

# Uniqueness for the harmonic map flow in two dimensions

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**Abstract.** Let  $M$  be a two-dimensional Riemannian manifold with smooth (possibly empty) boundary. If  $u$  and  $v$  are weak solutions of the harmonic map flow in  $H^1(M \times [0, T]; S^N)$  whose energy is non-increasing in time and having the same initial data  $u_0 \in H^1(M, S^N)$  (and same boundary values  $\gamma \in H^{3/2}(\partial M; S^N)$  if  $\partial M \neq \emptyset$ ) then  $u = v$ .

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## 1. Introduction

Let  $M$  be a compact two-dimensional Riemannian manifold with smooth (possibly empty) boundary  $\partial M$ . In this paper we obtain a uniqueness result for solutions of the ‘harmonic map flow’ on  $M$ :

$$(1.1) \quad \begin{cases} u_t - \Delta u = u|\nabla u|^2 & \text{on } M \times (0, T) \\ u(x, t) = \gamma(x) & \text{for } t \geq 0, x \in \partial M \\ u(x, 0) = u_0(x), & x \in M \end{cases}$$

where  $u(x, t)$  takes values in the unit sphere  $S^N \subset \mathbb{R}^{N+1}$ . Time-independent solutions of (1.1) correspond to harmonic maps from  $M$  to  $S^N$ . The following existence and uniqueness theorem for weak solutions of (1.1) when  $\partial M = \emptyset$  was obtained by M.Struwe. Define:

$$V_T = H^1(M \times [0, T]; S^N) \cap L^\infty([0, T]; H^1(M; S^N)) \cap L^2([0, T]; H^2(M; S^N))$$

**Theorem 1.1.** (M. Struwe, [1].) *Assume  $\partial M = \emptyset$ . For any initial value  $u_0 \in H^1(M; S^N)$  there exists a number  $T_0 = T_0(u_0) > 0$  and a solution  $v \in \bigcap_{T' < T_0} V_{T'}$  of (1.1) with  $u(\cdot, 0) = u_0$ . Moreover,*

- (i)  $v$  is regular in  $M \times (0, T_0]$  with the exception of finitely many points  $(x_i, T_0)$ ,  $1 \leq i \leq K$ ;
- (ii)  $v$  is the unique solution of (1.1) in the space  $\bigcap_{T' < T_0} V_{T'}$  with initial data  $u_0$ ;
- (iii) The energy  $E_v(t) = \int_{M \times \{t\}} |\nabla v|^2 dx$  is finite for all  $t \in [0, T_0]$  and non-increasing in  $t$ .

The same conclusions hold when  $\partial M \neq \emptyset$ , assuming  $\gamma \in H^{3/2}(\partial M)$  (K.C.Chang [2]). We have only stated some of the conclusions in [1] and [2]. In particular, M.Struwe's and K.C. Chang's results hold for arbitrary compact target manifolds. These authors also show that the solution can be continued to a weak solution  $v$  of (1.1) in  $M \times [0, \infty)$  whose singular set is finite. Precisely,

$$v \in H^1(M \times [0, \infty), S^N) \cap L^\infty([0, \infty), H^1(M; S^N))$$

and one may find a finite sequence of times  $0 < T_1 < \dots < T_k = \infty$  such that

$$v \in \bigcap_{i=1}^{k-1} L^2_{loc}([T_i, T_{i+1}); H^2(M; S^N)).$$

The solution  $v$  is unique in this class of weak solutions; we will refer to it as the 'almost smooth' solution. It is natural to wonder whether, with the same initial data, any other weak solutions  $u \in H^1(M \times [0, \infty), S^N)$  with bounded energy in  $[0, \infty)$  may exist. In this direction the following result was recently obtained by T.Rivière([3]).

**Theorem 1.2.** (T. Rivière, [3].) *Assume  $\partial M \neq \emptyset$ . There exists  $\alpha > 0$  such that, for any boundary values  $\gamma \in H^{3/2}(\partial M; S^N)$  and any  $u_0 \in H^1(M; S^N)$  satisfying  $E(u_0) < \alpha$ , (1.1) has a unique solution in  $H^1_{loc}([0, \infty) \times M)$  for which  $E_u(t) \leq E(u_0)$  for a.e.  $t$ . This solution is regular in  $[0, \infty) \times M$ .*

In [3] this theorem is stated for  $M$  an open set in  $\mathbb{R}^2$  with smooth boundary, but it is not hard to see that the proof applies to arbitrary Riemannian surfaces with non-empty boundary. The main result in this paper states that, assuming monotonicity of the energy, we have uniqueness in  $H^1$  without the small-energy assumption of theorem 1.2.

