

Slowed Exclusion Process: Hydrodynamics, Fluctuations and Phase Transitions

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1 Introduction

A major question in Statistical Mechanics is how to perform the limit from the discrete to the continuum in such a way that the discretization of the system really gives the correct description of the continuum? This question gave rise to plenty of famous models and results, both in Physics and Mathematics. In the particular context of *particle systems* and *hydrodynamic limits*, the passage of the discrete to the continuum is a consequence of rescaling both time and space. The discrete system consists in a collection of particles with a stochastic dynamics. Depending on the prescribed interaction we are lead to different limits. Therefore the random interaction of the microscopic system is connected to the macroscopic phenomena to be explored.

As the main reference on the subject, we cite the classical book [9], which treats the limit of several particle systems, as the zero range process, the symmetric and asymmetric exclusion process, the generalized K -exclusion process, independent

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random walks and some of their scaling limits. We point out some of the possible natures of those scaling limits.

The scaling limit for the time-trajectory of the spatial density of particles is the so-called *hydrodynamic limit* of the system, which is a Law of Large Numbers (L.L.N.) type-theorem. The scaling limit for how the discrete system oscillates around its hydrodynamic limit is usually referred as *fluctuations*, being a Central Limit Theorem (C.L.T.). The study of the rate at which the probability of observing the discrete deviates from the expected limit decreases (roughly, exponentially fast) is the theme of the Large Deviations Principle.

Recently, the scientific community has given attention to particle systems in random and non-homogeneous media, and several approaches have been developed in order to study the problem. In the papers [2, 8, 10], the authors considered random walks in a random environment, as for example the case where the environment is driven by an α -subordinator. These works inspired a series of other papers in the context of particle systems, as [1, 6, 7, 11]. The work in [6] was related to the hydrodynamic limit of exclusion processes driven by a general increasing function W , not necessarily a toss of an α -subordinator. This work, in its hand, inspired the work [3], which dealt with the case W being the distribution function of the Lebesgue measure plus a delta of Dirac measure, being the mass of the delta of Dirac dependent on the scale parameter. The model of [3] can be described as follows. To each site of the discrete torus with n sites, it is allowed to have at most one particle. Each bond has a Poisson clock which is independent of the clocks on other sites. When the Poisson clock of a bond rings, the occupation at the vertices of this bond are interchanged. All the Poisson clocks have parameter one, except one special clock, which has parameter given by $\alpha n^{-\beta}$, with $\alpha > 0$ and $\beta \in [0, \infty]$. This “slower” clock, makes the passage of particles across the corresponding bond more difficult, and for that reason that bond coined the name *slow bond*.

In the scenario of [3], according to the value of β , three different limits for the time trajectory of the spatial density of particles were obtained. If $\beta \in [0, 1)$ the limit is given by the weak solution of the periodic heat equation, meaning that the slow bond is not slow enough to originate any change in the continuum. If $\beta = 1$, the limit is given by the weak solution of the heat equation with some Robin’s boundary conditions representing the Fick’s Law of passage of particles. And if $\beta \in (1, \infty]$, the limit is given by the weak solution of the heat equation with Neumann’s boundary conditions, meaning that the slow bond in this regime of β is slow enough to divide the space in the continuum.

Such dynamical phase transition (based on the strength of a single slow bond) is not limited to the hydrodynamic limit. In the ensuing papers [4, 5], some other dynamical phase transitions were proved. In [4], it was shown that the solutions of the three partial differential equations aforementioned are continuously related to a given boundary’s parameter, indicating a dynamical phase transition also at the macroscopic level. In [5], it was proved that the equilibrium fluctuations of the exclusion process with a slow bond evolving on an infinite volume, is also characterized by the same regimes of β . As before, in each case, namely for

$\beta \in [0, 1)$, $\beta = 1$ or $\beta \in (1, \infty]$, the limit fluctuations of the system are driven by three Ornstein-Uhlenbeck processes. As a consequence of the density fluctuations, we have also obtained the corresponding phase transition for the current of particles through a fixed bond and for a tagged particle.

In these notes we make a synthesis of last results, all of them related to dynamic phase transitions that occur when the strength of a particular slow bond varies. We notice that the theme is not finished at all. There are a lot of particle systems to examine and different limits to prove. As an example, in the cited papers [3–5], the underlying particle systems are only of exclusion constrain and with symmetric dynamics. Therefore, one can exploit other dynamics and obtain other partial differential equations of physical interest. Moreover, even for the symmetric exclusion dynamics with a slow bond, the full scenario for the scaling limits is not closed yet: a Large Deviations Principle is still open. This is subject for future work.

Here follows an outline of these notes. In Sect. 2 we present the exclusion process with a slow bond. Section 3 is devoted to the scaling limits at the level of hydrodynamics. We present the hydrodynamic equations, the hydrodynamic limit and the phase transition for the corresponding partial differential equations. In Sect. 4 we present the scaling limits at the level of fluctuations. We present the Ornstein-Uhlenbeck processes and the fluctuations of the density of particles. We finish in Sect. 5 with a description of the fluctuations of the current of particles and of a tagged particle.

