

Design and Implementation of Solar Charging Electric Vehicle



Rahil Imtiyaz, Aman Kumar, Gitanjali Mehta , and Ruqaiya Khanam

Abstract The accessibility of non-renewable energy sources will diminish to increment popularity and will be depleted in the near future. Along these lines, it is important to track down the substitute fuel to work the vehicles. As a sustainable power source, solar energy is utilized to make solar charging electric vehicle (SCEV) that is our venture. This kind of vehicle would be fit to supplant conventional ignition engines for ordinary vehicle exercises. The utilization of solar-based energy to control the vehicle takes into account greater appropriateness and a method for utilizing environmentally friendly power energy. Standardization of the vehicle this kind would drastically decrease the harmful emissions delivered by the vehicles and diminish the oil demand. The authors have proposed a photovoltaic (PV) integrated electric vehicle (EV) instead of conventional EV with separate PV/grid/hybrid charging station. As starters, the goal is to execute our thought on an essential model and later with the assistance of this model, by building constant solar charging electric vehicle we may broaden our future.

Keywords Solar charging electric vehicle · Photovoltaics · Renewable energy

1 Introduction

In the current circumstance, due to the increase in population, usage of assets like petrol, coal and diesel are continuously increasing. The availability of these non-environmentally friendly power source will decrease accordingly, and it will be exhausted in sometime leading to a future with fuel and mineral deficit. In this way, present patterns in energy utilization, particularly oil, cannot be supported any longer

R. Imtiyaz · A. Kumar · G. Mehta (✉)
Electrical and Electronics Engineering, Galgotias University, Greater Noida, India
e-mail: gitanjali.iitr@gmail.com

R. Khanam
Computer Science and Engineering, Center for Artificial Intelligence in Medicine, Imaging and Forensic, Sharda University, Greater Noida, India

[1–3]. Additionally, the use of conventional energy sources is the major cause behind environmental imbalance, ozone layer consumption and global warming which thus is a major danger to the future human race. Once more, considering the chance of a worldwide temperature alteration, these assets are assuming a negative part. Along these lines, under the present situation, it is very important to make another investigation of the common asset of energy. It is viable, more affordable or more all, it is an unending wellspring of energy. With well-enhanced energy productivity, a shift to an energy-based wealth capable of supporting predicted global economic growth is possible [4, 5].

Power can be produced utilizing environmentally friendly power sources, for example, solar, wind and biomass. Sun-based energy is the cleanest and most abundant ecologically friendly power source available. Sunlight-based solar panels convert the sunlight rays into usable solar energy. The process of turning light (photons) into electricity (voltage) is defined as the photovoltaic effect. Solar panels convert the majority of visible light and a small amount of brilliant infrared light into electricity. Solar charging innovations can harness this energy for a variety of purposes, including generating electricity, providing light or a pleasant indoor atmosphere, and warming water for domestic, commercial or industrial usage [6–8].

The authors propose to decrease the utilization of natural fuel-controlled vehicle and plan climate-amicable electric vehicle. Sunlight-oriented vehicle is principally controlled by direct sun rays. On the solar vehicle, photovoltaic (PV) cells are utilized to capture the PV rays and convert the solar-oriented energy form into electric energy form. Silicon and mixtures of indium, gallium and nitrogen are used to create this product. The semiconductors assimilate light and afterwards discharge it, creating a progression of electrons that produce power which charges 24 V battery associated with it, which runs the 375 W Brushless DC (BLDC) motor to send the ability to drive the vehicle. We are using high-strength iron square pipes for good mechanical strength. The configuration is made with the end goal that vehicle has appropriate weight to power proportion and is light in weight and strong, which is a must for any solar charging vehicle.

Habib et al. [9] have discussed the present and future status of electric vehicle (EV) and charging system implementation. The EV batteries are charged during the day by PV charging stations in parking area. Khalid et al. [10] have reviewed EV charging infrastructures and the impact it has on power quality of grid. Savio et al. [11] have analysed the energy management strategy of hybrid microgrid structured EV charging station. Tazay and Miao [12] have proposed a hybrid converter for PV charging station. Ramadhani et al. [13] have reviewed the different PV-based charging techniques for EV. Abdelsalam et al. [14] have presented the modelling and simulation of PV-powered EV charging station. Tiano et al. [15] have evaluated the potential of PV panel installation on EV body.

