The Schwarz Lemma for Super-Conformal Maps

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Abstract A super-conformal map is a conformal map from a two-dimensional Riemannian manifold to the Euclidean four-space such that the ellipse of curvature is a circle. Quaternionic holomorphic geometry connects super-conformal maps with holomorphic maps. We report the Schwarz lemma for super-conformal maps and related results.

Introduction 1

For a smooth manifold M, we denote the tangent bundle by TM and its fiber at $p \in M$ by $T_n M$. Let Σ be a two-dimensional oriented Riemannian manifold and $f: \Sigma \to \mathbb{R}^4$ be an isometric immersion. We denote the Riemannian metric of Σ by g. For a tangent vector $X \in T_p \Sigma$, we denote the norm with respect to the Riemannian metric by ||X||. We denote the second fundamental form of f by h. Then

$$\mathscr{E}_p = \left\{ h(X, X) : X \in T_p \Sigma, \|X\| = 1 \right\}$$

is called the *ellipse of curvature* or the *curvature ellipse* of f at $p \in M$ [9]. It is indeed an ellipse in the normal space at p if it does not degenerate to a point or a line segment. If the ellipse of curvature is a circle or a point at any point p, then fis said to be *super-conformal* [2].

The author showed that a super-conformal map is a Bäcklund transform of a minimal surface [6]. Regarding f as an isometric immersion, the inequality

$$|\mathscr{H}|^2 - K - |K^{\perp}| \ge 0 \tag{1}$$

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holds between the mean curvature vector \mathcal{H} , the Gaussian curvature K and the normal curvature K^{\perp} [10]. The equality holds if and only if f is super-conformal. From this point of view, a super-conformal map is called a Wintgen ideal surface [8]. The integral of the left-hand side of (1) over Σ is the Willmore energy of f. This implies that a super-conformal map is a Willmore surface with vanishing Willmore energy. Hence the super-conformality is invariant under Möbius transforms of \mathbb{R}^4 .

We discuss the Möbius geometry of super-conformal immersion by exchanging a two-dimensional oriented Riemannian manifold with a Riemann surface and an isometric immersion with a conformal immersion. Regarding \mathbb{C} as a subspace of \mathbb{R}^4 and a holomorphic function on Σ as a map form Σ to \mathbb{R}^4 , a holomorphic function satisfies (1) and it is super-conformal. We may regard Möbius geometric theory of holomorphic functions on a Riemann surface as a special case of Möbius geometry of super-conformal immersion.

The author [7] discussed super-conformal maps as a higher codimensional analogue of holomorphic functions and meromorphic functions. In this paper, we report a part of the paper which discusses the Schwarz lemma for super-conformal maps.

For the discussion, we use quaternionic holomorphic geometry [3]. Quaternionic holomorphic geometry of surfaces in \mathbb{R}^4 connects theory of holomorphic functions with theory of surfaces in \mathbb{R}^4 .

2 Classical Results

We begin with reviewing the classical results of super-conformal maps by Friedrich [4] and Wong [11].

Throughout this paper, all manifolds and maps are assumed to be smooth. We compute the ellipse of curvature. We denote the inner product of \mathbb{R}^4 by \langle , \rangle . Let e_1 , e_2 , e_3 , e_4 be an adapted orthonormal local frame of the pull-back bundle $f^*T\mathbb{R}^4$ and $\theta_1, \theta_2, \theta_3, \theta_4$ the dual frame. Assume that the second fundamental form is

$$h = \sum_{p=3}^{4} \sum_{i,j=1}^{2} h_{ijp} \,\theta_i \otimes \theta_j \otimes e_p.$$

Then the ellipse of curvature is parametrized by the map

$$\varepsilon(u) = h(e_1 \cos u + e_2 \sin u, e_1 \cos u + e_2 \sin u)$$

= $\mathscr{H} + \left(\frac{h_{113} - h_{223}}{2}e_3 + \frac{h_{114} - h_{224}}{2}e_4\right)\cos 2u + (h_{123}e_3 + h_{124}e_4)\sin 2u.$

