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*Corrigendum:*  
*On the Time Derivatives*  
*of Equilibrated Response Functions*

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The last equation in Section IV, described as “the defining equation of hypoelasticity” is incorrect. In the usual situation, where  $\mathcal{X}$  is the collection of second-order tensors and  $f(0)$  is non-singular, the formula should read

$$\dot{\pi}(f) = A(\pi(f)) [\dot{f}(0)f(0)^{-1}].$$

The third in the list of sufficient conditions that  $\pi$  be hypoelastic must then be changed. Thus:  $\pi$  is a hypoelastic function if

- 1)  $\pi$  is rate-independent and smooth,
- 2)  $a_f$  exists for every  $f \in \mathcal{F}$ ,
- 3) there exists  $A: \mathcal{Y} \rightarrow \mathcal{L}(\mathcal{X}, \mathcal{Y})$  such that

$$a_f = A(\pi(f)) \circ R_{f(0)^{-1}}.$$

Here for any  $a \in \mathcal{X}$ ,  $R_a$  is the right-multiplication operator:

$$R_a b = ba, \quad b \in \mathcal{X}.$$

Accordingly, the last italicized statement in the introduction should read: *if the stress is given by a smooth rate-independent function, then the material is hypoelastic if and only if its instantaneous modulus is the composition of a function of the stress with right-multiplication by the inverse of the deformation gradient.*

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