

## An Inequality between the Exterior Diameter and the Mean Curvature of Bounded Immersions

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This paper is a natural outgrowth of [9], where the problem of studying the boundedness properties of complete minimal surfaces in  $\mathbb{R}^n$  was approached via the consideration of a certain gradient flow. After the completion of [9] it was soon realized that the basic technique (Lemma 3 below) could be successfully employed to study boundedness of arbitrary complete submanifolds. In this regard, the method can be used to prove the following three theorems.

**Theorem 1.** *Let  $M$  be a complete Riemannian manifold whose scalar curvature is bounded from below and let  $B_R$  be a closed normal ball of radius  $R$  in a Riemannian manifold  $\bar{M}$ . Set  $\bar{K}$  for the supremum of the sectional curvatures of  $\bar{M}$  in  $B_R$ . Let  $I: M \rightarrow B_R \subset \bar{M}$  be an isometric immersion with bounded mean curvature vector  $H$  (say,  $|H| \leq H_0$ ). Then the following holds*

- a)  $R \geq \frac{1}{\delta} \arctan \left( \frac{\delta}{H_0} \right)$ , if  $\bar{K} \leq \delta^2$  ( $\delta > 0$ ) and  $R < \frac{\pi}{2\delta}$ ,
- b)  $R \geq \frac{1}{H_0}$ , if  $\bar{K} \leq 0$ ,
- c)  $R \geq \frac{1}{\delta} \operatorname{arctanh} \left( \frac{\delta}{H_0} \right)$ , if  $\bar{K} \leq -\delta^2 < 0$ .

Theorem 1 was proved in [1] for  $M = \text{surface}$  and  $\bar{M} = \mathbb{R}^n$ . For arbitrary  $M$  and  $\bar{M} = \mathbb{R}^n$ , see [4] and [5]. In [3] the case  $\bar{M} = S^n$  is discussed. Recently, a different proof of Theorem 1 was offered by Koutroufiotis and the first named author in [8], where other related problems are also considered. Except for [1], all these proofs rely, in one way or another, on a rather technical theorem of Omori [11]. The present authors feel that the present approach is more conceptual and lends itself better for generalizations. For instance, the proofs of the following two seemingly unrelated theorems on minimal submanifolds have much in common with Theorem 1.

**Theorem 2.** *Let  $M$  be a complete Riemannian manifold with bounded scalar curvature and  $I: M \rightarrow \mathbb{R}^n - \{0\}$  be a minimal immersion. It is not possible to find*

a unit vector  $v \in \mathbb{R}^n$  and  $\delta > 0$  such that  $\left\langle v, \frac{I(x)}{\|I(x)\|} \right\rangle \geq \delta$  for all  $x \in M$  (otherwise said,  $I(M)$  does not lie inside of a non-degenerate cone of  $\mathbb{R}^N$ ).

When  $M$  is a surface and  $n=3$  a stronger statement can be made:

**Theorem 3.** *Let  $M^2$  be a complete surface with bounded Gaussian curvature and let  $f: \mathbb{R} \rightarrow \mathbb{R}^+$  be a proper function. It is not possible to find a minimal immersion of  $M$  into*

$$A_f = \{(x, y, z) \in \mathbb{R}^3 \mid z > f(y)\}.$$

Theorems 2 and 3 seem to be inaccessible to techniques using the theorem of Omori quoted above. They are very much in the spirit of [9] where, as pointed out at the beginning, the main enterprise was to find out the extrinsic boundedness properties of minimal surfaces in  $\mathbb{R}^n$ . This type of question was raised by Calabi and Chern [2]. The reader may also want to look at [7] and [10] where examples are constructed of complete minimal surfaces entirely contained in balls of  $\mathbb{R}^4$  and slabs of  $\mathbb{R}^3$ , respectively. Theorem 3 above should be compared with the result of [10]. It is also to be mentioned that, by letting  $H_0=0$  in Theorem 1, several results scattered throughout the aforementioned papers can be recovered.

In order to stress the conceptual simplicity of the methods the authors have refrained from proving a few other minor results that spring naturally from the given ones.

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### Preliminary Results

**Lemma 1.** *Let  $M$  be a complete Riemannian manifold and  $f: M \rightarrow \mathbb{R}^+$  a smooth function satisfying*

$$\text{Hess } f(p)(X, X) \geq c|X|^2 \quad (c > 0)$$

for all  $p \in M_\varepsilon = f^{-1}([0, \varepsilon])$ , and for all  $X \in T_p(M)$ . Then each connected component of  $M_\varepsilon$  is compact.