Most of the work proposes EV with PV charging stations. Our study designs and implements PV integrated EV system so as to improve the driving range and reduce battery storage size. The authors have designed and implemented PV-based EV system instead of conventional EV with PV charging stations. The advantages

offered by the proposed solar charging EV system are reduced grid energy demand, increased EV driving range and reduced carbon emissions.

The paper is organized as given. Section 2 discusses the modelling of solar charging electric vehicle. Section 3 focuses on the design calculation of the EV. Section 4 discusses the design vehicle specifications and a comparison with the conventional vehicles. Section 5 gives the conclusion along with future scope of work.

2 Proposed Work

The block diagram of solar charging electric vehicle with a battery charge/discharge controller is shown in Fig. 1. The SCEV project was at first begun in the fall of 2021. The required number of parts were bought, and associations were done with the creation shop close by for joint welding to the edges of the vehicle: 3 × 6 ft length 1.5" square iron pipe body, 2-rods at the end, 1-steering for 2 front wheel, 1-solar plate, 1 steering set, 1-brake build near to handle, 4 small wheels, 2 battery, 1 reverse switch, 1 chain set, 375 W BLDC motor, controller, 7 × bearings and 1 brake cable [16–18].

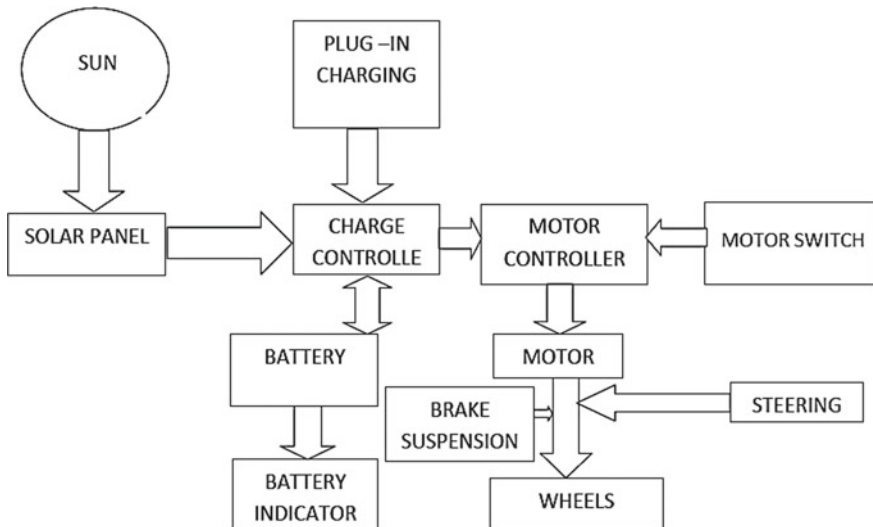
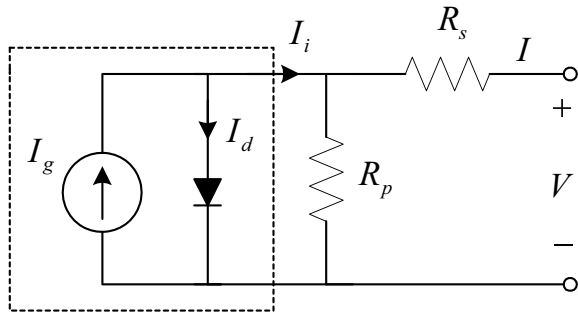


Fig. 1 Block diagram of solar charging electric vehicle

Fig. 2 Equivalent circuit of a single PV cell



2.1 Solar Panel

Solar cells are generally constructed of silicon that has been specially processed to shape an electric field. The back is heavily doped with boron, while the phosphorus-doped negative side is exposed to the sun. At the point when photons from sun rays hit the solar cells, making electron-opening sets, electrons are extracted from the particles in the semiconductor material. Figure 2 shows the block diagram of a single PV cell. Assuming electrical conduits are connected to the +ve and -ve sides, an electrical circuit is shaped and the moving electrons make electric flow I_g (photocurrent). The more noteworthy the power of daylight, the more prominent is the progression of power [19–24].

