previous paper by the same authors [1]. Its aim is to give an explicit solution of a factorization problem for groups of loops, and to establish a connection of Hamiltonian reduction methods with algebraic methods of Novikov and Krichever [2, 3] and of Mumford and van Moerbeke [4]. We also correct some erroneous statements in [1] concerning the factorization problem (see no. 2 below). To make our presentation more self-consistent, we give an elementary proof of the reduction theorem in a slightly more general form as compared to [1]. This generality corresponds to that of [3, 4] where the same equations are treated in terms of finite-difference operators. An approach based on affine Lie algebras is also described by Adler and van Moerbeke [5]. However, the Hamiltonian reduction questions are not treated there.

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1. Let G be a Lie group, \mathfrak{g} its Lie algebra, \mathfrak{g}^* the dual of \mathfrak{g} . Clearly, $\mathfrak{g} \subset C^\infty(\mathfrak{g}^*)$, and the Lie bracket on \mathfrak{g} gives rise to a Poisson bracket on $C^\infty(\mathfrak{g}^*)$ sometimes called the Kirillov bracket for \mathfrak{g} . The center of $C^\infty(\mathfrak{g}^*)$ coincides with the algebra $I(\mathfrak{g}^*)$ of Ad^*G -invariant functions. Restriction of the Kirillov bracket to Ad^*G -orbits in \mathfrak{g}^* induces on them the canonical symplectic structure.

Suppose that \mathfrak{g} splits as a vector space into a linear sum of two its subalgebras, $\mathfrak{g} = \mathfrak{a} + \mathfrak{b}$. Let A, B be the corresponding connected subgroups. Put $\mathfrak{g}_0 = \mathfrak{a} \oplus \mathfrak{b}$, $G_0 = A \times B$. We identify linear spaces \mathfrak{g}_0 and \mathfrak{g} by means of the mapping $\sigma_0: \mathfrak{g}_0 \rightarrow \mathfrak{g}$, $\sigma_0(x, y) = x - y$.

Hence there are two Kirillov brackets on $\mathfrak{g}^* \simeq \mathfrak{g}_0^*$.

Reduction Theorem. (i) $I(\mathfrak{g}^*)$ is abelian with respect to both brackets on \mathfrak{g}^* .

(ii) Let $\varphi \in I(\mathfrak{g}^*)$, $\zeta \in \mathfrak{g}^*$. Put $M = d\varphi(\zeta)$, $(M_+, M_-) = \sigma_0^{-1}(M) \in \mathfrak{g}_0$. The Hamiltonian equations of motion defined by φ with respect to the second Poisson bracket on \mathfrak{g}^* have the form

$$\dot{\zeta} = -\text{ad}_{\mathfrak{g}}^* M_+ \zeta = -\text{ad}_{\mathfrak{g}}^* M_- \zeta \quad (1)$$

(iii) Let $\exp tM = a(t)b(t)$, $a(\cdot)$, $b(\cdot)$ being smooth curves in A and B , respectively, $a(0) = b(0) = e$. The solution to equations (1) starting at ξ has the form

$$\xi(t) = \text{Ad}_G^* a(t)^{-1} \cdot \xi = \text{Ad}_G^* b(t) \cdot \xi$$

Proof. Define a mapping $\sigma: G_0 \rightarrow G$ by $\sigma(a \times b) = a b^{-1}$. We trivialize the tangent bundles of groups by means of left translations. Then the differential of σ at $a \times b \in G_0$ is equal to $\text{Ad}_G b \circ \sigma_0$. Indeed, it is clear from the definition that $d\sigma(a \times b) = \text{Ad}_G b \circ d\sigma(e)$. Evidently, $d\sigma(e) = \sigma_0$. It follows that σ is an immersion. Hence we may define a mapping $\sigma^*: T^*G_0 \rightarrow T^*G$ putting $\sigma^* = d\sigma(a \times b)^{* - 1}$ on the fiber $T_{a \times b}^*$. Given a function φ on T^*G put $\varphi^\sigma = \varphi \circ \sigma$. The mapping σ^* is a symplectic immersion and $\{\varphi^\sigma, \psi^\sigma\} = \{\varphi, \psi\}^\sigma$.

Now the Kirillov bracket on \mathfrak{g}^* coincides with the canonical Poisson bracket for left-invariant functions on T^*G . Observing that for $\varphi \in I(\mathfrak{g}^*)$ φ^σ is left G_0 -invariant we get (i).