*Proof.* Let  $\bar{M}_\varepsilon$  be a connected component of  $M_\varepsilon$  and  $\mathcal{C}$  be the set of critical points of  $f$  in  $\bar{M}_\varepsilon$ . The above condition on the Hessian of  $f$  implies that  $\mathcal{C}$  contains only non-degenerate points of minimum. Let  $x \in \bar{M}_\varepsilon$  and consider  $\varphi_x: (T_{(\bar{x})}, 0] \rightarrow \bar{M}_\varepsilon$ , the maximal semi-orbit of  $df^\#$  ending at  $x$  (i.e.,  $\varphi_x(0)=x$ ). Suppose, by way of contradiction, that  $\varphi_x$  has infinite length. Let then  $\beta: [0, \infty) \rightarrow \bar{M}_\varepsilon$  be its reparametrization by arc-length. A straightforward computation gives  $(f \circ \beta)'(s) = |df(\beta(s))|^2$  and  $(f \circ \beta)''(s) \geq c$ . It follows from this inequality that  $f \circ \beta$  is unbounded, thus contradicting the fact that  $\beta(s) \in \bar{M}_\varepsilon$ . Therefore  $\varphi_x$  has bounded length. In particular,  $\lim_{T \rightarrow T_{(\bar{x})}} \varphi_x(T)$  exists and belongs to  $\mathcal{C}$ . Let

$$\mathcal{O}_y = \{x \in \bar{M}_\varepsilon \mid \lim_{T \rightarrow T_{(\bar{x})}} \varphi_x(T) = y\}.$$

It is easy to see that each  $\mathcal{O}_y$  is open ( $\mathcal{C}$  contains only points of strict minimum). Since  $\bar{M}_\varepsilon = \bigcup_{y \in \mathcal{C}} \mathcal{O}_y$  is connected,  $\mathcal{C}$  consists of a single point say  $y_0$ .

Suppose now that  $\bar{M}_\varepsilon$  is noncompact. Since  $M$  is complete there are points  $p_n \in \bar{M}_\varepsilon$  with  $d(p_n, y_0) \rightarrow \infty$ . Consider  $\varphi_{p_n}: [T_{(p_n)}^-, 0] \rightarrow \bar{M}_\varepsilon$  (notation as above) and let  $\beta_n: [0, s_n]$  be its reparametrization by arc-length. It follows from the relations given above for  $(f \circ \beta_n)'$  and  $(f \circ \beta_n)''$  that

$$f(\beta_n(s_n)) \geq \frac{c s_n^2}{2} + f(y_0) = \frac{c}{2} d(p_n, y_0)^2 + f(y_0).$$

Hence  $f(\beta_n(s_n)) \rightarrow \infty$  as  $n \rightarrow \infty$ , contradicting the boundedness of  $f$  on  $\bar{M}_\varepsilon$ .

The proof of next lemma uses standard comparison theorems and may be found in [8] and [13].

**Lemma 2.** *Let  $N$  be an  $m$ -dimensional Riemannian manifold with sectional curvature  $K$ ,  $x_0$  and  $x$  points of  $N$  so that  $x$  does not lie in the cut locus of  $x_0$ . Let  $\gamma: [0, \ell]$  be the minimizing geodesic segment connecting  $x_0$  with  $x$ , parametrized by arc-length. Take a positive number  $\delta$ . For any unit vector  $X \in T_x N$ , perpendicular to  $\gamma'(\ell)$ , the Hessian of the function  $f(x) = \frac{1}{2}d(x_0, x)^2$  satisfies  $\text{Hess } f(X, X) \geq \mu(\ell)$ , where*

$$\mu(\ell) = \begin{cases} \ell \delta \cotan(\ell \delta) & \text{if } \max_{\gamma} K = \delta^2 \text{ and } \ell < \frac{\pi}{\delta} \\ 1 & \text{if } \max_{\gamma} K = 0 \\ \ell \delta \cotanh(\ell \delta) & \text{if } \max_{\gamma} K = -\delta^2. \end{cases}$$

**Lemma 3.** *Let  $M$  be complete and  $I: M \rightarrow \bar{M}$  an isometric immersion with bounded second fundamental form. Then, for each  $p \in \bar{M}$  there exists a closed ball  $B(p)$  such that all connected components of  $I^{-1}(B(p))$  are compact.*

*Proof.* It is well-known that the function  $g: \bar{M} \rightarrow \mathbb{R}$ ,  $g(q) = \frac{1}{2}d(p, q)^2$  is strictly convex on a sufficiently small neighborhood of  $p$ , say  $\text{Hess } g(q)(X, X) \geq c|X|^2$  ( $c > 0$ ) for  $q \in B(p)$ . Let then  $f = g|_M$ . A straightforward computation yields

$$\text{Hess } f(q)(X, X) = \text{Hess } g(q)(X, X) + \langle \nabla g(q), \alpha(q)(X, X) \rangle,$$

where  $\alpha$  represents the second fundamental form. On the other hand

$$|\langle \nabla g(q), \alpha(q)(X, X) \rangle| \leq |\nabla g(q)| |\alpha(q)| |X|^2 \leq d(p, q) |\alpha(q)| |X|^2$$

and this in turn can be made less than  $\frac{c}{2}|X|^2$  by taking  $d(p, q)$  small enough (i.e., by shrinking  $B(p)$ ). In particular,

$$\text{Hess } f(q)(X, X) \geq \frac{c}{2}|X|^2.$$

The result now follows from Lemma 1.