When there is no daylight, the sunlight-based cell is certainly not a functioning gadget, and it fills in as a diode. In the event that it is associated with an outer stockpile, it creates a current, I_d , called diode current. Figure contains a flow source, I_g , the diode and an arrangement opposition addressing the inner obstruction of a cell R_s . As a result, the difference between I_g and I_d is the net current I expressed as:

$$I = I_g - I_d = I_g - I_0 \left(e^{\frac{\beta(V+R_s I)}{\alpha}} - 1 \right), \tag{1}$$

where α is the diode ideality factor, β is the inverse thermal voltage, k is Boltzmann’s gas constant, V is cell voltage and I_0 is the diode reverse saturation current.

2.2 Battery

A battery is an electrical component that changes chemical energy into electrical energy and the other way around. Positive cathode and negative anode are the two terminals that it usually possesses. During a prospective shift (charging or releasing) the framework relies on the synthetic response of electrolyte (fluid or glue arrangement). Particles will pass between the two terminals because of the electrolyte

(cathode and anode) or the dynamic materials of the battery, enabling electricity to flow from the battery in order to complete necessary tasks.

The battery’s applications are limitless. For all electrical devices that necessities high energy stockpiling limit or for any gadget that requirements low energy yield (versatile gadgets like cell, PC and so forth), battery is utilized for either to capacity energy or to go about as a force supply. Along with technological advancements that increase the capacity limit, size and lifetime of batteries, new battery applications are gradually emerging [17–20].

For the solar-based vehicle, we were utilizing battery for a backup to store energy which has ceaseless yield. To do that we need explicit determination of battery to play out our undertaking effectively which require clear comprehension of its boundaries just as its inclination of conduct.

State of charge (SOC) is a statement of the current battery limit as a level of greatest limit. SOC is for the most part determined utilizing current incorporation to decide the adjustment of battery limit over the long run. It can likewise be clarified as:

$$SOC = \frac{\text{Available Capacity}}{\text{Nominal Capacity}} \tag{2}$$

Depth of discharge (DOD) defines the level of battery capacity that has been discharged with respect to the most extreme limit. Figure 3 shows the charging and discharging of the battery. The SOC represents an alternative form of DOD measurement, and hence, DOD is expressed as:

$$DOD = 1 - SOC \tag{3}$$

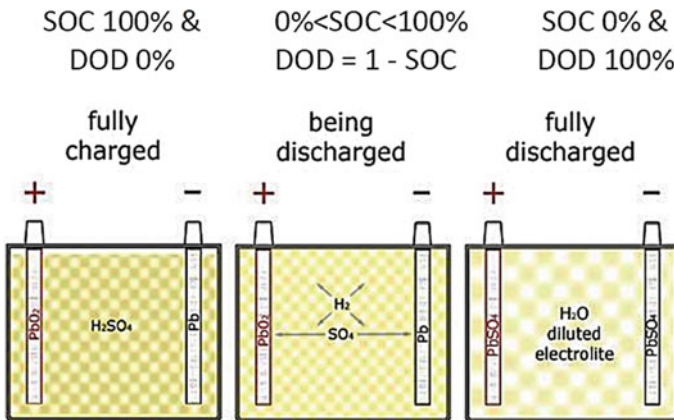


Fig. 3 Battery charging and discharging (SOC vs. DOD)

3 Design Calculation for Solar Charging Electric Vehicle

The solar vehicle is manufactured at the cost of INR 30,000. The vehicle has a wheelbase of 1066 mm (42 in.). The vehicle uses four wheels, two wheels in front and two in rear. The body material uses seamless square iron pipe for better mechanical strength. The ground clearance from the driver seat is 101.4 mm (4 in.). The ground clearance is decided as per the vehicle structure. There is square iron pipe bumper in the front and the rear of the vehicle. Two jack point is provided near the rear wheel. The driver's exit is so easy that he/she can exit from the vehicle within 5 s. Driver visibility is two hundred degrees (200°) field of vision and one hundred degrees (100°) to both sides of the driver. Steering system is well connected with the front two wheels. Proper braking system is attached with the rear wheels supporting by the disc. The BLDC motor is used with the power 375 W, and running voltage is limited to 24 V. Battery capacity is 24 V and 30 Ah all the time. Figure 4 shows the overview of the developed solar charging electric vehicle. Figure 5 displays the different parts of the SCEV. Figure 5a shows the braking system with the rear wheel, and Fig. 5b shows the wheel side view. Figure 5c shows the battery charge/discharge controller, and Fig. 5d shows the solar panel. Figure 5e shows the battery pack and Fig. 5f the chain set. Table 1 shows the dimensions of the designed solar charging electric vehicle. Table 2 gives the solar charging electric vehicle specifications. Table 3 shows the calculated values for angular velocity, frequency, peak torque, peak power, continuous torque, continuous power, continuous speed, air resistance and rolling resistance derived from Eqs. (4) to (12).



