

A Reliable Analytical Algorithm for Cubic Isothermal Auto-Catalytic Chemical System



Khaled M. Saad, H. M. Srivastava and Devendra Kumar

Abstract In this work we apply an algorithm for the q -homotopy analysis transform method (q -HATM) to solve the Cubic Isothermal Auto-catalytic Chemical System (CIACS). This technique is a combination of the Laplace decomposition method and the homotopy analysis scheme. This method gives the solution in the form of a rapidly convergent series with h -curves are employed to determine the intervals of convergent. Averaged residual errors are used to determine the optimal values of h . We show the behavior of the solutions graphically. The q -HATM solutions are compared with Numerical results by Mathematica and with finite difference method and excellent agreement is found.

Keywords Cubic isothermal auto-catalytic chemical system · Laplace transform · q -homotopy analysis transform method

K. M. Saad (✉)

Department of Mathematics, College of Arts and Sciences, Najran University,
Najran, Saudi Arabia

e-mail: khaledma_sd@hotmail.com; kmalhamam@nu.edu.sa

Faculty of Applied Science, Department of Mathematics, Taiz University, Taiz, Yemen

H. M. Srivastava

Department of Mathematics and Statistics, University of Victoria, Victoria,
BC V8W 3R4, Canada

e-mail: harimsri@math.uvic.ca

Department of Medical Research, China Medical University Hospital,
China Medical University, Taichung 40402, Taiwan, Republic of China

D. Kumar

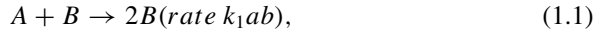
Department of Mathematics, University of Rajasthan, Jaipur 302004, Rajasthan, India
e-mail: devendra.maths@gmail.com; devendra.kumar@jecrcu.edu.in

© Springer Nature Singapore Pte Ltd. 2019

J. Singh et al. (eds.), *Mathematical Modelling, Applied Analysis and Computation*, Springer Proceedings in Mathematics & Statistics 272,
https://doi.org/10.1007/978-981-13-9608-3_17

1 Introduction

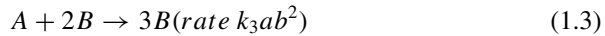
Merkin et al. in [26] investigated the reaction-diffusion traveling waves that occur in isothermal auto-catalysis chemical system. The researchers proposed that the reactions take place in two regions. These regions are separated and parallel. The quadratic auto-catalysis represents the reaction in region I and is presented by



with the step of the linear decay



where a and b are indicating the concentrations of reactant A and auto-catalyst B , the $k_i (i = 1, 2)$ are the rate constants and C is some inert product of reaction. The reaction in region II was the quadratic auto-catalytic step (1.1) only. The two regions were considered to be coupled through a linear diffusive interchange of the auto-catalytic species B . In this study we assume a similar kind of system as I, but having cubic auto-catalysis



together with a linear decay step



This gives to the system of equations below.

The subsequent nonlinear problem on $\varsigma > 0$ and $\tau > 0$ for the dimensionless concentrations (α_1, β_1) in region I and (α_2, β_2) in region II of species A and B is considered

$$\frac{\partial \alpha_1}{\partial \tau} = \frac{\partial^2 \alpha_1}{\partial \varsigma^2} - \alpha_1 \beta_1^2, \quad (1.5)$$

$$\frac{\partial \beta_1}{\partial \tau} = \frac{\partial^2 \beta_1}{\partial \varsigma^2} + \alpha_1 \beta_1^2 - k\beta_1 + \gamma(\beta_2 - \beta_1), \quad (1.6)$$

$$\frac{\partial \alpha_2}{\partial \tau} = \frac{\partial^2 \alpha_2}{\partial \varsigma^2} - \alpha_2 \beta_2^2, \quad (1.7)$$

$$\frac{\partial \beta_2}{\partial \tau} = \frac{\partial^2 \beta_2}{\partial \varsigma^2} + \alpha_2 \beta_2^2 + \gamma(\beta_1 - \beta_2), \quad (1.8)$$

with the boundary conditions

$$\alpha_i(0, \tau) = \alpha_i(L, \tau) = 1, \quad \beta_i(0, \tau) = \beta_i(L, \tau) = 0. \tag{1.9}$$

The dimensionless constants k and γ indicates the strength of the auto-catalyst decay and the coupling between the two regions respectively.

The system of Eqs. (1.5)–(1.8) also studied by [30] for space-fractional derivative. The fractional extension of CIACS is similarly useful and gives very interesting consequences, in this regards one can refer the work on fractional calculus [5, 18, 34, 37, 40]. The main idea of this work is to apply the q -HATM [19] on the CIACS and study the effectiveness and accuracy of this method. The q -HATM is a combination of q -HAM [19] and Laplace transform. Also we modified the work [31, 32] to q -HATM [19]. The convergence of q -HAM and applications of this method on models are studied in details [7, 14–17, 27].

The present article is organized as follows. The second section describes the basic idea of the standard q -HATM. The third section is devoted to the application of q -HATM to CIACS. The forth section is devoted to the numerical results. In the last section, we summarize the results in the conclusion.

2 Basic Ideas of the q -HATM

Definition 2.1 If D_τ^r is linear differential operator of order r , then the Laplace transform for the fractional derivative $D_\tau^r f(\tau)$ is given as

$$\mathcal{L}(D_\tau^r f(\tau)) = s^r F(s) - \sum_{k=0}^{r-1} f^{(k)}(0^+) s^{r-k-1}, \quad \tau > 0, \tag{2.1}$$

$$F(s) = \int_0^\infty f(\tau) e^{-s\tau} d\tau.$$

In order to illustrate the basic concepts and the treatment of this method we let $\mathcal{N}[\alpha(\varsigma, \tau)] = g(\varsigma, \tau)$, where \mathcal{N} represents the nonlinear partial differential operator in general. The Linear operator can be divided into two parts. The first part represents the linear operator of the highest order and indicates by L . The second part represents the reminder parts of the linear operator and indicates by R . So, it can be illustrated as

$$L\alpha(\varsigma, \tau) + R\alpha(\varsigma, \tau) + N\alpha(\varsigma, \tau) = g(\varsigma, \tau), \tag{2.2}$$

where $N\alpha(\varsigma, \tau)$ denotes the nonlinear terms. Now, if we let $L = D_\tau^r$ and apply the Laplace transform to Eq. (2.2) we obtain

$$\mathcal{L}[D_\tau^r \alpha(\varsigma, \tau)] + \mathcal{L}[R\alpha(\varsigma, \tau)] + \mathcal{L}[N\alpha(\varsigma, \tau)] = \mathcal{L}[g(\varsigma, \tau)]. \tag{2.3}$$

Making use of (2.1) we then have

$$\mathcal{L}[\alpha(\varsigma, \tau)] - \frac{1}{s} \sum_{i=0}^{r-1} \alpha^{(i)}(\varsigma, 0) s^{-i-1} + \frac{1}{s} \mathcal{L}[R\alpha(\varsigma, \tau) + N\alpha(\varsigma, \tau) - g(\varsigma, \tau)] = 0. \tag{2.4}$$

