

CONTINUATION OF DIFFEOMORPHISMS
RETAINING VOLUME

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1. In this paper we shall denote by M^m a connected, smooth, orientable, closed manifold of class C^∞ , by W^m its submanifold with smooth boundary ∂W^m , and by ω_0 the volume on M^m . On M^m some metric is fixed, W_i are the connected components of W^m , N_j are the connected components of $M \setminus W$, and id is the identity mapping of M (with this, if A is a subset then $id|_A$ is the identity embedding $A \rightarrow M$). For any region $A \subset M$ we write $\langle \omega, A \rangle = \int_A \omega$; here, ω is a differential m -form. The different families of mappings ($f_t(x)$, $F_t(x)$, etc.) are smooth functions of t and x of class C^∞ ; the exception is the family of diffeomorphisms entering into the lemma.

Let there be a continuous family of embeddings $f_t: \partial W \rightarrow M$, with $f_0 = id|_{\partial W}$; it is known [4] that then f_t can be continued to a family of diffeomorphisms $f_t: M \rightarrow M$, coinciding with f_t on ∂W and with id when $t = 0$; we set $W_t = f_t W$, $W_{it} = f_t W_i$, and $N_{jt} = f_t N_j$.

THEOREM 1. Let the family of embeddings $f_t: \partial W \rightarrow M$ possess the properties: $f_0 = id|_{\partial W}$, $\langle \omega_0, W_i \rangle = \langle \omega_0, W_{it} \rangle$ and $\langle \omega_0, N_j \rangle = \langle \omega_0, N_{jt} \rangle$ for all i and j . Then, there exists a family of diffeomorphisms $F_t: M \rightarrow M$, such that $F_t^* \omega_0 = \omega_0$, with $F_0 = id$ and $F_t|_{\partial W} = f_t$.

LEMMA. There exists a continuous mapping ν of the set of positive definite m -forms ω with identical $\langle \omega, M \rangle = \langle \omega_0, M \rangle$ into $Diff(M)$ such that $\nu(\omega) * \omega = \omega_0$.

Proof of the Lemma. (Actually, we shall repeat the arguments of J. Moser, [1], Theorem 2, although this assertion does not formally appear there.) $\omega_t = (1-t)\omega_0 + t\omega$ is the family of forms. We specify a vector field V_t such that the family of diffeomorphisms $\varphi_t: M \rightarrow M$ defined by it has the property $\varphi_t^* \omega_t = \omega_0$.

We perform the following computations:

$$0 = \frac{d}{dt} \varphi_t^* \omega_t = \varphi_t^* (\dot{\omega}_t + L_{V_t} \omega_t) = \varphi_t^* (\dot{\omega}_t + \text{div}_{V_t} \omega_t)$$

(i denotes inner multiplication and L the Lie derivative). Hence, $\text{div}_{V_t} \omega_t = -\dot{\omega}_t$. Moreover, $\langle \dot{\omega}_t, M \rangle = 0$, so that $\dot{\omega}_t$ is an exact form. By using the expansion given in [2] (§31), we obtain $\text{div}_{V_t} \omega_t = -d\delta G \dot{\omega}_t$. From the equation $i_{V_t} \omega_t = \delta G \dot{\omega}_t$ we uniquely find the field V_t plus the corresponding family of diffeomorphisms φ_t . We have the equation $\varphi_t^* \omega = \omega_0$, i.e., mapping $\nu(\omega) = \varphi_t$ is the one we seek. This mapping is continuous as a mapping of the space of forms with the topology of C^n into the space of diffeomorphisms with the topology C^n , $n = 1, 2, \dots, \infty$. Indeed, G is continuous as a mapping of the space of differential forms of class C^n into the space of forms of class C^{n+1} , so that the mapping $\omega_t \rightarrow V_t$ is continuous as a mapping of a form into a vector field of class C^n ; finally, the continuity of mapping $V_t \rightarrow \varphi_t$ is, in essence, the theorem on the continuous dependence of the solutions of differential equations on the right-hand sides of those equations.

We note in passing that when $n = \infty$ the mapping we obtain is a global section of the fibration constituting the diffeomorphism φ of form $\varphi^* \omega_0$. When $n < \infty$ is not a section of this fibration since if ν is of class C^n we then have the formula $\varphi^* \omega_0$, and this means that $\nu(\varphi^* \omega_0)$ will, in general, be forms of class C^{n-1} . It is possible to consider ν as a section of the fibration the space of which consists of the diffeomorphisms of class C^n with Jacobians of class C^n . It is not hard to deduce from this that this space is the direct product of the space of forms by $Diff(M, \omega_0)$ (the space of diffeomorphisms retain volume ω_0).

