
Monitoring Performance and Progression in the Operating Theatre

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Take-Home Messages

- The definition of standardised benchmarks is required to define arthroscopic competency.
- Measuring surgical performance comes with challenges, but new developments such as affordable tracking systems and video analysis software can facilitate structural implementation.
- Objective monitoring of resident learning curves is feasible using global rating scales.
- ASSET and BAKSSS global rating scales are validated most extensively and suggested to be used in clinical practice, where ASSET offers potential for summative assessment of arthroscopic skills.

continued in the operating room to achieve the necessary proficiency. Based on the theory on learning strategies in Chap. 4, it is posed that if residents indeed acquire the basic skills before they enter the operating room, the focus in the operating room can be on more complex tasks. This requires the formulation of guidelines that determine the level that qualifies proficiency. For the actual cases in the operating room, this is a difficult task as the level of complexity of the procedure plays an important role, and proficiency is not necessarily defined as the summation of several part-task skills, but rather requires a holistic approach.

Generally, the complexity of an arthroscopy is divided in two levels: basic (removal) and advanced (reconstruction), e.g. meniscectomy vs. anterior cruciate ligament (ACL) reconstruction (Morris et al. 1993; O'Neill et al. 2002). For elbow arthroscopy, five levels of complexity have been defined (Savoie 2007). To cope with the complexity and support the holistic judgment, faculty members from recognised institutions that have performed a substantial number of procedures (>250) themselves qualify to judge proficiency (Morris et al. 1993; O'Neill et al. 2002) – a method that is being applied in many residency curricula. Despite arthroscopy being performed frequently, consensus is to be attained on the exact definition of arthroscopic competence and the number of procedures that are required to achieve it (Hodgins and Veillette 2013; O'Neill et al. 2002).

13.1 Introduction

Although previous chapters indicated the potential and benefits of training arthroscopic skills in simulated environments, training needs to be

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As little to no evidence is available on transfer validity of arthroscopic simulator training, and many residency curricula have yet to implement simulator training, the first section focuses on measuring surgical performance in the operating theatre. Measuring surgical performance is not only useful in training, but has also direct applications in quantification and monitoring of operative quality, patient safety and workflow optimisation. Tools and methods are presented from these areas. These could be applied to verify proficiency in basic arthroscopic skills. Additionally, work is presented to set reference baselines for comparing surgical performance.

As mentioned, training in the OR consists of the apprentice model, where the resident initially watches the teaching surgeon performing an operation and gradually takes over (Pedowitz et al. 2002). As modern medicine offers reduced time for residents to develop their arthroscopic skills, it is worthwhile to optimise the learning effect per operation. General educational theories indicate that feedback on one's performance and stimulation of active learning contributes significantly to a more effective learning process (Prince 2004). For surgery, it has been demonstrated that direct feedback on performance improves the resident's individual skills (Harewood et al. 2008; O'Connor et al. 2008). We present tools that are suitable to monitor this form of teaching and respect the holistic judgment model needed to assess the more complex tasks.

13.2 Measuring Surgical Performance and Baseline References

Measuring surgical performance is not an easy task, as patient care has number one priority, patient privacy and the sterile operating zone should be respected, and the operating theatre cannot be transformed into an experimental set-up. Besides, interpretation of the data is complex. That is why attention is paid as well to the registration of baseline reference data of procedures currently performed in the operating theatre. Two categories of tools are defined: sensors that can

measure psychomotor skills similarly as done in simulated environments and video and audio registrations that can capture overall surgical performance. Each is elucidated with examples.

13.2.1 Sensors

The first parameter to be discussed is not surprisingly the operation time. It is easy to measure and often used to track operative planning and workflow. Its value is deducted from the well-established fact that experts execute surgical actions more efficiently compared to novices (Bridges and Diamond 1999). Farnworth and co-workers demonstrated that residents are significantly slower in performing ACL reconstructions compared to orthopaedic surgeons, which can also have financial consequences (Farnworth et al. 2001).