2 Exclusion Processes

We are concerned with the study of dynamical phase transitions in particle systems with a single slow bond. Before discussing what we mean by a dynamical phase transition we describe our particle systems. We consider the simple exclusion process (SEP) with a single slow bond. Probabilistic speaking, the SEP is a Markov process that we denote by $\{\eta_t : t \geq 0\}$ and we consider it evolving on the state space $\Omega := \{0, 1\}^{\mathbb{T}_n}$, where $\mathbb{T}_n = \mathbb{Z}/n\mathbb{Z}$ is the one-dimensional discrete torus with n points. A configuration of this Markov process is denoted by η and it consists in a vector with n components, each one taking the value 0 or 1. The physical interpretation is that whenever $\eta(x) = 1$ we say that the site x is occupied, otherwise it is empty.

The microscopic dynamics of this process can be informally described as follows. At each bond $\{x, x + 1\}$ of \mathbb{T}_n , there is an exponential clock of parameter $a_{x,x+1}^n$. When this clock rings, the value of η at the vertices of this bond are interchanged. We choose the parameters of the clocks in all bonds equal to 1, except at the bond $\{-1, 0\}$, in such a way that the passage of particles across this bond is more difficult with respect to other bonds. For $\beta \in [0, \infty]$ and $\alpha > 0$, we consider

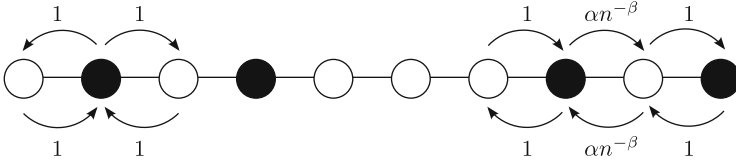


Fig. 1 SEP with a slow bond with vertices $\{-1, 0\}$, whose jump rates are given by $\alpha n^{-\beta}$. Black balls represent occupied sites

$$a_{x,x+1}^n = \begin{cases} \alpha n^{-\beta}, & \text{if } x = -1, \\ 1, & \text{otherwise.} \end{cases}$$

This means that particles cross all the bonds at rate 1, except the bond $\{-1, 0\}$, whose dynamics is slowed down as $\alpha n^{-\beta}$, with $\alpha > 0$ and $\beta \in [0, \infty]$, see Fig. 1.

The dynamics described above can be characterized via the infinitesimal generator, which we denote by \mathcal{L}_n and is given on functions $f : \Omega \rightarrow \mathbb{R}$ as

$$\mathcal{L}_n f(\eta) = \sum_{x \in \mathbb{T}_n} a_{x,x+1}^n [f(\eta^{x,x+1}) - f(\eta)],$$

where $\eta^{x,x+1}$ is the configuration obtained from η by exchanging the occupation variables $\eta(x)$ and $\eta(x + 1)$, namely

$$\eta^{x,x+1}(y) = \begin{cases} \eta(x + 1), & \text{if } y = x, \\ \eta(x), & \text{if } y = x + 1, \\ \eta(y), & \text{otherwise.} \end{cases}$$

Let $\rho \in [0, 1]$ and denote the Bernoulli product measure, defined in Ω and with parameter ρ , by

$$\nu_\rho^n \{ \eta \in \Omega : \eta(x) = 1, \text{ for any } x \in A \} = \rho^{\#A},$$

for all set $A \subset \mathbb{T}_n$. Here $\#A$ denotes the cardinality of the set A . It is well known that the measures ν_ρ^n are invariant for the dynamics introduced above. Moreover, these measures are also reversible.

The trajectories of the Markov process $\{\eta_t : t \geq 0\}$ live on the space $\mathcal{D}(\mathbb{R}_+, \Omega)$, that is, the path space of càdlàg trajectories with values in Ω . For a measure μ_n on Ω , we denote by \mathbb{P}_{μ_n} the probability measure on $\mathcal{D}(\mathbb{R}_+, \Omega)$ induced by μ_n and $\{\eta_t : t \geq 0\}$; and we denote by \mathbb{E}_{μ_n} expectation with respect to \mathbb{P}_{μ_n} .

We notice that we do not index the Markov process, the generator nor the measures, in β or α for simplicity of notation.

3 Hydrodynamical Phase Transition

The study of the hydrodynamical behavior consists in the analysis of the time evolution of the density of particles. For that purpose we introduce the empirical measure process as follows.

For $t \in [0, T]$, let $\pi_t^n(\eta, du) := \pi^n(\eta_t, du) \in \mathcal{M}$ be defined as

$$\pi^n(\eta_t, du) = \frac{1}{n} \sum_{x \in \mathbb{T}_n} \eta_t(x) \delta_{x/n}(du),$$

where δ_y is the Dirac measure concentrated on $y \in \mathbb{T}$. Above, \mathbb{T} denotes the one-dimensional torus and \mathcal{M} denotes the space of positive measures on \mathbb{T} with total mass bounded by one, endowed with the weak topology.

The hydrodynamic limit can be stated as follows. If we assume a L.L.N. for $\{\pi_0^n\}_{n \in \mathbb{N}}$ to a limit $\rho_0(u)du$ under the initial distribution of the system, then at any time $t > 0$ the L.L.N. holds for $\{\pi_t^n\}_{n \in \mathbb{N}}$ to a limit $\rho(t, u)du$ under the corresponding distribution of the system at time t . Moreover, the density $\rho(t, u)$ evolves according to a partial differential equation – the hydrodynamic equation. For this model, depending on the range of the parameter β , we obtain different hydrodynamic equations for the underlying particle system.