**Theorem 1.3.** *Let  $M$  be a two-dimensional Riemannian manifold with smooth (possibly empty) boundary. If  $u$  and  $v$  are weak solutions of (1.1) in  $H^1(M \times [0, T]; S^N)$  satisfying  $E_u(t) \leq E_u^{(s)}, E_v(t) \leq E_v^{(s)}$  for a.e.  $s < t$  and having the same initial data  $u_0 \in H^1(M; S^N)$  (and same boundary values  $\gamma \in H^{3/2}(\partial M, S^N)$  if  $\partial M \neq \emptyset$ ) then  $u = v$ .*

Combining this statement with theorem 1.1 we immediately obtain the following 'partial regularity' result:

**Corollary 1.4.** *Any weak solution  $u \in H^1(M \times [0, T]; S^N)$  of (1.1) such that  $u_0 \in H^1(M; S^N)$  and  $E_u(t)$  is non-increasing in  $t$  (with  $\gamma \in H^{3/2}(\partial M, S^N)$  if  $\partial M \neq \emptyset$ ) is smooth in  $M \times (0, T]$  away from finitely many points.*

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## 2. Preliminaries

In this section we list some well-known results that are used in the proof. We assume throughout that  $M$  is a compact Riemannian  $n$ -manifold with smooth (possibly empty) boundary.

### 2.1. Interpolation inequality

Assume  $M$  is two-dimensional. There exists  $c_1 = c_1(M) > 0$  such that if  $f \in H^1(M)$ ,

$$(2.1) \quad \int_M |f|^4 dx \leq c_1 \left( \int_M |\nabla f|^2 dx \right) \left( \int_M |f|^2 dx \right).$$

### 2.2. Hodge decomposition theorem

2.2.1 ( $\partial M = \emptyset$ ) Denote by  $\mathcal{H}^p$  ( $0 \leq p \leq n$ ) the space of harmonic forms in  $M$  of degree  $p$ . We have the orthogonal Hilbert space decomposition:

$$\Lambda^p L^2(M) = d\Lambda^{p-1} H^1(M) \oplus \delta\Lambda^{p+1} H^1(M) \oplus \mathcal{H}^p.$$

2.2.2 ( $\partial M \neq \emptyset$ ) [5, chapter 4.1] Let  $\theta \in \Lambda^1(M)|_{\partial M}$  be the metric dual to the unit normal  $\nu$ . Any  $p$ -form  $\omega \in \Lambda^p(M)$  has a unique orthogonal decomposition at points of  $\partial M$ :  $\omega = \omega_t + \theta \wedge \omega_n$ , where  $i_\nu \omega_n = 0$ . Denote by:

$\Lambda_T^{p+1} H^1(M)$ - the  $H^1$  closure of the space of smooth  $(p+1)$ -forms  $\omega$  in  $M$  such that  $\omega_n = 0$  on  $\partial M$ ;

$\mathcal{H}_T^p$ - the space of (smooth)  $p$ -forms  $\omega$  in  $M$  such that  $d\omega = \delta\omega = 0$  and  $\omega_n = 0$  on  $\partial M$ . This is a finite dimensional vector space, isomorphic to the ('absolute') cohomology space  $H^p(M, \mathbb{R})$ . We have:

$$\Lambda^p L^2(M) = d\Lambda^{p-1} H^1(M) \oplus \delta\Lambda_T^{p+1} H^1(M) \oplus \mathcal{H}_T^p.$$

In the unique decomposition

$$\omega = d\alpha + \delta\beta + h \quad (\delta\alpha = d\beta = 0)$$

corresponding to either of the two splittings above, one has the bounds:

$$\|\alpha\|_{H^1} \leq c_2 \|\omega\|_{L^2}, \quad \|\beta\|_{H^1} \leq c_2 \|\omega\|_{L^2},$$

for some  $c_2 = c_2(M) > 0$ .

### 2.3. Linear parabolic theory

The next two results summarize the existence and uniqueness theory in Sobolev spaces for the linear parabolic equation:

$$(2.2) \quad \begin{cases} \Phi_t - \Delta\Phi = g & \text{in } M \times (0, T) \\ \Phi(x, \cdot) = 0 & \text{on } \partial M \\ \Phi(\cdot, 0) = 0 & \text{in } M \end{cases}$$

We set  $I = [0, T]$ .