### Proofs of the Theorems

*Proof of Theorem 1.* Suppose that  $I: M \rightarrow B_R(P_0)$  and that  $P \in \partial B_R(P_0)$  is an accumulation point of  $I(M)$ . By Lemma 3 the set  $M_\varepsilon = I^{-1}(B_\varepsilon(P))$  has only compact components, provided  $\varepsilon > 0$  is small enough. Let  $\gamma$  be the radius joining  $P$  and  $P_0$ , extended somewhat. Take a sequence  $\{P_j\} \subset \gamma$  converging to  $P_0$  and such that  $P_0$  lies between  $P_j$  and  $P$ . For  $x \in S_\varepsilon = B_R(P_0) \cap \partial B_\varepsilon(P)$  one has

$$d(P_j, x) \leq d(P_j, P_0) + d(P_0, x) \leq d(P_j, P_0) + R = d(P_j, P).$$

Since broken geodesics do not realize distance the first inequality is strict. In particular,  $R_j = \max_{x \in S_\varepsilon} d(P_j, x) < d(P_j, P)$ . Let  $f_j: M \rightarrow \mathbb{R}$  be given by  $f_j(x) = \frac{1}{2}d(P_j, I(x))^2$ . Since  $P$  is an accumulation point of  $I(M)$  and  $I(\partial M_\varepsilon) \subset S_\varepsilon$  there exists points  $x$  in  $M_\varepsilon$  for which  $R_j < f_j(x) < d(P_j, P)$ . In particular, the maximum of  $f_j$  at each (compact) component of  $M_\varepsilon$  is attained at some interior point, say  $x_j$ . The formula given in the proof of Lemma 3 together with the estimate of Lemma 2 yields

$$0 \leq \Delta f_j(x_j) = \text{tr Hess } f_j(x_j) \geq (n-1)(\mu(T_j) - H_0 T_j), \quad \text{where } T_j = d(P_j, P).$$

The result now follows from  $\mu(T_j) \leq H_0 T_j$  by letting  $j \rightarrow \infty$ .

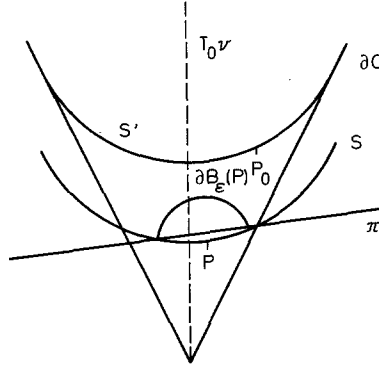
*Proof of Theorem 2.* There is no loss of generality in supposing that  $v = (0, 0, \dots, 1)$  and  $\overline{I(M)} \cap \partial C = \emptyset$ , where

$$C = \left\{ x \in \mathbb{R}^n \left| \left\langle v, \frac{x}{\|x\|} \right\rangle \leq \delta \right. \right\}.$$

Let  $P_0 \in I(M) \cap \text{int } C$ . It is possible to choose a sphere  $S_{R_0}(T_0 v)$  in  $\mathbb{R}^n$  which is tangent to the cone and so that  $P_0$  is between the hyperplanes  $\langle v, x \rangle = T_0$  and  $\langle v, x \rangle = 0$ , with  $P_0 \in S_{R_0}(T_0 v)$ . In particular the set  $S_{R_0}(T_0 v) \setminus \partial C$  has exactly two components. Let  $S'$  be the one that contains  $P_0$ . Set

$$T' = \sup \{ T : (S' - T v) \cap I(M) \neq \emptyset \}, \quad S = S' - T' v.$$

Let  $P \in \overline{I(M)} \cap S$ . Suppose that  $T' > 0$  (if  $T' = 0$ , set  $P = P_0$  in the sequel), so that  $\partial S \cap \partial C = \emptyset$  (recall that  $S_{R_0}(T_0 v)$  is tangent to  $C$ ). In particular,  $P \in \text{int } S \cap \overline{I(M)}$ . By Lemma 3 it is possible to choose  $\varepsilon > 0$  sufficiently small so that the components of  $I^{-1}(\overline{B_\varepsilon(P)})$  are compact submanifolds with boundary (it follows from the equation of Gauss and the minimality of  $I(M)$  that boundedness of the second fundamental form is equivalent to boundedness of the scalar curvature). Let  $M_0$  be such a component and let  $\pi$  be the hyperplane containing  $S \cap \partial_\varepsilon B(P)$ . Observe that  $\partial I(M_0) \subset \partial B_\varepsilon(P)$  and that  $\partial I(M_0)$  lies above  $S$ , in the obvious sense (actually,  $I(M)$  lies above  $S$ ). In particular  $\partial I(M_0)$  lies above  $\pi$ . It is well-known that compact minimal submanifolds of  $\mathbb{R}^n$  are contained in the convex hull of their boundaries. It follows from this that  $I(M_0)$  lies above  $\pi$ . Since  $d(P, \pi) > 0$  this implies that  $P \notin I(M)$ , a contradiction.