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Proof of Theorem 1. We set $\omega_t = (1-t)f_t^{-1*}\omega_0 + t(\bar{f}_1 \circ \bar{f}_t^{-1})^*\omega_0$, where \bar{f}_t is as above; then, $\langle \omega_t, W_{it} \rangle = \langle \omega_0, W_i \rangle, \langle \omega_t, N_{jt} \rangle = \langle \omega_0, N_j \rangle$ and $\omega_1 = \omega_0$. We set $\varphi_t = \nu(\omega_t)^{-1} \circ \bar{f}_t, \bar{N}_{jt} = \varphi_t N_j, \bar{W}_{it} = \varphi_t W_i$. The family of embeddings $\varphi_t|_{\partial W}$ has the properties $\varphi_0 = \bar{f}_0 = \text{id}, \varphi_1 = \bar{f}_1$, so that $\varphi_1|_{\partial W} = f_1, \langle \omega_0, \bar{W}_{it} \rangle = \langle \omega_0, N_{jt} \rangle = \langle \omega_0, N_j \rangle$. Indeed,

$$\langle \omega_0, \bar{N}_{jt} \rangle = \langle \omega_0, \nu(\omega_t)^{-1} N_{jt} \rangle = \langle \nu(\omega_t)^{-1*} \omega_0, N_{jt} \rangle = \langle \omega_t, N_{jt} \rangle = \langle \omega_0, N_j \rangle.$$

We now proceed to the construction of F_t . On $\varphi_t \partial W$ we define the vector field $V_t(\varphi_t x) = \frac{d}{ds} \Big|_{s=0} \varphi_{t+sx}$. In a ε -neighborhood of ∂W we introduce coordinate y transversal to ∂W . We continue field V_0 in this neighborhood in the following way: $V_{0x}(x, y) = V_{0x}(x)$, and we find $V_{0y}(x, y)$ from the equation $\text{div}_0 \omega_0 = 0$ with the initial condition $V_{0y}(x)$. By an analogous construction we proceed in $\varphi_t U_\varepsilon \partial W$. We obtain the closed $(n-1)$ -form $i_{V_t} \omega_0$ in the corresponding neighborhoods of manifolds $\varphi_t \partial W$. It remains to construct the family of closed forms w_t on M coinciding with $i_{V_t} \omega_0$ in some neighborhood of manifold $\varphi_t \partial W$.

Let $\{z_h\}$ be the nonzero generators of $H_{n-1}(M, \mathbf{R})$ lying in $\varphi_t U_\varepsilon \partial W$ (i.e., of $H_{n-1}(\partial W, \mathbf{R})$). There exists on M a unique harmonic form ω_h , such that $\langle \omega_h, z_h \rangle = 1$ and $\langle \omega_h, z \rangle = 0$ for all other cycles not depending on z_h . The cycles of $H_{n-1}(\varphi_t U_\varepsilon \partial W, \mathbf{R})$, not depending on $\{z_h\}$, are formed by the boundaries \bar{N}_{jt} and \bar{W}_{it} . The values of $i_{V_t} \omega_0$ on them equal zero since

$$\langle i_{V_t} \omega_0, \partial \bar{N}_{jt} \rangle = \langle \text{div}_t \omega_0, \bar{N}_{jt} \rangle \langle L_{V_t} \omega_0, \bar{N}_{jt} \rangle = \frac{d}{ds} \Big|_{s=t} \langle (\varphi_s \circ \varphi_t^{-1})^* \omega_0, \bar{N}_{jt} \rangle = 0$$

The form $\alpha_t = i_{V_t} \omega_0 - \sum_h \langle i_{V_t} \omega_0, z_h \rangle \omega_h$ has zero period and, consequently, is exact on $\varphi_t U_\varepsilon \partial W$. Let $g_s : \varphi_t U_\varepsilon \partial W \rightarrow \varphi_t U_\varepsilon \partial W$ be a mapping which, in terms of the coordinates introduced above, is such that $g_s(x, y) = (x, sy)$. We construct an operator on the forms ψ

