

A Classification of a Random Walk Defined on a Finite Markov Chain

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1. Introduction

Let Y_1, Y_2, \dots be independent and identically distributed random variables (i.i.d. random variables). If Y_k is real valued then $S_n = \sum_1^n Y_k$ is a random walk on the real line. It is well known, see Feller [4, p.395] that such a random walk belongs to exactly one of the following four categories,

- (i) $\lim_n S_n = \infty$ a.s.
- (ii) $\lim_n S_n = -\infty$ a.s.
- (iii) $\overline{\lim}_n S_n = +\infty, \underline{\lim}_n S_n = -\infty$ a.s.
- (iv) For all $n, S_n = 0$ a.s.

To each random walk there is associated a random variable $N = \inf\{n > 0; S_n > 0\}$, the hitting time to the positive half-line, and also a random variable N^- , the hitting time to the negative half-line. It is also well known that those random walks which belong to category (i) above are precisely those for which N is a proper random variable and N^- is improper. Similar statements can be made concerning categories (ii), (iii) and (iv). Spitzer [12, p.189] developed a necessary and sufficient condition for N to be a proper random variable, namely, the divergence of the series $\sum_1^\infty n^{-1} P(S_n > 0)$.

The object of this paper is to generalise the above results to the situation where the distribution of the increment Y_k depends on the states X_{k-1} and X_k of an underlying ergodic finite state Markov chain $\{X_n\}$.

This type of random walk has been previously studied by Miller [8, 9] and Keilson and Wishart [5, 6] and [7]. A basic difference in this paper from these references is that we do not assume the existence of means for the increments Y_k . We note that if Z_k is the sum of the increments between the k -th and $(k+1)$ -st occurrence of the state j in the underlying chain, then $\{Z_k: k=1, \dots\}$ are i.i.d. random variables. The methods used in this paper rely heavily on this remark.

2. Preliminaries

Before beginning a description of the process under consideration we shall state the following facts for completeness and future reference. Y_1, Y_2, \dots are i.i.d. random variables and $S_n = \sum_1^n Y_k$.

Theorem A. *The random walk S_n falls into exactly one of the following four categories.*

- (i) $\lim_n S_n = \infty$ a.s.
- (ii) $\lim_n S_n = -\infty$ a.s.
- (iii) $\overline{\lim}_n S_n = \infty, \underline{\lim}_n S_n = -\infty$ a.s.
- (iv) For all $n, S_n = 0$ a.s.

In the following $N = \inf\{n > 0: S_n > 0\}$ is the hitting time to the positive half-line.

Lemma B. *N is a proper random variable if and only if $\overline{\lim}_n S_n = +\infty$ a.s.*

Theorem C. *N is a proper random variable if and only if $\sum_1^\infty n^{-1} P(S_n > 0) = \infty$.*

The process considered in this paper consists of a discrete Markov chain with finite state space $\{1, 2, \dots, m\}$ called the X -process, taking values $X_0, X_1, \dots, X_n, \dots$. Throughout this paper the Markov chain will be ergodic in the sense of Feller [3]. Alongside the X -process is a real valued process called the Y -process which proceeds $Y_0, Y_1, \dots, Y_n, \dots$ where $Y_0 = 0$, and for $n \geq 1$, the distribution of Y_n depends on X_{n-1} and X_n . It follows that given the random variables $\{X_0, \dots, X_n\}$, the random variables $\{Y_1, \dots, Y_n\}$ are conditionally independent. Our main concern is the study of the S -process which proceeds $S_0, S_1, \dots, S_n, \dots$ where $S_n = \sum_0^n Y_k$. The S -process is known as a *random walk defined on the Markov chain*.

To make this description precise we follow Pyke [10]. Let $Q = (Q_{ij})$ be a matrix valued function on $(-\infty, \infty)$ such that for $i = 1, \dots, m, \sum_{j=1}^m Q_{ij}(\infty) = 1$.