The map f is super-conformal map if and only if $\varepsilon(u)$ parametrizes a circle. The map f is minimal if and only if $\varepsilon(u)$ parametrize a curve of the linear transform of the circle centered at the origin. The linear transform is given by

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$$P(e_3 \ e_4) = (e_3 \ e_4) \begin{pmatrix} h_{113} \ h_{123} \\ h_{114} \ h_{124} \end{pmatrix}$$

Hence f is super-conformal and minimal if and only if the ellipse of curvature is a circle centered at the origin.

We normalize the second fundamental form and the ellipse of curvature. Let $n(u) = e_3 \cos u + e_4 \sin u$. Because

$$\langle h, n(u) \rangle = \sum_{i,j=1}^{2} h_{ij3} \,\theta_i \otimes \theta_j \cos u + \sum_{i,j=1}^{2} h_{ij4} \,\theta_i \otimes \theta_j \sin u,$$

$$\operatorname{tr} \langle h, n(u) \rangle = h_{113} \cos u + h_{114} \sin u + h_{223} \cos u + h_{224} \sin u$$

$$= (h_{113} + h_{223}) \cos u + (h_{114} + h_{224}) \sin u,$$

we may assume that $h_{114} + h_{224} = 0$. Let A_{e_4} be the shape operator such that $\langle A_{e_4}(X), Y \rangle = \langle h(X, Y), e_4 \rangle$ for any $X, Y \in T_p \Sigma$. Taking e_1 and e_2 as the eigenvectors of A_{e_4} , we may assume that $h_{124} = 0$. The ellipse of curvature becomes

$$\varepsilon(u) = \frac{h_{113} + h_{223}}{2}e_3 + \left(\frac{h_{113} - h_{223}}{2}e_3 + h_{114}e_4\right)\cos 2u + (h_{123}e_3)\sin 2u.$$

Then f is super-conformal if and only if

$$(h_{113} - h_{223})h_{123} = 0, \ \left(\frac{h_{113} - h_{223}}{2}\right)^2 + h_{114}^2 = h_{123}^2$$

This is equivalent to

$$h_{123} = h_{114} = 0$$
, $h_{113} = h_{223}$ or $h_{113} = h_{223}$, $h_{114}^2 = h_{123}^2$.

Hence the ellipse of curvature of a super-conformal map becomes

$$\varepsilon(u) = 0 \text{ or } \varepsilon(u) = h_{113} + (h_{114}e_4)\cos 2u + (\pm h_{114}e_3)\sin 2u.$$

If f is minimal, then the ellipse of curvature is

$$\varepsilon(u) = (h_{113}e_3 + h_{114}e_4)\cos 2u + (h_{123}e_3)\sin 2u.$$

Hence f is super-conformal and minimal if and only if

$$\varepsilon(u) = (h_{114}e_4)\cos 2u + (\pm h_{114}e_3)\sin 2u$$

Another notion is defined by the second fundamental form for surfaces in \mathbb{R}^4 .

Definition 1 ([5, 11]) The set

$$\mathscr{I}_p = \left\{ \langle h, n \rangle : n \in T_p \Sigma^{\perp}, \|n\| = 1 \right\}.$$

is called the *indicatrix* of the normal curvature or the *Kommerell conic* of f.

The indicatrix is parametrized by

$$\iota(u) = \langle h, n(u) \rangle = \sum_{i,j=1}^{2} (h_{ij3} \cos u + h_{ij4} \sin u) \theta_i \otimes \theta_j.$$

By the normalization, we may assume that

$$\iota(u) = (h_{113}\cos u + h_{114}\sin t)\theta_1 \otimes \theta_1 + h_{123}\cos u \theta_1 \otimes \theta_2$$
$$+h_{213}\cos u \theta_2 \otimes \theta_1 + (h_{223}\cos u - h_{114}\sin u)\theta_2 \otimes \theta_2.$$