Equations of motion on T^*G corresponding to a Hamiltonian $\varphi \in I(\mathfrak{g}^*)$ are $\dot{\xi} = 0$, $\dot{g} = d\varphi(\xi)$. Hence the trajectories are given by

$$(g(t), \xi(t)) = (g(0) \exp t d\varphi(\xi), \xi(0))$$

Trajectories of the Hamiltonian φ^σ on $T^*G_0 \simeq G_0 \times \mathfrak{g}_0^*$ are obtained from these by the change of variables σ^* . We are only interested in their projections to \mathfrak{g}_0^* . If $\exp t d\varphi(\xi) = a(t)b(t)$, then $d\sigma^*(\exp t d\varphi(\xi)) = \sigma_0^* \circ \text{Ad}_G^* b(t)$, whence we get (iii). Differentiating the trajectory with respect to t we get (ii). ■

If there is an invariant scalar product on \mathfrak{g} we may identify \mathfrak{g}^* with \mathfrak{g} . Then $\text{ad}_\mathfrak{g}^* = \text{ad}_\mathfrak{g}$ and the equations of motion have the Lax form.

The “reduced flows” of the Hamiltonians φ^σ may be restricted to Ad^*G_0 -invariant submanifolds in \mathfrak{g}^* . In particular, we get as a corollary Theorem 10 and Proposition 12 of [1].

Corollary. Let f be a character of \mathfrak{a} .

(i) Functions on \mathfrak{b}^* of the form $\varphi_f(\xi) = \varphi(\xi + f)$, $\varphi \in I(\mathfrak{g}^*)$ commute with respect to the Kirillov bracket on \mathfrak{b}^* .

(ii) Equations of motion corresponding to the Hamiltonian φ_f have the form

$$\dot{\xi} = -\text{ad}_\mathfrak{g}^* M_\pm \cdot (\xi + f), \quad M = d\varphi(\xi + f) \tag{2}$$

(iii) Let $\exp tM = a(t)b(t)$, $a(\cdot)$, $b(\cdot)$ being smooth curves in A and B , respectively. Solution to equations (2) starting at ξ is

$$\xi(t) = \text{Ad}_G^* b(t)(\xi + f) - f$$

or, equivalently,

$$\xi(t) = \text{Ad}_B^* b(t) \cdot \xi.$$

2. In the rest of the paper we shall be concerned with the following example of the above construction. Let \mathfrak{g} be a complex semisimple Lie algebra. Put $\tilde{\mathfrak{g}} = \mathfrak{g} \otimes \mathbb{C}[z, z^{-1}]$, $\mathfrak{a} = \mathfrak{g} \otimes z\mathbb{C}[z]$, $\mathfrak{b} = \mathfrak{g} \otimes \mathbb{C}[z^{-1}]$. We equip $\tilde{\mathfrak{g}}$ with a nondegenerate invariant bilinear form $(X, Y) = \text{Res}_{z=0} z^{-1} B(X, Y)$ and identify \mathfrak{a}^* with

$\mathfrak{g} \otimes z^{-1} \mathbf{C}[z^{-1}]$ and \mathfrak{b}^* with $\mathfrak{g} \otimes \mathbf{C}[z]$. Invariant functionals on $\tilde{\mathfrak{g}}^*$ are given by

$$\varphi_n(X) = \text{Res}_{z=0} z^{-n} \varphi(X(z)), \quad \varphi \in I(\tilde{\mathfrak{g}}^*), \quad n \in \mathbf{Z}.$$

The reduction theorem as applied to $\tilde{\mathfrak{g}} = \mathfrak{a} + \mathfrak{b}$ amounts to the following statement.

Let $L \in \tilde{\mathfrak{g}}^*$, $\varphi \in I(\tilde{\mathfrak{g}}^*)$, put $M = d\varphi(L)$, and let $\text{expt } M = g_+(t)^{-1} g_-(t)$, the factors g_+, g_- being analytic inside (outside) the unit circle. The trajectory of the Hamiltonian φ passing through L is given by

$$L(t) = \text{Ad } g_{\pm}(t) L. \tag{3}$$

In the present context the relevant groups are $\tilde{G} = C^\infty(S^1, G)$ and two of its subgroups G_{\pm} consisting of functions analytic inside (respectively, outside) the unit circle. For a careful formulation of the reduction theorem we must equip \tilde{G} with a topology of a Banach Lie group such that $\sigma: G_+ \times G_- \rightarrow \tilde{G}$, $\sigma(g_+ \times g_-) = g_+ g_-^{-1}$ maps some neighborhood of the unit element in $G_+ \times G_-$ onto an open set in \tilde{G} . A particular choice of topology is to a large extent arbitrary. One of the simplest possibilities is described below.