The (X, Y) -process is defined to be any two-dimensional stochastic process $\{(X_n, Y_n); n \geq 0\}$ defined on a complete probability space $(\Omega, \mathfrak{F}, P)$ which satisfies

- (i) $Y_0 = 0$ a.s.
- (ii) $P\{X_n = k, Y_n \leq x | \mathfrak{F}_{n-1}\} = Q_{X_{n-1}k}(x)$ a.s. for $n \geq 1$ where \mathfrak{F}_n denotes the σ -algebra generated by $\{X_0, \dots, X_n, Y_0, \dots, Y_n\}$. It should be noted that the X -process is a Markov chain with m states and has transition matrix $Q(\infty)$. As mentioned previously we shall also assume that the Markov chain is ergodic. If we let $S_n = \sum_0^n Y_k$ then the (X, S) -process is a bivariate Markov chain $\{(X_n, S_n); n \geq 0\}$ such that

$$P\{X_n = k, S_n \leq x | \mathfrak{F}_{n-1}\} = Q_{X_{n-1}k}(x - S_{n-1}).$$

The (X, S) -process with semi-Markov transition function Q is called the *Markov additive process with kernel Q* . This terminology follows that used by Çinlar [2] in the continuous time case.

Before stating the first lemma we make a few remarks. In some respects the value of X_0 affects the behaviour of the S -process. This can be illustrated by noting that whether the hitting time to the positive half-line is a proper random variable or not may depend on the value of X_0 . We will return to this later in the paper. The distribution of X_0 remains unspecified and we will deal with proba-

bilities conditional on X_0 . With this in mind, relative to $(\Omega, \mathfrak{F}, P)$, we denote $P\{\cdot | X_0 = i\}$ by $P_i\{\cdot\}$. Throughout the paper N and τ with and without subscripts and superscripts will denote stopping times.

In this paper the following lemma plays a crucial role. It is a generalisation of a result of Chung [1, p. 78] which states that if $\{X_n\}$ is a Markov chain and f a function from the state space of the chain to the real line then $\sum_{n=\tau_k+1}^{\tau_{k+1}} f(X_n)$, $k > 0$, are i.i.d. random variables, where τ_k , $k > 0$, are the times of successive occurrences of the state j in the Markov chain.

To simplify the statement of our lemma we introduce the following notation. Let $\{j_1, \dots, j_r\}$ be a sequence of states of the state space $\{1, \dots, m\}$. We define inductively the sequence of stopping times $\{\tau_k: k = 1, \dots, r\}$ by

$$\begin{aligned} \tau_1 &= \inf \{n \geq 0: X_n = j_1\}, \\ \tau_k &= \inf \{n > \tau_{k-1}: X_n = j_k\}, \quad k = 2, \dots, r. \end{aligned}$$

Let $Z_k = S_{\tau_{k+1}} - S_{\tau_k}$, $k = 1, \dots, r - 1$. With the above notation we have:

Lemma 1. $\{Z_k: k = 1, \dots, r - 1\}$ is a set of independent random variables.

The proof of this is an immediate consequence of the strong Markov property for the bivariate Markov chain $\{(X_n, S_n); n \geq 0\}$. We remark also that if $j_1 = j_2 = \dots = j_r$, then the random variables are identically distributed. In future we shall often refer to Z_1 as the increment from a (j_1, j_2) -block or simply a j_1 -block if $j_1 = j_2$.

3. Classification of the Random Walk

In our classification of the random walk defined on the chain, category (iv) of Theorem A is replaced by a modification of the idea of degeneracy introduced by Miller [8].

If $Q_{ij}(\infty) > 0$ then we let

$$F_{ij}(x) = \frac{Q_{ij}(x)}{Q_{ij}(\infty)} = P(Y_n \leq x | X_{n-1} = i, X_n = j).$$

Definition. The process (X, S) is *degenerate* if there exists constants $\beta_1 \dots \beta_m$ such that whenever $Q_{ij}(\infty) > 0$ it follows that F_{ij} is the distribution function of a degenerate random variable which takes the value $\beta_j - \beta_i$ a.s. This modification of Miller's definition rules out the possibility of an overall drift of the S -process. It follows that if $X_0 = i$ and $X_n = j$ then $S_n = \beta_j - \beta_i$. We are now in a position to state the analogue of Theorem A for the random walk defined on a Markov chain.