**2.3.1 Theorem.** (J.L. Lions–E. Magenes [7], p.89). *Assume  $g \in L^2(I, H^{-1}(M))$ . Then problem (2.2) has a unique solution in the space:*

$$W_0 = \{ \Phi \in L^2(I, H^1) \mid \Phi_t \in L^2(I, H^{-1}), \Phi|_{\partial M} = 0, \Phi(\cdot, 0) = 0 \text{ in } M \}.$$

Moreover the map  $\mathcal{U} : L^2(I, H^{-1}) \rightarrow W_0$ ,  $\mathcal{U}(g) = \Phi$  is an isomorphism with inverse  $L\Phi = \Phi_t - \Delta\Phi$ .

**2.3.2 Theorem.** (P. Grisvard [6], Theorem 9.3 and Remark 9.15). *Assume  $g \in L^p(I, L^q(M))$ , where  $1 < p, q < \infty$  are arbitrary. Problem (2.2) has a unique solution in the space:*

$$L_0^p(I, W^{2,q}) = \{ \Phi \in L^p(I, W^{2,q}) \mid \Phi_t \in L^p(I, L^q), \Phi|_{\partial M} = 0, \Phi(\cdot, 0) = 0 \text{ in } M \}.$$

Moreover the map  $\mathcal{L} : L^p(I, L^q) \rightarrow L_0^p(I, W^{2,q})$ ,  $\mathcal{L}(g) = \Phi$  is an isomorphism with inverse  $L\Phi = \Phi_t - \Delta\Phi$ .

In the references given these results are stated for bounded domains in Euclidean space; the reader familiar with the proofs will observe that they also apply to the present context.

### 2.4. Wentze's theorem

Let  $M$  be a compact two-dimensional Riemannian manifold with (possibly empty) smooth boundary. If  $\eta \in \Lambda^2 H^1(M)$  and  $\theta \in H^1(M)$ , then  $\langle \delta\eta, d\theta \rangle \in H^{-1}(M)$  and

$$\| \langle \delta\eta, d\theta \rangle \|_{H^{-1}} \leq c_3 \| \delta\eta \|_{L^2} \| d\theta \|_{L^2},$$

for some  $c_3 = c_3(M) > 0$ .

When  $M$  is a bounded domain in  $\mathbb{R}^2$  (with the Euclidean metric) and  $\eta = \eta_1 dx \wedge dy$ ,  $d\theta = \theta_x dx + \theta_y dy$ , we have:

$$\langle \delta\eta, d\theta \rangle = \theta_x(\eta_1)_y - \theta_y(\eta_1)_x,$$

and the lemma is proved in [9, lemma A.2] following Wentze's original proof for  $M = \mathbb{R}^2$  [8]. In the general case one takes local conformal coordinates in which the metric is written as  $g_{ij} = e^{-2v} \delta_{ij}$ ,  $1 \leq i, j \leq 2$ . This implies  $\delta_g \eta = e^{-2v} \delta_{eucl} \eta$ , so locally we are back in the Euclidean case, and we may globalize with a simple partitions-of-unity argument. We omit the details.

### 2.5. Notation

We try to adhere to self-explanatory notation; the following abbreviations are often used:

$$Q = M \times [0, T]; \quad I = [0, T]; \quad M_t = M \times \{t\}.$$

$W^{k,p}(M)$  is the Sobolev space of functions (or maps to  $S^N$ ) which have  $k$  distributional derivatives in  $L^p$ ;  $H^s$ ,  $s \in \mathbb{R}$ , denotes the scale of Hilbert spaces with  $H^k = W^{k,2}$  for  $k \in \mathbb{N}$ . The domain  $M$  and target ( $S^N$  or  $\mathbb{R}^{N+1}$ ) are usually omitted from the notation, with the understanding that, as usual:

$$W^{k,p}(M, S^N) = \{u \in W^{k,p}(M, \mathbb{R}^{N+1}) \mid u(x) \in S^N \text{ a.e.}(x)\}.$$

$$L^p(I, W^{k,q}) = L^p([0, T]; W^{k,q}(M)).$$

$\Lambda^p W^{k,p}$ ,  $\Lambda^p H^s$ , etc. denote spaces of differential forms of degree  $p$  with coefficients in the corresponding Sobolev spaces (smooth forms if no space is indicated);  $\delta$  denotes the co-differential in the metric of  $M$ .

$c$  denotes a generic positive constant whose value depends only on  $M$ .

