

Social Preferences and the Provision of Public Goods



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How selfish soever man may be supposed, there are evidently some principles in his nature, which interest him in the fortune of others, and render their happiness necessary to him, though he derives nothing from it, except the pleasure of seeing it [45, p. 9]

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1 Introduction

Public goods are characterized by *non-rivalry*, meaning that more than one person can simultaneously benefit from them, and *non-exclusivity*, meaning that it is difficult to prevent any individual from enjoying their benefits. They simultaneously benefit many people and their creation requires the coordinated actions of people who will subsequently enjoy its benefits. Environmental protection, research and innovation, vaccination, health care services, highways, and public parks are just a few important examples.

Despite receiving benefits from public goods, individuals tend to free ride on the contributions of others in a group. Given that these goods are non-rival and non-excludable, it is evident that once the goods have been produced, every agent can consume them regardless of their contribution. Unless there exist mechanisms to make individuals act in their common interests, rational or self interested individuals will not act to achieve their common or group interests [37]. There are various

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mechanisms to ensure cooperation or reduce free riding. We discuss punishment, commitment, and communication as some of the mechanisms which help increase cooperation in a society.

An alternative explanation for the cooperation seen can be provided by social preferences. Social norms and preferences also matter in the provision of public goods. For example, local resources can be managed well when users care about others and can organize and enforce their own rules, instead of following externally imposed norms [20].

The importance of social norms and preferences can also be seen in our daily lives. Consider a family with grandparents/parents and their children. Parents or grandparents might invest in infrastructure, environment, technology to mitigate climate change so that it can benefit their future generations. They have an added incentive to invest in highways, public schools, public parks, environment-friendly vehicles or practices because of the concern for their children. Another way to understand this idea is that your family member might contribute more to public goods that will benefit you in the future as compared to a stranger.

In the following subsection, we start with a simple public goods model and show how free riding is an equilibrium in this game. Our goal in this chapter is to examine the reasons for the absence of free riding, in particular, by focusing on the role of social preferences. In Sect. 2, we provide evidence on the absence of free riding and also discuss mechanisms available in the literature to ensure cooperation. Section 3 describes how social preferences can explain cooperation. The section also entails a model on social preferences and the equilibrium after incorporating social preferences. In Sect. 4, we will discuss models of various types of social preferences available in the literature. These theoretical models are also supplemented with experimental evidence. Section 5 discusses how social preferences influence public goods provisioning in a coalition or network framework. Section 6 concludes the chapter.

1.1 A Simple Model of Public Goods

To fix ideas formally, we now present the public goods model in Fehr and Schmidt [18]. We will use this model to arrive at a fundamental result in public goods which will also be the first Proposition of this chapter. Let there be $n \geq 2$ individuals in a society who simultaneously decide on their contribution levels $g_i \in [0, y]$, $i \in [1, 2, \dots, n]$ to the public good. Each player has an endowment of y . The monetary payoff of player i is given by [18, p. 836, Eq. 11]

$$x_i(g_1, g_2, \dots, g_n) = y - g_i + a \sum_{j=1}^n g_j, \quad 1/n < a < 1 \quad (1)$$

Here a denotes the constant marginal return to public good $G = \sum_{i=1}^n g_i$. Since $a < 1$, contributing to G leads to loss of $1 - a$. The dominant strategy of an individual i is to choose $g_i = 0$.

Definition 1 A strategy g_i^* is a Nash equilibrium of this game if for all $i \in [1, 2, \dots, n]$, $x_i(g_i^*, g_{-i}) \geq x_i(g'_i, g_{-i})$ for all $g'_i \in (0, y]$.

In this game, we have $g_i^* = 0$ as the Nash equilibrium strategy for any player $i \in [1, \dots, n]$. Strategy other than $g_i^* = 0$ is denoted by g'_i . Strategy of players other than i is given by g_{-i} .

Thus, the standard model predicts $g_i = 0$ for all $i \in [1, 2, \dots, n]$. However, since $a > 1/n$, aggregate monetary payoff is maximized at $g_i = y$. This observation leads us to fundamental result about public goods in economics summarized in our first Proposition.

Proposition 1 *Suppose the payoff function is given by Eq. 1 and satisfies $1/n < a < 1$, then in Nash equilibrium $g_i = 0$ for all $i \in [1, 2, \dots, n]$.*

Not contributing to the public goods is termed as ‘free riding’. Kim and Walker [30] summarize the ‘free-rider’ problem in their theoretical model: “If the method of voluntary contributions is used to determine the level at which public goods will be provided, then the resulting provision level will be far below the optimal level, and many individuals will contribute nothing at all.” Free riding is also evident in their experimental results.

In practice, however, we may not always see free riding. In the next section, we provide experimental and empirical evidence on lack of free riding. Various mechanisms to ensure cooperation or avoid free riding will also be discussed in the next section. In a later section, we examine how social preferences can be used to explain cooperation or absence of free riding.

2 Evidence on Free Riding Behavior

Free riding has been a widely accepted notion in the literature of public goods games. Previous theory suggests that players try to get the benefit from public goods without contributing towards it. However, those results are in sharp contrast to the existence of cooperative behavior among individuals in real-life public goods games. This behavior has been substantiated by data from national surveys as shown in Andreoni [1], who states: “Around 85% of households make donations to charity, 50% of tax returns include charitable deductions”. Another related evidence of cooperative behavior can be found in voting in elections. Individuals tend to vote in elections, even though economic theory predicts that free riding will be higher as the decisive power of one vote is low. Countries joining International Environment Agreements (IEA) to solve environmental issues is also an example of cooperation. Group of

77 (G77), United Nations Framework Convention on Climate Change (UNFCCC), Kyoto Protocol are some of the existing IEA's.

The contrast between the theoretical predictions and real-life evidence motivated the testing of 'free-rider' hypothesis in the lab. Ledyard [34] surveys the experimental literature on public goods before 1995. Some of the prominent papers included in the survey are Marwell and Ames [35], Isaac et al. [29], Isaac and Walker [28], and Andreoni [2]. One of the findings from these experiments suggests that individuals contribute more than the Nash equilibrium prediction in a public goods game. As we saw in the previous section, the Nash equilibrium in a public good game is to free ride, however, it is optimal to contribute the full amount. On an average, contributions were about 40–60% of the optimal level in these experiments. However, the contributions varied over individuals. The other common observation is that contributions start at 40–60% of the optimal level but over the periods decline to 'free riding' outcome.

This decay in contribution levels was further analyzed in Andreoni [2] through 'learning' and 'strategies' hypothesis. According to the learning hypothesis, repeated periods allow individuals to learn the incentives from the game which can explain the fall in contribution levels. At the same time learning also allow players to signal future moves to each other. This leads to the strategy hypothesis, where in a repeated games a rational player will develop multi period strategies that can lead to cooperative behavior. However, Andreoni finds no significant support for either of these hypotheses which could have explained the decay experienced in these games. We now state our first observation from findings in this section.