$$k\psi = \int_0^1 \frac{y}{s} i_{d/dy} g_s^* \psi ds.$$

Standard computations in the local coordinates show that $k d\alpha_t + d k\alpha_t = \alpha_t - g_0^* \bar{\alpha}_t$, where $\bar{\alpha}_t = (\text{id}|_{\varphi_t \partial W})^* \alpha_t$ is an $(m-1)$ -form of zero periods on the closed manifold $\varphi_t \partial W$. Using the expansion of [2] (§ 31), we obtain $\alpha_t = dk\alpha_t + dg_0^* \delta G \bar{\alpha}_t$. Let $p(y)$ be a smooth function equal to 1 when $|y| \leq (\varepsilon/2)$ and equal to 0 when $|y| \geq \varepsilon$, so that then the $(m-1)$ -form

$$\omega_t = \sum_h \langle i_{V_t} \omega_0, z_h \rangle \omega_h + d[p(y)(k\alpha_t + g_0^* \delta G \bar{\alpha}_t)]$$

is closed, is defined on M , and coincides with $i_{V_t} \omega_0$ in $\varphi_t U_{\varepsilon/2} \partial W$. In terms of it we uniquely reconstitute vector field V_t and "motions" F_t , coinciding with φ_t on ∂W and retaining volume ω_0 by virtue of the closure of w_t .

By analogous and, in part, simpler arguments we prove

THEOREM 2. Let the family of embeddings $f_t : W \rightarrow M$ have the properties: $f_0 = \text{id}|_W, f_t^* \omega_0 = \omega_0$ and $\langle \omega_0, N_{jt} \rangle = \langle \omega_0, N_j \rangle$. Then, there exists a family of diffeomorphisms $F_t : M \rightarrow M$ such that $F_t^* \omega_0 = \omega_0$ and $F_t|_W = f_t$.

Finally, for some connected components of manifold W one can specify "motions" $f_t : W_i \rightarrow M$, of their boundaries $f_t : \partial W_i \rightarrow M$.

Remark. An important special case is when W is the set of "balls" D_i^m on closed manifold M^m , with $m > 1$. Theorem 1 asserts that for any two sets, D_i and \bar{D}_i , with identical volumes of the corresponding "balls" there exists a motion M retaining volume and translating D_i into \bar{D}_i .

This assertion is also true in the case of nonclosed M , which strengthens Lemma 1.1 of [5]. Indeed, let $\varphi_t : \partial W \rightarrow M$ be an arbitrary family of embeddings taking ∂D_i into $\partial \bar{D}_i$. In M we choose a compact manifold with boundary N such that $N \supset D_{it}$ for all i and t . Splicing boundary N and that of the manifold N' we can obtain a smooth closed manifold (double). On the union of N' and $\cup \partial D_i$ we specify a family of embeddings f_t as follows: $f_t|_{N'} = \text{id}$ and $f_t|_{\partial D_i} = \varphi_t$. In view of what was said above there exist a motion Φ_t of the closed manifold such that $\Phi_t^* \omega_0 = \omega_0, \Phi_t D_i = \bar{D}_i$ and $\Phi_t|_{N'} = \text{id}|_{N'}$. Then, the F_t we have been seeking is defined by: F_t on N coincides with Φ_t and $F_t = \text{id}$ outside N .

2. We set $\langle \omega_0, W_i \rangle = a_i$, $\langle \omega_0, N_j \rangle = b_j$, $a = \{a_i\}$, $b = \{b_j\}$. If the embeddings $f: W \rightarrow M$ or $f: \partial W \rightarrow M$ are diffeotopically identical we have then uniquely defined $W_i(f) = \bar{f}W_i$, $N_j(f) = \bar{f}N_j$, where $\bar{f}: M \rightarrow M$ is related to id by means of the diffeotopy continuing the diffeotopy connecting f with id|W or with id|\partial W. (It is clear then $N_j(f)$ does not depend on the choice of the continuation.)

We introduce the following topological spaces with C^∞ -topology:

$E_{ab}(W, M)$ is the set of embeddings $f: W \rightarrow M$ diffeotopic to id|W and with properties 1) $\langle \omega_0, W_i(f) \rangle = a_i$; 2) $\langle \omega_0, N_j(f) \rangle = b_j$;

$E_{ab}(W, M, \omega_0)$ is the set of embeddings $f: W \rightarrow M$, diffeotopic to id|W and with properties 1, 2, and 3) $f^*\omega_0 = \omega_0$;

$E_{ab}(\partial W, M)$ is the set of embeddings $f: \partial W \rightarrow M$, diffeotopic to id|\partial W and satisfying conditions 1) and 2);

$E_a(W, M)$ and $E_a(\partial W, M)$ are the corresponding sets of $E_{ab}(W, M)$ and $E_{ab}(\partial W, M)$ extended by dropping condition 2).