Let $G \subset GL(n, \mathbf{C})$ be a connected matrix group, $\mathfrak{g} \subset \mathfrak{gl}(n, \mathbf{C})$ be its Lie algebra. Denote by \mathcal{W} the algebra of absolutely convergent Fourier series with coefficients in $\mathfrak{gl}(n, \mathbf{C})$. Put

$$\begin{aligned} \mathfrak{g}_{\mathcal{W}} &= \{u \in \mathcal{W} : u(z) \in \mathfrak{g} \text{ for } |z|=1\} \\ G_{\mathcal{W}} &= \{g \in \mathcal{W} : g(z) \in G \text{ for } |z|=1\} \end{aligned}$$

Denote by $\mathcal{W}_+(\mathcal{W}_-)$ subalgebras in \mathcal{W} consisting of functions analytic inside (outside) the unit circle. Put

$$G_{\pm} = \{g \in G_{\mathcal{W}} \cap \mathcal{W}_{\pm} : g(z) \in G \text{ for } |z^{\pm 1}| \leq 1\}$$

Put $A = \{g \in G_+ : g(0) = 1\}$, $B = G_-$, $\tilde{G}_0 = A \times B$. The set ${}^0G_{\mathcal{W}} = AB$ is open in $G_{\mathcal{W}}$ and contains a neighborhood of the unit element. The scheme of no. 1 can be directly applied to the present case.

Remark. We point out an error in [1]: in general, ${}^0G_{\mathcal{W}}$ is not a group (Lemma 19 of [1] is false). As a consequence the reduced Hamiltonian flows may be incomplete. The general theorems [6, Lemma 1.5.1] imply that $\text{expt } M \in {}^0G_{\mathcal{W}}$ only for t sufficiently small. We shall see below that in fact $\text{expt } M \in {}^0G_{\mathcal{W}}$ for all $t \in \mathbf{C}$ except possibly for a discrete set (which depends on M).

3. We now proceed to the study of the factorization problem. From [1, proposition 23] it follows that with no loss of generality we can restrict ourselves to the case $G = GL(n, \mathbf{C})$.

We begin with a brief exposition of the algebro-geometric pattern of solution of ‘‘Lax equations with a spectral parameter’’ based on papers [2], [3], [4]. For the sake of completeness we include the proofs of some basic results. The main novelty consists in a simple proof of correspondence between Lax equations and linear flows on the Jacobian of the spectral curve.

For $L \in \widetilde{\text{gl}}(n, \mathbf{C})$ let X^a be an affine curve defined by equation $\det(L(z) - \lambda) = 0$. Assume that $L(z)$ has a simple spectrum for general z and also that X^a is nonsingular and irreducible. Let X be the smooth compactification of X^a . Coordinates z, λ are meromorphic functions on X . Let $(z) = P_+ - P_-$ be the divisor of z , P_{\pm} being effective divisors of degree n . Put $U_{\pm} = X \setminus P_{\mp}$, $X_0 = U_+ \cap U_-$. Let R_0 be the algebra of regular functions in X_0 . Clearly, $R_0 = \mathbf{C}[z, z^{-1}, \lambda]$. Put $R = \mathbf{C}[z, z^{-1}]$.

For any $x \in X$ except for a finite set of branch points there exists a unique one-dimensional eigenspace of L i.e. a subspace $E_L(x) \subset \mathbf{C}^n$ such that $L(z(x))\psi = \lambda(x)\psi$ for $\psi \in E_L(x)$. The mapping $x \mapsto E_L(x)$ is clearly a meromorphic mapping of X into $\mathbf{C}P_{n-1}$. Since any such mapping is actually holomorphic we get a holomorphic line bundle $E_L \rightarrow X$.

Put $\mathfrak{g}_{p,q} = \left\{ \sum_{-p}^q x_i z^i, x_i \in \mathfrak{g} \right\}$. An element $L \in \mathfrak{g}_{p,q}$ will be called generic if its lowest and highest coefficients have simple spectrum.

Proposition 1. *Suppose $L = \sum l_i z^i \in \mathfrak{g}_{p,q}$ is generic. Then*

(i) *The genus of the spectral curve is equal to*

$$g = \frac{1}{2}n(n-1)(p+q) - n + 1$$

(ii) *The degree of the dual bundle is equal to $\text{deg } E_L^* = g + n - 1$ and $H^0(X, E_L^*(-P_+)) = 0$.*

Proof. (i) The only singular points of the closure of X^a in $\mathbf{C}P_1 \times \mathbf{C}P_1 \supset \mathbf{C}^2 = \{z, \lambda\}$ are $P = (\infty, \infty)$, $Q = (0, \infty)$. The genus of the nonsingular curve X is given by the Hurwitz formula

$$g = d_1 d_2 - d_1 - d_2 + 1 - v(P) - v(Q)$$

d_1, d_2 being the degrees of the defining equation, $v(P), v(Q)$ the indices of the singular points. In our case $d_1 = n(p+q)$, $d_2 = n$; the indices are easily computed using the principal part of the defining equation at P, Q : $v(P) = \frac{1}{2}n(n-1)p$, $v(Q) = \frac{1}{2}n(n-1)q$.