Psychomotor skills can also be monitored in the operating theatre by motion-tracking systems. Such systems exist using (infrared) cameras that track optical or reflective markers attached to the hands of the surgeon or the instruments or of electromagnetic systems with active markers. In surgical practice, such tracking systems are commonly used in computer-aided surgery for accurate positioning of orthopaedic implants (Fig. 13.1) (Matziolis et al. 2007; Moon et al. 2012; Rosenberger et al. 2008). Tracking can also be performed with normal video cameras and digital image-processing tools that recognise markers or other features in the image. Examples are presented by Doignon and co-workers (Blum et al. 2010; Doignon et al. 2005) who detected surgical instruments in the endoscopic video based on metal-coloured features of the system and by Bouarfa and co-workers who labelled various instruments with coloured markers at the tip to improve robustness (Fig. 13.2) (Bouarfa et al. 2012). Tracking of instrument motions provides insight in surgical performance and flow of the procedure (Aggarwal et al. 2007; Dosis et al. 2005). It does require careful data interpretation.

Another set of parameters that have been measured in the operating room are the forces and

Fig. 13.1 Example of an infrared camera tracking system used in combination with passive reflective markers. (a) Infrared camera. (b) Two markers attached to the shaft of (c) The arthroscopic punch. (d) Anatomic bench model of the knee joint (© GJM Tuijthof, 2014. Reprinted with permission)

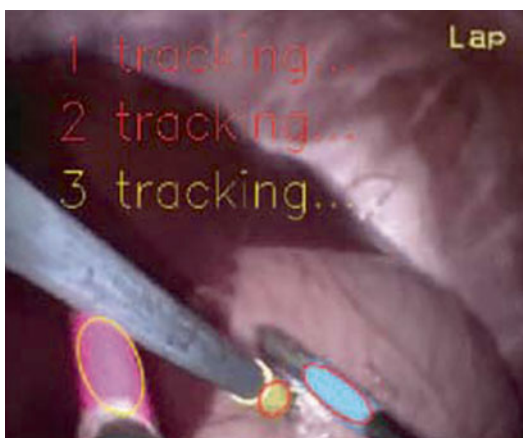


Fig. 13.2 Example of real-time in vivo instrument tracking using coloured labels attached to instruments. In this example three instruments are tracked simultaneously (Bouarfafa et al. (2012), copyright © 2012, Informa Healthcare. Reproduced with permission of Informa Healthcare)

torques executed during knee arthroscopy (Chami et al. 2006). Chami and co-workers showed that force parameters can indeed discriminate between novices and experts (Chami et al. 2008).

13.2.2 Video and Audio

Video recordings of a procedure could offer a tool which allows a holistic type of feedback with easy interpretative illustrations. However, the few studies that we could find on using video feedback to improve surgical training did not find significant differences (Backstein et al. 2004; Backstein et al. 2005). Drawbacks of using video recordings are that the replay of an entire operation is time-consuming and without post-processing they do not provide objective

measures. A similar line of reasoning can be given for audio recordings. Still, when executing post-processing techniques, video and audio recordings reveal useful cues that could be used to monitor surgical performance. We present some examples related to arthroscopic training.

Time-action analysis is a quantitative method to determine the number and duration of actions. It represents the relative timing of different events and the duration of the individual events. In the medical field, time-action analysis has proven its value in objectifying and quantifying surgical actions (den Boer et al. 2002; Minekus et al. 2003; Sjoerdsma et al. 2000). For training, patient safety and workflow monitoring, time-action analysis can be used to detect and to analyse deviations from the normal flow of the operation. This requires documentation of reference data sets through analysis of procedures performed by expert orthopaedic surgeons. We have performed such analyses for a set of predominantly meniscectomies with the intended purpose of investigating the effectiveness of arthroscopic pump systems (Tuijthof et al. 2007, 2008). To do so, the operations were divided into four phases – (1) creation of portals, (2) joint inspection with or without a probe, (3) cutting and (4) shaving – and their share in the operation time was quantified with the time-action analysis. Comparing the mean duration of each of the phases with those of a trainee can indicate if the trainee performs according to normal workflow or needs substantially more time for a certain phase. By analysing the number of instrument exchanges, repeated actions or the percentage of disturbed arthroscopic view as well, trainees can receive detailed objective feedback on the skills they need to improve. Other parameters that were analysed are the prevalence of instrument loss, triangulation time and prevalence of lookdowns, which showed a high correlation with global rating scale and motion analysis (Alvand et al. 2012).