Observation 1: *Empirical and experimental evidence show that individuals cooperate and contribute to public goods as opposed to the theoretical predictions.*

These experimental results motivated research on the importance of institutional environment which can help in achieving the optimal outcome or reduce free riding. In next subsection, we discuss these mechanisms which can help further increase cooperation in a public goods game.

2.1 Mechanisms that Avoid Free Riding

This section summarizes the institutional environments which have been used in the literature to reduce the incidence of 'free riding'. Institutional environment refers to the context or setting in which individuals would make their decisions. The pay-off function remains the same as in Eq. 1, however, we look into different settings under which the public goods game is played. We discuss three such institutional environments: communication, commitment, and punishment.

Communication

Communication between the participants regarding their strategies or intentions can help in increasing contributions to a public goods game. Isaac and Walker [28] were the first to test face-to-face communication as a means to reduce ‘free riding’. According to the authors, “The role of communication is to a) help the group understand the group profit implications for different allocations and b) build credibility to the expected decisions of group members”. Communication thus helps in learning the optimal strategy (contributing to public goods). Ostrom [38] also finds that face-to-face communication can sustain cooperation even through the last period. Communication enforces no verbal agreement and hence can be thought of as ‘cheap talk’ [39]. This paper summarizes the findings on collective action and one of the findings suggests that when communication is implemented by allowing subjects to signal promises through their computer terminals, much less cooperation is observed as compared to the case when subjects are allowed face-to-face communication.

Communication enhances cooperation, however, the effectiveness of communication depends on its structure and the level of private information among players. Palfrey et al. [41] provide an answer to this problem both theoretically and empirically. They find theoretical bounds on efficiency gains that can be attained through different modes of communication by using the Bayesian-mechanism design. The bounds depend upon the distribution of private information (value of endowed unit of output) and on the richness of the message space (communication structure). The authors choose three forms of pre-play communication: binary message (intention to contribute or not), practice game (announce their contribution against different contribution costs), and natural language communication (exchange of chat messages) in order to test their theoretical bounds. The results from their experiment find efficiency and public goods provisioning to be significantly higher in case of natural language communication as efficiency bounds predicted by the theoretical model were only achieved in this treatment. This might be because “unrestricted chats give subjects an opportunity to understand each other’s intentions and messages”. Natural language communication can be thought of as a more personal form of communication which gives more scope to convey an individual’s message and intentions than a restricted message or any other form.

Commitment

Commitment can also be used as a strategy to enhance cooperation. “Commitment is a means by which players can assure one another that they are not going to free ride on others’ contributions, so that group members can contribute without fearing that they will be free ridden” [32]. Chen [14] was one of the first paper to use ‘pledge to contribute’ as a commitment. The authors find that group-based pledge (subjects make a pledge before making a contribution, are given feedback and have to then

contribute a proportion of the mean pledge) and face-to-face communication have similar results in enhancing cooperation. Through commitment, individuals can eliminate free riding. However, once an individual makes a commitment, he/she is more vulnerable for being free ridden [32]. This is because individuals might use commitment by others as an opportunity to ‘free ride’ on their contribution. To respond to this issue authors design a mechanism, where players can commit to cooperating to a small degree and then observe other player’s reciprocal contributions. The mechanism allows participants to signal their commitment without exposing them to be ‘free-ridden’. They test for the efficiency of different ‘pledges for contribution’. The study finds that ‘increase only’ pledge is effective in increasing cooperation. This mechanism works as a commitment strategy by not letting the players reverse their contributions and allows players to reduce their extent of free riding by limiting their commitments.

Punishment

People who cooperate might be willing to ‘punish’ the free riders. Ostrom et al. [40] was one of the first papers to test the impact of punishment in a public goods framework. The authors allow for costly punishments in a repeated common pool resource game and find that participants punish free riders in their experiment. However, in their paper, the same subjects interacted for multiple periods, thus giving them an incentive to cooperate and punish free riders. To rule out these incentives, Fehr and Gächter [19] in their experiment have a punishment and non-punishment treatment crossed with a stranger (group composition changes every period) and partner treatment (group composition is fixed). The authors find that in both the treatments, the punishment is heavier if the more negatively individual deviates from the contributions of group members. The average contribution goes up in both the stranger and partner treatment when punishment is allowed and approaches to full cooperation in partner treatment.

Previous experiments which studied the role of punishments could not elicit much about the robustness of punishment schemes. Nikiforakis and Normann [36] in their paper provide a comparative statistics of punishment in public goods games. They find that contributions to public goods increase monotonically in the effectiveness of punishment (factor by which the punishment reduces the punished player’s income). Higher effectiveness leads us near to social optimal outcome.

Individuals do not contribute in a public goods game, due to the chance of being ‘free ridden’ by others. All the mechanisms discussed above change the environmental setting of a game in a manner which increases the incentive to cooperate. The success of the mechanism depends upon how effective it is in reducing chances of being ‘free ridden’.

3 Social Preferences: An Alternative Explanation

While the experimental literature has provided us with examples of several mechanisms that can lead to free riding and reduce cooperation, we now focus on an alternative approach to explain these findings: the presence of *social preferences*. Theories of others regarding preferences/social preferences are based on the assumption (and observation) that people care about the well-being of others. In his paper, Andreoni [5] shows that, on an average, about half of all cooperation is due to subjects who understand free riding but cooperate due to kindness. The author also suggests that the decline in cooperation observed in multiple trials of public goods experiment might not be due to learning, but maybe a result of frustrated attempts at kindness.

According to Fehr and Fischbacher [20]: ‘An individual exhibits social preference if the person cares about material resources allocated to relevant reference agents’. The relative reference agent can vary according to different domains, thus resulting in various types of social preferences. The authors empirically also show that it is difficult to understand concepts of competition on market outcomes, laws governing cooperation and collective action, optimal contracts and property rights, social norms and market failures without incorporation of social preferences.

Nash equilibrium strategy of players in a public goods game is to contribute nothing. However, past literature suggests clear evidence of cooperation among players. Players’ incentive to contribute positively can be predicted theoretically by including social preferences in their payoff functions. Examples of such social preferences include the responsibility of the older generation (grandparents/parents) towards their future generation. Such responsibility drives elders to contribute positively towards any public goods or service which will guarantee a secure future for their children. We illustrate such cooperative behavior using a model of social preferences from Fehr and Schmidt [18]. In the later subsections, we introduce different models of social preferences.

3.1 A Simple Model of Public Goods with Social Preferences

In order to show how the results in a public goods model (Proposition 1) change after incorporation of social preferences, we use the inequity aversion model of Fehr and Schmidt [18]. In this model, in addition to purely selfish individuals, the authors assume the presence of subjects who dislike inequity both when they are worse off than other players and also when they are better off than other players.