Theorem 1. For a random walk defined on a finite state ergodic Markov chain there are four mutually exclusive possibilities:

- (i) $\lim_n S_n = +\infty$ a.s.
- (ii) $\lim_n S_n = -\infty$ a.s.
- (iii) $\overline{\lim}_n S_n = +\infty$, $\underline{\lim}_n S_n = -\infty$ a.s.
- (iv) The (X, S) -process is degenerate.

Before giving a proof of the theorem we will state and prove the following lemmas.

Lemma 2. *If for some j the increment from a j -block equals zero a.s. then the (X, S) -process is degenerate.*

Proof. Let j be as above and fix i . We consider adjacent (i, j) and (j, i) -blocks having increments W_{ij} and W_{ji} respectively. Now W_{ij} and W_{ji} are independent random variables and $P(W_{ji} + W_{ij} = 0) = 1$. It follows that there exists a constant C_{ij} such that

$$P(W_{ij} = C_{ij}) = P(W_{ji} = -C_{ij}) = 1.$$

Similarly there exists constants C_{kj} for $k = 1, \dots, m$. If we now consider adjacent (j, k) , (k, l) and (l, j) blocks with increments W_{jk} , W_{kl} and W_{lj} respectively where $k, l \neq j$ then we see that

$$P(W_{kl} = -C_{jk} - C_{lj}) = 1 \quad \text{where } C_{jk} = -C_{kj}.$$

Let us denote by C_{kl} the value $(-C_{jk} - C_{lj})$. By similarly considering a (l, k) -block we can say that for all l and k the increment from a (l, k) -block is a degenerate random variable taking the value C_{lk} and moreover $C_{lk} = -C_{kl}$.

Let us now suppose that a certain $l \rightarrow k$ transition is possible and denote by Y_{lk} the increment associated with such a transition. Now $l \rightarrow k$ is a particular realisation of an (l, k) -block and therefore $Y_{lk} = C_{lk}$ a.s.

Define β_1, \dots, β_m as follows:

$$\begin{aligned} \beta_1 &= C \quad \text{an arbitrary constant,} \\ \beta_r &= C_{r1} + \beta_1 = C_{r1} + C \quad \text{for } r = 2, \dots, m. \end{aligned}$$

It is immediate that

$$C_{1l} + C_{lk} + C_{k1} = C_{11}$$

from which it follows that

$$C_{lk} = C_{11} + C_{1l} - C_{k1} = 0 + (\beta_l - \beta_1) - (\beta_k - \beta_1) = \beta_l - \beta_k.$$

Hence

$$Y_{lk} = \beta_l - \beta_k \quad \text{a.s.}$$

This completes the proof.

The sequence $\{S_n: n \geq 1\}$ is said to be *dominated* if there exists a finite valued function M such that for all $n: |S_n| \leq M$ a.s.

Lemma 3. *The process (X, S) is degenerate if and only if the sequence $\{S_n: n \geq 1\}$ is dominated.*

Proof. If the process is degenerate then since $\sup_n S_n = \max_{i,j} (\beta_i - \beta_j)$ it follows that $\{S_n: n \geq 1\}$ is dominated. Conversely we suppose $\{S_n: n \geq 1\}$ is dominated. Now for a fixed j we define the following sequence of stopping times $\{\tau_k: k \geq 0\}$ by

$$\tau_0 = 0, \quad \tau_k = \inf\{n > \tau_{k-1}: X_n = j\}, \quad k > 0.$$

If we let $Z_k = S_{\tau_{k+1}} - S_{\tau_k}$, $k = 0, 1, \dots$ then $S_{\tau_n} = Z_0 + \sum_{k=1}^{n-1} Z_k$. From Lemma 1 we see that Z_k , $k = 1, 2, \dots$ are i.i.d. random variables and since $\{S_{\tau_n}: n \geq 1\}$ is dominated

and Z_0 is finite a.s. it follows from Theorem A that $P(Z_k=0)=1$ for $k=1, 2, \dots$. Now Z_k is the increment from a j -block therefore by Lemma 2 we see that the (X, S) -process is degenerate, and the Lemma is proved.