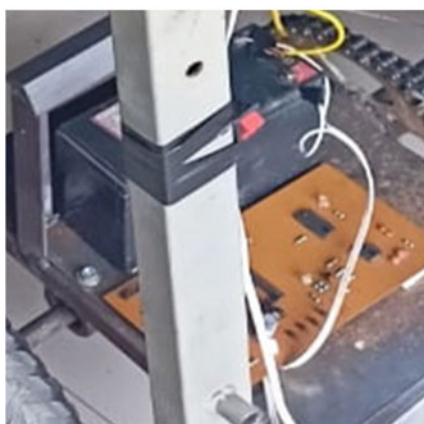
Fig. 4 Overall view of solar charging electric vehicle



(a) Braking system with the rear wheel



(b) Wheel Side View



(c) Battery Charge / Discharge Controller



(d) Solar Panel



(e) Battery Pack



(f) Chain set

Fig. 5 View of different parts of solar charging electric vehicle

Table 1 Dimensions of the designed solar charging electric vehicle

Parameter	Value (m)
Length	1.828
Width	0.914
Height	1.219
Ground clearance	0.101
Wheelbase	1.066

Table 2 Solar charging electric vehicle specifications

Parameter	Value
Weight of the vehicle	80 kg
Speed	20–25 km/h
Diameter of wheel	0.4 m
Weight of battery	20 kg
Average speed	20 km/h
Range	20 m

Table 3 Calculation results

Parameter	Value
Angular velocity	27.75 rad/s
Frequency	265.12 RPM
Peak torque	19.6 N-m
Peak power	543.9 W
Air resistance	32 W
Rolling resistance	147.2 W
Continuous power	179.2 W
Continuous speed	104.66 RPM
Continuous torque	16.34 N-m

• **Wheel angular velocity calculation**

Considering Linear Velocity = 20 km/h
 Speed = $20 \times (5/18)$ m/s = 5.55 m/s
 Wheel Diameter = 0.4 m

$$\begin{aligned}
 \text{Angular Velocity} &= \text{Linear Velocity} \div \text{Radius} \\
 &= 5.55/0.2 = 27.75 \text{ rad/s}
 \end{aligned}
 \tag{4}$$

$$\text{Angular Speed} = 2 \times \text{frequency} \times \pi$$

$$\begin{aligned} \text{Frequency} &= \text{Angular Speed} / 2\pi \text{RPS} = \text{Angular Speed} \times 60 / (\pi \times 2) \text{RPM} \\ &= 27.75 \times 60 / (3.14 \times 2) \text{RPM} = 265.12 \text{RPM} \end{aligned} \tag{5}$$

- **Peak torque calculation**

$$\begin{aligned} \text{Peak Torque Wheel} &= (\text{Wt. of Vehicle} + \text{Wt. of Battery}) \\ &\quad \times \text{Acceleration due to gravity} \\ &\quad \times \text{Slope\%} \times \text{Radius of wheel} \\ &= (80 + 20) \times 9.8 \times 0.2 \times 0.1 \text{ N-m} = 19.6 \text{ N-m} \end{aligned} \tag{6}$$

$$\begin{aligned} \text{Power Required} &= \text{Angular Velocity} \times \text{Torque} \\ &= 27.75 \times 19.6 \text{ W} = 543.9 \text{ W} \end{aligned} \tag{7}$$

- **Air resistance calculation**

$$\begin{aligned} \text{Air Resistance} &= (5/100,000) \times \text{Wt. of vehicle} \times (\text{Average Speed})^3 \\ &= (5/100,000) \times 80 \times 203 = 32 \text{ W} \end{aligned} \tag{8}$$

- **Rolling resistance calculation**

$$\begin{aligned} \text{Rolling Resistance} &= 0.092 \times \text{average speed} \times \text{Wt. of the vehicle} \\ &= 0.092 \times 20 \times 80 = 147.2 \text{ W} \end{aligned} \tag{9}$$