### 3. Proof of Theorem 1.3

(i) It is enough to prove the theorem assuming  $v$  is the ‘almost smooth’ solution. Moreover we may take  $T$  to be the  $T(u_0)$  given by theorem 1.1, and assume  $v$  is smooth in  $M \times (0, T)$ . For then the conclusion  $u = v$  in  $M \times (0, T)$  will imply  $u$  is smooth in  $M \times (0, T)$ , hence by the uniqueness result (ii) in theorem 1.1  $u = v$  in  $M_T$  and we may iterate.

(ii) Applying the interpolation inequality (2.1) to  $\nabla v \in H^1(M_t)$  we obtain for all  $t \in (0, T)$ :

$$(3.1) \quad \int_{M_t} |\nabla v|^4 dx \leq c_2 E_0 \int_{M_t} |\nabla^2 v|^2 dx.$$

Since, for each  $T' < T$ ,  $v \in L^2([0, T'], H^2)$ , this shows the function  $t \mapsto \int_{M_t} |\nabla v|^4 dx$  is in  $L^1([0, T'])$ . We fix an arbitrary  $T' < T$  for the remainder of the proof.

(iii) Let  $w = u - v$ . Then  $w \in H^1(Q) \cap L^\infty(I, H^1)$  and is a solution of:

$$(3.2) \quad \begin{cases} w_t - \Delta w = u|\nabla u|^2 - v|\nabla v|^2 \text{ in } Q; \\ w(x, t) = 0, x \in \partial M; \\ w(x, 0) = 0, x \in M. \end{cases}$$

The main step in the proof is the following lemma:

**Lemma 3.1.** *Let  $u$  and  $v$  satisfy the assumptions of the main Theorem 1.3; in addition, assume  $v$  is smooth in  $M \times (0, T)$ . Let  $w = u - v$ . Then there exists  $T' < T$  such that  $\nabla w \in L^4([0, T'], W^{1,4}(M))$ .*

Lemma 3.1 implies that  $w \in H^2(M_t, \mathbb{R}^{N+1})$  for a.e.  $t \in [0, T']$  (this was also observed by Rivière in [3]): it suffices to write the equation for  $w$  in the form:

$$w_t - \Delta w = u|\nabla w|^2 + 2u\nabla v \cdot \nabla w + w|\nabla v|^2,$$

from which it follows that:

$$|w_t - \Delta w| \leq c(|\nabla w|^2 + |\nabla v|^2),$$

which is in  $L^2(M \times [0, T'])$  by the lemma. Since  $w_t \in L^2(M \times [0, T])$ , we conclude that  $w \in H^2(M_t)$  for a.e.  $t$ . Thus we may integrate by parts (as in the uniqueness proof in [1]) and obtain for a.e.  $t \in [0, T']$ :

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int_{M_t} |w|^2 dx + \int_{M_t} |\nabla w|^2 dx = \int_{M_t} \langle u|\nabla u|^2 - v|\nabla v|^2, w \rangle dx \\ & \leq \int_{M_t} [|w|^2 |\nabla u|^2 + |v||w||\nabla U||\nabla w|] dx \\ & \leq c \int_{M_t} |w|^2 |\nabla U|^2 dx + \frac{1}{2} \int_{M_t} |\nabla w|^2 dx, \end{aligned}$$

where following [1] we adopt the suggestive notation  $|\nabla U|^p = |\nabla u|^p + |\nabla v|^p$  ( $p \geq 1$ ). This implies (using the interpolation inequality 2.1):

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \int_{M_t} |w|^2 dx + \frac{1}{2} \int_{M_t} |\nabla w|^2 dx \leq c \left( \int_{M_t} |w|^4 dx \right)^{\frac{1}{2}} \left( \int_{M_t} |\nabla U|^4 dx \right)^{\frac{1}{2}} \\ & \leq c \left( \int_{M_t} |w|^2 dx \right)^{\frac{1}{2}} \left( \int_{M_t} |\nabla w|^2 dx \right)^{\frac{1}{2}} \left( \int_{M_t} |\nabla U|^4 dx \right)^{\frac{1}{2}} \\ (3.3) \quad & \leq c \left( \int_{M_t} |w|^2 dx \right) \left( \int_{M_t} |\nabla U|^4 dx \right) + \frac{1}{2} \int_{M_t} |\nabla w|^2 dx, \end{aligned}$$

for a.e.  $t \in [0, T']$ .

From Lemma 3.1 we obtain that  $t \mapsto \int_{M_t} |\nabla w|^4 dx$  is in  $L^1([0, T'])$ ; combined with (3.1), this shows that  $t \mapsto \int_{M_t} |\nabla U|^4 dx$  is also in  $L^1([0, T'])$ . Given that  $w(\cdot, 0) \equiv 0$ , (3.3) and Gronwall's lemma show that  $w = 0$  a.e. in  $M \times [0, T']$ . Now iterate the argument, using monotonicity of the energy.