We regard $\langle h, n(u) \rangle$ as the shape operator which is is a symmetric (1, 1)-tensor. With the standard inner product of symmetric (1, 1)-tensors, the curve $\langle h, n(u) \rangle$ is isometrically the curve parametrized by

$$\iota(u) = \left(\frac{1}{\sqrt{2}}(h_{113}\cos u + h_{114}\sin u), \sqrt{2}h_{123}\cos u, \frac{1}{\sqrt{2}}(h_{223}\cos u - h_{114}\sin u)\right)$$

in \mathbb{R}^3 . Hence f is super-conformal if and only if the indicatrix is parametrized by

$$\iota(u) = \left(\frac{1}{\sqrt{2}}(h_{113}\cos u), 0, \frac{1}{\sqrt{2}}(h_{113}\cos u)\right)$$

or

$$\iota(u) = \left(\frac{1}{\sqrt{2}}(h_{113}\cos u + h_{114}\sin u), \pm \sqrt{2}h_{114}\cos u, \frac{1}{\sqrt{2}}(h_{113}\cos u - h_{114}\sin u)\right).$$

We see that f is minimal if and only if the indicatrix is parametrized by

$$\iota(u) = \left(\frac{1}{\sqrt{2}}(h_{113}\cos u + h_{114}\sin u), \sqrt{2}h_{123}\cos u, \frac{1}{\sqrt{2}}(-h_{113}\cos u - h_{114}\sin u)\right).$$

Moreover, f is super-conformal and minimal if and only if

$$\iota(u) = 0 \text{ or } \iota(u) = \left(\frac{1}{\sqrt{2}}(h_{114}\sin u), \pm\sqrt{2}h_{114}\cos u, \frac{1}{\sqrt{2}}(-h_{114}\sin u)\right).$$

Set

$$\mathscr{I}_p(X) = \left\{ \langle h(X, \cdot), n \rangle : n \in T_p \Sigma^{\perp}, \|n\| = 1 \right\} \subset (T_p \Sigma)^*.$$

Definition 2 ([4]) An immersion f is called *superminimal* if $\mathscr{I}_p(X)$ is a circle centered at 0 in $(T_p \Sigma)^*$.

The following lemma explains the relation among the super-conformal maps, minimal surfaces and superminimal surfaces.

Lemma 1 A map f is superminimal if and only if f is super-conformal and minimal.

Proof For $X = X_1e_1 + X_2e_2$ and the normalization, we have

$$\langle h(X, \cdot), n(u) \rangle = \sum_{i,j=1}^{2} X_i h_{ij3} \theta_j \cos u + \sum_{i,j=1}^{2} X_i h_{ij4} \theta_j \sin u$$

= $((X_1 h_{113} + X_2 h_{123}) \theta_1 + (X_1 h_{123} + X_2 h_{223}) \theta_2) \cos u$
+ $(X_1 h_{114} \theta_1 - X_2 h_{114} \theta_2) \sin u.$

Hence f is superminimal if and only if

$$(X_1^2 h_{113} - X_2^2 h_{223})h_{114} = 0,$$

$$(X_1 h_{113} + X_2 h_{213})^2 + (X_1 h_{123} + X_2 h_{223})^2 = (X_1^2 + X_2^2)h_{114}^2$$

Hence

$$h_{114} = X_1 h_{113} + X_2 h_{213} = X_1 h_{123} + X_2 h_{223} = 0$$

or

$$X_1^2 h_{113} - X_2^2 h_{223} = 0,$$

$$(X_1 h_{113} + X_2 h_{123})^2 + (X_1 h_{123} + X_2 h_{223})^2 = (X_1^2 + X_2^2) h_{114}^2$$

Because X_1 and X_2 is arbitrary under $X_1^2 + X_2^2 \neq 0$, we have h = 0, or $h_{113} = h_{223} = 0$ and $h_{123}^2 = h_{114}^2$. Hence the lemme holds.