Consider a set of n players indexed by $i \in [1, 2, \dots, n]$ and let $x = x_1, x_2, \dots, x_n$ denote vector of monetary payoffs. The utility function of $i \in [1, 2, \dots, n]$ is given by

$$U_i(x) = x_i - \alpha_i \left(\frac{1}{n-1} \sum_{j \neq i} \max|x_j - x_i, 0| \right) - \beta_i \left(\frac{1}{n-1} \sum_{j \neq i} \max|x_i - x_j, 0| \right) \quad (2)$$

The second term in Eq. 2 measures loss from disadvantageous inequality, the third term measures loss from advantageous inequality. The two parameters α_i and β_i measure player i 's utility loss from disadvantageous inequality and from advantageous inequality. The authors assume that $\beta_i \leq \alpha_i$ and $0 \leq \beta_i < 1$. $\beta_i \leq \alpha_i$ implies, players suffer more from inequality that is to their disadvantage, i.e., the subject is loss averse in social comparisons. $\beta_i \geq 0$, rules out the subjects who like to be better than others.

We now substitute Eq. 1 in Eq. 2 to see how public goods provisioning changes due to presence of inequity aversion. For this result, we focus on Proposition 4c of Fehr and Schmidt [18] which discusses positive contribution levels of individuals.¹ Player i who does not contribute ($g_i = 0$) is a 'free rider'. Let number of free riders be represented by k . Recall from Eq. 1, g_i and a denote the contribution levels and marginal return to public good, respectively.

Proposition 2 ([18, p. 839 Proposition 4(c)]) *If $k/(n-1) < (a + \beta_j - 1)/(\alpha_j + \beta_j)$ for all players $j \in [1, 2, \dots, n]$ with $a + \beta_j > 1$, then other equilibria with positive contribution levels does exist. In this equilibria, all k players with $a + \beta_i < 1$ must choose $g_i = 0$, while all other players contribute $g_i = g \in [0, y]$. Note further that $(a + \beta_j - 1)(\alpha_j + \beta_j) < a/2$.*

We first discuss the author's intuition behind the proof and then move towards the sketch of the proof. If there are sufficiently many players with $a + \beta_j > 1$, they can sustain cooperation among themselves even when other players are free riding. This only holds when contributors are not affected much by the disadvantageous inequality. This is because if α_j increases, it is less likely to be the case that: $k/(n-1) < (a + \beta_j - 1)/(\alpha_j + \beta_j)$

Sketch of the proof

- Following from the author's Proposition 4a, the dominant strategy of k free riders, with $a + \beta_i < 1$, is $g_i = 0$ (not contribute). This is because free rider's return from public good (a) and non-pecuniary benefit from reducing inequality (β_i) is less than 1.
- The remaining $n - k$ or j players with $a + \beta_j > 1$ contribute positively with $g_i = g \in [0, y]$. j 's payoff is given by

$$U_j(g) = y - g + (n - k)ag - \alpha_j \left(\frac{1}{n-1} kg \right) \quad (3)$$

Any individual who contributes is deprived of the advantageous utility which reduces the third term in Eq. 2 to zero, thereby forming Eq. 3.

¹ The case of free rider ($g_i = 0$) is studied in part a and b of the Proposition 4 of the original paper.

Suppose player deviates from contributing g to $g - \Delta$, such that $\Delta > 0$. The deviation strategy towards contributing less than g will not payoff if and only if $U(g - \Delta) \leq U(g)$. Simplifying this inequality leads us to the following condition: $k/(n - 1) \leq (a + \beta_j - 1)/(\alpha_j + \beta_j)$.

- Following from author's Proposition 4b, if there are only a few players with $a + \beta_i > 1$, they would suffer too much loss from the disadvantageous inequality caused by the free riders. The proof given by the authors shows that if a potential contributor knows that the number of free riders, k , is larger than $a(n - 1)/2$, then he will not contribute either.

4 Types of Social Preferences

As seen in the previous section, incorporation of inequity aversion in the standard utility functions, predicts cooperation in a public goods game. Depending on the assumptions of the model and the type of social preference, the model can look different. For instance, we can have altruism as a social preference, incorporated into the standard utility function. However, the mechanism to arrive at the equilibrium will be similar and will lead to positive contributions being made to the public goods game. In the next subsection, we will discuss other papers on fairness and inequity aversion. In the later subsections, we explain models with different social preferences and their outcomes.

4.1 Fairness and Inequity Aversion

Inequity aversion implies that individuals care for equitable distribution of resources or equal outcomes. These models consider an individual 'fair' if the individual is willing to give up their payoff to help others. A model of fairness is represented in Eq. 2. The second and third term which measures the individual loss from disadvantageous and advantageous inequality, respectively, are a measure of fairness in their model.

Rabin [42] was one of the first to develop game-theoretic solution concept "fairness equilibria". An outcome is considered to be fair if the intention behind the action is kind, whereas if the intention is hostile, the action is considered to be unfair. The model is applicable to all finite-strategy games involving two players. Each player's expected subjective utility depends on: his strategy, his beliefs about other player's strategy choices, and his beliefs about other player's beliefs about his strategy.

Let $a_1 \in S_1$ and $a_2 \in S_2$ represent strategies chosen by two players; $b_1 \in S_1$ and $b_2 \in S_2$ represent player 2's belief about strategy player 1 is choosing, and player 1's belief about what strategy player 2 is choosing. $c_1 \in S_1$ and $c_2 \in S_2$ represent player 1's belief about what player 2 believes player 1's strategy is, and player 2's beliefs about what player 1 believes player 2's strategy is.

Each player i chooses a_i to maximize expected utility

$$U_i(a_i, b_j, c_i) = \pi_i(a_i, b_j) + \bar{f}_j(b_j, c_i) \cdot [1 + f_i(a_i, b_j)] \quad (4)$$

- $\pi_i(a_i, b_j)$ is individual i 's material payoff.
- Player i 's kindness to player j is measured by $f_i(a_i, b_j)$. The function measures how much more than or less than player j 's equitable payoff² player i believes he is giving to player j . When $f_i = 0$, player i is giving j her equitable payoff. If $f_i > 0$, player i is giving j more than her equitable payoff. When $f_i < 0$, player i is giving j less than her equitable payoff.
- $\bar{f}_i(b_j, C_i)$ measures player i 's belief about how kind player j is being to him. If player i believes that player j is treating him badly ($\bar{f}_i(b_j, C_i) < 0$), then i chooses a_i such that $f_i(a_i, b_j)$ is low or negative. The opposite situation occurs when $\bar{f}_i(b_j, C_i) > 0$.

The above game by Rabin is a psychological game of the type described by Geanakoplos et al. [25]. The equilibrium concept in these games is called psychological Nash equilibrium which is an analog of Nash equilibrium. The psychological Nash equilibrium concept imposes an additional condition that all higher order beliefs match actual behavior. Rabin uses psychological Nash equilibrium to arrive at the *fairness equilibrium*, which we describe in the next definition.