*Proof of Corollary 1.4.* A few words have to be said, since the theorem only implies  $u = v$  a.e. on  $M \times [0, T]$ . The argument following the statement of lemma 3.1 shows that  $w$  (hence  $u$ ) is in  $\bigcap_{T' < T_0} V_{T'}$  (this would also imply uniqueness, by (ii) in Struwe's theorem 1.1 above). By theorem 4.1 in [1],  $u$  is smooth in  $(0, T(u_0)) \times M$  and at most a finite number of singularities develop at  $T(u_0)$ . Iterating the argument yields the conclusion.

#### 4. Proof of Lemma 3.1

The proof of Lemma 3.1 follows, broadly speaking, the same steps as the arguments in [3] and [4], with some changes. The main difference is that we appeal to linear parabolic existence theory in spaces of the form  $L^p([0, T], L^q(M))$  and  $L^2([0, T], H^{-1}(M))$ , in contrast with the elliptic theory used in [3] and [4].

4.1. Use of the Hodge decomposition

We begin by applying the Hodge decomposition theorem (2.2.1 or 2.2.2) to the 1-forms:

$$(4.1) \quad \begin{aligned} a^{ij} &= u^i du^j - u^j du^i \in \Lambda^1 L^\infty(I, L^2), \quad 1 \leq i, j \leq N + 1, \\ \|a^{ij}\|_{L^\infty(I, L^2)} &\leq c \|du\|_{L^\infty(I, L^2)} \leq c E_0^{\frac{1}{2}}. \end{aligned}$$

In the Hodge decomposition:

$$(4.2) \quad a^{ij} = d\alpha^{ij} + \delta\beta^{ij} + h^{ij} \text{ in } M \times (0, T)$$

we have:

$$(4.3) \quad \|\alpha^{ij}\|_{L^\infty(I, H^1)} + \|\beta^{ij}\|_{L^\infty(I, H^1)} \leq c \|a^{ij}\|_{L^\infty(I, L^2)} \leq c E_0^{\frac{1}{2}}.$$

(measurability in  $t$  is not a problem; for example we could consider the Hodge decomposition in the corresponding Hilbert spaces for  $M \times (0, T)$ , which coincides with the ‘slice-wise’ decomposition above for a.e.  $t \in [0, T]$ , by uniqueness). We will sometimes write 4.2 in the form:

$$(4.4) \quad a^{ij} = \delta\beta^{ij} + \phi^{ij},$$

where  $\phi^{ij} = d\alpha^{ij} + h^{ij} \in L^\infty(I, L^2)$  satisfies  $d\phi^{ij} = 0$  weakly and:

$$(4.5) \quad \|\phi^{ij}\|_{L^\infty(I, L^2)} \leq c(\|\delta\beta^{ij}\|_{L^\infty(I, L^2)} + \|a^{ij}\|_{L^\infty(I, L^2)}) \leq c E_0^{\frac{1}{2}}.$$

From the harmonic map flow equation (1.1) we derive two relations. *First*, denoting by  $\{e_a, a = 1, 2\}$  a local orthonormal frame, we have (using  $|u|^2 = 1$  a.e.):

$$\begin{aligned} u_t^i - \Delta u^i &= \sum_{j,a} (u^i du^j \cdot e_a - u^j du^i \cdot e_a) du^j \cdot e_a \\ &= \sum_{j,a} (a^{ij} \cdot e_a)(du^j \cdot e_a) = \sum_j \langle a^{ij}, du^j \rangle \\ &= \sum_j [\langle \delta\beta^{ij}, du^j \rangle + \langle \phi^{ij}, du^j \rangle], \end{aligned}$$

which we write in abbreviated form:

$$(4.6) \quad u_t - \Delta u = \langle \delta\beta, du \rangle + \langle \phi, du \rangle.$$

*Second*, from:

$$\delta a^{ij} = u^i \Delta u^j - u^j \Delta u^i = u^i u_t^j - u^j u_t^i \in L^2(M \times I)$$

and

$$(4.7) \quad \delta a^{ij} = \Delta \alpha^{ij},$$

which follows from (4.2), we conclude via the Calderón-Zygmund inequality that  $\alpha^{ij} \in L^2(I, H^2(M))$  and:

$$(4.8) \quad \|d\alpha^{ij}\|_{H^1(M_t)} \leq c \|\delta a^{ij}\|_{L^2(M_t)} \leq c \|u_t\|_{L^2(M_t)}$$

for a.e.  $t \in [0, T]$ .