We express a nonlinear operator as

$$\begin{aligned} \mathcal{N}[\phi(\varsigma, \tau, q)] &= \mathcal{L}[\phi(\varsigma, \tau; q)] - \frac{1}{s} \sum_{i=0}^{r-1} \phi^{(i)}(\varsigma, 0) s^{-i-1} \\ &+ \frac{1}{s} \mathcal{L}[R(\phi(\varsigma, \tau; q)) + N\phi(\varsigma, \tau; q) - g(\varsigma, \tau)], \end{aligned} \tag{2.5}$$

In the above expression $q \in [0, 1/n]$ is denoting an embedding parameter and $\phi(\varsigma, \tau; q)$ is a real function of ς, τ and q . By modifying the well known concept of homotopy methods Liao [20–23] constructed the deformation equation of zero order written as

$$(1 - nq)\mathcal{L}[\phi(\varsigma, \tau; q) - \alpha_0(\varsigma, \tau)] = qhH(\varsigma, \tau)\mathcal{N}[\phi(\varsigma, \tau; q)], \tag{2.6}$$

Here $h \neq 0$ is an auxiliary parameter, $H(\varsigma, \tau) \neq 0$ is an auxiliary function, $\alpha_0(\varsigma, \tau)$ is an initial approximation for $\alpha(\varsigma, \tau)$ and $\phi(\varsigma, \tau; q)$ is an unknown function. It is obvious that, when $q = 0$ and $q = 1/n$, we have

$$\phi(\varsigma, \tau; 0) = \alpha_0(\varsigma, \tau), \quad \phi(\varsigma, \tau; 1) = \alpha(\varsigma, \tau), \tag{2.7}$$

respectively. Therefore, as q increases from 0 to $1/n$, then there is a variation in solution $\phi(\varsigma, \tau; q)$ from the initial approximation $\alpha_0(\varsigma, \tau)$ to the solution $\alpha(\varsigma, \tau)$. Writing $\phi(\varsigma, \tau; q)$ in series form by using Taylor theorem about q we get the following result

$$\phi(\varsigma, \tau; q) = \alpha_0(\varsigma, \tau) + \sum_{m=1}^{\infty} \alpha_m(\varsigma, \tau) q^m, \tag{2.8}$$

where

$$\alpha_m(\varsigma, \tau) = \frac{1}{m!} \frac{\partial^m \phi(\varsigma, \tau; q)}{\partial q^m} \Big|_{q=0}. \tag{2.9}$$

If various parameters, operators and the initial approximation are properly selected, the series (2.8) converges at $q = \frac{1}{n}$ and we get

$$\alpha(\varsigma, \tau) = \alpha_0(\varsigma, \tau) + \sum_{m=1}^{\infty} \varsigma_m(\varsigma, \tau) \left(\frac{1}{n}\right)^m. \tag{2.10}$$

Let us now define the vectors

$$\vec{\alpha}_m(\varsigma, \tau) = \{\alpha_0(\varsigma, \tau), \alpha_1(\varsigma, \tau), \alpha_2(\varsigma, \tau), \dots, \alpha_m(\varsigma, \tau)\}. \tag{2.11}$$

Now we differentiate the Eq. (2.6) m times with respect to q , then set $q = 0$ and finally divide them by $m!$, and we get

$$\mathcal{L}[\alpha_m(\varsigma, \tau) - \mathcal{X}_m \alpha_{m-1}(\varsigma, \tau)] = hH(\varsigma, \tau) \mathcal{R}_m(\vec{\alpha}_{m-1}(\varsigma, \tau)). \tag{2.12}$$

Here

$$\mathcal{R}_m(\vec{\alpha}_{m-1}) = \frac{1}{(m-1)!} \frac{\partial^{m-1}(\mathcal{N}[\phi(\varsigma, \tau; q)])}{\partial q^{m-1}} \Big|_{q=0} \tag{2.13}$$

and

$$\mathcal{X}_m = \begin{cases} 0 & \text{if } m \leq 1, \\ n & \text{if } m > 1. \end{cases}$$

On finding the inverse of Laplace transform of (2.12) we get a power series solution $\alpha(\varsigma, \tau) = \sum_{m=0}^{\infty} \alpha_m(\varsigma, \tau) (\frac{1}{n})^m$ of the original Eq. (2.2).

To determine the interval of convergence of the q -HATM solutions, we use the h -curves. We can obtain the h -curves by plotting the derivative of the q -HATM solutions with respect to τ against h and then setting $\tau = 0$. Finally, the horizontal line in the h curve which parallels the ς axis gives the interval of convergence [21]. However, this procedure cannot determine the optimal value of h . Hence, we use the procedure which has been discussed by [3, 10, 24, 31, 32, 39]. Let

$$\Delta(h) = \int_{\Omega} (\mathcal{N}(\alpha_n(\varsigma, \tau)))^2 d\Omega, \tag{2.14}$$

which denotes the exact square residual error for Eq. (2.2) integrated over the whole physical region. As $\Delta(h) \rightarrow 0$, the rate of convergence of the q -HATM solution

increases. To obtain the optimal values of the convergence control parameter h , we minimize $\Delta(h)$ associated with the nonlinear algebraic equation

$$\frac{d\Delta(h)}{dh} = 0. \tag{2.15}$$

2.1 Convergence Analysis

To establish the convergence of the solution, we first need to give some conditions needed to prove the convergence of the series (2.10). These have been given by Odibat [29] and Elbeleze et al. [8] and Huseen and El-Tawil [14] via the following theorem:

Theorem 2.1.1 *Let the solution components $\alpha_0, \alpha_1, \alpha_2, \dots$ be expressed as given in (2.12). The series solution $\sum_{m=0}^{\infty} \alpha_m (\frac{1}{n})^m$ written in (2.10) converges if $\exists 0 < r < n$ s.t. $\|\alpha_{m+1}\| \leq (\frac{r}{n}) \|\alpha_m\|$ for all $m \geq m_0$, for some $m_0 \in N$.*

Moreover, the estimated error is given by

$$\|\alpha - \sum_{m=0}^k \alpha_m (\frac{1}{n})^m\| \leq \frac{1}{1 - (\frac{r}{n})} (\frac{r}{n})^{k+1} \|\alpha_0\|. \tag{2.16}$$

3 q-HATM solution of CIACS

In this portion, we apply the q -HATM on CIACS. We take the initial conditions to satisfy the boundary conditions, namely

$$\alpha_i(\varsigma, 0) = 1 - \sum_{n=1}^{\infty} a_{ni} \cos(0.5(L - 2\varsigma)\lambda) \sin(\lambda L/2), \quad (i = 1, 2), \tag{3.1}$$

$$\beta_i(\varsigma, 0) = \sum_{n=1}^{\infty} b_{ni} \cos(0.5(L - 2\varsigma)\lambda) \sin(\lambda L/2), \quad (i = 1, 2), \tag{3.2}$$

where $\lambda = \frac{n\pi}{L}$. As we know that HAM is based on a particular type of continuous mapping

$$\alpha_i(\varsigma, \tau) \rightarrow \phi_i(\varsigma, \tau; q), \quad \beta_i(\varsigma, \tau) \rightarrow \psi_i(\varsigma, \tau; q)$$

such that, as the embedding parameter q increases from 0 to $1/n$, $\phi_i(\varsigma, \tau; q)$, $\psi_i(\varsigma, \tau; q)$ and $i = 1, 2$ varies from the initial iteration to the exact solution.