Definition 2 ([42, p. 1288, Definition 3]) The pair of strategies $(a_1, a_2) \in (S_1, S_2)$ is fairness equilibrium if for $i = 1, 2, j \neq i$

- $a_i \in \arg \max_{a \in S_i} U_i(a, b_j, c_i)$
- $c_i = b_i = a_i$

According to the above definition, an individual i 's strategy (a_i) should maximize her payoff. The strategy should also be equal to player j 's belief about player i 's strategy (b_i) and player i 's belief about what player j believes player i 's strategy is (c_i). Thus, individuals actions and their higher order beliefs both match their actual behavior.

A mutual-max(min) outcome is the one where the player's mutually maximize (minimize) each other's payoffs. We now discuss one of the Propositions which talks about two types of Nash equilibrium being 'fairness equilibrium'.

Proposition 3 ([42, p. 1290, Proposition 1]) *Suppose that (a_1, a_2) is a Nash equilibrium, and either a mutual-max outcome or a mutual-min outcome. Then (a_1, a_2) is a fairness equilibrium.*

The proof is intuitive. First, suppose (a_1, a_2) is mutual-max outcome, then both f_1 and f_2 are non-negative. This implies players have positive regard for each other. Since both players are choosing a strategy that maximizes their payoff and payoff of

² Equitable payoff is the average of highest and lowest payoff of player j .

other players, this must maximize their own utility. Now suppose (a_1, a_2) is mutual-min outcome, then f_1 and f_2 will be non-positive, both players would like to decrease the well-being of others. Simultaneously, player also maximizes his own utility by maximizing his material well-being.

We can draw predictions by applying a prisoner dilemma game into a public goods framework with only 2 players. The Nash equilibrium in a prisoner's dilemma game is to defect, which can be interpreted as no cooperation in a public goods game. Incorporation of reciprocal motives, in a public goods game can lead to full cooperation as one of the equilibrium. The implications will be difficult if there are more than two people (which is usually the case). The payoff function incorporates the stylized facts evident in many experiments: people are willing to sacrifice their own well-being to help those who are kind, people are willing to sacrifice their own well-being to punish those who are unkind. However, Rabin [42] model can only be applied to two persons game.

Fehr and Schmidt [18] models fairness as a self-entered inequity aversion, i.e., individuals are willing to give up some payoff to move in the direction of an equitable outcome. Individuals in these models are concerned about their relative utility or payoff as compared to others. Unlike Rabin [42], Fehr and Schmidt [18] do not model intentions explicitly and use standard game theory in order to analyze n -person public goods game. The authors assume that subjects suffer more from inequity due to their material disadvantage than from inequity due to their material advantage (see Sect. 3.1). In the presence of inequity-averse people, the authors can explain "fair" and "cooperative" as well as "competitive" and "non-cooperative" behavioral patterns. The model also accounts for the interaction between distribution of preferences in a given society. For instance, the presence of 'free riders' in the society induces many inequity-averse individuals to behave in a selfish manner. This happens because if there are only a few individuals who have $\alpha + \beta_i > 1$, they suffer too much loss from disadvantageous inequality caused by free riders. This is Proposition 4(b) in their paper, discussed briefly in our Sect. 3.1.

The experimental evidence on fairness and inequity aversion is not obvious. Dannenberg et al. [16] test for inequity aversion using model from Fehr and Schmidt [18]. The experiment is a two-step procedure using within-subject design. In the first step, subjects played selected games to estimate their individual other regarding preferences. In the second step, subjects with preferences (fair and selfish) according to Fehr and Schmidt [18] were matched into pairs and interacted with the possibility of punishment. They find a significant effect of advantageous inequity aversion (third term in Eq. 2) on an individual's contribution to public goods. Another paper, Blanco et al. [8] also uses within-subject design to assess predictive power of Fehr and Schmidt [18] model. They find that inequity aversion can explain an individual's behavior in a public goods game at an aggregate level, however, not at the individual level. Aggregate level tests compare the distribution of outcomes across different experiments that were run with different samples and thereby check for consistency. Individual level analysis on the other hand uses within-subject design to test for decisions in different experiments with the same sample. The model of

inequity aversion was based on the relative payoff of individuals. In our next section, we discuss models of altruism focusing on absolute payoff of individuals.

4.2 Altruism

Standard utility function as defined in Eq. 1 focus on individual's monetary payoff. Models of giving or donating to a charity have been based on 'altruism', where an individual is assumed to contribute to the public goods because they simply demand more of public goods. However, these models have low predictive power and were not able to incorporate the empirical findings, this lead to the development of models with 'impure altruism'. In the models with 'impure altruism', individuals are assumed to contribute to public goods because of two reasons: (1) altruism: people demand more of public goods, (2) people get some private goods benefits from the gift per se which is called 'warm-glow'. The second motive is also termed as 'egoistic motive'.

Andreoni [3, 4] presents the model of giving that incorporates a warm glow in a public goods game. Suppose there is one private good and one public good. Individuals are endowed with wealth w_i , which they can allocate between consumption of private good x_i and their gift to the public good g_i . Let n be total number of individuals and $G = \sum_{i=1}^n g_i$. In order to explain how a utility function transforms in case of impure altruism, we use the utility function from [4, p. 465, Eq. 1] as stated below

$$U_i = U_i(x_i, G, g_i), \quad i = 1, 2, \dots, n \quad (5)$$

Here, U_i is assumed to be strictly quasi concave. Notice that g_i enters twice in the utility function, once as part of public good G , and as private good g_i . This captures the fact that an individual's contribution/gift (g_i) has properties of a private good that are independent of its properties as a public good.

If the utility function is of the form $U_i = U_i(x_i, G)$ then preferences are purely altruistic. This is because individual does not get any private goods to benefit from the contribution. In contrast, if the utility function is of the form $U_i = U_i(x_i, g_i)$, then the preferences are purely egoistic and the individual is only motivated to give because of the warm glow. Individual only derives private goods benefit from contributing to the public goods.