In the next section we describe the hydrodynamic equations we obtained and we precise in which sense $\rho(t, u)$ is a solution to those equations.

3.1 Hydrodynamic Equations

We start by describing the hydrodynamic equations that govern the evolution of the density of particles for the models introduced above. Depending on the range of the parameter β we obtain hydrodynamic equations which have different behavior. More precisely, we always obtain the heat equation but with different boundary conditions. The first hydrodynamic equation is the heat equation with periodic boundary conditions, namely:

$$\begin{cases} \partial_t \rho(t, u) = \Delta \rho(t, u), & t \geq 0, u \in \mathbb{T}, \\ \rho(0, u) = \rho_0(u), & u \in \mathbb{T}. \end{cases} \tag{1}$$

In the hydrodynamic limit scenario, we obtain $\rho(t, u)$ as a weak solution of the corresponding hydrodynamic equation. To make this notion precise, we introduce the following definition:

Definition 1. Let $\rho_0 : \mathbb{T} \rightarrow [0, 1]$ be a measurable function. We say that $\rho : [0, T] \times \mathbb{T} \rightarrow [0, 1]$ is a weak solution of the heat equation with periodic boundary conditions given in (1) if ρ is measurable and, for any $t \in [0, T]$ and any $H \in C^{1,2}([0, T] \times \mathbb{T})$,

$$\int_{\mathbb{T}} \rho(t, u) H(t, u) du - \int_{\mathbb{T}} \rho(0, u) H(0, u) du - \int_0^t \int_{\mathbb{T}} \rho(s, u) (\partial_s H(s, u) + \Delta H(s, u)) du ds = 0. \tag{2}$$

Above and in the sequel the space $C^{1,2}([0, T] \times \mathbb{T})$ is the space of real valued functions defined on $[0, T] \times \mathbb{T}$ of class C^1 in time and C^2 in space.

The second equation we consider is the heat equation with a type of Robin’s boundary conditions, that is:

$$\begin{cases} \partial_t \rho(t, u) = \Delta \rho(t, u), & t \geq 0, u \in (0, 1), \\ \partial_u \rho(t, 0) = \partial_u \rho(t, 1) = \alpha(\rho(t, 0) - \rho(t, 1)), & t \geq 0, \\ \rho(0, u) = \rho_0(u), & u \in (0, 1). \end{cases} \tag{3}$$

To introduce the notion of weak solution of this equation we need to recall the notion of Sobolev’s spaces.

Definition 2. Let \mathcal{H}^1 be the set of all locally summable functions $\xi : (0, 1) \rightarrow \mathbb{R}$ such that there exists a function $\partial_u \xi \in L^2(0, 1)$ satisfying

$$\int_{\mathbb{T}} \partial_u G(u) \xi(u) du = - \int_{\mathbb{T}} G(u) \partial_u \xi(u) du,$$

for all $G \in C^\infty(0, 1)$ with compact support. Let $L^2(0, T; \mathcal{H}^1)$ be the space of all measurable functions $\xi : [0, T] \rightarrow \mathcal{H}^1$ such that

$$\|\xi\|_{L^2(0, T; \mathcal{H}^1)}^2 := \int_0^T \left(\|\xi\|_{L^2[0, 1]}^2 + \|\partial_u \xi\|_{L^2[0, 1]}^2 \right) dt < \infty.$$

Above $\|\cdot\|_{L^2[0, 1]}$ denotes the L^2 -norm in $[0, 1]$.

Definition 3. Let $\rho_0 : \mathbb{T} \rightarrow [0, 1]$ be a measurable function. We say that $\rho : [0, T] \times \mathbb{T} \rightarrow [0, 1]$ is a weak solution of the heat equation with Robin’s boundary conditions given in (3) if $\rho \in L^2(0, T; \mathcal{H}^1)$ and for all $t \in [0, T]$ and for all $H \in C^{1,2}([0, T] \times [0, 1])$,

$$\begin{aligned} & \int_{\mathbb{T}} \rho(t, u) H(t, u) du - \int_{\mathbb{T}} \rho(0, u) H(0, u) du \\ & - \int_0^t \int_{\mathbb{T}} \rho(s, u) (\partial_s H(s, u) + \Delta H(s, u)) du ds \\ & - \int_0^t (\rho_s(0) \partial_u H_s(0) - \rho_s(1) \partial_u H_s(1)) ds \\ & + \int_0^t \alpha(\rho_s(0) - \rho_s(1))(H_s(0) - H_s(1)) ds = 0. \end{aligned} \tag{4}$$

The last equation we consider is the heat equation with Neumann’s boundary conditions given by:

$$\begin{cases} \partial_t \rho(t, u) = \Delta \rho(t, u), & t \geq 0, u \in (0, 1), \\ \partial_u \rho(t, 0) = \partial_u \rho(t, 1) = 0, & t \geq 0, \\ \rho(0, u) = \rho_0(u), & u \in (0, 1). \end{cases} \quad (5)$$