For a holomorphic function g(z) on \mathbb{C} , define a map $\tilde{g} \colon \mathbb{C} \to \mathbb{C}^2 \cong \mathbb{R}^4$ by $\tilde{g}(z) = (z, g(z))$. Then \tilde{g} is called an *R*-surface [5]. Kommerell showed that an *R*-surface is superminimal.

3 Quaternionic Holomorphic Geometry

We review super-conformal maps by quaternionic holomorphic geometry of surfaces in \mathbb{R}^4 [2]. We identify \mathbb{R}^4 with the set of all quaternions \mathbb{H} . The inner product of \mathbb{R}^4 becomes

$$\langle a, b \rangle = \operatorname{Re}(\overline{a}b) = \operatorname{Re}(\overline{b}a) = \frac{1}{2}(\overline{a}b + \overline{b}a).$$

We identify \mathbb{R}^3 with the set of all imaginary parts of quaternions Im \mathbb{H} . Then two-dimensional sphere with radius one centered at the origin in \mathbb{R}^3 is $S^2 = \{a \in \text{Im } \mathbb{H} : a^2 = -1\}$.

Let Σ be a Riemann surface with complex structure J_{Σ} . For a one-form ω on Σ , we define a one-form $*\omega$ by $*\omega = \omega \circ J_{\Sigma}$. A map $f: \Sigma \to \mathbb{H}$ is called a conformal map if $\langle df \circ J_{\Sigma}, df \rangle = 0$. This is equivalent to that *df = N df = -df R with maps $N, R: \Sigma \to S^2$. Each point where f fails to be an immersion is isolated. This means that a conformal map is a branched immersion. The second fundamental form of f is

$$h(X,Y) = \frac{1}{2} (*df(X) dR(Y) - dN(X) * df(Y)).$$

Let $\mathscr{H} \colon \varSigma \to \mathbb{H}$ be the mean curvature vector of f. Then

$$df \,\overline{\mathscr{H}} = -\frac{1}{2} (* \, dN + N \, dN), \ \overline{\mathscr{H}} \, df = \frac{1}{2} (* \, dR + R \, dR).$$

The ellipse of curvature is

$$\mathscr{E}_{p} = \left\{ \mathscr{H} |df(e_{1})|^{2} + \frac{1}{4} \cos 2\theta (a - b)(e_{1}) + \frac{1}{4} \sin 2\theta N(a + b)(e_{1}) : \theta \in \mathbb{R} \right\},\$$
$$a = df (*dR - R dR), \ b = (*dN - N dN) df.$$

Then f is super-conformal if and only one of the following equations holds.

$$*dR - RdR = 0, *dN - NdN = 0$$

at any point $p \in \Sigma$.

In the following, we restrict ourselves to super-conformal maps with *dN = N dN.

Lemma 2 A super-conformal map $f: \Sigma \to \mathbb{H}$ with *df = N df and *dN = N dN is superminimal if and only if f is holomorphic with respect to a right quaternionic linear complex structure of \mathbb{H} .

Proof A super-conformal map $f: \Sigma \to \mathbb{H}$ with *df = N df and *dN = N dN satisfies the equation

$$df \ \overline{\mathscr{H}} = -N \ dN.$$

Hence f is minimal if and only if N is a constant map. Define $J: \mathbb{H} \to \mathbb{H}$ by Jv = Nv for any $v \in \mathbb{H}$. Then J is a right quaternionic linear complex structure of \mathbb{H} . Because *df = J df, the map f is holomorphic with respect to J.

By the above lemma, we see that a holomorphic map g from Σ to $\mathbb{C}^2 \cong \mathbb{C} \oplus \mathbb{C} j \cong \mathbb{H}$ is superminimal because * dg = i dg. A holomorphic function and an *R*-surface are special cases of this superminimal surface.

4 The Schwarz Lemma

Because a holomorphic function is a super-conformal map, we may expect that a super-conformal map is an analogue of a holomorphic function. A factorization of super-conformal map given in Theorem 4.3 in [7] may support this idea. The following is a variant of the theorem.