Let gift/contribution of all the other players except i be denoted by $G_{-i} = \sum_{j \neq i} g_j$, individual donations/contributions can be found by solving

$$\begin{aligned} \max_{x_i, g_i, G} \quad & U_i(x_i, G, g_i) \\ \text{s.t.} \quad & x_i + g_i = w_i \\ & G_{-i} + g_i = G \end{aligned}$$

Under the Nash equilibrium, G_{-i} is treated exogenously, thus we can rewrite $g_i = G - G_{-i}$. Substituting the budget constraints given above into utility function (Eq. 5),

we get

$$\max_G U_i(w_i + G_{-i} - G, G, G - G_{-i}) \quad (6)$$

Differentiating Eq. 6 w.r.t G and solving leads a donation function that is given by the following:

$$G = f_i(w_i + G_{-i}, G_{-i}) \quad (7)$$

$$g_i = f_i(w_i + G_{-i}, G_{-i}) - G_{-i} \quad (8)$$

The first argument in Eq. 7 is from the public dimension of the utility function. The second argument is from the private goods dimension of the utility function. The partial derivative of f_i with respect to first argument is denoted by $f_{i\alpha}$. This is i 's marginal propensity to donate for altruistic reasons. f_{ie} represents the partial derivative of f_i with respect to second argument. This is i 's marginal propensity to donate due to egoistic reasons. Thus, the model incorporates both altruistic and egoistic reasons for contributing to public goods. In the model, $0 < f_{i\alpha} < 1$ and $f_{ie} > 0$. From the equations above, we can say that individual's contribution g_i is increasing in both egoistic and altruistic motives.

Incorporation of these motives can lead to positive contribution ($g_i > 0$) unlike the standard model, which will predict no contribution ($g_i = 0$). The predictions from their model are also consistent with various empirical findings mentioned by Andreoni. Including private provisioning of public goods or impure altruism also increase the predictive power of the models. For instance, the pure altruism model predicts that an increase in the amount of public good provided (G), implies a dollar-for-dollar decrease in an individual's own contribution (g_i). If there is a dollar-for-dollar decrease in g_i for any increase in G , we call such crowding out of g_i as complete. However, empirically, the magnitude of such crowding out is found to be incomplete or proportionately less than the magnitude of change in G . Such findings are consistent with the theoretical predictions from impure altruism models.

Andreoni et al. [6] provide evidence of altruistic preferences in various games: prisoner's dilemma, public goods game, dictator game, trust games, and gift exchange games. The survey also suggests the formation of altruistic preferences can be due to cultural norms, psychological development, socialization, and neural foundations.

The model of impure altruism also predicts that individuals will reduce their contribution to the public goods when other individuals increase their contributions. However, this observation is in contrast to various other outcomes in a public goods game. For instance, conditional cooperation (discussed in the next section) is observed in a public goods game, where individuals cooperate if they see others contributing. Reciprocity observed in many games also contradicts the assumption of altruism. "An altruistic person's kindness does not depend on behavior of others, whereas the kindness of a strong reciprocator is conditional on the perceived kindness of other players" Fehr et al. [21]. We next discuss reciprocity and conditional cooperation.

4.3 Reciprocity and Conditional Cooperation

Theories of reciprocity and conditional cooperation incorporate an individual's willingness to cooperate if others are cooperating as well. In these models, individuals are also concerned about the intentions behind other's decisions. We can also apply the concept of 'conditional cooperation' to the section of inequity aversion, wherein individuals contribute if they believe others will contribute due to his/her concern for equity in payoffs [13]. However, models of reciprocity or conditional cooperation capture the intentions or beliefs of individuals as compared to models of inequity aversion.

Reciprocal motivation is modeled in Rabin [42], however, the model does not apply to sequential games. Falk and Fischbacher [17] extend the notion of reciprocity in a sequential game. The authors present a formal theory of reciprocity (Eq. 9), where the players utility now depends upon an individual's payoff and also on the kindness (how kind a person perceives action by another player) and the reciprocation term (response to the experienced kindness). We now represent their utility function in a 'reciprocity game' [17, p. 301, Definition 3]

$$U_i(f, s_i'', s_i') = \pi_i(f) + \rho_i \sum_{n \rightarrow f} \psi_j(n, s_i'', s_i') \sigma_i(n, s_i'', s_i') \quad n \in N_i \quad (9)$$

The game is a two-player extensive form game with finite number of stages. Let $i \in \{1, 2\}$ be a player in the game and let player j be the other player. N denotes the set of nodes and N_i is the set of nodes where player i has the first move. $n \in N$ is one of the node in the game. S_i and S_j is behavioral strategy space of player i and j respectively. $s_i \in S_i, s_j \in S_j$ are behavior strategy of player i and j , respectively. s_i' denotes *first order belief* of player i and captures i 's belief about the behavior strategy player j will choose. s_i'' denotes the *second order belief* of player i and captures i 's belief about j 's belief about which strategy player i will choose. F denotes the set of end nodes of the game. The models fixes, f as an end node that follows (directly or indirectly) node n .

The first term in Eq. 9: $\pi_i(f)$ is individual i 's material payoff. The second term is the reciprocity utility and comprises of

- Reciprocity parameter: ρ_i is a positive constant and common knowledge. It captures the strength of player i 's reciprocal preferences. A high ρ_i implies reciprocal utility is more important as compared to the other utility. If $\rho_i = 0$, then utility equals material payoff $\pi_i(f)$.
- Kindness term: $\psi_j(n, s_i'', s_i')$ which measures how kind i perceives action by another player j . It depends upon the consequence or outcome of that action and underlying intention. ψ_j is product of outcome term (Δ_j) and intention factor (v_j). Outcome term measures the output, $\Delta_j > 0$ expresses advantageous outcome for i , $\Delta_j < 0$ expresses disadvantageous outcome for i . The intention factor measures the intention behind the outcome. $v_j = 1$ captures a situation where Δ_j is the result

of an action which j completed intentionally and $v_j < 1$ implies j 's action was not fully intentional.

- Reciprocation term: $\sigma_i(n, s_i'', s_i')$ expresses response to experienced kindness, how much i alters payoff of j with his move in node n . A rewarding action implies a positive reciprocation term, whereas a punishment implies a negative reciprocation term.
- Product of kindness term and reciprocation term measures the reciprocal utility in a particular node. If the kindness term in a particular node n is positive, then individual i 's utility increases if he/she chooses an action in that node which increases j 's payoff. The opposite holds when the kindness term is negative and i has an incentive to reduce j 's payoff. The model measures kindness in each node where i has the move, hence the overall reciprocity utility is the sum of the reciprocity utility in all nodes (before the considered end node), weighted with the reciprocity parameter (ρ_i).

The authors discuss the intuition of their theoretical prediction for public goods game. According to the authors: 'the strategic structure of a prisoner's dilemma is very similar to a public goods game'. In a sequential prisoner's dilemma, player 1 either cooperates or defects, and after observing player 1's outcome, player 2 also chooses to cooperate or defect. The subgame perfect solution is for both the players to defect. The above model predicts that if player 2 is sufficiently reciprocally motivated there is a positive probability that player 2 rewards player 1's cooperation with cooperation. Also, player 2 will defect if player 1 defects. Conditional cooperation between subjects can also be seen through the payoff function (Eq. 9), subjects contribute more if the contributions of other group members are also higher. In terms of model parameters: if player j is cooperative then kindness term ψ_j will be positive and if player i expresses response to experienced kindness then, σ_i is also positive. Since $\rho_i > 0$, i 's contribution increases in response to higher contribution by j .