We now present the nonlinear operators

$$\begin{aligned} \mathcal{N}_i(\phi_i(\varsigma, \tau; q)) &= \mathcal{L}_i(\phi_i(\varsigma, \tau; q)) - \frac{1}{s}\alpha_i(\varsigma, 0) \\ &\quad + \frac{1}{s}\mathcal{L}_i\left(-\phi_{i,\varsigma\varsigma}(\varsigma, \tau; q) + \phi_i(\varsigma, \tau; q)\psi_i^2(\varsigma, \tau; q)\right), \\ \mathcal{M}_i(\psi_i(\varsigma, \tau; q)) &= \mathcal{L}_i(\psi_i(\varsigma, \tau; q)) - \frac{1}{s}\beta_i(\varsigma, 0) \\ &\quad + \frac{1}{s}\mathcal{L}_i\left(-\psi_{i,\varsigma\varsigma}(\varsigma, \tau; q) + (-2(i-1)k + ik)\psi_i(\varsigma, \tau; q) \right. \\ &\quad \left. + (-1)^i\gamma(\psi_1(\varsigma, \tau; q) - \psi_2(\varsigma, \tau; q)) - \phi_i(\varsigma, \tau; q)\psi_i^2(\varsigma, \tau; q)\right). \end{aligned}$$

Now, we develop a set of equations, using the embedding parameter q

$$(1 - nq)\mathcal{L}_i(\phi_i(\varsigma, \tau; q) - \alpha_{i0}(\varsigma, \tau)) = qhH(\varsigma, \tau)\mathcal{N}_i(\phi_i(\varsigma, \tau; q)),$$

$$(1 - nq)\mathcal{L}_i(\psi_i(\varsigma, \tau; q) - \beta_{i0}(\varsigma, \tau)) = qhH(\varsigma, \tau)\mathcal{M}_i(\psi_i(\varsigma, \tau; q)),$$

with the initial conditions

$$\phi_i(\varsigma, 0; q) = \alpha_{i0}(\varsigma, 0), \quad \psi_i(\varsigma, 0; q) = \beta_{i0}(\varsigma, 0), \quad (i = 1, 2)$$

where $h \neq 0$ and $H(\varsigma, \tau) \neq 0$ are the auxiliary parameter and the auxiliary function, respectively. We expand $\phi_i(\varsigma, \tau; q)$ and $\psi_i(\varsigma, \tau; q)$ in series form by employing the Taylor theorem with respect to q , and get

$$\phi_i(\varsigma, \tau; q) = \alpha_{i0}(\varsigma, \tau) + \sum_{m=1}^{\infty} \alpha_{im}(\varsigma, \tau)q^m, \tag{3.3}$$

$$\psi_i(\varsigma, \tau; q) = \beta_{i0}(\varsigma, \tau) + \sum_{m=1}^{\infty} \beta_{im}(\varsigma, \tau)q^m, \tag{3.4}$$

where

$$\alpha_{im}(\varsigma, \tau) = \frac{1}{m!} \frac{\partial^m \phi_i(\varsigma, \tau; q)}{\partial q^m} \Big|_{q=0},$$

$$\beta_{im}(\varsigma, \tau) = \frac{1}{m!} \frac{\partial^m \psi_i(\varsigma, \tau; q)}{\partial q^m} \Big|_{q=0}.$$

If we let $q = \frac{1}{n}$ into (3.3)–(3.4), the series become

$$\alpha_i(\varsigma, \tau) = \alpha_{i0}(\varsigma, \tau) + \sum_{m=1}^{\infty} \alpha_{im}(\varsigma, \tau) \left(\frac{1}{n}\right)^m,$$

$$\beta_i(\varsigma, \tau) = \beta_{i0}(\varsigma, \tau) + \sum_{m=1}^{\infty} \beta_{im}(\varsigma, \tau) \left(\frac{1}{n}\right)^m.$$

Now, we construct the m th-order deformation equation from (2.12)–(2.13) as follows:

$$\mathcal{L}_i(\alpha_{im}(\varsigma, \tau) - \mathcal{X}_m \alpha_{i(m-1)}(\varsigma, \tau)) = hH(\varsigma, \tau)R_1((\vec{\alpha}_{i(m-1)}, \vec{\beta}_{i(m-1)})),$$

$$\mathcal{L}_i(\beta_{im}(\varsigma, \tau) - \mathcal{X}_m \beta_{i(m-1)}(\varsigma, \tau)) = hH(\varsigma, \tau)R_2((\vec{\alpha}_{i(m-1)}, \vec{\beta}_{i(m-1)})),$$

with initial conditions $\alpha_{im}(\varsigma, 0) = 0, \beta_{im}(\varsigma, 0) = 0, m > 1$ where

$$\begin{aligned} R_1((\vec{\alpha}_{i(m-1)}, \vec{\beta}_{i(m-1)})) &= \mathcal{L}_i(\alpha_{i(m-1)}(\varsigma, \tau)) - \frac{1}{s}\alpha_i(\varsigma, 0)\left(1 - \frac{\mathcal{X}_m}{n}\right) \\ &+ \frac{1}{s}\mathcal{L}_i(-\alpha_{i(m-1),\varsigma\varsigma}(\varsigma, \tau) + \alpha_{i(m-1)}(\varsigma, \tau)\beta_{i(m-1)}^2(\varsigma, \tau)), \end{aligned}$$

$$\begin{aligned} R_2((\vec{\alpha}_{i(m-1)}, \vec{\beta}_{i(m-1)})) &= \mathcal{L}_{i(m-1)}(\beta_{i(m-1)}(\varsigma, \tau)) - \frac{1}{s}\beta_i(\varsigma, 0)\left(1 - \frac{\mathcal{X}_m}{n}\right) \\ &+ \frac{1}{s}\mathcal{L}_i(-\beta_{i(m-1),\varsigma\varsigma}(\varsigma, \tau) + (-2(i-1)k + ik)\beta_{i(m-1)}(\varsigma, \tau) \\ &+ (-1)^i\gamma(\beta_{1(m-1)}(\varsigma, \tau) - \beta_{2(m-1)}(\varsigma, \tau)) \\ &- \alpha_{i(m-1)}(\varsigma, \tau)\beta_{i(m-1)}^2(\varsigma, \tau; q)). \end{aligned}$$

If we take $\mathcal{L}_i =$ Laplace transform ($i = 1, 2$) then the right inverse of $\mathcal{L}_i =$ inverse Laplace transform will be \mathcal{L}_i^{-1}

$$\alpha_{im} = \mathcal{X}_m \alpha_{i(m-1)} + h\mathcal{L}_i^{-1}R_1((\vec{\alpha}_{i(m-1)}, \vec{\beta}_{i(m-1)})), \tag{3.5}$$

$$\beta_{im} = \mathcal{X}_m \beta_{i(m-1)} + h\mathcal{L}_i^{-1}R_2((\vec{\alpha}_{i(m-1)}, \vec{\beta}_{i(m-1)})). \tag{3.6}$$