#### 4.2. Rewriting the equation for $w$

We may write for  $v$  an equation analogous to (4.6) for  $u$ :

$$v_t - \Delta v = \langle \delta \eta, dv \rangle + \langle \psi, dv \rangle,$$

where  $\eta \in L^2 L^\infty(I, H^1)$  with  $\|\eta\|_{L^\infty(I, H^1)} \leq cE_0^{\frac{1}{2}}$  and  $\psi = (\psi^{j\bar{j}}) \in L^\infty(I, L^2)$  satisfies  $\|\psi\|_{L^\infty(I, L^2)} \leq cE_0^{\frac{1}{2}}$ . A simple calculation gives for  $w = u - v$ :

$$(4.9) \quad \begin{cases} w_t - \Delta w = \langle \delta \beta, dw \rangle + f, \\ w(\cdot, 0) = 0 \\ w(x, t) = 0, t \in I, x \in \partial M, \end{cases}$$

where

$$f(x, t) = \langle \phi, dw \rangle + \langle \delta(\beta - \eta), dv \rangle + \langle \phi - \psi, dv \rangle.$$

**Claim.**  $f \in L^4(I, L^{\frac{4}{3}}(M))$  and

$$\|f\|_{L^4(I, L^{\frac{4}{3}})} \leq cT^{\frac{1}{4}}E_0 + cE_0^{\frac{3}{4}} \left( \|u_t\|_{L^2(M \times I)}^{\frac{1}{2}} + \|v\|_{L^2(I, H^2)}^{\frac{1}{2}} \right)$$

#### 4.3. Proof of claim

$f$  consists of three terms, which we estimate in turn.

4.3.1. Recall  $\phi^{j\bar{j}} = d\alpha^{j\bar{j}} + h^{j\bar{j}}$ . The  $h^{j\bar{j}}$  are smooth harmonic forms, so:

$$(4.10) \quad \sup_{M_t} |h^{j\bar{j}}| \leq c \|h^{j\bar{j}}\|_{L^2(M_t)} \leq c [\|a^{j\bar{j}}\|_{L^2} + \|d\alpha^{j\bar{j}}\|_{L^2} + \|d\beta^{j\bar{j}}\|_{L^2}] \leq cE_0^{\frac{1}{2}}$$

for a.e.  $t$ . The second inequality follows from (4.2) and the third from (4.3) and the bounds in the Hodge theorem; the first inequality is clear, since the space of harmonic forms is finite-dimensional. Thus for a.e.  $t$ :

$$(4.11) \quad \|\langle h^{j\bar{j}}, dw^i \rangle\|_{L^{4/3}(M_t)} \leq c(\sup_{M_t} |h^{j\bar{j}}|) \|dw^i\|_{L^2(M_t)} \leq cE_0.$$

Now by Hölder's inequality:

$$(4.12) \quad \|\langle d\alpha^{j\bar{j}}, dw^i \rangle\|_{L^{\frac{4}{3}}(M_t)} \leq c \|d\alpha^{j\bar{j}}\|_{L^4(M_t)} \|dw^i\|_{L^2(M_t)}$$

(recall from (4.3) that  $d\alpha^{j\bar{j}} \in H^1(M_t)$ , hence is in  $L^p(M_t)$  for any  $p < \infty$ , a.e. (t)). We now apply the interpolation inequality (2.1) to  $\nabla \alpha^{j\bar{j}}$  and conclude:

$$\begin{aligned} \int_{M_t} |d\alpha^{j\bar{j}}|^4 dx &\leq c \left( \int_{M_t} |\nabla^2 \alpha^{j\bar{j}}|^2 dx \right) \left( \int_{M_t} |d\alpha^{j\bar{j}}|^2 dx \right) \\ &\leq c \|\delta a^{j\bar{j}}\|_{L^2(M_t)}^2 E_0 \quad a.e.(t), \end{aligned}$$

where the second inequality follows from (4.3), the Calderón-Zygmund inequality and (4.7). Combined with (4.8) this gives:



$$(4.13) \quad \int_0^T \left( \int_{M_t} |d\alpha^{ij}|^4 dx \right) dt \leq cE_0 \int_0^T \left( \int_{M_t} |u_t|^2 dx \right) dt = cE_0 \|u_t\|_{L^2(M \times I)}^2.$$