In view of the next Lemma, now is an opportune time to elaborate further the importance of the value of X_0 , the initial position of the chain. To do this we define the two stopping times

$$N = \inf\{n > 0; S_n > 0\}, \quad N^- = \inf\{n > 0; S_n < 0\}.$$

If for all i we have $P_i(N < \infty) = 1$ then we say that N is *totally proper*. It is important to note that if $P_i(N < \infty) = 1$ for some i then it does not necessarily follow that N is totally proper. This can be seen in the following example.

Let

$$H_a(x) = \begin{cases} 0 & \text{if } x < a \\ 1 & \text{if } x \geq a \end{cases}$$

and we will consider the (X, S) -process in which the X -process is a 2 state Markov chain and the semi-Markov transition function $Q(x)$ is of the form

$$Q(x) = \begin{pmatrix} p H_0(x) & q H_d(x) \\ r H_b(x) & s H_c(x) \end{pmatrix}$$

where $p, q, r, s, d > 0$ and $b, c < -d$. It can be seen that $P_1(N < \infty) = 1$ but $P_2(N < \infty) = 0$.

In some respects however the value of X_0 does not affect the process. For example if $\overline{\lim} S_n = \infty$ a.s. P_i then $\overline{\lim} S_n = \infty$ a.s. P_j for all j . We are now able to state the following lemma.

Lemma 4. N is totally proper if and only if $\overline{\lim}_n S_n = \infty$ a.s.

Proof. If $\overline{\lim}_n S_n = \infty$ a.s. then it is obvious that N is totally proper. Conversely if N is totally proper then we define the sequence of stopping times $\{\tau_k; k \geq 0\}$ inductively by

$$\tau_0 = 0, \quad \tau_k = \inf\{n > \tau_{k-1}; S_n > S_{\tau_{k-1}}\}, \quad k > 0.$$

By assumption each τ_k is a proper random variable and moreover $\lim_k S_{\tau_k} = \infty$ a.s. It follows from this that $\lim S_n = \infty$ a.s.

Theorem 1 is now an immediate corollary from the following theorem.

Theorem 2. (i) N and N^- are both totally proper if and only if $\overline{\lim}_n S_n = +\infty$ a.s. and $\underline{\lim}_n S_n = -\infty$ a.s.

(ii) N is totally proper and N^- is not totally proper if and only if $\lim_n S_n = \infty$ a.s.

(iii) N is not totally proper and N^- is totally proper if and only if $\lim_n S_n = -\infty$ a.s.

(iv) Neither N nor N^- is totally proper if and only if the (X, S) -process is degenerate.

Proof. (i) This is immediate from Lemma 4.

(ii) Assume N is totally proper and N^- is not totally proper. For each j we define the following sequence of stopping times $\{\tau_k^j: k > 0\}$ by

$$\begin{aligned} \tau_1^j &= \inf\{n: X_n = j\}, \\ \tau_k^j &= \inf\{n > \tau_{k-1}^j: X_n = j\}, \quad k > 1. \end{aligned}$$

If we let $Z_k^j = S_{\tau_{k+1}^j} - S_{\tau_k^j}$ then τ_k^j is the time of the k -th occurrence of the state j in the Markov chain and Z_k^j is the increment from the k -th j -block. We further define for each j the stopping time N_j to be

$$N_j = \inf\{k > 1: S_{\tau_k^j} > S_{\tau_1^j}\}.$$

Similarly we define $N_j^- = \inf\{k > 1: S_{\tau_k^j} < S_{\tau_1^j}\}$.

