

CONVEX BODIES FORMING PAIRS OF CONSTANT WIDTH

Hiroshi Maehara

1. INTRODUCTION

All sets considered in this note are subsets of the n -dimensional Euclidean space E^n . Let X be a nonempty compact convex set and u be a point in E^n different from the origin o . The width of X in the direction \vec{ou} , $w(X;u)$, is the distance between the two supporting hyperplanes of X that are perpendicular to the line ou . In terms of the support function

$$h_X(u) = \sup\{\langle u, x \rangle; x \in X\}$$

we have

$$w(X;u) = h_X(u/|u|) + h_X(-u/|u|),$$

where $||$ and $\langle \rangle$ denote the Euclidean norm and inner product. A set of constant width is a nonempty compact convex set whose width is constant in any direction.

We extend the notion of width to a pair (X,Y) of nonempty compact convex sets. Define the width of (X,Y) in the direction \vec{ou} , $w(X,Y;u)$, by

$$w(X,Y;u) = h_X(u/|u|) + h_Y(-u/|u|).$$

A pair (X,Y) of sets is called a pair of constant width if X and Y are nonempty compact convex sets and $w(X,Y;u)$ is constant for

all $u \neq 0$. It is clear that a set X is of constant width if and only if the pair (X, X) is of constant width.

Pairs of constant width have certain properties in common with sets of constant width (see Theorems 1 and 2). Furthermore, if (X, Y) is a pair of constant width r , then the 'vector sum' $X + Y$ is a set of constant width $2r$.

Pairs of constant width are well described in terms of the following operation Ω_r . For a nonempty set X and a positive number r , $\Omega_r(X)$ is defined to be the intersection of all closed balls of radius r whose centers belong to X . Then it is proved that a pair (X, Y) is of constant width r if and only if $\Omega_r(X) = Y$ and $\Omega_r(Y) = X$. Moreover, for a nonempty set X of circumradius r , the pair $(\Omega_r(X), \Omega_r^2(X))$ turns out to be of constant width r . Figure 1 shows two pairs of constant width constructed in this way from a line segment, and from a triangle, in the plane.

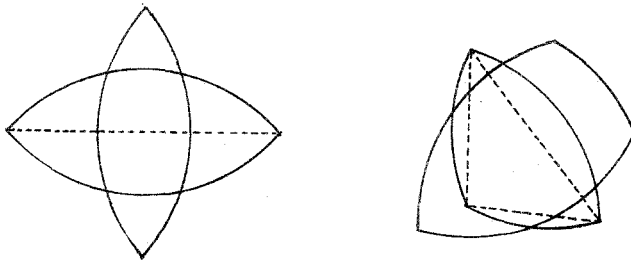


Figure 1.

2. PAIRS OF CONSTANT WIDTH

We first note that if (X, Y) is a pair of constant width r , then $r \geq 0$. For $2r = w(X, Y; u) + w(X, Y; -u) = w(X; u) + w(Y; u) \geq 0$.

A sphere of largest diameter that lies in a compact convex set X is called an insphere of X . The sphere of smallest diameter that encloses X is called the circumsphere of X . The radius of the circumsphere of X is the circumradius of X . In general, a convex set may have many inspheres, but the circumsphere is always unique.

Theorem 1. Let (X, Y) be a pair of constant width r . Then any insphere of X is concentric with the circumsphere of Y (hence X has the unique insphere), and the sum of their radii equals r .

In the case $X = Y$ (then X is a set of constant width), the theorem is well known, see e.g. [1, p.125]. The proof of the theorem for $X \neq Y$ is much the same, and is omitted.

Theorem 2. (The plane case $n=2$) Let (X, Y) be a pair of constant width r in E^2 . Then the sum of the perimeters of X and Y equals $2\pi r$.

Proof. It is well known that for a compact convex set S in E^2 , the perimeter of S equals

$$\frac{1}{2} \int_0^{2\pi} w(S; u_\theta) d\theta, \quad u_\theta = (\cos\theta, \sin\theta).$$

Therefore the sum of the perimeters of X and Y equals

$$\begin{aligned} \frac{1}{2} \int_0^{2\pi} \{w(X; u_\theta) + w(Y; u_\theta)\} d\theta &= \frac{1}{2} \int_0^{2\pi} \{h_X(u_\theta) + h_X(-u_\theta) + h_Y(u_\theta) + h_Y(-u_\theta)\} d\theta \\ &= \frac{1}{2} \int_0^{2\pi} 2r d\theta = 2\pi r. \end{aligned}$$

Theorem 3. If (X, Y) is a pair of constant width r , then the set $X + Y := \{x+y; x \in X, y \in Y\}$ is a set of constant width $2r$.

Proof. Since the support function $h_{X+Y}(u)$ of $X+Y$ equals $h_X(u) + h_Y(u)$ as easily verified, we have

$$\begin{aligned}
 w(X+Y;u) &= h_{X+Y}(u/|u|) + h_{X+Y}(-u/|u|) \\
 &= h_X(u/|u|)+h_Y(u/|u|)+h_X(-u/|u|)+h_Y(-u/|u|) \\
 &= w(X,Y;u) + w(X,Y;-u) = 2r.
 \end{aligned}$$

3. THE OPERATION Ω_r

We denote by $B(x,r)$ the closed ball of radius r centered at x . Then $\Omega_r(X) = \cap\{B(x,r); x \in X\}$. The operation Ω_r also appeared in [1] in connection with sets of constant width, but in rather restricted form and in different notation.

By the definition, $\Omega_r(X)$ is compact and convex, $\Omega_r(X \cup Y)$ equals $\Omega_r(X) \cap \Omega_r(Y)$, and if $X \subset Y$ then $\Omega_r(Y) \subset \Omega_r(X)$.