The authors also substantiate their theoretical predictions with experimental results from Fischbacher et al. [23]. In their experiment, subjects could conditionally indicate how many tokens they wanted to contribute to public goods. The best strategy is to contribute nothing irrespective of others contributions, however, subjects' average contribution was increasing in the mean contributions of others. Using this conditional-cooperation strategy, more than half of the subjects were classified as "conditional cooperators" and the rest were classified as free riders.

Fehr and Gächter [19] also find evidence of reciprocity in their public goods experiment, the more a subject free rides relative to others the more he/she is punished. In order to test multiple preferences, Croson [15] conducts an experiment to test theories of commitment, theories of altruism, and theories of reciprocity in a public goods game. Almost all subjects demonstrate a positive correlation between their own contribution and belief of others' contributions, consistent with the theory of reciprocity.

4.4 *Heterogeneous Social Preferences*

Positive contribution towards public goods game can be explained and sustained through incorporation of others regarding preferences. We have discussed theoretical models of three types of social preferences along with their experimental evidence. These models incorporate heterogeneity, thereby allowing for the presence of different equilibria.

Experimental evidence in the public goods game, further add to the above observation. Chaudhuri [13] in his survey summarizes the advances made in the literature since Ledyard [34] by agreeing upon the presence of distinct types of players. These players differ in social preferences and/or their beliefs about others, which can explain their behavior being contrary to the standard theoretical prediction of free riding. Gunnthorsdottir et al. [27] in their voluntary contribution mechanism (VCM) public goods experiment classify the subjects into ‘free riders’ (contributes 30% or less of his/her endowment) and ‘cooperators’ (contributes more than 30%) based on their first round contribution.

Heterogeneous preferences can also explain the decline in cooperation in these experiments due to the presence of free riders [22]. The decline in cooperation over periods is suggested due to the “presence of imperfect conditional cooperators”, those who match others contributions but only partially. Interaction of “imperfect conditional cooperators” with free riders leads to an increase in free-rider behavior.

5 Extensions

In this section, we discuss extensions of the model of social preferences in public goods game. We explain how the effectiveness of ‘Coalition’ and ‘Networks’ increases through the incorporation of social preferences.

5.1 *Coalition Formation*

Coalitions, subgroups of individuals who agree to act collectively to produce public goods, represent a possible solution to the public goods problem. Coalitions such as International Environmental Agreements (IEA) where countries cooperate for an environmental cause are also observed in practice. Agents in a coalition first decide whether or not to join a coalition, then members decide how much to contribute. Social preferences also influence coalition size and their inclusion can lower the threshold for contributing to the public goods.

Kolstad [31] assumes homogeneous Charness and Rabin [12] preferences. Let there be $i = 1, 2, \dots, N$ countries, each with potential to emit w_i . Each country

chooses level of abatement (a public good) given by g_i or level of emissions $x_i = w_i - g_i$.

Welfare is positively affected by

1. Direct benefits of emitting: x_i . If the country has more emissions, the production cost reduces.
2. Aggregate level of abatement: G . Higher abatement leads to lower pollution levels or reduces the environmental damage.

National welfare (u_i) depends upon egoistic component/self centered (π_i) and pro-social or altruistic component (α_i). Altruistic component (α_i) depends on the vector of egoistic payoffs of other countries. The payoff is given as follows:

$$u_i(x_i, G) = \lambda_i \pi_i(x_i, G) + (1 - \lambda_i) \alpha_i(\pi) \quad (10)$$

Here, $\lambda_i \in [0, 1]$ reflects extent to which country is selfish or altruistic. Egoistic component can be described as following in a public goods game framework:

$$\pi_i = x_i + aG, \quad \text{where } x_i + g_i = w_i, G = \sum g_i \quad (11)$$

$$= w_i - g_i + aG, \quad \text{where } G = \sum g_i; 0 \leq g_i \leq w_i \quad (12)$$

Here, w_i is the maximum possible emissions for country i , g_i is the level of abatement for country i and G is aggregate abatement over all the countries. a represents the marginal per capita return (MPCR) and indicates how much an investment in abatement returns privately. The authors assume $a \in (1/(N - 1), 1)$. This is because, for $a = 1$, the individual will be indifferent between abating and non-abating (welfare from emitting and abatement have the same return). Small values of a are also excluded because coordination might not be enough for abatement.

Now we talk about the altruistic payoff in the utility function which is taken from Charness and Rabin [12].

$$\alpha_i(\pi) = [\delta_i (\min_{j \neq i} \pi_j) + \epsilon_i \sum_j \pi_j] / (1 - \lambda_i) \quad \text{where } \delta_i, \epsilon_i \geq 0; \delta_i + \epsilon_i + \lambda_i = 1 \quad (13)$$

Here, δ_i reflects relative importance of agent i of distribution/equity and ϵ_i reflects importance of efficiency. Equity is represented in the model by a Rawlsian preference which is the minimum monetary payoff over the rest of the population. Efficiency is represented by total monetary payoffs over the population. The inclusion of social preferences in the model reduces the threshold for contributing to the public goods. This result is given by Proposition 1 in the paper

Proposition 4 ([31, p. 15, Proposition 1]) *Assuming the N homogeneous player public goods game with Charness and Rabin social preferences, then*

1. *Efficient (Pareto Optimal) outcomes involve all countries undertaking maximal abatement; and*
2. *The Non-cooperative Nash equilibrium involves each agent either not abating ($g_i = 0$) or fully abating ($g_i = w_i$) according to*

$$g_i = 0 \quad \text{if } a < \bar{a}_i \quad (14)$$

$$g_i = w_i \quad \text{if } a > \bar{a}_i \quad (15)$$

$$\text{where } \bar{a}_i = (\lambda_i + \epsilon_i) / [1 + \epsilon_i(N - 1)]. \quad (16)$$

In case of standard preferences, the cutoff for abating and not abating is $a = 1$, with social preferences cutoffs are lower, by construction $\bar{a}_i < 1$. \bar{a}_i can also be interpreted as MPCR between cooperation and non-cooperation. Concerns for efficiency ($\epsilon_i > 0$), keeping δ_i constant also lowers \bar{a}_i . Thus, inclusion of social preferences reduces the cutoff for abating or not abating. With the presence of social preferences, countries find it individually rational to abate (provide public goods).

Ringius et al. [43] identify ‘fairness’ as a motivation for countries in environmental negotiation. The study also analyzes various IEA’s with negotiations leading to the Kyoto protocol and find considerations of fairness and equity to be building characteristics of these negotiations. In their empirical analysis, Lange et al. [33] show that equity issues are considered highly important in international climate negotiations by using a worldwide survey of people involved in international climate policy. Polluter pays rule (rule of equal ratio between abatement costs and emissions) and the accompanying poor losers rule (exempting due to GDP) are the most widely accepted equity principles according to this study.