Definition 4. Let $\rho_0 : \mathbb{T} \rightarrow [0, 1]$ be a measurable function. We say that $\rho : [0, T] \times \mathbb{T} \rightarrow [0, 1]$ is a weak solution of the heat equation with Neumann’s boundary conditions if $\rho \in L^2(0, T; \mathcal{H}^1)$ and for all $t \in [0, T]$ and for all $H \in C^{1,2}([0, T] \times [0, 1])$,

$$\begin{aligned} & \int_{\mathbb{T}} \rho(t, u) H(t, u) du - \int_{\mathbb{T}} \rho(0, u) H(0, u) du \\ & - \int_0^t \int_{\mathbb{T}} \rho(s, u) (\partial_s H(s, u) + \Delta H(s, u)) du ds \quad (6) \\ & - \int_0^t (\rho_s(0) \partial_u H_s(0) - \rho_s(1) \partial_u H_s(1)) ds = 0. \end{aligned}$$

Our argument to prove the hydrodynamic limit is standard in the theory of stochastic processes and goes through a tightness argument for $\{\pi_t^n\}_{n \in \mathbb{N}}$, which means relatively compactness of $\{\pi_t^n\}_{n \in \mathbb{N}}$. Therefore, there exists a limit point. To have uniqueness of the limit point of $\{\pi_t^n\}_{n \in \mathbb{N}}$ it is sufficient to prove uniqueness of the weak solution of the corresponding hydrodynamic equation. Then, it follows the convergence of the whole sequence $\{\pi_t^n\}_{n \in \mathbb{N}}$ to the unique limit point. For tightness issues we refer the reader to [3] and the uniqueness of the weak solution is stated below.

Proposition 1. *Let $\rho_0 : \mathbb{T} \rightarrow [0, 1]$ be a measurable function. There exists a unique weak solution of the heat equation with periodic boundary conditions given in (1) and a unique weak solution of the heat equation with Neumann’s boundary conditions given in (5). Moreover, for each $\alpha > 0$, there exists a unique weak solution of the heat equation with Robin’s boundary conditions given in (3).*

3.2 Hydrodynamic Limit

Returning to our discussion on the validity of the hydrodynamic limit, we introduce the set of initial measures for which we deduce the result.

Definition 5. Let $\rho_0 : \mathbb{T} \rightarrow [0, 1]$ be a measurable function. A sequence of probability measures $\{\mu_n\}_{n \in \mathbb{N}}$ on Ω is said to be associated to a profile $\rho_0 : \mathbb{T} \rightarrow [0, 1]$ if, for every $\delta > 0$ and every continuous function $H : \mathbb{T} \rightarrow \mathbb{R}$, it holds that

$$\lim_{n \rightarrow \infty} \mu_n \left\{ \eta : \left| \frac{1}{n} \sum_{x \in \mathbb{T}_n} H\left(\frac{x}{n}\right) \eta(x) - \int_{\mathbb{T}} H(u) \rho_0(u) du \right| > \delta \right\} = 0. \tag{7}$$

One could ask about the existence of a measure associated to the profile $\rho_0 : \mathbb{T} \rightarrow [0, 1]$. For instance, we can consider a Bernoulli product measure in Ω with marginal at $\eta(x)$ given by $\mu_n \{ \eta \in \Omega : \eta(x) = 1 \} = \rho_0(x/n)$.

For these processes we obtained in [3, 4] that:

Theorem 1 (L.L.N. for the density of particles). *Fix $\beta \in [0, \infty]$ and $\rho_0 : \mathbb{T} \rightarrow [0, 1]$ a measurable function. Let $\{\mu_n\}_{n \in \mathbb{N}}$ be a sequence of probability measures on Ω associated to ρ_0 . Then, for any $t \in [0, T]$, for every $\delta > 0$ and every continuous function $H : \mathbb{T} \rightarrow \mathbb{R}$:*

$$\lim_{n \rightarrow \infty} \mathbb{P}_{\mu_n} \left\{ \eta : \left| \frac{1}{n} \sum_{x \in \mathbb{T}_n} H\left(\frac{x}{n}\right) \eta_t(x) - \int_{\mathbb{T}} H(u) \rho(t, u) du \right| > \delta \right\} = 0,$$

where:

- For $\beta \in [0, 1)$, $\rho(t, \cdot)$ is the unique weak solution of (1);
- For $\beta = 1$, $\rho(t, \cdot)$ is the unique weak solution of (3);
- For $\beta \in (1, \infty]$, $\rho(t, \cdot)$ is the unique weak solution of (5).

All equations have the same initial condition $\rho_0 : \mathbb{T} \rightarrow [0, 1]$.

3.3 Phase Transition for the Hydrodynamic Equations

A puzzling question is whether there is a similar phase transition as described above, but at the macroscopic level. More precisely, does the unique weak solution of the heat equation with Robin’s boundary conditions, that we denote by ρ^α , converge in any sense to the weak solution of the heat equation with periodic boundary conditions or to the weak solution of the heat equation with Neumann’s boundary conditions? In [4] we gave an affirmative answer to this question. We proved that ρ^α converges to the unique weak solution of the heat equation with Neumann’s boundary conditions, when α goes to zero and to the unique weak solution of the heat equation with periodic boundary conditions, when α goes to infinity. This is the content of the next theorem.