4 Numerical Results

In this part, we compute the first approximations. We show the behavior of the solution graphically and investigate the intervals of convergence by the h -curves. Also, we will compute the average residual error. Finally, we will check the accuracy of the q -HATM solutions by comparing with another numerical method using the command NDSolve by Mathematica. We take the initial approximation

$$\alpha_{i0}(\varsigma, \tau) = \alpha_{i0}(\varsigma, 0), \beta_{i0}(\varsigma, \tau) = \beta_{i0}(\varsigma, 0). \tag{4.1}$$

For $m = 1$, we obtain the first approximation as following:

$$\alpha_{i1} = h\mathcal{L}_i^{-1} \left(\mathcal{L}_i(\alpha_{i0}(\varsigma, \tau)) - \frac{1}{s}\alpha_i(\varsigma, 0)(1 - \frac{\mathcal{X}_m}{n}) \right) \tag{4.2}$$

$$+ \frac{1}{s}\mathcal{L}_i(-\alpha_{i0,\varsigma\varsigma}(\varsigma, \tau) + \alpha_{i0}(\varsigma, \tau)\beta_{i0}^2(\varsigma, \tau)) \tag{4.3}$$

$$\beta_{i1} = h\mathcal{L}_i^{-1} \left(\mathcal{L}_i(\beta_{i0}(\varsigma, \tau)) - \frac{1}{s}\beta_i(\varsigma, 0)(1 - \frac{\mathcal{X}_m}{n}) \right) \tag{4.4}$$

$$+ \frac{1}{s}\mathcal{L}_i(-\beta_{i0,\varsigma\varsigma}(\varsigma, \tau) + (-2(i - 1)k + ik)\beta_{i0}(\varsigma, \tau)) \tag{4.5}$$

$$+ (-1)^i\gamma(\beta_{10}(\varsigma, \tau) - \beta_{20}(\varsigma, \tau) - \alpha_{i0}(\varsigma, \tau)\beta_{i0}^2(\varsigma, \tau; q)) \tag{4.6}$$

And by the similar procedure we can evaluate the rest of the approximation.

First we show the q -HATM solutions for CIACS for different values of τ . In Fig. 1 the q -HATM solutions are displayed against ς for $n = 5, k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.08, a_{n_2} = 0.07, b_{n_1} = 0.0054, b_{n_2} = 0.0055$ with $\tau = 0.5, 15, 50$. From this figure we find that the oscillation produced by the reaction in the system of finite size. And also, we find that, beside the boundaries, the q -HATM solutions are more significant compared the q -HATM solutions far away from the boundaries. The amplitude of the oscillation decays with increasing the distance from the boundaries. These behaviors agree with [4, 6, 9]. It is clear that the symmetric pattern for CIACS with respect to $\varsigma = L/2$. The two dominant modes generated from the boundaries are travelling towards the center. Thus permanent travelling waves solution exists in systems of finite size with periodic initial conditions and these behaviors agree with [25]. For more details for the effects of other parameters on the behaviors of CIACS see [26, 33].

4.1 h -Curves

To observe the intervals of convergence of the q -HATM solutions, we draw the h -curves of 5 terms of q -HATM solutions in Figs. 2, 3 and 4 for $n = 1, 5$ and $n = 20$ respectively. In Fig. 2a, we draw $\alpha_{1\tau}(\varsigma, 0), \alpha_{2\tau}(\varsigma, 0)$ and in Fig. 2b we draw $\beta_{1\tau}(\varsigma, 0), \beta_{2\tau}(\varsigma, 0)$ against h respectively at $k = 0.01, \gamma = 0.4, L = 100, \varsigma = 20, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. From these figures, we note that the straight line that parallels the h -axis provides the valid region of the convergence [21].

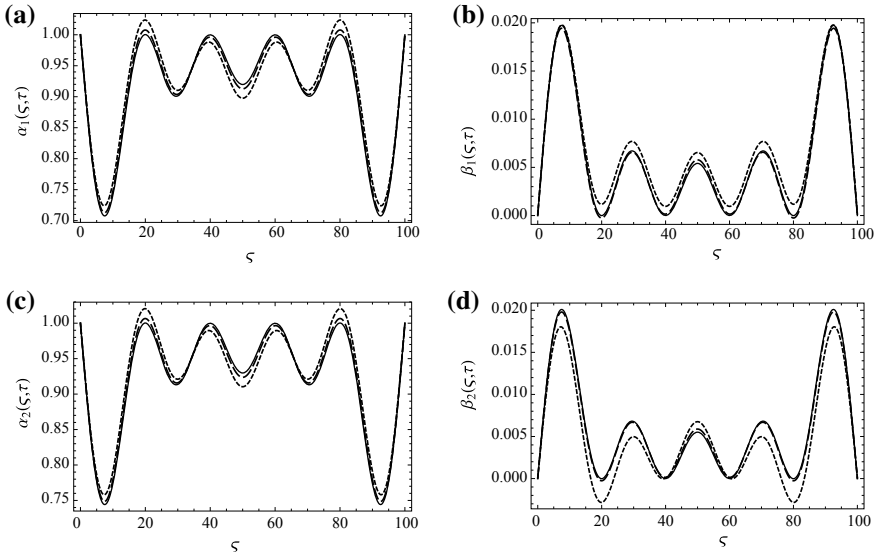


Fig. 1 The q -HATM solutions are displayed against ζ for $n = 5, k = 0.01, \gamma = 0.4, L = 100, a_{n_1} = 0.08, a_{n_2} = 0.07, b_{n_1} = 0.0054, b_{n_2} = 0.0055$. Solid line: $\tau = 0.5$, Dash line: $\tau = 15$, and Dot line: $\tau = 50$

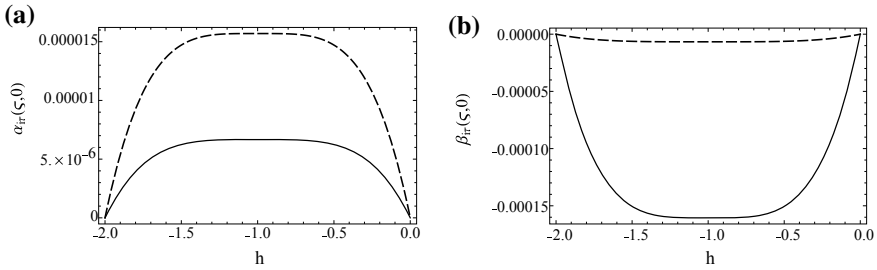


Fig. 2 The h -curve of the 5-terms of q -HATM solutions at $n = 1, k = 0.1, \gamma = 0.2, L = 100, \zeta = 20, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. Solid line = $\alpha_{1\tau}(\zeta, 0), \beta_{1\tau}(\zeta, 0)$, Dash line = $\alpha_{2\tau}(\zeta, 0), \beta_{2\tau}(\zeta, 0)$

4.2 Average Residual Errors

We notice, however, that h -curve does not give the best value of the parameter h . So, we evaluate the optimal values of the convergence-control parameters by the minimum of the averaged residual errors [1–3, 11, 13, 24, 31, 32, 35, 36, 38, 39]

$$E_{\alpha_i}(h) = \frac{1}{NM} \sum_{s=0}^N \sum_{j=0}^M \left[\mathcal{N} \left(\sum_{k=0}^m \alpha_{ik} \left(\frac{100s}{N}, \frac{30j}{M} \right) \right) \right]^2, \quad (4.7)$$