- **Continuous power calculation**

$$\begin{aligned} \text{Power Required (Continuous)} &= \text{Rolling Resistance} + \text{Air Resistance} \\ &= 147.2 + 32 = 179.2 \text{ W} \end{aligned} \tag{10}$$

- **Continuous speed calculation**

$$\begin{aligned} \text{Continuous Speed} &= \text{Average Speed} \times 60 / (2 \times \text{Wheel Radius} \times \pi) \\ &= 20 \times (5/18) \times 60 / (2 \times 0.2 \times \pi) = 104.66 \text{ RPM} \end{aligned} \tag{11}$$

Table 4 SWOT analysis

Strength	Weakness	Opportunities	Threats
Light in weight and long-lasting chassis	Not suitable for long drives	Environment-friendly vehicle	Bad weather condition and not getting proper sunlight rays
Directly run-on solar power	Performance varies with change in weather	Directed towards a green and clean future	Roads are not settled everywhere

- **Continuous torque calculation**

$$\begin{aligned}
 \text{Torque Required} &= (\text{Air Resistance} + \text{Rolling Resistance}) \\
 &\quad \times 60 / (2 \times \text{Continuous Speed} \times \pi) \\
 &= (32 + 147.2) \times 60 / (2 \times 104.66 \times \pi) = 16.34 \text{ N-m} \quad (12)
 \end{aligned}$$

4 Solar Charging Electric Vehicle Specifications

It's just a DC transformer with a chopper circuit that allows it to go up or down in voltage. We can increase the yield voltage by changing the semiconductor switch's obligation pattern. To avoid a sudden shift in current, we may simply charge the battery through an inductor. We may connect the DC motor to the circuit in a similar manner. Table 4 presents the SWAT analysis for SCEV. Table 5 gives a comparison of solar charging electric vehicle with petrol vehicle and electric vehicle. Table 6 provides a comparison of running cost for petrol vehicle, electric vehicle and solar electric vehicle.

5 Conclusions

A four-wheeled minimal expense photovoltaic integrated electric vehicle is achievable and practicable. Our SCEV, a solitary situated vehicle controlled by 375 W BLDC-centred motor can be a decent decision for the Asian market. A multivariate specialized gathering has improved the design and manufacturing of our SCEV, ensuring that it stays a safe, elite and cost-effective electric sun-based vehicle. Utilization of square iron pipes for strong mechanical strength, utilization of ergonomically planned solar vehicle inside, moving on direct sunlight-based energy without

Table 5 Comparison of solar charging electric vehicle with petrol vehicle and electric vehicle

Petrol versus solar charging electric vehicle	Solar charging electric vehicle versus electric vehicle	Environment-friendliness
Fixed number of non-renewable resources and will end in coming years	Not possible to charging on shadow or any covered halt	No pollution and CO ₂ emit
Too costly	For charging using power supply required rated power supply	Better use of sun rays
Not safe/dangerous	On moving constant charging not possible due to uneven sunlight rays	Will be helpful to reduce global warming
Environment disaster	If charging on EVs charging stations is time taking	The vehicle is manufactured of eco-friendly material
Very high running cost and maintenance are expensive	Should not be best for long-distance travel	
	Maintenance cost is less but once after battery dies replacement of battery is expensive	
	It is environment-friendly but not be best for every place	

Table 6 Comparison of running cost

Parameters	Petrol vehicle	Electric vehicle	Solar vehicle
Fuel	Petrol	Electricity	Solar electricity
Rate of fuel	INR 98/L	INR 28/Full charge	Free
Vehicle mileage	12–20 km/L	100–200 km/charge	50–200 km/charge
Running cost per km	INR 4–7	INR 0.2	Free
Running cost per year (18,000 km)	INR 72,000–126,000	INR 3600	Free
Yearly saving	–	INR 68,400–122,400	INR 72,000–126,000

external source, utilization of a few electronic gadgets like solar board heat sensors, advanced cooling framework and so forth have reinforced the vehicle as a high-level SCEV ready for worldwide market. Thus, the authors have designed a photovoltaic integrated electric vehicle which has numerous advantages when compared with conventional EV with the requirement of separate charging station.

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