This result is concerned only with the partial differential equations, having at principle nothing to do with the underlying particle systems. Nevertheless, our approach of proof is based on energy estimates coming from these particle systems.

Theorem 2 (Phase transition for the heat equation with Robin’s boundary conditions). *For $\alpha > 0$, let $\rho^\alpha : [0, T] \times [0, 1] \rightarrow [0, 1]$ be the unique weak solution of the heat equation with Robin’s boundary conditions:*

$$\begin{cases} \partial_t \rho^\alpha(t, u) = \Delta \rho^\alpha(t, u), & t \geq 0, u \in (0, 1), \\ \partial_u \rho^\alpha(t, 0) = \partial_u \rho^\alpha(t, 1) = \alpha(\rho^\alpha(t, 0) - \rho^\alpha(t, 1)), & t \geq 0, \\ \rho^\alpha(0, u) = \rho_0(u), & u \in (0, 1). \end{cases}$$

Then, $\lim_{\alpha \rightarrow 0} \rho^\alpha = \rho^0$, in $L^2([0, T] \times [0, 1])$, where $\rho^0 : [0, T] \times [0, 1] \rightarrow [0, 1]$ is the unique weak solution of the heat equation with Neumann's boundary conditions

$$\begin{cases} \partial_t \rho^0(t, u) = \Delta \rho^0(t, u), & t \geq 0, u \in (0, 1), \\ \partial_u \rho^0(t, 0) = \partial_u \rho^0(t, 1) = 0, & t \geq 0, \\ \rho^0(0, u) = \rho_0(u), & u \in (0, 1) \end{cases}$$

and $\lim_{\alpha \rightarrow \infty} \rho^\alpha = \rho^\infty$, in $L^2([0, T] \times [0, 1])$, where $\rho^\infty : [0, T] \times [0, 1] \rightarrow [0, 1]$ is the unique weak solution of the heat equation with periodic boundary conditions

$$\begin{cases} \partial_t \rho^\infty(t, u) = \Delta \rho^\infty(t, u), & t \geq 0, u \in \mathbb{T}, \\ \rho^\infty(0, u) = \rho_0(u), & u \in \mathbb{T}. \end{cases}$$

4 Equilibrium Fluctuations

Above we obtained a L.L.N. for the empirical measure considering the process starting from a measure which is associated to a profile $\rho_0 : \mathbb{T} \rightarrow [0, 1]$. The natural question that follows is: what are the fluctuations around this “mean” profile? Do we have a C.L.T. for the density of particles? Under what set of initial measures? In the next lines we answer this question for a particular set of initial distributions, namely for the invariant measures ν_ρ^n . In case of non-invariant measures the problem is still open.

In this case we consider the process evolving on \mathbb{Z} , being its state space $\{0, 1\}^{\mathbb{Z}}$. To define properly our results, we fix $\rho \in [0, 1]$, and we introduce the density fluctuation field as follows. For $t \in [0, T]$, let

$$\mathcal{Y}_t^n(\eta, du) = \sqrt{n} \pi_{tn^2}^n(\eta, du) - E_{\nu_\rho^n}[\sqrt{n} \pi_{tn^2}^n(\eta, du)],$$

where x runs through \mathbb{Z} in the definition of $\pi_t^n(\eta, du)$ and $E_{\nu_\rho^n}$ denotes expectation with respect to ν_ρ^n . Then, for any function $H : \mathbb{R} \rightarrow \mathbb{R}$ we have that

$$\int_{\mathbb{R}} H(u) \mathcal{Y}_t^n(\eta, du) = \frac{1}{\sqrt{n}} \sum_{x \in \mathbb{Z}} H\left(\frac{x}{n}\right) [\eta_{m^2}(x) - \rho].$$

By computing the characteristic function of \mathcal{Y}_0^n , we obtain that $\{\mathcal{Y}_0^n\}_{n \in \mathbb{N}}$ converges as n goes to ∞ to a mean zero gaussian process \mathcal{Y}_0 . More precisely, for any $H, \mathcal{Y}_0(H)$ is a gaussian random variable with mean zero and variance given by

$$\rho(1 - \rho) \int_{\mathbb{R}} (H(x))^2 dx.$$

Next, we are going to characterize the stochastic partial differential equations governing the evolution of the limit points of $\{\mathcal{Y}_t^n\}_{n \in \mathbb{N}}$.

4.1 Ornstein-Uhlenbeck Processes

In order to properly write down the stochastic partial differential equations that we deal with, we need to introduce different sets of test functions and two type of operators defined on these spaces.

Definition 6. Define $\mathcal{S}(\mathbb{R} \setminus \{0\})$ as the space of functions $H \in C^\infty(\mathbb{R} \setminus \{0\})$, that are continuous from the right at $x = 0$, for which

$$\|H\|_{k,\ell} := \sup_{x \in \mathbb{R} \setminus \{0\}} |(1 + |x|^\ell) H^{(k)}(x)| < \infty,$$

for all integers $k, \ell \geq 0$, and $H^{(k)}(0^-) = H^{(k)}(0^+)$, for all k integer, $k \geq 1$.