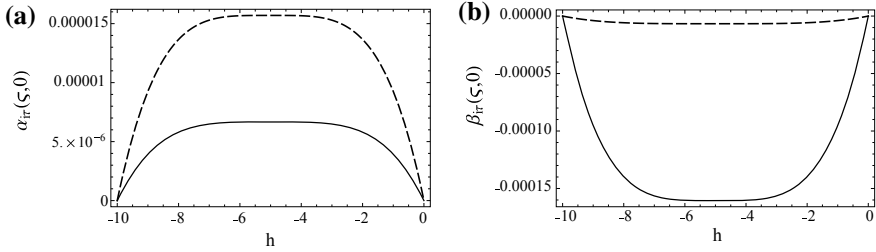


Fig. 3 The h -curve of the 5-terms of q -HATM solutions at $n = 5, k = 0.1, \gamma = 0.2, L = 100, \zeta = 20, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. Solid line = $\alpha_{1r}(\zeta, 0), \beta_{1r}(\zeta, 0)$, Dash line = $\alpha_{2r}(\zeta, 0), \beta_{2r}(\zeta, 0)$

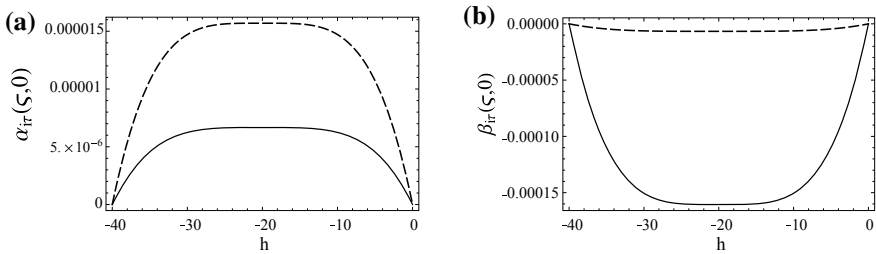


Fig. 4 The h -curve of the 5-terms of q -HATM solutions at $n = 20, k = 0.1, \gamma = 0.2, L = 100, \zeta = 20, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. Solid line = $\beta_{1r}(\zeta, 0), \alpha_{1r}(\zeta, 0)$, Dash line = $\alpha_{2r}(\zeta, 0), \beta_{2r}(\zeta, 0)$

$$E_{\beta_i}(h) = \frac{1}{NM} \sum_{s=0}^N \sum_{j=0}^M \left[\mathcal{M} \left(\sum_{k=0}^m \beta_{ik} \left(\frac{100s}{N}, \frac{30j}{M} \right) \right) \right]^2, \tag{4.8}$$

corresponding to a nonlinear algebraic equations

$$\frac{dE_{\alpha_i}(h)}{dh} = 0, \tag{4.9}$$

$$\frac{dE_{\beta_i}(h)}{dh} = 0. \tag{4.10}$$

We show $E_{\alpha_i}(h)$ and $E_{\beta_i}(h)$ in Figs. 5, 6, 7 and 8 and in Table 1 for different values of n . Figures 3–8 and Table 2 show that the $E_{\alpha_i}(h)$ and $E_{\beta_i}(h)$ for 5 terms q -HATM solutions. We set into (4.9)–(4.10) $N = 100$ and $M = 30$ with $k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. We use the command Find Minimum and Minimize of Mathematica and the plotting of residual error against h to get the optimal values h .

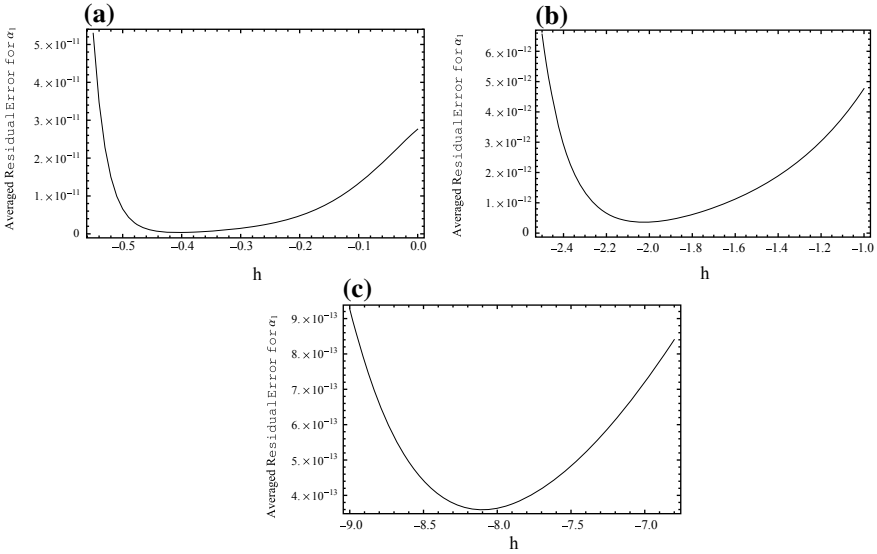


Fig. 5 The averaged residual errors at the 5-terms of the q -HATM solutions for $\alpha_1(\zeta, \tau)$ with $0 \leq \zeta \leq 100, 0 \leq \tau \leq 30, k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. **a** $n = 1, \mathbf{b} n = 5, \mathbf{c} n = 20$

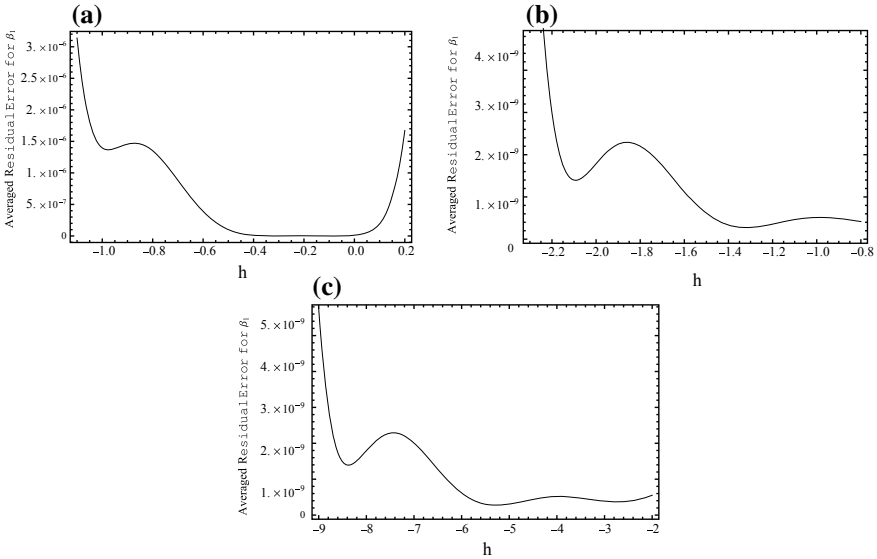


Fig. 6 The averaged residual errors at the 5-terms of the q -HATM solutions for $\beta_1(\zeta, \tau)$ with $0 \leq \zeta \leq 100, 0 \leq \tau \leq 30, k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. **a** $n = 1, \mathbf{b} n = 5, \mathbf{c} n = 20$