Theorem 1 ([7], Theorem 4.3) Let $\phi: \Sigma \to \mathbb{H}$ be a super-conformal map with $*d\phi = N d\phi, *dN = N dN$ and $N\phi = \phi i$ and $h: \Sigma \to \mathbb{C}^2 \cong \mathbb{C} \oplus \mathbb{C} j \cong \mathbb{H}$ be a holomorphic map. Then, a map $f = \phi h$ is a super-conformal map with *df = N df.

This theorem shows that a holomorphic section of a complex vector bundle of rank two, trivialized by the super-conformal map f is a super-conformal map. We see that N + i is a super-conformal map with N(N + i) = (N + i)i. The condition *dN = N dN implies N is the inverse of the stereographic projection followed by an anti-holomorphic function ([7], Corollary 3.2). Hence if Σ is an open Riemann surface and $N: \Sigma \to S^2$ is the inverse of the stereographic projection of an anti-holomorphic function with $N(\Sigma) \subset S^2 \setminus \{-i\}$, then N + i is a global super-conformal trivializing section. A super-conformal map $f: \Sigma \to \mathbb{H}$ with *df = N df, *dN = N dN always factors f = (N + i)h with a holomorphic map $h: \Sigma \to \mathbb{C} \oplus \mathbb{C}j$. We don't need to see -i in a special light. If $a \in S^2$ and $a \notin N(\Sigma)$, then we can rotate f so that $-i \notin N(\Sigma)$. The condition that N fails to be surjective is necessary.

This fact suggests that we should distinguish the case where the Riemann surface Σ is parabolic or hyperbolic. In the case where $\Sigma = \mathbb{C}$, we have an analogue of Liouville's theorem.

Theorem 2 ([7], Theorem 4.4) Let $\phi : \mathbb{C} \to \mathbb{H}$ be a super-conformal map with $*d\phi = N d\phi, *dN = N dN$ and $N\phi = \phi i$. Assume that $N(\mathbb{C}) \subset S^2 \setminus \{-i\}$ and $|\phi|^{-1}$ is bounded above. If $f : \mathbb{C} \to \mathbb{H}$ is a super-conformal map with *df = N df and |f| is bounded above, then $f = \phi C$ for some constant $C \in \mathbb{H}$.

In the case where $\Sigma = B^2 = \{z \in \mathbb{C} : |z| < 1\}$, we have an analogue of the Schwarz lemma.

Theorem 3 ([7], Theorem 4.5) Let $\phi: B^2 \to \mathbb{H}$ be a super-conformal map with $*d\phi = N d\phi, *dN = N dN$ and $N\phi = \phi i$. Assume that $N(B^2) \subset S^2 \setminus \{-i\}$ and $|\phi| < c$ and $|\phi|^{-1} < \tilde{c}$. If $f: B^2 \to \mathbb{H}$ is a super-conformal map with *df = N df and f(0) = 0, then there exists a constant C such that

$$|f(z)| \le C|z|.$$

Moreover, if $f = \phi(\lambda_0 + \lambda_1 j)$ for holomorphic functions λ_0 and λ_1 , then there exist constants C_0 , $C_1 > 0$ such that

$$|f(z)| \le c(C_0^2 + C_1^2)^{1/2} |z|.$$

The equality holds if and only if $\phi = c$ and there exists $z_0 \in B^2$ such that $|\lambda_n(z)| = C_n |z_0|$ (n = 0, 1). We also have

$$\left|f_{x}(0) - N(0)f_{y}(0)\right| \leq c(C_{0}^{2} + C_{1}^{2})^{1/2}.$$

The equality holds if and only if f = c and there exists $z_0 \in B^2$ such that $|\lambda_n(z)| = C_n |z_0|$ (n = 0, 1).