- For $\beta \in [0, 1)$, let $\mathcal{S}_\beta(\mathbb{R})$ be the subset of $\mathcal{S}(\mathbb{R} \setminus \{0\})$ composed of functions H satisfying $H(0^-) = H(0^+)$.
- For $\beta = 1$, let $\mathcal{S}_\beta(\mathbb{R})$ as the subset of $\mathcal{S}(\mathbb{R} \setminus \{0\})$ composed of functions H satisfying $H^{(1)}(0^+) = H^{(1)}(0^-) = \alpha(H(0^+) - H(0^-))$.
- For $\beta \in (1, +\infty]$, let $\mathcal{S}_\beta(\mathbb{R})$ be the subset of $\mathcal{S}(\mathbb{R} \setminus \{0\})$ composed of functions H satisfying $H^{(1)}(0^+) = H^{(1)}(0^-) = 0$.

Above and in the sequel, $H^{(k)}(\cdot)$ represents the k -th derivative of the function H and $H(0^+)$ (resp. $H(0^-)$) denotes the limit of H from the right (resp. left) of 0.

Definition 7. For $\beta \in [0, \infty]$, we define the operators $\Delta_\beta, \nabla_\beta : \mathcal{S}_\beta(\mathbb{R}) \rightarrow \mathcal{S}(\mathbb{R})$ by

$$\nabla_\beta H(u) = \begin{cases} H^{(1)}(u), & \text{if } u \neq 0, \\ H^{(1)}(0^+), & \text{if } u = 0, \end{cases}$$

and

$$\Delta_\beta H(u) = \begin{cases} H^{(2)}(u), & \text{if } u \neq 0, \\ H^{(2)}(0^+), & \text{if } u = 0, \end{cases}$$

which are essentially the usual derivative and the usual second derivative, but defined in the domains $\mathcal{S}_\beta(\mathbb{R})$. We have the following uniqueness result which is a key point in our approach.

Denote by T_t^β the semigroup corresponding to the partial differential equations (1), (3) or (5), if $\beta \in [0, 1)$, if $\beta = 1$ or if $\beta \in (1, \infty]$, respectively.

Proposition 2. *For each $\beta \in [0, \infty]$ and $\alpha > 0$, there exists a unique random element \mathcal{Y} taking values in the space $C([0, T], \mathcal{S}'_\beta(\mathbb{R}))$ such that:*

(i) *For every function $H \in \mathcal{S}_\beta(\mathbb{R})$, $\mathcal{M}_t(H)$ and $\mathcal{N}_t(H)$ given by*

$$\begin{aligned} \mathcal{M}_t(H) &= \mathcal{Y}_t(H) - \mathcal{Y}_0(H) - \int_0^t \mathcal{Y}_s(\Delta_\beta H) ds, \\ \mathcal{N}_t(H) &= (\mathcal{M}_t(H))^2 - 2\chi(\rho) t \|\nabla_\beta H\|_{2,\beta}^2 \end{aligned} \tag{8}$$

are \mathcal{F}_t -martingales, where $\mathcal{F}_t := \sigma(\mathcal{Y}_s(H); s \leq t, H \in \mathcal{S}_\beta(\mathbb{R}))$, for $t \in [0, T]$.

(ii) \mathcal{Y}_0 *is a mean zero gaussian field with covariance given on $G, H \in \mathcal{S}_\beta(\mathbb{R})$ as*

$$\mathbb{E}[\mathcal{Y}_0(G)\mathcal{Y}_0(H)] = \chi(\rho) \int_{\mathbb{R}} G(u)H(u)du. \tag{9}$$

Moreover, for each $H \in \mathcal{S}_\beta(\mathbb{R})$, the stochastic process $\{\mathcal{Y}_t(H); t \geq 0\}$ is gaussian, being the distribution of $\mathcal{Y}_t(H)$ conditionally to \mathcal{F}_s , for $s < t$, gaussian of mean $\mathcal{Y}_s(T_{t-s}^\beta H)$ and variance $\int_0^{t-s} \|\nabla_\beta T_r^\beta H\|_{2,\beta}^2 dr$.

Above and in the sequel $\mathcal{S}'_\beta(\mathbb{R})$ denotes the space of bounded linear functionals $f : \mathcal{S}_\beta(\mathbb{R}) \rightarrow \mathbb{R}$ and $\mathcal{D}([0, T], \mathcal{S}'_\beta(\mathbb{R}))$ (resp. $C([0, T], \mathcal{S}'_\beta(\mathbb{R}))$) is the space of càdlàg (resp. continuous) $\mathcal{S}'_\beta(\mathbb{R})$ valued functions endowed with the Skohorod topology. Also $\|H\|_{2,\beta}^2 = \|H\|_2^2 + (H(0))^2 \mathbf{1}_{\{\beta=1\}}$, where $\|\cdot\|_2$ denotes the L^2 -norm in \mathbb{R} . We call to \mathcal{Y} the generalized Ornstein-Uhlenbeck process of characteristic operators Δ_β and ∇_β and it is the formal solution of the following equation

$$d\mathcal{Y}_t = \Delta_\beta \mathcal{Y}_t dt + \sqrt{2\chi(\rho)} \nabla_\beta d\mathcal{W}_t,$$

where \mathcal{W}_t is a space-time white noise of unit variance.