It follows from Lemma 4 that $\overline{\lim}_n S_n = +\infty$ a.s. If we suppose that N_j^- is proper for some j then by Lemma B $\underline{\lim}_k S_{\tau_k^j} = -\infty$ a.s. therefore $\underline{\lim}_n S_n = -\infty$ a.s. and this contradicts, by use of Lemma 4, the fact that N^- is not totally proper. Hence N_j^- is improper for all j . If we now assume that N_j is improper for some j then by Theorem A $Z_k^j = 0$ a.s. and by application of Lemma 2 we see that the process is degenerate. This is also a contradiction therefore N_j is proper for all j . By further application of Lemma B we see that for all j $\lim_k S_{\tau_k^j} = \infty$ a.s. whereby it follows that $\lim_n S_n = \infty$ a.s.

Conversely we assume $\lim_n S_n = \infty$ a.s. The conclusion is a direct consequence of Lemma 4.

(iii) This is proved in a similar manner as (ii).

(iv) If N and N^- are both not totally proper then we show as in part (ii) that N_j and N_j^- are improper for all j .

Whence it follows that $Z_k^j = 0$ a.s. for all j . The fact that (X, S) is degenerate follows by appealing to Lemma 2. If conversely the process (X, S) is degenerate then the fact that N and N^- are both not totally proper is immediate from parts (i), (ii), (iii) and Lemma 3.

4. A Criterion

The aim in this section is to generalize Theorem C to the Markov additive process (X, S) . We will prove,

Theorem 3. *Let (X, S) be a Markov additive process in which the Markov chain $\{X_n\}$ is ergodic with a finite state space. A necessary and sufficient condition for N to be totally proper is that*

$$\sum_1^\infty n^{-1} P_i(S_n > 0) = \infty \quad \text{for all } i.$$

Before giving a proof we need the following two lemmas.

Lemma 5. Let Y, Z_1, Z_2, \dots be a sequence of independent random variables such that Z_1, Z_2, \dots are also identically distributed and let $S_n = \sum_1^n Z_i$. If $\sum_1^\infty n^{-1} P(S_n > 0) = \infty$ then $\sum_1^\infty n^{-1} P(S_n + Y > 0) = \infty$.

Proof. We denote by $F(x)$ the distribution function of Y . Now

$$\begin{aligned} \sum_1^\infty n^{-1} P(Y + S_n > 0) &= \sum_1^\infty n^{-1} \int_{-\infty}^\infty P(S_n > -x) dF(x) \\ &= \int_{-\infty}^\infty \left(\sum_1^\infty n^{-1} P(S_n > -x) \right) dF(x) = \int_{-\infty}^\infty c(x) dF(x) \end{aligned}$$

where $c(x) = \sum_1^\infty n^{-1} P(S_n > -x)$.

By application of Theorem 1 of a paper by Rosén [11, p. 324] which states that there is a constant A such that $P\{S_n \in (0, x)\} \leq A n^{-\frac{1}{2}}$, we see that for $x > 0$

$$\sum_1^\infty n^{-1} P(S_n \in (0, x)) \leq \sum_1^\infty n^{-\frac{3}{2}} A < \infty \quad \text{where } A \text{ is a constant.}$$

Since $c(0) = \infty$ it follows that $c(x) = \infty$ for all finite x . Thus the result follows.

We now let τ_k^j be as in Section 3, namely the time of the k -th occurrence of state j . With this notation we have:

Lemma 6. If for some j , $\sum_{k=1}^\infty k^{-1} P_i(S_{\tau_k^j} > 0) = \infty$, then $\sum_1^\infty n^{-1} P_i(S_n > 0) = \infty$.

Remark. As a consequence of this lemma we see that to prove the divergence of the series $\sum_1^\infty n^{-1} P_i(S_n > 0)$ it is sufficient to show that for some j , the imbedded series, namely the series obtained by considering the process only when the chain is in state j , diverges.

Proof. The $\tau_1^j, \tau_2^j - \tau_1^j, \tau_3^j - \tau_2^j, \dots$ are independent random variables and with the exception of τ_1^j they are also identically distributed. Here we are assuming the initial state i is not necessarily equal to j . Since the Markov chain is ergodic the above random variables have finite means and variances.