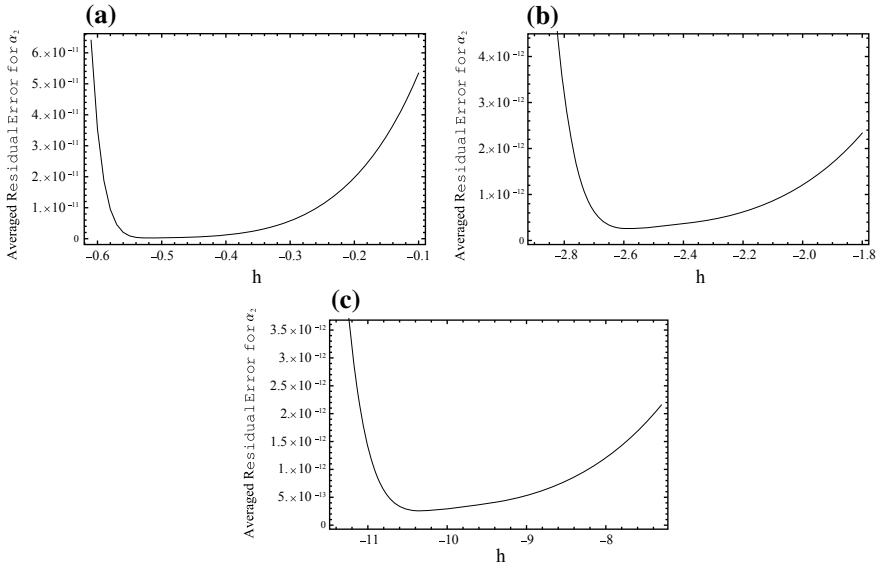


Fig. 7 The averaged residual errors at the 5-terms of the q -HATM solutions for $\alpha_2(\zeta, \tau)$ with $0 \leq \zeta \leq 100, 0 \leq \tau \leq 30, k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. **a** $n = 1$, **b** $n = 5$, **c** $n = 20$

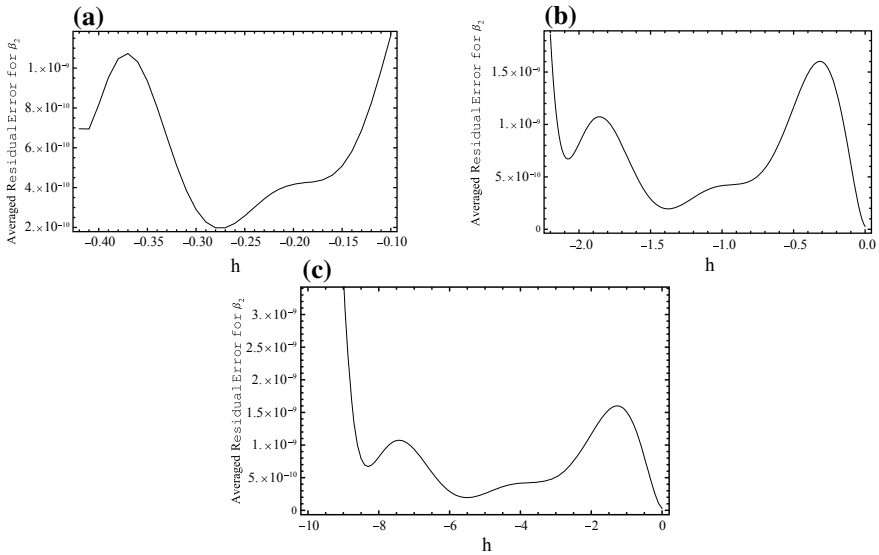


Fig. 8 The averaged residual errors at the 5-terms of the q -HATM solutions for $\beta_2(\zeta, \tau)$ with $0 \leq \zeta \leq 100, 0 \leq \tau \leq 30, k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. **a** $n = 1$, **b** $n = 5$, **c** $n = 20$

Table 1 Optimal values of h for q -HATM solutions of $\alpha_i(\zeta, \tau)$ at $0 \leq \zeta \leq 100, 0 \leq \tau \leq 30, k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$

n	Optimal value of h_{α_1}	Minimum of $E_{\alpha_1}(h)$	Optimal value of h_{α_2}	Minimum of $E_{\alpha_2}(h)$
1	-0.404028	3.59782×10^{-13}	-0.520508	2.3569×10^{-13}
5	-2.02603	3.59593×10^{-13}	-2.63657	3.02373×10^{-13}
20	-8.10413	3.59593×10^{-13}	-10.3873	2.55769×10^{-13}

Table 2 Optimal values of h for q -HATM solutions of $\beta_i(\zeta, \tau)$ at $0 \leq \zeta \leq 100, 0 \leq \tau \leq 30, k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$

n	Optimal value of h_{β_1}	Minimum of $E_{\beta_1}(h)$	Optimal value of h_{β_2}	Minimum of $E_{\beta_2}(h)$
1	-0.137431	7.02541×10^{-10}	-0.223388	3.67024×10^{-10}
5	-1.18981	3.67977×10^{-10}	-1.38421	1.95288×10^{-10}
20	-5.34697	2.76228×10^{-10}	-5.50912	1.94929×10^{-10}

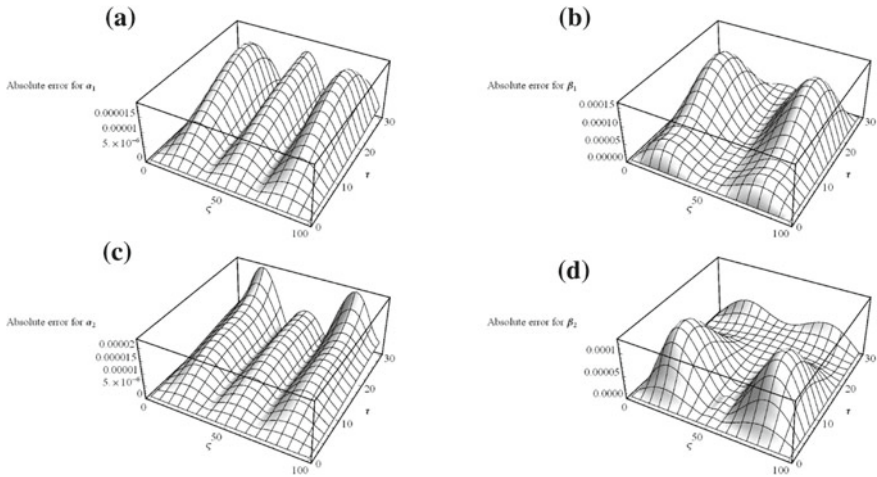


Fig. 9 The comparison of the 5-terms of the q -HATM solutions with numerical method in Mathematica for $n = 5, h_{\alpha_1} = -0.30, h_{\beta_1} = -0.18, h_{\alpha_2} = -0.30, h_{\beta_2} = -0.21, k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$

4.3 Comparison Analysis

Now, we compare 5-terms of q -HATM solutions obtained with a numerical method using the commands with Mathematica 9 for solving CIACS numerically. We draw the 5-terms of HATM solutions in Fig.9. Figure 9 shows the comparison of q -HATM solutions with numerical method for $n = 5, k = 0.1, \gamma = 0.2, L = 100, a_{n_1} = 0.001, a_{n_2} = 0.002, b_{n_1} = 0.001, b_{n_2} = 0.002$. We observed from this figure that the QHATM solutions have a good agreement with the results by Mathematica.