As these early time-action analyses initially were performed manually by replaying the video frame by frame (den Boer et al. 2002; Minekus et al. 2003; Sjoerdsma et al. 2000; Tuijthof et al. 2007, 2008), implementation of this method for training purposes is unrealistic as it is too time-consuming. However, efforts have been made to

perform such analyses automatically using image-processing techniques (Doignon et al. 2005; Tuijthof et al. 2011) or specific tracking systems (Bouarfa et al. 2012). When combined with statistical models, such as Markov models, one can even predict preoperatively what the flow of the operation is (Bouarfa et al. 2011; Bouarfa and Dankelman 2012; Padoy et al. 2012). Such methods could lead to tools that provide real-time objective feedback to a trainee during the operation.

Another feasible approach to implement time-action analysis techniques for training purposes is derived from training of high performance athletes. In this field, it is becoming a daily practice that training activities are recorded on video. To cope with the huge amount of data, sports analysis video software has been developed, which makes it easier to tag events, to assign event to categories, to make annotations and to perform quantitative analyses. Examples of commercial video analysis software packages are Utilius (CCC software, Leipzig, Germany, www.ccc-software.de), MotionView™ (AllSportSystems, Willow Springs, USA, www.allsportsystems.com) and SportsCode Gamebreaker Plus (Sportstec, Sydney, Australia, www.sportstec.com). We present an example of applying such software for the analysis of verbal feedback during arthroscopic training in our university hospital. During supervised training of arthroscopy, verbal communication is mainly used to guide the resident through the procedure. This suggests that the training process can be monitored through verbal communication. To investigate if current training in the operating room involves sufficient feedback and/or questioning to stimulate active learning, verbal communication was objectified and quantified.

Within a period of two times 3 months, 18 arthroscopic knee procedures were recorded with a special capturing system consisting of two video cameras – one from the arthroscopic camera and one of the hands of the residents (digital CCD camera, 21CW, Sony CCD, Tokyo, Japan) – and a tie-clip microphone (ECM-3003, Monacor, Bremen, Germany) that was mounted on the supervising surgeon. The video images were combined by a colour quad proces-