(ii) We divide the proof into several steps.

(a) Let V denote the subspace of $H^0(X, E_L^*)$ generated by linear coordinates in \mathbf{C}^n .

Let $\psi \in V$. If $\psi z \in H^0(X, E_L^*)$ or $\psi z^{-1} \in H^0(X, E_L^*)$ then $\psi = 0$.

Indeed, $\psi z \in H^0(X, E_L^*)$ means that ψ vanishes on the eigenspaces $E_L(P_-^i)^1$, which are just the eigenspaces of l_{-p} . By our assumption $E_L(P_-)$ span \mathbf{C}^n , so that ψ vanishes on \mathbf{C}^n . The treatment of the second case is similar.

(b) Now, following [4] we prove that the natural mapping $r: V \otimes R \rightarrow H^0(X_0, E_L^*)$ is surjective. To this end observe that $r(V \otimes R)$ is an R_0 -module: if $\psi = (\psi^1, \dots, \psi^n)$ is the standard basis in V then $\lambda \psi = L\psi$ so that $\lambda \psi^i \in r(V \otimes R)$. Suppose that $r(V \otimes R)$ is a proper R_0 -submodule in $H^0(X_0, E_L^*)$. Then by a theorem from Commutative Algebra there exists a point $x \in X_0$, such

1 Since L is generic, the divisor P_{\pm} contains n distinct points P_{\pm}^i .

that $\varphi(x)=0$ for every $\varphi \in r(V \otimes R)$. On the other hand, there exists a $\psi \in V$ which does not vanish on the eigenspace $E_L(x)$, a contradiction.

(c) Next we prove that $V=H^0(X, E_L^*)$. Let $\varphi \in H^0(X, E_L^*)$. Since $\varphi \in r(V \otimes R)$, we have $\varphi = \sum_{i=0}^m \psi_i z^i$, $\psi_i \in V$. We may assume that $\psi_k \neq 0$, $\psi_m \neq 0$; we shall prove that $k=m=0$. Suppose that $m>0$. Then we may write $\psi_m z = \psi z^{1-m} - \sum_{i \leq 0} \psi_{i+m-1} z^i$ whence $\psi_m z \in H^0(X, E_L^*)$. Now, (a) implies that $\psi_m = 0$, a contradiction. The assumption $k < 0$ leads to a similar contradiction.

(d) The statement of (a) combined with $V=H^0(X, E_L^*)$ implies $H^0(X, E_L^*(-P_+))=0$. Since $\text{deg } P_+ = n$, it follows from the Riemann-Roch theorem that $\text{deg } E_L^* \leq g+n-1$. To prove the opposite inequality, consider the bundle $E_k = E_L^*(kP_+)$. For k sufficiently large,

$$\dim H^0(X, E_k) = \text{deg } E_L^* + kn - g + 1$$

Now, $r\left(V \otimes \left\{ \sum_0^k c_i z^i \right\}\right) \subset H^0(X, E_k)$. We shall see below that r is injective (cf. Proposition 2), so $\dim H^0(X, E_k) \geq (k+1)n$, or $\text{deg } E_L^* \geq g+n-1$. ■

Definition. The line bundle $E \rightarrow X$ of degree $g+n-1$ is called regular (or, more precisely, z -regular) if $H^0(X, E(-P_+))=0$.

Clearly, regular bundles form a Zarisky open set in the space \mathcal{L}_{g+n-1} of all line bundles of given degree. We shall readily see that the regularity condition completely characterizes line bundles of eigenspaces of matrices $L \in \tilde{\mathfrak{g}}$ with spectrum X .

Proposition 2. *Let E be a line bundle over X of degree $g+n-1$. The following properties of E are equivalent:*

(i) E is regular.

(ii) The natural mapping $r: H^0(X, E) \otimes R \rightarrow H^0(X_0, E)$ is an isomorphism of R -modules.

Proof. (i) \Rightarrow (ii) Injectivity. Let $\sum_{i \geq k} \varphi_i z^i = 0$, $\varphi_i \in H^0(X, E)$. Then $\varphi_k z^{-1} = -\sum_{i \geq 0} \varphi_{i+k-1} z^i$ and the right hand side is regular at P_+ so that $\varphi_k \in H^0(X, E(-P_+))$. Hence $\varphi_k = 0$ and by induction $\varphi_i = 0$ for every i . Surjectivity. We denote $E_k = E(kP_+ + P_-)$ and prove that for all k $H^0(X, E_k) \subset r(H^0(X, E) \otimes R)$ which is clearly sufficient. Since E is regular, for any $\varphi \in H^0(X, E_k)$ there exist $\varphi_1, \varphi_2 \in H^0(X, E)$ such that $\varphi - \varphi_1 z^k - \varphi_2 z^{-k} \in H^0(X, E_{k-1})$. Our claim now follows by induction.