We also compare our results also with finite differences method. We discretise with time step: $\Delta\tau = \frac{T}{N_\tau}$ and in space with grid spacing $\Delta\varsigma = \frac{L}{N_\varsigma}$, and let $\tau_j = j\Delta\tau$, where $0 \leq j \leq N_\tau$ and $\varsigma_n = n\Delta\varsigma$, $0 \leq n \leq N_\varsigma$. We put $\alpha_{1,n}^j = \alpha_1(\varsigma, \tau)$, $\beta_{1,n}^j = \beta_1(\varsigma, \tau)$, $\alpha_{2,n}^j = \alpha_2(\varsigma, \tau)$ and $\beta_{2,n}^j = \beta_2(\varsigma, \tau)$. Then the finite differences approximations for (1.5)–(1.8) are given by

$$\alpha_{1,n}^{j+1} = (1 - 2r)\alpha_{1,n}^j + r(\alpha_{1,n+1}^j + \alpha_{1,n-1}^j) - \Delta\tau(\alpha_{1,n}^j(\beta_{1,n}^j)^2), \tag{4.11}$$

$$\begin{aligned} \beta_{1,n}^{j+1} &= (1 - 2r)\beta_{1,n}^j + r(\beta_{1,n+1}^j + \beta_{1,n-1}^j) \\ &+ \Delta\tau \left(-k\beta_{1,n}^j + \gamma(\beta_{2,n}^j - \beta_{1,n}^j) - (\alpha_{1,n}^j(\beta_{1,n}^j)^2) \right), \end{aligned} \tag{4.12}$$

$$\alpha_{2,n}^{j+1} = (1 - 2r)\alpha_{2,n}^j + r(\alpha_{2,n+1}^j + \alpha_{2,n-1}^j) - \Delta\tau(\alpha_{2,n}^j(\beta_{2,n}^j)^2), \tag{4.13}$$

$$\begin{aligned} \beta_{1,n}^{j+1} &= (1 - 2r)\beta_{1,n}^j + r(\beta_{1,n+1}^j + \beta_{1,n-1}^j) - \beta_{1,n}^j \\ &+ \gamma(\beta_{1,n}^j - \beta_{2,n}^j) - \Delta\tau(\alpha_{1,n}^j(\beta_{1,n}^j)^2), \end{aligned} \tag{4.14}$$

where $r = \frac{\Delta\tau}{(\Delta\varsigma)^2}$. We mention that here we use the central difference scheme for the space derivatives of second order and the forward difference scheme for the time derivative of order one [28]. The initial and boundary conditions become

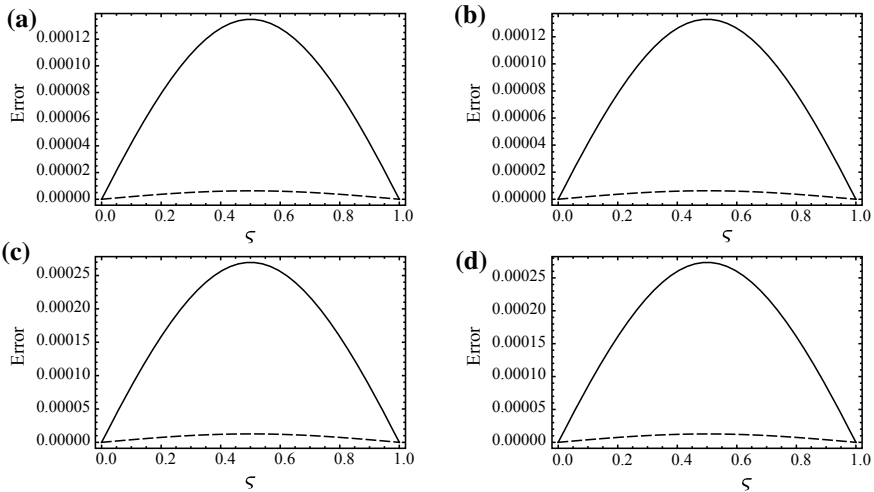


Fig. 10 The absolute error between the 6-terms of the q -HATM solutions with numerical solutions by (4.11)–(4.14) scheme for **a** α_1 , **b** β_1 , **c** α_2 , and **d** β_2 with $h = -1.95$, $k = 0.1$, $\gamma = 0.2$, $L = 1$, $T = 1$, $\Delta\varsigma = \frac{1}{50}$, $\Delta\tau = \frac{1}{9000}$, $a_{n1} = 0.001$, $a_{n2} = 0.002$, $b_{n1} = 0.001$, $b_{n2} = 0.002$. Solid line ($n = 1$), Dashed line ($n = 5$)

$$\alpha_{i,n}^0 = \alpha_i(\zeta(n)) = \alpha_{i,n}, \beta_{i,n}^0 = \beta_i(\zeta(n)) = \beta_{i,n}, \quad i = 1, 2, \quad n = 0, 1, 2, \dots, N_\zeta,$$

$$\alpha_{i,0}^j = 1 = \alpha_{i,N}^j, \beta_{i,0}^j = 0 = \beta_{i,N}^j, \quad i = 1, 2, \quad j = 1, 2, \dots, N_\tau.$$

Stable solutions with the (4.11)–(4.14) scheme are only obtained if $r < \frac{1}{2}$. See, e.g., [12, 28] for a proof that this condition gives the stability limit for the (4.11)–(4.14) scheme. In Fig. 10, the absolute error between the q -HATM solutions and the numerical solutions by the (4.11)–(4.14) scheme are plotted. Also, in this figure we show that the effect of the factor $\frac{1}{n}$ on the accelerate of the convergence. It is clear when n is increasing, the absolute error is decreasing.

5 Conclusion

In this paper, the q -HATM was employed to analytically compute approximate solutions of CIACS. By comparing q -HATM solutions with results by Mathematica, the averaged residual error the residual error and finite difference method were found an excellent agreement. Also the effected on the accelerating of the convergence by the factor $\frac{1}{n}$ is shown. Mathematica was used for the computations of this article.

Competing Interests The authors declare that there is no conflict of interests regarding the publication of this paper.