Theorem 4. If X is a nonempty set of circumradius $\leq r$, then $\Omega_r^2(X)$ is the intersection of all closed balls of radius r that contain X , and $\Omega_r^3(X) = \Omega_r(X)$.

Proof. Since

$$X \subset B(y,r) \leftrightarrow |y-x| \leq r \text{ for all } x \in X \leftrightarrow y \in \Omega_r(X),$$

we have

$$\Omega_r^2(X) = \cap\{B(y,r); y \in \Omega_r(X)\} = \cap\{B(y,r); X \subset B(y,r)\}.$$

And

$$y \in \Omega_r(X) \leftrightarrow X \subset B(y,r) \leftrightarrow \Omega_r^2(X) \subset B(y,r)$$

$$\leftrightarrow |y-z| \leq r \text{ for all } z \in \Omega_r^2(X) \leftrightarrow y \in \Omega_r^3(X).$$

Remark 1. The set $\Omega_r^2(X)$ is called the r -convex hull of X , see [2,p.99].

Remark 2. If we restrict operands of Ω_r to nonempty compact sets of circumradius $\leq r$, then Ω_r is continuous with respect to the

'Hausdorff distance'.

4. PAIRS OF CONSTANT WIDTH AND THE OPERATION Ω_r

Lemma. Suppose $\Omega_r(X) \neq \emptyset$ and let H be a hyperplane supporting $\Omega_r^2(X)$ at x . Let B be the closed ball of radius r which touches H at x and lies on the same side of H as X . Then B contains X .

Proof. First we note the following fact: If the two end points of a minor circular arc (or a semicircle) of radius r belong to a ball of radius r , then the arc is contained in the ball.

Now suppose B does not contain X . Let y be a point of X not in B and let z be the center of B . Since $|x-y| \leq 2r$ and y is not in B , the points x, y, z are not collinear. Let P be the plane determined by x, y, z . Then the line $L = P \cap H$ is tangent to the circle C bounding the disk $P \cap B$. So the line L cuts any circle of radius r on P passing through x and different from the circle C and its reflection in L . Hence, in the plane P , there is a minor circular arc (or semicircle) A of radius r with end points x, y which crosses the line L . Then the arc A intersects with both sides of the hyperplane H . Now, by the fact noted above, every closed ball of radius r that contains X also contains the arc A . Hence $\Omega_r^2(X)$ contains A . But since H is a supporting hyperplane of $\Omega_r^2(X)$, this is a contradiction.

Theorem 5. A pair (X, Y) is of constant width r if and only if $\Omega_r(X) = Y$ and $\Omega_r(Y) = X$.

Proof. First suppose (X, Y) is a pair of constant width r . Then $|x-y| \leq r$ for all $x \in X$ and all $y \in Y$. Hence $Y \subset \Omega_r(X)$. Assume $\Omega_r(X) \neq Y$ and take a point u of $\Omega_r(X)$ not in Y . Let v be the point of Y nearest to u . Then the hyperplane H through v and perpendicular to the line uv supports Y at v . Since the width of

(X, Y) in the direction \vec{uv} is r , there is a supporting hyperplane H' of X parallel to H at distance r apart and lying on the side of H opposite to u . Let w be the contact point of H' with X . Then $|u-w| > |v-w| \geq r$. Since $w \in X$, this implies $u \notin \Omega_r(X)$, a contradiction. Hence $\Omega_r(X) = Y$ and similarly $\Omega_r(Y) = X$.

Now suppose $\Omega_r(X) = Y$ and $\Omega_r(Y) = X$. Then $|x-y| \leq r$ for all $x \in X$ and all $y \in Y$. So the width of (X, Y) in any direction is $\leq r$. Therefore it is enough to show that for any direction \vec{ou} , there are two points $x \in X$ and $y \in Y$ such that $|x-y| = r$ and \vec{yx} has the same direction as \vec{ou} . Let H be the supporting hyperplane of X with exterior normal \vec{ou} , and x_0 be the contact point of H with X . Let B be the closed ball of radius r that touches H at x_0 and lies on the same side of H as X . Then by the lemma, B contains X . Hence the center of B , say y_0 , belongs to $\Omega_r(X) = Y$. Clearly $|x_0 - y_0| = r$ and $\vec{y_0x_0}$ has the same direction as \vec{ou} .

Corollary 1. A set X is of constant width r if and only if $\Omega_r(X) = X$.

The 'only if' part of this corollary is also proved in [1, p.123]. But no mention of the converse is made there.

Corollary 2. For any set X of circumradius $\leq r$, $(\Omega_r(X), \Omega_r^2(X))$ is a pair of constant width r , and $\frac{1}{2}(\Omega_r(X) + \Omega_r^2(X))$ is a set of constant width r .

Use Theorem 5 and the last assertion of Theorem 4.

The diameter of a nonempty bounded set is the least upper bound of the distance between any two points of the set. The following is also proved in [1, p.126].

Corollary 3. Every set of diameter r is contained in a set of constant width r .

Proof. Let X be a set of diameter r . Then since $X \subset \Omega_r(X)$ and $X \subset \Omega_r^2(X)$, we have $X \subset \frac{1}{2}(\Omega_r(X) + \Omega_r^2(X))$.

ACKNOWLEDGMENT

The author wishes to thank the referee for helpful comments and suggestions.

REFERENCES

- [1] Eggleston, H. G.: Convexity, Cambridge University Press, Cambridge, England (1969).
- [2] Valentine, F. A.: Convex Sets, McGraw-Hill, New York (1964).

College of Education,
Ryukyu University,
Nishihara, Okinawa,
Japan.

(Eingegangen am 1. November 1982)
(Revidierte Form am 13. Juli 1983)