(ii) \Rightarrow (i) Let $\varphi \in H^0(X, E(-P_+))$, i.e. let φ be a section of E which vanishes at P_+ . Then $\psi = \varphi z^{-1}$ belongs to $H^0(X, E)$ and $r(\psi - \varphi z^{-1}) = 0$. It follows that $\varphi = 0$.

Proposition 3. *A regular line bundle E corresponds to a $GL(n)$ -orbit in $\mathfrak{g}_{p,q}$ consisting of matrices L with spectrum X such that $E_L^* \simeq E$.*

Proof. Multiplication by λ gives an R -linear operator in $H^0(X_0, E)$. Identifying $H^0(X_0, E)$ and $H^0(X, E) \otimes R$ we get an R -linear operator in $H^0(X, E) \otimes R$ i.e. a Laurent polynomial with coefficients in $\text{End } H^0(X, E)$. Choosing a basis in $H^0(X, E)$ we get an $L \in \tilde{\mathfrak{g}}$. It is easy to check that $L \in \mathfrak{g}_{p,q}$. ■

Fix a Hamiltonian $\varphi \in I(\tilde{\mathfrak{g}})$. Put $M = d\varphi(L)$ and let $L(t)$ be the solution to the Hamiltonian Lax equation $\frac{d}{dt} L = [L, M_+]$, $L(0) = L$. The spectral curve X does not vary with t . The time evolution of the corresponding line bundle $E_{L(t)}$ is easy to describe. Let $\psi(x) \in E_L(x)$ be an eigenvector of $L(z(x))$ corresponding to $x \in X$. Since $[L, M] = 0$, we get $M(z(x))\psi(x) = \mu(x)\psi(x)$, $\mu \in R_0$. Let F_t be the line bundle over X defined by transition function $\text{exp } t \mu$ with respect to the covering $X = U_+ \cup U_-$.

Proposition 4. $E_{L(t)} = E_L \otimes F_t$.

Proof. Let $\text{exp } t M = g_+(t)^{-1} g_-(t)$ be the solution to the factorization problem defined a priori for sufficiently small t . The time evolution of L is given by

$$L(t) = g_+(t) L g_+(t)^{-1} = g_-(t) L g_-(t)^{-1}. \tag{3}$$

Now, $E_{L(t)}$ is a subbundle of $X \times \mathbb{C}^n$. Functions $g_+(t)$ give isomorphisms of E_L and $E_{L(t)}$ over U_+ : $E_{L(t)}(x) = g_+(z(x), t) E_L(x)$. The transition function in $U_+ \cap U_-$ which distinguishes between these two isomorphisms is

$$g_+(t)^{-1} g_-(t)|_{E_L} = \text{exp } t M|_{E_L} = \text{exp } t \mu. \quad \blacksquare$$

The group of linear bundles over X of degree zero is isomorphic to the Jacobian of X and F_t is its one-parameter subgroup. So the reduction theorem readily leads to the main result of the “direct spectral problem”: Lax equations generate linear flows on the Jacobian of the spectral curve. The converse is also true.

Proposition 5. Every linear bundle over X of degree zero may be defined by a transition function $\text{exp } \mu$ with respect to the covering $\{U_+, U_-\}$.

Proof. The domains U_\pm being affine curves, our bundle is trivial over U_\pm and so is defined by a transition function φ . The degree of the bundle being zero, φ may be so chosen that a univalent $\mu = \log \varphi$ exists. ■

For any $\mu \in R_0$ there exists a Hamiltonian $\varphi \in I(\tilde{\mathfrak{g}})$ such that $d\varphi(L) = \mu(z, z^{-1}, L)$. We obtain

Corollary 1. Every linear flow on \mathcal{L}_{g+n-1} is generated by a Lax equation.

This corollary enables us to prove that Lax equations are completely integrable. Let $L = \sum_{-p}^q l_i z^i$ be generic and let H be the centralizer of l_{-p} in $GL(n, \mathbb{C})$ if $p > 0$, or $H = GL(n, \mathbb{C})$ if $p = 0$. Let $\tilde{G}_0 = A \times B$ be as in n°2. Let \mathcal{O}_L be the $\text{Ad}^* \tilde{G}_0$ -orbit of L .