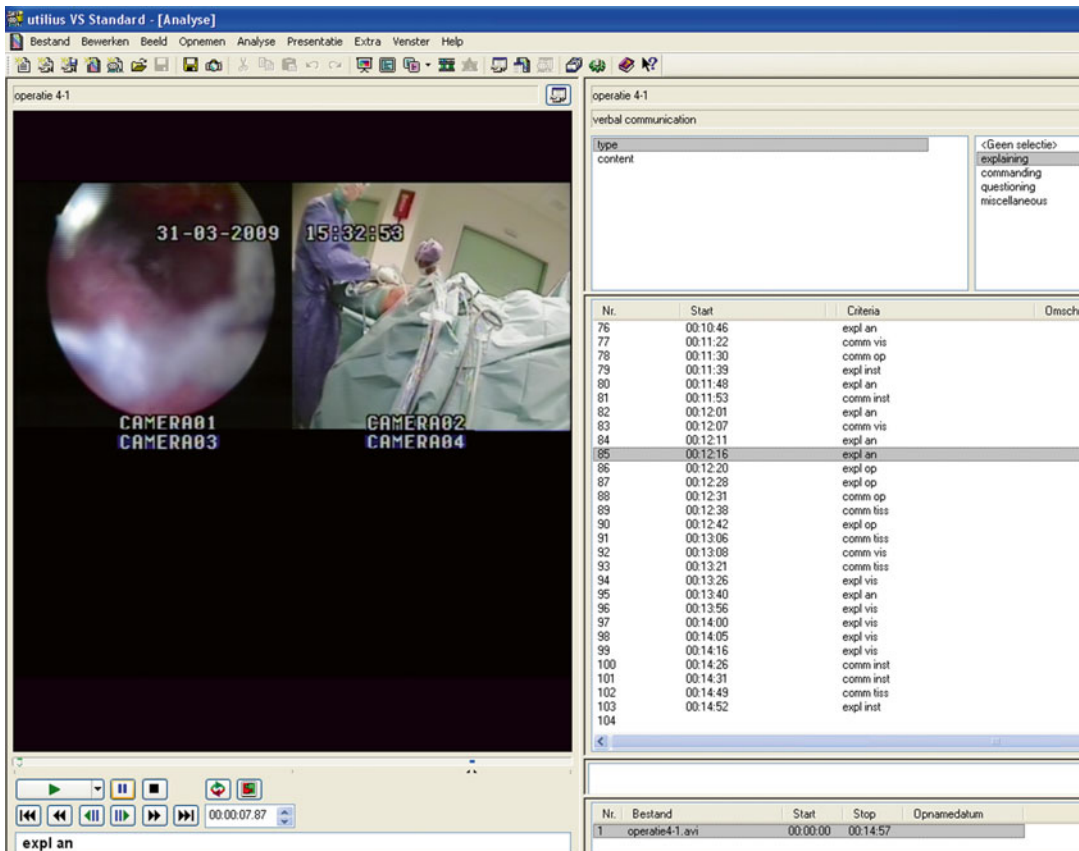


Fig. 13.3 Screenshot of software used to analyse verbal communication (© GJM Tuijthof, 2014. Reprinted with permission)

sor (GS-C4CQR, Golden State Instrument Co., Tustin, USA) and digitised simultaneously with the sound by an A/D converter (ADVC 110, GV Thomson, Paris, France). Four residents who were supervised by either one of two participating surgeons performed the operations. Communication events were tagged with Utilius VS 4.3.2 (CCC-software, Leipzig, Germany) and assigned to categories for the type and content of communication (Fig. 13.3). Four communication types were adopted from Blom et al. (2007): explaining, questioning, commanding and miscellaneous (Table 13.1). As this study specifically focuses on training, one category was added, feedback, which reflects the judgment of the teaching surgeon on the actions of the resident. Six categories for communication content were defined as follows: operation method (that has an accent on steps that have to be taken in the near future e.g. start creating the second portal), anat-

omy and pathology, instrument handling and tissue interaction (e.g. open punch, reposition instrument, stress joint, increase portal size, push meniscus backwards), visualisation (e.g. move scope, irrigation, focus), miscellaneous (general or private) and indefinable (Table 13.1). The frequency of events as percentage of total events in each of the categories was determined (Table 13.1). A multivariable linear regression analysis was performed to determine if the teaching surgeon and the experience of the residents significantly influenced the frequency of communication events per minute ($p < 0.05$).

On average 6.0 (SD 1.8) communication events took place every minute. The communication types *explaining* and *commanding* show a considerable frequency compared to *questioning* and *feedback* (Table 13.1). The explaining events were primarily on *anatomy and pathology* followed by *instrument handling and tissue interac-*

Table 13.1 Crosstabs for type (upper row) and content (left column) categories as percentage of total events

	Total (%)	Explaining (%)	Commanding (%)	Questioning (%)	Feedback (%)	Miscellaneous (%)
Total	100.0	38.8	27.4	5.7	10.6	17.4
Operation method	4.2	3.6	0.1	0.1	0.5	0.0
Anatomy and pathology	17.7	14.8	0.0	2.4	0.5	0.0
Instrument handling and tissue interaction	35.7	13.0	14.2	2.0	6.4	0.1
Visualisation	24.9	7.4	13.1	1.2	3.2	0.0
Miscellaneous	14.0	0.0	0.1	0.1	0.0	13.9
Indefinable	3.5	0.0	0.0	0.0	0.0	3.5

tion. The commanding events were primarily on *instrument handling and tissue interaction* and *visualisation*, which in general were the most frequent communication content categories (Table 13.1). A difference in mean events per minute was found between both teaching surgeons ($p < 0.05$). No significant correlation was found between the frequency of events and the experience of the residents.

The results highlight distinctive communication patterns. The relative high frequency of the types *explaining* and *commanding* as opposed to *questioning* and *feedback* is noticeable as the latter two stimulate active learning in general. Additionally, explaining on the contents *anatomy and pathology* and *instrument handling and tissue interaction* is considerable. These items are particularly suitable for training outside the operating room. If trained so, more options are left to focus on other learning goals. As a clear difference was present between the frequency of events per minute amongst the surgeons and no correlation was found for the experience of residents, we cannot confirm that this method is suitable as an objective evaluation tool for new training methods. Additional research is recommended with a larger group of residents to minimise the effect of outliers.

13.3 Monitoring Complex Tasks and Assessing Learning Curves

To respect the holistic assessment model, expert surgeons are needed to assess the more complex tasks. This type of assessment is sensitive to the

subjective opinion of the assessor, which might compromise fair judgment (Mabrey et al. 2002). To overcome this issue, education theories recommend the formulation of rubrics, which describe clear evaluation criteria and various levels of competence. In surgical training, such rubrics are called global rating scales (GRS). The GRS suggested that arthroscopic skills will be elucidated as well as their validation and examples to assess learning curves.