Finally from (4.12) and (4.13) we obtain:

$$(4.14) \quad \int_0^T \|\langle d\alpha^{ij}, dw^i \rangle\|_{L^{\frac{4}{3}}(M_t)}^4 dt \leq cE_0^3 \|u_t\|_{L^2(M \times I)}^2.$$

and from (4.11):

$$\int_0^T \|\langle h^{ij}, dw^i \rangle\|_{L^{\frac{4}{3}}(M_t)}^4 dt \leq cTE_0^4,$$

which combine to give the estimate for the first term in  $f(x, t)$ :

$$(4.15) \quad \|\langle \phi, dw \rangle\|_{L^4(I, L^{\frac{4}{3}})} \leq cT^{\frac{1}{4}}E_0 + c\|u_t\|_{L^2(M \times I)}^{\frac{1}{2}}E_0^{3/4}.$$

4.3.2. For the second term, Hölder's inequality yields:

$$\begin{aligned} \|\langle \delta(\beta - \eta), dv \rangle\|_{L^4(I, M_t)} &\leq \|\delta(\beta - \eta)\|_{L^2(M_t)} \|dv\|_{L^4(M_t)} \quad a.e.(t) \\ &\leq cE_0^{1/2} \|dv\|_{L^4(M_t)}, \end{aligned}$$

using the estimate (4.3) for  $\delta\beta$  and the analogous estimate for  $\delta\eta$ . We also used the fact that  $v \in L^2(I, H^2(M))$  (recall we're assuming that  $v$  is smooth in  $M \times (0, T)$ ). Applying once more the interpolation inequality (2.1) yields:

$$\begin{aligned} \|\langle \delta(\beta - \eta), dv \rangle\|_{L^{4/3}(M_t)}^4 &\leq cE_0^2 \int_{M_t} |dv|^4 dx \\ &\leq cE_0^2 \left( \int_{M_t} |dv|^2 dx \right) \left( \int_{M_t} |\nabla^2 v|^2 dx \right) \quad a.e.(t), \end{aligned}$$

so

$$\int_0^T \|\langle \delta(\beta - \eta), dv \rangle\|_{L^{4/3}(M_t)}^4 dt \leq cE_0^3 \int_0^T \|v\|_{H^2(M_t)}^2 dt.$$

This gives the estimate for the second term in  $f(x, t)$ :

$$(4.16) \quad \|\langle \delta(\beta - \eta), dv \rangle\|_{L^4(I, L^{\frac{4}{3}})} \leq cE_0^{3/4} \|v\|_{L^2(I, H^2)}^{1/2}.$$

4.3.3. The estimate for the third term is similar. Notice that (4.5) for  $\phi$  and the corresponding inequality for  $\psi$  imply  $\phi - \psi \in L^\infty(I, L^2)$  and

$$\|\phi - \psi\|_{L^\infty(I, L^2)} \leq cE_0^{1/2}.$$

This implies, exactly as in 4.3.2:

$$\|\langle \phi - \psi, dv \rangle\|_{L^{4/3}(M_t)}^4 \leq cE_0^3 \|v\|_{H^2(M_t)}^2 \quad a.e.(t),$$

so:

$$(4.17) \quad \|\langle \phi - \psi, dv \rangle\|_{L^4(I, L^{\frac{4}{3}})} \leq cE_0^{3/4} \|v\|_{L^2(I, H^2)}^{1/2}.$$

(4.15), (4.16) and (4.17) prove the claim.

4.4. Decomposition of the ‘most singular’ term in (4.9)

In 4.4 and 4.5 we set  $I = [0, T']$ . Given  $\epsilon > 0$  there exists  $T' \in (0, T)$  such that:

$$\beta = \beta_\epsilon + \beta'_\epsilon$$

where  $\|\beta_\epsilon\|_{L^\infty(I, H^1)} < \epsilon$  and  $\beta'_\epsilon \in C^\infty(I, \Lambda^2(M))$  satisfies:

$$\sup_{M \times [0, T]} |\delta\beta'_\epsilon| \leq cE_0^{1/2}.$$

(Write the decomposition at time zero and note the initial data is achieved in  $H^1$ .) Thus:

$$(4.18) \quad \|\langle \delta\beta'_\epsilon, dw \rangle\|_{L^4(I, L^{\frac{4}{3}})} \leq cT^{1/4}E_0^{1/2} \|dw\|_{L^\infty(I, L^2)} \leq cT^{1/4}E_0.$$

We rewrite (4.9) as:

$$(4.19) \quad \begin{cases} w_t - \Delta w = \langle \delta\beta_\epsilon, dw \rangle + f_\epsilon \\ w(x, \cdot) = 0, \quad x \in \partial M \\ w(\cdot, 0) = 0 \quad \text{in } M, \end{cases}$$

where  $f_\epsilon = f + \langle \delta\beta'_\epsilon, dw \rangle \in L^4(I, L^{\frac{4}{3}})$  (by the claim in 4.2 and (4.18)).