4.2 Central Limit Theorem

We are in position to state the equilibrium fluctuations for the density of particles. Notice that our initial distribution is ν_ρ^n , an invariant measure.

Theorem 3 (C.L.T. for the density of particles). *The sequence of processes $\{\mathcal{Y}_t^n\}_{n \in \mathbb{N}}$ converges in distribution, as n goes to ∞ , with respect to the Skorohod topology of $\mathcal{D}([0, T], \mathcal{S}'_\beta(\mathbb{R}))$ to a gaussian process \mathcal{Y}_t in $C([0, T], \mathcal{S}'_\beta(\mathbb{R}))$, which is the formal solution of the Ornstein-Uhlenbeck equation given by*

$$d\mathcal{Y}_t = \Delta_\beta \mathcal{Y}_t dt + \sqrt{2\chi(\rho)} \nabla_\beta d\mathcal{W}_t. \tag{10}$$

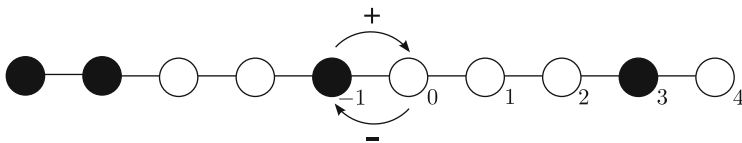


Fig. 2 Current at the bond $\{-1, 0\}$ of the SEP with a slow bond. Every time a particle jumps from -1 to 0 (0 to -1) the current increases (decreases) by one

5 Current and Tagged Particle Fluctuations

In this section we are still restricted to the invariant state ν_ρ^n and for that purpose we fix a density ρ from now on up to the rest of these notes.

5.1 The Current

Now, we introduce the notion of current of particles through a fixed bond $\{x, x + 1\}$. For a bond $e_x := \{x, x + 1\}$, denote by $J_{e_x}^n(t)$ the current of particles over the bond e_x , that is $J_{e_x}^n(t)$ counts the total number of jumps from the site x to the site $x + 1$ minus the total number of jumps from the site $x + 1$ to the site x in the time interval $[0, t]$, see the figure below. More generally, to each macroscopic point $u \in \mathbb{R}$ we can define the current through its associated microscopic bond of vertices $\{\lfloor un \rfloor - 1, \lfloor un \rfloor\}$, as $J_u^n(t) := J_{e_{\lfloor un \rfloor - 1}}^n(t)$. Here $\lfloor un \rfloor$ denotes the biggest integer smaller or equal to un . As a consequence of the C.L.T. for the density of particles, namely of Theorem 3, it is simple to derive the C.L.T. for the current of particles which we enounce as follows (Fig. 2).

Theorem 4 (C.L.T. for the current of particles). *Under $\mathbb{P}_{\nu_\rho^n}$, for every $t \geq 0$ and every $u \in \mathbb{R}$,*

$$\frac{J_u^n(t)}{\sqrt{n}} \xrightarrow{n \rightarrow \infty} J_u(t)$$

in the sense of finite-dimensional distributions, where $J_u(t)$ is a gaussian process with mean zero and variance given by

- For $\beta \in [0, 1)$, $\mathbb{E}_{\nu_\rho^n}[(J_u(t))^2] = 2\chi(\rho)\sqrt{\frac{t}{\pi}}$, that is $J_u(t)$ is a fractional Brownian Motion of Hurst exponent $1/4$;
- For $\beta = 1$, $\mathbb{E}_{\nu_\rho^n}[(J_u(t))^2] = 2\chi(\rho)\left(\sqrt{\frac{t}{\pi}} + \frac{\Phi_{2t}(2u+4\alpha t)e^{4\alpha u+4\alpha^2 t}-\Phi_{2t}(2u)}{2\alpha}\right)$;
- For $\beta \in (1, +\infty]$, $\mathbb{E}_{\nu_\rho^n}[(J_u(t))^2] = 2\chi(\rho)\left(\sqrt{\frac{t}{\pi}}\left[1 - e^{-u^2/t}\right] + 2u\Phi_{2t}(2u)\right)$,

where

$$\Phi_{2t}(x) := \int_x^{+\infty} \frac{e^{-u^2/4t}}{\sqrt{4\pi t}} du.$$

It worth to remark the variance at $u = 0$, corresponding to the current of particles through the slow bond e_{-1} . If $\beta \in [0, 1)$, the variance corresponds to the one of a fractional Brownian Motion of Hurst exponent $1/4$. If $\beta \in (1, \infty]$, the variance equals to zero as expected. This is a consequence of having Neumann's boundary conditions at $x = 0$ which turns it into an isolated boundary. And for $\beta = 1$, we obtain a family of gaussian processes indexed in α interpolating the two aforementioned processes.

Corollary 1. For $\beta = 1$, denote the limit, as $n \rightarrow \infty$, of $J_u^n(t)/\sqrt{n}$ by $J_u^\alpha(t)$.