Within this section, we loosely follow Hodgins and Veillette who reviewed assessment tools for arthroscopic competency (Hodgins and Veillette 2013). Recently, various GRS have been developed specifically for structured, objective feedback during training of arthroscopies (Table 13.2):

1. Orthopaedic Competence Assessment Project (OCAP) (Howells et al. 2008)
2. Basic Arthroscopic Knee Skill Scoring System (BAKSSS) (Insel et al. 2009)
3. Arthroscopic Skills Assessment (ASA) (Elliott et al. 2012)
4. Objective Assessment of Arthroscopic Skills (OAAS) (Slade Shantz et al. 2013)
5. Arthroscopic Surgery Skill Evaluation Tool (ASSET) (Koehler et al. 2013)

The actual forms are available in Appendices 13.A, 13.B, 13.C, 13.D and 13.E. Noticeable is that all arthroscopic GRS except for ASA have a similar structure with 7–10 items that need to be scored on a 5-point Likert scale. At least 3 of 5 points are explicitly described, which should help uniform assessment. Also

Table 13.2 All GRS that are suggested for rating of arthroscopic skills based on Hodgins and Veillette (2013)

Acronyms of Global Rating Scales	Description	Validation
OCAP	9 items, scored on a 1–5 point Likert scale	Based on OSATS validation protocols
BAKSSS	10 items, scored on a 1–5 point Likert scale	Construct validity level of experience ($p < 0.05$) Concurrent validity with year of residency ($r = 0.93$) Concurrent validity with motion analysis ($r = 0.58$) (Alvand et al. 2013) Internal consistency (Cronbach's $\alpha = 0.88$) (Alvand et al. 2013) Interrater reliability ($\kappa = 0.543$) (Olson et al. 2013)
ASA	100-point score, 75 for structure identification, 25 for time to completion and penalties for cartilage damage	Construct validity level of experience ($p < 0.001$)
OAAS	7 items, scored on a 1–5 point Likert scale, complexity of procedure	Construct validity level of experience ($p < 0.0001$) Internal consistency (Cronbach's $\alpha = 0.97$) Level of agreement (ICC = 0.80) Test-retest reliability ($r = 0.52$)
ASSET	8 items, scored on a 1–5 point Likert scale, complexity of procedure	Content validity: expert group Concurrent validity level of experience ($p < 0.05$) Level of agreement (ICC = 0.90) Test-retest reliability ($r = 0.79$)

The forms can be found in Appendices 13.A, 13.B, 13.C, 13.D and 13.E

many of the items are similar, such as instrument handling, flow of operation, efficiency and autonomy. OCAP and BAKSSS are also recommended to be used with task-specific checklists, whereas ASA solely focuses on knee arthroscopy with such a checklist. Analysing these GRS, one can conclude that a certain level of consensus exists on arthroscopic skills that a resident should be able to demonstrate in the operating theatre and the required level to qualify as competent.

OCAP is not specifically tested, but its items are derived from the well-established OSATS GRS, which has been validated extensively (Martin et al. 1997; Reznick et al. 1997). The four other GRS have been validated for construct, content and concurrent validity as well as internal consistency, interrater and test-retest reliability (Table 13.2). The results indicate that they meet the requirements and show a high correlation with year of residency. Notice that none of the study designs for validation are the same, thus one-to-one comparison is not possible. The

ASSET has also been evaluated for summative assessment in a pass-fail examination, which was confirmed with a high rater agreement (ICC = 0.83) (Koehler and Nicandri 2013).

For OCAP and BAKSSS, we determined if they reflect the learning curve during arthroscopic training in the operating room and what their discriminative level is. 75 arthroscopic procedures performed by 15 residents in their fourth, fifth and sixth year of their residency were assessed by their supervising surgeon.

Pearson correlation coefficients were calculated between year of residence and normalised sum scores of both GRS questionnaires. The normalised sum score consisted of all points scored on each of the items normalised to a 100-point scale. The Pearson correlation was significant for BAKSSS ($R = 0.73$) and for OCAP 0.70 ($R = 0.70$). A linear regression analysis demonstrated a significant increase of the GRS sum score of 9.2 points (95 % CI 6.2–12.1) for BAKSSS and 9.5 points (95 % CI 6.5–12.5) for

OCAP. The results lead to our conclusion that both GRS are suitable to monitor overall arthroscopic skills progression in the operating theatre.