References

1. Abbasbandy, S., Jalili, M.: Determination of optimal convergence-control parameter value in homotopy analysis method. *Numer. Algorithms* **64**(4), 593–605 (2013)
2. Abbasbandy, S., Shivanian, E.: Predictor homotopy analysis method and its application to some nonlinear problems. *Commun. Nonlinear Sci. Numer. Simulat.* **16**, 2456–2468 (2011)
3. Abo-Dahab, S.M., Mohamed, M.S., Nofal, T.A.: A one step optimal homotopy analysis method for propagation of harmonic waves in nonlinear generalized magnetothermoelasticity with two relaxation times under influence of rotation. *Abstr. Appl. Anal.* (Hindawi Publishing Corporation) 14 pages (2013). Article ID 614874
4. Britton, N.F.: *Reaction-Diffusion Equations and Their Applications to Biology*. Academic, New York (1986)
5. Cattani, C., Srivastava, H.M., Yang, X.-J. (eds.): *Fractional Dynamics*. Emerging Science Publishers (De Gruyter Open), Berlin and Warsaw (2015)
6. Debnath, L.: *Nonlinear Partial Differential Equations for Scientists and Engineers*. Birkhauser, Boston (1997)
7. El-Tawil, M.A., Huseen, S.N.: The q -homotopy analysis method (q -ham). *Int. J. Appl. Math. Mech.* **8**, 51–75 (2012)
8. Elbeleze, A.A., Kılıçman, A., Taib, B.M.: Note on the convergence analysis of homotopy perturbation method for fractional partial differential equations. *Abstr. Appl. Anal.* (Hindawi Publishing Corporation) **2014**, (2014)

9. Epstein, I.R., Pojman, J.A.: *An Introduction to Nonlinear Chemical Dynamics: Oscillations, Waves, Patterns and Chaos*. Oxford, New York (1998)
10. Gepreel, K.A., Mohamed, M.S.: An optimal homotopy analysis method nonlinear fractional differential equation. *J. Adv. Res. Dyn. Control Syst.* **6**(1), 1–10 (2014)
11. Ghanbari, M., Abbasbandy, S., Allahviranloo, T.: A new approach to determine the convergence-control parameter in the application of the homotopy analysis method to systems of linear equations. *Appl. Comput. Math.* **12**(3), 355–364 (2013)
12. Golub, G., Ortega, J.M.: *Scientific Computing: An Introduction with Parallel Computing*. Academic Press Inc, Boston (1993)
13. Gondal, M.A., Arife, A.S., Khan, M., Hussain, I.: An efficient numerical method for solving linear and nonlinear partial differential equations by combining homotopy analysis and transform method. *World Appl. Sci. J.* **14**(12), 1786–1791 (2011)
14. Huseen, S.N., El-Tawil, M.A.: On convergence of the q-homotopy analysis method. *Int. J. Contemp. Math. Sci.* **8**, 481–497 (2013)
15. Huseen, S.N., Grace, S.R.: Approximate solutions of nonlinear partial differential equations by modified q-homotopy analysis method (mq-ham). *J. Appl. Math.* (Hindawi Publishing Corporation) (2013). Article ID 569674 9
16. Huseen, S.N., Grace, S.R., El-Tawil, M.A.: The optimal q-homotopy analysis method (oq-ham). *Int. J. Comput. Technol.* **11**(8), 2859–2866 (2013)
17. Iyiola, O.S.: q-homotopy analysis method and application to fingero-imbibition phenomena in double phase flow through porous media. *Asian J. Curr. Eng. Math.* **2**, 283–286 (2013)
18. Kilbas, A.A., Srivastava, H.M., Trujillo, J.J.: *Theory and Applications of Fractional Differential Equations*, vol. 204. Elsevier (North-Holland) Science Publishers, Amsterdam (2006)
19. Kumar, D., Singh, J., Baleanu, D.: A new analysis for fractional model of regularized long-wave equation arising in ion acoustic plasma waves. *Math. Methods Appl. Sci.* **40**, 5642–5653 (2017)
20. Liao, S.-J. : The proposed homotopy analysis technique for the solution of nonlinear problems. Ph.D. thesis, Shanghai Jiao Tong University (1992)
21. Liao, S.-J.: *Beyond Perturbation: Introduction to the Homotopy Analysis Method*. Chapman and Hall/CRC Press, Boca Raton (2003)
22. Liao, S.-J.: On the homotopy analysis method for nonlinear problems. *Appl. Math. Comput.* **147**, 499–513 (2004)
23. Liao, S.-J.: Comparison between the homotopy analysis method and homotopy perturbation method. *Appl. Math. Comput.* **169**, 1186–1194 (2005)
24. Liao, S.-J.: An optimal homotopy-analysis approach for strongly nonlinear differential equations. *Commun. Nonlinear Sci. Numer. Simul.* **15**(8), 2003–2016 (2010)
25. Merkin, J.H., Leach, J.A., Scott, S.K.: Oscillations and waves in the belousov-zhabotinskii reaction in a finite medium. *J. Math. Chem.* **16**, 115–124 (1994)
26. Merkin, J.H., Needham, D.J., Scott, S.K.: Coupled reaction-diffusion waves in an isothermal autocatalytic chemical system. *IMA J. Appl. Math.* **50**, 43–76 (1993)
27. Mohamed, M.S., Hamed, Y.S.: Solving the convection diffusion equation by means of the optimal q-homotopy analysis method (oq-ham). *Results Phys.* **6**, (2016)
28. Morton, K.W., Mayers, D.F.: *Numerical Solution of Partial Differential Equations: An Introduction*. Cambridge University Press, Cambridge England (1994)
29. Odibat, Z.M.: A study on the convergence of homotopy analysis method. *Appl. Math. Comput.* **217**(2), 782–789 (2010)
30. Saad, K.M.: An approximate analytical solutions of coupled nonlinear fractional diffusion equations. *J. Fract. Calculus Appl.* **5**(1), 58–70 (2014)
31. Saad, K.M., AL-Shareef, E.H., Mohamed, M.S., Yang, X.-J.: Optimal q-homotopy analysis method for time-space fractional gas dynamics equation. *Eur. Phys. J. Plus* **132**(1), 23 (2017)
32. Saad, K.M., AL-Shomrani, A.A.: An application of homotopy analysis transform method for riccati differential equation of fractional order. *J. Fract. Calculus Appl.* **7**(1), 61–72 (2016)
33. Saad, K.M., El-Shrae, A.M.: Travelling waves in a cubic autocatalytic reaction. *Adv. Appl. Math. Sci.* **8**, 01 (2011)

34. Saad, K.M., Srivastava, H.M., Kumar, D.: A reliable analytical algorithm for time and space fractional cubic isothermal auto-catalytic chemical system. In preparing
35. Singh, J., Kumar, D., Swroop, R.: Numerical solution of time- and space-fractional coupled burgers equations via homotopy algorithm. *Alexandria Eng. J.* **55**(2), 1753–1763 (2016)
36. Singh, J., Kumar, D., Swroop, R., Kumar, S.: An efficient computational approach for time-fractional rosenau-hyman equation. *Neural Comput. Appl.* **45**, 192–204 (2017). <https://doi.org/10.1007/s00521-017-2909-8>
37. Singh, H., Srivastava, H.M., Kuma, D.: A reliable numerical algorithm for the fractional vibration equation. *Chaos Solitons Fractals* **103**, 131–138 (2017)
38. Srivastava, H.M., Kumar, D., Singh, J.: An efficient analytical technique for fractional model of vibration equation. *Appl. Math. Modell.* **45**, 192–204 (2017)
39. Yamashita, M., Yabushita, K., Tsuboi, K.: An analytic solution of projectile motion with the quadratic resistance law using the homotopy analysis method. *J. Phys. A. Math. Gen.* **40**, 8403–8416 (2007)
40. Yang, X.-J., Baleanu, D., Srivastava, H.M.: *Local Fractional Integral Transforms and Their Applications*. Academic Press (Elsevier Science Publishers), Amsterdam, Heidelberg, London and New York (2016)