Let

$$c = \max \{E_i(\tau_1^j), E_i(\tau_2^j - \tau_1^j)\} + 1$$

and

$$\sigma^2 = \max \{\text{Var}_i(\tau_1^j), \text{Var}_i(\tau_2^j - \tau_1^j)\}.$$

Our initial aim is to show

$$\sum_{k=1}^\infty (ck)^{-1} \sum_{n > ck} P_i(S_{\tau_k^j} > 0, \tau_k^j = n) < \infty. \tag{1}$$

Now

$$\begin{aligned}
 \sum_{k=1}^{\infty} (ck)^{-1} \sum_{n>ck} P_i(S_{\tau_k^j} > 0, \tau_k^j = n) &\leq \sum_{k=1}^{\infty} (ck)^{-1} \sum_{n>ck} P_i(\tau_k^j = n) \\
 &= \sum_{k=1}^{\infty} (ck)^{-1} P_i(\tau_k^j > ck) \\
 &= \sum_{k=1}^{\infty} (ck)^{-1} P_i\{\tau_k^j - E_i(\tau_k^j) > ck - E_i(\tau_k^j)\} \\
 &\leq \sum_{k=1}^{\infty} (ck)^{-1} P_i(\tau_k^j - E_i(\tau_k^j) > k) \\
 &\hspace{15em} \text{this follows by definition of } c \\
 &\leq \sum_{k=1}^{\infty} (ck)^{-1} \sigma^2 k^{-1} < \infty.
 \end{aligned}$$

The last step follows by application of Čebyšev’s inequality. This proves (1). Now

$$\begin{aligned}
 \sum_1^{\infty} n^{-1} P_i(S_n > 0) &= \sum_{n=1}^{\infty} \sum_{k=1}^n \sum_{l=1}^m n^{-1} P_i(S_n > 0, \tau_k^l = n) \\
 &\geq \sum_{k=1}^{\infty} \sum_{n=k}^{\infty} n^{-1} P_i(S_{\tau_k^j} > 0, \tau_k^j = n) \\
 &\geq \sum_{k=1}^{\infty} \sum_{ck \geq n \geq k} n^{-1} P_i(S_{\tau_k^j} > 0, \tau_k^j = n) \\
 &\geq \sum_{k=1}^{\infty} (ck)^{-1} \sum_{ck \geq n \geq k} P_i(S_{\tau_k^j} > 0, \tau_k^j = n) \\
 &= \sum_{k=1}^{\infty} (ck)^{-1} \sum_{n=k}^{\infty} P_i(S_{\tau_k^j} > 0, \tau_k^j = n) - \sum_{k=1}^{\infty} (ck)^{-1} \sum_{n>ck} P_i(S_{\tau_k^j} > 0, \tau_k^j = n) \\
 &= \frac{1}{c} \sum_{k=1}^{\infty} k^{-1} P_i(S_{\tau_k^j} > 0) - \sum_{k=1}^{\infty} (ck)^{-1} \sum_{n>ck} P_i(S_{\tau_k^j} > 0, \tau_k^j = n).
 \end{aligned}$$

It follows from (1) and the assumption of the lemma that $\sum_1^{\infty} n^{-1} P_i(S_n > 0) = \infty$. We are now in a position to prove the theorem.

Proof of Theorem 3. Assume N is totally proper. Let $X_0 = i$ be fixed and N_j be as in Theorem 2 namely

$$N_j = \inf\{k > 1 : S_{\tau_k^j} > S_{\tau_1^j}\}.$$

By the argument used in Theorem 2 it follows that N_j is proper for some j . An application of Theorem C yields the fact that $\sum_{k=1}^{\infty} k^{-1} P_i(S_{\tau_k^j} - S_{\tau_1^j} > 0) = \infty$ for that particular j . From Lemma 5 we obtain

$$\sum_{k=1}^{\infty} k^{-1} P_i(S_{\tau_k^j} > 0) = \infty.$$

The conclusion that $\sum_1^{\infty} n^{-1} P_i(S_n > 0) = \infty$ is now an immediate consequence of Lemma 6.