Grüning et al. [26] in their paper incorporate fairness and justice in countries’ preferences. We now illustrate their utility function to understand how coalitions/IEA incorporate social preferences. The public goods problem arises because each country can choose their level of abatement (say reducing carbon emissions) and benefits from the reduced emissions by all the other countries as well. Country j ’s payoff can be represented by the following quasi-linear logarithmic function (consisting of benefit minus abatement cost) minus a term which measures heterogeneity by means of variance in all abatement strategies [26, p. 141, Eq. 1].

$$P_j = \ln \left(\sum_i a_i \right) - a_j - \theta \cdot \sigma(a_1, a_2, \dots, a_N) \quad (17)$$

In the above payoff, $\ln(\sum_i a_i)$, measure the benefit from abatement of all the countries. (a_i, a_j) measures the abatement levels of country i and j . $\sigma(a_1, a_2, \dots, a_N)$ measures variance in the environmental policies of all the countries. Variance is a measure of fairness and justice in their model since countries prefer a more egalitarian cost sharing. Variance in their model is defined as $\sum_i \frac{(a_i - \bar{a})^2}{N}$, where \bar{a} is the global average of all countries environmental policies. A country’s payoff is also assumed to be concave in its own strategy and continuous in that of the opponents. $\theta \geq 0$

represents preference intensity for welfare loss due to cost dispersion. For instance, $\theta = 0$ corresponds to the case of pure selfishness, increasing θ corresponds with stronger concern for ‘fair or just’ cost sharing. Equity concerns are homogeneous in this symmetric payoff function, however, their model is also robust to heterogeneous countries. The authors extend their results to asymmetry in measuring equity (σ is modified by incorporating countries self interest), heterogeneous countries (countries have different θ or different abatement costs).

The authors find that stronger fairness attitudes lead to homogeneous results as countries both inside and outside IEA adjust abatement levels to each other. This is explained by Proposition 1 from their paper

Proposition 5 ([26, p. 143, Proposition 1]) *Abatements inside and outside the coalition.*

1. *For signatories, stronger fairness preferences result in smaller abatement activities. If θ exceeds the threshold level $\tilde{\theta}$, even an outsider becomes active. The stronger θ , the more abatements an outsider carries out. In the limit (for $\theta \rightarrow \infty$) there is no difference between an insider and an outsider.*
2. *The aggregate does not significantly change in θ . For $\theta < \tilde{\theta}$; fairness has a negative impact on global abatements, while $A(S; \theta)$ remains constant for all θ exceeding the threshold $\tilde{\theta}$.*

Here $A(S; \theta)$, is the aggregate abatement activity and is given by

$$A(S; \theta) = S a_S^*(S, \theta) + (N - S) a_o^*(S, 0) \quad (18)$$

Here, $a_S^*(S, \theta)$ and $a_o^*(S, 0)$ are the abatement activities of countries inside and outside IEA, respectively. Countries in IEA are signatories and are represented by S . According to the above Proposition, if $\theta < \tilde{\theta}$ ³; outsiders are free riders and fairness concern leads to signatories reducing their abatements. This leads to a lower $A(S; \theta)$ or loss in environmental quality. For $\theta > \tilde{\theta}$, $A(S; \theta)$ does not change and for stronger θ countries abatement becomes similar, leading to not much difference between insider and outsider. In other words, stronger fairness preferences lead to more abatement by non-signatories. Fairness concerns imply that countries should not deviate too much from other countries’ environmental policies. This deviation is measured by the variance in the payoff function (Eq. 17). Fairness concern thus leads to similar abatements by signatories as well.

Thus, either all or almost none of the countries form an IEA. Internalization of the global environmental externality stabilizes IEA’s, whereas free riding hinders larger coalitions. Thus, stronger fairness preferences are needed to overcome the instability of grand coalition as these preferences favor similar behavior with respect to abatement.

Sarangi and Upadhyay [44] study the role of social preference in a two-stage public goods game where, in the first stage, heterogeneous agents first choose whether or not

³ $a_o^*(S, 0) = 0$ for $\theta < \tilde{\theta}$, see Grüning and Peters [26, p. 142, Eq. 5].

to join a coalition then, in the next stage, the coalition votes on whether its members will contribute. The preferences are assumed to be Rawlsian, wherein the individuals care about the least well-off person in the society.

Let there be $i = 1, 2, \dots, n$ players. The individuals payoff depend on their own payoff and the payoff of the least well-off person. λ_i is the weight on their own payoff. The utility function in their model is as follows:

$$\pi_i = \lambda_i(P_i) + (1 - \lambda_i)(\min(P_j)) \quad (19)$$

Here P_i is the monetary payoff of i and $\min(P_j)$ is the lowest monetary payoff of any player j .⁴

They find that individuals with stronger social preferences are more likely to join the coalition and vote for the coalition to contribute to the public goods. This can be summarized from Proposition 2 in their paper given below. Let the decision to join be given by j_i , $j_i = 1$ means individual joins the coalition and $j_i = 0$ implies individual does not join the coalition.

Proposition 6 ([44, p. 10, Proposition 2]) *In the subgame perfect Nash equilibrium, if $\lambda_i \leq \gamma$ then $j_i = 1$. If $\lambda_i > \gamma$ then $j_i = 0$.*

The threshold for joining the coalition ($\lambda_i \leq \gamma$), also satisfies the threshold for contributing to the public goods in their paper. Thus, incorporation of social preferences can result in a larger coalition. The result is intuitive since individuals with stronger social preferences are more likely to join the coalition and contribute to public goods.

The inclusion of social preferences lowers the thresholds for contribution and increases the likelihood of a larger coalition/grand coalition. Accounting for social preferences in the coalition framework helps in learning about the successful development of coalitions.

5.2 Network Formation

Bramoullé et al. [10] provide the first network model of public goods and answer how social or geographical structure affects the level and pattern of public goods. The study finds that individuals who have active social neighbors usually gain more from the contribution of others (due to more links) but contribute less to public goods. This is similar to the concept of free riding observed in a general public goods game. For similar reasons, an addition of a new link increases access to public goods, however, reduces an individual's incentive to contribute. Galeotti et al. [24] suggest that the effect of adding links to a network depends upon where is the link added.

Galeotti et al. [24] in their paper also examine patterns of social communication in a network. In the game, individuals choose to personally acquire information

⁴ Player i can also have the least payoff, in that case $\pi_i = P_i$.

and form connections with others. Main findings of the paper suggest that strict equilibrium of the game exhibits the “law of the few”. According to the “law of the few”, in a social group, small subset of individuals personally acquire information (called hub), while rest of the population forms connections with this small set of information acquirers. Individual information acquisition is a local public good game and implies that an equilibrium which entails links can lead to under provision of information acquisition. The socially optimal output is when central player in a star network acquires information and the others form links with hub. This happens when cost for forming an additional link is less than cost of acquiring information. If this is not the case, then in the social optimal outcome, all players acquire information and no one forms links.