Then for every $t \geq 0$ and every $u \in \mathbb{R}$,

$$J_u^\alpha(t) \xrightarrow{\alpha \rightarrow +\infty} J_u^\infty(t),$$

where $J_u^\infty(t)$ is the fractional Brownian Motion with Hurst exponent $1/4$ and

$$J_u^\alpha(t) \xrightarrow{\alpha \rightarrow 0} J_u^0(t),$$

where $J_u^0(t)$ is the mean zero gaussian process with variance given by $\mathbb{E}_{\nu_\rho^n} [(J_u(t))^2] = 2\chi(\rho) \left(\sqrt{\frac{t}{\pi}} \left[1 - e^{-u^2/t} \right] + 2u \Phi_{2t}(2u) \right)$.

The convergence is in the sense of finite dimensional distributions.

5.2 Tagged Particle Fluctuations

Our last goal is to present the asymptotic behavior of a tagged particle in the system. The dynamic of this tagged particle is no longer Markovian, since its behavior is influenced by the presence of other particles in the system. Nevertheless, we can relate the position of the tagged particle with the current and the density of particles, and from the previous results we obtain information about the behavior of this particle.

Suppose to start the system from a configuration with a particle at the site $[un]$ and in all other sites suppose that the configuration is distributed according to ν_ρ^n . In other words, this means that we consider the Markov process $\{\eta_t : t \geq 0\}$ starting from the measure ν_ρ^n conditioned to have a particle at the site $[un]$, that we denote by $\nu_\rho^{n,u}$. That is, $\nu_\rho^{n,u}(\cdot) := \nu_\rho^n(\cdot | \eta_{tn^2}([un]) = 1)$ (Fig. 3).

We notice that the previous results were obtained considering the process starting from ν_ρ^n . In order to be able to use them, we couple the process starting from $\nu_\rho^{n,u}$ and starting from ν_ρ^n , in such a way that both processes differ at most by one site at

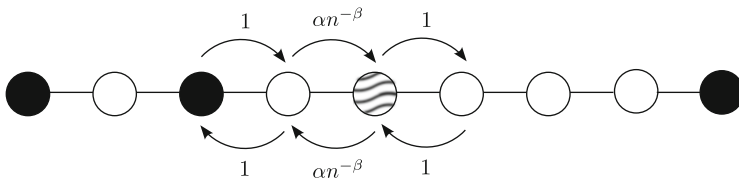


Fig. 3 The tagged particle of the SEP with a slow bond. At initial time, the tagged particle is at the site 0

any given time. This allow us to derive the same statements of Theorems 3 and 4 for the starting measure $\nu_\rho^{n,u}$.

Now, let $X_u^n(t)$ be the position at the time tn^2 of a tagged particle initial at the site $\lfloor un \rfloor$. Since our study is restricted to the one dimensional setting, particles do preserve their order, and it is simple to check that

$$\{X_u^n(t) \geq k\} = \left\{ J_u^n(t) \geq \sum_{x=\lfloor un \rfloor}^{\lfloor un \rfloor+k-1} \eta_{m^2}(x) \right\}.$$

We explain briefly how to get the previous equality. Suppose for simplicity that $u = 0$, so that we start the system with the tagged particle at the origin. If this particle is, at time tn^2 , at the right hand side of n , then all the particles that jumped from -1 to 0 and did not jump backwards, are somewhere at the sites $\{0, 1, \dots, X_u^n(t)\}$. It follows that the current through the bond $\{-1, 0\}$ has to be greater or equal than the density of particles in $\{0, \dots, n\}$. Reasoning similarly, we get the equality between those events.

Finally, last relation together with Theorem 4, implies the following result.

Theorem 5 (C.L.T. for a tagged particle). *Under $\mathbb{P}_{\nu_\rho^u}$, for all $\beta \in [0, \infty]$, every $u \in \mathbb{R}$ and $t \geq 0$*

$$\frac{X_u^n(t)}{\sqrt{n}} \xrightarrow{n \rightarrow +\infty} X_u(t)$$

in the sense of finite-dimensional distributions, where $X_u(t) = J_u(t)/\rho$ in law and $J_u(t)$ is the same as in Theorem 4. In particular, the variance of the process $X_u(t)$ is given by

- For $\beta \in [0, 1)$, $\mathbb{E}_{\nu_\rho^n}[(X_u(t))^2] = 2 \frac{\chi(\rho)}{\rho^2} \sqrt{\frac{t}{\pi}}$, that is $X_u(t)$ is a fractional Brownian Motion of Hurst exponent $1/4$;
- For $\beta = 1$, $\mathbb{E}_{\nu_\rho^n}[(X_u(t))^2] = 2 \frac{\chi(\rho)}{\rho^2} \left(\sqrt{\frac{t}{\pi}} + \frac{\Phi_{2t}(2u+4\alpha t) e^{4\alpha u+4\alpha^2 t}}{2\alpha} \right)$;
- For $\beta \in (1, +\infty]$, $\mathbb{E}_{\nu_\rho^n}[(X_u(t))^2] = 2 \frac{\chi(\rho)}{\rho^2} \left(\sqrt{\frac{t}{\pi}} [1 - e^{-u^2/t}] + 2u \Phi_{2t}(2u) \right)$.

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