Now that the tools for monitoring surgical performance in the operating theatre are summarised, this section focusses on the application of these tools to assess learning curves. As the number of studies is quite limited all are briefly described. The learning curve of arthroscopic rotator cuff repair was determined using operation time as metric (Guttmann et al. 2005). Using blocks of ten operations for comparison, a significant decrease in operation was determined between the first two blocks, but not for consecutive blocks. This indicates that learning took place in the first ten procedures. The learning curve for hip arthroscopy is determined by measuring the operation but also by determining the complication rate (Hoppe et al. 2014). Improvement was seen between early and late experience with 30 patient cases as being the most common cut-off. A similar study design was used to assess the learning curve for arthroscopic Latarjet procedures, which showed a significant decrease in operation time and complication rate between the first 15 patient cases and the consecutive 15 patient cases (Castricini et al. 2013). Van Oldenrijk and co-workers, who used time-action analysis to assess a learning curve for minimally invasive total hip arthroplasty, found that learning took place in the first five to ten patient cases (Van Oldenrijk et al. 2008). This was quantified by the number of repetitions, waiting and additional actions executed during the operation.

13.4 Discussion

In this chapter, monitoring tools to measure surgical performance and training progression were presented. Operation time is easy to measure and as shown capable of reflecting learning curves. Still, using the operation time as a measure for training purposes is less useful, since it does not give clues for the trainee on what to improve, and it reflects many more factors than the surgical

performance such as the complexity of the patient case. This is also acknowledged in the global rating scales. The tracking systems that have been used on research studies are quite expensive and require preoperative installation and calibration, which could explain the absence of studies performed in the operating room to determine learning curves. However, in the entertainment and gaming industry, motion-tracking developments are growing fast, from which the surgical training field could benefit. For example, Wii controllers are affordable and their accuracy is continuously being improved. Measuring of forces as presented by Chami requires a specific measurement set-up and modification of the instruments (Chami et al. 2008). Furthermore, attention needs to be paid on the manner of feedback using force parameters as the feedback should make sense for the trainee. Overall, these metrics are used in simulated environments and are strong in monitoring confined less complex tasks or actions. However, video monitoring seems to reflect the required holistic judgment model needed to assess more complex cognitive tasks. The challenge is to cope with the huge amounts of data that video registration gives. In that perspective, automatic detection with image-based tracking algorithms would be a perfect alternative tool as the arthroscopic view is available anyhow. However, until now these algorithms lacked robustness due to continuous changing lighting conditions in the view. With this feature perspective, video analysis software as applied in athlete training might be a good alternative at short notice, especially if supervising surgeons define critical phases of the procedure that will be the focus of the learning experience, since this would limit the video recordings to those events solely. A major advantage of video analysis is that it can provide highly comprehensive feedback to the trainee. Another alternative is the use of global rating scales. These scales structure and objectify the feedback of the supervising surgeons, but cannot be so illustrative as video feedback. Furthermore, it is recommended that assessors using the scales are trained to attain uniform assessment. However, they are truly easy to implement in residency curricula, have been demonstrated to

reflect the learning curve of residents and could also be used for self-assessment. Summarizing, quite some tools have been presented, and validation of GRS for arthroscopic skills has been performed. This offers feasible tools to continue

arthroscopic skills monitoring in an objective, structured and comprehensive manner that is formative assessment. Still more research is required to determine which of the tools could be used for summative assessment.