Assume that $f(B^2) \subset B^4 = \{a \in \mathbb{H} : |a| < 1\}$. It is known that

$$T(a) = \frac{(1 - |a_1|^2)(a - a_1) - |a - a_1|^2 a_1}{1 + |a|^2 |a_1|^2 - 2\langle a, a_1 \rangle}$$

is a Möbius transform of \mathbb{R}^4 with $T(a_1) = 0$ [1]. The transform T is

$$T(a) = \frac{a - a_1 - |a_1|^2 a + |a_1|^2 a_1 - |a|^2 a_1 + a|a_1|^2 + a_1 \overline{a}a_1 - |a_1|^2 a_1}{|1 - \overline{a}_1 a|^2}$$
$$= \frac{a - a_1 - |a|^2 a_1 + a_1 \overline{a}a_1}{|1 - \overline{a}_1 a|^2} = \frac{(1 - a_1 \overline{a})(a - a_1)}{|1 - \overline{a}_1 a|^2}$$
$$= (1 - a\overline{a}_1)^{-1}(a - a_1)$$

and T preserves B^4 . If $f: B^2 \to B^4$ is a super-conformal map with *df = N dfand *dN = N dN, then

$$*d(T \circ f) = (1 - f\overline{a}_1)^{-1} (*df\overline{a})(1 - f\overline{a}_1)^{-1}(1 - f) - (1 - f\overline{a}_1)^{-1} * df$$

= $(1 - f\overline{a}_1)^{-1} N(1 - f\overline{a}_1) d(T \circ f).$

It is known that a Möbius transform of a super-conformal map is super-conformal. Then we have an analogue of the Schwarz-Pick theorem. **Theorem 4** ([7], Theorem 4.7) Let $\phi: B^2 \to B^4$ be a super-conformal map with $*d\phi = N d\phi, *dN = N dN$ and $N\phi = \phi i$. Assume that $|\phi|$ and $|\phi|^{-1}$ are bounded. Let $f: \Sigma \to \mathbb{H}$ be a super-conformal map with *df = N df. Assume that the map

$$\tilde{N} := (1 - \tilde{f}(z)\overline{\tilde{f}(z_1)})^{-1}N(1 - \tilde{f}(z)\overline{\tilde{f}(z_1)}) \colon \Sigma \to S^2$$

satisfies $\tilde{N}(B^2) \subset S^2 \setminus \{-i\}$. Then there exists a constant C > 0 such that

$$\frac{|f(z) - f(z_1)|}{\left|1 - \overline{f(z_1)}f(z)\right|} \le C \frac{|z - z_1|}{|1 - \overline{z_1}z|}$$

Moreover,

$$\frac{|f_x(z_1)|}{1-|f(z_1)|^2} = \frac{|f_y(z_1)|}{1-|f(z_1)|^2} \le \frac{C}{1-|z_1|^2}.$$

We fix Riemannian metrics $ds_{B^2}^2$ on B^2 and $ds_{B^4}^2$ on B^4 as

$$ds_{B^2}^2 = \frac{4}{(1 - (x^2 + y^2))^2} (dx \otimes dx + dy \otimes dy),$$
$$ds_{B^4}^2 = \frac{4}{(1 - \sum_{n=0}^3 a_n^2)^2} (\sum_{n=0}^3 da_n \otimes da_n).$$

Then a geometric version of the Schwarz-Pick theorem becomes as follows.

Theorem 5 Let $\phi: B^2 \to B^4$ be a super-conformal map with $* d\phi = N d\phi, * dN = N dN$ and $N\phi = \phi i$. Assume that $|\phi|$ and $|\phi|^{-1}$ are bounded. Let $f: \Sigma \to \mathbb{H}$ be a super-conformal map with * df = N df. Assume that the map

$$\tilde{N} := (1 - f(z)\overline{f(z_1)})^{-1}N(1 - f(z)\overline{f(z_1)}) \colon \Sigma \to S^2$$

satisfies $\tilde{N}(B^2) \subset S^2 \setminus \{-i\}$. Then there exists a constant C > 0 such that $f^*ds_{B^4}^2 \leq Cds_{B^2}^2$.

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