Proposition 6. *The orbit \mathcal{L}_L and Lax equations are invariant under the action of H in $\mathfrak{g}_{p,q}$. This action is Hamiltonian.*

Proof. For $p=0$ the statement is obviously true. For $p>0$ we use the arguments of [5]. Consider the Hamiltonians

$$\tilde{\varphi}(L) = \text{Res}_{z=0} z^{-p-1} \varphi(Lz^p), \quad \varphi \in I(\mathfrak{g}).$$

If $M = d\tilde{\varphi}(L)$, then $M_- = d\varphi(l_{-p})$, so that the Hamiltonian flow of $\tilde{\varphi}$ coincides with the adjoint action of the subgroup $\exp t M_- \subset H$. Since the spectrum of l_{-p} is simple, H is generated by these subgroups. ■

Let $\Phi: \mathcal{O}_L \rightarrow \mathfrak{h}^*$ be the momentum map, let $\bar{\mathcal{O}}_L$ be the reduced space over the point $\xi = \Phi(L)$, i.e. $\bar{\mathcal{O}}_L = \Phi^{-1}(\xi)/H_\xi$. Let \bar{T}_L be the level surface of the reduced Hamiltonians $\bar{\varphi}$, $\varphi \in I(\mathfrak{g})$, which contains the image \bar{L} of L .

Theorem 1. (i) *Reduced Hamiltonian systems on $\bar{\mathcal{O}}_L$ defined by the Hamiltonians $\varphi \in I(\mathfrak{g})$ are completely integrable.*

(ii) *There is a natural isomorphism of \bar{T}_L onto a Zarisky open subset of $\mathcal{L}_{\mathfrak{g}+n-1}$.*

Proof. Let T_L denote the set of elements of $\mathfrak{g}_{p,q}$ which are isospectral with L ; in other words, T_L is the level surface of the algebra $I(\mathfrak{g})$. Put $T_L^0 = T_L \cap \mathcal{O}_L$. Proposition 1 gives rise to a mapping $I: T_L \rightarrow \mathcal{L}_{\mathfrak{g}+n-1}$, whose fibres are the $GL(n)$ -orbits in $\mathfrak{g}_{p,q}$. Clearly, the fibres of $I|_{T_L^0}: T_L^0 \rightarrow \mathcal{L}_{\mathfrak{g}+n-1}$ are the H -orbits. The Hamiltonian reduction with respect to H' contracts the H -orbits (or rather their intersections with $\Phi^{-1}(\xi)$) into points. Hence the reduced mapping $\bar{I}: \bar{T}_L \rightarrow \mathcal{L}_{\mathfrak{g}+n-1}$ is one-to-one. On the other hand, corollary 1 says that the trajectories of reduced Lax equations with the initial point \bar{L} cover an open part of $\mathcal{L}_{\mathfrak{g}+n-1}$. This implies complete integrability. ■

Corollary 2. *If $p>0$, $I(\mathfrak{g})$ is a maximal involutive algebra on \mathcal{O}_L and T_L is a maximal torus. If $p=0$, a maximal involutive system on \mathcal{O}_L is obtained by combining $I(\mathfrak{g})$ with a maximal $\mathfrak{gl}(n)$ -involutive system of functions of l_0 .*

4. Now we consider the factorization problem. Let $\psi(t) = (\psi^1(t), \dots, \psi^n(t))$ be the n -tuple of sections of $E_{L(t)}^*$ generated by the linear coordinates in \mathbb{C}^n . By Proposition 4 $\psi(t)$ is described by two n -tuples $\psi_\pm(t)$ of sections of $E_{L^\pm}^*|_{U_\pm}$ related by

$$\psi_-(t) = e^{t\mu} \psi_+(t)$$

If $g_\pm(t)$ solve the factorization problem, then it is clear from (3) that

$$\psi_\pm(t) = g_\pm(t) \psi(0)$$

Suppose $z \in \mathbb{C}$ is such that X is unramified over z and let x_1, \dots, x_n be the points of X over z . Define the matrices $\hat{\psi}_\pm(z, t)$ by