Caria and Fafchamps [11] conduct a public good experiment on a star network (one central player and seven spokes). The design of the experiment is based on the theoretical work of Bramoullé et al. [10]. By design, the contribution of the center player benefits all individuals located at the spokes, while the contributions of the spokes only benefits the center. Following prediction from equity and efficiency, center player should be motivated to contribute more than the spokes. Also, the central player experiences ‘social pressure’ as other players also expect central player to contribute more than others. This is captured using the ‘guilt aversion’ model from Battigalli and Dufwenberg [7], where subjects experience guilt if their actions determine a payoff for other players that is lower than what these players expect.

Guilt aversion that star center i feel towards player j can be captured by [11, p. 397]

$$G_{ij}(c_i, \alpha_j, z) = \max\{E_j[\pi_j] - \pi_j, 0\} = \max\{r(\alpha_j^z - c_i^z), 0\} \quad (20)$$

Here, $E_j[\pi_j]$ is the expected payoff of spoke player j and π_j is the actual payoff of player j . c_i is the contribution profile of the star player, z indicates the average contribution of all spoke players. Thus, c_i^z indicates the contribution of player i when seven spokes have contributed on average z . α_j^z is the expectation profile of player j from player i when spoke members contribute on average z . r indicates the rate of return to public good contributions. Thus, guilt is a measure of the difference between player i 's contribution and what spoke members expect i to contribute.

Each player was also asked to predict the average value of contribution among the other 7 players for each level of z . α_i^z records how much player i expects other 7 players to contribute when they play as center of the star and spokes on average contribute z . $\bar{\alpha}_z$ is the contribution that individuals in the network, on an average, expect from a player at the center of the star. This is arrived at by taking the group expectations: average of α_i^z over all the eight players.

We now use their utility function to illustrate incorporation of social preference (guilt aversion here) in a Network [11, p. 397, Eq. 2].

$$u_i(c_i, \bar{\alpha}, z) = \pi_i - \frac{1}{7} \sum_{j \neq i} 7g_i * G_{ij}(c_i, \alpha_j, z) \quad (21)$$

Utility is monetary payoff minus cost of guilt central player experiences for each of the 7 spoke members. The authors assume that player i believes that each spoke has the same expectations, so that individual expectation coincide with group expectation ($\alpha_j = \bar{\alpha}$). Hence, the central player experiences same guilt towards each of the 7 spoke players. The utility function simplifies to [11, p. 397, Eq. 3]

$$u_i(c_i, \bar{\alpha}, z) = \pi_i - g_i * G_{ij}(c_i, \bar{\alpha}, z) \quad (22)$$

Here $G_{ij}(c_i, \bar{\alpha}, z) = \max\{r(\bar{\alpha}^z - c_i^z), 0\}$. The first term in the utility function, Eq. 22 reflects concern for monetary payoff and second term is cost of guilt. If player i is sufficiently averse to guilt, he/she will align his/her contributions to expectations of other players to minimize guilt. For instance, if player i contributes an amount lower than what other players expected, he/she will be guilty. Suppose player i increases contribution by one unit, this will decrease guilt of player i by $g_i r$.

The Contribution decisions in the game were made before assigning positions in the network. This was done in order to ask subjects how much they would like to contribute: (i) if they are assigned the spoke position and (ii) if they are assigned the center position. Contribution in case (i) is denoted by s_i and in case (ii) is denoted by c_i . Each player had three notes worth 50 INR and had to decide how many notes to contribute, thus $z \in \{0, 1, 2, 3\}$. For each value of z , central player has to decide how much he would like to contribute. Vector $c_i = (c_i^0, c_i^1, c_i^2, c_i^3)$ collects four conditional decision of player i . Subjects were also asked to predict the average value of contribution (c_j^z) among the other seven players for each value of z . This helps to get an estimate of α_j^z , and we thereby arrive at $\bar{\alpha}^z$. The results from the experiment suggest that subjects in the center contribute as much as the average contribution, thus suggesting evidence of ‘conditional cooperation’. Subjects play ‘conditional cooperation’ even when efficiency and equity concerns would require star player to contribute more than others. Disclosing group expectations significantly increases the contribution made by the star central player, thus confirming evidence of guilt aversion.

Altruism has been studied in a network framework [9], however, in the context of transfers. The structure of the network again plays a role in determining how income shocks lead to change in inequality. The consequence of change in altruism network is uncertain and also depends upon where the expansion takes place.

Zhang [47] investigate social preferences in a networks game. Their models incorporate inequity aversion [18] and welfare preferences [12]. The experiment manipulated the network structure: star or circle and the return from public good. Subjects at the core/center of a network contribute more than others in a star network. Subjects in a circular network, who earned less than others also contribute more than the predicted outcome in the subsequent period. This behavior suggests individuals exhibit welfare preferences rather than inequity aversion.

Cooperation is reinforced when conditional cooperators are more likely to interact. Thus, cooperation should fare better in highly clustered networks. Suri and Watts [46] conducted a series of web experiments in which individuals play local public goods game with network topology varying across the sessions. In contrast to the earlier results, they find that network topology had no significant effect on an average contribution. Players were as likely to decrease their contributions for low contributing neighbors as they were to increase their contributions in response to high contributing neighbors, thereby suggesting evidence of conditional cooperation. Positive effects of cooperation were contagious only to direct neighbors in the network.

6 Conclusion

Public goods simultaneously benefit many people and are vital to individuals and societies which further fosters economic growth. A key theme in public goods research is deciding how much of public goods to produce and how to pay for it. While public goods theory predicts free riding and inefficient outcomes, experimental results suggest the existence of cooperation, with contribution rates at 40–60 percent of the efficient level. Donations to charity, payment of taxes, voting in elections, and countries participating in IEA's are some of the other examples which support the claim that cooperation does exist. There are various mechanisms in the literature to reduce 'free riding'. Face-to-face communication, pledging the contribution, punishing the free riders are some of the effective tools to increase and sustain cooperation over the periods.

Studies on public goods highlight that human behavior is not entirely motivated by pure self interest. This has led to the formalization of others regarding preferences in the standard utility function. We have classified social preferences as impure altruism, fairness and inequity aversion, reciprocity and conditional cooperation. These models with social preferences are able to generate predictions for positive contribution and cooperation in a public goods game. However, there are variations in predictions of these models which arise from the heterogeneity of preferences of individuals. Further, the preference of one individual might vary, contingent on the situation. Thereby in some situations, an individual's behavior can be driven by fairness, while in other scenarios, he might be influenced by reciprocity.

Another possible solution to the public goods problem can be carried out through coalitions among individuals who agree to act collectively. Incorporation of social preferences in a public goods framework with coalition can then explain the existence of groups like IEA. Further incorporation of social preferences in a network framework can lead to interesting insights into a public goods game.

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