Conversely assume that $\sum_1^\infty n^{-1} P_i(S_n > 0) = \infty$ for all i . Let i be arbitrary but fixed. Then

$$\begin{aligned} \sum_1^\infty n^{-1} P_i(S_n > 0) &= \sum_{n=1}^\infty \sum_{k=1}^n \sum_{j=1}^m n^{-1} P_i(S_n > 0, n = \tau_k^j) \\ &= \sum_{j=1}^m \sum_{k=1}^\infty \sum_{n=k}^\infty n^{-1} P_i(S_{\tau_k^j} > 0, \tau_k^j = n) \\ &\leq \sum_{j=1}^m \sum_{k=1}^\infty k^{-1} P_i(S_{\tau_k^j} > 0). \end{aligned}$$

It follows that at least one of the series $\sum_{k=1}^\infty k^{-1} P_i(S_{\tau_k^j} > 0) j = 1, \dots, m$ diverges. We will denote by $\theta(i)$ the least j for which this is so. Similarly we define $\theta(l)$ for $l = 1, \dots, m$.

Define the sequence $\{\theta^k(i): k \geq 1\}$ inductively by $\theta(i)$ as above, $\theta^k(i) = \theta(\theta^{k-1}(i))$ for $k > 1$.

The sequence of stopping times $\{\lambda_k: k \geq 0\}$ are defined inductively as follows:

$$\lambda_0 = 0, \quad \lambda_k = \inf\{n > \lambda_{k-1}: X_n = \theta^k(i)\}, \quad k > 0.$$

If we let $U_k = S_{\lambda_{k+1}} - S_{\lambda_k}$ for $k \geq 0$ then the elements of the sequence $\{U_k: k \geq 0\}$ are the increments from adjacent $(\theta^k(i), \theta^{k+1}(i))$ blocks. Let τ be the stopping time defined by $\tau = \inf\{\lambda_k: U_k \leq 0\}$.

We consider separately the two possibilities that $P_i(\tau < \infty) = 1$ or otherwise.

Firstly we suppose $P_i(\tau < \infty) = 1$. We define the sequence of stopping times $\{\tau_k: k > 0\}$ inductively by

$$\begin{aligned} \tau_1 &= \inf\{n > \tau: X_n = \theta(X_\tau)\}, \\ \tau_k &= \inf\{n > \tau_{k-1}: X_n = \theta(X_\tau)\}, \quad k > 1. \end{aligned}$$

From these definitions and that of θ we see that $\sum_1^\infty k^{-1} P_i(S_{\tau_k} - S_\tau > 0) = \infty$. Using the definition of τ which implies that $S_{\tau_1} - S_\tau \leq 0$ we deduce that

$$\sum_1^\infty k^{-1} P_i(S_{\tau_k} - S_{\tau_1} > 0) = \infty.$$

It is easy to see that $\sum_1^\infty k^{-1} P_i(S_{\tau_{k+1}} - S_{\tau_1} > 0) = \infty$.

Noting that $(S_{\tau_{k+1}} - S_{\tau_1})$ is the sum of k i.i.d. random variables we can use Theorem C and Lemma B to deduce that $\overline{\lim}_k S_{\tau_k} = \infty$ a.s. Hence $\overline{\lim}_n S_n = \infty$ a.s. and by Lemma 4 it follows that N is totally proper.

Secondly suppose that $P_i(\tau < \infty) < 1$ from which it follows that $P_i\{U_k > 0; k = 0, 1, \dots\} > 0$. Since the Markov chain has only m states we know that least from $k = m$ onwards the sequence $\{\theta^k(i): k = 1, \dots\}$ will be of a cyclic nature. Hence the distribution functions of the U_k will also be so and since the U_k are independent

random variables it follows that at least for $k > m$, $P(U_k > 0) = 1$. Hence $\overline{\lim}_k S_{\lambda_k} = \infty$ a.s. P_i therefore $\overline{\lim} S_n = \infty$ a.s. P_i and therefore by Lemma 4 we can say that N is totally proper.

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