$$\hat{\psi}_\pm^{ij}(z, t) = \psi_\pm^i(x_j, t) \tag{4}$$

Then $\hat{\psi}_\pm(t) = g_\pm(t)\hat{\psi}(0)$, so that

$$g_\pm(z, t) = \hat{\psi}_\pm(z, t)\hat{\psi}(z, 0)^{-1} \tag{5}$$

This formula reconstructs g_\pm in terms of ψ_\pm . Hence if we can write down ψ_\pm explicitly, we solve the factorization problem. To this end we interpret $H^0(X, E_L^*)$ as a linear space $\mathfrak{Q}(D)$ of meromorphic functions on X subordinate to a divisor D which corresponds to E_L^* . By Proposition 1 $\text{deg} D = g + n - 1$. The regularity condition allows for a simple choice of basis in $\mathfrak{Q}(D)$. Since L is generic, the divisor P_+ contains n distinct points P_+^i . Let ψ^i be a (unique up to a constant factor) function on X such that $(\psi^i) \geq -D + P_+ - P_+^i$. Clearly, the functions ψ^i are linearly independent and generate the whole space $\mathfrak{Q}(D)$. To motivate this choice note that if the lowest coefficient of L is diagonal and has simple spectrum, then ψ^i are just the canonical sections (i.e. those defined by standard coordinates in \mathbf{C}^n). It is convenient to assume that $D - P = D_0 - P_0$, $D_0 \geq 0$, $\text{deg} D_0 = g$, $P_0 \in X$, which is always possible.

Theorem 2 [3]. *Let $\mu \in R_0$. Then (i) There exist meromorphic functions $\psi_\pm^i(z, t)$ defined in U_\pm such that*

$$\psi_-^i = e^{t\mu} \psi_+^i, \quad (\psi_\pm^i) \geq -D_0 + P_0 - P_+^i$$

These functions are unique up to a multiple $c_i(t)$.

(ii) *Equations*

$$\begin{aligned} L\psi_\pm &= \lambda\psi_\pm \\ \partial_t \psi_\pm &= \mp M_\pm \psi_\pm \end{aligned}$$

define matrix-valued polynomials $L(t) \in \mathfrak{g}[z, z^{-1}]$, $M_\pm(t) \in \mathfrak{g}[z^{\pm 1}]$ whose coefficients are meromorphic functions of t .

Proof. Define a linear bundle F_t by the transition function $\text{expt } \mu$ for the covering $\{U_+, U_-\}$. Put $E_t = E_L \otimes F_t$. For almost all t the bundle E_t^* is regular and from the Riemann-Roch theorem it follows that for such t $\psi_\pm^i(t)$ is unique up to a factor. Hence a t -smooth function ψ_\pm^i is unique up to a factor $c_i(t)$. The existence of ψ_\pm^i follows from an explicit formula. To write it down we introduce some notation. Fix a basis $\{\omega^i\}$ of holomorphic differentials on X and let ω :

$X \times X \rightarrow \text{Jac} X$ be the Abel transform defined by $\omega(x, y) = \left\{ \int_x^y \omega^i \right\}$. Choose a \mathfrak{A} -

function on \mathbf{C}^g in such a way that there exist $(g - 1)$ points x_1, \dots, x_{g-1} with the property $\mathfrak{A}(\omega(x, x_i)) = 0$ for every $x \in X$ but $\mathfrak{A}(\omega(x, y))$ is not identically zero. There exist unique meromorphic differentials v_\pm on X such that

a) v_\pm are regular in U_\pm and $(v_\pm - d\mu)$ are regular in U_\mp .

b) The \mathbf{Z} -linear functionals on $H_1(X, \mathbf{Z})$ defined by $\gamma \mapsto \int_\gamma v_\pm$ extend to \mathbf{C} -

antilinear functionals on $\mathbf{C}^g(H_1(X, \mathbf{Z}))$ is embedded into \mathbf{C}^g via the period mapping $\gamma \mapsto \left\{ \int_\gamma \omega^i \right\}$. Let $V_\pm \in \mathbf{C}^g$ represent these functionals with respect to the Riemann scalar product in \mathbf{C}^g .

Fix a point $x_0 \in X$ and choose $c \in \mathbf{C}^g$ so that $(\mathfrak{g}(\omega(x_0, \cdot) - c)) = D_0$. Then

$$\psi_{\pm}^i(x) = e^{t \int_{x_0}^x v_{\pm}} \frac{\mathfrak{g}(\omega(P_0, x)) \mathfrak{g}(\omega(x_0, x) + \omega(P_+^i, P_0) - t V_{\pm} - c)}{\mathfrak{g}(\omega(P_+^i, x)) \mathfrak{g}(\omega(x_0, x) - c)}$$

The formula is derived as in [2], [4] and shows that ψ_{\pm}^i is holomorphic in t . If E_t^* is regular the natural mapping

$$H^0(X, E_t^*) \otimes \mathbf{C}[z^{\pm 1}] \rightarrow H^0(U_{\pm}, E_t^*)$$

is a $\mathbf{C}[z^{\pm 1}]$ -module isomorphism. The relation $\partial_t \psi_{-} = e^{t\mu}(\partial_t \psi_{+} + \mu \psi_{+})$ allows to interpret $\partial_t \psi_{\pm}$ as meromorphic sections of E_t^* which are regular in U_{\pm} . Hence there exist matrix polynomials $M_{\pm}(t) \in \mathfrak{g}[z^{\pm 1}]$ such that

$$\partial_t \psi_{\pm} = \mp M_{\pm} \psi_{\pm}$$

To obtain $L(t) \in \mathfrak{g}[z, z^{-1}]$ we use Proposition 3. Coefficients of L, M_{\pm} may be computed recurrently by decomposing $\lambda \psi_{\pm}, \partial_t \psi_{\pm}$ into a power series in the local parameter in the vicinity of P_{\pm}^i . ■