13.5 Appendix 13.A Orthopaedic Competence Assessment Project

Skill	Score 1	Score 2	Score 3	Score 4	Score 5
Follows protocol	Unsatisfactory		Adequate. Occasional need for guidance and help		Excellent adherence to agreed protocol. No prompts. No mistakes
Handles tissue well	Careless. Potential to cause damage		Adequate. No tissue damage. Occasional need for increased care		Excellent tissue handling. Precise and delicate
Appropriate and safe use of instruments	Dangerous. Risk to patient and assistant. Potential for damage to equipment		Adequate use of instruments and scope. Occasional guidance to ensure instruments remain within field of vision		Excellent use of instruments. Good control of arthroscope. Instruments constantly within field of vision
Appropriate pace with economy of movement	Erratic pace and movements. Overly rushing or inappropriately slow		Adequate economy of movement. Majority of movements controlled and careful. Occasional erratic movement		Excellent fluidity and economy of movement. Procedure performed at appropriate pace without erratic movements
Act calmly and effectively with untoward events	Unable to deal with adverse events. Panic and inability to respond		Remains calm. Remains safe. Takes advice from supervisor. Unable to cope independently		Excellent ability to cope with adverse events. Remains calm. Deals with complication independently
Appropriate use of assistant	Fails to involve assistant appropriately. Resultant poor positioning. Poor rapport		Asks for appropriate joint position at appropriate times. Unable to suggest alternative positions to improve view/access		Excellent use of assistant. Good rapport. Able to constantly modify input of assistant to best advantage throughout procedure
Communicates with scrubs nurse	Inappropriate communication resulting in confusion or operative delay		Appropriate communication with scrub nurse. Occasional need for clarification from supervisor		Excellent rapport with scrub nurse. Clear and effective communication, maximising procedural efficiency
Clearly identifies common abnormalities	Unable to identify common abnormalities. Confusion over basic anatomy		Adequate identification of common pathology. Occasional mistake. Unsure of precise classifications		Excellent knowledge of pathology of common abnormalities. Clear understanding of classification of injuries

Skill	Score 1	Score 2	Score 3	Score 4	Score 5
Protecting the articular surface	Inability to protect articular surface appropriately. Potential to cause damage		Awareness of need to protect articular surface. Adequate care taken. Occasional prompt from supervisor required		Excellent awareness of articular surfaces. High degree of care maintained throughout the procedure

13.6 Appendix 13.B Basic Arthroscopic Knee Skill Scoring System

Skill	Score 1	Score 2	Score 3	Score 4	Score 5
Dissection	Appeared excessively hesitant, caused trauma to tissues, did not dissect into correct anatomical plan		Controlled and safe dissection into correct anatomical plane, caused minimal trauma to tissues		Superior and atraumatic dissection into the correct anatomical plane
Instrument handling	Repeatedly makes tentative or awkward movements with instruments		Competent use of instruments, although occasionally appeared stiff or awkward		Fluid moves with instruments and no awkwardness
Depth perception	Constantly overshoots target, slow to correct		Some overshooting or missing of target		Accurately directs instruments in the correct plane to target
Bimanual dexterity	Noticeably awkward with non-dominant hand, poor coordination between hands		Uses both hands but does not maximise interaction between hands		Expertly uses both hands in complementary manner to provide optimum performance
Flow of operation and forward planning	Frequently stopped operating or needed to discuss next move		Demonstrated ability for forward planning with steady progression of operative procedure		Obviously planned course of operation with effortless flow from one move to the next
Knowledge of instruments	Frequently asked for the wrong instrument or used inappropriate instrument		Knew the names of most instruments and used appropriate instrument for the task		Obviously familiar with the instruments required and their names
Efficiency	Many unnecessary, inefficient movements. Constantly changing focus or persisting without progress		Slow, but planned movements are reasonably organised with few unnecessary or repetitive movements		Confident, clear economy of movement and maximum efficiency
Knowledge of specific procedure	Deficient knowledge, needed specific instruction at most operative steps		Knew all important aspects of the operation		Demonstrated familiarity with all aspects of the operation
Autonomy	Unable to complete entire task, even with verbal guidance		Able to complete task safely with moderate guidance		Able to complete task independently without prompting
Quality of final product	Very poor		Competent		Clearly superior

13.7 Appendix 13.C Arthroscopic Skills Assessment

Start time	Stop time	Total time
Landmark	To be visualised	Score
Suprapatellar pouch	View all areas of pouch	(3)
Patella	View medial facet	(3)
	View lateral facets	(3)
Trochlea	View trochlear surface	(4)
Medial recess	View medial gutter/assess meniscal synovial junction	(4)
Lateral recess	View lateral gutter/assess meniscal junction/popliteus	(4)
Medial compartment	Assess condyle for chondral lesions	(5)
	Meniscus/view anterior, middle, posterior	(5)
	Probe superior and inferior surface	(10)
Intercondylar notch	View and inspect ACL	(5)
	View and inspect PCL	(5)
Lateral compartment	Assess condyle for chondral lesions	(5)
	Meniscus/view anterior, middle, posterior	(5)
	Probe superior and inferior surface	(10)
	View popliteus tendon	(4)