4.5. Conclusion of the proof

We now use Theorem 2.3.2 to show that, for small enough  $\epsilon > 0$ , (4.19) has a unique solution  $\Phi \in L^4_0(I, W^{2,4/3})$  (where we regard  $f_\epsilon$  as given). Observe that (4.19) may be written as (replacing  $w$  by  $\Phi$ ):

$$\Phi - \mathcal{L}(\langle \delta\beta_\epsilon, d\Phi \rangle) = \mathcal{L}(f_\epsilon), \quad \Phi \in L^4_0(I, W^{2,4/3}).$$

Showing that  $\Phi \mapsto \Phi - \mathcal{L}(\langle \delta\beta_\epsilon, d\Phi \rangle)$  is an isomorphism of  $L^4_0(I; W^{2,4/3})$  will establish the existence and uniqueness claimed for (4.19). Let  $\Phi \in L^4_0(I; W^{2,4/3})$ . The Sobolev embedding  $W^{1,4/3}(M) \hookrightarrow L^4(M)$  implies  $d\Phi \in L^4(I; L^4)$ . By Hölder’s inequality we have, for almost every  $t$ :

$$\|\langle \delta\beta_\epsilon, d\Phi \rangle\|_{L^{4/3}(M_t)} \leq c\|\delta\beta_\epsilon\|_{L^2(M_t)} \|d\Phi\|_{L^4(M_t)} \leq c\epsilon \|d\Phi\|_{L^4(M_t)},$$

and hence:

$$\|\langle \delta\beta_\epsilon, d\Phi \rangle\|_{L^4(I; L^{4/3})} \leq c\epsilon \|\Phi\|_{L^4(I; W^{2,4/3})}.$$

Since  $\mathcal{L} : L^4(I; L^{4/3}) \rightarrow L^4_0(I; W^{2,4/3})$  is bounded, choosing  $\epsilon = \epsilon_0$  sufficiently small establishes the claim. (The bound on  $\mathcal{L}$  depends on  $T$  but not on  $T'$ .)

As in [3] and [4] we must also consider problem (4.19) in the Hilbert spaces  $L^2(I; H^s(M))$ . In order to apply theorem 2.3.1, we must verify that  $f_\epsilon \in L^2(I; H^{-1})$  and  $\langle \delta\beta_\epsilon, d\psi \rangle \in L^2(I; H^{-1})$  if  $\psi \in W_0$ . The first assertion follows from  $L^{4/3}(M) \hookrightarrow H^{-1}(M)$  and  $f_\epsilon \in L^4(I; L^{4/3})$ . The second assertion follows from Wentz’s theorem 2.4. Indeed we have, for a.e.  $t$ :

$$\begin{aligned} \|\langle \delta\beta_\epsilon, d\Psi \rangle\|_{H^{-1}(M_t)} &\leq c \|\Psi\|_{H^1(M_t)} \|\delta\beta_\epsilon\|_{H^1(M_t)} \\ &\leq c\epsilon \|\Psi\|_{H^1(M_t)}, \end{aligned}$$

so that:

$$\|\langle \delta\beta_\epsilon, d\Psi \rangle\|_{L^2(I; H^{-1})} \leq c\epsilon \|\Psi\|_{L^2(I; H^1)}.$$

As before, this implies that choosing  $\epsilon = \epsilon_1 < \epsilon_0$  sufficiently small, the map  $\Psi \mapsto \Psi - \mathcal{Q}(\langle \delta\beta_\epsilon, d\Psi \rangle)$  is an isomorphism of  $W_0$ . Equivalently, (4.19) has a unique solution in  $W_0$ . Since both the solution  $\Phi$  obtained in the previous paragraph and the original  $w$  are solutions of (4.19) in  $W_0$  (note  $\Phi_t \in L^4(I; L^{4/3}) \hookrightarrow L^2(I; H^{-1})$ ), it follows that  $\Phi = w$ , hence  $w \in L^4(I, W^{2,4/3}) \subset L^4(I; W^{1,4})$ . This concludes the proof of lemma 3.1, and with it the proof of theorem 1.3.

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