Remark. If ψ_{\pm}^i are normalized so that $\partial_t \psi_{+}(0, t) = 0$, then $M_{+}(t) \in \mathfrak{g} \otimes z \mathbf{C}[z]$.

Proposition 6. $M_{+}(t) + M_{-}(t) = \mu(z, z^{-1}, L(t))$

Proof. From $\psi_{-} = e^{t\mu} \psi_{+}$ we get

$$M_{-} \psi_{-} = \partial_t \psi_{-} = \mu \psi_{-} - M_{+} \psi_{-}$$

hence $(M_{+} + M_{-}) \psi_{-} = \mu \psi_{-}$. ■

Since the functions of Theorem 2 are analytic in t , the factors $g_{\pm}(t)$ related to them by (5) are regular for all t except for a discrete subset of \mathbf{C} . In what follows we give an alternative proof for the existence of a factorization which makes no appeal to general theorems of [6].

As in (4) we define the matrices $\hat{\psi}_{\pm}(z, t)$ by

$$\hat{\psi}_{\pm}^{ij}(z, t) = \psi_{\pm}^i(x_j, t)$$

and put

$$g_{\pm}(z, t) = \hat{\psi}_{\pm}(z, t) \hat{\psi}(z, 0)^{-1} \tag{5}$$

The definition of g_{\pm} is easily seen to be correct (cf. [2]).

Theorem 3 (i) g_{\pm} are entire functions of $z^{\pm 1}$. If t lies outside of a discrete subset of \mathbf{C} , then $\det g_{\pm}(z, t) \neq 0$.

(ii) g_{\pm} provide a factorization for $\exp t M$:

$$\exp t M = g_{+}(t)^{-1} g_{-}(t)$$

Proof. (i) Let M_{\pm} be as in Theorem 2, let Γ be the set of poles of their coefficients. If $t \in \mathbf{C} \setminus \Gamma$ then

$$\partial_t g_{\pm} = \mp M_{\pm} g_{\pm}$$

Thus g_{\pm} are fundamental solutions of analytic differential equations and hence g_{\pm} are regular in $z^{\pm 1}$ and $\det g_{\pm}(z, t) \neq 0$. The definition (5) of g_{\pm} shows that they are regular for all $t \in \mathbb{C}$.

Since $\widehat{\psi}_{-}(t) = \widehat{\psi}_{+}(t) \widehat{\text{expt}} \mu$, we have

$$\begin{aligned} g_{+}(t)^{-1} g_{-}(t) &= \widehat{\psi}(0) \widehat{\psi}_{+}(t)^{-1} \widehat{\psi}_{-}(t) \widehat{\psi}(0)^{-1} \\ &= \widehat{\psi}(0) \widehat{\text{expt}} \mu \widehat{\psi}(0)^{-1} = \text{expt } M. \end{aligned}$$

Clearly, for $t \in \mathbb{C} \setminus \Gamma$

$$L(t) = g_{\pm}(t) L g_{\pm}(t)^{-1}.$$

Remark. Theorem 2 shows that the solutions of Lax equations may have poles in time variable. Formulae (3, 5) give a regularization of trajectories.

In the algebraic approach to Lax equations $L(t)$ and $M_{\pm}(t)$ are determined by the power series expansion of $\lambda \psi_{\pm}$, $\partial_t \psi_{\pm}$ in P_{\pm}^i . On the other hand, the group-theoretic approach gives $L(t) = g_{\pm}(t) L g_{\pm}(t)^{-1}$. The relationship of two methods is based on a remarkable property of g_{\pm} :

$$\text{Ad}_{g_{\pm}}^* L = \text{Ad}_{g_{\pm}}^* L + \text{Ad}_{g_{\pm}}^* g_{\pm}(t) L_{\pm} + \text{Ad}_{g_{\pm}}^* g_{\pm}(t) L_{\mp}.$$

Following Zakharov and Shabat we may say that g_{\pm} are dressing transformations. To sum up, our approach gives a group-theoretic interpretation of the Zakharov-Shabat dressing-up and of algebraic methods of Novikov, Matveev, Dubrovin, Krichever, Mumford, Moerbeke and others. This approach also applies to partial differential equations [7].

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