	Missed items	Scope score
Time	Time penalty	Total time score
		Total score

13.8 Appendix 13.D Objective Assessment of Arthroscopic Skills

Skill	Novice	Advanced beginner	Competent	Proficient	Expert
Examining/manipulating joint	Did not examine joint or position to give improved visualisation during procedure	Examined joint without diagnostic abilities and lacked ability to facilitate view by positioning	Positioned knee appropriately after some difficulty with visualisation	Used common positioning to facilitate view during arthroscopy	Used accepted and novel positioning to perform the arthroscopy effortlessly
Triangulating instruments	Could not insert instruments into ports and maintain them in view. Unable to locate instrument tips without difficulty	Unable to maintain instrument in field of view consistently	Found instruments with delay. Field of view wandered from operative site but returned	Found instruments quickly and began work. Occasionally delayed in orienting camera to afford better visualisation	Immediately located instruments and began work without delay. Kept instrument in field of view at all times
Controlling fluid flow and joint distension	Under-/overdistended joint consistently due to inappropriate matching of suction and flow.	Achieved proper distension after delays. Some extravasation into tissue due to overdistension	Distended joint adequately after initial loss of pressure during suction	Joint distended appropriately through control of flow and suction	Minimal fluid extravasated with constantly maintained field of view

Skill	Novice	Advanced beginner	Competent	Proficient	Expert
Maintaining field of view	Often disoriented. Was unable to adjust scope to improve visualisation	Maintained field of view part of the time	Maintained and adjusted arthroscope to provide maximal view with some difficulty	Maintained field of view in same portal	Changed portals quickly to improve visualisation
Controlling instruments	Was unable to perform tasks with provided instruments. Caused cartilage damage	Repeatedly made tentative or awkward moves with instruments	Competently used instruments although occasionally appeared stiff or awkward	Used instruments appropriately and efficiently	Made fluid moves with instruments and used some instruments in novel ways to increase efficiency
Economising time and planning forward	Was unable to complete any portion of the procedure	Was able to complete components of the procedure, but needed to discuss next move	Completed all components of the operation with some unnecessary moves	Was efficient, but continued discovering new time saving motions	Showed economy of movement and maximum efficiency
Overall	Possessed rudimentary arthroscopic skills with only basic anatomical and mechanical understanding	Knew basic steps of procedure and performed some independently	Performed the procedure independently	Performed procedure with changes to improve efficiency	Performed the procedure with minimal chance to improve efficiency
Complexity	No difficulties	Slightly difficult	Moderately difficult	Considerable difficulty	Critical

13.9 Appendix 13.E Arthroscopic Surgical Skill Evaluation Tool

Skill	Score 1	Score 2	Score 3	Score 4	Score 5
Safety	Significant damage to articular cartilage or soft tissue		Insignificant damage to articular cartilage or soft tissue		No damage to articular cartilage or soft tissue
Field of view	Narrow field of view, inadequate arthroscope or light source positioning		Moderate field of view, adequate arthroscope and light source positioning		Expansive field of view, optimal arthroscope and light source positioning
Camera dexterity	Awkward or graceless movements, fails to keep camera centred and correctly oriented		Appropriate use of camera, occasionally needs to reposition		Graceful and dexterous throughout procedure with camera always centred and correctly
Instrument dexterity	Overly tentative or awkward with instruments, unable to consistently direct instruments to targets		Careful, controlled use of instruments, occasionally misses targets		Confident and accurate use of all instruments

Skill	Score 1	Score 2	Score 3	Score 4	Score 5
Bimanual dexterity	Unable to use both hands or no coordination between hands		Uses both hands but occasionally fails to coordinate movement of camera and instruments		Uses both hands to coordinate camera and instrument positioning for optimal performance
Flow of procedure	Frequently stops operating or persists without progress, multiple unsuccessful attempts prior to completing tasks		Steady progression of operative procedure with few unsuccessful attempts prior to completing tasks		Obviously planned course of procedure, fluid transition from one task to the next with no unsuccessful attempts
Quality of procedure	Inadequate or incomplete final product		Adequate final product with only minor flaws that do not require correction		Optimal final product with no flaws
Autonomy	Unable to complete procedure even with intervention(s)		Able to complete procedure but required intervention(s)		Able to complete procedure without intervention
Complexity	No difficulty		Moderate difficulty (mild inflammation or scarring)		Extreme difficulty (severe inflammation or scarring, abnormal anatomy)

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