The following mappings arise:

$$\begin{array}{ccccc} \text{Diff}_0(M, \omega_0) & \text{Diff}(M, \omega_0) & E_{ab}(W, M) & E_{ab}(W, M, \omega_0) & E_a(W, M) \\ \downarrow \pi & \downarrow \pi & \downarrow \pi & \downarrow \pi & \downarrow \pi \\ E_{ab}(\partial W, M) & E_{ab}(W, M, \omega_0) & E_{ab}(\partial W, M) & E_{ab}(\partial W, M) & E_a(\partial W, M) \end{array}$$

(here, Diff_0 is the connected component of id in Diff, and π restriction mapping on, respectively, W or ∂W).

THEOREM 3. The triple $(\text{Diff}_0(M, \omega_0), E_{ab}(\partial W, M), \pi)$ is a locally trivial fibration.

Proof. Our goal is the construction of a local section, i.e., a continuous mapping η of some neighborhood $Uf_0 \in E_{ab}(\partial W, M)$ in $\text{Diff}_0(M, \omega_0)$ such that $\eta(f) \circ f = f_0$ for all f of Uf_0 . With no loss of generality we can assume that $f_0 = \text{id}|\partial W$. Denoting the exponential geodesic mapping by exp, we construct the homotopy $f_t(x) = \exp_x(\exp_x^{-1}(f(x)))$, joining f_0 and $f_1 = f$. It is known from Theorem 1 that there exists a family of diffeomorphisms F_t retaining ω_0 and such that $F_0 = \text{id}$ and $F_1|\partial W = f$. In the construction of F_t there is an indeterminacy in the choice of $\bar{f}_t: M \rightarrow M$, the continuation of f_t . It can be eliminated by using the local section $\chi: Uf_0 \rightarrow \text{Diff}_0(M)$, constructed by R. Palais in [3] (section 4). We set $\bar{f}_t = \chi(f_t)$, by which there will be defined on Uf_0 the continuous mapping $\eta(f) = F_1$, q.e.d.

It immediately follows from Theorem 3 that the triples $(E_{ab}(W, M), E_{ab}(\partial W, M), \pi)$ and $(E_{ab}(W, M, \omega_0), E_{ab}(\partial W, M), \pi)$ are locally trivial fibrations. By similar methods we prove the local triviality of the fibration $(\text{Diff}_0(M, \omega_0), E_{ab}(W, M, \omega_0), \pi)$.

THEOREM 4. The triple $(E_a(W, M), E_a(\partial W, M), \pi)$ is a locally trivial fibration.

Proof. For a sufficiently small neighborhood Uf_0 there exist "balls" $D_{\rho j}$ of radius ρ such that $D_{\rho j} \subset N_j(f)$ for all f of Uf_0 . We put into correspondence with each $f \in Uf_0$

$$\omega(f) = \begin{cases} \omega_0 & \text{outside } \bigcup_j D_{\rho j}, \\ \omega_0 + c_j(f) p_j(x) \omega_0 & \text{in } D_{\rho j}, \end{cases}$$

where $p_j(x)$ is a smooth function, equal to 1 in $D_{\frac{\rho}{2} j}$ and equal to 0 outside $D_{\rho j}$, while the $c_j(f)$ are found

from the equation $\langle \omega(f), N_j(f) \rangle = \langle \omega_0, N_j(f_0) \rangle$. Using the lemma, we obtain the mapping $\xi: Uf_0 \rightarrow \text{Diff}_0(M)$, where $\xi(f) = \nu(\omega(f))$ and $\xi(f)^*\omega(f) = \omega_0$. Embedding $\xi(f)^{-1} \circ f_0$ belongs to $E_{ab}(\partial W, M)$. Using the local section η , constructed for the proof of Theorem 3, we get $\eta(\xi(f)^{-1} \circ f) \circ \xi(f_0)^{-1} \circ f_0 = \xi(f)^{-1} \circ f$ or $\xi(f) \circ f_0 = f$, where $\xi(f) = \xi(f) \circ \eta(\xi(f)^{-1} \circ f) \circ \xi(f_0)^{-1}$ is a mapping of Uf_0 in the set of diffeomorphisms M leaving volume W invariant. Thus, the local section is constructed.

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