*Proof of Theorem 3.* Suppose that  $I: M \rightarrow A_f$  is minimal. By passing to the universal covering it may be assumed, in view of the uniformization theorem for Riemann surfaces, that  $M$  is conformally the unit disc  $D$  or  $\mathbb{C}$ . Since the coordinate functions of a minimal immersion are harmonic and  $I_3 > 0$  ( $I = (I_1, I_2, I_3)$ ) the first alternative must prevail. Therefore, it may be supposed that (see [9] for details)

$$I: (D, \lambda |dz|^2) \rightarrow A_f, \quad \lambda = \left( \sum_{i=1}^3 |\varphi_i|^2 \right),$$

where the  $\varphi_i$ 's are holomorphic functions satisfying  $\sum_{i=1}^3 \varphi_i^2 = 0$ . The immersion can be recovered by the formulas  $I_k(z) = \text{Re} \int_a^z \varphi_k(\xi) d\xi$ , for a suitable choice of  $a \in D$  (see [12] for general facts on minimal surfaces). For the completion of the proof it is necessary to use several classical results on the boundary behavior of holomorphic functions on the unit disc, associated to the names of Fatou, Herglotz, Lusin, Privalov, Marcinkiewicz and Zygmund. Since their proofs (and in some cases their statements) are fairly elaborate, it seems wise just to quote them. An excellent source is the treatise [14]; for those who want to get acquainted with some of the techniques involved, a convenient reference is [6]. Coming back to the proof, denote by  $T_\theta \subset D$  an open equilateral triangle of side  $\frac{1}{4}$  with a vertex at  $e^{i\theta}$ . Since  $I_3 > 0$ , Herglotz's theorem ([6], p. 38) implies that  $\lim_{z \in T_\theta, z \rightarrow e^{i\theta}} T_3(z)$  exists for almost all  $e^{i\theta} \in S^1$ . Pick  $e^{i\theta}$  for which this limit exists. Since  $0 < f(I_2(z)) < I_3(z)$  for all  $z \in T_\theta$  and  $f$  is proper, the set  $\{I_2(z) | z \in T_\theta\}$  is bounded. Theorem 1.1 of [14], p. 199, implies that  $\lim_{z \in T_\theta, z \rightarrow e^{i\theta}} I_2(z)$  exists almost everywhere. By the remark ii) following Theorem 1.10 of [14], p. 204, the limits of  $\int_a^z \varphi_k(\xi) d\xi$  in  $T_\theta$  as  $z \rightarrow e^{i\theta}$  exist almost everywhere ( $k=2, 3$ ). By Theorem 2.2 i of [14], p. 207,  $\int_{T_\theta} |\varphi_2|^2 + \int_{T_\theta} |\varphi_3|^2 < \infty$  for almost all  $e^{i\theta} \in S^1$ . In view of the relation  $\sum_{i=1}^3 \varphi_i^2 = 0$  this implies that  $\int_{T_\theta} |\varphi_1|^2 < \infty$  almost everywhere. The converse of Theorem 2.2 ii) above can then be applied to show that

$\lim_{z \in T_\alpha, z \rightarrow e^{i\theta}} \int_a^z \varphi_1(\xi) d\xi$  exists almost everywhere. In particular,  $\lim_{z \in T_\alpha, z \rightarrow e^{i\theta}} I_1(z)$  exists almost everywhere. Let then  $e^{i\alpha} \in S^1$  be such that the limits of  $I_k$  ( $k=1, 2, 3$ ) over  $T_\alpha$  as  $z \rightarrow e^{i\alpha}$  exist. Denote them by  $a_1, a_2$  and  $a_3$ , respectively. Consider the function  $f: D \rightarrow \mathbb{R}$ ,  $f(z) = \sum_{k=1}^3 (I_k(z) - a_k)^2$ . As before, for  $\varepsilon > 0$  small enough, the set  $f^{-1}(0, \varepsilon)$  has only compact connected components. In particular it has a component  $C$  containing a segment of the form  $\{re^{i\alpha}, b \leq r < 1\}$ . Since this path is divergent,  $C$  must be non-compact, a contradiction.

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